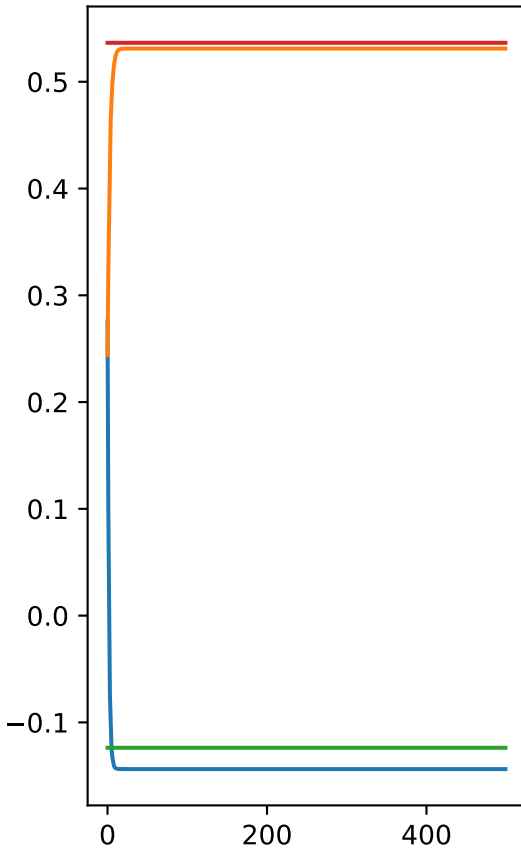
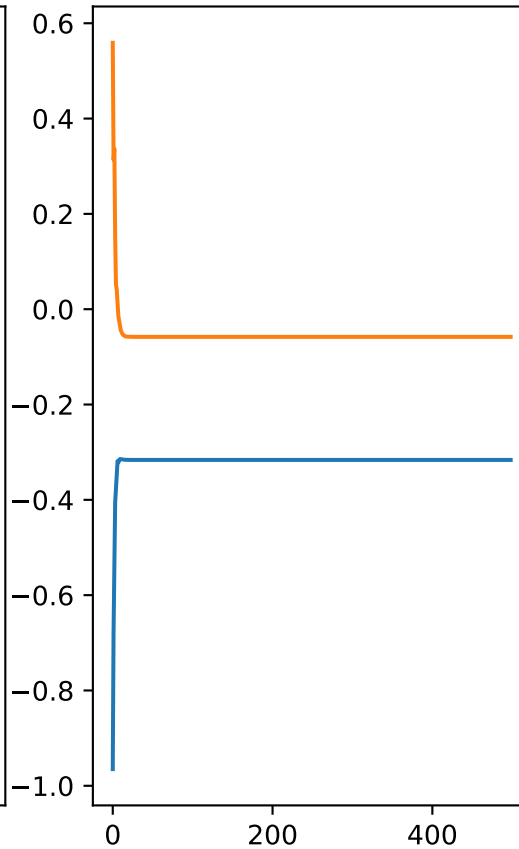


Reward: quadratic_2
Speed = 581.6093400366805 [rad/s]

State vs step



Action vs step



Reward vs step

