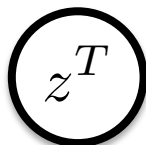
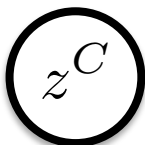


Latent style
parameters

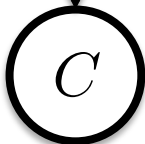
Latent pose
parameters



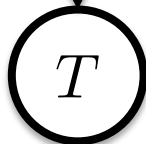
$f_C(\cdot; \theta_C)$

$f_T(\cdot; \theta_T)$

Image in
canonical
pose



Pose
transformation
matrix



Observed image