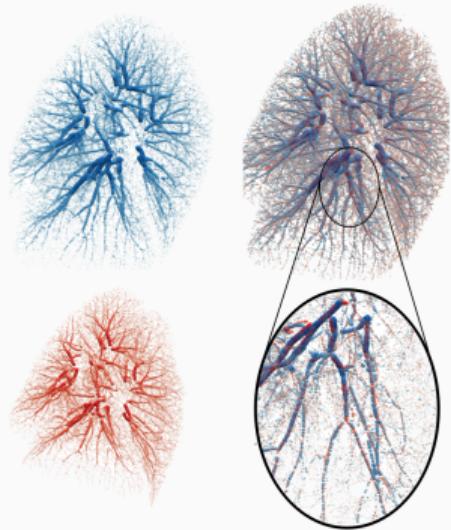


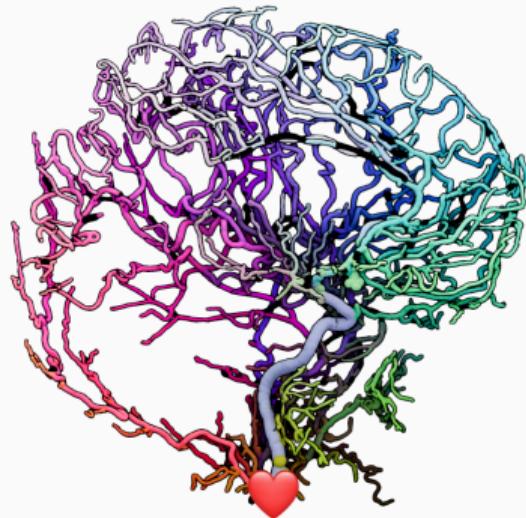
The geometric software stack: past, present, future

Jean Feydy
HeKA team, Inria Paris
Inserm, Université Paris-Cité

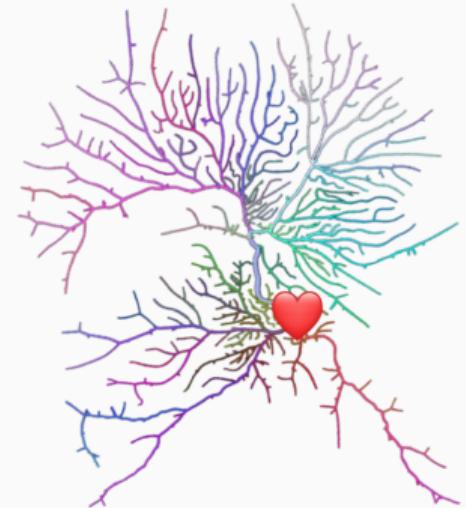
28th of October, 2024
SIGMA 2024
CIRM, Marseille



Lung **registration**.

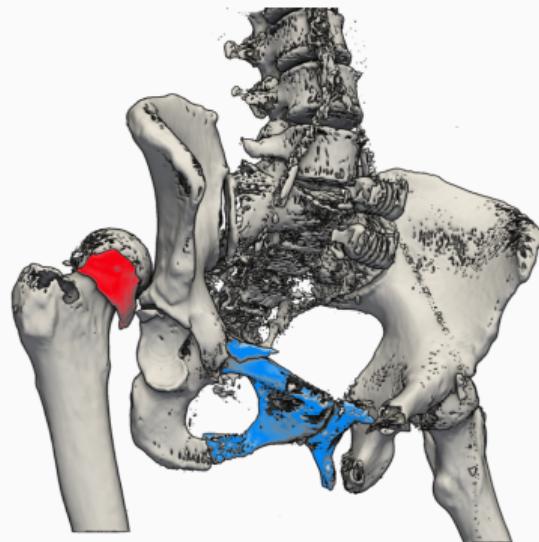


Interventional **radiology**.

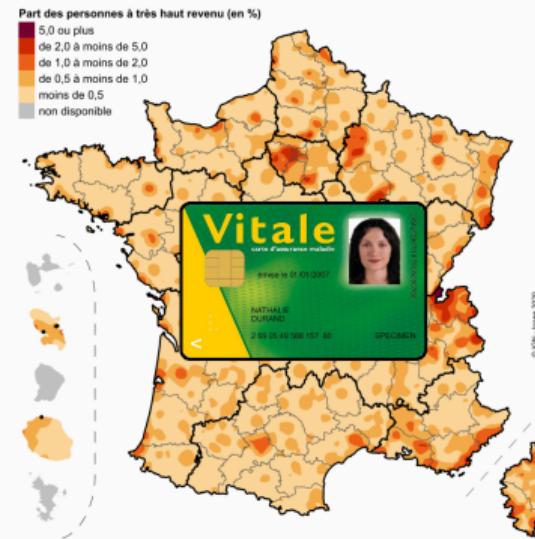


⇒ **Accessible** to you guys, but **barely anyone else**.

Recent works

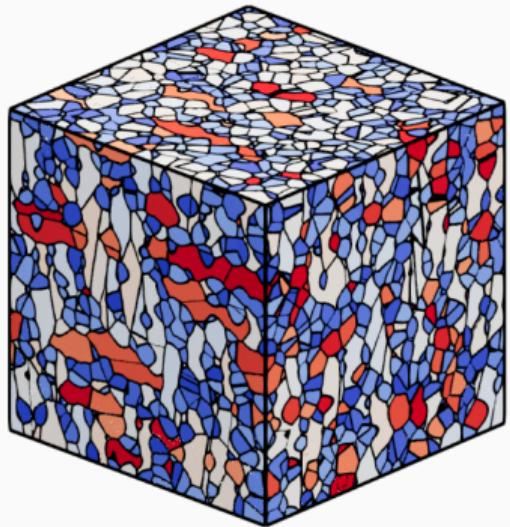


Orthopedic **surgery**.

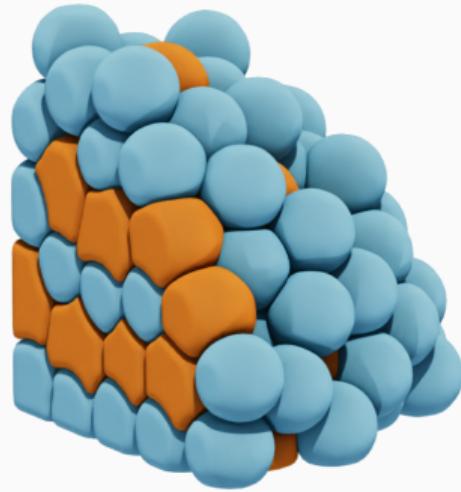


Public health.

⇒ **Accessible** to you guys, but **barely anyone else**.



Metallurgy.



Swarms of incompressible **cells**.

⇒ **Accessible** to you guys, but **barely anyone else**.

Hospitals

Inria Inserm

Universities



Geometric data analysts are in a delicate position

Our constraints:

1. Differential geometry is **not** part of the **mainstream curriculum**
⇒ High **entry cost** for students and users.
2. **Credibility** ⇔ **Performance** and high-resolution figures
⇒ Constant work to **keep up** with new technology.
3. We are already **very busy**
⇒ Our **career incentives** do **not** reward long-term software **maintenance**.

Today's talk – some practical answers to three pressing questions

1. Which **language** and **libraries** should I use?
2. Is my code still going to run in **2030**?
3. How do I get **rewarded** for all of that extra work?

Which language should I use?

The **C++ era** (2000-2015):

- High-performance C++ was **necessary** to handle **3D data**.
- **Monolithic** code-bases with a lot of **inertia**, cryptic to scientists.
- The Visualization ToolKit, the Computational Geometry Algorithms Library...

The **Python era** (since 2015):

- **Modular** and **inter-operable** tools via dictionaries and NumPy arrays.
- **Permissive** open source licences create trust.
- Scikit-learn, Scikit-image, PyVista, Vedo...

Which language should I use?

Domain-specific languages are fine too:

- **R** is data-centric: native idiom for biologists and medical doctors.
- **Julia** is convenient for numerical analysis.

But **Python** is the **lingua franca** for **gluing** pipelines together:

1. Identify the key **building blocks** in your method.
2. Implement them in the language that suits you best.
3. Write a **Python interface** – now super easy.

⇒ Speak **French**, **German** or **Hindi** at home... but publish in **English**.

KeOps – www.kernel-operations.io:

- For PyTorch, NumPy, Matlab and R, on **CPU and GPU**.
- **Automatic differentiation**.
- Just-in-time **compilation** of **optimized C++ schemes**, triggered for every new **reduction**: sum, min, etc.

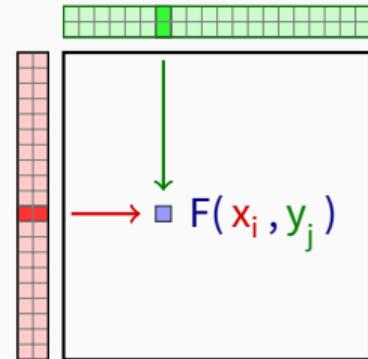
If the formula “F” is simple (≤ 100 arithmetic operations):

“ $100k \times 100k$ ” computation \rightarrow 10ms – 100ms,

“ $1M \times 1M$ ” computation \rightarrow 1s – 10s.

Hardware ceiling of 10^{12} operations/s.

$\times 10$ to $\times 100$ speed-up vs standard GPU implementations
for a wide range of problems.



Symbolic matrix

Formula + data

- Distances $d(x_i, y_j)$.
- Kernel $k(x_i, y_j)$.
- Numerous transforms.

Yet another python compiler?

Many impressive tools out there (Numba, Triton, Halide, Taichi...):

- Focus on **generality** (software + hardware).
- Increasingly easy to use via e.g. PyTorch 2.0.

KeOps fills a **scientific niche** (like FFT libraries):

- Focus on a **single major bottleneck**: geometric interactions.
- **Agnostic** with respect to Euclidean / non-Euclidean formulas.
- Fully compatible with PyTorch, NumPy, R.
- Can actually be **used by mathematicians** (**700k+** downloads).

KeOps is a **bridge** between geometers (with a maths background)
and compiler experts (with a CS background).

Which libraries should I use?

Exciting libraries get **killed** all the time :-(

Theano (2008-2017):

- **Pioneering** deep learning library: Python + Autodiff + GPU.
- Created and maintained in Montreal (MILA).
- Development stopped when **PyTorch** became available.

Taichi (2017-2023?):

- **Awesome** Python dialect for 3D shape processing and graphics, 25k GitHub stars.
- **PhD thesis** of Yuanming Hu at MIT, now **CEO** of Meshy.
- Active development stopped in the summer of 2023.

Tip #1: look at the developers' long term incentives

PyTorch (Meta) – sending all the **right signals**:

- Business strategy on AI is to make it an **open source commodity**.
- **Transparent governance structure**, PyTorch foundation.
- **Extensive** internal documentation.

JAX and TensorFlow (Google) – several **red flags**:

- Business strategy on AI is to protect the **Google search monopoly** and **GCP**.
- **Opaque** governance structure, killedbygoogle.com.
- **Minimal** internal documentation.

Tip #2: Implement a future-proof interface

Insulate users from deprecations:

- Numpy arrays.
- Human-readable files.

User-centric design:

- Principle of **least surprise**.
- Write **tutorials** – a feature that is not documented **does not exist**.
- Plain, descriptive names:

Kernel → **covariance**

Splines → **deformation**(covariance="thin plate spline")

DDMM → deformation(covariance="gaussian", scale=2, **n_steps=10**)

Problem: software rots

Some personal nightmares:

- CMake, **Boost**...
- Nvidia **actively deprecates** “old” GPUs.
- `torch.solve(A, B) = $B^{-1}A \rightarrow A^{-1}B$.`

Without **constant gardening**,
software breaks after 3-5 years.



Some of my old GitHub repositories.

Research you're proud of should be in a library

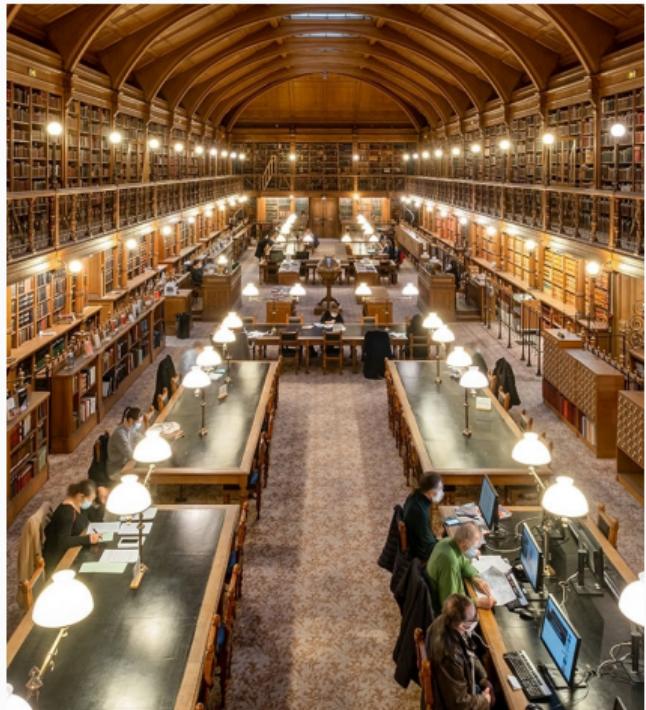
#1 – Include your model in a **pre-existing** library:

- **Outsource maintenance**, gain visibility.
- Permissive licenses are key: MIT, BSD...

#2 – Develop and maintain **your own** library:

- Be realistic: focus on your **core expertise**.
- Bet on **interoperability** with other packages.
- Freedom for you, minimize risk for users.

⇒ Agree on a **consistent interface** with
the community and **keep your word**.



*A **professional** storage facility.*

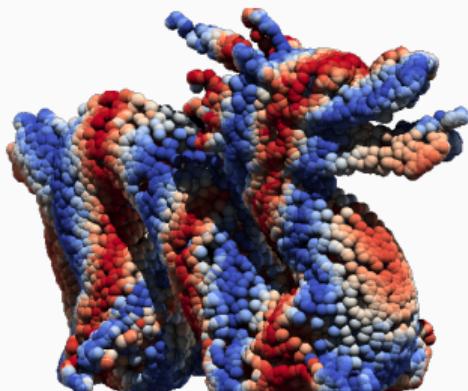
GeomLoss: scaling up optimal transport to anatomical data

Progresses of the last decade add up to a $\times 100$ - $\times 1000$ acceleration:

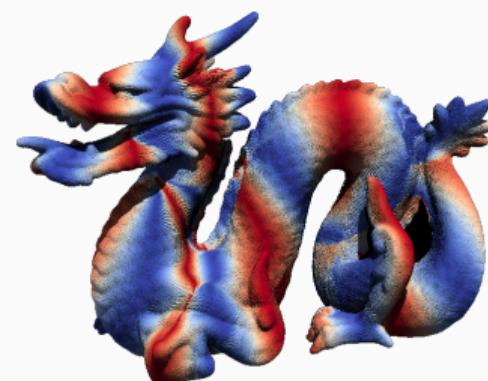
Sinkhorn GPU $\xrightarrow{\times 10}$ + KeOps $\xrightarrow{\times 10}$ + Annealing $\xrightarrow{\times 10}$ + Multi-scale

With a precision of 1%, on a modern gaming GPU:

pip install
geomloss
+
gaming GPU
(1 000 €)



10k points in 30-50ms



100k points in 100-200ms

GeomLoss: going forward

Current landscape in computational optimal transport:

- **Python Optimal Transport (POT)**: tons of tutorials, but slow solvers from 2015.
- Mérigot, Lévy, De Goes: super-fast OT solvers for **physics**.
- Schmitzer, GeomLoss: super-fast OT solvers for **geometric data**.
- Massive **waste of time for newcomers** in the field.

How to solve the issue:

- Agree on a **common interface**.
- Include GeomLoss and others as **optional backends** in POT.
- **Automated benchmark** website to highlight “solved” and “open” problems.

⇒ Put egos aside, move forward as a community.

→ Only possible because we are not judged by our h-index.

But Jean... I'm just a mathematician!

Writing good code is easy now!

Use **professional tools**:

- Black and Ruff **beautify** your code.
- Pytest and Hypothesis **find bugs**.
- Copilot **writes documentation**.
- Sphinx creates a **clean website**.
- GitHub actions **deploy automagically**.

Check out **scientific-python.org**.



*Invest in **power tools**.*

But Jean... I'm just a mathematician!

Why should I bother?

- If you don't code your method first, **no one will**.
- Get to meet a wide range of **exciting users**.
- Open up **career paths** for students.

Publish or perish?

- French open source software awards from the Ministry of research.
- At INRIA, **clear incentives** for software development.
- Career paths for **research engineers** in academia?

From Deformetrica to scikit-shapes (with an ‘s’)

scikit-shapes:

- Follows the tips above!
- Named after **scikit-image**: a reference library for classical image processing.
- Targets shape data analysis.
- **Abstracts** multiscaling and feature extraction.
- **Foundations** are now solid (Louis Pujol).
- Funded by INRIA and Prairie.

Next steps:

- GPMM, elastic metrics, functional maps.
- **Research** on robustness and modularity.
- Ready for JupyterLite + WebGPU ?

The screenshot shows the "Gallery of examples" section of the scikit-Shapes 0.1 documentation. It includes sections for "Data", "Multiscaling", and "Registration".

- Data:** Shows examples of PolyData conversion from/to PyVista or Vedo, and the PolyData class which stores point clouds, wireframes, and triangle meshes.
- Multiscaling:** Shows examples of Multiscaling (triangle mesh), Multiscaling and landmarks, and Multiscaling and signal propagation.
- Registration:** Shows the URL scikit-shapes.github.io.

scikit-shapes.github.io

Check it out in 2025!

Our community is judged by its software output



The C++ tower of Babel.



The Python market of ideas.

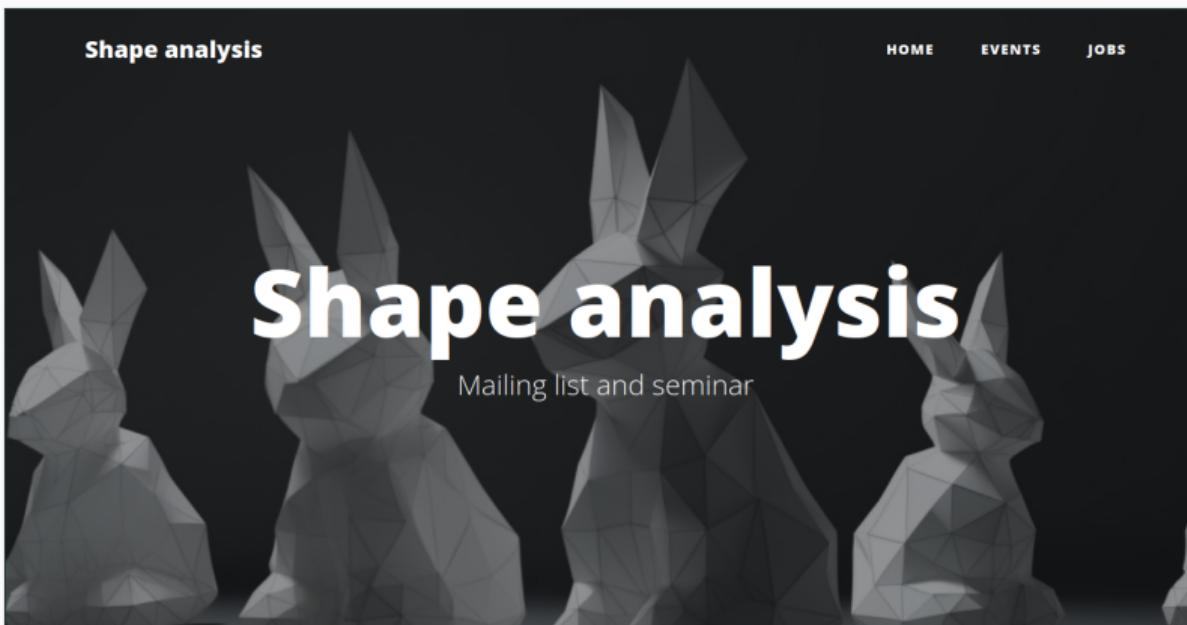
Major challenge: beyond goodwill, create **sustainable open business models**.

Are **universities** hostile environments? Kitware (VTK), Tutte Institute (UMAP), INRIA...

Documentation and tutorials are available online



shape-analysis.github.io



Monthly seminar, videos on YouTube.

References

References i
