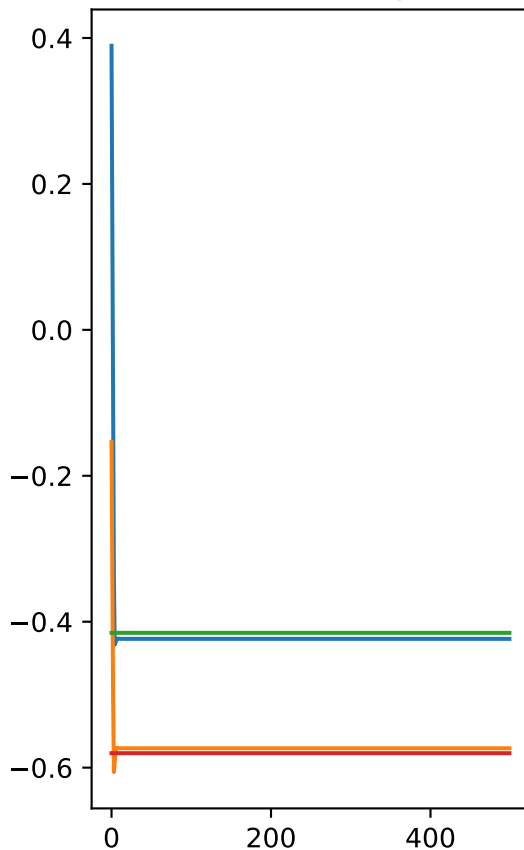
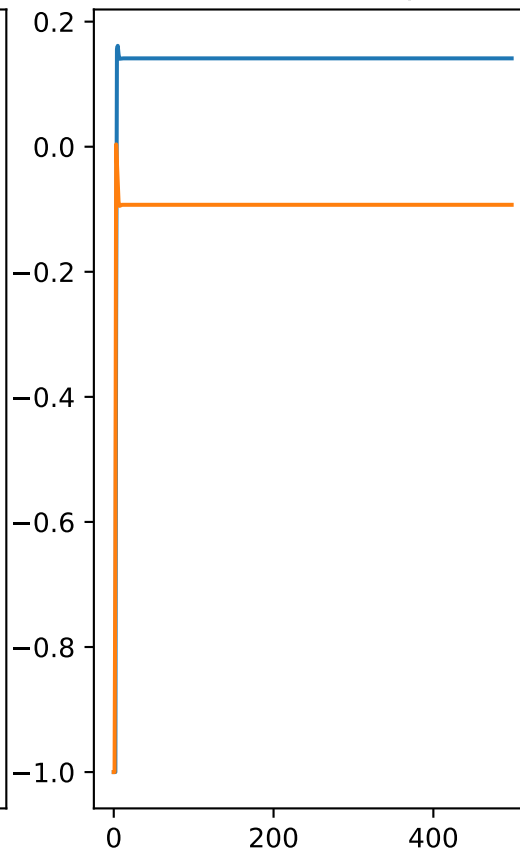


Reward: quartic_root
Speed = 196.9275924475314 [rad/s]

State vs step



Action vs step



Reward vs step

