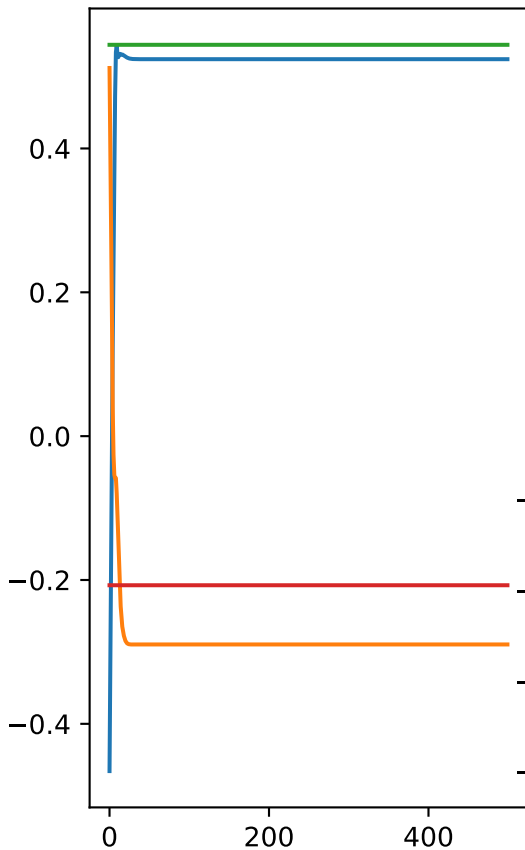
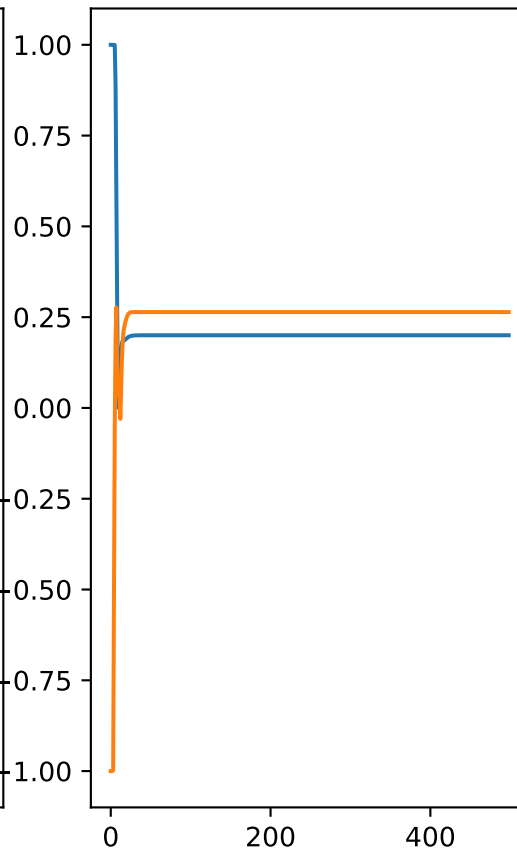


Reward: quadratic_2
Speed = 355.6534082205831 [rad/s]

State vs step



Action vs step



Reward vs step

