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**The Future of AI in Air Traffic
Management: Coordinating Autonomous
Airliners and UAM within Busy Airspaces
using AI**

SEMINAR PAPER

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The Future of AI in Air Traffic Management: Coordinating Autonomous Airliners and UAM within Busy Airspaces using AI

Affidavit

I certify that I have completed the work without outside help and without using sources other than those specified and that the work has not yet been submitted in the same or a similar form to any other examination authority and has been accepted by them as part of an examination. All statements that have been adopted literally or analogously are marked as such.

Ingolstadt, 6 May 2025

Signature

Abstract

The summary gives the reader a rough overview of the content (brief problem definition, approach, solution approaches and possibly key findings). The scope should be about half a page. This chapter is not mandatory and should only be considered optional.

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1 Introduction

1.1 Artificial Intelligence

Artificial intelligence (AI), along with its subfields machine learning (ML) and deep learning (DL), has emerged as fundamental tools in the modernisation and optimisation of various industries, including aviation [1]. ML involves the development of algorithms and models that enable computers to learn from data and make informed decisions without being explicitly programmed [1]. DL, a subset of ML, utilises artificial neural networks that mimic the structure and function of the human brain to process complex patterns and large datasets [1]. In combination with AI-driven tools such as natural language processing (NLP) and computer vision, , these tools are being integrated across a wide range of aviation applications, from flight operations and maintenance to passenger services and air traffic management [1].

1.2 Urban Air Mobility

According to European Union Aviation Safety Agency (EASA), urban air mobility (UAM) refers to an air transportation system for passengers and cargo in urban environments, with the transportation performed by an electric aircraft capable of vertical takeoff and landing (VTOL), either remotely piloted or with a pilot on board. Commercial operations in European cities are expected to begin as early as 2025, with initial applications focusing on drone-based goods delivery and passenger transport using piloted aircraft [2]. Several pilot projects are currently underway. European manufacturers such as Airbus, with its CityAirbus NextGen, and Volocopter, with its VoloDrone, are actively developing and testing aircraft designed for both passenger and cargo transport [3].

The anticipated benefits of UAM include faster and more sustainable transportation, reduced congestion, and extended urban connectivity. However, major concerns remain regarding safety, environmental impact, noise pollution, and cybersecurity. Public acceptance and user confidence will be critical factors for the successful implementation of UAM in Europe [4].

Currently, many UAM vehicles are in the development or testing phase, with a long-term objective of achieving fully autonomous operations using unmanned aerial vehicles (UAVs) [5].

1.3 Autonomous Airlines

Autonomous airliners represent a branch of UAVs, consisting of fixed-wing aircraft capable of flying and navigating without direct intervention of a human pilot. Although modern commercial airliners already automate approximately 93% of flight functions, such as autopilot systems and automatic dependent surveillance-broadcast (ADS-B), there remains a growing demand to implement higher levels of autonomy. Increased automation is seen as a path toward enhanced safety, greater scalability, and improved affordability.

Human error is cited as the leading cause in approximately 80% of general aviation accidents. As a result, the vision for autonomous airliners includes minimising single points of failure in both design and operation by removing the human from direct aviate-navigate-communicate roles and replacing them with reliable, intelligent automation [6].

While fully autonomous aircraft are technically feasible today, they have not yet been deployed for public use [6]. This limited adoption can be attributed to several key factors [7]:

- a) public acceptance rates remain below the 50% threshold typical for early adopters of innovative technologies,
- b) persistent public trust in the value of direct human pilot presence and intervention, and
- c) unresolved regulatory and cybersecurity concerns.

1.4 Air Traffic Management

Air traffic management (ATM) refers to the systems and services that ensure the safe and efficient movement of aircrafts during all phases of operations, through controlled airspaces and on the ground at airports [8]. It comprises several components, including air traffic control (ATC) (its main component), airspace management (ASM), air traffic flow management (ATFM), and air traffic service (ATS) [9].

Air traffic controllers (ATCOs) are responsible for directing aircraft safely and efficiently, managing takeoffs and landings, maintaining safe distances between aircraft en route and handling emergencies. Their role demands high levels of situational awareness, rapid decision-making, and the ability to manage multiple tasks under high stress conditions. These indispensable skills, such as judgement, flexibility and the ability to handle unexpected situations, remains critical and are not easily replicated by automated systems, despite advancements in digitalisation [10].

However, the rapid expansion of commercial aviation, UAM, and UAVs have significantly increased the complexity of ASM [11]. With air traffic volume increases, the

scalability of the system is limited by the finite capacity of ATCOs, who are subject to workload constraints and cognitive overload [12]. Fatigue and information overload have become key contributors to operational inefficiencies and potential safety risks [11]. Furthermore, human limitations in reaction time and decision-making speed highlight the need for intelligent, automated support systems that can enhance overall system performance.

Integrating UAM into air traffic flow poses a significant challenge due to their unique performance characteristics, which differ from those of fixed-wing aircraft. These differences can lead to suboptimal use of airport capacity [9]. Compounding the issue is the current shortage of ATCOs, alongside the long training periods required to qualify new personnel, this has amplified the demand for AI-based solutions in ATM. AI technologies are able to solve these challenges through real-time data processing, predictive analytics, and autonomous decision-making capabilities [11]. While some automations already exist in some areas [13], existing systems often rely on rigid rule-based frameworks and lack the flexibility and adaptability needed for dynamic environments [12].

The integration of UAV into ATM has led to the development of a new branch known as UAS traffic management (UTM). As UAVs often operate across both controlled and uncontrolled airspaces – and ATCOs are only responsible for controlled airspaces – a key challenge arises: there is no ATC service in uncontrolled airspaces. This lack of oversight increases the risk of mid-air collisions or accidents involving other UAVs, manned aircraft, ground vehicles, or natural and artificial obstacles. Therefore, a dedicated system like UTM is essential to ensure safe and efficient UAV operations in all types of airspace [14].

The integration of UAM and UTM into the existing ATM framework will not only stress current infrastructure but also require faster, more adaptive decision-making [15] – an area where AI technologies can provide substantial value.

This report explores the roles of AI in shaping the future of ATM, focusing particularly on its application to autonomous airliners and UAM integration.

2 Current Research Areas of AI in ATM

The rapid growth of global aviation presents significant challenges for ATC operations, with such being and not limited to airspace congestion and traffic complexity, human cognitive limitations in ATC operations, environmental and weather uncertainties, increasing demand for fuel efficiency and sustainability, and cybersecurity and safety risks. Together with UAM and UAVs, they have further complicated ASM. These challenges necessitate the integration of AI to assist human decision-making, improve overall efficiency, and ensure safety in these increasing complex air traffic environments [11].

The following subsections describe the current research areas of AI in ATM [11].

2.1 Real-Time Decision Support and Conflict Resolution

Decision support systems utilise advanced ML algorithms and neural networks to deliver real-time risk assessments and support dynamic decision making processing. Its ability to automate repetitive tasks and process real-time data assist ATCOs by offering precise risk evaluations and actionable recommendations, improving situational awareness [12].

In conflict detection and resolution, AI systems not only detect potential conflicts, but also generate appropriate resolutions that align with ATCOs' typical strategies [12]. Through reinforcement learning and multi-agent coordination, faster and more precise resolutions can be generated [11].

2.2 Predictive Analytics for Traffic Flow Optimisation

This is a research area where AI is explored to anticipate and manage air traffic demand, congestion, and delays more efficiently. AI algorithms can forecast traffic congestion patterns using historical and real-time flight data [11]. Trajectory and path planning utilises AI to enhance 4D trajectory planning by enabling real-time dynamic re-planning during flight, responding to weather, or airspace restrictions without manual interventions [12]. To tackle the arrival sequencing and scheduling problem (ASSP), techniques like time-based separation (TBS) and particle swarm optimisation (PSO) are used to optimise arrival order and timing, reducing delays at busy airports [12]. Developments in prediction systems relating to weather and environmental factors are done by combining radar and weather data, aiding in route planning and reducing weather-related delays [12] [16]. The use of Graph Neural Networks (GNNs) and Transformer models optimise airspace sectorisation dynamically.

2.3 Intelligence Communication Between Pilots and Controllers

AI-driven speech recognition systems (e.g. large language model (LLM)-powered) transcribe and interpret ATC communications. With Automatic Speech Recognition (ASR), it generates information table by processing voice communication transcripts, which serves as references for producing potential taxi plans and calculating the surface movement collision risk [17].

Such models like OpenAI o3 and Gemini 2.0 reduce misunderstandings and improve controller-pilot interactions [11].

2.4 AI-Driven Automation for UAS

Autonomous UTM (aUTM) is enabled with AI, preventing conflicts between manned and unmanned aircrafts.

This is a rapidly growing research field, especially for integrating drones safely into controlled airspaces.

2.5 Enhancing Safety through AI-Powered Surveillance and Monitoring

AI is being researched to detect anomalies, monitor aircraft behaviour, and improve situational awareness using sensor fusion and video analytics.

AI-based radar and satellite tracking improve aircraft detection and monitoring. Computer Vision models analyse runway occupancy and ground movement for airport safety [11].

3 Vision of Future ATM

Future [18]

4 Challenges and Risks

Challenges [13]

5 Conclusion

Acronyms

ADS-B automatic dependent surveillance-broadcast. 2

AI artificial intelligence. 1, 3–5

ASM airspace management. 2, 3

ASR Automatic Speech Recognition. 4

ASSP arrival sequencing and scheduling problem. 4

ATC air traffic control. 2–4

ATCO air traffic controller. 2–4

ATFM air traffic flow management. 2

ATM air traffic management. 2–4

ATS air traffic service. 2

aUTM autonomous UTM. 5

DL deep learning. 1

EASA European Union Aviation Safety Agency. 1

GNN Graph Neural Network. 4

LLM large language model. 4

ML machine learning. 1, 4

NLP natural language processing. 1

PSO particle swarm optimisation. 4

TBS time-based separation. 4

UAM urban air mobility. 1–3

UAV unmanned aerial vehicle. 1–3

UTM UAS traffic management. 3

VTOL vertical takeoff and landing. 1

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