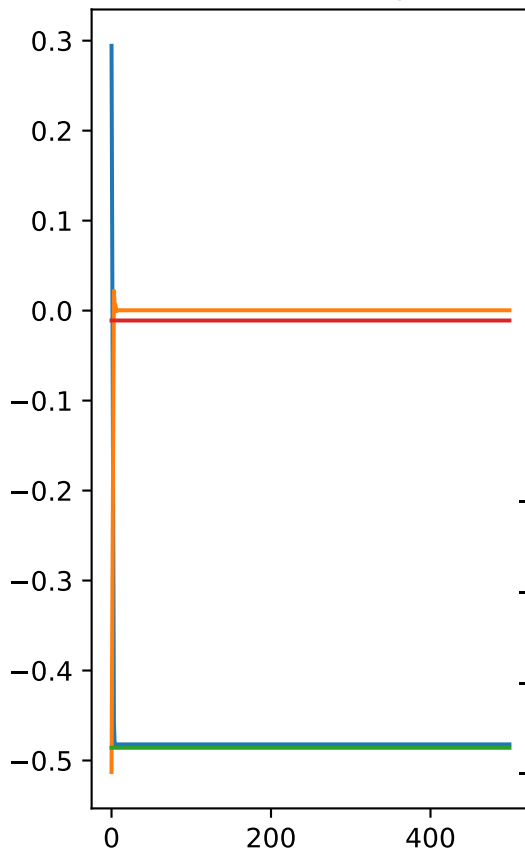
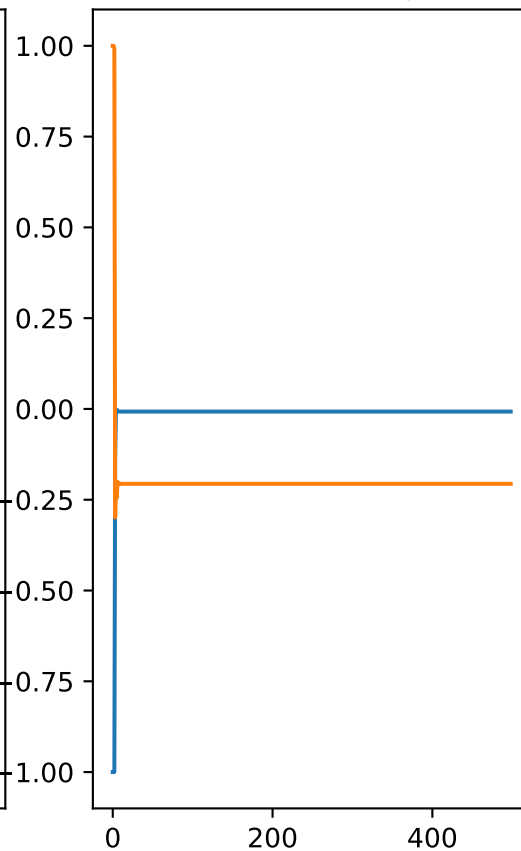


Reward: quartic\_root  
Speed = 851.8742844404329 [rad/s]

State vs step



Action vs step



Reward vs step

