# An introduction to graph analysis and modeling The Stochastic block model

MSc in Statistics for Smart Data - ENSAI

Autumn semester 2017

http://julien.cremeriefamily.info





## **Motivations**

Last time: find an underlying organization in a observed network Spectral or hierachical clustering for network data

Not model-based, thus no statistical inference possible

Today: clustering of network based on a probabilistic model of the graph

- the stochastic block model, a random graph model tailored for clustering vertices,
- the variational EM algorithm used to infer SBM from network data
  - hierarchical clustering  $\leftrightarrow$  Gaussian mixture models  $\updownarrow$

hierarchical/spectral clustering for network ↔ Stochastic block model.

# Motivations

Last time: find an underlying organization in a observed network Spectral or hierachical clustering for network data

Not model-based, thus no statistical inference possible

Today: clustering of network based on a probabilistic model of the graph

#### Become familiar with

- the stochastic block model, a random graph model tailored for clustering vertices,
- the variational EM algorithm used to infer SBM from network data.

hierarchical clustering  $\leftrightarrow$  Gaussian mixture models  $\updownarrow$ 

hierarchical/spectral clustering for network ↔ Stochastic block model

# Motivations

Last time: find an underlying organization in a observed network Spectral or hierachical clustering for network data

Not model-based, thus no statistical inference possible

Today: clustering of network based on a probabilistic model of the graph

Become familiar with

- the stochastic block model, a random graph model tailored for clustering vertices,
- the variational EM algorithm used to infer SBM from network data.

hierarchical clustering  $\leftrightarrow$  Gaussian mixture models  $\updownarrow$ 

hierarchical/spectral clustering for network  $\leftrightarrow$  Stochastic block model

# Outline

Background: mixture models and EM
 Mixture models
 Expectation-Maximization algorithm
 Example: mixture of Gaussians

2 The Stochastic Block Model (SBM) Some Graphs Models and their limitations Mixture of Erdös-Rényi and the SBM Inference in SBM with variational EM

# Outline

- 1 Background: mixture models and EM Mixture models Expectation-Maximization algorithm Example: mixture of Gaussians
- 2 The Stochastic Block Model (SBM)

## References



Pattern recognition and machine learning, Christopher Bishop Chapter 9: Mixture Models and EM

http://users.isr.ist.utl.pt/~wurmd/Livros/school/



Classification non-supervisées,

É. Lebarbier, T. Mary-Huard

Chapitre 3 - méthode probabiliste: le modèle de mélange

https://www.agroparistech.fr/IMG/pdf/ClassificationNonSupervisee-AgroParisTech.pdf

# Outline

Background: mixture models and EM
 Mixture models
 Expectation-Maximization algorithm
 Example: mixture of Gaussians

2 The Stochastic Block Model (SBM)

# Latent variables models

#### Definition

A latent variable model is a statistical model that relates, for  $i=1,\ldots,n$  individuals,

- a set of manifest (observed) variables  $\mathbf{X} = (X_i, i = 1, \dots, n)$  to
- a set of latent (unobserved) variables  $\mathbf{Z} = (Z_i, i = 1, \dots, n)$ .

Common assumption: conditional independence

$$\mathbb{P}((X_1,\ldots,X_n)|(Z_1,\ldots,Z_n))=\prod_{i=1}^n\mathbb{P}(X_i|Z_i).$$

Famous examples

- $(Z_i, i \ge 1)$  is Markov chain: Markov models
- $Z_i$  categorical and independent: mixture models

# Latent variables models

#### Definition

A latent variable model is a statistical model that relates, for  $i=1,\ldots,n$  individuals,

- a set of manifest (observed) variables  $\mathbf{X} = (X_i, i = 1, \dots, n)$  to
- a set of latent (unobserved) variables  $\mathbf{Z} = (Z_i, i = 1, \dots, n)$ .

Common assumption: conditional independence

$$\mathbb{P}((X_1,\ldots,X_n)|(Z_1,\ldots,Z_n))=\prod_{i=1}^n\mathbb{P}(X_i|Z_i).$$

### Famous examples

- $(Z_i, i \ge 1)$  is Markov chain: Markov models
- $Z_i$  categorical and independent: mixture models
- what if  $X_i = X_{i'i'}$  is a collection of edges in a graph?

# Latent variables models

#### Definition

A latent variable model is a statistical model that relates, for  $i=1,\ldots,n$  individuals,

- a set of manifest (observed) variables  $\mathbf{X} = (X_i, i=1,\ldots,n)$  to
- a set of latent (unobserved) variables  $\mathbf{Z} = (Z_i, i = 1, \dots, n)$ .

Common assumption: conditional independence

$$\mathbb{P}((X_1,\ldots,X_n)|(Z_1,\ldots,Z_n))=\prod_{i=1}^n\mathbb{P}(X_i|Z_i).$$

### Famous examples

- $(Z_i, i \ge 1)$  is Markov chain: Markov models
- $Z_i$  categorical and independent: mixture models
- what if  $X_i = X_{i'j'}$  is a collection of edges in a graph?

# Mixture models: the latent variables

When  $(Z_1, \ldots, Z_n)$  are independent categorical variables, they give a natural (latent) classification of the observations  $(X_1, \ldots, X_n)$  – or labels.

Notations

Let  $(Z_1,\ldots,Z_n)$  be *iid* categorical variables with distribution

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_i = q) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1.$$

Alternative (equivalent) notation

Let  $Z_i = (Z_{i1}, \dots, Z_{iq})$  be an indicator vector of label for i:

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_{iq} = 1) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1$$

By definition,  $Z_i \sim \mathcal{M}(1, oldsymbol{lpha})$ , with  $oldsymbol{lpha} = (lpha_1, \dots, lpha_Q)$ .

# Mixture models: the latent variables

When  $(Z_1, \ldots, Z_n)$  are independent categorical variables, they give a natural (latent) classification of the observations  $(X_1, \ldots, X_n)$  – or labels.

#### Notations

Let  $(Z_1, \ldots, Z_n)$  be *iid* categorical variables with distribution

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_i = q) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1.$$

Alternative (equivalent) notation

Let  $Z_i = (Z_{i1}, \dots, Z_{iq})$  be an indicator vector of label for i:

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_{iq} = 1) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1$$

By definition,  $Z_i \sim \mathcal{M}(1, \boldsymbol{lpha})$ , with  $\boldsymbol{lpha} = (lpha_1, \dots, lpha_Q)$ .

# Mixture models: the latent variables

When  $(Z_1, \ldots, Z_n)$  are independent categorical variables, they give a natural (latent) classification of the observations  $(X_1, \ldots, X_n)$  – or labels.

#### Notations

Let  $(Z_1, \ldots, Z_n)$  be *iid* categorical variables with distribution

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_i = q) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1.$$

Alternative (equivalent) notation

Let  $Z_i = (Z_{i1}, \dots, Z_{iq})$  be an indicator vector of label for i:

$$\mathbb{P}(i \in q) = \mathbb{P}(Z_{iq} = 1) = \alpha_q, \quad \text{s.t.} \sum_{q=1}^{Q} \alpha_q = 1.$$

By definition,  $Z_i \sim \mathcal{M}(1, \boldsymbol{\alpha})$ , with  $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_Q)$ .

# Mixture models: the manifest variables

A mixture model represents the presence of subpopulations within an overall population as follows:

$$\mathbb{P}(X_i) = \sum_{z_i \in \mathcal{Z}_i} \mathbb{P}(X_i, Z_i) = \sum_{Z_i \in \mathcal{Z}_i} \mathbb{P}(X_i | Z_i) \mathbb{P}(Z_i).$$

Conditional distribution of the manifest variables

We assume a parametric distribution of X in each subpopulation

$$X_i | \{Z_i = q\} \sim \mathbb{P}_{\theta_q} \qquad \left( \Leftrightarrow X_i | \{Z_{iq}\} = 1 \sim \mathbb{P}_{\theta_q} \right)$$

The specificity of each class is handled by  $\{\boldsymbol{\theta}_q\}_{q=1}^Q$ .

# Mixture models: likelihoods

### The complete-data likelihood

It is the join distribution of  $(X_i, Z_i)$ :

$$\mathbb{P}(X_i, Z_i) = \alpha_{Z_i} \mathbb{P}_{\boldsymbol{\theta}_q}(X_{Z_i})$$

The incomplete-data likelihood

It is the marginal distribution of  $X_i$  once  $Z_i$  integrated

$$\mathbb{P}(X_i) = \sum_{q=1}^{Q} \mathbb{P}(X_i, Z_i = q) = \sum_{q=1}^{Q} \alpha_q \mathbb{P}_{\boldsymbol{\theta}_q}(X_i)$$

 $\leadsto$  A mixture model is a sum of distributions weigthed by the proportion of each subpopulation.

# Mixture models: likelihoods

#### The complete-data likelihood

It is the join distribution of  $(X_i, Z_i)$ :

$$\mathbb{P}(X_i, Z_i) = \alpha_{Z_i} \mathbb{P}_{\boldsymbol{\theta}_g}(X_{Z_i})$$

### The incomplete-data likelihood

It is the marginal distribution of  $X_i$  once  $Z_i$  integrated:

$$\mathbb{P}(X_i) = \sum_{q=1}^{Q} \mathbb{P}(X_i, Z_i = q) = \sum_{q=1}^{Q} \alpha_q \mathbb{P}_{\boldsymbol{\theta}_q}(X_i)$$

→ A mixture model is a sum of distributions weighted by the proportion of each subpopulation.

# Outline

Background: mixture models and EM
 Mixture models
 Expectation-Maximization algorithm

2 The Stochastic Block Model (SBM)

# Intractability of the Likelihood

#### Maximum Likelihood Estimator

The MLE aims to maximize the (marginal) likehood of the observations:

$$L(\boldsymbol{\theta}; \mathbf{X}) = \mathbb{P}_{\boldsymbol{\theta}}((X_1, \dots, X_n)) = \int_{\mathbf{Z} \in \mathcal{Z}} \mathbb{P}_{\boldsymbol{\theta}}(\mathbf{X}, \mathbf{Z}) d\mathbf{Z}$$

Integrations are summation over  $\{1,\ldots,Q\}$ : we have  $Q^n$  terms !

Intractable summation

With mixture models, for  $\theta = (\theta_1, \dots, \theta_Q)$  we have

$$\log L(\boldsymbol{\theta}; \mathbf{X}) = \sum_{i=1}^{n} \log \left\{ \sum_{q=1}^{Q} \alpha_q \mathbb{P}_{\boldsymbol{\theta}_q}(X_i) \right\}$$

→ Direct maximization of the likelihood is impossible in practice

# Intractability of the Likelihood

#### Maximum Likelihood Estimator

The MLE aims to maximize the (marginal) likehood of the observations:

$$L(\boldsymbol{\theta}; \mathbf{X}) = \mathbb{P}_{\boldsymbol{\theta}}((X_1, \dots, X_n)) = \int_{\mathbf{Z} \in \mathcal{Z}} \mathbb{P}_{\boldsymbol{\theta}}(\mathbf{X}, \mathbf{Z}) d\mathbf{Z}$$

Integrations are summation over  $\{1,\ldots,Q\}$ : we have  $Q^n$  terms !

#### Intractable summation

With mixture models, for  $oldsymbol{ heta} = (oldsymbol{ heta}_1, \dots, oldsymbol{ heta}_Q)$  we have

$$\log L(\boldsymbol{\theta}; \mathbf{X}) = \sum_{i=1}^{n} \log \left\{ \sum_{q=1}^{Q} \alpha_{q} \mathbb{P}_{\boldsymbol{\theta}_{q}}(X_{i}) \right\}.$$

→ Direct maximization of the likelihood is impossible in practice

# Bayes decision rule / Maximum a posteriori

# Principle

Affect an individual i to the subpopulation which is the most likely according to the data:

$$\tau_{iq} = \mathbb{P}(Z_{iq} = 1 | X_i = x_i)$$

This is the posterior probability for  $i \in q$ .

## Application of the Bayes Theorem

It is straightforward to show that

$$\tau_{iq} = \frac{\alpha_q \mathbb{P}_{\theta_q}(x_i)}{\sum_{q=1}^{Q} \alpha_q \mathbb{P}_{\theta_q}(x_i)}$$

# Principle of the EM algorithm

#### If $\theta$ were known

... estimating the posterior probability  $\mathbb{P}(Z_i|\mathbf{X})$  of  $\mathbf{Z}$  should be easy By means of the Bayes decision rule

#### If **Z** were known...

 $\dots$  estimating the best set of parameter heta should be easy This is close to usual maximum likelihood estimation

#### EM principle

Maximize the marginal likelihood iteratively:

- $oldsymbol{0}$  Initialize  $oldsymbol{ heta}$
- $oldsymbol{arrho}$  Compute the probability of  $oldsymbol{Z}$  given  $oldsymbol{ heta}$
- $oldsymbol{G}$  Get a better  $oldsymbol{\theta}$  with the new  $oldsymbol{Z}$
- 4 Iterate until convergence

# Principle of the EM algorithm

#### If $\theta$ were known

... estimating the posterior probability  $\mathbb{P}(Z_i|\mathbf{X})$  of  $\mathbf{Z}$  should be easy By means of the Bayes decision rule

#### If **Z** were known...

 $\dots$  estimating the best set of parameter heta should be easy This is close to usual maximum likelihood estimation

### EM principle

Maximize the marginal likelihood iteratively:

- $oldsymbol{0}$  Initialize  $oldsymbol{ heta}$
- ② Compute the probability of  ${f Z}$  given  ${m heta}$
- $\odot$  Get a better  $\theta$  with the new  $\mathbf{Z}$
- 4 Iterate until convergence

# Formal algorithm

Initialization: start from a good guess either of **Z** or  $\theta$ , then iterate 1-2

### 1. Expectation step

Calculate the expected value of the loglikelihood under the current heta

$$Q\left(\boldsymbol{\theta}|\boldsymbol{\theta}^{(t)}\right) = \mathbb{E}_{\mathbf{Z}|\mathbf{X};\boldsymbol{\theta}^{(t)}}\big[\log L(\boldsymbol{\theta};\mathbf{X},\mathbf{Z})\big] \qquad (\textit{needs } \mathbb{P}_{\boldsymbol{\theta}^{(t)}}(\mathbf{Z}|\mathbf{X}))$$

### 2. Maximization step

Find the parameters that maximize this quantity

$$\boldsymbol{\theta}^{(t+1)} = \arg\max_{\boldsymbol{\theta}} Q\left(\boldsymbol{\theta}|\boldsymbol{\theta}^{(t)}\right)$$

Stop when 
$$\| \pmb{\theta}^{(t+1)} - \pmb{\theta}^{(t)} \| < \varepsilon$$
 or  $\| Q^{(t+1)} - Q^{(t)} \| < \varepsilon$ 

# (Basic) Convergence analysis

#### Theorem

At each step of the EM algorithm, the loglikelihood increases. EM thus reaches a local optimum.

#### Proof.

On board.

# Choosing the number of component

## Reminder: Bayesian Information Criterion

The BIC is a model selection criterion which penalizes the adjustement to the data by the number of parameter in model  ${\cal M}$  as follows:

$$\operatorname{BIC}(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}) - \frac{1}{2} \log(n) \operatorname{df}(\mathcal{M}).$$

Integrated Classification Criterion

It is an adaptation working with the complete-data likelihood

$$ICL(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}, \hat{\mathbf{Z}}) + \frac{1}{2} \log(n) df(\mathcal{M})$$
$$= BIC - \mathcal{H}(\mathbb{P}(\hat{\mathbf{Z}}|\mathbf{X}),$$

where the entropy  ${\mathcal H}$  measures the separability of the subpopulations

 $\rightsquigarrow$  We choose  $\mathcal{M}(Q)$  that maximizes either BIC or ICL

# Choosing the number of component

## Reminder: Bayesian Information Criterion

The BIC is a model selection criterion which penalizes the adjustement to the data by the number of parameter in model  ${\cal M}$  as follows:

$$\operatorname{BIC}(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}) - \frac{1}{2} \log(n) \operatorname{df}(\mathcal{M}).$$

## Integrated Classification Criterion

It is an adaptation working with the complete-data likelihood:

$$ICL(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}, \hat{\mathbf{Z}}) + \frac{1}{2} \log(n) df(\mathcal{M})$$
$$= BIC - \mathcal{H}(\mathbb{P}(\hat{\mathbf{Z}}|\mathbf{X}),$$

where the entropy  ${\cal H}$  measures the separability of the subpopulations.

ightsquigarrow We choose  $\mathcal{M}(\mathit{Q})$  that maximizes either BIC or ICL

# Choosing the number of component

## Reminder: Bayesian Information Criterion

The BIC is a model selection criterion which penalizes the adjustement to the data by the number of parameter in model  ${\cal M}$  as follows:

$$\operatorname{BIC}(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}) - \frac{1}{2} \log(n) \operatorname{df}(\mathcal{M}).$$

## Integrated Classification Criterion

It is an adaptation working with the complete-data likelihood:

$$ICL(\mathcal{M}) = \log L(\hat{\boldsymbol{\theta}}; \mathbf{X}, \hat{\mathbf{Z}}) + \frac{1}{2} \log(n) df(\mathcal{M})$$
$$= BIC - \mathcal{H}(\mathbb{P}(\hat{\mathbf{Z}}|\mathbf{X}),$$

where the entropy  ${\cal H}$  measures the separability of the subpopulations.

 $\leadsto$  We choose  $\mathcal{M}(Q)$  that maximizes either BIC or ICL

# Outline

Background: mixture models and EM
 Mixture models
 Expectation-Maximization algorithm
 Example: mixture of Gaussians

2 The Stochastic Block Model (SBM)

# Mixture of Gaussians

Calculs in the univariate case: complete likelihood

The distribution of  $X_i$  conditional on the label of i is assumed to be a univariate Gaussian distribution with unknown parameters:

$$X_i|Z_{iq}=1 \sim \mathcal{N}(\mu_q, \sigma_q^2)$$

complete Likelihood  $(\mathbf{X}, \mathbf{Z})$ 

The model complete loglikelihood is

$$\log L(\boldsymbol{\mu}, \boldsymbol{\sigma}^2; \mathbf{X}, \mathbf{Z}) = \sum_{i=1}^{n} \sum_{q=1}^{Q} Z_{iq} \left( \log \alpha_q - \log \sigma_q - \log(\sqrt{2\pi}) - \frac{1}{2\sigma_q^2} (x_i - \mu_q)^2 \right)$$

# Mixture of Gaussians

Calculs in the univariate case: E-step

## E-step

For fixed values of  $\mu_q, \sigma_q^2$  and  $\alpha_q$ , the estimates of the posterior probabilities  $\hat{\tau}_{iq} = \mathbb{P}(Z_{iq} = 1|X_i)$  are

$$\hat{\tau}_{iq} = \frac{\alpha_q \mathcal{N}(x_i; \mu_q, \sigma_q^2)}{\sum_{q=1}^{Q} \alpha_q \mathcal{N}(x_i; \mu_q, \sigma_q^2)},$$

where  ${\cal N}$  is the density of the normal distribution.

# Mixture of Gaussians

Calculs in the univariate case: M-step

## M-step

For fixed values of  $au_{iq}$ , the estimates of the model parameters are

$$\hat{\alpha}_q = \frac{\sum_{i=1}^n \tau_{iq}}{\sum_{i=1}^n \sum_{q=1}^Q \tau_{iq}} \quad \hat{\mu}_q = \frac{\sum_i \tau_{iq} x_i}{\sum_i \tau_{iq}} \quad \hat{\sigma}_q^2 = \frac{\sum_{i=1}^n \tau_{iq} (x_i - \mu_q)^2}{\sum_{i=1}^n \tau_{iq}}$$

# R code: auxiliary functions

We start by defining functions to compute the complete model loglikelihood, perform the E step and the M step.

```
get.cloglik <- function(X, Z, theta) {</pre>
  alpha <- theta$alpha; mu <- theta$mu; sigma <- theta$sigma
  xs <- scale(matrix(X,length(x),length(alpha)),mu,sigma)</pre>
  return(sum(Z*(log(alpha)-log(sigma)-.5*(log(2*pi)+xs^2))))
M.step <- function(X, tau) {
  n <- length(X); Q <- ncol(tau)</pre>
  alpha <- colMeans(tau)
  mu <- colMeans(tau * matrix(X,n,Q)) / alpha</pre>
  sigma <- sqrt(colMeans(tau*sweep(matrix(X,n,Q),2,mu,"-")^2)/alpha)
  return(list(alpha=alpha, mu=mu, sigma=sigma))
E.step <- function(X, theta) {</pre>
  tau <- mapply(function(alpha, mu, sigma) {
      alpha*dnorm(X,mu,sigma)
    }, theta$alpha, theta$mu, theta$sigma)
  return(tau / rowSums(tau))
```

# R code: EM for univariate mixture

```
EM.mixture <- function(X, Q,
                        init.cl=sample(1:Q,n,rep=TRUE), max.iter=100, eps=1e-5) {
    n <- length(X); tau <- matrix(0,n,Q); tau[cbind(1:n,init.cl)] <- 1</pre>
    Eloglik <- vector("numeric", max.iter)</pre>
    iter <- 0: cond <- FALSE
    while (!cond) {
        iter <- iter + 1
        ## M step
        theta <- M.step(X, tau)
        ## E step
        tau <- E.step(X, theta)
        ## check consistency
        Eloglik[iter] <- get.cloglik(X, tau, theta)</pre>
        if (iter > 1)
            cond <- (iter>=max.iter) | Eloglik[iter]-Eloglik[iter-1] < eps</pre>
    return(list(alpha = theta$alpha, mu = theta$mu, sigma = theta$sigma,
                tau = tau, cl = apply(tau, 1, which.max),
                Eloglik = Eloglik[1:iter]))
```

# Example: data generation

## We first generate data with 4 components:

```
mu1 <- 5 ; sigma1 <- 1; n1 <- 100
mu2 <- 10 ; sigma2 <- 1; n2 <- 200
mu3 <- 15 ; sigma3 <- 2; n3 <- 50
mu4 <- 20 ; sigma4 <- 3; n4 <- 100
cl \leftarrow rep(1:4,c(n1,n2,n3,n4))
x <- c(rnorm(n1,mu1,sigma1),rnorm(n2,mu2,sigma2),
       rnorm(n3,mu3,sigma3),rnorm(n4,mu4,sigma4))
n <- length(x)
## we randomize the class ordering
rnd <- sample(1:n)</pre>
cl <- cl[rnd]
x <- x[rnd]
alpha \leftarrow c(n1,n2,n3,n4)/n
```

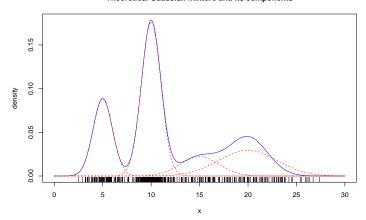
# Example: data generation - plot I

Let us plot the data and the theoretical mixture.

```
curve(alpha[1]*dnorm(x,mu1,sigma1) +
    alpha[2]*dnorm(x,mu2,sigma2) +
    alpha[3]*dnorm(x,mu3,sigma3) +
    alpha[4]*dnorm(x,mu4,sigma3),
    col="blue", lty=1, from=0,to=30, n=1000,
    main="Theoretical Gaussian mixture and its components",
    xlab="x", ylab="density")
curve(alpha[1]*dnorm(x,mu1,sigma1), col="red", add=TRUE, lty=2)
curve(alpha[2]*dnorm(x,mu2,sigma2), col="red", add=TRUE, lty=2)
curve(alpha[3]*dnorm(x,mu3,sigma3), col="red", add=TRUE, lty=2)
curve(alpha[4]*dnorm(x,mu4,sigma4), col="red", add=TRUE, lty=2)
rug(x)
```

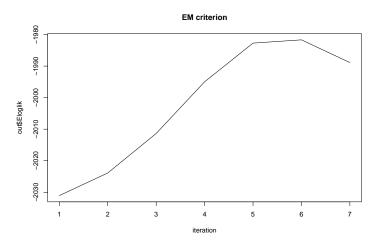
# Example: data generation - plot II





## Example: adjustment

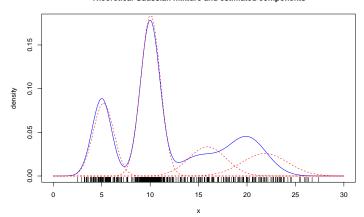
```
out <- EM.mixture(x, Q=4, init.cl=sample(1:4,n,rep=TRUE))
plot(out$Eloglik, main="EM criterion", type="1", xlab="iteration")</pre>
```



## Example: adjustment - plot I

## Example: adjustment - plot II

#### Theoretical Gaussian mixture and estimated components



## Example: adjustment - classification I

## Outline

- 1 Background: mixture models and EM
- 2 The Stochastic Block Model (SBM) Some Graphs Models and their limitations

Mixture of Erdös-Rényi and the SBM Inference in SBM with variational EM

### References



Mixture model for random graphs, Statistics and Computing Daudin, Robin, Picard

pbil.univ-lyon1.fr/members/fpicard/franckpicard\_fichiers/pdf/DPR08.pdf

Analyse statistique de graphes, Catherine Matias Chapitre 4, Section 4

### Outline

- 1 Background: mixture models and EM
- 2 The Stochastic Block Model (SBM) Some Graphs Models and their limitations Mixture of Erdös-Rényi and the SBM Inference in SBM with variational EM

## A mathematical model: Erdös-Rényi graph

### Definition

Let  $\mathcal{V}=1,\ldots,n$  be a set of fixed vertices. The (simple) Erdös-Rény model  $\mathcal{G}(n,\pi)$  assumes random edges between pairs of nodes with probability  $\pi$ . In orther word, the (random) adjacency matrix  $\mathbf{X}$  is such that

$$X_{ij} \sim \mathcal{B}(\pi)$$

## Proposition (degree distribution)

The (random) degree  $D_i$  of vertex i follows a binomial distribution:

$$D_i \sim b(n-1,\pi).$$

## Erdös-Rényi - example

```
G1 <- igraph::sample_gnp(10, 0.1)

G2 <- igraph::sample_gnp(10, 0.9)

G3 <- igraph::sample_gnp(100, .02)

par(mfrow=c(1,3))

plot(G1, vertex.label=NA); plot(G2, vertex.label=NA)

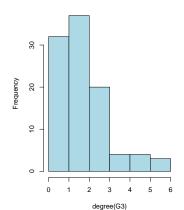
plot(G3, vertex.label=NA, layout=layout.circle)
```

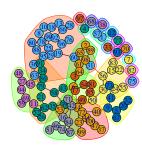


# Erdös-Rény - limitations: very homegeneous

```
average.path.length(G3); diameter(G3)
## [1] 6.186269
## [1] 13
```

#### Histogram of degree(G3)





## Mechanism-based model: preferential attachment

The graph is defined dynamically as follows

#### Definition

Start from a initial graph  $\mathcal{G}_0 = (\mathcal{V}_0, \mathcal{E}_0)$ , then for each time step,

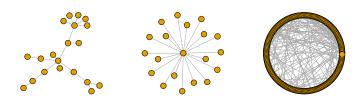
- $oldsymbol{1}$  At t a new node  $V_t$  is added
- 2  $V_t$  is connected to  $i \in V_{t-1}$  with probability

$$D_i^{\alpha} + \text{cst.}$$

Nodes with high degree get more connections thus richers get richers

## Preferential attachment - example

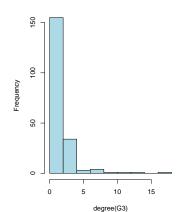
```
G1 <- igraph::sample_pa(20, 1, directed=FALSE)
G2 <- igraph::sample_pa(20, 5, directed=FALSE)
G3 <- igraph::sample_pa(200, directed=FALSE)
par(mfrow=c(1,3))
plot(G1, vertex.label=NA); plot(G2, vertex.label=NA)
plot(G3, vertex.label=NA, layout=layout.circle)
```

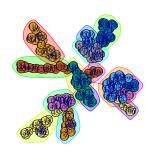


## Preferential attachment - limitations

```
average.path.length(G3); diameter(G3)
## [1] 5.965327
## [1] 14
```

#### Histogram of degree(G3)





### Limitations

### Erdös-Rényi

The ER model does not fit well real world network

- As can been seen from its degree distribution
- ER is generally too homogeneous
- Preferential attachment
  - Is defined through an algorithm so performing statistics is complicated
  - Is stucked to the power-law distribution of degrees

#### The Stochastic Block Model

The SBM¹ generalizes ER in a mixture framework. It provides

- a statistical framework to adjust and interpret the parameters
- a flexible yet simple specification that fits many existing network data

<sup>&</sup>lt;sup>1</sup>Other models exist (e.g. exponential model for random graphs) but less popular.

### Outline

- 1 Background: mixture models and EM
- 2 The Stochastic Block Model (SBM) Some Graphs Models and their limitations Mixture of Erdös-Rényi and the SBM Inference in SBM with variational EM

## Stochastic Block Model: definition

Mixture model point of view: mixture of Erdös-Rényi

#### Latent structure

Let  $\mathcal{V}=\{1,..,n\}$  be a fixed set of vertices. We give each  $i\in\mathcal{V}$  a latent label among a set  $\mathcal{Q}=\{1,\ldots,Q\}$  such that

- $\alpha_q = \mathbb{P}(i \in q), \quad \sum_q \alpha_q = 1;$
- $Z_{iq} = \mathbf{1}_{\{i \in q\}}$  are independent hidden variables.

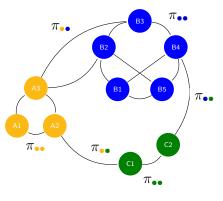
### The conditional distribution of the edges

Connexion probabilities depend on the node class belonging:

$$X_{ij} | \{i \in q, j \in \ell\} \sim \mathcal{B}(\pi_{q\ell}) \qquad \left( \Leftrightarrow X_{ij} | \{Z_{iq}Z_{j\ell} = 1\} \sim \mathcal{B}(\pi_{q\ell}). \right)$$

The  $Q \times Q$  matrix  $\pi$  gives for all couple of labels  $\pi_{q\ell} = \mathbb{P}(X_{ij} = 1 | i \in q, j \in \ell)$ .

## Stochastic Block Model: the big picture



#### Stochastic Block Model

Let n nodes divided into

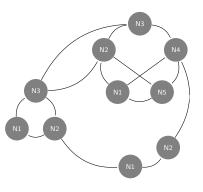
• 
$$Q = \{ \bullet, \bullet, \bullet \}$$
 classes

• 
$$\alpha_{\bullet} = \mathbb{P}(i \in \bullet)$$
,  $\bullet \in \mathcal{Q}, i = 1, \dots, n$ 

• 
$$\pi_{\bullet \bullet} = \mathbb{P}(i \leftrightarrow j | i \in \bullet, j \in \bullet)$$

$$\begin{split} Z_i &= \mathbf{1}_{\{i \in \bullet\}} \ \sim^{\mathsf{iid}} \mathcal{M}(1, \alpha), \quad \forall \bullet \in \mathcal{Q}, \\ X_{ij} \mid \{i \in \bullet, j \in \bullet\} \sim^{\mathsf{ind}} \mathcal{B}(\pi_{\bullet \bullet}) \end{split}$$

## Stochastic Block Model: unknown parameters



#### Stochastic Block Model

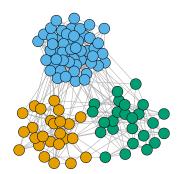
Let n nodes divided into

- $Q = \{ \bullet, \bullet, \bullet \}$ , card(Q) known
- $\alpha_{\bullet} = ?$
- $\pi_{\bullet \bullet} = ?$

$$\begin{split} Z_i &= \mathbf{1}_{\{i \in \bullet\}} \ \sim^{\mathsf{iid}} \mathcal{M}(1, \alpha), \quad \forall \bullet \in \mathcal{Q}, \\ X_{ij} \mid \{i \in \bullet, j \in \bullet\} \sim^{\mathsf{ind}} \mathcal{B}(\pi_{\bullet \bullet}) \end{split}$$

## Stochastic block models – examples of topology

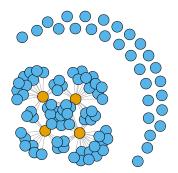
#### Community network



# Stochastic block models – examples of topology

#### Star network

```
pi <- matrix(c(0.05,0.3,0.3,0),2,2)
star <- igraph::sample_sbm(100, pi, c(4, 96))
plot(star, vertex.label=NA, vertex.color = rep(1:2,c(4,96)))</pre>
```



## Degree distributions

### Conditional degree distribution

The conditional degree distribution of a node  $i \in q$  is

$$D_i|i \in q \sim b(n-1,\bar{\pi}) \approx \mathcal{P}(\lambda_q), \quad \bar{\pi}_q = \sum_{\ell=1}^Q \alpha_\ell, \pi_{q\ell} \quad \lambda_q = (n-1)\bar{\pi}_q$$

### Conditional degree distribution

The degree distribution of a node i can be approximated by a mixture of Poisson distributions:

$$\mathbb{P}(D_i = k) = \sum_{q=1}^{Q} \alpha_q \exp\{-\lambda_q\} \frac{\lambda_q^k}{k!}$$

### Likelihoods

### Complete-data loglikelihood

$$\log L(\mathbf{X}, \mathbf{Z}) = \sum_{i,q} Z_{iq} \log \alpha_q + \sum_{i < j,q,\ell} Z_{iq} Z_{j\ell} \log \pi_{q\ell}^{X_{ij}} (1 - \pi_{q\ell})^{1 - X_{ij}}.$$

### Conditional expectation of the complete-data loglikelihood

$$\mathbb{E}_{\mathbf{Z}|\mathbf{X}}\left[\log L(\boldsymbol{\theta}; \mathbf{X}, \mathbf{Z})\right] = \sum_{i, q} \tau_{iq} \log \alpha_q + \sum_{i < j, q, \ell} \eta_{ijq\ell} \log \pi_{q\ell}^{X_{ij}} (1 - \pi_{q\ell})^{1 - X_{ij}}$$

where  $\tau_{iq}, \eta_{ijq\ell}$  are the posterior probabilities:

- $\tau_{iq} = \mathbb{P}(Z_{iq} = 1|\mathbf{X}) = \mathbb{E}[Z_{iq}|\mathbf{X}].$
- $\eta_{ijq\ell} = \mathbb{P}(Z_{iq}Z_{j\ell} = 1|\mathbf{X}) = \mathbb{E}[Z_{iq}Z_{j\ell}|\mathbf{X}].$

### Outline

- 1 Background: mixture models and EM
- 2 The Stochastic Block Model (SBM) Some Graphs Models and their limitations Mixture of Erdös-Rényi and the SBM Inference in SBM with variational EM

## The EM strategy does not apply directly for SBM

### Ouch: another intractability problem

- the  $Z_{iq}$  are not independent in the SBM framework. . .
- we cannot compute  $\eta_{ijq\ell} = \mathbb{P}(Z_{iq}Z_{j\ell} = 1|\mathbf{X}) = \mathbb{E}\left[Z_{iq}Z_{j\ell}|\mathbf{X}\right]$ ,
- the conditional expectation  $Q(\theta)$ , i.e. the main EM ingredient, is intractable.

### Solution: mean field approximation

Approximate  $\eta_{ijq\ell}$  by  $\tau_{iq}\tau_{j\ell}$ , i.e., assume independence between  $Z_{iq}$   $\leadsto$  This can be formalized in the variational framework

# Revisting the EM algorithm I

### Proposition

Consider a distribution  $\mathbb{Q}$  for the  $\{Z_{iq}\}$ . We have

$$\log L(\boldsymbol{\theta}; \mathbf{X}) = \mathbb{E}_{\mathbb{Q}}[\log L(\boldsymbol{\theta}, \mathbf{X}, \mathbf{Z})] + \mathcal{H}(\mathbb{Q}) + \mathrm{KL}(\mathbb{Q} \mid \mathbb{P}(\mathbf{Z} | \mathbf{X}; \boldsymbol{\theta})),$$

where  ${\cal H}$  is the entropy and  ${\rm KL}(\cdot|\cdot)$  is the Kullback-Leibler divergence:

$$\mathcal{H}(\mathbb{Q}) = -\sum_{z} \mathbb{Q}(z) \log \mathbb{Q}(z) = -\mathbb{E}_{\mathbb{Q}}[\log \mathbb{Q}(Z)]$$

$$\mathcal{KL}(\mathbb{Q} \mid \mathbb{P}(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta})) = \sum_{z} \mathbb{Q}(z) \log \frac{\mathbb{Q}(z)}{\mathbb{P}(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta})} = \mathbb{E}_{\mathbb{Q}} \left[ \log \frac{\mathbb{Q}(z)}{\mathbb{P}(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta})} \right]$$

# Revisting the EM algorithm II

Let

$$J(\mathbb{Q}, \boldsymbol{\theta}) \triangleq \mathbb{E}_{\mathbb{Q}} \left( \log L(\boldsymbol{\theta}; \mathbf{X}, \mathbf{Z}) \right) + \mathcal{H}(\mathbb{Q})$$

The steps in the EM algorithm may be viewed as:

Expectation step : choose  $\mathbb Q$  to maximize  $J(\mathbb Q; \boldsymbol{\theta}^{(t)})$ 

The solution is  $\mathbb{P}(\mathbf{Z}|\mathbf{X};\boldsymbol{\theta}^{(t)})$ 

Maximization step : choose  $\theta$  to maximize  $J(\mathbb{Q}^{(t)}; \theta)$ 

The solution maximizes  $\mathbb{E}_{\mathbf{Z}|\mathbf{X}:\boldsymbol{\theta}^{(t)}}\left(\log L(\boldsymbol{\theta};\mathbf{X},\mathbf{Z})\right)$ 

# Variational approximation for SBM

#### Problem for SBM

 $\mathbb{P}(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta}^{(t)})$  cannot be computed thus the E-step cannot be solved.

### Idea

Choose  $\mathbb Q$  in a class of function so that the E-step can be solved.

### Family of distribution that factorizes

We chose  $\mathbb{Q}$  so as the  $Z_{iq}$  are marginally independents:

$$\mathbb{Q}(\mathbf{Z}) = \prod_{i=1}^{n} \mathbb{Q}_i(Z_i) = \prod_{i=1}^{n} \prod_{q=1}^{Q} \tau_{iq}^{Z_{iq}},$$

where  $\tau_{iq} = \mathbb{Q}_i(Z_i = q) = \mathbb{E}Q(Z_{iq})$ , with  $\sum_q \tau_{iq} = 1$  for all  $i = 1, \dots, n$ .

### Variational EM for SBM: the criterion

### Lower bound of the loglikehood

Since  $\mathbb Q$  is an approximation of  $\mathbb P(\mathbf Z|\mathbf X),$  the Kullback-Leibler divergence is non-negative and

$$\log L(\boldsymbol{\theta}; \mathbf{X}) \ge \mathbb{E}_{\mathbb{Q}}[\log L(\boldsymbol{\theta}, \mathbf{X}, \mathbf{Z})] + \mathcal{H}(\mathbb{Q}) = J(\mathbb{Q}, \boldsymbol{\theta}).$$

For the SBM,

$$J(\mathbb{Q}, \boldsymbol{\theta}) = \sum_{i,q} \tau_{iq} \log \alpha_q + \sum_{i < j,q,\ell} \tau_{iq} \tau_{j\ell} \log b(X_{ij}; \pi_{q\ell}) - \sum_{i,q} \tau_{iq} \log(\tau_{iq}),$$

 $\rightsquigarrow$  we optimize the loglikelihood lower bound  $J(\mathbb{Q}, \theta) = J(\tau, \theta)$  in  $(\tau, \theta)$ .

## E and M steps for SBM

### Variational E-step

Maximizing  $J(\tau)$  for fixed  $\theta$ , we find a fixed-point relationship:

$$\hat{\tau}_{iq} \propto \alpha_q \prod_j \prod_\ell b(X_{ij}, \pi_{q\ell})^{\hat{\tau}_{j\ell}} \tag{1}$$

### M-step

Maximizing  $J(\theta)$  for fixed  $\tau$ , we find,

$$\hat{\alpha}_q = \frac{1}{n} \sum_{i} \hat{\tau}_{iq}, \quad \hat{\pi}_{q\ell} = \frac{\sum_{i \neq j} \hat{\tau}_{iq} \hat{\tau}_{j\ell} X_{ij}}{\sum_{i \neq j} \hat{\tau}_{iq} \hat{\tau}_{j\ell}}.$$
 (2)

### Model selection

We use our lower bound of the loglikelihood to compute an approximation of the ICL

$$\begin{aligned} \text{vICL}(Q) &= \mathbb{E}_{\hat{\mathbb{Q}}}[\log L(\hat{\boldsymbol{\theta}}); \mathbf{X}, \mathbf{Z}] \\ &- \frac{1}{2} \left( \frac{Q(Q+1)}{2} \log \frac{n(n-1)}{2} + (Q-1) \log(n) \right), \end{aligned}$$

where

$$\mathbb{E}_{\hat{\mathbb{Q}}}[\log L(\hat{\boldsymbol{\theta}}; \mathbf{X}, \mathbf{Z})] = J(\hat{\boldsymbol{\tau}}, \hat{\boldsymbol{\theta}}) - \mathcal{H}(\hat{\mathbb{Q}}).$$

The variational BIC is just

$$\mathrm{vBIC}(Q) = J(\hat{\boldsymbol{\tau}}, \hat{\boldsymbol{\theta}}) - \frac{1}{2} \left( \frac{Q(Q+1)}{2} \log \frac{n(n-1)}{2} + (Q-1) \log(n) \right).$$

# Example on the French blogsphere I

```
library(mixer)
data(blog)
mix.blog <- mixer(x=blog$links,qmin=2,qmax=20)

## Mixer: the adjacency matrix has been transformed in a undirected edge list
plot(mix.blog)</pre>
```

## Example on the French blogsphere II

