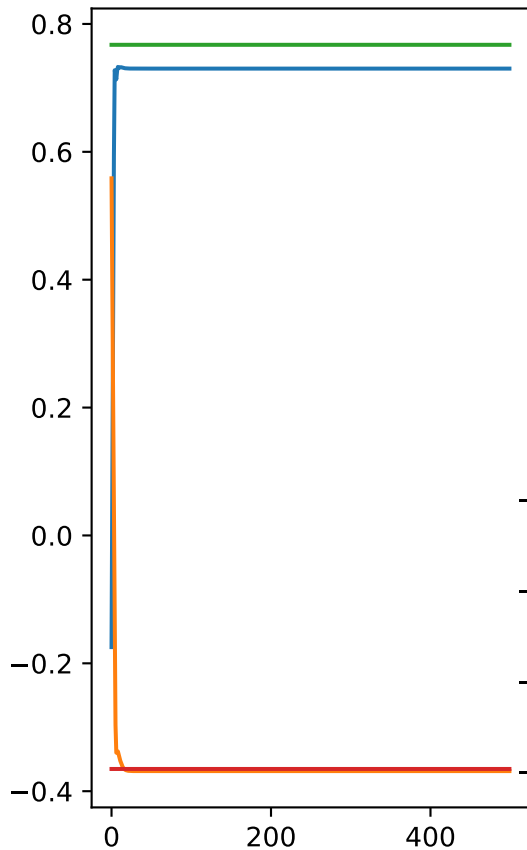
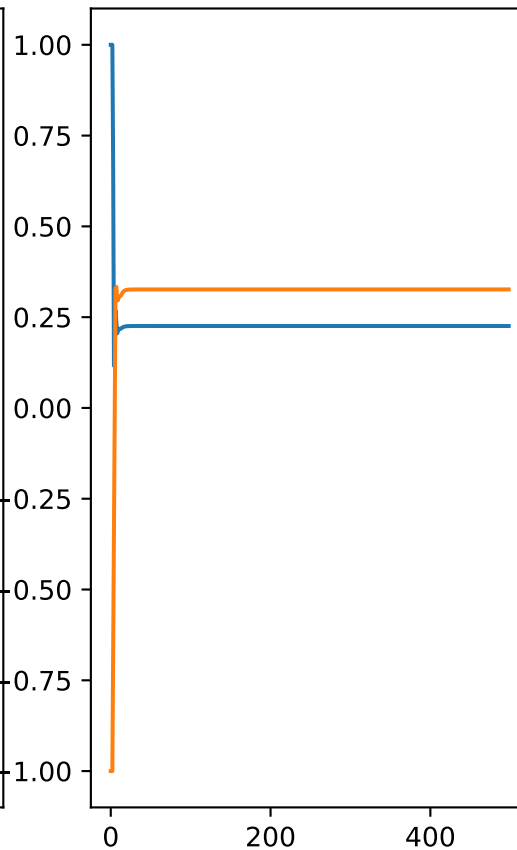


Reward: quadratic_2
Speed = 14.76548496628754 [rad/s]

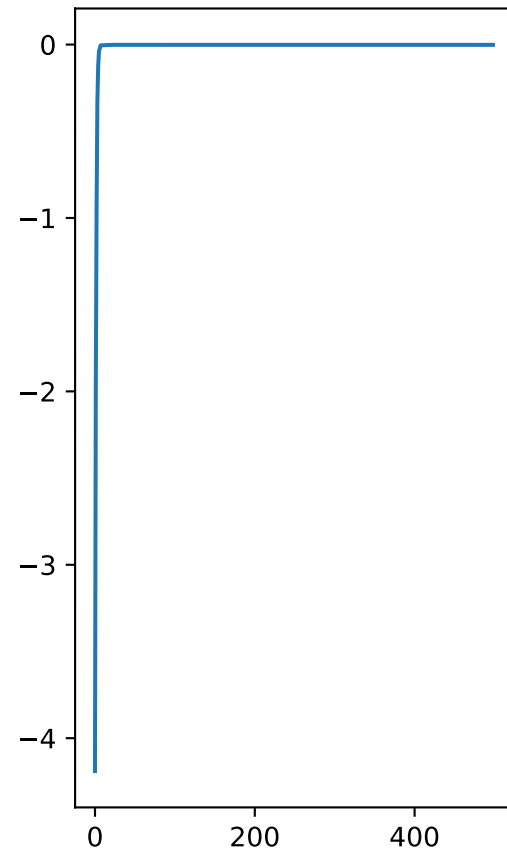
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq