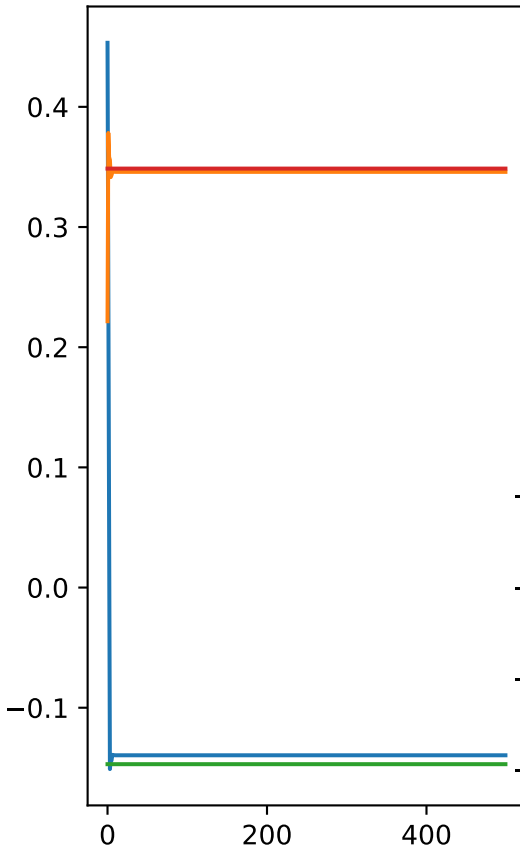
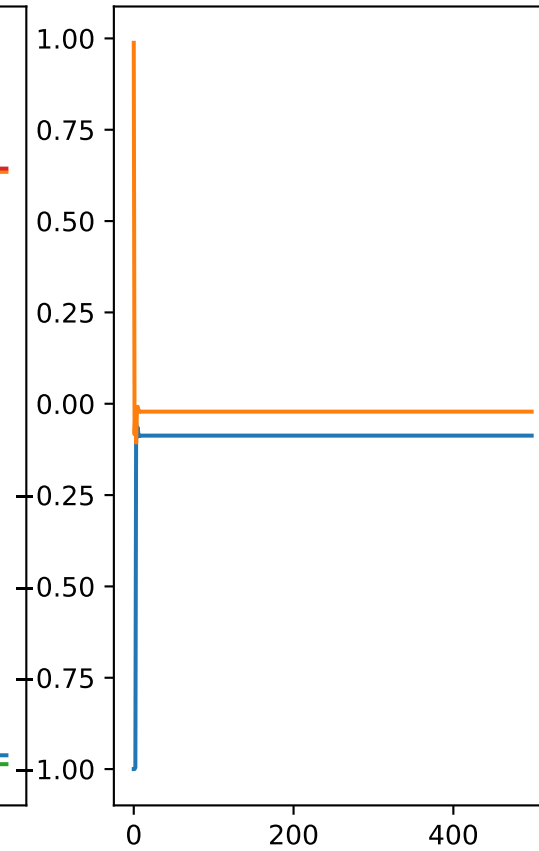


Reward: quartic_root
Speed = 141.8114960831727 [rad/s]

State vs step



Action vs step



Reward vs step

