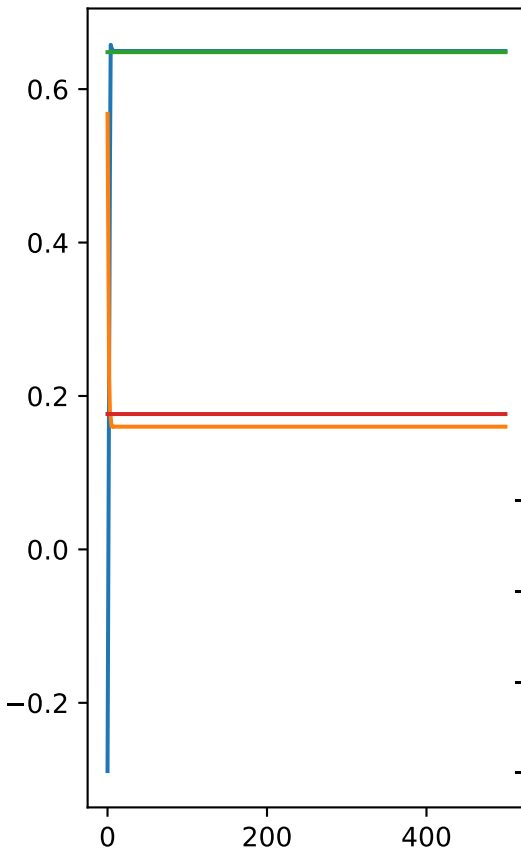
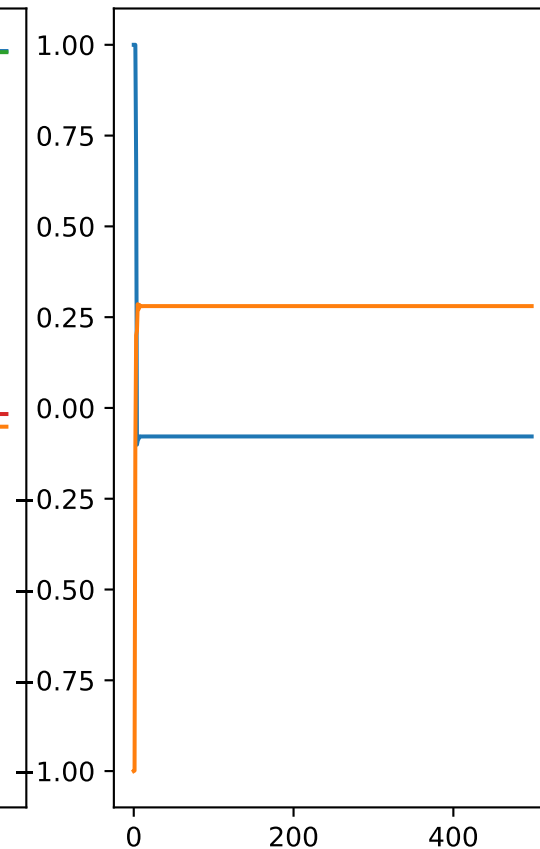


Reward: quartic_root
Speed = 620.1880954858393 [rad/s]

State vs step



Action vs step



Reward vs step

