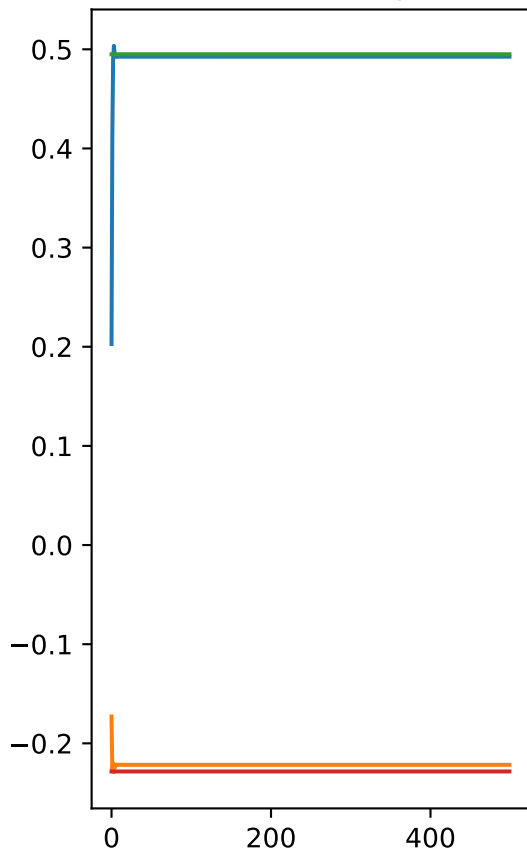
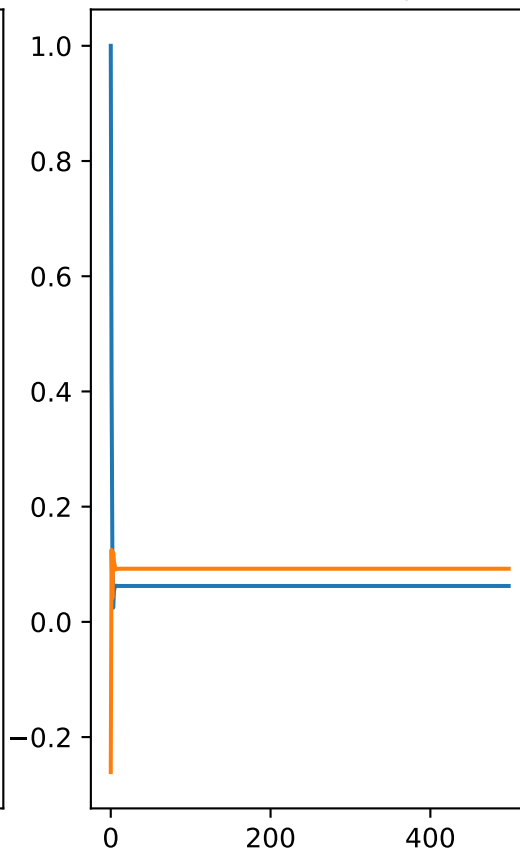


Reward: square\_root  
Speed = 242.93308442264814 [rad/s]

State vs step



Action vs step



Reward vs step

