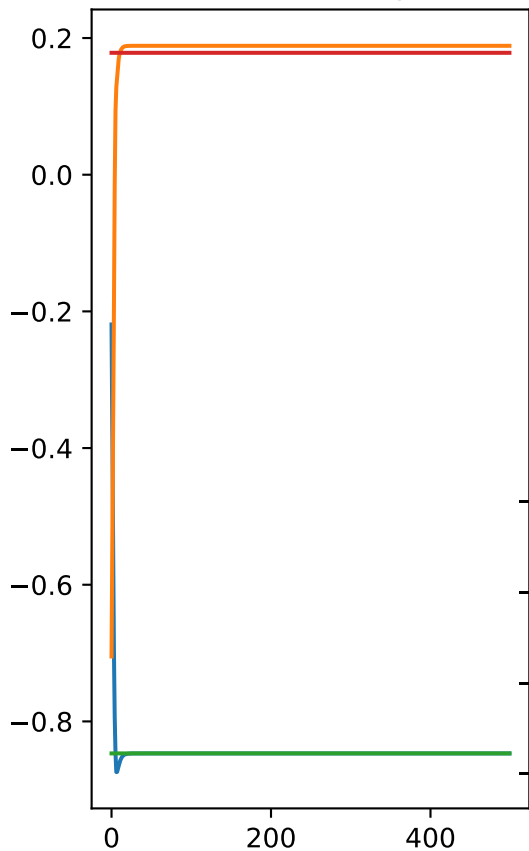
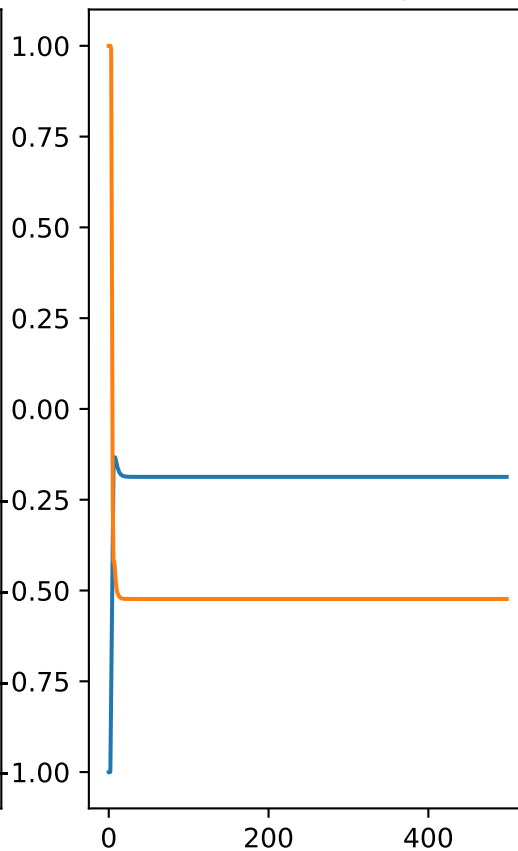


Reward: quadratic
Speed = 414.45146107092273 [rad/s]

State vs step



Action vs step



Reward vs step

