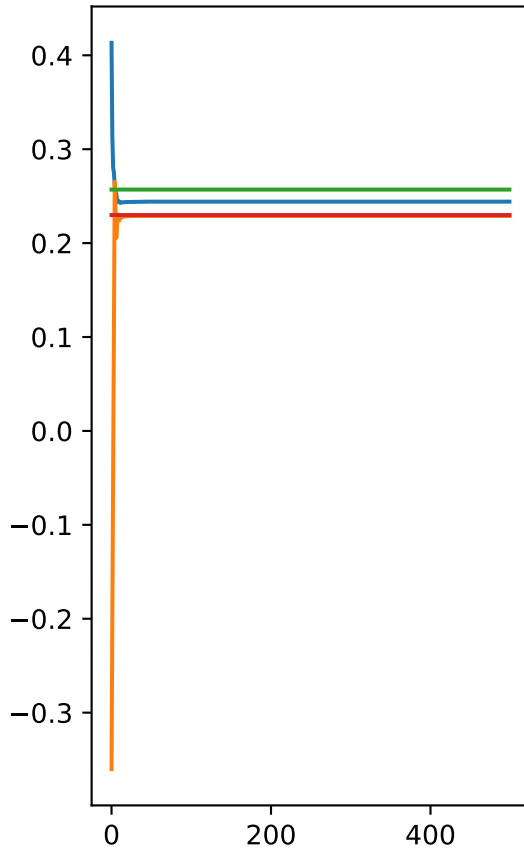
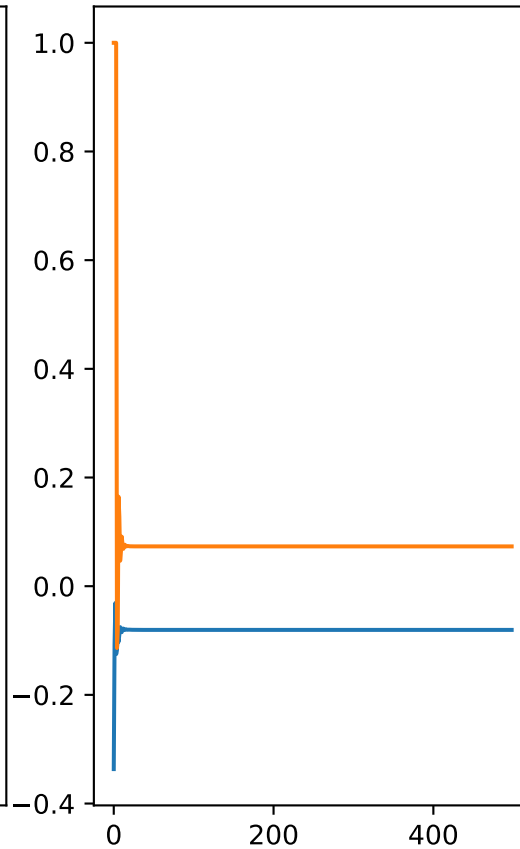


Reward: quadratic\_2  
Speed = 410.6313021288262 [rad/s]

State vs step



Action vs step



Reward vs step

