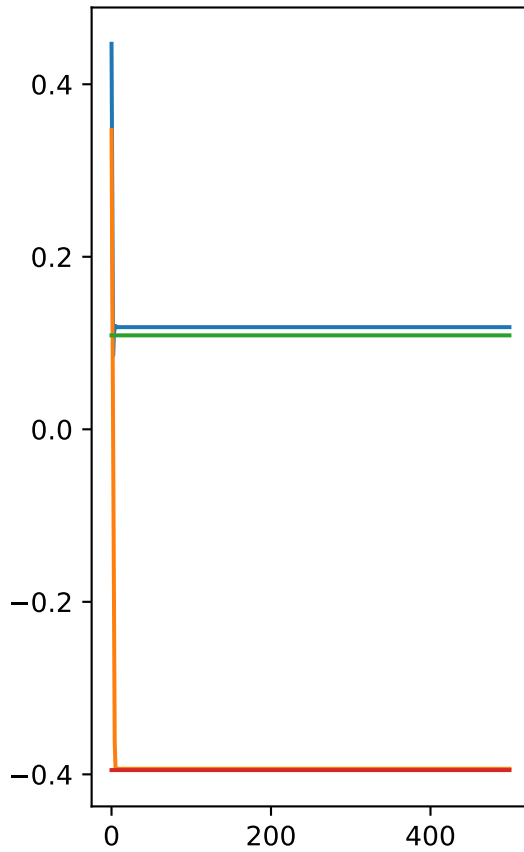
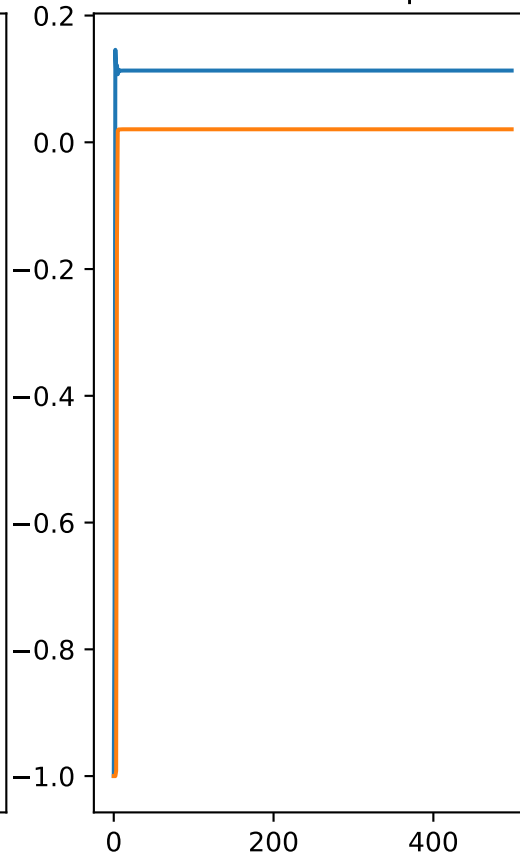


Reward: square_root_2
Speed = 447.5010322050755 [rad/s]

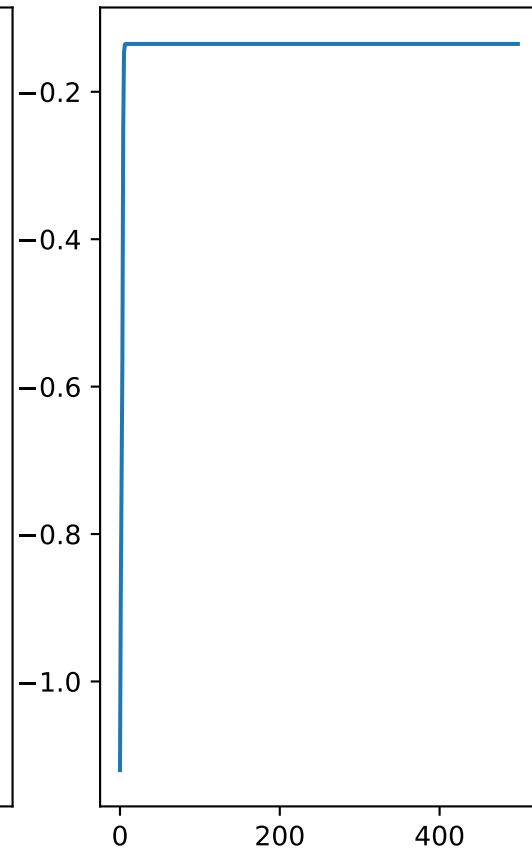
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq