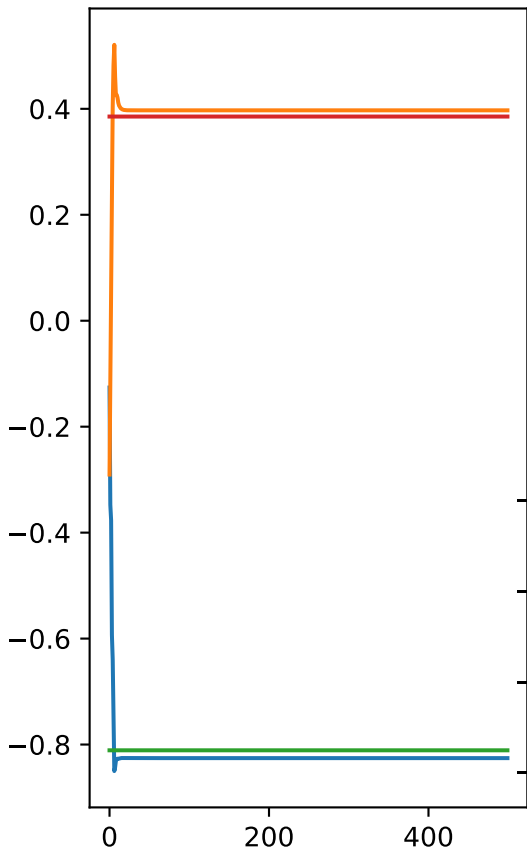
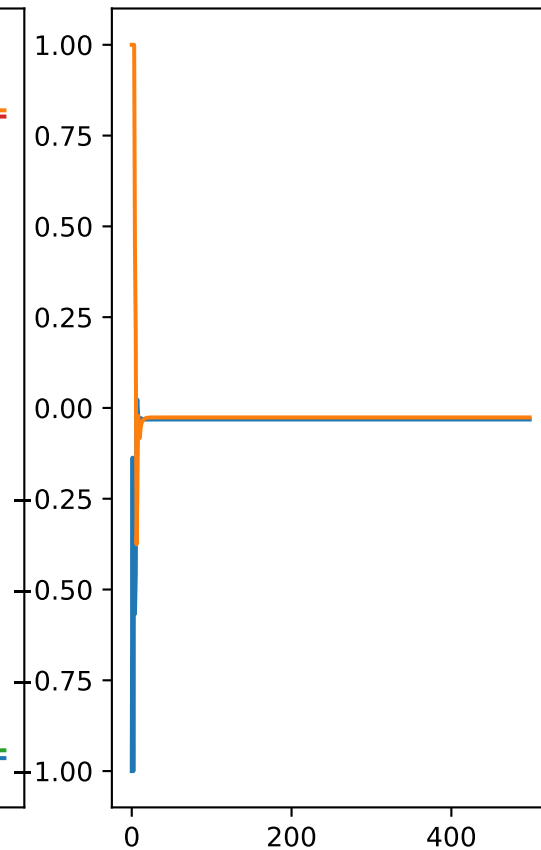


Reward: quadratic_2
Speed = 102.17715512406896 [rad/s]

State vs step



Action vs step



Reward vs step

