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LIDAR-Lite v3 Hookup Guide

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Introduction

Note: While this guide was written primarily for the LIDAR-Lite v3, it can be used for the LIDAR-Lite v3HP.

The LIDAR-Lite Series - the v3 and v3HP - are compact optical distance measurement sensors, which are ideal for drones and unmanned vehicles.



LIDAR-Lite v3

● SEN-14032

\$129.99

★★★★☆ 24



LIDAR-Lite v3HP

© SEN-14599

\$149.99

★★★★☆ 6

LIDAR is a combination of the words "light" and "RADAR." Or, if you'd like, a backronym for "LIght Detection and Ranging" or "Laser Imaging, Detection, and Ranging." At it's core, LIDAR works by shooting a laser at an object and then measuring the time it takes for that light to return to the sensor. With this, the distance to the object can be measured with fairly good accuracy.

By sweeping or spinning a LIDAR unit, systems can create detailed distance maps. Survey equipment, satellites, and aircraft can be equipped with complex LIDAR systems to create topographic maps of terrain and buildings. Luckily, Garmin[™] has created a user-friendly LIDAR unit for your robotics and DIY needs!

Note that these use a Class 1 Laser, if you are concerned about your safety (in short: A Class 1 laser is safe under all conditions of normal use).

CLASS 1 LASER PRODUCT CLASSIFIED EN/IEC 60825-1 2014. This product is in conformity with performance standards for laser products under 21 CFR 1040, except with respect to those characteristics authorized by Variance Number FDA-2016-V-2943 effective September 27, 2016.

Suggested Viewing

What is the difference between the LIDAR-Lite v3 and the LIDAR-Lite v3HP? Let's ask Shawn Hymel!

Product Showcase: LIDAR-Lite v3HP



Required Materials

To follow along with this project tutorial, you will need the following materials:

LIDAR-Lite v3 Hookup Guide SparkFun Wish List



USB micro-B Cable - 6 Foot

CAB-10215

USB 2.0 type A to micro USB 5-pin. This is a new, smaller connector for USB devices. Micro USB connecto...



Resistor Kit - 1/4W (500 total)

COM-10969

Resistors are a good thing, in fact, they're actually crucial in a lot of circuit designs. The only problem seem...



SparkFun RedBoard Qwiic

DEV-15123



LIDAR-Lite v3

SEN-14032

It's back! This is the LIDAR-Lite v3, a compact, high-performance optical distance measurement sensor fro...



Breadboard - Self-Adhesive (White)

PRT-12002

This is your tried and true white solderless breadboard. It has 2 power buses, 10 columns, and 30 rows - a t...



Jumper Wires Premium 6" M/M Pack of 10

PRT-08431

This is a SparkFun exclusive! These are 155mm long jumpers with male connectors on both ends. Use thes...



Electrolytic Decoupling Capacitors - 1000uF/25V

COM-08982

Electrolytic decoupling capacitors 1000uF/25V. These capacitors are great transient/surge suppressors and...

Suggested Reading

If you aren't familiar with the following concepts, we recommend checking out these tutorials before continuing.

Installing an Arduino Library How do I install a custom Arduino library? It's easy! This tutorial will go over how to install an Arduino library using the Arduino Library Manager. For libraries not linked with the Arduino IDE, we will also go over manually installing an Arduino library.		erful world of breadboards. It a breadboard is and how to
What is an Arduino? What is this 'Arduino' thing anyway? This tutorials dives into what an Arduino is and along with Arduino projects and widgets.		DE o installing and testing the Vindows, Mac, and Linux.
I2C An introduction to I2C, one of the main embedded communications protocols in use today.		
Hardware Overview		
Differences Between v3 and v3HP		
Differences Between v3 and v3HP Functionally, the LIDAR-Lite v3 and LIDAR-Lite v3HP here:	are quite similar. The pri	mary differences are listed

Update Rate	500 Hz	> 1kHz
Current Consumption (idle)	105 mA	65 mA
Current Consumption (acquisition)	130 mA	85 mA
Casing	None	IPX7 rated casing

Note: An IPX7 rating means that the body of this device can withstand incidental exposure to water of up to 1meter for up to 30 minutes. The bare wire portion of the wiring harness is not water resistant. All bare wire connections must either be made in a water tight location or properly sealed.

Case

The LIDAR-Lite has two tubes on the front that contain a transmitter (laser) and receiver. You'll want to face these toward your target.



This step is only necessary for the LIDAR-Lite v3:

On the side, you'll find an electrical port that connects to the included 6-wire cable. Plug in the wire harness to the port to break out the pins.

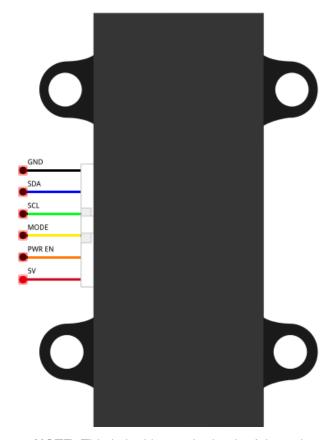


On the back, you'll find 4 mounting holes that are designed to accept #6 or M3.5 screws or bolts.



Wires

The LIDAR-Lite has 6 wires that can be used to communicate with the sensor.



NOTE: This is looking at the back of the unit

Color	Pin	Description
Red	5V	Power (5V)
Orange	PWR EN	Power enable (internal pullup)
Yellow	MODE	Mode control (for PWM mode)
Green	SCL	I ² C clock
Blue	SDA	I ² C data
Black	GND	Ground

Note: V3's pinout, default address I^2C (**0x62**), and overall functionality is the same as other versions. However, the connector and cable for the V3 are different compared to V3HP and V2.



LIDAR-Lite Accessory Cable

○ CAB-14043

\$4.95

 $\star\star\star\star$

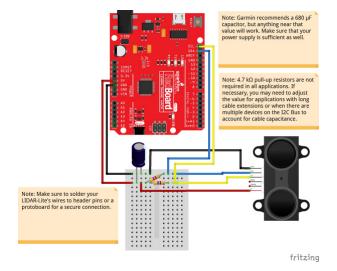
Power

Both the LIDAR-Lite v3 as well as the LIDAR-Lite v3HP units require between **4.5V to 5.5V** of DC power to operate (**nominally**, **5V**). The LIDAR-LITE v3 can draw up to 135 mA of current during continuous operation (105 mA at idle). Contrarily, the v3HP unit draws up to 85 mA of current during continuous operation (65 mA at idle). To maintain a level voltage, Garmin recommends putting a **680 µF capacitor** between power (5V) and ground (GND) as close to the LIDAR unit as possible.

✓ Note the difference in current draw! Be aware that while the input voltage for the LIDAR-Lite v3 and v3HP is the same, the current draw is different

Hardware Assembly

Follow the diagram below to connect the LIDAR unit to a RedBoard or other Arduino-compatible board. The LIDAR-Lite can communicate over I²C as well as use a pulse-width modulated (PWM) signal to denote measured distances. For this guide, we will show how to use I²C to communicate with the LIDAR unit.



Click on the image to enlarge it

Note: Garmin recommends a 680 µF capacitor, but anything near that value will work. I used a 1000 μF capacitor in this example. Make sure to add the electrolytic capacitor correctly to the circuit since it has a polarity.

You also may need I²C pull-up resistors for the SCL and SDA lines. It depends on the length between the Arduino and I^2C device but usually a $4.7k\Omega$ resistor is a good start. For long runs or systems with lots of devices, it is recommended to use smaller resistors. You can also use a I²C bus extender for distances beyond the maximum bus length as well.

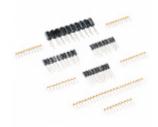


Resistor Kit - 1/4W (500 total)

○ COM-10969

\$7.95

★★★★ 176



SparkFun Capacitor Kit

O KIT-13698

\$7.95

★★★★ 10



Electrolytic Decoupling Capacitors -1000uF/25V

O COM-08982

★★★☆☆1



SparkFun Differential I2C Breakout -PCA9615 (Qwiic)

Ø BOB-14589

★ ★ ★ ★ 15 Retired

Software

Note: This example assumes you are using the latest version of the Arduino IDE on your desktop. If this is your first time using Arduino, please review our tutorial on installing the Arduino IDE. If you have not previously installed an Arduino library, please check out our installation guide.

Garmin maintains an Arduino library to make working with the LIDAR-Lite very easy. Visit the GitHub repository, or click the button below to download the library.

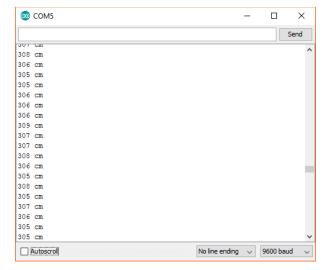
DOWNLOAD THE GARMIN LIDAR-LITE V3 ARDUINO LIBRARY

Open a new Arduino sketch, and copy in the following code:

```
/**
* LIDARLite I2C Example
 * Author: Garmin
 * Modified by: Shawn Hymel (SparkFun Electronics)
 * Date: June 29, 2017
 * Read distance from LIDAR-Lite v3 over I2C
 * See the Operation Manual for wiring diagrams and more information:
 * http://static.garmin.com/pumac/LIDAR Lite v3 Operation Manual and Technical Sp
ecifications.pdf
*/
#include <Wire.h>
#include <LIDARLite.h>
// Globals
LIDARLite lidarLite;
int cal cnt = 0;
void setup()
 Serial.begin(9600); // Initialize serial connection to display distance reading
 lidarLite.begin(0, true); // Set configuration to default and I2C to 400 kHz
 lidarLite.configure(0); // Change this number to try out alternate configuratio
ns
}
void loop()
 int dist;
 // At the beginning of every 100 readings,
  // take a measurement with receiver bias correction
 if ( cal_cnt == 0 ) {
   } else {
   dist = lidarLite.distance(false); // Without bias correction
  }
 // Increment reading counter
 cal_cnt++;
 cal cnt = cal cnt % 100;
 // Display distance
 Serial.print(dist);
 Serial.println(" cm");
 delay(10);
}
```

Upload the program, and open a Serial Monitor. You should see distance measurements (in cm) being

printed.



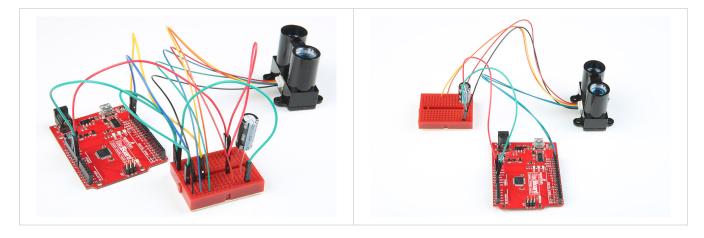
Troubleshooting

Arduino Output Error Poor Connection

Are you seeing this output from the LIDAR-Lite V3 I²C example code with the decoupling capacitors connected to the Arduino?

```
> nack
> nack
> nack
```

You probably do not have a secure connection between the Lidar and the Arduino. I²C is sensitive to its connection. The cable wires are thin and can disconnect when in the Arduino's female header from a bump. A breadboard seems to work fine if there is not a lot of mechanical vibrations. However, a small bump can mess up the timing for the I²C even on the breadboard.



For a secure connection, it is recommended soldering header pins with some heat shrink or make sort of adapter when connecting it to an Arduino. Once disconnected, the Arduino might stop outputting sensor data. You can reset the Arduino for testing but to prevent the wires from disconnecting, it would be better to solder the wires to header pins. This is a common "issue" with any I²C sensor and if they do not secure the wires, the Arduino will have problems talking with the Lidar Lite V3.



Break Away Headers - Straight

O PRT-00116

\$1.50

★★★★☆20



Heat Shrink Kit

O PRT-09353

\$7.95

★★★★↑7

Arduino Output Error 12C Pull-Up Resistors

Another reason for the nack error may be that you need I2C pull-up resistors for the SCL and SDA lines. It depends on the length between the Arduino and I²C device but usually a 4.7kΩ resistor is a good start. For long runs or systems with lots of devices, it is recommended to use smaller resistors. You can also use a I²C bus extender for distances beyond the maximum bus length as well.



Resistor Kit - 1/4W (500 total)

● COM-10969

\$7.95

★★★★ 176



SparkFun Differential I2C Breakout -PCA9615 (Qwiic)

Ø BOB-14589

★ ★ ★ ★ 15 Retired

Decoupling Capacitor

Looking for a 680µF capacitor? Unfortunately, the SparkFun catalog does not include a 680µF capacitor. There are 1000µF capacitors, which can work as a substitute with the Lidar Lite.

12/25/21, 14:44 11 of 15





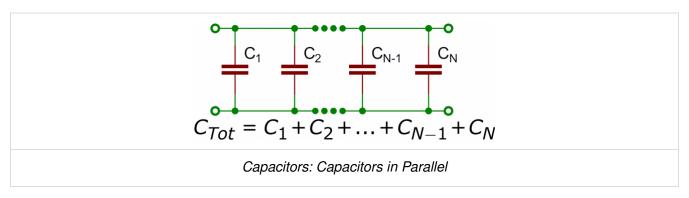
SparkFun Capacitor Kit ● KIT-13698 \$7.95 Electrolytic Decoupling Capacitors - 1000uF/25V

O COM-08982

★ ★ ★ ☆ 1

★★★★ 10

Or, you can also wire capacitors in series and parallel to get an equivalent capacitance.



Dimensions

For more details on the dimensions, check out the links below.

- V3 Top and Side Dimension
- V3HP Top Dimension

Product Showcase Example for LIDAR-Lite V3 Wand

Looking for the example code used in the product video for the LIDAR-LIte V3? Nick Poole basically used the same parts and example code that was used with the Lidar Lite V2 Glasses. For the Lidar Lite V3 Wand, he used the following components:

- LEDs
- · micro-B USB breakout
- micro-B USB Cable
- a backup portable cell phone charger
- 1kΩ resistor
- 5V/16 MHz Pro Micro

He happened to have a 5V/16 MHz Pro Micro around when building the project for the Lidar Lite V2 Glasses. The parts were reused for the Lidar Lite V3 Wand. Try looking at the old wishlist for the Lidar Lite V2 Glasses for more information. Make sure to also add a $1k\Omega$ resistor when using the PWM wiring as stated on page 3 of the user manual.

Additional Troubleshooting

Looking for additional troubleshooting tips and application notes related to the LIDAR Lite? Check out Garmin's support on the LIDAR Lite:

GARMIN SUPPORT: LIDAR LITE V3 AND V3HP

Application Notes on Reflective Surfaces

For more application notes on using the LIDAR-Lite v3/v3HP, check out the link below.

GARMIN SUPPORT: HOW THE LIDAR-LITE V3/V3HP WORKS WITH REFLECTIVE SURFACES

This can also be found in the operation & technical manual on page 11.

Resources and Going Further

Now that you've successfully got your LIDAR up and running, it's time to incorporate it into your own project! For more information, check out the resources below:

- Operation & Technical Manual
 - LIDAR-Lite v3 (PDF)
 - LIDAR-Lite v3HP (PDF)
- · Garmin's Product Page
 - LIDAR-Lite v3
 - LIDAR-Lite v3HP
- SparkFun Product Showcase
 - LIDAR-Lite Module Demo
 - GitHub Repo LIDAR-Lite Glasses Example Code used for the LIDAR-Lite Glasses and Lidar Lite V3 Wand
 - SparkFun Speed Trap
 - LIDAR-Lite V3 Demo
 - LIDAR-Lite v3HP
 - Large Digit Driver Hookup Guide Example: Speed Trap
 - GitHub Repo Speed Trap
 - GitHub Repository
 - Fritzing Diagram The old Fritzing Part can be found from this repository. The pinout is the same so it can be used to represent the LIDAR-Lite V3.
 - LIDAR-Lite V3/v3HP Arduino Library

Want to know more about how LIDAR works? Check out this great YouTube video:

Adventures in Science: LIDAR		
Need some inspiration for your next project? Check out some of these related tutorials:		
Large Digit Driver Hookup Guide Getting started guide for the Large Digit display driver board. This tutorial explains how to solder the module (backpack) onto the back of the large 7-segment LED display and run example code from an Arduino. ReconBot with the Tessel 2 Build a robot with the Tessel 2	ro	
Building an Autonomous Vehicle: The Batmobile Documenting a six-month project to race autonomous Power Wheels at the SparkFun		

Or check out these 3D Scanner projects using the LIDAR-Lite V3.

Autonomous Vehicle Competition (AVC) in 2016.

	LIDAR-Lite v3 - 3D-Scan	
	Rotating dense 3D point cloud of scanned room	
	eck out these related blog post.	
Adventures in Science: LIDAR		Distance Sensing: How Far Is It?

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