Signals and Systems

Signals and their classifications-III

Energy and Power Signals

A signal is said to be energy signal when it has finite energy.

Energy
$$E = \int_{-\infty}^{\infty} x^2(t) dt$$

A signal is said to be power signal when it has finite power.

$$\operatorname{Power} P = \lim_{T o \infty} \, rac{1}{2T} \, \int_{-T}^T x^2(t) dt$$

NOTE:A signal cannot be both, energy and power simultaneously. Also, a signal may be neither energy nor power signal.

Power of energy signal = 0

Energy of power signal = ∞

Signal Energy and Power

A signal with finite signal energy is called an **energy signal**.

A signal with infinite signal energy and finite average signal power is called a **power signal**.

Ex-
$$\chi(t) = e^{-2t} u(t)$$

$$E = \int_{-\infty}^{\infty} |\chi^{2}(t)| dt \text{ or } \int_{-\infty}^{\infty} |\chi(t)|^{2} dt$$

$$= \int_{0}^{\infty} |e^{2t}|^{2} dt$$

$$= \int_{0}^{\infty} e^{-4t} dt$$

$$= \frac{e^{-4t}}{4} \Big|_{0}^{\infty}$$

$$= \frac{|e^{-\infty} - e^{0}|}{4} = \frac{|o^{-1}|}{4}$$

$$E = \frac{1}{4}$$

$$P = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} z t^{2} (t) dt$$

$$P = \lim_{T \to \infty} \int_{0}^{T} e^{-At} dt$$

$$= \frac{1}{2T} \int_{-4}^{e} e^{-At} dt$$

$$= \frac{1}{2T} \int_{0}^{e} e^{-At} dt$$

$$= \frac{-e^{-4t}}{0}$$

$$= -e^{-4t} + 1$$

$$T \to \infty$$

$$P = 0$$

$$\therefore x(t) = e^{-2t} u(t) \text{ is an energy signal.}$$

BASIC CONTINUOUS-TIME SIGNALS

A. The Unit Step Function:

The unit step function u(t), also known as the Heaviside unit function, is defined as

$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases} \tag{1.18}$$

which is shown in Fig. 1-4(a). Note that it is discontinuous at t = 0 and that the value at t = 0 is undefined. Similarly, the shifted unit step function $u(t - t_0)$ is defined as

$$u(t - t_0) = \begin{cases} 1 & t > t_0 \\ 0 & t < t_0 \end{cases}$$
 (1.19)

which is shown in Fig. 1-4(b).

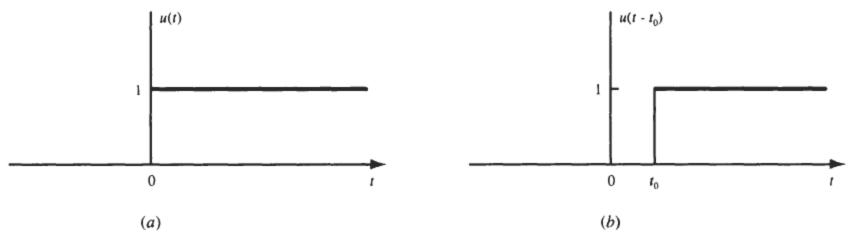


Fig. 1-4 (a) Unit step function; (b) shifted unit step function.

The Unit Impulse Function:

The unit impulse function $\delta(t)$, also known as the Dirac delta function, plays a central role in system analysis. Traditionally, $\delta(t)$ is often defined as the limit of a suitably chosen conventional function having unity area over an infinitesimal time interval as shown in Fig. 1-5 and possesses the following properties:

$$\delta(t) = \begin{cases} 0 & t \neq 0 \\ \infty & t = 0 \end{cases}$$
$$\int_{-\varepsilon}^{\varepsilon} \delta(t) dt = 1$$

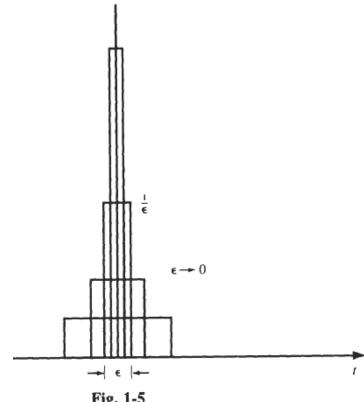


Fig. 1-5

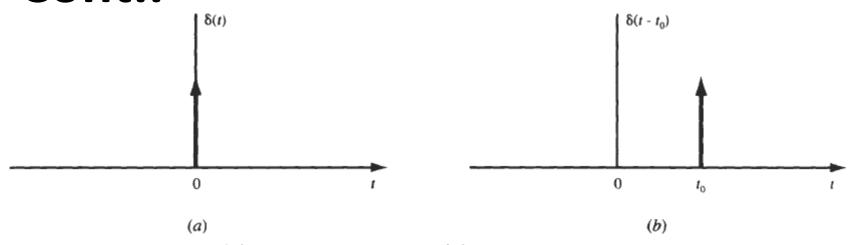


Fig. 1-6 (a) Unit impulse function; (b) shifted unit impulse function.

Some additional properties of $\delta(t)$ are

$$\delta(at) = \frac{1}{|a|}\delta(t) \tag{1.23}$$

$$\delta(-t) = \delta(t) \tag{1.24}$$

$$x(t)\delta(t) = x(0)\delta(t) \tag{1.25}$$

if x(t) is continuous at t = 0.

$$x(t)\delta(t - t_0) = x(t_0)\delta(t - t_0)$$
 (1.26)

if x(t) is continuous at $t = t_0$.

Using Eqs. (1.22) and (1.24), any continuous-time signal x(t) can be expressed as

$$x(t) = \int_{-\infty}^{\infty} x(\tau)\delta(t-\tau) d\tau$$
 (1.27)

Relation between unit step function and unit impulse function

$$\delta(t) = u'(t) = \frac{du(t)}{dt}$$

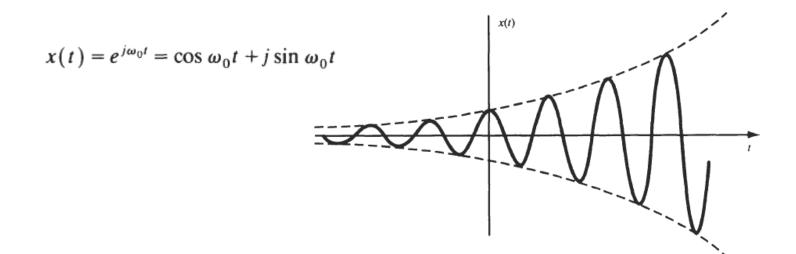
Then the unit step function u(t) can be expressed as

$$u(t) = \int_{-\infty}^{t} \delta(\tau) \, d\tau$$

C. Complex Exponential Signals:

The complex exponential signal

$$x(t) = e^{j\omega_0 t} \tag{1.32}$$



BASIC DISCRETE-TIME SIGNALS

The *unit step* sequence u[n] is defined as

$$u[n] = \begin{cases} 1 & n \ge 0 \\ 0 & n < 0 \end{cases}$$
 (1.43)

which is shown in Fig. 1-10(a). Note that the value of u[n] at n = 0 is defined [unlike the continuous-time step function u(t) at t = 0] and equals unity. Similarly, the shifted unit step sequence u[n - k] is defined as

$$u[n-k] = \begin{cases} 1 & n \ge k \\ 0 & n < k \end{cases} \tag{1.44}$$

which is shown in Fig. 1-10(b).

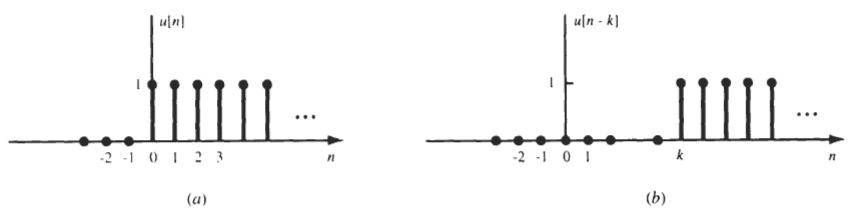


Fig. 1-10 (a) Unit step sequence; (b) shifted unit step sequence.

B. The Unit Impulse Sequence:

The unit impulse (or unit sample) sequence $\delta[n]$ is defined as

$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases} \tag{1.45}$$

which is shown in Fig. 1-11(a). Similarly, the shifted unit impulse (or sample) sequence $\delta[n-k]$ is defined as

$$\delta[n-k] = \begin{cases} 1 & n=k \\ 0 & n\neq k \end{cases} \tag{1.46}$$

which is shown in Fig. 1-11(b).

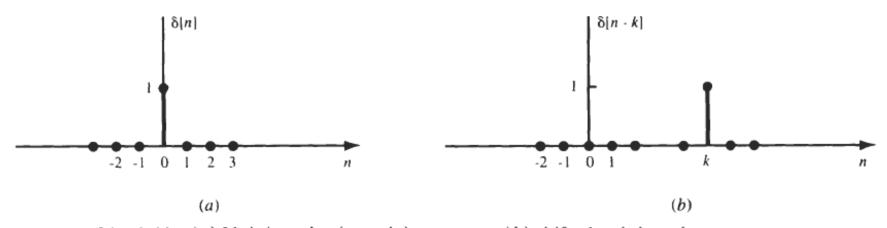
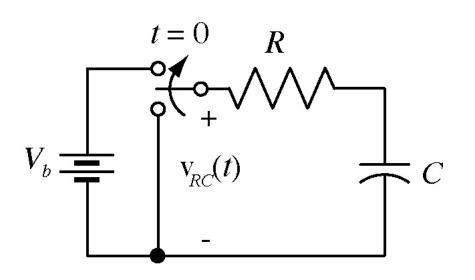


Fig. 1-11 (a) Unit impulse (sample) sequence; (b) shifted unit impulse sequence.

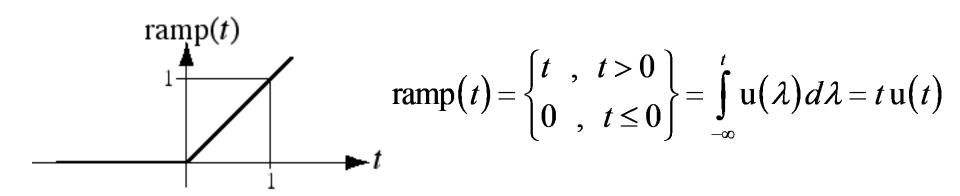
The Unit Step Function

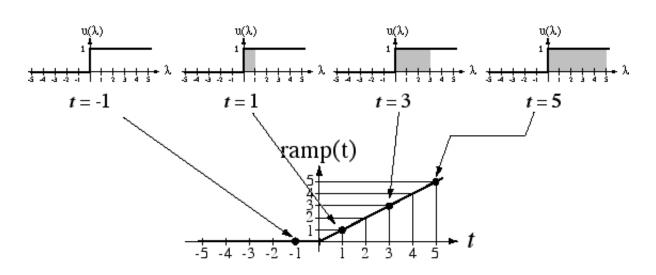
The unit step function can mathematically describe a signal that is zero up to some point in time and non-zero after that.



$$\begin{array}{ccc}
& v_{RC}(t) = V_b u(t) \\
& i(t) = (V_b / R) e^{-t/RC} u(t) \\
& v_C(t) = V_b (1 - e^{-t/RC}) u(t)
\end{array}$$

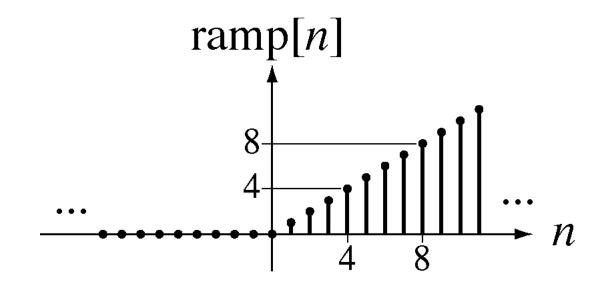
The Unit Ramp Function





The Unit Ramp Function

ramp
$$[n] = \begin{cases} n, & n \ge 0 \\ 0, & n < 0 \end{cases} = n \mathbf{u}[n] = \sum_{m=-\infty}^{n} \mathbf{u}[m-1]$$



C. Complex Exponential Sequences:

The complex exponential sequence is of the form

$$x[n] = e^{j\Omega_0 n} \tag{1.52}$$

Again, using Euler's formula, x[n] can be expressed as

$$x[n] = e^{j\Omega_0 n} = \cos \Omega_0 n + j \sin \Omega_0 n \tag{1.53}$$

Thus x[n] is a complex sequence whose real part is $\cos \Omega_0 n$ and imaginary part is $\sin \Omega_0 n$.

Periodicity of $e^{j\Omega_0 n}$:

In order for $e^{j\Omega_0 n}$ to be periodic with period N (>0), Ω_0 must satisfy the following condition (Prob. 1.11):

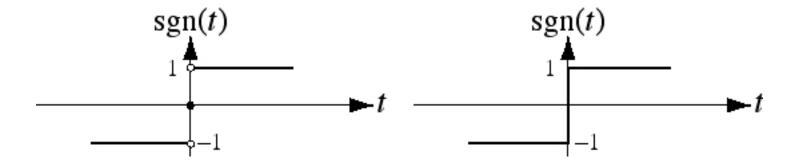
$$\frac{\Omega_0}{2\pi} = \frac{m}{N}$$
 $m = \text{positive integer}$ (1.54)

The Signum Function

$$\operatorname{sgn}(t) = \begin{cases} 1 & , t > 0 \\ 0 & , t = 0 \\ -1 & , t < 0 \end{cases}$$

Precise Graph

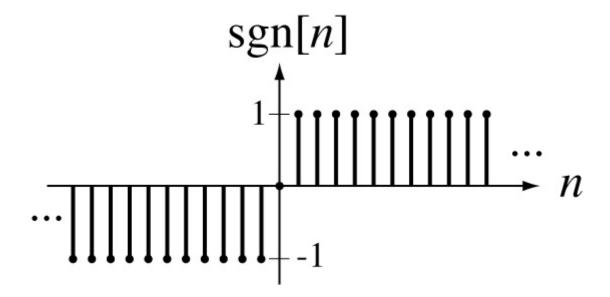
Commonly-Used Graph



The signum function, in a sense, returns an indication of the sign of its argument.

The Signum Function

$$\operatorname{sgn}[n] = \begin{cases} 1 & , n > 0 \\ 0 & , n = 0 \\ -1 & , n < 0 \end{cases}$$



Thank You