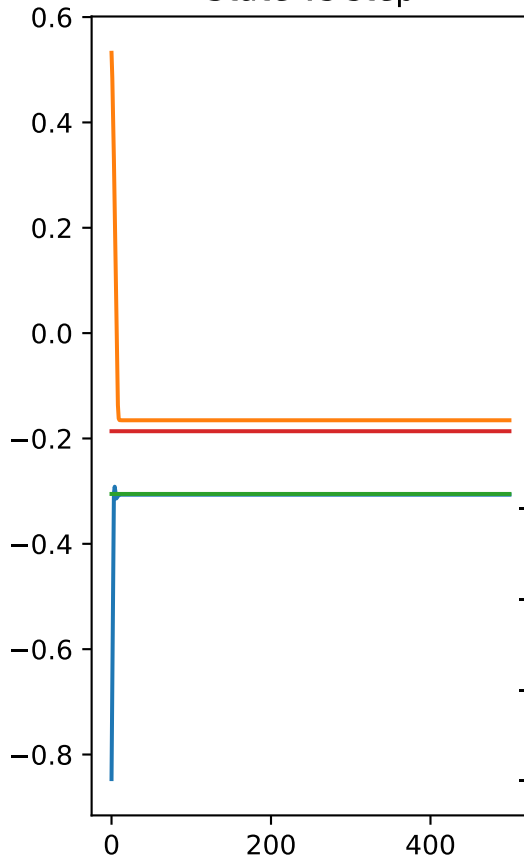
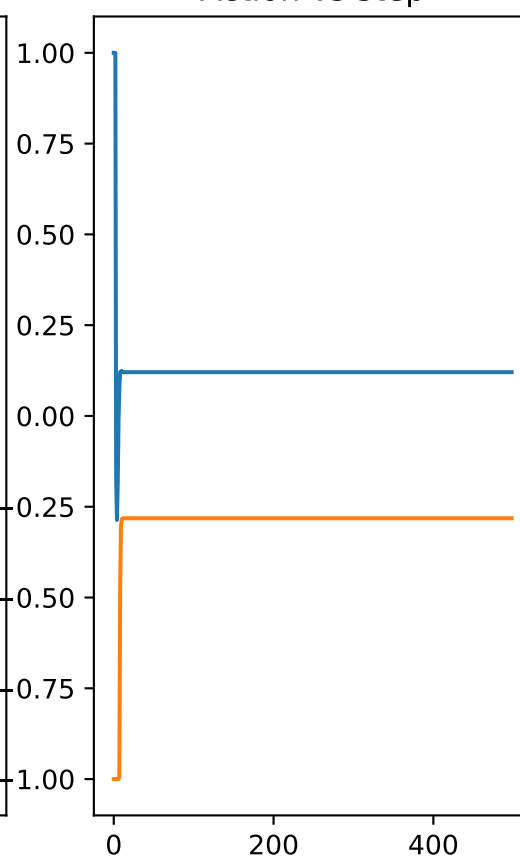


Reward: quartic_root
Speed = 791.7818603989091 [rad/s]

State vs step



Action vs step



Reward vs step

