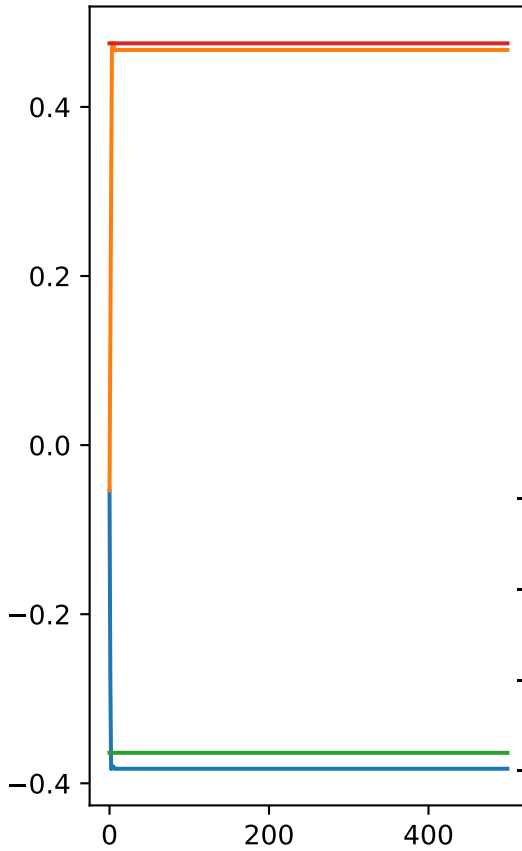
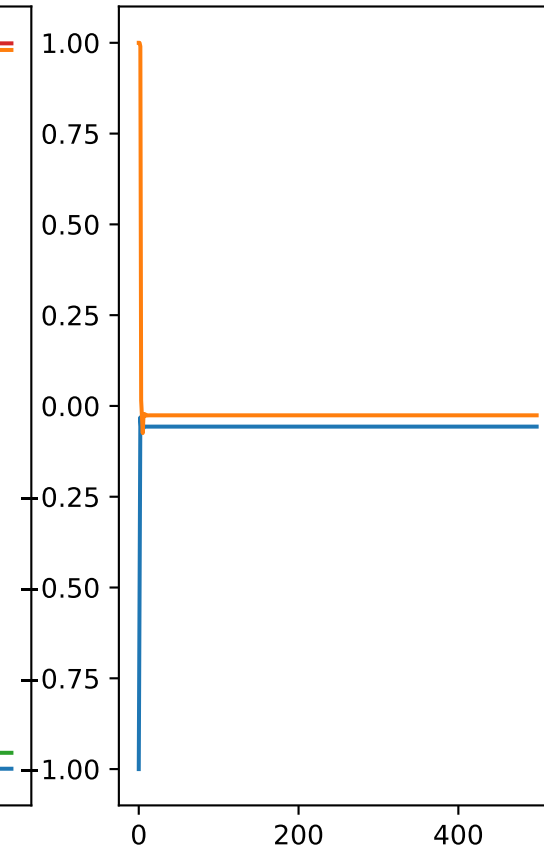


Reward: quartic\_root  
Speed = 328.6483056216639 [rad/s]

State vs step



Action vs step



Reward vs step

