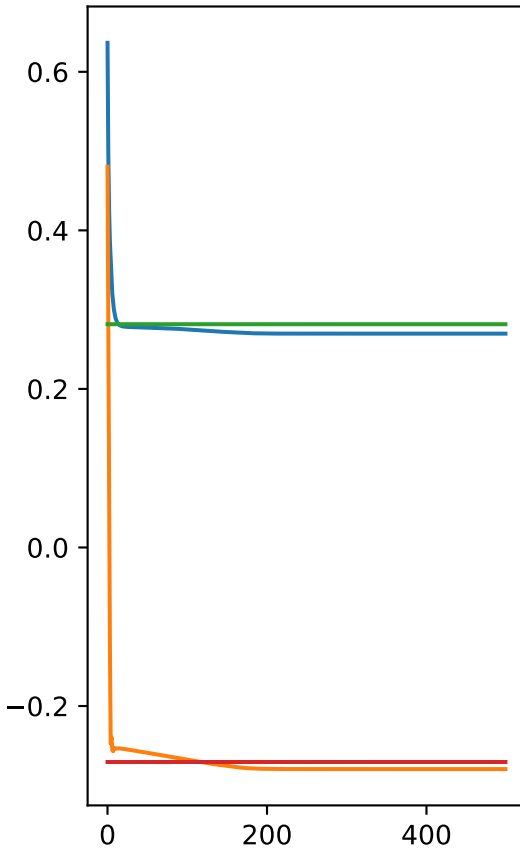
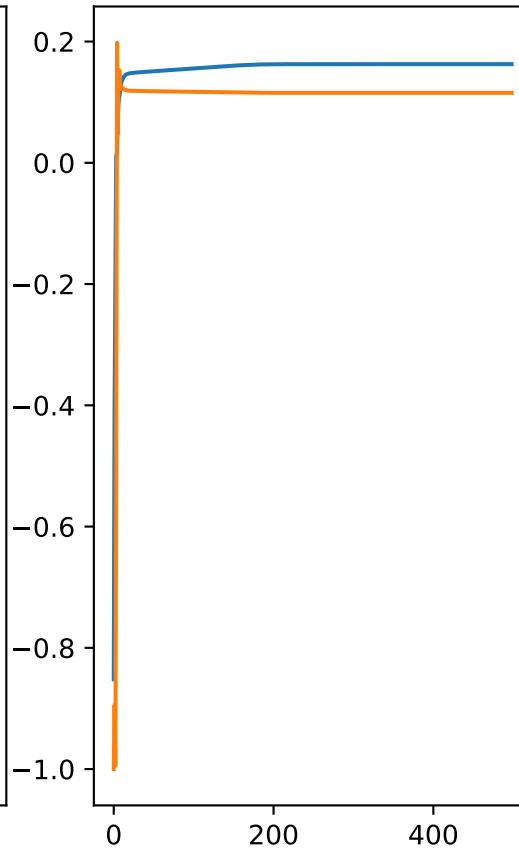


Reward: quadratic\_2  
Speed = 1024.6116065643937 [rad/s]

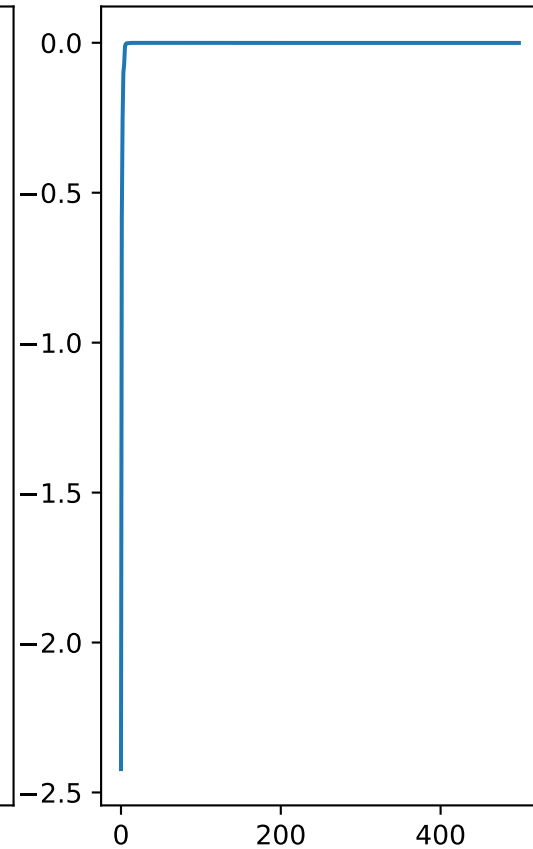
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq