# A hybrid parareal Monte-Carlo algorithm for the parabolic time dependant diffusion equation

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### Outline

- Introduction
- 2 Model problem
- Numerical experiments
- Conclusion

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Study the neutron transport in nuclear reactors

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**Model:** Linear Boltzmann equation for the angular flux

$$\partial_t \Psi(t, \boldsymbol{x}, \boldsymbol{v}) + \boldsymbol{v} \cdot \nabla \Psi(t, \boldsymbol{x}, \boldsymbol{v}) + \sigma(\boldsymbol{x}, \boldsymbol{v}) \Psi(t, \boldsymbol{x}, \boldsymbol{v}) - \int_{\mathbb{R}^3} k(\boldsymbol{x}, \boldsymbol{v}, \boldsymbol{v}') \Psi(t, \boldsymbol{x}, \boldsymbol{v}') \, \mathrm{d} \boldsymbol{v}' = 0$$

Balance between the neutrons that are created and that disappear in the core.

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- Monte-Carlo approach
- Deterministic approach

Can we speed up a Monte-Carlo resolution?

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Parareal-in-time algorithm ⇒ important computational savings



Complicated problem... Start with a diffusion problem to understand the involved underlying mechanisms.

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$$\begin{cases} \partial_t u - \mathcal{D} \Delta u = g & \text{in} \quad \Omega \times [0, T], \\ u(\cdot, 0) = u^0 & \text{in} \quad \Omega, \\ u = 0 & \text{on} \quad \partial \Omega \times [0, T]. \end{cases}$$

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**Parareal procedure:** It constructs a sequence  $\boldsymbol{u}_k^n := (\boldsymbol{u}_k^n)_{1 \le n \le N}$  such that  $\boldsymbol{u}_k^n \approx u^n$ . It involves a coarse propagator  $\mathcal{G}_{\Delta t}$  and a fine propagator  $\mathcal{F}_{\delta t}$ .

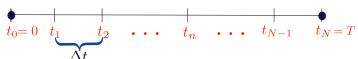
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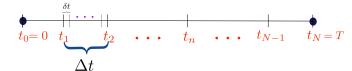
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6. **Update:**  $u_{k=2}^2$  and  $u_{k=2}^3$  and  $u_{k=2}^4$ 

### Coarse propagator

 $\mathcal{T}_h$ : mesh of the domain  $\Omega$ 

 $V_h$ : Lagrange nodes,  $V_h^{int}$ : interior nodes,

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#### The finite element propagator

$$\begin{split} & X_h^{p} := \left\{ v_h \in \mathcal{C}^0(\Omega); v_h|_K \in \mathbb{P}_p(K) \ \forall K \in \mathcal{T}_h \right\} \subset H^1(\Omega) \\ & X_{0h}^{p} := \left\{ v_h \in \mathcal{C}^0(\Omega); v_h|_K \in \mathbb{P}_p(K) \ \forall K \in \mathcal{T}_h, \ v_h|_{\partial\Omega} = 0 \right\} \subset H^1_0(\Omega) \end{split}$$

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#### The cell centered finite volume propagator

 $extbf{\emph{U}}_{h}^{n} := ( extbf{\emph{U}}_{K}^{n})_{K \in \mathcal{T}_{h}}, \quad ext{one value per cell and time step}$ 

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#### The discontinuous Galerkin propagator

 $\mathcal{N}_h^{\text{int}}$ : total number of local internal degrees of freedom.

### **Discontinuous Galerkin space:**

$$\begin{split} X_h^{\rho} &:= \left\{ v_h \in L^2(\Omega); v_h|_K \in \mathbb{P}_p(K) \ \forall K \in \mathcal{T}_h \right\} \not\subset H^1(\Omega), \\ X_{0h}^{\rho} &:= \left\{ v_h \in L^2(\Omega); v_h|_K \in \mathbb{P}_p(K) \ \forall K \in \mathcal{T}_h, v_h|_{\partial \Omega} = 0 \right\} \not\subset H^1_0(\Omega) \end{split}$$

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**local matrix**  $[\mathbb{A}^n]_K^{-1} = \text{stiffness matrix} + \text{mass matrix} + \text{consistency and stability terms.}$ 

### Fine propagator: Monte-Carlo

Principle: It gives an approximation of

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Consider M particles and sample a collection  $X_1, X_2, \cdots, X_M$  of M points from the PDF f. Denote by  $\omega_i \in \mathbb{R}_+$  their statistical weight.

Compute  $g(X_1),...,g(X_M)$ .

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$$\int_{K} u(\boldsymbol{x}) dx = \overline{\mathbb{E}} \left[ u(g(\boldsymbol{x})) \right].$$

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**Central limit Theorem:** 

error 
$$\approx 1/\sqrt{M}$$
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#### The table lookup method:

Probability each element:  $\mathbb{P}([x_{i-1}, x_i]) = \int_{[x_{i-1}, x_i]} f(x) dx$ ,

Cumulative function:  $F_i: \Omega \to [0,1], F_i = \sum_{i \le i} \mathbb{P}([x_{i-1},x_i])$ 

Let  $\xi_1 \sim \mathcal{U}([0,1])$ . Identify the two intervals such that  $F_{i-1} \leq \xi_1 \leq F_i$ .

Position of the particle:  $X_i = \frac{(x_i - x_{i-1}) \xi_1 - x_i F_{i-1} + x_{i-1} F_i}{F_i - F_{i-1}}$ .

Repeat *M* times the procedure.

### Often used when the PDF f is hard to invert. Assume there exists a PDF $g:\Omega\to\mathbb{R}_+$ "easy" to simulate such that

$$f(x) \le kg(x)$$
, where  $k \ge 1$  is a constant.

Set 
$$\alpha(x) = \frac{f(x)}{kg(x)}$$
.

Compute the cumulative function  $G: \Omega \to [0, 1]$  associated to g.

Let 
$$\xi \sim \mathcal{U}([0,1])$$
.

Find  $X_i \in K$  using the direct inversion procedure.

Compute  $\alpha(X_i)$ .

Let  $\xi_1 \sim \mathcal{U}([0,1])$ . If  $\xi_1 < \alpha(X_i)$  accept  $X_i$ . Otherwise reject and and come back to first step.

How define the transport of the particles?

### Kernel Transport

 $(\mathbf{x},t)$ : position of the particle  $\mathbf{x}$  at time t

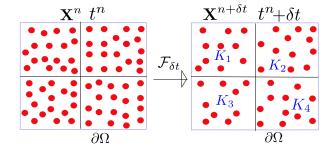
 $(\mathbf{x}', t')$ : position of the particle  $\mathbf{x}'$  at time t'

Density transition kernel:

$$T(\mathbf{x}',t' o \mathbf{x},t) := \frac{1}{\sqrt{2\pi\mathcal{D}(t-t')}} \exp\left(-\frac{(\mathbf{x}-\mathbf{x}')^2}{2\mathcal{D}(t-t')}\right).$$

Pratical formula for the brownian motion:

$$T(\mathbf{X}^{n+\delta t}, t^n + \delta t) = T(\mathbf{X}^n, t^n) + \sqrt{2D\delta t} \, \mathcal{S}_n$$
 where  $\mathcal{S}_n \sim \mathcal{N}(0, 1)$ 



### Hybrid parareal algorithm

Coarse propagator: Deterministic solver

Fine propagator: Monte-Carlo solver: deterministic data + sampling + average

Consider p independent replicas and M' particles so that the total number of particles is  $M = p \times M'$ . The numerical solution obtained for a replica  $j \in [1, p]$  at parareal iteration k is denoted by  $\boldsymbol{U}_{k,j}^{n+1}$ 

$$U_k^{n+1} := \frac{1}{p} \sum_{j=1}^p U_{k,j}^{n+1}$$

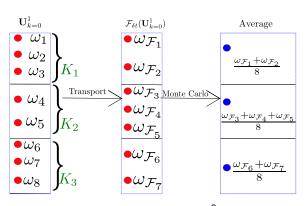


When  $\boldsymbol{U}_{k,j}^{n+1}$  is computed, we need its statistical version for the computation of  $\boldsymbol{U}_{k+1,j}^{n+2} = \mathcal{G}_{\Delta t}(\boldsymbol{U}_{k+1,j}^{n+1}) \times \frac{\mathcal{F}_{\delta t}(\boldsymbol{U}_{k,j}^{n+1})}{\mathcal{G}_{\Delta t}(\boldsymbol{U}_{k,j}^{n+1})}$ . Introduce bias in the Monte-Carlo solver.

### Updating the statistical weights

**Example:** How avoid sampling  $U_{\nu-1}^2$ ?

$$[\omega_1^2]_{i\in\mathcal{K}} = [\omega_{\mathcal{F}}]_{i\in\mathcal{K}} \times \left(\frac{\mathbf{U}_{k=1}^2}{\mathcal{F}(\mathbf{U}_{k=0}^1)}\right)|_{\mathcal{K}}$$



$$\operatorname{hist}(\omega_{k=1}^2)|_{\mathcal{K}_1} = \frac{1}{8} \left( \omega_{\mathcal{F}_1} + \omega_{\mathcal{F}_2} \right) \times \left( \frac{\boldsymbol{U}_{k=1}^2}{\mathcal{F}(\boldsymbol{U}_{k=0}^1)} \right) |_{\mathcal{K}_1} = \boldsymbol{U}_{k=1}^2$$

### Outline

- Numerical experiments

### Numerical experiments

 $\Omega$ : one-dimensional core with length L=5m, **Final simulation time:** T=10s.

Numerical experiments

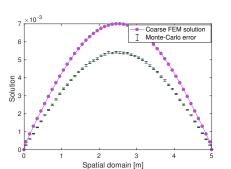
**Deterministic propagator:**  $\mathbb{P}_1$  finite element,  $\Delta t = 2s$ .

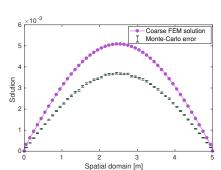
Fine propagator: Monte-Carlo,  $\delta t = 2 \times 10^{-4} s$ .

Diffusion coefficient:  $\mathcal{D} = 0.5 \text{m}^2 \cdot \text{s}^{-1}$ ,

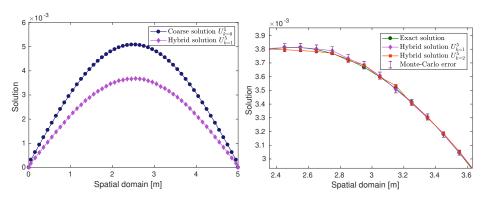
Initial condition:  $u_0(x) = \frac{1}{t}$ .

Number of particles: 10<sup>4</sup>, Number of replicas: 10<sup>3</sup>

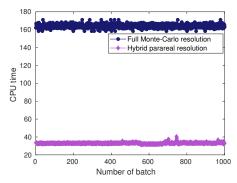


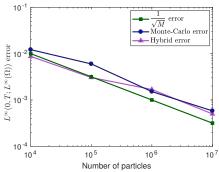


### Hybrid solution



### CPU time and convergence





Number of particles	Number of replica	Parallelized Monte-Carlo	Hybrid parallelized Monte-Carlo $k = 1$	Hybrid parallelized Monte-Carlo $k = 2$	Gain factor $k = 1$	Gain factor $k=2$	
10 <sup>5</sup>	10 <sup>2</sup>	1653.4 s	335.76 s	534.16 s	4.92	3.04	
10 <sup>4</sup>	10 <sup>3</sup>	164.09 s	33.05 s	7.97 s	4.96	3.09	
10 <sup>3</sup>	10 <sup>4</sup>	16.86 s	3.39 s	0.83 s	4.97	3.07	
10 <sup>2</sup>	10 <sup>5</sup>	1.78 s	0.35 s	0.11 s	5.08	3.02	

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Final simulation time: T = 14s.

**Deterministic propagator:**  $\mathbb{P}_1$  finite element,  $\Delta t = 2s$ .

Fine propagator: Monte-Carlo,  $\delta t = 2 \times 10^{-4} s$ .

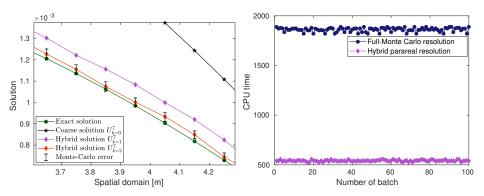
**Diffusion coefficient MC:**  $\mathcal{D} = 0.5 m^2 \cdot s^{-1}$ 

Diffusion coefficient FEM:  $\mathcal{D} = 0.48 \, \text{m}^2 \cdot \text{s}^{-1}$ 

**Initial condition:**  $u_0(x) = \frac{1}{L} (1 + \cos(\frac{\pi x}{L})).$ 

Number of particles: 10<sup>5</sup>, Number of replicas: 10<sup>2</sup>

### CPU time and convergence



### **Outline**

- Introduction
- Model problem
- Numerical experiments
- Conclusion

### Conclusion

- We devised for the diffusion equation a hybrid parareal algorithm.
- Our approach reduces the CPU time of a Monte-Carlo simulation.

#### **Ongoing work:**

Extension to Boltzmann equation in neutronics



J. DABAGHI, Y. MADAY, A. ZOIA, A hybrid parareal Monte-Carlo algorithm for the parabolic time dependant diffusion equation. IN PREPARATION

## Thank you for your attention!

