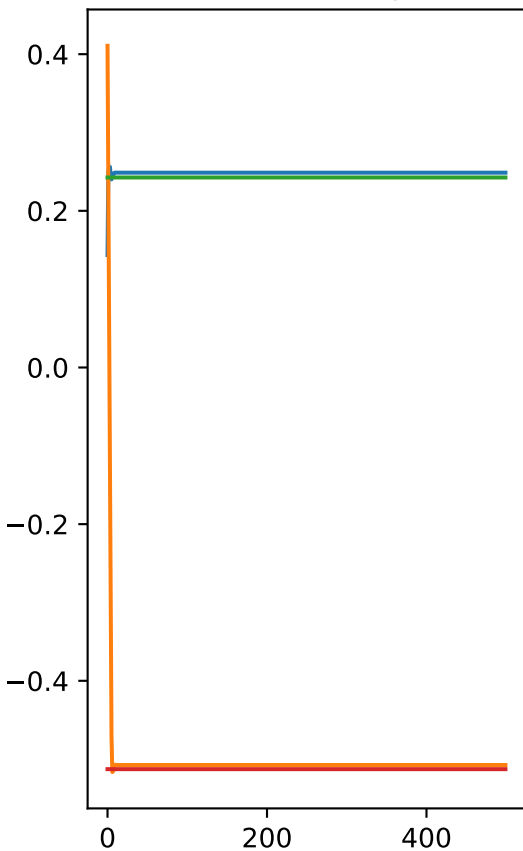
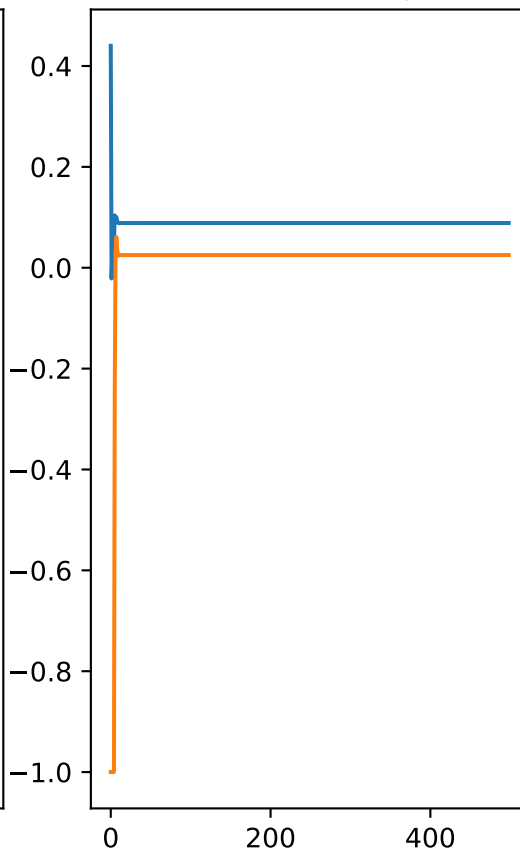


Reward: quartic_root
Speed = 51.760878535211425 [rad/s]

State vs step



Action vs step



Reward vs step

