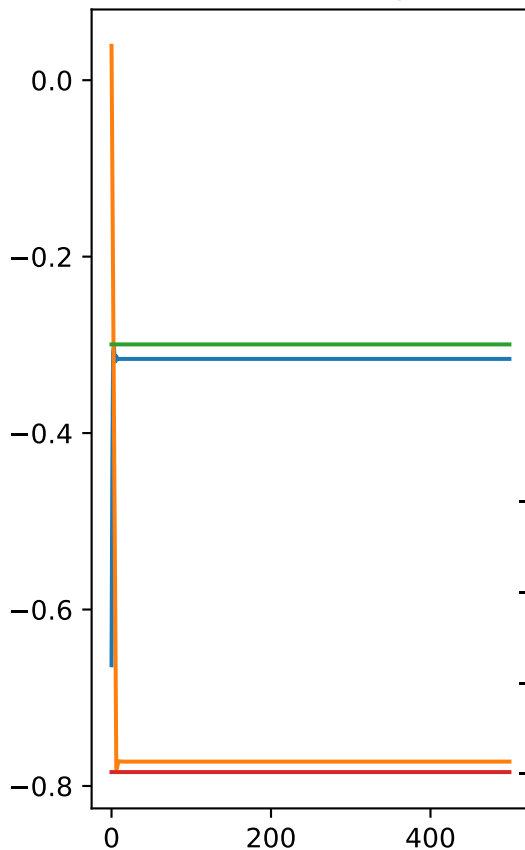
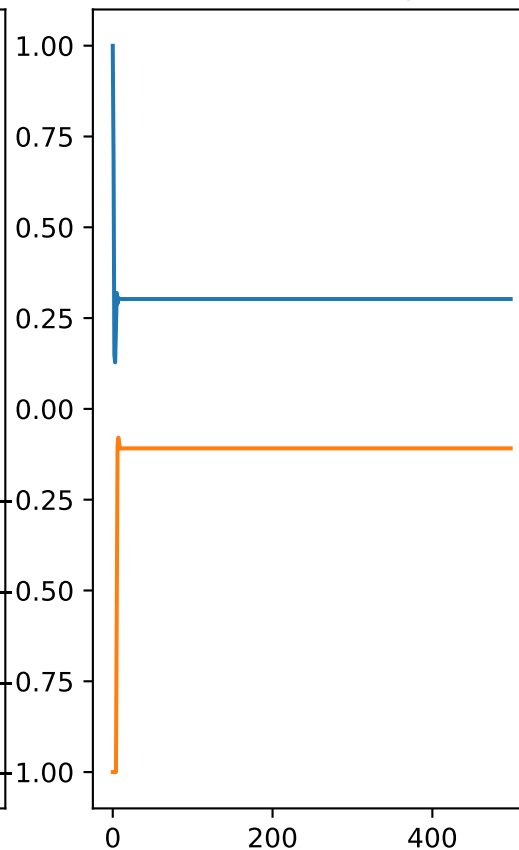


Reward: quartic_root
Speed = 969.7719432002932 [rad/s]

State vs step



Action vs step



Reward vs step

