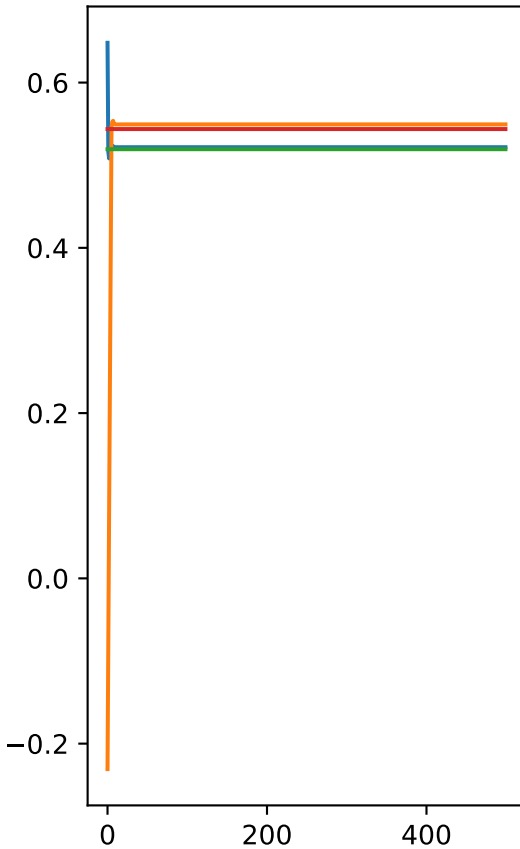
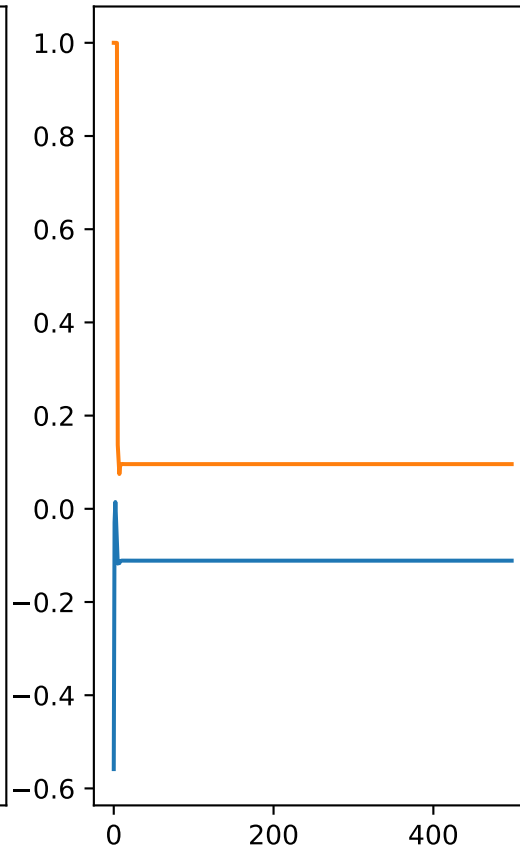


Reward: quartic\_root  
Speed = 442.3111138069995 [rad/s]

State vs step



Action vs step



Reward vs step

