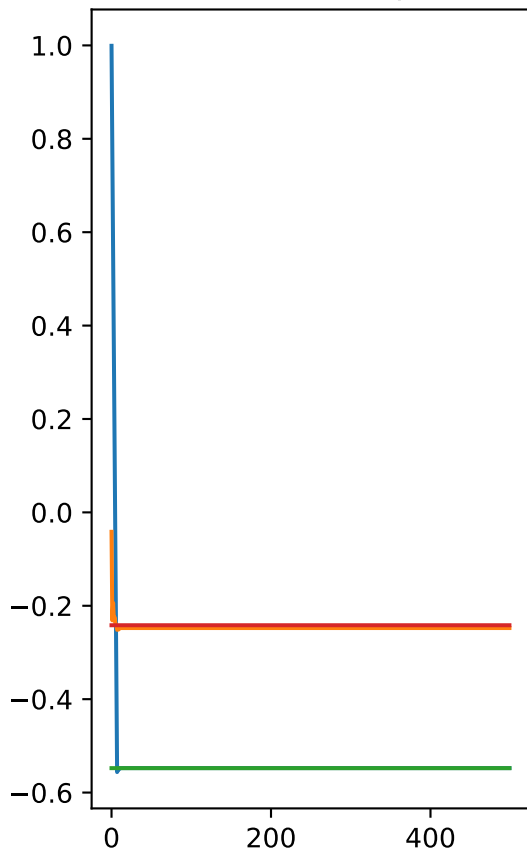
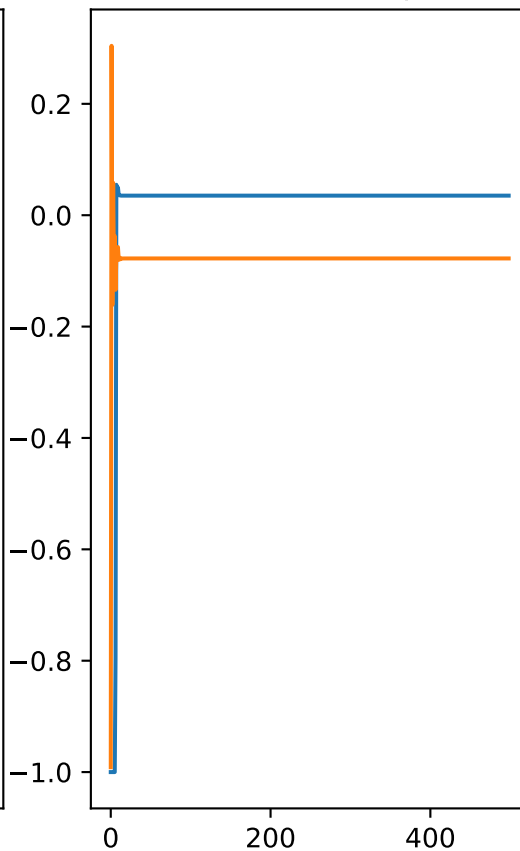


Reward: quartic_root
Speed = 1020.9924455443816 [rad/s]

State vs step



Action vs step



Reward vs step

