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1  /**
2   * MECH 458 - Lab 4A - PWM
3   * Benjamin Klammer - V00829094
4   * Joshua Columbus - V00825727
5   */
6
7  #include <asf.h>
8  #include <avr/io.h>
9  #include <avr/interrupt.h>
10
11 int main (int argc, char *argv[]) {
12     CLKPR = 0b10000000;          /* Modify prescale lock bit */
13     CLKPR = 0b00000000;          /* Reset prescaler to 1 (8MHz clock) ↗
14     */
15     DDRB = 0b11111111;           /* Set all of Port B to output bits, ↗
16     OC0A outputs to PB7 */
17     DDRC = 0b11111111;           /* Set all of Port C to output bits, ↗
18     for debugging */
19     TCCR0A |= _BV(WGM01) | _BV(WGM00); /* Set timer/counter 0 to fast PWM ↗
20     mode */
21     TIMSK0 |= _BV(OCIE0A);        /* Enable timer/counter 0 Compare ↗
22     Match A interrupt */
23     TCCR0A |= _BV(COM0A1);         /* Set timer/counter 0 to clear OC0A ↗
24     on Compare Match, set OC0A at TOP */
25     TCCR0B |= _BV(CS01) | _BV(CS00); /* Set timer/counter 0 to take system ↗
26     clock with prescaler = 64 */
27     OCR0A = 0b10000000;           /* Set output compare register to be ↗
28     half of total (50% duty cycle) */
29
30     while (1) {
31         /* Nothing should happen */
32     } /* while */
33
34     return(0);
35 } /* main */
```