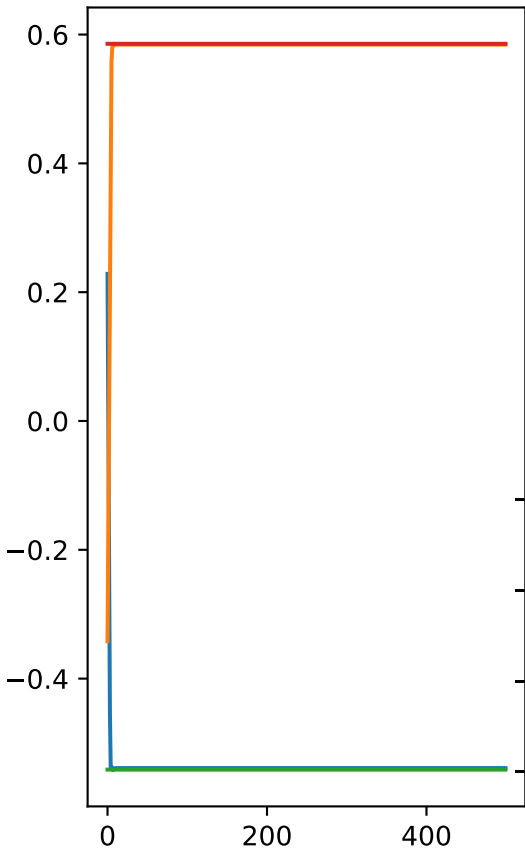
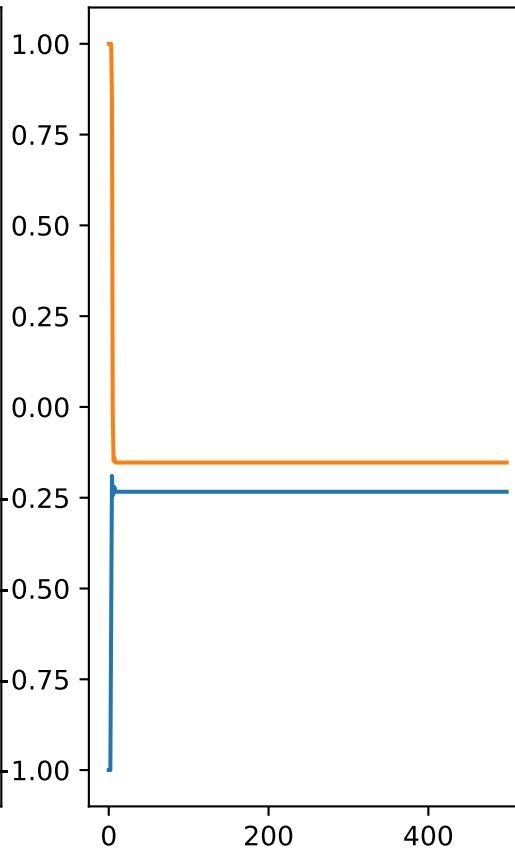


Reward: square_root
Speed = 89.37202953804687 [rad/s]

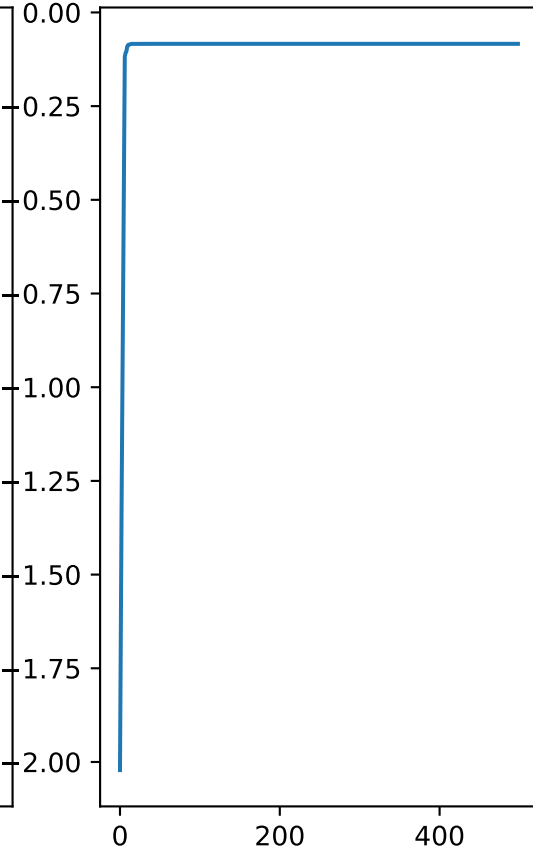
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq