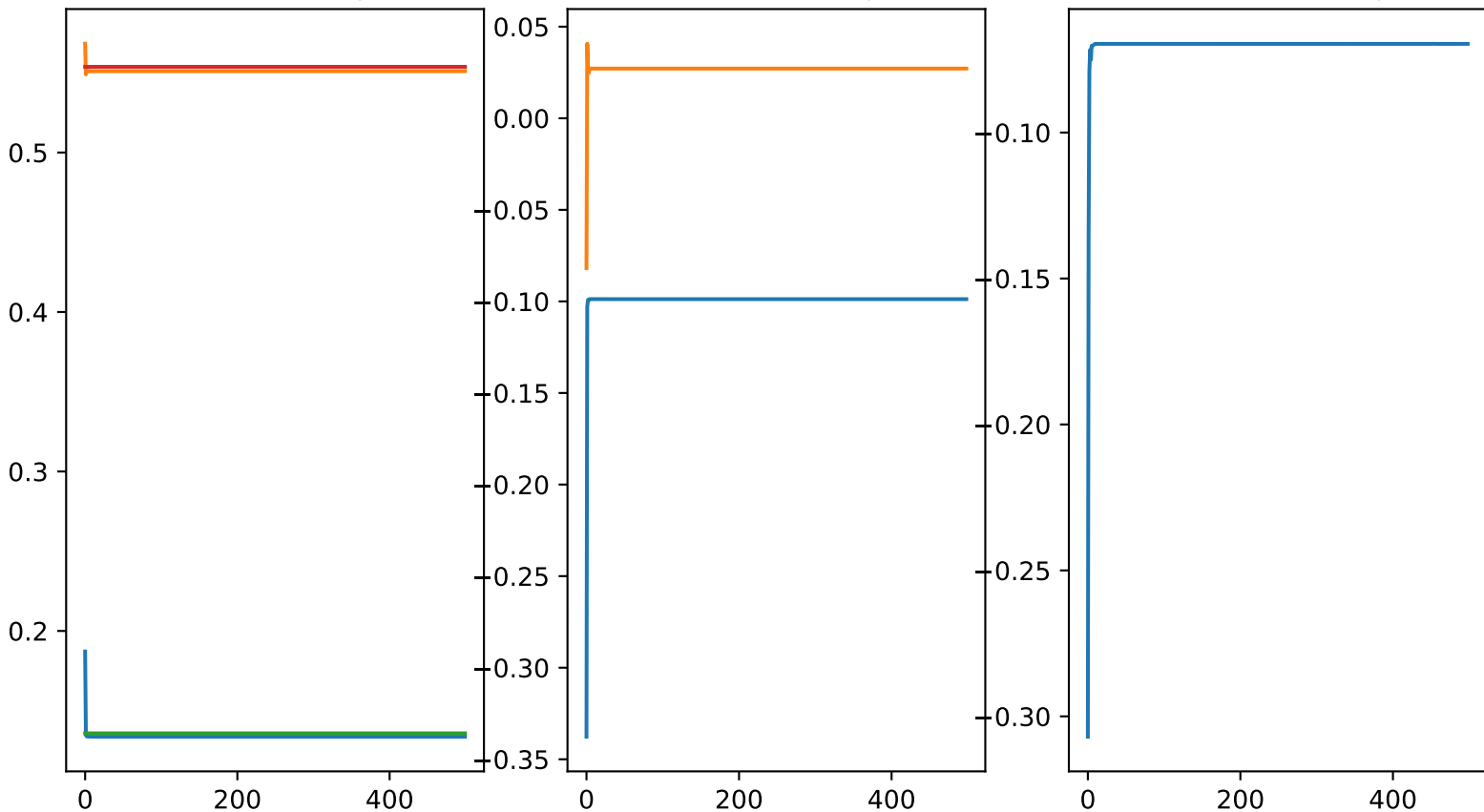


Reward: square_root_2
Speed = 542.3143024452097 [rad/s]

State vs step

Action vs step

Reward vs step



I_d I_{dref}
 I_q I_{qref}

V_d V_q