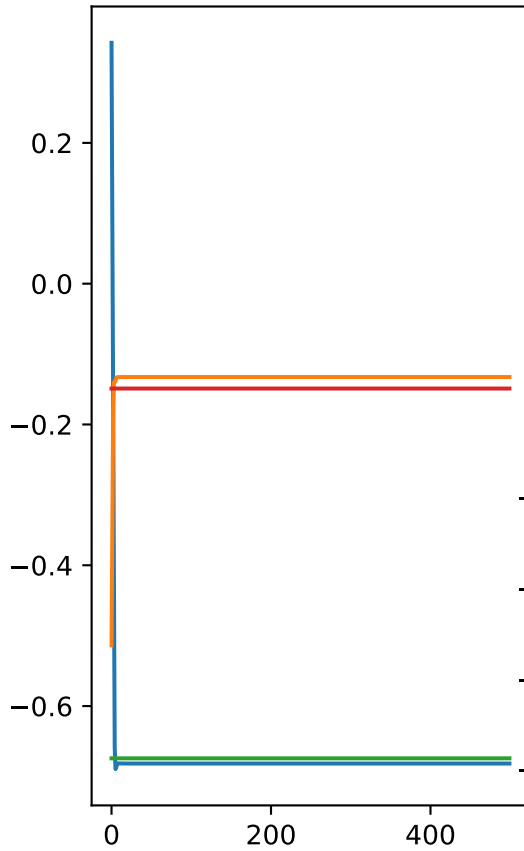
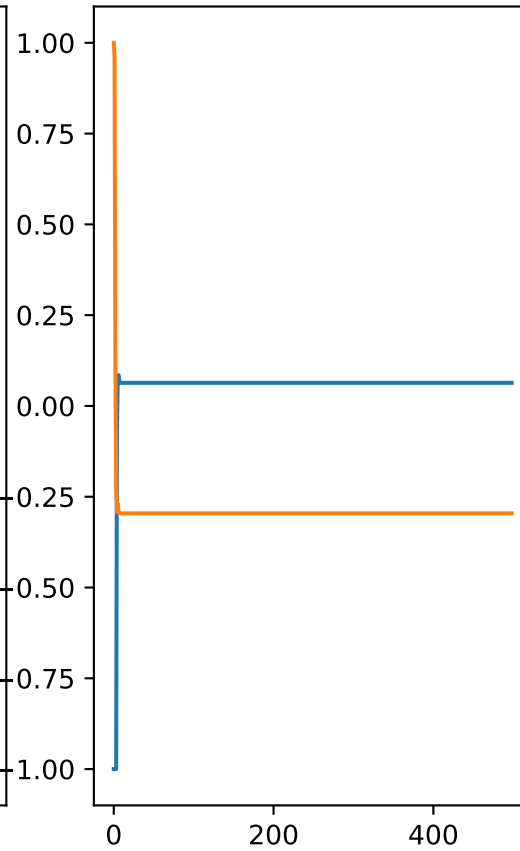


Reward: quartic_root_2
Speed = 852.6282419897911 [rad/s]

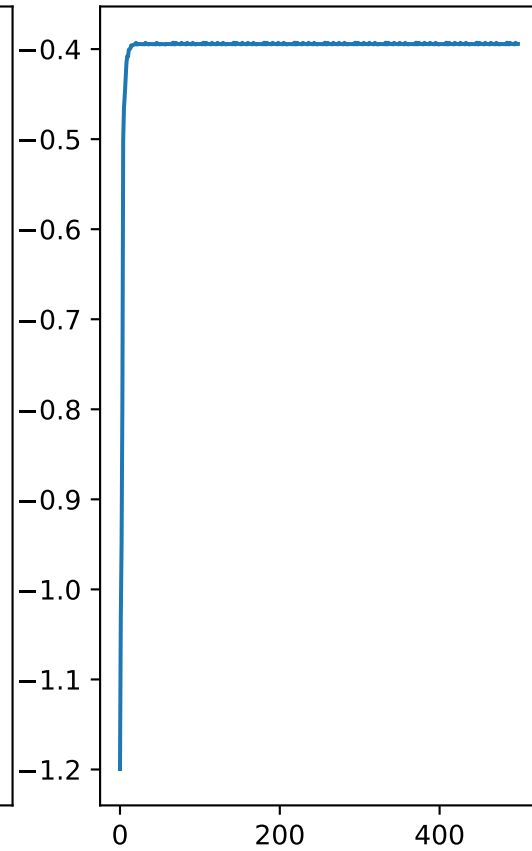
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq