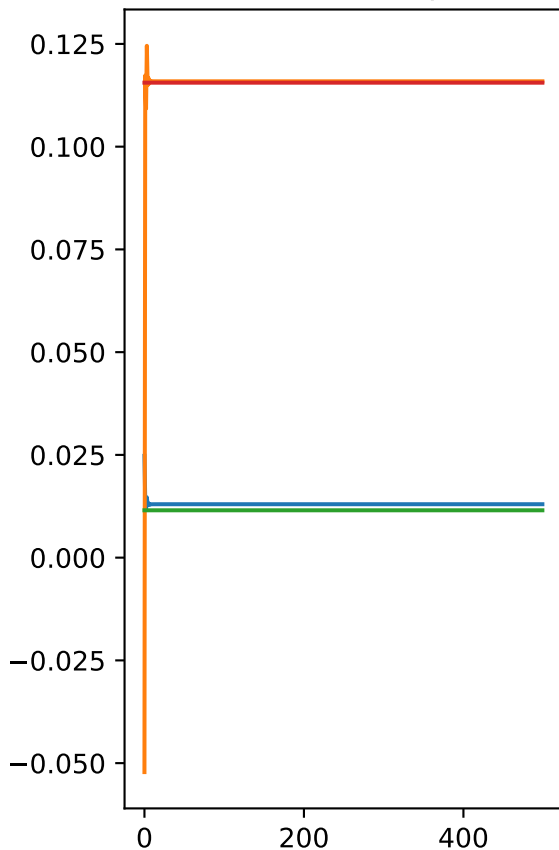
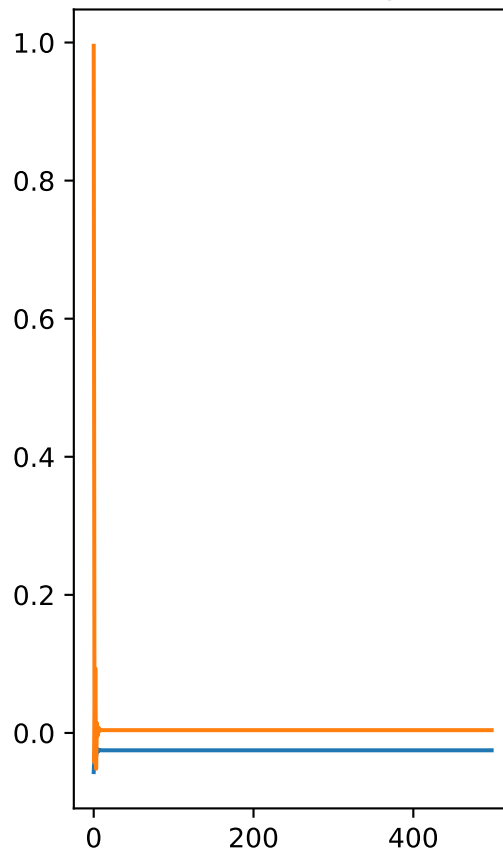


Reward: quartic_root
Speed = 644.302940093912 [rad/s]

State vs step



Action vs step



Reward vs step

