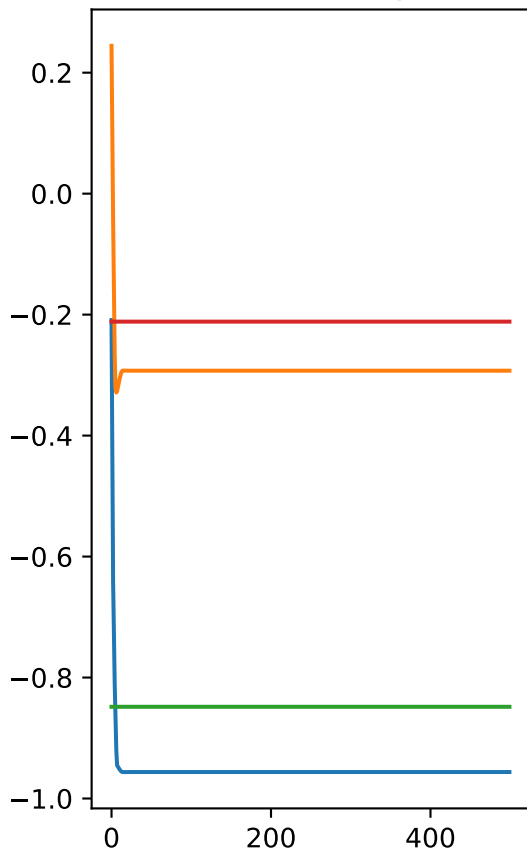
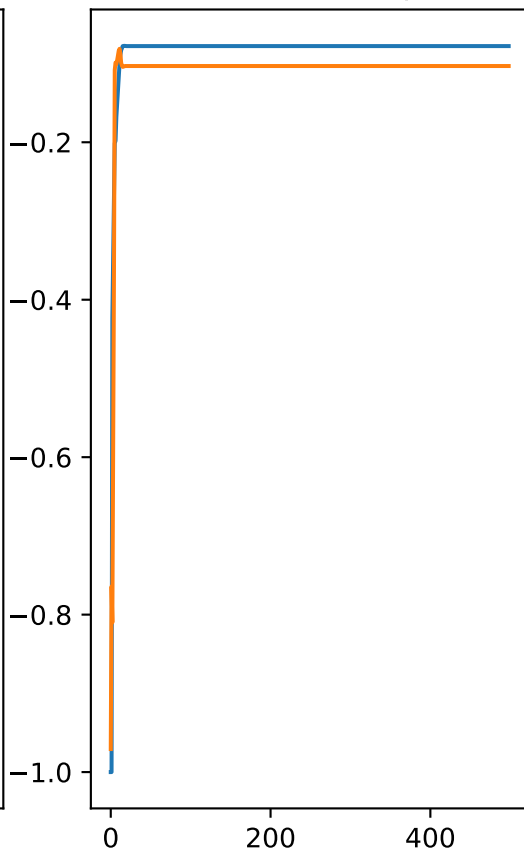


Reward: quadratic_2
Speed = 1049.7819992317084 [rad/s]

State vs step



Action vs step



Reward vs step

