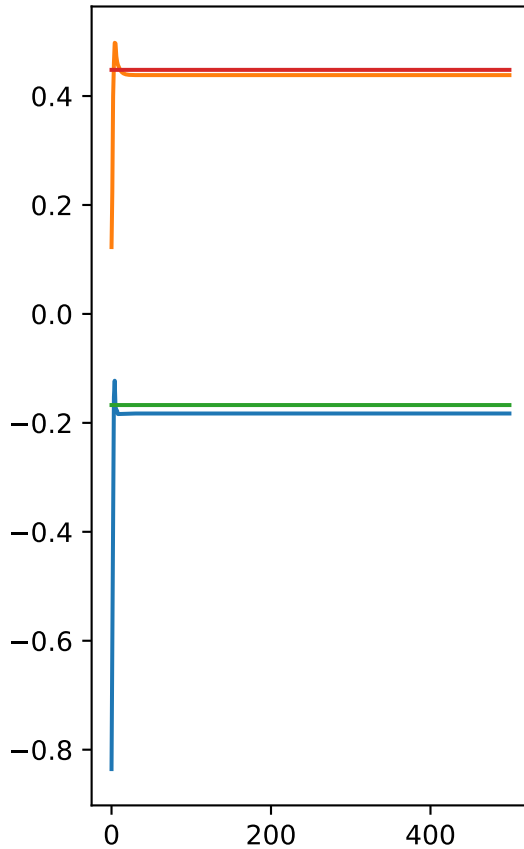
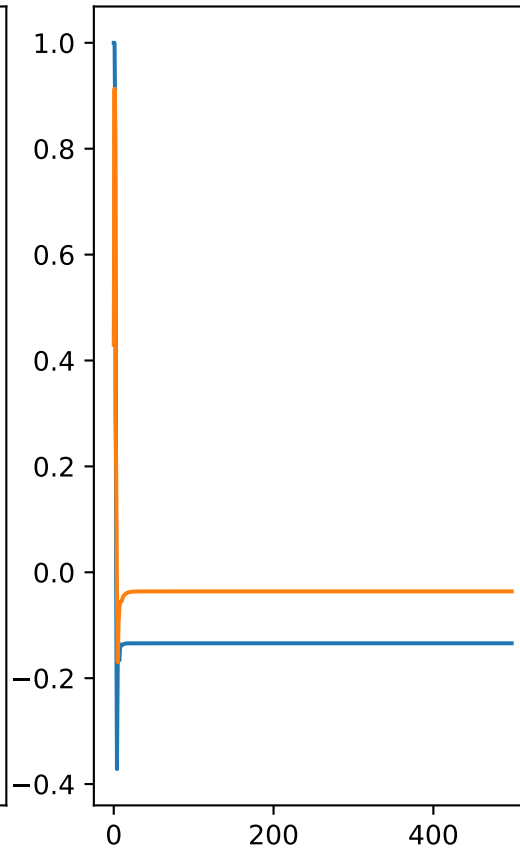


Reward: quadratic_2
Speed = 516.1888045036408 [rad/s]

State vs step



Action vs step



Reward vs step

