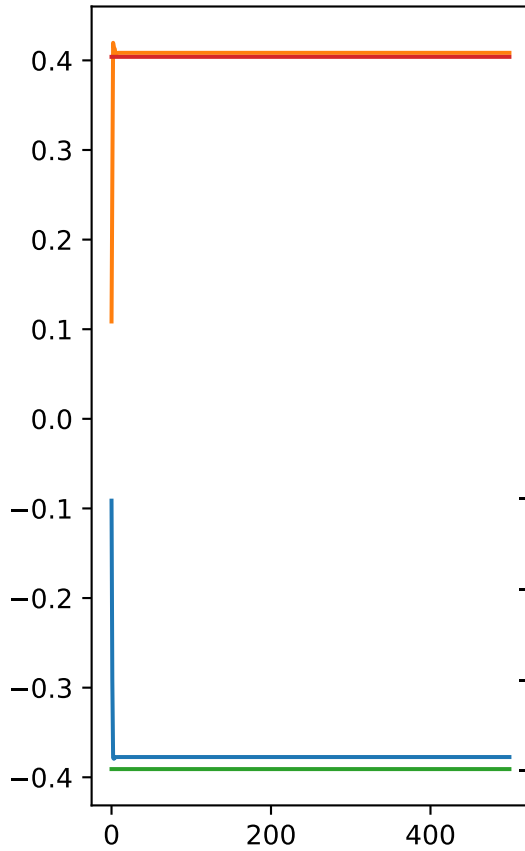
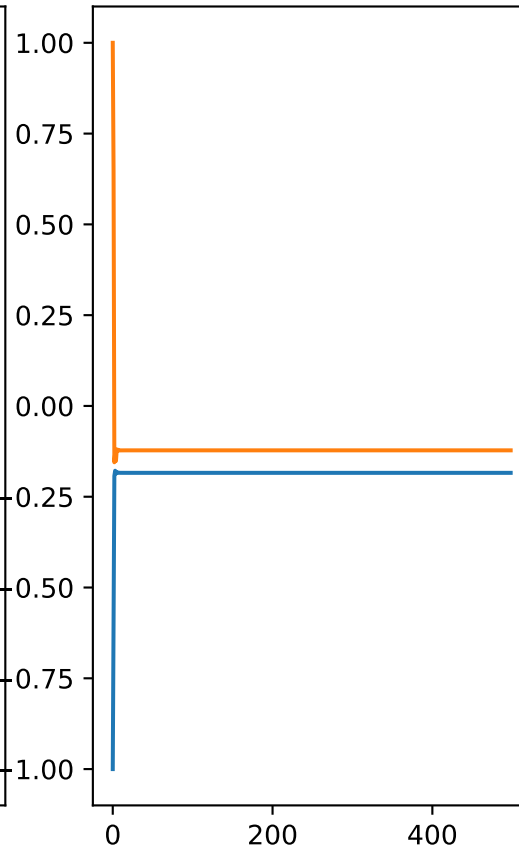


Reward: quartic_root
Speed = 359.6369645791236 [rad/s]

State vs step



Action vs step



Reward vs step

