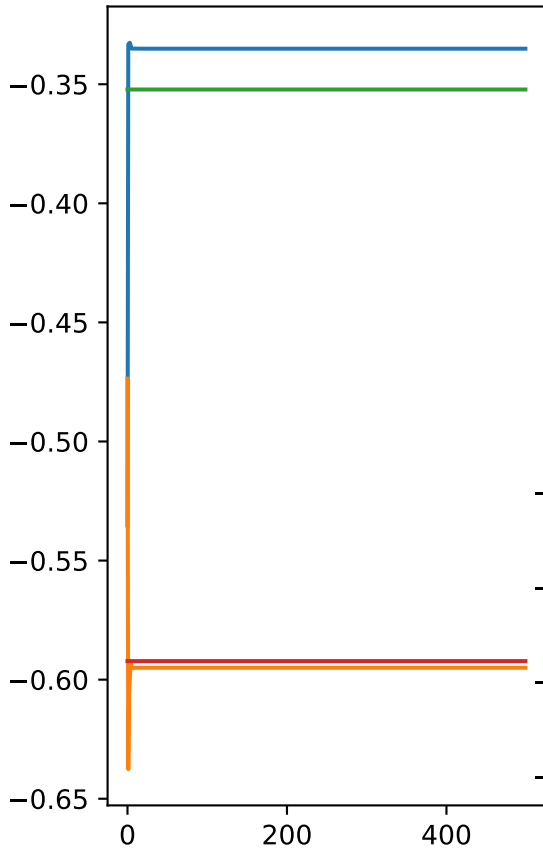
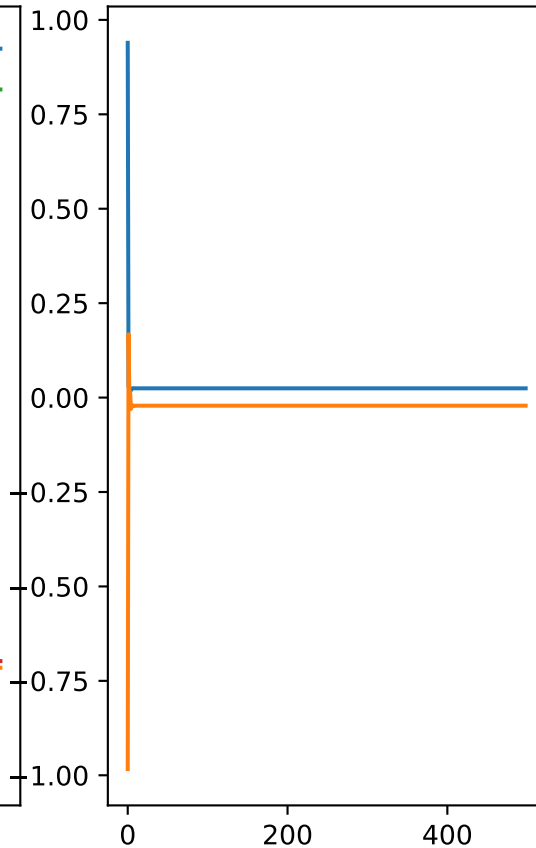


Reward: quartic\_root  
Speed = 32.8987571538594 [rad/s]

State vs step



Action vs step



Reward vs step

