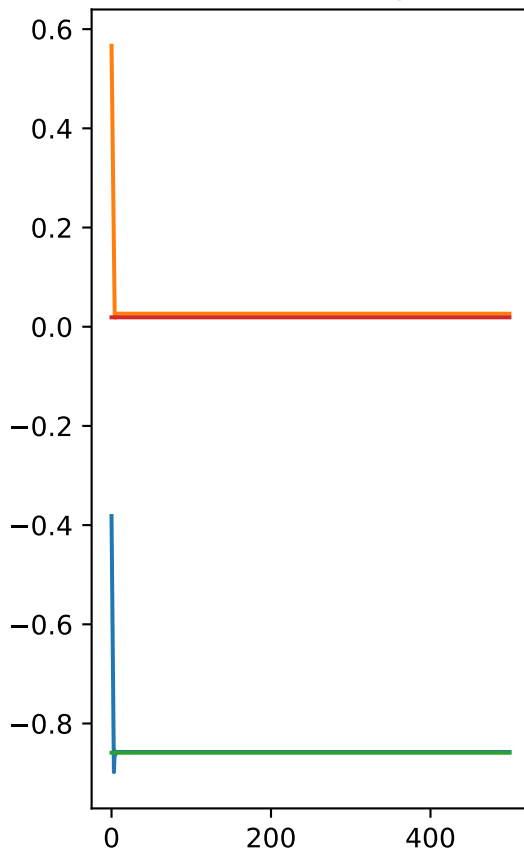
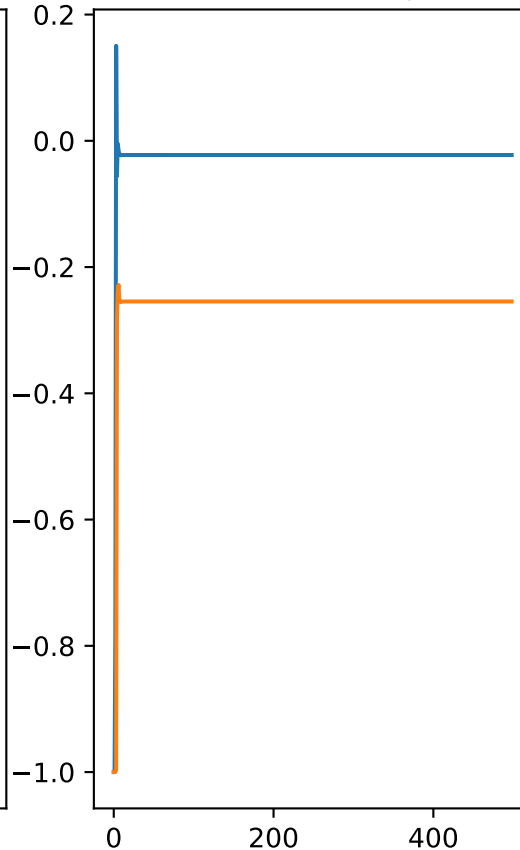


Reward: quartic_root
Speed = 864.8678806884432 [rad/s]

State vs step



Action vs step



Reward vs step

