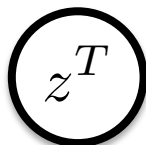
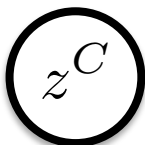


Latent style  
parameters

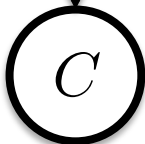
Latent pose  
parameters



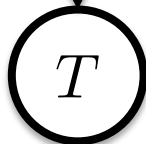
$f_C(\cdot; \theta_C)$

$f_T(\cdot; \theta_T)$

Image in  
canonical  
pose



Pose  
transformation  
matrix



Observed image