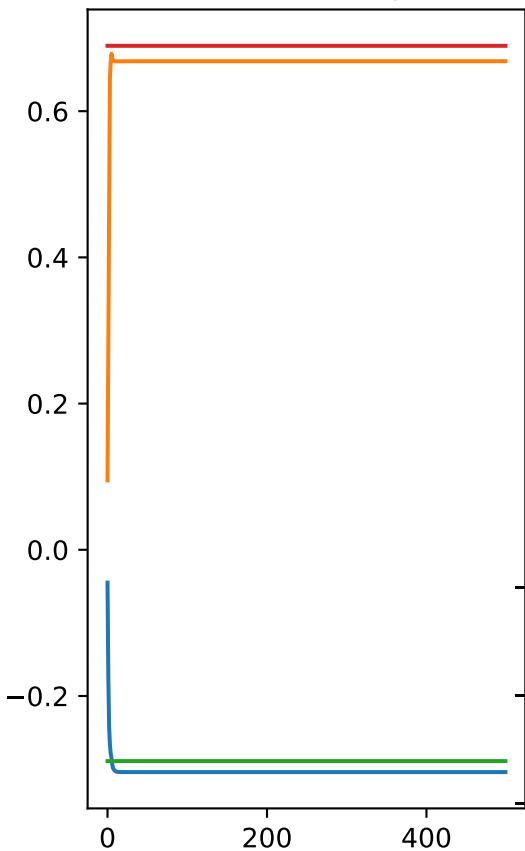
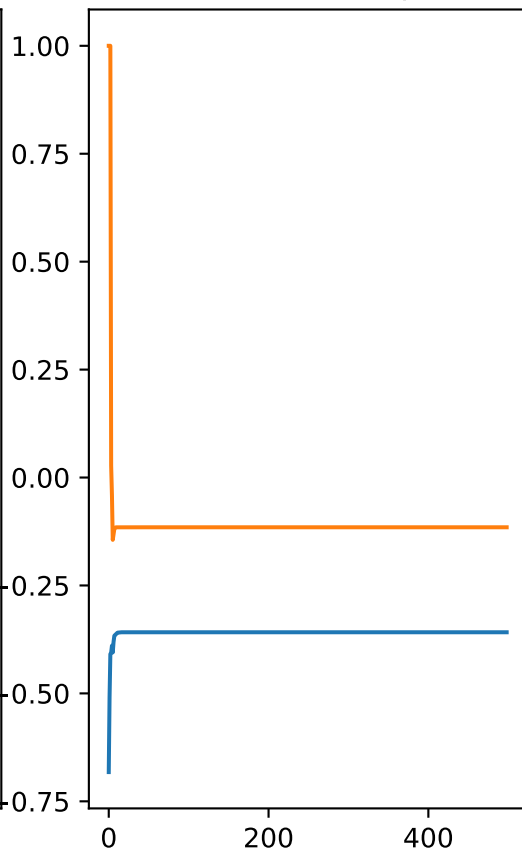


Reward: quadratic_2
Speed = 179.62370118414694 [rad/s]

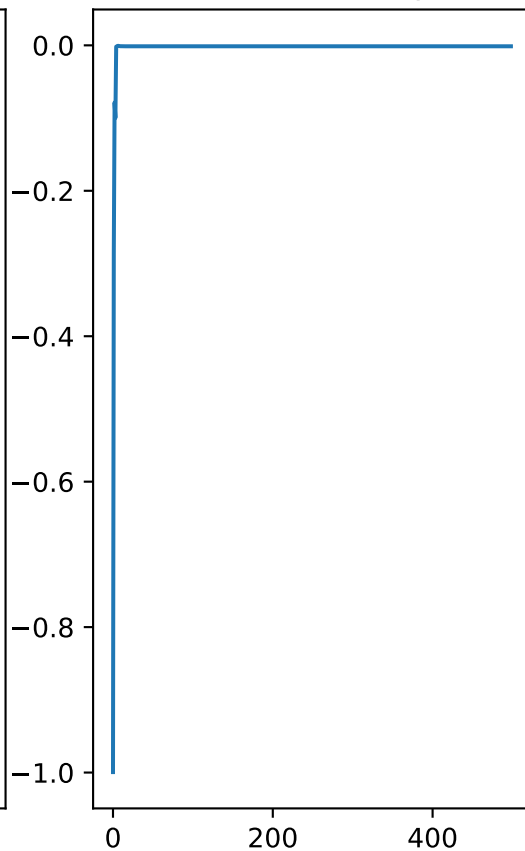
State vs step



Action vs step



Reward vs step



Id Iqref
Iq Iqref

Vd Vq