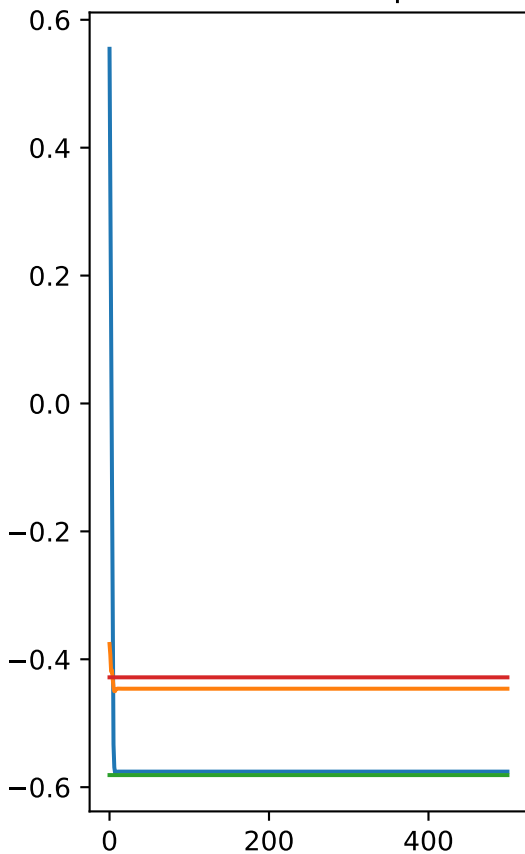
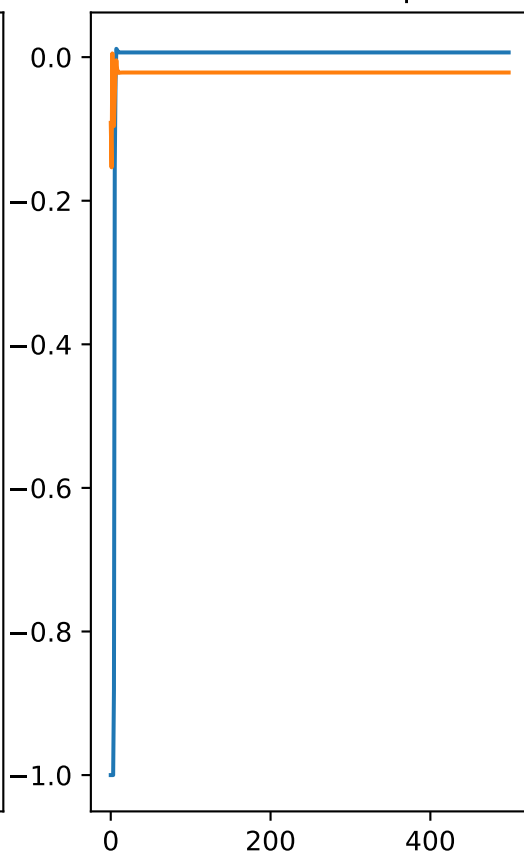


Reward: quartic_root
Speed = 360.01394335380274 [rad/s]

State vs step



Action vs step



Reward vs step

