

Concurrent Computational Models

6CCS3COM Computational Models

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- **Introduction**
 - Sequential models
 - Properties of concurrent computation
 - Required notions
- **Transition systems**
- **Equivalence**
 - Simulation
 - Bisimulation
- **The calculus of communicating systems (CCS)**

Sequential models of computation

- Turing machines and lambda calculus are **sequential models** of computation.
- Interaction nets allow for **distribution** and **parallel** computation, but do not account for concurrent interactions.
- They are all universal models of computation — so why care if they specifically allow for concurrency?
 - Concurrent hardware.
 - Concurrent models can be more intuitive for concurrent problems.

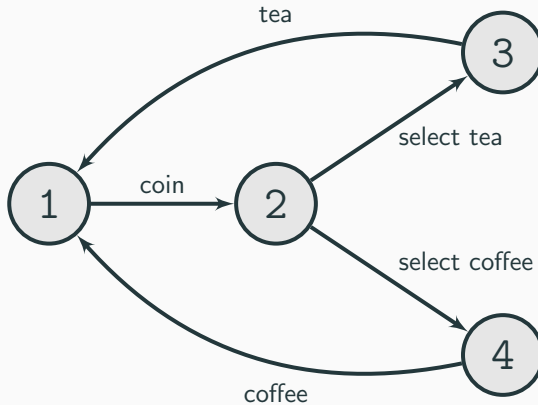
Properties of concurrent computation

- Concurrent computation can be characterised with having the following properties.
 - **Parallelism:** steps of computation can occur simultaneously.
 - **Interference:** the meaning of a program may depend on the behaviour of other programs that are being executed.
 - **Non-determinism:** the same computations do not always produce the same results.
 - **Non-termination:** the program(s) may not terminate, and indeed the output of a program may not be the focus of the computation.

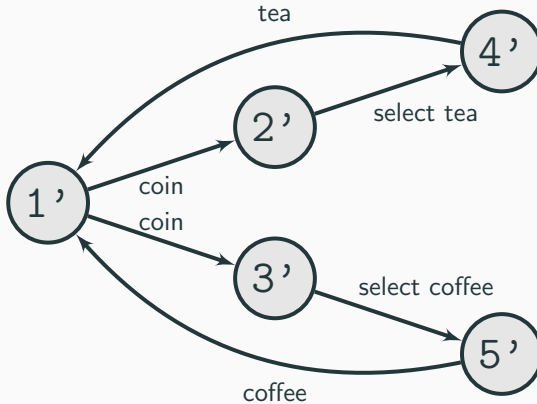
Notions for concurrent computation

- **Process:** A process is an entity that undertakes computation. In different domains they may also be referred to as agents, component, or thread.
- **Communication:** Processes can exchange information directly between themselves.
- **Interaction:** Shared resources between processes can mean the collective behaviour of the system depends on an individual's actions. Interaction can be positive and intended, or negative interference.
- **Behaviour:** The observable processes are called the behaviour of the system. Behaviour replaces the notion of *result* from sequential programs.

Example: vending machine



Example: vending machine (deterministic)



- How do we know if programs are **equivalent**?
 - Two *sequential* programs are equivalent if for all inputs they give the same outputs.

$$f = g \text{ iff } \forall x, f(x) = g(x)$$

- But in concurrent programs the output is rarely the focus, and is more commonly non-deterministic/non-terminating...
- For concurrent programs, we could:
 - Compare their associated language? No (accepted words are not the only thing we care about with concurrent systems).
 - Compare their *behaviour*? First, we need some formal definitions.

Transition system

- We can describe a concurrent program with a particular kind of automaton.
- Let Act be an alphabet (infinite set of **labels**):

$$Act = \mathcal{N} \cup \bar{\mathcal{N}}$$

\mathcal{N} is the set of **actions**, and $\bar{\mathcal{N}}$ is the set of **co-actions**.

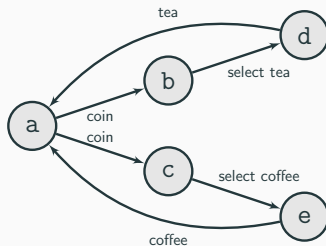
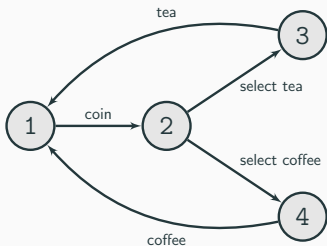
For example, for a vending machine, $\mathcal{N} = \{coin, coffee, tea, \dots\}$ and $\bar{\mathcal{N}} = \{\overline{coin}, \overline{coffee}, \overline{tea}, \dots\}$

- A **transition system** with labels in Act is a pair (Q, T) where:
 - Q is a set of states,
 - T is a ternary relation $T \subseteq (Q \times Act \times Q)$, the **transition relation**.

We write $q \rightarrow^a q'$ if $(q, a, q') \in T$, and say that in the state q the process can perform the action a and move to state q' .

- Let (Q, T) be a labelled transition system on Act .
- A binary relation S on Q is a **strong simulation** if pSq implies that, for each $a \in Act$ such that $p \rightarrow^a p'$, there exists q' in Q such that $q \rightarrow^a q'$ and $p'Sq'$.
- The idea is that if pSq holds, any transition can be done from the state p can also be done from q , and the resulting states are still in the relation.
- If pSq holds we say p **simulates** q .

Simulation: example



- For these two transition systems we can show a simulation:
 - $S = \{(a, 1), (b, 2), (c, 2), (d, 3), (e, 4)\}$
- Check that, for each pair $(p, q) \in S$ and for each each action a such that $p \rightarrow^a p'$ there is a transition $q \rightarrow^a q'$ such that $(p', q') \in S$.
- This shows the deterministic vending machine can simulate the non-deterministic vending machine.
 - But the non-deterministic vending machine can't simulate the deterministic vending machine. **Exercise:** why not?

- Simulation allows us to compare transition systems, but just because there is simulation in a single direction it doesn't mean the systems are equivalent.
- To show equivalence there needs to be simulation in both directions.

- Let (Q, T) be a labelled transition system on Act .
- A binary relation S on Q is a **strong bisimulation** if S and S^{-1} are strong simulations, where S^{-1} denotes the inverse of S (i.e., $pS^{-1}q$ if qSp).
- We will write $p \sim q$ if there is a strong bisimulation S such that $(p, q) \in S$.
- $p \sim q$ implies p simulates q and q simulates p , but the reverse is not true. **Exercise:** why not?

The calculus of communicating systems (CCS)

- Introduced by Milner in 1980s to have an abstract model that focuses on the *essence* of concurrent systems.
- Milner's general model:
 - A concurrent system is a collection of processes
 - A process is an independant agent that may perform internal activities in isolation, or may interact with the environment to perform shared activities.

A simple example

- A vending machine can be represented as follows:

$\text{coke.coin}.\overline{\text{coke_can}}.0 + \text{chocolate.coin}.\overline{\text{chocolate_bar}}.0$

- With the following elements of syntax:

1. **Actions:** $\text{coke}, \overline{\text{coke_can}}, \dots$
2. **Sequential composition:** $.$ (the dot)
 - $a.b$, first do a , then do b
3. **Non-deterministic choice:** $+$
 - $c + d$, do c or d
4. **Terminal process:** 0

- Processes **perform actions** ($\rightarrow^{\text{action}}$), and become a new process:

$\text{coke.coin}.\overline{\text{coke_can}}.0 + \text{chocolate.coin}.\overline{\text{chocolate_bar}}.0$

$\rightarrow^{\text{coke}} \text{coin}.\overline{\text{coke_can}}.0$

$\rightarrow^{\text{coin}} \overline{\text{coke_can}}.0$

$\rightarrow^{\overline{\text{coke_can}}} 0$

- The simplest possible process is a terminal process, which is a **terminated**, **inactive**, or **deadlocked** process.
- Represented by 0

- A set of **labels** for actions:

$$Act = \mathcal{N} \cup \overline{\mathcal{N}} = \{a, b, c, \dots\} \cup \{\bar{a}, \bar{b}, \bar{c}, \dots\}$$

- **Input actions:** $i \in \mathcal{N}$ represents the receiving of an input.
- **Output actions:** $o \in \overline{\mathcal{N}}$ represent the sending of an output.

- The simplest behaviour is **sequential action**
- If P is a process, we write $\alpha.P$ to denote the **prefixing** of P with action α .
- $\alpha.P$ models a system that is ready to perform the action α and then it will behave as P
 - i.e. $\alpha.P \rightarrow^\alpha P$

CCS syntax: non-deterministic choice

- Alternative behaviours can be used to model **non-deterministic choice**.
- If P and Q are processes, we write $P + Q$ to denote the **non-deterministic choice** between P and Q .
- $P + Q$ models a process that can behave as P (discarding Q), or behave as Q (discarding P).

$$\begin{aligned} & coke.coin.\overline{coke_can}.0 + chocolate.coin.\overline{chocolate_bar}.0 \\ & \quad \rightarrow^{coke} coin.\overline{coke_can}.0 \end{aligned}$$

- Note: $P + Q = Q + P$

- We can define **process constants**, that can be defined recursively.
- $P ::= a.b.c.0$, P is defined as a constant for the process $a.b.c.0$
- e.g., A ticking clock: $C ::= tick.tock.C$
 $tick.tock.C \rightarrow^{tick} tock.C \rightarrow^{tock} C = tick.tock.C \rightarrow^{tick} tock.C \rightarrow^{tock} \dots$
- Allows processes to continue *ad infinitum*.
- A program is a collection of process constants.

- **Concurrent behaviour** can be modelled with **parallel composition**.
- If P and Q are processes, we write $P|Q$ to denote the **parallel composition** of P and Q .
- $P|Q$ models a process that behaves like P and Q in parallel:
 - Each may proceed independently
 - If P is ready to perform an action a and Q is ready to perform the complementary action \bar{a} , they may **interact** (\rightarrow^τ , a step internal to the process).
 - Note: $P|Q = Q|P$

CCS syntax: parallel composition example

- First, let us update the model of our hot drinks machine...

$$HDM ::= \text{tea.coin}.\overline{\text{cup_of_tea}}.HDM + \text{coffee.coin.coin}.\overline{\text{mug_of_coffee}}.HDM$$

- Now, consider the concurrent system, me...

$$JM ::= \overline{\text{tea}}.\overline{\text{coin}}.\overline{\text{cup_of_tea}}.\overline{\text{teach}}.JM + \overline{\text{coffee}}.\overline{\text{coin}}.\overline{\text{coin}}.\overline{\text{mug_of_coffee}}.\overline{\text{research}}.JM$$

CCS syntax: parallel composition example

- We can now compose a process for the average day:

$$HDM \mid JM$$

- How might the process behave?

$$\begin{aligned} & (\overline{tea}.coin.\overline{cup_of_tea}.HDM + \overline{coffee}.coin.coin.\overline{mug_of_coffee}.HDM) \mid \\ & \quad (\overline{tea}.coin.\overline{cup_of_tea}.teach.JM + \\ & \quad \overline{coffee}.coin.coin.\overline{mug_of_coffee}.research.JM) \end{aligned}$$

$$\rightarrow^\tau (\overline{coin}.cup_of_tea.HDM) \mid (\overline{coin}.cup_of_tea.teach.JM)$$

$$\rightarrow^\tau (\overline{cup_of_tea}.HDM) \mid \overline{cup_of_tea}.teach.JM$$

$$\rightarrow^\tau HDM \mid \overline{teach}.JM$$

$$\rightarrow^{teach} HDM \mid JM$$

- **Exercise:** trace an execution that includes the action $\rightarrow^{research}$

- We can control **unwanted interactions** between a process and the environment by **restricting** action/co-action pairs.
- If P is a process and a is an action we write $\nu a.P$ for the restriction of a in P .
 - P can no longer take action a or \bar{a} .

CCS syntax: Restriction example

- Restricting the HDM on coffee makes the coffee button inaccessible to JM: $\nu_{coffee}.(HDM \mid JM)$
- As a consequence, JM can only teach, and never research

Summary of CCS syntax

- We can define a grammar for CCS processes as follows.

$P \rightarrow$	K		Process constants
	$\alpha.P$		Action prefixing ($\alpha \in Act$)
	$\sum_{i \in I} P_i$		Summation ($P_0 + P_1 + \dots + P_I$)
	$P_1 \mid P_2$		Parallel composition
	$\nu \alpha.P$		Restriction ($\alpha \in Act$)
	0		Terminal process

- **Exercise:** Which of the following expressions are well-formed processes in CCS?
 - $a.b.A + B$
 - $\nu a.(a.0 + \bar{a}.A)$
 - $(a.b.A + \bar{a}.0) \mid B$
 - $((a.b.A) + \bar{a}.0).B$

RULE	Premise	Conclusion	Conditions
ACT		$\alpha.P \rightarrow^\alpha P$	
SUM	$P \rightarrow^\alpha P'$	$M + P \rightarrow^\alpha P'$	
COM ₁	$P \rightarrow^\alpha P'$	$P \mid Q \rightarrow^\alpha P' \mid Q$	
COM ₂	$Q \rightarrow^\alpha Q'$	$P \mid Q \rightarrow^\alpha P \mid Q'$	
COM ₃	$P \rightarrow^a P', Q \rightarrow^{\bar{a}} Q'$	$P \mid Q \rightarrow^\tau P' \mid Q'$	
RES	$P \rightarrow^\alpha P'$	$\nu\beta.P \rightarrow^\alpha \nu\beta.P'$	$\alpha, \bar{\alpha} \neq \beta$
CON	$P \rightarrow^\alpha P'$	$K \rightarrow^\alpha P'$	$K ::= P$

Exercise: reducing expressions

- **Exercise:** Show a possible run for the following process, identifying the rules used in each step.

$$\nu b.((a.b.P_1 + b.P_2 + c.0) \mid \bar{a}.0) \mid \bar{b}.P_3 + \bar{a}.P_4$$

- **Challenge:** Are CCS process reductions confluent (can different orders of reduction give different results)? Justify your answer.

Exercise: reducing expressions

- **Exercise:** Show a possible run for the following process.

$$\nu b.((\textcolor{red}{a}.b.P_1 + b.P_2 + c.0) \mid \bar{\textcolor{red}{a}}.0) \mid \bar{b}.P_3 + \bar{a}.P_4$$

- We can use SUM in combination with COM₃ to reduce the expression.

- SUM: $(\textcolor{red}{a}.b.P_1 + b.P_2 + c.0) \rightarrow^a b.P_1$

- COM₃: $(\textcolor{red}{a}.b.P_1 + b.P_2 + c.0) \mid \bar{\textcolor{red}{a}}.0 \rightarrow^\tau b.P_1 \mid 0$

- After reduction step:

$$\nu b.(b.P_1 \mid 0) \mid \bar{b}.P_3 + \bar{\textcolor{red}{a}}.P_4$$

- We can use SUM in combination with COM₂ to reduce the expression.

- SUM: $\bar{b}.P_3 + \bar{\textcolor{red}{a}}.P_4 \rightarrow^{\bar{a}} P_4$

- COM₂: $\nu b.(b.P_1 \mid 0) \mid \bar{b}.P_3 + \bar{\textcolor{red}{a}}.P_4 \rightarrow^{\bar{a}} \nu b.(b.P_1 \mid 0) \mid P_4$

- After reduction step:

$$\nu b.(b.P_1 \mid 0) \mid P_4$$

- Concurrent systems have particular properties, and so bespoke computational models (e.g. CCS) have been developed to represent them.
- Equivalence of concurrent systems can be shown through bisimulation.
- CCS
 - Syntax
 - Semantics
 - *Lecture slides use slightly different notation compared to textbook*