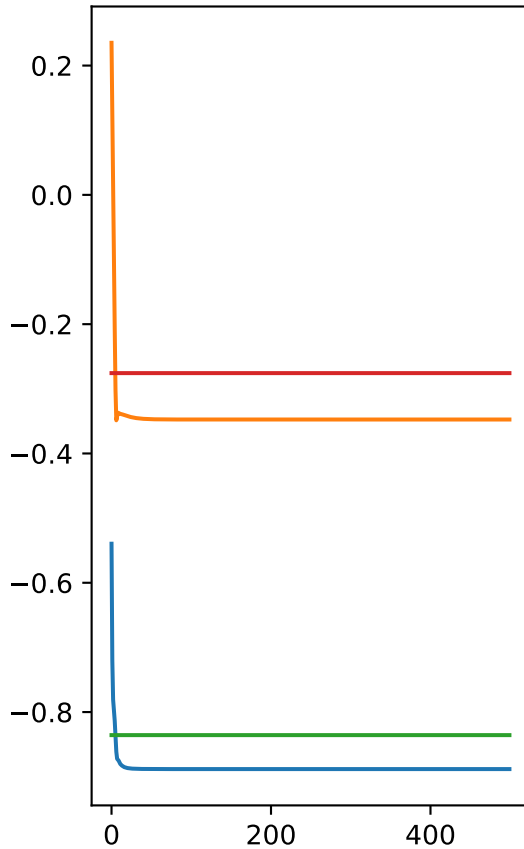
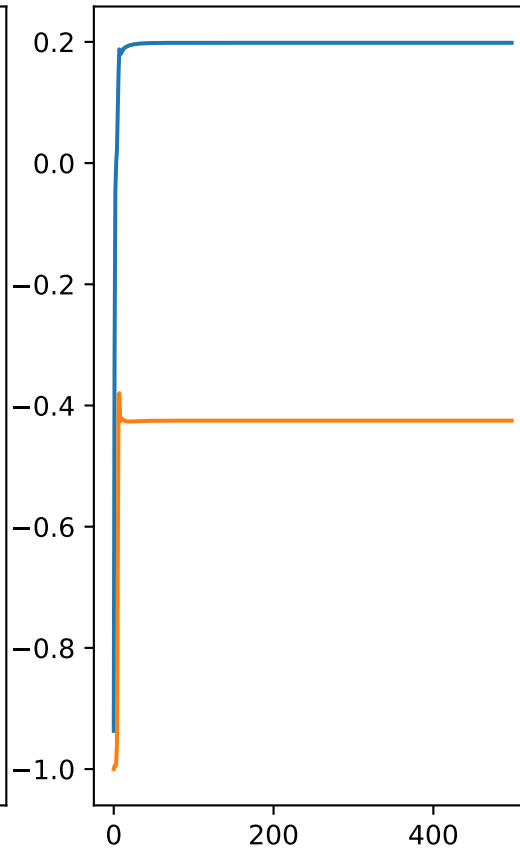


Reward: quadratic_2
Speed = 142.1633547989291 [rad/s]

State vs step



Action vs step



Reward vs step

