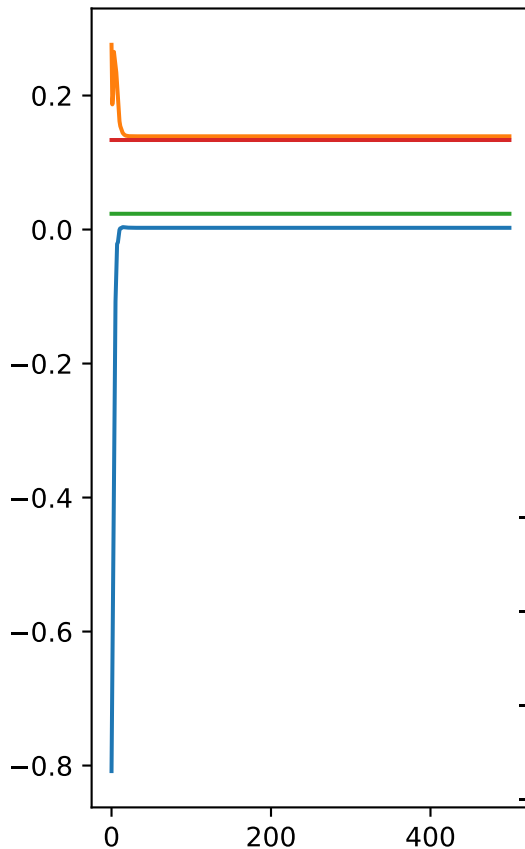
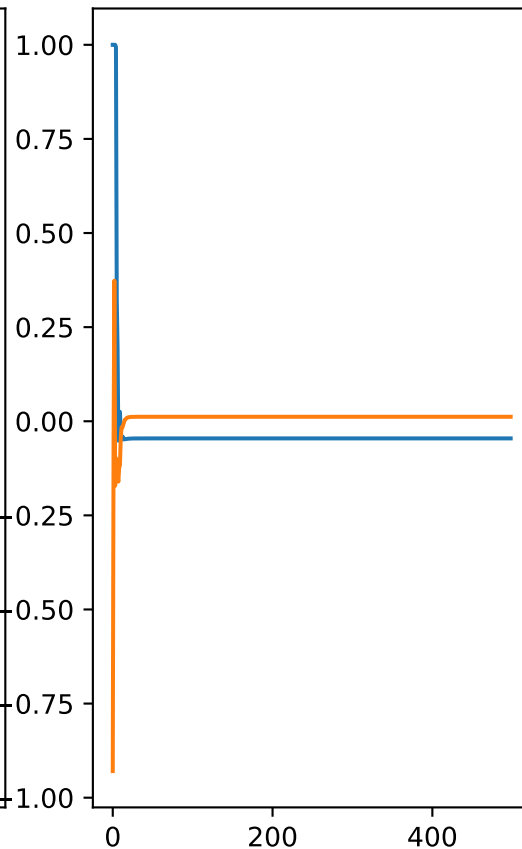


Reward: quadratic_2
Speed = 377.82051667591264 [rad/s]

State vs step



Action vs step



Reward vs step

