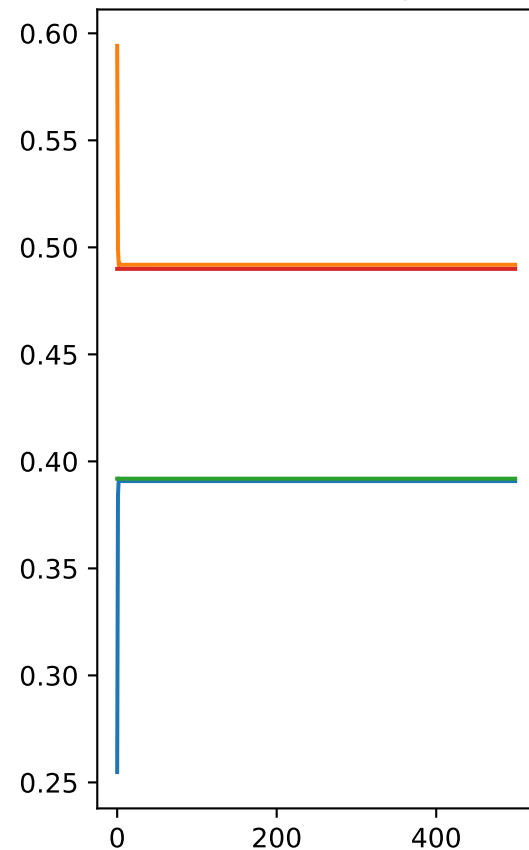
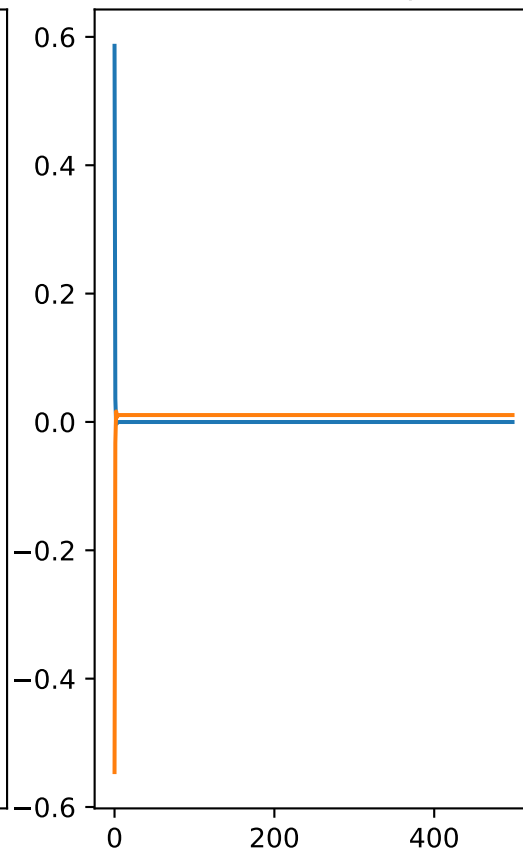


Reward: square_root
Speed = 268.4051050505496 [rad/s]

State vs step



Action vs step



Reward vs step

