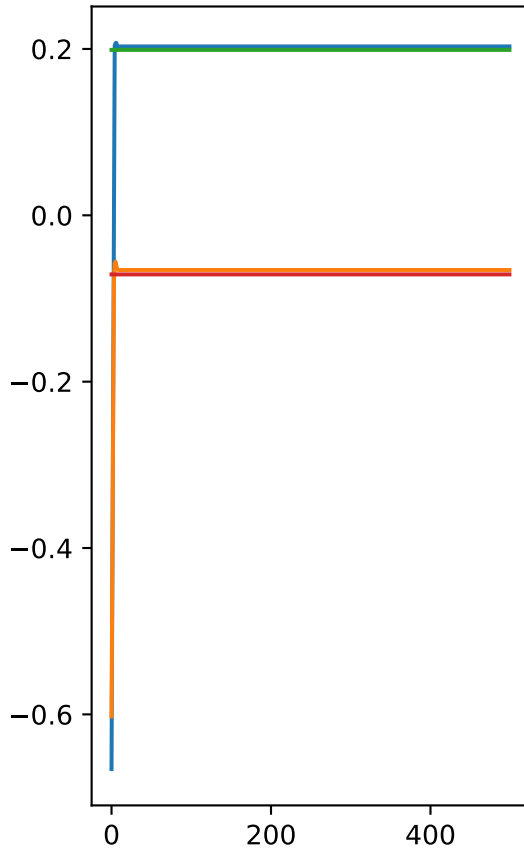
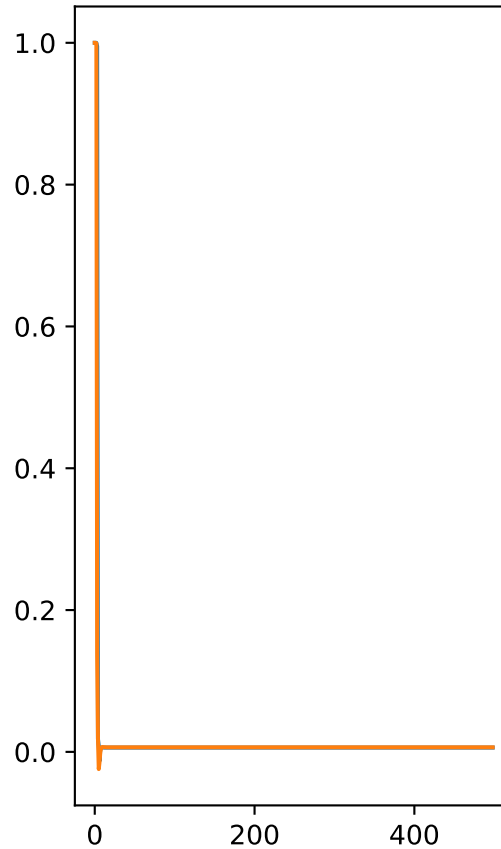


Reward: quartic\_root  
Speed = 1129.679029041985 [rad/s]

State vs step



Action vs step



Reward vs step

