

CSE 2421

Array and Structure Storage and Access



Today

- ▶ Arrays
 - One-dimensional
 - Multi-dimensional (nested)
 - Multi-level
- ▶ Structures
 - Allocation
 - Access
 - Alignment

Pointer arithmetic

- If p is a pointer to data type T
- And, the value of p (i.e., an address) is x_p
- Then, then $p+i$ has value $x_p + L*i$
 - where, L is the size of data type T
- Thus for an array A of elements, $A[i] == *(A+i)$

► Example

- `int E[10]; /*Assume int is 4 bytes long */`
- Suppose `rdx` holds starting address of array `E`
- Suppose `rcx` holds integer index `i`

C expression	Type	Assembly code... result in <code>eax</code>	Comment
<code>E</code>	<code>int *</code>	<code>movq %rdx, %rax</code>	
<code>E[i]</code>	<code>int</code>	<code>movl (%rdx,%rcx,4),%eax</code>	Reference memory
<code>&(E[i])</code>	<code>int *</code>	<code>leaq (%rdx,%rcx,4),%rax</code>	Generate address
<code>E+i-1</code>	<code>int *</code>	<code>leaq -4(%rdx,%rcx,4),%rax</code>	Generate address
<code>*(E+i-3)</code>	<code>int</code>	<code>movl -12(%rdx,%rcx,4),%eax</code>	Reference memory

Arrays

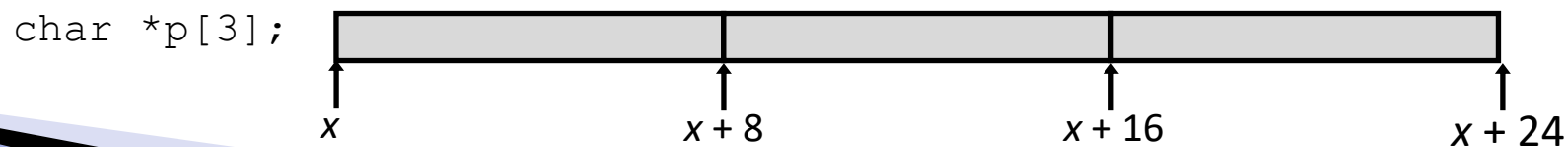
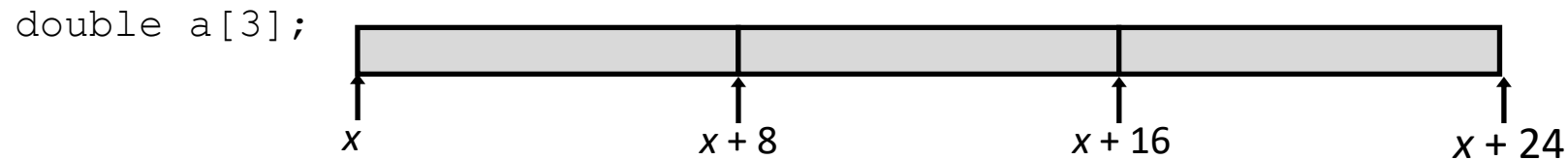
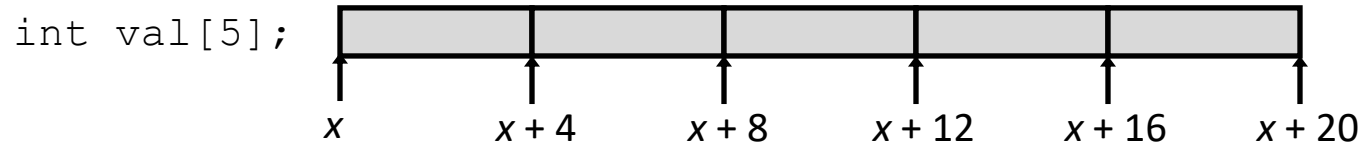
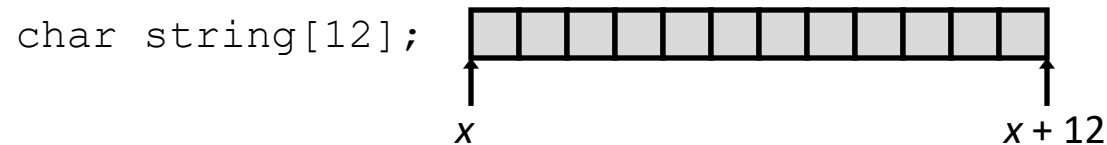
- ▶ C declaration: *type* array[length]
- ▶ Arrays are means for storing multiple data objects of the same type
- ▶ Stored sequentially, often accessed as an offset from a pointer which points to the beginning of the array.
 - $\text{size} = \text{length} * \text{sizeof}(\text{type})$
- ▶ If x is the address of the first byte of the first element in the array, then array element i will be stored at address $x + \text{sizeof}(\text{type}) * i$

Array Allocation

► Basic Principle

$T \ A[L];$

- Array of data type T and length L
- Contiguously allocated region of $L * \text{sizeof}(T)$ bytes in memory

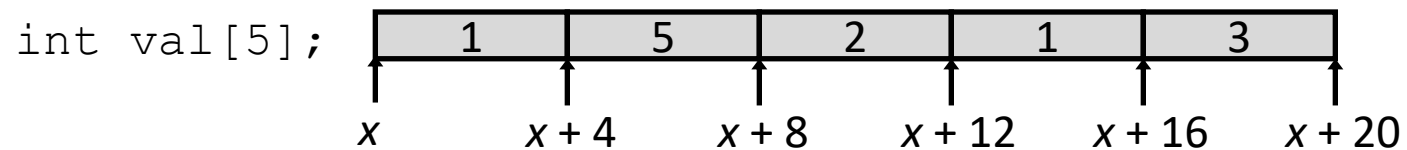


Array Access

► Basic Principle

T **A**[L] ;

- Array of data type T and length L
- Identifier **A** can be used as a pointer to array element 0: Type T^*

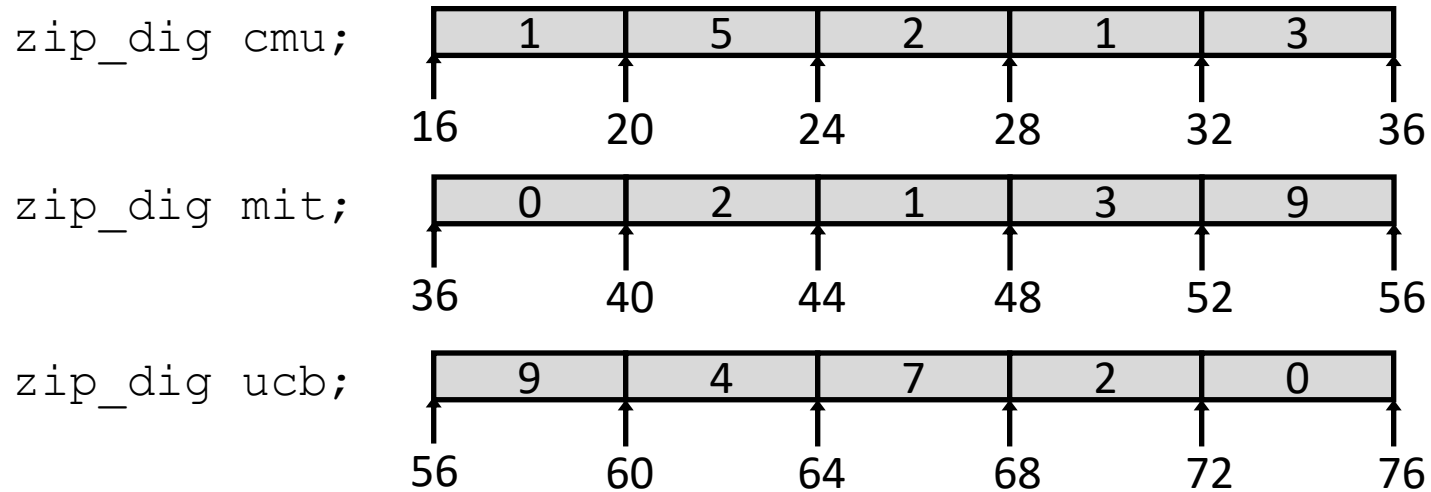


Reference	Type	Value
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	x
<code>val+1</code>	<code>int *</code>	$x + 4$
<code>&val[2]</code>	<code>int *</code>	$x + 8$
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5
<code>val + i</code>	<code>int *</code>	$x + 4i$

Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

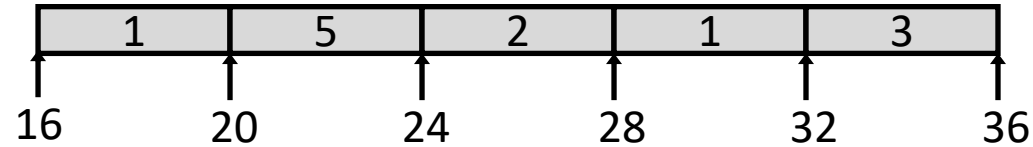
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



- ▶ Declaration “zip_dig cmu” equivalent to “int cmu[5]”
- ▶ Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

Array Accessing Example

zip_dig cmu;



```
int get_digit
(zip_dig z, int digit)
{
    return z[digit];
}
```

X86-64

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register `%rdi` contains starting address of array
- Register `%rsi` contains array index
- Desired digit at
 $\%rdi + 4 * \%rsi$
- Use memory reference $(\%rdi, \%rsi, 4)$
- use `movl` instruction to move 4 bytes
- Use 4 byte register `%eax`

Array Loop Example

```
void zincr(zip_dig z) {  
    size_t i;  
    for (i = 0; i < ZLEN; i++)  
        z[i]++;  
}
```

```
# %rdi = z  
movq    $0, %rax          # i = 0  
jmp     .L3               # goto middle  
.L4:                      # loop:  
    addl    $1, (%rdi,%rax,4) # z[i]++  
    addq    $1, %rax        # i++  
.L3:                      # middle  
    cmpq    $4, %rax        # i:4  
    jle     .L4             # if <=, goto loop  
ret                                # ret
```

Arrays – Example 1

- ▶ Consider the following C code:

```
static int x, array[30];  
x = array[25];
```

- ▶ Which is equivalent to assembly code:

REMINDER: \$ in assembly language with a label gives an address.
array and x must have been defined in the data segment (.data section) of the program.

<code>movq \$array, %rbx</code>	<code>#rbx is base register</code>
<code>movq \$25, %rcx</code>	<code>#rcx is index register</code>
<code>movl (%rbx,%rcx,4), %eax</code>	<code>#eax = array[25]</code>
<code>movl %eax, x</code>	<code>#x = array[25] Note: no \$ - Why?</code>

Arrays – Example 2 – dynamic arrays

C code:

```
int MyFunction1()  
{  
    int data[20];  
    ...  
}
```

MyFunction1:

```
pushq %rbp  
movq %rsp, %rbp  
subq $80,%rsp      #Allocate space for array on the stack: 20 elements,  
                   #4 bytes each  
leaq (%rsp), %rax  #using %rax as base register  
                   #OR movq %rsp, %rax  
...
```

Arrays – Example 3

C code

```
void MyFunction2()  
{  
    char buffer[12];  
    ...  
}
```

MyFunction2:

```
pushq %rbp  
movq %rsp, %rbp  
subq $12, %rsp          #allocate 12 bytes for array  
leaq (%rsp), %rax       #rax is base register  
                        #OR movq %rsp, %rax
```

...

Array – Example 3

MyFunction2:

pushq %rbp

movq %rsp, %rbp

subq \$12, %rsp

leaq (%rsp), %rax #OR movq %rsp, %rax

...

What happens if rcx has 16, and the code tries to access (%rax,%rcx,1)? For example, suppose dl has 5, and this instruction is executed:

movb %dl, (%rax,%rcx,1)

Array – Example 3

MyFunction2:

```
pushq %rbp
```

```
movq %rsp, %rbp
```

```
subq $12, %rsp
```

```
leaq (%rsp), %rax    #OR movq %rsp, %rax
```

...

What happens if rcx equals 16, and the code tries to access (%rax,%rcx,1)? For example, suppose %dl equals 5, and this instruction is executed:

```
movb %dl, (%rax,%rcx,1)
```

Buffer Overflow!

Arrays On the Stack – cont

- ▶ Look for large allocation on the stack
- ▶ Look for data references using a register other than `rsp/rbp` as the base

StackArrayEx:

```
pushq %rbp
```

```
movq %rsp, %rbp
```

```
subq $520, %rsp
```

```
pushq %rbx      # save callee-saved registers before use
```

```
leaq 8(%rsp), %rbx # the array is higher than pushed rbx
```

```
                # leaq -520(%rbp), %rbx also works
```

```
movl $0x0, (%rbx)    #set first element to 0
```

Arrays On the Stack – initialization

- ▶ For the dynamic array on the preceding slide, how could the compiler generate code for a loop to initialize all of the array elements to 0?

StackArrayEx:

```
    pushq %rbp
    movq %rsp, %rbp
    subq $520, %rsp           # make space for the array
    pushq %rbx                #push callee saved register
    leaq 8(%rsp), %rbx        #base register (array is above pushed rbx)
    movq $0, %rcx             #index register
```

initialize:

```
    cmpq $130, %rcx           # alternative loop saves 260 instructions
    je      next              # movq $129, %rcx
    movl $0x0, (%rbx,%rcx,4)   # backwards:
    incq    %rcx               # movl $0x0, (%rbx,%rcx,4)
    jmp     initialize         # decq %rcx
next:                          # jge backwards
```


Arrays On the Stack – cleanup

- ▶ For the dynamic array on the preceding slides, what needs to happen with respect to cleanup before return?

StackArrayEx:

```
pushq %rbp
movq %rsp, %rbp
subq $520, %rsp
pushq %rbx
leaq 8(%rsp), %rbx           #base register for array.
```

```
. . . . .                  #other code (omitted)
```

Return:

```
popq %rbx      # last thing we pushed, restore old value
movq %rbp, %rsp  # these 2 are the same as leave
popq %rbp
ret
```

Why order things in the stack that way?

- ▶ We put RBP, the array, and then the other callee-saved registers (RBX) in the stack in that order
- ▶ It makes cleanup simpler
 - The callee-saved registers (other than rbp) are at the top of the stack so we can pop them off in reverse order of the pushes without doing any math to figure out where they are
 - Then the leave instruction (or the 2 instruction equivalent) cleans up the array and gets the pushed RBP back in place – without caring about how many bytes were allocated for the array
- ▶ We paid for simple cleanup by having a more complex assignment for the array pointer
 - `leaq 8(%rsp), %rbx` #specific to this example –or–
 - `leaq -520(%rbp), %rbx` # general method for any allocated space
- ▶ Assumes we need to use a callee-saved register

Arrays on the heap

- ▶ “Global” Arrays
- ▶ Arrays of elements with initial values of 0 by default
 - If stored in the data section of application (i.e., static arrays)
- ▶ Accessed through a memory address

MemArrayEx:

```
pushq %rbp
movq %rsp, %rbp
pushq %rbx
pushq %r12
movq $staticArray, %r12    #base register
movq $0x0, %rbx             #index register
movl $0x0, (%r12,%rbx,4)    #set 1st element to 0
```

Arrays on the heap – alternative

- ▶ “Global” Arrays – the compiler knows where they go in the heap
- ▶ So a label is available to use for the address

MemArrayEx:

```
pushq %rbp
movq %rsp, %rbp
pushq %rbx
movq $0x0, %rbx           #index register
    # use the label as a displacement (no $)
    # and we won't need a base register
movl $0x0, staticArray(,%rbx,4) #set 1st element to 0
```

Arrays

- ▶ If an array holds elements larger than 1 byte, the index will need to be multiplied by the size of the element

#access to array of elements of size 4, with
#scaling, where rax holds the index i, and rbx is
#the base register:

#e.g., arr[i] = 11223344

```
movl $11223344, (%rbx,%rax,4)
```

...

Arrays of size larger than 8 bytes

- ▶ What if the array holds elements larger than 8 bytes? For example, what if it is an array of structures?
- ▶ Recall that, in x86-64, scaling factors are to 1, 2, 4, or 8
- ▶ Therefore, for arrays with elements larger than 8 bytes, manual scaling must be used

*#Here, two index registers are used, one
#for the conventional index (here, rcx),
#and one for a scaled index register,
#here, rax. This is "manual scaling."*

```
movq $0, %rcx
```

```
                # signed multiply
```

```
                # imulq aux, src, Dest
```

```
imulq $20,%rcx,%rax                # manually scale index
```

```
#Suppose we want: ptr = &arr[i]
```

```
leaq (%rbx,%rax), %rdx
```

Multidimensional (Nested) Arrays

► Declaration

$T \text{ } \mathbf{A}[R][C];$

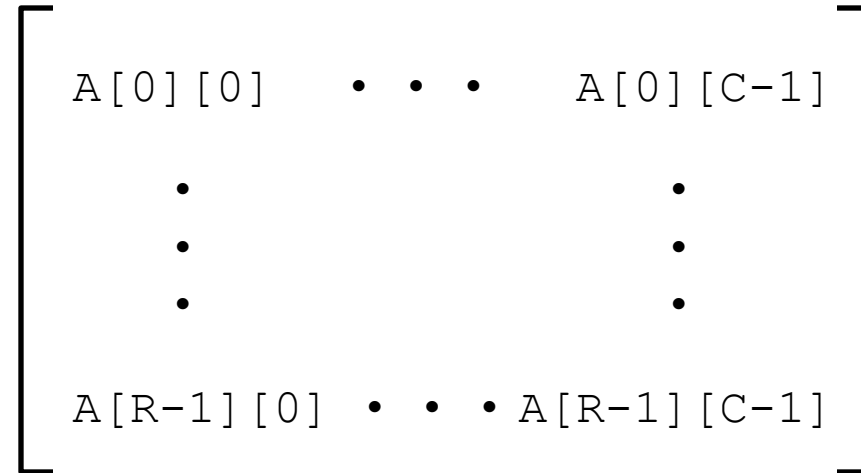
- 2D array of data type T
- R rows, C columns
- Type T element requires K bytes

► Array Size

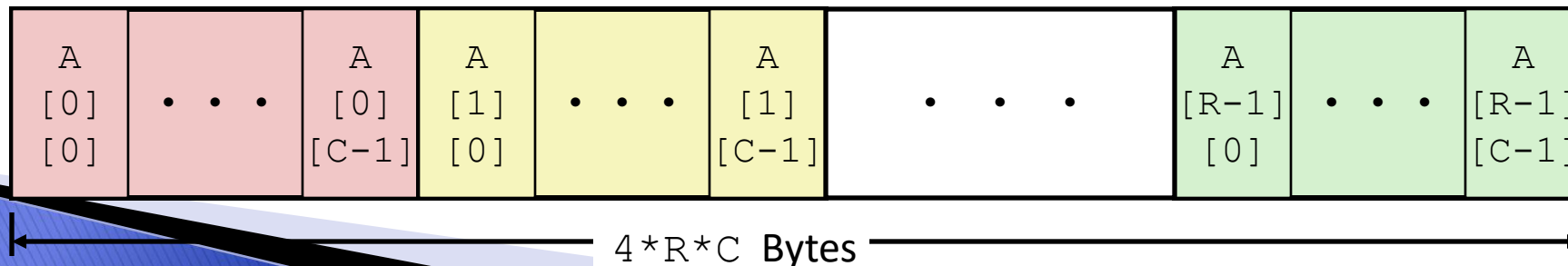
- $R * C * K$ bytes

► Arrangement

- Row-Major Ordering

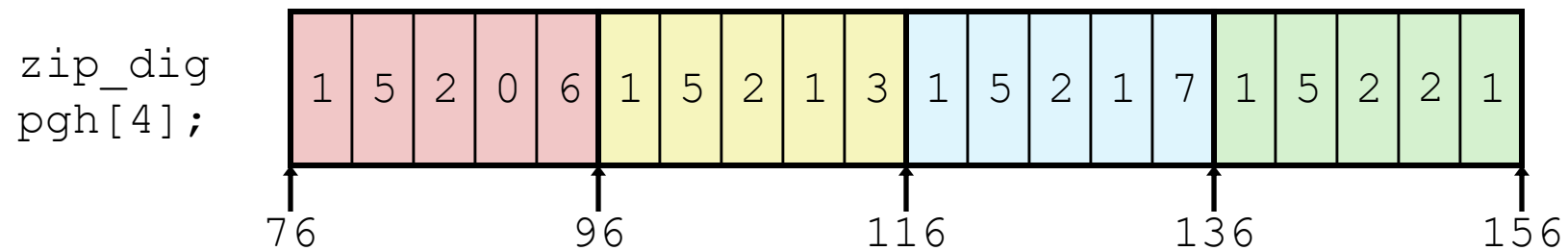


`int A[R][C];`



Nested Array Example

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
    {{1, 5, 2, 0, 6},
     {1, 5, 2, 1, 3 },
     {1, 5, 2, 1, 7 },
     {1, 5, 2, 2, 1 }};
```



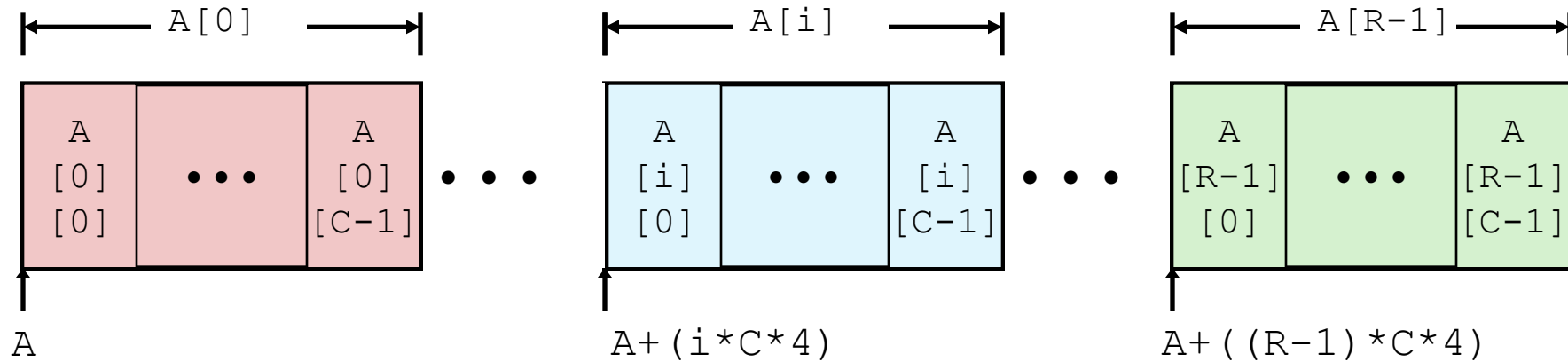
- ▶ “zip_dig pgh[4]” equivalent to “int pgh[4][5]”
 - Variable **pgh**: array of 4 elements, allocated contiguously
 - Each element is an array of 5 **int**’s, allocated contiguously
- ▶ “Row-Major” ordering of all elements in memory

Nested Array Row Access

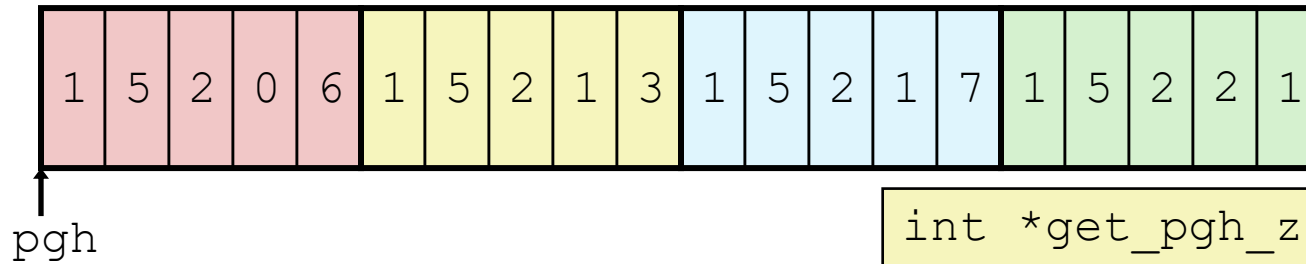
▶ Row Vectors

- $\mathbf{A}[i]$ is array of C elements
- Each element of type T requires K bytes
- Starting address $\mathbf{A} + i * (C * K)$

```
int A[R][C];
```



Nested Array Row Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
leaq (%rdi,%rdi,4),%rax # 5 * index
leaq pgh(,%rax,4),%rax  # pgh + (20 * index)
```

► Row Vector

- **pgh[index]** is array of 5 **int**'s
- Starting address **pgh+20*index**

► Machine Code

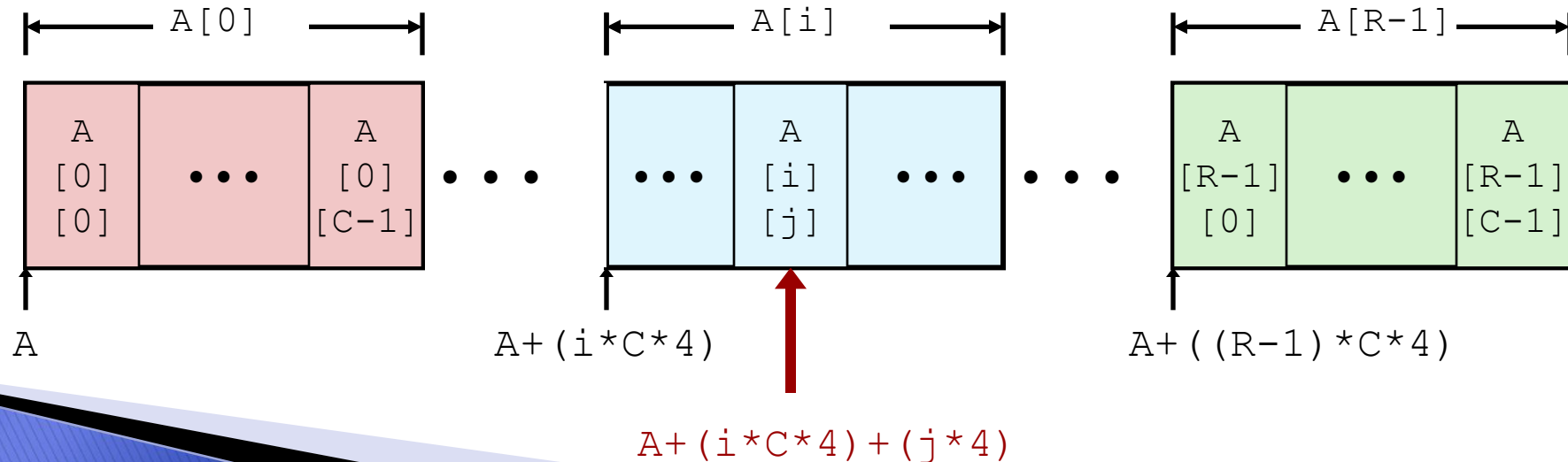
- Computes and returns address
- Compute as **pgh + 4*(index+4*index)**

Nested Array Element Access

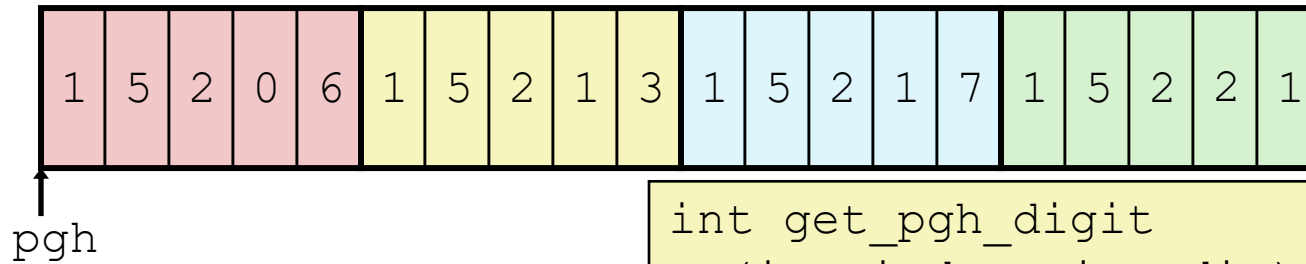
▶ Array Elements

- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i * (C * K) + j * K = A + (i * C + j) * K$

```
int A[R][C];
```



Nested Array Element Access Code



```
int get_pgh_digit
(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq    (%rdi,%rdi,4), %rax    # 5*index
                                # %rsi => 2nd parameter
addq    %rax, %rsi             # 5*index+dig
movl    pgh(,%rsi,4), %eax     # M[pgh + 4*(5*index+dig)]
```

► Array Elements

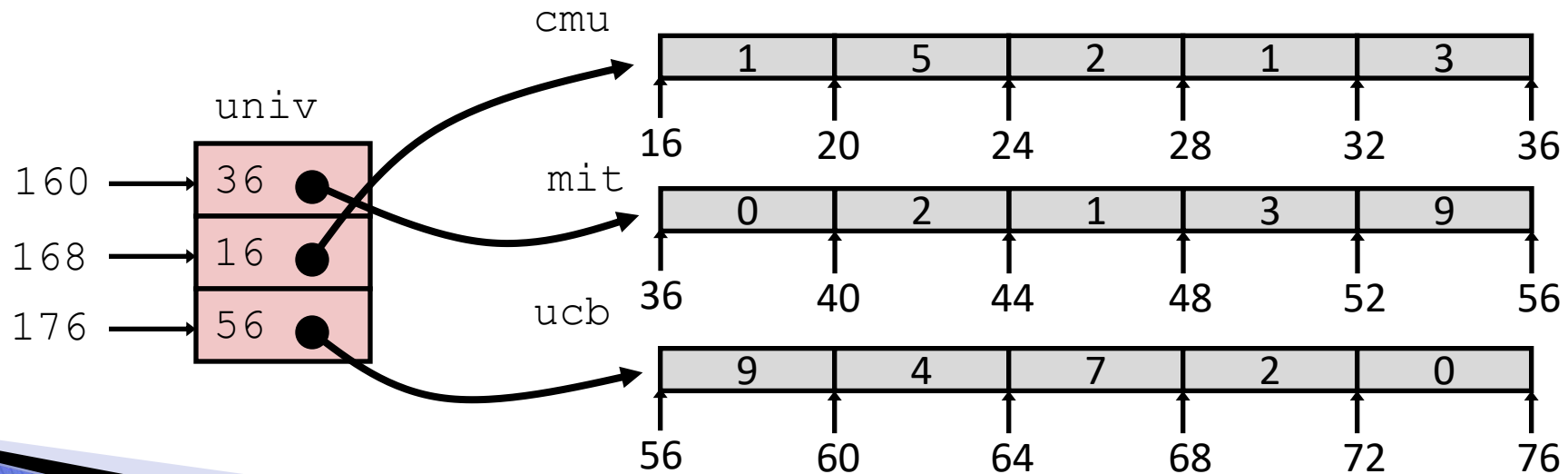
- **pgh[index][dig]** is **int**
- Address: **pgh + 20*index + 4*dig**
 - = **pgh + 4*(5*index + dig)**

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

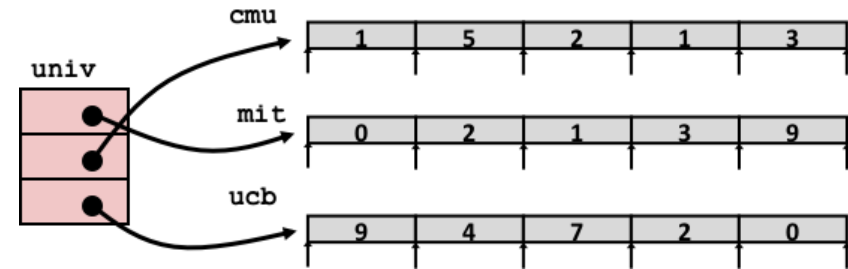
```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, ucb};
```

- ▶ Variable `univ` denotes array of 3 elements
- ▶ Each element is a pointer
 - 8 bytes
- ▶ Each pointer points to array of `int`'s



Element Access in Multi-Level Array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



```
salq    $2, %rsi          # 4*digit (2nd parameter)
addq    univ(,%rdi,8), %rsi # p = univ[index] + 4*digit
movl    (%rsi), %eax       # return *p
ret
```

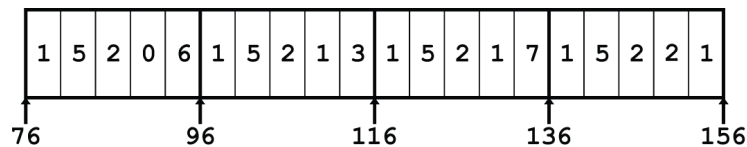
► Computation

- Element access **Mem[Mem[univ+8*index]+4*digit]**
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

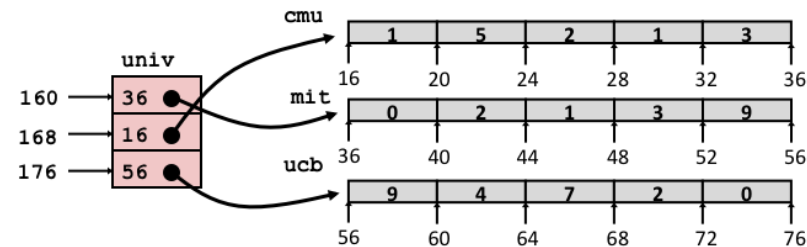
Nested array

```
int get_pgh_digit
(size_t index, size_t digit)
{
    return pgh[index][digit];
}
```



Multi-level array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

Mem[pgh+20*index+4*digit] Mem[Mem[univ+8*index]+4*digit]