# Jonathan DiGiorgio

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## EDUCATION

#### University of Waterloo

Waterloo, ON

BASc in Mechanical Engineering with Mechatronics option (96% CGPA)

Sept 2022 - April 2027

• 2x First in Class Engineering Scholarship, 4x Dean's Honours List

#### Experience

## Mechanical Design Engineering Intern

Aug 2024 – Dec 2024

Tesla (Detail limited by NDA)

Fremont, CA

- Designed new **sheet-metal stamped** and **high-pressure die-casted** parts for Cybertruck and RoboTaxi using **CATIA**, **DFM**, **Tolerance Stackup Analysis**, and **GD&T**, and projected to save customers \$10M annually
- Created and conducted design validations and functional investigations using custom 3D Printed parts
- Collaborated directly with part suppliers to optimize designs for DFM, formability and cost-savings
- Analyzed CAE crash simulations to optimize structural designs and ensure passing of FMVSS legal requirements
- Drafted and released 10 GD&T drawings, utilizing my Tesla training and certification in advanced GD&T
- Conducted research on aluminum and adhesive bond thickness properties to support design and development
- Collaborated with various cross-functional teams and managing multiple high-priority projects simultaneously
  Developed 4 repair procedures along with fastening strategy for structural components relating to Model Y

# Mechanical Engineering Intern

Jan 2024 - May 2024

Pratt & Whitney (Detail limited by NDA)

Missisauga, ON

- Contributed to various R&D projects, working within a multi-disciplinary team to optimize flight performance
- Conducted FEA on jet engine subassemblies using the ANSYS Suite, LS-DYNA and Altair HyperWorks
- Utilized CATIA and SpaceClaim to conduct iterative optimization to CAD models according to FEA results
- Led a 42% weight-saving project, using ACP to analyze a part's replacement from aluminum to composite

#### Mechanical Team Lead - Chassis and Propulsion

May 2024 - Present

The Boring Company Competition - WatDig

Waterloo, ON

- Leading a team of 4 on the research and design of a tunnel boring machine to compete in NaBC 2025 in Texas
- Designed a motorized & hydraulic articulation system in OnShape, to steer and support 3kNm of torque
- Performed hand calculations to determine required steering force, and obtain hydraulic actuator specifications

## Mechanical Engineer Team Member

Sept 2023 – Present

Waterloo Aerial Robotics Group

Waterloo, ON

- Designed a drone arm clamping mechanism, reducing arm play by 56%, resulting in reduced vibrations utilized DFM principles for 3D Printing, water jet cutting, and tapping
- Designed PCB housings in Solidworks, including safety considerations and thermal board ventilation

## Quality Assurance Engineering Intern

May 2023 – Aug 2023

S&C Electric Canada

Etobicoke, ON

- Inspected high-voltage interrupt switches and subassemblies with **GD&T** drawings, using calipers, gauge calibrations/R&Rs, audits, hipot testing, and hardness testing, leading to **0** defective returns
- Developed a **Python** script to automate inspection data/image collection that was implemented department-wide, increasing inspection efficiency by 43% and collecting photographic evidence for use in customer quality disputes

#### PROJECTS

Autonomous Chess Robot | Solidworks, AutoCAD, RobotC, Python

Jan 2023 – Apr 2023

- Used Python for move detection (OpenCV), move computation, and robot communication (PyAutoGUI)
- Utilized RobotC, motors, servos and sensors to facilitate a 3-axis gantry, resulting in a >95\% successful move rate
- Utilized Solidworks, AutoCAD, 3D printing and laser cutting to create housings, racks, guides and more

#### Technical Skills

Engineering Software: 3DExperience, CATIA V5/V6, Solidworks CAD/FEA/PDM (CSWA), ANSYS Workbench, LS-DYNA (PrePost), Altair Hyperworks, OnShape, Enovia VPM, AutoCad, ACP, PLC, Excel, Jira Engineering Processes: CAD, GD&T, Drafting, FEA, Stamping, Casting, 3D Printing, Rapid Prototyping Programming: Ladder Logic, Python (PyAutoGUI, OpenCV), C/C++, MATLAB, HTML, CSS, Github, VS Code