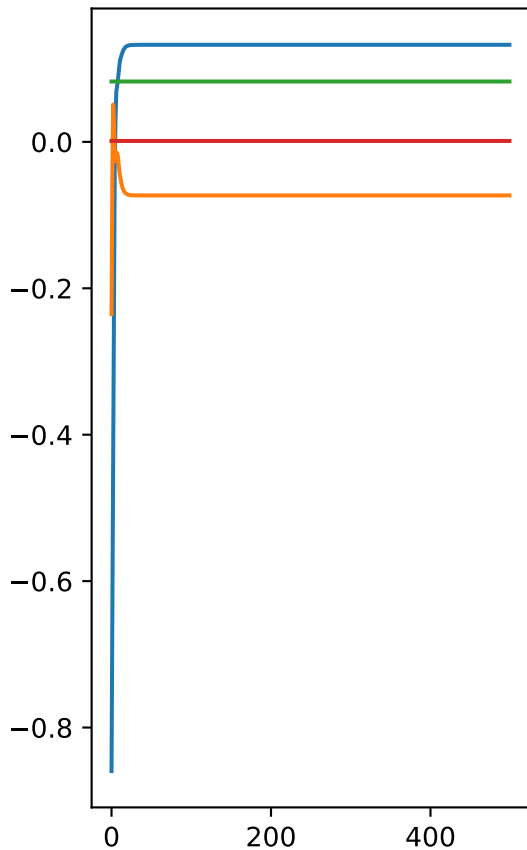
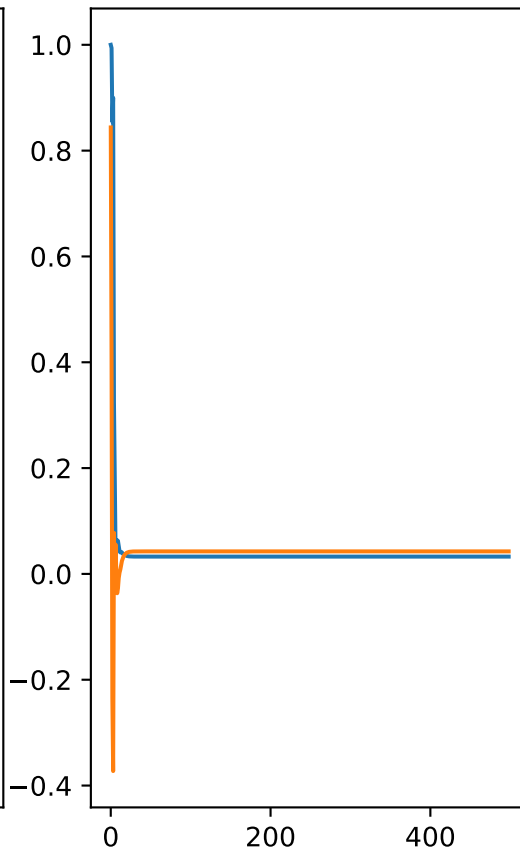


Reward: quadratic
Speed = 104.32601091368076 [rad/s]

State vs step



Action vs step



Reward vs step

