# Lecture 7: Priority Queues and Heaps

(Chapter 8, Sections 8.1, 8.2, and 8.3 from the book)

## Agenda

- Priority Queues
  - Concepts priority queue, entry, key, total order relation, comparator
  - Priority queue implementation with a list
  - Priority queue sorting
    - Selection-sort
    - Insertion-sort
- Heaps
  - Priority queue implementation with a heap
  - Insertion into/Deletion from a heap
  - Heap-sort

## **Priority Queues**



## Priority Queue - Definition

- A priority queue is a collection of elements, called values, each having an associated key that is provided at the time the element is inserted.
- A key-value pair, (key,value), inserted into a priority queue is called an entry of the priority queue
- The name "priority queue" comes from the fact that keys determine the priority used to pick entries to be removed

## Keys in Priority Queue

- Keys are parameters or properties according to which we compare the objects; Keys are assigned for each object in a collection
  - e.g. we can compare companies by earnings or by number of employees
- Formally: a key is an object that is assigned to an element as a specific attribute for that element, which can be used to identify or weigh that element.
- Keys in a priority queue can be arbitrary objects on which an order is defined
- Note! Two distinct entries in a priority queue can have the same key

#### **Total Order Relations**

- Mathematical concept of total order relation ≤
  - Reflexive property:

$$x \leq x$$

Antisymmetric property:

$$x \leq y \land y \leq x \Rightarrow x = y$$

Transitive property:

$$x \leq y \land y \leq z \Rightarrow x \leq z$$

 Comparison rule that satisfies these three properties will never lead to a comparison contradiction. Such a rule defines a linear ordering relationship among a set of keys.

## **Priority Queue ADT**

- Methods of the Priority Queue ADT
  - insert(k, x): inserts into priority queue P an entry with key k and value x; return the inserted entry; an error occurs if k is invalid (that is, k cannot be compared with other keys);
  - removeMin(): removes from P and returns an entry with smallest key; an error condition occurs if P is empty;
  - min(): returns, but does not remove, an entry of P with smallest key;
     an error condition occurs if P is empty;
  - size(): returns the number of entries in priority queue P;
  - isEmpty(): tests whether priority queue P is empty;
- Applications:
  - Standby flyers
  - Auctions
  - Stock market

#### Priority Queue ADT – Java Interface

```
public interface PriorityQueue<K, V>
   public int size();
   public boolean isEmpty();
   public Entry<K, V> min() throws
EmptyPriorityQueueException;
   public Entry<K, V> insert(K key, V
value) throws InvalidKeyException;
   public Entry<K, V> removeMin() throws
EmptyPriorityQueueException;
```

## **Entry ADT**

- An entry in a priority queue is simply a key-value pair
- Priority queues store entries to allow for efficient insertion and removal based on keys
- Methods:
  - getKey: returns the key for this entry
  - getValue: returns the value associated with this entry
- Java Interface for a key-value pair entry

```
public interface Entry<K, V> {
   public K getKey();
   public V getValue();
}
```

## **Comparator ADT**

- A comparator encapsulates the action of comparing two objects according to a given total order relation
- A comparator is an object that compares two keys
- The comparator is external to the keys being compared
- A generic priority queue uses a default comparator
- When the priority queue needs to compare two keys, it uses its comparator

- Primary method of the Comparator ADT:
  - compare(x, y): returns an integer i such that
    - i < 0 if x < y,
    - i = 0 if x = y
    - i > 0 if x > y
    - An error occurs if a and b cannot be compared.
  - equals() compares a comparator to other comparator

#### Comparator – Java Interface

```
public interface Comparator
{
public int compare(Object o1, Object o2);
public boolean equals(Object obj);
}
```

#### Exercise 1 – Priority Queue ADT

- Starting from an empty priority queue,
   show the output and priority queue
   after each of the following operations:
- insert(7,A); insert(3,G); removeMin(); size(); insert(5,S), insert(4,T), removeMin(); min(); insert(ALA, W)

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#### Exercise 1 – Priority Queue ADT – Answer

<ul><li>Operation;</li></ul>	Output;	Priority Queue
□ insert(7,A);	(7,A)	(7,A)
□ insert(3,G);	(3,G)	(7,A); (3,G)
<pre>removeMin();</pre>	(3,G)	(7,A)
□ size();	1	(7,A)
□ insert(5,S),	(5,S)	(7,A); (5,S)
□ insert(4,T),	(4,T)	(7,A); (5,S); (4,T)
<pre>removeMin();</pre>	(4,T)	(7,A); (5,S)
□ min();	(5,S)	(7,A); (5,S)
□ insert(ALA, W)	Error	(7,A); (5,S)

Queues

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## Sequence-based Priority Queue

Implementation with an unsorted list



- Performance:
  - insert takes *O*(1) time since we can insert the item at the beginning or end of the sequence
  - removeMin and min take
    O(n) time since we have
    to traverse the entire
    sequence to find the
    smallest key

Implementation with a sorted list



- Performance:
  - insert takes O(n) time since we have to find the place where to insert the item
  - removeMin and min take
    O(1) time, since the
    smallest key is at the
    beginning
- size and is Empty take O(1) in both cases

#### **Priority Queue Sorting**

- We can use a priority queue to sort a set of comparable elements
  - 1. Put the elements of sequence S into initially empty priority queue P by means of a series of insert operations, one for each element.
  - 2. Remove the elements in sorted order from the priority queue  $\boldsymbol{P}$  with a series of removeMin operations, putting them back into  $\boldsymbol{S}$  in order.
- The running time of this sorting method depends on the priority queue implementation

#### **Priority Queue Sorting**

```
Algorithm PriorityQueueSort(S, P)
```

**Input** sequence *S* storing *n* elements, on which a total order relation is defined; priority queue *P*, that compares keys using the same total order relation

Output sequence S sorted by the total order relation

while !S.isEmpty () do

 $e \leftarrow S.removeFirst()$ 

*P.insert*  $(e, \emptyset)$  {a null value is used}

while !P.isEmpty() do

 $e \leftarrow P.removeMin().getKey()$ 

**S.addLast(e)** {the smallest key in P is added to the end of S}

#### Selection-Sort

- Selection-sort is the variation of *PriorityQueueSort* where the priority queue is implemented with an unsorted sequence
- Running time of Selection-sort:
  - 1. Inserting the elements into the priority queue with n insert operations takes O(n) time
  - 2. Removing the elements in sorted order from the priority queue with *n* removeMin operations takes time proportional to

$$O(n+(n-1)+...+2+1)=O(n(n+1)/2)=O(n^2)$$

□ Selection-sort runs in  $O(n^2)$  time

## Selection-Sort Example

Input:	Sequence S (7,4,8,2,5,3,9)	Priority Queue P ()
Phase 1 (a) (b)	(4,8,2,5,3,9) (8,2,5,3,9)	(7) (7,4)
(g)	0	(7,4,8,2,5,3,9)
Phase 2 (a) (b) (c) (d) (e) (f) (g)	(2) (2,3) (2,3,4) (2,3,4,5) (2,3,4,5,7) (2,3,4,5,7,8) (2,3,4,5,7,8,9)	(7,4,8,5,3,9) (7,4,8,5,9) (7,8,5,9) (7,8,9) (8,9) (9)

#### **Insertion-Sort**

- Insertion-sort is the variation of *PriorityQueueSort* where the priority queue is implemented with a sorted sequence
- Running time of Insertion-sort:
  - 1. Inserting the elements into the priority queue with *n* insert operations takes time proportional to

$$O(n+(n-1)+...+2+1)=O(n(n+1)/2)=O(n^2)$$

- 2. Removing the elements in sorted order from the priority queue with a series of n removeMin operations takes O(n) time
- □ Insertion-sort runs in  $O(n^2)$  time

## Insertion-Sort Example

Input:	Sequence S (7,4,8,2,5,3,9)	Priority queue P
Phase 1	(2),,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,	
(a) (b)	(4,8,2,5,3,9) (8,2,5,3,9)	(7) (4,7)
(c) (d)	(2,5,3,9) (5,3,9)	(4,7,8) (2,4,7,8)
(e) (f)	(3,9) (9)	(2,4,5,7,8) (2,3,4,5,7,8)
(g)	O	(2,3,4,5,7,8,9)
Phase 2 (a) (b)	(2) (2,3)	(3,4,5,7,8,9) (4,5,7,8,9)
(g)	 (2,3,4,5,7,8,9)	Ö

#### Exercise 2 – Selection-Sort

 Illustrate the execution of the selectionsort algorithm on the following input sequence:

(23,98,12,99,1,78,9)

#### Exercise 2 – Selection-Sort – Answer

	Sequence S	Priority queue P	
Input:	(23,98,12,99,1,78,9)	O	
Phase 1			
(a)	(98,12,99,1,78,9)	(23)	
(b)	(12,99,1,78,9)	(23,98)	
(c)	(99,1,78,9)	(23,98,12)	
(d)	(1,78,9)	(23,98,12,99)	
(e)	(78,9)	(23,98,12,99,1)	
(f)	(9)	(23,98,12,99,1,78)	
(g)	6	(23,98,12,99,1,78,9)	
Phase 2	<b>Y</b>	(=0,50,1=2,50,1=2,50,5)	
(a)	(1)	(23,98,12,99,78,9)	
(b)	(1,9)	(23,98,12,99,78)	
(c)	(1,9,12)	(23,98,99,78)	
(d)	(1,9,12,23)	(98,99,78)	
(e)	(1,9,12,23,78)	(98,99)	
(f)	(1,9,12,23,78,98)	(99)	
(g) © 2010 Goodrich, Tamassia	(1,9,12,23,78,98,99) Priority Queues	- V	22
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#### Exercise 3 – Insertion-Sort

 Illustrate the execution of the insertionsort algorithm on the following input sequence:

(23,98,12,99,1,78,9)

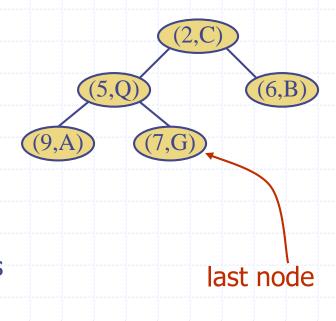
#### Exercise 3 – Insertion-Sort – Answer

	Sequence S	Priority queue P	
Input:	(23,98,12,99,1,78,9)	O	
Phase 1			
(a)	(98,12,99,1,78,9)	(23)	
(b)	(12,99,1,78,9)	(23,98)	
(c)	(99,1,78,9)	(12,23,98)	
(d)	(1,78,9)	(12,23,98,99)	
(e)	(78,9)	(1,12,23,98,99)	
(f)	(9)	(1,12,23,98,99)	
(g)	0	(1,9,12,23,78,98,99)	
Phase 2	· · · · · · · · · · · · · · · · · · ·		
(a)	(1)	(9,12,23,78,98,99)	
(b)	(1,9)	(12,23,78,98,99)	
(c)	(1,9,12)	(23,78,98,99)	
(d)	(1,9,12,23)	(78,98,99)	
(e)	(1,9,12,23,78)	(98,99)	
(f)	(1,9,12,23,78,98)	(99)	
(g)	(1,9,12,23,78,98,99)	0	
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#### Heaps

- A heap is a binary tree storing keys at its nodes and satisfying the following properties:
- □ Heap-Order: for every internal node v other than the root,  $key(v) \ge key(parent(v))$
- Complete Binary Tree: let h be the height of the heap
  - for i = 0, ..., h 1, there are  $2^{i}$  nodes of depth i
  - at depth (h-1), the internal nodes are to the left of the external nodes

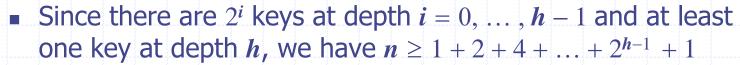
 The last node of a heap is the rightmost node of maximum depth



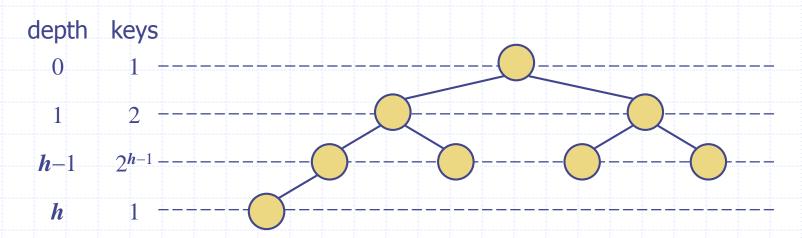
## Height of a Heap

- □ Theorem: A heap storing n keys has height  $O(\log n)$ 
  - Proof: (we apply the complete binary tree property)





■ Thus,  $n \ge 2^h$ , i.e.,  $h \le \log n$ 



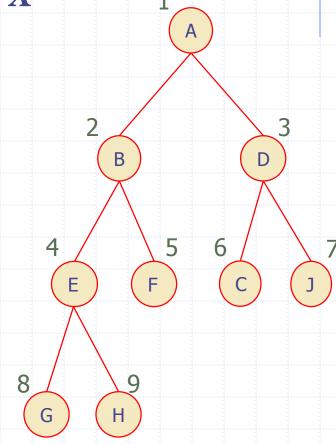


## Array-Based Representation of **Complete** Binary Trees

 $\square$  Nodes are stored in an array X



- $\square$  Node v is stored at X[rank(v)]
  - $\blacksquare$  rank(root) = 1
  - if node v is the left child of parent(v), rank(v) = 2 · rank(parent(v))
  - if node v is the right child of parent(v), rank(v) = 2· rank(parent(v)) + 1

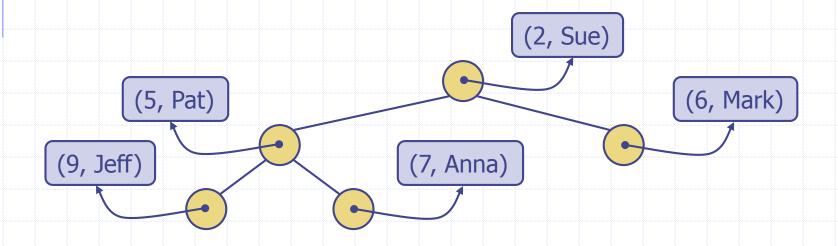


## Complete Binary Tree ADT

- Complete binary T supports all methods of binary tree ADT, plus the following:
  - add(o): add to T and return a new
     external node v storing element o such that the resulting tree is a complete binary tree with last node v
  - remove(): remove the last node of T and return its element

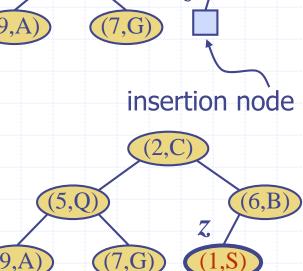
## Heaps and Priority Queues

- We can use a heap to implement a priority queue
- We store one (key, value) item at one node
- We keep track of the position of the last node



#### Insertion into a Heap

- □ Consider inserting entry (k,x)=(1, S) to the priority queue implemented with a heap T (9,
- The insertion algorithm (insert(k,x))
   from the priority queue ADT) is as follows:
  - Add a node z to T with operation add so that this new node becomes the last node of T and stores entry (k,x)
  - Restore the heap-order property that may be violated by the previous action (discussed next)

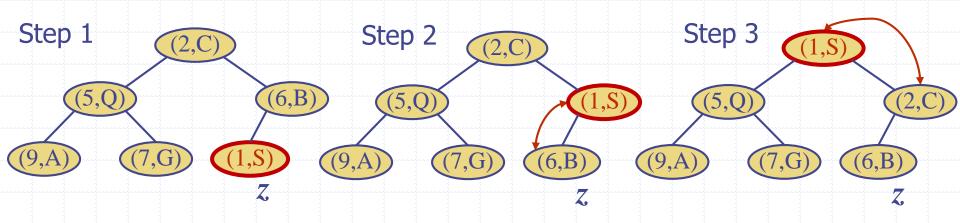


(6,B)

(5,Q)

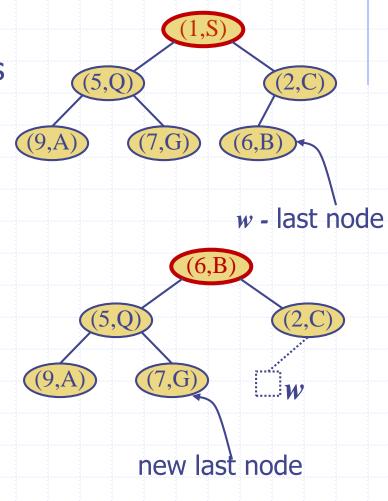
## Up-heap bubbling

- ullet After the insertion of a new entry with key  $m{k}$ , the heap-order property may be violated
- ullet Algorithm up-heap restores the heap-order property by swapping entry with key  $oldsymbol{k}$  along an upward path from the insertion node
- ullet Up-heap terminates when the entry with key k reaches the root or a node whose parent has a key smaller than or equal to k
- □ Since a heap has height  $O(\log n)$ , up-heap runs in  $O(\log n)$  time



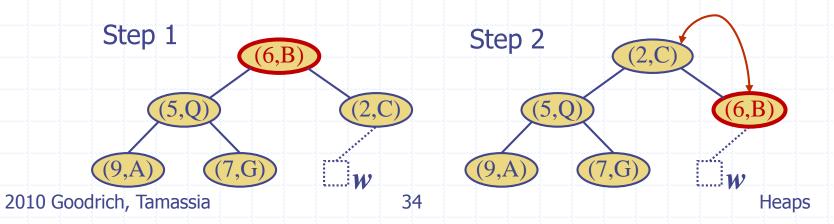
#### Removal from a Heap

- Method removeMin() of the priority queue ADT corresponds to the removal of the root key from the heap
- The removal algorithm consists of three steps
  - Replace the root element with the entry that is in the last node w
  - Remove w
  - Restore the heap-order property (discussed next)



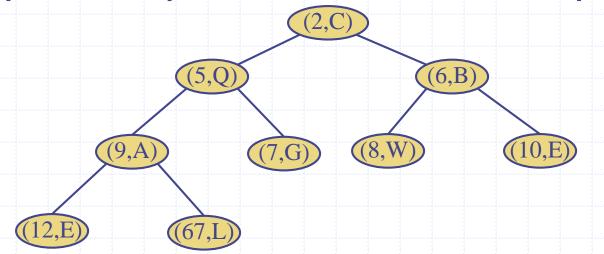
## Down-heap bubbling

- ullet After replacing the root element with the entry with key  $oldsymbol{k}$  of the last node, the heap-order property may be violated
- a Algorithm down-heap restores the heap-order property by swapping entry with key k along a downward path from the root (swap the entry with key k with its child with the smallest key)
- ullet Down-heap terminates when key  $m{k}$  reaches a leaf or a node whose children have keys greater than or equal to  $m{k}$
- □ Since a heap has height  $O(\log n)$ , down-heap runs in  $O(\log n)$  time



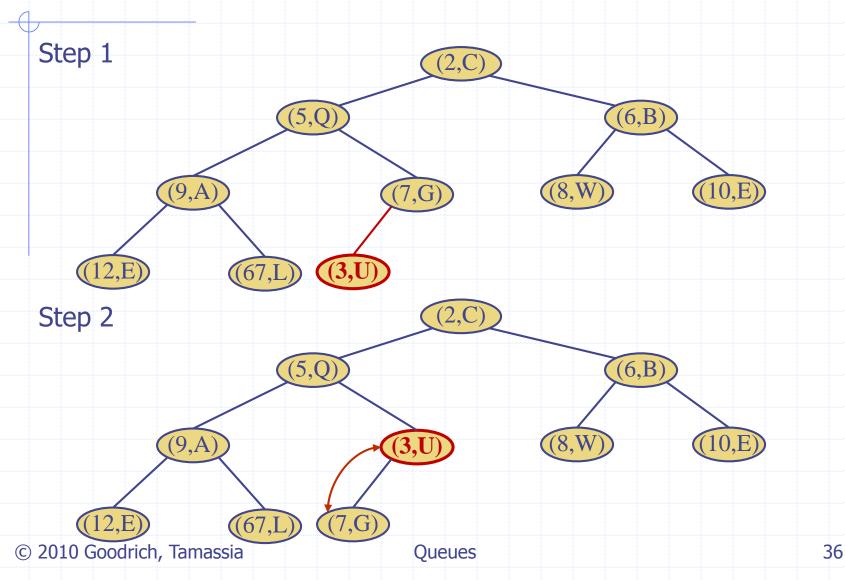
#### Exercise 4 – Insert

 Insert entry (3,U) into the priority queue implemented with a heap:

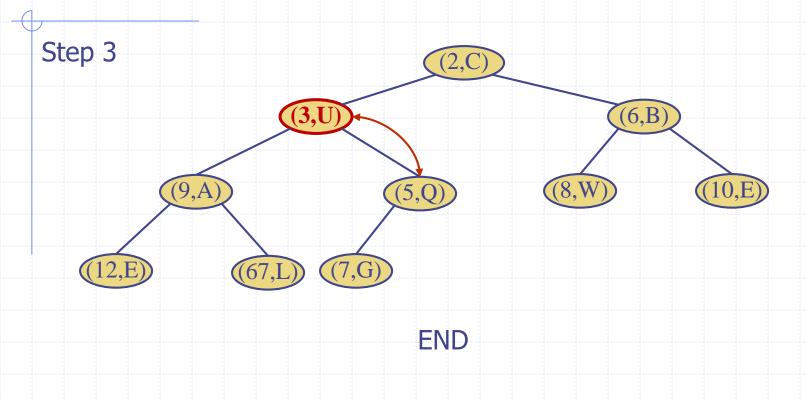


Present the process step by step

#### Exercise 4 – Insert – Answer

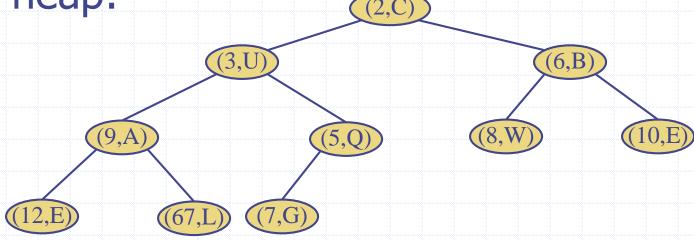


#### Exercise 4 – Insert – Answer



#### Exercise 5 - Remove

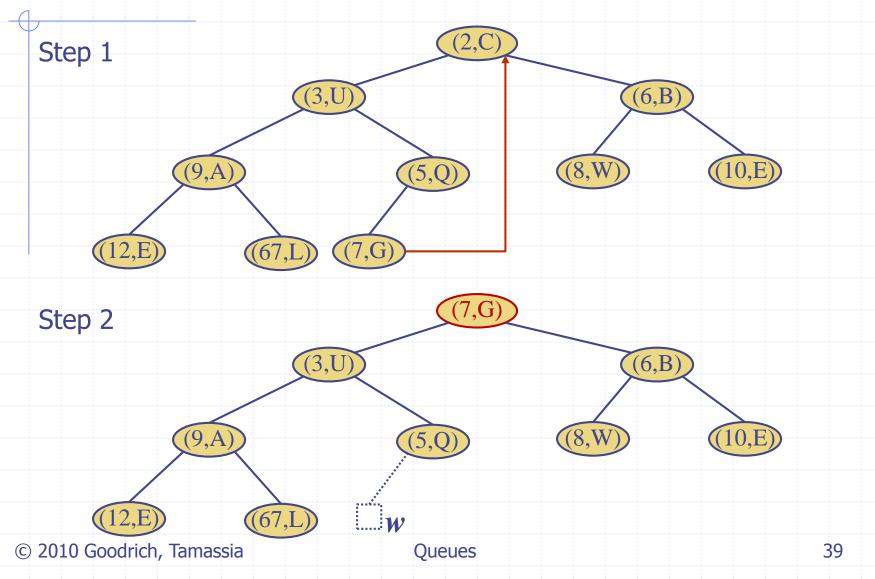
Perform removal of entry from the priority queue implemented with a heap:

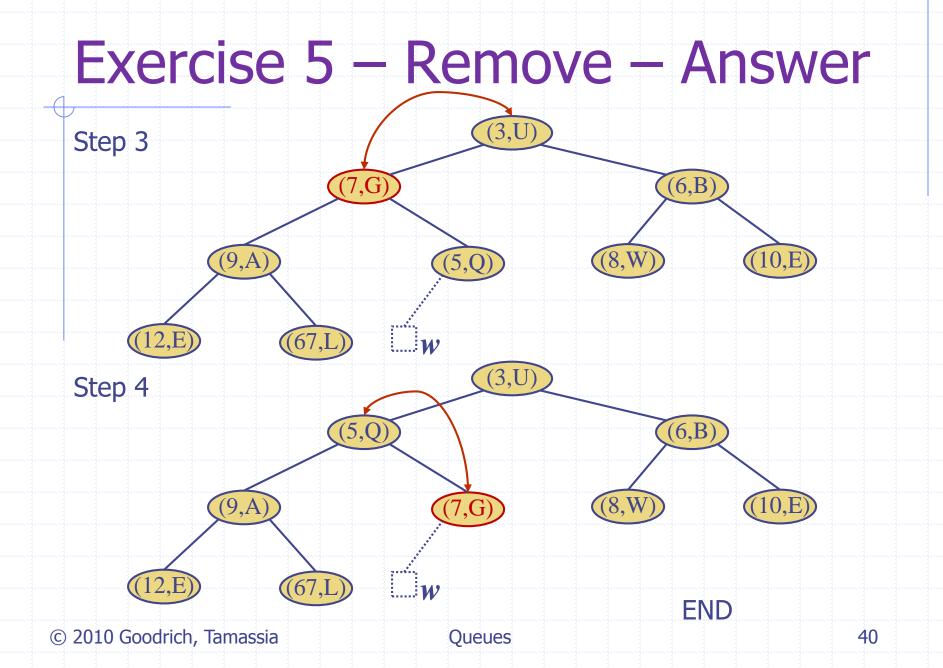


Present the process step by step

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#### Exercise 5 – Remove – Answer





# Heap-Sort

- Consider a priority
   queue with n items
   implemented by means
   of a heap
  - the space used is O(n)
  - methods insert and removeMin take O(log n) time
  - methods size, isEmpty,
     and min take time O(1)
     time

- using a heap-based priority queue, we can sort a sequence of n elements in  $O(n \log n)$  time
- The resulting algorithm is called heap-sort
- Heap-sort is much faster than quadratic sorting algorithms, such as insertion-sort and selection-sort

# Exercise 6 – Heap Sort

 Illustrate the execution of the heap-sort algorithm on the following input sequence:

(14, 45, 23, 98, 12, 99, 1, 78)

# Appendix Java Implementations

#### Interface for the priority queue ADT

```
/** Interface for the priority queue ADT */
public interface PriorityQueue<K,V> {
 /** Returns the number of items in the priority queue. */
 public int size();
 /** Returns whether the priority queue is empty. */
 public boolean isEmpty();
 /** Returns but does not remove an entry with minimum key. */
 public Entry<K,V> min() throws EmptyPriorityQueueException;
 /** Inserts a key-value pair and return the entry created. */
 public Entry<K,V> insert(K key, V value) throws InvalidKeyException;
 /** Removes and returns an entry with minimum key. */
 public Entry<K,V> removeMin() throws EmptyPriorityQueueException;
```

#### DefaultComparator.java

```
import java.util.Comparator;
import java.io.Serializable;
/** Comparator based on the natural ordering */
public class DefaultComparator<E> implements Comparator<E> {
/** Compares two given elements
* @return a negative integer if a is less than b,
* zero if a equals b, or a positive integer if a is greater than b
*/
public int compare(E a, E b) throws ClassCastException {
 return ((Comparable<E>) a).compareTo(b);
```

4CCS1DST, 2016/17 – Lecture 7 – Priority Queues and Heaps

# SortedListPriorityQueue.java

```
/** Realization of a priority queue by means of a sorted node list in nondecreasing
   order. */
public class SortedListPriorityQueue<K,V> implements PriorityQueue<K,V> {
 protected PositionList<Entry<K,V>> entries;
 protected Comparator<K> c;
 protected Position<Entry<K,V>> actionPos; // variable used by subclasses
 /** Inner class for entries */
 protected static class MyEntry<K,V> implements Entry<K,V> {
  protected K k; // key
  protected V v; // value
  public MyEntry(K key, V value) {
    k = key;
    v = value;
  // methods of the Entry interface
  public K getKey() { return k; }
  public V getValue() { return v; }
```

## SortedListPriorityQueue.java

```
/** Creates the priority queue with the default comparator. */
 public SortedListPriorityQueue () {
  entries = new NodePositionList<Entry<K,V>>();
  c = new DefaultComparator<K>();
 /** Creates the priority queue with the given comparator. */
 public SortedListPriorityQueue (Comparator<K> comp) {
  entries = new NodePositionList<Entry<K,V>>();
  c = comp;
/** Returns the number of elements in the priority queue. */
 public int size () {return entries.size();
 /** Returns whether the priority queue is empty. */
 public boolean isEmpty () {return entries.isEmpty();
```

# 4CCS1DST, 2016/17 - Lecture 7 - Priority Queues and Heaps Priority Queue Java

```
/** Inserts a key-value pair and return the entry created. */
 public Entry<K,V> insert (K k, V v) throws InvalidKeyException {
  checkKey(k);
                         // auxiliary key-checking method (could throw exception)
  Entry<K,V> entry = new MyEntry<K,V>(k, v);
  insertEntry(entry); // auxiliary insertion method
  return entry; }
 /** Auxiliary method used for insertion. */
 protected void insertEntry(Entry<K,V> e) {
  if (entries.isEmpty()) {
    entries.addFirst(e); // insert into empty list
    actionPos = entries.first(); } // insertion position
  else if (c.compare(e.getKey(), entries.last().element().getKey()) > 0) {
    entries.addLast(e); // insert at the end of the list
    actionPos = entries.last(); } // insertion position
  else {
    Position<Entry<K,V>> curr = entries.first();
    while (c.compare(e.getKey(), curr.element().getKey())> 0) {
      curr = entries.next(curr); } // advance toward insertion position
    entries.addBefore(curr, e);
    actionPos = entries.prev(curr); }} // insertion position
```

## SortedListPriorityQueue.java

```
/** Returns but does not remove an entry with minimum key. */
 public Entry<K,V> min () throws EmptyPriorityQueueException {
  if (entries.isEmpty())
    throw new EmptyPriorityQueueException("priority queue is empty");
  else
    return entries.first().element();
/** Removes and returns an entry with minimum key. */
 public Entry<K,V> removeMin() throws EmptyPriorityQueueException {
  if (entries.isEmpty())
    throw new EmptyPriorityQueueException("priority queue is empty");
  else
    return entries.remove(entries.first());
```