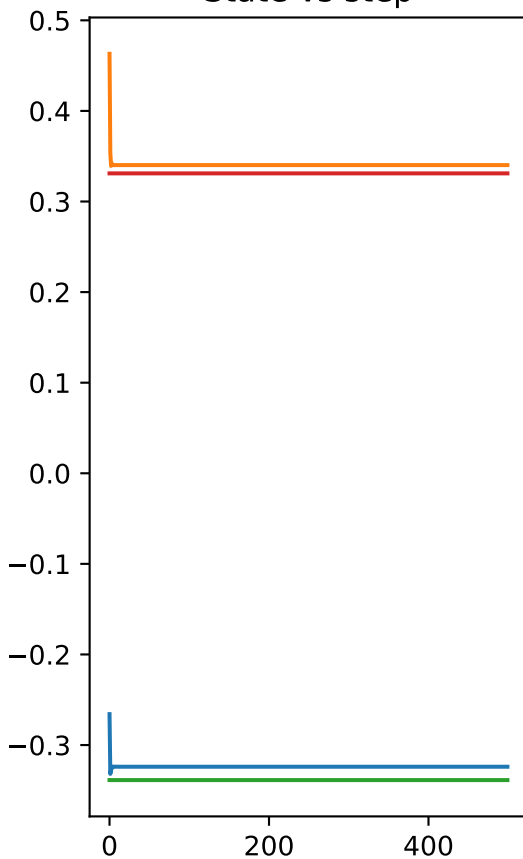
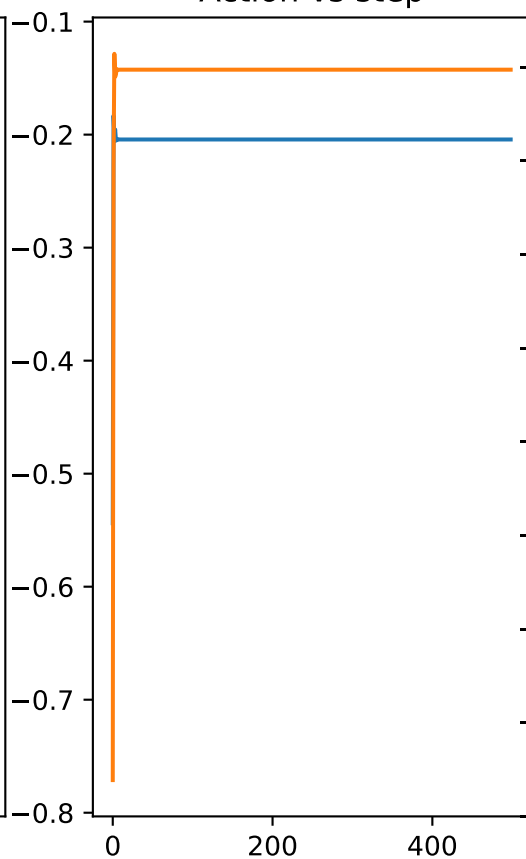


Reward: quartic_root_2
Speed = 230.32901293476485 [rad/s]

State vs step



Action vs step



Reward vs step

