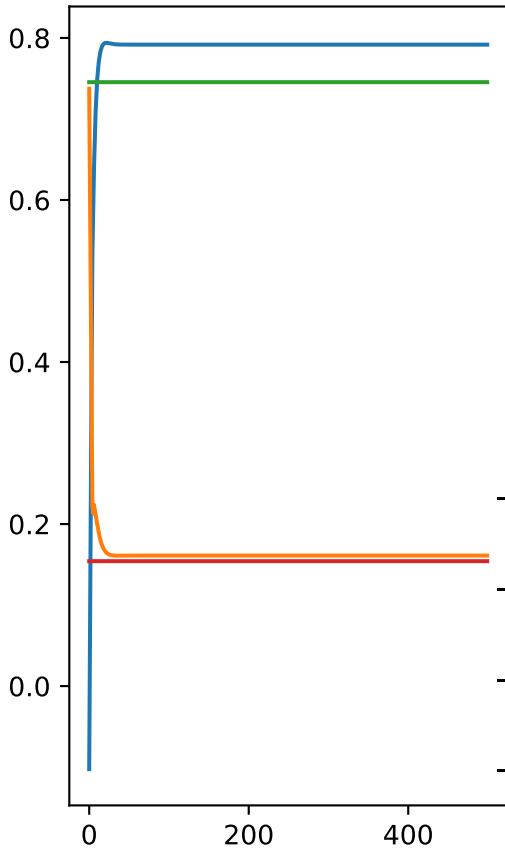
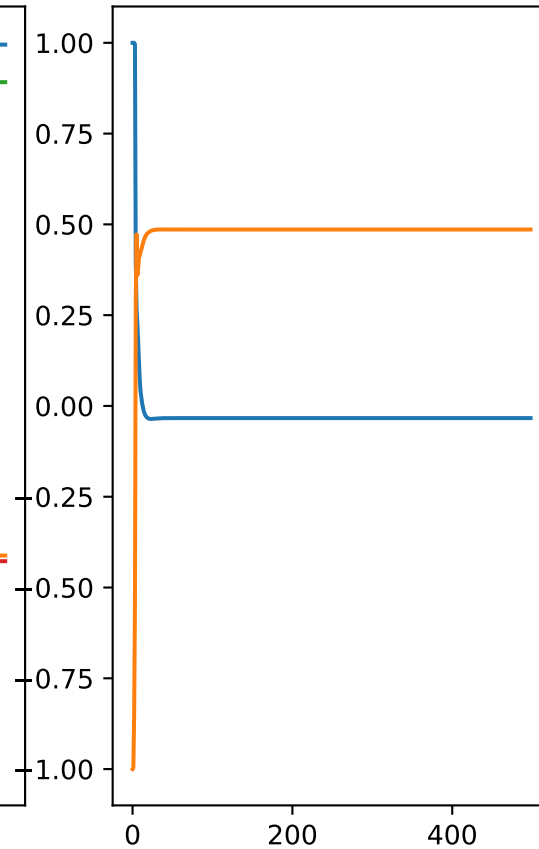


Reward: quadratic
Speed = 825.4471959889802 [rad/s]

State vs step



Action vs step



Reward vs step

