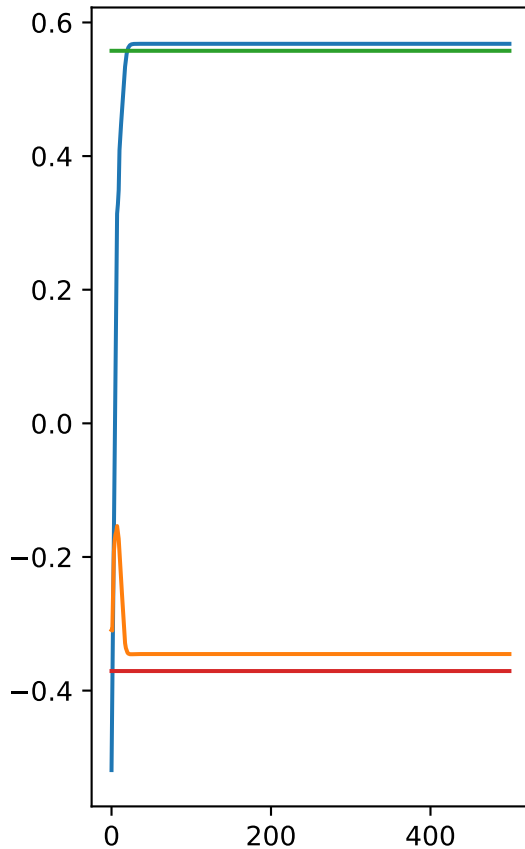
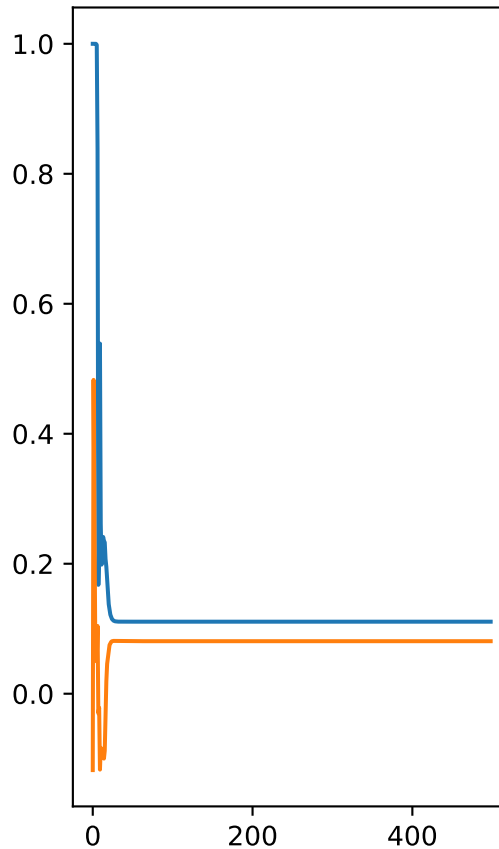


Reward: quadratic  
Speed = 729.2516203074189 [rad/s]

State vs step



Action vs step



Reward vs step

