linalg

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1.1 Introduction

LINALG is a linear algebra library that provides a user-friendly interface to several BLAS and LAPACK routines.

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Version

1.0

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lapack

Data Types

- interface DLAMCH

4.1.1 Detailed Description

lapack

Purpose

Provides interfaces to various LAPACK routines.

4.2 linalg_constants Module Reference

linalg_constants

Variables

- integer, parameter dp = real64

  Defines a double-precision (64-bit) floating-point type.
- integer, parameter i32 = int32

  Defines a 32-bit signed integer type.
- integer, parameter i64 = int64

  Defines a 64-bit signed integer type.
- integer, parameter la_invalid_input_error = 101

  An error flag denoting an invalid input.
- integer, parameter la_array_size_error = 102

An error flag denoting an improperly sized array.

- integer, parameter la_singular_matrix_error = 103

  An error flag denoting a singular matrix.
- integer, parameter la_matrix_format_error = 104

  An error flag denoting an issue with the matrix format.
- integer, parameter la_out_of_memory_error = 105

  An error flag denoting that there is insufficient memory available.
- integer, parameter la_convergence_error = 106

  An error flag denoting a convergence failure.
- integer, parameter la_invalid_operation_error = 107

  An error resulting from an invalid operation.

4.2.1 Detailed Description

linalg_constants

Purpose

Provides a set of constants and error flags for the library.

4.3 linalg_core Module Reference

linalg_core

Data Types

- interface diag_mtx_mult

  Multiplies a diagonal matrix with another matrix or array.
- interface mtx_mult

  Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.
- interface solve_triangular_system

  Solves a triangular system of equations.

Functions/Subroutines

- subroutine solve_tri_mtx (lside, upper, trans, nounit, alpha, a, b, err)

  Solves one of the matrix equations: op(A) ∗ X = alpha ∗ B, or X ∗ op(A) = alpha ∗ B, where A is a triangular matrix.
- subroutine solve_tri_vec (upper, trans, nounit, a, x, err)

  Solves the system of equations: op(A) ∗ X = B, where A is a triangular matrix.
- subroutine mtx_mult_mtx (transa, transb, alpha, a, b, beta, c, err)

  Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.
- subroutine mtx_mult_vec (trans, alpha, a, b, beta, c, err)

  Performs the matrix-vector operation: c = alpha ∗ op(A) ∗ b + beta ∗ c.
- subroutine, public rank1_update (alpha, x, y, a, err)

  *Performs the rank-1 update to matrix A such that: A = alpha ∗ X ∗ Y**T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.*
- subroutine diag_mtx_mult_mtx (lside, trans, alpha, a, b, beta, c, err)

*Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C.*

- subroutine diag_mtx_mult_mtx2 (lside, alpha, a, b, err)

  *Computes the matrix operation: B = alpha * A * op(B), or B = alpha * op(B) * A.*
- subroutine diag_mtx_mult_mtx3 (lside, trans, alpha, a, b, beta, c, err)

  *Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A and C are complex-valued.*
- subroutine diag_mtx_mult_mtx4 (lside, trans, alpha, a, b, beta, c, err)

  *Computes the matrix operation: C = alpha * A * op(B) + beta * C, or C = alpha * op(B) * A + beta * C, where A, B, and C are complex-valued.*
- pure real(dp) function, public trace (x)

  Computes the trace of a matrix (the sum of the main diagonal elements).
- integer(i32) function, public mtx_rank (a, tol, work, olwork, err)

  Computes the rank of a matrix.
- real(dp) function, public det (a, iwork, err)

  Computes the determinant of a square matrix.
- subroutine, public swap (x, y, err)

  Swaps the contents of two arrays.
- subroutine, public recip_mult_array (a, x)

  Multiplies a vector by the reciprocal of a real scalar.

4.3.1 Detailed Description

linalg_core

Purpose

Provides common "core" linear algebra routines.

4.3.2 Function/Subroutine Documentation

4.3.2.1 real(dp) function, public linalg_core::det (real(dp), dimension(:,:), intent(inout) *a*, integer(i32), dimension(:), intent(out), optional, pointer *iwork*, class(errors), intent(inout), optional, target *err*)

Computes the determinant of a square matrix.

Parameters

in,out	*a*	On input, the N-by-N matrix on which to operate. On output the contents are overwritten by the LU factorization of the original matrix.
out	*iwork*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least N-elements.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Returns

The determinant of `a`.

Definition at line 1306 of file linalg_core.f90.

4.3.2.2 subroutine linalg_core::diag_mtx_mult_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* real(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* real(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B∗∗T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	The LDB-by-TDB matrix B where: • `lside` == true & `trans` == true: LDA = N, TDB = P • `lside` == true & `trans` == false: LDA = P, TDB = N • `lside` == false & `trans` == true: LDA = P, TDB = M • `lside` == false & `trans` == false: LDA = M, TDB = P
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 548 of file linalg_core.f90.

4.3.2.3 subroutine linalg_core::diag_mtx_mult_mtx2 (logical, intent(in) *lside,* real(dp), intent(in) *alpha,* real(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: B = alpha ∗ A ∗ op(B), or B = alpha ∗ op(B) ∗ A.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	On input, the M-by-N matrix B. On output, the resulting M-by-N matrix.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 715 of file linalg_core.f90.

4.3.2.4 subroutine linalg_core::diag_mtx_mult_mtx3 (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* complex(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* complex(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A and C are complex-valued.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B∗∗T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if lside is true; else, if lside is false, MIN(N,P) >= K >= 0.
in	*b*	The LDB-by-TDB matrix B where: • lside == true & trans == true: LDA = N, TDB = P • lside == true & trans == false: LDA = P, TDB = N • lside == false & trans == true: LDA = P, TDB = M • lside == false & trans == false: LDA = M, TDB = P
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 797 of file linalg_core.f90.

4.3.2.5 subroutine linalg_core::diag_mtx_mult_mtx4 (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* complex(dp), dimension(:), intent(in) *a,* complex(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* complex(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A, B, and C are complex-valued.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B**T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	The LDB-by-TDB matrix B where: • `lside` == true & `trans` == true: LDA = N, TDB = P • `lside` == true & `trans` == false: LDA = P, TDB = N • `lside` == false & `trans` == true: LDA = P, TDB = M • `lside` == false & `trans` == false: LDA = M, TDB = P
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 973 of file linalg_core.f90.

4.3.2.6 subroutine linalg_core::mtx_mult_mtx (logical, intent(in) *transa,* logical, intent(in) *transb,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp), intent(in) *beta,* real(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.

Parameters

in	*transa*	Set to true if op(A) = A**T; else, set to false for op(A) = A.
in	*transb*	Set to true if op(B) = B**T; else, set to false for op(B) = B.
in	*alpha*	A scalar multiplier.
in	*a*	If `transa` is set to true, an K-by-M matrix; else, if `transa` is set to false, an M-by-K matrix.
in	*b*	If `transb` is set to true, an N-by-K matrix; else, if `transb` is set to false, a K-by-N matrix.
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the M-by-N result.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMM.

Definition at line 305 of file linalg_core.f90.

4.3.2.7 subroutine linalg_core::mtx_mult_vec (logical, intent(in) *trans,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(in) *b,* real(dp), intent(in) *beta,* real(dp), dimension(:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix-vector operation: c = alpha ∗ op(A) ∗ b + beta ∗ c.

Parameters

in	*trans*	Set to true if op(A) = A∗∗T; else, set to false for op(A) = A.
in	*alpha*	A scalar multiplier.
in	*a*	The M-by-N matrix A.
in	*b*	If trans is set to true, an M-element array; else, if trans is set to false, an N-element array.
in	*beta*	A scalar multiplier.
in,out	*c*	On input, if trans is set to true, an N-element array; else, if trans is set to false, an M-element array. On output, the results of the operation.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMV.

Definition at line 399 of file linalg_core.f90.

4.3.2.8 integer(i32) function, public linalg_core::mtx_rank (real(dp), dimension(:,:), intent(inout) *a,* real(dp), intent(in), optional *tol,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the rank of a matrix.

Parameters

in,out	*a*	On input, the M-by-N matrix of interest. On output, the contents of the matrix are overwritten.
in	*tol*	An optional input, that if supplied, overrides the default tolerance on singular values such that singular values less than this tolerance are treated as zero. The default tolerance is: MAX(M, N) ∗ EPS ∗ MAX(S). If the supplied value is less than the smallest value that causes an overflow if inverted, the tolerance reverts back to its default value, and the operation continues; however, a warning message is issued.

Parameters

out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

See Also

- Wolfram MathWorld

Definition at line 1186 of file linalg_core.f90.

4.3.2.9 subroutine, public linalg_core::rank1_update (real(dp), intent(in) *alpha,* real(dp), dimension(:), intent(in) *x,* real(dp), dimension(:), intent(in) *y,* real(dp), dimension(:,:), intent(inout) *a,* class(errors), intent(inout), optional, target *err*)

Performs the rank-1 update to matrix A such that: A = alpha ∗ X ∗ Y∗∗T + A, where A is an M-by-N matrix, alpha is a scalar, X is an M-element array, and N is an N-element array.

Parameters

in	*alpha*	The scalar multiplier.
in	*x*	An M-element array.
in	*y*	An N-element array.
in,out	*a*	On input, the M-by-N matrix to update. On output, the updated M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if the size of a does not match with x and y.

Notes

This routine is based upon the BLAS routine DGER.

Definition at line 477 of file linalg_core.f90.

4.3.2.10 subroutine, public linalg_core::recip_mult_array (real(dp), intent(in) *a,* real(dp), dimension(:), intent(inout) *x*)

Multiplies a vector by the reciprocal of a real scalar.

Parameters

in	*a*	The scalar which is used to divide each component of X. The value must be >= 0, or the subroutine will divide by zero.
in,out	*x*	The vector.

Notes

This routine is based upon the LAPACK routine DRSCL.

Definition at line 1457 of file linalg_core.f90.

4.3.2.11 subroutine linalg_core::solve_tri_mtx (logical, intent(in) *lside,* logical, intent(in) *upper,* logical, intent(in) *trans,* logical, intent(in) *nounit,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves one of the matrix equations: op(A) ∗ X = alpha ∗ B, or X ∗ op(A) = alpha ∗ B, where A is a triangular matrix.

Parameters

in	*lside*	Set to true to solve op(A) ∗ X = alpha ∗ B; else, set to false to solve X ∗ op(A) = alpha ∗ B.
in	*upper*	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	*trans*	Set to true if op(A) = A∗∗T; else, set to false if op(A) = A.
in	*nounit*	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	*alpha*	The scalar multiplier to B.
in	*a*	If lside is true, the M-by-M triangular matrix on which to operate; else, if lside is false, the N-by-N triangular matrix on which to operate.
in,out	*b*	On input, the M-by-N right-hand-side. On output, the M-by-N solution.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A∗X = B, where A is an N-by-N upper triangular matrix, and B and X are N-by-NRHS matrices, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N
! matrix, and B and X are N-by-NRHS in size.

! Variables
```

```
integer(i32) :: info
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b

! Initialize A and B...

! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .true., .false., .true., &
     1.0d0, a, b)
```

Notes

This routine is based upon the BLAS routine DTRSM.

Definition at line 114 of file linalg_core.f90.

4.3.2.12 subroutine linalg_core::solve_tri_vec (logical, intent(in) *upper,* logical, intent(in) *trans,* logical, intent(in) *nounit,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(inout) *x,* class(errors), intent(inout), optional, target *err*) [private]

Solves the system of equations: op(A) $*$ X = B, where A is a triangular matrix.

Parameters

in	*upper*	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	*trans*	Set to true if op(A) = A$**$T; else, set to false if op(A) = A.
in	*nounit*	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	*a*	The N-by-N triangular matrix.
in,out	*x*	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A$*$X = B, where A is an N-by-N upper triangular matrix, and B and X are N-element arrays, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N
! matrix, and B and X are N-elements in size.

! Variables
integer(i32) :: info
real(dp), dimension(n, n) :: a
real(dp), dimension(n) :: b

! Initialize A and B...

! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .false., a, b)
```

Notes

This routine is based upon the BLAS routine DTRSV.

Definition at line 220 of file linalg_core.f90.

4.3.2.13 subroutine, public linalg_core::swap (real(dp), dimension(:), intent(inout) *x*, real(dp), dimension(:), intent(inout) *y*, class(errors), intent(inout), optional, target *err*)

Swaps the contents of two arrays.

Parameters

in,out	*x*	One of the N-element arrays.
in,out	*y*	The other N-element array.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if x and y are not the same size.

Definition at line 1411 of file linalg_core.f90.

4.3.2.14 pure real(dp) function, public linalg_core::trace (real(dp), dimension(:,:), intent(in) *x*)

Computes the trace of a matrix (the sum of the main diagonal elements).

Parameters

in	*x*	The matrix on which to operate.

Returns

The trace of x.

Definition at line 1130 of file linalg_core.f90.

4.4 linalg_eigen Module Reference

linalg_eigen

Data Types

- interface eigen

  Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

Functions/Subroutines

- subroutine eigen_symm (vecs, a, vals, work, olwork, err)

  Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.
- subroutine eigen_asymm (a, vals, vecs, work, olwork, err)

  Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.
- subroutine eigen_gen (a, b, alpha, beta, vecs, work, olwork, err)

  Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A∗X = lambda∗B∗X.

4.4.1 Detailed Description

linalg_eigen

Purpose

Provides routines for computing the eigenvalues and eigenvectors of matrices.

4.4.2 Function/Subroutine Documentation

4.4.2.1 subroutine linalg_eigen::eigen_asymm (real(dp), dimension(:,:), intent(inout) *a,* complex(dp), dimension(:), intent(out) *vals,* complex(dp), dimension(:,:), intent(out), optional *vecs,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.

Parameters

in,out	*a*	On input, the N-by-N matrix on which to operate. On output, the contents of this matrix are overwritten.
out	*vals*	An N-element array containing the eigenvalues of the matrix. The eigenvalues are not sorted.
out	*vecs*	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DGEEV.

Definition at line 185 of file linalg_eigen.f90.

4.4.2.2 subroutine linalg_eigen::eigen_gen (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* complex(dp), dimension(:), intent(out) *alpha,* real(dp), dimension(:), intent(out), optional *beta,* complex(dp), dimension(:,:), intent(out), optional *vecs,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A∗X = lambda∗B∗X.

Parameters

in,out	*a*	On input, the N-by-N matrix A. On output, the contents of this matrix are overwritten.
in,out	*b*	On input, the N-by-N matrix B. On output, the contents of this matrix are overwritten.
out	*alpha*	An N-element array that, if `beta` is not supplied, contains the eigenvalues. If `beta` is supplied however, the eigenvalues must be computed as ALPHA / BETA. This however, is not as trivial as it seems as it is entirely possible, and likely, that ALPHA / BETA can overflow or underflow. With that said, the values in ALPHA will always be less than and usually comparable with the NORM(A).
out	*beta*	An optional N-element array that if provided forces `alpha` to return the numerator, and this array contains the denominator used to determine the eigenvalues as ALPHA / BETA. If used, the values in this array will always be less than and usually comparable with the NORM(B).
out	*vecs*	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Usage

As an example, consider the eigenvalue problem arising from a mechanical system of masses and springs such that the masses are described by a mass matrix M, and the arrangement of springs are described by a stiffness matrix K.

```
! Parameters
real(dp), parameter :: pi = 3.141592653589793d0

! Variables
real(dp), dimension(n, n) :: m, k
complex(dp), dimension(n, n) :: mode_shapes
complex(dp), dimension(n) :: vals
real(dp), dimension(n) :: nat_freq

! Initialize the mass matrix (m) and the stiffness matrix (k)...

! Solve the eigenvalue problem.  The eigenvectors define the mode shapes
! for the system (each eigenvector defines a different mode shape, and
```

```
! are stored one per column).
call eigen(k, m, vals, vecs = mode_shapes)

! The eigenvalues represent the square of the system natural frequencies.
! Also, a properly constrained mechanical system will exhibit only real
! eigenvalues; therefore, the following relationship will return the
! natural frequencies with units of Hz.
nat_freq = sqrt(real(vals, dp)) / (2.0d0 * pi)
```

Notes

This routine utilizes the LAPACK routine DGGEV.

Definition at line 426 of file linalg_eigen.f90.

4.4.2.3 subroutine linalg_eigen::eigen_symm (logical, intent(in) *vecs,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *vals,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

Parameters

in	*vecs*	Set to true to compute the eigenvectors as well as the eigenvalues; else, set to false to just compute the eigenvalues.
in,out	*a*	On input, the N-by-N symmetric matrix on which to operate. On output, and if vecs is set to true, the matrix will contain the eigenvectors (one per column) corresponding to each eigenvalue in vals. If vecs is set to false, the lower triangular portion of the matrix is overwritten.
out	*vals*	An N-element array that will contain the eigenvalues sorted into ascending order.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DSYEV.

Definition at line 68 of file linalg_eigen.f90.

4.5 linalg_factor Module Reference

linalg_factor

Data Types

- interface form_lu

  Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.
- interface form_qr

  Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.
- interface mult_qr

  Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.
- interface mult_rz

  Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.
- interface qr_factor

  Computes the QR factorization of an M-by-N matrix.

Functions/Subroutines

- subroutine, public lu_factor (a, ipvt, err)

  Computes the LU factorization of an M-by-N matrix.
- subroutine form_lu_all (lu, ipvt, u, p, err)

  Extracts the L, U, and P matrices from the output of the lu_factor routine.
- subroutine form_lu_only (lu, u, err)

  Extracts the L, and U matrices from the output of the lu_factor routine.
- subroutine qr_factor_no_pivot (a, tau, work, olwork, err)

  Computes the QR factorization of an M-by-N matrix without pivoting.
- subroutine qr_factor_pivot (a, tau, jpvt, work, olwork, err)

  Computes the QR factorization of an M-by-N matrix with column pivoting such that A ∗ P = Q ∗ R.
- subroutine form_qr_no_pivot (r, tau, q, work, olwork, err)

  Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.
- subroutine form_qr_pivot (r, tau, pvt, q, p, work, olwork, err)

  Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.
- subroutine mult_qr_mtx (lside, trans, a, tau, c, work, olwork, err)

  Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) ∗ C, or C = C ∗ op(Q).
- subroutine mult_qr_vec (trans, a, tau, c, work, olwork, err)

  Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) ∗ C.
- subroutine, public qr_rank1_update (q, r, u, v, work, err)

  Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q ∗ R, and A1 = A + U ∗ V∗∗T such that A1 = Q1 ∗ R1.
- subroutine, public cholesky_factor (a, upper, err)

  Computes the Cholesky factorization of a symmetric, positive definite matrix.
- subroutine, public cholesky_rank1_update (r, u, work, err)

  Computes the rank 1 update to a Cholesky factored matrix (upper triangular).
- subroutine, public rz_factor (a, tau, work, olwork, err)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that A = R ∗ Z = (R 0) ∗ Z. Z is an orthogonal matrix of dimension (M+L)-by-(M+L), and R is an M-by-M upper triangular matrix.

- subroutine mult_rz_mtx (lside, trans, l, a, tau, c, work, olwork, err)

  Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) ∗ C, or C = C ∗ op(Z).
- subroutine mult_rz_vec (trans, l, a, tau, c, work, olwork, err)

  Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) ∗ C.
- subroutine, public svd (a, s, u, vt, work, olwork, err)

  Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U ∗ S ∗ V∗∗T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

4.5.1 Detailed Description

linalg_factor

Purpose

Provides a set of matrix factorization routines.

4.5.2 Function/Subroutine Documentation

4.5.2.1 subroutine, public linalg_factor::cholesky_factor (real(dp), dimension(:,:), intent(inout) *a,* logical, intent(in), optional *upper,* class(errors), intent(inout), optional, target *err*)

Computes the Cholesky factorization of a symmetric, positive definite matrix.

Parameters

`in,out`	*a*	On input, the N-by-N matrix to factor. On output, the factored matrix is returned in either the upper or lower triangular portion of the matrix, dependent upon the value of `upper`.
`in`	*upper*	An optional input that, if specified, provides control over whether the factorization is computed as A = U∗∗T ∗ U (set to true), or as A = L ∗ L∗∗T (set to false). The default value is true such that A = U∗∗T ∗ U.
`out`	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if `a` is not square. • LA_MATRIX_FORMAT_ERROR: Occurs if `a` is not positive definite.

Usage

To solve a system of N equations of N unknowns using Cholesky factorization, the following code will suffice. Notice, the system of equations must be positive definite.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.

! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b
```

```
logical :: upper

! Initialize A and B...

! Specify that we're using the upper portion of A (remember positive
! definite matrices are symmetric)
upper = .true.

! Compute the factorization of A.
call cholesky_factor(a, upper)

! Solve A*X = B for X - Note: X overwrites B.
call solve_cholesky(upper, a, b)
```

Notes

This routine utilizes the LAPACK routine DPOTRF.

Definition at line 1307 of file linalg_factor.f90.

4.5.2.2 subroutine, public linalg_factor::cholesky_rank1_update (real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(inout) *u,* real(dp), dimension(:), intent(out), optional, target *work,* class(errors), intent(inout), optional, target *err*)

Computes the rank 1 update to a Cholesky factored matrix (upper triangular).

Parameters

in,out	*r*	On input, the N-by-N upper triangular matrix R. On output, the updated matrix R1.
in,out	*u*	On input, the N-element update vector U. On output, the rotation sines used to transform R to R1.
out	*work*	An optional argument that if supplied prevents local memory allocation. If provided, the array must have at least N elements. Additionally, this workspace array is used to contain the rotation cosines used to transform R to R1.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the QRUPDATE routine DCH1UP.

See Also

Source

Definition at line 1399 of file linalg_factor.f90.

4.5.2.3 subroutine linalg_factor::form_lu_all (real(dp), dimension(:,:), intent(inout) *lu,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:,:), intent(out) *u,* real(dp), dimension(:,:), intent(out) *p,* class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, U, and P matrices from the output of the lu_factor routine.

Parameters

in,out	*lu*	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
in	*ipvt*	The N-element pivot array as output by lu_factor.
out	*u*	An N-by-N matrix where the U matrix will be written.
out	*p*	An N-by-N matrix where the row permutation matrix will be written.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Remarks

This routine allows extraction of the actual "L", "U", and "P" matrices of the decomposition. To use these matrices to solve the system A∗X = B, the following approach is used.

1. First, solve the linear system: L∗Y = P∗B for Y.
2. Second, solve the linear system: U∗X = Y for X.

Notice, as both L and U are triangular in structure, the above equations can be solved by forward and backward substitution.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 210 of file linalg_factor.f90.

4.5.2.4 subroutine linalg_factor::form_lu_only (real(dp), dimension(:,:), intent(inout) *lu,* real(dp), dimension(:,:), intent(out) *u,* class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, and U matrices from the output of the lu_factor routine.

Parameters

in,out	*lu*	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
out	*u*	An N-by-N matrix where the U matrix will be written.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 287 of file linalg_factor.f90.

4.5.2.5 subroutine linalg_factor::form_qr_no_pivot (real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(out) *q,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	*r*	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in h.
out	*q*	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that M $>$ N, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q $*$ R = [Q1, Q2] $*$ [R1; 0].
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 693 of file linalg_factor.f90.

4.5.2.6 subroutine linalg_factor::form_qr_pivot (real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *pvt,* real(dp), dimension(:,:), intent(out) *q,* real(dp), dimension(:,:), intent(out) *p,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	*r*	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in h.
in	*pvt*	An N-element column pivot array as returned by the QR factorization.
out	*q*	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that M $>$ N, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q $*$ R = [Q1, Q2] $*$ [R1; 0].
out	*p*	An N-by-N matrix where the pivot matrix will be written.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 824 of file linalg_factor.f90.

4.5.2.7 subroutine, public linalg_factor::lu_factor (real(dp), dimension(:,:), intent(inout) *a,* integer(i32), dimension(:), intent(out) *ipvt,* class(errors), intent(inout), optional, target *err*)

Computes the LU factorization of an M-by-N matrix.

Parameters

in,out	*a*	On input, the M-by-N matrix on which to operate. On output, the LU factored matrix in the form [L\U] where the unit diagonal elements of L are not stored.
out	*ipvt*	An MIN(M, N)-element array used to track row-pivot operations. The array stored pivot information such that row I is interchanged with row IPVT(I).
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if ipvt is not sized appropriately. • LA_SINGULAR_MATRIX_ERROR: Occurs as a warning if a is found to be singular.

Usage

To solve a system of N equations of N unknowns using LU factorization, the following code will suffice.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.

! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b

! Define the array used to track row pivots.
integer(i32), dimension(n) :: pvt

! Initialize A and B...

! Compute the LU factorization of A.  On output, A contains [L\U].
call lu_factor(a, pvt)

! Solve A*X = B for X - Note: X overwrites B.
call solve_lu(a, pvt, b)
```

Notes

This routine utilizes the LAPACK routine DGETRF.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 126 of file linalg_factor.f90.

4.5.2.8 subroutine linalg_factor::mult_qr_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) $*$ C, or C = C $*$ op(Q).

Parameters

in	*lside*	Set to true to apply Q or Q**T from the left; else, set to false to apply Q or Q**T from the right.
in	*trans*	Set to true to apply Q**T; else, set to false.
in	*a*	On input, an LDA-by-K matrix containing the elementary reflectors output from the QR factorization. If lside is set to true, LDA = M, and M >= K >= 0; else, if lside is set to false, LDA = N, and N >= K >= 0. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	*c*	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Q and the original matrix C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMQR.

Definition at line 926 of file linalg_factor.f90.

4.5.2.9 subroutine linalg_factor::mult_qr_vec (logical, intent(in) *trans,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) $*$ C.

Parameters

in	*trans*	Set to true to apply Q$**$T; else, set to false.
in	*a*	On input, an M-by-K matrix containing the elementary reflectors output from the QR factorization. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	*c*	On input, the M-element vector C. On output, the product of the orthogonal matrix Q and the original vector C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon the LAPACK routine DORM2R.

Definition at line 1053 of file linalg_factor.f90.

4.5.2.10 subroutine linalg_factor::mult_rz_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* integer(i32), intent(in) *l,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) $*$ C, or C = C $*$ op(Z).

Parameters

in	*lside*	Set to true to apply Z or Z$**$T from the left; else, set to false to apply Z or Z$**$T from the right.
in	*trans*	Set to true to apply Z$**$T; else, set to false.
in	*l*	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, M >= L >= 0; else, if lside is false, N >= L >= 0.
in,out	*a*	On input the K-by-LTA matrix C, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of the elementary reflectors, where M >= K >= 0 if lside is true; else, N >= K >= 0 if lside is false.
in,out	*c*	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Z and the original matrix C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1642 of file linalg_factor.f90.

4.5.2.11 subroutine linalg_factor::mult_rz_vec (logical, intent(in) *trans,* integer(i32), intent(in) *l,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) $*$ C.

Parameters

in	*trans*	Set to true to apply Z**T; else, set to false.
in	*l*	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, M >= L >= 0; else, if lside is false, N >= L >= 0.
in,out	*a*	On input the K-by-LTA matrix C, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of the elementary reflectors, where M >= K >= 0 if lside is true; else, N >= K >= 0 if lside is false.
in,out	*c*	On input, the M-element array C. On output, the product of the orthogonal matrix Z and the original array C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1784 of file linalg_factor.f90.

4.5.2.12 subroutine linalg_factor::qr_factor_no_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix without pivoting.

Parameters

in,out	*a*	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if M >= N). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	*tau*	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if `tau` or `work` are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Remarks

QR factorization without pivoting is best suited to solving an overdetermined system in least-squares terms, or to solve a normally defined system. To solve an underdetermined system, it is recommended to use either LQ factorization, or a column-pivoting based QR factorization.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice assuming M >= N.

```
! Solve the system: A*X = B in a least-squares sense, where A is an
! M-by-N matrix, B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, nrhs) :: b, qtb
real(dp), dimension(n, nrhs) :: x
real(dp), dimension(n) :: tau
real(dp), dimension(m, m) :: q

! Initialize A and B...

! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
! scalar factors in TAU.  Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau)

! Solve A*X = B for X.  The first N rows of B are used to store X.
call solve_qr(a, tau, b)

! Also note, we could form Q and R explicitly.  Then solution of the
! system of equations can be found.  First we form Q and R.
call form_qr(a, tau, q) ! Forms Q, and R is stored in A

! Since we now have Q and R, we seek a solution to the equation:
! Q*R*X = B, but Q is an orthogonal matrix (i.e. Q**T = inv(Q)).
! Then: R*X = Q**T * B, and R is upper triangular; therefore, back
! substitution will suffice for a solution procedure.
!
! Next, compute Q**T * B, and store in QTB.
call mtx_mult(.true., .false., 1.0d0, q, b, 0.0d0, qtb)

! Copy the first N rows of Q**T * B into X for the solution process.
! Notice, only the first N rows are needed as rows N+1:M are all zero in
! matrix R.
x = qtb(1:n,nrhs)

! Compute the solution and store in X
call solve_triangular_system(.true., .true., .false., .true., 1.0d0, &
 a(1:n,1:n), x)
```

Notes

This routine utilizes the LAPACK routine DGEQRF.

Definition at line 424 of file linalg_factor.f90.

4.5.2.13 subroutine linalg_factor::qr_factor_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* integer(i32), dimension(:), intent(inout) *jpvt,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix with column pivoting such that A ∗ P = Q ∗ R.

Parameters

in,out	*a*	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if M >= N). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	*tau*	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in,out	*jpvt*	On input, an N-element array that if JPVT(I) .ne. 0, the I-th column of A is permuted to the front of A ∗ P; if JPVT(I) = 0, the I-th column of A is a free column. On output, if JPVT(I) = K, then the I-th column of A ∗ P was the K-th column of A.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice for any M and N.

```
! Solve the least-squares (M >= N), or the underdetermined (M < N)
! problem A*X = B, where A is an M-by-N matrix, B is an M-by-NRHS matrix,
! and X is an N-by-NRHS matrix.  In the underdetermined case, or the
! case where the rank of matrix A is less than N, the solution obtained
! contains the fewest possible non-zero entries.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(n, nrhs) :: b
real(dp), dimension(k) :: tau ! k = min(m, n)
real(dp), dimension(m, m) :: q
real(dp), dimension(n, n) :: p
integer(i32), dimension(n) :: pvt

! Initialize A and B...

! Allow all columns to be free.
pvt = 0

! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
! scalar factors in TAU.  Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau, pvt)

! Solve A*X = B for X.  If M > N, the first N rows of B are used to store
! X.  If M < N, the input matrix B must be N-by-NRHS, and only the first
```

```
! M rows are used for the actual matrix B.  The remaining N-M rows
! can contain whatever as they are not referenced until they are
! overwritten by the N-by-NRHS solution matrix X.
call solve_qr(a, tau, pvt, b)

! Notice, if the explicit Q matrix from the factorization is desired,
! the form_qr routine works similarly as in the no-pivot case;
! however, the permutation matrix P is also constructed.  The call would
! be as follows.  Also, as with the no-pivot algorithm, the matrix R is
! stored in matrix A.
call form_qr(a, tau, pvt, q, p)

! Solution can proceed as per typical, but with a full Q matrix.  Also
! note, the problem is of the form: A*P = Q*R.  Solution is straight
! forward, as with the no-pivot case; however, if M < N, then R is upper
! trapezoidal, and must be appropriately partitioned to solve.  The rank
! of matrix r should be considered when applying the partition.
```

Notes

This routine utilizes the LAPACK routine DGEQP3.

Definition at line 578 of file linalg_factor.f90.

4.5.2.14 subroutine, public linalg_factor::qr_rank1_update (real(dp), dimension(:,:), intent(inout) *q,* real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(inout) *u,* real(dp), dimension(:), intent(inout) *v,* real(dp), dimension(:), intent(out), optional, target *work,* class(errors), intent(inout), optional, target *err*)

Computes the rank 1 update to an M-by-N QR factored matrix A (M >= N) where A = Q ∗ R, and A1 = A + U ∗ V**T such that A1 = Q1 ∗ R1.

Parameters

in,out	*q*	On input, the original M-by-K orthogonal matrix Q. On output, the updated matrix Q1.
in,out	*r*	On input, the M-by-N matrix R. On output, the updated matrix R1.
in,out	*u*	On input, the M-element U update vector. On output, the original content of the array is overwritten.
in,out	*v*	On input, the N-element V update vector. On output, the original content of the array is overwritten.
out	*work*	An optional argument that if supplied prevents local memory allocation. If provided, the array must have at least 2∗K elements.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Remarks

```
Notice, K must either be equal to M, or to N.  In the event that K = N,
only the submatrix Qa is updated.  This is appropriate as the QR
factorization for an overdetermined system can be written as follows:
 A = Q * R = [Qa, Qb] * [Ra]
                        [0 ]

Note: Ra is upper triangular of dimension N-by-N.
```

Notes

This routine utilizes the QRUPDATE routine DQR1UP.

See Also

Source

Definition at line 1179 of file linalg_factor.f90.

4.5.2.15 subroutine, public linalg_factor::rz_factor (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Factors an upper trapezoidal matrix by means of orthogonal transformations such that A = R ∗ Z = (R 0) ∗ Z. Z is an orthogonal matrix of dimension (M+L)-by-(M+L), and R is an M-by-M upper triangular matrix.

Parameters

in,out	*a*	On input, the M-by-N upper trapezoidal matrix to factor. On output, the leading M-by-M upper triangular part of the matrix contains the upper triangular matrix R, and elements N-L+1 to N of the first M rows of A, with the array tau, represent the orthogonal matrix Z as a product of M elementary reflectors.
out	*tau*	
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Further Details

```
The factorization is obtained by Householder's method.  The kth
transformation matrix, Z( k ), which is used to introduce zeros into
the ( m - k + 1 )th row of A, is given in the form

   Z( k ) = ( I     0   ),
            ( 0  T( k ) )

where

   T( k ) = I - tau*u( k )*u( k )**T,   u( k ) = (   1    ),
                                                 (   0    )
                                                 ( z( k ) )

tau is a scalar and z( k ) is an l element vector. tau and z( k )
are chosen to annihilate the elements of the kth row of A2.
```

```
The scalar tau is returned in the kth element of TAU and the vector
u( k ) in the kth row of A2, such that the elements of z( k ) are
in  a( k, l + 1 ), ..., a( k, n ). The elements of R are returned in
the upper triangular part of A1.

Z is given by

   Z =  Z( 1 ) * Z( 2 ) * ... * Z( m ).
```

Notes

This routine is based upon the LAPACK routine DTZRZF.

See Also

- LAPACK Users Manual

Definition at line 1530 of file linalg_factor.f90.

4.5.2.16 subroutine, public linalg_factor::svd (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *s,* real(dp), dimension(:,:), intent(out), optional *u,* real(dp), dimension(:,:), intent(out), optional *vt,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the singular value decomposition of a matrix A. The SVD is defined as: A = U ∗ S ∗ V∗∗T, where U is an M-by-M orthogonal matrix, S is an M-by-N diagonal matrix, and V is an N-by-N orthogonal matrix.

Parameters

in,out	*a*	On input, the M-by-N matrix to factor. The matrix is overwritten on output.
out	*s*	A MIN(M, N)-element array containing the singular values of a sorted in descending order.
out	*u*	An optional argument, that if supplied, is used to contain the orthogonal matrix U from the decomposition. The matrix U contains the left singular vectors, and can be either M-by-M (all left singular vectors are computed), or M-by-MIN(M,N) (only the first MIN(M, N) left singular vectors are computed).
out	*vt*	An optional argument, that if supplied, is used to contain the transpose of the N-by-N orthogonal matrix V. The matrix V contains the right singular vectors.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Usage

```
! Decompose matrix the M-by-N matrix A such that A = U * S * V**T with
! M >= N.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, m) :: u
real(dp), dimension(n, n) :: vt
real(dp), dimension(n) :: s

! Initialize A...

! Compute the SVD of A. On output, S contains the MIN(M,N) singular
! values of A in descending order, U contains the left singular vectors
! (one per column), and VT contains the right singular vectors (one per
! row).
call svd(a, s, u, vt)

! Note: If M > N, then we can make U M-by-N, and compute the N
! left singular vectors of A, as there are at most N singular values
! of A.  Also, if M < N, then there are at most M singular values of A,
! and as such, the length of the array s should be m.
```

Notes

This routine utilizes the LAPACK routine DGESVD.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 1943 of file linalg_factor.f90.

4.6 linalg_solve Module Reference

linalg_solve

Data Types

- interface least_squares_solve

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns.
- interface least_squares_solve_full

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.
- interface least_squares_solve_svd

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.
- interface solve_cholesky

  Solves a system of Cholesky factored equations.
- interface solve_lu

  Solves a system of LU-factored equations.
- interface solve_qr

  Solves a system of M QR-factored equations of N unknowns.

Functions/Subroutines

- subroutine solve_lu_mtx (a, ipvt, b, err)

  Solves a system of LU-factored equations.
- subroutine solve_lu_vec (a, ipvt, b, err)

  Solves a system of LU-factored equations.
- subroutine solve_qr_no_pivot_mtx (a, tau, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where M >= N.
- subroutine solve_qr_no_pivot_vec (a, tau, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where M >= N.
- subroutine solve_qr_pivot_mtx (a, tau, jpvt, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.
- subroutine solve_qr_pivot_vec (a, tau, jpvt, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.
- subroutine solve_cholesky_mtx (upper, a, b, err)

  Solves a system of Cholesky factored equations.
- subroutine solve_cholesky_vec (upper, a, b, err)

  Solves a system of Cholesky factored equations.
- subroutine, public mtx_inverse (a, iwork, work, olwork, err)

  Computes the inverse of a square matrix.
- subroutine, public mtx_pinverse (a, ainv, tol, work, olwork, err)

  Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix.
- subroutine least_squares_solve_mtx (a, b, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine least_squares_solve_vec (a, b, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine least_squares_solve_mtx_1 (a, b, x, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine least_squares_solve_mtx_pvt (a, b, ipvt, arnk, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.
- subroutine least_squares_solve_vec_pvt (a, b, ipvt, arnk, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.
- subroutine least_squares_solve_mtx_svd (a, b, arnk, s, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.
- subroutine least_squares_solve_vec_svd (a, b, arnk, s, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

4.6.1 Detailed Description

linalg_solve

Purpose

Provides a set of routines for solving systems of linear equations.

4.6.2 Function/Subroutine Documentation

4.6.2.1 subroutine linalg_solve::least_squares_solve_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1347 of file linalg_solve.f90.

4.6.2.2 subroutine linalg_solve::least_squares_solve_mtx_1 (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:,:), intent(out) *x,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.

Parameters

in,out	*b*	On input, the M-by-NRHS matrix B. On output the contents are overwritten.
out	*x*	The N-by-NRHS solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1560 of file linalg_solve.f90.

4.6.2.3 subroutine linalg_solve::least_squares_solve_mtx_pvt (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* integer(i32), dimension(:), intent(inout), optional, target *ipvt,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.

Definition at line 1653 of file linalg_solve.f90.

4.6.2.4 subroutine linalg_solve::least_squares_solve_mtx_svd (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out) *s,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*s*	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 1941 of file linalg_solve.f90.

4.6.2.5 subroutine linalg_solve::least_squares_solve_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.
in,out	*b*	If M >= N, the M-element array B. On output, the first N elements contain the N-element solution array X. If M < N, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1454 of file linalg_solve.f90.

4.6.2.6 subroutine linalg_solve::least_squares_solve_vec_pvt (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* integer(i32), dimension(:), intent(inout), optional, target *ipvt,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-element array B. On output, the first N elements contain the N-element solution array X. If M < N, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	*ipvt*	On input, an N-element array that if IPVT(I) .ne. 0, the I-th column of A is permuted to the front of A ∗ P; if IPVT(I) = 0, the I-th column of A is a free column. On output, if IPVT(I) = K, then the I-th column of A ∗ P was the K-th column of A.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.

Parameters

out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1797 of file linalg_solve.f90.

4.6.2.7 subroutine linalg_solve::least_squares_solve_vec_svd (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out) *s,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*s*	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2069 of file linalg_solve.f90.

4.6.2.8 subroutine, public linalg_solve::mtx_inverse (real(dp), dimension(:,:), intent(inout) *a,* integer(i32), dimension(:), intent(out), optional, target *iwork,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the inverse of a square matrix.

Parameters

in,out	*a*	On input, the N-by-N matrix to invert. On output, the inverted matrix.
out	*iwork*	An optional N-element integer workspace array.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square. Will also occur if incorrectly sized workspace arrays are provided. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_SINGULAR_MATRIX_ERROR: Occurs if the input matrix is singular.

Usage

```
! The following example illustrates how to solve a system of linear
! equations by matrix inversion.  Notice, this is not a preferred
! solution technique (use LU factorization instead), but is merely a
! means of illustrating how to compute the inverse of a square matrix.

! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b, x

! Initialize A and B...

! Compute the inverse of A.  The inverse will overwrite the original
! matrix.
call mtx_inverse(a)

! Solve A*X = B as X = inv(A) * B.
x = matmul(a, b)
```

Notes

This routine utilizes the LAPACK routines DGETRF to perform an LU factorization of the matrix, and DGETRI to invert the LU factored matrix.

See Also

- Wikipedia

- Wolfram MathWorld

Definition at line 1018 of file linalg_solve.f90.

4.6.2.9 subroutine, public linalg_solve::mtx_pinverse (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(out) *ainv,* real(dp), intent(in), optional *tol,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*)

Computes the Moore-Penrose pseudo-inverse of a M-by-N matrix using the singular value decomposition of the matrix.

Parameters

in,out	*a*	On input, the M-by-N matrix to invert. The matrix is overwritten on output.
out	*ainv*	The N-by-M matrix where the pseudo-inverse of a will be written.
in	*tol*	An optional input, that if supplied, overrides the default tolerance on singular values such that singular values less than this tolerance are forced to have a reciprocal of zero, as opposed to 1/S(I). The default tolerance is: MAX(M, N) $*$ EPS $*$ MAX(S). If the supplied value is less than a value that causes an overflow, the tolerance reverts back to its default value, and the operation continues; however, a warning message is issued.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Usage

```
! Use the pseudo-inverse to obtain a least-squares solution to the
! overdetermined problem A*X = B, where A is an M-by-N matrix (M >= N),
! B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(n, m) :: ainv
real(dp), dimension(m, nrhs) :: b
real(dp), dimension(n, nrhs) :: x

! Initialize A, and B...

! Compute the pseudo-inverse of A.  Let the subroutine allocate its
! own workspace array.
call mtx_pinverse(a, ainv)

! Compute X = AINV * B to obtain the solution.
x = matmul(ainv, b)
```

See Also

- Wikipedia
- Wolfram MathWorld
- MathWorks

Definition at line 1178 of file linalg_solve.f90.

4.6.2.10 subroutine linalg_solve::solve_cholesky_mtx (logical, intent(in) *upper,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	*upper*	Set to true if the original matrix A was factored such that A = U∗∗T ∗ U; else, set to false if the factorization of A was A = L∗∗T ∗ L.
in	*a*	The N-by-N Cholesky factored matrix.
in,out	*b*	On input, the N-by-NRHS right-hand-side matrix B. On output, the solution matrix X.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 851 of file linalg_solve.f90.

4.6.2.11 subroutine linalg_solve::solve_cholesky_vec (logical, intent(in) *upper,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	*upper*	Set to true if the original matrix A was factored such that A = U∗∗T ∗ U; else, set to false if the factorization of A was A = L∗∗T ∗ L.
in	*a*	The N-by-N Cholesky factored matrix.
in,out	*b*	On input, the N-element right-hand-side vector B. On output, the solution vector X.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 917 of file linalg_solve.f90.

4.6.2.12 subroutine linalg_solve::solve_lu_mtx (real(dp), dimension(:,:), intent(in) *a,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

Parameters

in	*a*	The N-by-N LU factored matrix as output by lu_factor.
in	*ipvt*	The N-element pivot array as output by lu_factor.
in,out	*b*	On input, the N-by-NRHS right-hand-side matrix. On output, the N-by-NRHS solution matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 129 of file linalg_solve.f90.

4.6.2.13 subroutine linalg_solve::solve_lu_vec (real(dp), dimension(:,:), intent(in) *a,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

Parameters

in	*a*	The N-by-N LU factored matrix as output by lu_factor.
in	*ipvt*	The N-element pivot array as output by lu_factor.
in,out	*b*	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 190 of file linalg_solve.f90.

4.6.2.14 subroutine linalg_solve::solve_qr_no_pivot_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where M >= N.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*b*	On input, the M-by-NRHS right-hand-side matrix. On output, the first N columns are overwritten by the solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 265 of file linalg_solve.f90.

4.6.2.15 subroutine linalg_solve::solve_qr_no_pivot_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where M >= N.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*b*	On input, the M-element right-hand-side vector. On output, the first N elements are overwritten by the solution vector X.

Parameters

out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 380 of file linalg_solve.f90.

4.6.2.16 subroutine linalg_solve::solve_qr_pivot_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *jpvt,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*jpvt*	An N-element array, as output by qr_factor, used to track the column pivots.
in	*b*	On input, the MAX(M, N)-by-NRHS matrix where the first M rows contain the right-hand-side matrix B. On output, the first N rows are overwritten by the solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 493 of file linalg_solve.f90.

4.6.2.17 subroutine linalg_solve::solve_qr_pivot_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *jpvt,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*jpvt*	An N-element array, as output by qr_factor, used to track the column pivots.
in	*b*	On input, the MAX(M, N)-element array where the first M elements contain the right-hand-side vector B. On output, the first N elements are overwritten by the solution vector X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 680 of file linalg_solve.f90.

Chapter 5

Data Type Documentation

5.1 linalg_core::diag_mtx_mult Interface Reference

Multiplies a diagonal matrix with another matrix or array.

Private Member Functions

- subroutine diag_mtx_mult_mtx (lside, trans, alpha, a, b, beta, c, err)

  Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C.
- subroutine diag_mtx_mult_mtx2 (lside, alpha, a, b, err)

  Computes the matrix operation: B = alpha ∗ A ∗ op(B), or B = alpha ∗ op(B) ∗ A.
- subroutine diag_mtx_mult_mtx3 (lside, trans, alpha, a, b, beta, c, err)

  Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A and C are complex-valued.
- subroutine diag_mtx_mult_mtx4 (lside, trans, alpha, a, b, beta, c, err)

  Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A, B, and C are complex-valued.

5.1.1 Detailed Description

Multiplies a diagonal matrix with another matrix or array.

Definition at line 53 of file linalg_core.f90.

5.1.2 Member Function/Subroutine Documentation

5.1.2.1 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* real(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* real(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B**T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	The LDB-by-TDB matrix B where: • `lside` == true & `trans` == true: LDA = N, TDB = P • `lside` == true & `trans` == false: LDA = P, TDB = N • `lside` == false & `trans` == true: LDA = P, TDB = M • `lside` == false & `trans` == false: LDA = M, TDB = P
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 548 of file linalg_core.f90.

5.1.2.2 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx2 (logical, intent(in) *lside,* real(dp), intent(in) *alpha,* real(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: B = alpha ∗ A ∗ op(B), or B = alpha ∗ op(B) ∗ A.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	On input, the M-by-N matrix B. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 715 of file linalg_core.f90.

5.1.2.3 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx3 (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* complex(dp), dimension(:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* complex(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A and C are complex-valued.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B∗∗T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.
in	*b*	The LDB-by-TDB matrix B where: • `lside` == true & `trans` == true: LDA = N, TDB = P • `lside` == true & `trans` == false: LDA = P, TDB = N • `lside` == false & `trans` == true: LDA = P, TDB = M • `lside` == false & `trans` == false: LDA = M, TDB = P
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 797 of file linalg_core.f90.

5.1.2.4 subroutine linalg_core::diag_mtx_mult::diag_mtx_mult_mtx4 (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp) *alpha,* complex(dp), dimension(:), intent(in) *a,* complex(dp), dimension(:,:), intent(in) *b,* real(dp) *beta,* complex(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Computes the matrix operation: C = alpha ∗ A ∗ op(B) + beta ∗ C, or C = alpha ∗ op(B) ∗ A + beta ∗ C, where A, B, and C are complex-valued.

Parameters

in	*lside*	Set to true to apply matrix A from the left; else, set to false to apply matrix A from the left.
in	*trans*	Set to true if op(B) == B∗∗T; else, set to false if op(B) == B.
in	*alpha*	A scalar multiplier.
in	*a*	A K-element array containing the diagonal elements of A where MIN(M,P) >= K >= 0 if `lside` is true; else, if `lside` is false, MIN(N,P) >= K >= 0.

Parameters

`in`	*b*	The LDB-by-TDB matrix B where: • `lside` == true & `trans` == true: LDA = N, TDB = P • `lside` == true & `trans` == false: LDA = P, TDB = N • `lside` == false & `trans` == true: LDA = P, TDB = M • `lside` == false & `trans` == false: LDA = M, TDB = P
`in`	*beta*	A scalar multiplier.
`in,out`	*c*	On input, the M-by-N matrix C. On output, the resulting M-by-N matrix.
`out`	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 973 of file linalg_core.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_core.f90

5.2 lapack::DLAMCH Interface Reference

Public Member Functions

- real(dp) function **dlamch** (cmach)

5.2.1 Detailed Description

Definition at line 14 of file lapack.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/lapack.f90

5.3 linalg_eigen::eigen Interface Reference

Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

Private Member Functions

- subroutine eigen_symm (vecs, a, vals, work, olwork, err)

  Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.
- subroutine eigen_asymm (a, vals, vecs, work, olwork, err)

  Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.
- subroutine eigen_gen (a, b, alpha, beta, vecs, work, olwork, err)

  Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A∗X = lambda∗B∗X.

5.3.1 Detailed Description

Computes the eigenvalues, and optionally the eigenvectors, of a matrix.

See Also

- Wikipedia
- Wolfram MathWorld
- LAPACK Users Manual

Definition at line 24 of file linalg_eigen.f90.

5.3.2 Member Function/Subroutine Documentation

5.3.2.1 subroutine linalg_eigen::eigen::eigen_asymm (real(dp), dimension(:,:), intent(inout) *a,* complex(dp), dimension(:), intent(out) *vals,* complex(dp), dimension(:,:), intent(out), optional *vecs,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix.

Parameters

in,out	*a*	On input, the N-by-N matrix on which to operate. On output, the contents of this matrix are overwritten.
out	*vals*	An N-element array containing the eigenvalues of the matrix. The eigenvalues are not sorted.
out	*vecs*	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DGEEV.

Definition at line 185 of file linalg_eigen.f90.

5.3.2.2 subroutine linalg_eigen::eigen::eigen_gen (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* complex(dp), dimension(:), intent(out) *alpha,* real(dp), dimension(:), intent(out), optional *beta,* complex(dp), dimension(:,:), intent(out), optional *vecs,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the right eigenvectors of a square matrix assuming the structure of the eigenvalue problem is A∗X = lambda∗B∗X.

Parameters

in,out	*a*	On input, the N-by-N matrix A. On output, the contents of this matrix are overwritten.
in,out	*b*	On input, the N-by-N matrix B. On output, the contents of this matrix are overwritten.
out	*alpha*	An N-element array that, if `beta` is not supplied, contains the eigenvalues. If `beta` is supplied however, the eigenvalues must be computed as ALPHA / BETA. This however, is not as trivial as it seems as it is entirely possible, and likely, that ALPHA / BETA can overflow or underflow. With that said, the values in ALPHA will always be less than and usually comparable with the NORM(A).
out	*beta*	An optional N-element array that if provided forces `alpha` to return the numerator, and this array contains the denominator used to determine the eigenvalues as ALPHA / BETA. If used, the values in this array will always be less than and usually comparable with the NORM(B).
out	*vecs*	An optional N-by-N matrix, that if supplied, signals to compute the right eigenvectors (one per column). If not provided, only the eigenvalues will be computed.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Usage

As an example, consider the eigenvalue problem arising from a mechanical system of masses and springs such that the masses are described by a mass matrix M, and the arrangement of springs are described by a stiffness matrix K.

```
! Parameters
real(dp), parameter :: pi = 3.141592653589793d0
```

```
! Variables
real(dp), dimension(n, n) :: m, k
complex(dp), dimension(n, n) :: mode_shapes
complex(dp), dimension(n) :: vals
real(dp), dimension(n) :: nat_freq

! Initialize the mass matrix (m) and the stiffness matrix (k)...

! Solve the eigenvalue problem.  The eigenvectors define the mode shapes
! for the system (each eigenvector defines a different mode shape, and
! are stored one per column).
call eigen(k, m, vals, vecs = mode_shapes)

! The eigenvalues represent the square of the system natural frequencies.
! Also, a properly constrained mechanical system will exhibit only real
! eigenvalues; therefore, the following relationship will return the
! natural frequencies with units of Hz.
nat_freq = sqrt(real(vals, dp)) / (2.0d0 * pi)
```

Notes

This routine utilizes the LAPACK routine DGGEV.

Definition at line 426 of file linalg_eigen.f90.

5.3.2.3 subroutine linalg_eigen::eigen::eigen_symm (logical, intent(in) *vecs,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *vals,* real(dp), dimension(:), intent(out), optional, pointer *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the eigenvalues, and optionally the eigenvectors of a real, symmetric matrix.

Parameters

in	*vecs*	Set to true to compute the eigenvectors as well as the eigenvalues; else, set to false to just compute the eigenvalues.
in,out	*a*	On input, the N-by-N symmetric matrix on which to operate. On output, and if `vecs` is set to true, the matrix will contain the eigenvectors (one per column) corresponding to each eigenvalue in `vals`. If `vecs` is set to false, the lower triangular portion of the matrix is overwritten.
out	*vals*	An N-element array that will contain the eigenvalues sorted into ascending order.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs if the algorithm failed to converge.

Notes

This routine utilizes the LAPACK routine DSYEV.

Definition at line 68 of file linalg_eigen.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_eigen.f90

5.4 linalg_factor::form_lu Interface Reference

Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.

Private Member Functions

- subroutine form_lu_all (lu, ipvt, u, p, err)

  Extracts the L, U, and P matrices from the output of the lu_factor routine.
- subroutine form_lu_only (lu, u, err)

  Extracts the L, and U matrices from the output of the lu_factor routine.

5.4.1 Detailed Description

Extracts the L and U matrices from the condensed [L\U] storage format used by the lu_factor.

Definition at line 30 of file linalg_factor.f90.

5.4.2 Member Function/Subroutine Documentation

5.4.2.1 subroutine linalg_factor::form_lu::form_lu_all (real(dp), dimension(:,:), intent(inout) *lu,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:,:), intent(out) *u,* real(dp), dimension(:,:), intent(out) *p,* class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, U, and P matrices from the output of the lu_factor routine.

Parameters

in,out	*lu*	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
in	*ipvt*	The N-element pivot array as output by lu_factor.
out	*u*	An N-by-N matrix where the U matrix will be written.
out	*p*	An N-by-N matrix where the row permutation matrix will be written.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Remarks

This routine allows extraction of the actual "L", "U", and "P" matrices of the decomposition. To use these matrices to solve the system A∗X = B, the following approach is used.

1. First, solve the linear system: L∗Y = P∗B for Y.
2. Second, solve the linear system: U∗X = Y for X.

Notice, as both L and U are triangular in structure, the above equations can be solved by forward and backward substitution.

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 210 of file linalg_factor.f90.

5.4.2.2 subroutine linalg_factor::form_lu::form_lu_only (real(dp), dimension(:,:), intent(inout) *lu*, real(dp), dimension(:,:), intent(out) *u*, class(errors), intent(inout), optional, target *err*) [private]

Extracts the L, and U matrices from the output of the lu_factor routine.

Parameters

in,out	*lu*	On input, the N-by-N matrix as output by lu_factor. On output, the N-by-N lower triangular matrix L.
out	*u*	An N-by-N matrix where the U matrix will be written.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Definition at line 287 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.5 linalg_factor::form_qr Interface Reference

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Private Member Functions

- subroutine form_qr_no_pivot (r, tau, q, work, olwork, err)

  Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.
- subroutine form_qr_pivot (r, tau, pvt, q, p, work, olwork, err)

  Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

5.5.1 Detailed Description

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

See Also

- Wikipedia
- LAPACK Users Manual

Definition at line 54 of file linalg_factor.f90.

5.5.2 Member Function/Subroutine Documentation

5.5.2.1 subroutine linalg_factor::form_qr::form_qr_no_pivot (real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(out) *q,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	*r*	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in h.
out	*q*	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that M > N, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q ∗ R = [Q1, Q2] ∗ [R1; 0].
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 693 of file linalg_factor.f90.

5.5.2.2 subroutine linalg_factor::form_qr::form_qr_pivot (real(dp), dimension(:,:), intent(inout) *r,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *pvt,* real(dp), dimension(:,:), intent(out) *q,* real(dp), dimension(:,:), intent(out) *p,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Forms the full M-by-M orthogonal matrix Q from the elementary reflectors returned by the base QR factorization algorithm.

Parameters

in,out	*r*	On input, an M-by-N matrix where the elements below the diagonal contain the elementary reflectors generated from the QR factorization. On and above the diagonal, the matrix contains the matrix R. On output, the elements below the diagonal are zeroed such that the remaining matrix is simply the M-by-N matrix R.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of each elementary reflector defined in h.
in	*pvt*	An N-element column pivot array as returned by the QR factorization.
out	*q*	An M-by-M matrix where the full orthogonal matrix Q will be written. In the event that M $>$ N, Q may be supplied as M-by-N, and therefore only return the useful submatrix Q1 (Q = [Q1, Q2]) as the factorization can be written as Q $*$ R = [Q1, Q2] $*$ [R1; 0].
out	*p*	An N-by-N matrix where the pivot matrix will be written.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORGQR.

Definition at line 824 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.6 linalg_solve::least_squares_solve Interface Reference

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns.

Private Member Functions

- subroutine least_squares_solve_mtx (a, b, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine least_squares_solve_vec (a, b, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.
- subroutine least_squares_solve_mtx_1 (a, b, x, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

5.6.1 Detailed Description

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns.

Definition at line 83 of file linalg_solve.f90.

5.6.2 Member Function/Subroutine Documentation

5.6.2.1 subroutine linalg_solve::least_squares_solve::least_squares_solve_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately.
		• LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1347 of file linalg_solve.f90.

5.6.2.2 subroutine linalg_solve::least_squares_solve::least_squares_solve_mtx_1 (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:,:), intent(out) *x,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.
in,out	*b*	On input, the M-by-NRHS matrix B. On output the contents are overwritten.
out	*x*	The N-by-NRHS solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1560 of file linalg_solve.f90.

5.6.2.3 subroutine linalg_solve::least_squares_solve::least_squares_solve_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a QR or LQ factorization of the matrix A. Notice, it is assumed that matrix A has full rank.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, if M >= N, the QR factorization of A in the form as output by qr_factor; else, if M < N, the LQ factorization of A in the form as output by lq_factor.
in,out	*b*	If M >= N, the M-element array B. On output, the first N elements contain the N-element solution array X. If M < N, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_INVALID_OPERATION_ERROR: Occurs if a is not of full rank.

Notes

This routine utilizes the LAPACK routine DGELS.

Definition at line 1454 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.7 linalg_solve::least_squares_solve_full Interface Reference

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.

Private Member Functions

- subroutine least_squares_solve_mtx_pvt (a, b, ipvt, arnk, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.
- subroutine least_squares_solve_vec_pvt (a, b, ipvt, arnk, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

5.7.1 Detailed Description

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns, but uses a full orthogonal factorization of the system.

Definition at line 93 of file linalg_solve.f90.

5.7.2 Member Function/Subroutine Documentation

5.7.2.1 subroutine linalg_solve::least_squares_solve_full::least_squares_solve_mtx_pvt (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* integer(i32), dimension(:), intent(inout), optional, target *ipvt,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.

Definition at line 1653 of file linalg_solve.f90.

5.7.2.2 subroutine linalg_solve::least_squares_solve_full::least_squares_solve_vec_pvt (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* integer(i32), dimension(:), intent(inout), optional, target *ipvt,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a complete orthogonal factorization of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-element array B. On output, the first N elements contain the N-element solution array X. If M < N, an N-element array with the first M elements containing the array B. On output, the N-element solution array X.
out	*ipvt*	On input, an N-element array that if IPVT(I) .ne. 0, the I-th column of A is permuted to the front of A ∗ P; if IPVT(I) = 0, the I-th column of A is a free column. On output, if IPVT(I) = K, then the I-th column of A ∗ P was the K-th column of A.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DGELSY.

Definition at line 1797 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.8 linalg_solve::least_squares_solve_svd Interface Reference

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Private Member Functions

- subroutine least_squares_solve_mtx_svd (a, b, arnk, s, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.
- subroutine least_squares_solve_vec_svd (a, b, arnk, s, work, olwork, err)

  Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

5.8.1 Detailed Description

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Definition at line 102 of file linalg_solve.f90.

5.8.2 Member Function/Subroutine Documentation

5.8.2.1 subroutine linalg_solve::least_squares_solve_svd::least_squares_solve_mtx_svd (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:,:), intent(inout) *b,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out) *s,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*s*	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 1941 of file linalg_solve.f90.

5.8.2.2 subroutine linalg_solve::least_squares_solve_svd::least_squares_solve_vec_svd (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(inout) *b,* integer(i32), intent(out), optional *arnk,* real(dp), dimension(:), intent(out) *s,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves the overdetermined or underdetermined system (A∗X = B) of M equations of N unknowns using a singular value decomposition of matrix A.

Parameters

in,out	*a*	On input, the M-by-N matrix A. On output, the matrix is overwritten by the details of its complete orthogonal factorization.
in,out	*b*	If M >= N, the M-by-NRHS matrix B. On output, the first N rows contain the N-by-NRHS solution matrix X. If M < N, an N-by-NRHS matrix with the first M rows containing the matrix B. On output, the N-by-NRHS solution matrix X.
out	*arnk*	An optional output, that if provided, will return the rank of a.
out	*s*	A MIN(M, N)-element array that on output contains the singular values of a in descending order. Notice, the condition number of a can be determined by S(1) / S(MIN(M, N)).

Parameters

`out`	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
`out`	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
`out`	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available. • LA_CONVERGENCE_ERROR: Occurs as a warning if the QR iteration process could not converge to a zero value.

Notes

This routine utilizes the LAPACK routine DGELSS.

Definition at line 2069 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.9 linalg_core::mtx_mult Interface Reference

Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.

Private Member Functions

- subroutine mtx_mult_mtx (transa, transb, alpha, a, b, beta, c, err)
  Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.
- subroutine mtx_mult_vec (trans, alpha, a, b, beta, c, err)
  Performs the matrix-vector operation: c = alpha ∗ op(A) ∗ b + beta ∗ c.

5.9.1 Detailed Description

Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.

Definition at line 46 of file linalg_core.f90.

5.9.2 Member Function/Subroutine Documentation

5.9.2.1 subroutine linalg_core::mtx_mult::mtx_mult_mtx (logical, intent(in) *transa,* logical, intent(in) *transb,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(in) *b,* real(dp), intent(in) *beta,* real(dp), dimension(:,:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix operation: C = alpha ∗ op(A) ∗ op(B) + beta ∗ C.

Parameters

in	*transa*	Set to true if op(A) = A**T; else, set to false for op(A) = A.
in	*transb*	Set to true if op(B) = B**T; else, set to false for op(B) = B.
in	*alpha*	A scalar multiplier.
in	*a*	If `transa` is set to true, an K-by-M matrix; else, if `transa` is set to false, an M-by-K matrix.
in	*b*	If `transb` is set to true, an N-by-K matrix; else, if `transb` is set to false, a K-by-N matrix.
in	*beta*	A scalar multiplier.
in,out	*c*	On input, the M-by-N matrix C. On output, the M-by-N result.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMM.

Definition at line 305 of file linalg_core.f90.

5.9.2.2 subroutine linalg_core::mtx_mult::mtx_mult_vec (logical, intent(in) *trans,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(in) *b,* real(dp), intent(in) *beta,* real(dp), dimension(:), intent(inout) *c,* class(errors), intent(inout), optional, target *err*) [private]

Performs the matrix-vector operation: c = alpha ∗ op(A) ∗ b + beta ∗ c.

Parameters

in	*trans*	Set to true if op(A) = A**T; else, set to false for op(A) = A.
in	*alpha*	A scalar multiplier.
in	*a*	The M-by-N matrix A.
in	*b*	If `trans` is set to true, an M-element array; else, if `trans` is set to false, an N-element array.
in	*beta*	A scalar multiplier.
in,out	*c*	On input, if `trans` is set to true, an N-element array; else, if `trans` is set to false, an M-element array. On output, the results of the operation.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the BLAS routine DGEMV.

Definition at line 399 of file linalg_core.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_core.f90

5.10 linalg_factor::mult_qr Interface Reference

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.

Private Member Functions

- subroutine mult_qr_mtx (lside, trans, a, tau, c, work, olwork, err)

  Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) ∗ C, or C = C ∗ op(Q).
- subroutine mult_qr_vec (trans, a, tau, c, work, olwork, err)

  Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) ∗ C.

5.10.1 Detailed Description

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization.

Definition at line 62 of file linalg_factor.f90.

5.10.2 Member Function/Subroutine Documentation

5.10.2.1 subroutine linalg_factor::mult_qr::mult_qr_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Q from a QR factorization such that: C = op(Q) ∗ C, or C = C ∗ op(Q).

Parameters

in	*lside*	Set to true to apply Q or Q∗∗T from the left; else, set to false to apply Q or Q∗∗T from the right.
in	*trans*	Set to true to apply Q∗∗T; else, set to false.
in	*a*	On input, an LDA-by-K matrix containing the elementary reflectors output from the QR factorization. If lside is set to true, LDA = M, and M >= K >= 0; else, if lside is set to false, LDA = N, and N >= K >= 0. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	*c*	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Q and the original matrix C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.

Parameters

out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMQR.

Definition at line 926 of file linalg_factor.f90.

5.10.2.2 subroutine linalg_factor::mult_qr::mult_qr_vec (logical, intent(in) *trans,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a vector by the orthogonal matrix Q from a QR factorization such that: C = op(Q) $*$ C.

Parameters

in	*trans*	Set to true to apply Q$**$T; else, set to false.
in	*a*	On input, an M-by-K matrix containing the elementary reflectors output from the QR factorization. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of each elementary reflector defined in a.
in,out	*c*	On input, the M-element vector C. On output, the product of the orthogonal matrix Q and the original vector C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon the LAPACK routine DORM2R.

Definition at line 1053 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.11 linalg_factor::mult_rz Interface Reference

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.

Private Member Functions

- subroutine mult_rz_mtx (lside, trans, l, a, tau, c, work, olwork, err)

  Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) ∗ C, or C = C ∗ op(Z).
- subroutine mult_rz_vec (trans, l, a, tau, c, work, olwork, err)

  Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) ∗ C.

5.11.1 Detailed Description

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization.

Definition at line 70 of file linalg_factor.f90.

5.11.2 Member Function/Subroutine Documentation

5.11.2.1 subroutine linalg_factor::mult_rz::mult_rz_mtx (logical, intent(in) *lside,* logical, intent(in) *trans,* integer(i32), intent(in) *l,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a general matrix by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) ∗ C, or C = C ∗ op(Z).

Parameters

in	*lside*	Set to true to apply Z or Z∗∗T from the left; else, set to false to apply Z or Z∗∗T from the right.
in	*trans*	Set to true to apply Z∗∗T; else, set to false.
in	*l*	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, M >= L >= 0; else, if lside is false, N >= L >= 0.
in,out	*a*	On input the K-by-LTA matrix C, where LTA = M if lside is true; else, LTA = N if lside is false. The l-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.

Parameters

in	*tau*	A K-element array containing the scalar factors of the elementary reflectors, where M >= K >= 0 if lside is true; else, N >= K >= 0 if lside is false.
in,out	*c*	On input, the M-by-N matrix C. On output, the product of the orthogonal matrix Z and the original matrix C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1642 of file linalg_factor.f90.

5.11.2.2 subroutine linalg_factor::mult_rz::mult_rz_vec (logical, intent(in) *trans,* integer(i32), intent(in) *l,* real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *c,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Multiplies a vector by the orthogonal matrix Z from an RZ factorization such that: C = op(Z) $*$ C.

Parameters

in	*trans*	Set to true to apply Z$*$T; else, set to false.
in	*l*	The number of columns in matrix a containing the meaningful part of the Householder vectors. If lside is true, M >= L >= 0; else, if lside is false, N >= L >= 0.
in,out	*a*	On input the K-by-LTA matrix C, where LTA = M if lside is true; else, LTA = N if lside is false. The I-th row must contain the Householder vector in the last k rows. Notice, the contents of this matrix are restored on exit.
in	*tau*	A K-element array containing the scalar factors of the elementary reflectors, where M >= K >= 0 if lside is true; else, N >= K >= 0 if lside is false.
in,out	*c*	On input, the M-element array C. On output, the product of the orthogonal matrix Z and the original array C.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine utilizes the LAPACK routine DORMRZ.

Definition at line 1784 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.12 linalg_factor::qr_factor Interface Reference

Computes the QR factorization of an M-by-N matrix.

Private Member Functions

- subroutine qr_factor_no_pivot (a, tau, work, olwork, err)

  Computes the QR factorization of an M-by-N matrix without pivoting.
- subroutine qr_factor_pivot (a, tau, jpvt, work, olwork, err)

  Computes the QR factorization of an M-by-N matrix with column pivoting such that $A * P = Q * R$.

5.12.1 Detailed Description

Computes the QR factorization of an M-by-N matrix.

See Also

- Wikipedia
- Wolfram MathWorld
- LAPACK Users Manual

Definition at line 42 of file linalg_factor.f90.

5.12.2 Member Function/Subroutine Documentation

5.12.2.1 subroutine linalg_factor::qr_factor::qr_factor_no_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix without pivoting.

Parameters

in,out	*a*	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if M >= N). The elements below the diagonal, along with the array `tau`, represent the orthogonal matrix Q as a product of elementary reflectors.
out	*tau*	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if `tau` or `work` are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Remarks

QR factorization without pivoting is best suited to solving an overdetermined system in least-squares terms, or to solve a normally defined system. To solve an underdetermined system, it is recommended to use either LQ factorization, or a column-pivoting based QR factorization.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice assuming M >= N.

```
! Solve the system: A*X = B in a least-squares sense, where A is an
! M-by-N matrix, B is an M-by-NRHS matrix, and X is an N-by-NRHS matrix.

! Variables
real(dp), dimension(m, n) :: a
real(dp), dimension(m, nrhs) :: b, qtb
real(dp), dimension(n, nrhs) :: x
real(dp), dimension(n) :: tau
real(dp), dimension(m, m) :: q

! Initialize A and B...

! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
! scalar factors in TAU.  Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau)

! Solve A*X = B for X.  The first N rows of B are used to store X.
call solve_qr(a, tau, b)

! Also note, we could form Q and R explicitly.  Then solution of the
! system of equations can be found.  First we form Q and R.
call form_qr(a, tau, q) ! Forms Q, and R is stored in A

! Since we now have Q and R, we seek a solution to the equation:
! Q*R*X = B, but Q is an orthogonal matrix (i.e. Q**T = inv(Q)).
! Then: R*X = Q**T * B, and R is upper triangular; therefore, back
! substitution will suffice for a solution procedure.
!
! Next, compute Q**T * B, and store in QTB.
call mtx_mult(.true., .false., 1.0d0, q, b, 0.0d0, qtb)

! Copy the first N rows of Q**T * B into X for the solution process.
```

```
! Notice, only the first N rows are needed as rows N+1:M are all zero in
! matrix R.
x = qtb(1:n,nrhs)

! Compute the solution and store in X
call solve_triangular_system(.true., .true., .false., .true., 1.0d0, &
 a(1:n,1:n), x)
```

Notes

This routine utilizes the LAPACK routine DGEQRF.

Definition at line 424 of file linalg_factor.f90.

5.12.2.2 subroutine linalg_factor::qr_factor::qr_factor_pivot (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(out) *tau,* integer(i32), dimension(:), intent(inout) *jpvt,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Computes the QR factorization of an M-by-N matrix with column pivoting such that A ∗ P = Q ∗ R.

Parameters

in,out	*a*	On input, the M-by-N matrix to factor. On output, the elements on and above the diagonal contain the MIN(M, N)-by-N upper trapezoidal matrix R (R is upper triangular if M >= N). The elements below the diagonal, along with the array tau, represent the orthogonal matrix Q as a product of elementary reflectors.
out	*tau*	A MIN(M, N)-element array used to store the scalar factors of the elementary reflectors.
in,out	*jpvt*	On input, an N-element array that if JPVT(I) .ne. 0, the I-th column of A is permuted to the front of A ∗ P; if JPVT(I) = 0, the I-th column of A is a free column. On output, if JPVT(I) = K, then the I-th column of A ∗ P was the K-th column of A.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Usage

To solve a system of M equations of N unknowns using QR factorization, the following code will suffice for any M and N.

```
! Solve the least-squares (M >= N), or the underdetermined (M < N)
! problem A*X = B, where A is an M-by-N matrix, B is an M-by-NRHS matrix,
! and X is an N-by-NRHS matrix.  In the underdetermined case, or the
! case where the rank of matrix A is less than N, the solution obtained
! contains the fewest possible non-zero entries.

! Variables
```

```
real(dp), dimension(m, n) :: a
real(dp), dimension(n, nrhs) :: b
real(dp), dimension(k) :: tau ! k = min(m, n)
real(dp), dimension(m, m) :: q
real(dp), dimension(n, n) :: p
integer(i32), dimension(n) :: pvt

! Initialize A and B...

! Allow all columns to be free.
pvt = 0

! Compute the QR factorization. We're intentionally not forming the full
! Q matrix, but instead storing it in terms of its elementary reflector
! components in the sub-diagonal portions of A, and the corresponding
! scalar factors in TAU.  Additionally, we'll let the algorithm allocate
! it's own workspace array; therefore, the call to factor A is:
call qr_factor(a, tau, pvt)

! Solve A*X = B for X.  If M > N, the first N rows of B are used to store
! X.  If M < N, the input matrix B must be N-by-NRHS, and only the first
! M rows are used for the actual matrix B.  The remaining N-M rows
! can contain whatever as they are not referenced until they are
! overwritten by the N-by-NRHS solution matrix X.
call solve_qr(a, tau, pvt, b)

! Notice, if the explicit Q matrix from the factorization is desired,
! the form_qr routine works similarly as in the no-pivot case;
! however, the permutation matrix P is also constructed.  The call would
! be as follows.  Also, as with the no-pivot algorithm, the matrix R is
! stored in matrix A.
call form_qr(a, tau, pvt, q, p)

! Solution can proceed as per typical, but with a full Q matrix.  Also
! note, the problem is of the form: A*P = Q*R.  Solution is straight
! forward, as with the no-pivot case; however, if M < N, then R is upper
! trapezoidal, and must be appropriately partitioned to solve.  The rank
! of matrix r should be considered when applying the partition.
```

Notes

This routine utilizes the LAPACK routine DGEQP3.

Definition at line 578 of file linalg_factor.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_factor.f90

5.13 linalg_solve::solve_cholesky Interface Reference

Solves a system of Cholesky factored equations.

Private Member Functions

- subroutine solve_cholesky_mtx (upper, a, b, err)

  Solves a system of Cholesky factored equations.
- subroutine solve_cholesky_vec (upper, a, b, err)

  Solves a system of Cholesky factored equations.

5.13.1 Detailed Description

Solves a system of Cholesky factored equations.

Definition at line 75 of file linalg_solve.f90.

5.13.2 Member Function/Subroutine Documentation

5.13.2.1 subroutine linalg_solve::solve_cholesky::solve_cholesky_mtx (logical, intent(in) *upper,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	*upper*	Set to true if the original matrix A was factored such that A = U∗∗T ∗ U; else, set to false if the factorization of A was A = L∗∗T ∗ L.
in	*a*	The N-by-N Cholesky factored matrix.
in,out	*b*	On input, the N-by-NRHS right-hand-side matrix B. On output, the solution matrix X.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 851 of file linalg_solve.f90.

5.13.2.2 subroutine linalg_solve::solve_cholesky::solve_cholesky_vec (logical, intent(in) *upper,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of Cholesky factored equations.

Parameters

in	*upper*	Set to true if the original matrix A was factored such that A = U∗∗T ∗ U; else, set to false if the factorization of A was A = L∗∗T ∗ L.
in	*a*	The N-by-N Cholesky factored matrix.
in,out	*b*	On input, the N-element right-hand-side vector B. On output, the solution vector X.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

This routine utilizes the LAPACK routine DPOTRS.

Definition at line 917 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.14 linalg_solve::solve_lu Interface Reference

Solves a system of LU-factored equations.

Private Member Functions

- subroutine solve_lu_mtx (a, ipvt, b, err)

  Solves a system of LU-factored equations.
- subroutine solve_lu_vec (a, ipvt, b, err)

  Solves a system of LU-factored equations.

5.14.1 Detailed Description

Solves a system of LU-factored equations.

Usage

To solve a system of N equations of N unknowns using LU factorization, the following code will suffice.

```
! Solve the system: A*X = B, where A is an N-by-N matrix, and B and X are
! N-by-NRHS in size.

! Variables
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b

! Define the array used to track row pivots.
integer(i32), dimension(n) :: pvt

! Initialize A and B...

! Compute the LU factorization of A.  On output, A contains [L\U].
call lu_factor(a, pvt)

! Solve A*X = B for X - Note: X overwrites B.
call solve_lu(a, pvt, b)
```

See Also

- Wikipedia
- Wolfram MathWorld

Definition at line 55 of file linalg_solve.f90.

5.14.2 Member Function/Subroutine Documentation

5.14.2.1 subroutine linalg_solve::solve_lu::solve_lu_mtx (real(dp), dimension(:,:), intent(in) *a,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

Parameters

in	*a*	The N-by-N LU factored matrix as output by lu_factor.
in	*ipvt*	The N-element pivot array as output by lu_factor.
in,out	*b*	On input, the N-by-NRHS right-hand-side matrix. On output, the N-by-NRHS solution matrix.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 129 of file linalg_solve.f90.

5.14.2.2 subroutine linalg_solve::solve_lu::solve_lu_vec (real(dp), dimension(:,:), intent(in) *a,* integer(i32), dimension(:), intent(in) *ipvt,* real(dp), dimension(:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of LU-factored equations.

Parameters

in	*a*	The N-by-N LU factored matrix as output by lu_factor.
in	*ipvt*	The N-element pivot array as output by lu_factor.
in,out	*b*	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input array sizes are incorrect.

Notes

The routine is based upon the LAPACK routine DGETRS.

Definition at line 190 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.15 linalg_solve::solve_qr Interface Reference

Solves a system of M QR-factored equations of N unknowns.

Private Member Functions

- subroutine solve_qr_no_pivot_mtx (a, tau, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where M >= N.
- subroutine solve_qr_no_pivot_vec (a, tau, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where M >= N.
- subroutine solve_qr_pivot_mtx (a, tau, jpvt, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.
- subroutine solve_qr_pivot_vec (a, tau, jpvt, b, work, olwork, err)

  Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

5.15.1 Detailed Description

Solves a system of M QR-factored equations of N unknowns.

See Also

- Wikipedia
- LAPACK Users Manual

Definition at line 66 of file linalg_solve.f90.

5.15.2 Member Function/Subroutine Documentation

5.15.2.1 subroutine linalg_solve::solve_qr::solve_qr_no_pivot_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where M >= N.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*b*	On input, the M-by-NRHS right-hand-side matrix. On output, the first N columns are overwritten by the solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 265 of file linalg_solve.f90.

5.15.2.2 subroutine linalg_solve::solve_qr::solve_qr_no_pivot_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where M >= N.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are restored. Notice, M must be greater than or equal to N.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*b*	On input, the M-element right-hand-side vector. On output, the first N elements are overwritten by the solution vector X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least olwork.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for work, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELS.

Definition at line 380 of file linalg_solve.f90.

5.15.2.3 subroutine linalg_solve::solve_qr::solve_qr_pivot_mtx (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *jpvt,* real(dp), dimension(:,:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*jpvt*	An N-element array, as output by qr_factor, used to track the column pivots.
in	*b*	On input, the MAX(M, N)-by-NRHS matrix where the first M rows contain the right-hand-side matrix B. On output, the first N rows are overwritten by the solution matrix X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 493 of file linalg_solve.f90.

5.15.2.4 subroutine linalg_solve::solve_qr::solve_qr_pivot_vec (real(dp), dimension(:,:), intent(inout) *a,* real(dp), dimension(:), intent(in) *tau,* integer(i32), dimension(:), intent(in) *jpvt,* real(dp), dimension(:), intent(inout) *b,* real(dp), dimension(:), intent(out), optional, target *work,* integer(i32), intent(out), optional *olwork,* class(errors), intent(inout), optional, target *err*) [private]

Solves a system of M QR-factored equations of N unknowns where the QR factorization made use of column pivoting.

Parameters

in	*a*	On input, the M-by-N QR factored matrix as returned by qr_factor. On output, the contents of this matrix are altered.
in	*tau*	A MIN(M, N)-element array containing the scalar factors of the elementary reflectors as returned by qr_factor.
in	*jpvt*	An N-element array, as output by qr_factor, used to track the column pivots.
in	*b*	On input, the MAX(M, N)-element array where the first M elements contain the right-hand-side vector B. On output, the first N elements are overwritten by the solution vector X.
out	*work*	An optional input, that if provided, prevents any local memory allocation. If not provided, the memory required is allocated within. If provided, the length of the array must be at least `olwork`.
out	*olwork*	An optional output used to determine workspace size. If supplied, the routine determines the optimal size for `work`, and returns without performing any actual calculations.

Parameters

out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if any of the input arrays are not sized appropriately. • LA_OUT_OF_MEMORY_ERROR: Occurs if local memory must be allocated, and there is insufficient memory available.

Notes

This routine is based upon a subset of the LAPACK routine DGELSY.

Definition at line 680 of file linalg_solve.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_solve.f90

5.16 linalg_core::solve_triangular_system Interface Reference

Solves a triangular system of equations.

Private Member Functions

- subroutine solve_tri_mtx (lside, upper, trans, nounit, alpha, a, b, err)

  Solves one of the matrix equations: op(A) ∗ X = alpha ∗ B, or X ∗ op(A) = alpha ∗ B, where A is a triangular matrix.
- subroutine solve_tri_vec (upper, trans, nounit, a, x, err)

  Solves the system of equations: op(A) ∗ X = B, where A is a triangular matrix.

5.16.1 Detailed Description

Solves a triangular system of equations.

Definition at line 38 of file linalg_core.f90.

5.16.2 Member Function/Subroutine Documentation

5.16.2.1 subroutine linalg_core::solve_triangular_system::solve_tri_mtx (logical, intent(in) *lside,* logical, intent(in) *upper,* logical, intent(in) *trans,* logical, intent(in) *nounit,* real(dp), intent(in) *alpha,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:,:), intent(inout) *b,* class(errors), intent(inout), optional, target *err*) [private]

Solves one of the matrix equations: op(A) ∗ X = alpha ∗ B, or X ∗ op(A) = alpha ∗ B, where A is a triangular matrix.

Parameters

in	*lside*	Set to true to solve op(A) ∗ X = alpha ∗ B; else, set to false to solve X ∗ op(A) = alpha ∗ B.
in	*upper*	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	*trans*	Set to true if op(A) = A∗∗T; else, set to false if op(A) = A.
in	*nounit*	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	*alpha*	The scalar multiplier to B.
in	*a*	If `lside` is true, the M-by-M triangular matrix on which to operate; else, if `lside` is false, the N-by-N triangular matrix on which to operate.
in,out	*b*	On input, the M-by-N right-hand-side. On output, the M-by-N solution.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if `a` is not square, or if the sizes of `a` and `b` are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A∗X = B, where A is an N-by-N upper triangular matrix, and B and X are N-by-NRHS matrices, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N
! matrix, and B and X are N-by-NRHS in size.

! Variables
integer(i32) :: info
real(dp), dimension(n, n) :: a
real(dp), dimension(n, nrhs) :: b

! Initialize A and B...

! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .true., .false., .true., &
     1.0d0, a, b)
```

Notes

This routine is based upon the BLAS routine DTRSM.

Definition at line 114 of file linalg_core.f90.

5.16.2.2 subroutine linalg_core::solve_triangular_system::solve_tri_vec (logical, intent(in) *upper,* logical, intent(in) *trans,* logical, intent(in) *nounit,* real(dp), dimension(:,:), intent(in) *a,* real(dp), dimension(:), intent(inout) *x,* class(errors), intent(inout), optional, target *err*) [private]

Solves the system of equations: op(A) ∗ X = B, where A is a triangular matrix.

Parameters

in	*upper*	Set to true if A is an upper triangular matrix; else, set to false if A is a lower triangular matrix.
in	*trans*	Set to true if op(A) = A∗∗T; else, set to false if op(A) = A.

Parameters

in	*nounit*	Set to true if A is not a unit-diagonal matrix (ones on every diagonal element); else, set to false if A is a unit-diagonal matrix.
in	*a*	The N-by-N triangular matrix.
in,out	*x*	On input, the N-element right-hand-side array. On output, the N-element solution array.
out	*err*	An optional errors-based object that if provided can be used to retrieve information relating to any errors encountered during execution. If not provided, a default implementation of the errors class is used internally to provide error handling. Possible errors and warning messages that may be encountered are as follows. • LA_ARRAY_SIZE_ERROR: Occurs if a is not square, or if the sizes of a and b are not compatible.

Usage

To solve a triangular system of N equations of N unknowns A∗X = B, where A is an N-by-N upper triangular matrix, and B and X are N-element arrays, the following code will suffice.

```
! Solve the system: A*X = B, where A is an upper triangular N-by-N
! matrix, and B and X are N-elements in size.

! Variables
integer(i32) :: info
real(dp), dimension(n, n) :: a
real(dp), dimension(n) :: b

! Initialize A and B...

! Solve A*X = B for X - Note: X overwrites B.
call solve_triangular_system(.true., .false., a, b)
```

Notes

This routine is based upon the BLAS routine DTRSV.

Definition at line 220 of file linalg_core.f90.

The documentation for this interface was generated from the following file:

- /home/jason/Documents/Code/linalg/src/linalg_core.f90

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