CS4442 - Assignment 3 Report

Problem 1) Separable Convolution

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Artifical Intelligence 11 - Assingment 3
1) Proof of Separable Convolution for Gaussian ternal
                                  y = [m, n] = x [m, n] * h [m, n] = \sum_{n=1}^{\infty} \sum_{i=1}^{\infty} x [i, i] \cdot h[m-i, n-j]
                                     13 By 2D definition of convolution
                                  y = [m,n] = h[m,n] * x[m,n] = \ \ \ h[i,i] \ x[m-i,n-i]
                                          1) Showing communicative property
                                     If h [m,n] & separable to (mx1) and (1) N) neans h [m,n] = h.[m].
                                     h_2 [n]. Assuming matrix size is (2k+1)·(2k+1) it can be separated to my) recolumn vector and 1xN row vector.
                                               y[m,n] = h[m,n] * x[m,n] = \( \sum_{in} \sum_{
                                                                                                                                                                                                                       = \( \sum_{\text{hill}} \frac{1}{2} \sum_{\text{loj}} \cdot \( \text{m-i, n-i} \)
                                                                                                                                                                                                                  = \( \frac{1}{2} \hrac{1}{2} \
                                 Defintion of 1D convolution is: YEng= xEng* hEng = = XEt]. h[n-k]
                              2D convolution performs 2x the ID convolution in horizontanal and
                                  vertical direction. Since the Gaussian Kernal can be separated into
                                  (MXI) and (IXN) vetors, it shows a spatially separable convolution
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Is Sobel ternal spitially separable. $\begin{bmatrix}
-1 & 0 & 1 \\
-2 & 0 & 2 \\
-1 & 0 & 1
\end{bmatrix} = \begin{bmatrix}
1 \\
2
\end{bmatrix} * [-1 & 0 & 1]$ $\begin{bmatrix}
1 & 2 & 1 \\
0 & 0 & 0 \\
-1 & -2 & -1
\end{bmatrix} = \begin{bmatrix}
1 \\
0
\end{bmatrix} * [1 & 2 & 1]$ The sobel ternal is spatially separable since it can be put into a (Mx1) and (1xN) vectors.

Problem 2) Edge Detection

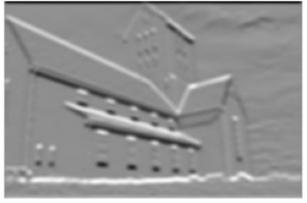
The Original Image



Gaussian Smoothing sigma is 2



Derivative with respect to x



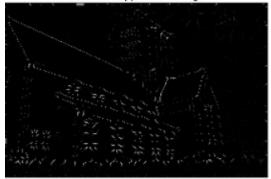
Derivative with respect to y



Gradient Intensity Image



Non-Max Suppression Image

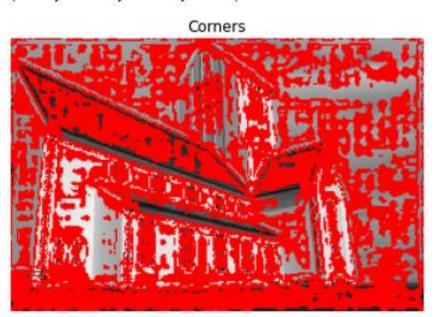


Hysteresis Binary Threshold: Low= 30 High= 60



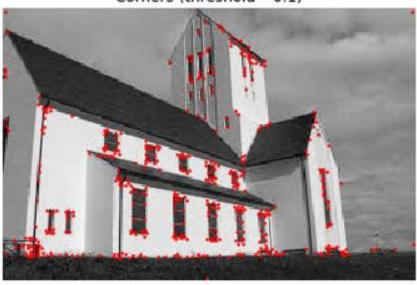
Problem 3) Corner Detection

(-0.5, 275.5, 181.5, -0.5)



[<matplotlib.lines.Line2D at 0x1881ce14370>]





References:

 $\frac{https://towards datascience.com/canny-edge-detection-step-by-step-in-python-computer-vision-b49c3a2d8123}{}$

 $\underline{\text{https://www.geeksforgeeks.org/python-corner-detection-with-harris-detection-with-harris-$

https://iq.opengenus.org/separable-convolution/

https://www.csd.uwo.ca/~oveksler/Courses/Winter2013/CS4442 9542b/L12-CV-Intro-Filtering.pdf