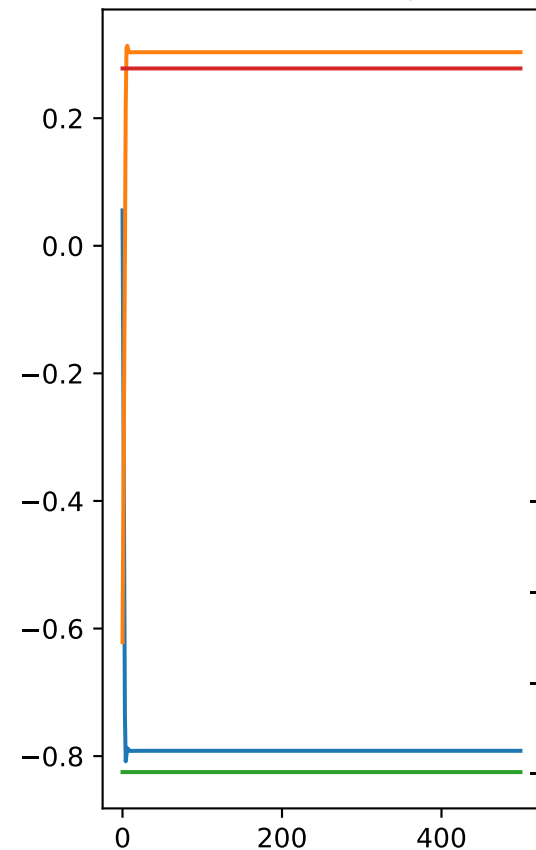
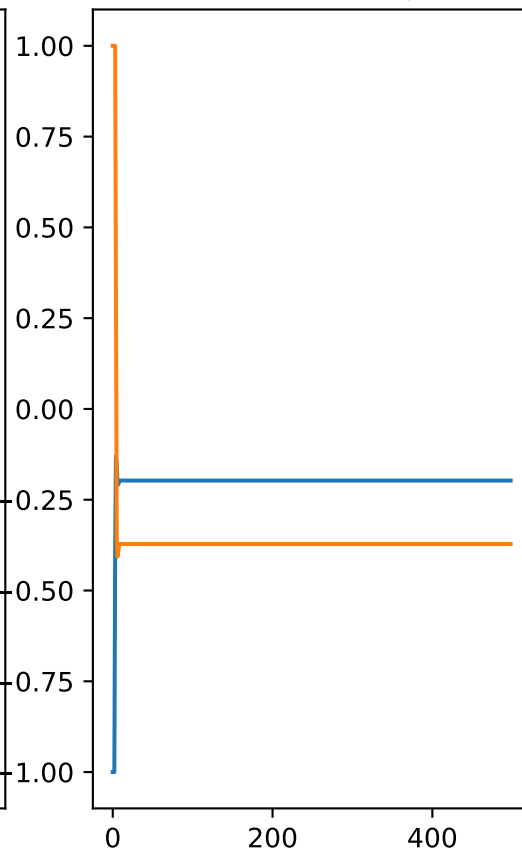


Reward: quartic_root
Speed = 902.8685845394326 [rad/s]

State vs step



Action vs step



Reward vs step

