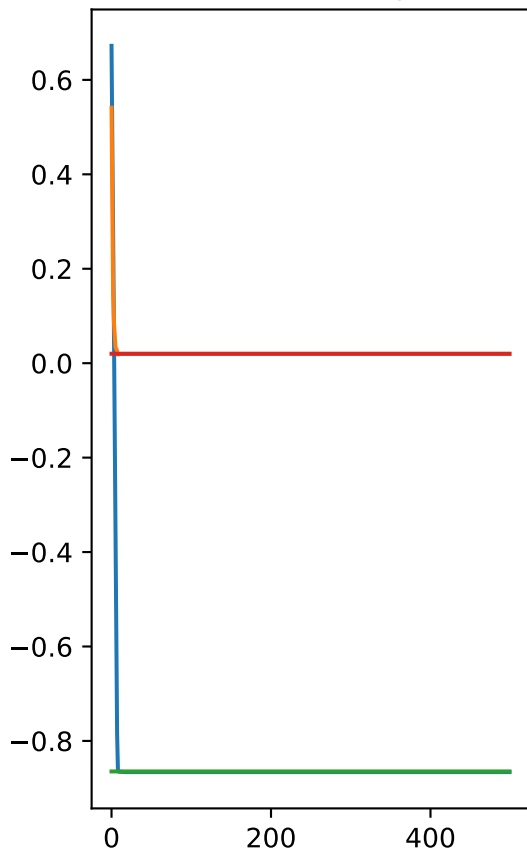
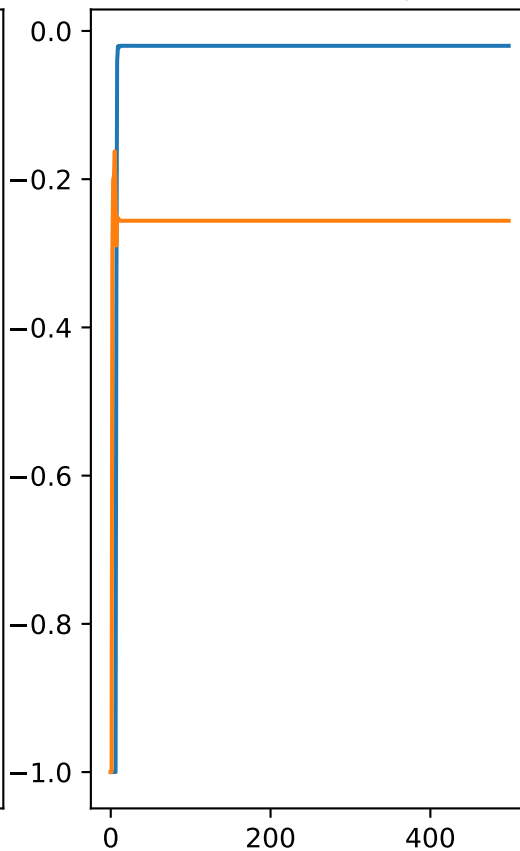


Reward: square_root
Speed = 1019.1578105141828 [rad/s]

State vs step



Action vs step



Reward vs step

