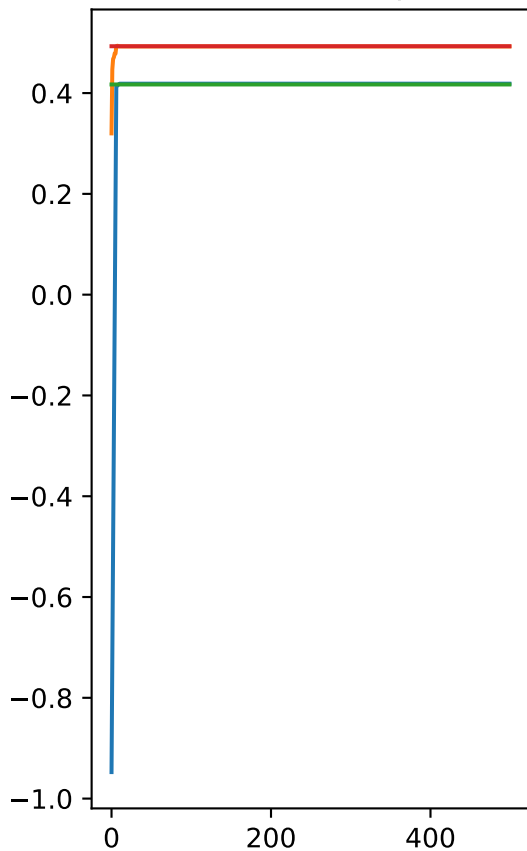
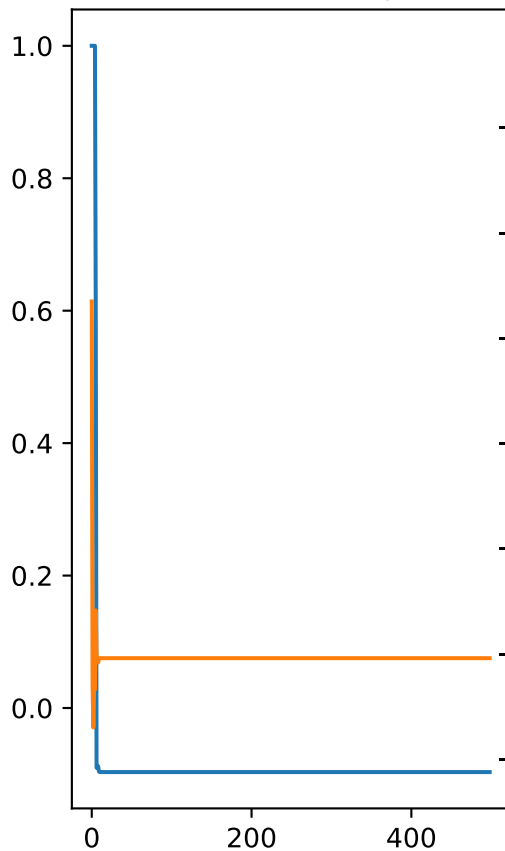


Reward: square\_root  
Speed = 204.26635727254347 [rad/s]

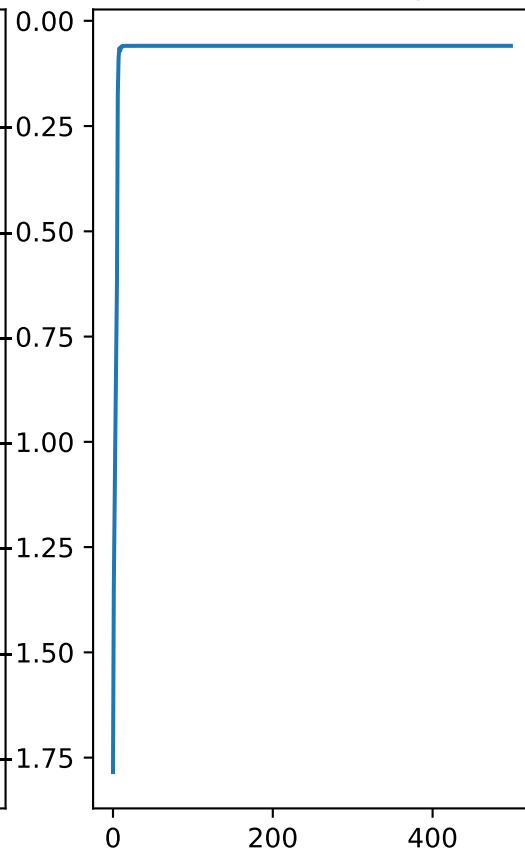
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq