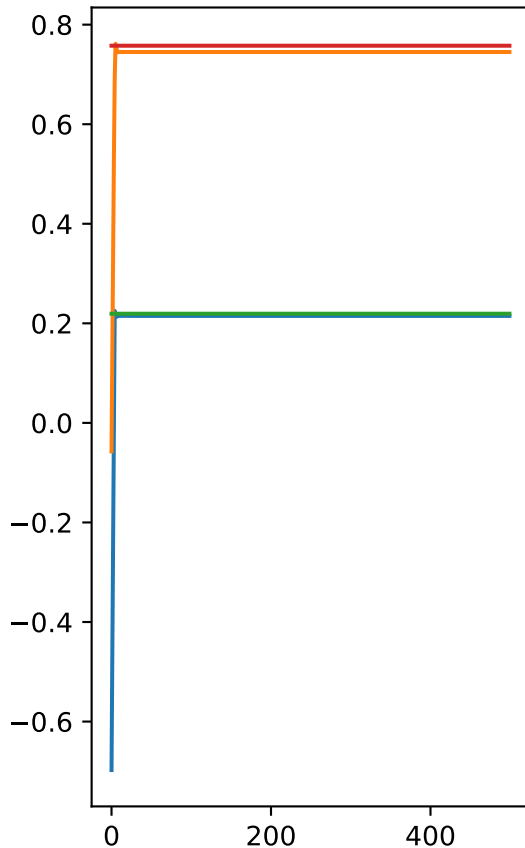
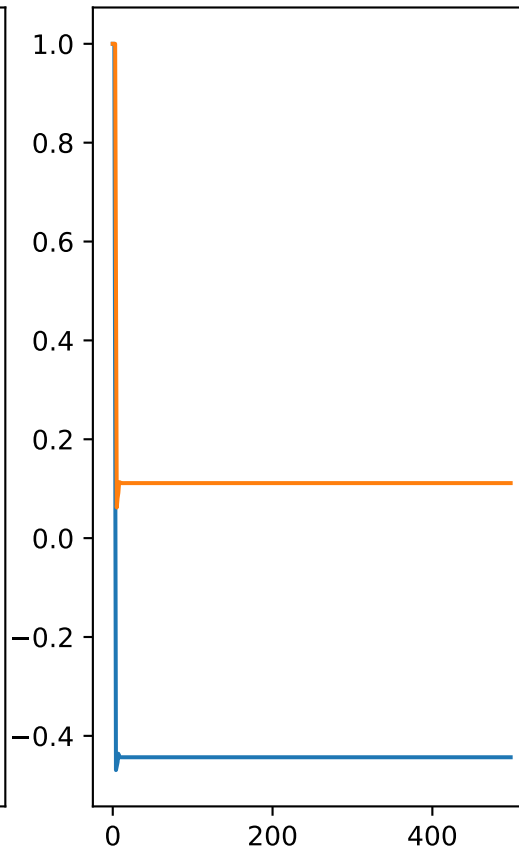


Reward: quartic_root
Speed = 96.06990048554218 [rad/s]

State vs step



Action vs step



Reward vs step

