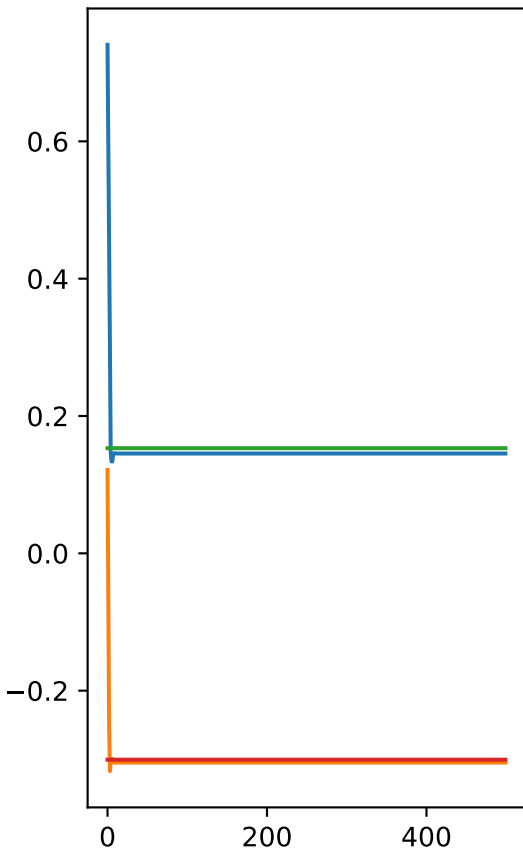
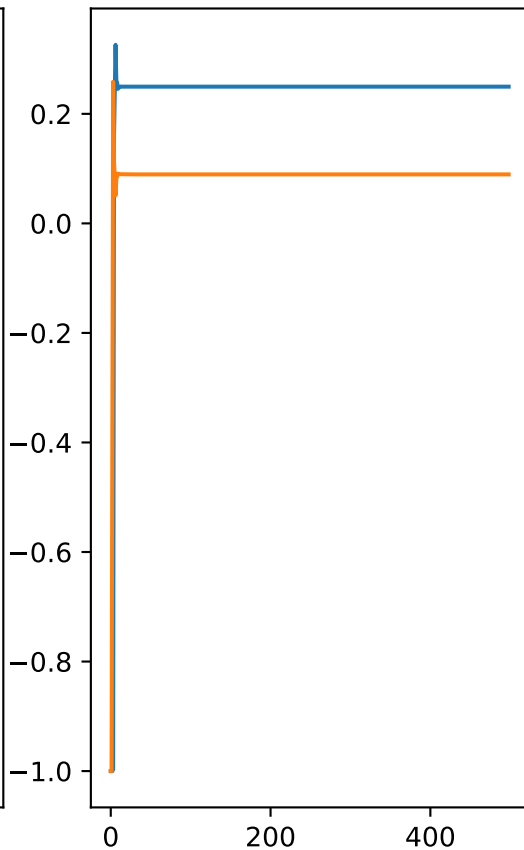


Reward: quartic_root
Speed = 1034.5013634633221 [rad/s]

State vs step



Action vs step



Reward vs step

