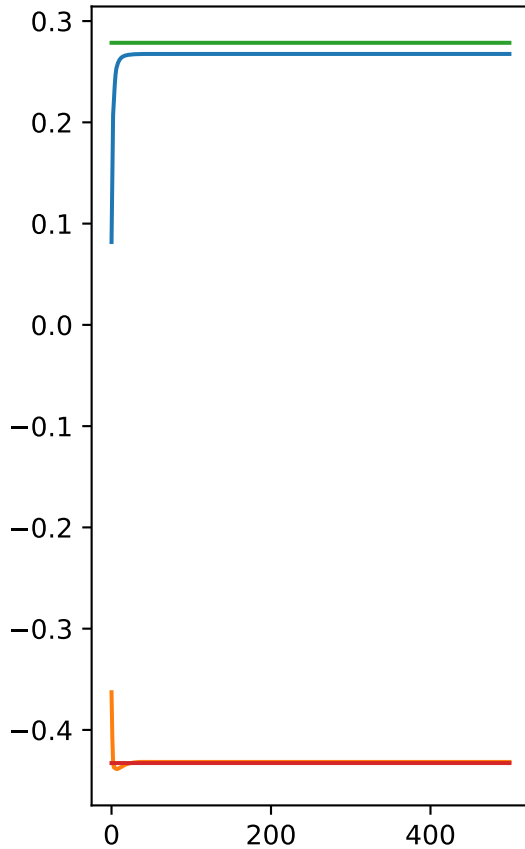
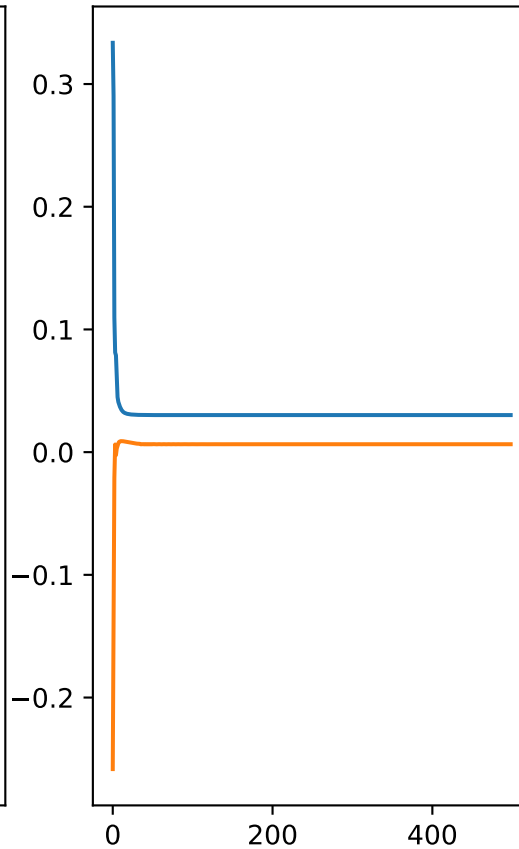


Reward: quadratic\_2  
Speed = 33.6401733991077 [rad/s]

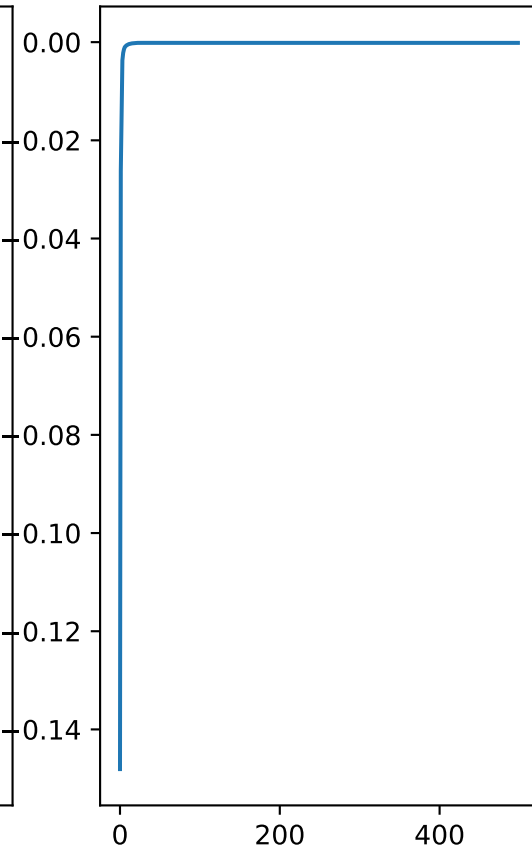
State vs step



Action vs step



Reward vs step



—  $I_d$     —  $I_d^{ref}$   
—  $I_q$     —  $I_q^{ref}$

—  $V_d$     —  $V_q$