Modal solution for a n2-profile

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1 Analytical solution of the wave equation in a n²-linear profile

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This code computes the analytic solution for a n^2 -linear profile, whose eigenfunctions are Airy functions.

1.1 Theoretical Background

1.1.1 Derivation

Consider the following Helmholtz equation in a two-dimensional coordinate system, as a function of range r and altitude z:

$$\left[\nabla^2 + k^2\right] p(r, z, \omega) = 0 \tag{1}$$

Here, $k(z) = \frac{\omega}{c(z)}$ is the medium wavenumber, where ω and c(z) correspond to the angular frequency $(\omega = 2\pi f)$ and sound speed, respectively. Separation in variables $(p(r,z) = \psi(z)e^{ik_Hr})$ leads to the following one-dimensional vertical wave equation:

$$\[\frac{d^2}{dz^2} + k^2 - k_H^2 \] \psi(z) = 0 \tag{2}$$

where k_H is the horizontal wavenumber. Note that the frequency dependence of $\psi(z)$ is kept implicit.

In the case of a n^2 -linear profile, the medium wavenumber squared has the form $k^2(z) = b - az$, where a and b are constants and z is the altitude. Substituting and rearranging leads to:

$$\left[\frac{d^2}{dz^2} - \left(az - b + k_H^2\right)\right]\psi(z) = 0 \tag{3}$$

It can be shown that this equation can be written in the form of the Airy equation:

$$\left[\frac{d^2}{d\zeta^2} - \zeta\right]\psi(\zeta) = 0\tag{4}$$

For this, we need a variable transformation $\zeta = \zeta(z)$. Consider $\alpha \zeta(z) = az - b + k_H^2 = k_H^2 - k^2(z)$, where α is a constant.

Using the chain rule:

$$\frac{d^2\psi(\zeta(z))}{dz^2} = \left(\frac{d\zeta}{dz}\right)^2 \frac{d^2\psi}{d\zeta^2} + \frac{d^2\zeta}{dz^2} \frac{d\psi}{d\zeta} = a_0 \frac{d^2\psi}{d\zeta^2} + a_1 \frac{d\psi}{d\zeta}$$
 (5)

where $a_0 = \left(\frac{d\zeta}{dz}\right)^2$ and $a_1 = \frac{d^2\zeta}{dz^2}$. From the definition of $\zeta(z)$, it follows that $a_0 = \left(\frac{a}{\alpha}\right)^2$ and $a_1 = 0$. Substituting Equation 5 in Equation 3 leads to:

$$\left[\left(\frac{a}{\alpha} \right)^2 \frac{d^2}{d\zeta^2} - \alpha \zeta \right] \psi(\zeta) = 0 \tag{6}$$

Solving $\left(\frac{a}{\alpha}\right)^2 = \alpha$ leads to $\alpha = a^{\frac{2}{3}}$ and thus:

$$a^{\frac{2}{3}} \left[\frac{d^2}{d\zeta^2} - \zeta \right] \psi(\zeta) = 0 \tag{7}$$

Omitting trivial solution a=0 leaves the homogeneous Airy equation. Independent solutions to the homogeneous Airy equation are a linear combination of the Airy functions $Ai(\zeta)$ and $Bi(\zeta)$ where:

$$\zeta(z) = a^{-\frac{2}{3}} \left[k_H^2 - k^2(z) \right] \tag{8}$$

so:

$$\psi_a(k_H, z) = Ai \left(a^{-\frac{2}{3}} \left[k_H^2 - k^2(z) \right] \right) \tag{9}$$

$$\psi_b(k_H, z) = Bi \left(a^{-\frac{2}{3}} \left[k_H^2 - k^2(z) \right] \right) \tag{10}$$

therefore, the total solution becomes:

$$\psi(k_H, z) = C_1 \psi_a(k_H, z) + C_2 \psi_b(k_H, z) \tag{11}$$

For the problem of interest, we require solutions to satisfy the following boundary conditions:

$$\frac{d\psi}{dz}\Big|_{z=0} = 0 \qquad \lim_{z \to \infty} \psi(k_H, z) = 0 \tag{12}$$

Airy functions $Ai(\zeta)$ satisfy these conditions, and therefore $C_2=0.$ C_1 is chosen to be one.

Phase and group speed

Phase velocity c_{ph} and group velocity c_g can be computed for each solution (k_H, ψ) as follows:

$$c_{ph} = \frac{\omega}{k_H} \tag{13}$$

$$c_g = \frac{k_H}{\omega \int_0^\infty \psi(k_H, z) dz} = \frac{1}{c_{ph} \int_0^\infty \psi(k_H, z) dz}$$
(14)

For each mode, the phase speed provides information on the local horizontal propagation speed while the group speed quantifies the average horizontal speed of the mode through the waveguide. The phase speed corresponds to the observed trace velocity, whereas the group speed corresponds to the celerity.

n^2 -linear Profile design

The two coefficients that determine a n^2 -linear profile, a and b, can be determined from two sound speed values at two altitudes, say at the bottom $(z_0 = 0 \text{ km})$ and the top (z_{max}) of the domain. From these points, we obtain a set of two equations that can be solved for the two unknown variables a and b.

Thus, we have for this c(z) profile the following values:

$$c(z_0) = c_0 (15)$$

$$c(z_{max}) = c_{max} (16)$$

So:

$$k^{2}(z_{0}) = \frac{\omega^{2}}{c^{2}(z_{0})} = b - az_{0}$$
 (17)

$$k^2(z_{max}) = \frac{\omega^2}{c^2(z_{max})} = b - az_{max}$$
 (18)

Combining and re-arranging leads to the following expressions for a and b:

$$a = \frac{k^2(z_0) - k^2(z_{max})}{z_{max} - z_0}$$

$$b = k^2(z_0) + az_0$$
(19)

$$b = k^2(z_0) + az_0 (20)$$

In most applications, $z_0 = 0$ km and b can be immediately determined from the sound speed on the ground.

Algorithm 1.3

```
[1]: import numpy as np
  from scipy.special import airy

[3]: %matplotlib inline
  import matplotlib.pylab as plt
```

1.3.1 Classes and methods

plt.rcParams['figure.dpi'] = 125

```
[4]: from numpy.polynomial.polynomial import polyval
     class Atmosphere(object):
         def __init__(self):
             return
         def get_n2_profile(self,**kwargs):
             z = self.z
             z0 = self.z_min
             z1 = self.z max
             k0 = self.omega/self.c_min
             k1 = self.omega/self.c_max
             a = (k0**2 - k1**2)/(z1 - z0)
             b = k0**2 + a*z0
             c = self.omega/np.sqrt(b-a*z_)
             k2 = (self.omega/c)**2
             # Generate atmospheric state variable profiles
             gamma = 1.4
             R_{universal} = 8.31446261815324
             molar_mass_air = 0.0289644
             R_specific = R_universal/molar_mass_air
             rho = self.get_toy_density_profile()
             T = c**2 / (gamma*R_specific)
             P = rho*R specific*T
             self.profile = { 'type': 'n**2 linear profile',
                              'a_coeff': float(a),
                              'b_coeff': float(b),
                              'c': c,
                              'k2': k2,
                              'rho': rho,
                              'P': P,
                               'T': T
                            }
             return
         def get_toy_density_profile(self):
```

```
z_{-} = self.z
    rho_0 = 1.225
    A = np.array([-3.9082017E-02, -1.1526465E-03,
                    3.2891937E-05, -2.0494958E-07,
                   -4.7087295E-02, 1.2506387E-03,
                   -1.5194498E-05, 6.5818877E-08])
   B = np.array([-4.9244637E-03, -1.2984142E-06,
                   -1.5701595E-06, 1.5535974E-08,
                   -2.7221769E-02, 4.2474733E-04,
                   -3.9583181E-06, 1.7295795E-08])
   Pa_coeff = A[:4]
   Pb\_coeff = B[:4]
   Pa_coeff = np.insert(Pa_coeff, 0, 0)
   Pb_coeff = np.insert(Pb_coeff, 0, 1)
   rho = rho_0*10**(polyval(z_/1e3,Pa_coeff)/polyval(z_/1e3,Pb_coeff))
   return rho
def write_profile(self,fid):
   z_ = self.z/1e3
   u = np.zeros(self.z.shape)
   v = u
   w = u
   T = self.profile['T']
   rho = self.profile['rho']/1e3
   P = self.profile['P']/1e2
   line = np.c_[z_, u, v, w, T, rho, P]
   line_fmt = '%9.3f %8.3f %8.3f %8.3f %10.3f %11.4e %11.4e'
   np.savetxt(fid, line, fmt=line_fmt)
   return
```

```
return
def set_altitude_grid(self):
    Build altitude grid based on the wavelength of the signal
    A good choice is to take 10 samples per wavelength
    self.dz = 2*np.pi/self.k0/10
    self.z = np.arange(self.z_min,self.z_max+self.dz,self.dz)
    self.z max = self.z[-1]
    self.nz = len(self.z)
    self.nzrcv = int(np.floor(self.zrcv/self.dz))
    self.nzsrc = int(np.floor(self.zsrc/self.dz))
def set_range_grid(self):
   11 11 11
    Build range grid based on the wavelength of the signal
    A good choice is to take 10 samples per wavelength
    HHHH
    r_min = self.dr
    r_max = self.r_max + self.dr
    self.r = np.arange(r_min, r_max, self.dr)
    self.nr = len(self.r)
def compute_transmission_loss(self, p):
    return 20.0*np.log10(np.abs(4*np.pi*p))
```

```
[6]: from scipy.optimize import root_scalar
from tqdm.notebook import trange, tqdm

class Modes(Propagation):
    def __init__(self):
        return

def compute_airy_zeta(self, kH, k2):
        a_coeff = self.profile['a_coeff']
        zeta = (kH**2 - k2) / a_coeff**(2./3)
        return zeta

def compute_airy_function_argument(self, kH):
    """

    Computes the argument to the Airy function (Ai),
    i.e. zeta, as defined in the theoretical background.
    """
    zeta = self.compute_airy_zeta(kH, self.profile['k2'])
    return zeta
```

```
def compute_airy_bndcnd(self, kH):
    Helper function to find roots, called from find_modes()
    zeta = self.compute_airy_zeta(kH, self.profile['k2'][0])
    ai, aip, bi, bip = airy(zeta)
    return aip
def compute_airy_ground(self, kH):
    Returns the Airy function on the ground for a given
    wavenumber kH
    11 11 11
    zeta = self.compute_airy_zeta(kH, self.profile['k2'][0])
    ai, aip, bi, bip = airy(zeta)
    return ai
def compute_airy_eigenfunction(self, kH):
    Compute the normalized eigenfunction for a given mode
    with eigenvalue kH
    11 11 11
    zeta = self.compute_airy_zeta(kH, self.profile['k2'])
    ai, aip, bi, bip = airy(zeta)
    ain = self.normalize function(ai)
    return ain
def normalize_function(self, psi):
    Helper function to normalize mode shape functions using
    orthonormality relation
    psi_norm = np.sqrt(np.trapz(psi*psi, dx=self.dz))
    return psi / psi_norm
def find_modes(self):
    Find modes of waveguide by looking at roots of derivative
    of Airy function Brent's method is used to look at roots
    within wavenumber interval [a, b]
    self.kH_modes = []
    self.psi_modes = []
    for ikh in tqdm(range(0,len(self.kH)-1)):
        a = self.kH[ikh]
        b = self.kH[ikh+1]
```

```
try:
            sol = root_scalar(self.compute_airy_bndcnd,
                              bracket=[a, b],
                              method='brentq')
            kH_mode = sol.root
            #print('Mode isolated at {:6.2f}'.format(self.omega/sol.root))
            self.kH_modes.append(kH_mode)
            self.psi_modes.append(self.compute_airy_eigenfunction(kH_mode))
        except ValueError as e:
            #print('No mode found [ {} ]'.format(e))
            pass
    self.psi_modes = np.array(self.psi_modes)
    self.kH_modes = np.array(self.kH_modes)
    self.n_modes = len(self.kH_modes)
    print('{:d} mode(s) found!'.format(self.n_modes))
    return
def compute_phase_group_speeds(self):
    Compute phase and group speed for a given eigenpair
    cph_j = omega/kH_j
    cg_j = 1./0 / cph_j*int_0^z_max psi_j^2/c_eff^2 dz
    self.cph_modes = self.omega/self.kH_modes
    self.cg_modes = np.zeros(self.cph_modes.shape)
    for ikh in tqdm(range(0,self.n_modes)):
        psi = self.psi_modes[ikh,:]
        c = self.profile['c']
        integral = np.trapz(psi**2/c**2, dx=self.dz)
        self.cg_modes[ikh] = 1.0/(self.cph_modes[ikh]*integral)
    return
def compute_modal_sum(self):
    Computes modal sum for a selection of eigenpairs
    HHHH
    (rr, _) = np.meshgrid(self.r, self.z)
    prefix = np.exp(-1j*np.pi*0.25)*np.sqrt(1./8./np.pi/rr)
    modal sum = 0
    for m in range(0,self.n_modes):
        psi = ( np.repeat(self.psi_modes[m,:], self.nr
                         ).reshape(self.nz, self.nr) )
        kH = self.kH_modes[m]
```

```
modal_sum += psi[self.nzsrc,0]*psi*np.exp(1j*kH*rr)/np.sqrt(kH)
return prefix*modal_sum
```

1.3.2 Main program: A modal expansion for the n^2 -linear profile as numerical solution

```
[7]: # Set up propagation object and set attributes
     pm = Modes()
     pm.freq = 0.4
     pm.c_0 = 340.0
     pm.zrcv = 0.0*1e3
     pm.zsrc = 2.0*1e3
     pm.z_min = 0.0
     pm.z_max = 25.0*1e3
     pm.c_min = 330.0
     pm.c_max = 450.0
     pm.dr = 0.5e3
     pm.r_min = pm.dr
     pm.r_max = 1000.0*1e3
     pm.cph_min = 330.0
     pm.cph_max = 440.0
     pm.dcph = 0.5
```

```
[8]: pm.set_parameters()
    pm.set_altitude_grid()
    pm.set_range_grid()
```

1.3.3 Plotting sound speed profile

Using the two sound speed datapoints, it is now possible to generate a n^2 -linear profile. The a and b coefficients are also stored for analysis and later use, as the a parameter appears in the argument of the Airy function $Ai(\zeta)$.

From the form of the sound speed profile $c(z)=\frac{\omega}{\sqrt{b-a*z}}$, it follows that the sound speed at z=0 is $c(z=0)=\frac{\omega}{\sqrt{b}}$ while the function has a vertical asymptote at $z=\frac{b}{a}$, i.e. $\lim_{z\to\frac{b}{a}}c(z)=\infty$

At the altitude of the vertical asymptote, the medium wavenumber squared is 0.

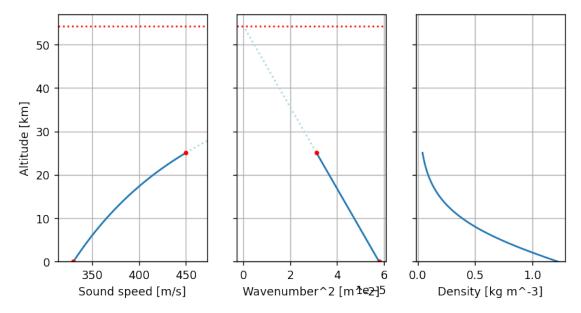
```
[9]: pm.get_n2_profile()
    a=pm.profile['a_coeff']
    b=pm.profile['b_coeff']
    z_asymptote = b/a
    print('n2-linear a-coefficent is {:15.8e} (s^2/m^3)'.format(a))
```

```
print('n2-linear b-coefficent is {:15.8e} (s^2/m^2)'.format(b))
      print('')
      print('Sound speed at z = 0 km is {:6.2f} m/s'.format(pm.omega/np.sqrt(b)))
      print('The vertical asymptote of the sound speed profile is found at altitude {:

→6.2f} km'.format(z_asymptote/1e3))
     n2-linear a-coefficent is 1.06920682e-09 (s^2/m^3)
     n2-linear b-coefficent is 5.80031847e-05 (s^2/m^2)
     Sound speed at z = 0 \text{ km} is 330.00 m/s
     The vertical asymptote of the sound speed profile is found at altitude 54.25 km
[10]: fig, ax = plt.subplots(1, 3, figsize=(8, 4), sharey=True)
      z_tmp = np.arange(pm.z_min,z_asymptote,pm.dz)
      c tmp = pm.omega / np.sqrt(b-a*z tmp)
      k2\_tmp = b-a*z\_tmp
      # plot sound speed
      ax[0].plot(c_tmp,z_tmp/1e3, color='lightblue', linestyle=':')
      ax[0].plot(pm.profile['c'],pm.z/1e3)
      ax[0].plot(pm.c_min,pm.z_min/1e3,'.r')
      ax[0].plot(pm.c_max,pm.z_max/1e3,'.r')
      ax[0].axhline(y=z_asymptote/1e3, color='r', linestyle=':')
      ax[0].set_xlim(pm.c_min*0.95,pm.c_max*1.05)
      ax[0].set_ylim(pm.z_min/1e3,1.05*z_asymptote/1e3)
      ax[0].set_xlabel('Sound speed [m/s]')
      ax[0].set_ylabel('Altitude [km]')
      ax[0].grid()
      # medium wavenumber
      k2 max = (pm.omega/pm.c min)**2
      k2_min = (pm.omega/pm.c_max)**2
      ax[1].plot(k2_tmp,z_tmp/1e3, color='lightblue', linestyle=':')
      ax[1].plot(pm.profile['k2'],pm.z/1e3)
      ax[1].plot(k2_max,pm.z_min/1e3,'.r')
      ax[1].plot(k2_min,pm.z_max/1e3,'.r')
      ax[1].axhline(y=z_asymptote/1e3, color='r', linestyle=':')
      ax[1].set_xlabel('Wavenumber^2 [m^-2]')
      ax[1].grid()
      # medium wavenumber
      k2 max = (pm.omega/pm.c min)**2
      k2_min = (pm.omega/pm.c_max)**2
      z_tmp = np.arange(pm.z_min,z_asymptote+pm.dz,pm.dz)
```

 $k2_tmp = b-a*z_tmp$

```
ax[2].plot(pm.profile['rho'],pm.z/1e3)
ax[2].set_xlabel('Density [kg m^-3]')
ax[2].grid()
plt.show()
```



1.3.4 Write out profile to disk

This routine writes the profile to a standard 1-D atmosphere format that can be used with NCPA-prop.

```
[11]: pm.write_profile('profile_n2.dat')
```

1.3.5 Analysis of the vertical solution

Recall that the variable of the Airy function reads:

$$\zeta = a^{-\frac{2}{3}} [k_H^2 - k^2(z)] = \frac{k_H^2 + az - b}{a^{\frac{2}{3}}}$$
 (21)

We can now visualize the behavior of the vertical solution as a function of horizontal wavenumber k_H .

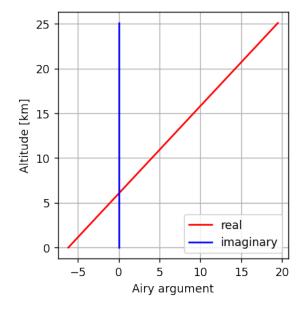
```
[12]: c_ph = 350.0

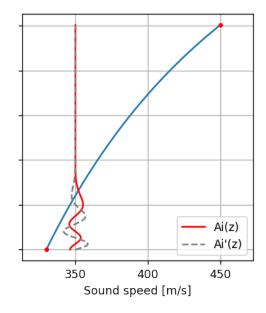
idx = (np.abs(pm.cph - c_ph)).argmin()
kH = pm.kH[idx]
```

```
c_ph = pm.cph[idx]
print('Computing vertical solution with phase speed: {:6.2f} m/s'.format(c_ph))
airy_arg = pm.compute_airy_function_argument(kH)
ai, aip, bi, bip = airy((airy_arg))
```

Computing vertical solution with phase speed: 350.00 m/s

```
[13]: fig, ax = plt.subplots(1, 2, figsize=(8, 4), sharey=True)
      ax[0].plot(np.real(airy_arg),pm.z/1e3,'r', label='real')
      ax[0].plot(np.imag(airy_arg),pm.z/1e3,'b', label='imaginary')
      ax[0].set_xlabel('Airy argument')
      ax[0].set ylabel('Altitude [km]')
      ax[0].grid()
      ax[0].legend(loc='lower right')
      ax[1].plot(pm.profile['c'],pm.z/1e3)
      ax[1].plot(pm.c_min,pm.z_min/1e3,'.r', label='')
      ax[1].plot(pm.c_max,pm.z_max/1e3,'.r', label='')
      ax[1].plot(c_ph+ai*10,pm.z/1e3, color='red', label='Ai(z)')
      ax[1].plot(c_ph+aip*10,pm.z/1e3, linestyle='--', color='gray', label='Ai\'(z)')
      ax[1].set_xlim(0.95*pm.c_min,1.05*pm.c_max)
      ax[1].set_xlabel('Sound speed [m/s]')
      ax[1].grid()
      ax[1].legend(loc='lower right')
      plt.show()
```





1.3.6 Finding the modes: finding the zero-crossings for the Airy derivative

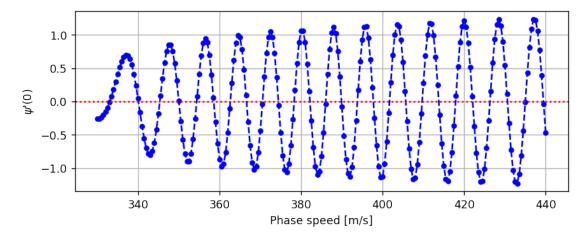
Recall that vertical solutions that satisfy the following boundary conditions are eigenfunctions.

$$\frac{d\psi}{dz}\Big|_{z=0} = 0 \qquad \lim_{z \to \infty} \psi(k_H, z) = 0 \tag{22}$$

By evaluating $\frac{d\psi}{dz}\Big|_{z=0}$ for the range of wavenumbers in our domain, it is possible to identify the modes as the wavenumbers for which the value of $\frac{d\psi}{dz}$ changes sign.

As all Airy functions under consideration decay for $k_H>k(z)$, the boundary condition $\lim_{z\to\infty}\psi(k_H,z)=0$ is satisfied for all wavenumbers k_H considered here.

```
[14]: boundary_condition = pm.compute_airy_bndcnd(pm.kH) solution_ground = pm.compute_airy_ground(pm.kH)
```



A root-finding routine (that makes use of Brent's method) is used to find the positions where the derivative of the Airy function changes sign. The routine returns the eigenpairs as part of the object, where pm.kH_modes and pm.psi_modes contain the eigenvalues and the eigenfunctions, respectively.

```
[16]: pm.find_modes()
```

```
0%| | 0/220 [00:00<?, ?it/s]
```

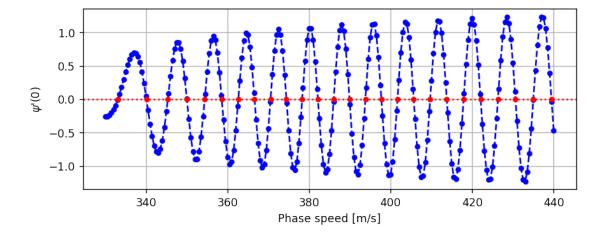
26 mode(s) found!

Using the eigenpairs, the phase speed c_{ph} and group speed c_g are computed. These are stored in the pm.cph_modes and pm.cg_modes arrays, respectively

```
[17]: pm.compute_phase_group_speeds()
```

```
0%| | 0/26 [00:00<?, ?it/s]
```

The wavenumbers can now be plotted on top of the derivative versus phase speed curve, to verify that these are indeed at locations where the derivative of the airy function changes sign.

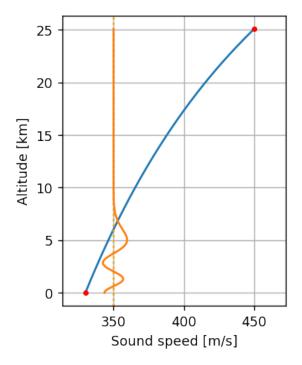


```
[19]: c_ph = 350.0

idx = (np.abs(pm.cph_modes - c_ph)).argmin()
mode_ = pm.psi_modes[idx,:]
```

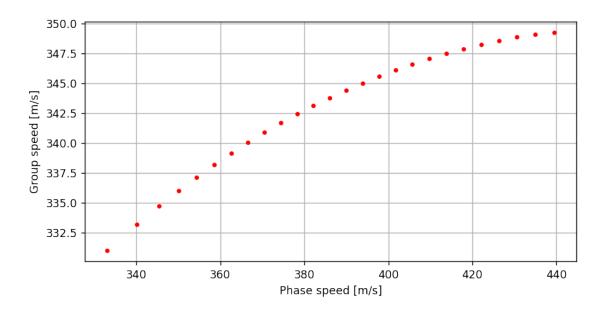
```
c_ph_ = pm.cph_modes[idx]
```

```
[20]: fig=plt.figure(figsize=(3,4))
   plt.plot(pm.profile['c'],pm.z/1e3)
   plt.plot(pm.c_min,pm.z_min/1e3,'.r')
   plt.plot(pm.c_max,pm.z_max/1e3,'.r')
   ax = fig.gca()
   ax.axvline(x=c_ph_, color='orange', linestyle=':')
   ax.plot(c_ph_+mode_*5e2,pm.z/1e3)
   ax.set_xlim(0.95*pm.c_min,1.05*pm.c_max)
   ax.set_xlabel('Sound speed [m/s]')
   ax.set_ylabel('Altitude [km]')
   plt.grid()
   plt.show()
```



1.3.7 Phase speed versus group speed

```
[21]: fig=plt.figure(figsize=(8,4))
    plt.plot(pm.cph_modes,pm.cg_modes,'.r')
    ax = fig.gca()
    ax.set_xlabel('Phase speed [m/s]')
    ax.set_ylabel('Group speed [m/s]')
    plt.grid()
    plt.show()
```



1.3.8 Discrete spectrum and acoustic field

In general, the total field consists of a contribution from the discrete spectrum and the continuum integral. In the case of ground-to-ground propagation over rigid ground, the former corresponds to the downward refracting field, the latter represents the field in the near-field, i.e. the region above the source.

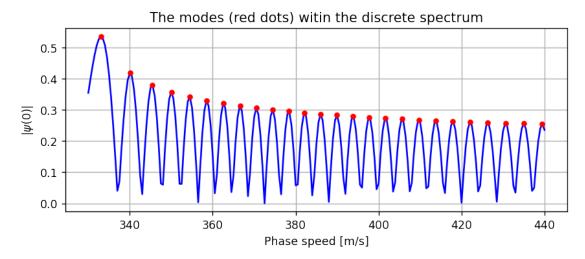
$$\hat{p}(r,z,\omega) = \underbrace{\frac{e^{-i\frac{\pi}{4}}}{\sqrt{8\pi r}} \sum_{j=1}^{N} \psi_j(z) \psi_j(z_{src}) \frac{e^{ik_{H,j}r}}{\sqrt{k_{H,j}}}}_{\text{discrete sum}} + \underbrace{\oint_{\mathcal{BC}} \psi(z,k_H) e^{ik_H r} dk_H}_{\text{discrete sum}}$$
(23)

At longer ranges, the continuum integral can be neglected and the field is completely described by the discrete spectrum, i.e. by the modal sum. Using the set of eigenpairs $(k_{H,j}, \psi_j(z))$ we can now compute the Green's function and the transmission loss.

As the vertical part of the solutions are Airy functions, it is straightforward now to compute the full spectral solution for the bracketed wavenumbers and plot the modes as red dots.

It can be seen that the modes correspond to the peaks of the spectral solution. Note that in the case of a wavenumber integration or FFP code, an integration is performed along the blue curve.

```
ax.set_title('The modes (red dots) witin the discrete spectrum')
ax.set_xlabel('Phase speed [m/s]')
ax.set_ylabel('|$\psi$(0)|')
ax.grid()
```



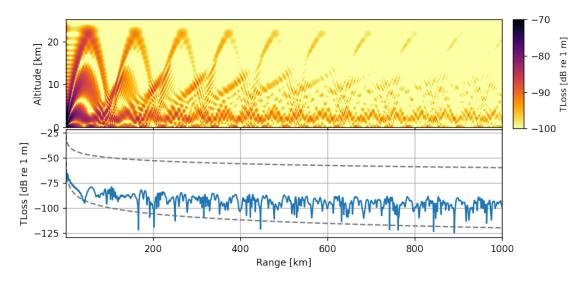
```
[23]: p = pm.compute_modal_sum()
tl = pm.compute_transmission_loss(p)
tl_rcv = tl[pm.nzrcv,:]
```

It can be useful to compute the transmission loss for Green's functions for spherical spreading (no duct) and cylindrical spreading (ideal duct), to be included as bounds when plotting the transmission loss as a function of range and altitude

```
[24]: # Compute Transmission loss
tl_spherical = 10*np.log10(1./pm.r)
tl_cylindrical = 20*np.log10(1./pm.r)
```

```
cbar = fig.colorbar(im, cax=cb_ax)
cbar.set_label(label='TLoss [dB re 1 m]', size=9)

ax[1]
ax[1].plot(pm.r/1e3, tl_spherical, linestyle='--', color='gray')
ax[1].plot(pm.r/1e3, tl_cylindrical, linestyle='--', color='gray')
ax[1].plot(pm.r/1e3, tl_rcv)
ax[1].grid()
ax[1].set_xlabel('Range [km]')
ax[1].set_ylabel('TLoss [dB re 1 m]')
plt.show()
```



1.3.9 Data output

Write out ground transmission loss curve to be compared with other models

```
[26]: np.savetxt('tl_analytic.dat', np.c_[pm.r/1e3, tl_rcv], fmt='%6.1f %9.3f')

[]:
```