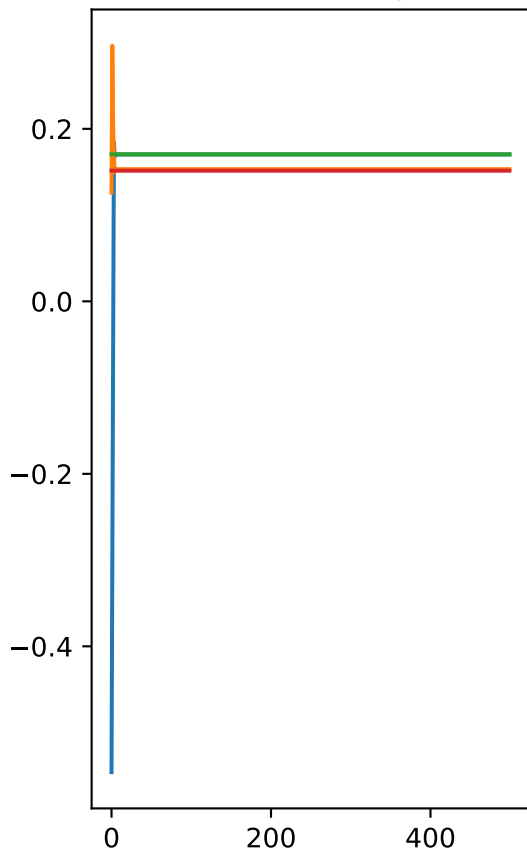
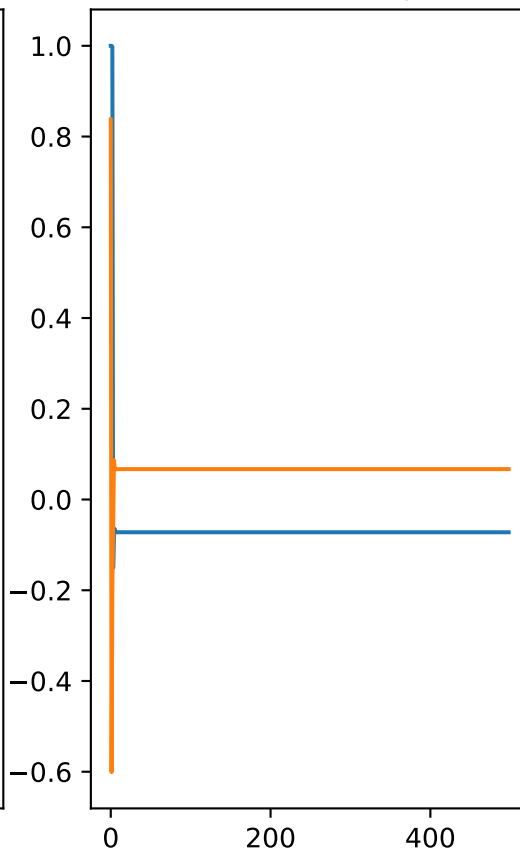


Reward: square_root_2
Speed = 253.30033778264948 [rad/s]

State vs step



Action vs step



Reward vs step

