STATERI HWI Changeleng Ji

Q1. It's generally a circle, while condeved next to the origin and getting sparse when moving far from origin.

Q2: Yes. consider point P(x,y,Z), the S.t. ||P-O||=r, r is given. The points P with the same r (i.e. $x+y+z^2$) with have same prob. to have the random point. Thus everything would look like a sphere.

HS- $\bar{E}_{XZ,2}$. |A|=0, it's impossible that all λ_i of A are positive. $\det(A)=\prod_{i=1}^n \lambda_i=0$ \iff , which is contradict to $\lambda_i>0$ $\forall i$. \square

HS-Ex2.3. $\lambda_i \neq 0$ Hi. $\det(A) = \prod \lambda_i \neq 0$. $\Rightarrow A$ is nonsignlar matrix. \Rightarrow Thus A is invertible, A^{-1} exists. \Box

Iz-Ex.320. (obsulate det(1) () of R=(p)

 $det(R) = \begin{vmatrix} 1 & \rho \\ \rho & 1 \end{vmatrix} = \begin{vmatrix} 1+h-1)\rho & \dots & 1+(n-1)\rho \\ \rho & 1 & \dots & 1-\rho \end{vmatrix} = (1+(n-1)\rho) \begin{vmatrix} 1 & 1 & \dots & 1-\rho \\ 0 & 1-\rho & \dots & 1-\rho \end{vmatrix} = (1-\rho)(1+(n-1)\rho)$

 $\mathcal{R}^{-1} = \left(\operatorname{diag}(1-P, \dots, 1-P) + \binom{P}{P} \cdot \prod_{j \neq n} \right)^{-1} = D^{-1} - \frac{1}{1+1!} \cdot D^{-1} \cdot P \cdot \prod \cdot D^{-1} \cdot D^{-1}$ $= \operatorname{diag}(1-P, \dots, 1-P) - \frac{1-P}{nP} \cdot \frac{P}{(1-P)^{2}} \cdot \prod_{n \times n} = (1-P) \cdot \prod - \frac{1}{n(1-P)} \cdot \overline{J}.$

Q-6 Set new matrix(va) $\begin{pmatrix} Y \\ Z \end{pmatrix} = \begin{pmatrix} AX \\ BX \end{pmatrix}$ $\begin{pmatrix} Cov(M) = \begin{pmatrix} A\Sigma A' & A\Sigma B' \\ B\Sigma A' & B\Sigma B' \end{pmatrix}$ 0 as. $Y \perp L Z$, $A \leq B' = 0$.

Q7. Set $Y = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix}$ $Z = \begin{pmatrix} X_3 \end{pmatrix}$. $X = \begin{pmatrix} Y \\ Z \end{pmatrix}$ in $N_P \begin{pmatrix} \begin{pmatrix} \mu_Y \\ \mu_Z \end{pmatrix}$, $\begin{pmatrix} Z_{YY} & Z_{YZ} \\ Z_{YY} & Z_{ZZ} \end{pmatrix}$ $Z_{YZ} = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}$. $\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \times \begin{pmatrix} (\mu_1 + \rho^2(X_2 - \mu_3)), \begin{pmatrix} 1 - \rho^4 \\ P \end{pmatrix} \end{pmatrix}$ $= \begin{pmatrix} (\mu_1 + \mu_2), (\mu_1 + \mu_2), (\mu_2 - \mu_3), (\mu_2 + \mu_2), (\mu_2 - \mu_3), (\mu_$

 $=\left(\begin{pmatrix} \mu_1+\rho^2(x_s-\mu_s)\\ \mu_2 \end{pmatrix},\begin{pmatrix} 1-\rho^4&\rho\\ \rho&1 \end{pmatrix}\right)=RHS\qquad \square.$

Stat 2221 Advanced Multivariate Analysis Spring 2024 Jason Fine

1. Härdle and Simar Exercise 1.19.

- 2. Härdle and Simar Exercise 1.20. (You may *imagine* the 3D point cloud, without actually rotating using a computer software.)
- 3. Härdle and Simar Exercise 2.2.
- 4. Härdle and Simar Exercise 2.3.
- 5. Izenman Exercise 3.20. Inverse and det of (A+uv')
- 6. Show that for $X \sim N_p(\mu, \Sigma)$, non-random matrices $A_{(q \times p)}$ and $B_{(r \times p)}$, Y = AX and Z = BX are independent if and only if $A\Sigma B = 0$.
- 7. Suppose $X = (X_1, X_2, X_3)'$ has mean $(\mu_1, \mu_2, \mu_3)'$ and covariance matrix

$$\Sigma = \begin{array}{ccc} 1 & \rho & \rho^2 \\ \rho & 1 & 0 \\ \rho^2 & 0 & 1 \end{array}.$$

Show that the conditional distribution of $(X_1, X_2)'$ given X_3 has mean $(\mu_1 + \rho^2(X_3 - \mu_3), \mu_2)'$ and covariance matrix

$$\begin{array}{ccc}
1 - \rho^4 & \rho \\
\rho & 1
\end{array}$$