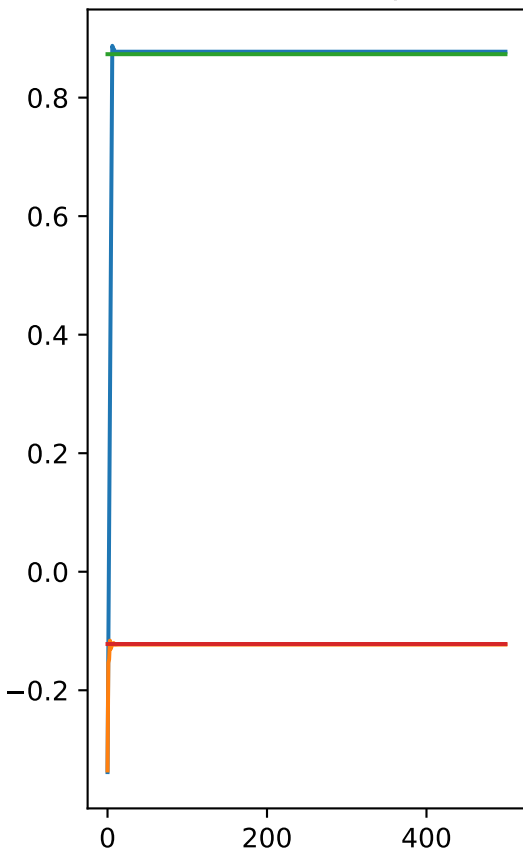
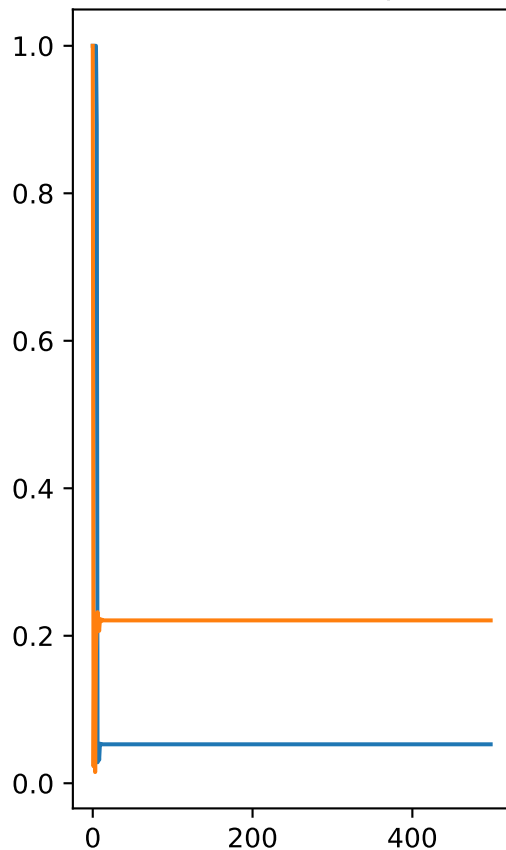


Reward: quartic_root
Speed = 36.203713799140885 [rad/s]

State vs step



Action vs step



Reward vs step

