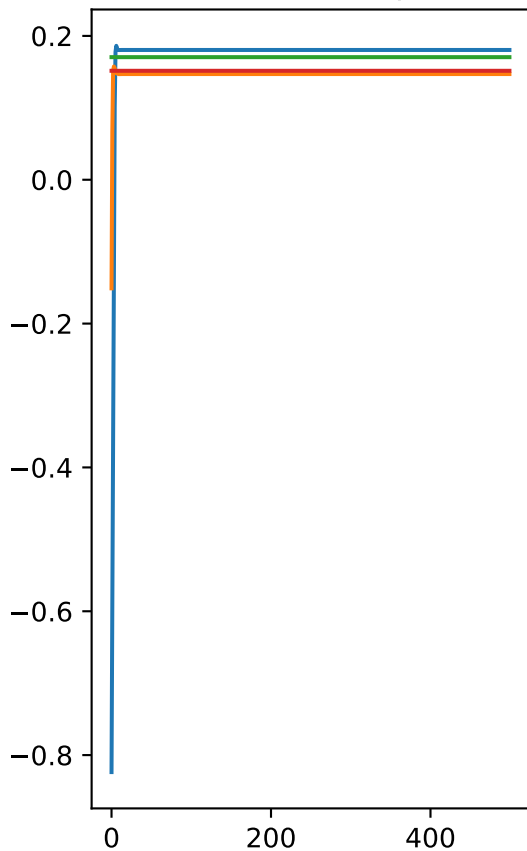
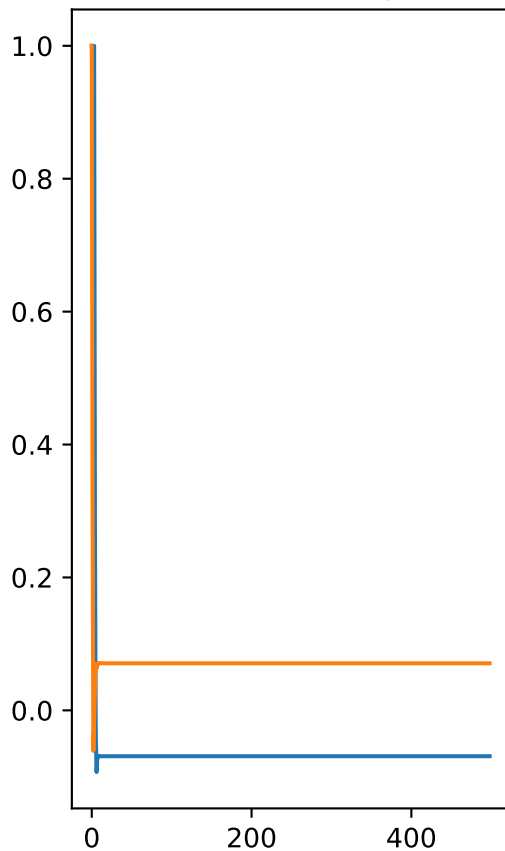


Reward: quartic_root
Speed = 253.30033778264948 [rad/s]

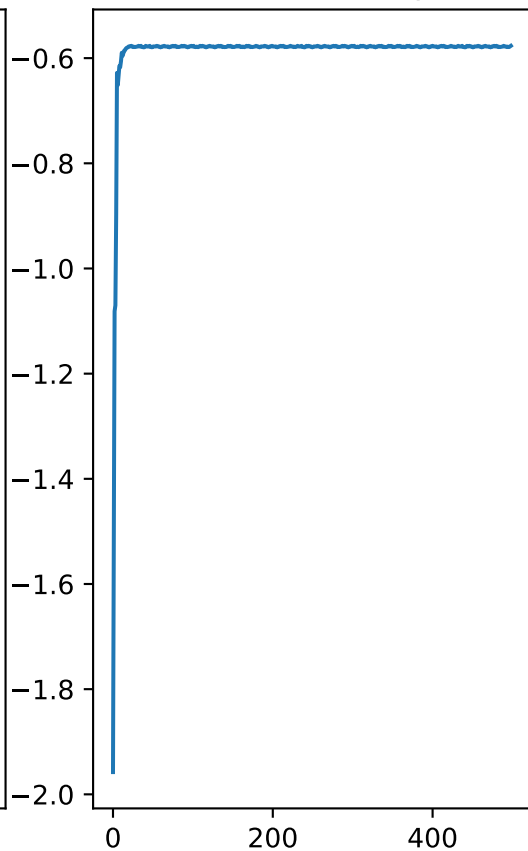
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq