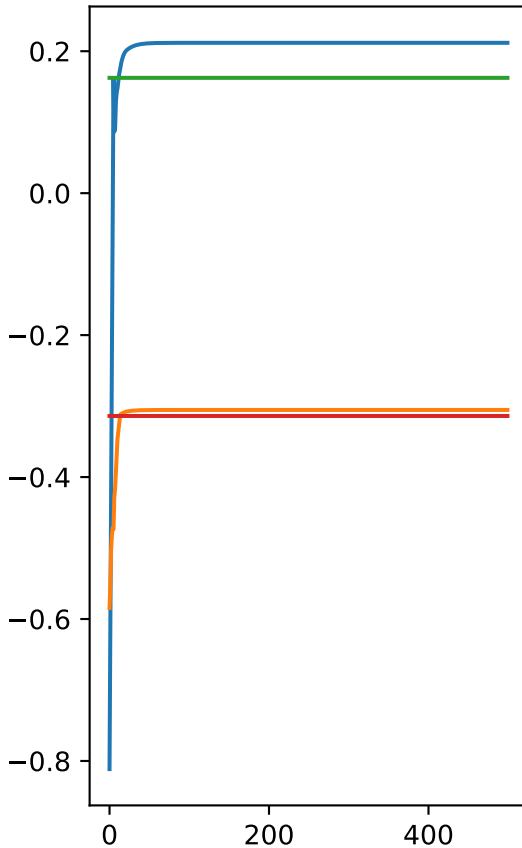
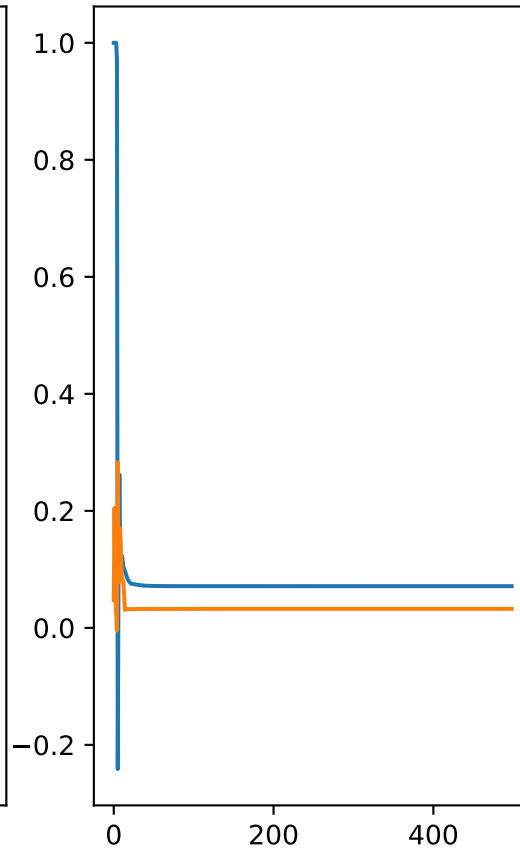


Reward: quadratic_2
Speed = 177.4497253356124 [rad/s]

State vs step



Action vs step



Reward vs step

