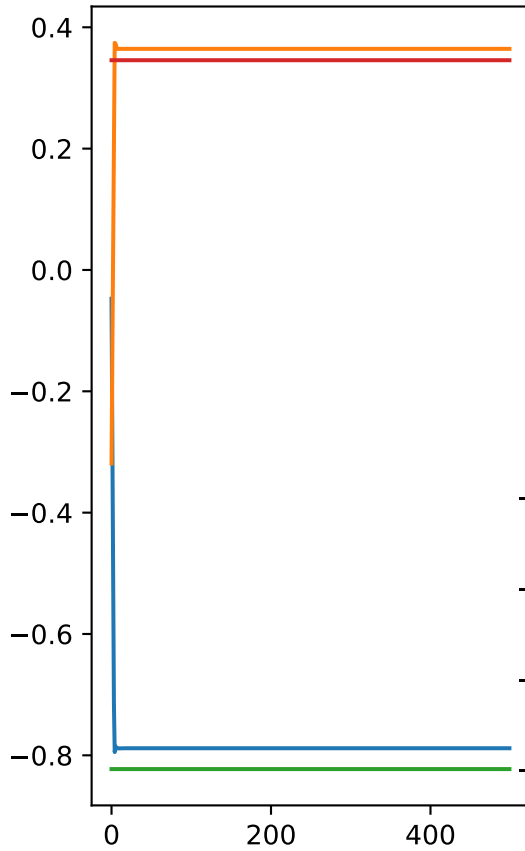
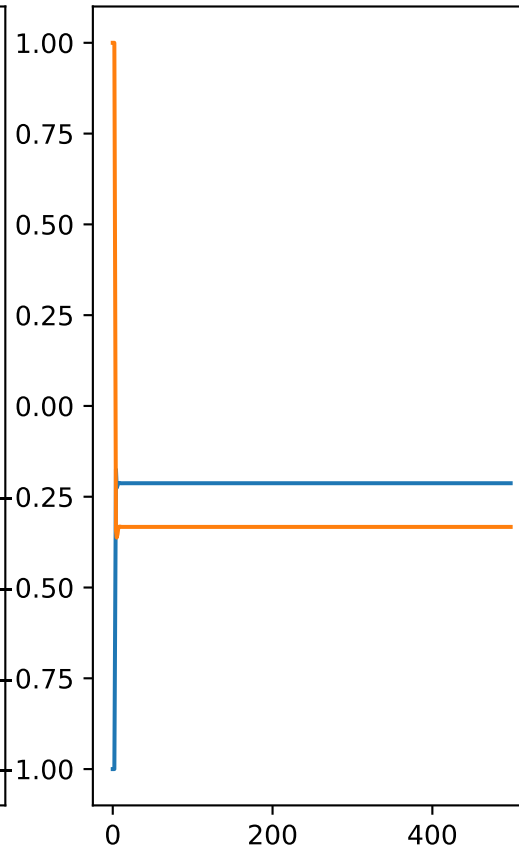


Reward: quartic_root
Speed = 674.5879003452102 [rad/s]

State vs step



Action vs step



Reward vs step

