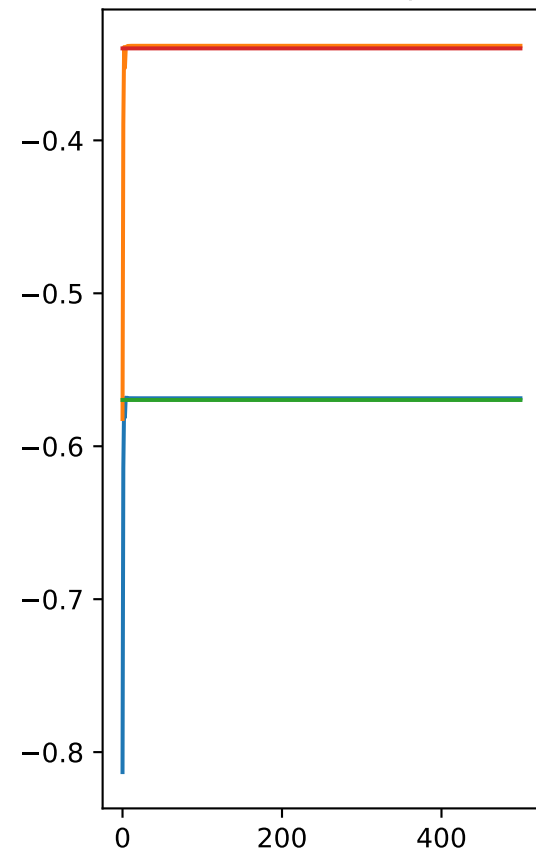
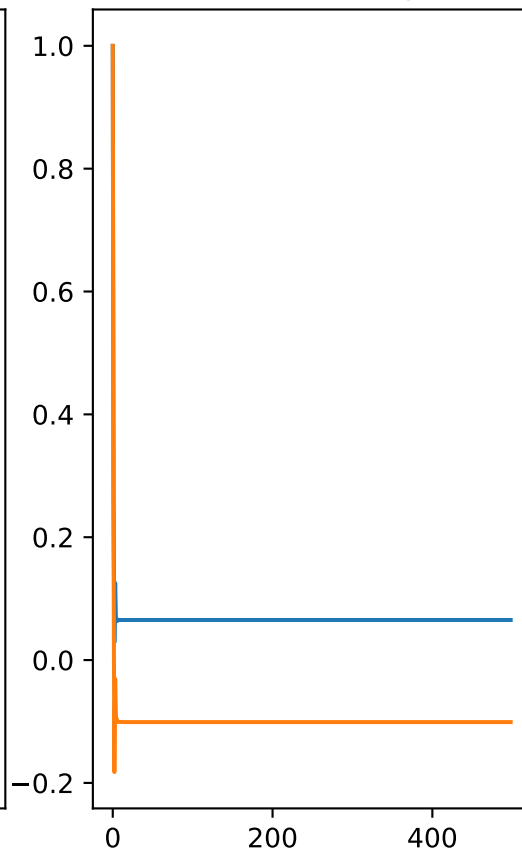


Reward: square\_root  
Speed = 809.8523488238567 [rad/s]

State vs step



Action vs step



Reward vs step

