

Integrating the Klein-Gordon on a 2-D Network

A set of Klein-Gordon oscillators each consisting of one degree of freedom (q, p) and coupled to the others on a square lattice network has the Hamiltonian

$$H = \sum_{x,y} \frac{p_{x,y}^2}{2} + \frac{\epsilon_{x,y} q_{x,y}^2}{2} + \frac{|q_{x,y}|^{\sigma+2}}{\sigma+2} - \frac{1}{2W} [(q_{x+1,y} - q_{x,y})^2 + (q_{x,y+1} - q_{x,y})^2] \quad (1)$$

which is separable into

$$\begin{aligned} H &= T(\vec{p}) + V(\vec{q}) \\ T(\vec{p}) &= \sum_{x,y} \frac{p_{x,y}^2}{2}, \\ V(\vec{q}) &= \sum_{x,y} \frac{\epsilon_{x,y} q_{x,y}^2}{2} + \frac{|q_{x,y}|^{\sigma+2}}{\sigma+2} - \frac{1}{2W} [(q_{x+1,y} - q_{x,y})^2 + (q_{x,y+1} - q_{x,y})^2] \end{aligned}$$

The former very easily integrates via $d_t q = \partial_p T$

$$\dot{q}_{x,y} = p_{x,y} \quad (2)$$

For V , need to expand to the full $q_{x,y}$ stencil

$$\begin{aligned} V &= \dots + \frac{\epsilon_{x,y} q_{x,y}^2}{2} + \frac{|q_{x,y}|^{\sigma+2}}{\sigma+2} + \dots \\ &\quad - \frac{1}{2W} [\dots (q_{x,y} - q_{x-1,y})^2 + (q_{x+1,y} - q_{x,y})^2 + (q_{x,y} - q_{x,y-1})^2 + (q_{x,y+1} - q_{x,y})^2 + \dots] \end{aligned}$$

Note the chain rule applied to the modulus term is $\frac{\partial}{\partial q} \frac{|q|^{\sigma+2}}{\sigma+2} = |q|^{\sigma+1} \frac{\partial}{\partial q} |q| = |q|^{\sigma+1} \frac{q}{|q|} = |q|^\sigma q$.

Using this in $d_t p = -\partial_q V$ gives

$$\dot{p}_{x,y} = -\epsilon_{x,y} q_{x,y} - |q_{x,y}|^\sigma q_{x,y} + \frac{1}{W} (q_{x-1,y} + q_{x+1,y} + q_{x,y-1} + q_{x,y+1} - 4q_{x,y}) \quad (3)$$

Corrector

The corrector step is defined from $C = \{\{A, B\}, B\}$. Expanding the bracyets gives

$$\{A, B\} = \sum_{x,y} \frac{\partial A}{\partial q_{x,y}} \frac{\partial B}{\partial p_{x,y}} - \frac{\partial A}{\partial p_{x,y}} \frac{\partial B}{\partial q_{x,y}}$$

Since we have $A(p)$ and $B(q)$, the first term is zero

$$\{A, B\} = - \sum_{x,y} \frac{\partial A}{\partial p_{x,y}} \frac{\partial B}{\partial q_{x,y}}$$

The fact $\partial_p B = 0$ can be used again to simplify the next bracket

$$\begin{aligned}\{\{A, B\}, B\} &= - \sum_{x,y} \frac{\partial}{\partial p_{x,y}} \left(\frac{\partial A}{\partial p_{x,y}} \frac{\partial B}{\partial q_{x,y}} \right) \frac{\partial B}{\partial q_{x,y}} \\ &= - \sum_{x,y} \left(\frac{\partial^2 A}{\partial p_{x,y}^2} \frac{\partial B}{\partial q_{x,y}} + \frac{\partial A}{\partial p_{x,y}} \frac{\partial^2 B}{\partial p_{x,y} \partial q_{x,y}} \right) \frac{\partial B}{\partial q_{x,y}}\end{aligned}$$

Previously, it was found

$$\frac{\partial A}{\partial p_{x,y}} = p_{x,y}, \quad \frac{\partial B}{\partial q_{x,y}} = \epsilon_{x,y} q_{x,y} + |q_{x,y}|^\sigma q_{x,y} - \frac{1}{W} (q_{x-1,y} + q_{x+1,y} + q_{x,y-1} + q_{x,y+1} - 4q_{x,y})$$

therefore the mixed derivative term goes to zero, giving

$$\{\{A, B\}, B\} = - \sum_{x,y} \frac{\partial^2 A}{\partial p_{x,y}^2} \left(\frac{\partial B}{\partial q_{x,y}} \right)^2$$

Substituting the previously found values

$$C = \{\{A, B\}, B\} = - \sum_{x,y} \left[\epsilon_{x,y} q_{x,y} + |q_{x,y}|^\sigma q_{x,y} - \frac{1}{W} (q_{x-1,y} + q_{x+1,y} + q_{x,y-1} + q_{x,y+1} - 4q_{x,y}) \right]^2$$

The corrector's momentum change is

$$\partial_t p_{x,y} = - \frac{\partial C}{\partial q_{x,y}}$$

which in order to do, we'll need to write out the full $q_{x,y}$ stencil. This is easily done by considering the variable

$$\zeta_{x,y} = \epsilon_{x,y} q_{x,y} + |q_{x,y}|^\sigma q_{x,y} - \frac{1}{W} (q_{x-1,y} + q_{x+1,y} + q_{x,y-1} + q_{x,y+1} - 4q_{x,y})$$

Note that $\zeta_{x,y}$ contains the $q_{x,y}$ stencil. We can expand C to a $\zeta_{x,y}$ stencil

$$C = \dots - \zeta_{x-1,y}^2 - \zeta_{x+1,y}^2 - \zeta_{x,y-1}^2 - \zeta_{x,y+1}^2 - \zeta_{x,y}^2 - \dots$$

In this expansion, every instance of $q_{x,y}$ is present, so then

$$\begin{aligned}\partial_t p_{x,y} &= - \frac{\partial C}{\partial q_{x,y}} \\ &= 2\zeta_{x-1,y} \frac{\partial \zeta_{x-1,y}}{\partial q_{x,y}} + 2\zeta_{x+1,y} \frac{\partial \zeta_{x+1,y}}{\partial q_{x,y}} + 2\zeta_{x,y-1} \frac{\partial \zeta_{x,y-1}}{\partial q_{x,y}} + 2\zeta_{x,y+1} \frac{\partial \zeta_{x,y+1}}{\partial q_{x,y}} + 2\zeta_{x,y} \frac{\partial \zeta_{x,y}}{\partial q_{x,y}}\end{aligned}$$

Looying term by term

$$\begin{aligned}
\zeta_{x,y} &= \epsilon_{x,y} q_{x,y} + |q_{x,y}|^\sigma q_{x,y} - \frac{1}{W} (q_{x-1,y} + q_{x+1,y} + q_{x,y-1} + q_{x,y+1} - 4q_{x,y}) \\
\zeta_{x-1,y} &= \epsilon_{x-1,y} q_{x-1,y} + |q_{x-1,y}|^\sigma q_{x-1,y} - \frac{1}{W} (q_{x-2,y} + q_{x,y} + q_{x-1,y-1} + q_{x-1,y+1} - 4q_{x-1,y}) \\
\zeta_{x+1,y} &= \epsilon_{x+1,y} q_{x+1,y} + |q_{x+1,y}|^\sigma q_{x+1,y} - \frac{1}{W} (q_{x,y} + q_{x+2,y} + q_{x+1,y-1} + q_{x+1,y+1} - 4q_{x+1,y}) \\
\zeta_{x,y-1} &= \epsilon_{x,y-1} q_{x,y-1} + |q_{x,y-1}|^\sigma q_{x,y-1} - \frac{1}{W} (q_{x-1,y-1} + q_{x+1,y-1} + q_{x,y-2} + q_{x,y} - 4q_{x,y-1}) \\
\zeta_{x,y+1} &= \epsilon_{x,y+1} q_{x,y+1} + |q_{x,y+1}|^\sigma q_{x,y+1} - \frac{1}{W} (q_{x-1,y+1} + q_{x+1,y+1} + q_{x,y} + q_{x,y+2} - 4q_{x,y+1})
\end{aligned}$$

And noting the derivative

$$\frac{\partial}{\partial q} |q|^\sigma q = \sigma |q|^{\sigma-1} \frac{\partial |q|}{\partial q} q + |q|^\sigma = (\sigma + 1) |q|^\sigma$$

We then have

$$\begin{aligned}
\frac{\partial \zeta_{x,y}}{\partial q_{x,y}} &= \epsilon_{x,y} + (\sigma + 1) |q_{x,y}|^\sigma + \frac{4}{W} \\
\frac{\partial \zeta_{x\pm 1,y}}{\partial q_{x,y}} &= \frac{\partial \zeta_{x,y\pm 1}}{\partial q_{x,y}} = -\frac{1}{W}
\end{aligned}$$

And finally

$$\partial_t p_{x,y} = -\frac{2}{W} (\zeta_{x-1,y} + \zeta_{x+1,y} + \zeta_{x,y-1} + \zeta_{x,y+1}) + 2\zeta_{x,y} \left(\epsilon_{x,y} + (\sigma + 1) |q_{x,y}|^\sigma + \frac{4}{W} \right)$$

which can be re-written as

$$\partial_t p_{x,y} = 2 \left(\epsilon_{x,y} + (\sigma + 1) |q_{x,y}|^\sigma \right) \zeta_{x,y} - \frac{2}{W} (\zeta_{x-1,y} + \zeta_{x+1,y} + \zeta_{x,y-1} + \zeta_{x,y+1} - 4\zeta_{x,y})$$

which is then simply qpdated

$$p(t+\tau) = p(t) + 2\tau \left[\left(\epsilon_{x,y} + (\sigma + 1) |q_{x,y}|^\sigma \right) \zeta_{x,y} - \frac{1}{W} (\zeta_{x-1,y} + \zeta_{x+1,y} + \zeta_{x,y-1} + \zeta_{x,y+1} - 4\zeta_{x,y}) \right]$$
