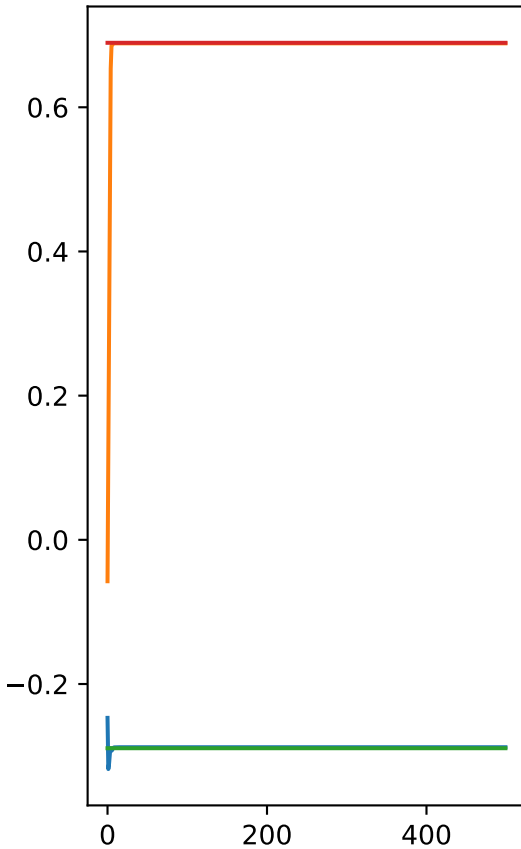
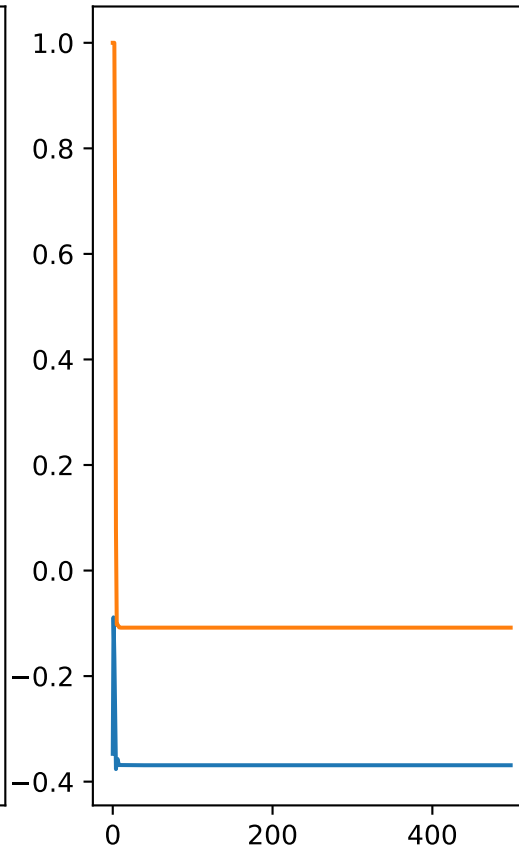


Reward: square_root
Speed = 179.62370118414694 [rad/s]

State vs step



Action vs step



Reward vs step

