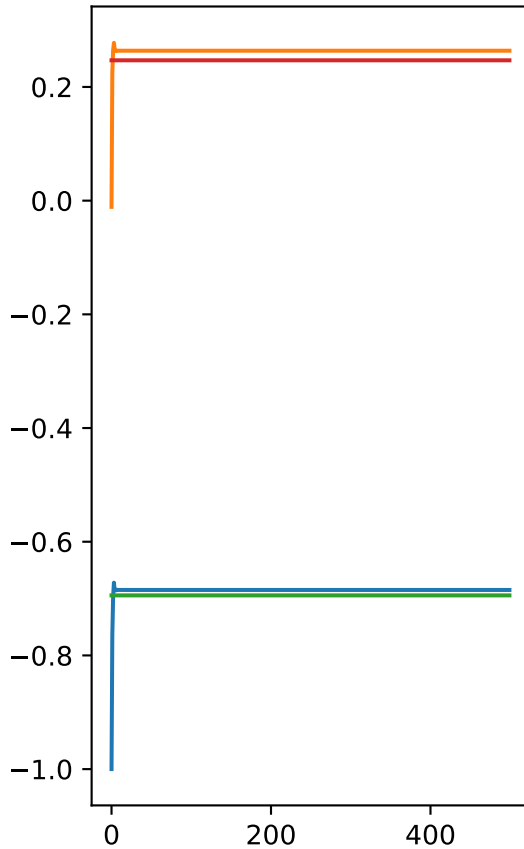
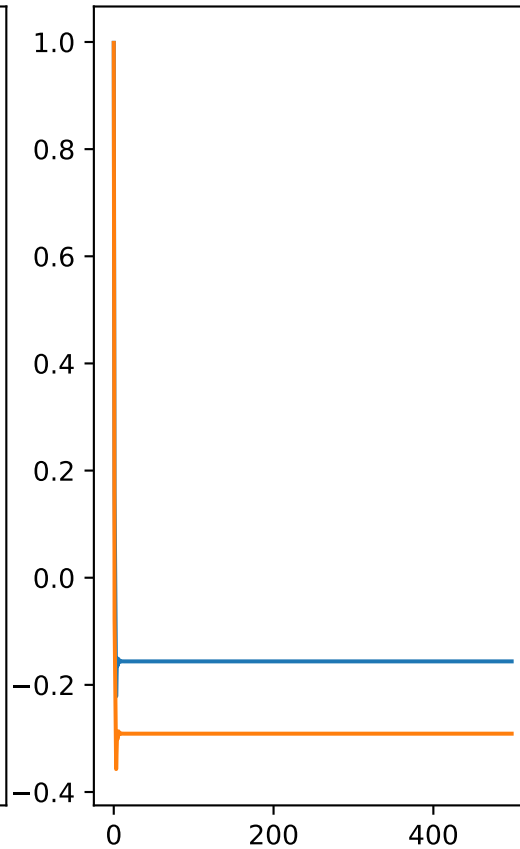


Reward: quartic\_root  
Speed = 351.1169671361745 [rad/s]

State vs step



Action vs step



Reward vs step

