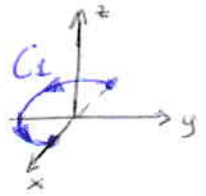


Entonces $\partial S_1 = C_1 + C_3$ y $\partial S_2 = C_2 + C_3^-$ donde

C_1, C_2, C_3 son las siguientes curvas orientadas simples:

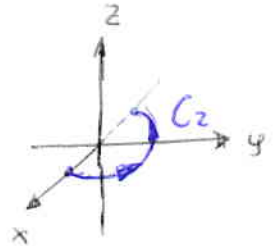
$$\gamma_1: [\pi, 2\pi] \rightarrow \mathbb{R}^3 \\ t \rightarrow (\cos t, \sin t, 0)$$

$$\gamma_1([\pi, 2\pi]) = C_1$$



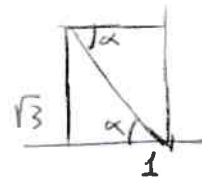
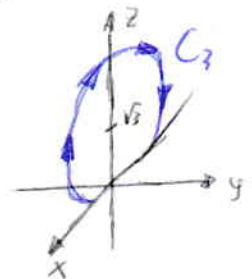
$$\gamma_2: [0, \pi] \rightarrow \mathbb{R}^3 \\ t \rightarrow (\cos t, \sin t, 0)$$

$$\gamma_2([0, \pi]) = C_2$$

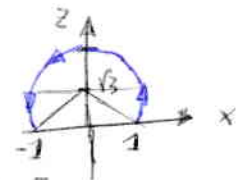


$$\gamma_3: [-\frac{\pi}{3}, \frac{4\pi}{3}] \rightarrow \mathbb{R}^3 \\ t \rightarrow (2\cos t, 0, 2\sin t) + \sqrt{3}$$

$$\gamma_3([-\frac{\pi}{3}, \frac{4\pi}{3}]) = C_3$$



$$\tan \alpha = \frac{\sqrt{3}}{1} = \frac{\sqrt{3}/2}{1/2} = \frac{\sin \frac{\pi}{2}}{\cos \frac{\pi}{3}}$$



De esta forma, aplicando el teorema de Stokes a cada una de las superficies

$$\boxed{\iint_S \text{rot}(\vec{F}) \cdot d\vec{S}} = \iint_{S_1} \text{rot}(\vec{F}) \cdot d\vec{S} + \iint_{S_2} \text{rot}(\vec{F}) \cdot d\vec{S} =$$

$$= \iint_{C_1} \vec{F} \cdot d\vec{S} + \iint_{C_3} \vec{F} \cdot d\vec{S} + \iint_{C_2} \vec{F} \cdot d\vec{S} + \iint_{C_3^-} \vec{F} \cdot d\vec{S} = \iint_{C_1} \vec{F} \cdot d\vec{S} + \iint_{C_2} \vec{F} \cdot d\vec{S} =$$

$$= \int_0^{2\pi} \vec{F}(\cos t, \sin t, 0) \cdot (-\sin t, \cos t, 0) dt =$$

$$= \int_0^{2\pi} (\sin t, -\cos t, 1) \cdot (-\sin t, \cos t, 0) dt = - \int_0^{2\pi} (\sin^2 t + \cos^2 t) dt = \boxed{-2\pi}$$