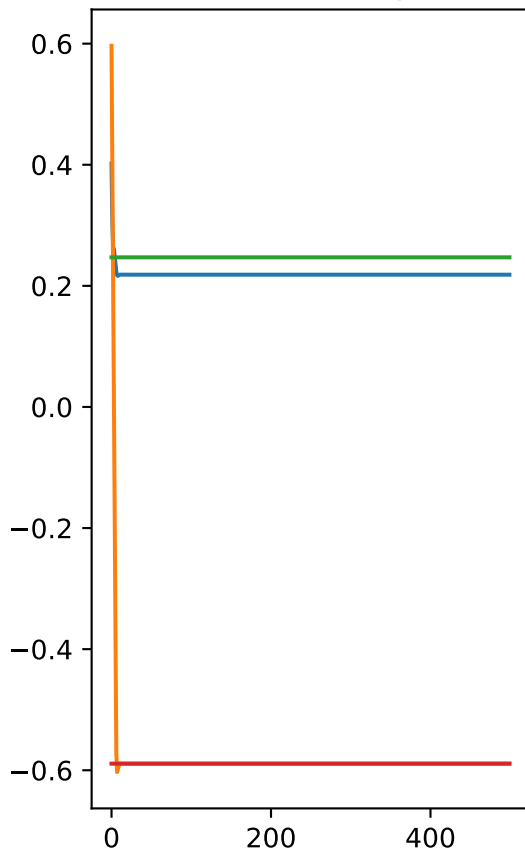
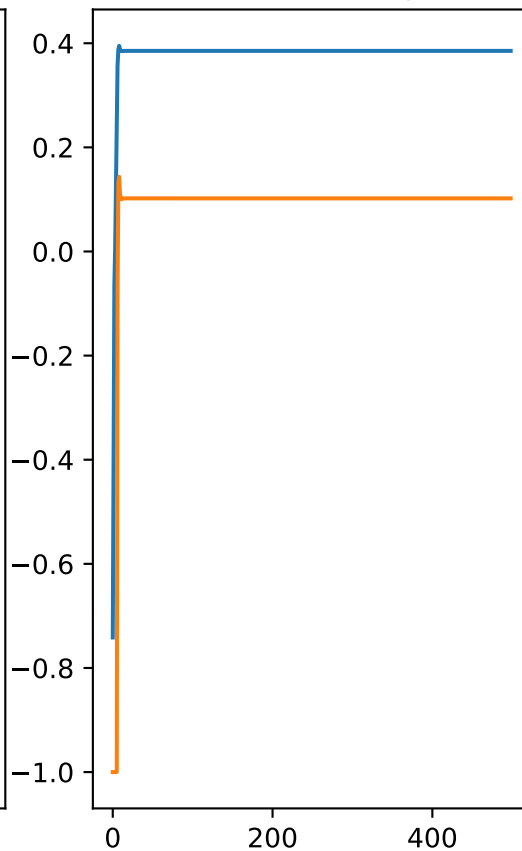


Reward: quartic_root
Speed = 293.68865501646286 [rad/s]

State vs step



Action vs step



Reward vs step

