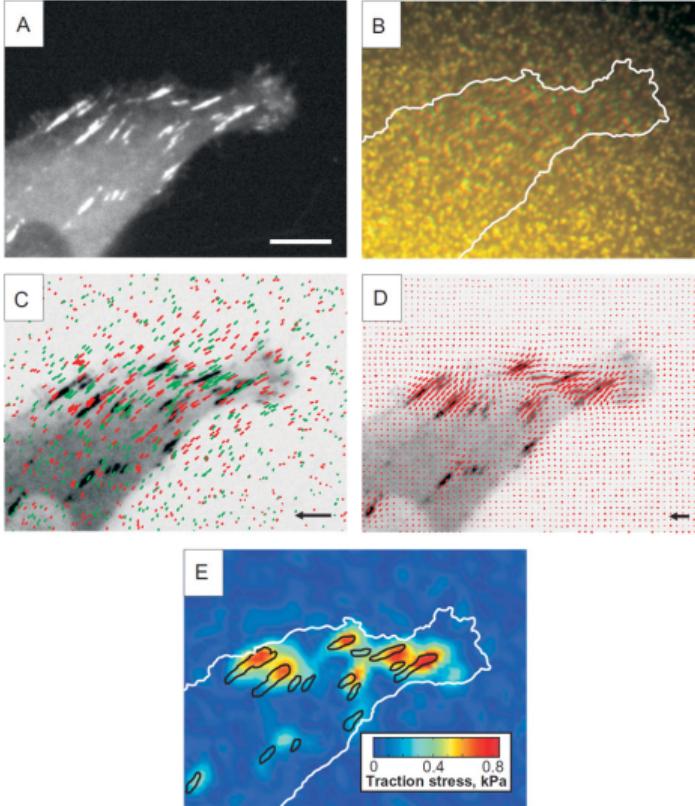


# Reconstruction of localized force distributions in cells and tissues from substrate displacements using physically-consistent regularization

Joshua C. Chang (NIH), Yanli Liu (UCLA), Tom Chou (UCLA)

APS March Meeting 2017  
Session S5: Machine Learning for Modeling and Control of Biological Systems I

# Traction force microscopy



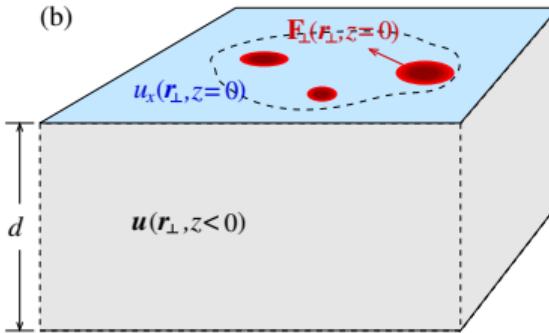
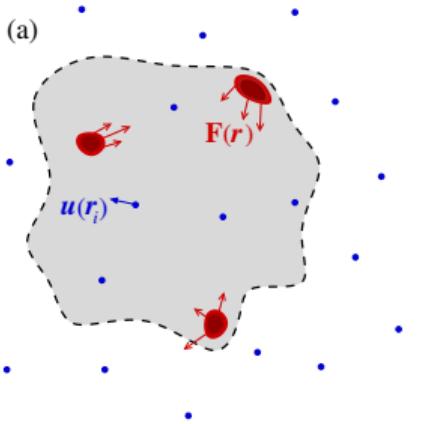
Imaging focal cell adhesions by tracking the displacement of fluorescent markers placed within a medium

- A Confocal image of human breast adenocarcinoma cell
- B Position of fluorescent beads
- C Displacement field for beads
- D Stress field
- E Stress magnitude

**Goal:** Determine tangential traction stress at the surface of medium

Plotnikov et. al. Methods Cell Biol. 2014

# Linear elasticity theory for displacements $\mathbf{u}$



- $\sigma$  is tangential surface stress tensor, proportional to the  $\mathbf{F}_\perp$
- $\mathbf{u}$  found “exactly” in closed-form for any fixed piecewise-polynomial approximation of  $\sigma$

In-plane surface displacements, as  $d \rightarrow \infty$ , where  $G \propto (Er)^{-1}$

$$u_x(x, y) = \int_{\Omega} dx' dy' G_{xx}(x - x', y - y') \sigma_{xz}(x', y') + \int_{\Omega} dx' dy' G_{xy}(x - x', y - y') \sigma_{yz}(x', y')$$

$$u_y(x, y) = \int_{\Omega} dx' dy' G_{yx}(x - x', y - y') \sigma_{xz}(x', y') + \int_{\Omega} dx' dy' G_{yy}(x - x', y - y') \sigma_{yz}(x', y')$$

# Discretized forward problem

## Linear algebra system

- $\sigma$  interpolated about points  $\mathbf{s}_i$  (using polynomials)
- Solution exact up to order of interpolation of  $\sigma_i$

$$\underbrace{\begin{pmatrix} u_x(\mathbf{r}_1) \\ u_x(\mathbf{r}_2) \\ \vdots \\ u_x(\mathbf{r}_N) \\ u_y(\mathbf{r}_1) \\ u_y(\mathbf{r}_2) \\ \vdots \\ u_y(\mathbf{r}_N) \end{pmatrix}}_{2N \times 1} = \underbrace{\begin{pmatrix} \mathbb{G}_{xx} & \mathbb{G}_{xy} \\ \mathbb{G}_{yx} & \mathbb{G}_{yy} \end{pmatrix}}_{\mathbb{G}} \underbrace{\begin{pmatrix} \sigma_{xz}(\mathbf{s}_1) \\ \sigma_{xz}(\mathbf{s}_2) \\ \vdots \\ \sigma_{xz}(\mathbf{s}_M) \\ \sigma_{yz}(\mathbf{s}_1) \\ \sigma_{yz}(\mathbf{s}_2) \\ \vdots \\ \sigma_{yz}(\mathbf{s}_M) \end{pmatrix}}_{2M \times 1}$$

- $\{\mathbf{r}_i\}_{i=1}^N$  locations at which measurements are taken
- $\{\mathbf{s}_i\}_{i=1}^M$  locations controlling interpolation of  $\sigma$
- $\mathbb{G}$  composed of grid-cell moments of the Greens function
- $\mathbb{G}$  depends on the interpolation order of  $\sigma$

# Using the physics to help constrain the inverse problem

## Reasonable physical assumptions

- ① No force outside the cell footprint
- ② No inertia (forces and torques each sum to zero)

## Advantage gained

- ① Reduction in problem size
  - ▶ Throw away far data points
- ② Multipole expansion  $\Rightarrow$  decay at rate  $r^{-2}$ 
  - ▶ Cutoff data by distance
  - ▶ Sparsify the matrix  $\mathbb{G}$

## Still need to regularize the inverse problem

### Criteria for a well-posed problem

- Solution exists
- Solution unique
- Solution continuous w.r.t. data

$$\hat{\boldsymbol{\sigma}} = \arg \min_{\boldsymbol{\sigma}} \left[ \underbrace{||\mathbf{u} - \mathbb{G}\boldsymbol{\sigma}||_2^2}_{\Phi_{\text{data}}} + \lambda \Phi_{\text{reg}}[\boldsymbol{\sigma}] \right]$$

# Respecting the physics in regularizing the inverse problem

- **Principle:** Coordinate system should not bias results
- **Solution:** Regularize using functionals of the tensor invariants

## Tensor invariants

$$\text{Tr}(\sigma) = \sigma_{xz} + \sigma_{yz}$$

$$\text{Det}(\sigma) = \sigma_{xz}\sigma_{yz}$$

## Invariant regularization functionals $\Phi_{\text{reg}}$

$$\Phi_{L^1(\text{Tr})} = \int_{\Omega} |\sigma_{xz}(x, y) + \sigma_{yz}(x, y)| dx dy$$

$$\Phi_{TV(\text{Tr})} = \int_{\Omega} |\nabla(\sigma_{xz}(x, y) + \sigma_{yz}(x, y))| dx dy.$$

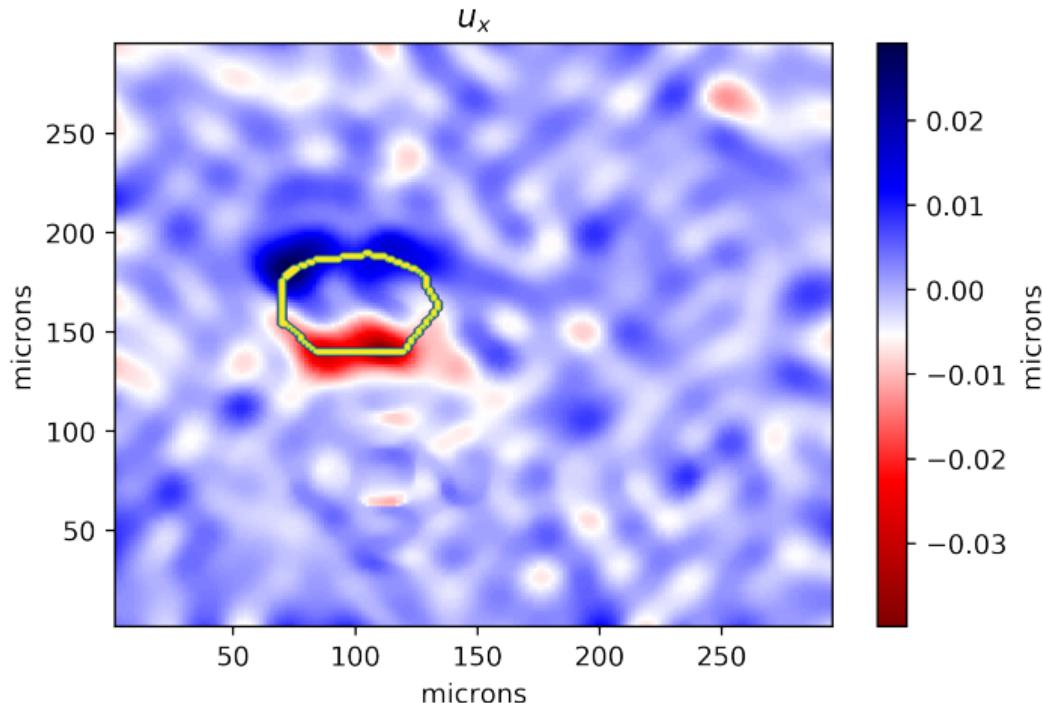
## Non-invariant functionals $\Phi_{\text{reg}}$

$$\Phi_{L1} = \int_{\Omega} (|\sigma_{xz}(x, y)| + |\sigma_{yz}(x, y)|) d\mathbf{x},$$

$$\Phi_{TV_1} = \int_{\Omega} (|\nabla \sigma_{xz}(x, y)| + |\nabla \sigma_{yz}(x, y)|) d\mathbf{x} \quad \Phi_{TV_2} = \int_{\Omega} (|\partial_x \sigma_{xz}| + |\partial_y \sigma_{xz}| + |\partial_x \sigma_{yz}| + |\partial_y \sigma_{yz}|) d\mathbf{x}$$

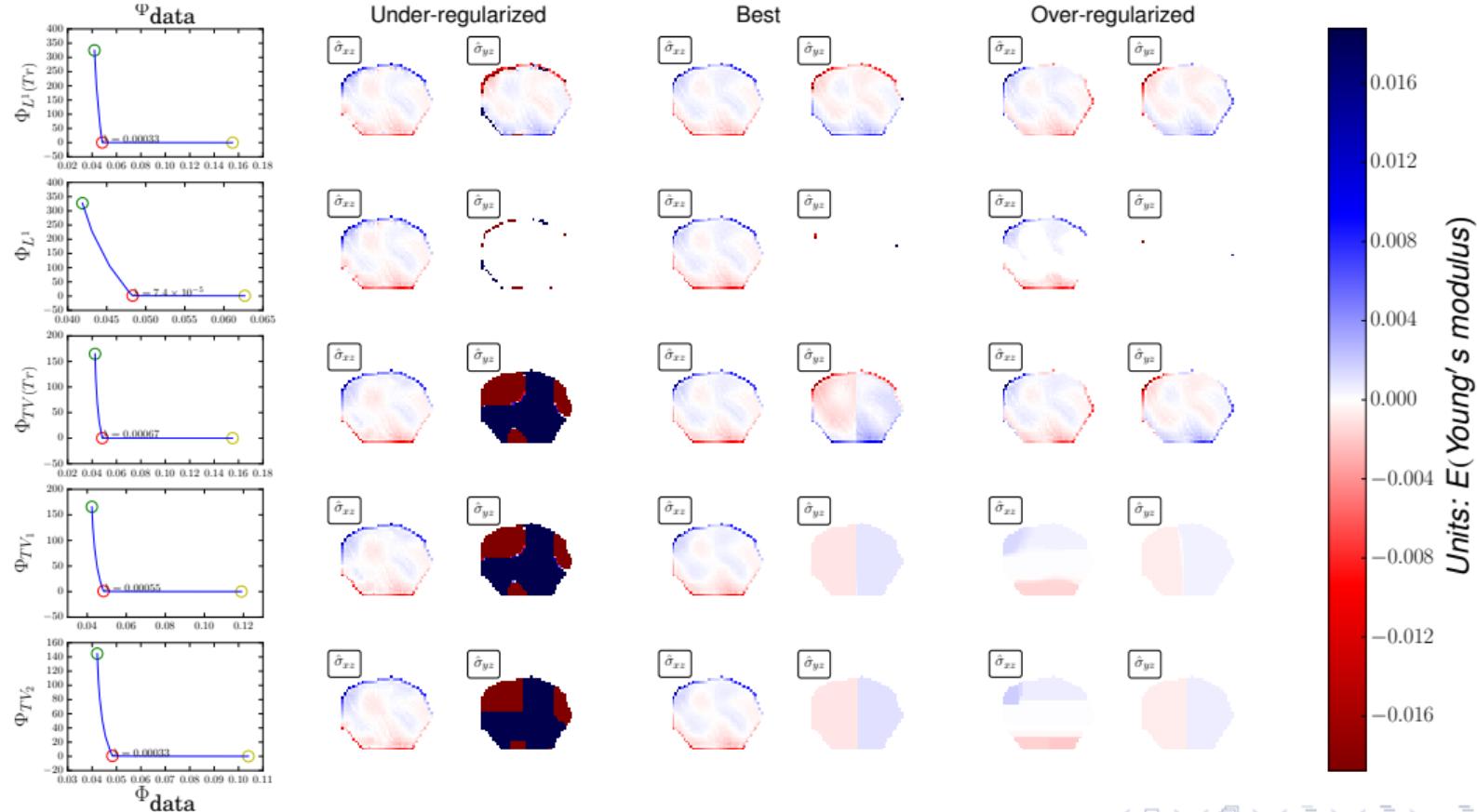
# High-resolution data

- Mesenchymal stem cell
- Polyacrylamide hydrogels
- Fluorescent beads in a regular grid
- High-resolution measurement of displacement field
- Cell boundary estimated from raw bright-field image (superimposed)

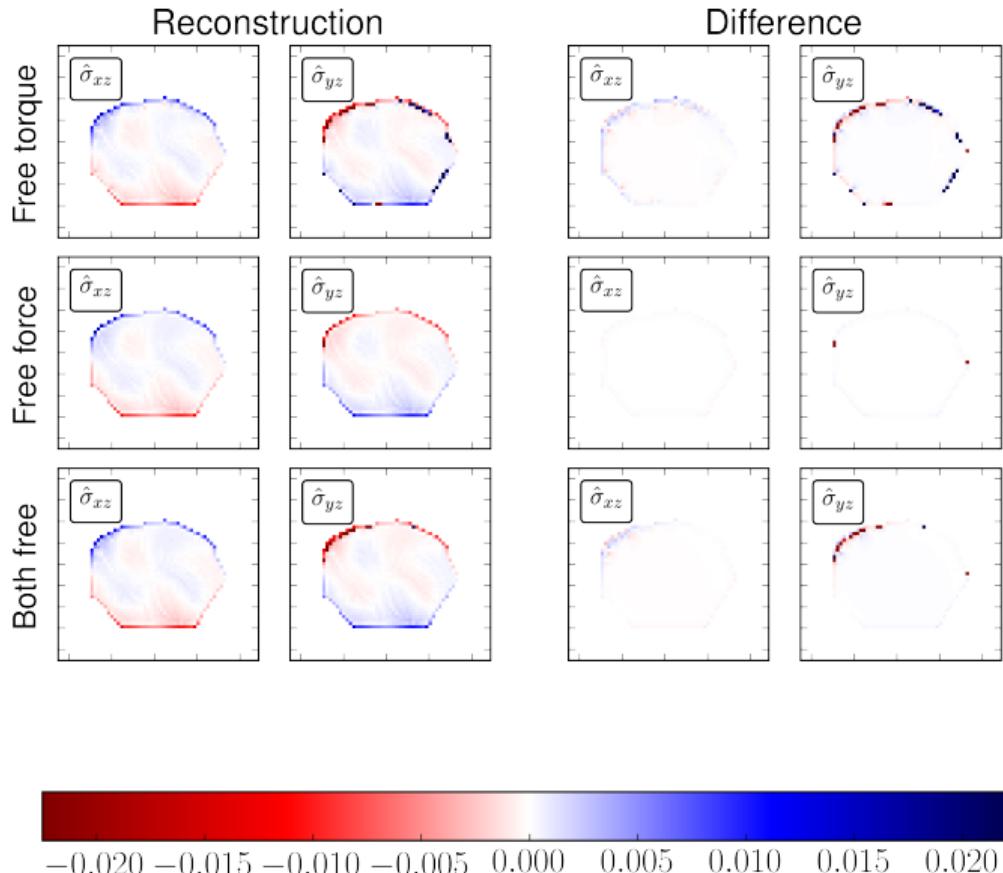


*Courtesy of Gabriel Popescu, UIUC*

# Rotational invariance matters

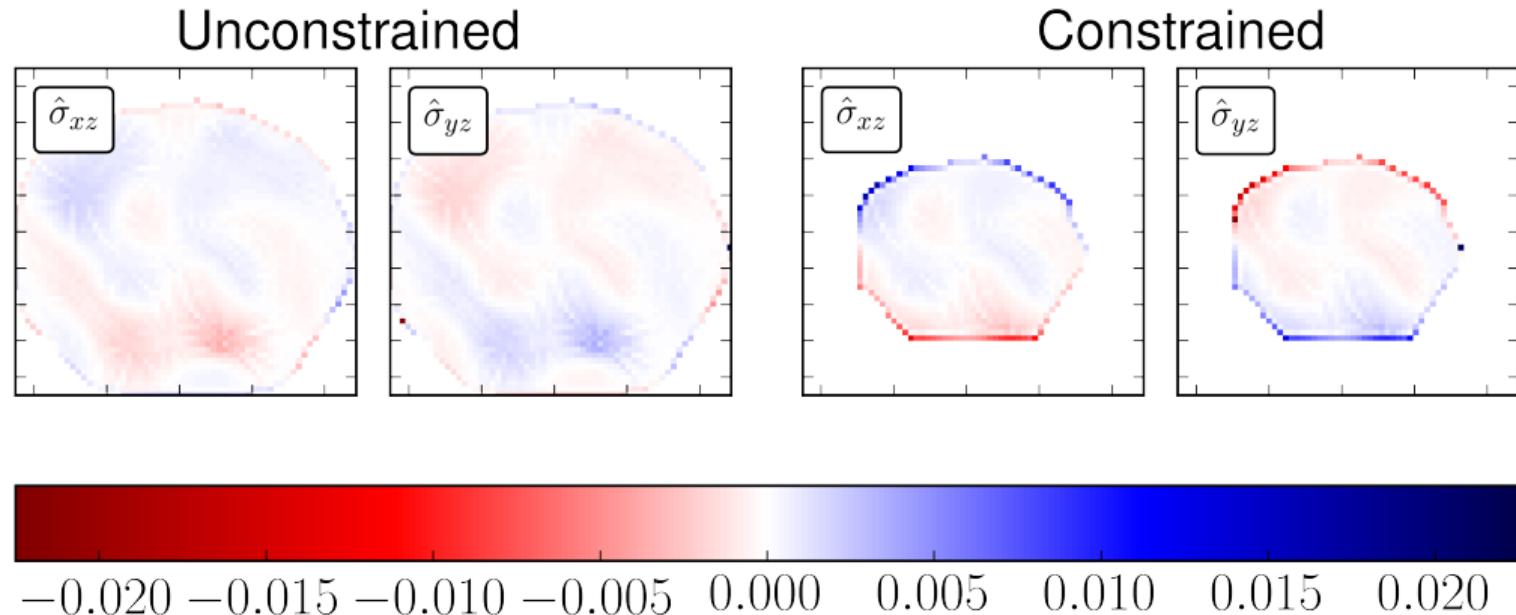


# Force constraints matter



- Reconstructions performed using  $L_1(Tr)$
- Difference compared to fully-constrained reconstruction
- Neither force nor torque cancel unless enforced explicitly

# The footprint constraint matters



- Force concentrated near edges of the cell
- Location of edges is important

# Summary and Future directions

- The regularization should be consistent with the known physics (as in a Bayesian prior)
- The numerical solution of the forward problem should be consistent with the regularization
- Localization of the cell footprint is important in determining traction
  - ▶ Extension: Joint force reconstruction and cell boundary determination
  - ▶ Extension: Uncertainty quantification through Bayes

*From the authors:* Joshua C. Chang (NIH), Yanli Liu (UCLA), Tom Chou (UCLA),  
Thank you!

*Funding:* NIH Intramural Research Program, ARO, NSF