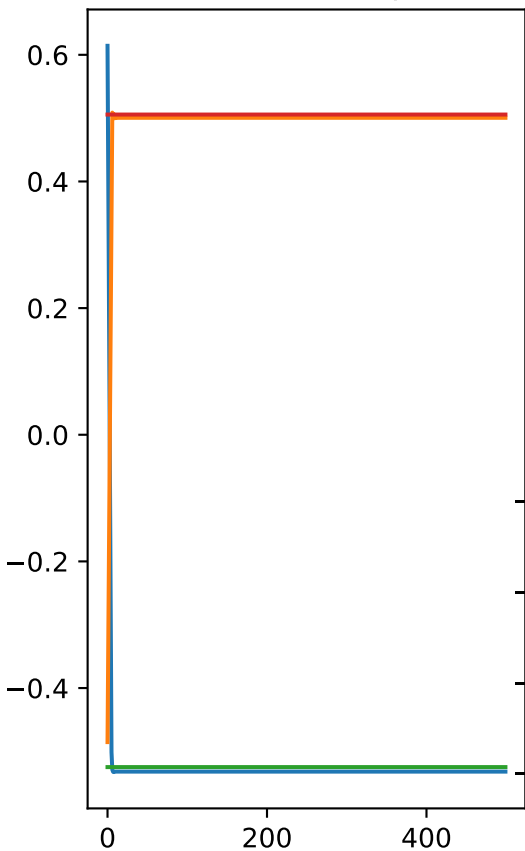
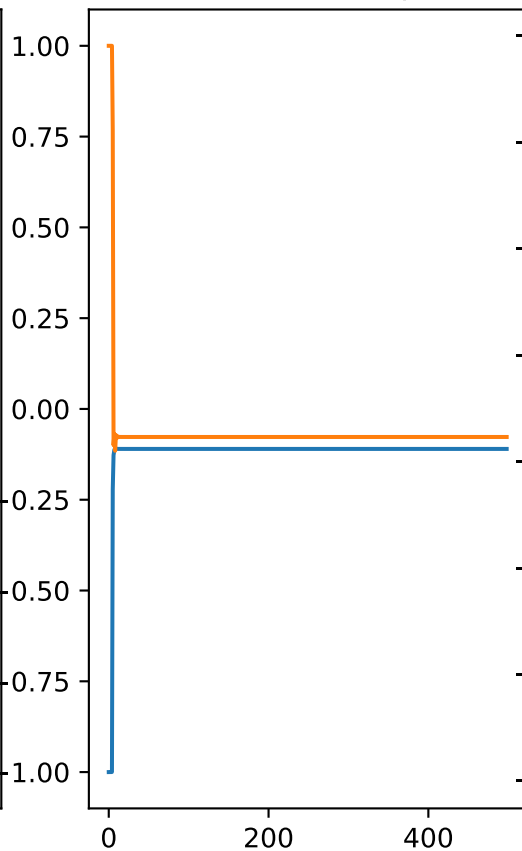


Reward: quartic_root
Speed = 158.98971215053794 [rad/s]

State vs step



Action vs step



Reward vs step

