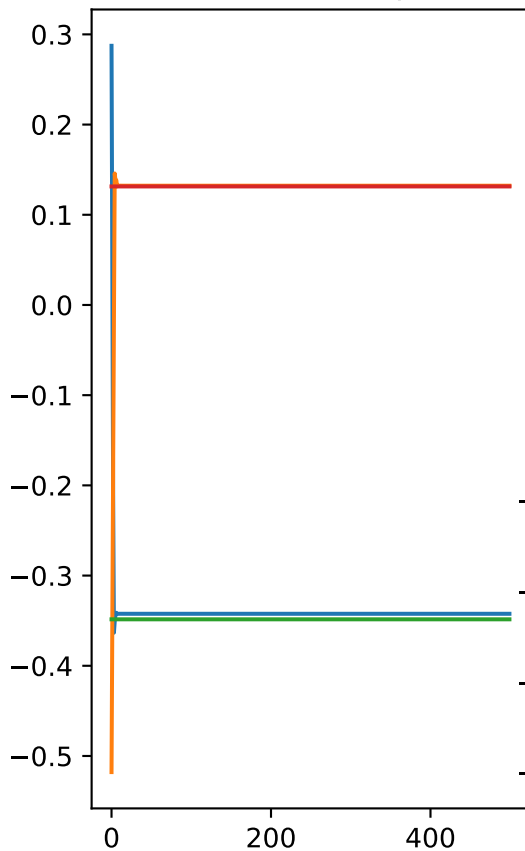
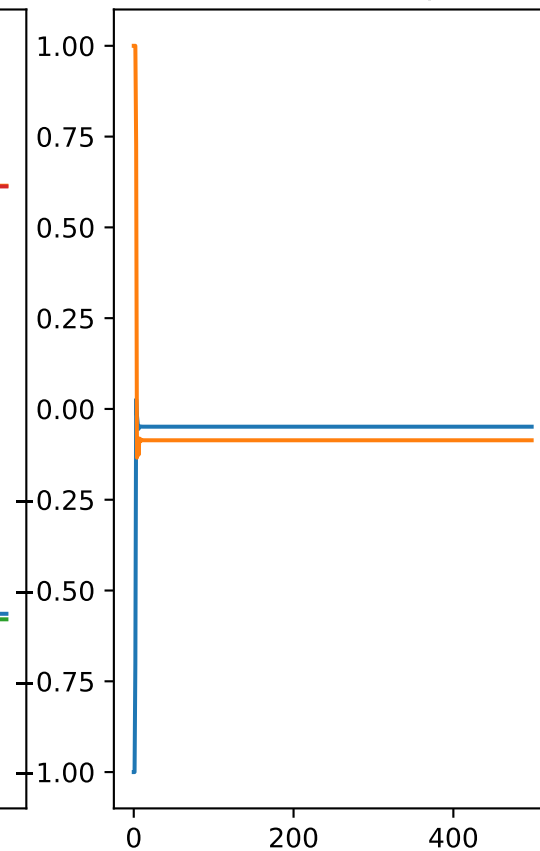


Reward: quartic_root
Speed = 894.9266386946529 [rad/s]

State vs step



Action vs step



Reward vs step

