PIT CHECKLIST		Mati	Matc	n Watc	D Matc	n Match o	atch Mate	Mati	Matc	n Matc	n Maic	Match	Match	<b>,</b> \$3
Logs	Archive Robot Logs													_
	Archive DS Logs													
	Review Startup Logs													_
Controls	Driver Joysticks													_
	Driver Controls													
Health Check	Check limit switches													_
	Run Health Check													_
	Check results													_
Driver Station	Plug in													_
	Check free disk space													
	Check CAN utilization													
	ALL CHECK													=
	Time stamp Match end													_
	Time stamp Match start													_

- 1. Jumper in
- 2. Check with drive team
- 3. Power on
- 4. Check limit switches
- 5. Position axis
- 6. Health check
- 7. Review results
- 8. Power down
- 9. REMOVE FLAG
- 10. Battery

PACKING LIST		Sack
	DS version	
	deepspace	
	thirdcoast	
	pyeye	
Versions	roboRIO version	
	navX version	
	CTRELib version	
	talon firmware version	
	PDP firmware Check	
	deepspace	
	thirdcoast	
	pyeye	
	talon firmware	
Release Copies	RoboRIO	
	Shuffleboard config	
	Driver Station	
	WPILib version	
	Backup copy of all software releases (USB)	
	driver station (3)	
	controller case (2 controller sets)	
Table (Charle Duise Trans to als)	USB drive	
Tools (Check Drive Team tools)	Velcro measuring block	
	digital protractor	
	ethernet switch and 120v inverter	
	DP - HDMI (2)	
	HDMI Cables (2)	
C 11	POE	
Cables	ethernet short (4)	
	ethernet extra long (1)	
	ethernet 25ft (1)	
	event interlock	
	roboRIO	
	navX	
Spare Parts	rPi	
	lifecam HD-3000	
	USB3 cables A and B	
	radio	
	ALL CHECK	
	ALL OREON	