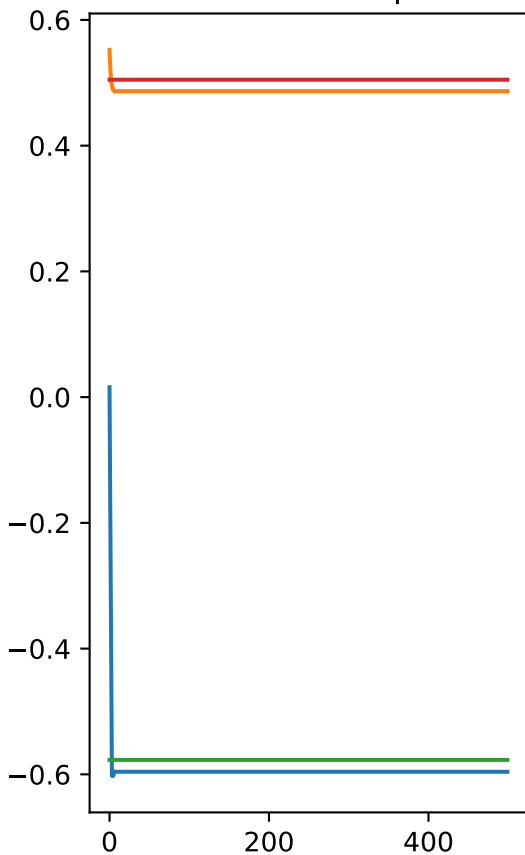
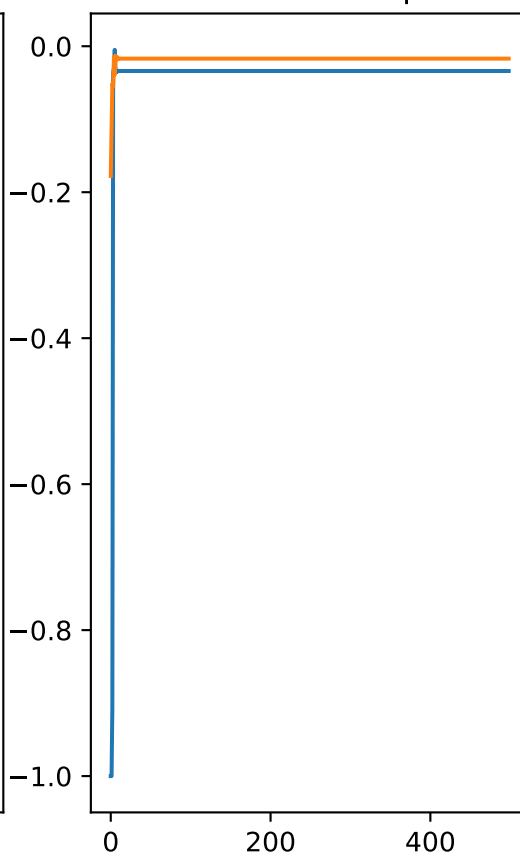


Reward: quartic_root
Speed = 306.93360165651154 [rad/s]

State vs step



Action vs step



Reward vs step

