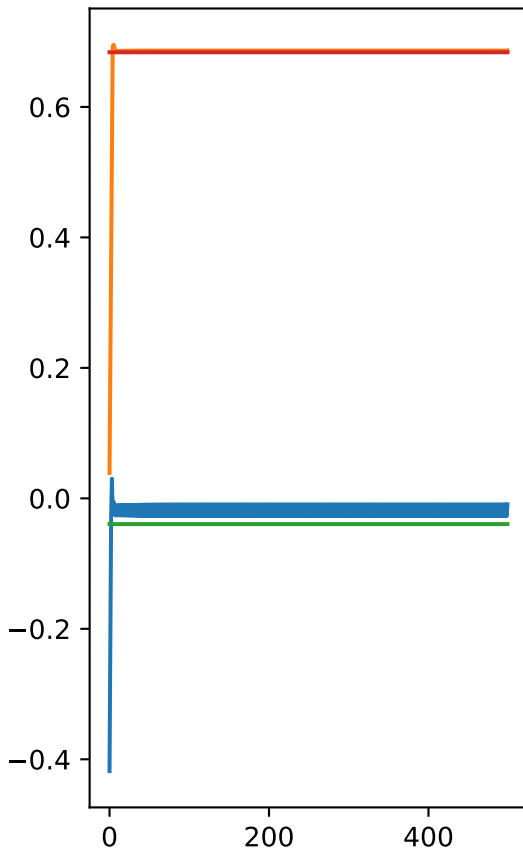
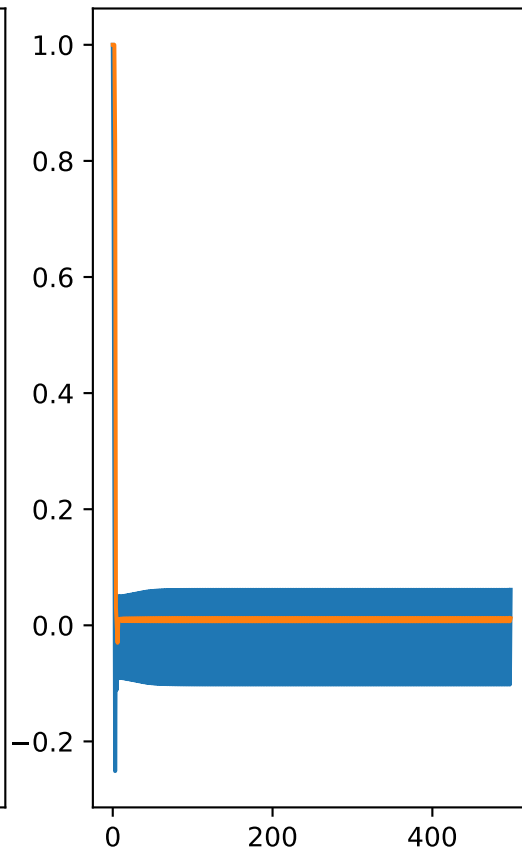


Reward: quartic_root
Speed = 896.9623839990446 [rad/s]

State vs step



Action vs step



Reward vs step

