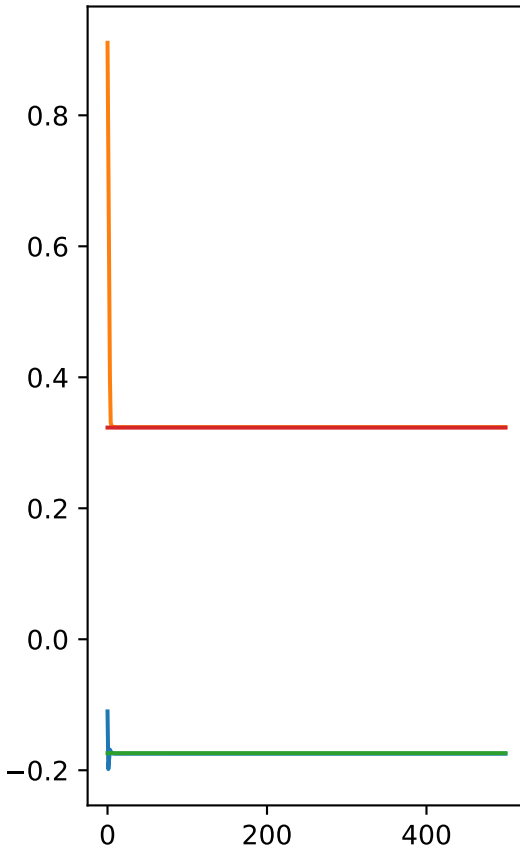
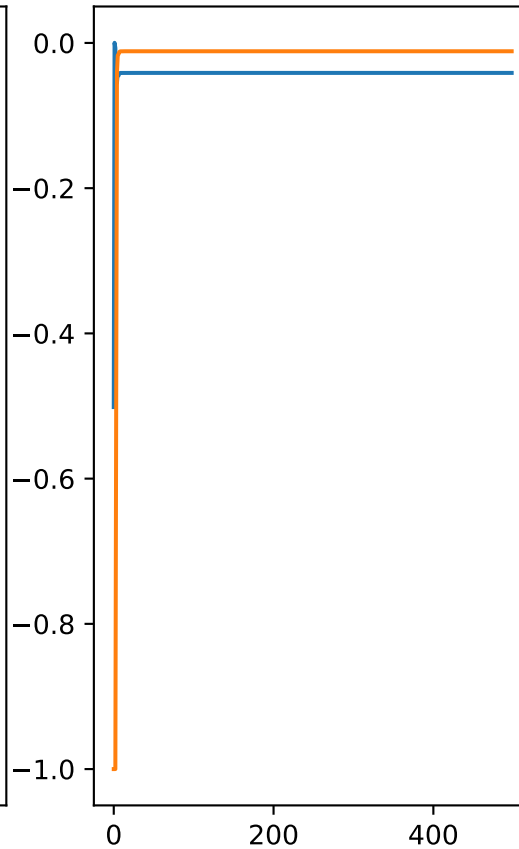


Reward: square\_root  
Speed = 578.0153458889697 [rad/s]

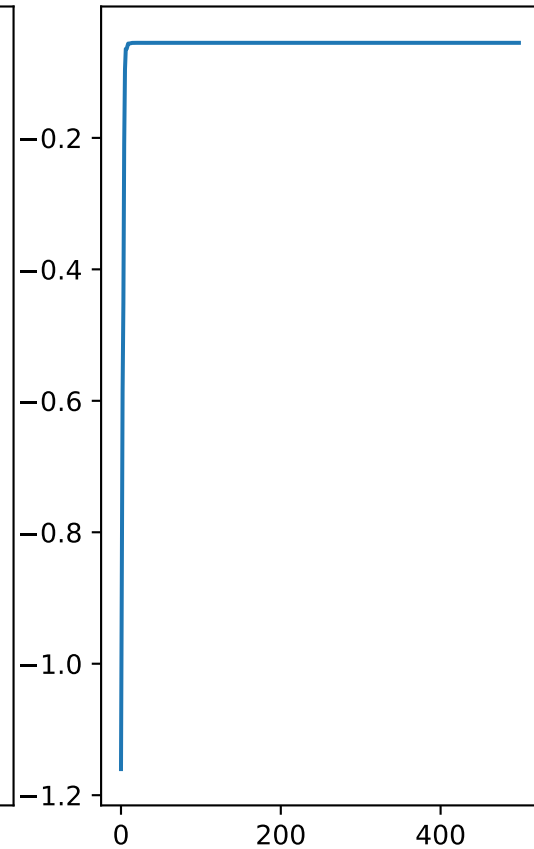
State vs step



Action vs step



Reward vs step



— Id — Idref  
— Iq — Iqref

— Vd — Vq