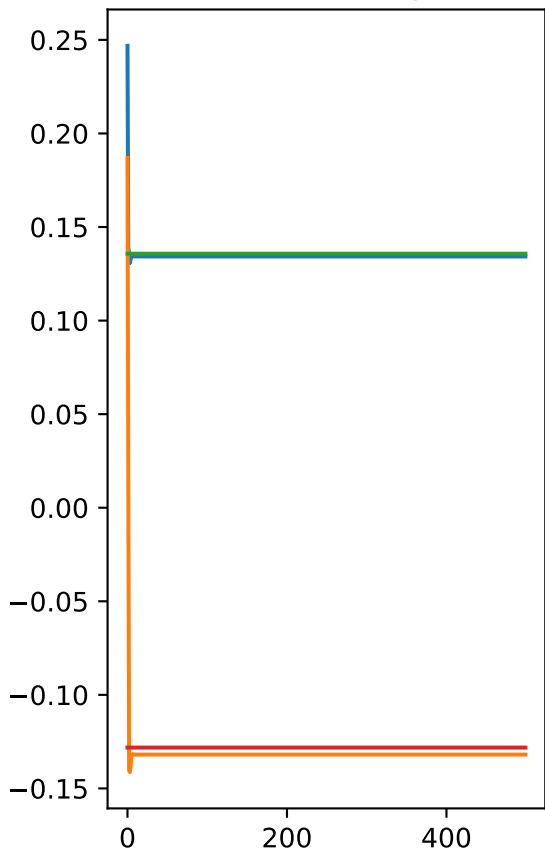
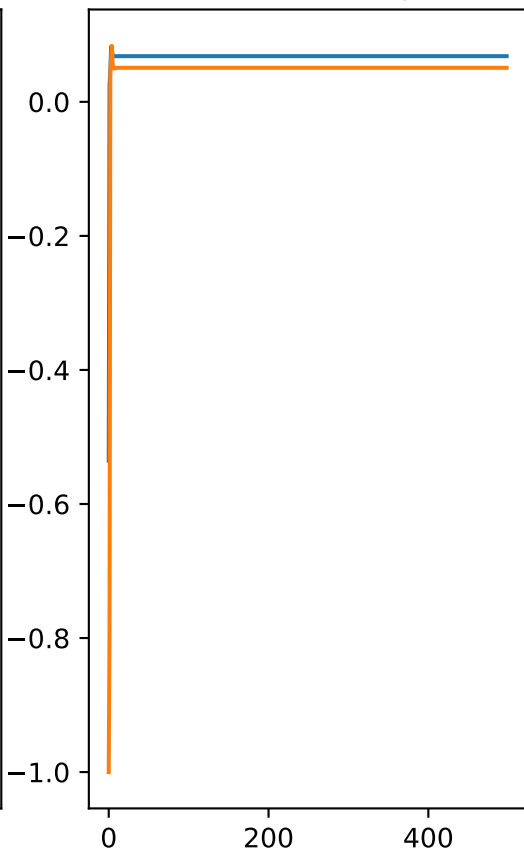


Reward: quartic\_root  
Speed = 372.60546885623825 [rad/s]

State vs step



Action vs step



Reward vs step

