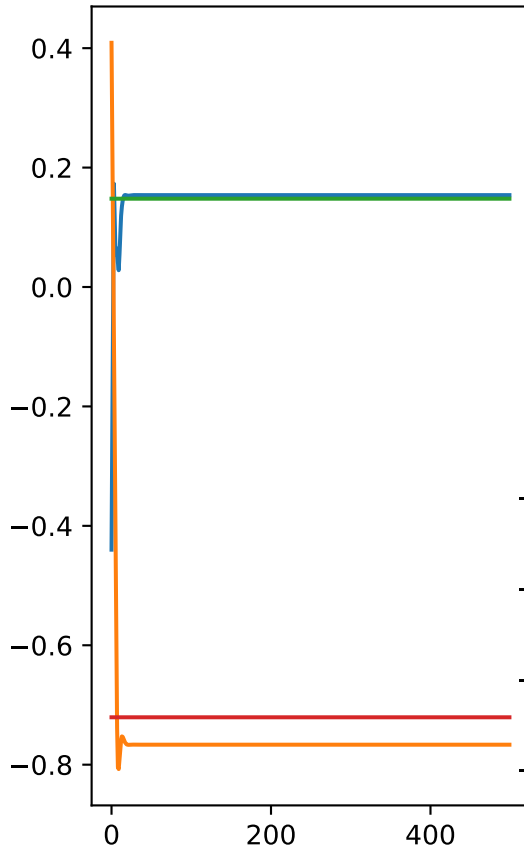
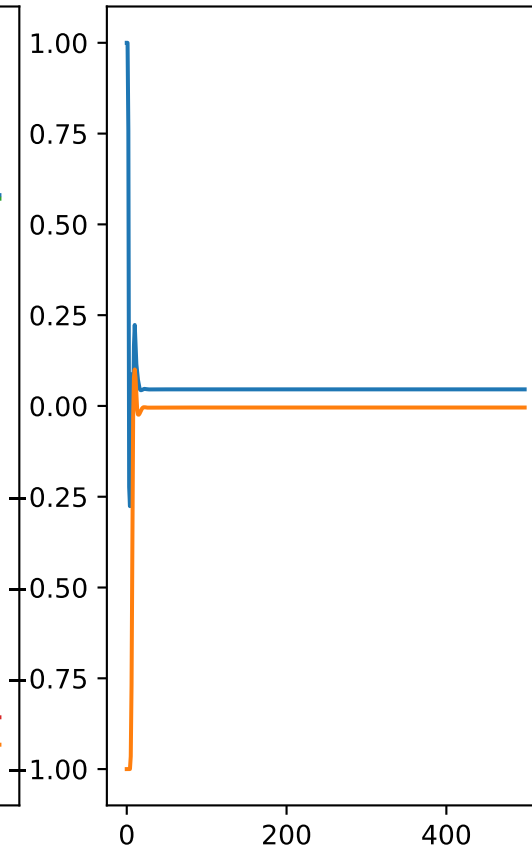


Reward: quadratic_2
Speed = 489.849687753134 [rad/s]

State vs step



Action vs step



Reward vs step

