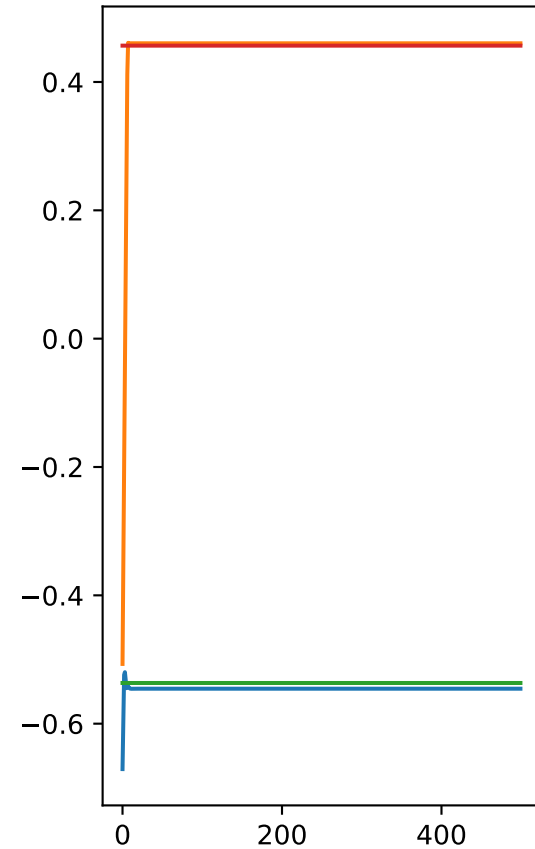
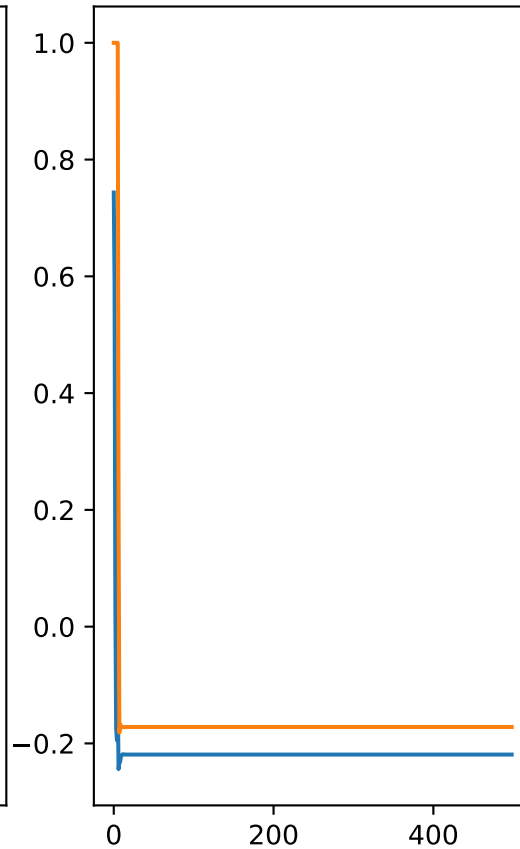


Reward: quartic_root
Speed = 251.9557264736199 [rad/s]

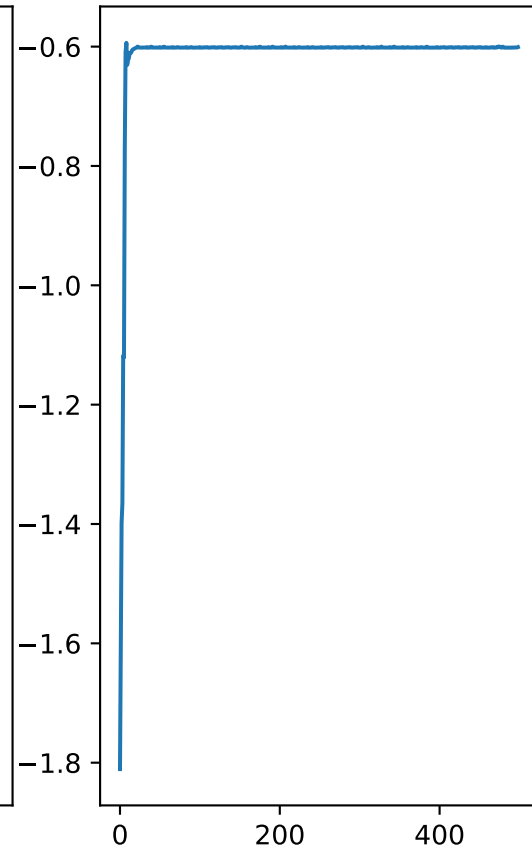
State vs step



Action vs step



Reward vs step



Id Iqref
Iq Iqref

Vd Vq