

Deriving the Reverse Process (Inference) Equations

So we know how to corrupt an image

$$g(x_t | x_0) = N(\sqrt{\alpha_t} x_{t-1}, (1-\alpha_t)I) \quad \begin{cases} \mu = \sqrt{\alpha_t} x_{t-1} \\ \sigma^2 = (1-\alpha_t)I \end{cases}$$

\Rightarrow to get x_t all we need to do is

$$x_t = \sqrt{\alpha_t} x_{t-1} + \sqrt{1-\alpha_t} \epsilon_t, \quad \epsilon_t \sim N(0, I)$$

But to actually generate an image won't go from pure noise to our image: $\overset{T}{x} \rightarrow x_0$

This is the whole point of SDXL, the inference where we generate an image
Steps:

1) Show Marginal forward posterior intractable

2) Condition on x_0 : Exact forward posterior

3) we don't have x_0 : $\rightarrow \hat{x}_0$

4) Use \hat{x}_0 to get mean

5) Get $\hat{\beta}_t$ for var

1) Show Marginal forward posterior intractable

To perform inference, we need the posterior distribution

$$\begin{aligned} g(x_{t-1} | x_t) &= \frac{g(x_{t-1}, x_t)}{g(x_t)} \\ &= \frac{g(x_t | x_{t-1}) g(x_{t-1})}{g(x_t)} \\ &= g(x_t | x_{t-1}) g(x_{t-1}) \end{aligned}$$

we know $g(x_t | x_{t-1})$ and $g(x_{t-1})$ are both Gaussian by modeling assumption: the normalization is irrelevant by $N(a,b) \times N(a,b) = N(g,f)$

So now, what is $g(x_{t-1})$?

$$g(x_{t-1}) = \int g(x_{t-1}, x_0) dx_0 = \int \underbrace{p_{\text{data}}(x_0)}_{p_{\text{data}}}(x_0) \underbrace{g(x_{t-1} | x_0)}_{p}(x_{t-1} | x_0) dx_0$$

Technically, we have closed form

So $g(x_{t+1})$ is a marginal distribution and an unconditional distribution where we must average over all possible x_0 's in order to infer the next step in the reverse process.

Problem: $P_{\text{Data}}(x_t)$ is unknown

$\therefore g(x_{t+1}|x_t)$ intractable

2) Condition on x_0 : Exact forward posterior

$$g(x_{t+1}|x_t, x_0) \propto g(x_t|x_{t+1}, x_0) g(x_{t+1}|x_0)$$

$$= N(\bar{\alpha}_t x_{t+1}, \beta_t I) \times N(\bar{\alpha}_{t+1} x_0, (1-\bar{\alpha}_{t+1})I)$$

we already know
from forward process

$$\text{How } g(x_{t+1}|x_t, x_0) \propto g(x_t|x_{t+1}, x_0) g(x_{t+1}|x_0) \\ = g(x_t|x_{t+1}) g(x_{t+1}|x_0)$$

$$g(x_{t+1}|x_t, x_0) = \frac{g(x_{t+1}|x_t, x_0)}{g(x_t, x_0)} \quad \text{Bayes Rule}$$

by Markov assumption

$$\xrightarrow{\text{Conditional probabilities}} = \frac{g(x_t|x_{t+1}, x_0) g(x_{t+1}|x_0)}{g(x_t|x_0) g(x_0)}$$

known Gaussian known Gaussian

$$= \frac{g(x_t|x_{t+1}) g(x_{t+1}|x_0)}{g(x_t|x_0)}$$

\rightarrow trap because posterior form known to be Gaussian

$$\propto g(x_t|x_{t+1}) g(x_{t+1}|x_0)$$

$$g(x_{t+1}|x_t, x_0) \propto g(x_t|x_{t+1}) g(x_{t+1}|x_0)$$

$$= N(\bar{\alpha}_t x_{t+1}, \beta_t I) \times N(\bar{\alpha}_{t+1} x_0, (1-\bar{\alpha}_{t+1})I)$$

So now to get the parameters of $g(x_t | x_{t-1}, \lambda)$
 we will multiply the log densities of the two
 Gaussians and simplify to find $\{\mu, \sigma^2\}$

why log?

Since log is monotonic and additive for products the quadratic form in x is identical whether you start from the product or go straight to logs

log pdf Multivariate Gaussian

$$\log N(x; m, \Sigma) =$$

$$-\frac{1}{2} [\log(2\pi) + \log|\Sigma| + (x-m)^T \Sigma^{-1} (x-m)]$$

(A)

$$N(\bar{\alpha}_t x_{t-1}, \beta_t I) \rightarrow \Sigma^{-1} = \frac{1}{\beta_t} I$$

$$= \frac{1}{2} (x_t - \bar{\alpha}_t x_{t-1})^T \frac{1}{\beta_t} I (x_{t-1} - \bar{\alpha}_t x_{t-1})$$

Drop constants!

$$= \frac{1}{2\beta_t} \|x_t - \bar{\alpha}_t x_{t-1}\|^2$$

(B)

$$N(\bar{\alpha}_{t-1} x_0, (1-\bar{\alpha}_{t-1}) I) = \frac{1}{2} (x_0 - \bar{\alpha}_{t-1} x_0)^T \frac{1}{(1-\bar{\alpha}_{t-1})} I (x_0 - \bar{\alpha}_{t-1} x_0)$$

$$= \frac{1}{2(1-\bar{\alpha}_{t-1})} \|x_{t-1} - \bar{\alpha}_{t-1} x_0\|^2$$

$$\lg A + \lg B = \frac{1}{2\beta_t} \|x_t - \bar{\alpha}_t^T x_{t-1}\|^2 + \frac{1}{2(1-\bar{\alpha}_{t-1})} \|x_{t-1} - \bar{\alpha}_{t-1}^T x_0\|^2$$

$$= \frac{1}{2\beta_t} (x_t^T x_t - 2\bar{\alpha}_t^T x_t^T x_{t-1} + \bar{\alpha}_t^T x_{t-1}^T x_{t-1})$$

$$+ \frac{1}{2(1-\bar{\alpha}_{t-1})} (x_{t-1}^T x_{t-1} - 2\bar{\alpha}_{t-1}^T x_{t-1}^T x_0 + \bar{\alpha}_{t-1}^T x_0^T x_0)$$

$(xy)^T = y^T x^T$
 $(a+b)^T = a^T + b^T$
 $M(c+d) = Mc + Md$

To get the form of the new Gaussian we collect terms and complete the square

...

covariance: $\frac{\beta_t (1-\bar{\alpha}_{t-1})}{1-\bar{\alpha}_t} I = \tilde{\beta}_t I$ (a.1)

mean $\mu_{post}(x_t, x_0) = \frac{\bar{\alpha}_t (1-\bar{\alpha}_{t-1})}{1-\bar{\alpha}_t} x_t + \frac{\bar{\alpha}_{t-1} \beta_t}{1-\bar{\alpha}_t} x_0$

using $x_t = \bar{\alpha}_t^T x_0 + \sqrt{1-\bar{\alpha}_t^2} \epsilon$, we can eliminate x_0 and show

$$\mu_{post}(x_t, \epsilon) = \frac{1}{\sqrt{\bar{\alpha}_t}} \left(x_t - \frac{\beta_t}{\sqrt{1-\bar{\alpha}_t}} \epsilon \right)$$

(a.1)

replace with ϵ_0

we need a predictor for x_0 called \hat{x}_0

$$x_t = \bar{\alpha}_t^T x_0 + \sqrt{1-\bar{\alpha}_t^2} \epsilon$$

\Rightarrow solve for x_0

$$x_0 = \frac{1}{\tau \alpha_t} (x_t - \overline{\tau_{1-\alpha_t}} \epsilon)$$

Swap ϵ for ϵ_0 , the models prediction

$$\Rightarrow x_0 = \frac{1}{\tau \alpha_t} (x_t - \overline{\tau_{1-\alpha_t}} \epsilon_0(x_t, t))$$

plug \hat{x}_0 into (A.1) and simplify

$$\Rightarrow \mu_t(x_t, \hat{x}_0) = \frac{1}{\tau \alpha_t} \left[x_t - \frac{\tilde{\beta}_t}{\tau_{1-\alpha_t}} \epsilon_0(x_t, t) \right] \quad (\text{Eq. 2})$$

Now we have mean $\mu_t(x_t)$ and Var $\tilde{\beta}_t$ to get x_{t+1}

$$x_{t+1} = \mu_t(x_t, \hat{x}_0) + \sigma_t z \quad z \sim N(0, I)$$

$$\sigma_t^2 = \tilde{\beta}_t$$