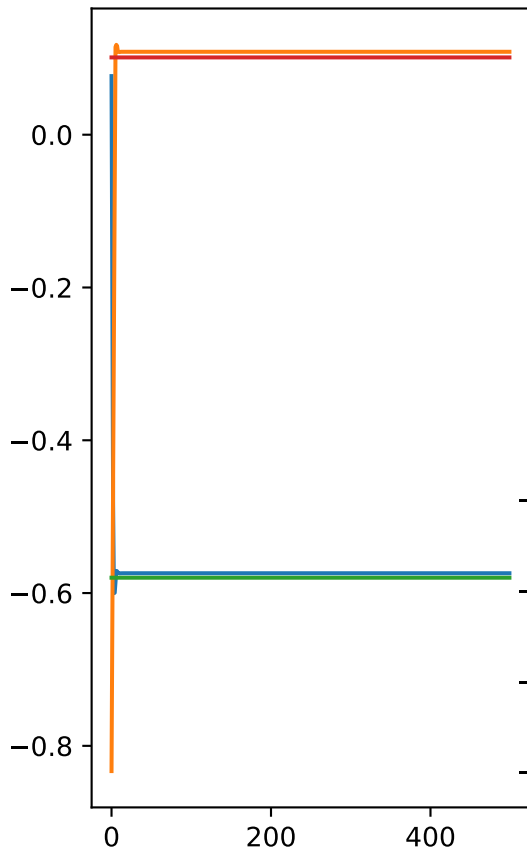
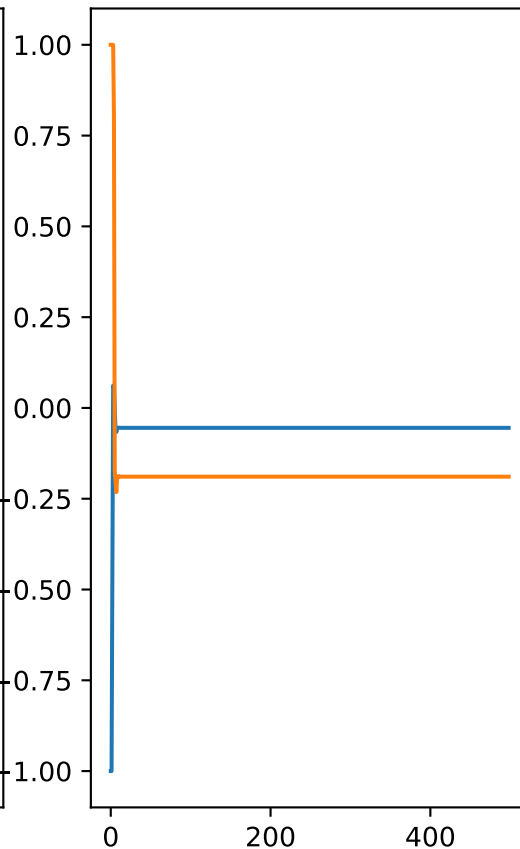


Reward: quartic_root
Speed = 623.3548145649713 [rad/s]

State vs step



Action vs step



Reward vs step

