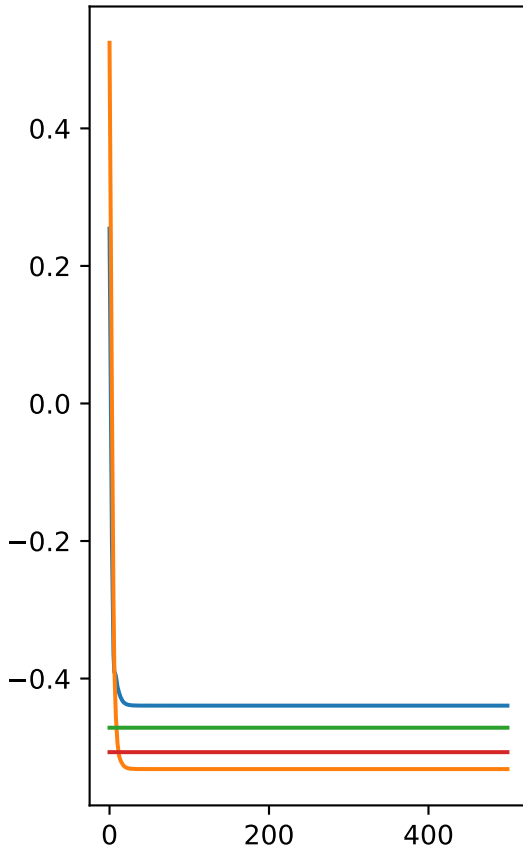
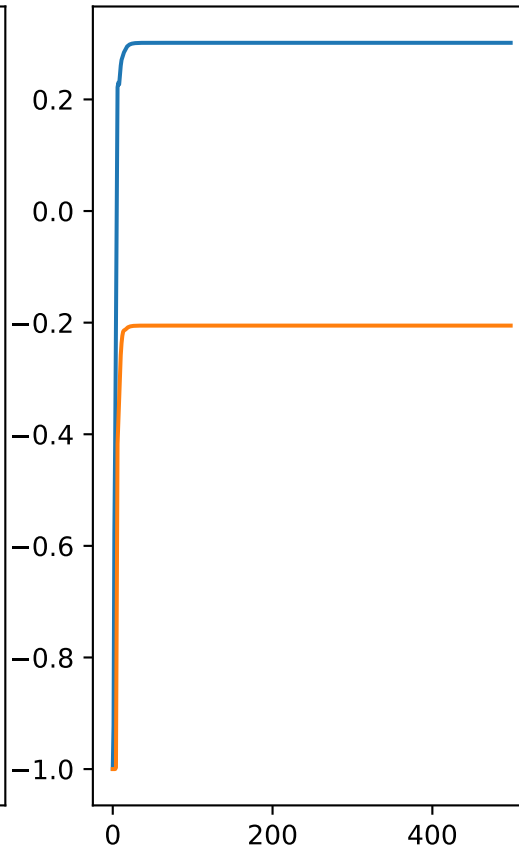


Reward: quadratic
Speed = 599.9436686630601 [rad/s]

State vs step



Action vs step



Reward vs step

