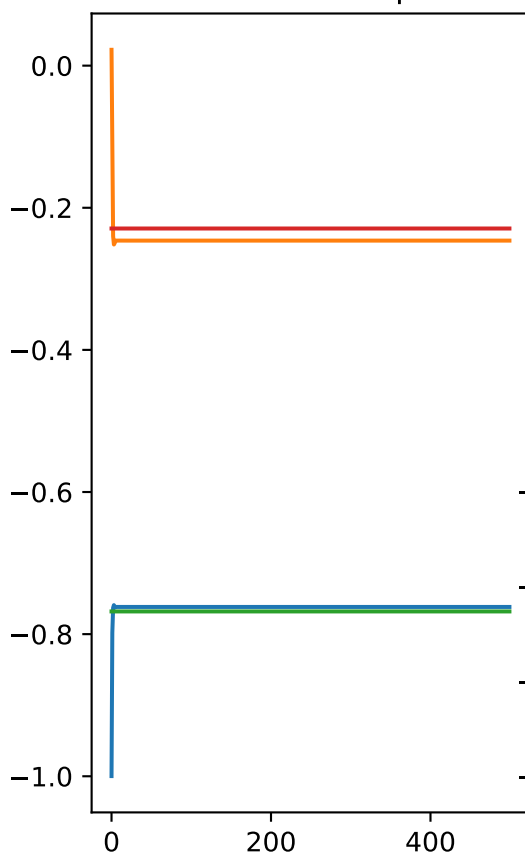
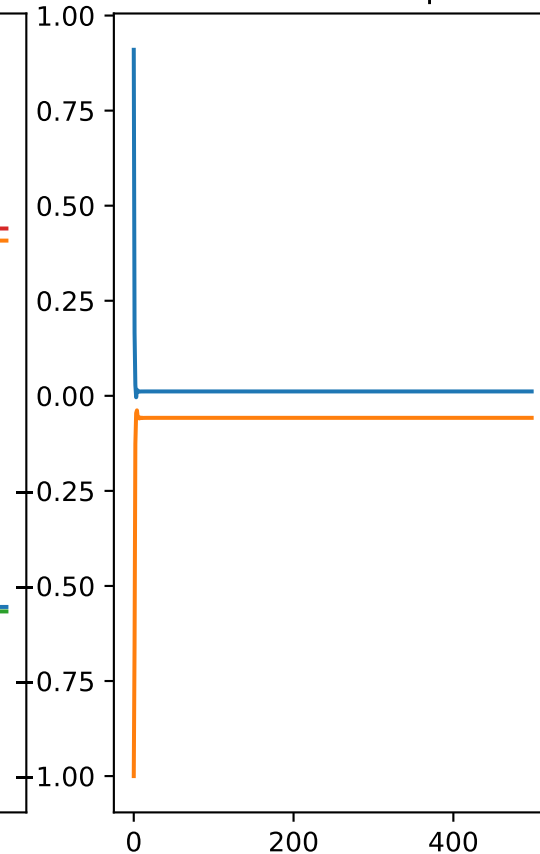


Reward: quartic\_root  
Speed = 854.5508861716387 [rad/s]

State vs step



Action vs step



Reward vs step

