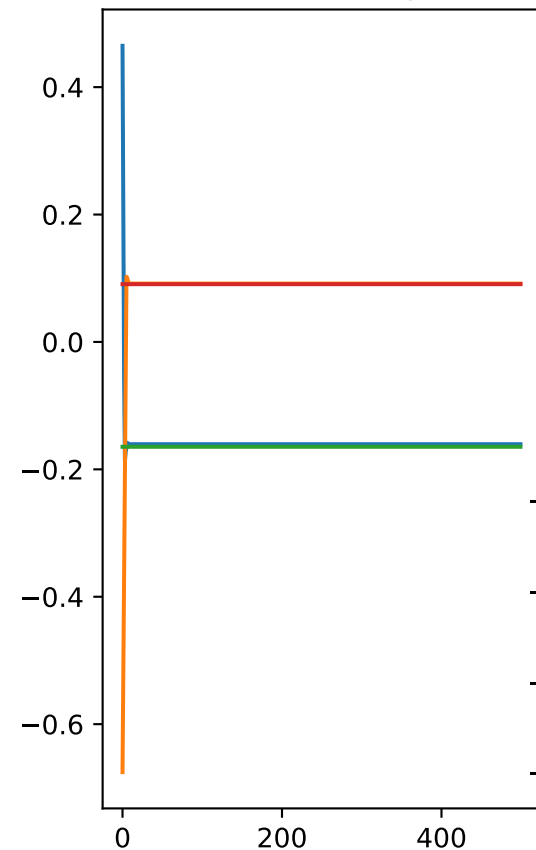
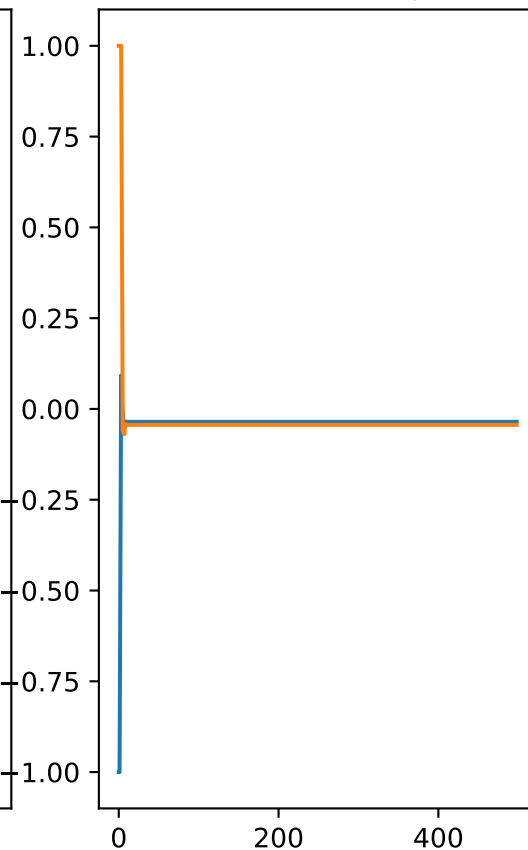


Reward: quartic_root
Speed = 480.91499867777567 [rad/s]

State vs step



Action vs step



Reward vs step

