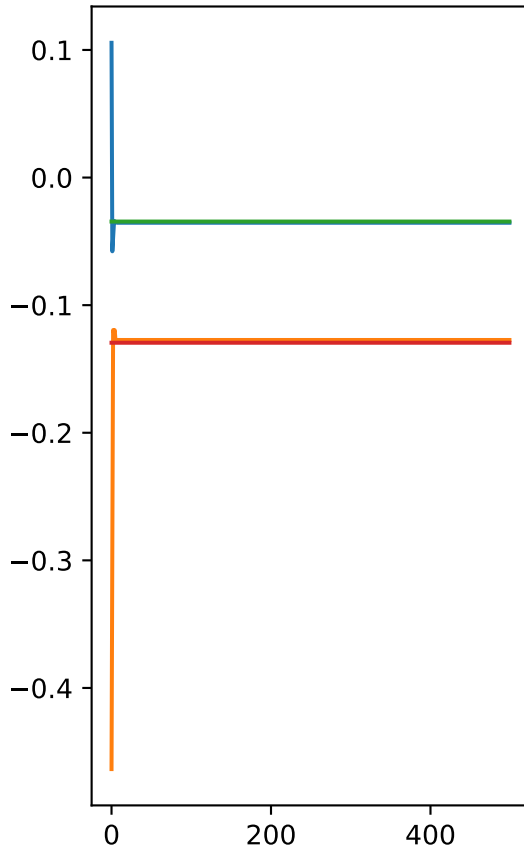
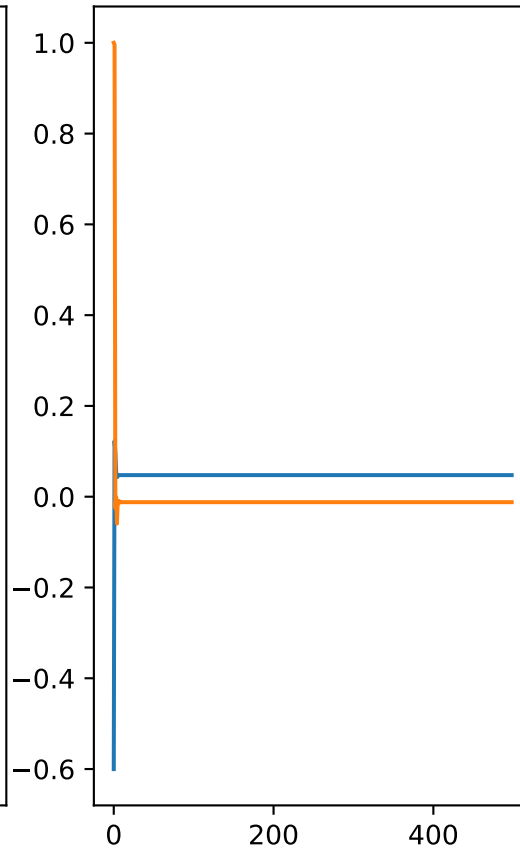


Reward: quartic_root
Speed = 213.2638699019168 [rad/s]

State vs step



Action vs step



Reward vs step

