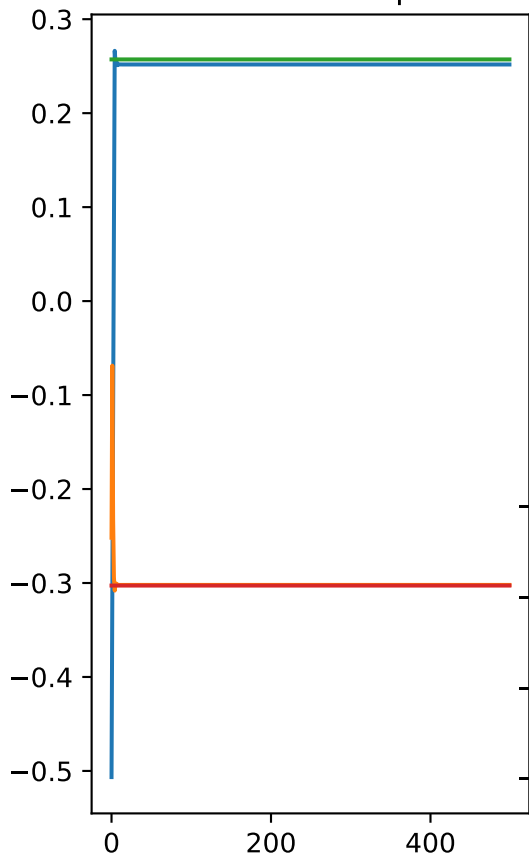
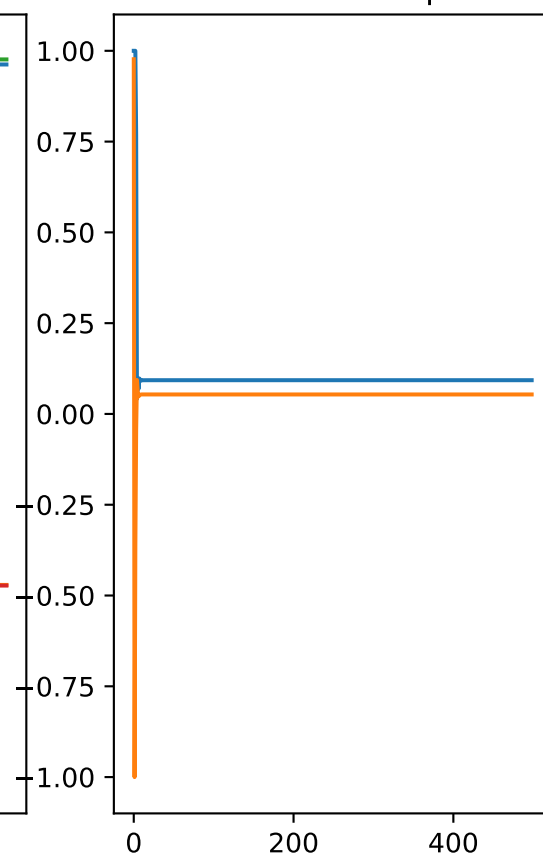


Reward: quartic_root_2
Speed = 1125.5572795900043 [rad/s]

State vs step



Action vs step



Reward vs step

