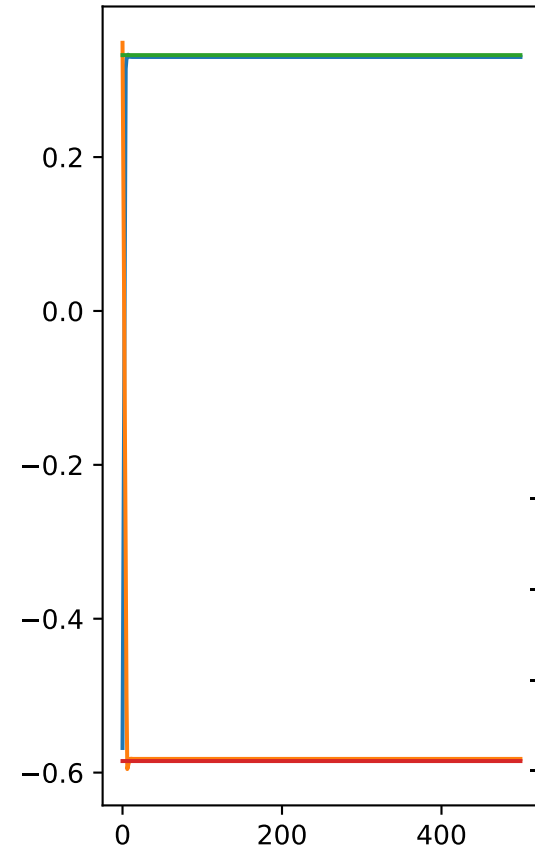
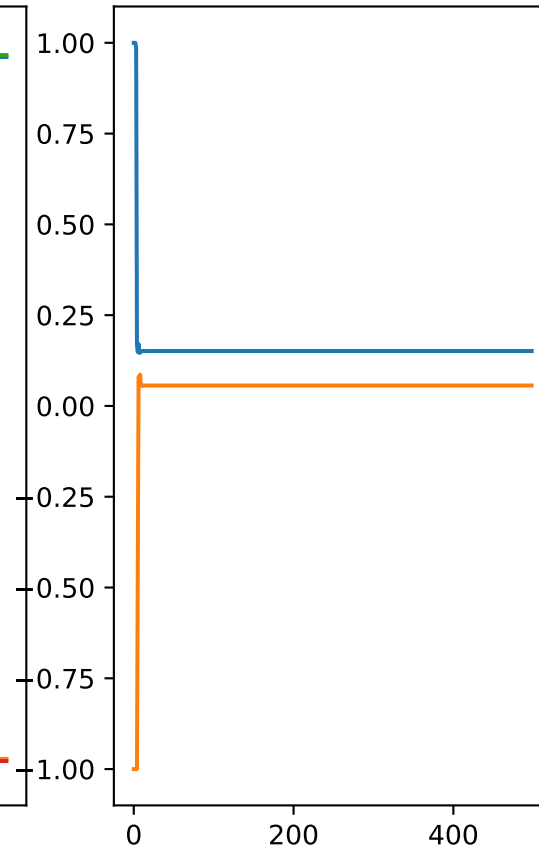


Reward: quartic_root_2
Speed = 129.7980409042579 [rad/s]

State vs step



Action vs step



Reward vs step

