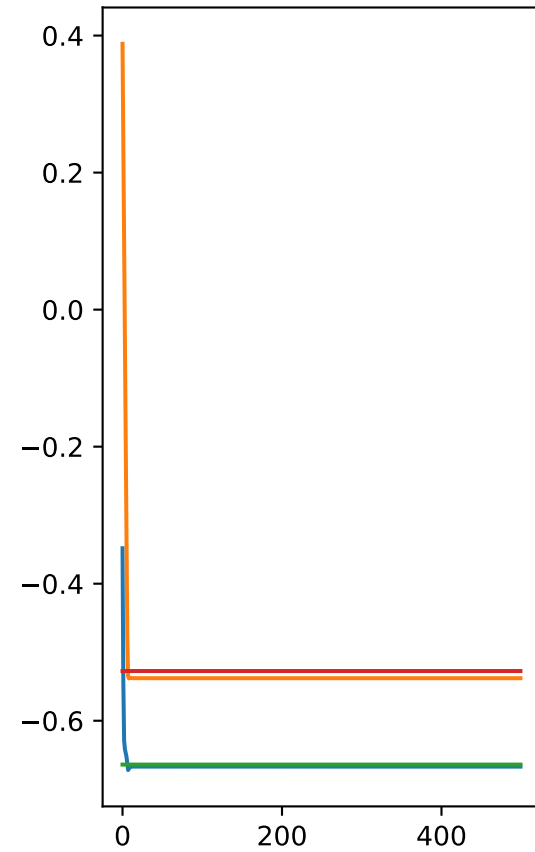
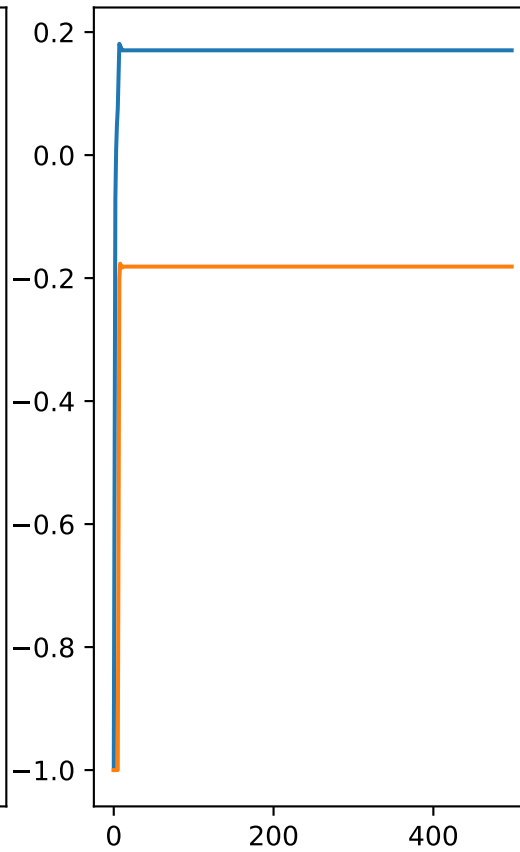


Reward: quartic\_root\_2  
Speed = 618.0141196373048 [rad/s]

State vs step



Action vs step



Reward vs step

