

# Stochastic Multilevel Emulation

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# Outline

Motivation

Emulation of Stochastic Simulators

Deterministic Multilevel Emulators

Stochastic Multilevel Emulators

Athena Model

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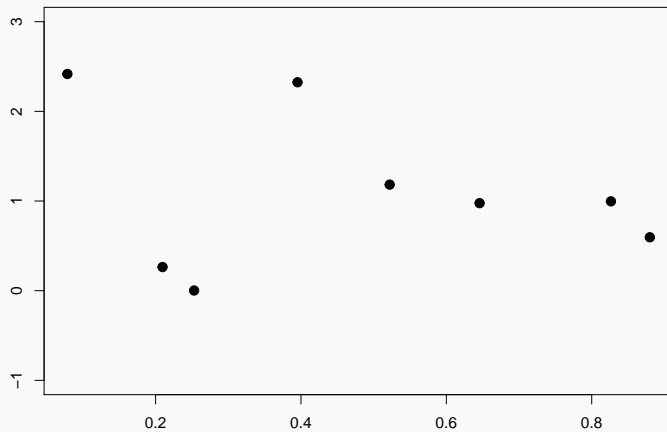
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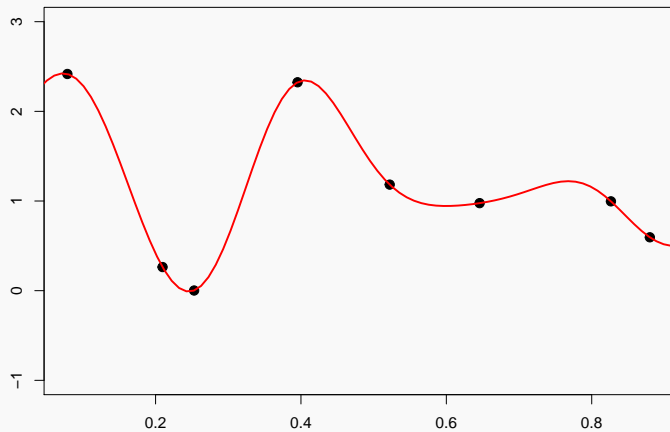
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- Theory on emulation of deterministic models is well developed (although still active!)

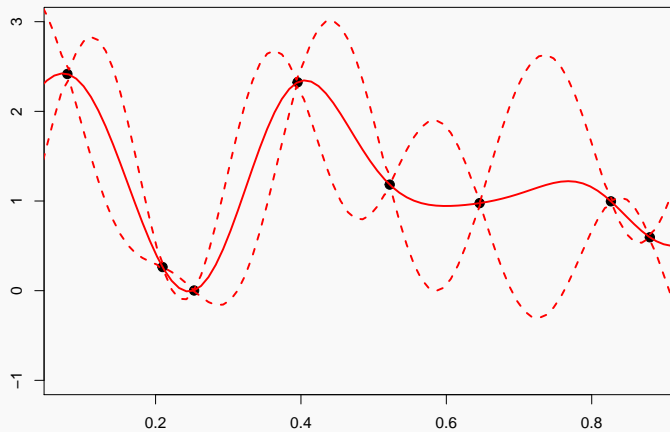
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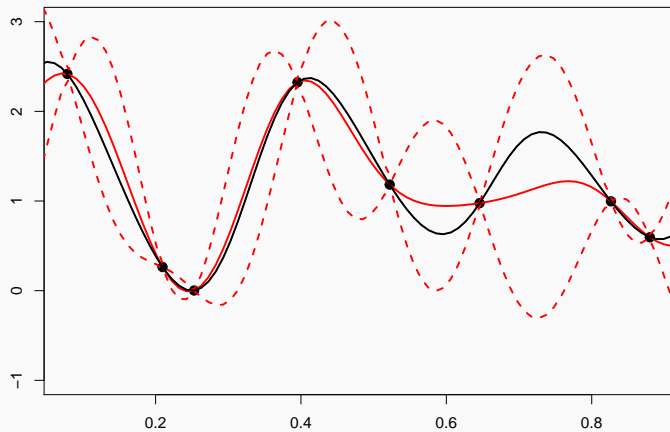
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- Stochastic computer experiments are becoming more and more popular
  - Agent based models and population dynamics
  - Probabilistic forecasting
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- Stochastic computer experiments are becoming more and more popular
  - Agent based models and population dynamics
  - Probabilistic forecasting
  - Catch all for scientific uncertainty
- We can also emulate stochastic simulators
- But is it not easy!



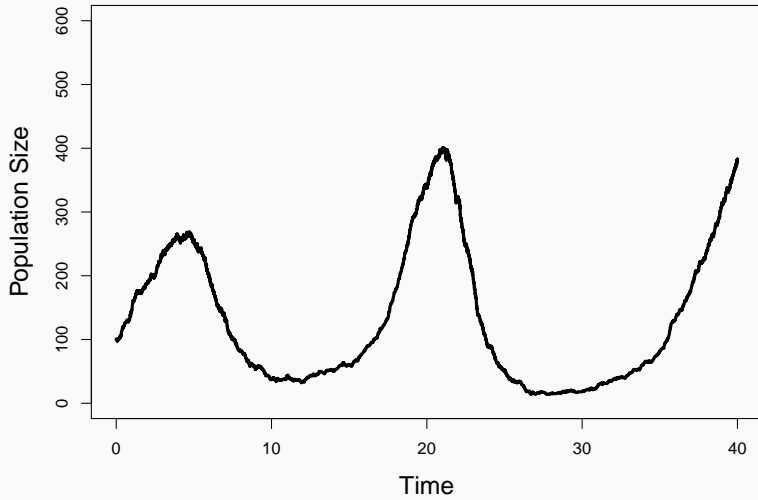
**Figure 1:** Random randy rabbits

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Some types of models can be thought as having dependence structure

- Dynamic simulators

# Dynamic Simulator

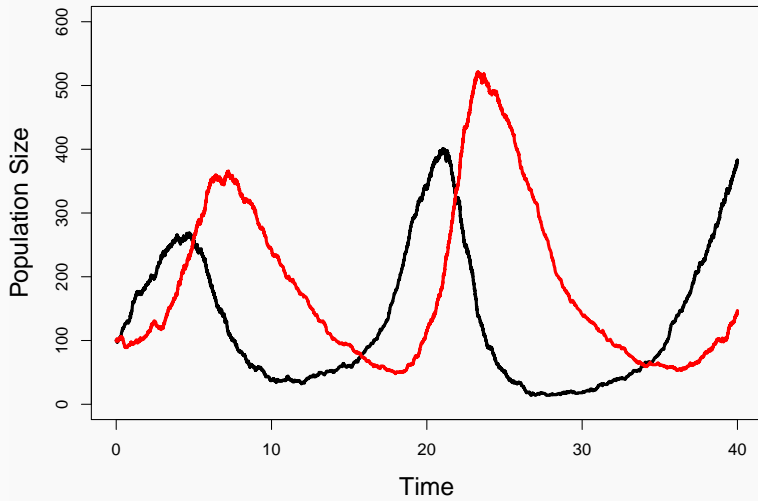


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Some types of models have a dependence structure

- Dynamic simulators
- Multiple output simulators

# Multiple Output Simulator



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Some types of models have a dependence structure

- Dynamic simulators
- Multiple output simulators
- Different versions of the “same” simulator

Note: Many simulators will fall into at least one of these categories

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- Many (stochastic) simulators can be made arbitrarily complex
  - Time step or grid coarseness
  - Model topology
  - Additional scientific understanding

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- Many (stochastic) simulators can be made arbitrarily complex
  - Time step or grid coarseness
  - Model topology
  - Additional scientific understanding
- These cheaper models will be correlated with a more expensive version but more accurate version
- There is an established literature on correlated deterministic models
- I want to utilise *cheap stochastic simulators* in a similar way



# Emulation of Stochastic Simulators

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# Emulation Via Heteroscedastic Gaussian Processes

- The current daddy of stochastic emulation is HetGP

$$\eta(\cdot) \sim \mathcal{GP}\{m(\cdot), C(\cdot, \cdot) + \lambda^2(\cdot)\mathbf{I}\}$$

$$\log(\lambda^2(\cdot)) \sim \mathcal{GP}\{m_\lambda(\cdot), C_\lambda(\cdot, \cdot) + \omega^2\mathbf{I}\}$$

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- Doubly non-parametric
- Gives us a joint (Bayesian) model for the mean and variance
- Allows us to learn about simulator stochasticity **without replication**
- Incredibly flexible approach to emulation of stochastic simulators

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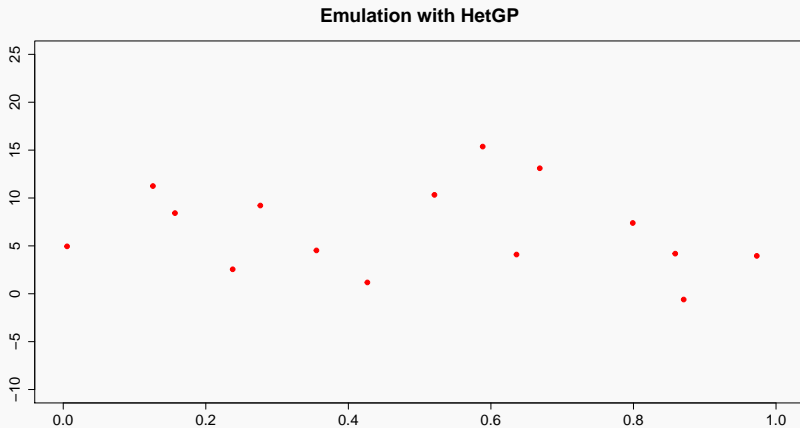
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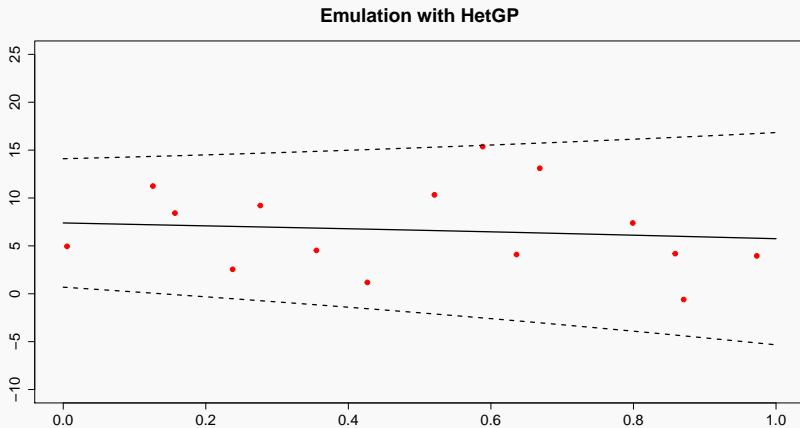
$$\eta(\mathbf{x}^*) | \mathcal{D}, \Theta \sim \mathcal{N}\{m^*(\mathbf{x}^*), C^*(\mathbf{x}^*, \mathbf{x}^*) + \lambda^{*2}(\mathbf{x}^*)\}$$

- Only tricky task is matrix inversion

# Simple Example

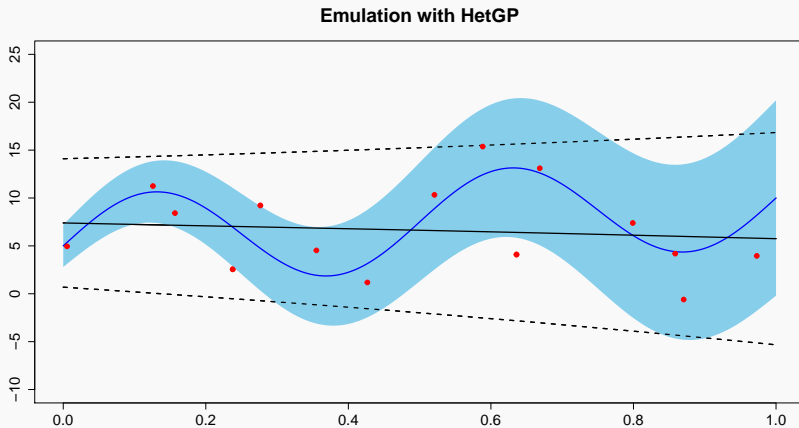


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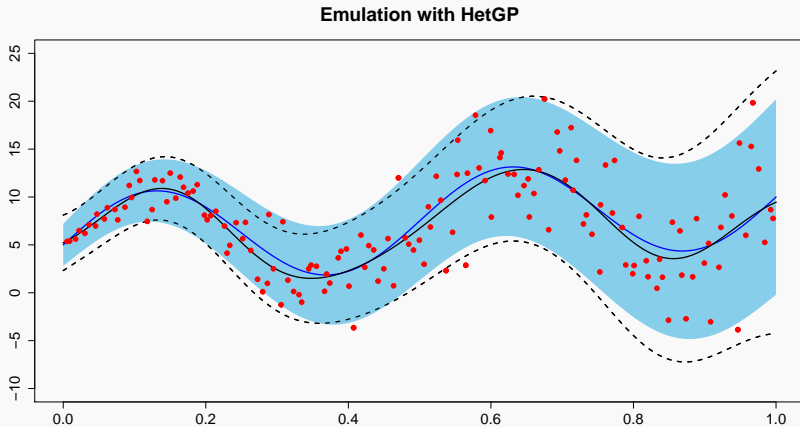
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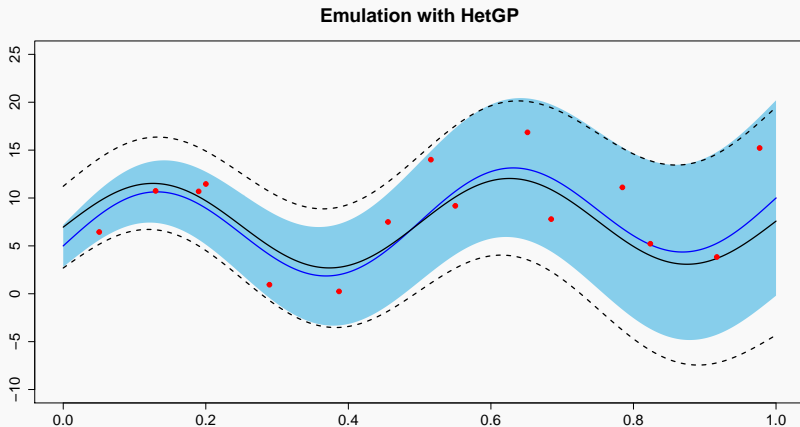
Periodic behaviour interpreted as noise!

# How to fix HetGP?

- Currently approaches to “good” emulation with HetGP:
  - Obtaining a massive training budget
  - Careful choice of mean function



We can bully HetGP into giving us a good emulator



Giving HetGP a “good” mean solves the problem too

# Emulation with HetGP

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  - Careful choice of mean function – but lack of knowledge in mean function is why we conduct such experiments!
  - Obtaining a massive training budget – but the model is expensive!
- More structured approach; use **cheap approximations** to build a mean function
- Goal: improved emulation of stochastic simulators at **fixed training budget**

# Deterministic Multilevel Emulators

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# Multilevel Emulators for Deterministic Simulators

- Proposed by Kennedy & O'Hagan (2000) <sup>1</sup>
- Suppose we have “levels” of a simulator  $\eta^\ell$  where  $\ell \in \{1, 2, \dots, L\}$

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- Proposed by Kennedy & O'Hagan (2000)<sup>1</sup>
- Suppose we have “levels” of a simulator  $\eta^\ell$  where  $\ell \in \{1, 2, \dots, L\}$
- Each level is more expensive than the last
- Most popular approach is an **autoregressive** model

$$\begin{aligned}\eta^1(\cdot) &\sim \mathcal{GP}\{m_1(\cdot), C_1(\cdot, \cdot)\} \\ \eta^\ell(\mathbf{x}) &= \rho_\ell \eta^{\ell-1}(\mathbf{x}) + \delta^\ell(\mathbf{x})\end{aligned}$$

- Model  $\delta^\ell$  as a GP  $\implies \eta^\ell$  also a GP

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## Design of ML emulators

- We run the cheap model(s) many more times than the expensive model(s)
- Computationally convenient to have **nested** design:  $X^\ell \subseteq X^{\ell-1}$
- If a non-nested design; data imputation mimics a nested design
- We can build designs from scratch and/or use data we have lying around

## Picture of Design Matrix

$$\begin{pmatrix} h^C(x_1^C) & 0 \\ h^C(x_2^C) & 0 \\ \vdots & \vdots \\ h^C(x_{N_C}^C) & 0 \\ \rho h^C(x_1^E) & h^E(x_1^E) \\ \rho h^C(x_2^E) & h^E(x_2^E) \\ \vdots & \vdots \\ \rho h^C(x_{N_E}^E) & h^E(x_{N_E}^E) \end{pmatrix} = \begin{pmatrix} h^C(X^C) & 0 \\ \rho h^C(X^E) & h^E(X^E) \end{pmatrix}$$

## ML Emulator Likelihood

$$\begin{pmatrix} Y^C \\ Y^E \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} h^C(X^C) & 0 \\ \rho h^C(X^E) & h^E(X^E) \end{pmatrix} \begin{pmatrix} \beta^C \\ \beta^E \end{pmatrix}, \begin{pmatrix} \text{Var}(Y^C) & \text{Cov}(Y^C, Y^E) \\ \text{Cov}(Y^E, Y^C) & \text{Var}(Y^E) \end{pmatrix} \right)$$

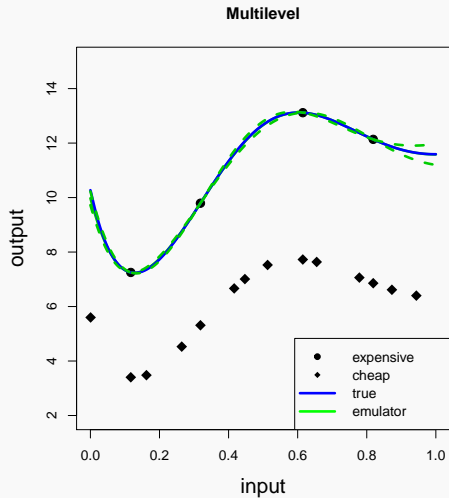
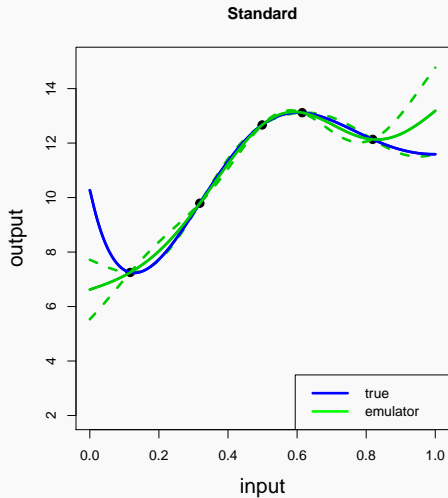
$$\text{Var}(Y^C)_{ij} = \sigma_C^2 \exp \left\{ - \sum (d_{ij}^k / \theta_k^C)^2 \right\}$$

$$\text{Var}(Y^E)_{ij} = \rho^2 \sigma_C^2 \exp \left\{ - \sum (d_{ij}^k / \theta_k^C)^2 \right\} + \sigma_E^2 \exp \left\{ - \sum (d_{ij}^k / \theta_k^E)^2 \right\}$$

$$\text{Cov}(Y^C, Y^E)_{ij} = \rho \sigma_C^2 \exp \left\{ - \sum (d_{ij}^k / \theta_k^C)^2 \right\}$$



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- Two level setup:
  - $\eta^C(\cdot)$  - “cheap” simulator
  - $\eta^E(\cdot)$  - “expensive” simulator
  - $Z_C = E(\eta^C)$

$$\eta^E(\cdot) | \rho, Z_C(\cdot) = \rho Z_C(\cdot) + \delta(\cdot)$$

$$\eta^C(\cdot) | Z_C(\cdot) = Z_C(\cdot) + \mathcal{N}\{0, \lambda_C^2 I_C\}$$

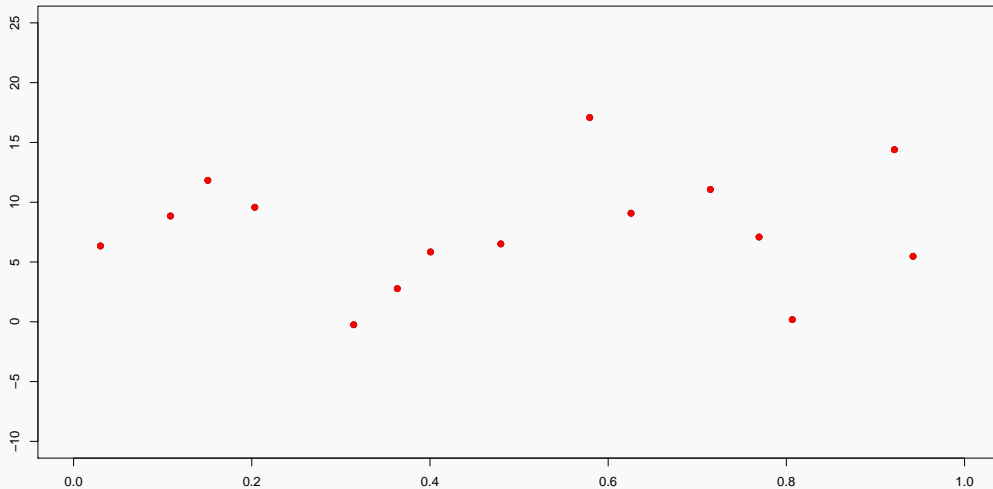
$$Z_C(\cdot) \sim \mathcal{GP}\{m_C(\cdot), C_C(\cdot, \cdot)\}$$

$$\delta(\cdot) | \lambda_E^2(\cdot) \sim \mathcal{GP}\{m_E(\cdot), C_E(\cdot, \cdot) + \lambda_E^2(\cdot) I\}$$

$$\log(\lambda_E^2(\cdot)) \sim \mathcal{GP}\{m_\lambda(\cdot), C_\lambda(\cdot, \cdot) + \omega^2 I_E\}$$

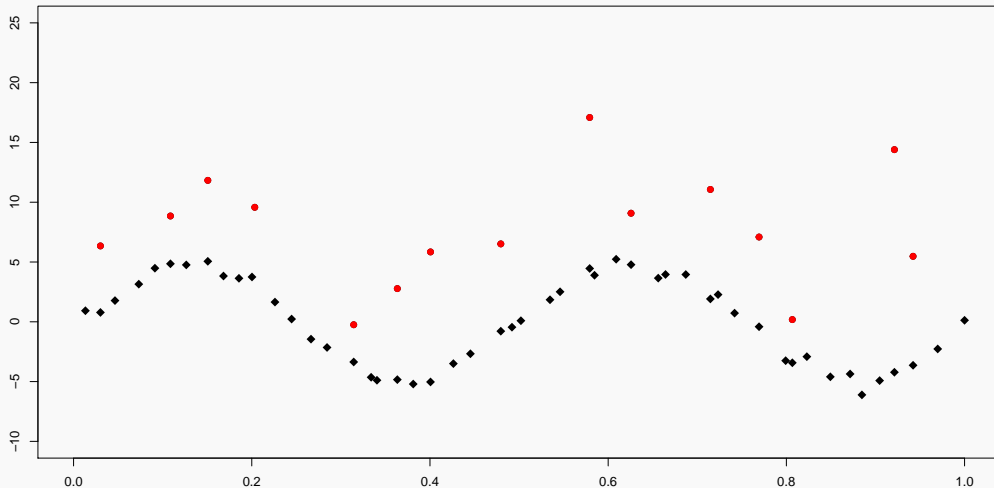
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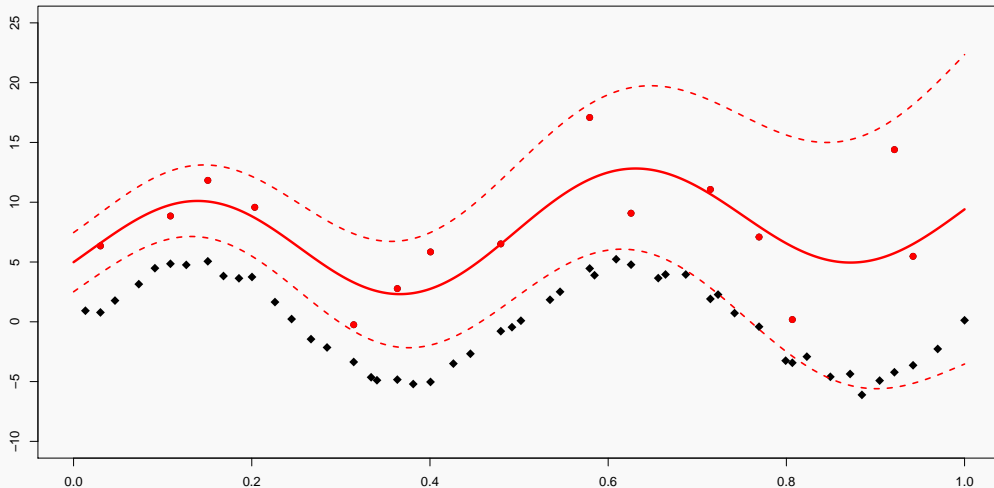
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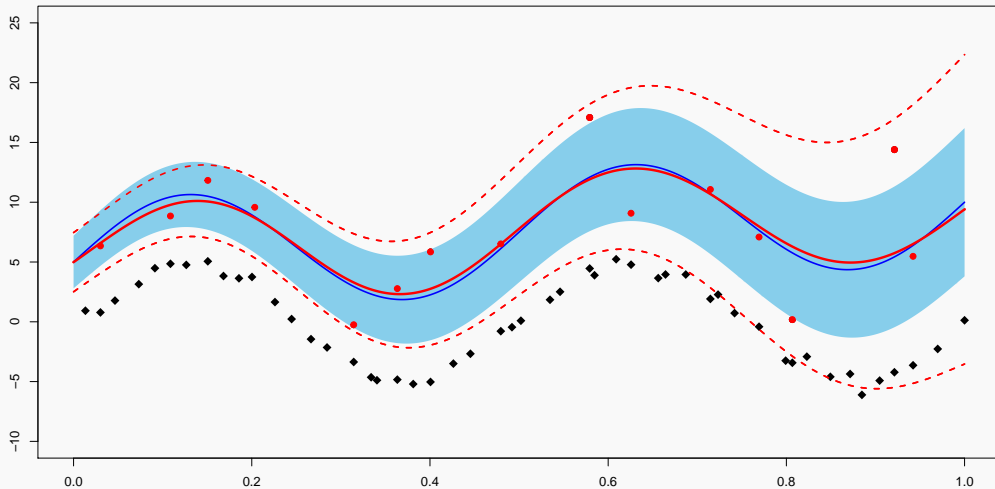
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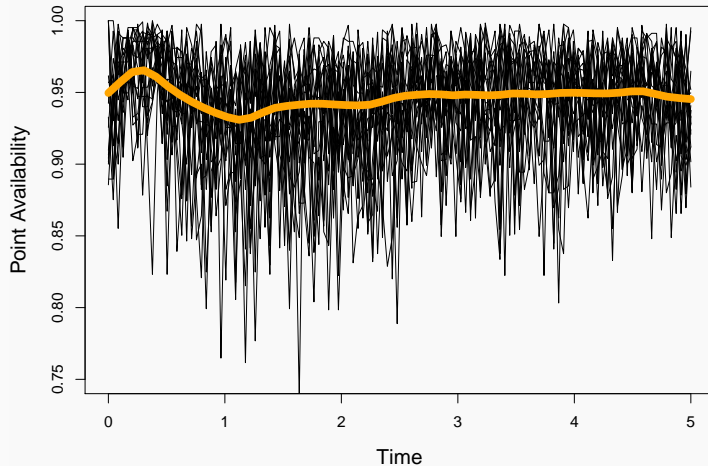
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- Key output: **Availability**
- Emulation part of a larger problem: decision analysis under uncertainty
- A reliable emulator is needed to perform a efficient and accurate decision making process

## Availability Trajectories



# Athena Model

- Accurate simulations take approx 30 mins for one run
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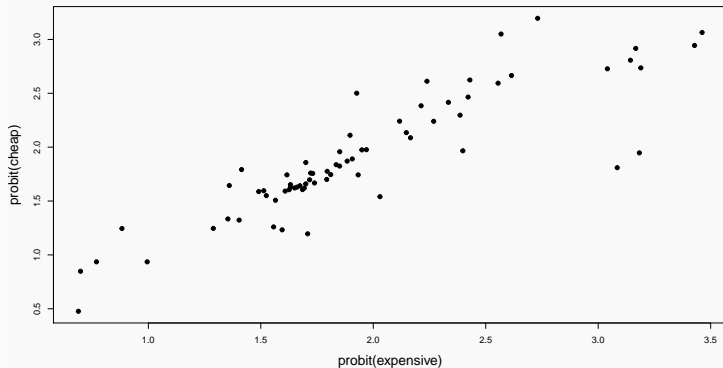
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- Cheap simulation involves using coarse time steps and simplified model topology
- Will vary three inputs;
  - Learning rate
  - Cable failure rate
  - Cable repair rate

# SML with Athena

- $R^2 = 0.76$  (noisy observations)
- I think it would be a shame to ignore this cheap source of information



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- Summaries based on 500 unseen validation points

	MSE (probit)	MSE/ $10^{-4}$ (original)	Score
HetGP	0.0296	3.72	1835
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- These comparisons are based on the same training budget in CPU time

# Conclusions

- Shown SML favourable over HetGP in synthetic case and for Athena model
- Would want to know possible failure cases of SML
- Potential bottleneck: many cheap points means inverting larger matrices, want to find a way to minimise this?
- A design rule? E.g. how much time on expensive and how much time on cheap data

## Future Work

- I need to adapt Athena to facilitate floating offshore wind turbines
- Ultimate goal: decision making framework for floating offshore windfarms
- Not a clue how I'm going to do that bit!



**Cheers!**

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