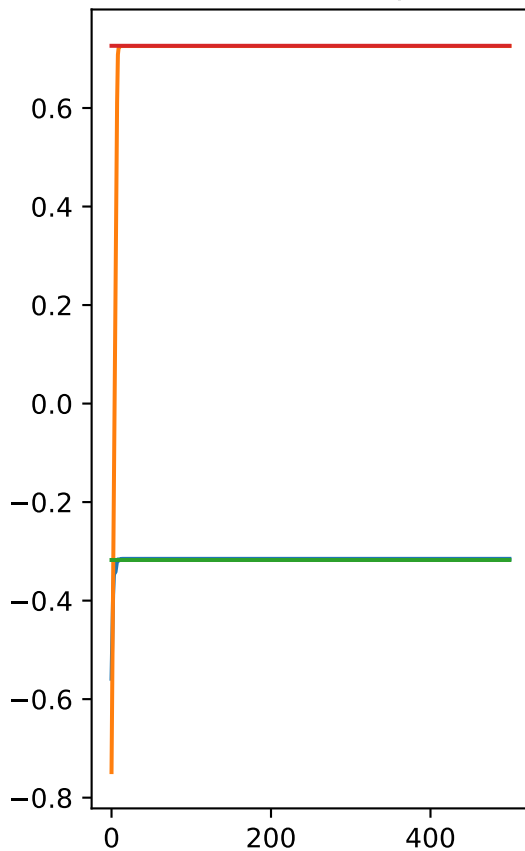
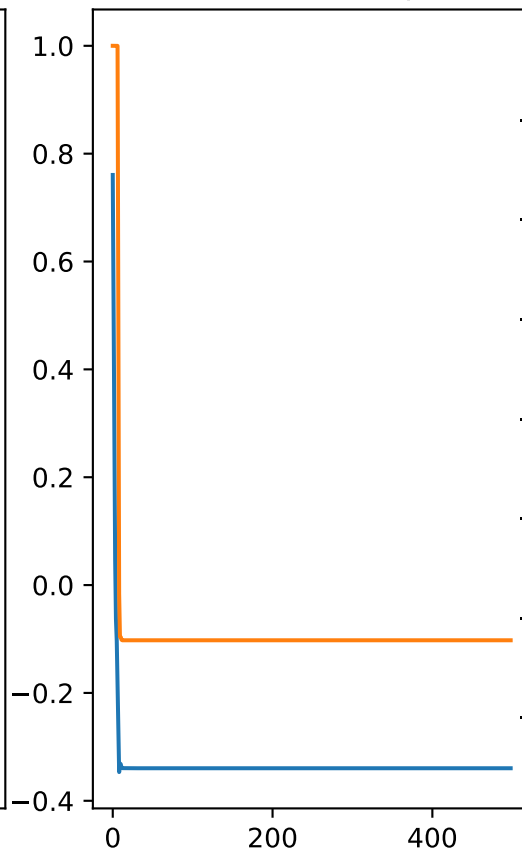


Reward: square_root
Speed = 893.0919287630484 [rad/s]

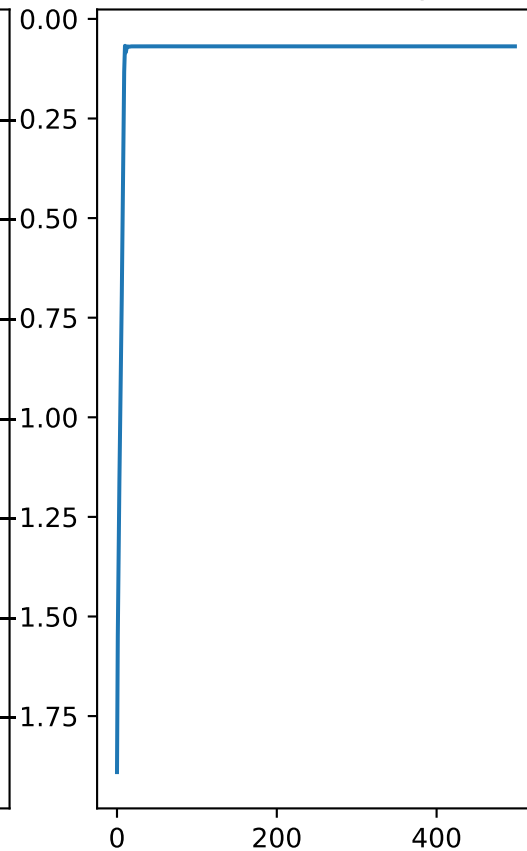
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq