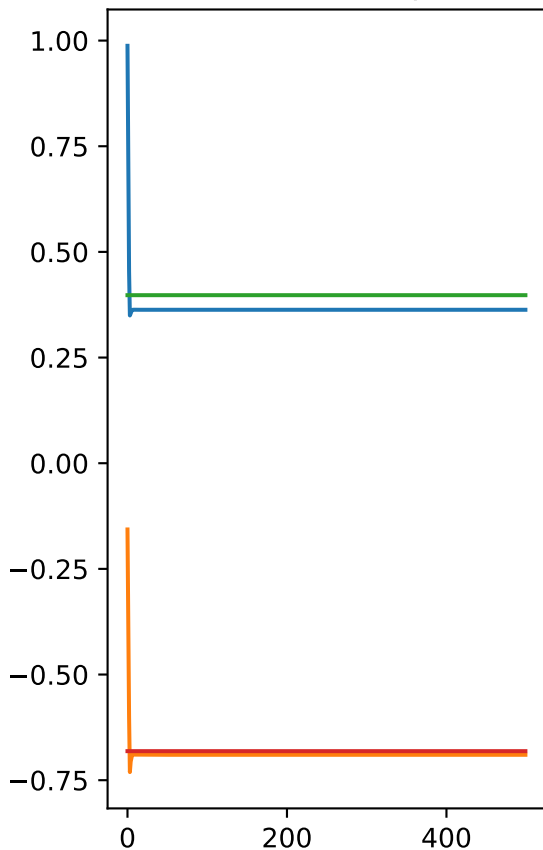
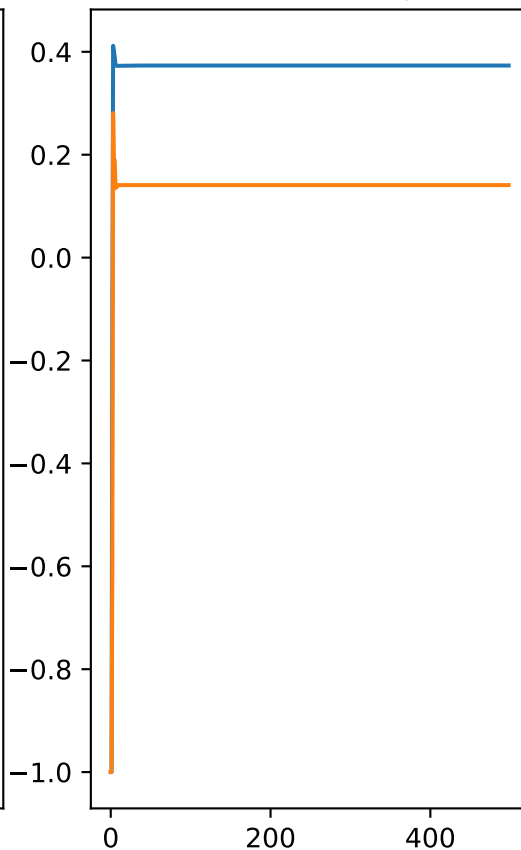


Reward: quartic_root
Speed = 349.3450994839175 [rad/s]

State vs step



Action vs step



Reward vs step

