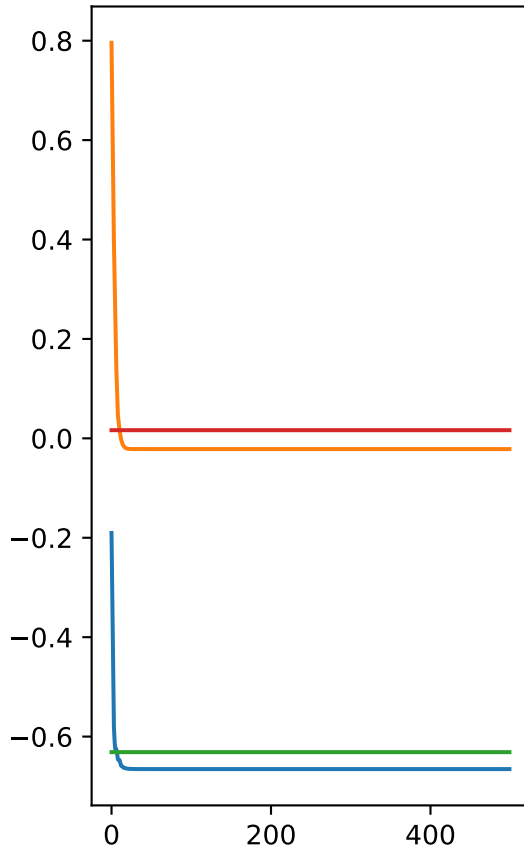
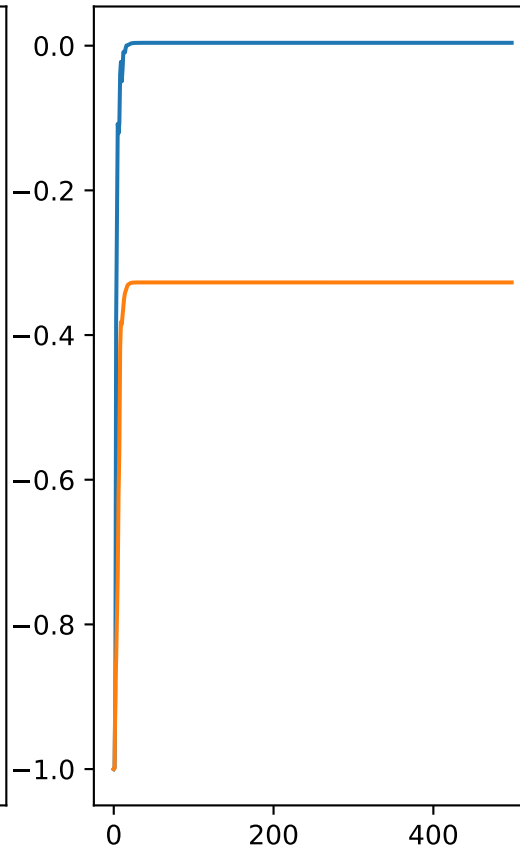


Reward: quadratic_2
Speed = 153.7244148503424 [rad/s]

State vs step



Action vs step



Reward vs step

