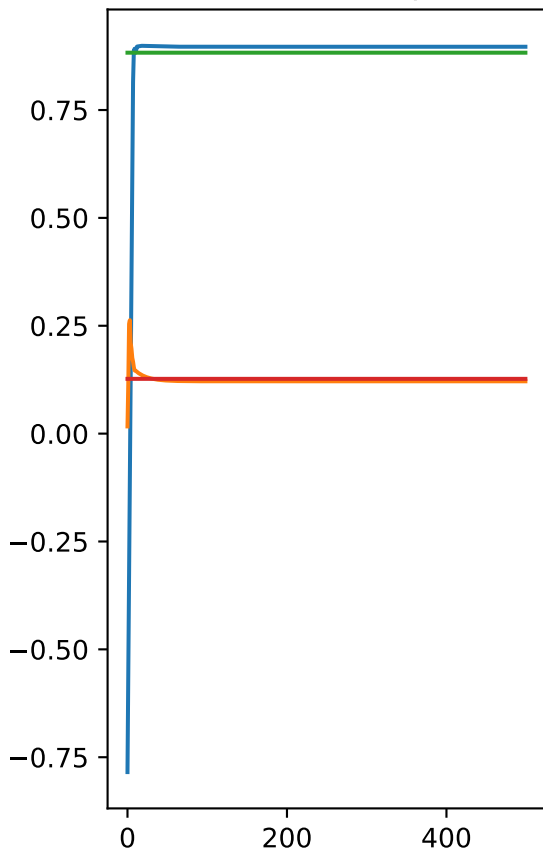
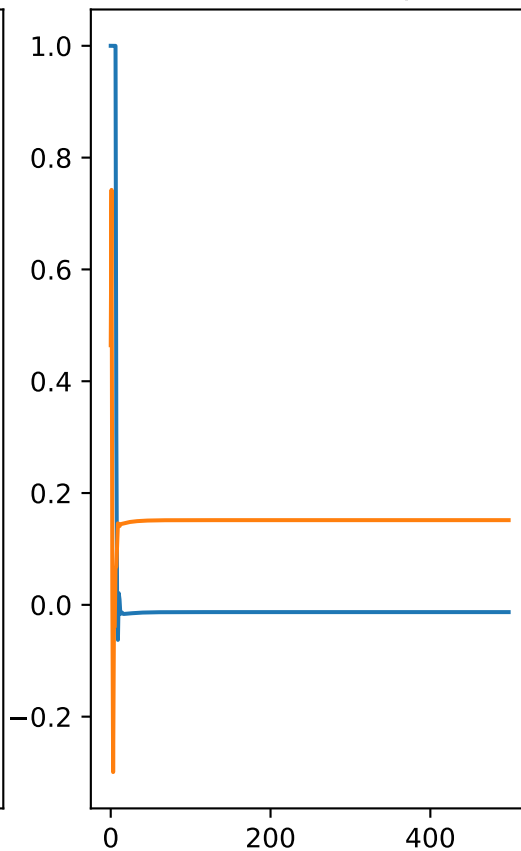


Reward: quadratic_2
Speed = 622.6385324226593 [rad/s]

State vs step



Action vs step



Reward vs step

