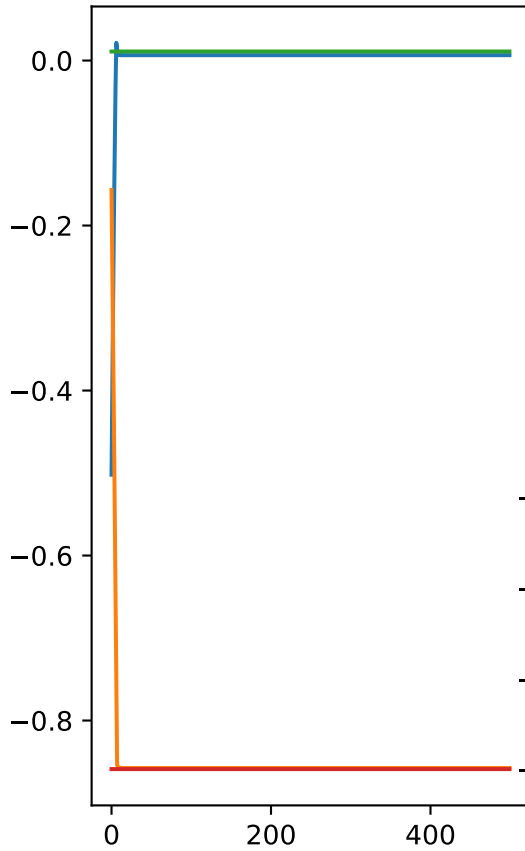
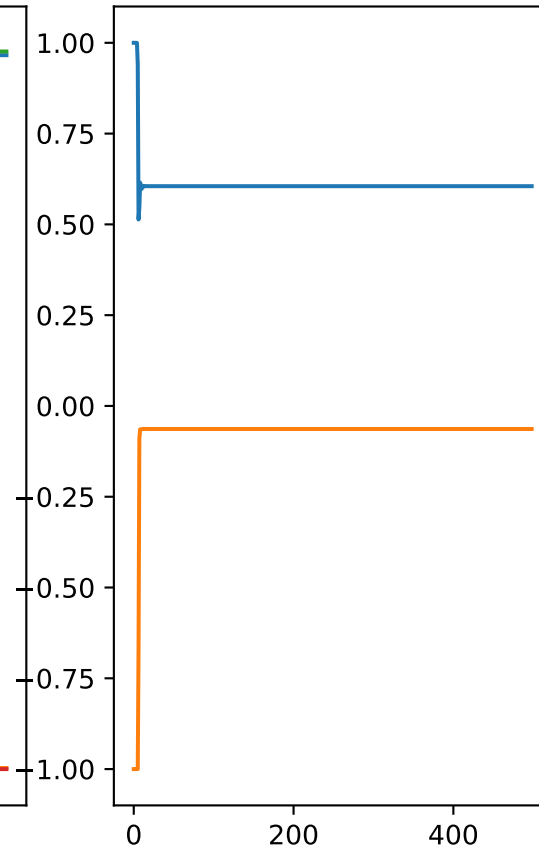


Reward: square_root_2
Speed = 802.1993726021072 [rad/s]

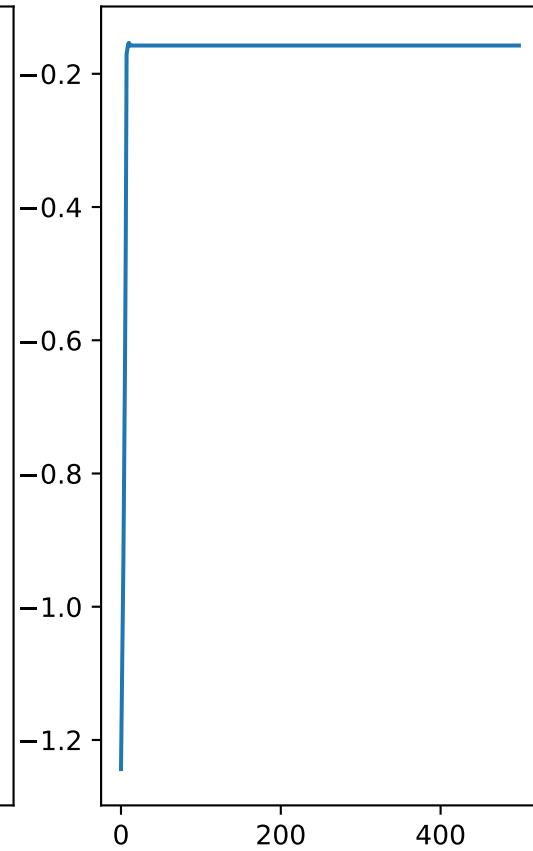
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq