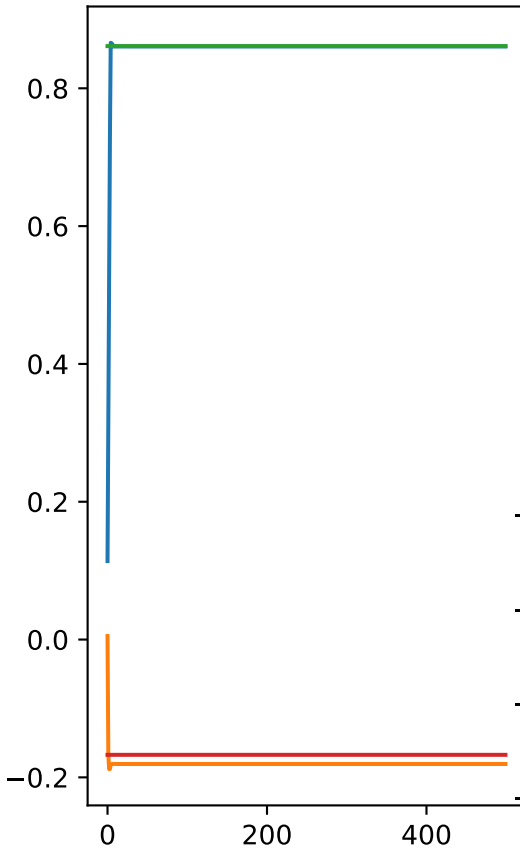
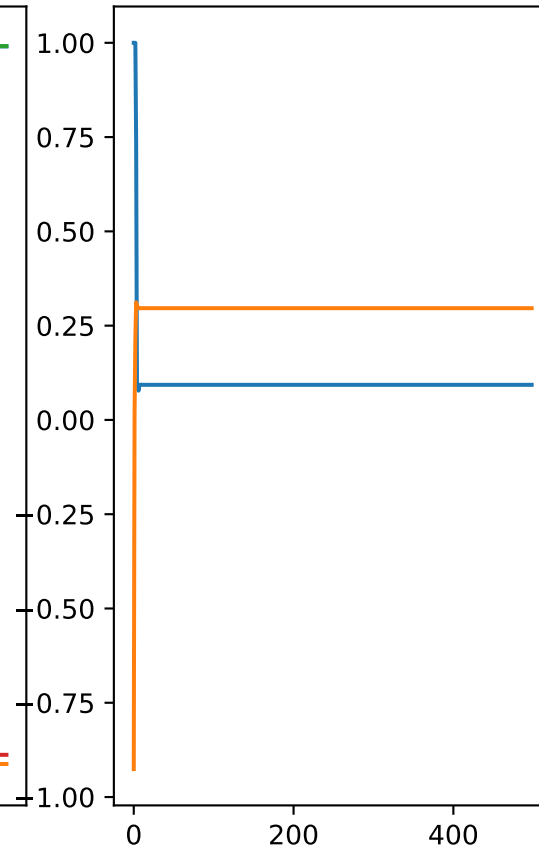


Reward: quartic_root
Speed = 844.3595762135291 [rad/s]

State vs step



Action vs step



Reward vs step

