linalg

1.1.0

Generated by Doxygen 1.8.11

Contents

1	Main	Page			1
	1.1	Introdu	uction		1
2	Mod	ules Ind	dex		3
	2.1	Module	es List		3
3	Data	Type I	ndex		5
	3.1	Data T	ypes List		5
4	Mod	ule Doc	cumentatio	on	7
	4.1	lapack	Module Re	eference	7
		4.1.1	Detailed	Description	7
	4.2	linalg_	c_binding	Module Reference	7
		4.2.1	Detailed	Description	9
		4.2.2	Function	Subroutine Documentation	9
			4.2.2.1	cholesky_factor_c(n, a, upper, err)	9
			4.2.2.2	cholesky_rank1_downdate_c(n, r, u, err)	10
			4.2.2.3	cholesky_rank1_update_c(n, r, u, err)	10
			4.2.2.4	det_c(n, a, err)	10
			4.2.2.5	diag_mtx_mult_c(trans, m, n, alpha, na, a, mb, nb, b, beta, c, err)	11
			4.2.2.6	diag_mtx_mult_cmplx_c(trans, m, n, alpha, na, a, mb, nb, b, beta, c, err)	12
			4.2.2.7	eigen_asymm_c(n, a, vals, vecs, err)	12
			4.2.2.8	eigen_gen_c(n, a, b, alpha, beta, vecs, err)	13
			4.2.2.9	eigen_symm_c(n, vecs, a, vals, err)	13
			42210	form lu c(n lu invt u n)	14

iv CONTENTS

		4.2.2.11	form_qr_c(m, n, r, nt, tau, q, err)	15
		4.2.2.12	form_qr_pivot_c(m, n, r, nt, tau, pvt, q, p, err)	15
		4.2.2.13	lu_factor_c(m, n, a, ni, ipvt, err)	16
		4.2.2.14	mtx_inverse_c(n, a, err)	16
		4.2.2.15	mtx_mult_c(transa, transb, m, n, k, alpha, a, lda, b, ldb, beta, c)	17
		4.2.2.16	mtx_pinverse_c(m, n, a, ainv, err)	17
		4.2.2.17	mtx_rank_c(m, n, a, err)	18
		4.2.2.18	mult_qr_c(trans, m, n, q, nt, tau, c, err)	18
		4.2.2.19	mult_rz_c(trans, m, n, l, a, tau, c, err)	19
		4.2.2.20	qr_factor_c(m, n, a, nt, tau, err)	20
		4.2.2.21	qr_factor_pivot_c(m, n, a, nt, tau, jpvt, err)	20
		4.2.2.22	qr_rank1_update_c(m, n, q, r, u, v, err)	21
		4.2.2.23	rank1_update_c(m, n, alpha, x, y, a)	21
		4.2.2.24	rz_factor_c(m, n, a, tau, err)	22
		4.2.2.25	solve_cholesky_c(upper, n, nrhs, a, b)	22
		4.2.2.26	solve_least_squares_c(m, n, nrhs, a, mb, b, err)	23
		4.2.2.27	solve_lu_c(n, nrhs, a, ipvt, b)	23
		4.2.2.28	solve_qr_c(m, n, nrhs, a, tau, b, err)	23
		4.2.2.29	solve_qr_pivot_c(m, n, nrhs, a, nt, tau, jpvt, mb, b, err)	24
		4.2.2.30	solve_tri_mtx_c(upper, trans, nounit, n, nrhs, alpha, a, b)	25
		4.2.2.31	svd_c(m, n, a, ns, s, u, vt, err)	25
		4.2.2.32	swap_c(n, x, y)	26
		4.2.2.33	trace_c(m, n, x)	26
4.3	linalg_	constants	Module Reference	26
	4.3.1	Detailed	Description	27
4.4	linalg_	core Modu	lle Reference	27
	4.4.1	Detailed	Description	28
	4.4.2	Function	Subroutine Documentation	28
		4.4.2.1	det(a, iwork, err)	28
		4.4.2.2	diag_mtx_mult_mtx(lside, trans, alpha, a, b, beta, c, err)	29

CONTENTS

		4.4.2.3	diag_mtx_mult_mtx2(lside, alpha, a, b, err)	30
		4.4.2.4	diag_mtx_mult_mtx3(lside, trans, alpha, a, b, beta, c, err)	30
		4.4.2.5	diag_mtx_mult_mtx4(lside, trans, alpha, a, b, beta, c, err)	31
		4.4.2.6	mtx_mult_mtx(transa, transb, alpha, a, b, beta, c, err)	31
		4.4.2.7	mtx_mult_vec(trans, alpha, a, b, beta, c, err)	32
		4.4.2.8	mtx_rank(a, tol, work, olwork, err)	33
		4.4.2.9	rank1_update(alpha, x, y, a, err)	33
		4.4.2.10	recip_mult_array(a, x)	34
		4.4.2.11	swap(x, y, err)	34
		4.4.2.12	trace(x)	35
		4.4.2.13	tri_mtx_mult(upper, alpha, a, beta, b, err)	35
4.5	linalg_	eigen Mod	lule Reference	35
	4.5.1	Detailed	Description	36
	4.5.2	Function	/Subroutine Documentation	36
		4.5.2.1	eigen_asymm(a, vals, vecs, work, olwork, err)	36
		4.5.2.2	eigen_gen(a, b, alpha, beta, vecs, work, olwork, err)	37
		4.5.2.3	eigen_symm(vecs, a, vals, work, olwork, err)	38
4.6	linalg_	factor Mod	lule Reference	39
	4.6.1	Detailed	Description	40
	4.6.2	Function	/Subroutine Documentation	40
		4.6.2.1	cholesky_factor(a, upper, err)	40
		4.6.2.2	cholesky_rank1_downdate(r, u, work, err)	41
		4.6.2.3	cholesky_rank1_update(r, u, work, err)	42
		4.6.2.4	form_lu_all(lu, ipvt, u, p, err)	42
		4.6.2.5	form_lu_only(lu, u, err)	43
		4.6.2.6	form_qr_no_pivot(r, tau, q, work, olwork, err)	44
		4.6.2.7	form_qr_pivot(r, tau, pvt, q, p, work, olwork, err)	44
		4.6.2.8	lu_factor(a, ipvt, err)	45
		4.6.2.9	mult_qr_mtx(lside, trans, a, tau, c, work, olwork, err)	46
		4.6.2.10	mult_qr_vec(trans, a, tau, c, work, olwork, err)	47

vi

		4.6.2.11	mult_rz_mtx(lside, trans, I, a, tau, c, work, olwork, err)	48
		4.6.2.12	mult_rz_vec(trans, I, a, tau, c, work, olwork, err)	48
		4.6.2.13	qr_factor_no_pivot(a, tau, work, olwork, err)	49
		4.6.2.14	qr_factor_pivot(a, tau, jpvt, work, olwork, err)	51
		4.6.2.15	qr_rank1_update(q, r, u, v, work, err)	52
		4.6.2.16	rz_factor(a, tau, work, olwork, err)	53
		4.6.2.17	svd(a, s, u, vt, work, olwork, err)	54
4.7	linalg_	solve Mod	ule Reference	55
	4.7.1	Detailed	Description	56
	4.7.2	Function	Subroutine Documentation	57
		4.7.2.1	mtx_inverse(a, iwork, work, olwork, err)	57
		4.7.2.2	mtx_pinverse(a, ainv, tol, work, olwork, err)	58
		4.7.2.3	solve_cholesky_mtx(upper, a, b, err)	59
		4.7.2.4	solve_cholesky_vec(upper, a, b, err)	59
		4.7.2.5	solve_least_squares_mtx(a, b, work, olwork, err)	60
		4.7.2.6	solve_least_squares_mtx_pvt(a, b, ipvt, arnk, work, olwork, err)	60
		4.7.2.7	solve_least_squares_mtx_svd(a, b, arnk, s, work, olwork, err)	61
		4.7.2.8	solve_least_squares_vec(a, b, work, olwork, err)	62
		4.7.2.9	solve_least_squares_vec_pvt(a, b, ipvt, arnk, work, olwork, err)	63
		4.7.2.10	solve_least_squares_vec_svd(a, b, arnk, s, work, olwork, err)	64
		4.7.2.11	solve_lu_mtx(a, ipvt, b, err)	64
		4.7.2.12	solve_lu_vec(a, ipvt, b, err)	65
		4.7.2.13	solve_qr_no_pivot_mtx(a, tau, b, work, olwork, err)	65
		4.7.2.14	solve_qr_no_pivot_vec(a, tau, b, work, olwork, err)	66
		4.7.2.15	solve_qr_pivot_mtx(a, tau, jpvt, b, work, olwork, err)	67
		4.7.2.16	solve_qr_pivot_vec(a, tau, jpvt, b, work, olwork, err)	67
		4.7.2.17	solve_tri_mtx(lside, upper, trans, nounit, alpha, a, b, err)	68
		4.7.2.18	solve_tri_vec(upper, trans, nounit, a, x, err)	69

CONTENTS vii

5	Data	Type [ocumentation		71
	5.1	linalg_	core::diag_mtx_m	ult Interface Reference	71
		5.1.1	Detailed Descrip	tion	71
		5.1.2	Member Function	n/Subroutine Documentation	71
			5.1.2.1 diag_n	mtx_mult_mtx(lside, trans, alpha, a, b, beta, c, err)	71
			5.1.2.2 diag_n	mtx_mult_mtx2(lside, alpha, a, b, err)	72
			5.1.2.3 diag_n	mtx_mult_mtx3(lside, trans, alpha, a, b, beta, c, err)	73
			5.1.2.4 diag_n	mtx_mult_mtx4(lside, trans, alpha, a, b, beta, c, err)	73
	5.2	lapack	:DLAMCH Interfac	ce Reference	74
		5.2.1	Detailed Descrip	tion	74
	5.3	linalg_	eigen::eigen Interf	ace Reference	74
		5.3.1	Detailed Descrip	tion	75
		5.3.2	Member Function	n/Subroutine Documentation	75
			5.3.2.1 eigen_	_asymm(a, vals, vecs, work, olwork, err)	75
			5.3.2.2 eigen_	gen(a, b, alpha, beta, vecs, work, olwork, err)	76
			5.3.2.3 eigen_	_symm(vecs, a, vals, work, olwork, err)	77
	5.4	linalg_	actor::form_lu Inte	erface Reference	78
		5.4.1	Detailed Descrip	tion	78
		5.4.2	Member Function	n/Subroutine Documentation	78
			5.4.2.1 form_l	u_all(lu, ipvt, u, p, err)	78
			5.4.2.2 form_l	u_only(lu, u, err)	79
	5.5	linalg_	actor::form_qr Inte	erface Reference	79
		5.5.1	Detailed Descrip	tion	80
		5.5.2	Member Function	n/Subroutine Documentation	80
			5.5.2.1 form_c	qr_no_pivot(r, tau, q, work, olwork, err)	80
			5.5.2.2 form_c	qr_pivot(r, tau, pvt, q, p, work, olwork, err)	81
	5.6	linalg_	core::mtx_mult Inte	erface Reference	82
		5.6.1	Detailed Descrip	tion	82
		5.6.2	Member Function	n/Subroutine Documentation	82
			5.6.2.1 mtx_m	nult_mtx(transa, transb, alpha, a, b, beta, c, err)	82

viii CONTENTS

		5.6.2.2	mtx_mult_vec(trans, alpha, a, b, beta, c, err)	83
5.7	linalg_f	actor::mul	t_qr Interface Reference	83
	5.7.1	Detailed	Description	83
	5.7.2	Member	Function/Subroutine Documentation	84
		5.7.2.1	mult_qr_mtx(lside, trans, a, tau, c, work, olwork, err)	84
		5.7.2.2	mult_qr_vec(trans, a, tau, c, work, olwork, err)	84
5.8	linalg_f	actor::mul	t_rz Interface Reference	85
	5.8.1	Detailed	Description	85
	5.8.2	Member	Function/Subroutine Documentation	86
		5.8.2.1	mult_rz_mtx(lside, trans, I, a, tau, c, work, olwork, err)	86
		5.8.2.2	mult_rz_vec(trans, I, a, tau, c, work, olwork, err)	86
5.9	linalg_f	actor::qr_f	actor Interface Reference	87
	5.9.1	Detailed	Description	88
	5.9.2	Member	Function/Subroutine Documentation	88
		5.9.2.1	qr_factor_no_pivot(a, tau, work, olwork, err)	88
		5.9.2.2	qr_factor_pivot(a, tau, jpvt, work, olwork, err)	89
5.10	linalg_s	solve::solv	e_cholesky Interface Reference	91
	5.10.1	Detailed	Description	91
	5.10.2	Member	Function/Subroutine Documentation	91
		5.10.2.1	solve_cholesky_mtx(upper, a, b, err)	91
		5.10.2.2	solve_cholesky_vec(upper, a, b, err)	91
5.11	linalg_s	solve::solv	e_least_squares Interface Reference	92
	5.11.1	Detailed	Description	92
	5.11.2	Member	Function/Subroutine Documentation	92
		5.11.2.1	solve_least_squares_mtx(a, b, work, olwork, err)	92
		5.11.2.2	solve_least_squares_vec(a, b, work, olwork, err)	93
5.12	linalg_s	solve::solv	e_least_squares_full Interface Reference	94
	5.12.1	Detailed	Description	94
	5.12.2	Member	Function/Subroutine Documentation	94
		5.12.2.1	solve_least_squares_mtx_pvt(a, b, ipvt, arnk, work, olwork, err)	94

CONTENTS

		5.12.2.2	solve_least_squares_vec_pvt(a, b, ipvt, arnk, work, olwork, err)	95
5.13	linalg_s	solve::solv	re_least_squares_svd Interface Reference	96
	5.13.1	Detailed	Description	96
	5.13.2	Member	Function/Subroutine Documentation	97
		5.13.2.1	solve_least_squares_mtx_svd(a, b, arnk, s, work, olwork, err)	97
		5.13.2.2	solve_least_squares_vec_svd(a, b, arnk, s, work, olwork, err)	97
5.14	linalg_s	solve::solv	re_lu Interface Reference	98
	5.14.1	Detailed	Description	99
	5.14.2	Member	Function/Subroutine Documentation	99
		5.14.2.1	solve_lu_mtx(a, ipvt, b, err)	99
		5.14.2.2	solve_lu_vec(a, ipvt, b, err)	100
5.15	linalg_s	solve::solv	re_qr Interface Reference	100
	5.15.1	Detailed	Description	100
	5.15.2	Member	Function/Subroutine Documentation	101
		5.15.2.1	solve_qr_no_pivot_mtx(a, tau, b, work, olwork, err)	101
		5.15.2.2	solve_qr_no_pivot_vec(a, tau, b, work, olwork, err)	101
		5.15.2.3	solve_qr_pivot_mtx(a, tau, jpvt, b, work, olwork, err)	102
		5.15.2.4	solve_qr_pivot_vec(a, tau, jpvt, b, work, olwork, err)	103
5.16	linalg_s	solve::solv	re_triangular_system Interface Reference	103
	5.16.1	Detailed	Description	104
	5.16.2	Member	Function/Subroutine Documentation	104
		5.16.2.1	solve_tri_mtx(lside, upper, trans, nounit, alpha, a, b, err)	104
		5.16.2.2	solve_tri_vec(upper, trans, nounit, a, x, err)	105
Index				107

Chapter 1

Main Page

1.1 Introduction

LINALG is a linear algebra library that provides a user-friendly interface to several BLAS and LAPACK routines.

Author

Jason Christopherson

Version

1.1.0

2 Main Page

Chapter 2

Modules Index

2.1 Modules List

Here is a list of all documented modules with brief descriptions:

lapack	
lapack	7
linalg_c_binding	
linalg_c_binding	7
linalg_constants	
linalg_constants	26
linalg_core	
linalg_core	27
linalg_eigen	
linalg_eigen	35
linalg_factor	
linalg_factor	39
linalg_solve	
linalg_solve	55

4 Modules Index

Chapter 3

Data Type Index

3.1 Data Types List

Here are the data types with brief descriptions:

linalg_core::diag_mtx_mult	
Multiplies a diagonal matrix with another matrix or array	71
lapack::DLAMCH	74
linalg_eigen::eigen	
Computes the eigenvalues, and optionally the eigenvectors, of a matrix	74
linalg_factor::form_lu	
Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor .	78
linalg_factor::form_qr	
Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base	
QR factorization algorithm	79
linalg_core::mtx_mult	
Performs the matrix operation: $C = alpha * op(A) * op(B) + beta * C \dots \dots \dots \dots$	82
linalg_factor::mult_qr	
Multiplies a general matrix by the orthogonal matrix Q from a QR factorization	83
linalg_factor::mult_rz	
Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization	85
linalg_factor::qr_factor	
Computes the QR factorization of an M-by-N matrix	87
linalg_solve::solve_cholesky	
Solves a system of Cholesky factored equations	91
linalg_solve::solve_least_squares	
Solves the overdetermined or underdetermined system $(A*X = B)$ of M equations of N unknowns	92
linalg_solve::solve_least_squares_full	
Solves the overdetermined or underdetermined system ($A*X = B$) of M equations of N unknowns,	
but uses a full orthogonal factorization of the system	94
linalg_solve::solve_least_squares_svd	
Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns	•
using a singular value decomposition of matrix A	96
linalg_solve::solve_lu	
Solves a system of LU-factored equations	98
linalg_solve::solve_qr	
Solves a system of M QR-factored equations of N unknowns	100
linalg_solve::solve_triangular_system	400
Solves a triangular system of equations	100

6 Data Type Index

Chapter 4

Module Documentation

4.1 lapack Module Reference

lapack

Data Types

• interface DLAMCH

4.1.1 Detailed Description

lapack

Purpose

Provides interfaces to various LAPACK routines.

4.2 linalg_c_binding Module Reference

linalg_c_binding

Functions/Subroutines

- subroutine mtx_mult_c (transa, transb, m, n, k, alpha, a, lda, b, ldb, beta, c)
 - Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.
- subroutine diag_mtx_mult_c (trans, m, n, alpha, na, a, mb, nb, b, beta, c, err)
 - Computes the matrix operation: C = alpha * A * op(B) + beta * C.
- subroutine diag_mtx_mult_cmplx_c (trans, m, n, alpha, na, a, mb, nb, b, beta, c, err)
 - Computes the matrix operation: C = alpha * A * op(B) + beta * C, where A and C are complex-valued.
- subroutine rank1_update_c (m, n, alpha, x, y, a)

Performs the rank-1 update to matrix A such that: A = alpha * X * Y * * T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.

pure real(dp) function trace_c (m, n, x)

Computes the trace of a matrix (the sum of the main diagonal elements).

integer(i32) function mtx_rank_c (m, n, a, err)

Computes the rank of a matrix.

real(dp) function det_c (n, a, err)

Computes the determinant of a square matrix.

subroutine swap_c (n, x, y)

Swaps the contents of two arrays.

- subroutine tri_mtx_mult_c (upper, n, alpha, a, beta, b, err)
- subroutine lu_factor_c (m, n, a, ni, ipvt, err)

Computes the LU factorization of an M-by-N matrix.

• subroutine form_lu_c (n, lu, ipvt, u, p)

Extracts the L, U, and P matrices from the output of the lu_factor routine.

• subroutine qr_factor_c (m, n, a, nt, tau, err)

Computes the QR factorization of an M-by-N matrix without pivoting.

• subroutine qr_factor_pivot_c (m, n, a, nt, tau, jpvt, err)

Computes the QR factorization of an M-by-N matrix with column pivoting such that A * P = Q * R.

• subroutine form_qr_c (m, n, r, nt, tau, q, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

subroutine form_qr_pivot_c (m, n, r, nt, tau, pvt, q, p, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

• subroutine mult_qr_c (trans, m, n, q, nt, tau, c, err)

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

• subroutine qr_rank1_update_c (m, n, q, r, u, v, err)

Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q * R, and A1 = A + U * V ** T such that A1 = Q1 * R1.

• subroutine cholesky_factor_c (n, a, upper, err)

Computes the Cholesky factorization of a symmetric, positive definite matrix.

subroutine cholesky_rank1_update_c (n, r, u, err)

Computes the rank 1 update to a Cholesky factored matrix (upper triangular).

• subroutine cholesky rank1 downdate c (n, r, u, err)

Computes the rank 1 downdate to a Cholesky factored matrix (upper triangular).

subroutine rz_factor_c (m, n, a, tau, err)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that $A = R * Z = (R \ 0) * Z$. Z is an orthogonal matrix of dimension N-by-N, and R is an M-by-M upper triangular matrix.

• subroutine mult_rz_c (trans, m, n, l, a, tau, c, err)

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

subroutine svd_c (m, n, a, ns, s, u, vt, err)

Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U * S * V * * T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

• subroutine solve tri mtx c (upper, trans, nounit, n, nrhs, alpha, a, b)

Solves one of the matrix equations: op(A) * X = alpha * B, where A is a triangular matrix.

subroutine solve_lu_c (n, nrhs, a, ipvt, b)

Solves a system of LU-factored equations.

• subroutine solve_qr_c (m, n, nrhs, a, tau, b, err)

Solves a system of M QR-factored equations of N unknowns where M >= N.

• subroutine solve_qr_pivot_c (m, n, nrhs, a, nt, tau, jpvt, mb, b, err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

• subroutine solve_cholesky_c (upper, n, nrhs, a, b)

Solves a system of Cholesky factored equations.

• subroutine mtx_inverse_c (n, a, err)

Computes the inverse of a square matrix.

• subroutine mtx_pinverse_c (m, n, a, ainv, err)

Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix.

• subroutine solve_least_squares_c (m, n, nrhs, a, mb, b, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

• subroutine eigen_symm_c (n, vecs, a, vals, err)

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

• subroutine eigen_asymm_c (n, a, vals, vecs, err)

Computes the eigenvalues, and the right eigenvectors of a square matrix.

• subroutine eigen_gen_c (n, a, b, alpha, beta, vecs, err)

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

4.2.1 Detailed Description

linalg_c_binding

Purpose

Provides a C friendly interface to the LINALG library.

4.2.2 Function/Subroutine Documentation

4.2.2.1 subroutine linalg_c_binding::cholesky_factor_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *a*, logical(c_bool), intent(in), value *upper*, type(c_ptr), intent(in), value *err*)

Computes the Cholesky factorization of a symmetric, positive definite matrix.

Parameters

in	n	The dimension of the matrix.
in,out	а	On input, the N-by-N matrix to factor. On output, the factored matrix is returned in either
		the upper or lower triangular portion of the matrix, dependent upon the value of upper.
in	upper	An optional input that, if specified, provides control over whether the factorization is computed as $A = U**T*U$ (set to true), or as $A = L*L**T$ (set to false). The default value is true such that $A = U**T*U$.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_MATRIX_FORMAT_ERROR: Occurs if a is not positive definite.

Definition at line 716 of file linalg c binding.f90.

4.2.2.2 subroutine linalg_c_binding::cholesky_rank1_downdate_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *r*, real(dp), dimension(n), intent(inout) *u*, type(c_ptr), intent(in), value *err*)

Computes the rank 1 downdate to a Cholesky factored matrix (upper triangular).

Parameters

in	n	The dimension of the matrix.
in,out	r	On input, the N-by-N upper triangular matrix R. On output, the updated matrix R1.
in,out	и	On input, the N-element update vector U. On output, the rotation sines used to transform R to
out	err	R1. A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_MATRIX_FORMAT_ERROR: Occurs if the downdated matrix is not positive definite.
		 LA_SINGULAR_MATRIX_ERROR: Occurs if r is singular.

Definition at line 790 of file linalg_c_binding.f90.

4.2.2.3 subroutine linalg_c_binding::cholesky_rank1_update_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *r*, real(dp), dimension(n), intent(inout) *u*, type(c_ptr), intent(in), value *err*)

Computes the rank 1 update to a Cholesky factored matrix (upper triangular).

Parameters

in	n	The dimension of the matrix.
in, out	r	On input, the N-by-N upper triangular matrix R. On output, the updated matrix R1.
in, out	и	On input, the N-element update vector U. On output, the rotation sines used to transform R to
		R1.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 751 of file linalg_c_binding.f90.

4.2.2.4 real(dp) function linalg_c_binding::det_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *a*, type(c_ptr), intent(in), value *err*)

Computes the determinant of a square matrix.

Parameters

in	n	The dimension of the matrix.
in,out	а	On input, the N-by-N matrix on which to operate. On output the contents are overwritten by the LU factorization of the original matrix.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if the input matrix is not square. LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 264 of file linalg_c_binding.f90.

4.2.2.5 subroutine linalg_c_binding::diag_mtx_mult_c (logical(c_bool), intent(in), value *trans*, integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), intent(in), value *alpha*, integer(i32), intent(in), value *na*, real(dp), dimension(na), intent(in) *a*, integer(i32), intent(in), value *mb*, integer(i32), intent(in), value *nb*, real(dp), dimension(mb, nb), intent(in) *b*, real(dp), intent(in), value *beta*, real(dp), dimension(m, n), intent(inout) *c*, type(c_ptr), intent(in), value *err*)

Computes the matrix operation: C = alpha * A * op(B) + beta * C.

Parameters

trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
m	The number of rows in matrix C.
n	The number of columns in matrix C.
alpha	The scalar multiplier to matrix A.
na	The length of a.
а	A MIN(M,P)-element array containing the diagonal elements of matrix A.
mb	The number of rows in matrix B.
nb	The number of columns in matrix B.
b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing
	dimension of B):
	• trans == true: LDB = N, TDB = P
	• trans == false: LDB = P, TDB = N
beta	The scalar multiplier to matrix C.
С	THe M-by-N matrix C.
err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
	m n alpha na a mb nb b

Definition at line 94 of file linalg_c_binding.f90.

4.2.2.6 subroutine linalg_c_binding::diag_mtx_mult_cmplx_c (logical(c_bool), intent(in), value trans, integer(i32), intent(in), value m, integer(i32), intent(in), value n, real(dp), intent(in), value alpha, integer(i32), intent(in), value na, complex(dp), dimension(na), intent(in) a, integer(i32), intent(in), value mb, integer(i32), intent(in), value nb, real(dp), dimension(mb, nb), intent(in) b, real(dp), intent(in), value beta, complex(dp), dimension(m, n), intent(inout) c, type(c_ptr), intent(in), value err)

Computes the matrix operation: C = alpha * A * op(B) + beta * C, where A and C are complex-valued.

Parameters

in	trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	m	The number of rows in matrix C.
in	n	The number of columns in matrix C.
in	alpha	The scalar multiplier to matrix A.
in	na	The length of a.
in	а	A MIN(M,P)-element array containing the diagonal elements of matrix A.
in	mb	The number of rows in matrix B.
in	nb	The number of columns in matrix B.
in	b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing
		dimension of B):
		• trans == true: LDB = N, TDB = P
		• trans == false: LDB = P, TDB = N
in	beta	The scalar multiplier to matrix C.
in,out	С	THe M-by-N matrix C.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.

Definition at line 143 of file linalg_c_binding.f90.

4.2.2.7 subroutine linalg_c_binding::eigen_asymm_c (integer(i32), intent(in), value n, real(dp), dimension(n,n), intent(inout) a, complex(dp), dimension(n), intent(out) vals, complex(dp), dimension(n,n), intent(out) vecs, type(c_ptr), intent(in), value err)

Computes the eigenvalues, and the right eigenvectors of a square matrix.

in	n	The dimension of the matrix.
in,out	а	On input, the N-by-N matrix on which to operate. On output, the contents of this matrix are
		overwritten.
out	vals	An N-element array containing the eigenvalues of the matrix on output. The eigenvalues
		are not sorted.
out	vecs	An N-by-N matrix containing the right eigenvectors (one per column) on output.

Parameters

in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Definition at line 1281 of file linalg_c_binding.f90.

4.2.2.8 subroutine linalg_c_binding::eigen_gen_c (integer(i32), intent(in), value *n*, real(dp), dimension(n, n), intent(inout) *a*, real(dp), dimension(n, n), intent(inout) *b*, complex(dp), dimension(n), intent(out) *alpha*, real(dp), dimension(n), intent(out) *beta*, complex(dp), dimension(n,n), intent(out) *vecs*, type(c_ptr), intent(in), value *err*)

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

Parameters

in	n	The dimension of the matrix.
in, out	а	On input, the N-by-N matrix A. On output, the contents of this matrix are overwritten.
in, out	b	On input, the N-by-N matrix B. On output, the contents of this matrix are overwritten.
out	alpha	An N-element array that, on output, contains the numerator of the eigenvalue ration ALPHA / BETA. Computation of this ratio isn't necessarily as trivial as it seems as it is entirely possible, and likely, that ALPHA / BETA can overflow or underflow. With that said, the values in ALPHA will always be less than and usually comparable with the NORM(A).
out	beta	An N-element array that, on output, contains the denominator used to determine the eigenvalues as ALPHA / BETA. The values in this array will always be less than and usually comparable with the NORM(B).
out	vecs	An N-by-N matrix containing the right eigenvectors (one per column) on output.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Definition at line 1330 of file linalg_c_binding.f90.

4.2.2.9 subroutine linalg_c_binding::eigen_symm_c (integer(i32), intent(in), value *n*, logical(c_bool), intent(in), value *vecs*, real(dp), dimension(n,n), intent(inout) *a*, real(dp), dimension(n), intent(out) *vals*, type(c_ptr), intent(in), value *err*)

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

Parameters

in	n	The dimension of the matrix.
in	vecs	Set to true to compute the eigenvectors as well as the eigenvalues; else, set to false to just compute the eigenvalues.
in,out	а	On input, the N-by-N symmetric matrix on which to operate. On output, and if $vecs$ is set to true, the matrix will contain the eigenvectors (one per column) corresponding to each eigenvalue in $vals$. If $vecs$ is set to false, the lower triangular portion of the matrix is overwritten.
out	vals	An N-element array that will contain the eigenvalues sorted into ascending order.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Definition at line 1242 of file linalg_c_binding.f90.

4.2.2.10 subroutine linalg_c_binding::form_lu_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *lu*, integer(i32), dimension(n), intent(in) *ipvt*, real(dp), dimension(n,n), intent(out) *u*, real(dp), dimension(n,n), intent(out) *p*

Extracts the L, U, and P matrices from the output of the lu_factor routine.

Parameters

in	n	The dimension of the original matrix.
in,out	lu	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular
		matrix L.
in	ipvt	The N-element pivot array as output by lu_factor.
out	и	An N-by-N matrix where the U matrix will be written.
out	р	An N-by-N matrix where the row permutation matrix will be written.

Remarks

This routine allows extraction of the actual "L", "U", and "P" matrices of the decomposition. To use these matrices to solve the system A*X = B, the following approach is used.

- 1. First, solve the linear system: L*Y = P*B for Y.
- 2. Second, solve the linear system: U*X = Y for X.

Notice, as both L and U are triangular in structure, the above equations can be solved by forward and backward substitution.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 413 of file linalg_c_binding.f90.

4.2.2.11 subroutine linalg_c_binding::form_qr_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *r*, integer(i32), intent(in), value *nt*, real(dp), dimension(nt), intent(in) *tau*, real(dp), dimension(m,m), intent(out) *q*, type(c_ptr), intent(in), value *err*)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in	m	The number of rows in the original matrix.
in	n	The number of columns in the original matrix.
in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in r.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M > N$, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q * R = [Q1, Q2] * [R1; 0].
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if the scalar factor array is not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 541 of file linalg_c_binding.f90.

4.2.2.12 subroutine linalg_c_binding::form_qr_pivot_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *r*, integer(i32), intent(in), value *nt*, real(dp), dimension(nt), intent(in) *tau*, integer(i32), dimension(n), intent(in) *pvt*, real(dp), dimension(m,m), intent(out) *q*, real(dp), dimension(n,n), intent(out) *p*, type(c_ptr), intent(in), value *err*)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

in	m	The number of rows in the original matrix.
in	n	The number of columns in the original matrix.
in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined
		inr.

Parameters

in	pvt	An N-element column pivot array as returned by the QR factorization.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M>N$,
		Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as $Q * R = [Q1, Q2] * [R1; 0]$.
out	р	An N-by-N matrix where the pivot matrix will be written.
	<u> </u>	·
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if the scalar factor array is not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 592 of file linalg_c_binding.f90.

4.2.2.13 subroutine linalg_c_binding::lu_factor_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, integer(i32), intent(in), value *ni*, integer(i32), dimension(ni), intent(out) *ipvt*, type(c_ptr), intent(in), value *err*)

Computes the LU factorization of an M-by-N matrix.

Parameters

in	m	The number of rows in the matrix.
in	n	The number of columns in the matrix.
in,out	а	On input, the M-by-N matrix on which to operate. On output, the LU factored matrix in the form [L\U] where the unit diagonal elements of L are not stored.
in	ni	The number of elements in the pivot array ipvt. This value must be equal to MIN(M, N).
out	ipvt	An MIN(M, N)-element array used to track row-pivot operations. The array stored pivot information such that row I is interchanged with row IPVT(I).
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if the pivot array is not sized appropriately. LA_SINGULAR_MATRIX_ERROR: Occurs as a warning if a is found to be singular.

Definition at line 367 of file linalg_c_binding.f90.

4.2.2.14 subroutine linalg_c_binding::mtx_inverse_c (integer(i32), intent(in), value *n*, real(dp), dimension(n,n), intent(inout) *a*, type(c_ptr), intent(in), value *err*)

Computes the inverse of a square matrix.

in	n	The dimension of the matrix.
----	---	------------------------------

Parameters

in,out	а	On input, the N-by-N matrix to invert. On output, the inverted matrix.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. LA_SINCLUAR_MATRIX_ERROR: Occurs if the input metrix is singular.
		LA_SINGULAR_MATRIX_ERROR: Occurs if the input matrix is singular.

Definition at line 1122 of file linalg_c_binding.f90.

4.2.2.15 subroutine linalg_c_binding::mtx_mult_c (logical(c_bool), intent(in), value transa, logical(c_bool), intent(in), value transb, integer(i32), intent(in), value m, integer(i32), intent(in), value n, integer(i32), intent(in), value k, real(dp), intent(in), value alpha, real(dp), dimension(lda,*), intent(in) a, integer(i32), intent(in), value lda, real(dp), dimension(ldb,*), intent(in) b, integer(i32), intent(in), value ldb, real(dp), intent(in), value beta, real(dp), dimension(m,n), intent(inout) c)

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Parameters

in	transa	Set to true if $op(A) == A**T$; else, set to false if $op(A) == A$.
in	transb	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	m	The number of rows in matrix C, and the number of rows in matrix op(A).
in	n	The number of columns in matrix C, and the number of columns in matrix op(B).
in	k	The number of columns in matrix op(A), and the number of rows in the matrix op(B).
in	alpha	The scalar multiplier to matrix A.
in	а	The M-by-K matrix A.
in	lda	The leading dimension of matrix A. If transa is true, this value must be at least MAX(1, K); else, if transa is false, this value must be at least MAX(1, M).
in	b	The K-by-N matrix B.
in	ldb	The leading dimension of matrix B. If transb is true, this value must be at least MAX(1, N); else, if transb is false, this value must be at least MAX(1, K).
in	beta	The scalar multiplier to matrix C.
in,out	С	The M-by-N matrix C.

Definition at line 45 of file linalg_c_binding.f90.

4.2.2.16 subroutine linalg_c_binding::mtx_pinverse_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, real(dp), dimension(n,m), intent(out) *ainv*, type(c_ptr), intent(in), value *err*)

Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix.

in m The number of rows in the matrix to invert.
--

Parameters

in	n	The number of columns in the matrix to invert.
in,out	а	On input, the M-by-N matrix to invert. The matrix is overwritten on output.
out	ainv	The N-by-M matrix where the pseudo-inverse of a will be written.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Definition at line 1158 of file linalg_c_binding.f90.

4.2.2.17 integer(i32) function linalg_c_binding::mtx_rank_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, type(c_ptr), intent(in), value *err*)

Computes the rank of a matrix.

Parameters

in	m	The number of rows in the matrix.
in	n	The number of columns in the matrix.
in, out	а	On input, the M-by-N matrix of interest. On output, the contents of the matrix are overwritten.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Definition at line 231 of file linalg_c_binding.f90.

4.2.2.18 subroutine linalg_c_binding::mult_qr_c (logical(c_bool), intent(in), value *trans*, integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,m), intent(inout) *q*, integer(i32), intent(in), value *nt*, real(dp), dimension(m,n), intent(inout) *c*, type(c_ptr), intent(in), value *err*)

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

in	trans	Set to true to apply Q**T; else, set to false.
----	-------	--

Parameters

in	m	The number of rows in the matrix c.
in	n	The number of columns in the matrix c.
in	q	On input, an M-by-M matrix containing the elementary reflectors output from the QR factorization. Notice, the contents of this matrix are restored on exit. that the remaining matrix is simply the M-by-N matrix R.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
in	tau	A MIN(M,N)-element array containing the scalar factors of each elementary reflector defined in a.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Q and the original matrix C.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if the scalar factor array is not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 639 of file linalg_c_binding.f90.

4.2.2.19 subroutine linalg_c_binding::mult_rz_c (logical(c_bool), intent(in), value *trans*, integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, integer(i32), intent(in), value *l*, real(dp), dimension(m,m), intent(inout) *a*, real(dp), dimension(m), intent(in) *tau*, real(dp), dimension(m,n), intent(inout) *c*, type(c_ptr), intent(in), value *err*)

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

Parameters

in	trans	Set to true to apply Z**T; else, set to false.
in	m	The number of rows in the matrix c.
in	n	The number of columns in the matrix c.
in	1	The number of columns in matrix a containing the meaningful part of the Householder vectors (M $>=$ L $>=$ 0).
in,out	а	On input, the M-by-M matrix Z as output by rz_factor . The matrix is used as in-place storage during execution; however, the contents of the matrix are restored on exit.
in	tau	An M-element array containing the scalar factors of the elementary reflectors found in a.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Z and the original matrix C.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 871 of file linalg_c_binding.f90.

4.2.2.20 subroutine linalg_c_binding::qr_factor_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *m*, real(dp), dimension(mt), intent(out) *a*, integer(i32), intent(in), value *nt*, real(dp), dimension(nt), intent(out) *tau*, type(c_ptr), intent(in), value *err*)

Computes the QR factorization of an M-by-N matrix without pivoting.

Parameters

in	m	The number of rows in the matrix.
in	n	The number of columns in the matrix.
in,out	а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
out	tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if the scalar factor array is not sized appropriately. LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and
		there is insufficient memory available.

Definition at line 447 of file linalg_c_binding.f90.

4.2.2.21 subroutine linalg_c_binding::qr_factor_pivot_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, integer(i32), intent(in), value *nt*, real(dp), dimension(nt), intent(out) *tau*, integer(i32), dimension(n), intent(inout) *jpvt*, type(c_ptr), intent(in), value *err*)

Computes the QR factorization of an M-by-N matrix with column pivoting such that A * P = Q * R.

in	m	The number of rows in the matrix.
in	n	The number of columns in the matrix.
in,out	а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
out	tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in,out	jpvt	On input, an N-element array that if $JPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $JPVT(I) = 0$, the I-th column of A is a free column. On output, if $JPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A.

Parameters

in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if the scalar factor array is not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 494 of file linalg_c_binding.f90.

4.2.2.22 subroutine linalg_c_binding::qr_rank1_update_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,m), intent(inout) *q*, real(dp), dimension(m,n), intent(inout) *r*, real(dp), dimension(m), intent(inout) *v*, type(c_ptr), intent(in), value *err*)

Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q * R, and A1 = A + U * V**T such that A1 = Q1 * R1.

Parameters

in	m	The number of rows in the original matrix.
in	n	The number of columns in the original matrix.
in,out	q	On input, the original M-by-M orthogonal matrix Q. On output, the updated matrix Q1.
in,out	r	On input, the M-by-N matrix R. On output, the updated matrix R1.
in,out	и	On input, the M-element U update vector. On output, the original content of the array is overwritten.
in,out	V	On input, the N-element V update vector. On output, the original content of the array is overwritten.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 680 of file linalg_c_binding.f90.

4.2.2.23 subroutine linalg_c_binding::rank1_update_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), intent(in), value *alpha*, real(dp), dimension(m), intent(in) *x*, real(dp), dimension(n), intent(in) *y*, real(dp), dimension(m,n), intent(inout) *a*)

Performs the rank-1 update to matrix A such that: A = alpha * X * Y * * T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.

in	m	The number of elements in \mathbf{x} , and the number of rows in matrix \mathbf{a} .
in	n	The number of elements in y , and the number of columns in matrix a .
in	alpha	The scalar multiplier.

Parameters

	in	X	An M-element array.
Ī	in	У	An N-element array.
Ī	in,out	а	On input, the M-by-N matrix to update. On output, the updated M-by-N matrix.

Notes

This routine is based upon the BLAS routine DGER.

Definition at line 184 of file linalg_c_binding.f90.

4.2.2.24 subroutine linalg_c_binding::rz_factor_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, real(dp), dimension(m), intent(out) *tau*, type(c_ptr), intent(in), value *err*)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that $A = R * Z = (R \ 0) * Z$. Z is an orthogonal matrix of dimension N-by-N, and R is an M-by-M upper triangular matrix.

Parameters

in	m	The number of roug in the original matrix
T11	m	The number of rows in the original matrix.
in	n	The number of columns in the original matrix.
in,out	а	On input, the M-by-N upper trapezoidal matrix to factor. On output, the leading M-by-M upper triangular part of the matrix contains the upper triangular matrix R, and elements N-L+1 to N of the first M rows of A, with the array tau, represent the orthogonal matrix Z as a product of M elementary reflectors.
out	tau	An M-element array used to store the scalar factors of the elementary reflectors.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 829 of file linalg_c_binding.f90.

4.2.2.25 subroutine linalg_c_binding::solve_cholesky_c (logical(c_bool), intent(in), value *upper*, integer(i32), intent(in), value *n*, integer(i32), intent(in), value *nrhs*, real(dp), dimension(n,n), intent(in) *a*, real(dp), dimension(n,nrhs), intent(inout) *b*)

Solves a system of Cholesky factored equations.

in	upper	Set to true if the original matrix A was factored such that $A = U**T*U$; else, set to false if the factorization of A was $A = L**T*L$.
in	n	The dimension of the original matrix a.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in	а	The N-by-N Cholesky factored matrix.
in, out	b	On input, the N-by-NRHS right-hand-side matrix B. On output, the solution matrix X.

Definition at line 1098 of file linalg_c_binding.f90.

4.2.2.26 subroutine linalg_c_binding::solve_least_squares_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *nrhs*, real(dp), dimension(m, n), intent(inout) *a*, integer(i32), intent(in), value *mb*, real(dp), dimension(mb, nrhs), intent(inout) *b*, type(c_ptr), intent(in), value *err*)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in	m	The number of rows in the original coefficient matrix A.
in	n	The number of columns in the original coefficient matrix A.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in	mb	The number of rows in the matrix b. This value must be equal to MAX(M, N).
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 1201 of file linalg_c_binding.f90.

4.2.2.27 subroutine linalg_c_binding::solve_lu_c (integer(i32), intent(in), value *n*, integer(i32), intent(in), value *nrhs*, real(dp), dimension(n,n), intent(in) *a*, integer(i32), dimension(n), intent(in) *ipvt*, real(dp), dimension(n,nrhs), intent(inout) *b*)

Solves a system of LU-factored equations.

Parameters

in	n	The dimension of the original matrix a.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in	а	The N-by-N LU factored matrix as output by lu_factor.
in	ipvt	The N-element pivot array as output by lu_factor.
in,out	b	On input, the N-by-NRHS right-hand-side matrix. On output, the N-by-NRHS solution matrix.

Definition at line 983 of file linalg_c_binding.f90.

4.2.2.28 subroutine linalg_c_binding::solve_qr_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *nrhs*, real(dp), dimension(m,n), intent(inout) *a*, real(dp), dimension(n), intent(in) *tau*, real(dp), dimension(m,nrhs), intent(inout) *b*, type(c_ptr), intent(in), value *err*)

Solves a system of M QR-factored equations of N unknowns where M >= N.

Parameters

in	m	The number of rows in the original coefficient matrix A.
in	n	The number of columns in the original coefficient matrix A.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	b	On input, the M-by-NRHS right-hand-side matrix. On output, the first N columns are overwritten by the solution matrix X.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 1016 of file linalg_c_binding.f90.

4.2.2.29 subroutine linalg_c_binding::solve_qr_pivot_c (integer(i32), intent(in), value m, integer(i32), intent(in), value nr, integer(i32), intent(in), value nrhs, real(dp), dimension(m,n), intent(inout) a, integer(i32), intent(in), value nt, real(dp), dimension(nt), intent(in) tau, integer(i32), dimension(n), intent(in) jpvt, integer(i32), intent(in), value mb, real(dp), dimension(mb,nrhs), intent(inout) b, type(c_ptr), intent(in), value err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

in	m	The number of rows in the original coefficient matrix A.
T11	111	<u> </u>
in	n	The number of columns in the original coefficient matrix A.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	nt	The number of elements in the scalar factor array tau. This value must be equal to MIN(M, N).
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	jpvt	An N-element array, as output by qr_factor, used to track the column pivots.
in	mb	The number of rows in the matrix b. This value must be equal to MAX(M, N).
in	b	On input, the MAX(M, N)-by-NRHS matrix where the first M rows contain the right-hand-side matrix B. On output, the first N rows are overwritten by the solution matrix X.
in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Definition at line 1065 of file linalg_c_binding.f90.

4.2.2.30 subroutine linalg_c_binding::solve_tri_mtx_c (logical(c_bool), intent(in), value *upper*, logical(c_bool), intent(in), value *trans*, logical(c_bool), intent(in), value *nounit*, integer(i32), intent(in), value *n*, integer(i32), intent(in), value *nrhs*, real(dp), intent(in), value *alpha*, real(dp), dimension(n,n), intent(in) *a*, real(dp), dimension(n,nrhs), intent(inout) *b*)

Solves one of the matrix equations: op(A) * X = alpha * B, where A is a triangular matrix.

Parameters

in	upper	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	trans	Set to true if $op(A) = A**T$; else, set to false if $op(A) = A$.
in	nounit	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	n	The dimension of the triangular matrix a.
in	nrhs	The number of right-hand-side vectors (number of columns in matrix b).
in	alpha	The scalar multiplier to B.
in	а	N-by-N triangular matrix on which to operate.
in,out	b	On input, the N-by-NRHS right-hand-side. On output, the N-by-NRHS solution.

Definition at line 960 of file linalg_c_binding.f90.

4.2.2.31 subroutine linalg_c_binding::svd_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(inout) *a*, integer(i32), intent(in), value *ns*, real(dp), dimension(ns), intent(out) *s*, real(dp), dimension(m,m), intent(out) *u*, real(dp), dimension(n,n), intent(out) *vt*, type(c_ptr), intent(in), value *err*)

Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U * S * V * * T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

in	m	The number of rows in the original matrix.
in	n	The number of columns in the original matrix.
in,out	а	On input, the M-by-N matrix to factor. The matrix is overwritten on output. that the remaining matrix is simply the M-by-N matrix R.
in	ns	The number of elements in the singular value array s. This value must be equal to MIN(M, N).
out	s	A MIN(M, N)-element array containing the singular values of a sorted in descending order.
out	и	An M-by-M matrix that on output contains the left singular vectors (matrix U in the decomposition: $A = U * S * V * * T$)
out	vt	An N-by-N matrix that on output contains the right singular vectors (matrix $V**T$ in the decomposition: $A = U * S * V**T$).

Parameters

in	err	A pointer to the C error handler object. If no error handling is desired, simply pass NULL, and errors will be dealt with by the default internal error handler. Possible errors that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if the singular value array is not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Definition at line 920 of file linalg_c_binding.f90.

4.2.2.32 subroutine linalg_c_binding::swap_c (integer(i32), intent(in), value n, real(dp), dimension(n), intent(inout) x, real(dp), dimension(n), intent(inout) y)

Swaps the contents of two arrays.

Parameters

in	n	The number of elements either array.
in,out	X	One of the N-element arrays.
in,out	У	The other N-element array.

Definition at line 289 of file linalg_c_binding.f90.

4.2.2.33 pure real(dp) function linalg_c_binding::trace_c (integer(i32), intent(in), value *m*, integer(i32), intent(in), value *n*, real(dp), dimension(m,n), intent(in) *x*)

Computes the trace of a matrix (the sum of the main diagonal elements).

Parameters

in	m	The number of rows in the matrix.
in	n	The number of columns in the matrix.
in	Х	The matrix on which to operate.

Returns

The trace of x.

Definition at line 204 of file linalg_c_binding.f90.

4.3 linalg_constants Module Reference

linalg_constants

Variables

• integer, parameter dp = c_double

Defines a double-precision (64-bit) floating-point type.

• integer, parameter i32 = c_int

Defines a 32-bit signed integer type.

• integer, parameter la_invalid_input_error = 101

An error flag denoting an invalid input.

• integer, parameter la_array_size_error = 102

An error flag denoting an improperly sized array.

• integer, parameter la_singular_matrix_error = 103

An error flag denoting a singular matrix.

integer, parameter la_matrix_format_error = 104

An error flag denoting an issue with the matrix format.

• integer, parameter la_out_of_memory_error = 105

An error flag denoting that there is insufficient memory available.

• integer, parameter la_convergence_error = 106

An error flag denoting a convergence failure.

• integer, parameter la_invalid_operation_error = 107

An error resulting from an invalid operation.

4.3.1 Detailed Description

linalg_constants

Purpose

Provides a set of constants and error flags for the library.

4.4 linalg_core Module Reference

linalg_core

Data Types

interface diag_mtx_mult

Multiplies a diagonal matrix with another matrix or array.

• interface mtx mult

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Functions/Subroutines

• subroutine mtx_mult_mtx (transa, transb, alpha, a, b, beta, c, err)

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

• subroutine mtx_mult_vec (trans, alpha, a, b, beta, c, err)

Performs the matrix-vector operation: c = alpha * op(A) * b + beta * c.

• subroutine, public rank1_update (alpha, x, y, a, err)

Performs the rank-1 update to matrix A such that: A = alpha * X * Y * * T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.

• subroutine diag_mtx_mult_mtx (Iside, trans, alpha, a, b, beta, c, err)

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C.

• subroutine diag mtx mult mtx2 (Iside, alpha, a, b, err)

Computes the matrix operation: B = alpha * A * op(B), or B = alpha * op(B) * A.

subroutine diag mtx mult mtx3 (Iside, trans, alpha, a, b, beta, c, err)

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A and C are complex-valued.

• subroutine diag mtx mult mtx4 (Iside, trans, alpha, a, b, beta, c, err)

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A, B, and C are complex-valued.

• pure real(dp) function, public trace (x)

Computes the trace of a matrix (the sum of the main diagonal elements).

integer(i32) function, public mtx rank (a, tol, work, olwork, err)

Computes the rank of a matrix.

real(dp) function, public det (a, iwork, err)

Computes the determinant of a square matrix.

• subroutine, public swap (x, y, err)

Swaps the contents of two arrays.

• subroutine, public recip_mult_array (a, x)

Multiplies a vector by the reciprocal of a real scalar.

• subroutine, public tri mtx mult (upper, alpha, a, beta, b, err)

Computes the triangular matrix operation: B = alpha * A**T * A + beta * B, or B = alpha * A * A**T + beta * B, where A is a triangular matrix.

4.4.1 Detailed Description

linalg core

Purpose

Provides common "core" linear algebra routines.

4.4.2 Function/Subroutine Documentation

4.4.2.1 real(dp) function, public linalg_core::det (real(dp), dimension(:,:), intent(inout) a, integer(i32), dimension(:), intent(out), optional, pointer iwork, class(errors), intent(inout), optional, target err)

Computes the determinant of a square matrix.

Parameters

in,out	а	On input, the N-by-N matrix on which to operate. On output the contents are overwritten by the LU factorization of the original matrix.
out	iwork	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least N-elements.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Returns

The determinant of a.

Definition at line 1086 of file linalg_core.f90.

4.4.2.2 subroutine linalg_core::diag_mtx_mult_mtx (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp) *alpha*, real(dp), dimension(:), intent(in) *a*, real(dp), dimension(:,:), intent(in) *b*, real(dp) *beta*, real(dp), dimension(:,:), intent(inout) *c*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C.

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
in	b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing dimension of B):
		• lside == true & trans == true: LDB = N, TDB = P
		• lside == true & trans == false: LDB = P, TDB = N
		• lside == false & trans == true: LDB = P, TDB = M
		• lside == false & trans == false: LDB = M, TDB = P
in	beta	A scalar multiplier.
in,out	С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.

Definition at line 327 of file linalg_core.f90.

4.4.2.3 subroutine linalg_core::diag_mtx_mult_mtx2 (logical, intent(in) *lside*, real(dp), intent(in) *alpha*, real(dp), dimension(:), intent(in) *a*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: B = alpha * A * op(B), or B = alpha * op(B) * A.

Parameters

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
in	b	On input, the M-by-N matrix B. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 494 of file linalg_core.f90.

4.4.2.4 subroutine linalg_core::diag_mtx_mult_mtx3 (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* complex(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* complex(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A and C are complex-valued.

Iside	Cat to true to apply matrix A from the left, also not to falso to apply matrix A from the left
	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
alpha	A scalar multiplier.
а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing dimension of B): • lside == true & trans == true: LDB = N, TDB = P • lside == true & trans == false: LDB = P, TDB = N • lside == false & trans == true: LDB = P, TDB = M • lside == false & trans == false: LDB = M, TDB = P
beta	A scalar multiplier.
С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
	alpha a b

Parameters

out	err	An optional errors-based object that if provided can be used to retrieve information relating
		to any errors encountered during execution. If not provided, a default implementation of
		the errors class is used internally to provide error handling. Possible errors and warning
		messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 577 of file linalg_core.f90.

4.4.2.5 subroutine linalg_core::diag_mtx_mult_mtx4 (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp) *alpha*, complex(dp), dimension(:,:), intent(in) *b*, real(dp) *beta*, complex(dp), dimension(:,:), intent(inout) *c*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A, B, and C are complex-valued.

Parameters

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
in	b	The LDB-by-TDB matrix B where:
		• lside == true & trans == true: LDA = N, TDB = P
		• lside == true & trans == false: LDA = P, TDB = N
		• lside == false & trans == true: LDA = P, TDB = M
		• lside == false & trans == false: LDA = M, TDB = P
in	beta	A scalar multiplier.
in,out	С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 753 of file linalg_core.f90.

4.4.2.6 subroutine linalg_core::mtx_mult_mtx (logical, intent(in) *transa*, logical, intent(in) *transb*, real(dp), intent(in) *alpha*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:,:), intent(in) *b*, real(dp), intent(in) *beta*, real(dp), dimension(:,:), intent(inout) *c*, class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Parameters

in	transa	Set to true if $op(A) = A**T$; else, set to false for $op(A) = A$.
in	transb	Set to true if $op(B) = B**T$; else, set to false for $op(B) = B$.
in	alpha	A scalar multiplier.
in	а	If transa is set to true, an K-by-M matrix; else, if transa is set to false, an M-by-K matrix.
in	b	If transb is set to true, an N-by-K matrix; else, if transb is set to false, a K-by-N matrix.
in	beta	A scalar multiplier.
in, out	С	On input, the M-by-N matrix C. On output, the M-by-N result.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMM.

Definition at line 83 of file linalg_core.f90.

4.4.2.7 subroutine linalg_core::mtx_mult_vec (logical, intent(in) trans, real(dp), intent(in) alpha, real(dp), dimension(:,:), intent(in) a, real(dp), dimension(:), intent(in) b, real(dp), intent(in) beta, real(dp), dimension(:), intent(inout) c, class(errors), intent(inout), optional, target err) [private]

Performs the matrix-vector operation: c = alpha * op(A) * b + beta * c.

Parameters

in	trans	Set to true if $op(A) = A**T$; else, set to false for $op(A) = A$.
in	alpha	A scalar multiplier.
in	а	The M-by-N matrix A.
in	b	If trans is set to true, an M-element array; else, if trans is set to false, an N-element array.
in	beta	A scalar multiplier.
in,out	С	On input, if trans is set to true, an N-element array; else, if trans is set to false, an M-element array. On output, the results of the operation.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMV.

Definition at line 177 of file linalg_core.f90.

4.4.2.8 integer(i32) function, public linalg_core::mtx_rank (real(dp), dimension(:,:), intent(inout) *a,* real(dp), intent(in), optional *tol,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the rank of a matrix.

Parameters

in,out	а	On input, the M-by-N matrix of interest. On output, the contents of the matrix are overwritten.
in	tol	An optional input, that if supplied, overrides the default tolerance on singular values such that singular values less than this tolerance are treated as zero. The default tolerance is: $MAX(M, N) * EPS * MAX(S)$. If the supplied value is less than the smallest value that causes an overflow if inverted, the tolerance reverts back to its default value, and the operation continues; however, a warning message is issued.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

See Also

• Wolfram MathWorld

Definition at line 966 of file linalg_core.f90.

4.4.2.9 subroutine, public linalg_core::rank1_update (real(dp), intent(in) alpha, real(dp), dimension(:), intent(in) x, real(dp), dimension(:), intent(in) y, real(dp), dimension(:), intent(inout) a, class(errors), intent(inout), optional, target err)

Performs the rank-1 update to matrix A such that: A = alpha * X * Y * * T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.

in	alpha	The scalar multiplier.
in	X	An M-element array.

Parameters

in	У	An N-element array.
in,out	а	On input, the M-by-N matrix to update. On output, the updated M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if the size of a does not match with x and y.

Notes

This routine is based upon the BLAS routine DGER.

Definition at line 255 of file linalg_core.f90.

4.4.2.10 subroutine, public linalg_core::recip_mult_array (real(dp), intent(in) a, real(dp), dimension(:), intent(inout) x)

Multiplies a vector by the reciprocal of a real scalar.

Parameters

in	а	The scalar which is used to divide each component of X . The value must be $>=$ 0, or the subroutine will divide by zero.
in,out	X	The vector.

Notes

This routine is based upon the LAPACK routine DRSCL.

Definition at line 1237 of file linalg_core.f90.

4.4.2.11 subroutine, public linalg_core::swap (real(dp), dimension(:), intent(inout) x, real(dp), dimension(:), intent(inout) y, class(errors), intent(inout), optional, target *err*)

Swaps the contents of two arrays.

in,out	Х	One of the N-element arrays.
in,out	У	The other N-element array.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		• LA_ARRAY_SIZE_ERROR: Occurs if $\mathbf x$ and $\mathbf y$ are not the same size.

Definition at line 1191 of file linalg_core.f90.

4.4.2.12 pure real(dp) function, public linalg_core::trace (real(dp), dimension(:,:), intent(in) x)

Computes the trace of a matrix (the sum of the main diagonal elements).

Parameters

in	Х	The matrix on which to operate.
----	---	---------------------------------

Returns

The trace of x.

Definition at line 910 of file linalg_core.f90.

4.4.2.13 subroutine, public linalg_core::tri_mtx_mult (logical, intent(in) *upper*, real(dp), intent(in) *alpha*, real(dp), dimension(:,:), intent(in) *a*, real(dp), intent(in) *beta*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*)

Computes the triangular matrix operation: B = alpha * A**T * A + beta * B, or B = alpha * A * A**T + beta * B, where A is a triangular matrix.

Parameters

in	upper	Set to true if matrix A is upper triangular, and B = alpha $*$ A**T $*$ A + beta $*$ B is to be calculated; else, set to false if A is lower triangular, and B = alpha $*$ A $*$ A**T + beta $*$ B is to be computed.
in	alpha	A scalar multiplier.
in	а	The N-by-N triangular matrix. Notice, if upper is true only the upper triangular portion of this matrix is referenced; else, if upper is false, only the lower triangular portion of this matrix is referenced.
in	beta	A scalar multiplier.
in,out	b	On input, the N-by-N matrix B. On output, the N-by-N solution matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized
		appropriately.

Definition at line 1314 of file linalg_core.f90.

4.5 linalg_eigen Module Reference

linalg_eigen

Data Types

• interface eigen

Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

Functions/Subroutines

• subroutine eigen_symm (vecs, a, vals, work, olwork, err)

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

• subroutine eigen_asymm (a, vals, vecs, work, olwork, err)

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.

• subroutine eigen_gen (a, b, alpha, beta, vecs, work, olwork, err)

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

4.5.1 Detailed Description

linalg_eigen

Purpose

Provides routines for computing the eigenvalues and eigenvectors of matrices.

4.5.2 Function/Subroutine Documentation

4.5.2.1 subroutine linalg_eigen::eigen_asymm (real(dp), dimension(:,:), intent(inout) a, complex(dp), dimension(:), intent(out) vals, complex(dp), dimension(:,:), intent(out), optional vecs, real(dp), dimension(:), intent(out), optional, pointer work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.

in,out	а	On input, the N-by-N matrix on which to operate. On output, the contents of this matrix are overwritten.
out	vals	An N-element array containing the eigenvalues of the matrix. The eigenvalues are not sorted.
out	vecs	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DGEEV.

Definition at line 185 of file linalg_eigen.f90.

4.5.2.2 subroutine linalg_eigen::eigen_gen (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, complex(dp), dimension(:), intent(out) alpha, real(dp), dimension(:), intent(out), optional beta, complex(dp), dimension(:,:), intent(out), optional vecs, real(dp), dimension(:), intent(out), optional, pointer work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

Parameters

in,out	а	On input, the N-by-N matrix A. On output, the contents of this matrix are overwritten.
in,out	b	On input, the N-by-N matrix B. On output, the contents of this matrix are overwritten.
out	alpha	An N-element array that, if beta is not supplied, contains the eigenvalues. If beta is supplied however, the eigenvalues must be computed as ALPHA / BETA. This however, is not as trivial as it seems as it is entirely possible, and likely, that ALPHA / BETA can overflow or underflow. With that said, the values in ALPHA will always be less than and usually comparable with the NORM(A).
out	beta	An optional N-element array that if provided forces $alpha$ to return the numerator, and this array contains the denominator used to determine the eigenvalues as ALPHA / BETA. If used, the values in this array will always be less than and usually comparable with the NORM(B).
out	vecs	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Usage

As an example, consider the eigenvalue problem arising from a mechanical system of masses and springs such that the masses are described by a mass matrix M, and the arrangement of springs are described by a stiffness matrix K.

```
! Parameters real(dp), parameter :: pi = 3.141592653589793d0
```

```
! Variables
real(dp), dimension(n, n) :: m, k
complex(dp), dimension(n, n) :: mode_shapes
complex(dp), dimension(n) :: vals
real(dp), dimension(n) :: vals
real(dp), dimension(n) :: nat_freq

! Initialize the mass matrix (m) and the stiffness matrix (k)...
! Solve the eigenvalue problem. The eigenvectors define the mode shapes
! for the system (each eigenvector defines a different mode shape, and
! are stored one per column).
call eigen(k, m, vals, vecs = mode_shapes)
! The eigenvalues represent the square of the system natural frequencies.
! Also, a properly constrained mechanical system will exhibit only real
! eigenvalues; therefore, the following relationship will return the
! natural frequencies with units of Hz.
nat_freq = sqrt(real(vals, dp)) / (2.0d0 * pi)
```

Notes

This routine utilizes the LAPACK routine DGGEV.

Definition at line 426 of file linalg eigen.f90.

4.5.2.3 subroutine linalg_eigen::eigen_symm (logical, intent(in) *vecs*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(out), optional, pointer *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

in	vecs	Set to true to compute the eigenvectors as well as the eigenvalues; else, set to false to just compute the eigenvalues.
in,out	а	On input, the N-by-N symmetric matrix on which to operate. On output, and if $vecs$ is set to true, the matrix will contain the eigenvectors (one per column) corresponding to each eigenvalue in $vals$. If $vecs$ is set to false, the lower triangular portion of the matrix is overwritten.
out	vals	An N-element array that will contain the eigenvalues sorted into ascending order.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DSYEV.

Definition at line 68 of file linalg eigen.f90.

4.6 linalg_factor Module Reference

linalg_factor

Data Types

· interface form lu

Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.

interface form gr

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

· interface mult_qr

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.

· interface mult rz

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.

· interface qr factor

Computes the QR factorization of an M-by-N matrix.

Functions/Subroutines

subroutine, public lu_factor (a, ipvt, err)

Computes the LU factorization of an M-by-N matrix.

• subroutine form_lu_all (lu, ipvt, u, p, err)

Extracts the L, U, and P matrices from the output of the lu_factor routine.

• subroutine form_lu_only (lu, u, err)

Extracts the L, and U matrices from the output of the lu_factor routine.

• subroutine qr_factor_no_pivot (a, tau, work, olwork, err)

Computes the QR factorization of an M-by-N matrix without pivoting.

• subroutine qr_factor_pivot (a, tau, jpvt, work, olwork, err)

Computes the QR factorization of an M-by-N matrix with column pivoting such that A*P=Q*R.

• subroutine form_qr_no_pivot (r, tau, q, work, olwork, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

• subroutine form_qr_pivot (r, tau, pvt, q, p, work, olwork, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

• subroutine mult_qr_mtx (Iside, trans, a, tau, c, work, olwork, err)

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C, or C = C * op(Q).

subroutine mult_qr_vec (trans, a, tau, c, work, olwork, err)

Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

• subroutine, public qr_rank1_update (q, r, u, v, work, err)

Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q * R, and A1 = A + U * V ** T such that A1 = Q1 * R1.

subroutine, public cholesky_factor (a, upper, err)

Computes the Cholesky factorization of a symmetric, positive definite matrix.

• subroutine, public cholesky_rank1_update (r, u, work, err)

Computes the rank 1 update to a Cholesky factored matrix (upper triangular).

• subroutine, public cholesky_rank1_downdate (r, u, work, err)

Computes the rank 1 downdate to a Cholesky factored matrix (upper triangular).

• subroutine, public rz_factor (a, tau, work, olwork, err)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that $A = R * Z = (R \ 0) * Z$. Z is an orthogonal matrix of dimension N-by-N, and R is an M-by-M upper triangular matrix.

• subroutine mult_rz_mtx (Iside, trans, I, a, tau, c, work, olwork, err)

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C, or C = C * op(Z).

• subroutine mult_rz_vec (trans, I, a, tau, c, work, olwork, err)

Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

• subroutine, public svd (a, s, u, vt, work, olwork, err)

Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U * S * V * * T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

4.6.1 Detailed Description

linalg_factor

Purpose

Provides a set of matrix factorization routines.

4.6.2 Function/Subroutine Documentation

4.6.2.1 subroutine, public linalg_factor::cholesky_factor (real(dp), dimension(:,:), intent(inout) *a,* logical, intent(in), optional *upper,* class(errors), intent(inout), optional, target *err*)

Computes the Cholesky factorization of a symmetric, positive definite matrix.

ir	n,out	а	On input, the N-by-N matrix to factor. On output, the factored matrix is returned in either the upper or lower triangular portion of the matrix, dependent upon the value of upper.
ir	า	upper	An optional input that, if specified, provides control over whether the factorization is computed as $A = U**T*U$ (set to true), or as $A = L*L**T$ (set to false). The default value is true such that $A = U**T*U$.
01	ıt	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
			 LA_ARRAY_SIZE_ERROR: Occurs if a is not square. LA_MATRIX_FORMAT_ERROR: Occurs if a is not positive definite.

Usage

To solve a system of N equations of N unknowns using Cholesky factorization, the following code will suffice. Notice, the system of equations must be positive definite.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.
! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b
logical :: upper
! Initialize A and B...
! Specify that we're using the upper portion of A (remember positive
! definite matrices are symmetric)
upper = .true.
! Compute the factorization of A.
call cholesky_factor(a, upper)
! Solve A*X = B for X - Note: X overwrites B.
call solve_cholesky(upper, a, b)
```

Notes

This routine utilizes the LAPACK routine DPOTRF.

Definition at line 1308 of file linalg_factor.f90.

4.6.2.2 subroutine, public linalg_factor::cholesky_rank1_downdate (real(dp), dimension(:,:), intent(inout) *r*, real(dp), dimension(:), intent(inout) *u*, real(dp), dimension(:), intent(out), optional, target *work*, class(errors), intent(inout), optional, target *err*)

Computes the rank 1 downdate to a Cholesky factored matrix (upper triangular).

Parameters

in,out	r	On input, the N-by-N upper triangular matrix R. On output, the updated matrix R1.
in,out	и	On input, the N-element update vector U. On output, the rotation sines used to transform R
		to R1.
out	work	An optional argument that if supplied prevents local memory allocation. If provided, the
		array must have at least N elements. Additionally, this workspace array is used to contain
		the rotation cosines used to transform R to R1.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_MATRIX_FORMAT_ERROR: Occurs if the downdated matrix is not positive definite.
		LA_SINGULAR_MATRIX_ERROR: Occurs if r is singular.

Notes

This routine utilizes the QRUPDATE routine DCH1DN.

See Also

Source

Definition at line 1494 of file linalg_factor.f90.

4.6.2.3 subroutine, public linalg_factor::cholesky_rank1_update (real(dp), dimension(:,:), intent(inout) *r*, real(dp), dimension(:), intent(inout) *u*, real(dp), dimension(:), intent(out), optional, target *work*, class(errors), intent(inout), optional, target *err*)

Computes the rank 1 update to a Cholesky factored matrix (upper triangular).

Parameters

in,out	r	On input, the N-by-N upper triangular matrix R. On output, the updated matrix R1.
in,out	и	On input, the N-element update vector U. On output, the rotation sines used to transform R
		to R1.
out	work	An optional argument that if supplied prevents local memory allocation. If provided, the
		array must have at least N elements. Additionally, this workspace array is used to contain
		the rotation cosines used to transform R to R1.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the QRUPDATE routine DCH1UP.

See Also

Source

Definition at line 1400 of file linalg_factor.f90.

4.6.2.4 subroutine linalg_factor::form_lu_all (real(dp), dimension(:,:), intent(inout) *lu*, integer(i32), dimension(:), intent(in) *ipvt*, real(dp), dimension(:,:), intent(out) *u*, real(dp), dimension(:,:), intent(out) *p*, class(errors), intent(inout), optional, target err) [private]

Extracts the L, U, and P matrices from the output of the lu_factor routine.

in,out	lu	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
in	ipvt	The N-element pivot array as output by lu_factor.
out	и	An N-by-N matrix where the U matrix will be written.
out	р	An N-by-N matrix where the row permutation matrix will be written.

Parameters

out	err	An optional errors-based object that if provided can be used to retrieve information relating
		to any errors encountered during execution. If not provided, a default implementation of the
		errors class is used internally to provide error handling. Possible errors and warning
		messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Remarks

This routine allows extraction of the actual "L", "U", and "P" matrices of the decomposition. To use these matrices to solve the system A*X = B, the following approach is used.

- 1. First, solve the linear system: L*Y = P*B for Y.
- 2. Second, solve the linear system: U*X = Y for X.

Notice, as both L and U are triangular in structure, the above equations can be solved by forward and backward substitution.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 211 of file linalg_factor.f90.

4.6.2.5 subroutine linalg_factor::form_lu_only (real(dp), dimension(:,:), intent(inout) *lu*, real(dp), dimension(:,:), intent(out) *u*, class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, and U matrices from the output of the lu_factor routine.

Parameters

in,out	lu	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular
		matrix L.
out	и	An N-by-N matrix where the U matrix will be written.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 288 of file linalg_factor.f90.

4.6.2.6 subroutine linalg_factor::form_qr_no_pivot (real(dp), dimension(:,:), intent(inout) r, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:,:), intent(out) q, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in r.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M > N$, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as $Q * R = [Q1, Q2] * [R1; 0]$.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 694 of file linalg_factor.f90.

4.6.2.7 subroutine linalg_factor::form_qr_pivot (real(dp), dimension(:,:), intent(inout) r, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) pvt, real(dp), dimension(:,:), intent(out) q, real(dp), dimension(:,:), intent(out) p, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in r.
in	pvt	An N-element column pivot array as returned by the QR factorization.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M > N$, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as $Q * R = [Q1, Q2] * [R1; 0]$.
out	р	An N-by-N matrix where the pivot matrix will be written.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 825 of file linalg_factor.f90.

4.6.2.8 subroutine, public linalg_factor::lu_factor (real(dp), dimension(:,:), intent(inout) a, integer(i32), dimension(:), intent(out) ipvt, class(errors), intent(inout), optional, target err)

Computes the LU factorization of an M-by-N matrix.

in,out	а	On input, the M-by-N matrix on which to operate. On output, the LU factored matrix in the form [L\U] where the unit diagonal elements of L are not stored.
out	ipvt	An MIN(M, N)-element array used to track row-pivot operations. The array stored pivot information such that row I is interchanged with row IPVT(I).
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if ipvt is not sized appropriately. • LA_SINGULAR_MATRIX_ERROR: Occurs as a warning if a is found to be singular.

Usage

To solve a system of N equations of N unknowns using LU factorization, the following code will suffice.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.
! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b
! Define the array used to track row pivots.
integer(i32), dimension(n) :: pvt
! Initialize A and B...
! Compute the LU factorization of A. On output, A contains [L\U].
call lu_factor(a, pvt)
! Solve A*X = B for X - Note: X overwrites B.
call solve_lu(a, pvt, b)
```

Notes

This routine utilizes the LAPACK routine DGETRF.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 127 of file linalg_factor.f90.

4.6.2.9 subroutine linalg_factor::mult_qr_mtx (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(inout) *a*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C, or C = C * op(Q).

in	Iside	Set to true to apply Q or Q**T from the left; else, set to false to apply Q or Q**T from the right.
in	trans	Set to true to apply Q**T; else, set to false.
in	а	On input, an LDA-by-K matrix containing the elementary reflectors output from the QR factorization. If lside is set to true, LDA = M, and $M >= K >= 0$; else, if lside is set to false, LDA = N, and $N >= K >= 0$. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Q and the original matrix C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMQR.

Definition at line 927 of file linalg_factor.f90.

4.6.2.10 subroutine linalg_factor::mult_qr_vec (logical, intent(in) *trans*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(inout), intent(inout), intent(inout), intent(inout), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

Parameters

in	trans	Set to true to apply Q**T; else, set to false.
in	а	On input, an M-by-K matrix containing the elementary reflectors output from the QR factorization. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	С	On input, the M-element vector C. On output, the product of the orthogonal matrix Q and the original vector C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon the LAPACK routine DORM2R.

Definition at line 1054 of file linalg_factor.f90.

4.6.2.11 subroutine linalg_factor::mult_rz_mtx (logical, intent(in) *lside*, logical, intent(in) *trans*, integer(i32), intent(in) *l*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(inout) *tau*, real(dp), dimension(:), intent(inout) *c*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C, or C = C * op(Z).

Parameters

in	Iside	Set to true to apply Z or Z**T from the left; else, set to false to apply Z or Z**T from the right.
in	trans	Set to true to apply Z**T; else, set to false.
in	1	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, $M >= L >= 0$; else, if lside is false, $N >= L >= 0$.
in,out	а	On input the K-by-LTA matrix Z, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of the elementary reflectors, where $M \ge K \ge 0$ if lside is true; else, $N \ge K \ge 0$ if lside is false.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Z and the original matrix C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1745 of file linalg_factor.f90.

4.6.2.12 subroutine linalg_factor::mult_rz_vec (logical, intent(in) trans, integer(i32), intent(in) I, real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:), intent(inout) c, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

Parameters

in	trans	Set to true to apply Z**T; else, set to false.
in	1	The number of columns in matrix a containing the meaningful part of the Householder vectors. If $lside$ is true, $M >= L >= 0$; else, if $lside$ is false, $N >= L >= 0$.
in,out	а	On input the K-by-LTA matrix Z, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of the elementary reflectors, where $M \ge K \ge 0$ if lside is true; else, $N \ge K \ge 0$ if lside is false.
in,out	С	On input, the M-element array C. On output, the product of the orthogonal matrix Z and the original array C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized
		 appropriately. LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1887 of file linalg_factor.f90.

4.6.2.13 subroutine linalg_factor::qr_factor_no_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix without pivoting.

in,out	а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if tau or work are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Remarks

QR factorization without pivoting is best suited to solving an overdetermined system in least-squares terms, or to solve a normally defined system. To solve an underdetermined system, it is recommended to use either LQ factorization, or a column-pivoting based QR factorization.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice assuming $M \ge N$

```
! Solve the system: A*X = B in a least-squares sense, where A is an
! M-by-N matrix, B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.
! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, nrhs) :: b, qtb
real(dp), dimension(n, nrhs) :: x
real(dp), dimension(n) :: tau
real(dp), dimension(m, m) :: q
! Initialize A and B...
! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
 scalar factors in TAU. Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau)
! Solve A*X = B for X.
                        The first N rows of B are used to store X.
call solve_qr(a, tau, b)
! Also note, we could form Q and R explicitly. Then solution of the ! system of equations can be found. First we form Q and R.
call form_qr(a, tau, q) ! Forms Q, and R is stored in A
 Since we now have Q and R, we seek a solution to the equation:
  Q*R*X = B, but Q is an orthogonal matrix (i.e. Q**T = inv(Q))
! Then: R*X = Q**T * B, and R is upper triangular; therefore, back
! substitution will suffice for a solution procedure.
! Next, compute Q**T * B, and store in QTB.
call mtx_mult(.true., .false., 1.0d0, q, b, 0.0d0, qtb)
! Copy the first N rows of Q**T * B into X for the solution process.
! Notice, only the first N rows are needed as rows N+1:M are all zero in
! matrix R.
x = qtb(1:n,nrhs)
! Compute the solution and store in \boldsymbol{X}
call solve_triangular_system(.true., .true., .false., .true., 1.0d0, &
 a(1:n,1:n), x)
```

Notes

This routine utilizes the LAPACK routine DGEQRF.

Definition at line 425 of file linalg_factor.f90.

4.6.2.14 subroutine linalg_factor::qr_factor_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* integer(i32), dimension(:), intent(inout) *jpvt,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix with column pivoting such that A * P = Q * R.

Parameters

in,out	а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in,out	jpvt	On input, an N-element array that if $JPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $JPVT(I) = 0$, the I-th column of A is a free column. On output, if $JPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice for any M and N.

```
! Solve the least-squares (M \geq= N), or the underdetermined (M < N)
! problem A*X = B, where A is an M-by-N matrix, B is an M-by-NRHS matrix,
 and X is an N-by-NRHS matrix. In the underdetermined case, or the
 case where the rank of matrix A is less than N, the solution obtained
! contains the fewest possible non-zero entries.
! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(n, nrhs) :: b
real(dp), dimension(k) :: tau ! k = min(m, n)
real(dp), dimension(m, m) :: q
real(dp), dimension(n, n) :: p
integer(i32), dimension(n) :: pvt
! Initialize A and B...
! Allow all columns to be free.
pvt = 0
! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
 scalar factors in TAU. Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau, pvt)
! Solve A*X = B for X. If M > N, the first N rows of B are used to store
! X. If M < N, the input matrix B must be N-by-NRHS, and only the first
```

```
! M rows are used for the actual matrix B. The remaining N-M rows ! can contain whatever as they are not referenced until they are ! overwritten by the N-by-NRHS solution matrix X. call solve_qr(a, tau, pvt, b)

! Notice, if the explicit Q matrix from the factorization is desired, ! the form_qr routine works similarly as in the no-pivot case; ! however, the permutation matrix P is also constructed. The call would ! be as follows. Also, as with the no-pivot algorithm, the matrix R is ! stored in matrix A. call form_qr(a, tau, pvt, q, p)

! Solution can proceed as per typical, but with a full Q matrix. Also ! note, the problem is of the form: A*P = Q*R. Solution is straight ! forward, as with the no-pivot case; however, if M < N, then R is upper ! trapezoidal, and must be appropriately partitioned to solve. The rank ! of matrix r should be considered when applying the partition.
```

Notes

This routine utilizes the LAPACK routine DGEQP3.

Definition at line 579 of file linalg_factor.f90.

4.6.2.15 subroutine, public linalg_factor::qr_rank1_update (real(dp), dimension(:,:), intent(inout) q, real(dp), dimension(:,:), intent(inout) r, real(dp), dimension(:), intent(inout) u, real(dp), dimension(:), intent(inout) v, real(dp), dimension(:), intent(out), optional, target work, class(errors), intent(inout), optional, target err)

Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q * R, and A1 = A + U * V**T such that A1 = Q1 * R1.

Parameters

in,out	q	On input, the original M-by-K orthogonal matrix Q. On output, the updated matrix Q1.
in,out	r	On input, the M-by-N matrix R. On output, the updated matrix R1.
in,out	и	On input, the M-element U update vector. On output, the original content of the array is overwritten.
in,out	V	On input, the N-element V update vector. On output, the original content of the array is overwritten.
out	work	An optional argument that if supplied prevents local memory allocation. If provided, the array must have at least 2*K elements.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Remarks

```
Notice, K must either be equal to M, or to N. In the event that K = N, only the submatrix Qa is updated. This is appropriate as the QR factorization for an overdetermined system can be written as follows: A = Q \, \star \, R = [Qa, \, Qb] \, \star \, [Ra] \\ [0]
```

Note: Ra is upper triangular of dimension N-by-N.

Notes

This routine utilizes the QRUPDATE routine DQR1UP.

See Also

Source

Definition at line 1180 of file linalg_factor.f90.

4.6.2.16 subroutine, public linalg_factor::rz_factor (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that $A = R * Z = (R \ 0) * Z$. Z is an orthogonal matrix of dimension N-by-N, and R is an M-by-M upper triangular matrix.

Parameters

in,out	а	On input, the M-by-N upper trapezoidal matrix to factor. On output, the leading M-by-M upper triangular part of the matrix contains the upper triangular matrix R, and elements N-L+1 to N of the first M rows of A, with the array tau, represent the orthogonal matrix Z as a product of M elementary reflectors.
out	tau	An M-element array used to store the scalar factors of the elementary reflectors.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for \mathtt{work} , and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Further Details

```
The factorization is obtained by Householder's method. The kth transformation matrix, Z( k ), which is used to introduce zeros into the ( m - k + 1 )th row of A, is given in the form  Z( \ k \ ) = ( \ I \qquad 0 \qquad ), \qquad \qquad ( \ 0 \qquad T( \ k \ ) \ )  where  T( \ k \ ) = I - tau*u( \ k \ )*u( \ k \ )**T, \quad u( \ k \ ) = ( \ 1 \qquad ), \qquad \qquad ( \ 0 \qquad ) \qquad \qquad ( \ z( \ k \ ) \ )  tau is a scalar and Z( k ) is an l element vector. tau and Z( k ) are chosen to annihilate the elements of the kth row of A2.
```

The scalar tau is returned in the kth element of TAU and the vector $u(\ k\)$ in the kth row of A2, such that the elements of $z(\ k\)$ are in a(k, l + l), ..., a(k, n). The elements of R are returned in the upper triangular part of A1.

```
Z is given by Z = Z(1) * Z(2) * \dots * Z(m).
```

Notes

This routine is based upon the LAPACK routine DTZRZF.

See Also

• LAPACK Users Manual

Definition at line 1633 of file linalg_factor.f90.

4.6.2.17 subroutine, public linalg_factor::svd (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(out) s, real(dp), dimension(:,:), intent(out), optional u, real(dp), dimension(:,:), intent(out), optional vt, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err)

Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U * S * V * * T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

in,out	а	On input, the M-by-N matrix to factor. The matrix is overwritten on output.
out	s	A MIN(M, N)-element array containing the singular values of a sorted in descending order.
out	и	An optional argument, that if supplied, is used to contain the orthogonal matrix U from the decomposition. The matrix U contains the left singular vectors, and can be either M-by-M (all left singular vectors are computed), or M-by-MIN(M,N) (only the first MIN(M, N) left singular vectors are computed).
out	vt	An optional argument, that if supplied, is used to contain the transpose of the N-by-N orthogonal matrix V. The matrix V contains the right singular vectors.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Usage

```
! Decompose matrix the M-by-N matrix A such that A = U * S * V**T with
! M >= N.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, m) :: u
real(dp), dimension(n) :: vt
real(dp), dimension(n) :: s

! Initialize A...
! Compute the SVD of A. On output, S contains the MIN(M,N) singular
! values of A in descending order, U contains the left singular vectors
! (one per column), and VT contains the right singular vectors (one per ! row).
call svd(a, s, u, vt)
! Note: If M > N, then we can make U M-by-N, and compute the N
! left singular vectors of A, as there are at most N singular values
! of A. Also, if M < N, then there are at most M singular values of A,
! and as such, the length of the array s should be m.</pre>
```

Notes

This routine utilizes the LAPACK routine DGESVD.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 2046 of file linalg_factor.f90.

4.7 linalg solve Module Reference

linalg solve

Data Types

· interface solve_cholesky

Solves a system of Cholesky factored equations.

• interface solve_least_squares

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns.

• interface solve_least_squares_full

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.

interface solve_least_squares_svd

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

interface solve_lu

Solves a system of LU-factored equations.

· interface solve_qr

Solves a system of M QR-factored equations of N unknowns.

• interface solve_triangular_system

Solves a triangular system of equations.

Functions/Subroutines

• subroutine solve_tri_mtx (Iside, upper, trans, nounit, alpha, a, b, err)

Solves one of the matrix equations: op(A) * X = alpha * B, or X * op(A) = alpha * B, where A is a triangular matrix.

• subroutine solve_tri_vec (upper, trans, nounit, a, x, err)

Solves the system of equations: op(A) * X = B, where A is a triangular matrix.

subroutine solve lu mtx (a, ipvt, b, err)

Solves a system of LU-factored equations.

• subroutine solve lu vec (a, ipvt, b, err)

Solves a system of LU-factored equations.

subroutine solve_qr_no_pivot_mtx (a, tau, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where M >= N.

subroutine solve qr no pivot vec (a, tau, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where M >= N.

subroutine solve_qr_pivot_mtx (a, tau, jpvt, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

• subroutine solve_qr_pivot_vec (a, tau, jpvt, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

• subroutine solve_cholesky_mtx (upper, a, b, err)

Solves a system of Cholesky factored equations.

• subroutine solve_cholesky_vec (upper, a, b, err)

Solves a system of Cholesky factored equations.

• subroutine, public mtx_inverse (a, iwork, work, olwork, err)

Computes the inverse of a square matrix.

• subroutine, public mtx_pinverse (a, ainv, tol, work, olwork, err)

Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix

subroutine solve_least_squares_mtx (a, b, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

• subroutine solve_least_squares_vec (a, b, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

subroutine solve least squares mtx pvt (a, b, ipvt, arnk, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

• subroutine solve_least_squares_vec_pvt (a, b, ipvt, arnk, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

• subroutine solve least squares mtx svd (a, b, arnk, s, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

subroutine solve_least_squares_vec_svd (a, b, arnk, s, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

4.7.1 Detailed Description

linalg solve

Purpose

Provides a set of routines for solving systems of linear equations.

4.7.2 Function/Subroutine Documentation

4.7.2.1 subroutine, public linalg_solve::mtx_inverse (real(dp), dimension(:,:), intent(inout) *a,* integer(i32), dimension(:), intent(out), optional, target *iwork,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the inverse of a square matrix.

Parameters

in,out	а	On input, the N-by-N matrix to invert. On output, the inverted matrix.
out	iwork	An optional N-element integer workspace array.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square. Will also occur if incorrectly
		sized workspace arrays are provided.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_SINGULAR_MATRIX_ERROR: Occurs if the input matrix is singular.

Usage

```
! The following example illustrates how to solve a system of linear
! equations by matrix inversion. Notice, this is not a preferred
! solution technique (use LU factorization instead), but is merely a
! means of illustrating how to compute the inverse of a square matrix.
! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b, x
! Initialize A and B...
! Compute the inverse of A. The inverse will overwrite the original
! matrix.
call mtx_inverse(a)
! Solve A*X = B as X = inv(A) * B.
x = matmul(a, b)
```

Notes

This routine utilizes the LAPACK routines DGETRF to perform an LU factorization of the matrix, and DGETRI to invert the LU factored matrix.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 1240 of file linalg_solve.f90.

4.7.2.2 subroutine, public linalg_solve::mtx_pinverse (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(out) *ainv,* real(dp), intent(in), optional *tol,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix.

Parameters

in,out	а	On input, the M-by-N matrix to invert. The matrix is overwritten on output.
out	ainv	The N-by-M matrix where the pseudo-inverse of a will be written.
in	tol	An optional input, that if supplied, overrides the default tolerance on singular values such that singular values less than this tolerance are forced to have a reciprocal of zero, as opposed to $1/S(I)$. The default tolerance is: $MAX(M, N) * EPS * MAX(S)$. If the supplied value is less than a value that causes an overflow, the tolerance reverts back to its default value, and the operation continues; however, a warning message is issued.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Usage

```
! Use the pseudo-inverse to obtain a least-squares solution to the
! overdetermined problem A*X = B, where A is an M-by-N matrix (M >= N),
! B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.
! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(n, m) :: ainv
real(dp), dimension(m, nrhs) :: b
real(dp), dimension(n, nrhs) :: x
! Initialize A, and B...
! Compute the pseudo-inverse of A. Let the subroutine allocate its
! own workspace array.
call mtx_pinverse(a, ainv)
! Compute X = AINV * B to obtain the solution.
x = matmul(ainv, b)
```

See Also

- Wikipedia
- Wolfram MathWorld
- MathWorks

Definition at line 1400 of file linalg_solve.f90.

4.7.2.3 subroutine linalg_solve::solve_cholesky_mtx (logical, intent(in) *upper*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	upper	Set to true if the original matrix A was factored such that $A = U**T*U$; else, set to false if
		the factorization of A was $A = L**T*L$.
in	а	The N-by-N Cholesky factored matrix.
in, out	b	On input, the N-by-NRHS right-hand-side matrix B. On output, the solution matrix X.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 1073 of file linalg_solve.f90.

4.7.2.4 subroutine linalg_solve::solve_cholesky_vec (logical, intent(in) *upper*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	upper	Set to true if the original matrix A was factored such that $A = U**T*U$; else, set to false if the factorization of A was $A = L**T*L$.
in	а	The N-by-N Cholesky factored matrix.
in,out	b	On input, the N-element right-hand-side vector B. On output, the solution vector X.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 1139 of file linalg_solve.f90.

4.7.2.5 subroutine linalg_solve::solve_least_squares_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	а	On input, the M-by-N matrix A. On output, if $M \ge N$, the QR factorization of A in the form as output by qr_factor; else, if $M < N$, the LQ factorization of A.
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1568 of file linalg_solve.f90.

4.7.2.6 subroutine linalg_solve::solve_least_squares_mtx_pvt (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, integer(i32), dimension(:), intent(inout), optional, target ipvt, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.

Parameters

out	ipvt	An optional input that on input, an N-element array that if $IPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $IPVT(I) = 0$, the I-th column of A is a free column. On output, if $IPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A. If not supplied, memory is allocated internally, and $IPVT$ is set to all zeros such that all columns are treated as free.
out	arnk	An optional output, that if provided, will return the rank of a.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1786 of file linalg_solve.f90.

4.7.2.7 subroutine linalg_solve::solve_least_squares_mtx_svd (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out) s, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	arnk	An optional output, that if provided, will return the rank of a.
out	s	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2076 of file linalg_solve.f90.

4.7.2.8 subroutine linalg_solve::solve_least_squares_vec (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

in,out	а	On input, the M-by-N matrix A. On output, if $M \ge N$, the QR factorization of A in the form as output by qr_factor; else, if $M < N$, the LQ factorization of A.
in,out	b	If $M >= N$, the M-element array B. On output, the first N elements contain the N-element solution array X. If $M < N$, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

This routine utilizes the LAPACK routine DGELS.

Definition at line 1674 of file linalg_solve.f90.

4.7.2.9 subroutine linalg_solve::solve_least_squares_vec_pvt (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, integer(i32), dimension(:), intent(inout), optional, target ipvt, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If $M >= N$, the M-element array B. On output, the first N elements contain the N-element solution array X. If $M < N$, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	ipvt	An optional input that on input, an N-element array that if $IPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $IPVT(I) = 0$, the I-th column of A is a free column. On output, if $IPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A. If not supplied, memory is allocated internally, and $IPVT$ is set to all zeros such that all columns are treated as free.
out	arnk	An optional output, that if provided, will return the rank of a.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1932 of file linalg_solve.f90.

64 Module Documentation

4.7.2.10 subroutine linalg_solve::solve_least_squares_vec_svd (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out) s, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If M $>=$ N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M $<$ N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	arnk	An optional output, that if provided, will return the rank of a.
out	s	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized
		appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2204 of file linalg_solve.f90.

4.7.2.11 subroutine linalg_solve::solve_lu_mtx (real(dp), dimension(:,:), intent(in) *a,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

in	а	The N-by-N LU factored matrix as output by lu_factor.
in	ipvt	The N-element pivot array as output by lu_factor.
in,out	b	On input, the N-by-NRHS right-hand-side matrix. On output, the N-by-NRHS solution matrix.

out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.	
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.	

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 351 of file linalg_solve.f90.

4.7.2.12 subroutine linalg_solve::solve_lu_vec (real(dp), dimension(:,:), intent(in) *a*, integer(i32), dimension(:), intent(in) *ipvt*, real(dp), dimension(:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

Parameters

in	а	The N-by-N LU factored matrix as output by lu_factor.
in	ipvt	The N-element pivot array as output by lu_factor.
in, out	b	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 412 of file linalg_solve.f90.

4.7.2.13 subroutine linalg_solve::solve_qr_no_pivot_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:,:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where $M \ge N$.

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of
		this matrix are restored. Notice, M must be greater than or equal to N.

66 Module Documentation

Parameters

in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	b	On input, the M-by-NRHS right-hand-side matrix. On output, the first N columns are overwritten by the solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is input flighted.
		is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 487 of file linalg_solve.f90.

4.7.2.14 subroutine linalg_solve::solve_qr_no_pivot_vec (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where M >= N.

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	b	On input, the M-element right-hand-side vector. On output, the first N elements are overwritten by the solution vector X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		• LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated ம்றை is insufficient memory available.

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 602 of file linalg solve.f90.

4.7.2.15 subroutine linalg_solve::solve_qr_pivot_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) jpvt, real(dp), dimension(:,:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err)

[private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	jpvt	An N-element array, as output by qr_factor, used to track the column pivots.
in	b	On input, the MAX(M, N)-by-NRHS matrix where the first M rows contain the right-hand-side matrix B. On output, the first N rows are overwritten by the solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 715 of file linalg_solve.f90.

4.7.2.16 subroutine linalg_solve::solve_qr_pivot_vec (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) jpvt, real(dp), dimension(:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err)

[private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

68 Module Documentation

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	jpvt	An N-element array, as output by qr_factor, used to track the column pivots.
in	b	On input, the MAX(M, N)-element array where the first M elements contain the right-hand-side vector B. On output, the first N elements are overwritten by the solution vector X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 902 of file linalg_solve.f90.

4.7.2.17 subroutine linalg_solve::solve_tri_mtx (logical, intent(in) *lside,* logical, intent(in) *upper,* logical, intent(in) *trans,* logical, intent(in) *nounit,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves one of the matrix equations: op(A) * X = alpha * B, or X * op(A) = alpha * B, where A is a triangular matrix.

in	Iside	Set to true to solve $op(A) * X = alpha * B$; else, set to false to solve $X * op(A) = alpha * B$.
in	upper	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	trans	Set to true if $op(A) = A**T$; else, set to false if $op(A) = A$.
in	nounit	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	alpha	The scalar multiplier to B.
in	а	If lside is true, the M-by-M triangular matrix on which to operate; else, if lside is false, the N-by-N triangular matrix on which to operate.
in,out	b	On input, the M-by-N right-hand-side. On output, the M-by-N solution.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		• LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes வின்றிற்கிறி not compatible.

Usage

To solve a triangular system of N equations of N unknowns A*X = B, where A is an N-by-N upper triangular matrix, and B and X are N-by-NRHS matrices, the following code will suffice.

Notes

This routine is based upon the BLAS routine DTRSM.

Definition at line 169 of file linalg_solve.f90.

4.7.2.18 subroutine linalg_solve::solve_tri_vec (logical, intent(in) upper, logical, intent(in) trans, logical, intent(in) nounit, real(dp), dimension(:,:), intent(in) a, real(dp), dimension(:), intent(inout) x, class(errors), intent(inout), optional, target err) [private]

Solves the system of equations: op(A) * X = B, where A is a triangular matrix.

Parameters

in	upper	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	trans	Set to true if $op(A) = A**T$; else, set to false if $op(A) = A$.
in	nounit	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	а	The N-by-N triangular matrix.
in,out	Х	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A*X = B, where A is an N-by-N upper triangular matrix, and B and X are N-element arrays, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N ! matrix, and B and X are N-elements in size.
! Variables integer(i32) :: info
```

70 Module Documentation

```
real(dp), dimension(n, n) :: a
real(dp), dimension(n) :: b

! Initialize A and B...
! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .false., a, b)
```

Notes

This routine is based upon the BLAS routine DTRSV.

Definition at line 275 of file linalg_solve.f90.

Chapter 5

Data Type Documentation

5.1 linalg_core::diag_mtx_mult Interface Reference

Multiplies a diagonal matrix with another matrix or array.

Private Member Functions

- subroutine diag mtx mult mtx (Iside, trans, alpha, a, b, beta, c, err)
 - Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C.
- subroutine diag_mtx_mult_mtx2 (Iside, alpha, a, b, err)
 - Computes the matrix operation: B = alpha * A * op(B), or B = alpha * op(B) * A.
- subroutine diag_mtx_mult_mtx3 (Iside, trans, alpha, a, b, beta, c, err)
 - Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A and C are complex-valued.
- subroutine diag_mtx_mult_mtx4 (Iside, trans, alpha, a, b, beta, c, err)
 - Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A, B, and C are complex-valued.

5.1.1 Detailed Description

Multiplies a diagonal matrix with another matrix or array.

Definition at line 46 of file linalg core.f90.

5.1.2 Member Function/Subroutine Documentation

subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* real(dp), dimension(:), intent(in) *a,* real(dp), dimension(:), intent(in) *b,* real(dp) *beta,* real(dp), dimension(:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C.

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
in	b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing dimension of B): • lside == true & trans == true: LDB = N, TDB = P • lside == true & trans == false: LDB = P, TDB = N • lside == false & trans == true: LDB = P, TDB = M • lside == false & trans == false: LDB = M, TDB = P
in	beta	A scalar multiplier.
in,out	С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 327 of file linalg_core.f90.

5.1.2.2 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx2 (logical, intent(in) *lside*, real(dp), intent(in) *alpha*, real(dp), dimension(:), intent(in) *a*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: B = alpha * A * op(B), or B = alpha * op(B) * A.

Parameters

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
in	b	On input, the M-by-N matrix B. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 494 of file linalg_core.f90.

5.1.2.3 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx3 (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp) *alpha*, complex(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:,:), intent(in) *b*, real(dp) *beta*, complex(dp), dimension(:,:), intent(inout) *c*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A and C are complex-valued.

Parameters

Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
alpha	A scalar multiplier.
а	A K-element array containing the diagonal elements of A where $K = MIN(M,P)$ if lside is true; else, if lside is false, $K = MIN(N,P)$.
b	The LDB-by-TDB matrix B where (LDB = leading dimension of B, and TDB = trailing dimension of B): • lside == true & trans == true: LDB = N, TDB = P
	151de == lide & claifs == lide. LDB = N, TDB = I
	• lside == true & trans == false: LDB = P, TDB = N
	• lside == false & trans == true: LDB = P, TDB = M
	• lside == false & trans == false: LDB = M, TDB = P
beta	A scalar multiplier.
С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.
	trans alpha a b beta c

Definition at line 577 of file linalg_core.f90.

5.1.2.4 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx4 (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp) *alpha*, complex(dp), dimension(:,:), intent(in) *a*, complex(dp), dimension(:,:), intent(in) *b*, real(dp) *beta*, complex(dp), dimension(:,:), intent(inout) *c*, class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A, B, and C are complex-valued.

in	Iside	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	trans	Set to true if $op(B) == B**T$; else, set to false if $op(B) == B$.
in	alpha	A scalar multiplier.
in	а	A K-element array containing the diagonal elements of A where K = MIN(M,P) if lside is
		true; else, if lside is false, K = MIN(N,P).

in	b	The LDB-by-TDB matrix B where:
		• lside == true & trans == true: LDA = N, TDB = P
		• lside == true & trans == false: LDA = P, TDB = N
		• lside == false & trans == true: LDA = P, TDB = M
		• lside == false & trans == false: LDA = M, TDB = P
in	beta	A scalar multiplier.
in,out	С	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 753 of file linalg_core.f90.

The documentation for this interface was generated from the following file:

• /home/jason/Documents/Code/linalg/src/linalg_core.f90

5.2 lapack::DLAMCH Interface Reference

Public Member Functions

• real(dp) function **dlamch** (cmach)

5.2.1 Detailed Description

Definition at line 14 of file lapack.f90.

The documentation for this interface was generated from the following file:

• /home/jason/Documents/Code/linalg/src/lapack.f90

5.3 linalg_eigen::eigen Interface Reference

Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

Private Member Functions

- subroutine eigen_symm (vecs, a, vals, work, olwork, err)
 - Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.
- subroutine eigen_asymm (a, vals, vecs, work, olwork, err)
 - Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.
- subroutine eigen_gen (a, b, alpha, beta, vecs, work, olwork, err)

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

5.3.1 Detailed Description

Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

See Also

- Wikipedia
- Wolfram MathWorld
- LAPACK Users Manual

Definition at line 24 of file linalg_eigen.f90.

5.3.2 Member Function/Subroutine Documentation

5.3.2.1 subroutine linalg_eigen::eigen_asymm (real(dp), dimension(:,:), intent(inout) a, complex(dp), dimension(:), intent(out) vals, complex(dp), dimension(:,:), intent(out), optional vecs, real(dp), dimension(:), intent(out), optional, pointer work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.

in,out	а	On input, the N-by-N matrix on which to operate. On output, the contents of this matrix are overwritten.
out	vals	An N-element array containing the eigenvalues of the matrix. The eigenvalues are not sorted.
out	vecs	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
enerated by De	xygen	LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.
	1	

This routine utilizes the LAPACK routine DGEEV.

Definition at line 185 of file linalg_eigen.f90.

5.3.2.2 subroutine linalg_eigen::eigen_gen (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, complex(dp), dimension(:), intent(out) alpha, real(dp), dimension(:), intent(out), optional beta, complex(dp), dimension(:,:), intent(out), optional vecs, real(dp), dimension(:), intent(out), optional, pointer work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A*X = lambda*B*X.

Parameters

in,out	а	On input, the N-by-N matrix A. On output, the contents of this matrix are overwritten.
in,out	b	On input, the N-by-N matrix B. On output, the contents of this matrix are overwritten.
out	alpha	An N-element array that, if beta is not supplied, contains the eigenvalues. If beta is supplied however, the eigenvalues must be computed as ALPHA / BETA. This however, is not as trivial as it seems as it is entirely possible, and likely, that ALPHA / BETA can overflow or underflow. With that said, the values in ALPHA will always be less than and usually comparable with the NORM(A).
out	beta	An optional N-element array that if provided forces alpha to return the numerator, and this array contains the denominator used to determine the eigenvalues as ALPHA / BETA. If used, the values in this array will always be less than and usually comparable with the NORM(B).
out	vecs	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Usage

As an example, consider the eigenvalue problem arising from a mechanical system of masses and springs such that the masses are described by a mass matrix M, and the arrangement of springs are described by a stiffness matrix K.

```
! Parameters real(dp), parameter :: pi = 3.141592653589793d0
```

```
! Variables
real(dp), dimension(n, n) :: m, k
complex(dp), dimension(n, n) :: mode_shapes
complex(dp), dimension(n) :: vals
real(dp), dimension(n) :: vals
real(dp), dimension(n) :: nat_freq

! Initialize the mass matrix (m) and the stiffness matrix (k)...
! Solve the eigenvalue problem. The eigenvectors define the mode shapes
! for the system (each eigenvector defines a different mode shape, and
! are stored one per column).
call eigen(k, m, vals, vecs = mode_shapes)
! The eigenvalues represent the square of the system natural frequencies.
! Also, a properly constrained mechanical system will exhibit only real
! eigenvalues; therefore, the following relationship will return the
! natural frequencies with units of Hz.
nat_freq = sqrt(real(vals, dp)) / (2.0d0 * pi)
```

This routine utilizes the LAPACK routine DGGEV.

Definition at line 426 of file linalg eigen.f90.

5.3.2.3 subroutine linalg_eigen::eigen_symm (logical, intent(in) *vecs*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(out) *vals*, real(dp), dimension(:), intent(out), optional, pointer *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

in	vecs	Set to true to compute the eigenvectors as well as the eigenvalues; else, set to false to just compute the eigenvalues.
in,out	а	On input, the N-by-N symmetric matrix on which to operate. On output, and if vecs is set to true, the matrix will contain the eigenvectors (one per column) corresponding to each eigenvalue in vals. If vecs is set to false, the lower triangular portion of the matrix is overwritten.
out	vals	An N-element array that will contain the eigenvalues sorted into ascending order.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

This routine utilizes the LAPACK routine DSYEV.

Definition at line 68 of file linalg eigen.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_eigen.f90

5.4 linalg_factor::form_lu Interface Reference

Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.

Private Member Functions

- subroutine form_lu_all (lu, ipvt, u, p, err)
 - Extracts the L, U, and P matrices from the output of the lu_factor routine.
- subroutine form_lu_only (lu, u, err)

Extracts the L, and U matrices from the output of the lu_factor routine.

5.4.1 Detailed Description

Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.

Definition at line 31 of file linalg_factor.f90.

5.4.2 Member Function/Subroutine Documentation

5.4.2.1 subroutine linalg_factor::form_lu::form_lu_all (real(dp), dimension(:,:), intent(inout) *lu*, integer(i32), dimension(:), intent(in) *ipvt*, real(dp), dimension(:,:), intent(out) *u*, real(dp), dimension(:,:), intent(out) *p*, class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, U, and P matrices from the output of the lu_factor routine.

in,out	lu	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
in	ipvt	The N-element pivot array as output by lu_factor.
out	и	An N-by-N matrix where the U matrix will be written.
out	р	An N-by-N matrix where the row permutation matrix will be written.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Remarks

This routine allows extraction of the actual "L", "U", and "P" matrices of the decomposition. To use these matrices to solve the system A*X = B, the following approach is used.

- 1. First, solve the linear system: L*Y = P*B for Y.
- 2. Second, solve the linear system: U*X = Y for X.

Notice, as both L and U are triangular in structure, the above equations can be solved by forward and backward substitution.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 211 of file linalg_factor.f90.

5.4.2.2 subroutine linalg_factor::form_lu::form_lu_only (real(dp), dimension(:,:), intent(inout) lu, real(dp), dimension(:,:), intent(out) u, class(errors), intent(inout), optional, target err) [private]

Extracts the L, and U matrices from the output of the lu_factor routine.

Parameters

in,out	lu	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular
		matrix L.
out	и	An N-by-N matrix where the U matrix will be written.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 288 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.5 linalg_factor::form_qr Interface Reference

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Private Member Functions

• subroutine form_qr_no_pivot (r, tau, q, work, olwork, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

• subroutine form_qr_pivot (r, tau, pvt, q, p, work, olwork, err)

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

5.5.1 Detailed Description

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

See Also

- Wikipedia
- LAPACK Users Manual

Definition at line 55 of file linalg_factor.f90.

5.5.2 Member Function/Subroutine Documentation

5.5.2.1 subroutine linalg_factor::form_qr::form_qr_no_pivot (real(dp), dimension(:,:), intent(inout) r, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:,:), intent(out) q, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in r.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M > N$, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q * R = [Q1, Q2] * [R1; 0].
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		• LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

This routine utilizes the LAPACK routine DORGQR.

Definition at line 694 of file linalg_factor.f90.

5.5.2.2 subroutine linalg_factor::form_qr::form_qr_pivot (real(dp), dimension(:,:), intent(inout) r, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) pvt, real(dp), dimension(:,:), intent(out) q, real(dp), dimension(:,:), intent(out) p, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	r	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	tau	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in r.
in	pvt	An N-element column pivot array as returned by the QR factorization.
out	q	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that $M > N$, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q * R = [Q1, Q2] * [R1; 0].
out	р	An N-by-N matrix where the pivot matrix will be written.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 825 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.6 linalg_core::mtx_mult Interface Reference

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Private Member Functions

- subroutine mtx_mult_mtx (transa, transb, alpha, a, b, beta, c, err)

 Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.
- subroutine mtx_mult_vec (trans, alpha, a, b, beta, c, err)

 Performs the matrix-vector operation: c = alpha * op(A) * b + beta * c.

5.6.1 Detailed Description

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Definition at line 39 of file linalg_core.f90.

5.6.2 Member Function/Subroutine Documentation

5.6.2.1 subroutine linalg_core::mtx_mult::mtx (logical, intent(in) *transa,* logical, intent(in) *transb,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp), intent(in) *beta,* real(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix operation: C = alpha * op(A) * op(B) + beta * C.

Parameters

in	transa	Set to true if $op(A) = A**T$; else, set to false for $op(A) = A$.
in	transb	Set to true if $op(B) = B**T$; else, set to false for $op(B) = B$.
in	alpha	A scalar multiplier.
in	а	If transa is set to true, an K-by-M matrix; else, if transa is set to false, an M-by-K matrix.
in	b	If transb is set to true, an N-by-K matrix; else, if transb is set to false, a K-by-N matrix.
in	beta	A scalar multiplier.
in,out	С	On input, the M-by-N matrix C. On output, the M-by-N result.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMM.

Definition at line 83 of file linalg_core.f90.

5.6.2.2 subroutine linalg_core::mtx_mult::mtx_mult_vec (logical, intent(in) trans, real(dp), intent(in) alpha, real(dp), dimension(:), intent(in) b, real(dp), intent(in) beta, real(dp), dimension(:), intent(inout) c, class(errors), intent(inout), optional, target err) [private]

Performs the matrix-vector operation: c = alpha * op(A) * b + beta * c.

Parameters

in	trans	Set to true if $op(A) = A**T$; else, set to false for $op(A) = A$.
in	alpha	A scalar multiplier.
in	а	The M-by-N matrix A.
in	b	If trans is set to true, an M-element array; else, if trans is set to false, an N-element
		array.
in	beta	A scalar multiplier.
in,out	С	On input, if trans is set to true, an N-element array; else, if trans is set to false, an
		M-element array. On output, the results of the operation.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMV.

Definition at line 177 of file linalg_core.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg core.f90

5.7 linalg_factor::mult_qr Interface Reference

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.

Private Member Functions

- subroutine mult_qr_mtx (Iside, trans, a, tau, c, work, olwork, err)
 Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C, or C = C * op(Q).
- subroutine mult_qr_vec (trans, a, tau, c, work, olwork, err)
 Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

5.7.1 Detailed Description

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.

Definition at line 63 of file linalg_factor.f90.

5.7.2 Member Function/Subroutine Documentation

5.7.2.1 subroutine linalg_factor::mult_qr::mult_qr_mtx (logical, intent(in) *lside*, logical, intent(in) *trans*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(inout) *a*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C, or C = C * op(Q).

Parameters

in	Iside	Set to true to apply Q or Q**T from the left; else, set to false to apply Q or Q**T from the right.
in	trans	Set to true to apply Q**T; else, set to false.
in	а	On input, an LDA-by-K matrix containing the elementary reflectors output from the QR factorization. If lside is set to true, LDA = M, and $M >= K >= 0$; else, if lside is set to false, LDA = N, and $N >= K >= 0$. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Q and the original matrix C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMQR.

Definition at line 927 of file linalg_factor.f90.

5.7.2.2 subroutine linalg_factor::mult_qr::mult_qr_vec (logical, intent(in) *trans*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(in) *tau*, real(dp), dimension(:), intent(inout) *c*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) * C.

|--|

in	а	On input, an M-by-K matrix containing the elementary reflectors output from the QR
		factorization. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	С	On input, the M-element vector C. On output, the product of the orthogonal matrix Q and the original vector C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for \mathtt{work} , and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon the LAPACK routine DORM2R.

Definition at line 1054 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.8 linalg_factor::mult_rz Interface Reference

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.

Private Member Functions

- subroutine mult_rz_mtx (Iside, trans, I, a, tau, c, work, olwork, err)
 Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C, or C = C * op(Z).
- subroutine mult_rz_vec (trans, I, a, tau, c, work, olwork, err)

 Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

5.8.1 Detailed Description

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.

Definition at line 71 of file linalg_factor.f90.

5.8.2 Member Function/Subroutine Documentation

5.8.2.1 subroutine linalg_factor::mult_rz::mult_rz_mtx (logical, intent(in) *lside*, logical, intent(in) *trans*, integer(i32), intent(in) *l*, real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(in) *tau*, real(dp), dimension(:,:), intent(inout) *c*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C, or C = C * op(Z).

Parameters

in	Iside	Set to true to apply Z or $Z**T$ from the left; else, set to false to apply Z or $Z**T$ from the right.
in	trans	Set to true to apply Z**T; else, set to false.
in	1	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, $M >= L >= 0$; else, if lside is false, $N >= L >= 0$.
in,out	а	On input the K-by-LTA matrix Z, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of the elementary reflectors, where M $>=$ K $>=$ 0 if lside is true; else, N $>=$ K $>=$ 0 if lside is false.
in,out	С	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Z and the original matrix C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1745 of file linalg factor.f90.

5.8.2.2 subroutine linalg_factor::mult_rz::mult_rz_vec (logical, intent(in) trans, integer(i32), intent(in) l, real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, real(dp), dimension(:), intent(inout) c, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) * C.

in	trans	Set to true to apply Z**T; else, set to false.
in	1	The number of columns in matrix a containing the meaningful part of the Householder vectors. If $lside$ is true, $M >= L >= 0$; else, if $lside$ is false, $N >= L >= 0$.
in,out	а	On input the K-by-LTA matrix Z, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	tau	A K-element array containing the scalar factors of the elementary reflectors, where $M \ge K \ge 0$ if lside is true; else, $N \ge K \ge 0$ if lside is false.
in,out	С	On input, the M-element array C. On output, the product of the orthogonal matrix Z and the original array C.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized
		 appropriately. LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1887 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.9 linalg_factor::qr_factor Interface Reference

Computes the QR factorization of an M-by-N matrix.

Private Member Functions

- subroutine qr_factor_no_pivot (a, tau, work, olwork, err)
 Computes the QR factorization of an M-by-N matrix without pivoting.
- subroutine qr_factor_pivot (a, tau, jpvt, work, olwork, err)

Computes the QR factorization of an M-by-N matrix with column pivoting such that A*P=Q*R.

5.9.1 Detailed Description

Computes the QR factorization of an M-by-N matrix.

See Also

- Wikipedia
- Wolfram MathWorld
- LAPACK Users Manual

Definition at line 43 of file linalg factor.f90.

5.9.2 Member Function/Subroutine Documentation

5.9.2.1 subroutine linalg_factor::qr_factor::qr_factor_no_pivot (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(out) tau, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the QR factorization of an M-by-N matrix without pivoting.

Parameters

а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
	LA_ARRAY_SIZE_ERROR: Occurs if tau or work are not sized appropriately.
	 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
	tau work

Remarks

QR factorization without pivoting is best suited to solving an overdetermined system in least-squares terms, or to solve a normally defined system. To solve an underdetermined system, it is recommended to use either LQ factorization, or a column-pivoting based QR factorization.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice assuming $M \ge N$.

```
! Solve the system: A*X = B in a least-squares sense, where A is an
! M-by-N matrix, B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.
! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, nrhs) :: b, qtb
real(dp), dimension(n, nrhs) :: x
real(dp), dimension(n) :: tau
real(dp), dimension(m, m) :: q
! Initialize A and B...
! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of \ensuremath{\mathtt{A}}\xspace, and the corresponding
! scalar factors in TAU. Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor \mbox{A} is:
call qr_factor(a, tau)
! Solve A*X = B for X. The first N rows of B are used to store X.
call solve_qr(a, tau, b)
! Also note, we could form {\tt Q} and {\tt R} explicitly. Then solution of the
! system of equations can be found. First we form Q and R. call form_qr(a, tau, q) ! Forms Q, and R is stored in A
! Since we now have \ensuremath{\mathsf{Q}} and \ensuremath{\mathsf{R}}, we seek a solution to the equation:
! Q*R*X = B, but Q is an orthogonal matrix (i.e. Q**T = inv(Q)).
! Then: R*X = Q**T * B, and R is upper triangular; therefore, back
! substitution will suffice for a solution procedure.
! Next, compute Q**T * B, and store in QTB.
call mtx_mult(.true., .false., 1.0d0, q, b, 0.0d0, qtb)
! Copy the first N rows of Q**T * B into X for the solution process.
! Notice, only the first N rows are needed as rows N+1:M are all zero in
! matrix R.
x = qtb(1:n,nrhs)
! Compute the solution and store in \boldsymbol{X}
call solve_triangular_system(.true., .true., .false., .true., 1.0d0, &
 a(1:n,1:n), x)
```

This routine utilizes the LAPACK routine DGEQRF.

Definition at line 425 of file linalg factor.f90.

5.9.2.2 subroutine linalg_factor::qr_factor::qr_factor_pivot (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(out) tau, integer(i32), dimension(:), intent(inout) jpvt, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Computes the QR factorization of an M-by-N matrix with column pivoting such that A * P = Q * R.

in,out	а	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if $M \ge N$). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	tau	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in,out	jpvt	On input, an N-element array that if $JPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $JPVT(I) = 0$, the I-th column of A is a free column. On output, if $JPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.

out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice for any M and N.

```
! Solve the least-squares (M \geq= N), or the underdetermined (M < N)
! problem A*X = B, where A is an M-by-N matrix, B is an M-by-NRHS matrix,
  and X is an N-by-NRHS matrix. In the underdetermined case, or the
  case where the rank of matrix A is less than N, the solution obtained
! contains the fewest possible non-zero entries.
! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(n, nrhs) :: b
real(dp), dimension(k) :: tau ! k = min(m, n)
real(dp), dimension(m, m) :: q real(dp), dimension(n, n) :: p
integer (i32), dimension (n) :: pvt
! Initialize A and B...
! Allow all columns to be free.
pvt = 0
! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
! scalar factors in TAU. Additionally, we'll let the algorithm allocate ! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau, pvt)
! Solve A*X = B for X. If M > N, the first N rows of B are used to store
! X. If M < N, the input matrix B must be N-by-NRHS, and only the first
! M rows are used for the actual matrix B. The remaining N-M rows
! can contain whatever as they are not referenced until they are ! overwritten by the N-by-NRHS solution matrix {\tt X}.
call solve_qr(a, tau, pvt, b)
! Notice, if the explicit Q matrix from the factorization is desired,
! the form_qr routine works similarly as in the no-pivot case; ! however, the permutation matrix P is also constructed. The call would
! be as follows. Also, as with the no-pivot algorithm, the matrix R is ! stored in matrix A.
call form_qr(a, tau, pvt, q, p)
! Solution can proceed as per typical, but with a full {\bf Q} matrix. Also
! note, the problem is of the form: A*P = Q*R. Solution is straight! forward, as with the no-pivot case; however, if M < N, then R is upper
  trapezoidal, and must be appropriately partitioned to solve. The rank
! of matrix r should be considered when applying the partition.
```

Notes

This routine utilizes the LAPACK routine DGEQP3.

Definition at line 579 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

· /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.10 linalg_solve::solve_cholesky Interface Reference

Solves a system of Cholesky factored equations.

Private Member Functions

- subroutine solve_cholesky_mtx (upper, a, b, err)
 Solves a system of Cholesky factored equations.
- subroutine solve_cholesky_vec (upper, a, b, err)

 Solves a system of Cholesky factored equations.

5.10.1 Detailed Description

Solves a system of Cholesky factored equations.

Definition at line 83 of file linalg_solve.f90.

5.10.2 Member Function/Subroutine Documentation

5.10.2.1 subroutine linalg_solve::solve_cholesky::solve_cholesky_mtx (logical, intent(in) *upper*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	upper	Set to true if the original matrix A was factored such that $A = U**T*U$; else, set to false if
		the factorization of A was $A = L**T*L$.
in	а	The N-by-N Cholesky factored matrix.
in,out	b	On input, the N-by-NRHS right-hand-side matrix B. On output, the solution matrix X.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 1073 of file linalg solve.f90.

5.10.2.2 subroutine linalg_solve::solve_cholesky::solve_cholesky_vec (logical, intent(in) *upper*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

in	upper	Set to true if the original matrix A was factored such that $A = U**T*U$; else, set to false if the factorization of A was $A = L**T*L$.
in	а	The N-by-N Cholesky factored matrix.
in,out	b	On input, the N-element right-hand-side vector B. On output, the solution vector X.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 1139 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg solve.f90

5.11 linalg_solve::solve_least_squares Interface Reference

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns.

Private Member Functions

- subroutine solve_least_squares_mtx (a, b, work, olwork, err)

 Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine solve_least_squares_vec (a, b, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

5.11.1 Detailed Description

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns.

Definition at line 91 of file linalg solve.f90.

5.11.2 Member Function/Subroutine Documentation

5.11.2.1 subroutine linalg_solve::solve_least_squares::solve_least_squares_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

in,out	а	On input, the M-by-N matrix A. On output, if $M \ge N$, the QR factorization of A in the form as output by qr_factor; else, if $M < N$, the LQ factorization of A.
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for \mathtt{work} , and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1568 of file linalg_solve.f90.

5.11.2.2 subroutine linalg_solve::solve_least_squares::solve_least_squares_vec (real(dp), dimension(:,:), intent(inout) *a*, real(dp), dimension(:), intent(inout) *b*, real(dp), dimension(:), intent(out), optional, target *work*, integer(i32), intent(out), optional *olwork*, class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

in,out	а	On input, the M-by-N matrix A. On output, if $M \ge N$, the QR factorization of A in the form as output by qr_factor; else, if $M < N$, the LQ factorization of A.
in,out	Ь	If $M >= N$, the M-element array B. On output, the first N elements contain the N-element solution array X. If $M < N$, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1674 of file linalg solve.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.12 linalg_solve::solve_least_squares_full Interface Reference

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.

Private Member Functions

- subroutine solve_least_squares_mtx_pvt (a, b, ipvt, arnk, work, olwork, err)

 Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.
- subroutine solve_least_squares_vec_pvt (a, b, ipvt, arnk, work, olwork, err)

 Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

5.12.1 Detailed Description

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.

Definition at line 100 of file linalg solve.f90.

5.12.2 Member Function/Subroutine Documentation

5.12.2.1 subroutine linalg_solve::solve_least_squares_full::solve_least_squares_mtx_pvt (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, integer(i32), dimension(:), intent(inout), optional, target ipvt, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	ipvt	An optional input that on input, an N-element array that if $IPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $IPVT(I) = 0$, the I-th column of A is a free column. On output, if $IPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A. If not supplied, memory is allocated internally, and $IPVT$ is set to all zeros such that all columns are treated as free.
out	arnk	An optional output, that if provided, will return the rank of a.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1786 of file linalg_solve.f90.

5.12.2.2 subroutine linalg_solve::solve_least_squares_full::solve_least_squares_vec_pvt (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, integer(i32), dimension(:), intent(inout), optional, target ipvt, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If $M >= N$, the M-element array B. On output, the first N elements contain the N-element solution array X. If $M < N$, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	ipvt	An optional input that on input, an N-element array that if $IPVT(I)$.ne. 0, the I-th column of A is permuted to the front of A $*$ P; if $IPVT(I) = 0$, the I-th column of A is a free column. On output, if $IPVT(I) = K$, then the I-th column of A $*$ P was the K-th column of A. If not supplied, memory is allocated internally, and $IPVT$ is set to all zeros such that all columns are treated as free.

Generated by Doxygen

out	arnk	An optional output, that if provided, will return the rank of a.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and
		there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1932 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.13 linalg_solve::solve_least_squares_svd Interface Reference

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Private Member Functions

- subroutine solve_least_squares_mtx_svd (a, b, arnk, s, work, olwork, err)
 - Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.
- subroutine solve_least_squares_vec_svd (a, b, arnk, s, work, olwork, err)

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

5.13.1 Detailed Description

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Definition at line 109 of file linalg_solve.f90.

5.13.2 Member Function/Subroutine Documentation

5.13.2.1 subroutine linalg_solve::solve_least_squares_svd::solve_least_squares_mtx_svd (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:,:), intent(inout) b, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out) s, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
b	If $M >= N$, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If $M < N$, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
arnk	An optional output, that if provided, will return the rank of a.
s	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by $S(1) / S(MIN(M, N))$.
work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
	 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
	 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
	 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.
	b arnk s work

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2076 of file linalg_solve.f90.

5.13.2.2 subroutine linalg_solve::solve_least_squares_svd::solve_least_squares_vec_svd (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, integer(i32), intent(out), optional arnk, real(dp), dimension(:), intent(out) s, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves the overdetermined or underdetermined system (A*X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

in,out	а	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	b	If M $>=$ N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M $<$ N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	arnk	An optional output, that if provided, will return the rank of a.
out	S	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by $S(1) / S(MIN(M, N))$.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.
		 LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2204 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

• /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.14 linalg_solve::solve_lu Interface Reference

Solves a system of LU-factored equations.

Private Member Functions

- subroutine solve_lu_mtx (a, ipvt, b, err)
 Solves a system of LU-factored equations.
- subroutine solve_lu_vec (a, ipvt, b, err)
 Solves a system of LU-factored equations.

5.14.1 Detailed Description

Solves a system of LU-factored equations.

Usage

To solve a system of N equations of N unknowns using LU factorization, the following code will suffice.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.
! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b
! Define the array used to track row pivots.
integer(i32), dimension(n) :: pvt
! Initialize A and B...
! Compute the LU factorization of A. On output, A contains [L\U].
call lu_factor(a, pvt)
! Solve A*X = B for X - Note: X overwrites B.
call solve_lu(a, pvt, b)
```

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 63 of file linalg_solve.f90.

5.14.2 Member Function/Subroutine Documentation

5.14.2.1 subroutine linalg_solve::solve_lu::solve_lu_mtx (real(dp), dimension(:,:), intent(in) a, integer(i32), dimension(:), intent(in) ipvt, real(dp), dimension(:,:), intent(inout) b, class(errors), intent(inout), optional, target err)

[private]

Solves a system of LU-factored equations.

Parameters

in	а	The N-by-N LU factored matrix as output by lu_factor.
in	ipvt	The N-element pivot array as output by lu_factor.
in,out	b	On input, the N-by-NRHS right-hand-side matrix. On output, the N-by-NRHS solution matrix.
out	An optional errors-based object that if provided can be used to retrieve infor to any errors encountered during execution. If not provided, a default impler errors class is used internally to provide error handling. Possible errors and messages that may be encountered are as follows.	
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 351 of file linalg_solve.f90.

5.14.2.2 subroutine linalg_solve::solve_lu::solve_lu_vec (real(dp), dimension(:,:), intent(in) a, integer(i32), dimension(:), intent(in) ipvt, real(dp), dimension(:), intent(inout) b, class(errors), intent(inout), optional, target err) [private]

Solves a system of LU-factored equations.

Parameters

in	а	The N-by-N LU factored matrix as output by lu_factor.
in	ipvt	The N-element pivot array as output by lu_factor.
in,out	b	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 412 of file linalg solve.f90.

The documentation for this interface was generated from the following file:

/home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.15 linalg_solve::solve_qr Interface Reference

Solves a system of M QR-factored equations of N unknowns.

Private Member Functions

- subroutine solve_qr_no_pivot_mtx (a, tau, b, work, olwork, err)
 Solves a system of M QR-factored equations of N unknowns where M >= N.
- subroutine solve_qr_no_pivot_vec (a, tau, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where M >= N.

subroutine solve_qr_pivot_mtx (a, tau, jpvt, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

• subroutine solve_qr_pivot_vec (a, tau, jpvt, b, work, olwork, err)

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

5.15.1 Detailed Description

Solves a system of M QR-factored equations of N unknowns.

See Also

- Wikipedia
- LAPACK Users Manual

Definition at line 74 of file linalg_solve.f90.

5.15.2 Member Function/Subroutine Documentation

5.15.2.1 subroutine linalg_solve::solve_qr::solve_qr_no_pivot_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where $M \ge N$.

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	b	On input, the M-by-NRHS right-hand-side matrix. On output, the first N columns are overwritten by the solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for $work$, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 487 of file linalg_solve.f90.

5.15.2.2 subroutine linalg_solve::solve_qr::solve_qr_no_pivot_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where $M \ge N$.

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	b	On input, the M-element right-hand-side vector. On output, the first N elements are overwritten by the solution vector X.

Parameters

out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 602 of file linalg_solve.f90.

5.15.2.3 subroutine linalg_solve::solve_qr::solve_qr_pivot_mtx (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) jpvt, real(dp), dimension(:,:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	jpvt	An N-element array, as output by qr_factor, used to track the column pivots.
in	b	On input, the MAX(M, N)-by-NRHS matrix where the first M rows contain the right-hand-side matrix B. On output, the first N rows are overwritten by the solution matrix X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there
		is insufficient memory available. Generated by Doxygen

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 715 of file linalg_solve.f90.

5.15.2.4 subroutine linalg_solve::solve_qr::solve_qr_pivot_vec (real(dp), dimension(:,:), intent(inout) a, real(dp), dimension(:), intent(in) tau, integer(i32), dimension(:), intent(in) jpvt, real(dp), dimension(:), intent(inout) b, real(dp), dimension(:), intent(out), optional, target work, integer(i32), intent(out), optional olwork, class(errors), intent(inout), optional, target err) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	а	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	tau	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	jpvt	An N-element array, as output by qr_factor, used to track the column pivots.
in	b	On input, the MAX(M, N)-element array where the first M elements contain the right-hand-side vector B. On output, the first N elements are overwritten by the solution vector X.
out	work	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	olwork	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows.
		 LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		 LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 902 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

• /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.16 linalg_solve::solve_triangular_system Interface Reference

Solves a triangular system of equations.

Private Member Functions

- subroutine solve_tri_mtx (Iside, upper, trans, nounit, alpha, a, b, err)
 - Solves one of the matrix equations: op(A) * X = alpha * B, or X * op(A) = alpha * B, where A is a triangular matrix.
- subroutine solve_tri_vec (upper, trans, nounit, a, x, err)

Solves the system of equations: op(A) * X = B, where A is a triangular matrix.

5.16.1 Detailed Description

Solves a triangular system of equations.

Definition at line 29 of file linalg_solve.f90.

5.16.2 Member Function/Subroutine Documentation

5.16.2.1 subroutine linalg_solve::solve_triangular_system::solve_tri_mtx (logical, intent(in) *lside*, logical, intent(in) *upper*, logical, intent(in) *trans*, logical, intent(in) *nounit*, real(dp), intent(in) *alpha*, real(dp), dimension(:,:), intent(in) *a*, real(dp), dimension(:,:), intent(inout) *b*, class(errors), intent(inout), optional, target *err*) [private]

Solves one of the matrix equations: op(A) * X = alpha * B, or X * op(A) = alpha * B, where A is a triangular matrix.

Parameters

in	Iside	Set to true to solve $op(A) * X = alpha * B$; else, set to false to solve $X * op(A) = alpha * B$.
in	upper	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	trans	Set to true if $op(A) = A**T$; else, set to false if $op(A) = A$.
in	nounit	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	alpha	The scalar multiplier to B.
in	а	If lside is true, the M-by-M triangular matrix on which to operate; else, if lside is false, the N-by-N triangular matrix on which to operate.
in,out	b	On input, the M-by-N right-hand-side. On output, the M-by-N solution.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A*X = B, where A is an N-by-N upper triangular matrix, and B and X are N-by-NRHS matrices, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N ! matrix, and B and X are N-by-NRHS in size.
```

! Variables

Notes

This routine is based upon the BLAS routine DTRSM.

Definition at line 169 of file linalg solve.f90.

5.16.2.2 subroutine linalg_solve::solve_triangular_system::solve_tri_vec (logical, intent(in) upper, logical, intent(in) trans, logical, intent(in) nounit, real(dp), dimension(:,:), intent(in) a, real(dp), dimension(:), intent(inout) x, class(errors), intent(inout), optional, target err) [private]

Solves the system of equations: op(A) * X = B, where A is a triangular matrix.

Parameters

in	upper	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	trans	Set to true if $op(A) = A**T$; else, set to false if $op(A) = A$.
in	nounit	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	а	The N-by-N triangular matrix.
in,out	х	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	err	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A*X = B, where A is an N-by-N upper triangular matrix, and B and X are N-element arrays, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N
! matrix, and B and X are N-elements in size.
! Variables
integer(i32) :: info
real(dp), dimension(n, n) :: a
real(dp), dimension(n) :: b
! Initialize A and B...
! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .false., a, b)
```

Notes

This routine is based upon the BLAS routine DTRSV.

Definition at line 275 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

 $\bullet \ \ /home/jason/Documents/Code/linalg/src/linalg_solve.f90$

Index

cholesky_factor	form_lu_all
linalg_factor, 40	linalg_factor, 42
cholesky_factor_c	linalg_factor::form_lu, 78
linalg_c_binding, 9	form_lu_c
cholesky rank1 downdate	linalg_c_binding, 14
linalg_factor, 41	form lu only
cholesky_rank1_downdate_c	linalg_factor, 43
linalg_c_binding, 9	linalg_factor::form_lu, 79
	form_qr_c
cholesky_rank1_update	linalg_c_binding, 14
linalg_factor, 42	form_qr_no_pivot
cholesky_rank1_update_c	linalg_factor, 43
linalg_c_binding, 10	linalg_factor::form_qr, 80
	form_qr_pivot
det	linalg_factor, 44
linalg_core, 28	-
det_c	linalg_factor::form_qr, 81
linalg_c_binding, 10	form_qr_pivot_c linalg c binding, 15
diag_mtx_mult_c	illiaig_c_bilidilig, 13
linalg_c_binding, 11	lapack, 7
diag_mtx_mult_cmplx_c	lapack::DLAMCH, 74
linalg_c_binding, 11	linalg_c_binding, 7
diag_mtx_mult_mtx	cholesky_factor_c, 9
linalg_core, 29	cholesky_rank1_downdate_c, 9
linalg_core::diag_mtx_mult, 71	cholesky_rank1_update_c, 10
diag_mtx_mult_mtx2	det_c, 10
linalg_core, 30	diag_mtx_mult_c, 11
linalg_core::diag_mtx_mult, 72	diag_mtx_mult_cmplx_c, 11
diag_mtx_mult_mtx3	eigen_asymm_c, 12
linalg_core, 30	eigen_gen_c, 13
linalg_core::diag_mtx_mult, 72	eigen_symm_c, 13
diag_mtx_mult_mtx4	form_lu_c, 14
linalg_core, 31	form_qr_c, 14
linalg core::diag mtx mult, 73	form_qr_pivot_c, 15
<u> </u>	lu factor c, 16
eigen asymm	mtx_inverse_c, 16
linalg_eigen, 36	mtx_mult_c, 17
linalg_eigen::eigen, 75	
eigen asymm c	mtx_pinverse_c, 17 mtx_rank_c, 18
linalg_c_binding, 12	mult_qr_c, 18
eigen gen	— • —
linalg_eigen, 37	mult_rz_c, 19
linalg_eigen::eigen, 76	qr_factor_c, 19
eigen_gen_c	qr_factor_pivot_c, 20
linalg c binding, 13	qr_rank1_update_c, 21
5— — 5	rank1_update_c, 21
eigen_symm	rz_factor_c, 22
linalg_eigen, 38	solve_cholesky_c, 22
linalg_eigen::eigen, 77	solve_least_squares_c, 23
eigen_symm_c	solve_lu_c, 23
linalg_c_binding, 13	solve_qr_c, 23

108 INDEX

solve_qr_pivot_c, 24	form_qr_no_pivot, 80
solve_tri_mtx_c, 25	form_qr_pivot, 81
svd_c, 25	linalg_factor::mult_qr, 83
swap_c, 26	mult_qr_mtx, 84
trace_c, 26	mult_qr_vec, 84
linalg_constants, 26	linalg_factor::mult_rz, 85
linalg_core, 27	mult_rz_mtx, 86
det, 28	mult_rz_vec, 86
diag_mtx_mult_mtx, 29	linalg_factor::qr_factor, 87
diag_mtx_mult_mtx2, 30	qr_factor_no_pivot, 88
diag_mtx_mult_mtx3, 30	qr_factor_pivot, 89
diag_mtx_mult_mtx4, 31	linalg_solve, 55
mtx_mult_mtx, 31	mtx_inverse, 57
mtx_mult_vec, 32	mtx_pinverse, 57
mtx_rank, 33	solve_cholesky_mtx, 58
rank1_update, 33	solve_cholesky_vec, 59
recip_mult_array, 34	solve_least_squares_mtx, 59
swap, 34	solve_least_squares_mtx_pvt, 60
trace, 35	solve_least_squares_mtx_svd, 61
tri_mtx_mult, 35	solve_least_squares_vec, 62
linalg_core::diag_mtx_mult, 71	solve_least_squares_vec_pvt, 63
diag_mtx_mult_mtx, 71	solve_least_squares_vec_svd, 63
diag_mtx_mult_mtx2, 72	solve_lu_mtx, 64
diag_mtx_mult_mtx3, 72	solve_lu_vec, 65
diag_mtx_mult_mtx4, 73	solve_qr_no_pivot_mtx, 65
linalg_core::mtx_mult, 82	solve_qr_no_pivot_vec, 66 solve_qr_pivot_mtx, 67
mtx_mult_mtx, 82	solve_qr_pivot_mx, 67 solve_qr_pivot_vec, 67
mtx_mult_vec, 82	solve_tri_mtx, 68
linalg_eigen, 35	solve_tri_trix, 68
eigen_asymm, 36	linalg_solve::solve_cholesky, 91
eigen_gen, <mark>37</mark>	solve_cholesky_mtx, 91
eigen_symm, 38	solve_cholesky_vec, 91
linalg_eigen::eigen, 74	linalg_solve::solve_least_squares, 92
eigen_asymm, 75	solve_least_squares_mtx, 92
eigen_gen, 76	solve_least_squares_vec, 93
eigen_symm, 77	linalg solve::solve least squares full, 94
linalg_factor, 39	solve least squares mtx pvt, 94
cholesky_factor, 40	solve_least_squares_vec_pvt, 95
cholesky_rank1_downdate, 41	linalg_solve::solve_least_squares_svd, 96
cholesky_rank1_update, 42	solve_least_squares_mtx_svd, 97
form_lu_all, 42	solve_least_squares_vec_svd, 97
form_lu_only, 43	linalg_solve::solve_lu, 98
form_qr_no_pivot, 43	solve lu mtx, 99
form_qr_pivot, 44	solve lu vec, 99
lu_factor, 45	linalg solve::solve qr, 100
mult_qr_mtx, 46	solve gr no pivot mtx, 101
mult_qr_vec, 47	solve_qr_no_pivot_vec, 101
mult_rz_mtx, 48	solve_qr_pivot_mtx, 102
mult_rz_vec, 48	solve_qr_pivot_vec, 103
qr_factor_no_pivot, 49	linalg_solve::solve_triangular_system, 103
qr_factor_pivot, 50	solve_tri_mtx, 104
qr_rank1_update, 52	solve_tri_vec, 105
rz_factor, 53	lu_factor
svd, 54	linalg_factor, 45
linalg_factor::form_lu, 78	lu_factor_c
form_lu_all, 78	linalg_c_binding, 16
form_lu_only, 79	a.g_o_oioig, 10
linalg_factor::form_qr, 79	mtx_inverse

INDEX 109

linalg_solve, 57	rz_factor_c
mtx_inverse_c	linalg_c_binding, 22
linalg c binding, 16	illaig_c_bilding, 22
mtx_mult_c	solve_cholesky_c
linalg_c_binding, 17	linalg_c_binding, 22
mtx mult mtx	solve_cholesky_mtx
linalg_core, 31	linalg_solve, 58
linalg_core::mtx_mult, 82	linalg_solve::solve_cholesky, 91
mtx_mult_vec	solve_cholesky_vec
linalg_core, 32	linalg_solve, 59
linalg_core::mtx_mult, 82	linalg_solve::solve_cholesky, 91
mtx_pinverse	solve_least_squares_c
linalg_solve, 57	linalg_c_binding, 23
mtx_pinverse_c	solve_least_squares_mtx
linalg_c_binding, 17	linalg_solve, 59
-	linalg_solve::solve_least_squares, 92
mtx_rank linalg core, 33	solve_least_squares_mtx_pvt
<u> </u>	linalg_solve, 60
mtx_rank_c	linalg_solve::solve_least_squares_full, 94
linalg_c_binding, 18	solve_least_squares_mtx_svd
mult_qr_c	linalg solve, 61
linalg_c_binding, 18	linalg_solve::solve_least_squares_svd, 97
mult_qr_mtx	solve_least_squares_vec
linalg_factor, 46	linalg solve, 62
linalg_factor::mult_qr, 84	linalg_solve::solve_least_squares, 93
mult_qr_vec	solve_least_squares_vec_pvt
linalg_factor, 47	linalg_solve, 63
linalg_factor::mult_qr, 84	linalg_solve; 65 linalg_solve::solve_least_squares_full, 95
mult_rz_c	
linalg_c_binding, 19	solve_least_squares_vec_svd
mult_rz_mtx	linalg_solve, 63
linalg_factor, 48	linalg_solve::solve_least_squares_svd, 97
linalg_factor::mult_rz, 86	solve_lu_c
mult_rz_vec	linalg_c_binding, 23
linalg_factor, 48	solve_lu_mtx
linalg_factor::mult_rz, 86	linalg_solve, 64
	linalg_solve::solve_lu, 99
qr_factor_c	solve_lu_vec
linalg_c_binding, 19	linalg_solve, 65
qr_factor_no_pivot	linalg_solve::solve_lu, 99
linalg_factor, 49	solve_qr_c
linalg_factor::qr_factor, 88	linalg_c_binding, 23
qr_factor_pivot	solve_qr_no_pivot_mtx
linalg_factor, 50	linalg_solve, 65
linalg_factor::qr_factor, 89	linalg_solve::solve_qr, 101
qr_factor_pivot_c	solve_qr_no_pivot_vec
linalg_c_binding, 20	linalg_solve, 66
gr rank1 update	linalg_solve::solve_qr, 101
linalg factor, 52	solve_qr_pivot_c
qr_rank1_update_c	linalg_c_binding, 24
linalg_c_binding, 21	solve_qr_pivot_mtx
a.g_o_oag, _ 1	linalg_solve, 67
rank1_update	linalg_solve::solve_qr, 102
linalg_core, 33	solve_qr_pivot_vec
rank1_update_c	linalg_solve, 67
linalg_c_binding, 21	linalg_solve; 67
recip_mult_array	solve_tri_mtx
linalg_core, 34	linalg_solve, 68
-	-
rz_factor	linalg_solve::solve_triangular_system, 104
linalg_factor, 53	solve_tri_mtx_c

110 INDEX

```
linalg_c_binding, 25
solve_tri_vec
    linalg_solve, 69
    linalg_solve::solve_triangular_system, 105
svd
    linalg_factor, 54
svd_c
     linalg_c_binding, 25
swap
    linalg_core, 34
swap_c
    linalg_c_binding, 26
trace
    linalg_core, 35
trace_c
    linalg_c_binding, 26
tri_mtx_mult
    linalg_core, 35
```