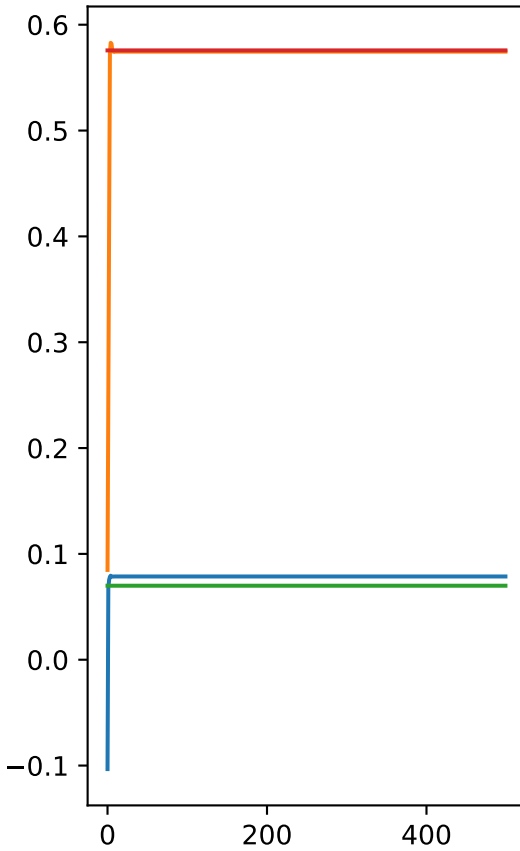
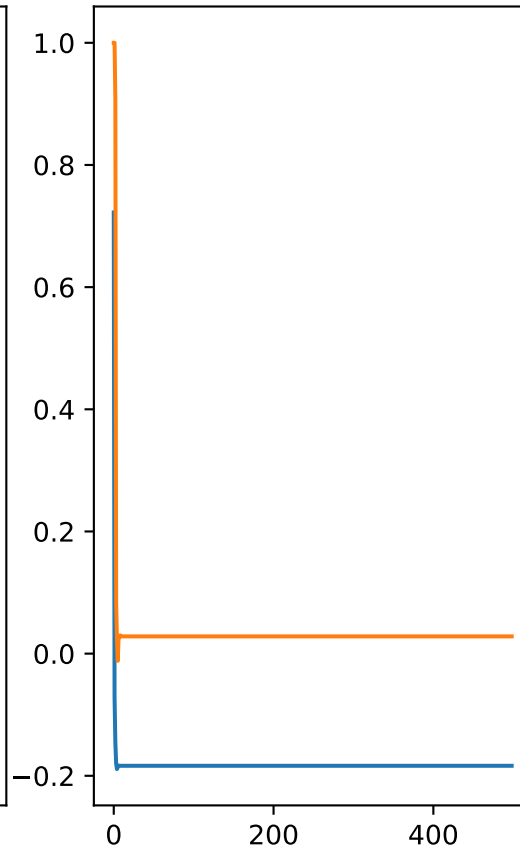


Reward: quartic_root
Speed = 190.19202736763845 [rad/s]

State vs step



Action vs step



Reward vs step

