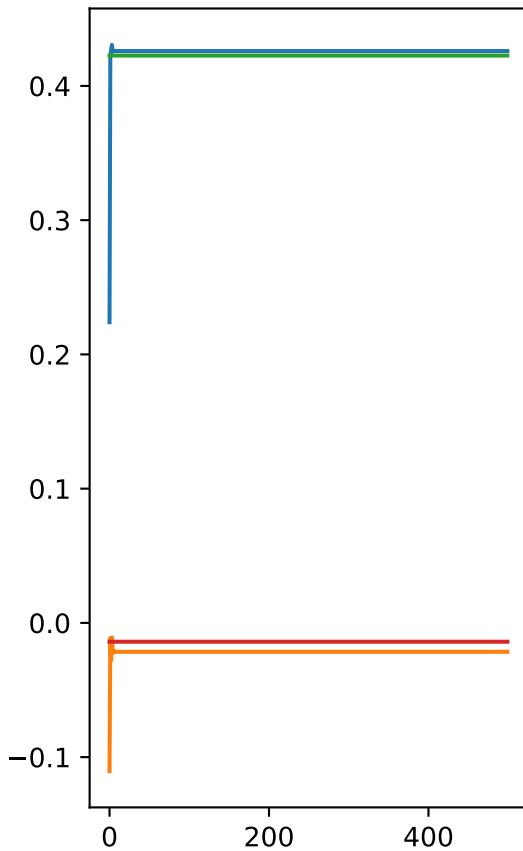
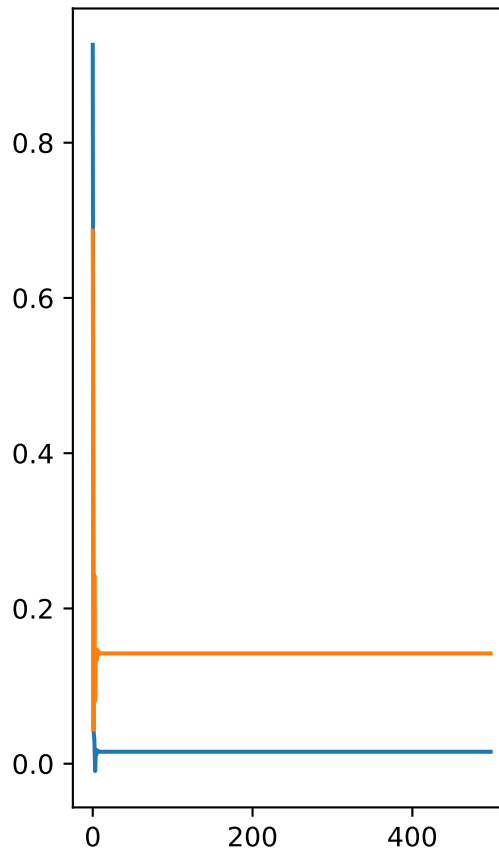


Reward: quartic_root
Speed = 86.5571598119956 [rad/s]

State vs step



Action vs step



Reward vs step

