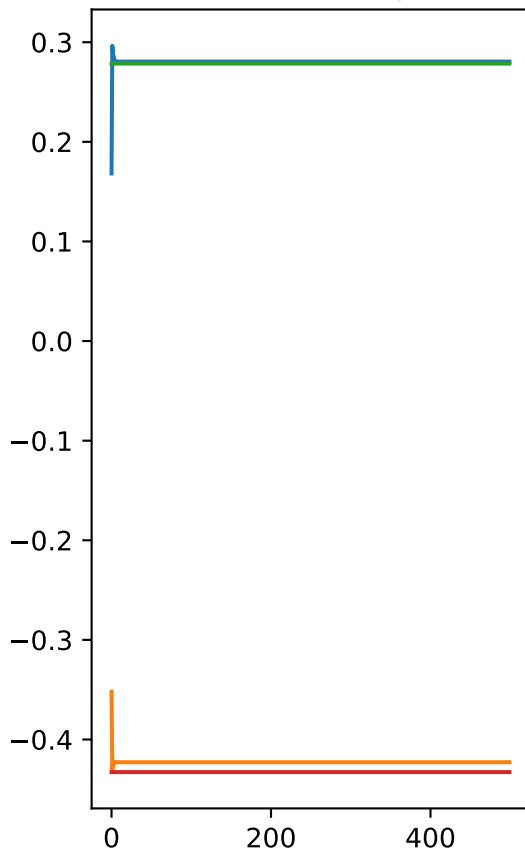
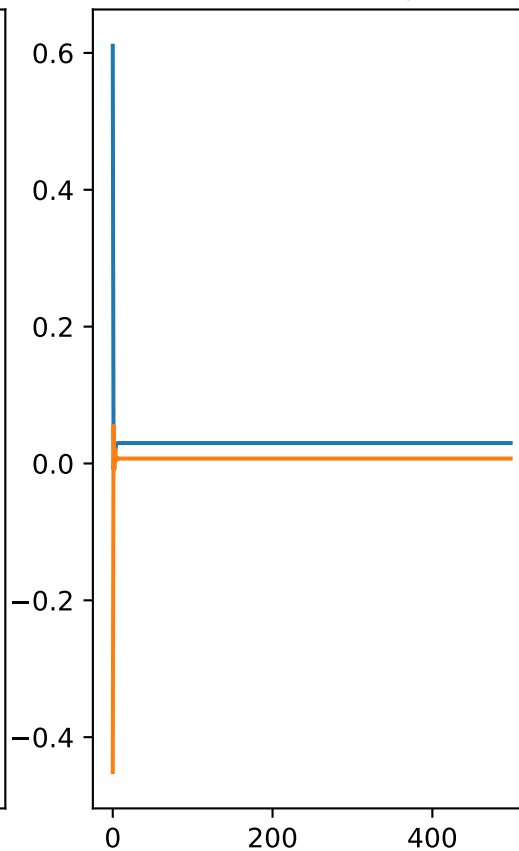


Reward: quartic_root
Speed = 33.6401733991077 [rad/s]

State vs step



Action vs step



Reward vs step

