

---

```

A=[2,1;3,2]
B=[3,1;2,2]
A'
B'
A1=A*B, A2=B*A, A3=(A'*B')', A4=(B'*A')'

A1=inv(A*B), A2=inv(A)*inv(B), A3=inv(B*A), A4=inv(B)*inv(A)
A1*(A*B),(A*B)*A1

C=[1,0,1;3,3,4;2,2,3;]
S=[10;12;5]
V=[19;-3;-9]
inv(C)*S
C*V

D=[2,4;1,2]
inv(D)

t=[0:0.01:10];
p=5*cos(2*pi*3*t);
v=5*exp(-0.5*t);
figure(1)
plot(t,p)
figure(2)
plot(t,v)
b=p.*v;
figure(3)
plot(t,b)

A =

     2     1
     3     2

B =

     3     1
     2     2

ans =

     2     3
     1     2

ans =

     3     2
     1     2

```

---

---

A1 =

8	4
13	7

A2 =

9	5
10	6

A3 =

9	5
10	6

A4 =

8	4
13	7

A1 =

1.7500	-1.0000
-3.2500	2.0000

A2 =

1.5000	-1.2500
-2.5000	2.2500

A3 =

1.5000	-1.2500
-2.5000	2.2500

A4 =

1.7500	-1.0000
-3.2500	2.0000

ans =

1	0
0	1

---

*ans* =

1.0000	-0.0000
0.0000	1.0000

*C* =

1	0	1
3	3	4
2	2	3

*S* =

10
12
5

*V* =

19
-3
-9

*ans* =

19.0000
-3.0000
-9.0000

*ans* =

10
12
5

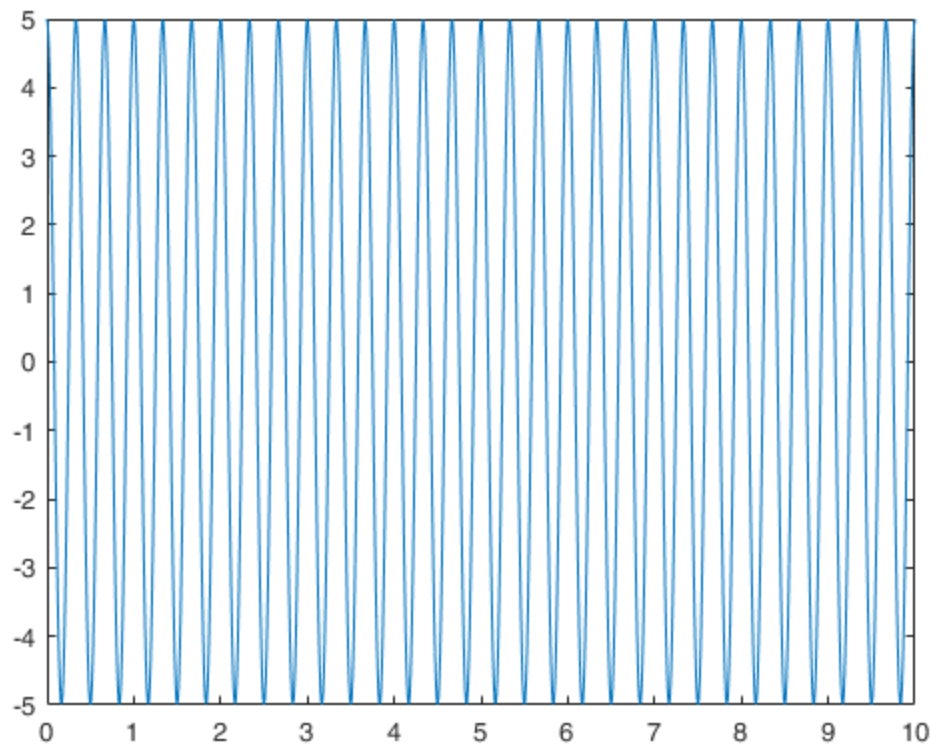
*D* =

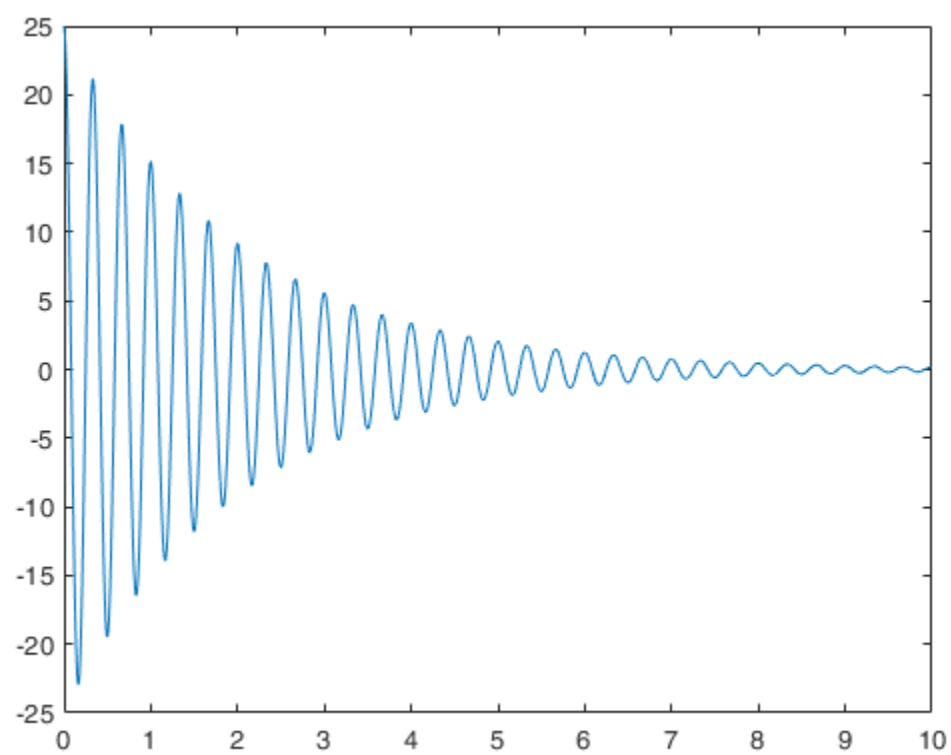
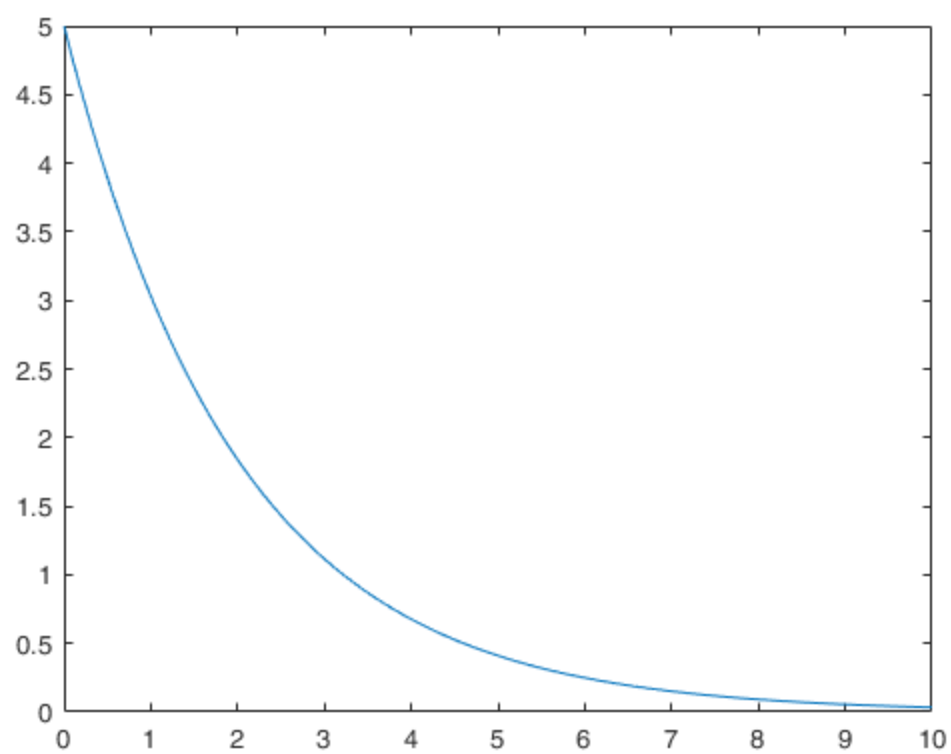
2	4
1	2

*Warning: Matrix is singular to working precision.*

*ans* =

<i>Inf</i>	<i>Inf</i>
<i>Inf</i>	<i>Inf</i>





---

*Published with MATLAB® R2016b*