Assignment 5

https://github.com/jchryssanthacopoulos/quantum_information/tree/main/assignment_5

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Time-Dependent Quantum System



■ Goal is to solve 1D time-dependent quantum harmonic oscillator

$$\hat{H}\left|\Psi(x,t)\right\rangle = i\hbar\frac{\partial}{\partial t}\left|\Psi(x,t)\right\rangle, \quad \hat{H} \equiv \hat{T} + \hat{V} = \frac{\hat{p}^2}{2m} + \frac{1}{2}m\omega^2\left(\hat{x} - \frac{t}{T}\right)^2, \ t \in [0,T]$$

■ Problem was solved using **split operator method**, where state is evolved using

$$|\Psi(x,t+\Delta t)\rangle = e^{-\frac{i\hat{V}\Delta t}{2}}\mathcal{F}^{-1}e^{-i\hat{T}\Delta t}\mathcal{F}e^{-\frac{i\hat{V}\Delta t}{2}}|\Psi(x,t)\rangle$$

where $\mathcal F$ and $\mathcal F^{-1}$ are the Fourier transform and its inverse, respectively $(\hbar=\omega=m=1 \text{ was used})$

```
l multiply by potential part of Hamiltonian
do ii = 1, N
    V(ii) * potential(x_grid(ii), time, tmax)
   final_state(ii) = cexp(cmplx(8.8, -0.5 * V(ii) * dt)) * init_state(ii)
end do
! normalize
call normalize(final_state, dx)
! call FFT to go from coordinate space to momentum space
call dfftx_plan_dft_ld(plan, Nx, final_state, state_transform, -1, 64)
call dfftx_execute_dft(plan, final_state, state_transform)
call dfftx_execute_dft(plan, final_state, state_transform)
call dfftx_execute_dft(plan, final_state, state_transform)
```

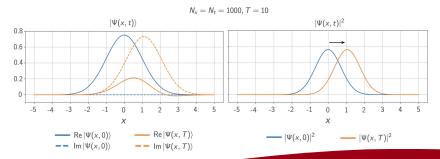
```
$ complied/solve_time_dep_ho —xmin -15 —xmax 15 —tmax 10 —num_x_pts 100 —num_t_pts 100 xmin = -15.000
xmax = 15.000
tmax = 10.000
tmax = 10.000
num_x_pts = 100
num_x_pts = 100
debug = F
output_filename = solution.txt
Elapsed time to evolve state = 2.9180000000E-03
```

- fftw library installed from source and used to compute FFT
- System simulated using discretization parameters and wavefunction saved to file, results analyzed in Jupyter notebook

Implementation and Solution



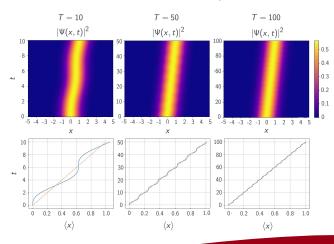
- $\blacksquare |\Psi(x,t)\rangle$ starts in ground state, $(\frac{1}{\pi})^{1/4}e^{-\frac{x^2}{2}}$
- Position and time discretized using N_x and N_t equispaced bins of size Δx and Δt
- Discretized momentum is $\left[0, \frac{2\pi}{L}, \dots, \frac{\pi(N_x-2)}{L}, -\frac{\pi N_x}{L}, \dots, -\frac{2\pi}{L}\right]$, where L is x range
- Wavefunction properly normalized by dividing by $\sqrt{\sum_{i=1}^{N_x} |\Psi(x_i,t)|^2 \Delta x}$
- Wavefunction moves to right, developing complex phase, as expected



Wavefunction for Different T



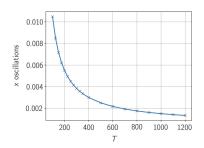
- Expected position $\langle x(t) \rangle$ computed using $\sum_{i=1}^{N_x} x_i |\Psi(x_i, t)|^2 \Delta x$
- Deviations from minimum of potential, $\langle x(t) \rangle \frac{t}{T}$, decrease with increasing T



Position Oscillations



- Position oscillations decrease when *T* increases because when *T* is large, potential changes slowly (i.e., adiabatic approximation)
- Fit of oscillations to αT^{β} results in $\alpha=0.60\pm0.03$ and $\beta=-0.88\pm0.01$



lacktriangle Experiments showed that there are no oscillations with varying N_t

Self-Rating



- Correctness. Results seem sensible, but it is hard to know exactly without analytical wavefunction
- Stability. Code is numerically stable, but results sensitive to discretization
- Accurate Discretization. Error of split operator method is $\mathcal{O}(\Delta t^3)$. For $\Delta t \gtrsim 1$, expected final state not reproduced (see below)
- Flexibility. Split operator method assumes \hat{V} is only function of \hat{x} and \hat{T} is only function of \hat{p} , enabling exact diagonal representation
- Efficiency. Overall time complexity is $\mathcal{O}(N_t N_x \log N_x)$. It took \sim 8 s to solve using $N_x = N_t = 10^4$ on M1 Macbook Pro 32 GB

