

# CONCURRIT: Testing Concurrent Programs with Programmable State-Space Exploration (A DSL for Writing Concurrent Tests)

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# How to write an xUnit-like test for a concurrent program?

- Consider:
  - Mozilla SpiderMonkey JavaScript Engine
    - Used in Firefox browser
    - 121K lines of code
  - Want to test `JS_NewContext`, `JS_DestroyContext`
    - Contain 2K < lines of code



# How to write an xUnit-like test for a *sequential* program?

- Fix inputs → Deterministic test
  - If there is a bug, every run manifests it!

```
// check if any assertion fails
test_Context() {
    ...
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```



**Firefox**  
Rediscover the web

# How to write an xUnit-like test for a concurrent program?

- Nondeterminism due to thread schedules
  - Hard to specify and control schedule!

```
// check if any assertion fails
test_Context() {

    ... // create 10 threads to run testfunc

}

testfunc() {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```



# Approaches to testing concurrent programs

## 1. Stress testing: No control over thread schedules

→ No guarantee about generated schedules

```
// check if any assertion fails
test_Context() {
    Loop 1000 times {
        ... // create 100 threads to run testfunc
    }
}

testfunc() {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        ...
        JS_DestroyContext(cx);
    }
}
```

# Approaches to testing concurrent programs

1. **Stress testing:** No control over thread schedules

→ No guarantee about generated schedules

2. **Model checking:** Enumerate all possible schedules

– Too many schedules

→ Not scalable for large programs!

**Missing:** Programmer has no direct control on thread schedule

- **Key** to effective and efficient testing

# Programmers have often insights/ideas about which schedules to look at

[Wan-Teh Chang](#) 2002-08-29 16:08:33 PDT

[Description](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

This bug affects the pthreads version of NSPR, which is used on most Unix platforms.

There is a race condition when we use PR\_Interrupt to interrupt PR\_WaitCondVar.

Suppose thread A is calling PR\_WaitCondVar and thread B is interrupting thread A. The following event sequence is problematic.

Thread A	Thread B
-----	-----
Test its interrupt flag	
Set thred->waiting to cvar	
	Set thread A's interrupt flag
	Call pthread_cond_broadcast on thread A's 'waiting' cvar
Call pthread_cond_wait	
-----	-----

Thread A misses the broadcast and blocks in pthread\_cond\_wait forever.

This can be reproduced with the 'join' test program, at least on Red Hat Linux 6.2.

**DO NOT READ!**

# Programmers have often insights/ideas about which schedules to look at

[paul.barnetta@smx.co.nz](mailto:paul.barnetta@smx.co.nz) 2009-02-04 13:54:41 PST [Description](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

I have a multi-threaded application that periodically crashes. I maintain a pool of JSContexts: as they're requested from the pool JS\_SetContextThread and JS\_BeginRequest are called; when they're returned JS\_EndRequest and JS\_ClearContextThread are called.

**DO NOT READ!**

The crashes consistently occurs inside js\_GC in the following code block:

```
while ((acx = js_ContextIterator(rt, JS_FALSE, &iter)) != NULL) {
    if (!acx->thread || acx->thread == cx->thread)
        continue;
    memset(acx->thread->gcFreeLists, 0, sizeof acx->thread->gcFreeLists);
    GSN_CACHE_CLEAR(&acx->thread->gsnCache);
}
```

acx always appears to be valid but acx->thread == NULL when the application crashes (which may be in the memset or GSN\_CACHE\_CLEAR line). This shouldn't occur as these lines should be skipped if (!acx->thread)..

What I suspect is happening is that one thread is calling JS\_GC while a second is calling JS\_EndRequest and JS\_ClearContextThread (in returning a context to the pool). The call to JS\_GC will block until JS\_EndRequest finishes.. JS\_GC then resumes.. but while JS GC is running JS ClearContextThread also runs (no locking is done in this?), modifying the value of acx->thread as the code above runs. acx->thread becomes NULL just before it gets dereferenced and the application exits.

# Programmers have often insights/ideas about which schedules to look at

[Igor Bukanov](#) 2009-03-09 17:47:12 PDT

[Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

At least one problem that I can see from the code is that js\_GC does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

**DO NOT READ!**

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls js\_DestroyContext and thread C calls js\_NewContext.

**Fixed, known schedule for threads A and B**

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch rt->state and eventually calls js\_GC. The latter skips the above check and tries to take the GC lock.

Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets rt->state to LANDING, runs the-last-context-cleanup, runs the GC and then sets rt->state to DOWN.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when rt->state is DOWN.

**Unknown schedule for A and C**

Now the thread C enters the picture. It discovers under the GC lock in js\_NewContext that the newly allocated context is the first one. Since rt->state is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Inserting sleeps to enforce a schedule

## Sleeps:

- **Lightweight and convenient tool** for programmer
- **BUT:** Ad hoc, not reliable for long, complex schedules.

→ **Need: Formal and robust way to describe schedules!**

With the patched NSPR library, run the 'join' test.  
The events will happen at the following time instants:

Thread A	Thread B
-----	-----
T0: Test its interrupt flag	T0: Sleep 1 second
T0: Set thred->waiting to cvar	
T0: Sleep 2 seconds	
	T1: Set thread A's interrupt flag
	T1: Call pthread_cond_broadcast on thread A's 'waiting' cvar
T2: Call pthread_cond_wait	

# Case study: A bug in SpiderMonkey (1.8rc1)

- In RADBench [Jalbert, Sen, HotPar'10]



## DO NOT READ!

I have a multi-threaded application that periodically crashes, giving the following assertion error:

```
$ ./a.out
Assertion failure: rt->state == JSRTS_UP || rt
```

I've attached a test program which demonstrates the issue. It spawns many threads, each of which creates and destroys contexts. I'd expect the number of contexts active to fluctuate between 0 and .THREADS, possibly transitioning between them rapidly and showing a race condition in the code?

Reproducible: Always

Steps to Reproduce:  
Below is a simple application that exhibits the same behavior (me) when run directly from the command line:

8<---

```
#include <stdlib.h>
#include <pthread.h>
#include "jsapi.h"
static JSRuntime *rt;
#define THREADS 100
static void * testfunc(void *ignored) {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }
    return NULL;
}
int main(void) {
    rt = JS_NewRuntime(0x100000);
    if (rt == NULL)
        return 1;
    /* Uncommenting this to guarantee there's always at least
     * one context in the runtime prevents this problem. */
    // JSContext *cx = JS_NewContext(rt, 0x1000);
    // for (i = 0; i < THREADS; i++) {
    //     pthread_create(&thread[i], NULL, testfunc, NULL);
    // }
    for (i = 0; i < THREADS; i++) {
        pthread_join(thread[i], NULL);
    }
    return 0;
}
8<---
```

```
#define THREADS 100

static void * testfunc(void *ignored) {

    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }

    return NULL;
}
```

# Possible buggy schedule from bug report

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# Concurrit: A DSL for writing concurrent tests

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment 5](#) [reply] [-] [reply] [-]

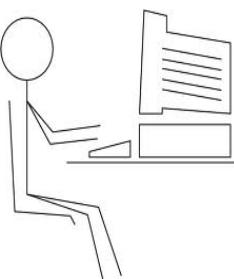
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Insights/ideas about  
thread schedules

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## Software Under Test

```
#define THREADS 100

static void * testfunc(void *ignored) {

    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }

    return NULL;
}
```



Test in  
Concurrit DSL

Systematically  
explore  
all-and-only  
thread schedules  
specified by DSL

Specify a set of schedules in **formal**,  
**concise**, and **convenient** way

# Unit-testing programs with Concurrit

(What about integration tests?: Wait for conclusion)

## Software Under Test (SUT)

Instrumented to control

Thread A

Thread B

Thread C

```
testfunc() {  
    JSContext *cx = JS_NewContext(r  
    if (cx) {  
        JS_BeginRequest(cx);  
        JS_DestroyContext(cx);  
    }  
}
```

Send event  
and block

Unblock thread

## Test in Concurrit DSL

Runs concurrently with SUT

.....  
.....  
.....  
.....  
.....  
.....  
.....  
.....

Kinds of events: Memory read/write, function enter/return, function call, end of thread, at particular source line, user-defined

# Unit-testing programs with Concurrit

(What about integration tests?: Wait for conclusion)

## Software Under Test (SUT)

Instrumented to control

Thread A

Thread B

Thread C

```
testfunc() {
    JSContext *cx = JS_NewContext(r);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }
}
```

Send event  
and block

Unblock thread

## Concurrit monitor

Runs concurrently with SUT

```
// Test in Concurrit DSL
```

.....

.....

.....

**Kinds of events:** Memory read/write, function enter/return, function call, end of thread, at particular source line, user-defined

# Outline

- Bug report for Mozilla SpiderMonkey
- Write tests in Concurrit DSL to generate buggy schedule

## → **Simple schedules:**

- Few schedules **BUT** not manifesting bug
- **All schedules:**
- Manifests bug **BUT** too many schedules
- **Target buggy schedule in bug report**
- Few schedules **AND** manifests bug

# Possible buggy schedule from bug report

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

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# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:   WITH T IN [TA, TB, TC]

4:   RUN T UNTIL COMPLETES
}
```

# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL
```

1: TA, TB, TC = **WAIT\_FOR\_DISTINCT\_THREADS()**

2: LOOP UNTIL TA, TB, TC COMPLETE {

3: WITH T IN [TA, TB, TC]

4: RUN T UNTIL COMPLETES

}

Wait until 3 distinct threads sending events



# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {
3:   WITH T IN [TA, TB, TC]
4:   RUN T UNTIL COMPLETES
}
```

Loop until all 3 threads complete



# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

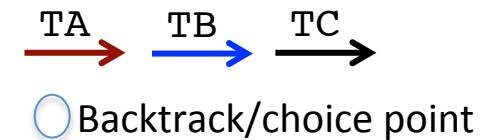
2: LOOP UNTIL TA, TB, TC COMPLETE {

3:   WITH T IN [TA, TB, TC]

4:   RUN T UNTIL COMPLETES
}
```

Pick one of the threads

TA 



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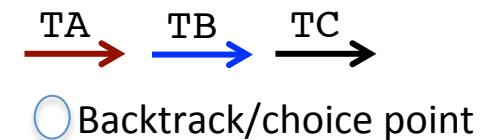
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```

Run selected thread  
until it completes



Thread  
completes

TA

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```
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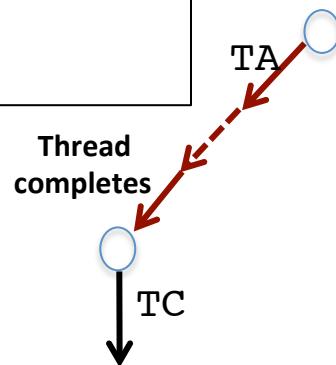
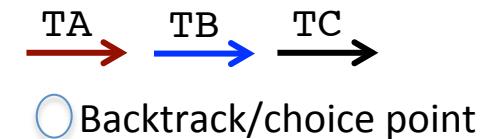
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Pick one of the threads



# First test: Run each thread sequentially until completion (No interleaving)

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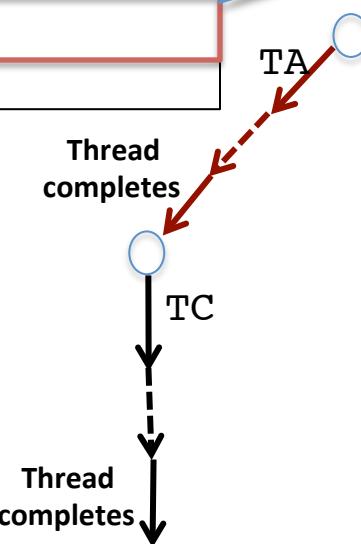
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Run selected thread  
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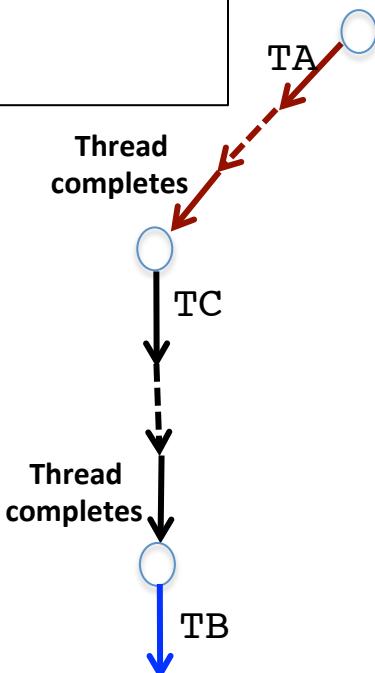
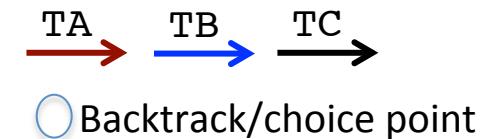
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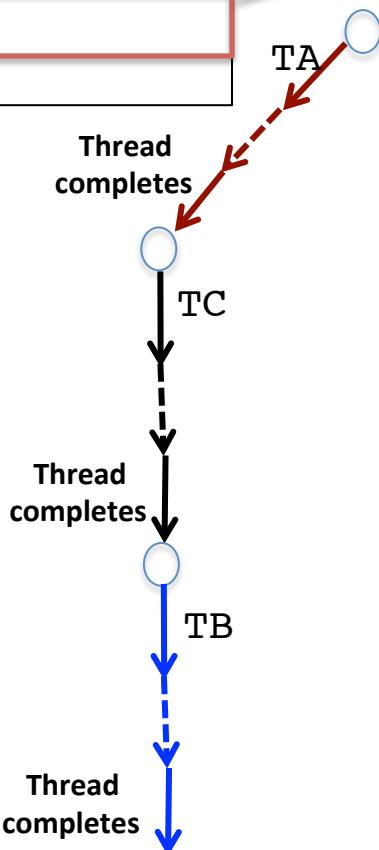
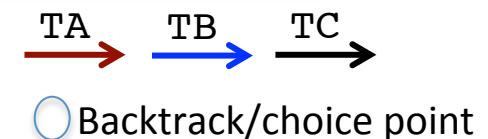
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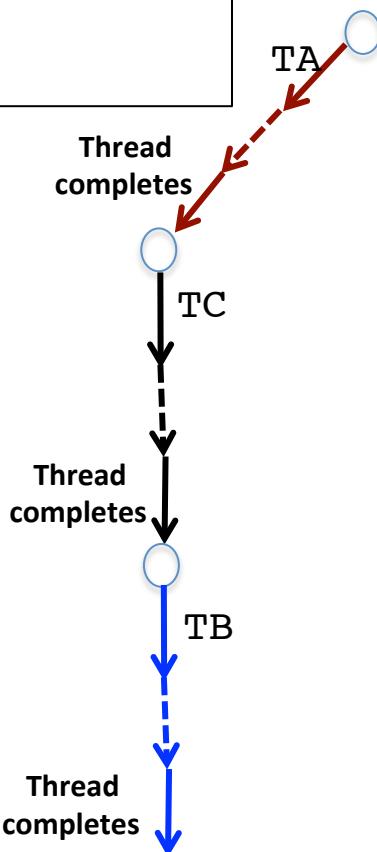
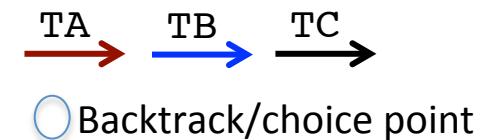
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3:   BACKTRACK HERE WITH T IN [TA, TB, TC]

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}
```

Pick a different thread  
when backtracked



# First test: Run each thread sequentially until completion (No interleaving)

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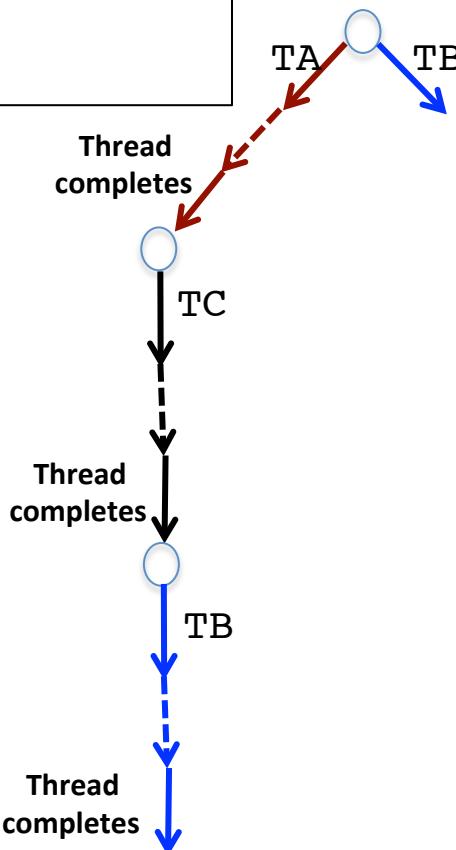
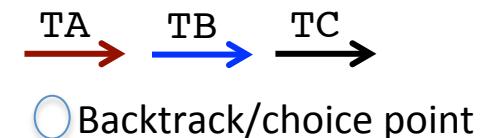
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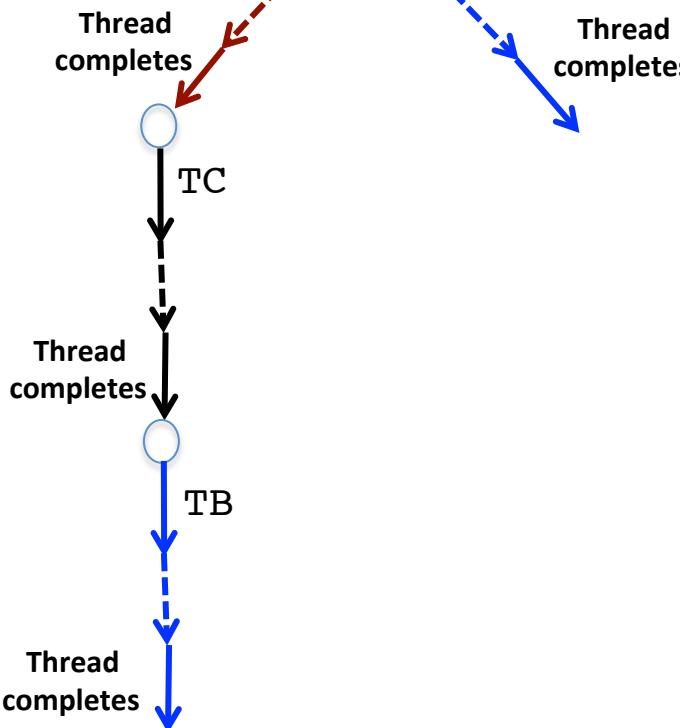
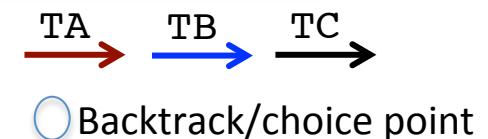
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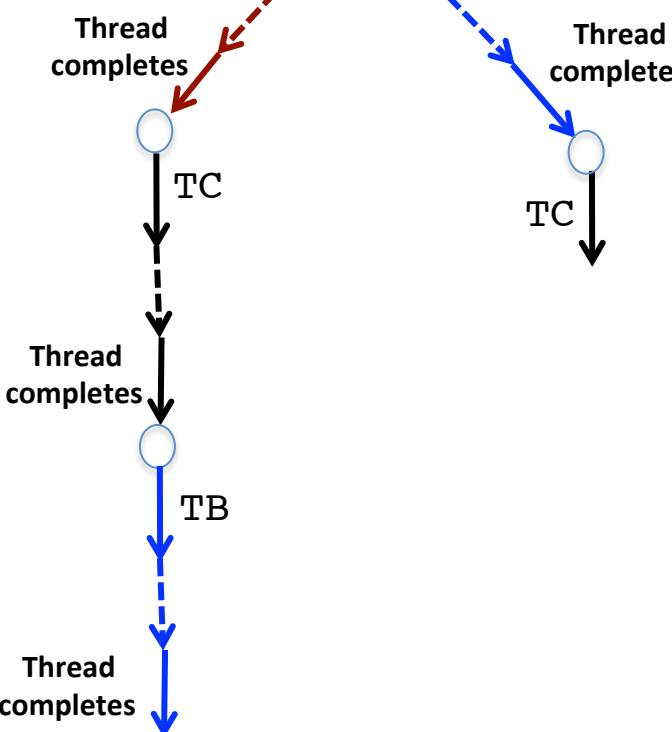
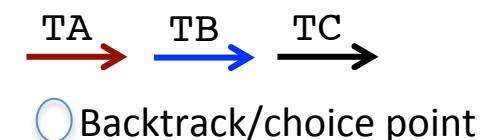
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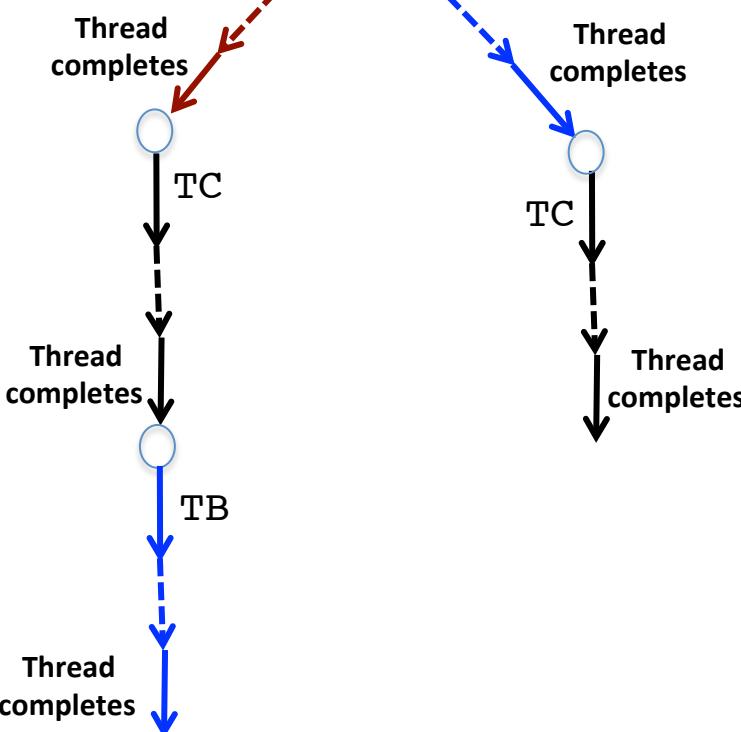
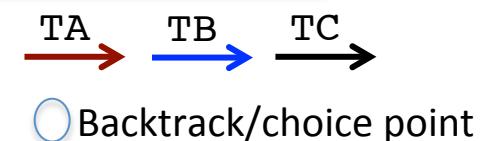
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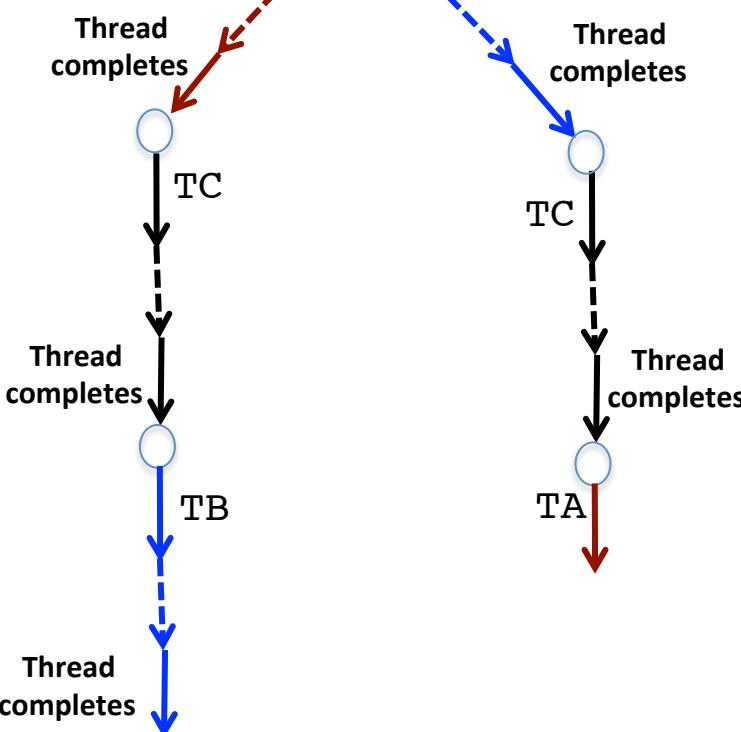
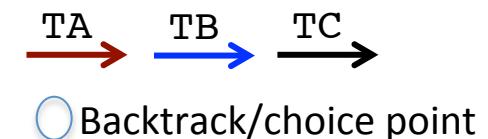
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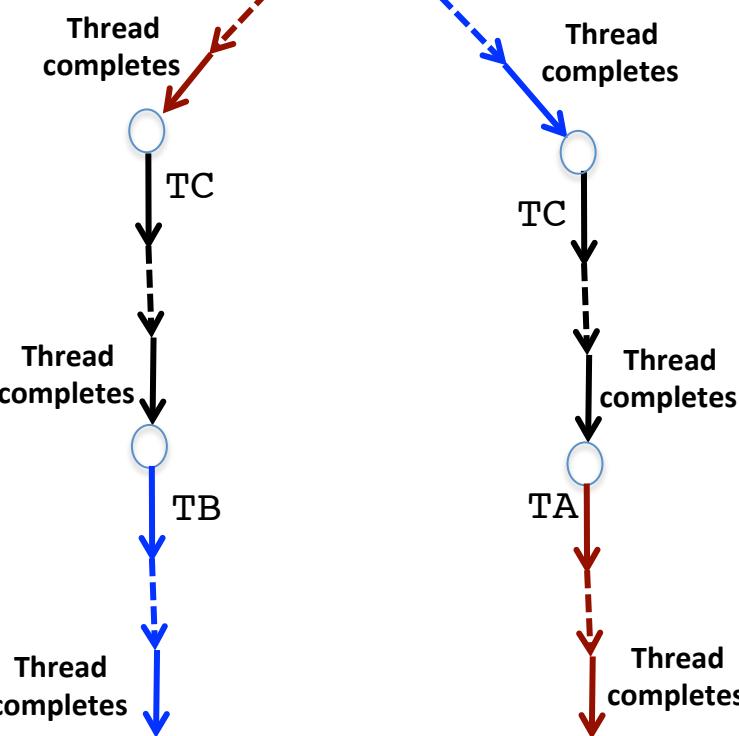
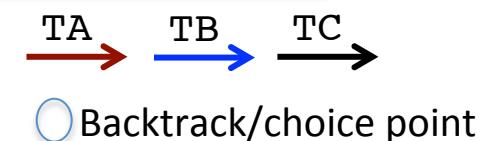
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```
// Test in Concurrit DSL

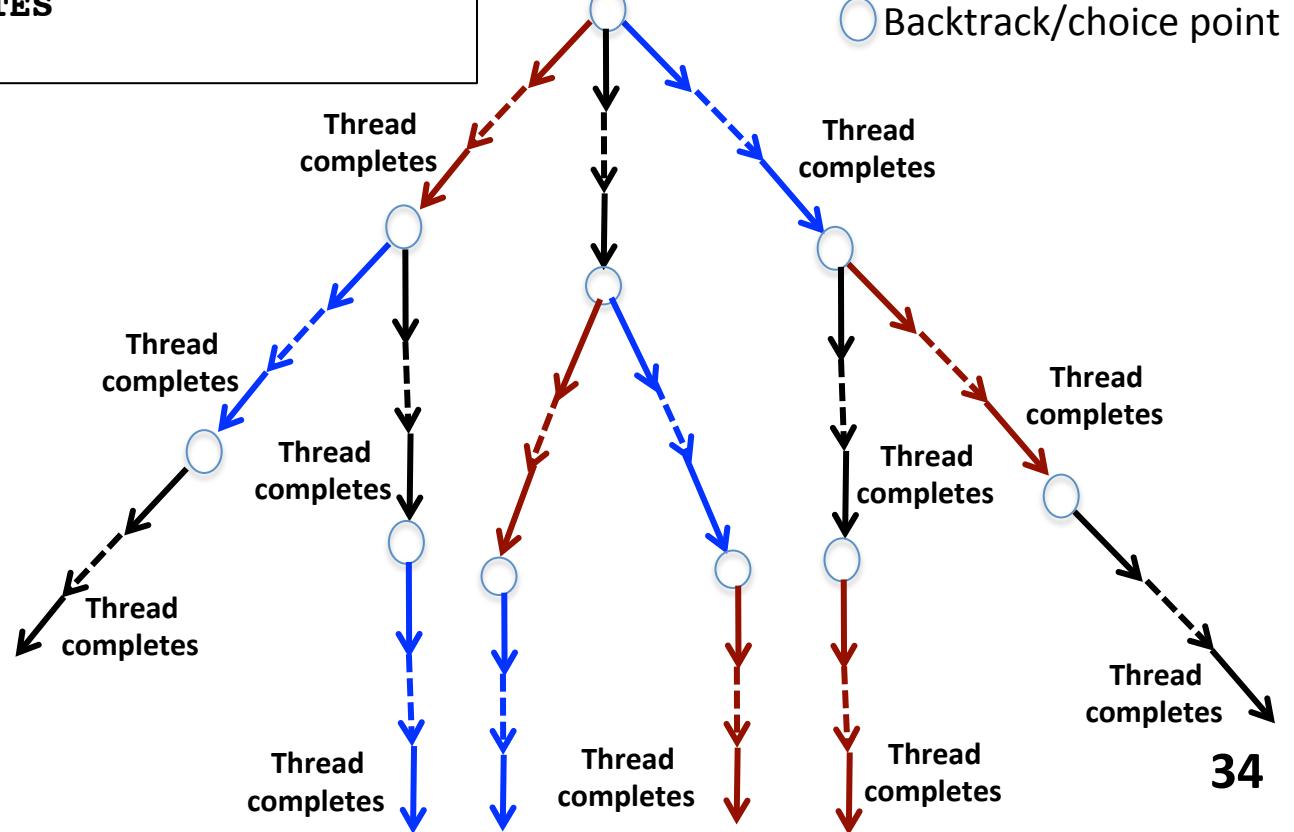
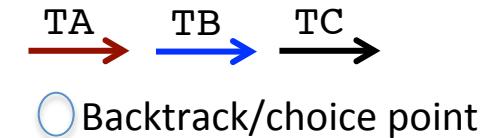
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:   BACKTRACK HERE WITH T IN [TA, TB, TC]

4:   RUN T UNTIL COMPLETES
}
```

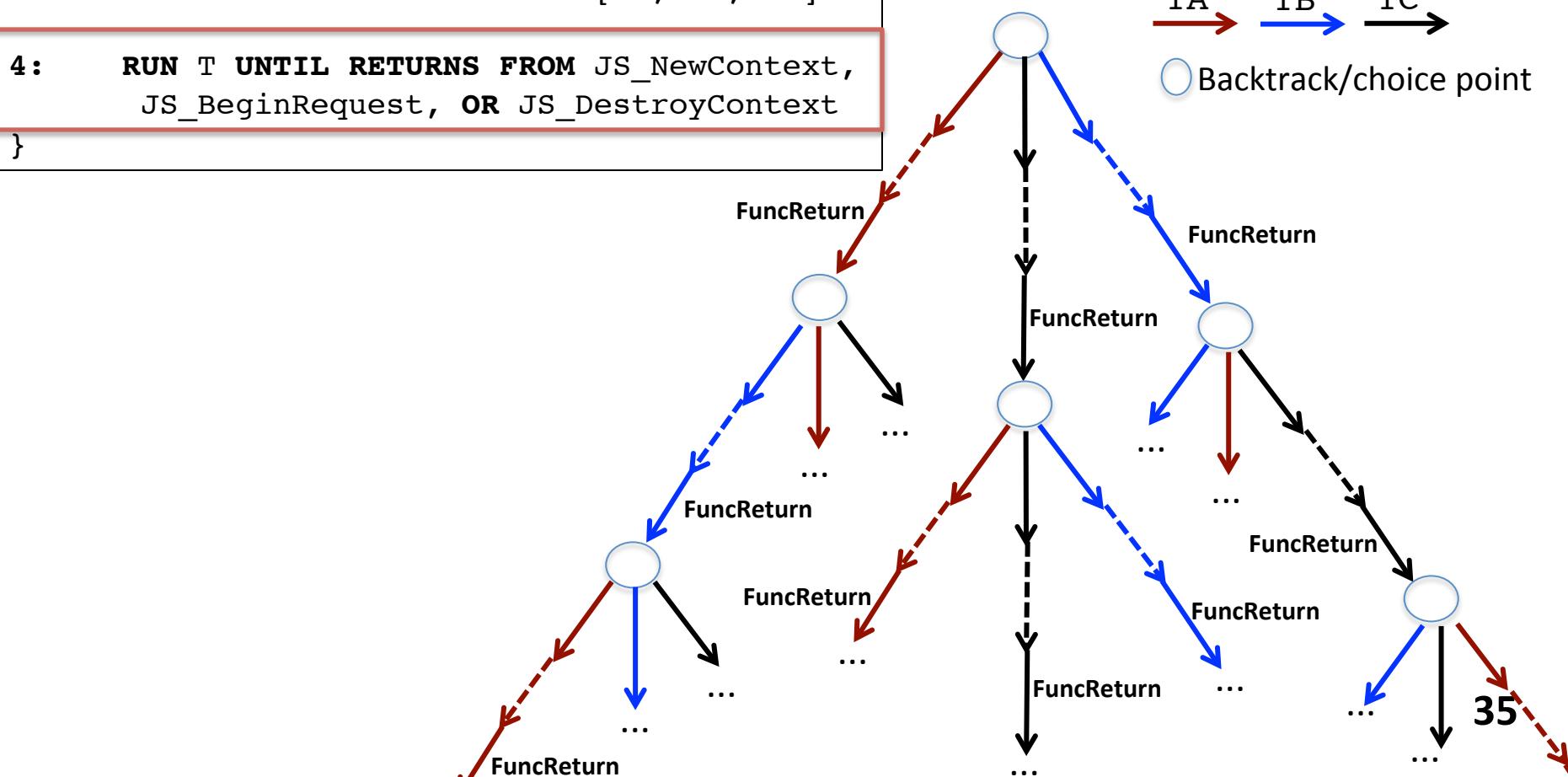
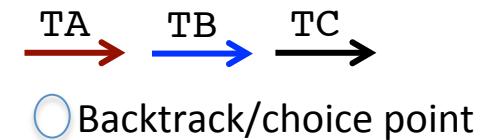
**Result:**  
6 schedules  
No assertion failure!



# Second test: Run each thread sequentially until it returns from function

```
// Test in Concurrit DSL  
  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
  
4:   RUN T UNTIL RETURNS FROM JS_NewContext,  
      JS_BeginRequest, OR JS_DestroyContext  
}
```

**Result:**  
< 50 schedules  
No assertion failure!



# Outline

- Bug report for Mozilla SpiderMonkey
- Write tests in Concurrit DSL to generate buggy schedule
  - **Simple schedules**
    - Few schedules **BUT** not manifesting bug
  - **All schedules**
    - Manifests bug **BUT** too many schedules
    - **Target buggy schedule in bug report**
      - Few schedules **AND** manifests bug

# First test: Run each thread sequentially until completion (No interleaving)

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:     BACKTRACK HERE WITH T IN [TA, TB, TC]

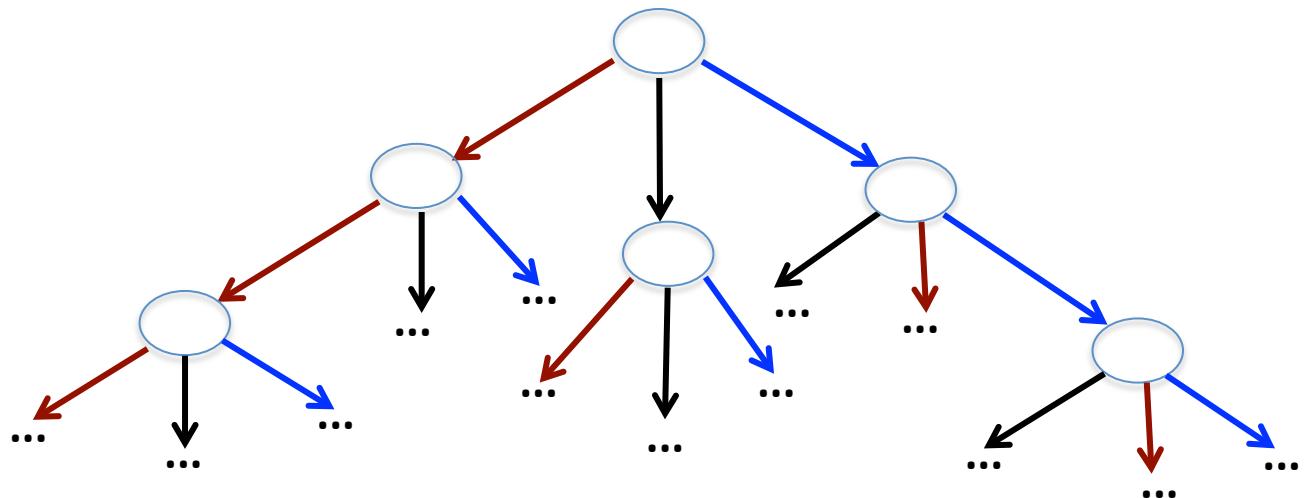
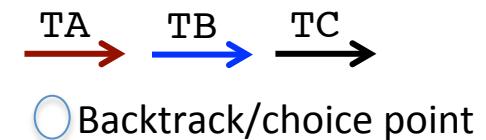
4:     RUN T UNTIL COMPLETES
}
```

# Generate all thread schedules

```
// Test in Concurrit DSL  
  
1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()  
  
2: LOOP UNTIL TA, TB, TC COMPLETE {  
  
3:   BACKTRACK HERE WITH T IN [TA, TB, TC]  
  
4:   RUN T UNTIL NEXT EVENT  
}
```

## Result:

> 100,000 schedules  
Assertion failure  
after a night!



# What is different from (traditional) model checking?



## 1. Cannot control/instrument everything!

- Must tolerate uncontrolled non-determinism
- Backtrack-and-replay-prefix may fail

## 2. Localize the search

- To particular functions, operations, states, ...

**BUT:** Can express traditional model checking algorithms

- If every operation can be controlled
- Feasible for small programs, data structures, ...

# Outline

- Bug report for Mozilla SpiderMonkey
- Write tests in Concurrit DSL to generate buggy schedule
  - **Simple schedules**
    - Few schedules **BUT** not manifesting bug
  - **All schedules**
    - Manifests bug **BUT** too many schedules
- **Target buggy schedule in bug report**
  - Few schedules **AND** manifests bug

# Possible buggy schedule from bug report

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

At least one problem that I can see from the code is that js\_GC does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls js\_DestroyContext and thread C calls js\_NewContext.

First thread A runs the GC. It releases the GC lock. Thread B runs and calls js\_DestroyContext. At this stage the GC lock is released. Thread C runs and calls js\_NewContext. The code looks like this:

```
static void * testfunc(void *ignore) {
    JSContext *cx = JS_NewContext(rt, 0x1000);
    if (cx) {
        JS_BeginRequest(cx);
        JS_DestroyContext(cx);
    }
    return NULL;
}
```

Threads A, B run the GC and release the lock. Thread C runs and calls js\_NewContext. The code looks like this:

```
JSContext *cx = JS_NewContext(rt, 0x1000);
if (cx) {
    JS_BeginRequest(cx);
    JS_DestroyContext(cx);
}
return NULL;
```

Now the thread C enters the picture. It discovers under the GC lock in js\_NewContext that the newly allocated context is the first one. Since rt->state is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Generate all thread schedules

```
// Test in Concurrit DSL

1: TA, TB, TC = WAIT_FOR_DISTINCT_THREADS()

2: LOOP UNTIL TA, TB, TC COMPLETE {

3:   BACKTRACK HERE WITH T IN [TA, TB, TC]

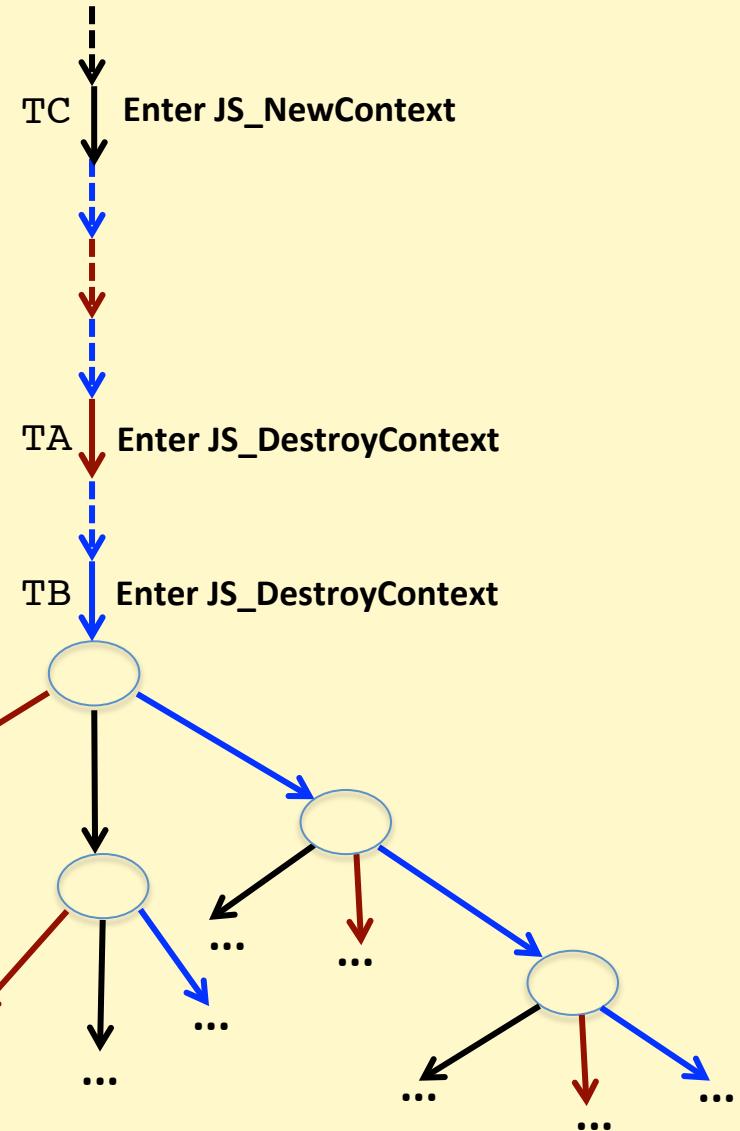
4:   RUN T UNTIL NEXT EVENT
}
```

# Exploiting programmer's insights about bug

```
// Test in Concurr.  
  
1: TC = WAIT_FOR_T  
2: TA = WAIT_FOR_D  
3: TB = WAIT_FOR_D  
4: LOOP UNTIL TA,  
5:     BACKTRACK HERE  
6:     RUN T UNTIL I  
}
```

**Result:**

< 50,000 schedules  
Assertion failure  
after a few hours!



# What is different from (traditional) model checking?

## 1. Cannot control/instrument everything!

- Must tolerate uncontrolled non-determinism
- Backtrack-and-replay-prefix may fail

## 2. Localize the search

- To particular functions, operations, states, ...

**BUT:** Can express traditional model checking algorithms

- If every operation can be controlled
- Feasible for small programs, data structures, ...

# Possible buggy schedule from bug report

- Shared variables involved in the bug:
  - **rt->state, rt->gcLock, rt->gcThread**
- Reschedule threads when accessing them.

outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls `js_DestroyContext` and thread C calls `js_NewContext`.

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch `rt->state` and eventually calls `js_GC`. The latter skips the above check and tries to take the GC lock.

Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets `rt->state` to LANDING, runs the-last-context-cleanup, runs the GC and then sets `rt->state` to DOWN.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when `rt->state` is DOWN.

Now the thread C enters the picture. It discovers under the GC lock in `js_NewContext` that the newly allocated context is the first one. Since `rt->state` is DOWN, it releases the GC lock and starts the first context initialization procedure. That procedure includes the allocation of the initial atoms and it will happen when the thread A runs the GC. This may lead precisely to the first stack trace from the [comment 4](#).

# Exploiting programmer's insights about bug

```
// Test in Concurrit DSL

1: TC = WAIT_FOR_THREAD(ENTERS JS_NewContext)

2: TA = WAIT_FOR_DISTINCT_THREAD(ENTERS JS_DestroyContext)

3: TB = WAIT_FOR_DISTINCT_THREAD(ENTERS JS_DestroyContext)

4: LOOP UNTIL TA, TB, TC COMPLETE {

5:     BACKTRACK HERE WITH T IN [TA, TB, TC]

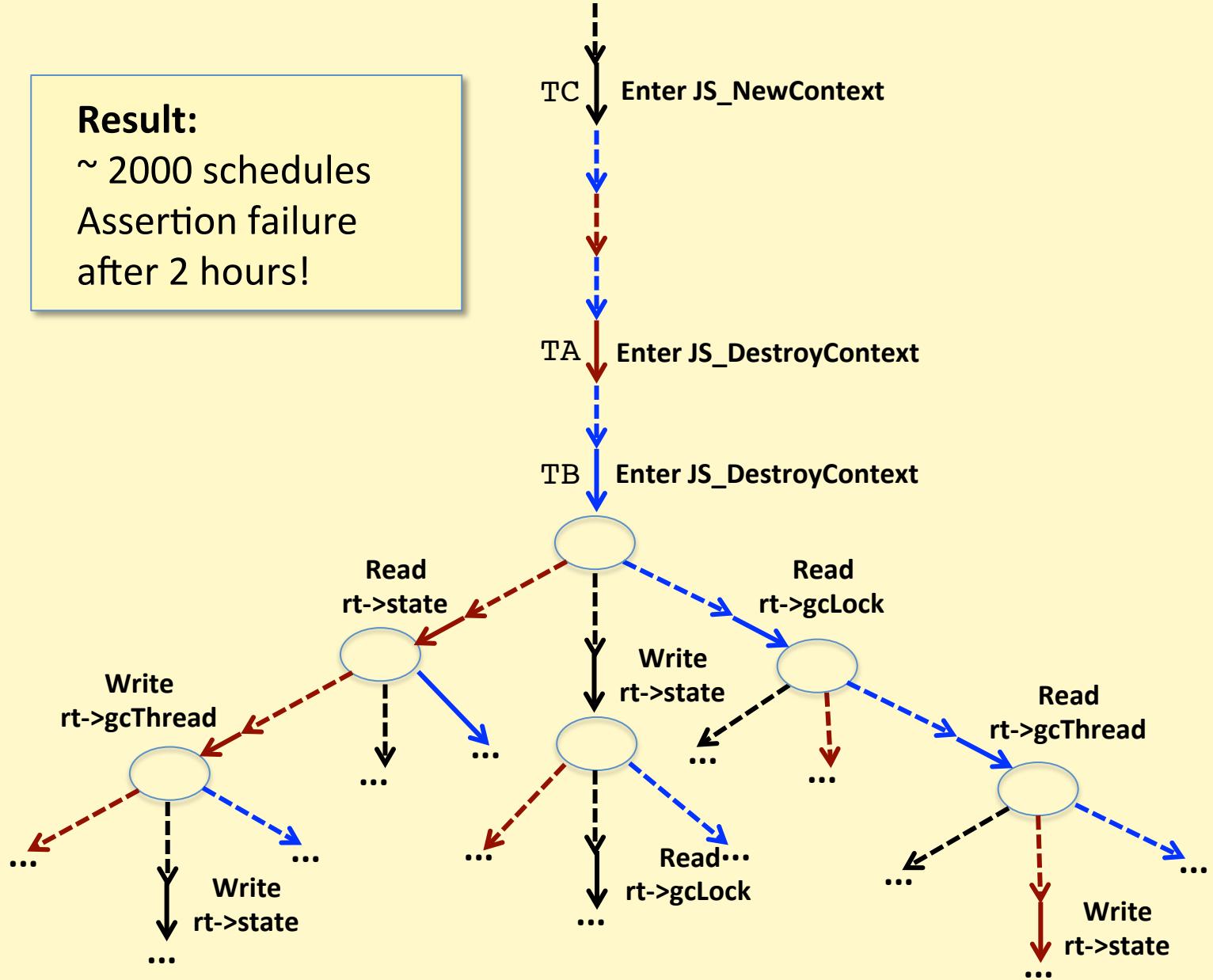
6:     RUN T UNTIL NEXT EVENT
}
```

# Exploiting programmer's insights about bug

```
// Test in C  
1: TC = WAIT_  
2: TA = WAIT_  
3: TB = WAIT_  
4: LOOP UNTIL  
5: BACKTRACE  
6: RUN T U  
}
```

**Result:**

~ 2000 schedules  
Assertion failure  
after 2 hours!



# Possible buggy schedule from bug report

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment 5](#) [\[reply\]](#) [\[-\]](#) [\[reply\]](#) [\[-\]](#)

At least one problem that I can see from the code is that js\_GC does the check:

```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
    return;
```

outside the GC lock. Now suppose there are calls js\_DestroyContext and thread C calls

## Setup

First thread A removes its context from the runtime list. That context is not the last one so thread does not touch rt->state and eventually calls js\_GC. The latter skips the above check and tries to ~~to take the GC lock~~

Before this moment the thread B takes the runtime list, discovers that it is the last-the-last-context-cleanups, runs the GC and

## Fixed, known schedule for threads A and B

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when rt->state is DOWN.

Now the thread C enters the picture. It discovers that the newly allocated context's rt->state is DOWN, it releases the GC lock and starts the initialization procedure. That procedure is atomic and it will happen when the thread A returns to the first stack trace from the [comment 4](#).

## Unknown schedule for A and C

# Final test

```
// Test in Concurrit DSL
```

```
TC = WAIT_FOR_THREAD(  
    ENTERS JS_NewContext)
```

```
TA = WAIT_FOR_DISTINCT_THREAD(  
    ENTERS JS_DestroyContext)
```

```
TB = WAIT_FOR_DISTINCT_THREAD(  
    ENTERS JS_DestroyContext)
```

```
RUN TA UNTIL READS &rt->state IN js_GC
```

```
RUN TB UNTIL COMPLETES
```

```
RUN TA UNTIL WRITES &rt->gcThread IN js_GC
```

```
LOOP UNTIL TA, TC COMPLETE {
```

```
    BACKTRACK HERE WITH T IN [TA, TC]
```

```
    RUN T UNTIL READS OR WRITES MEMORY
```

```
}
```

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment](#)

At least one problem that I can see from the code is that js  
if (rt->state != JSRTS\_UP && gckind != GC\_LAST\_CONTEXT)  
 return;  
outside the GC lock. Now  
calls js\_DestroyContext

## Setup

First thread A removes its context from the runtime list. Then  
the last one so thread does not touch rt->state and eventual  
latter skips the above code.

Before this moment the t  
runtime list, discovers  
the-last-context-cleanups

## Fixed, known schedule for threads A and B

At this stage the thread A gets the GC lock, setup itself as  
runs the GC and releases the GC lock to proceed with the GC  
DOWN.

Now the thread C enters :  
js\_NewContext that the no  
rt->state is DOWN, it re  
initialization procedure  
atoms and it will happen  
to the first stack trace from the [comment 4](#).

## Unknown schedule for A and C

# Final test

Igor Bukanov 2009-03-09 17:47:12 PDT

[Comment 5](#) [reply] [-] [reply] [-]

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```
if (rt->state != JSRTS_UP && gckind != GC_LAST_CONTEXT)
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outside the GC lock. Now suppose there are 3 threads, A, B, C. Threads A and B calls js\_DestroyContext and thread C calls js\_NewContext.

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Before this moment the thread B takes the lock, removes its context from the runtime list, discovers that it is the last, sets rt->state to LANDING, runs the last-context-cleanup, runs the GC and then sets rt->state to DOWN.

At this stage the thread A gets the GC lock, setup itself as the thread that runs the GC and releases the GC lock to proceed with the GC when rt->state is DOWN.

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## Software Under Test

• • • •  
• • • •

// Test in Concurrent DSL

```
TC = WAIT_FOR_THREAD(
    ENTERS JS_NewContext)

TA = WAIT_FOR_DISTINCT_THREAD(
    ENTERS JS_DestroyContext)

TB = WAIT_FOR_DISTINCT_THREAD(
    ENTERS JS_DestroyContext)

RUN TA UNTIL READS &rt->state IN js_GC

RUN TB UNTIL COMPLETES

RUN TA UNTIL WRITES &rt->gcThread IN js_GC

LOOP UNTIL TA, TC COMPLETE {

    BACKTRACK HERE WITH T IN [TA, TC]

    RUN T UNTIL READS OR WRITES MEMORY
}
```

Triggers assertion failure  
in < 30 thread schedules  
(Add to regression test suit)

# Implementation/Evaluation

- **Implementation:** DSL embedded in C++
  - Prototype: <http://code.google.com/p/concurrit/>
- Wrote concise tests for (real/manually-inserted) bugs in well-known benchmarks
  - Reproducing bugs
    - using < 20 lines of DSL code, after < 30 schedules
  - **Inspect:** bbuf, bzip2, pbzip2, pfscan
  - **PARSEC:** dedup, streamcluster
  - **RADBench:** SpiderMonkey 1/2, Mozilla NSPR 1/2/3
    - **Ongoing:** Apache httpd, Chromium, Memcached
  - Can write various model checking algorithms (next slide)

# Default search policies

```
EXPLORE_ALL_SCHEDULES(THREADS) {  
    LOOP UNTIL ALL THREADS COMPLETE {  
        BACKTRACK HERE WITH T IN THREADS  
        RUN T UNTIL NEXT EVENT  
    }  
}
```

```
EXPLORE_TWO_CONTEXT_BOUNDED_SCHEDULES(THREADS) {  
    BACKTRACK HERE WITH T1 IN THREADS  
    BACKTRACK HERE LOOP NONDETERMINISTICALLY {  
        RUN T1 UNTIL NEXT EVENT  
    }  
  
    BACKTRACK HERE WITH T2 IN [THREADS EXCEPT T1]  
    BACKTRACK HERE LOOP NONDETERMINISTICALLY {  
        RUN T2 UNTIL NEXT EVENT  
    }  
  
    -- EXPLORE_THREADS_UNTIL_COMPLETION(THREADS)  
}
```

```
→ EXPLORE_THREADS_UNTIL_COMPLETION(THREADS) {  
    LOOP UNTIL ALL THREADS COMPLETE {  
        BACKTRACK HERE WITH T IN THREADS  
        RUN T UNTIL COMPLETION  
    }  
}
```

# Positioning Concurrit: Usage scenarios

Insert sleeps:  
Explore one schedule

Model checking:  
Explore all schedules

Concurrit

**Control user-defined events**

- Portable, testing library
- Manual instrumentation
- Generate exact/perfect schedule

**Control all operations**

- Exhaustive testing tool
- Automated instrumentation
- Generate all schedules

# Unit-testing programs with Concurrit

## Software Under Test (SUT)

Instrumented to control

Thread A

Thread B

Thread C

```
testfunc() {  
    JSContext *cx = JS_NewContext(r  
    if (cx) {  
        JS_BeginRequest(cx);  
        JS_DestroyContext(cx);  
    }  
}
```

Send event  
and block

Unblock thread

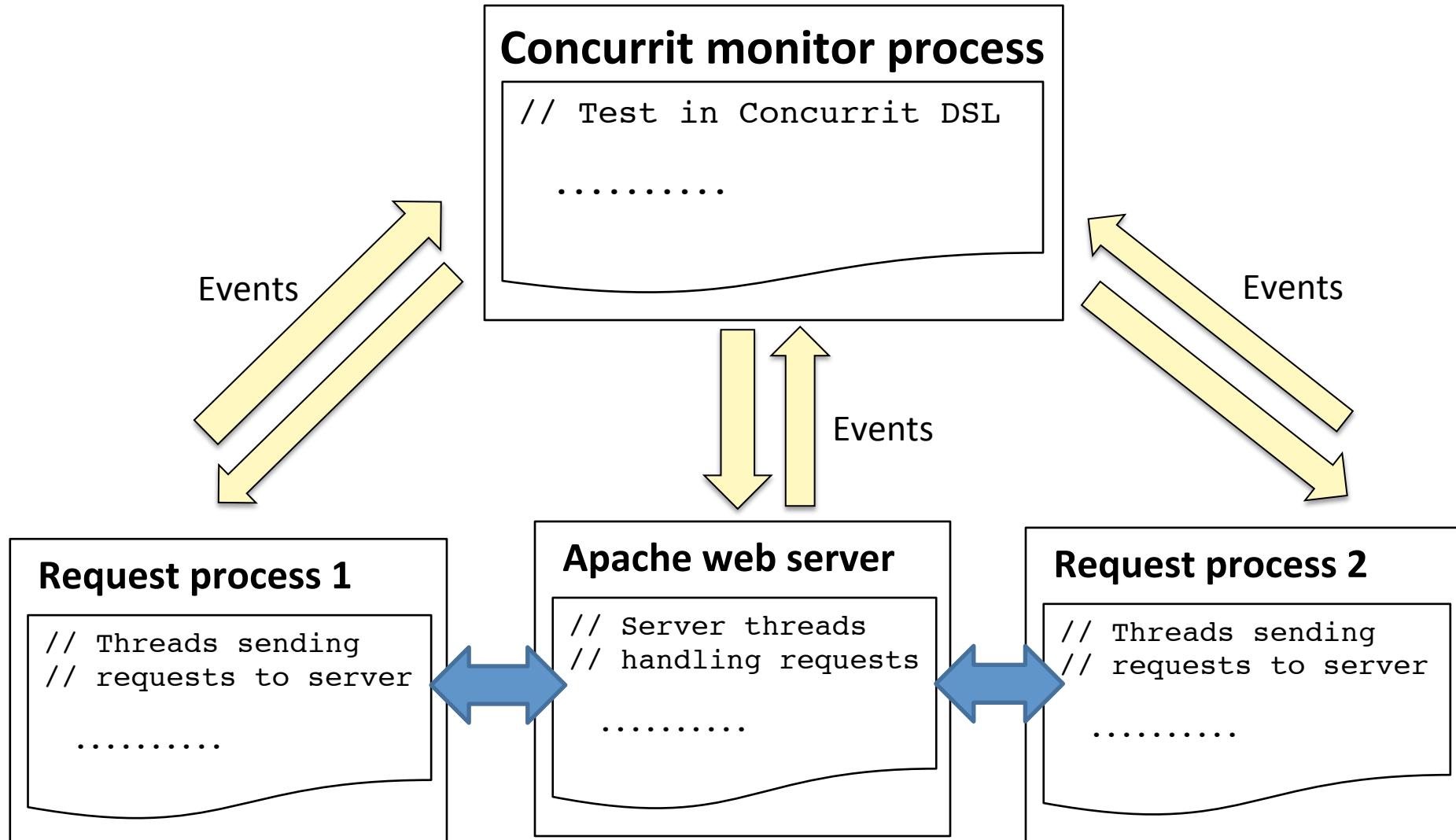
## Test in Concurrit DSL

Runs concurrently with SUT

.....  
.....  
.....  
.....  
.....  
.....  
.....  
.....

# Ongoing work: Integration testing

## Controlling multi-process/distributed applications



# Approaches to controlling thread schedules

**Test run:** A set of executions of the test driver.

**Success:** At least one execution in the run hits the bug.

