

Weak Identification Robust Methods for Production Function Estimation

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- ▶ **Production function (PF) estimation:**

$$y = x'\beta + \omega + \varepsilon$$

Firms choose inputs x after observing state ω (Marschak and Andrews, 1944).

- ▶ **Control function approach (CFA):** Proxying ω with a control function allows to estimate β with GMM (Akerberg et al., 2015).
- ▶ **Weak identification:** When proxies have low explanatory power (measurement error) Jacobian near-singular, leading to biased, non-normal estimates and invalid standard inference.

This Paper

Contributions

1. Identification with noisy proxy feasible (under restrictions)
2. Weak proxies (small signal/noise) can cause biased estimates with non-normal distributions.
3. Adapt weak identification-robust methods: bootstrap pre-tests for proxy strength (Angelini et al., 2024) and ID-robust confidence sets (Stock and Wright, 2000).

Related Literature

Production-function identification

- ▶ Olley and Pakes (1996) (OP), Levinsohn and Petrin (2003) (LP), Akerberg et al. (2015) (ACF) discuss identification using (strong) proxies; Gandhi et al. (2020) (GNR) discuss non-identification (in nonparametric models)
- ▶ *We consider sources for weak identification*

Weak identification in structural models

- ▶ DSGE (Canova & Sala 2009), NK Phillips curve (Mavroeidis, Plagborg-Møller & Stock 2013), BLP demand (Armstrong 2016)
- ▶ *We extend this list with structural production-function estimation*

Empirical work

- ▶ Empirical applications using control function estimator
 - ▶ Trade: Pavcnik (2002); Topalova (2010); Fernandes (2007)
 - ▶ Market power: De Loecker et al. (2020); Autor et al. (2020)
 - ▶ Finance: Gopinath et al. (2017); Gourinchas et al. (2020)
- ▶ *We give guidance on model specification and add to toolbox*

Structure of Presentation

- ▶ Identification Analysis
 - ▶ Present identification strategy of CFA
 - ▶ Weak proxies
- ▶ Methods
 - ▶ Bootstrap pretest
 - ▶ AR-GMM
- ▶ Monte Carlo simulation
- ▶ Empirical Analysis
- ▶ Conclusion

Outline

Introduction

Identification Analysis

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The Control Function Approach

- ▶ General PF specification for firm i at period t :

$$y_{it} = x'_{it}\beta + \omega_{it} + \varepsilon_{it}, \quad \mathbb{E}[\varepsilon_{it} | \mathcal{I}_{it}] = 0 \quad (1)$$

- ▶ Markov process for state variable

$$\omega_{it} = \rho \omega_{it-1} + \xi_{it}, \quad \mathbb{E}[\xi_{it} | \mathcal{I}_{it-1}] = 0 \quad (2)$$

- ▶ Demand function h of intermediate inputs m

$$m_{it} = h(\omega_{it}, x_{it}) + \nu_{it} \quad (3)$$

- ▶ strictly monotonic in ω_{it}
 - ▶ allow for unobservable ν_{it} (unlike OP, LP, ACF)

- ▶ Control function

$$\begin{aligned} \omega_{it} &= h^{-1}(m_{it} - \nu_{it}, x_{it}) \\ &= \Psi(m_{it}, x_{it}) + \eta_{it}, \quad \mathbb{E}[\eta_{it} | x_{it}, m_{it}] = 0 \end{aligned}$$

- ▶ $\Psi(m, x) = E[\omega_{it} | m_{it} = m, x_{it} = x]$

Identification and Estimation

- ▶ Proxy equation (first stage)

$$y_{it} = x'_{it}\beta + \underbrace{\Psi(m_{it}, x_{it})}_{\Phi(m_{it}, x_{it})} + \eta_{it} + \varepsilon_{it}$$

- ▶ Structural equation (second stage)

$$y_{it} = x'_{it}\beta + \rho (\Phi(m_{it-1}, x_{it-1}) - x'_{it-1}\beta) - \rho\eta_{it-1} + \xi_{it} + \varepsilon_{it}$$

- ▶ Combining both stages allows estimation in one go

$$y_{it} = x'_{it}\beta + \rho (y_{it-1} - x'_{it-1}\beta) - \rho\varepsilon_{it-1} + \xi_{it} + \varepsilon_{it}$$

$$\mathbb{E}[\xi_{it} + \varepsilon_{it} - \rho\varepsilon_{it-1} | \mathcal{I}_{it-1}] = 0$$

$$z_{it} = \{x_{it-1}, m_{it-1}, \dots\} \in \mathcal{I}_{it-1}$$

- ▶ Straightforward to get CUE (Hansen et al., 1996) for ID-robust inference methods

Nonidentification & Weak Proxies

Identification in GMM

- ▶ Moment conditions of second stage

$$\mathbb{E}[f_{it}(\beta_0, \rho_0)] = \mathbb{E}\left[z_{it}(y_{it} - x'_{it}\beta - \rho_0(\Phi_{it-1} - x'_{it-1}\beta_0))\right] = 0$$

- ▶ Identification requires full-rank Jacobian

$$\mathcal{J} := \left(\mathcal{J}_\beta : \mathcal{J}_\rho\right) = \left(\mathbb{E}[z_{it}(x'_{it} - \rho_0 x'_{it-1})] : \mathbb{E}[z_{it}(\underbrace{\Phi_{it-1} - x'_{it-1}\beta_0}_{\Psi_{it-1}})]\right)$$

Nonidentification

- ▶ Assume linear control function $\Psi_{it-1} = \gamma_m m_{it-1} + x'_{it-1} \gamma_x$
- ▶ \mathcal{J} is rank-deficient, if
 - ▶ x_{it} and x_{it-1} collinear
 - ▶ $\gamma_m \rightarrow 0$

Weak proxies

- ▶ Small γ_m (weak proxies) lead to near rank-deficiency \Rightarrow Weak identification
- ▶ Example: classical measurement error in proxies attenuates γ_m

Strong ID: Standard Asymptotics

Standard Setup (Hansen, 1982)

- ▶ Parameter vector $\theta = (\beta^\top, \rho)^\top$
- ▶ Sample moments

$$f_n(\theta) = \frac{1}{n(T-1)} \sum_{i=1}^n \sum_{t=2}^T f_{it}(\theta)$$

- ▶ Estimator and Objective

$$\hat{\theta}_n = \arg \min_{\theta \in \Theta} Q_n(\theta), \quad Q_n(\theta) = n f_n(\theta)^\top W_n f_n(\theta)$$

- ▶ Under standard Assumptions, if Jacobian *full rank*
 - ▶ Consistency: $\hat{\theta}_n \xrightarrow{P} \theta_0$
 - ▶ Asymptotic normality: $\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{d} \mathcal{N}(0, V_\theta)$

Weak ID: Nonstandard Asymptotics

Partially identified Setup (Stock and Wright, 2000)

- ▶ Nearly singular Jacobian in β :

$$\mathcal{J}_\beta(\theta_0) = \Pi_n = \frac{C}{\sqrt{n}}, \quad C \text{ full column rank,}$$

with columns of C linearly independent of $\mathcal{J}_\rho(\theta_0) = r \neq 0$.

- ▶ $\hat{\rho}_n$ is \sqrt{n} -consistent
- ▶ Joint CLT

$$\sqrt{n} \begin{pmatrix} f_n(\theta_0) \\ \hat{\rho}_n - \rho_0 \end{pmatrix} \xrightarrow{d} \begin{pmatrix} \psi_f \\ \psi_\rho \end{pmatrix}$$

Limit process of sample moments

$$\sqrt{n}f_n(\beta, \hat{\rho}_n) \xrightarrow{d} \psi_f + C(\beta - \beta_0) + r\psi_\rho + O_p(1)$$

Implications

- ▶ $Q_n(\beta, \hat{\rho}_n) = O_p(1)$ for $\beta \neq \beta_0$
- ▶ No \sqrt{n} -consistency and asymptotic non-normality for $\hat{\beta}_n$

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Bootstrap pre-test for proxy relevance (Angelini et al., 2024)

- ▶ H_0 : Proxies (and instruments) are strong
- ▶ Denote full-sample estimate $\hat{\theta}_n$ with variance V_θ , and BS estimate $\hat{\theta}_n^*$
- ▶ Statistic: $\Gamma_n^* = \sqrt{n} \hat{V}_\theta^{-1/2} (\hat{\theta}_n^* - \hat{\theta}_n)$
- ▶ Asymptotically Gaussian *only* under strong proxies:

$$\Gamma_n^* \xrightarrow{d}_{H_0} \mathcal{N}(0, I)$$

- ▶ Testing Procedure
 - ▶ Draw BS samples and compute $\Gamma_{n,b}^*$ for each
 - ▶ Test (multivariate) normality of $\{\Gamma_{n,b}^*\}_{b=1}^B$
 - ▶ If reject normality: treat proxies/instruments as weak
- ▶ Key features
 - ▶ Post-test inference unaffected
 - ▶ Simplicity: only requires $\hat{\theta}_n^*$ and \hat{V}_θ (straightforward with CUE)

AR-GMM (Stock and Wright, 2000)

- ▶ $H_0 : \theta_0 = \theta^*$
- ▶ Statistic: $S(\theta^*) = nf_n(\theta^*)' \hat{V}_{ff}(\theta^*)^{-1} f_n(\theta^*)$
- ▶ Asymptotically chi-squared

$$S(\theta^*) \xrightarrow{d}_{H_0} \chi_{d_\theta}^2$$

- ▶ Confidence set by inversion

$$CS(\alpha) = \{\theta^* : S(\theta^*) \leq \chi_{d_f}^2(1 - \alpha)\} \quad (4)$$

- ▶ Key features
 - ▶ Confidence sets remain valid even under weak identification
 - ▶ Not most powerful, since also tests against overidentifying moment conditions
 - ▶ More powerful robust tests exist, e.g. Kleibergen (2002), Moreira (2003)
 - ▶ Easily implementable once we have CUE

Subset-inference (Kleibergen and Mavroeidis, 2009)

- ▶ Parameter partition: $\theta = (\theta_1, \theta_2)$
- ▶ Subset null hypothesis $H_0 : \theta_1 = \theta_1^*$
- ▶ Restricted CUE

$$\hat{\theta}_2(\theta_1^*) := \arg \min_{\theta_2} S(\theta_1, \theta_2) \big|_{\theta_1 = \theta_1^*}$$

- ▶ Asymptotics: Limiting distribution is stochastically dominated by chi-squared (equality when θ_2 is well identified)

$$S(\theta_1^*, \hat{\theta}_2(\theta_1^*)) \preceq_{H_0}^d \chi_{d_f - d_{\theta_2}}^2$$

- ▶ Confidence set

$$CS(\alpha) = \{\theta_1 : S(\theta_1, \hat{\theta}_2(\theta_1)) \leq \chi_{d_f - d_{\theta_2}}^2(1 - \alpha)\}.$$

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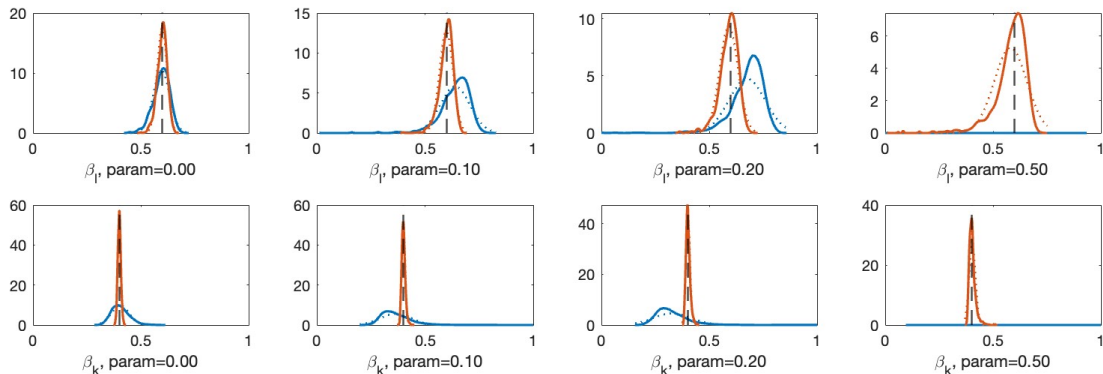
Monte Carlo

- ▶ Dynamic model of firm investment and production (ACF)
 - ▶ Two inputs capital k and labor l
 - ▶ Intermediate inputs, m , subject to measurement error
 - ▶ Tweak: reduce optimization error in l from 10% to 5%
- ▶ Estimators
 - ▶ ACF estimator
 - ▶ CUE

Table 1: Bias of simulated estimates (with standard errors). Measurement error in terms of additional % variance of m .

Meas.	ACF		CUE	
	β_l	β_k	β_l	β_k
0.0	−0.005 (0.038)	+0.005 (0.041)	−0.001 (0.023)	0.000 (0.007)
0.1	−0.500 (0.300)	−0.301 (0.299)	+0.038 (0.068)	−0.035 (0.070)
0.2	−0.445 (0.985)	−0.493 (0.983)	−0.461 (0.346)	−0.300 (0.300)
0.5	—	—	−0.532 (1.014)	−0.436 (0.968)

Monte Carlo Estimates of PF Parameters



1000 replications. ACF in blue. CUE in red. Empirical densities: solid. Normal pdf: dotted. Panels ordered left to right for larger measurement-error magnitudes.

► Measurement error \uparrow : stronger bias and non-normality

Monte Carlo: Inference on PF Parameters

Table 2: Rejection frequencies at 5 % nominal level

Meas.	Joint test (non-robust) ¹	Joint test (robust) ²	BS joint normality ³
0.0	0.064	0.060	0.057
0.1	0.059	0.048	0.068
0.2	0.075	0.062	0.167
0.5	0.128	0.050	0.431

Based on 1000 replications. ¹Wald. ²AR-GMM. ³Doornik and Hansen (2008).

- ▶ Measurement error ↑:
 - ▶ Wald over-rejects
 - ▶ AR-GMM keeps size
 - ▶ BS normality rejections ↑

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Data & empirical setting (Chile & U.S.)

- ▶ Replicate Raval (2023) and apply CUE estimator and identification-robust methods
- ▶ Chile (ENIA, plant-level)
 - ▶ Fabricated metal products (ISIC 381)
 - ▶ years 1979–1996
 - ▶ plant-year obs. $\approx 4,000$
 - ▶ Materials: plant-reported intermediate consumption (*high precision*)
- ▶ U.S. (Compustat, firm-level)
 - ▶ Manufacturing (mostly durables incl. metal products; NAICS 33)
 - ▶ years 1970–2010
 - ▶ firm-year obs. $\approx 8,000$
 - ▶ Materials: proxy via COGS – XLR; mixes labor/overhead (*lower precision*)
- ▶ Model & estimators.
 - ▶ Cobb–Douglas in k, l, m
 - ▶ Control function: third-order polynomial in k, l, m
 - ▶ Estimation: ACF baseline + CUE

Table 3: Production function estimates (Chile, ISIC 381)

Parameter	Estimates		95% CI		BS Normality ³
	ACF	CUE	Nonrobust ¹	Robust ²	p^3
β_k	0.064	0.047	[0.014, 0.080]	[0.003, 0.087]	0.0
β_l	0.122	0.053	[-0.090, 0.195]	[-0.083, 0.185]	0.0
β_m	0.875	0.956	[0.834, 1.078]	[0.848, 1.072]	0.0
Returns to scale	1.060	1.060	—	—	—

¹Wald. ²Subset AR-GMM. ³Shapiro–Wilk Normality test.

- ▶ ACF and CUE estimates in ballpark
- ▶ Non-robust and robust CI similar and rel. tight
- ▶ Normality is rejected still

Compustat, U.S. (NAICS 33)

Table 4: Production function estimates (U.S., NAICS 33)

Parameter	Estimates		95% CI		BS Normality
	ACF	CUE	Nonrobust ¹	Robust ²	p^3
β_k	0.422	0.187	$[-0.660, 1.034]$	$[-0.153, 0.507]$	0.0
β_l	0.411	0.333	$[-1.135, 1.801]$	$(-\infty, 0.787]$	0.0
β_m	0.237	0.219	$[0.106, 0.332]$	$[0.052, 0.332]$	0.0
Returns to scale	1.070	0.739	—	—	—

¹Wald. ²Subset AR-GMM. ³Shapiro–Wilk Normality test.

- ▶ CUE aligns less with ACF
- ▶ robust CIs are large, unbounded for β_l (weak ID)
- ▶ Normality again rejected

Conclusion

Findings

- ▶ Proxies with poor explanatory power (weak proxies) are source of weak identification
- ▶ Monte Carlo shows potential large imprecision and non-normality in case of weak proxies
- ▶ Robust methods ensure valid inference

Outlook

- ▶ Kitchen-sink approach for proxy
- ▶ Pretest that does not rely on BS (Andrews, 2018)
- ▶ More powerful robust inference (Kleibergen, 2005; Moreira, 2003)
- ▶ Other empirical applications

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