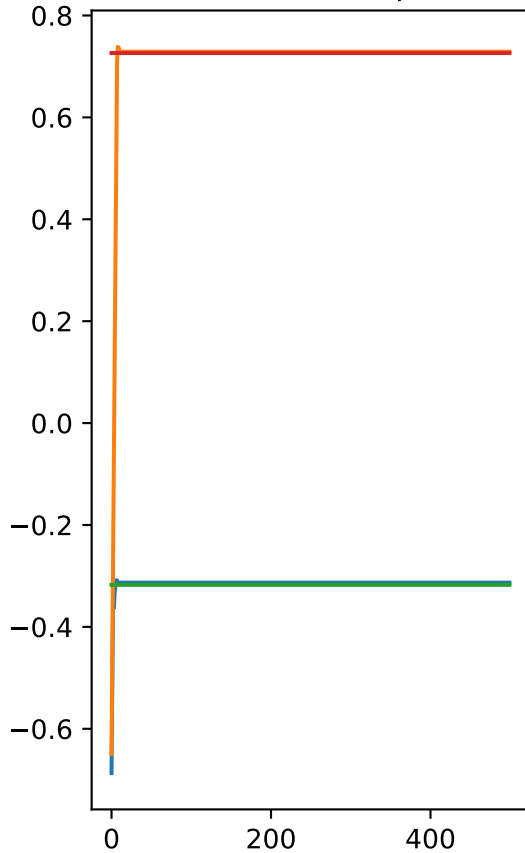
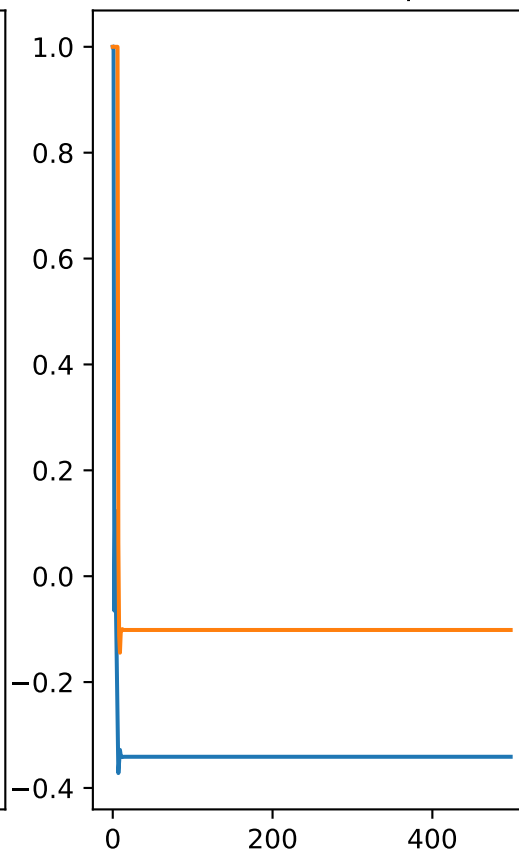


Reward: quartic_root
Speed = 893.0919287630484 [rad/s]

State vs step



Action vs step



Reward vs step

