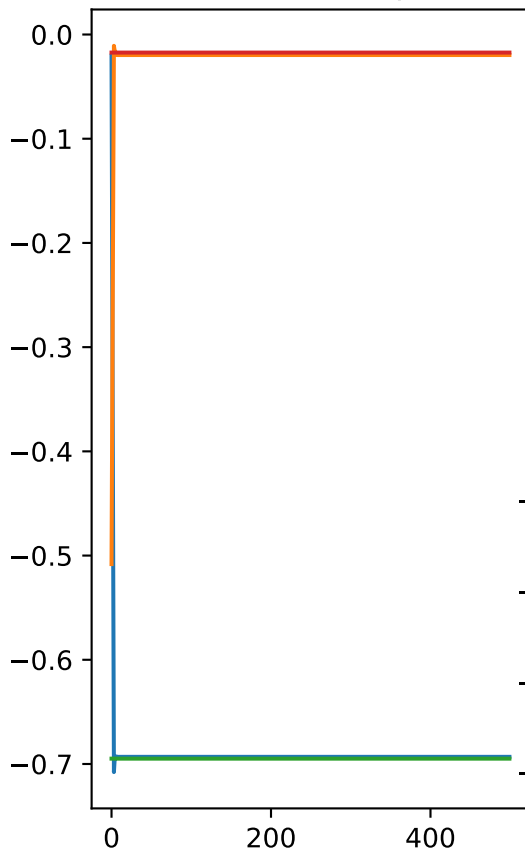
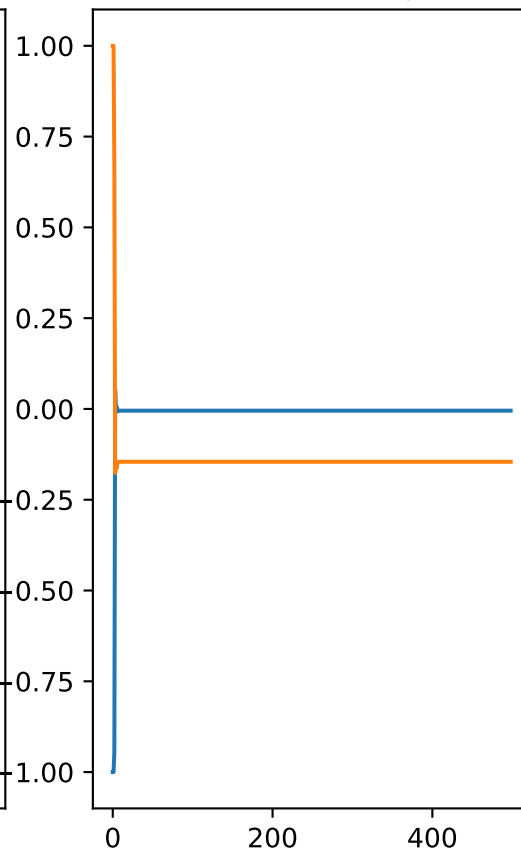


Reward: quartic_root
Speed = 558.9647351202781 [rad/s]

State vs step



Action vs step



Reward vs step

