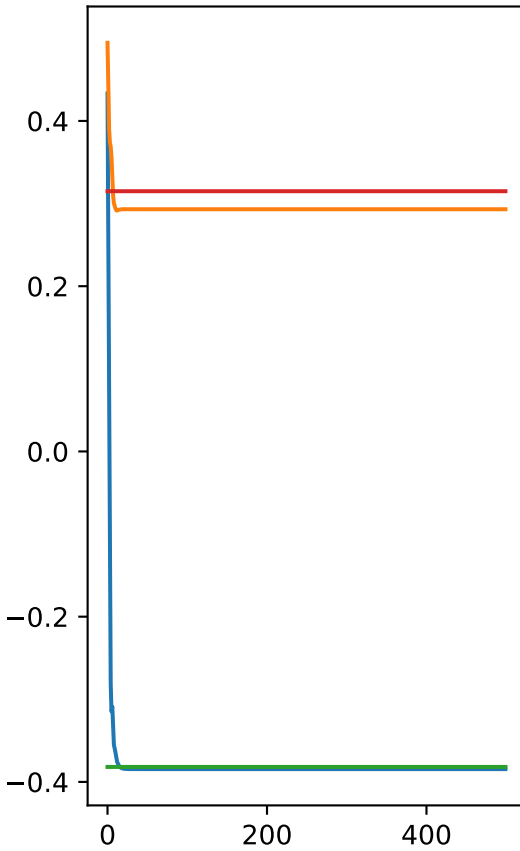
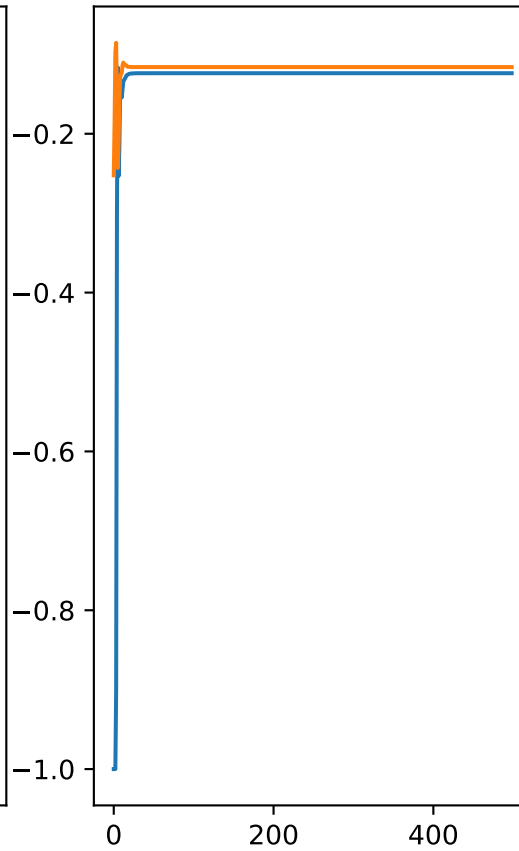


Reward: quadratic_2
Speed = 1047.3692751526373 [rad/s]

State vs step



Action vs step



Reward vs step

