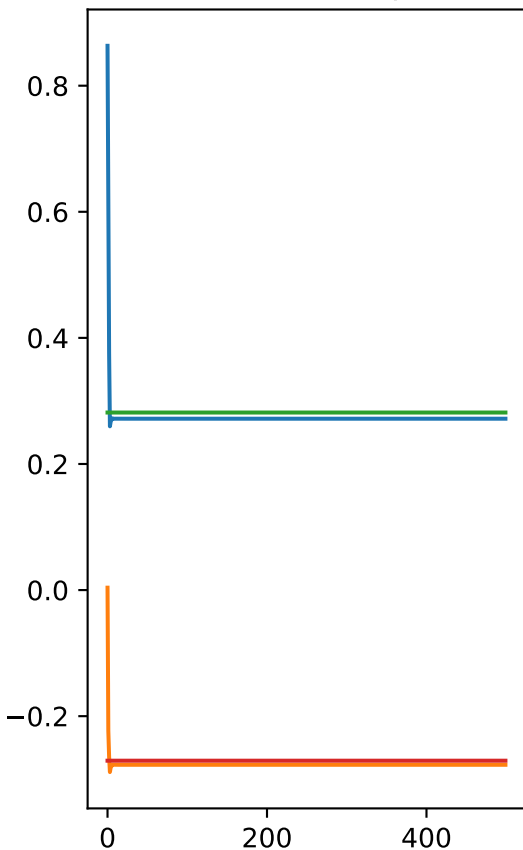
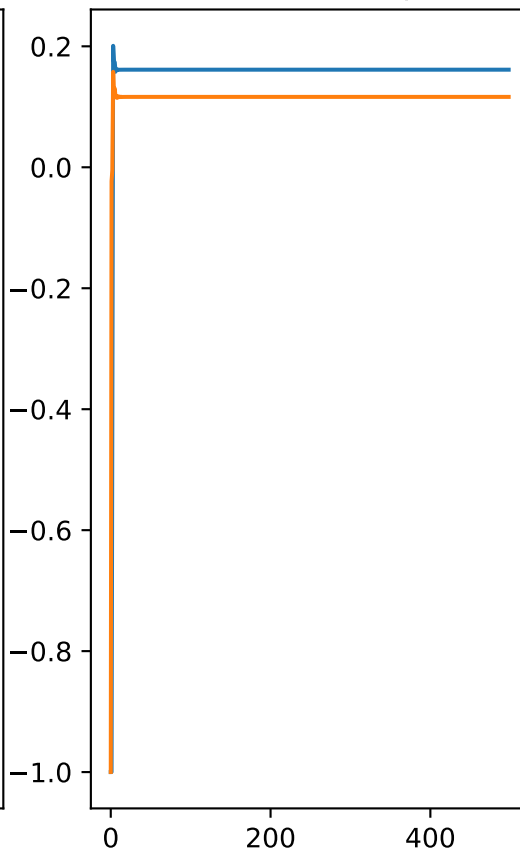


Reward: quartic_root
Speed = 1024.6116065643937 [rad/s]

State vs step



Action vs step



Reward vs step

