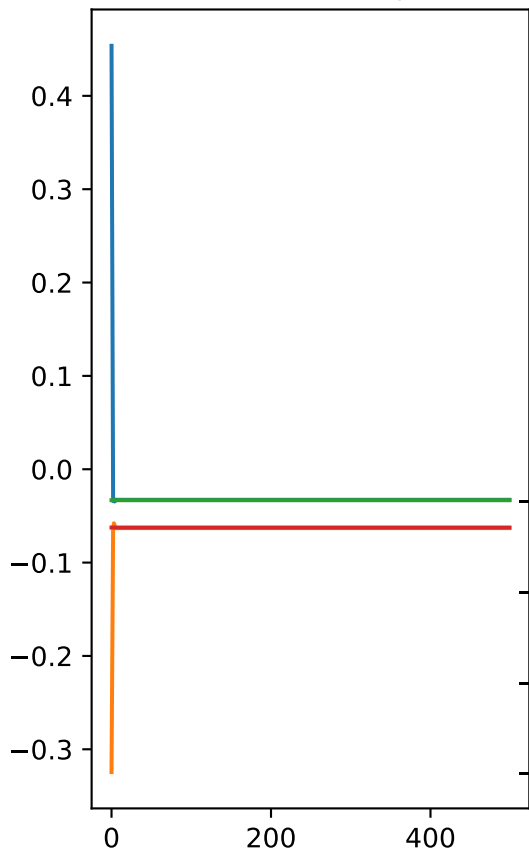
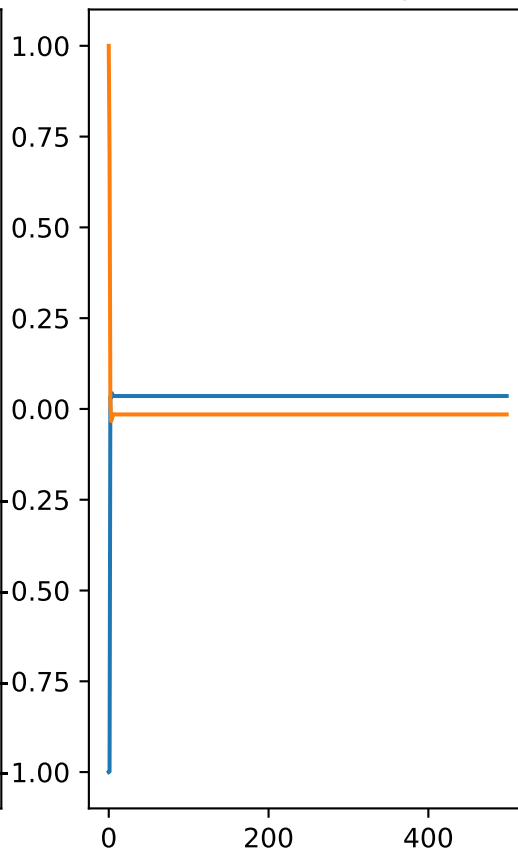


Reward: quartic_root
Speed = 1081.2608129877972 [rad/s]

State vs step



Action vs step



Reward vs step

