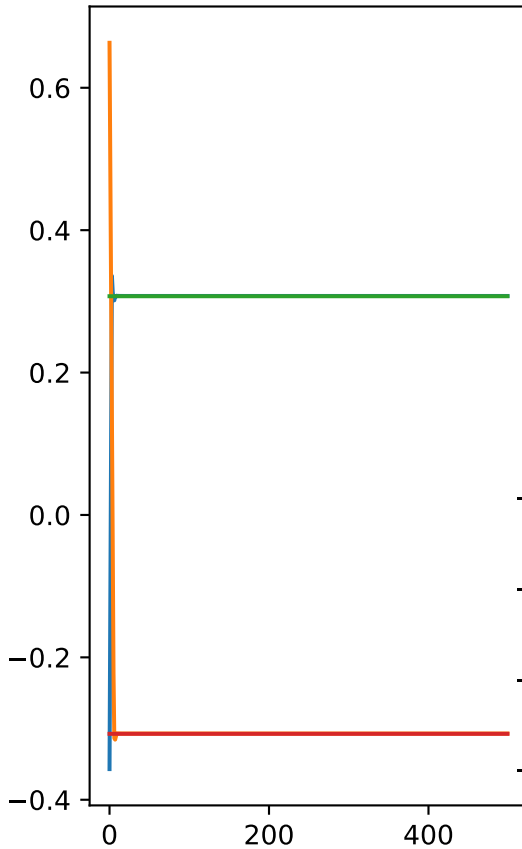
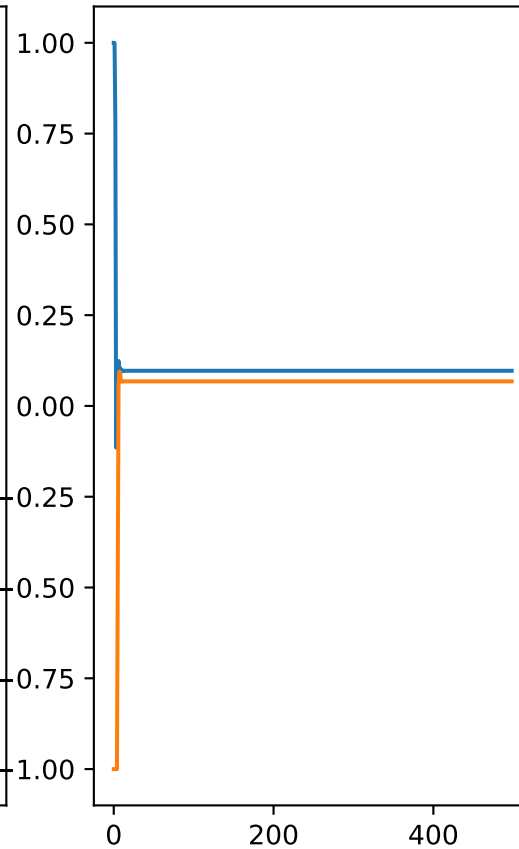


Reward: quartic\_root  
Speed = 993.0071831510155 [rad/s]

State vs step



Action vs step



Reward vs step

