High Performance Computing with Python Summer School in Dynamic Structural Econometrics Lausanne, August 21-26, 2023

Rafael Sarmiento ETHZürich / CSCS



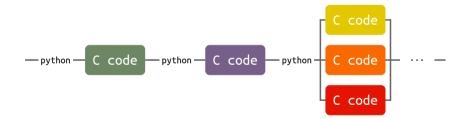
Python

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- It's fairly easy to glue it to other languages like C and Fortran



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Python in HPC

NumPy-like operations with multidimensional arrays

- NumPy, CuPy, PyTorch, TensorFlow, Jax, ...
- Many packages have reimplemented NumPy's API providing support on platforms like GPUs and TPUs

Compiled code

- Numba, Cython, Taichi Lang but also PyTorch and TensorFlow
- Support for multiple platforms
- Interfaces to languages like Fortran90 and C/C++ (pybind11, CFFI, F2PY, ...)

• Scaling workflows in clusters

- dask / dask.distributed, PySpark, IPyParallel, MPI4Py, CuNumerics, ...
- Scalable reimplementations of NumPy



NumPy-like operations with multidimensional arrays



NumPy is a Python library that adds support for large multi-dimensional arrays and matrices, along with a large collection of high-level mathematical functions to operate on these arrays.



- numpy.ndarray: a powerful N-dimensional array object
- Sophisticated functions often written in C
- Linear algebra, Fourier transform, and random number capabilities
- Tools for easy binding to Fortran code (F2PY)
- Compatibility with C
- Many libraries implement the NumPy API, such as Dask and CuPy for graph and GPU computing respectively [NEP 35]





CuPy is an open-source array library accelerated with NVIDIA CUDA. It provides GPU accelerated computing with Python

- CuPy uses CUDA-related libraries including cuBLAS, cuDNN, cuRand, cuSolver, cuSPARSE, cuFFT and NCCL
- CuPy's interface is highly compatible with NumPy: in most cases it can be used as a drop-in replacement
- It compiles a kernel code optimized for the shapes and dtypes of given arguments, sends it to the GPU device, and executes the kernel



The **SciPy** library provides many user-friendly and efficient numerical routines for operations such as numerical integration, interpolation, optimization, linear algebra and statistics. SciPy builds on the numpy.ndarray and expands the set of mathematical functions included in NumPy

Vectorization

• Use operations over the whole array instead of over single elements.

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```
y = np.exp(x) # x = np.array([...])

z = x @ y # equivalent to np.matmul(x, y)
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• Adapt your solutions to use the two points above.

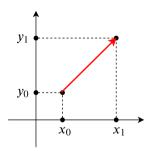
$$d_{\mathbf{e}} \begin{pmatrix} \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ \vdots & \vdots & \vdots \\ x_{n1} & x_{n2} & x_{n3} \end{bmatrix}, \begin{bmatrix} y_{11} & y_{12} & y_{13} \\ y_{21} & y_{22} & y_{23} \\ \vdots & \vdots & \vdots \\ y_{n1} & y_{n2} & y_{n3} \end{bmatrix} \end{pmatrix} = \begin{bmatrix} \sum (x_{1i} - y_{1i})^2 & \sum (x_{1i} - y_{2i})^2 & \dots & \sum (x_{1i} - y_{ni})^2 \\ \sum (x_{2i} - y_{1i})^2 & \sum (x_{2i} - y_{2i})^2 & \dots & \sum (x_{2i} - y_{ni})^2 \\ \vdots & \vdots & \vdots & \vdots \\ \sum (x_{ni} - y_{1i})^2 & \sum (x_{ni} - y_{2i})^2 & \dots & \sum (x_{ni} - y_{ni})^2 \end{bmatrix}$$

$$d_{\mathsf{e}} \left(\begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ \dots & \dots & \dots \\ x_{n1} & x_{n2} & x_{n3} \end{bmatrix}, \begin{bmatrix} y_{11} & y_{12} & y_{13} \\ y_{21} & y_{22} & y_{23} \\ \dots & \dots & \dots \\ y_{n1} & y_{n2} & y_{n3} \end{bmatrix} \right) = \begin{bmatrix} \sum (x_{1i} - y_{1i})^2 & \sum (x_{1i} - y_{2i})^2 & \dots & \sum (x_{1i} - y_{ni})^2 \\ \sum (x_{2i} - y_{1i})^2 & \sum (x_{2i} - y_{2i})^2 & \dots & \sum (x_{2i} - y_{ni})^2 \\ \dots & \dots & \dots & \dots \\ \sum (x_{ni} - y_{1i})^2 & \sum (x_{ni} - y_{2i})^2 & \dots & \sum (x_{ni} - y_{ni})^2 \end{bmatrix}$$

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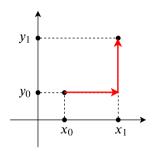
$$d_{\mathsf{e}} \begin{pmatrix} \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ \frac{x_{21}}{2} & \frac{x_{22}}{2} & \frac{x_{23}}{2} \\ \dots & \dots & \dots \\ x_{n1} & x_{n2} & x_{n3} \end{bmatrix}, \begin{bmatrix} y_{11} & y_{12} & y_{13} \\ y_{21} & y_{22} & y_{23} \\ \dots & \dots & \dots \\ y_{n1} & y_{n2} & y_{n3} \end{bmatrix} \end{pmatrix} = \begin{bmatrix} \sum (x_{1i} - y_{1i})^2 & \sum (x_{1i} - y_{2i})^2 & \dots & \sum (x_{1i} - y_{ni})^2 \\ \sum (x_{2i} - y_{1i})^2 & \sum (x_{2i} - y_{2i})^2 & \dots & \sum (x_{2i} - y_{ni})^2 \\ \dots & \dots & \dots & \dots \\ \sum (x_{ni} - y_{1i})^2 & \sum (x_{ni} - y_{2i})^2 & \dots & \sum (x_{ni} - y_{ni})^2 \end{bmatrix}$$



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$$\begin{bmatrix} \sum (x_{1i} - y_{1i})^2 & \sum (x_{1i} - y_{2i})^2 & \dots & \sum (x_{1i} - y_{ni})^2 \\ \sum (x_{2i} - y_{1i})^2 & \sum (x_{2i} - y_{2i})^2 & \dots & \sum (x_{2i} - y_{ni})^2 \\ \dots & \dots & \dots & \dots \\ \sum (x_{ni} - y_{1i})^2 & \sum (x_{ni} - y_{2i})^2 & \dots & \sum (x_{ni} - y_{ni})^2 \end{bmatrix}$$

Cityblock distance matrix



$$d_{\mathrm{cb}} \begin{pmatrix} \begin{bmatrix} x_{11} & x_{12} & x_{13} \\ x_{21} & x_{22} & x_{23} \\ \dots & \dots & \dots \\ x_{n1} & x_{n2} & x_{n3} \end{bmatrix}, \begin{bmatrix} y_{11} & y_{12} & y_{13} \\ y_{21} & y_{22} & y_{23} \\ \dots & \dots & \dots \\ y_{n1} & y_{n2} & y_{n3} \end{bmatrix} \end{pmatrix} = \begin{bmatrix} \sum |x_{1i} - y_{1i}| & \sum |x_{1i} - y_{2i}| & \dots & \sum |x_{1i} - y_{ni}| \end{bmatrix}$$

$$\begin{bmatrix} \sum |x_{1i}-y_{1i}| & \sum |x_{1i}-y_{2i}| & \dots & \sum |x_{1i}-y_{ni}| \\ \sum |x_{2i}-y_{1i}| & \sum |x_{2i}-y_{2i}| & \dots & \sum |x_{2i}-y_{ni}| \\ \dots & \dots & \dots & \dots \\ \sum |x_{ni}-y_{1i}| & \sum |x_{ni}-y_{2i}| & \dots & \sum |x_{ni}-y_{ni}| \end{bmatrix}$$

- Use operations over the whole array instead of over single elements.
- ✓ When working with arrays, use ufuncs and general NumPy's functions.
- **X** Adapt your solutions to use the two points above.



```
def euclidean_distance_matrix(x, y):
    diff = x[:, np.newaxis, :] - y[np.newaxis, :, :]
    return (diff * diff).sum(axis=2)
```

$$\sum_{i} (x_{ik} - y_{jk})^2 = (\vec{x}_i - \vec{y}_j) \cdot (\vec{x}_i - \vec{y}_j) = \vec{x}_i \cdot \vec{x}_i + \vec{y}_j \cdot \vec{y}_j - 2\vec{x}_i \cdot \vec{y}_j$$

$$\sum_{k} (x_{ik} - y_{jk})^2 = (\vec{x}_i - \vec{y}_j) \cdot (\vec{x}_i - \vec{y}_j) = \vec{x}_i \cdot \vec{x}_i + \vec{y}_j \cdot \vec{y}_j - 2\vec{x}_i \cdot \vec{y}_j$$

 $\vec{x}_i \cdot \vec{y}_j
ightarrow \mathbf{x}$ @ y.T

: Matrix product of $\{\vec{x}\}$ and $\{\vec{y}\}$

$$\sum_{k} (x_{ik} - y_{jk})^2 = (\vec{x}_i - \vec{y}_j) \cdot (\vec{x}_i - \vec{y}_j) = \vec{x}_i \cdot \vec{x}_i + \vec{y}_j \cdot \vec{y}_j - 2\vec{x}_i \cdot \vec{y}_j$$

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 $ec{x}_i \cdot ec{x}_i o$ (x * x).sum(axis=1) : A vector of elements $\sum_j x_{ij} x_{ij} \equiv \sum_j x_{ij}^2$

 $ec{y}_j \cdot ec{y}_j o$ (y * y).sum(axis=1) : A vector of elements $\sum_j y_{ij} y_{ij} \equiv \sum_j y_{ij}^2$

$$\sum_{i} (x_{ik} - y_{jk})^2 = (\vec{x}_i - \vec{y}_j) \cdot (\vec{x}_i - \vec{y}_j) = \vec{x}_i \cdot \vec{x}_i + \vec{y}_j \cdot \vec{y}_j - 2\vec{x}_i \cdot \vec{y}_j$$

$$\vec{x}_i \cdot \vec{y}_j
ightarrow x$$
 @ y.T

$$\vec{x}_i \cdot \vec{x}_i \rightarrow (x * x).sum(axis=1)[:, np.newaxis]$$

$$ec{y}_j \cdot ec{y}_j
ightarrow$$
 (y * y).sum(axis=1)[np.newaxis, :]

```
def euclidean_distance_matrix(x, y):
    x2 = (x * x).sum(axis=1)[:, np.newaxis]
    y2 = (y * y).sum(axis=1)[np.newaxis, :]
    xy = x @ y.T
    return np.abs(x2 + y2 - 2 * xy)
```

Cityblock distance matrix

$$\sum_{k} |x_{ik} - y_{jk}|$$

The trick we used for the Euclidean distance matrix doesn't work here!

Compiled code



Numba is an open source just-in-time (JIT) compiler that translates a subset of Python and NumPy code into fast machine code.



- Translation of python functions to machine code at runtime using the LLVM compiler library
- Designed to be used with NumPy arrays
- Options to parallelize code for CPUs and GPUs and automatic SIMD Vectorization
- Support for both NVIDIA's CUDA and AMD's ROCm driver allowing to write parallel GPU code from Python.



```
def reduce(x):
    x_sum = 0.0
    for i in range(x.shape[0]):
        x_sum += x[i]
    return x_sum
```



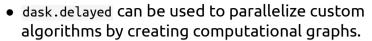
import numba

```
@numba.jit(nopython=True)
def reduce(x):
    x_sum = 0.0
    for i in range(x.shape[0]):
        x_sum += x[i]
    return x_sum
```

Scaling workflows in clusters



dask is a flexible library for parallel computing in Python. It provides dynamic task scheduling optimized for computation as well as big data collections like parallel arrays, dataframes, and lists that extend common interfaces like NumPy and Pandas to larger-than-memory or distributed environments.



```
# regular code
                         # with dask
x = func1(\langle args \rangle)
                     x = dask.delayed(func1)(<args>)
y = func2(<args>)
                         y = dask.delayed(func2)(<args>)
z = func3(x, y)
                         z = dask.delayed(func3)(x, y)
                                 func1
                                         func2
                                    func3
                         z.compute(scheduler='threads')
```



• dask.delayed can be used to parallelize custom algorithms by creating computational graphs.



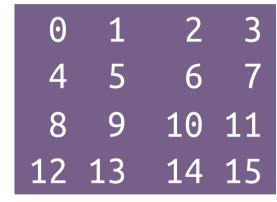
```
list delayed = [dask.delayed(func1)(<args>),
                dask.delayed(func2)(<arqs>).
                dask.delayed(func3)(<args>)]
```

```
dask.compute(*list delayed, scheduler='threads')
```



- dask.array implements a subset of the NumPy array interface using blocked algorithms, cutting up the large array into chunks of small arrays.
- dask.bag parallelizes computations across a large collection of generic Python objects.
- dask.dataframe is a large parallel DataFrame composed of many smaller Pandas DataFrames which may live on disk for larger-than-memory computing on a single machine or a cluster.

dask array





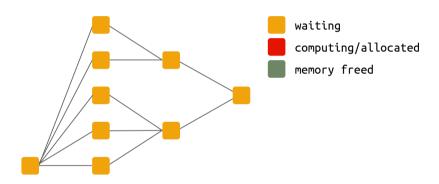
dask array

0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15

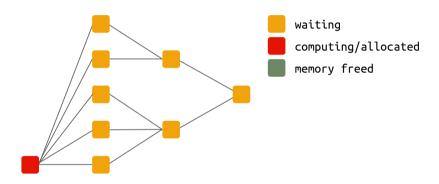


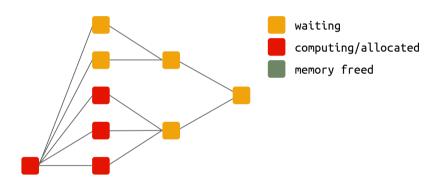
— Dask Arr NumPy Array	NumPy Array	NumPy Array	NumPy Array
NumPy	NumPy	NumPy	NumPy
Array	Array	Array	Array
NumPy	NumPy	NumPy	NumPy
Array	Array	Array	Array

- A dask array consists of many NumPy arrays arranged into a grid
- Those NumPy arrays may live on memory, disk or remote machines
- dask.array implements many of the numpy functions but in block-wise fashion and are executed through a graph.
- For equal sizes, operations on dask arrays are in general slower than the corresponding NumPy ones.

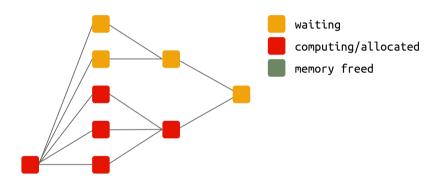




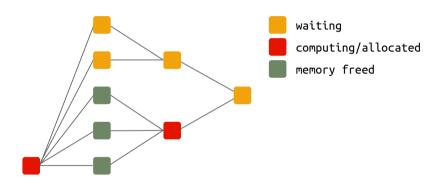




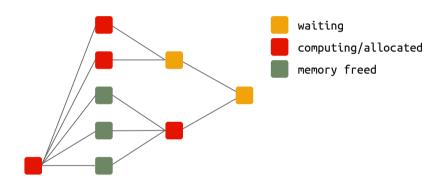




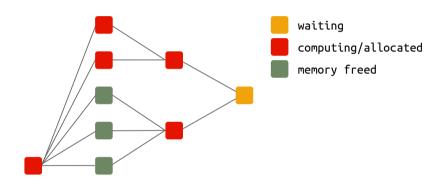




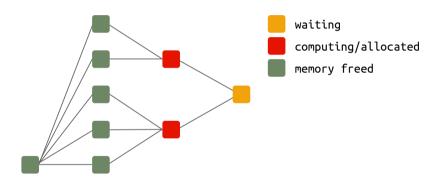


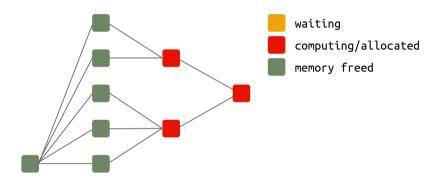


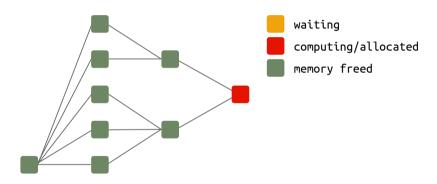


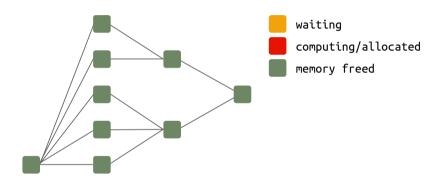














More content

 Material for the course "HPC with Python" at CSCS https://github.com/eth-cscs/PythonHPC





Thank you for your attention!

