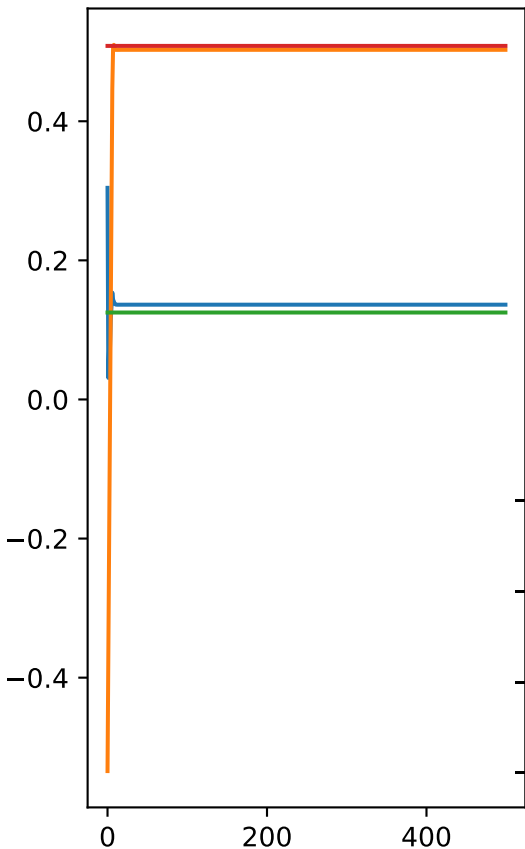
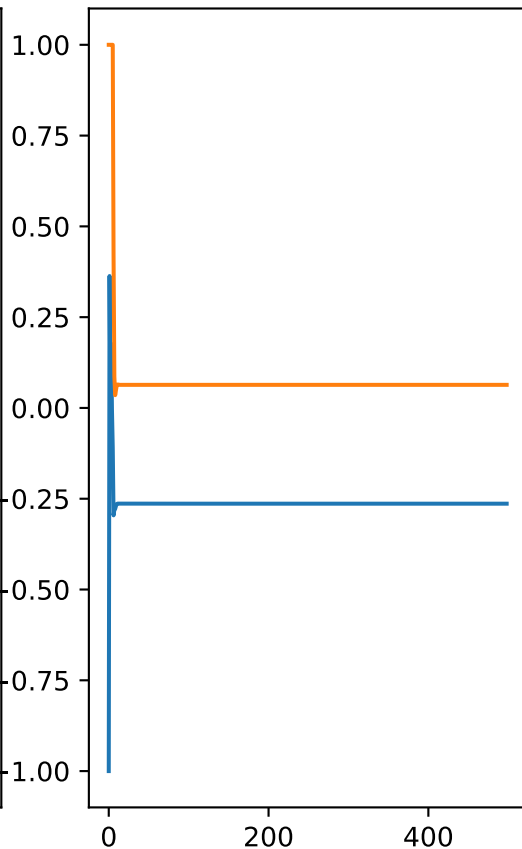


Reward: quartic_root
Speed = 1018.7556648672024 [rad/s]

State vs step



Action vs step



Reward vs step

