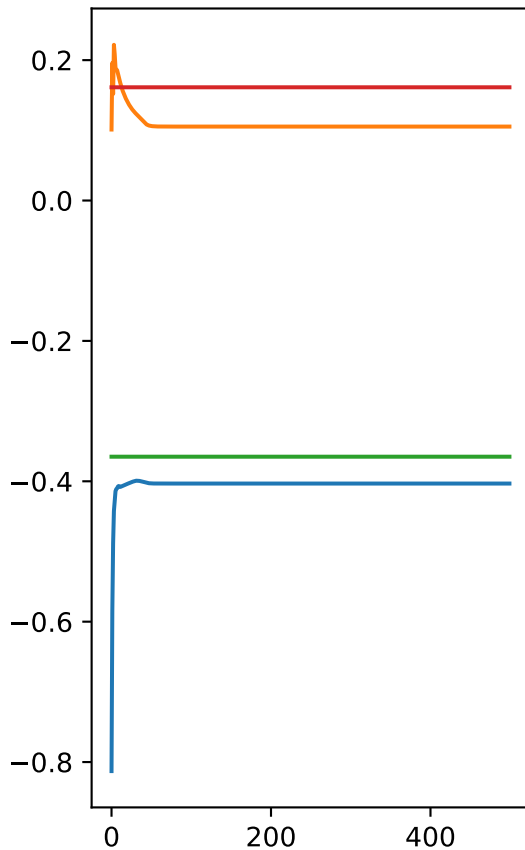
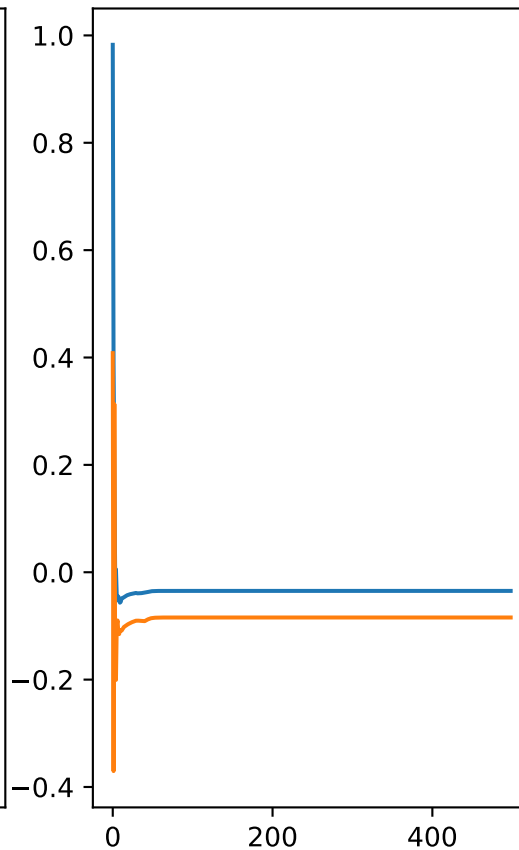


Reward: quadratic
Speed = 487.75110016939476 [rad/s]

State vs step



Action vs step



Reward vs step

