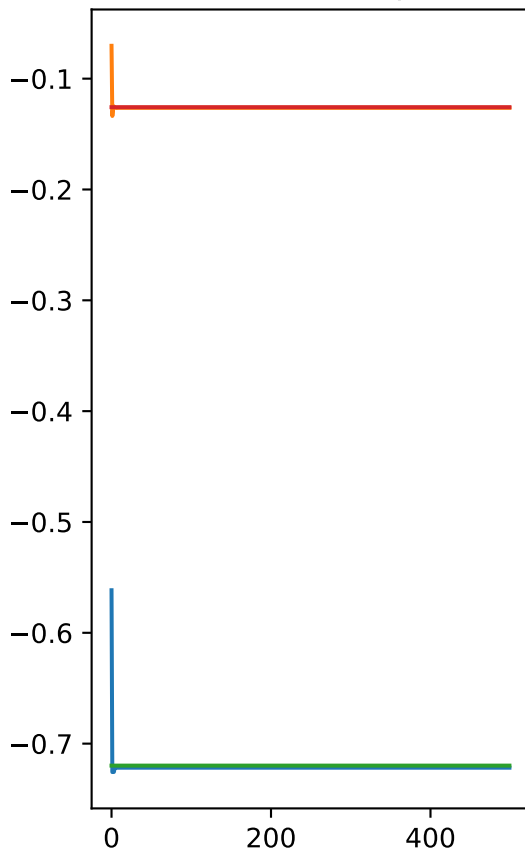
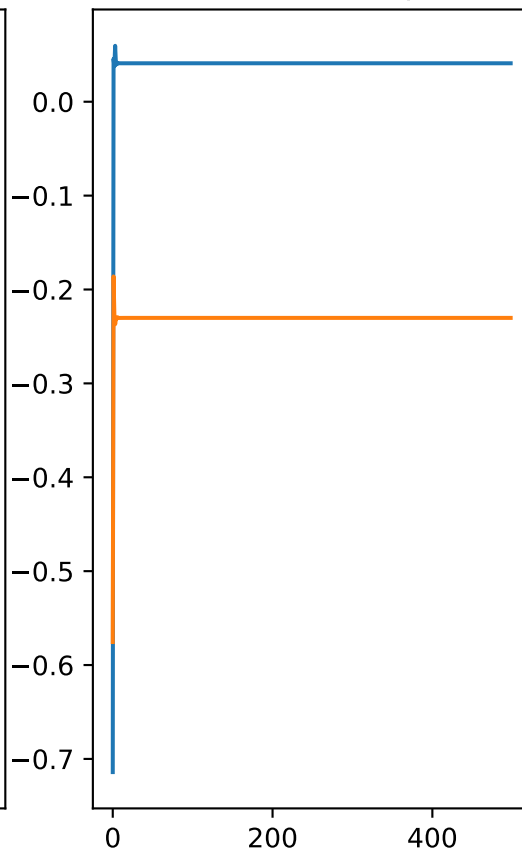


Reward: quartic_root
Speed = 146.98884040777378 [rad/s]

State vs step



Action vs step



Reward vs step

