# **Lecture 10 – Turing Machines**

NTIN071 Automata and Grammars

Jakub Bulín (KTIML MFF UK) Spring 2024

<sup>\*</sup> Adapted from the Czech-lecture slides by Marta Vomlelová with gratitude. The translation, some modifications, and all errors are mine.

#### Recap of Lecture 9

- Closure properties of context-free languages (including substitution, homomorphism, inverse homomorphism)
- Also closure properties of deterministic CFLs
- Dyck languages, a characterization of context-free languages

# Chapter 3: Turing Machines

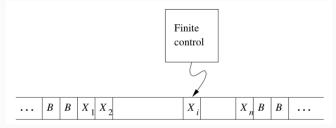
# 3.1 Turing machine

### History and motivation

1931–1936 Gödel, Church, Turing, Kleene: formalize 'algorithms'

Turing machine: a general model of any computer

- a two-way infinite tape (sequential memory)
- a head to read/write, moves in both directions
- a control unit (finite state)



Other formalizations: RAM,  $\lambda$ -calculus, partially recursive functions

Computability theory: what problems can['t] computers solve?

#### The definition

# A Turing Machine (TM) is $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$ where:

- Q is a finite, nonempty set of states
- $\bullet$   $\Sigma$  is a finite, nonempty input alphabet
- $\Gamma$  is a finite, nonempty tape alphabet,  $\Gamma \supseteq \Sigma$ ,  $Q \cap \Gamma = \emptyset$
- $\delta: (Q \setminus F) \times \Gamma \to Q \times \Gamma \times \{L, R\}$  is the (partial) transition function, i.e., one instruction is  $\delta(q, X) = (p, Y, D)$  where:
  - $q \in Q \setminus F$  is the current state [no transitions out of final states]
  - $X \in \Gamma$  is the tape symbol in the current cell
  - $p \in Q$  is the next state to switch to
  - $Y \in \Gamma$  is the tape symbol to rewrite X with in the current cell
  - $D \in \{L, R\}$  is the direction in which the head then moves
- $q_0 \in Q$  is the start state
- $B \in \Gamma \setminus \Sigma$  is the blank symbol, initially written in all but finitely many cells that hold the input symbols
- $F \subseteq Q$  are the final or accepting states

#### Describing computation: configurations

**Recall** computation graph: vertices=configurations, arcs=moves ⊢

A configuration of a TM is a finite string

$$X_1X_2 \dots X_{i-1}qX_iX_{i+1} \dots X_n$$

- $q \in Q$  is the current state
- $X_1 ... X_n \in \Gamma^*$  describe the contents of the relevant portion of the tape, that is, between
  - the first (leftmost) non-blank symbol or head position, and
  - the last (rightmost) non-blank symbol or head position
- the tape head is scanning the *i*-th symbol  $X_i \in \Gamma$

#### **Describing computation: moves**

For moves of a TM M, use same notation as for PDA:  $\vdash_M, \vdash_M^*, \vdash^*$ 

- For  $\delta(q, X_i) = (p, Y, L)$ :  $X_1 X_2 \dots X_{i-1} q X_i X_{i+1} \dots X_n \vdash_M X_1 X_2 \dots X_{i-2} p X_{i-1} \mathbf{Y} X_{i+1} \dots X_n$
- For  $\delta(q, X_i) = (p, Y, R)$ :  $X_1 X_2 \dots X_{i-1} q X_i X_{i+1} \dots X_n \vdash_M X_1 X_2 \dots X_{i-1} \mathbf{Y} p X_{i+1} \dots X_n$

And  $\vdash_{M}^{*}$  is a reflexive, transitive closure of  $\vdash_{M}$  (oriented path in the computation graph).

initial configuration:  $q_0w$  for the input word  $w \in \Sigma^*$  accepting configurations: those where  $q \in F$ , any tape contents (i.e., in our definition, the TM doesn't need to 'clean' the tape)

# The language, an example

The language recognized by a TM  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$  is:

$$L(M) = \{ w \in \Sigma^* \mid q_0 w \vdash_M^* \alpha p \beta, p \in F, \alpha, \beta \in \Gamma^* \}$$

A language is recursively enumerable if it is recognized by some TM

#### **Example**

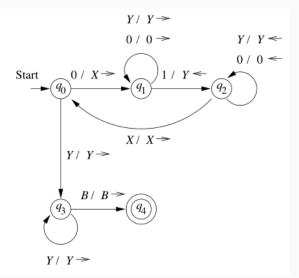
The following TM accepts the language  $L = \{0^n1^n \mid n \ge 1\}$ :

$$M = \big(\{q_0,q_1,q_2,q_3,q_4\},\{0,1\},\{0,1,X,Y,B\},\delta,q_0,B,\{q_4\}\big)$$

δ	0	1	X	Y	В
$q_0$	$(q_1, X, R)$	-	-	$(q_3, Y, R)$	-
$q_1$	$(q_1, 0, R)$	$(q_2, Y, L)$	-	$(q_1, Y, R)$	-
$q_2$	$(q_2, 0, L)$	-	$(q_0, X, R)$	$(q_2, Y, L)$	_
$q_3$	_	-	-	$(q_3, Y, R)$	$(q_4, B, R)$
$q_4$	_	-	-	-	-

#### **Transition diagram**

nodes are states, arcs  $q \to p$  are labeled by X/YD for all  $\delta(q,X) = (p,Y,D)$  (use  $D \in \{\leftarrow, \rightarrow\}$  instead of  $\{L,R\}$ )



# The program explained

Recognizes  $L = \{0^n 1^n \mid n > 0\}$ .

On tape always  $X^*0^*Y^*1^*$ .

Repeatedly rewrite a 0 to X, and the corresponding 1 to Y:

Start  $Q_1$   $Q_2$   $Q_3$   $Q_4$   $Q_4$   $Q_5$   $Q_7$   $Q_7$   $Q_8$   $Q_8$ 

 $q_0$ : rewrite 0 to X, switch to  $q_1$ 

 $q_1$ : search forward for the first 1, rewrite to Y, switch to  $q_2$ 

 $q_2$ : search backward for the last X, go forward, switch to  $q_0$ 

If  $q_0$  sees 0, continue as above, if it sees Y, switch to  $q_3$ 

q3: moves to the end to check that there are no remaining 1s

- if  $q_3$  finds B, switch to  $q_4$ , accept (accepting state)
- if  $q_3$  finds 1, fail (no instruction, not accepting state)

# Computation examples: w = 0011 and w = 0010

```
q_00011 \vdash
                                                  q_00010 \vdash
     Xq_1011 \vdash
                                                  Xq_1010 \vdash
     X0q_111 \vdash
                                                 X0q_110 \vdash
    Xq_20Y1 \vdash
                                                 Xq_20Y0 \vdash
    q_2X0Y1 \vdash
                                                q_2X0Y0 \vdash
    Xq_00Y1 \vdash
                                                 Xq_00Y0 \vdash
    XXq_1Y1 \vdash
                                                XXq_1Y0 \vdash
                                                 XXYq_10 \vdash
    XXYq_11 \vdash
   XXq_2YY \vdash
                                              XXY0q_1B ... fail (no instruction)
   Xg_2XYY \vdash
   XXq_0YY \vdash
   XXYq_3Y \vdash
 XXYYq_3B \vdash
XXYYBq_4B ...accepted
```

10

# Recognizing regular and context-free languages

#### Regular languages:

- simulate a DFA, move always right, never write on the tape
- if we see B, we are at the end of input: if the DFA is in accepting state, switch to a new accepting state  $q_F$
- (note: in a TM, the accepting state  $q_F$  cannot have outgoing transitions; in a DFA it is allowed)

#### **Example**

 $L = \{a^{2n} \mid n \ge 0\}$  recognized by the following TM:

$$M = (\{q_0, q_1, q_F\}, \{a\}, \{a, B\}, \delta, q_0, B, \{q_F\})$$
 with transitions

- $\bullet \ \delta(q_0,B)=(q_F,B,R)$
- $\delta(q_0, a) = (q_1, a, R)$
- $\delta(q_1, a) = (q_0, a, R)$

**Context-free languages:** simulate a PDA, simulate an auxiliary tape to hold the stack contents (how?? later)

# Turing machines with output

Turing Machines can give output, i.e., compute a (partial) function

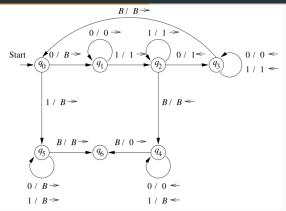
$$f_M: \Sigma^* \to \Gamma^*$$

where  $f_M(w)$  is defined as follows:

- if M halts, then  $f_M(w)$  equals the contents of the tape at the end of computation (everything between the first and last non-blank symbol, or  $f_M(w) = \epsilon$  if the tape is all blanks)
- if M does not halt, then  $f_M(w)$  is undefined

Note: the set of accepting states F is ignored, often omitted

# **Example: computing monus** $m ilde{-} n = max(m - n, 0)$



m, n encoded in unary at the start:  $0^m10^n$  at the end:  $0^{m+n}$  find leftmost 0, delete search right for a 1 if found, continue

find a 0, rewrite by 1 return left if no 0 found, either left or right: right: replace all 1s by B left (m < n): replace all 1s and 0s by B (leave the tape blank)

# Halting, recursively enumerable and recursive languages

#### **Definition**

A TM halts if it enters a state q, scanning a tape symbol X, and there is no transition in this situation, i.e.,  $\delta(q, X)$  is undefined.

A TM halts whenever it gets to an accepting state (no outgoing transitions allowed). In general, we cannot require that a TM always halts, even if it does not accept.

(Until a TM halts, we do not know whether it will accept or not.)

#### **Definition**

A language *L* is:

- recursively enumerable if it is recognized by some TM
- recursive if there exists at TM M that recognizes L and halts on every input  $w \in \Sigma^*$ ; in that case, we also say M decides L

# context-sensitive $\subsetneq$ recursive $\subsetneq$ recursively enumerable $\subsetneq$ all languages

- Every context-sensitive language is recursive.
- Not all recursive languages are context sensitive.
- Every recursive language is recursively enumerable.
- Not all recursively enumerable languages are recursive.
- A language is recursively enumerable, iff it is generated by a Type 0 grammar in the Chomsky hierarchy.
- Not all languages are recursively enumerable.

# 3.2 Variants of TMs

# Construction tricks

# Construction trick: storage in the FA unit

The following TM recognizes the language  $L = L(01^* + 10^*)$ ; it remembers 0, 1, or B in its state:

$$M = (\{q_0, q_1\} \times \{0, 1, B\}, \{0, 1\}, \{0, 1, B\}, \delta, [q_0, B], B, \{[q_1, B]\})$$

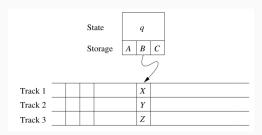
$\delta$	0	1	В
$[q_1, 0]$	$([q_1, 0], 0, R)$	$([q_1, 1], 1, R)$	$([q_1, B], B, R)$
	$([q_1, 1], 0, R)$	$([q_1, 0], 1, R)$	$([q_1, B], B, R)$

In general, we can store a finite number of variables with finitely many possible values (e.g. Boolean, input symbols, etc.): the state is a tuple, entries are values of the variables.

# Construction trick: tape with multiple tracks

To split the tape into two tracks, each of which can hold a tape symbol:  $\Gamma' = \Gamma \cup \{ \begin{smallmatrix} X \\ Y \end{smallmatrix} | X, Y \in \Gamma \}$ . At the beginning, traverse the input changing a to  $\begin{smallmatrix} B \\ a \end{smallmatrix}$ , then return.

Or say  $\Gamma=\{0,1,B\}$  and we want to put a mark \* over certain digits. Then  $\Gamma'=\{0,1,B,\ _0\,,_{\ 0}^*,\ _1\,,_{\ 1}^*\}.$  (We write [X,Y] for  $_Y^X$ .)



**NB:** This is different from (but will be used to simulate!) multiple tapes with heads moving independently.

# **Example:** $L_{wcw} = \{wcw \mid w \in \{0, 1\}^+\}$

Put a mark '\*' over the letter being checked, store it in memory. (We skip the preprocessing, assume a is already [B, a].)

$$M = (\{q_0, \dots, q_9\} \times \{0, 1, B\}, \{[B, 0], [B, 1], [B, c]\}, \{B, *\} \times \{0, 1, B, c\}, \delta, [q_1, B], [B, B], \{[q_9, B]\})$$
 where  $\delta$  is  $(a, b \in \Sigma)$ :

- $\delta([q_1, B], [B, a]) = ([q_2, a], [*, a], R)$  pick up the symbol a
- $\delta([q_2,a],[B,b]) = ([q_2,a],[B,b],R)$  move right, search for c
- $\delta([q_2, a], [B, c]) = ([q_3, a], [B, c], R)$  continue right, state changed
- $\delta([q_3, a], [*, b]) = ([q_3, a], [*, b], R)$  continue right
- $\delta([q_3, a], [B, a]) = ([q_4, B], [*, a], L)$  match symbols, clear memory
- $\delta([q_4, B], [*, a]) = ([q_4, B], [*, a], L)$  go left
- $\delta([q_4, B], [B, c]) = ([q_5, B], [B, c], L) c$  found, continue left
- are all symbols left and right checked? branch adequately

### **Example continued**

- are all symbols left and right checked? branch adequately
- $\delta([q_5, B], [B, a]) = ([q_6, B], [B, a], L)$  left symbol unchecked
- $\delta([q_6, B], [B, a]) = ([q_6, B], [B, a], L)$  proceed left
- $\delta([q_6, B], [*, a]) = ([q_1, B], [*, a], R)$  start again
- $\delta([q_5, B], [*, a]) = ([q_7, B], [*, a], R)$  symbol left from c checked, go right
- $\delta([q_7, B], [B, c]) = ([q_8, B], [B, c], R)$  proceed right
- $\delta([q_8, B], [*, a]) = ([q_8, B], [*, a], R)$  proceed right
- $\delta([q_8, B], [B, B]) = ([q_8, B], [B, B], R)$  accept

**Multi-tape Turing Machines** 

#### A multi-tape TM

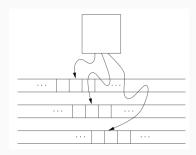
#### **Initial configuration:**

- input on first tape, others blank
- first head scans the first input letter
- FA unit in the initial state

#### One step:

- FA unit switches to the new state
- on each tape rewrite independently
- each head moves independently





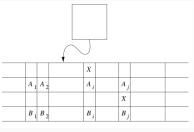
#### **Theorem**

Any language recognized by a multi-tape TM is also recognized by some (single-tape) Turing machine.

# Proof: simulate using multiple tracks, mark head positions

Split the single tape into 2k tracks

- odd: mark *i*<sup>th</sup> head position
- even tracks:  $i^{th}$  tape contents



To simulate one step, visit all heads and store in the FA unit:

- the simulated state
- the number of head marks to the left of us
- for every i, the symbol under i<sup>th</sup> head

Then we know enough to simulate one step. We visit all heads again to rewrite and move them.

Simulating n steps of a k-tape TM takes  $O(n^2)$  moves. (One step takes 4n + 2k, heads no further than 2n; read, write, move marks).

**Nondeterministic Turing Machines** 

# Nondeterministic Turing Machine

#### **Definition**

A nondeterministic Turing machine is  $M = (Q, \Sigma, \Gamma, \delta, q_0, B, F)$  where  $Q, \Sigma, \Gamma, q_0, B, F$  are the same as for a determ. TM, and

$$\delta: (Q - F) \times \Gamma \to \mathcal{P}(Q \times \Gamma \times \{L, R\})$$

A word  $w \in \Sigma^*$  is accepted by the nondeterminisic TM M iff there exists an accepting sequence of moves  $q_0w \vdash^* \alpha p\beta$ ,  $p \in F$ .

#### **Theorem**

For every nondeterministic Turing machine  $M_N$  there exist a deterministic TM  $M_D$  such that  $L(M_N) = L(M_D)$ .

**Proof idea:** Subset construction not possible, the tape is infinite. Instead, BFS of the computation graph. In k steps, at most  $m^k$  configs for  $m = \max_{q \in Q, x \in \Gamma} |\delta(q, x)|$ . Store on a tape & process.

#### **Proof**

Breadth-first search of all possible computations of  $M_N$  (configurations reachable from the initial configuration).

Use a two-tape TM:

- **first tape:** maintain a queue of open vertices (configurations) separated by a special symbol
- second tape: scratch tape for processing one configuration

To process one configuration:

- copy it to the scratch tape, dequeue (erase)
- read the state and scanned symbol
- if accepting state, accept and halt
- for each possible transition of  $\delta_N$ : perform the move and enqueue the resulting config (write at the end of tape 1)

[The transition function  $\delta_N$  is encoded in  $\delta_D$ .]

# One-way infinite tape

#### **Theorem**

Every recursively enumerable language is also recognized by a TM whose head never moves left of its initial position.

$X_0$	$X_1$	$X_2$	
*	$X_{-1}$	$X_{-2}$	

**Proof idea:** Two-track tape, lower track for negative indices. Remember in state if positive or negative. If negative, L means moving to the right and vice versa. Special cases around 0.

**Exercise:** Consider a variant of Turing Machine with an infinite 2D board instead of a tape, moves  $\{\uparrow, \rightarrow, \downarrow, \leftarrow\}$ . Show how to simulate by the standard TM.

### **Summary of Lecture 10**

- Turing machine: two-way infinite tape, read, write, move head
- Accept iff in a final state; configurations
- TMs with output, computing a function
- Recursively enumerable vs. recursive languages (always halt).
- Construction tricks:
  - · storage in state
  - multiple tracks (on a single tape)
- Variants of TMs:
  - multi-tape (independent heads),
  - nondeterministic (accept iff some choices lead to final state)