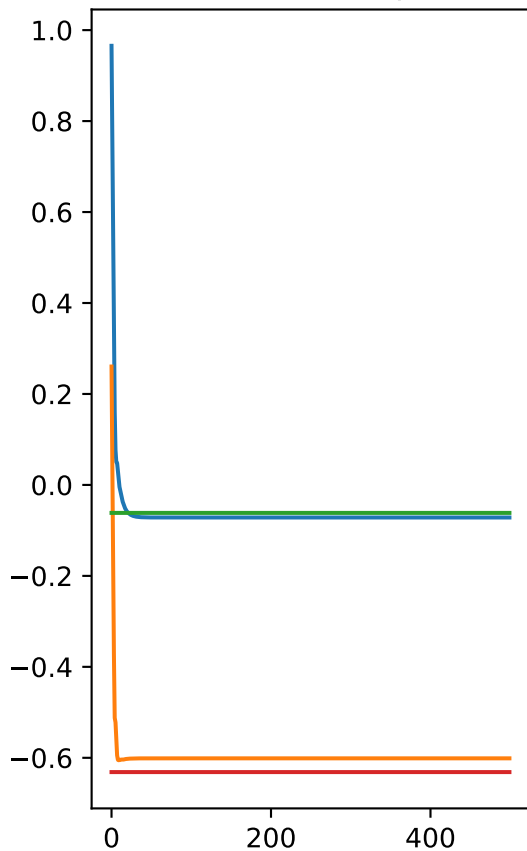
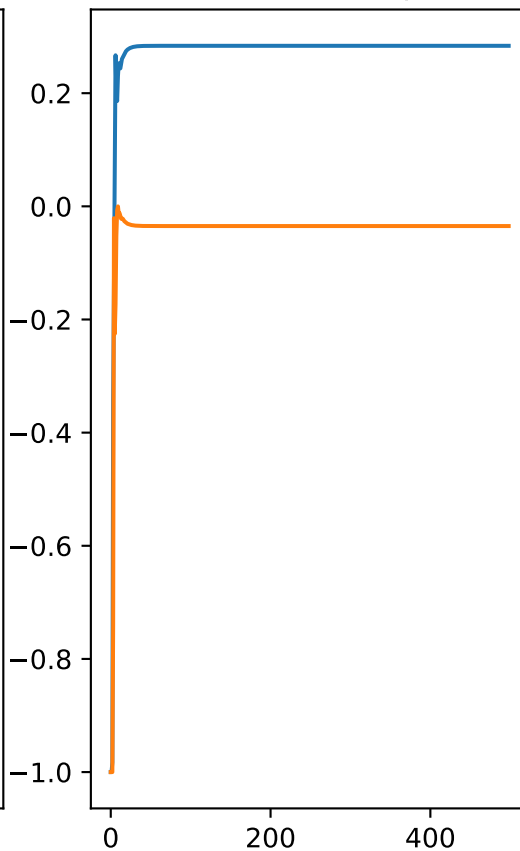


Reward: quadratic_2
Speed = 393.42794727718683 [rad/s]

State vs step



Action vs step



Reward vs step

