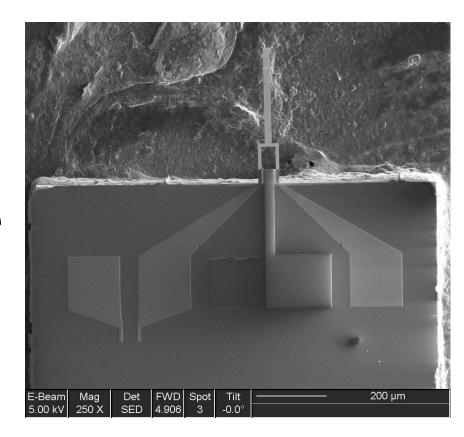
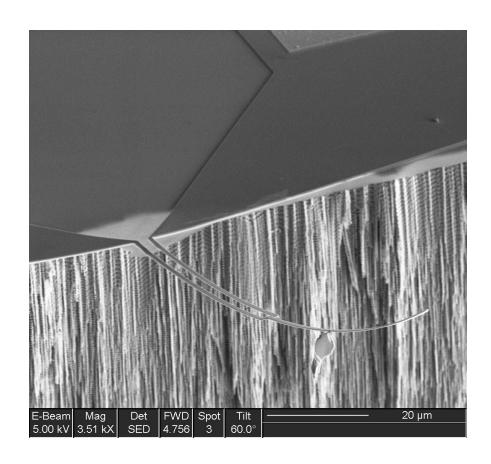
Research update: feedback control, device testing, and more

Joey Doll Group Meeting 11/4/2009

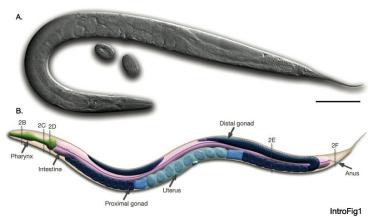


Today

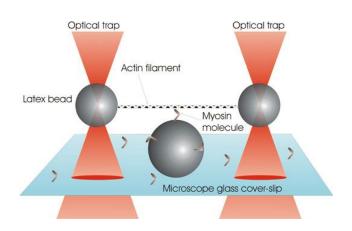
- Amplifier and feedback circuitry
- Combined PR+PE testing
- Cantilever bending stress



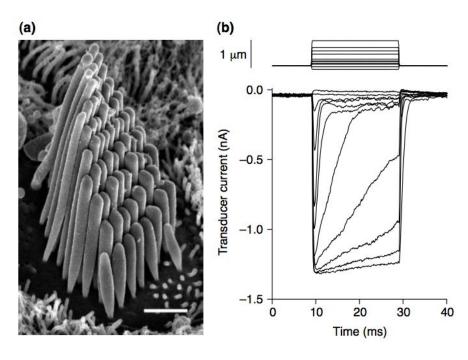
Motivation



Sense of touch (TRNs)



Protein conformational changes

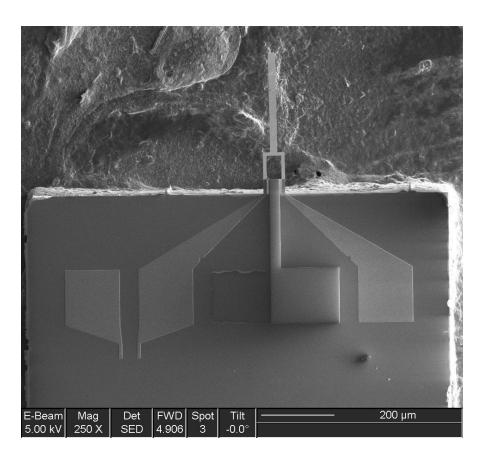


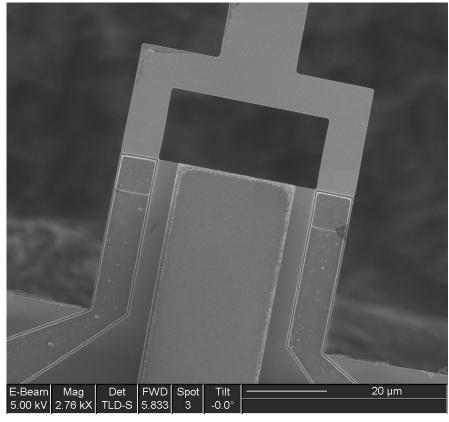
Sense of hearing (hair cells)

Performance Goals

- Rise time
 - 10 microseconds (turtle hair cell)
 - 1 microsecond (mammalian hair cell)
- Force resolution
 - 50 pN, 1 Hz 30 kHz (turtle)
 - 50 pN, 1 Hz 300 kHz (mammalian)
 - 30 pN, 1 Hz 10 kHz (TRN, single molecule)
- Closed loop force control
- Operation in fluid

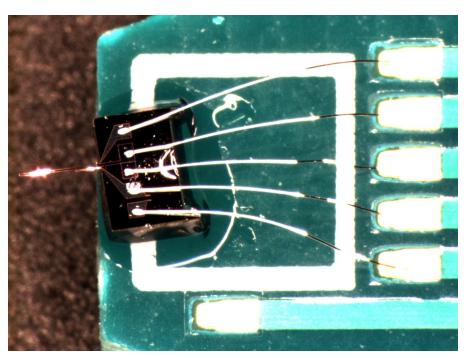
The Device

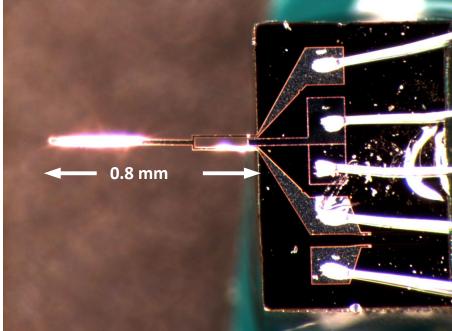




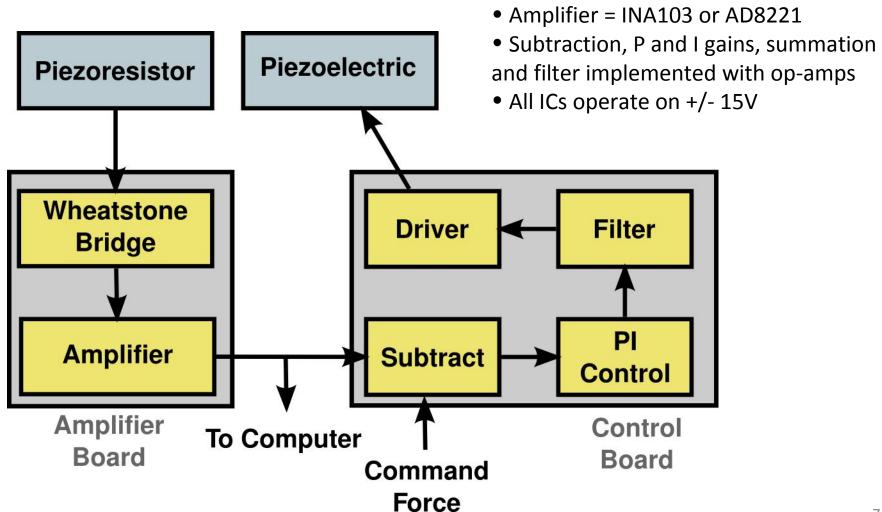
Piezoresistive force detection Piezoelectric actuation

The Device



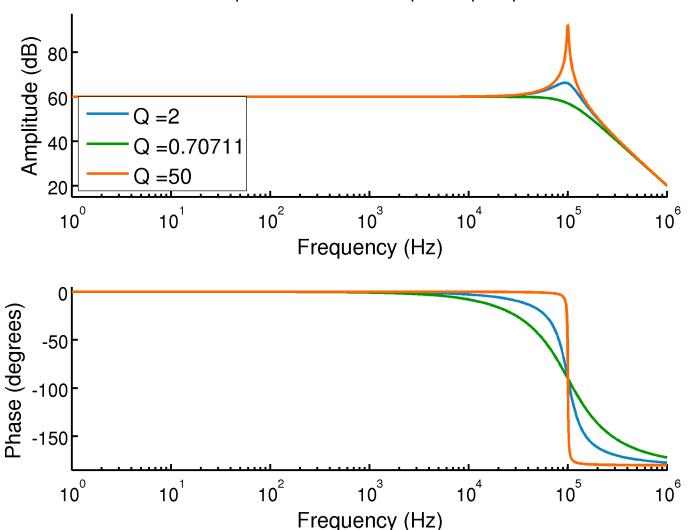


Feedback Circuit



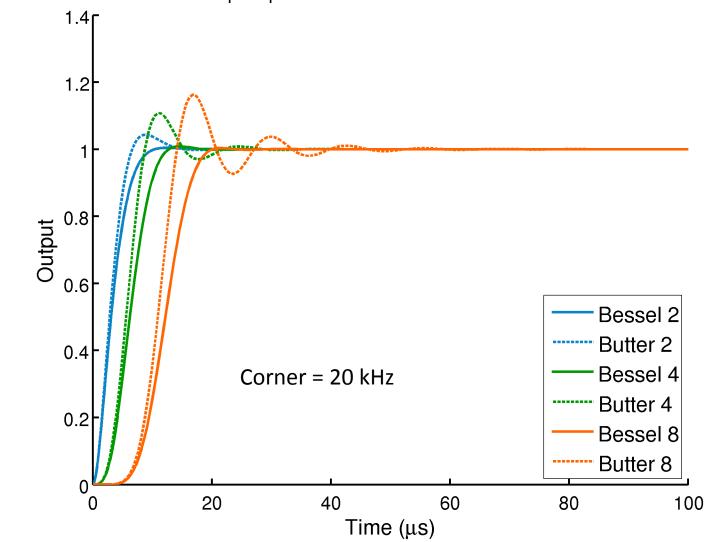
Feedback Modeling

Uncompensated cantilever open loop response



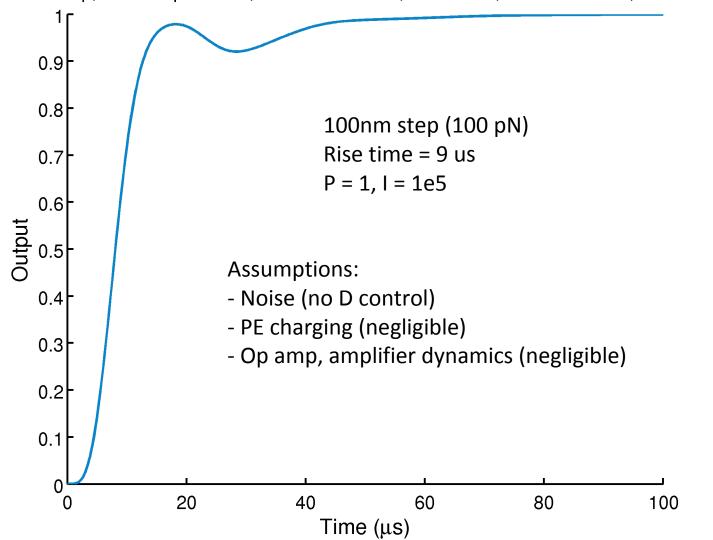
Feedback Modeling

Step response of bessel and butterworth filters

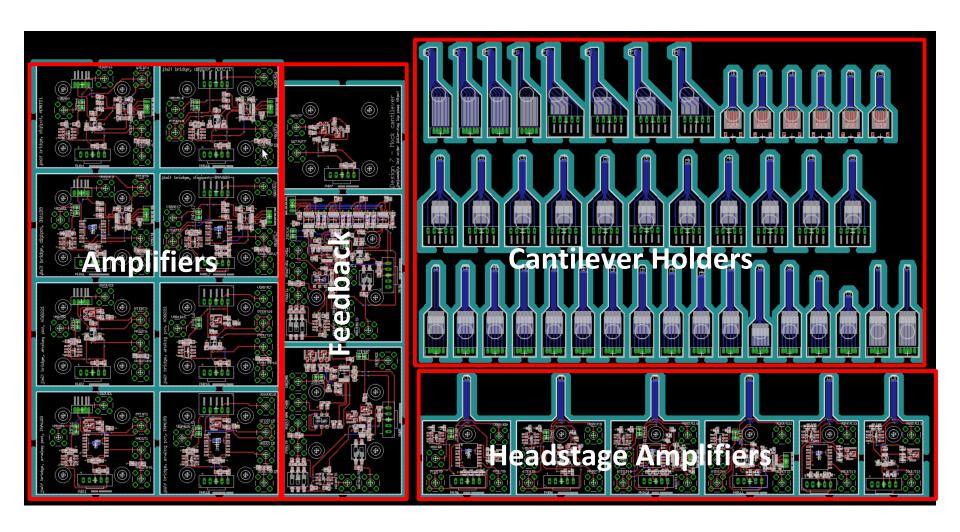


Feedback Modeling

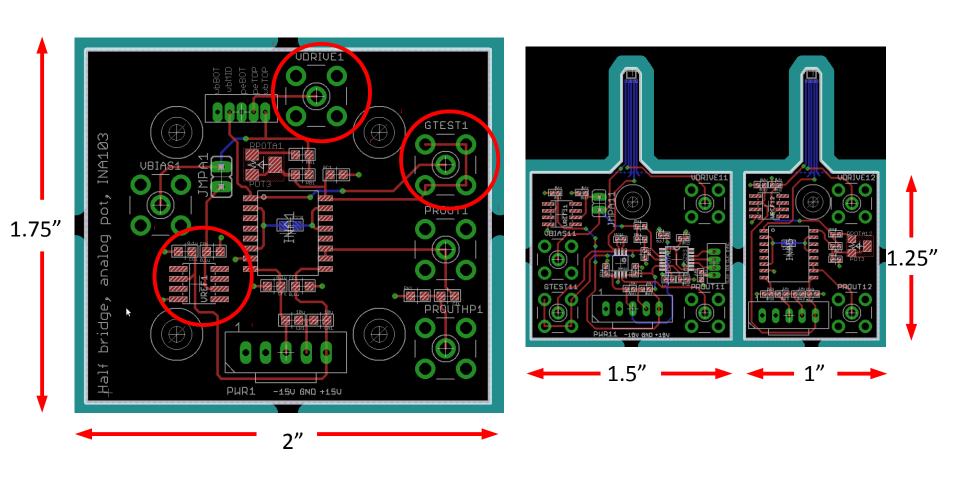
Closed loop, PID compensated, 2nd order Bessel, medium Q, lever = 100kHz, LP = 30kHz



PCB Layout

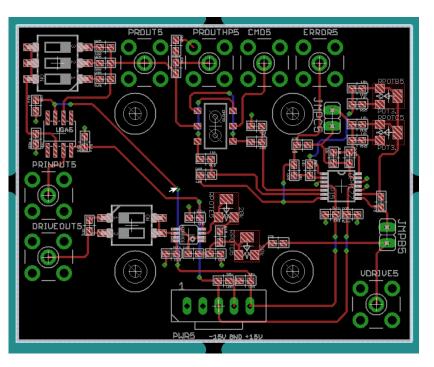


Circuits - Amplifiers

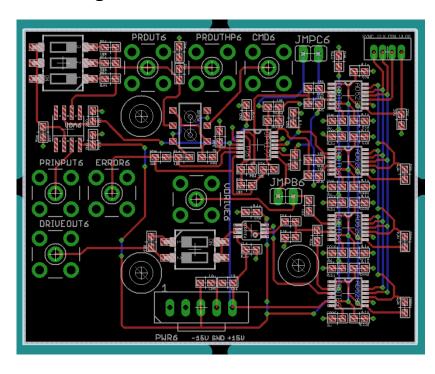


Circuits - Feedback

Analog Potentiometers

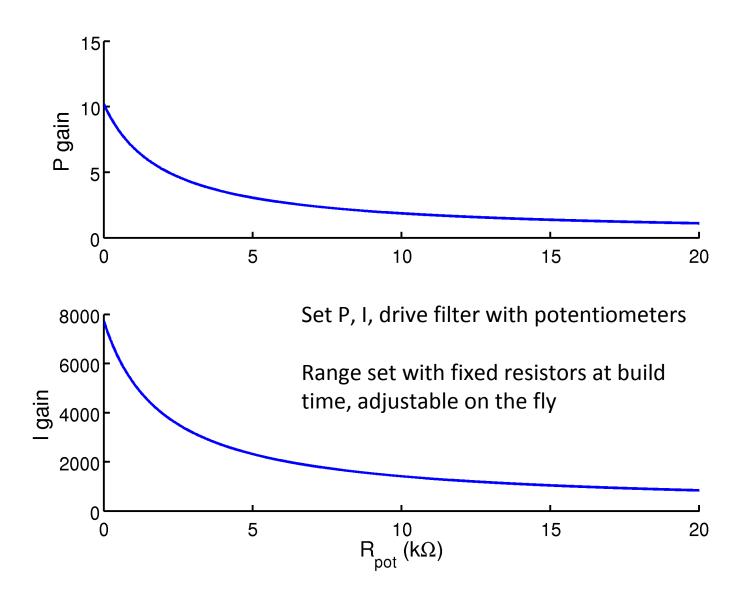


Digital Potentiometers

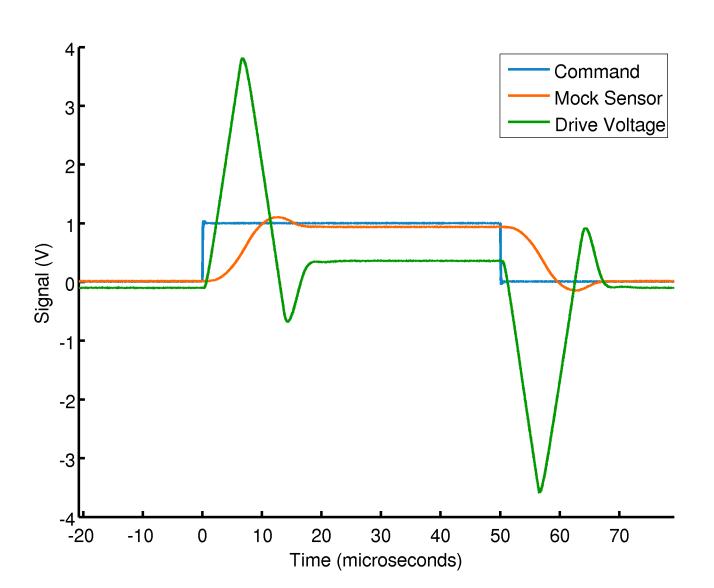


2.5"

Circuit Design



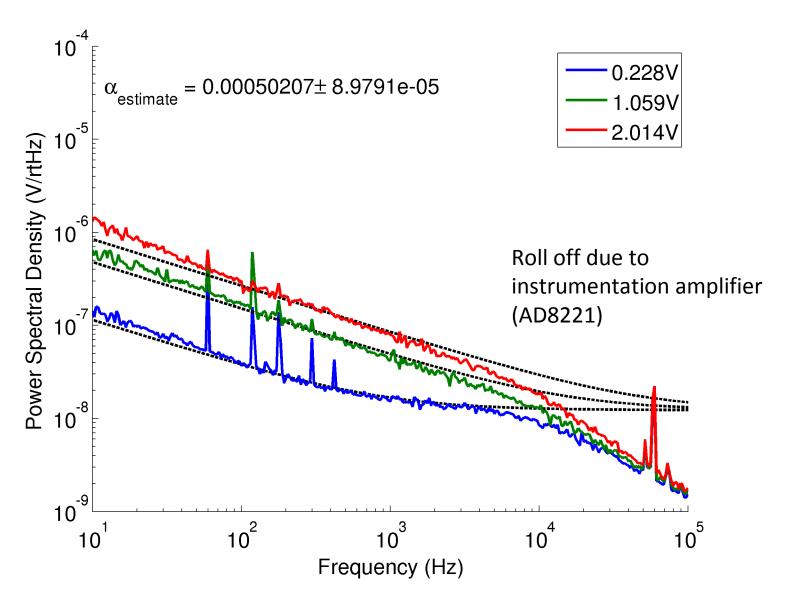
The circuit works



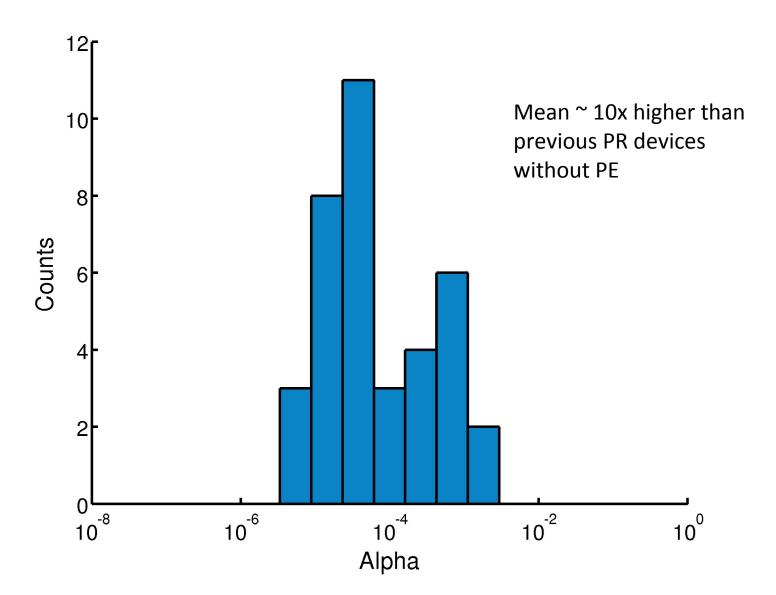
PR+PE Device Characterization

- Noise spectrum
- Piezoresistor resistance
- Electrical cross-talk
- Spring constant
- Force/displacement sensitivity
- Actuation distance

Noise spectra look good



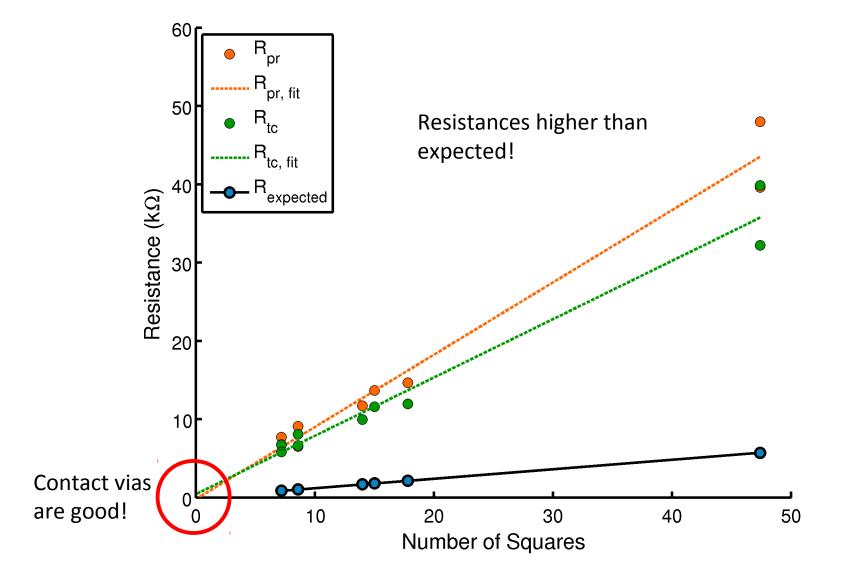
1/f noise higher than expected



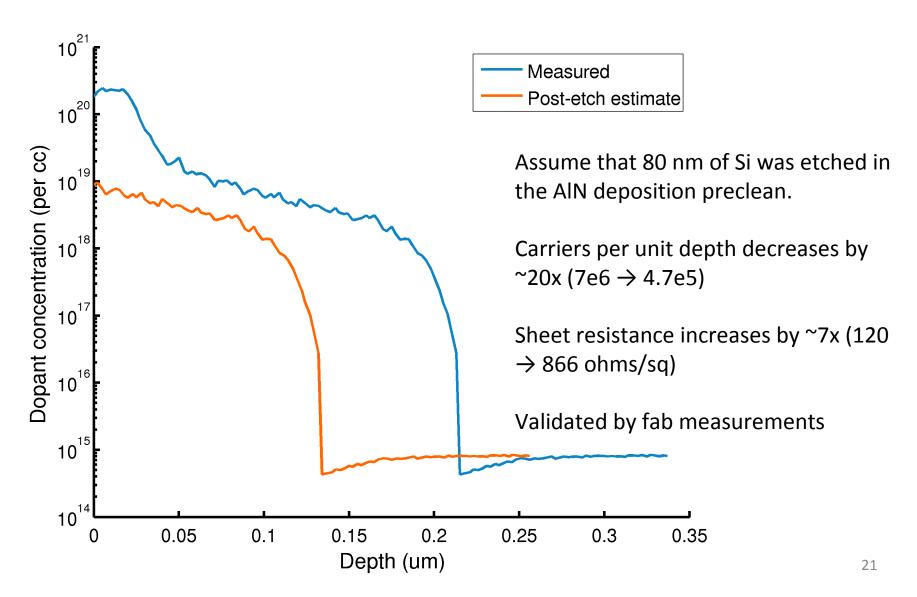
Two unknowns, one equation

- 1/f noise depends on alpha and the number of carriers
- Alpha could be higher or the number of carriers could be smaller
- Need an additional parameter for fitting

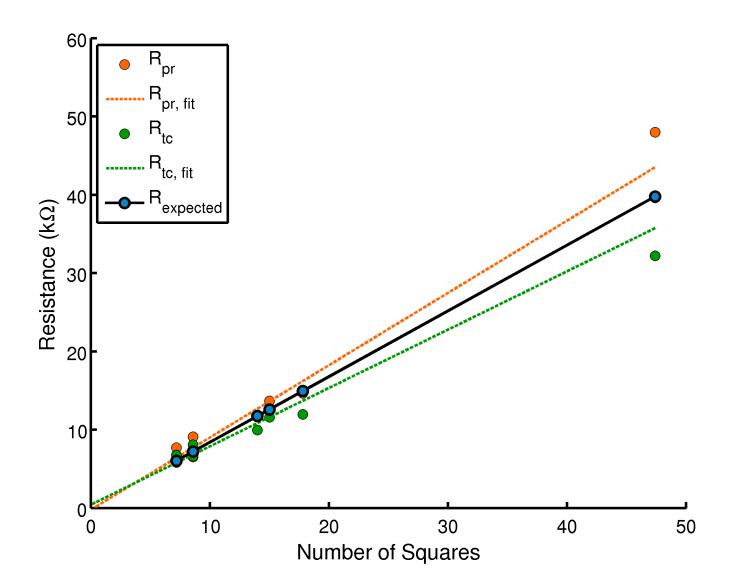
Piezoresistor resistance



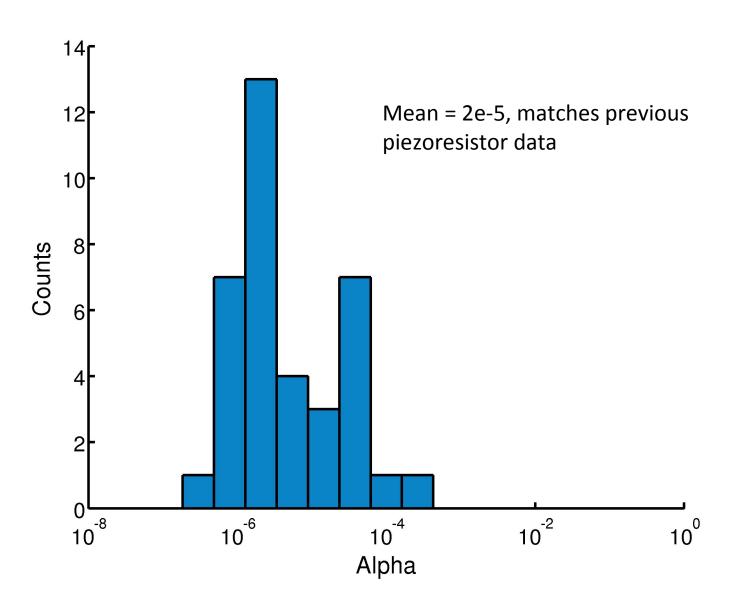
Accidental etching



Adjusted resistance model



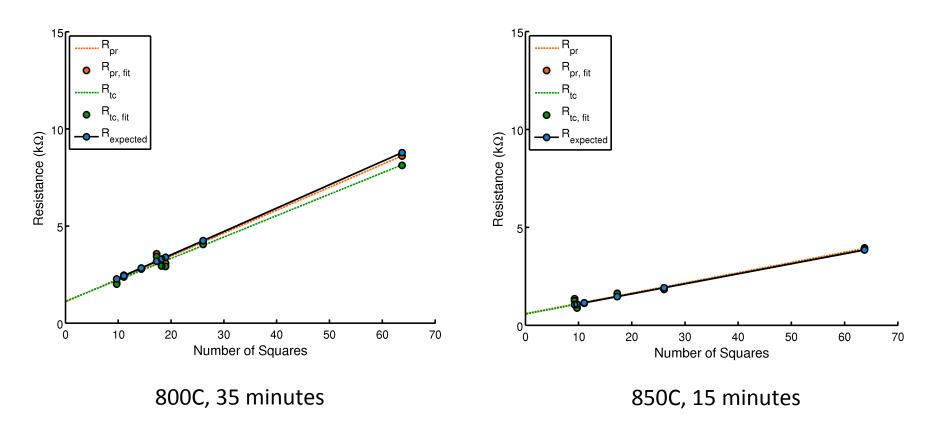
Alpha adjustment



Overall impact?

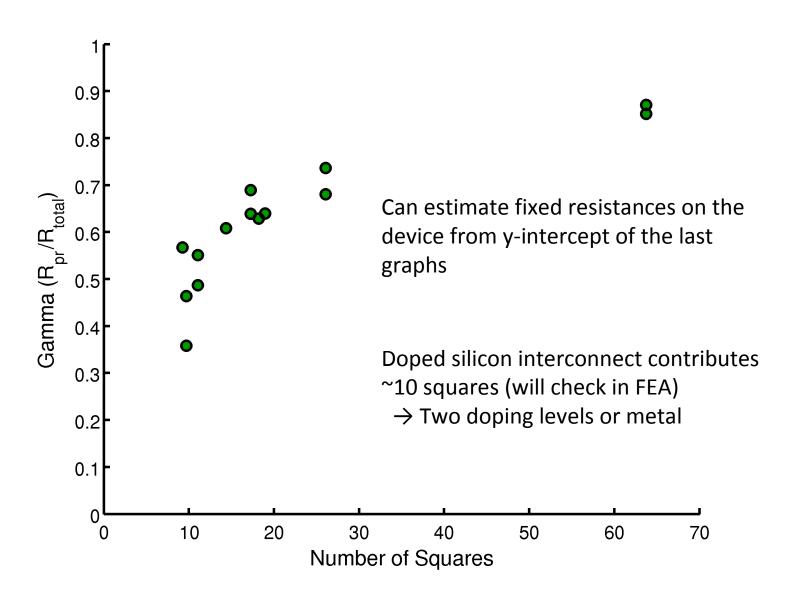
- Noise ~10x higher
 - Johnson noise 2.5x increase
 - 1/f noise 4x increase
- Sensitivity ~ 4x higher
 - Beta* 2x larger
 - Thickness 33% less
- Minimum detectable force increased by 2.5x, good enough for most applications

Resistance Analysis of PR Devices

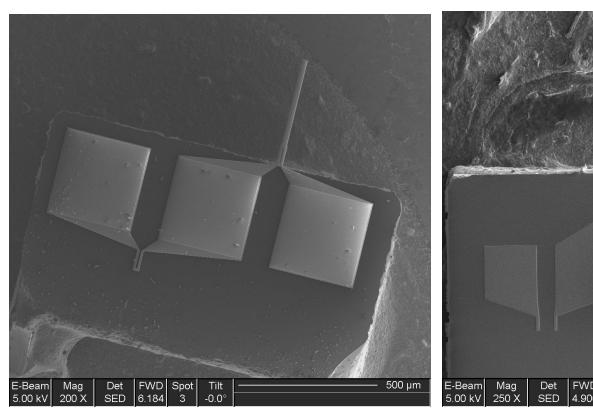


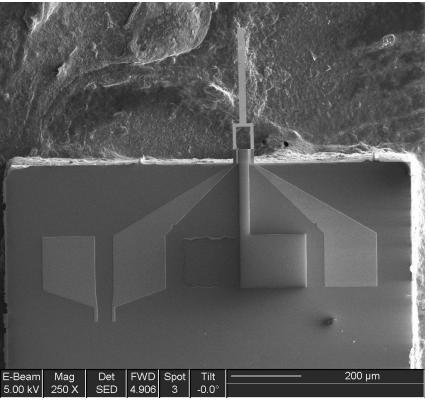
Assumed 100 nm undercut from litho/etch to improve fit (will measure)

Resistance Analysis of PR Devices



PR interconnects





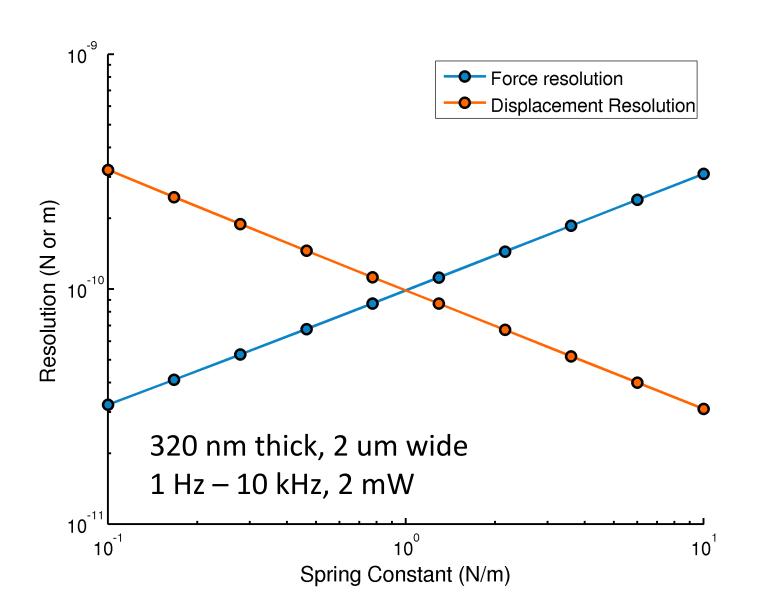
Doped Si interconnects

Al interconnects w/ 10-30 um square via

Sensitivity

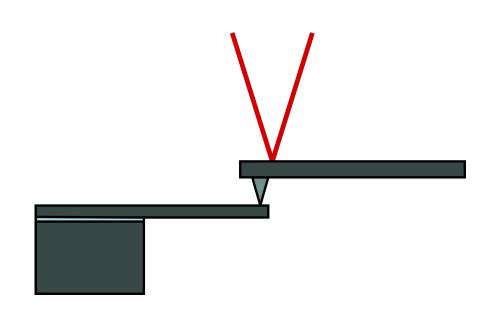
- Have had measurement issues
- Fixed PR output independent of wheatstone bridge bias voltage
- Devices optimized for high force sensitivity, low displacement sensitivity (i.e. long, soft levers)
- Piezoelectric shaker voltage couples to piezoresistor input (microvolts/nm)
- If displacement sensitivity isn't high enough, the PR signal is overwhelmed by the cross-talk signal

Force vs. Displacement Tradeoff



New Experiment Plan

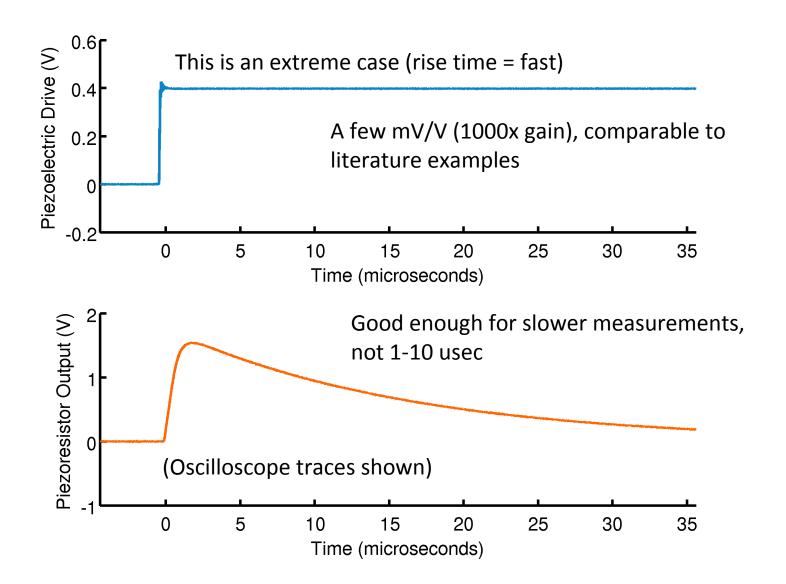
- AFM solves cross-talk problem
- But can't bounce the laser off of my devices
- Solution: mount the PR cantilever as a sample
- Can use for sensitivity, feedback



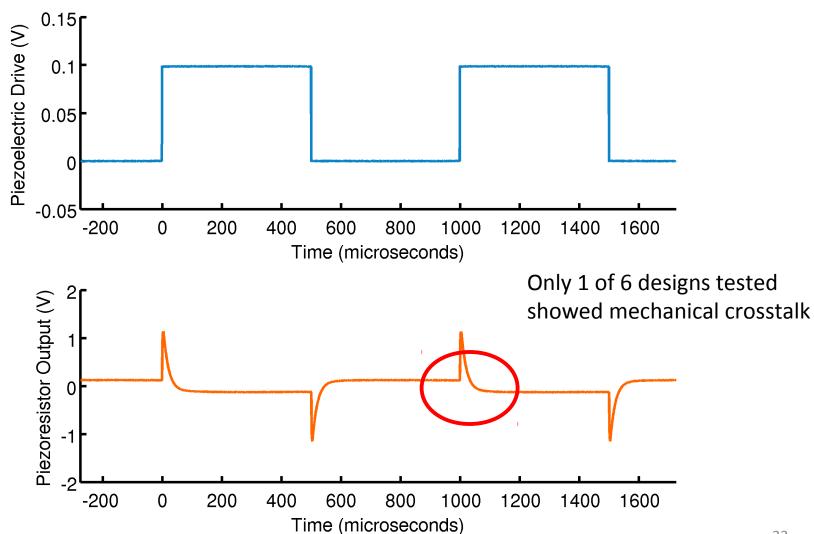
PE, PR Crosstalk

- Sensitivity and noise are great, but crosstalk could be the limiting factor
- Possible mechanisms
 - Capacitive: worse at higher frequencies, due to changing voltages in vicinity of each other
 - Mechanical: Piezoelectric bending changes piezoresistor resistance

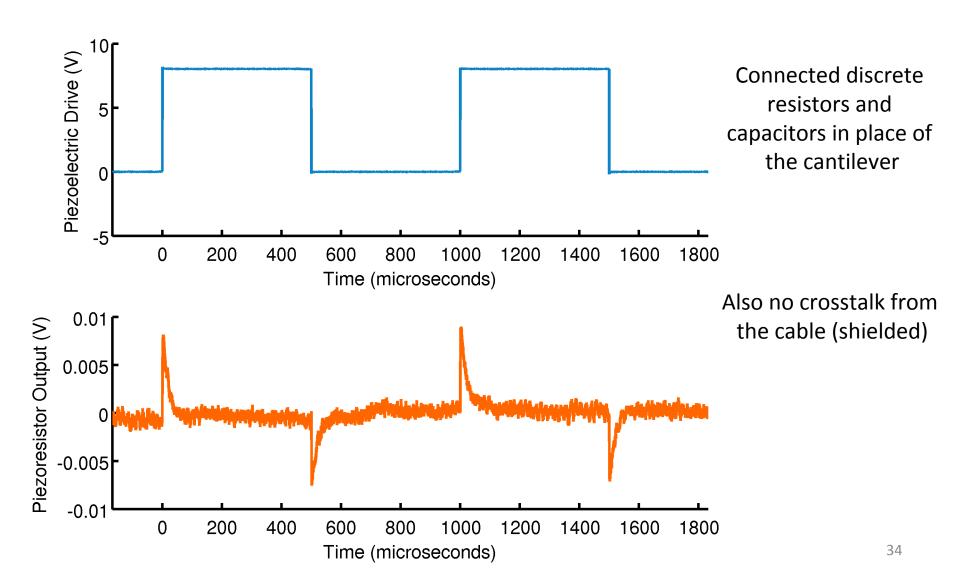
There is capacitive crosstalk



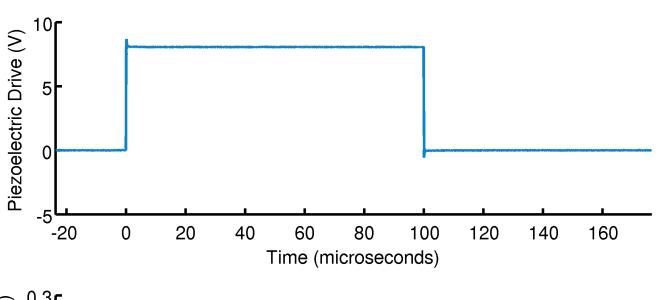
Some mechanical crosstalk



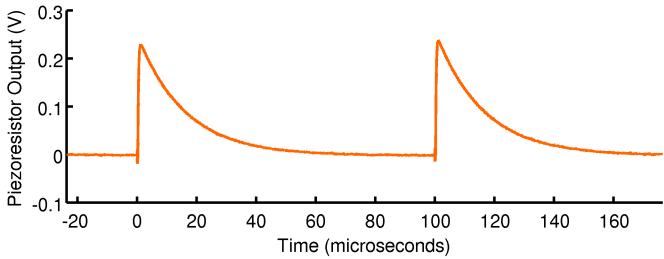
Minimal crosstalk from PCB



Some crosstalk from cantilever PCB



Connected cantilever PCB, shorted the bondpads by wirebonding



Crosstalk – What next?

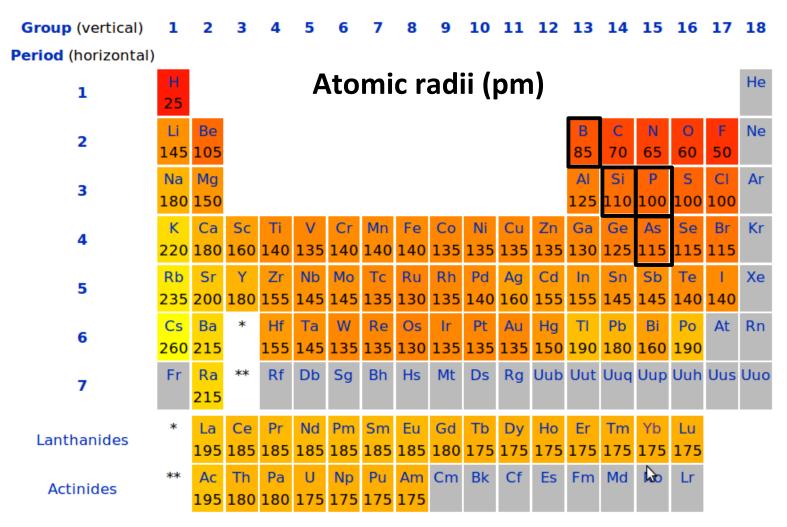
- Modeling required
- Affects highest speed measurements, not bad enough to stop system development
- Slower measurements (msec) fine
- Possible solution: compensation on silicon die by placing piezoelectric next to temperature compensation PR

Bending Stress

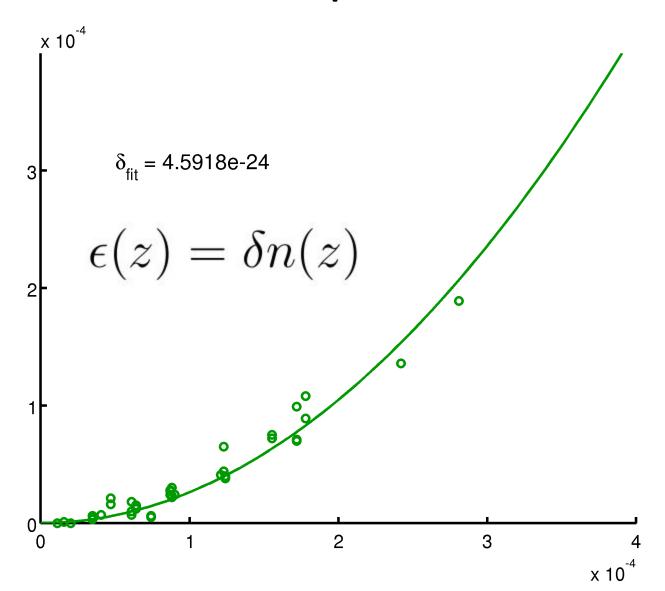
FWD Spot 4.756 3 20 µm E-Beam Mag 5.00 kV 3.51 kX Det SED Tilt 60.0°

Why?

How Big is an Atom?



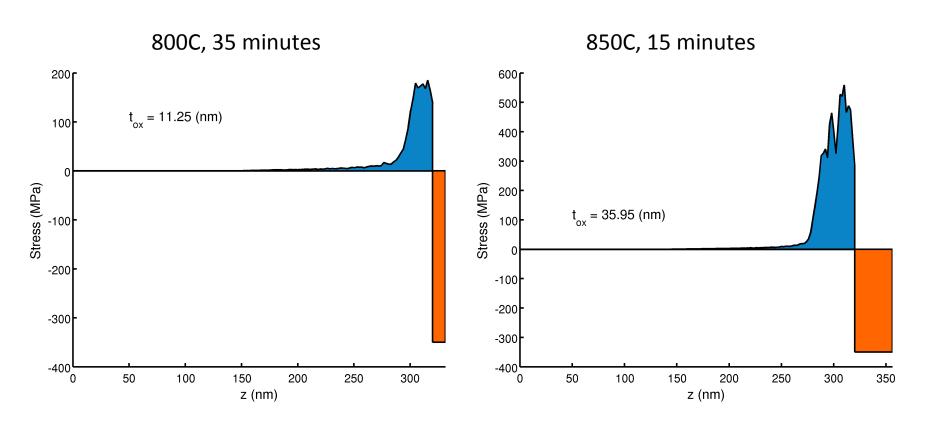
Cantilever Tip Deflection



Compensation Strategy

- Solution for tensile stress at the top surface
 - Tensile at the bottom
 - Compressive at the top
- SiO2 is ideal
 - E = 80 GPa
 - Stress = 350 MPa
- But how?
 - Thermal: Consumes Si, thermal budget (more diffusion)
 - LTO: Poor uniformity, time to deposit thin layers
 - PSG: Thickness control, unknown parameters
- How much oxide thickness?

Compensation Oxide

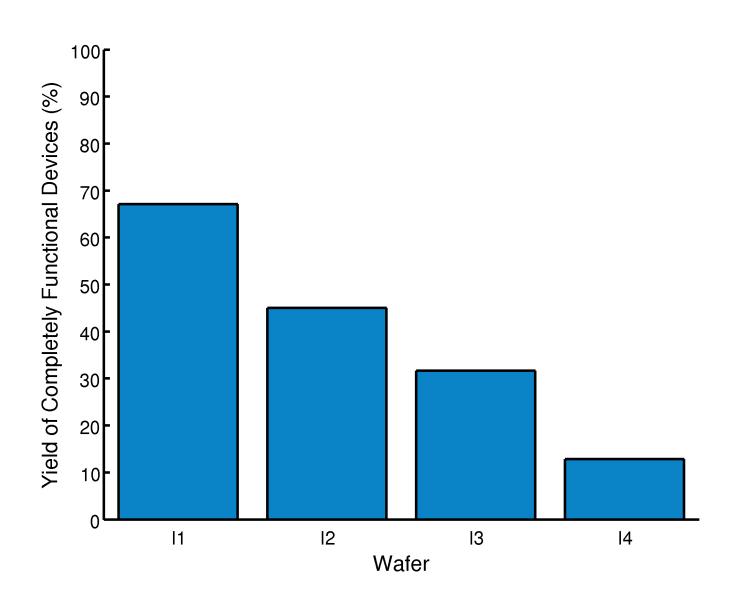


$$\sum M = \sum_{i} \int (z - \bar{z}) \sigma_i dA$$

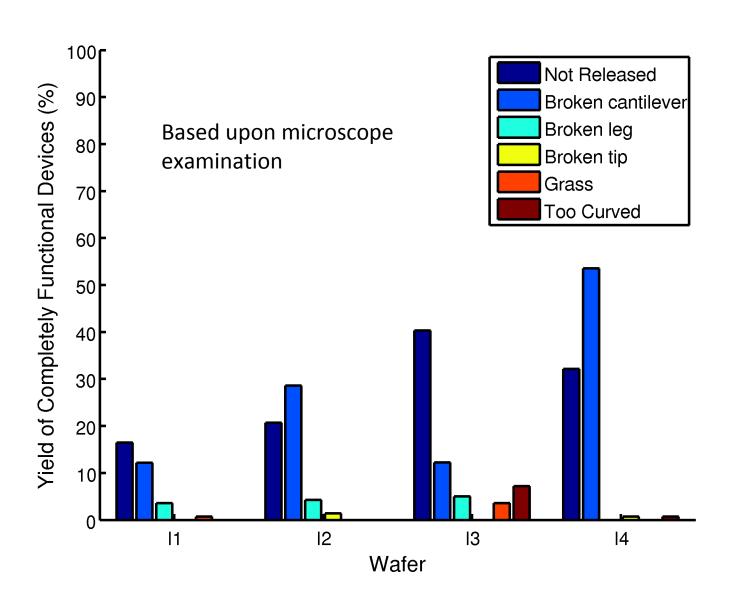
$$0 = w_{si} \int_0^{t_{si}} (z - \bar{z}) \sigma_{si}(z) dz + w_{oxide} \int_{t_{si}}^{t_{si} + t_{oxide}} (z - \bar{z}) \sigma_{oxide} dz$$

$$t_{oxide}^{2} \left(\frac{\sigma_{oxide}}{2}\right) + t_{oxide} \left(\frac{t_{si}\sigma_{oxide}}{2}\right) + \int_{0}^{t_{si}} (z - \frac{t_{si}}{2})\sigma_{si}(z)dz = 0$$

Postmortem on PR Fab

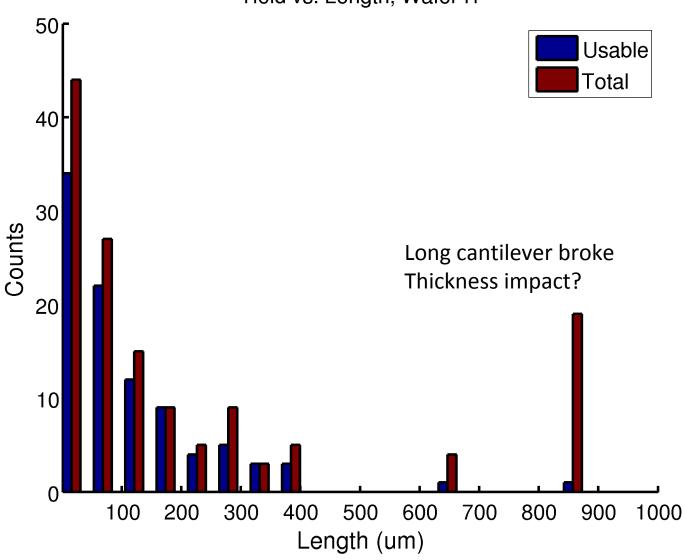


Failure types

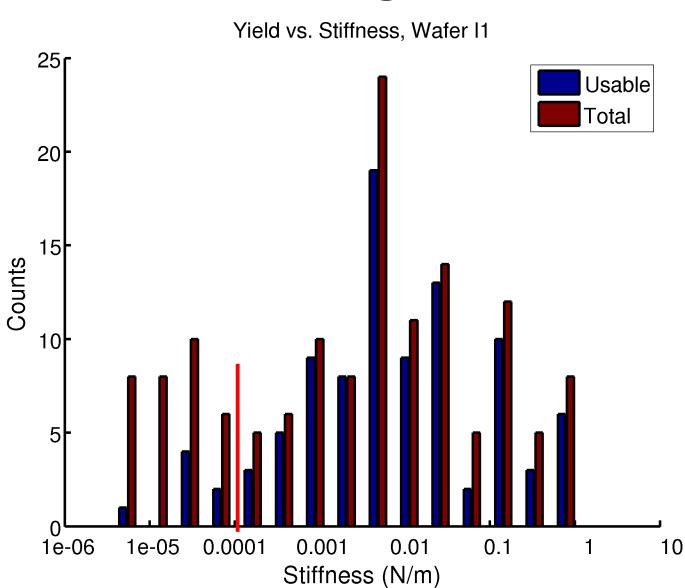


Which designs broke?





Which designs broke?



Conclusions

- Piezoresistors are noisier, higher resistance than expected, but minimal impact on performance
- There is electrical crosstalk on the microsecond scale
- Devices usable for system testing and some measurements
- Usual sensitivity calibration method doesn't work for (some) devices, will start doing some characterization on the AFM

What's Next?

- Sensitivity, feedback testing on AFM
- System prep for bio experiments
- Fab 2.0

