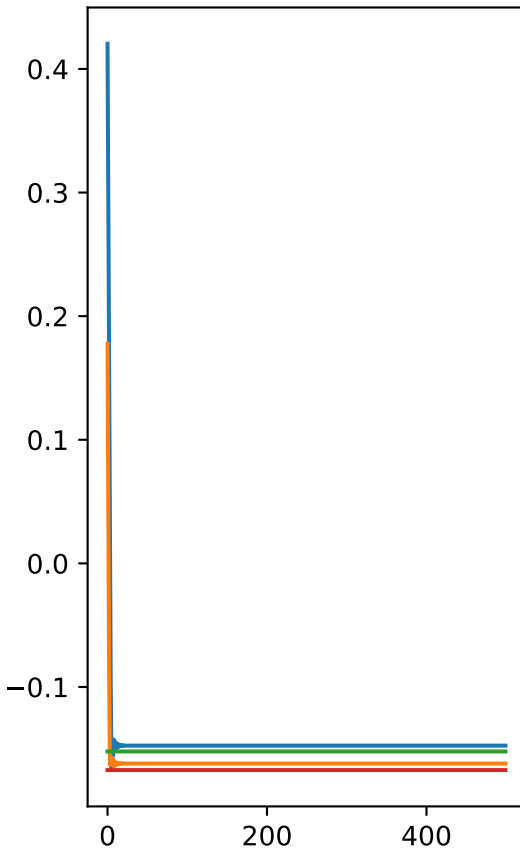
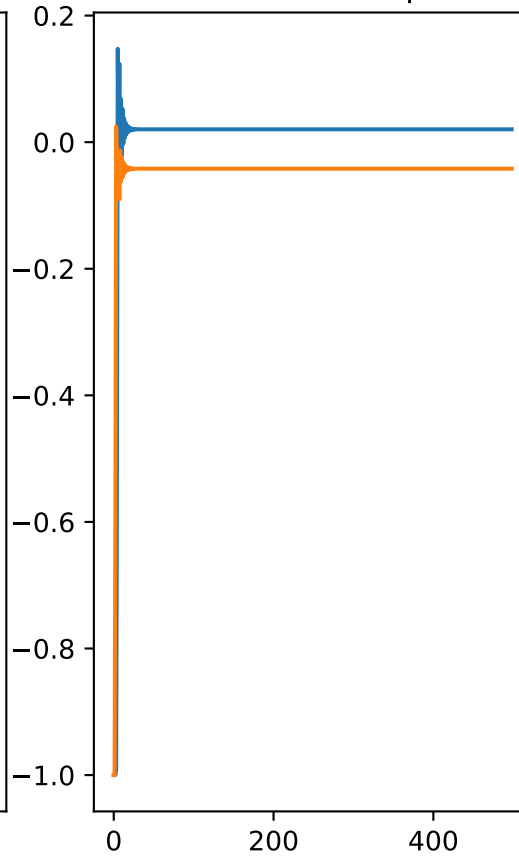


Reward: square_root
Speed = 944.7774190334646 [rad/s]

State vs step



Action vs step



Reward vs step

