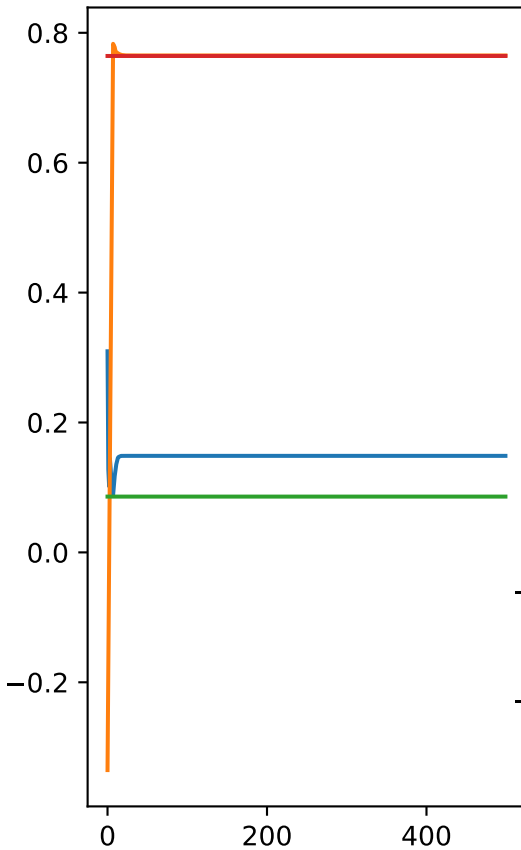
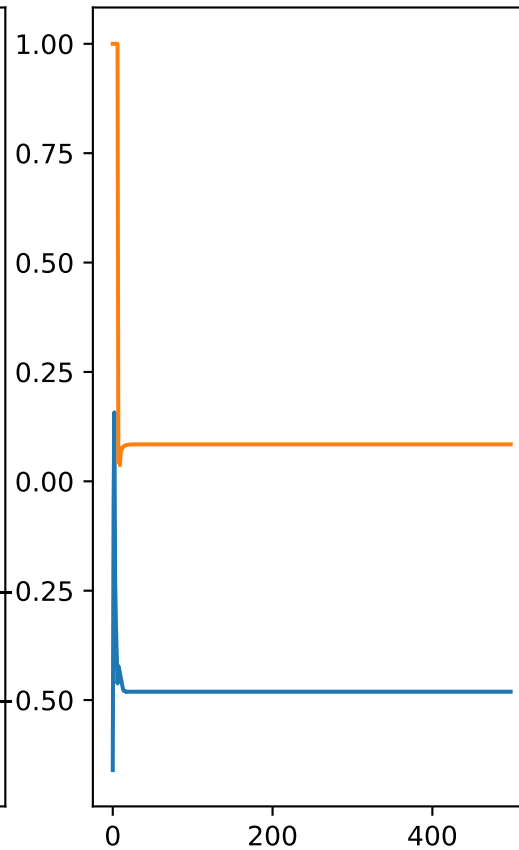


Reward: quadratic_2
Speed = 893.4814909738782 [rad/s]

State vs step



Action vs step



Reward vs step

