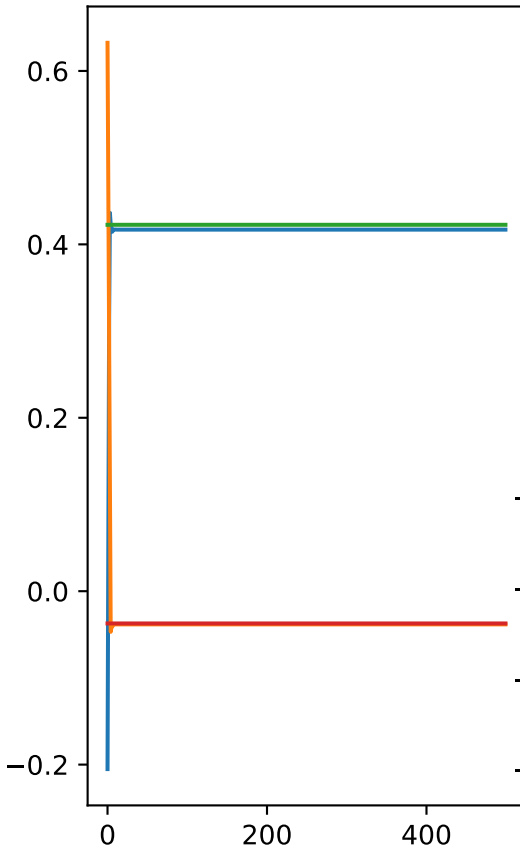
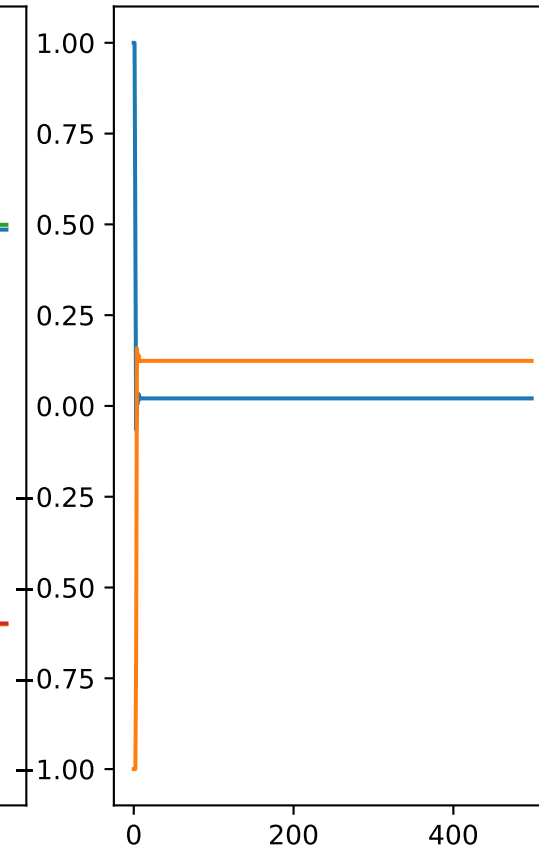


Reward: quartic_root_2
Speed = 923.6659335387828 [rad/s]

State vs step



Action vs step



Reward vs step

