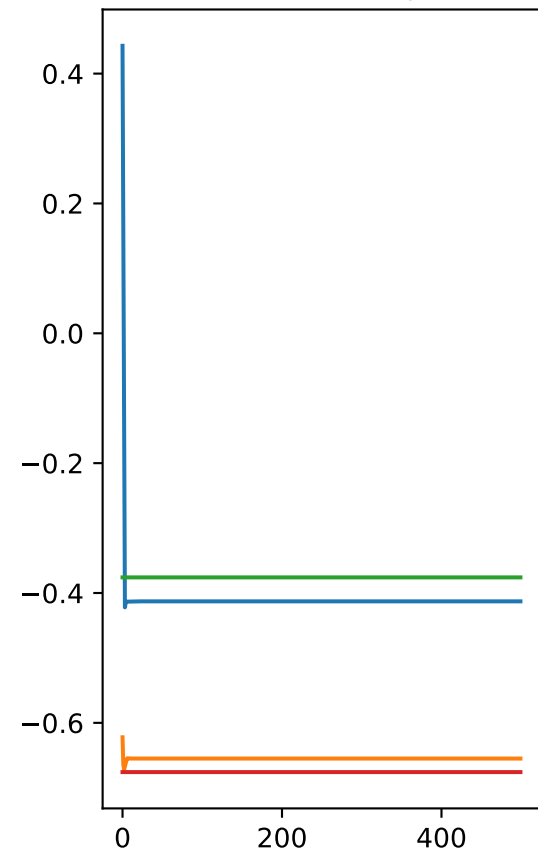
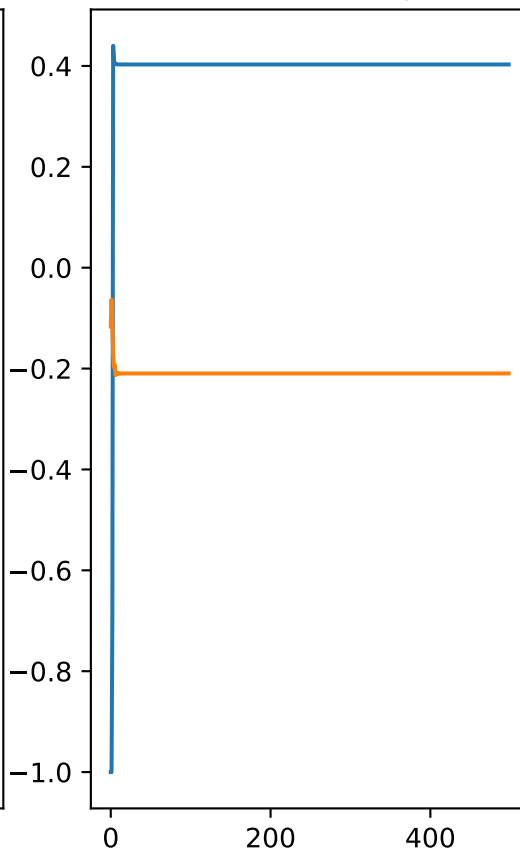


Reward: quartic_root
Speed = 395.74015366986407 [rad/s]

State vs step



Action vs step



Reward vs step

