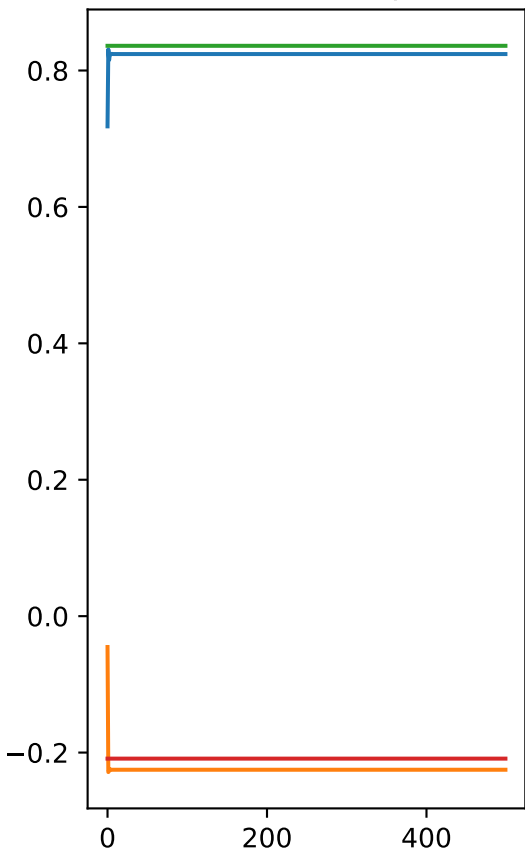
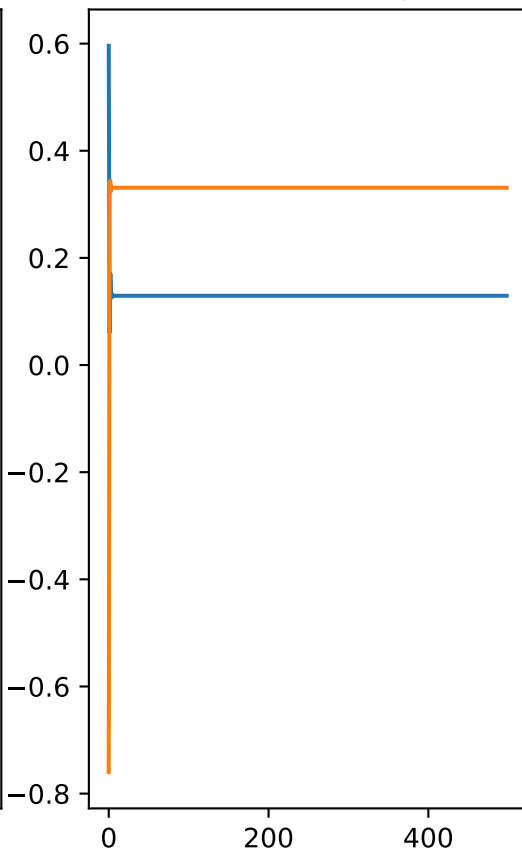


Reward: quartic_root_2
Speed = 1100.8517999476119 [rad/s]

State vs step



Action vs step



Reward vs step

