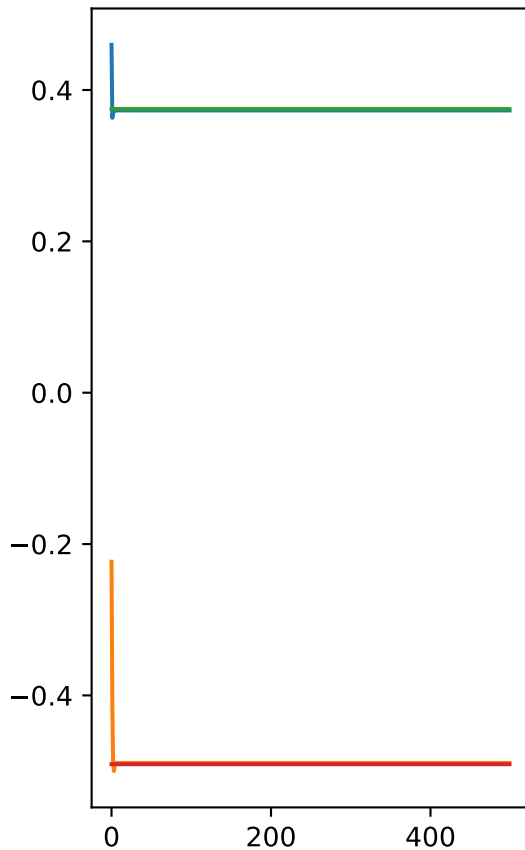
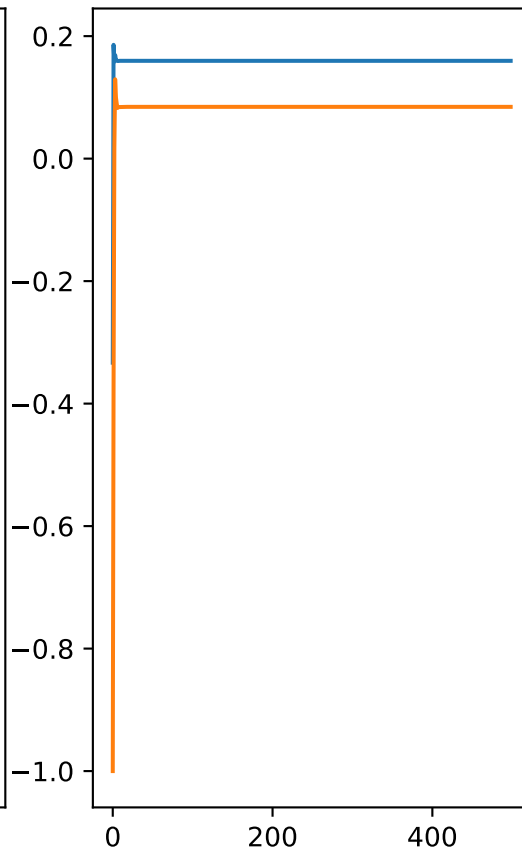


Reward: quartic_root
Speed = 230.94475866533176 [rad/s]

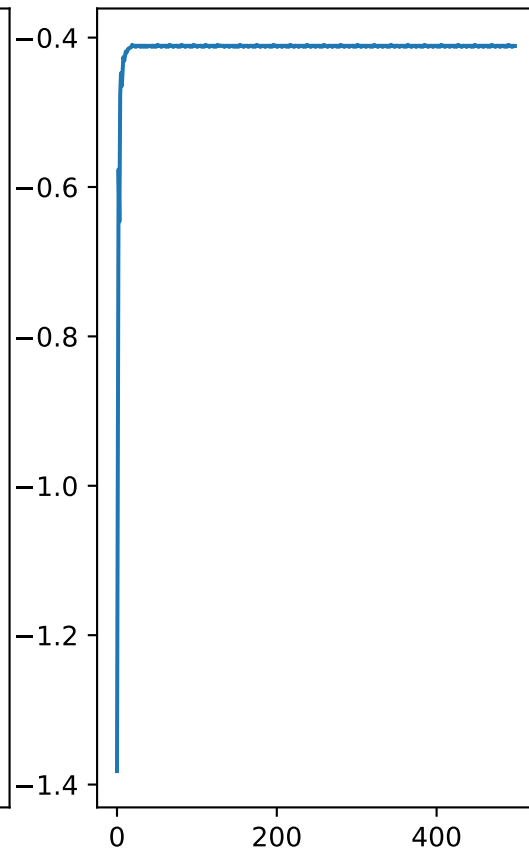
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq