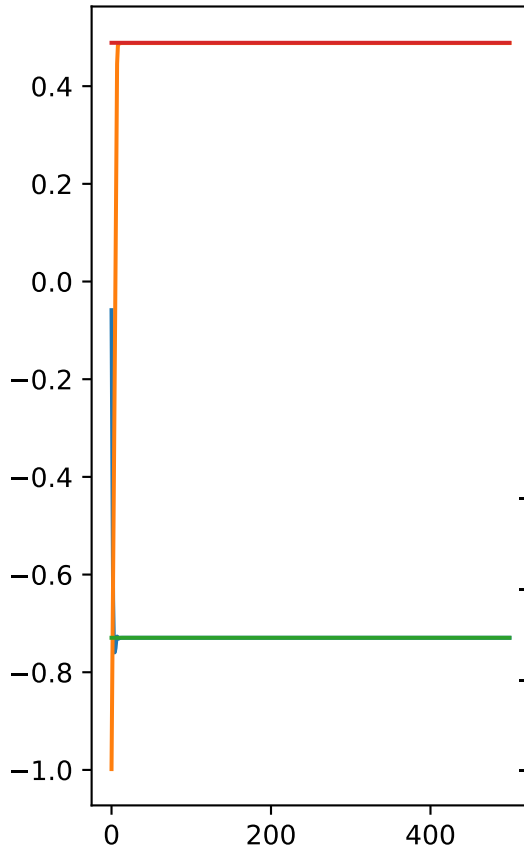
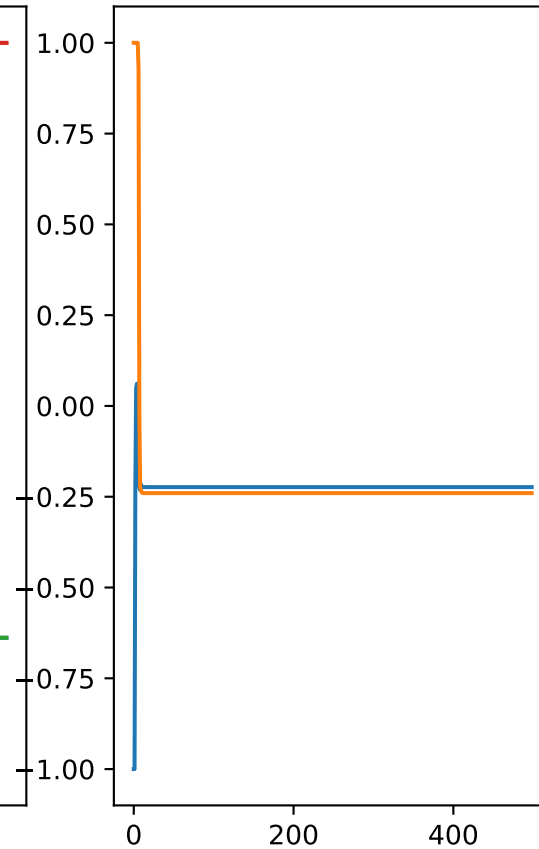


Reward: square\_root  
Speed = 735.1578208478069 [rad/s]

State vs step



Action vs step



Reward vs step

