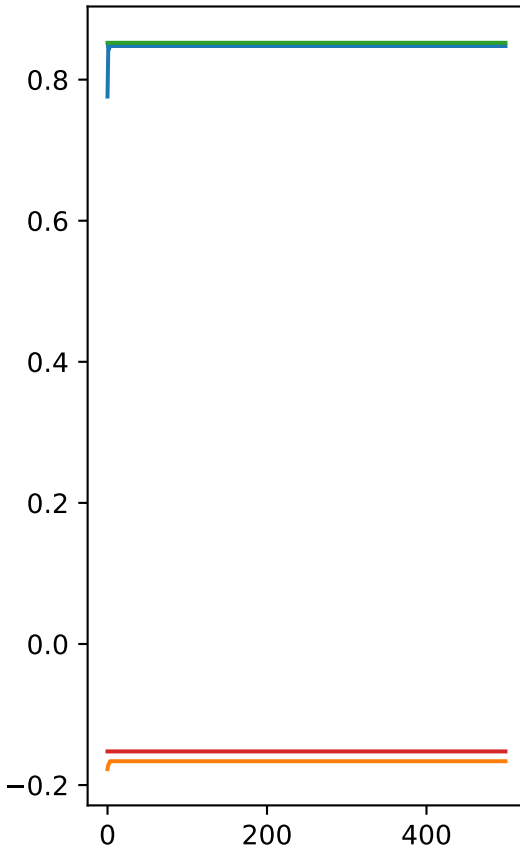
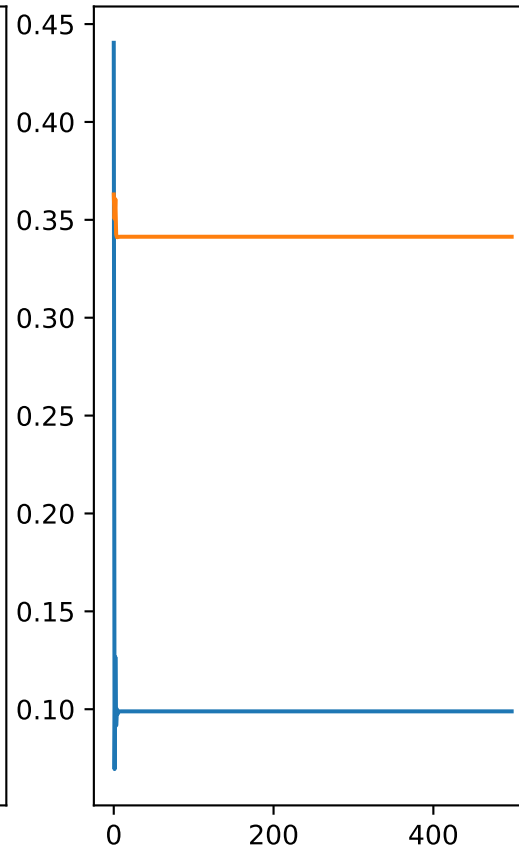


Reward: quartic_root
Speed = 731.6517609503392 [rad/s]

State vs step



Action vs step



Reward vs step

