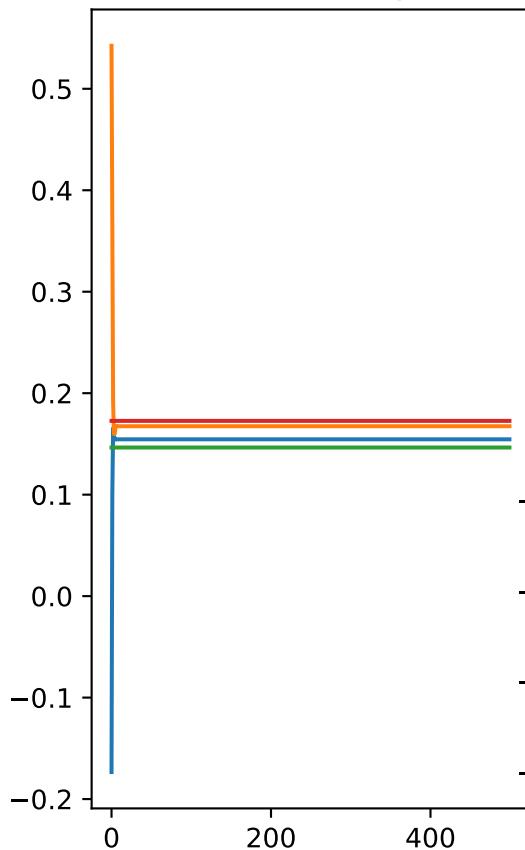
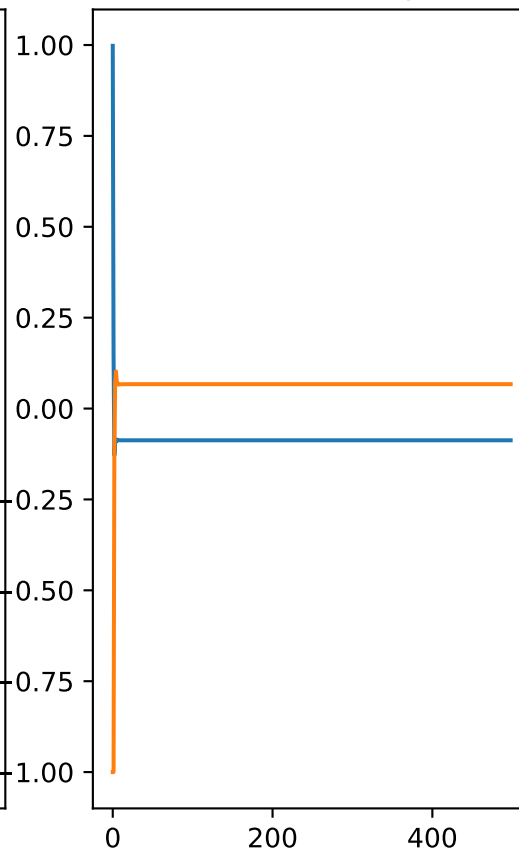


Reward: quartic_root
Speed = 746.8319539337373 [rad/s]

State vs step



Action vs step



Reward vs step

