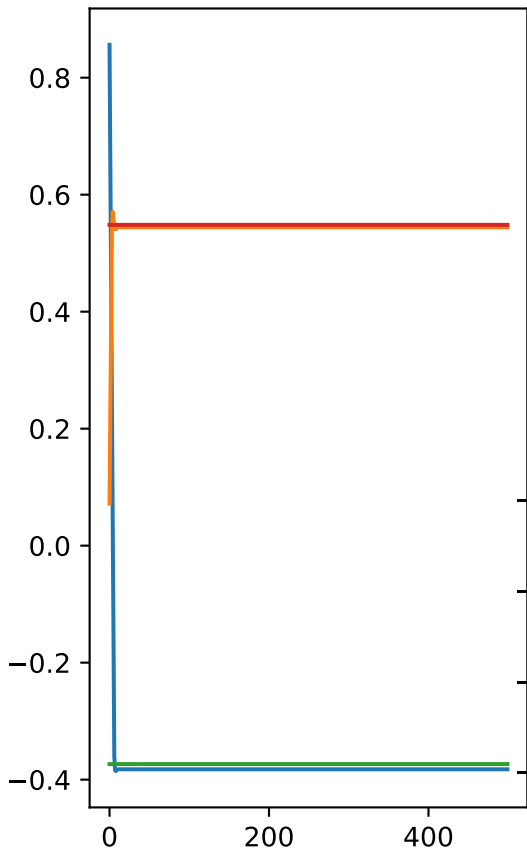
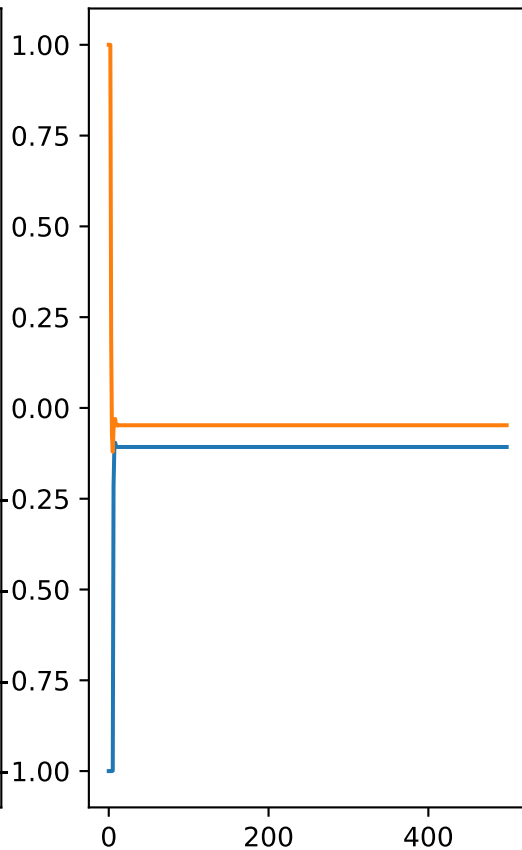


Reward: quartic_root
Speed = 1023.0910331281208 [rad/s]

State vs step



Action vs step



Reward vs step

