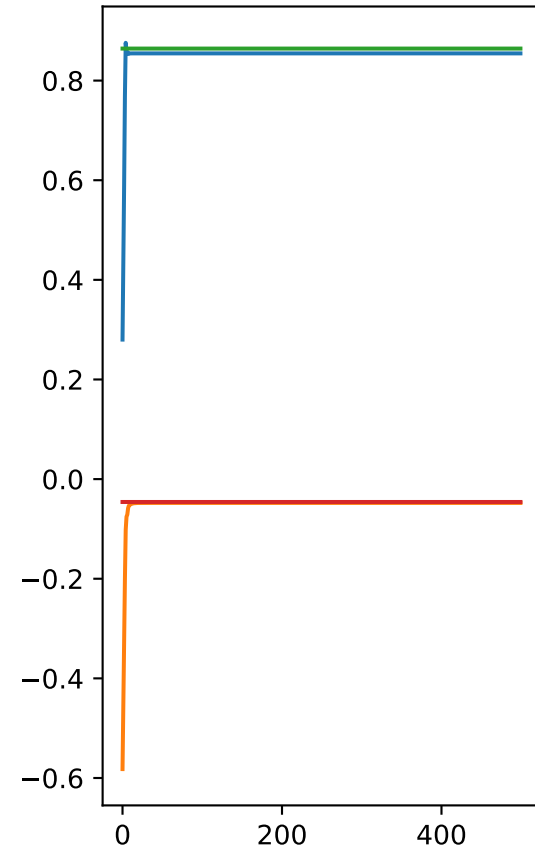
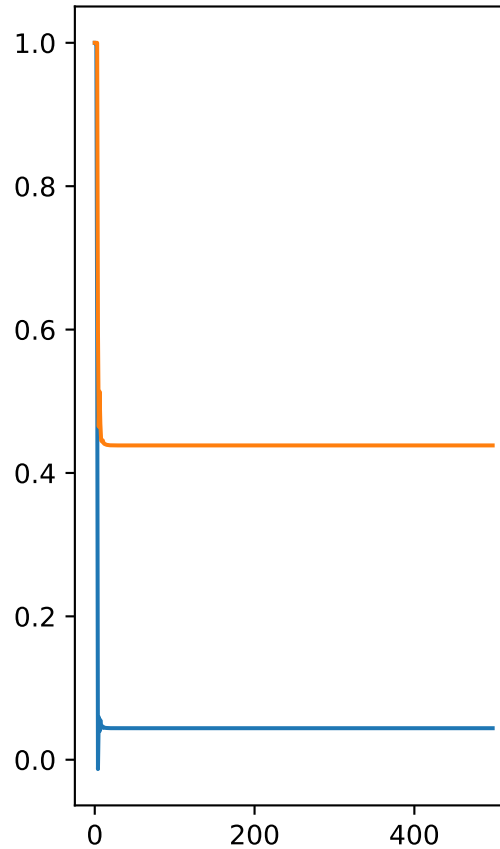


Reward: quartic_root
Speed = 1062.0593882388123 [rad/s]

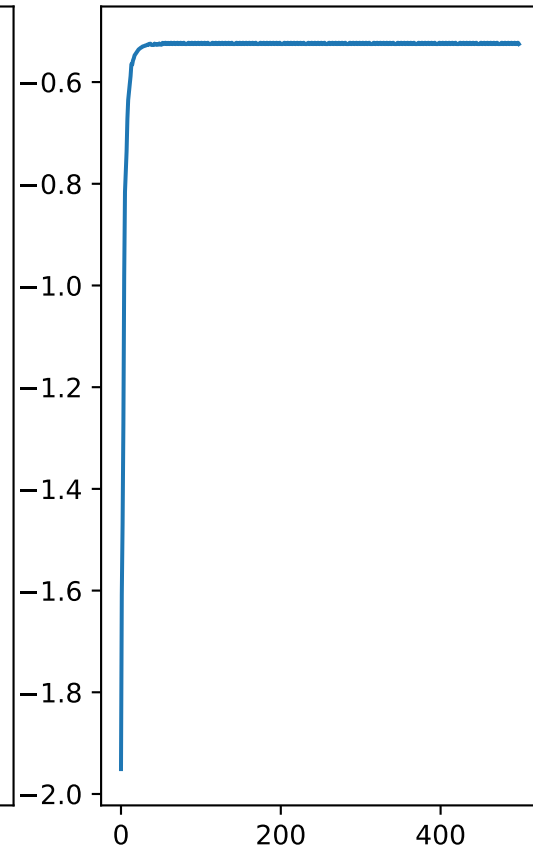
State vs step



Action vs step



Reward vs step



I_d I_d^{ref}
 I_q I_q^{ref}

V_d V_q