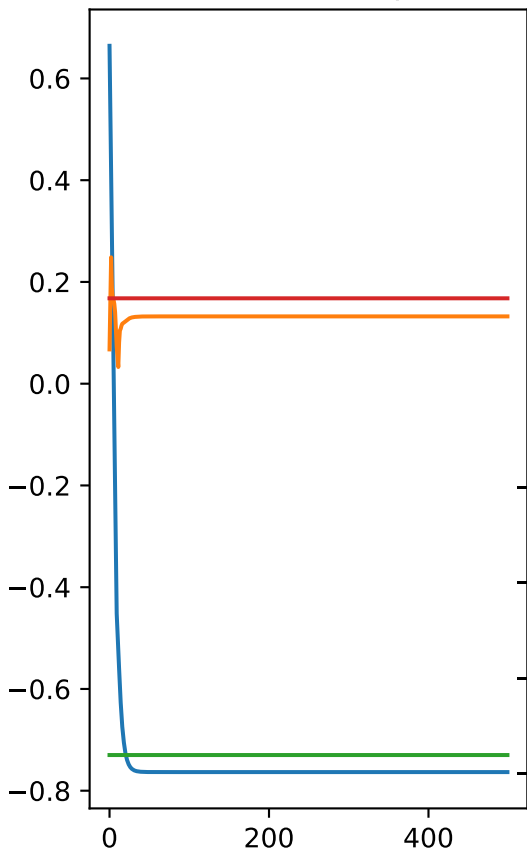
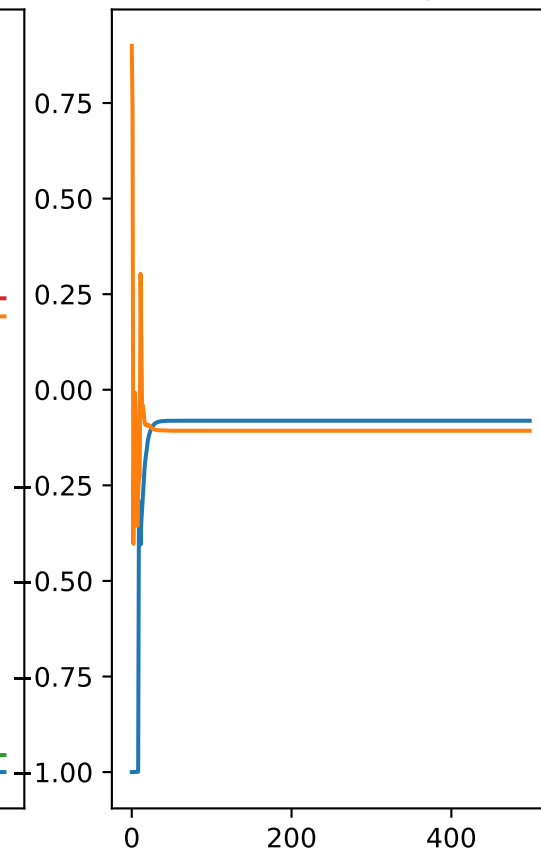


Reward: quadratic_2
Speed = 239.99254886325335 [rad/s]

State vs step



Action vs step



Reward vs step

