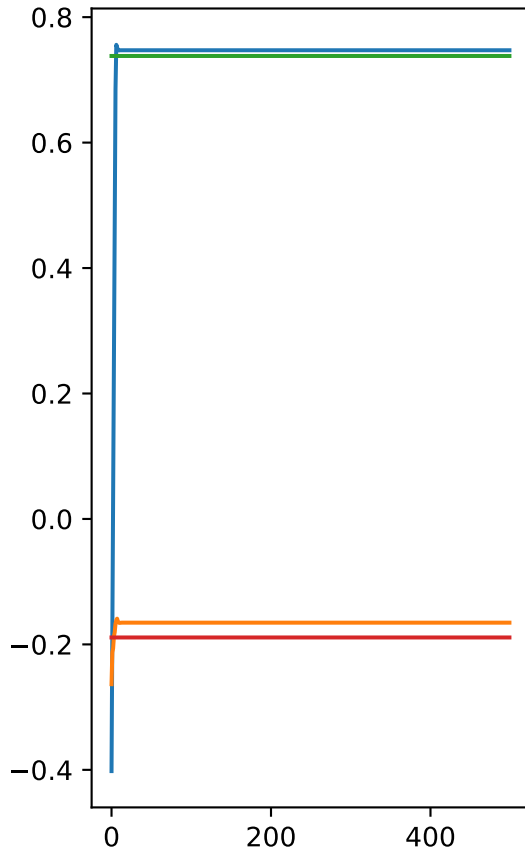
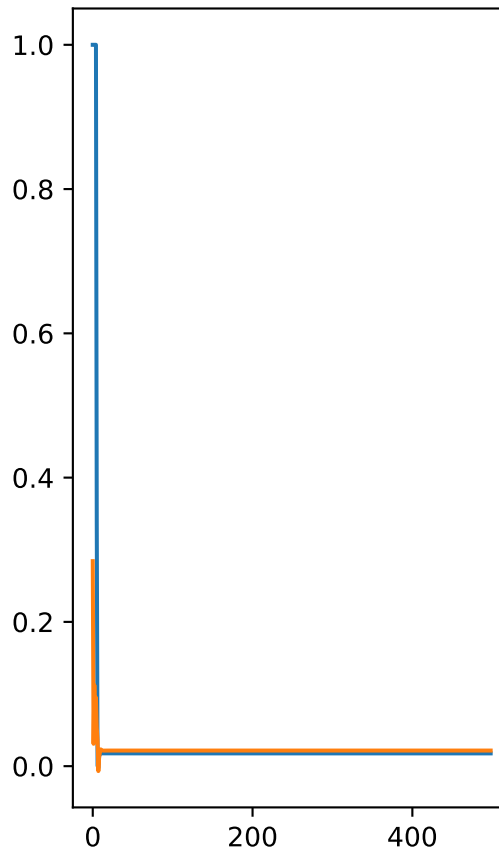


Reward: quartic_root
Speed = 662.2100685531184 [rad/s]

State vs step



Action vs step



Reward vs step

