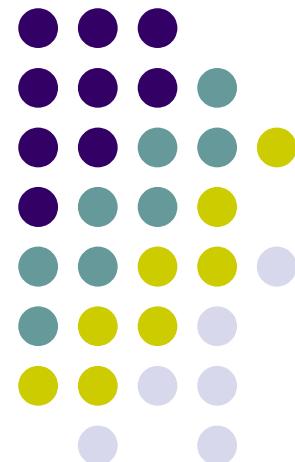
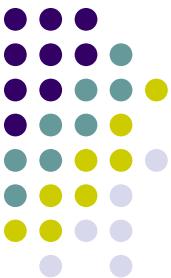


Chapter 30->28

Sources of the Magnetic Field





PHYS 2321

Week 10: Sources of Magnetic field

Day 1 Outline

Hwk: Ch. 28 P. 1,4,5,19,27,29,37,38

MiscQ. 1-13 (odd) (Due Wednesday)

1) Return Quiz 5 on Ch. 27 mean=5.1/8

2) Sources of magnetic fields (Ch 28)

a. Biot-Savart Law

$$d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{d\vec{s} \times \hat{r}}{r^2}$$
$$B = \frac{\mu_0 I}{2\pi r}$$

b. B due to straight line of current

c. B due to arc of current

d. Force between parallel currents

Notes: Will put PDF online soon.

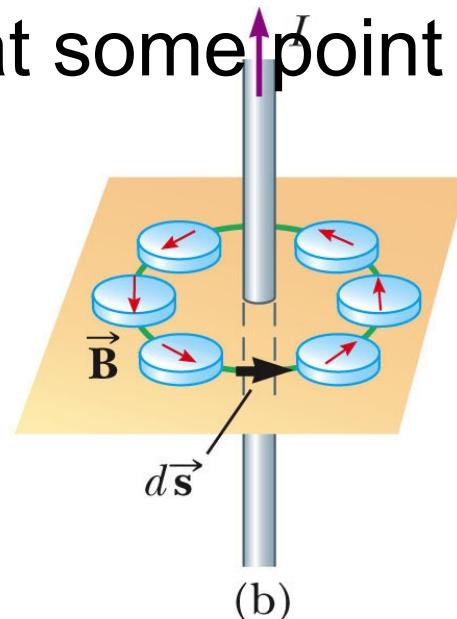
This material in this PPT is ordered differently than textbook.

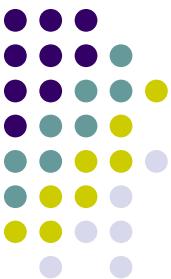
Planning Exam 2 after Ch. 29 (Faraday's Law).



Biot-Savart Law – Introduction

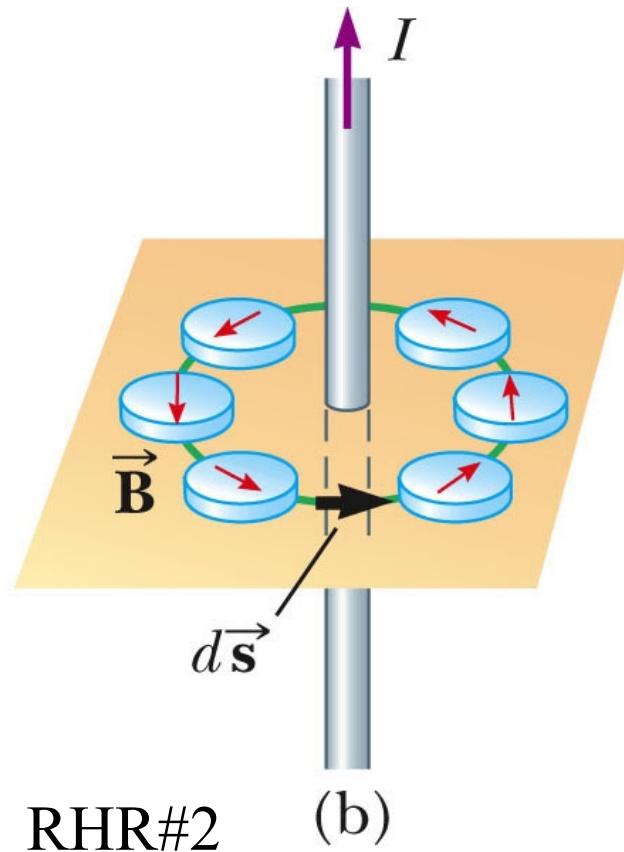
- Biot and Savart conducted experiments on the force exerted by an electric current on a nearby magnet
- They arrived at a mathematical expression that gives the magnetic field at some point in space due to a current

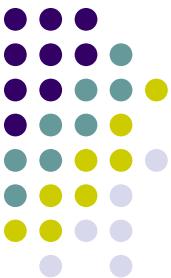




Biot-Savart Law – Experiments

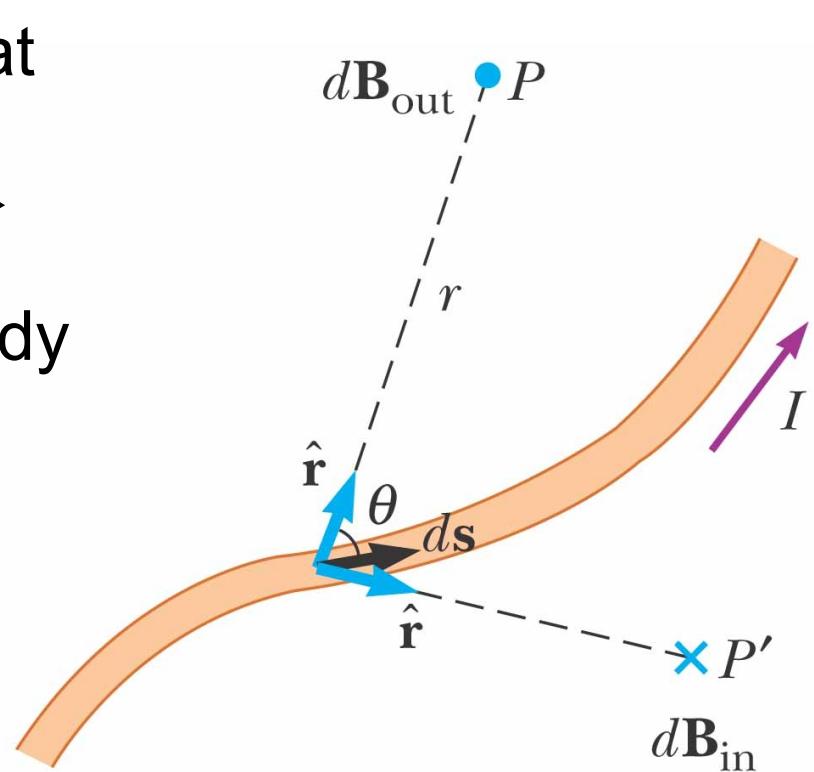
- $B \propto F_B$ exerted on compass needles
- $B \propto I/r$ for line current
- $E \propto 1/r$ for line charge
- Since $dE \propto dq/r^2$, $dB \propto dI/r^2$





Biot-Savart Law – Set-Up

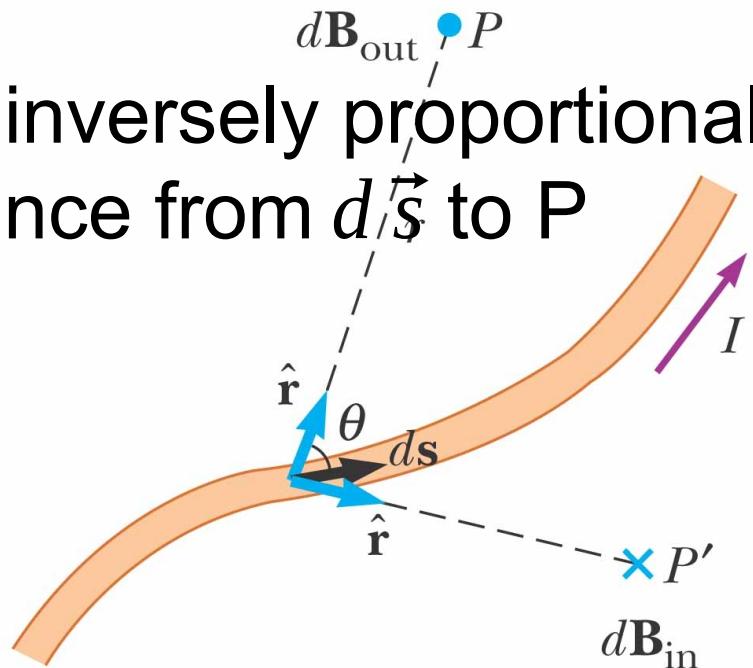
- The magnetic field is $d\vec{B}$ at some point P .
- The length element is $d\vec{s}$
- The wire is carrying a steady current, I



Biot-Savart Law – Observations



- The vector $d\vec{B}$ is perpendicular to both $d\vec{s}$ and to the unit vector \hat{r} directed from $d\vec{s}$ toward P
- The magnitude of $d\vec{B}$ is inversely proportional to r^2 , where r is the distance from $d\vec{s}$ to P

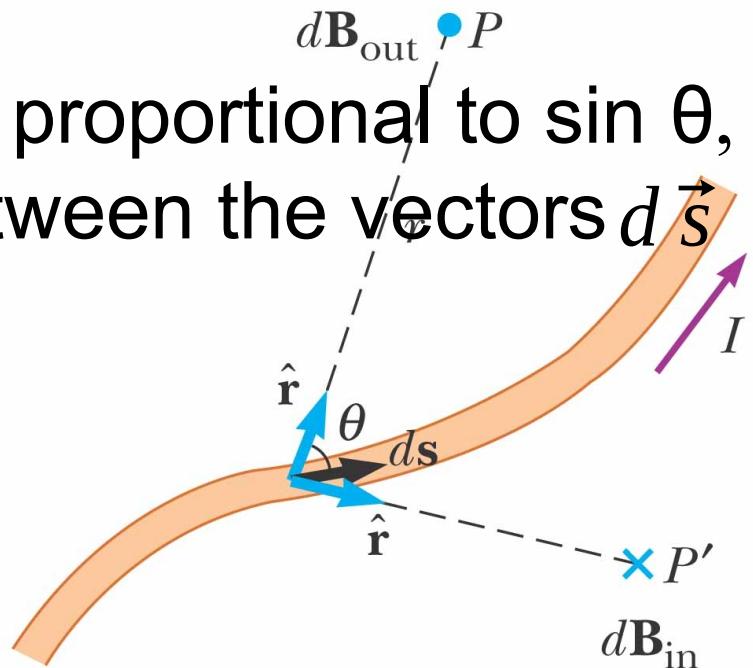


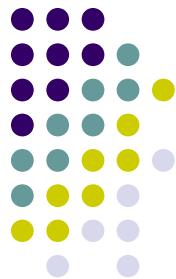
RHR#1 also applies

Biot-Savart Law – Observations, cont



- The magnitude of $d\vec{B}$ is proportional to the current and to the magnitude ds of the length element $d\vec{s}$
- The magnitude of $d\vec{B}$ is proportional to $\sin \theta$, where θ is the angle between the vectors $d\vec{s}$ and $\hat{\vec{r}}$





Biot-Savart Law – Equation

- The observations are summarized in the mathematical equation called the **Biot-Savart law**:

$$d \vec{B} = \frac{\mu_0 I}{4 \pi} \frac{d \vec{s} \times \hat{r}}{r^2}$$

- The magnetic field described by the law is the field *due to* the current-carrying segment $d \vec{s}$.
 - It doesn't include the B due to other currents or permanent magnets.



Permeability of Free Space

- The constant μ_0 is called the **permeability of free space**
- $\mu_0 = 4\pi \times 10^{-7} \text{ T} \cdot \text{m} / \text{A}$

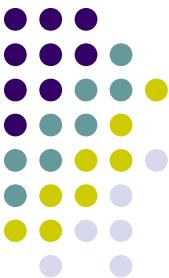


Total Magnetic Field

- $d\vec{B}$ is the field created by the current in the length segment ds
- To find the total field, sum up the contributions from all the current elements $\int d\vec{s}$

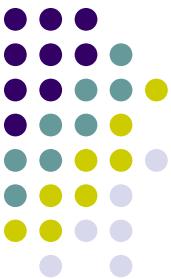
$$\vec{B}_{tot} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

- The integral is over the entire current distribution



\vec{B} Compared to \vec{E}

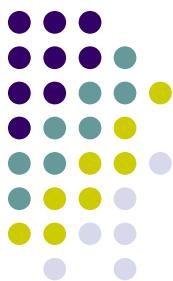
- Distance
 - The magnitude of the magnetic field varies as the inverse square of the distance from the source (when it's a “point” current)
 - The electric field due to a point charge also varies as the inverse square of the distance from the charge



\vec{B} Compared to \vec{E} , 2

- Direction
 - The electric field created by a point charge is radial in direction
 - The magnetic field created by a current element is perpendicular to both the length element $d\vec{s}$ and the unit vector \hat{r}

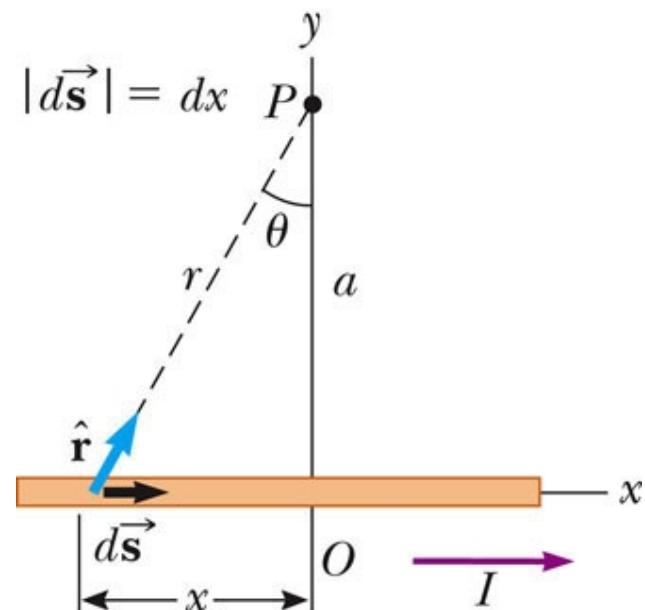
\vec{B} for a Long, Straight Conductor



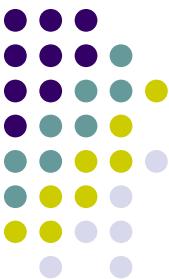
- The thin, straight wire is carrying a constant current, I
- $d\vec{s} \times \hat{r} = (dx \sin(90 - \theta)) \hat{k}$
- Integrating over all the current elements gives

$$B = \frac{\mu_0 I}{4\pi a} \int_{\theta_1}^{\theta_2} \cos \theta d\theta$$

$$B = -\frac{\mu_0 I}{4\pi a} (\sin \theta_1 - \sin \theta_2)$$



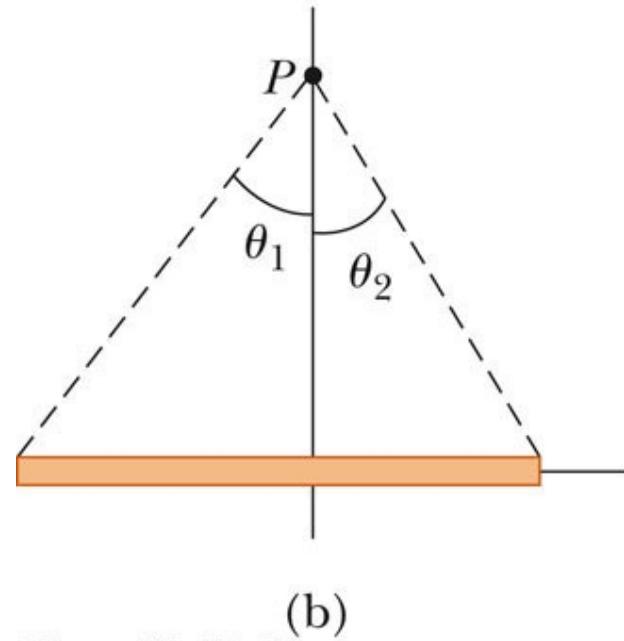
(a)



\vec{B} for a Long, Straight Conductor, Special Case

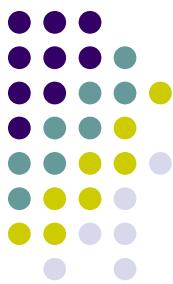
- If the conductor is an infinitely long, straight wire, $\theta_1 = -\pi/2$ and $\theta_2 = +\pi/2$
- The field becomes

$$B = \frac{\mu_0 I}{2 \pi a}$$

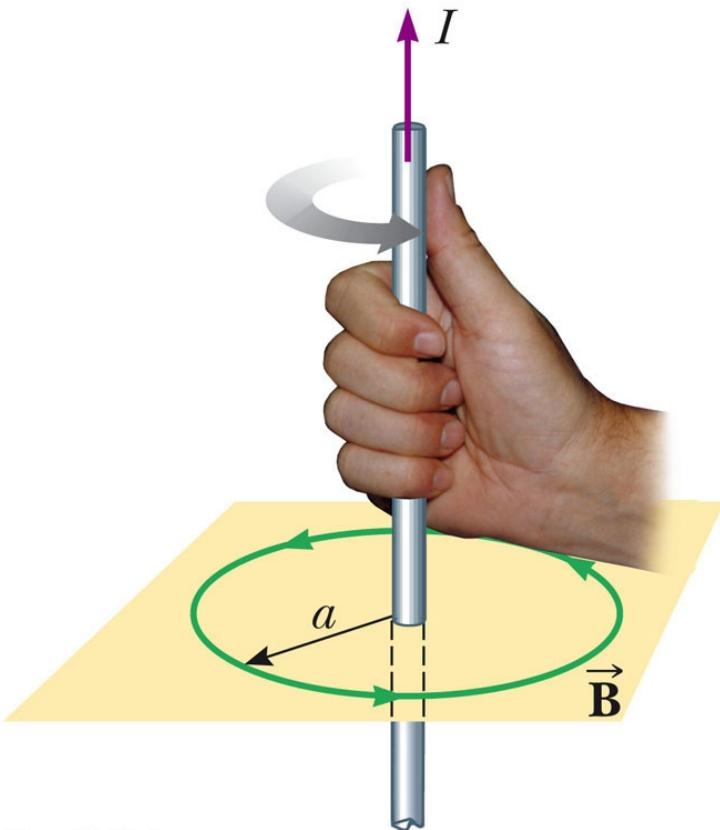


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B for a Long, Straight Conductor, Direction



- The magnetic field lines are circles concentric with the wire
- The field lines lie in planes perpendicular to the wire
- The **Right-Hand Rule #2** for determining the direction of the field is shown



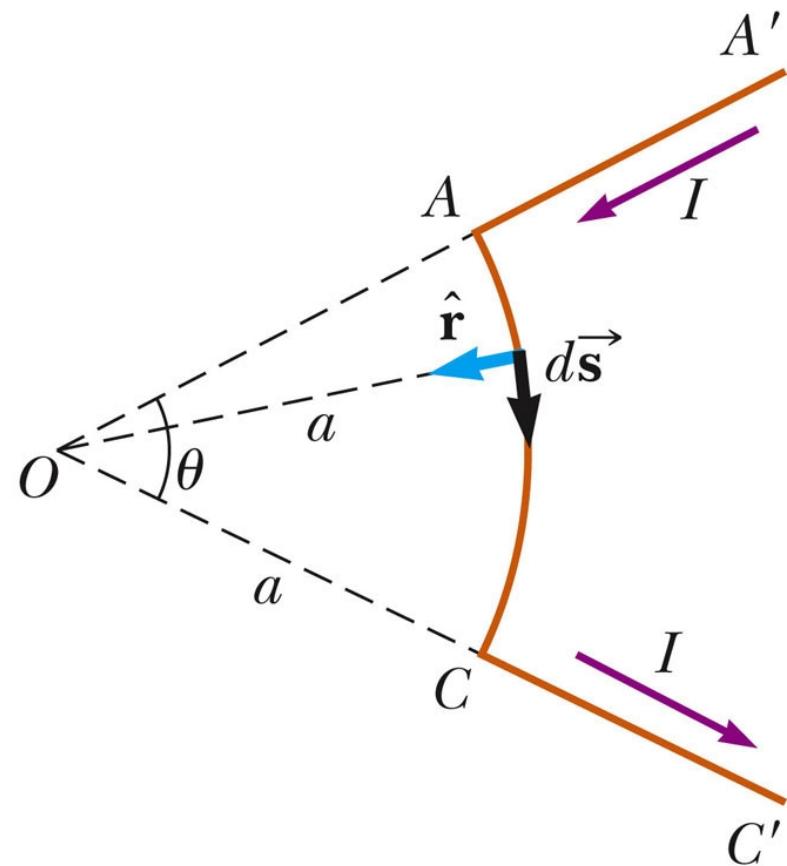
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B for a Curved Wire Segment

- Find the field at point O due to the wire segment
- I is constant
- Use Biot-Savart with $ds = a d\theta$. Result:
$$B = \mu_0 I \theta / 4\pi a$$

θ will be in radians



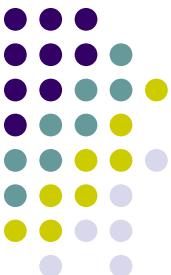


B for a Circular Loop of Wire

- Consider the previous result, with a full circle
 - $\theta = 2\pi$

$$B = \frac{\mu_0 I \theta}{4 \pi a} = \frac{\mu_0 I 2 \pi}{4 \pi a} = \frac{\mu_0 I}{2 a}$$

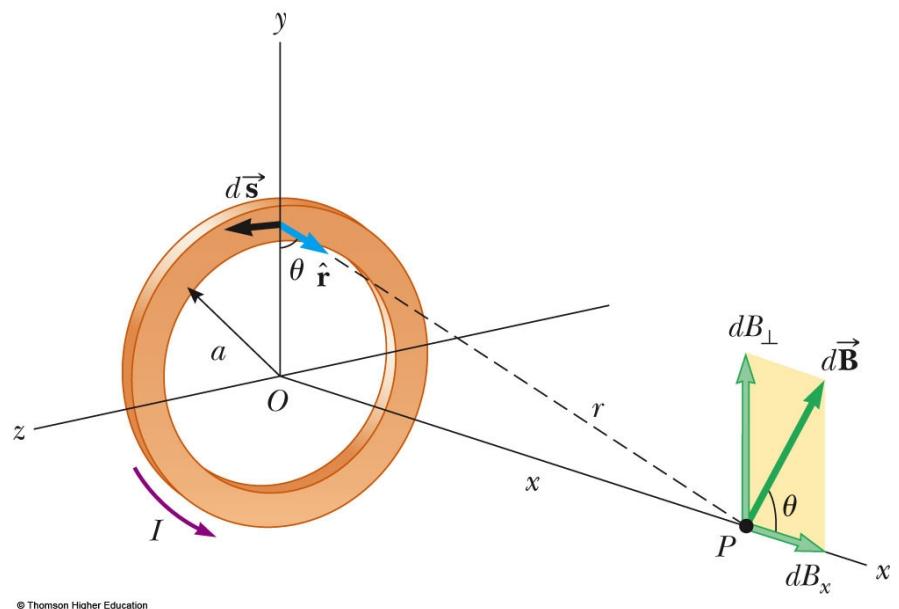
- This is the field at the *center* of the loop



B for a Circular Current Loop

- The loop has a radius of R and carries a steady current of I
- Find the field at point P

$$B_x = \frac{\mu_0 I a^2}{2(a^2 + x^2)^{3/2}}$$



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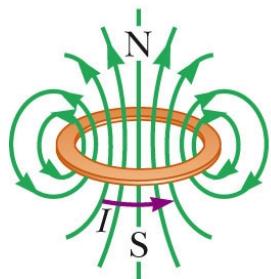
Comparison of Loops

- Consider the field at the center of the current loop
- At this special point, $x = 0$
- Then,

$$B_x = \frac{\mu_0 I a^2}{2(a^2 + x^2)^{3/2}} = \frac{\mu_0 I}{2a}$$

- This is exactly the same result as from the curved wire

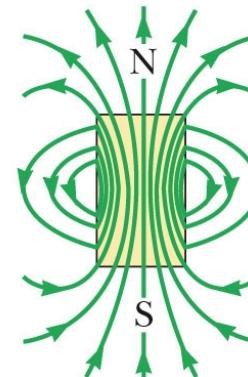
Magnetic Field Lines for a Loop



(a)



(b)



(c)

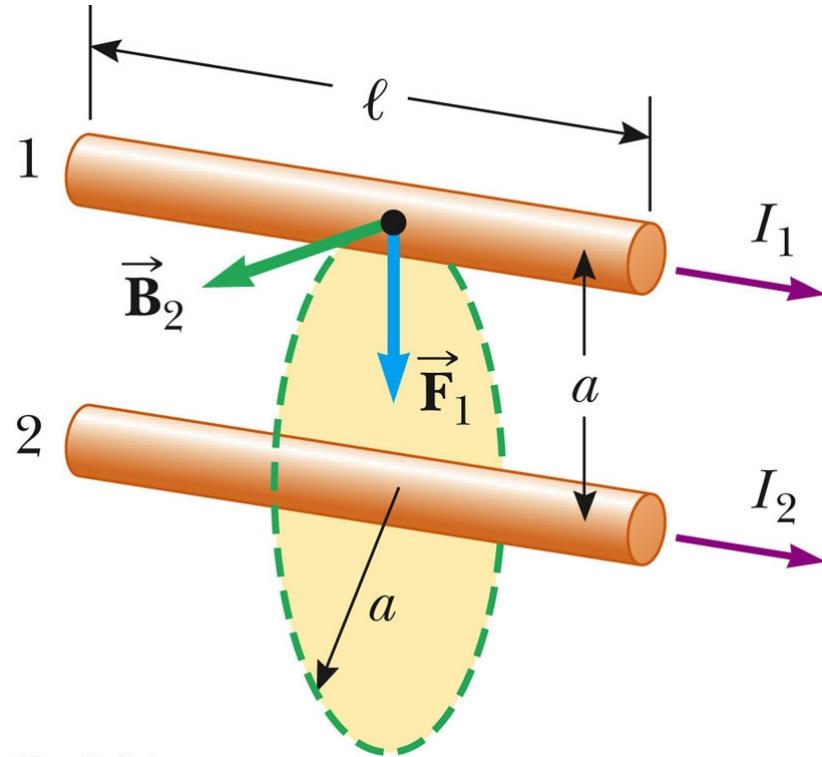
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- Figure (a) shows the magnetic field lines surrounding a current loop
- Figure (b) shows the field lines in the iron filings
- Figure (c) compares the field lines to that of a bar magnet

Magnetic Force Between Two Parallel Conductors



- Two parallel wires each carry a steady current
- The field \vec{B}_2 due to the current in wire 2 exerts a force on wire 1 of $F_1 = I_1 \ell B_2$



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PLAY
ACTIVE FIGURE

Magnetic Force Between Two Parallel Conductors, cont.



- Substituting $\vec{B}_2 = \frac{\mu_0 I_2}{2\pi a}$ gives

$$F_1 = \frac{\mu_0 I_1 I_2 l}{2\pi a}$$

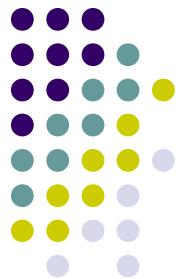
- RHR #1 shows us F_1 is down and F_2 is up.
- Parallel conductors carrying currents in the same direction attract each other
- Parallel conductors carrying current in opposite directions repel each other

Magnetic Force Between Two Parallel Conductors, final



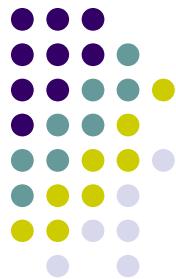
- The result is often expressed as the magnetic force between the two wires, F_B
- This can also be given as the force per unit length:

$$\frac{F_B}{l} = \frac{\mu_0 I_1 I_2}{2 \pi a}$$



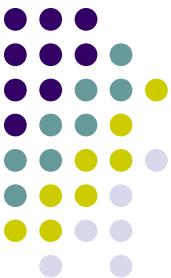
Definition of the Ampere

- The force between two parallel wires can be used to define the ampere
- When the magnitude of the force per unit length between two long, parallel wires that carry identical currents and are separated by 1 m is 2×10^{-7} N/m, the current in each wire is defined to be 1 A



Definition of the Coulomb

- The SI unit of charge, the coulomb, is defined in terms of the ampere
- When a conductor carries a steady current of 1 A, the quantity of charge that flows through a cross section of the conductor in 1 s is 1 C

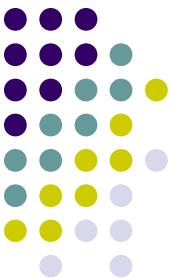


Andre-Marie Ampère

- 1775 – 1836
- French physicist
- Credited with the discovery of electromagnetism
 - The relationship between electric current and magnetic fields
- Also worked in mathematics

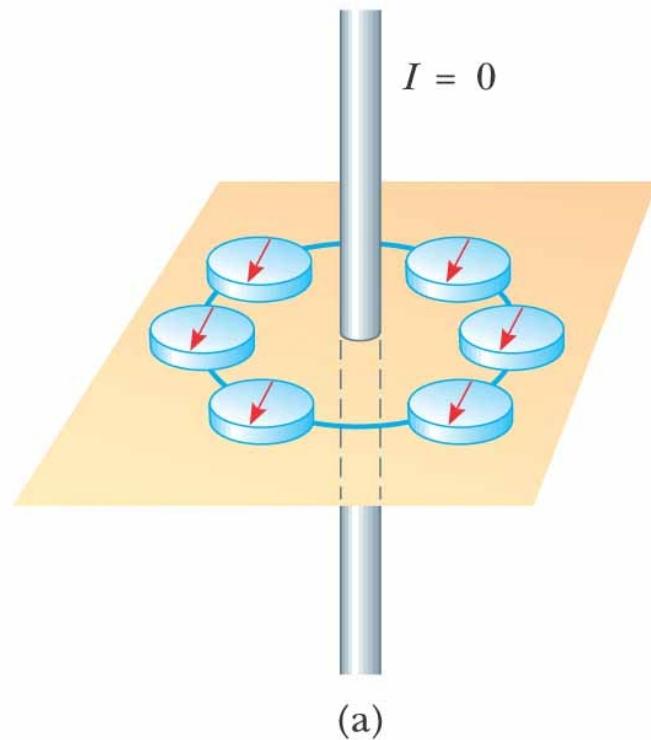


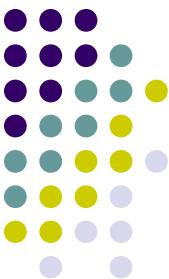
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Magnetic Field of a Wire

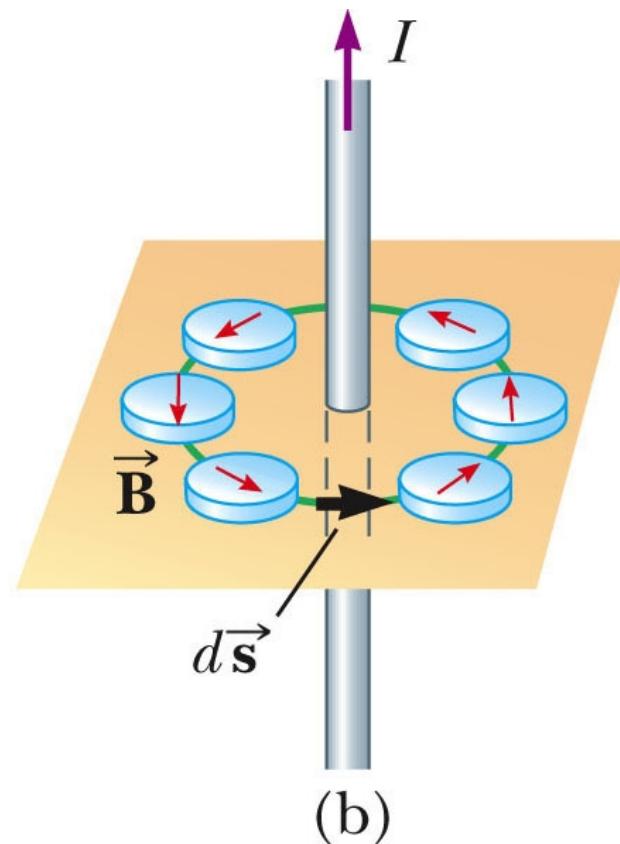
- A compass can be used to detect the magnetic field
- When there is no current in the wire, there is no field due to the current
- The compass needles all point toward the Earth's north pole
 - Due to the Earth's magnetic field



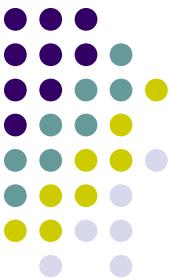


Magnetic Field of a Wire, 2

- Here the wire carries a strong current
- The compass needles deflect in a direction tangent to the circle
- This shows the direction of the magnetic field produced by the wire
- Use the active figure to vary the current



PLAY
ACTIVE FIGURE

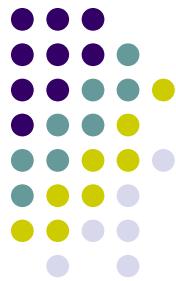


Magnetic Field of a Wire, 3

- The circular magnetic field around the wire is shown by the iron filings



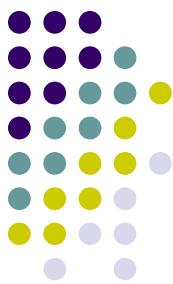
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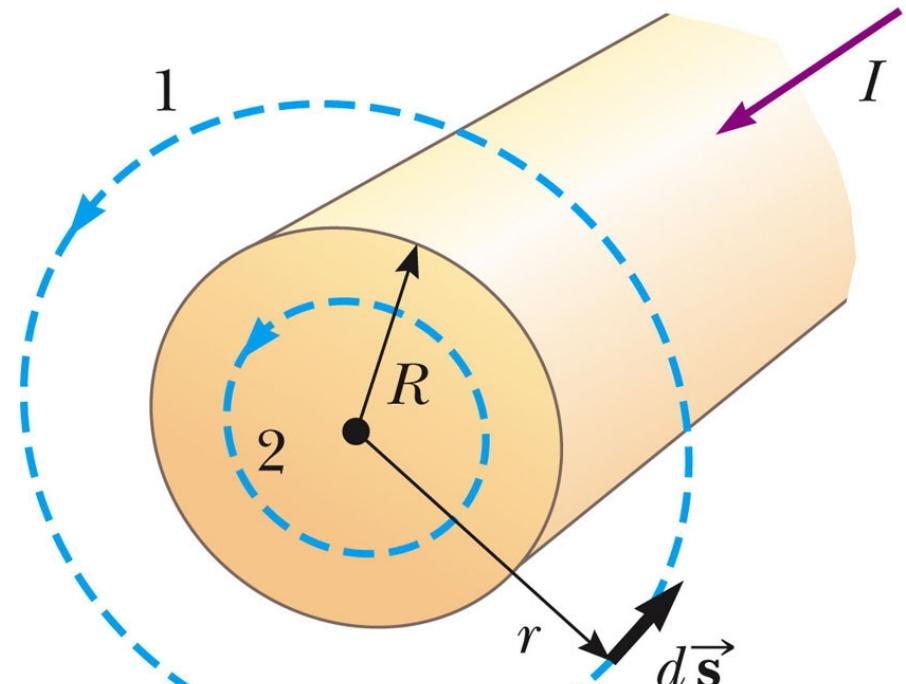
Ampere's Law

- The product of $\vec{B} \cdot d\vec{s}$ can be evaluated for small length elements $d\vec{s}$ on the circular path defined by the compass needles for the long straight wire
- Ampere's law states that the line integral of $\vec{B} \cdot d\vec{s}$ around any closed path equals $\mu_0 I_{enc}$ where I_{enc} is the total steady current passing through any surface bounded by the closed path:
$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enc}$$

Field Due to a Long Straight Wire – From Ampere's Law



- Want to calculate the magnetic field at a distance r from the center of a wire carrying a steady current I
- The current is uniformly distributed through the cross section of the wire





Field Due to a Long Straight Wire – Results From Ampere's Law

- Outside of the wire, $r > R$

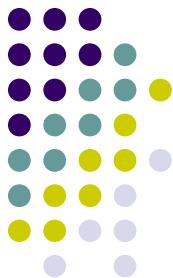
$$\int \vec{B} \cdot d\vec{s} = B(2\pi r) = \mu_0 I \quad \int \vec{B} \cdot d\vec{s} = B(2\pi r) = \mu_0 I$$

- Inside the wire, we need I' , the current inside the amperian circle. Assume J is uniform.

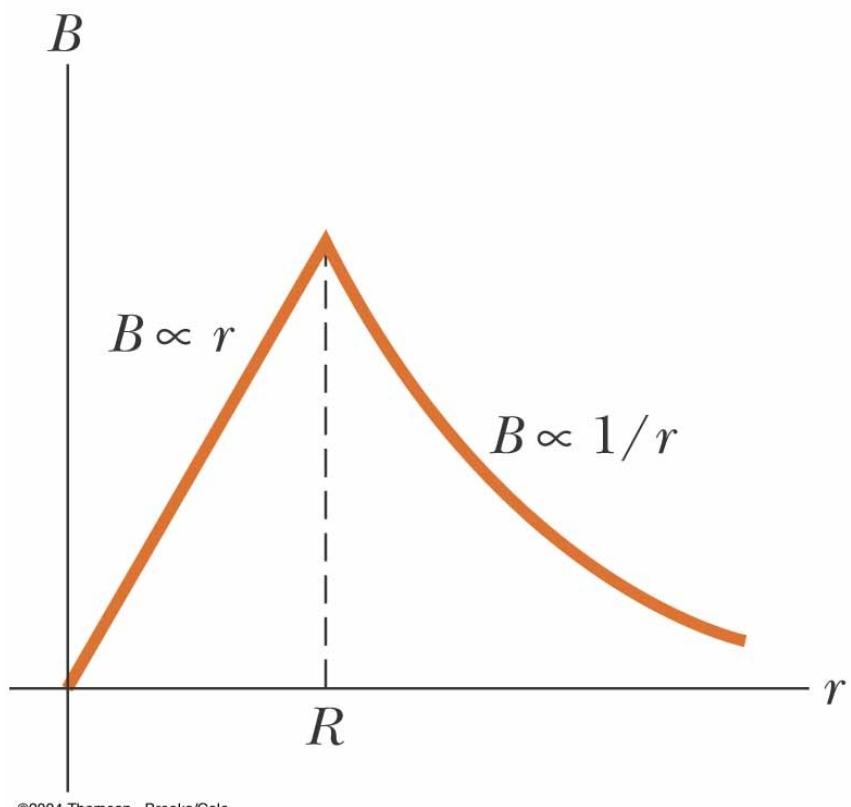
$$\int \vec{B} \cdot d\vec{s} = B(2\pi r) = \mu_0 I' \leftarrow I' = \frac{r^2}{R^2} I$$

$$B = \frac{\mu_0 I r}{2\pi R^2}$$

Field Due to a Long Straight Wire – Results Summary



- The field is proportional to r inside the wire
- The field varies as $1/r$ outside the wire
- Both equations are equal at $r = R$



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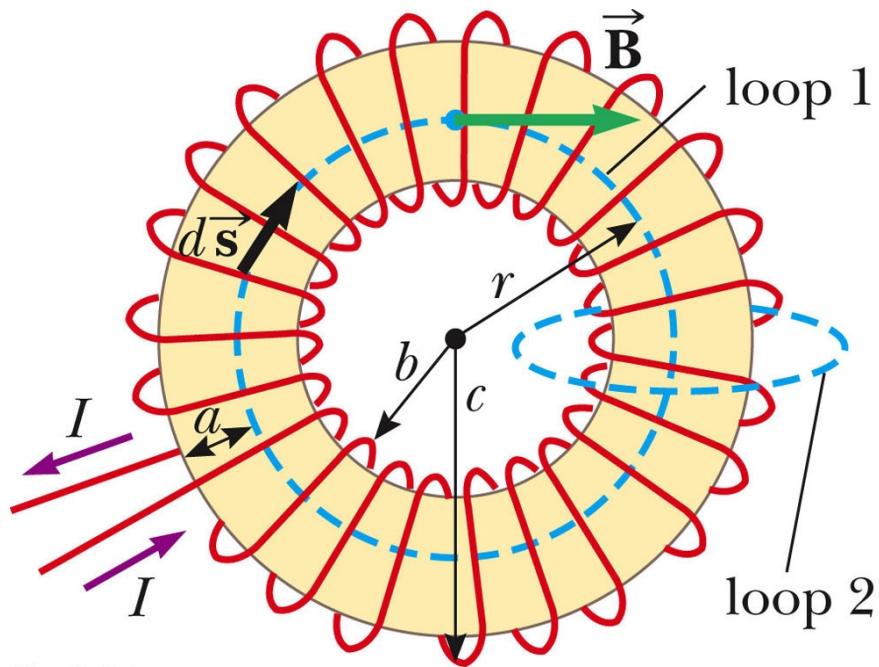


Magnetic Field of a Toroid

- Find the field at a point at distance r from the center of the toroid
- The toroid has N turns of wire

$$\oint \vec{B} \cdot d\vec{s} = B(2\pi r) = \mu_0 NI$$

$$B = \frac{\mu_0 NI}{2\pi r}$$

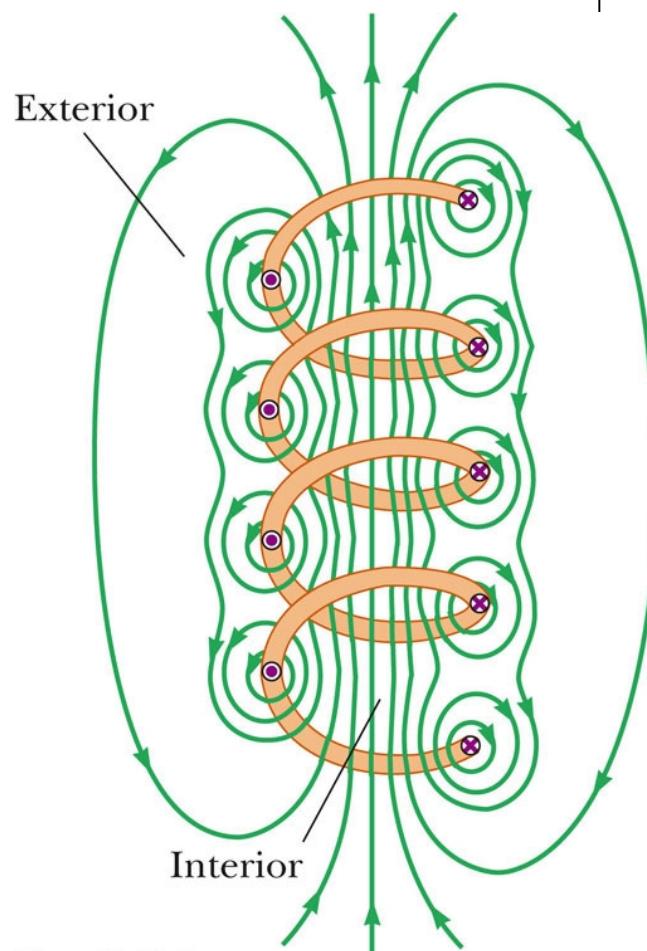


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Magnetic Field of a Solenoid

- A **solenoid** is a long wire wound in the form of a helix
- A reasonably uniform magnetic field can be produced in the space surrounded by the turns of the wire

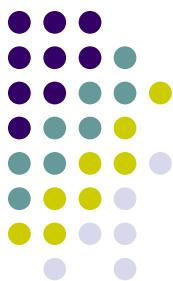


Magnetic Field of a Solenoid, Description

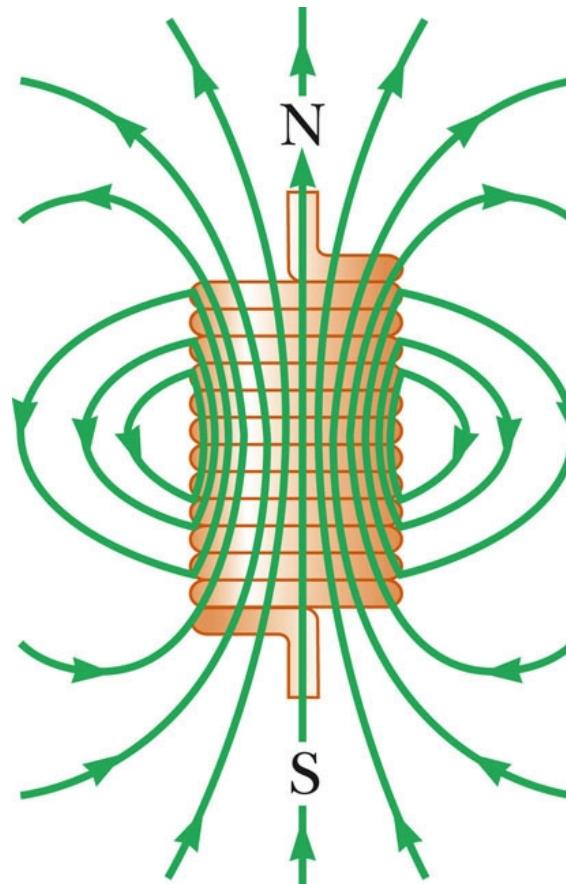


- The field lines in the interior are
 - nearly parallel to each other
 - uniformly distributed
 - close together
- This indicates the field is strong and almost uniform

Magnetic Field of a Tightly Wound Solenoid



- The field distribution is similar to that of a bar magnet
- As the length of the solenoid increases
 - the interior field becomes more uniform
 - the exterior field becomes weaker

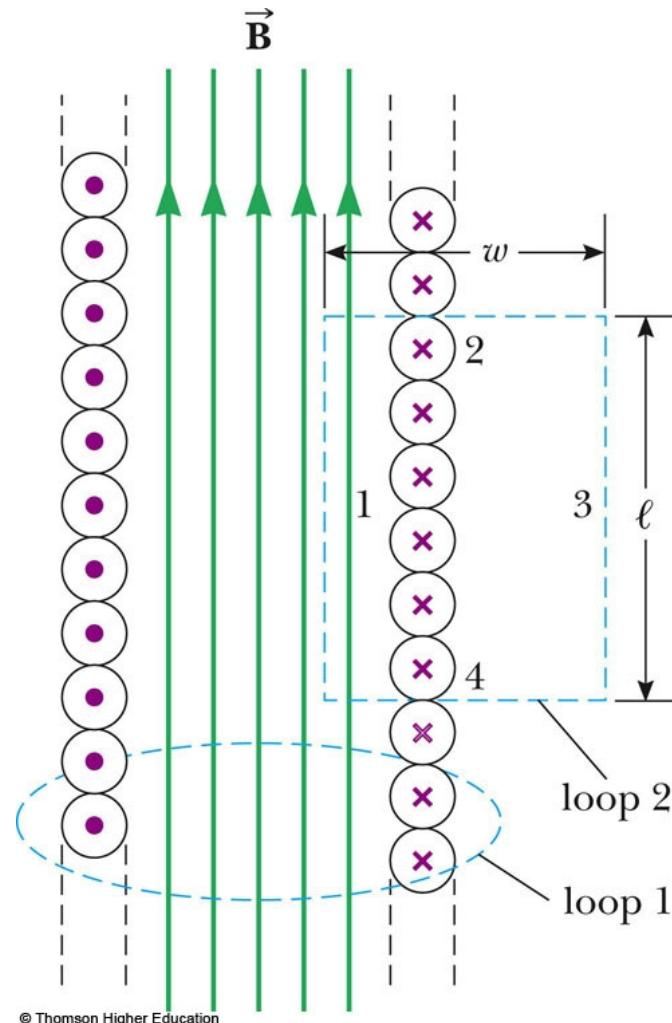


(a)

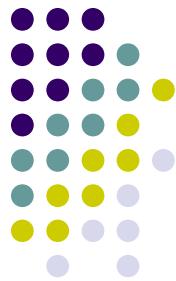
Ideal Solenoid – Characteristics



- An *ideal solenoid* is approached when:
 - the turns are closely spaced
 - the length is much greater than the radius of the turns

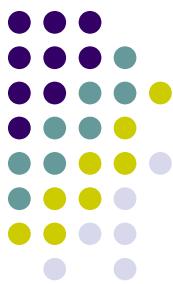


Ampere's Law Applied to a Solenoid



- Ampere's law can be used to find the interior magnetic field of the solenoid
- Consider a rectangle with side ℓ parallel to the interior field and side w perpendicular to the field
 - This is loop 2 in the diagram
- Only the side of length ℓ inside the solenoid contributes to the integral.
 - This is side 1 in the diagram

Ampere's Law Applied to a Solenoid, cont.



- Applying Ampere's Law gives

$$\oint \vec{B} \cdot d\vec{s} = \int_{path\ 1} B \cdot d\vec{s} = B \int_{path\ 1} ds = Bl$$

- The total current through the rectangular path equals the current through each turn multiplied by the number of turns

$$Bl = \mu_0 NI \dots B = \frac{\mu_0 NI}{l}$$

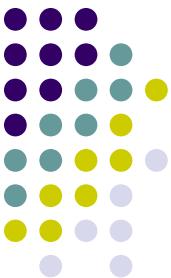
Magnetic Field of a Solenoid, final



- Solving Ampere's law for the magnetic field is

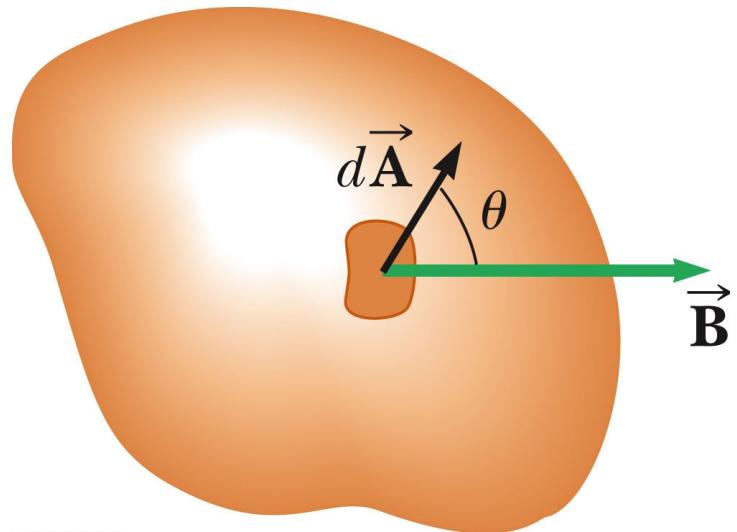
$$B = \frac{\mu_0 N I}{l} = \mu_0 n I$$

- $n = N / l$ is the number of turns per unit length
- This is most accurate at points near the center of a real solenoid

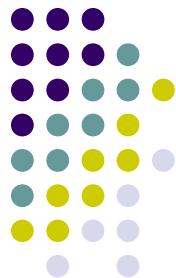


Magnetic Flux

- The magnetic flux associated with a magnetic field is defined in a way similar to electric flux
- Consider an area element dA on an arbitrarily shaped surface



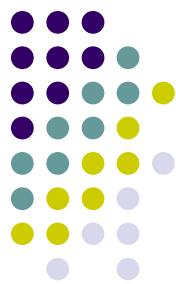
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Magnetic Flux, cont.

- The magnetic field in this element is \vec{B}
- $d\vec{A}$ is a vector that is perpendicular to the surface
- $d\vec{A}$ has a magnitude equal to the area dA
- The magnetic flux Φ_B is
$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$
- The unit of magnetic flux is $T \cdot m^2 = \text{Wb}$
 - Wb is a *weber*

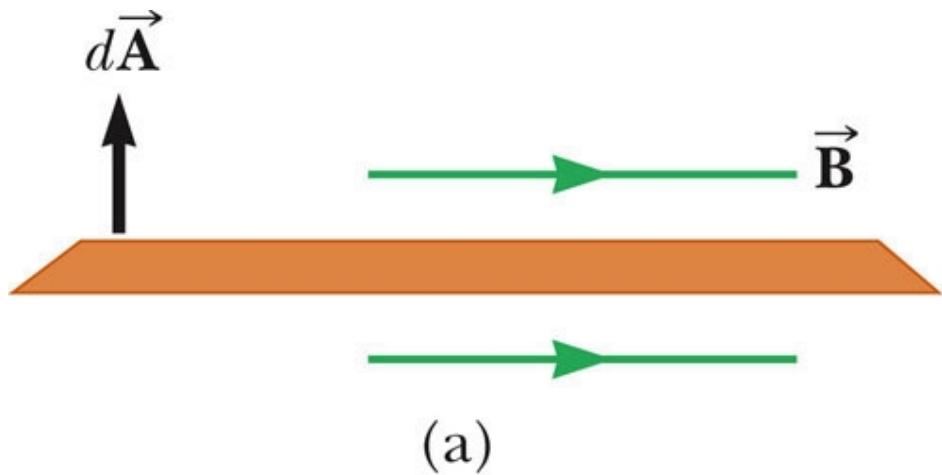
Magnetic Flux Through a Plane, 1



- A special case is when a plane of area A makes an angle θ with $d\vec{A}$

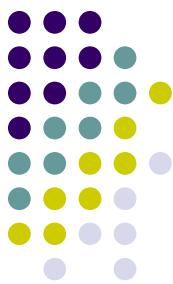
The magnetic flux is $\Phi_B = BA \cos \theta$

- In this case, the field is parallel to the plane and $\Phi_B = 0$

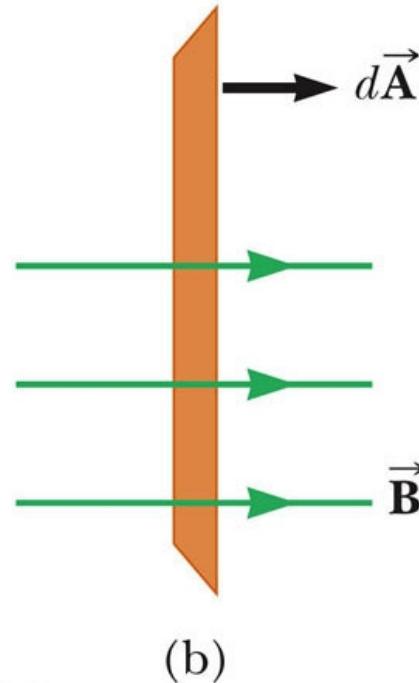


PLAY
ACTIVE FIGURE

Magnetic Flux Through A Plane, 2



- The magnetic flux is $\Phi_B = BA \cos \theta$
- In this case, the field is perpendicular to the plane and
$$\Phi_B = BA$$
- This will be the maximum value of the flux
- Use the active figure to investigate different angles



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PLAY
ACTIVE FIGURE



Gauss' Law in Magnetism

- Magnetic fields do not begin or end at any point
 - The number of lines entering a surface equals the number of lines leaving the surface
- **Gauss' law in magnetism** says the magnetic flux through any closed surface is always zero:

$$\oint \vec{B} \cdot d\vec{A} = 0$$