Thesis_over_sampling_data

November 1, 2019

1 Imports

```
In [1]: import pandas as pd
    import psycopg2

    %matplotlib inline

import matplotlib
 import numpy as np
 import matplotlib.pyplot as plt
 from datetime import datetime
 from sklearn import neighbors, datasets
 from matplotlib.colors import ListedColormap
```

2 Read Data Set

```
In [2]: df = pd.read_csv("mergeData_v4.csv")
        df.head()
Out[2]:
           speed_total_mean steering_total_mean brake_total_mean \
        0
                   5.919151
                                         0.503649
                                                           0.965743
        1
                   7.580378
                                         0.499771
                                                           0.891302
                   9.474048
                                         0.494557
                                                           0.952182
        3
                  11.669419
                                         0.500661
                                                           0.891913
                  12.187044
                                         0.499769
                                                           0.861132
           throttle_total_mean acceleration_total_mean speed_total_var \
        0
                      0.820576
                                                0.030731
                                                                13.796202
        1
                      0.878839
                                               -0.026652
                                                                31.451253
        2
                      0.781126
                                                0.006292
                                                                53.873833
        3
                      0.522365
                                                0.008028
                                                                47.209285
        4
                      0.558120
                                                0.001881
                                                                42.031423
                               brake_total_var throttle_total_var
           steering_total_var
        0
                     0.000655
                                       0.014468
                                                           0.028719
        1
                     0.000345
                                       0.058767
                                                           0.010391
```

```
2
            0.001231
                              0.022506
                                                  0.045416
3
            0.000396
                              0.055982
                                                  0.112551
4
             0.000430
                              0.102442
                                                  0.079023
   acceleration_total_var total_time distancePed max_speed
                                                                   PKE \
0
                0.039370
                            15.405173
                                         89.992450 11.669766 1.932290
1
                0.063480
                            11.412381
                                         85.063860 13.499710 0.878493
2
                0.106281 102.356492 789.212800 25.851397 2.857169
3
                0.159198
                             7.505478
                                        88.011610 20.055070 2.969647
4
                0.158822
                             8.681609
                                        105.973686 19.697004 4.033468
   PKE_Steering
               speed_react reaction_time
                                            hadCollision
0
      -0.000150
                   7.754880
                                   1.048791
                                                        0
1
      0.000274
                   13.472353
                                   2.106615
2
      0.000108
                   25.585112
                                   0.079211
                                                        1
3
                                                        0
     -0.000258
                  19.412087
                                   1.161592
      0.000066
                   18.461056
                                   1.275896
                                                        0
```

2.0.1 Distribution

Number of True cases: 54 (9.66%)
Number of False cases: 505 (90.34%)

2.1 Split data set

```
In [45]: from sklearn.model_selection import train_test_split

    data = df.copy()
    X = data.drop('hadCollision', axis=1)
    Y = data['hadCollision']

    X_train, X_test, y_train, y_test = train_test_split(X, Y, test_size=0.5, random_state)
In [46]: print("Training True : {0} ({1:0.2f}%)".format(len(y_train[y_train[:] == 1]), (len(y_print("Training False : {0} ({1:0.2f}%)".format(len(y_train[y_train[:] == 0]), (len(y_print("Training False : {0} ({1:0.2f}%)".format(len(y_train[y_train[:] == 0]))
```

 $: \{0\} (\{1:0.2f\}\%)$ ".format(len(y_test[y_test[:] == 1]), (len(y_test[y_test[:] == 1]))

 $: \{0\} (\{1:0.2f\}\%)$ ".format(len(y_test[y_test[:] == 0]), (len(y_test[y_test[:] == 0]))

Training True : 27 (9.68%)
Training False : 252 (90.32%)

print("Test True
print("Test False

print("")

Test True : 27 (9.64%) Test False : 253 (90.36%)

3 Over sampling data

3.1 Random Over Sampler

print("")

4]

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```
In [47]: from imblearn.over_sampling import RandomOverSampler
         ros = RandomOverSampler(random_state=0)
         X_resampled, y_resampled = ros.fit_sample(X_train, y_train)
         print("Training True : {0} ({1:0.2f}%)".format(len(y_resampled[y_resampled[:] == 1])
         print("Training False : {0} ({1:0.2f}%)".format(len(y_resampled[y_resampled[:] == 0])
Training True : 252 (50.00%)
Training False : 252 (50.00%)
3.2 Random forest
In [48]: from sklearn.ensemble import RandomForestClassifier
         rf_model = RandomForestClassifier(random_state=42, n_estimators=10)
                                                                                  # Create ran
         rf_model.fit(X_resampled, y_resampled.ravel())
Out[48]: RandomForestClassifier(bootstrap=True, class_weight=None, criterion='gini',
                     max_depth=None, max_features='auto', max_leaf_nodes=None,
                     min_impurity_decrease=0.0, min_impurity_split=None,
                     min_samples_leaf=1, min_samples_split=2,
                     min_weight_fraction_leaf=0.0, n_estimators=10, n_jobs=1,
                     oob_score=False, random_state=42, verbose=0, warm_start=False)
3.2.1 Predict Test Data
In [49]: rf_predict_test = rf_model.predict(X_test)
         # training metrics
         print("Accuracy: {0:.4f}".format(metrics.accuracy_score(y_test, rf_predict_test)))
Accuracy: 0.9179
```

print(metrics.classification_report(y_test, rf_predict_test))

In [50]: print(metrics.confusion_matrix(y_test, rf_predict_test))

print("Classification Report")

Classification Report precision recall f1-score support 0.93 0.98 0 0.96 253 1 0.67 0.30 27 0.41 avg / total 0.90 0.92 0.90 280

3.3 SMOT

3.4 Random forest

Training False : 252 (50.00%)

oob_score=False, random_state=42, verbose=0, warm_start=False)

3.4.1 Predict Test Data

```
[[241 12]
[ 13 14]]
```

Classification Report

support	f1-score	recall	precision	
253	0.95	0.95	0.95	0
27	0.53	0.52	0.54	1
280	0.91	0.91	0.91	avg / total

3.5 ADASYN

```
In [55]: from imblearn.over_sampling import SMOTE, ADASYN

X_resampled, y_resampled = ADASYN().fit_sample(X_train, y_train)

print("Training True : {0} ({1:0.2f}%)".format(len(y_resampled[y_resampled[:] == 1])
    print("Training False : {0} ({1:0.2f}%)".format(len(y_resampled[y_resampled[:] == 0])
```

Training True : 254 (50.20%)
Training False : 252 (49.80%)

3.6 Random forest

min_samples_leaf=1, min_samples_split=2,
min_weight_fraction_leaf=0.0, n_estimators=10, n_jobs=1,

oob_score=False, random_state=42, verbose=0, warm_start=False)

3.6.1 Predict Test Data

```
In [57]: rf_predict_test = rf_model.predict(X_test)

# training metrics
print("Accuracy: {0:.4f}".format(metrics.accuracy_score(y_test, rf_predict_test)))
```

Accuracy: 0.8536

```
In [58]: print(metrics.confusion_matrix(y_test, rf_predict_test) )
        print("")
        print("Classification Report")
        print(metrics.classification_report(y_test, rf_predict_test))
[[220 33]
[ 8 19]]
Classification Report
            precision
                         recall f1-score
                                            support
          0
                 0.96
                           0.87
                                     0.91
                                                253
          1
                 0.37
                           0.70
                                     0.48
                                                 27
avg / total
                 0.91
                           0.85
                                     0.87
                                                280
```