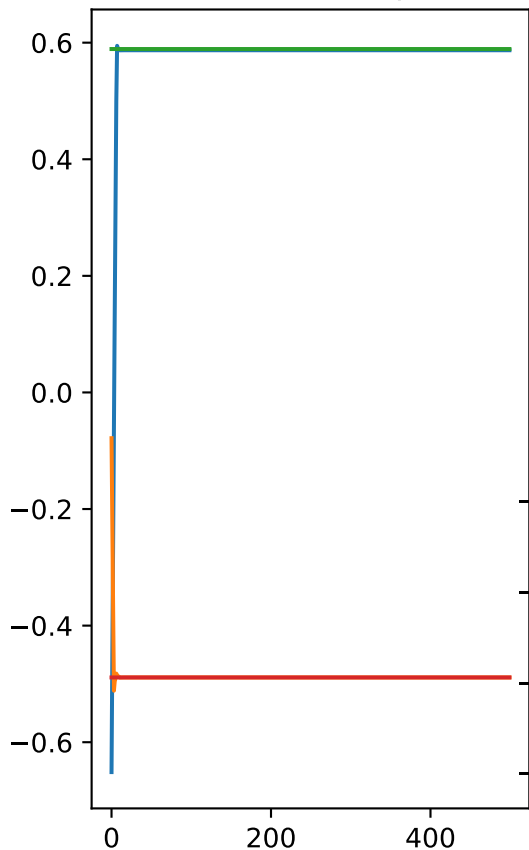
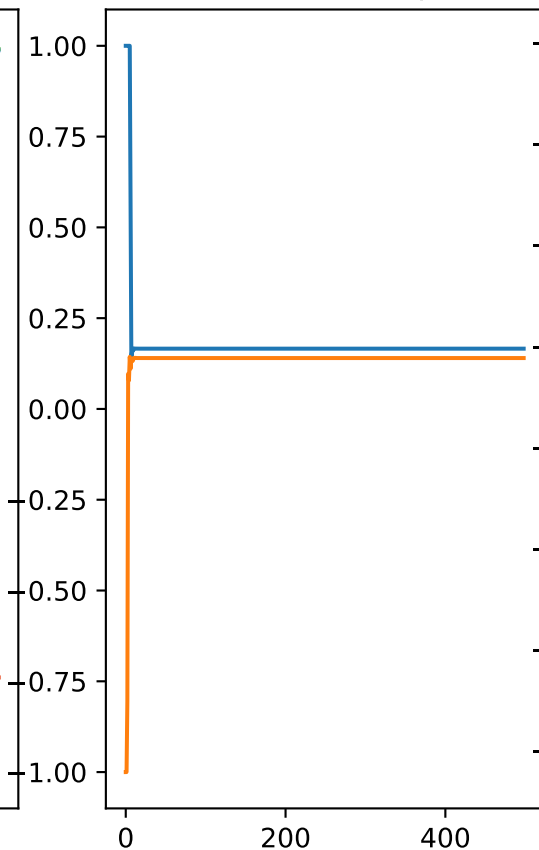


Reward: quartic\_root  
Speed = 31.15203296721441 [rad/s]

State vs step



Action vs step



Reward vs step

