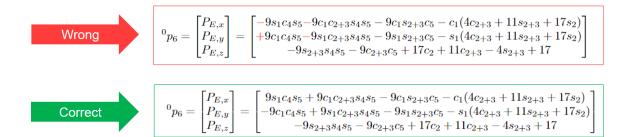
Correction explained

Assignment correction

The forward kinematics in eq. 2 were incorrect. The mistake and correct version are listed below.



Script correction

Old script

```
T5 = DHmatrix(pi/2,0,q(5),0);
T6 = DHmatrix(-pi/2,0,pi/2,16)
```

New script

```
T5 = DHmatrix(-pi/2,0,q(5),0);
T6 = DHmatrix(pi/2,0,pi/2,16)
```