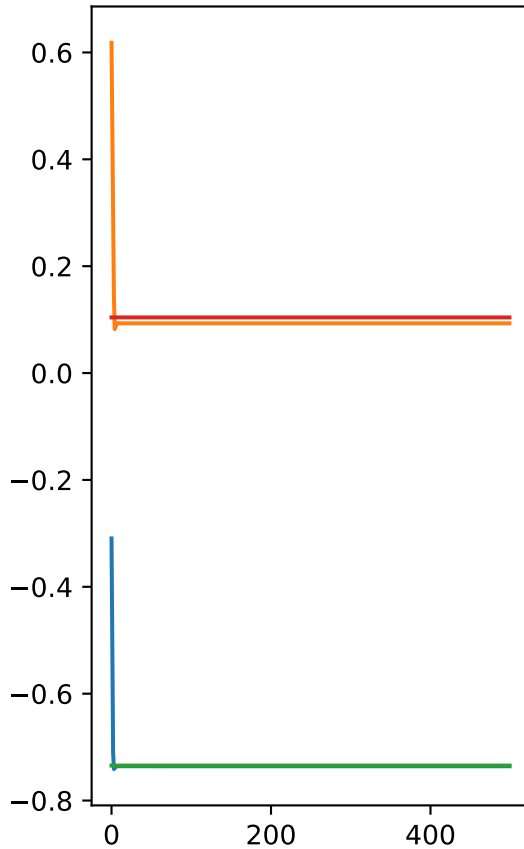
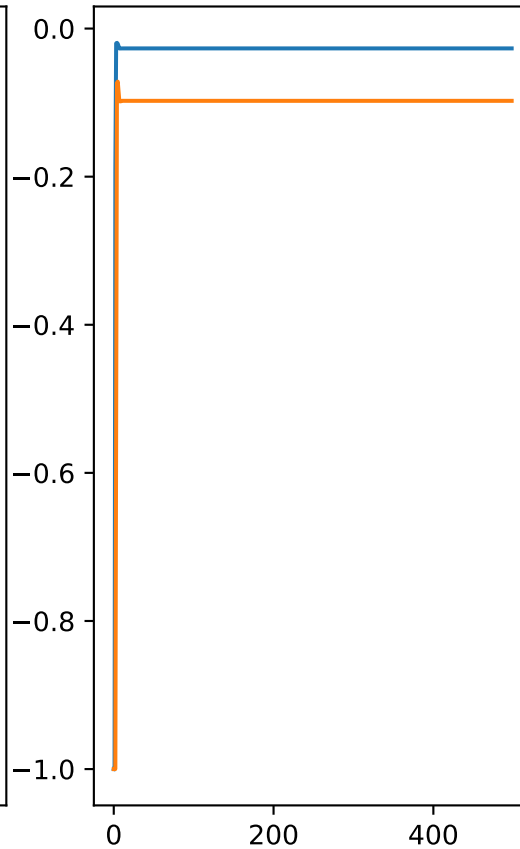


Reward: quartic\_root  
Speed = 823.9769562973099 [rad/s]

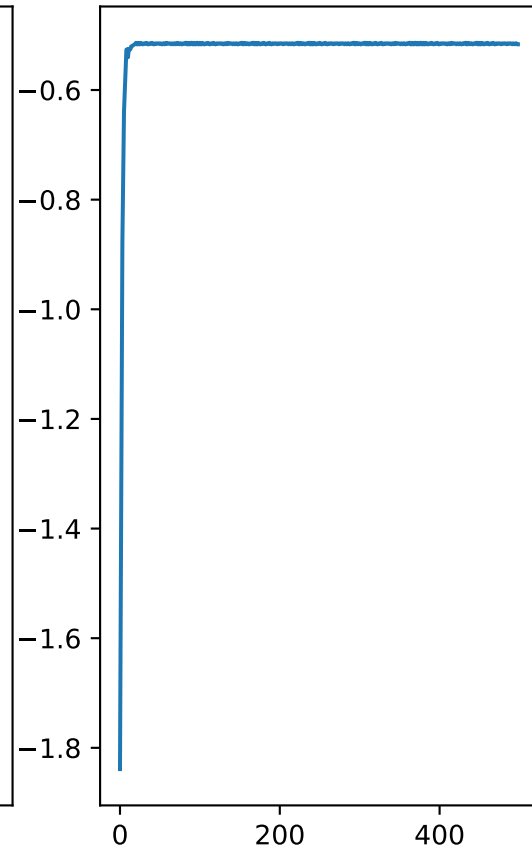
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq