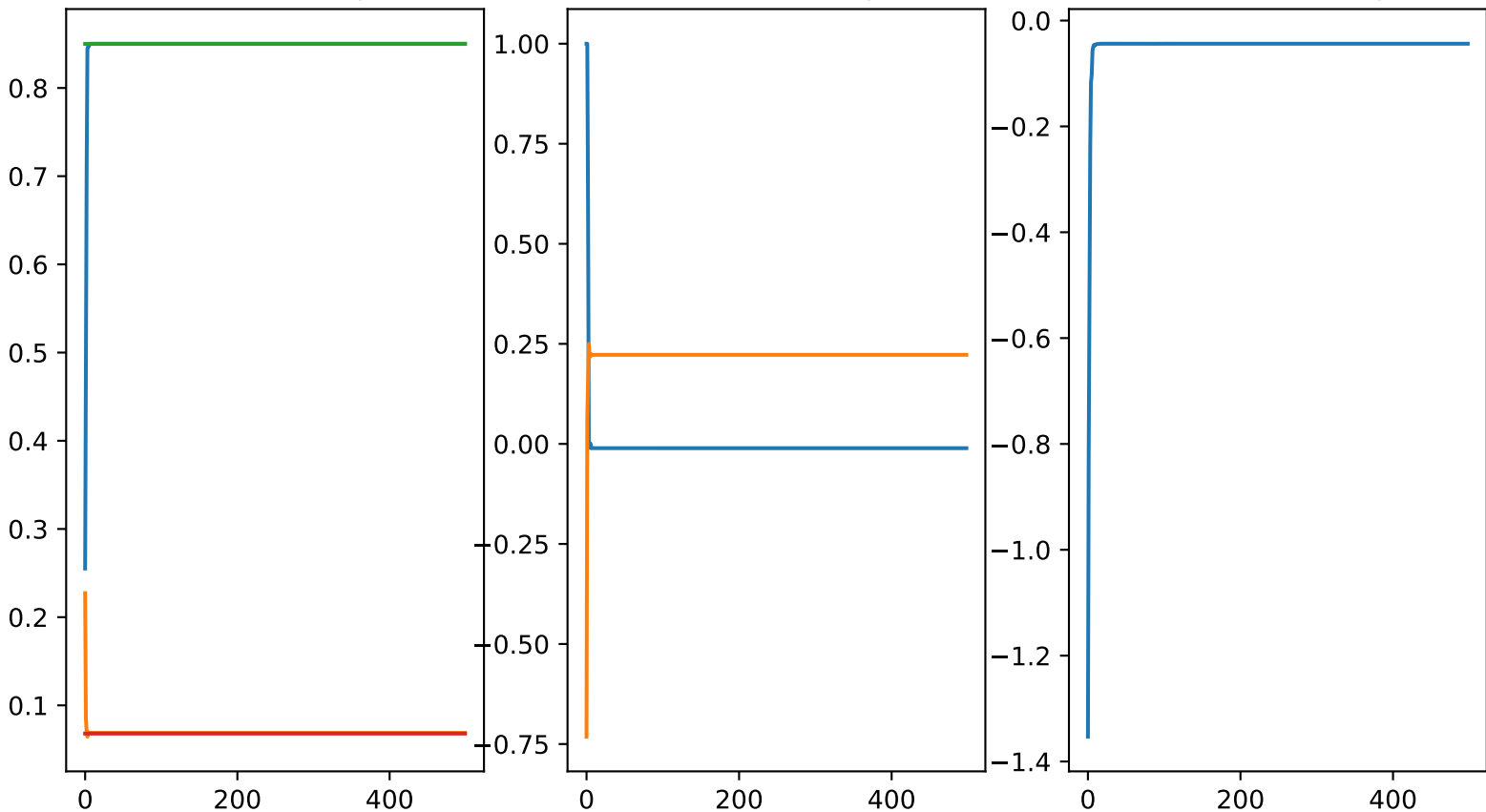


Reward: square_root
Speed = 642.7195992796974 [rad/s]

State vs step

Action vs step

Reward vs step



I_d I_{dref}
 I_q I_{qref}

V_d V_q