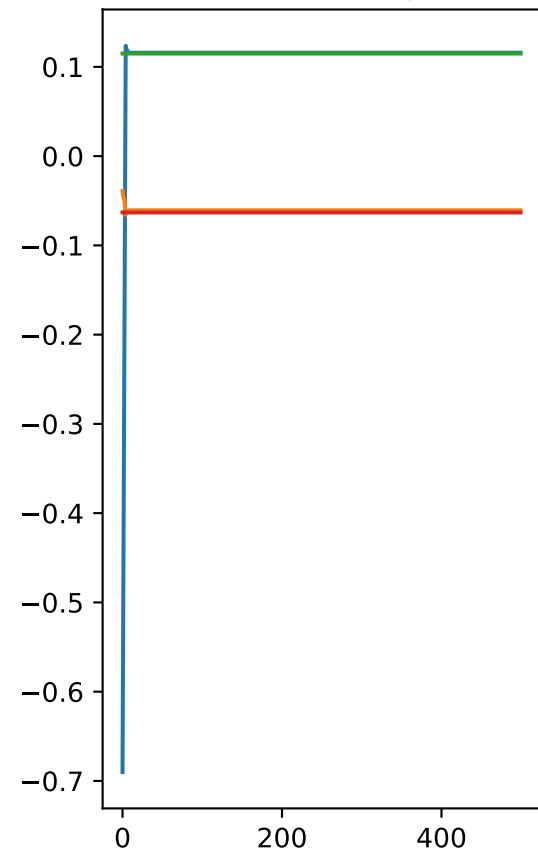
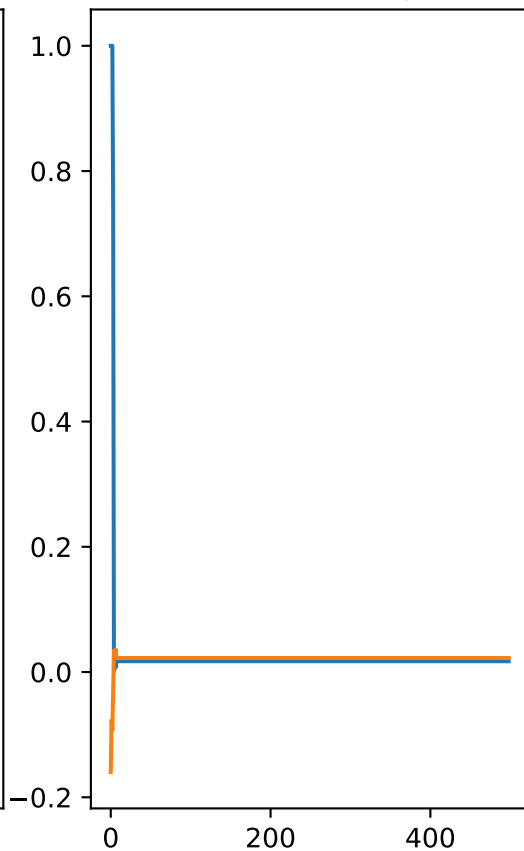


Reward: quartic_root
Speed = 1126.9898438746284 [rad/s]

State vs step



Action vs step



Reward vs step

