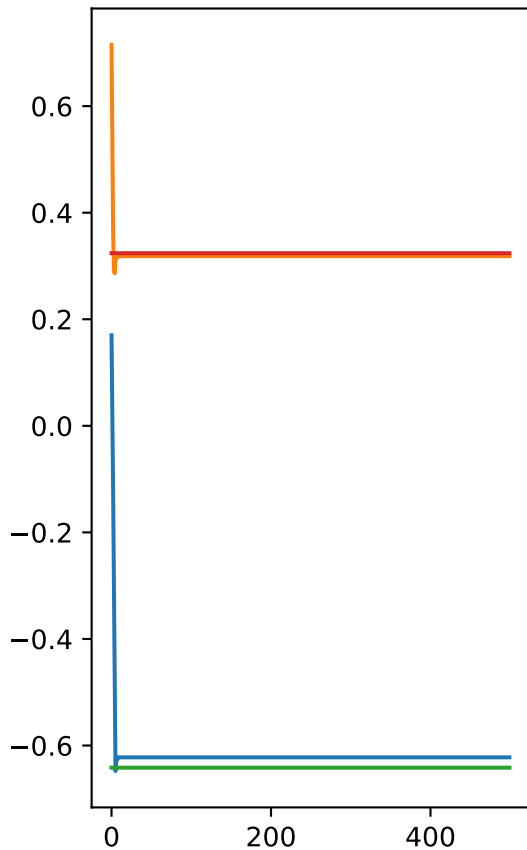
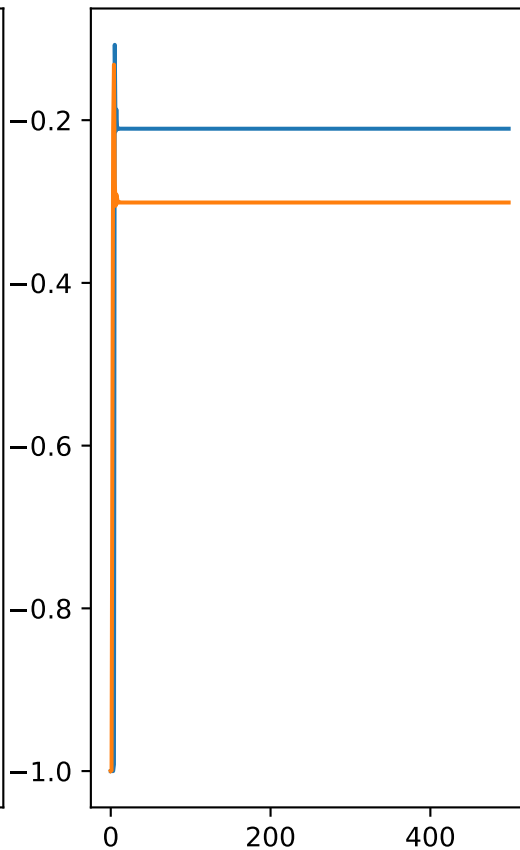


Reward: quartic_root_2
Speed = 27.005130686946305 [rad/s]

State vs step



Action vs step



Reward vs step

