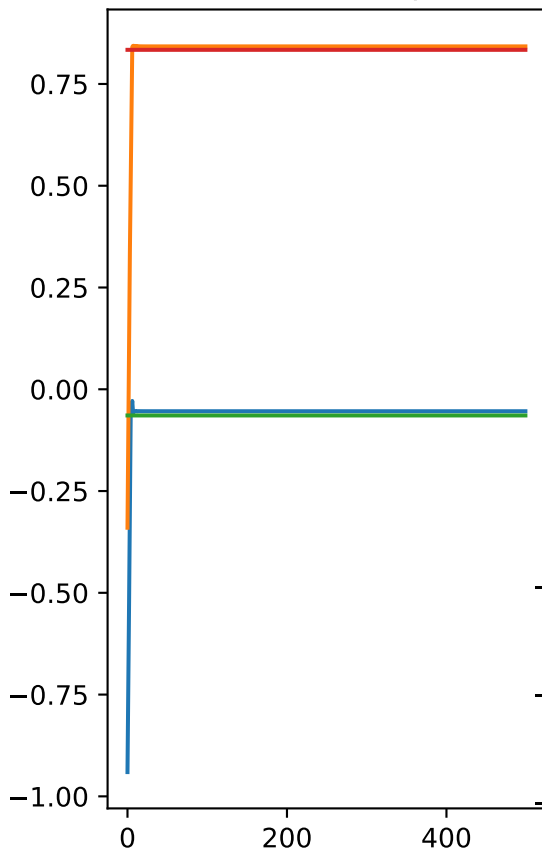
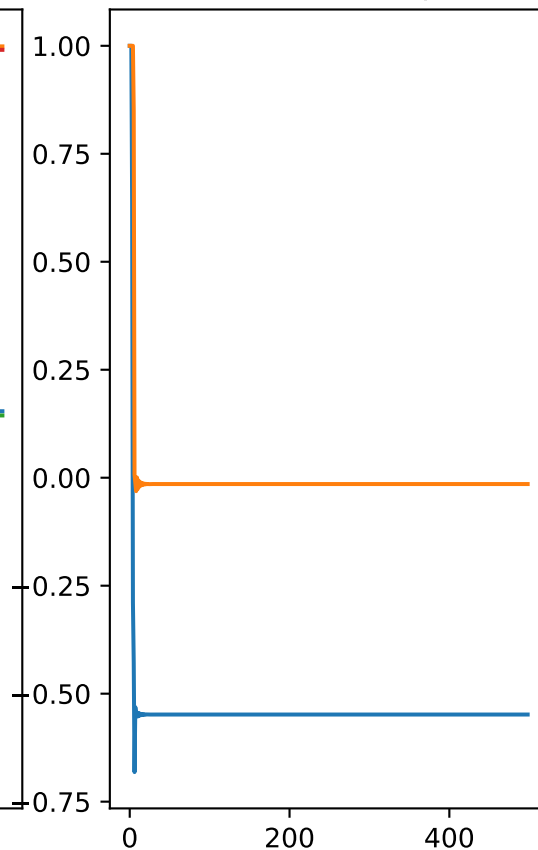


Reward: quartic_root_2
Speed = 156.97910563042026 [rad/s]

State vs step



Action vs step



Reward vs step

