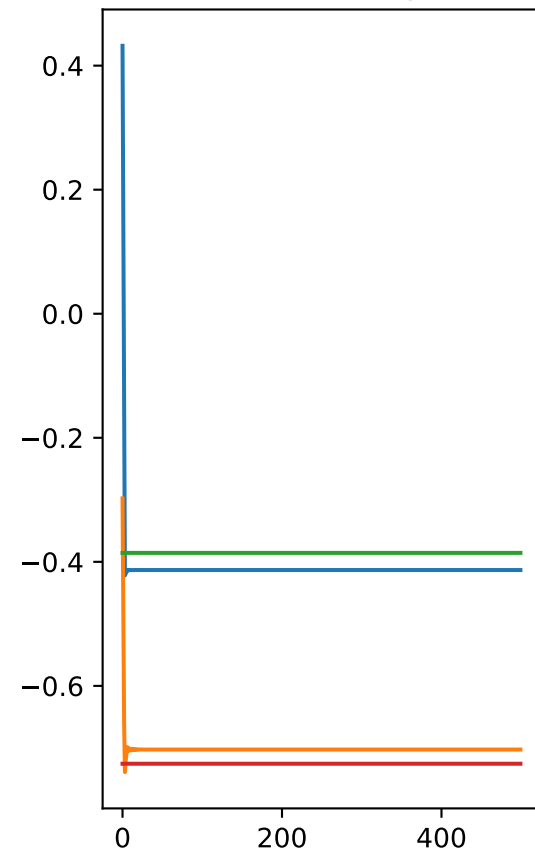
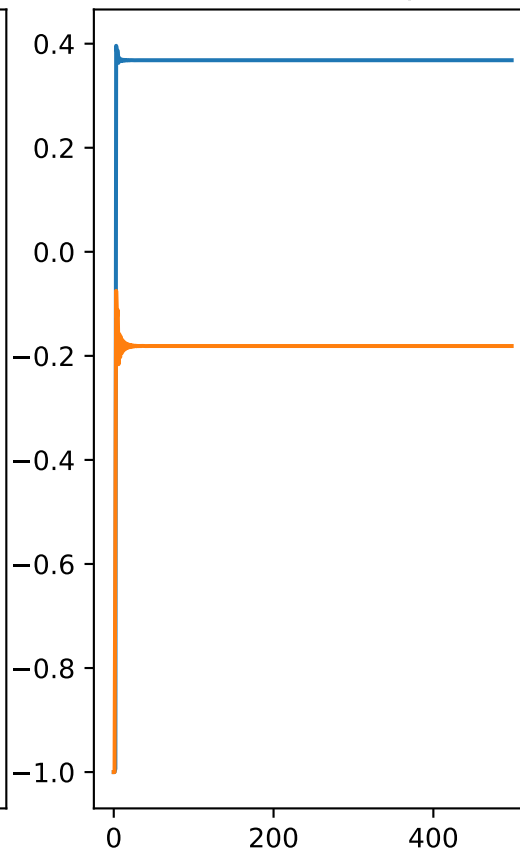


Reward: quartic_root
Speed = 433.5774975551124 [rad/s]

State vs step



Action vs step



Reward vs step

