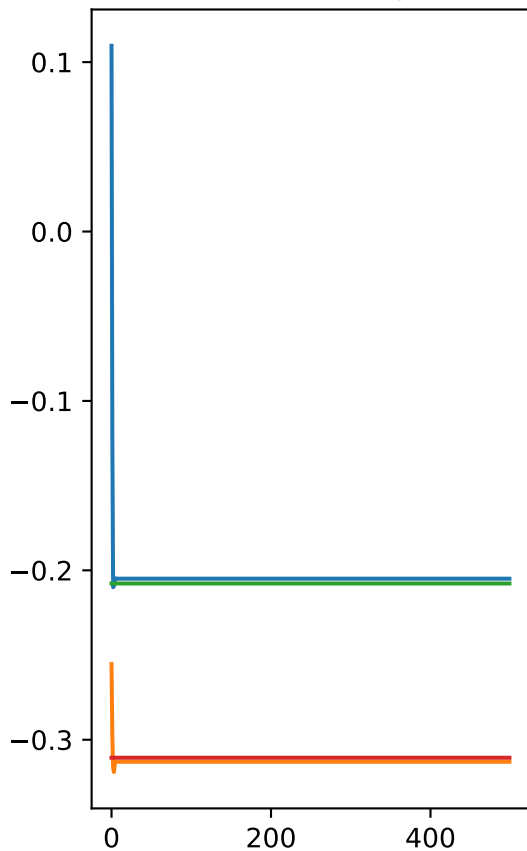
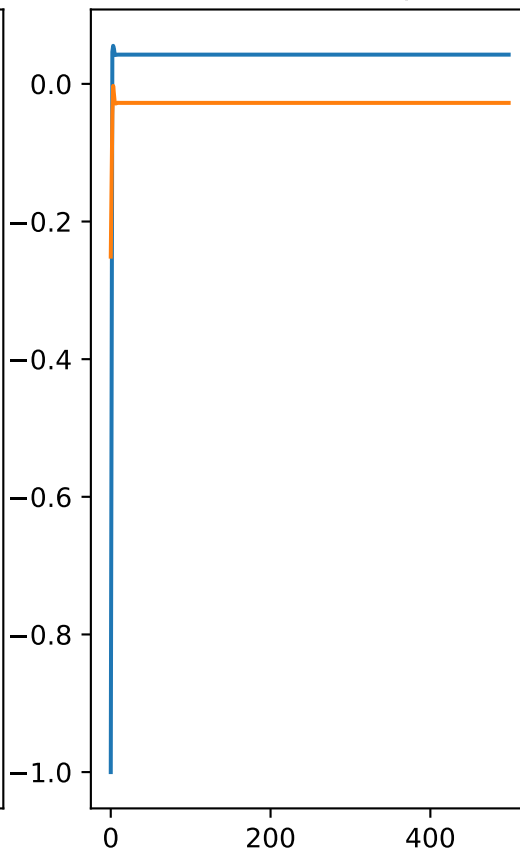


Reward: quartic_root
Speed = 205.64866271397068 [rad/s]

State vs step



Action vs step



Reward vs step

