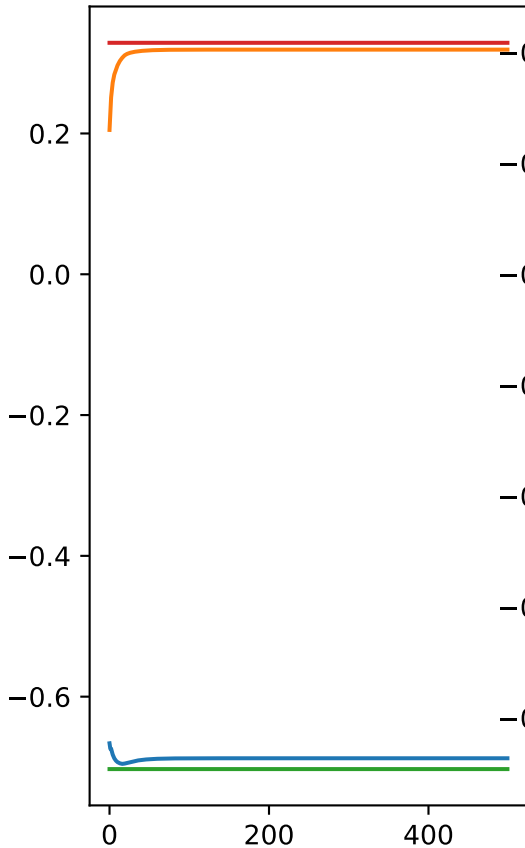
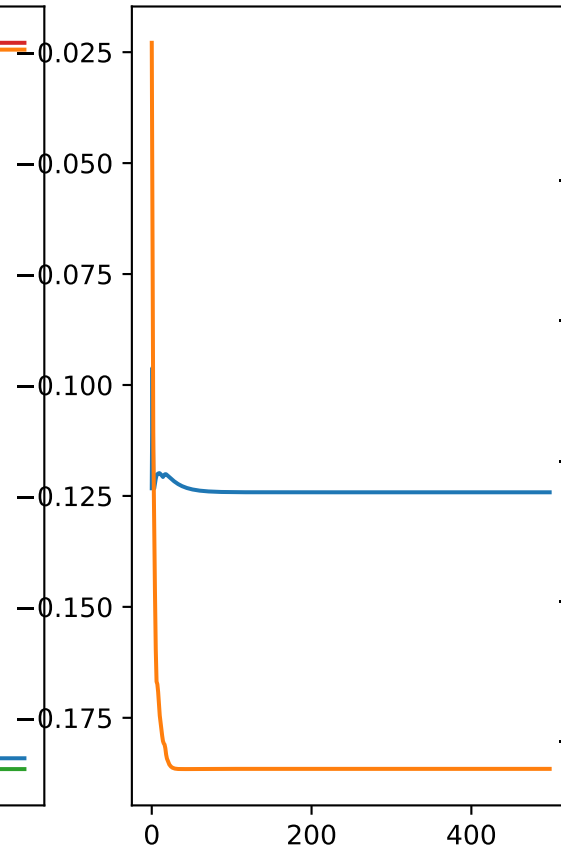


Reward: quadratic
Speed = 718.5576470159352 [rad/s]

State vs step



Action vs step



Reward vs step

