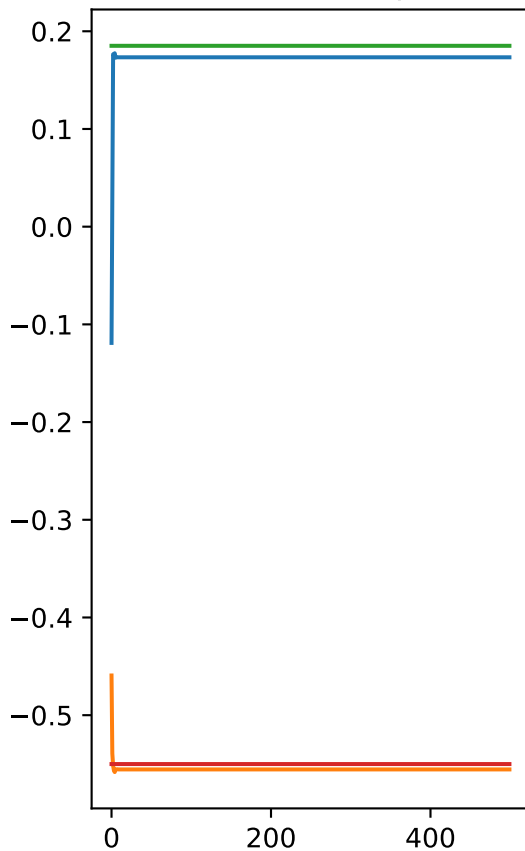
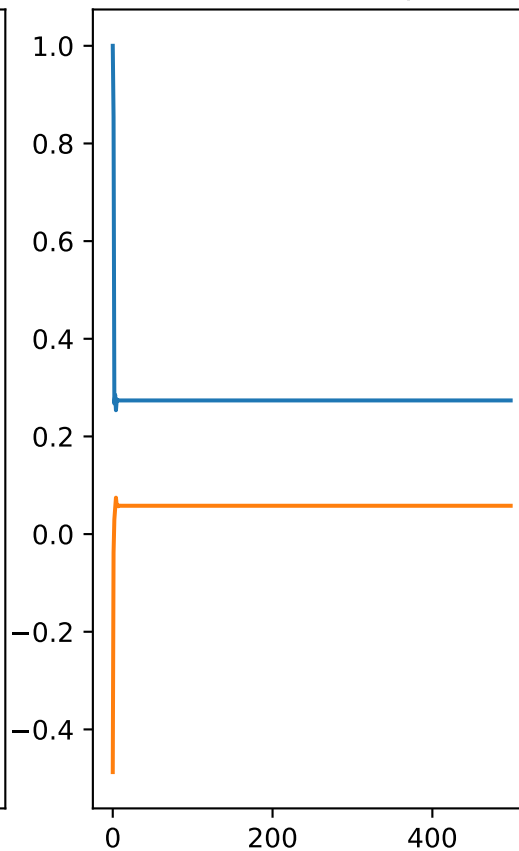


Reward: quartic_root
Speed = 423.3861501463 [rad/s]

State vs step



Action vs step



Reward vs step

