

1.3 Mode

The following three modes are available for YRC1000micro.

- Teach Mode
- Play Mode
- Remote Mode

1.3.1 Teach Mode

In the teach mode, the following can be done.

- Preparation and teaching of a job
- Modification of a registered job
- Setting of various characteristic files and parameters

1.3.2 Play Mode

In the play mode, the following can be done.

- Playback of a taught job

1.3.3 Remote Mode

In the remote mode, the operations such as Servo ON Ready, Start, Cycle Change, Call Master Job can be commanded by external input signals.

The operations by external input signals become enabled in the remote mode, while [START] on the programming pendant becomes disabled.

The data transmission function (optional function) is also available in the remote mode.

The following table shows how each operation is input in each mode.

Operation	Mode	Teach Mode	Play Mode	Remote Mode
Servo ON Ready		PP	PP	External input signal
Start		Invalid	PP	External input signal
Cycle Change		PP	PP	External input signal
Call Master Job		PP	PP	External input signal

Note: "PP" indicates the programming pendant.

1.3.4 Teach Mode Priority

In the teach mode, the following operations are disabled.

- Playback using [START]
- Playback from external input signals