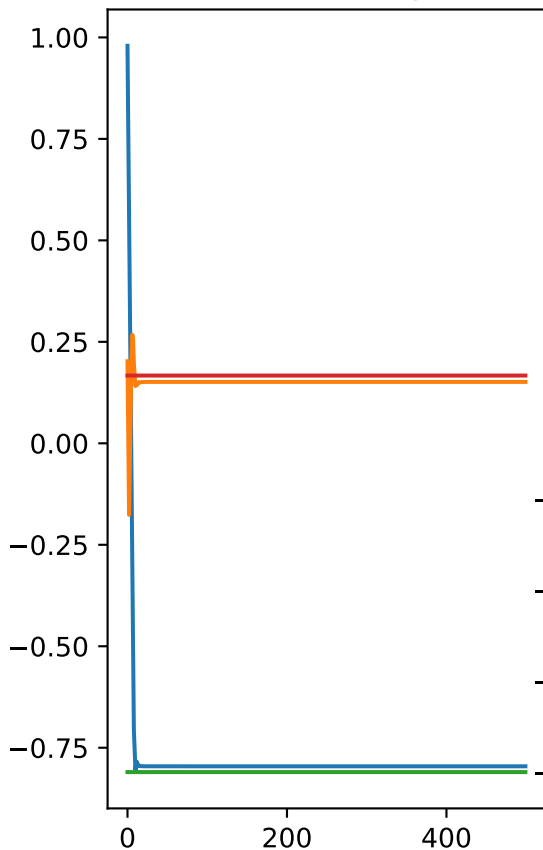
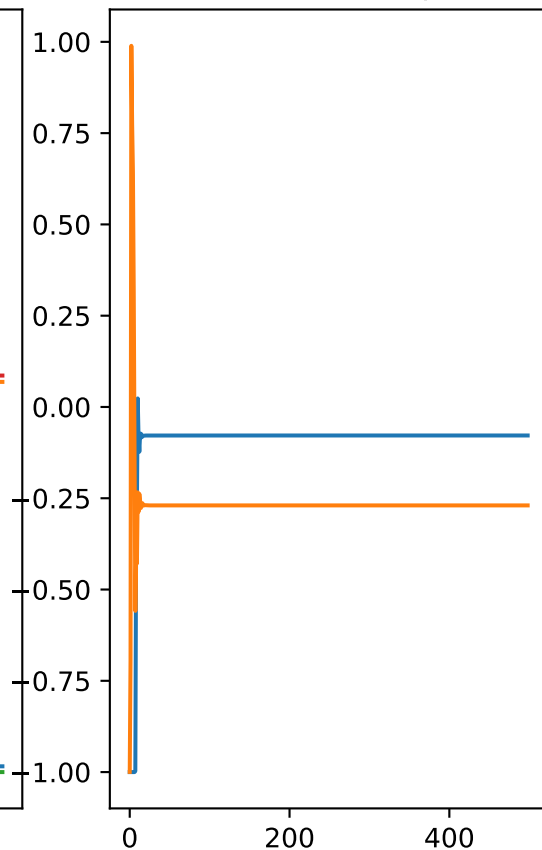


Reward: quadratic
Speed = 379.7557068432079 [rad/s]

State vs step



Action vs step



Reward vs step

