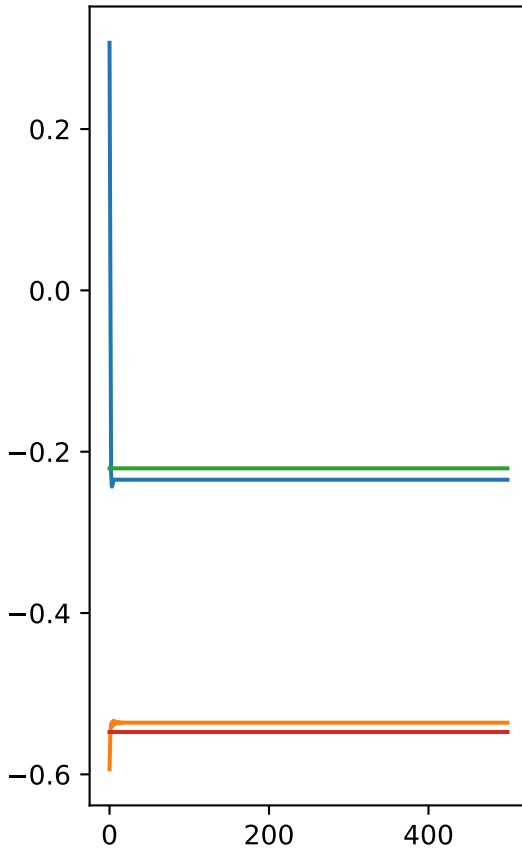
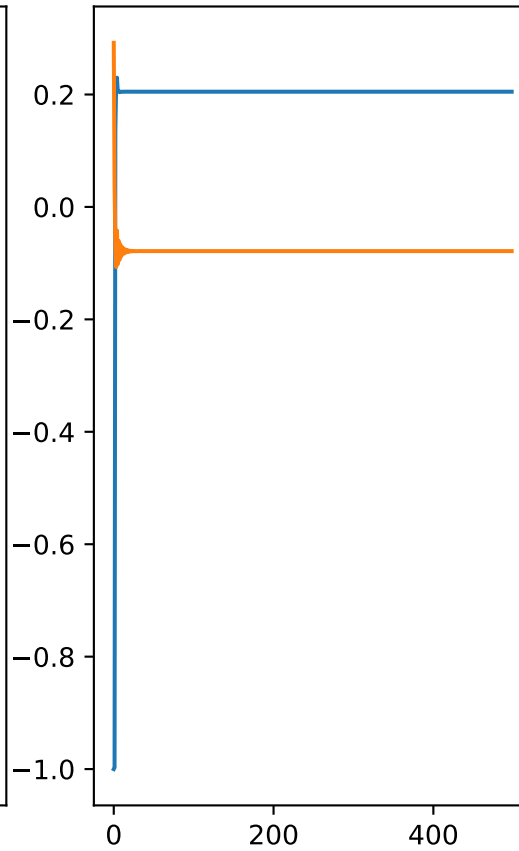


Reward: quartic_root
Speed = 181.2699030030604 [rad/s]

State vs step



Action vs step



Reward vs step

