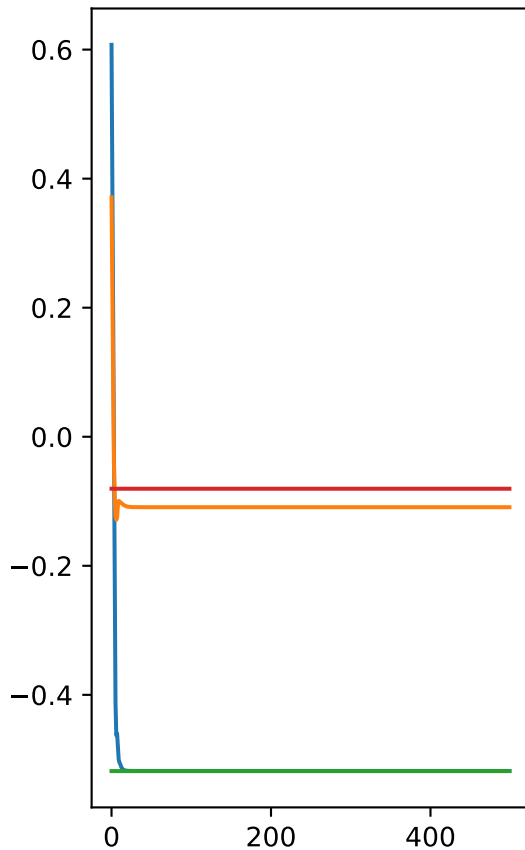
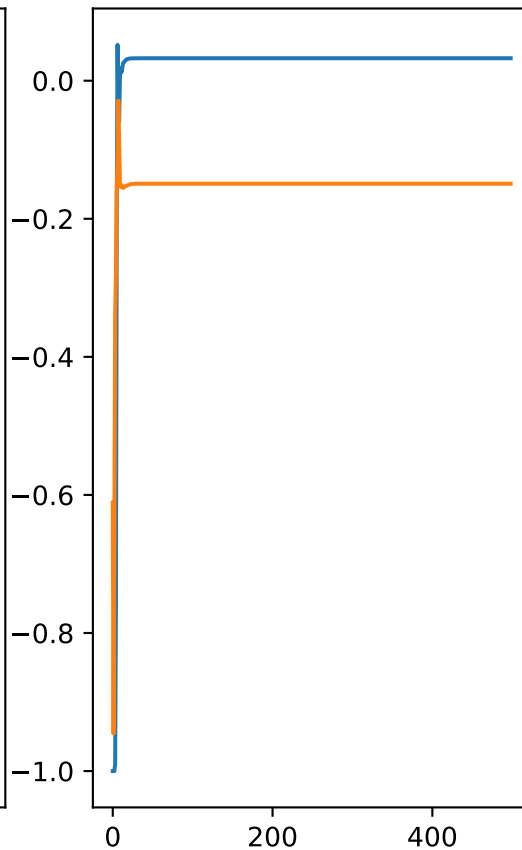


Reward: quadratic_2
Speed = 537.1872263264811 [rad/s]

State vs step



Action vs step



Reward vs step

