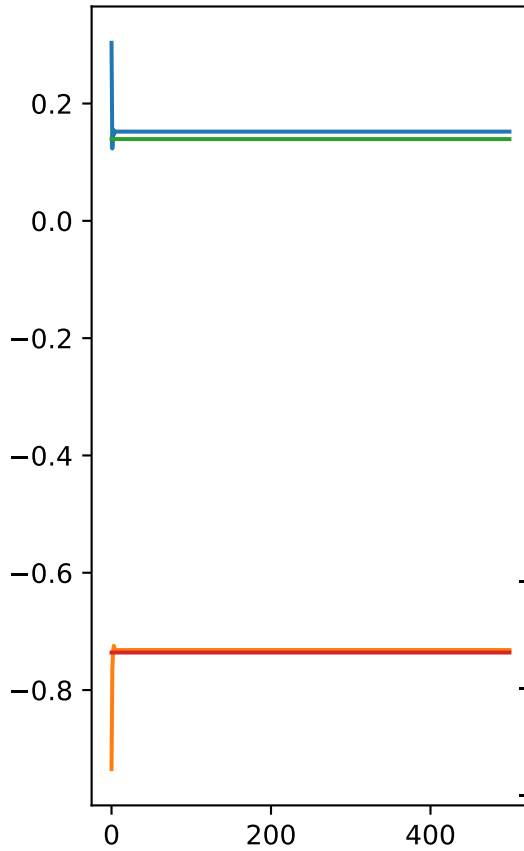
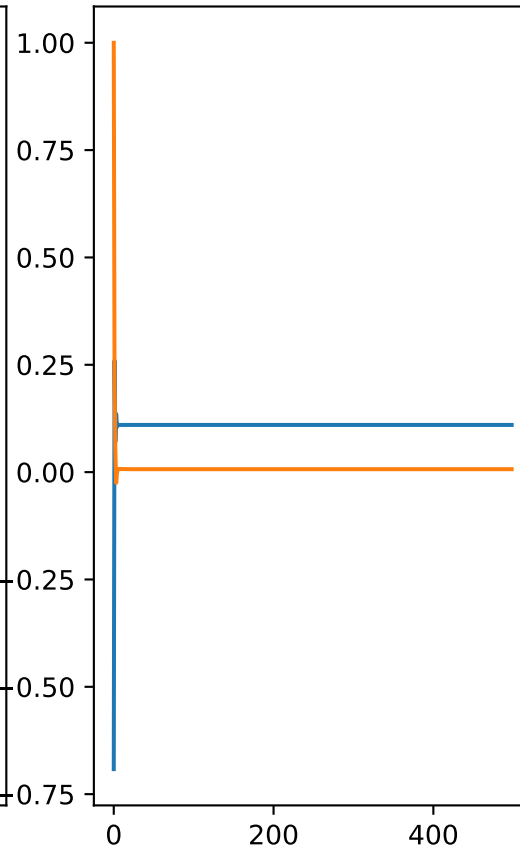


Reward: quartic_root
Speed = 514.9196001847579 [rad/s]

State vs step



Action vs step



Reward vs step

