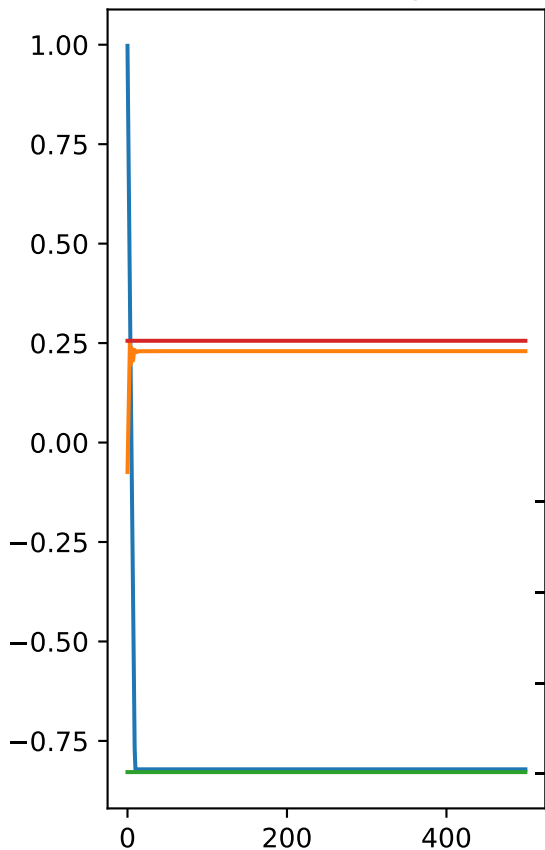
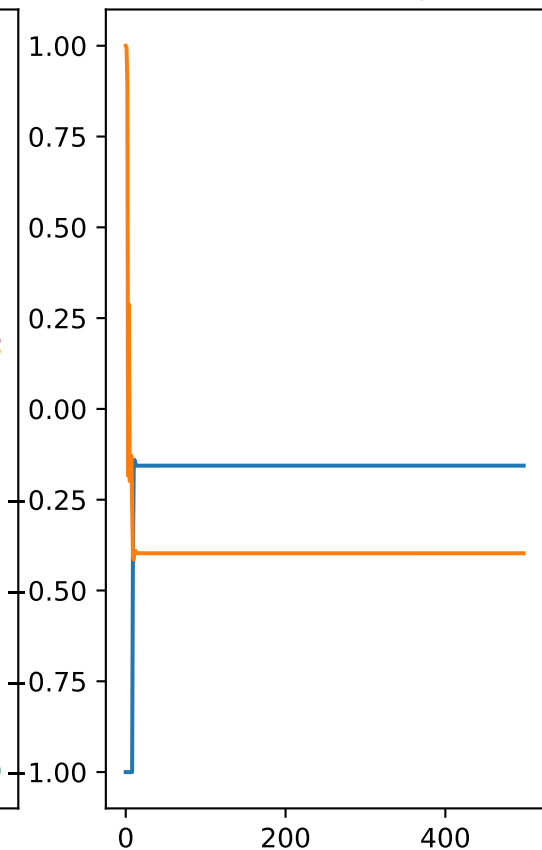


Reward: quartic_root_2
Speed = 1029.0600759478564 [rad/s]

State vs step



Action vs step



Reward vs step

