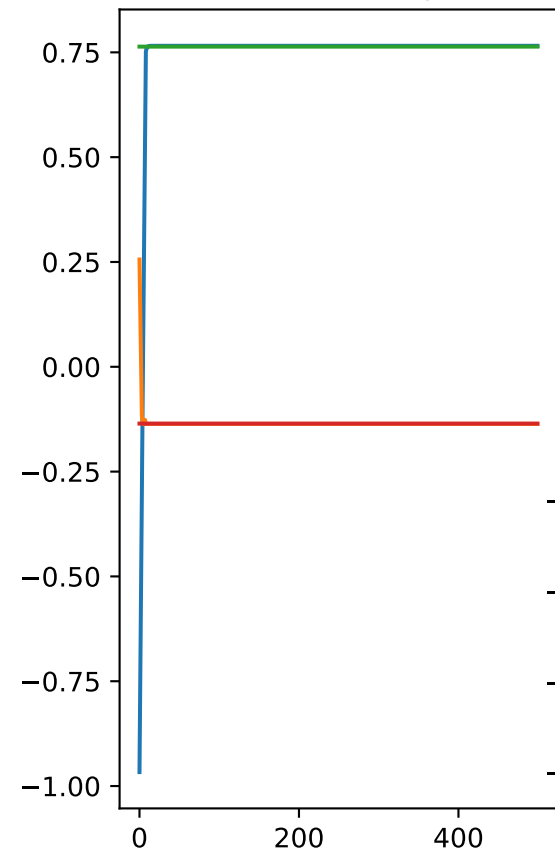
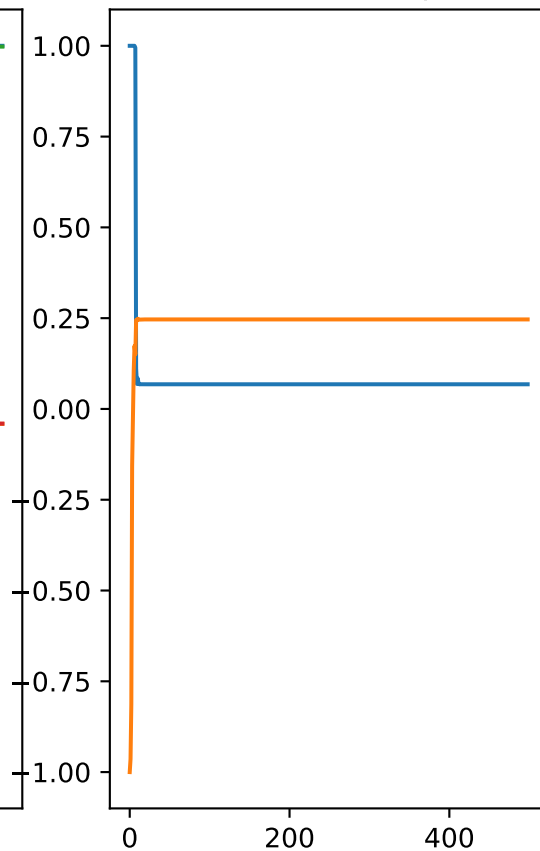


Reward: square_root
Speed = 669.2220385452425 [rad/s]

State vs step



Action vs step



Reward vs step

