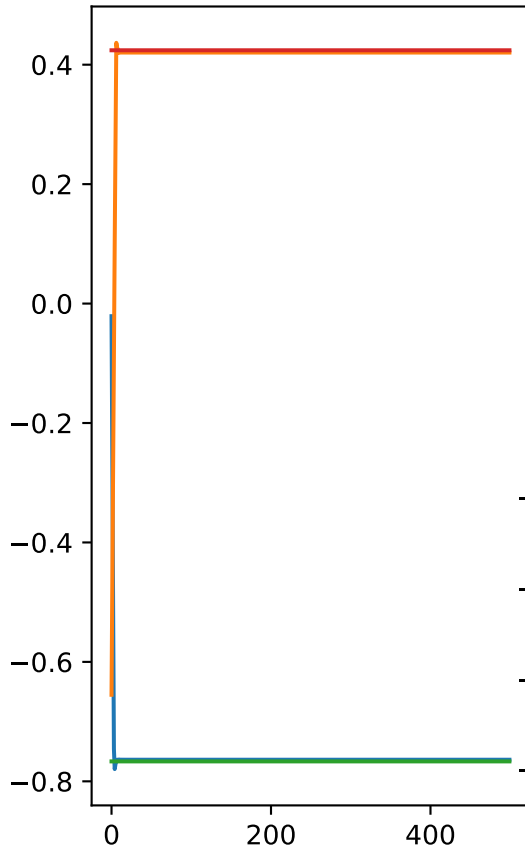
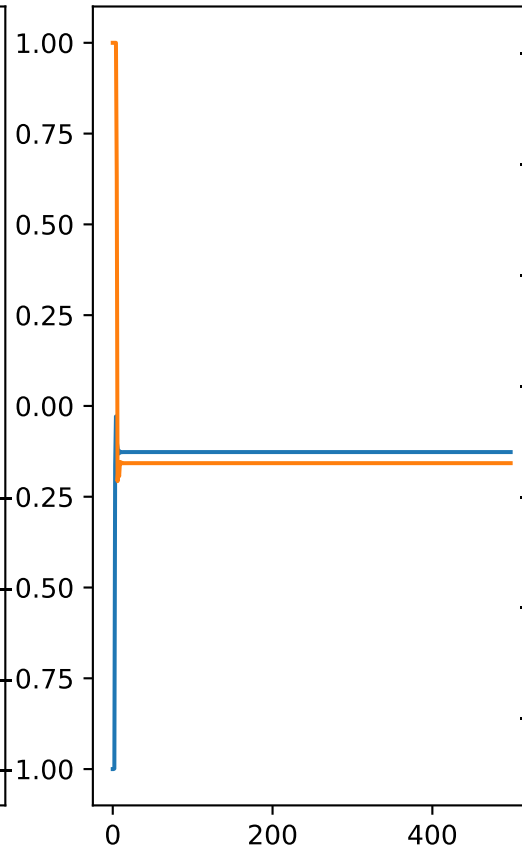


Reward: quartic_root
Speed = 98.67114203997977 [rad/s]

State vs step



Action vs step



Reward vs step

