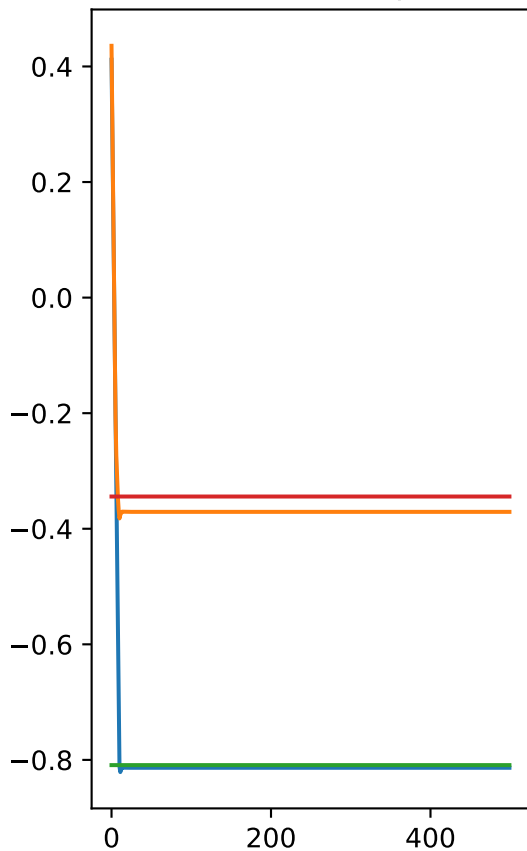
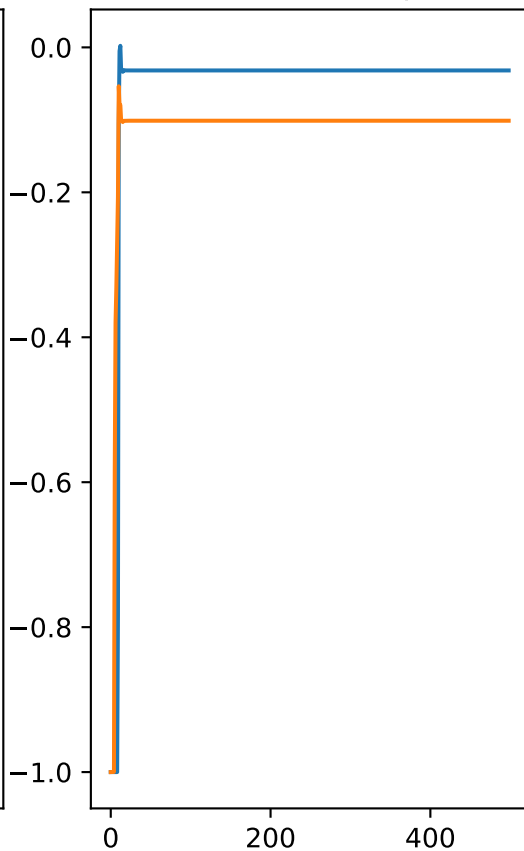


Reward: quartic\_root  
Speed = 1056.2286134139222 [rad/s]

State vs step



Action vs step



Reward vs step

