Jonathan DiGiorgio

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TECHNICAL SKILLS

CAD/FEA Software: Solidworks (CSWA), AutoCAD, Fusion360, COMSOL

Design Processes: GD&T, Drafting, FEA, DFMA, Quality Assurance, R&R, Rapid Prototyping Manufacturing Processes: Engineering Drawings, 3D Printing, Laser Cutting, Machining, 5S Programming: Python (PyAutoGUI, OpenCV), C/C++, MATLAB, HTML, CSS, Github, VS Code

EXPERIENCE

Mechanical Engineer Team Member

Sept 2023 – Present

Waterloo Aerial Robotics Group

Waterloo, ON

- Designed and modelled a light-weight carbon-fibre drone landing gear with a crash failsafe, using Solidworks
- Designed an ESC circuit housing in Solidworks, including safety considerations and proper board ventilation
- Conducted FEA to determine landing gear load distribution, landing angles, and housing ventilation effectiveness

Quality Assurance Engineering Intern

May 2023 – Aug 2023

S&C Electric Canada

Etobicoke, ON

- Inspected high-voltage interrupt switches and subassemblies with GD&T drawings, leading to 0 defective returns
- Developed a Python script to automate inspection data/image collection that was implemented department-wide, increasing inspection efficiency by 43% and collecting photographic evidence for use in customer quality disputes
- Led an automated package inspection project that uses Dori AI to detect and warn of missing parts from orders
- Conducted 30+ gauge calibrations/R&Rs, audits, hipot testing, and hardness testing every week to ensure quality
- Assembled various switches and sub-assemblies, gaining insight into manufacturing and **DFMA** principles
- Effectively tracked quality of 300+ products weekly using Excel and Oracle, to produce weekly quality reports

Airframe Design Team Member

Sept 2022 – April 2023

Waterloo Rocketry

 $Waterloo,\ ON$

- Led the safety team for the oxidizer loading system, through the UV-light inspection and assembly of ball valves
- Working on the airframe subteam to machine and assemble a competition-ready rocket frame using carbon fibre

PROJECTS

Autonomous Chess Robot | Solidworks, AutoCAD, RobotC, Python

Jan 2023 – Apr 2023

- Led a team of 4 to design a robot which autonomously plays pro-level chess against a live opponent
- Used Python for move detection (OpenCV), move computation, and robot communication (PyAutoGUI)
- Utilized RobotC, motors, servos and sensors to facilitate a 3-axis gantry, resulting in a >95% successful move rate
- Utilized Solidworks, AutoCAD, 3D printing and laser cutting to create housings, racks, guides and more
- Conducted simulations using Solidworks FEA to determine the best structure for load distribution and tipping
- Created a work breakdown structure and Gantt chart for project management, resulting in timely completion

Magnetic Whirpool - Fishing Toy | Solidworks, Machining, 3D Printing

Sept 2022 – Dec 2022

- Led a team of 4 to design a fishing toy with a magnetically influenced whirlpool and spring-powered 'fishing rods'
- Made whirlpool mechanism using a motor, magnets, potentiometer and switch, sustaining a 15+ min vortex
- Used **drill press** and **saw** to construct the PVC housing for a pinball-like launcher, resulting in a ~70cm range
- Used Solidworks and 3D printing for a reel mechanism that friction-fits into a ball bearing, storing 1m of reel

Lithophane Picture Stand | Solidworks, 3D Printing

May 2023 – Jun 2023

- Designed pictures that display only when lit from behind, by using varying thicknesses to create different shades
- Used Solidworks to design a sleek LED housing with a lithophane mount, allowing for easy picture swapping
- Designed product to be easily **3D printed** without supports, saving material and around **2 hours** in print time

Portfolio Website – Click here to see my engineering project portfolio

EDUCATION

University of Waterloo