$$y'' + \sin y + 1 = 0, \ y(0) = 0, \ y(\pi) = 0$$

```
In [ ]: # shooting method
          from numpy import pi, sin
          import matplotlib.pyplot as plt
          def bisect(y, x_start, x_end, func, max_iter=200, tol=1.0e-9) :
               y_start = func(x_start)
               y_{end} = func(x_{end})
               x_root = None
               for _ in range(max_iter) :
                   x_mid = (x_start + x_end) / 2
                   y_mid = func(x_mid)
                   if abs(y - y_mid) \leftarrow tol :
                       x_{root} = x_{mid}
                       break
                   if y_mid * y_start >= 0 :
                       x_start = x_mid
                       y_start = y_mid
                   else:
                       x_{end} = x_{mid}
                       y_{end} = y_{mid}
               if x root == None :
                   raise ValueError("Failed to converge.")
               return x_root
          def shooting(x_start, x_end, h, y_dif_init, bc, func_calc, func_dif, tol=1.0e-9) :
               y0 = bc[0]
               y_{end} = bc[1]
               def wrapper(y1_input) :
                   return func_calc(x_start, x_end, y0, y1_input, h, func_dif)
               y_dif = bisect(y_end, y_dif_init[0], y_dif_init[1], func=wrapper, tol=tol)
               return y_dif
          def calc_yb(x_start, x_end, y0, y1, h, func) :
               while x_start <= x_end + h :</pre>
                   y2 = func(x_start, y0)
                   y1 += y2 * h
                   y0 += y1 * h
                   x_start += h
               return y0
          def range_func(x_start, x_end, y0, y1, h, func) :
               x_range = []
               y_range = []
               while x_start <= x_end + h :</pre>
                   x_range.append(x_start)
                   y_range.append(y0)
                   y2 = func(x_start, y0)
```

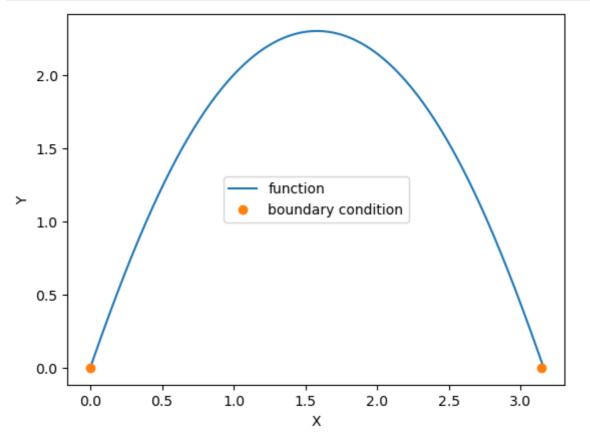
```
y1 += y2 * h
    y0 += y1 * h
    x_start += h

return x_range, y_range

def dif(x, y) :
    return -1 * (sin(y) + 1)

h = 0.01
y_dif = shooting(0, pi, h, [2.5, 3], [0, 0], func_calc=calc_yb, func_dif=dif, tol=1.0e-12)
x_range, y_range = range_func(0, pi, 0, y_dif, h, dif)

plt.plot(x_range, y_range, label="function")
plt.plot([0, pi], [0, 0], 'o', label="boundary condition")
plt.xlabel("X")
plt.ylabel("Y")
plt.legend()
plt.show()
```



Problem 2:

$$rac{d^4v}{dx^4}-rac{N}{EI}rac{d^2v}{dx^2}=rac{w_0}{EI}$$

with boundary condition

$$v_{(x=0)}=v_{(x=L)}=0,\;\;rac{d^2v}{dx^2}_{(x=0)}=rac{d^2v}{dx^2}_{(x=L)}=0$$

problem say eqaution can be shwon as,

$$\frac{d^4y}{d\xi^4} - \beta \frac{d^2y}{d\xi^2} = 1$$

with boundary condition

$$y_{(\xi=0)}=y_{(\xi=1)}=0,\;\;rac{d^2y}{d\xi^2}_{(\xi=0)}=rac{d^2y}{d\xi^2}_{(\xi=1)}=0$$

as

$$\xi=rac{x}{L},~~y=rac{EI}{w_0L^4}v,~~eta=rac{NL^2}{EI}$$

Let us use finite-difference method. We can rewrite equations.

$$rac{d^4y_i}{d\xi_i^4} = rac{y_{i-2} - 4y_{i-1} + 6y_i - 4y_{i+1} + y_{i+2}}{h^4} \ rac{d^2y_i}{d\xi_i^2} = rac{y_{i-1} - 2y_i + y_{i+1}}{h^2}$$

Therefore, equation can be shown as

$$rac{y_{i-2}-4y_{i-1}+6y_i-4y_{i+1}+y_{i+2}}{h^4}-etarac{y_{i-1}-2y_i+y_{i+1}}{h^2}=1$$
 $y_{i-2}-(4+h^2eta)y_{i-1}+(6+2h^2eta)y_i-(4+h^2eta)y_{i+1}+y_{i+2}=h^4$

Applying boundary condition $y_{i=0}=y_{i=m}=0,\ \ y_{i=0}^{(2)}=y_{i=m}^{(2)}=0$ $y_{i=0}=y_{i=m}=0$

$$y_0^{(2)} = rac{y_{-1} - 2y_0 + y_1}{h^2} = 0 o y_{-1} = y_1$$
 $y_m^{(2)} = rac{y_{m-1} - 2y_m + y_{m+1}}{h^2} = 0 o y_{m+1} = y_{m-1}$
 $i = 1 o y_{-1} - (4 + h^2 eta) y_0 + (6 + 2h^2 eta) y_1 - (4 + h^2 eta) y_2 + y_3 = h^4,$
 $i = 1 o - (4 + h^2 eta) y_0 + (7 + 2h^2 eta) y_1 - (4 + h^2 eta) y_2 + y_3 = h^4$
 $i = m - 1 o y_{m-3} - (4 + h^2 eta) y_{m-2} + (6 + 2h^2 eta) y_{m-1} - (4 + h^2 eta) y_m + y_{m+1} = h^4$
 $i = m - 1 o y_{m-3} - (4 + h^2 eta) y_{m-2} + (7 + 2h^2 eta) y_{m-1} - (4 + h^2 eta) y_m = h^4$

So the eqaution can be shown as

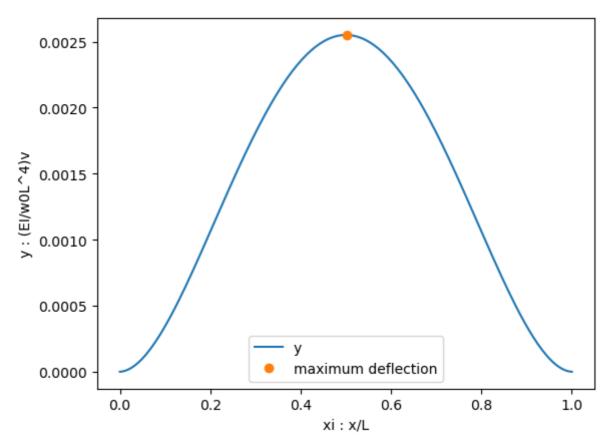
$$\left\{egin{aligned} &y_0=0,\;\;(i=0)\ -(4+h^2eta)y_0+(7+2h^2eta)y_1-(4+h^2eta)y_2+y_3=h^4,\;\;(i=1) \end{aligned}
ight.$$

```
y_{i-2} - (4 + h^2 \beta) y_{i-1} + (6 + 2h^2 \beta) y_i - (4 + h^2 \beta) y_{i+1} + y_{i+2} = h^4 \quad (i = 2, \dots m - 2)
\begin{cases} y_{m-3} - (4 + h^2 \beta) y_{m-2} + (7 + 2h^2 \beta) y_{m-1} - (4 + h^2 \beta) y_m = h^4, \quad (i = m - 1) \\ y_m = 0, \quad (i = m) \end{cases}
```

```
In [ ]: import numpy as np
          def gen_matrix(mesh_num, h, beta, bc) :
              A = (6 + 2 * h**2 * beta) * np.eye(N=mesh_num, k=0)
              A = (4 + h**2 * beta) * np.eye(N=mesh_num, k=1) 
                 + (4 + h**2 * beta) * np.eye(N=mesh_num, k=-1)
              A += np.eye(N=mesh_num, k=2) + np.eye(N=mesh_num, k=-2)
              B = np.zeros(shape=(mesh_num), dtype=float) + h**4
              A[0,:] = 0
              A[-1,:] = 0
              A[0,0], A[-1,-1] = 1, 1
              B[0], B[-1] = bc[0], bc[1]
              return A, B
          def finite_dif_fourth(x_start, x_end, mesh_num, beta, bc) :
              x_range = np.linspace(x_start, x_end, mesh_num)
              h = x_range[1] - x_range[0]
              A, B = gen_matrix(mesh_num, h, beta, bc)
              return x_range, np.linalg.solve(A, B)
```

2 - (a)

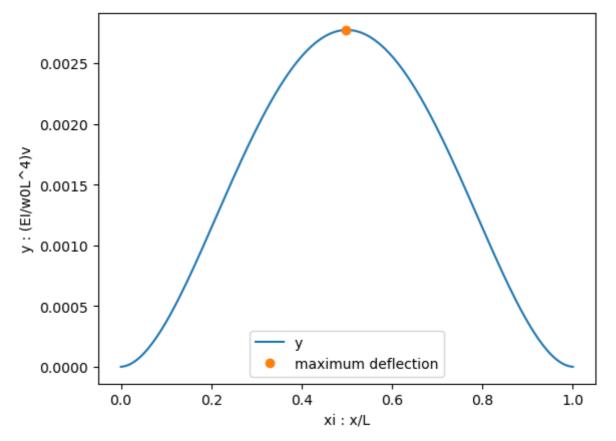
```
In [ ]: import matplotlib.pyplot as plt
          mesh num = 200
          beta = 1.6529
          bc = [0, 0]
          x_range, y_range = finite_dif_fourth(0, 1, mesh_num, beta, bc)
          max_index = np.where(y_range == y_range.max())
          plt.plot(x_range, y_range, label="y")
          plt.plot(x_range[max_index], y_range[max_index], 'o', label="maximum deflection")
          plt.xlabel("xi : x/L")
          plt.ylabel("y : (EI/w0L^4)v")
          plt.legend()
          plt.show()
          print("Since other variables like EI, N, L were not given,")
          print("we can only plot numerically via XI and Y dimension.")
          print("Maximum deflection of y : [{:.5f}]".format(*y_range[max_index]))
          print("At xi : [{:.5f}]".format(*x_range[max_index]))
```



Since other variables like EI, N, L were not given, we can only plot numerically via XI and Y dimension. Maximum deflection of y:[0.00255] At xi:[0.50251]

2 - (b)

```
In [ ]: import matplotlib.pyplot as plt
          mesh_num = 200
          beta = -1.6529
          bc = [0, 0]
          x_range, y_range = finite_dif_fourth(0, 1, mesh_num, beta, bc)
          max_index = np.where(y_range == y_range.max())
          plt.plot(x_range, y_range, label="y")
          plt.plot(x_range[max_index], y_range[max_index], 'o', label="maximum deflection")
          plt.xlabel("xi : x/L")
          plt.ylabel("y : (EI/w0L^4)v")
          plt.legend()
          plt.show()
          print("Since other variables like EI, N, L were not given,")
          print("we can only plot numerically via XI and Y dimension.")
          print("Maximum deflection of y : [{:.5f}]".format(*y_range[max_index]))
          print("At xi : [{:.5f}]".format(*x_range[max_index]))
```



Since other variables like EI, N, L were not given, we can only plot numerically via XI and Y dimension. Maximum deflection of y:[0.00277] At xi:[0.49749]

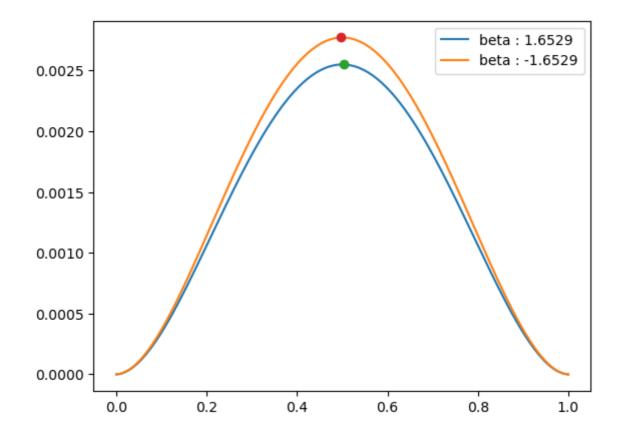
```
In []: # comparing both plot

mesh_num = 200
beta = [1.6529, -1.6529]
bc = [0, 0]

x1_range, y1_range = finite_dif_fourth(0, 1, mesh_num, beta[0], bc)
x2_range, y2_range = finite_dif_fourth(0, 1, mesh_num, beta[1], bc)

max_index1 = np.where(y1_range == y1_range.max())
max_index2 = np.where(y2_range == y2_range.max())

plt.plot(x1_range, y1_range, label="beta : {}".format(beta[0]))
plt.plot(x2_range, y2_range, label="beta : {}".format(beta[1]))
plt.plot(x1_range[max_index1], y1_range[max_index1], 'o')
plt.plot(x2_range[max_index2], y2_range[max_index2], 'o')
plt.legend()
plt.show()
```



problem 3:

$$-rac{d^2\psi}{d\xi^2}=(\xi^2-E_n')\psi$$

where

$$\xi=\sqrt{rac{mw}{\hbar}}x,~~E_n'=rac{2E_n}{\hbar w}=2n+1,~~n=0,1,2\ldots$$

with boundary condition : $\psi o 0$ when $x o \pm \infty$

$$rac{d^2y_i}{d\xi_i^2} = rac{y_{i-1} - 2y_i + y_{i+1}}{h^2}$$

$$-rac{\psi_{i-1}-2\psi_i+\psi_{i+1}}{h^2}=(\xi^2-2n-1)\psi_i$$

$$\psi_{i-1} - (2 - h^2(\xi^2 - 2n - 1))\psi_i + \psi_{i+1} = 0$$

```
In []: a = -10
b = 10
N = 100
x = np.linspace(a,b,N)
h = x[1]-x[0]
T = np.zeros((N-2)**2).reshape(N-2,N-2)
for i in range(N-2):
    for j in range(N-2):
```

```
if i==j:
            T[i,j] = -2
        elif np.abs(i-j)==1:
            T[i,j]=1
        else:
            T[i,j]=0
V = np.zeros((N-2)**2).reshape(N-2,N-2)
for i in range(N-2):
    for j in range(N-2):
        if i==j:
            V[i,j] = x[i+1]**2
        else:
            V[i,j]=0
H = -T/(2*h**2) + V
val,vec=np.linalg.eig(H)
z = np.argsort(val)
z = z[0:5]
energies=(val[z]/val[z][0])
for i in range(len(z)):
    y = []
    y = np.append(y,vec[:,z[i]])
    y = np.append(y,0)
    y = np.insert(y,0,0)
    plt.plot(x,y,lw=3, label="n = {}".format(i))
    plt.xlabel('x', size=14)
    plt.ylabel('$\psi$(x)',size=14)
plt.legend()
plt.title(
    'normalized wavefunctions for a harmonic oscillator using finite difference method',
plt.show()
```

normalized wavefunctions for a harmonic oscillator using finite difference method

