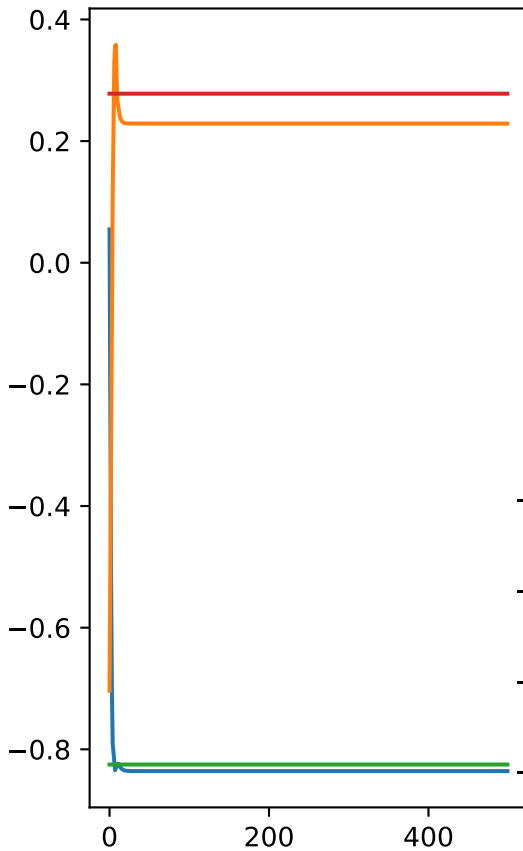
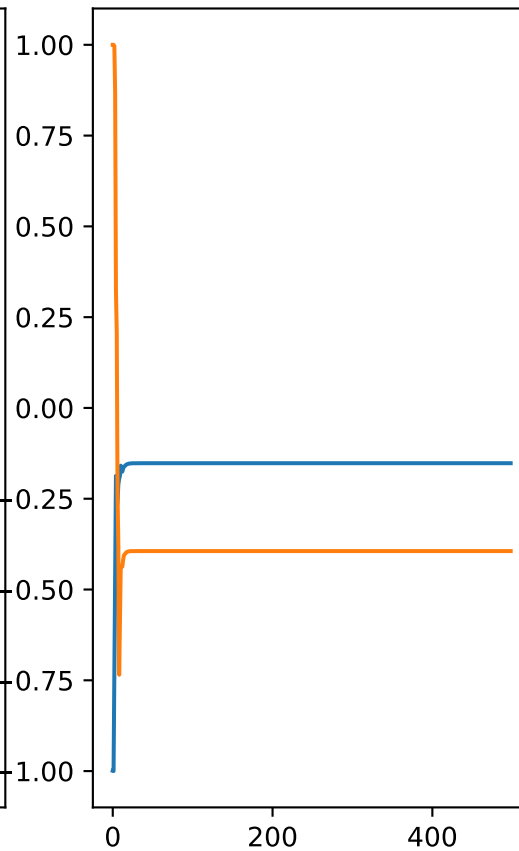


Reward: quadratic
Speed = 902.8685845394326 [rad/s]

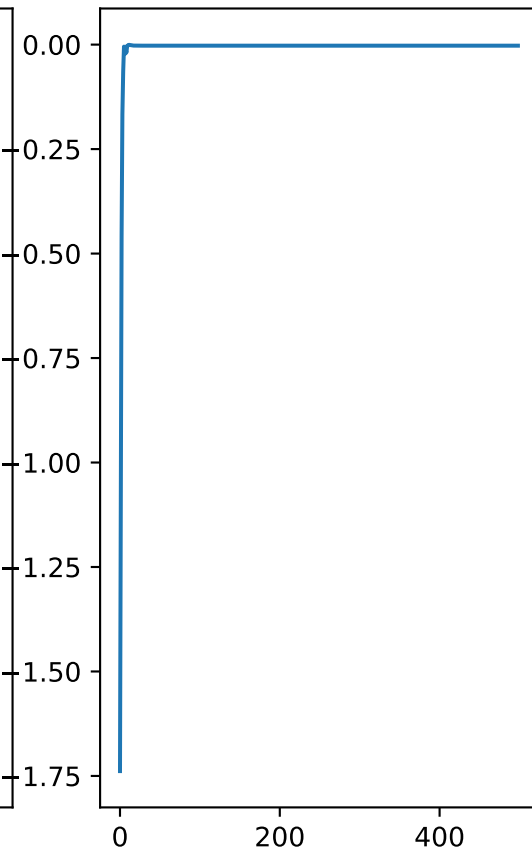
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq