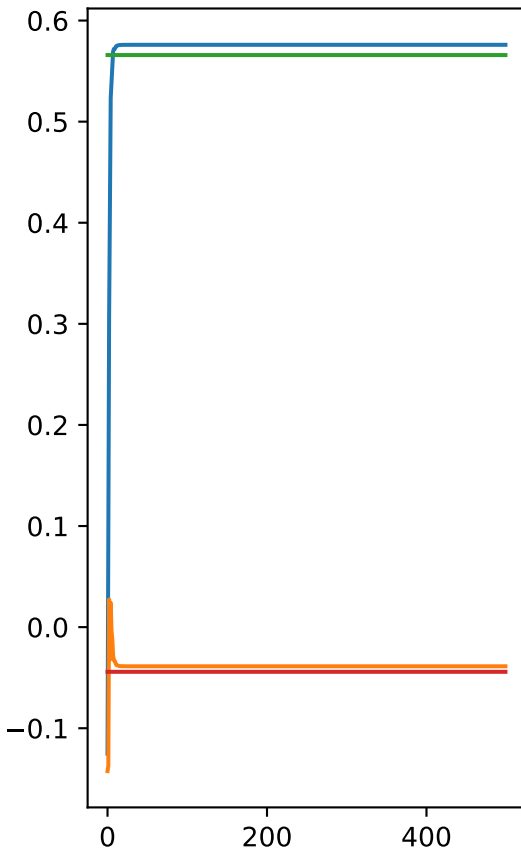
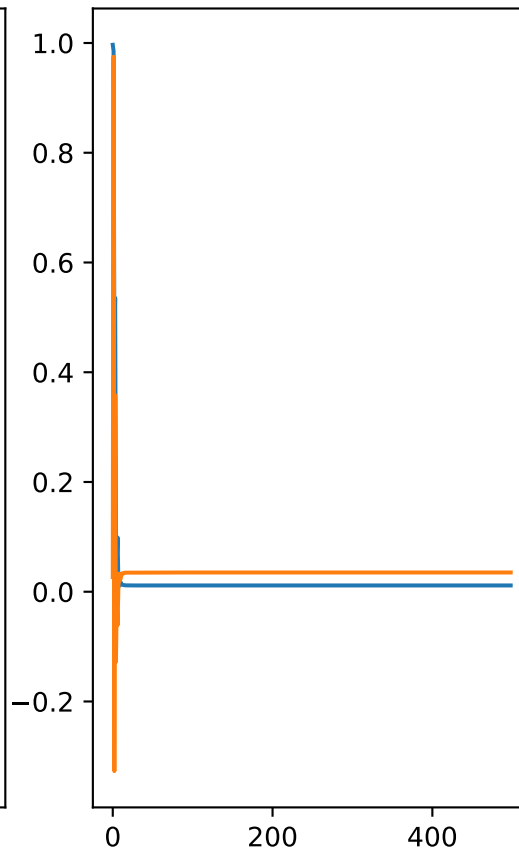


Reward: quadratic
Speed = 734.6174821073865 [rad/s]

State vs step



Action vs step



Reward vs step

