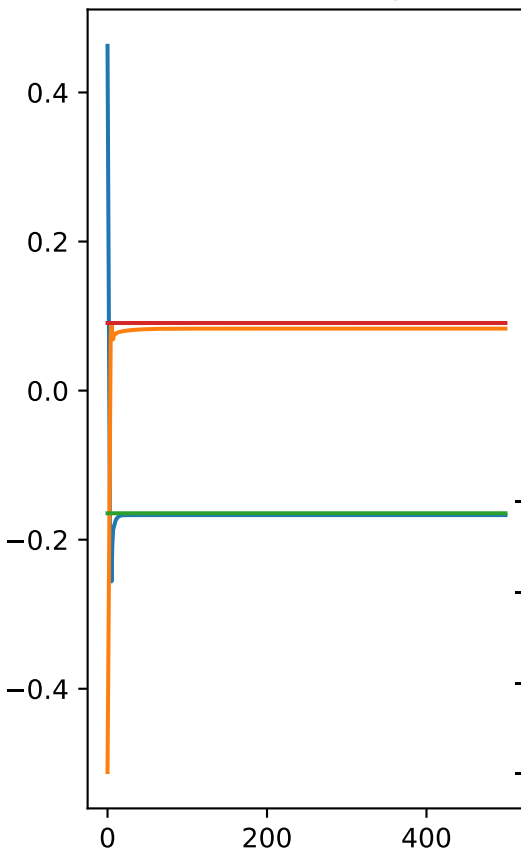
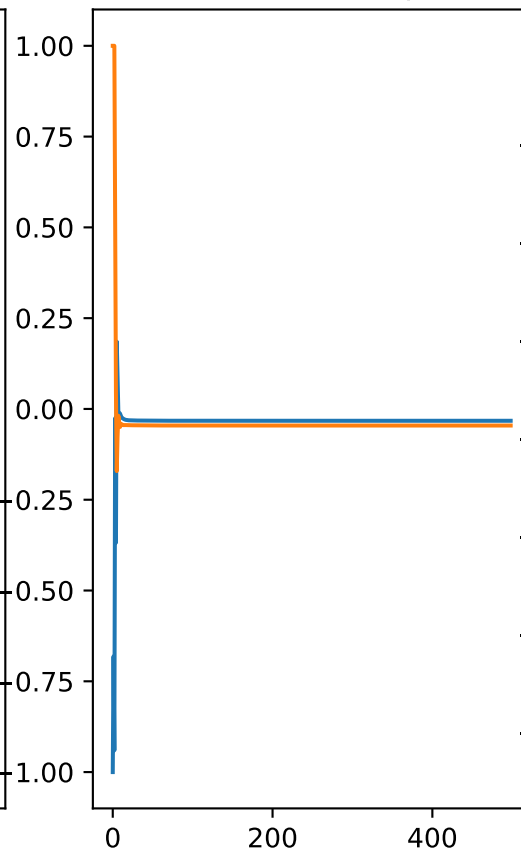


Reward: quadratic_2
Speed = 480.9149986777567 [rad/s]

State vs step



Action vs step



Reward vs step

