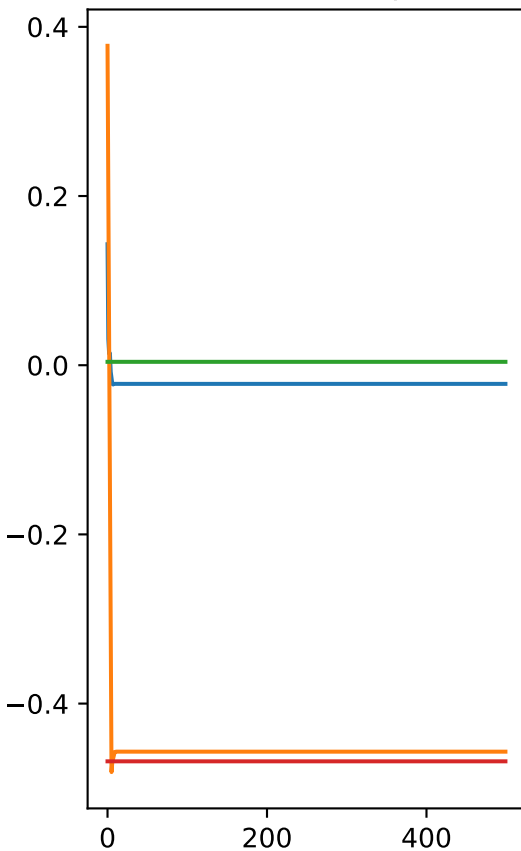
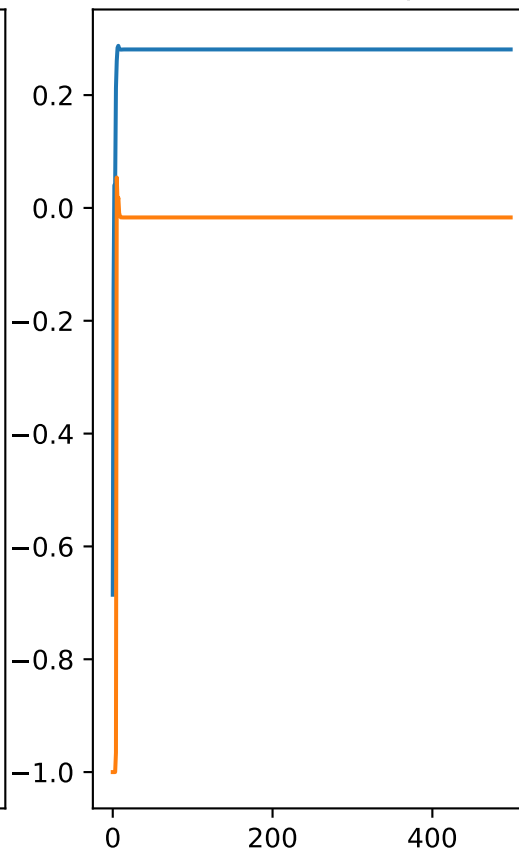


Reward: quartic_root
Speed = 991.1347978123649 [rad/s]

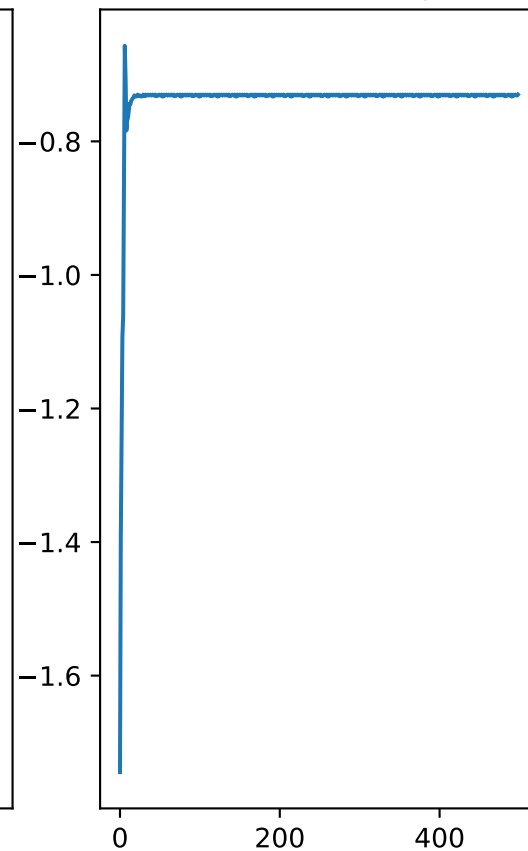
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq