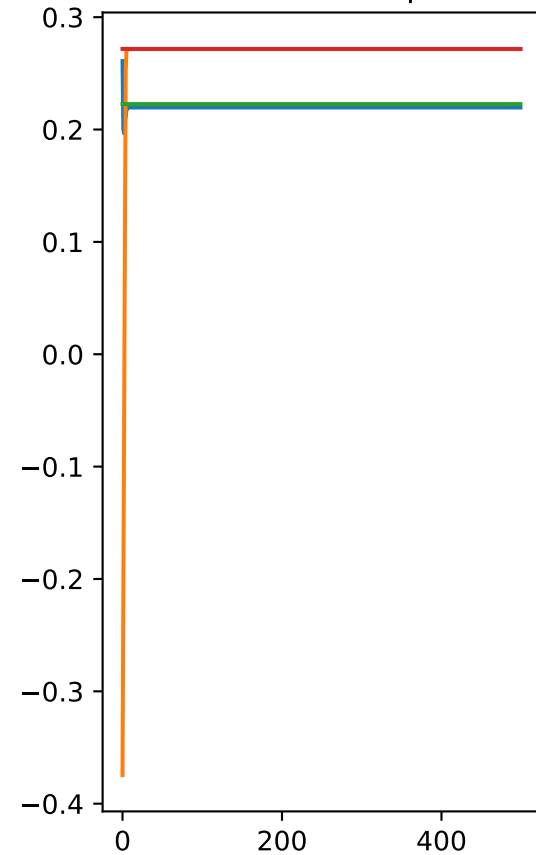
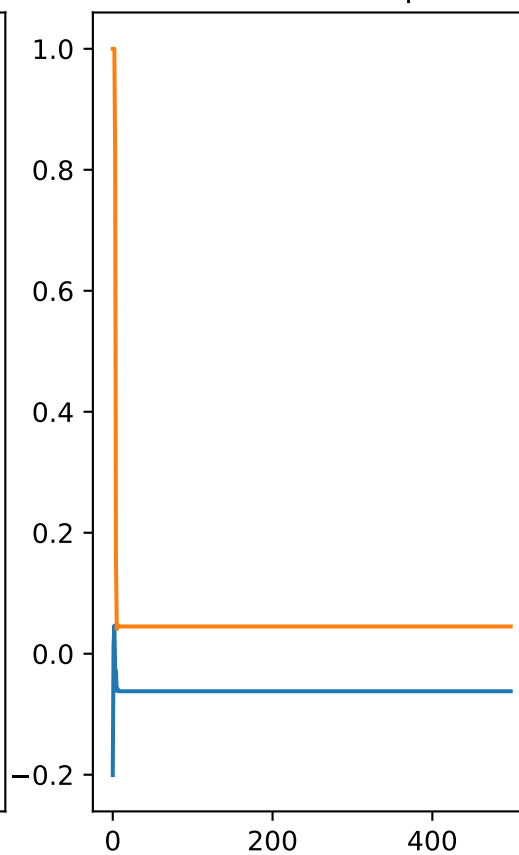


Reward: square_root
Speed = 15.368671837727586 [rad/s]

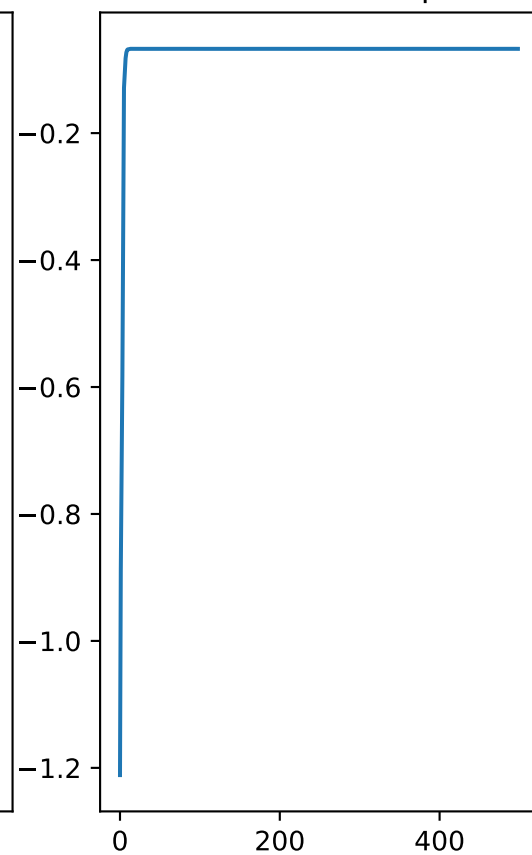
State vs step



Action vs step



Reward vs step



I_d I_{dref}
 I_q I_{qref}

V_d V_q