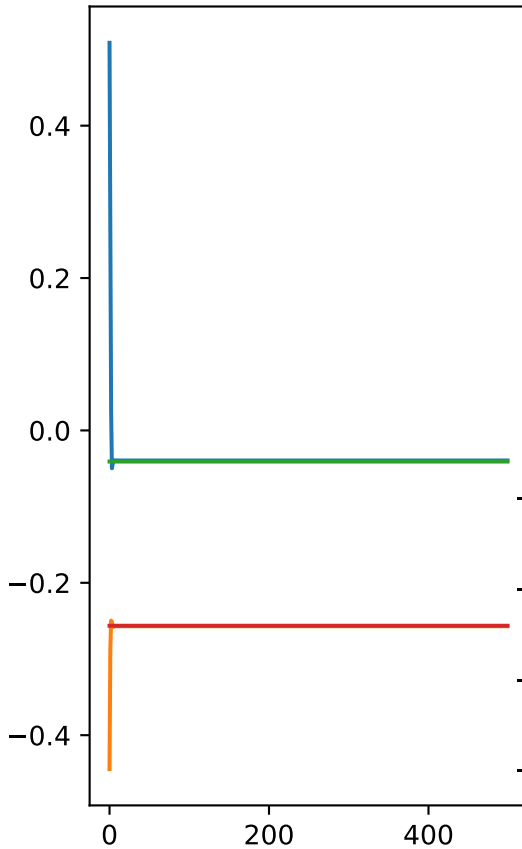
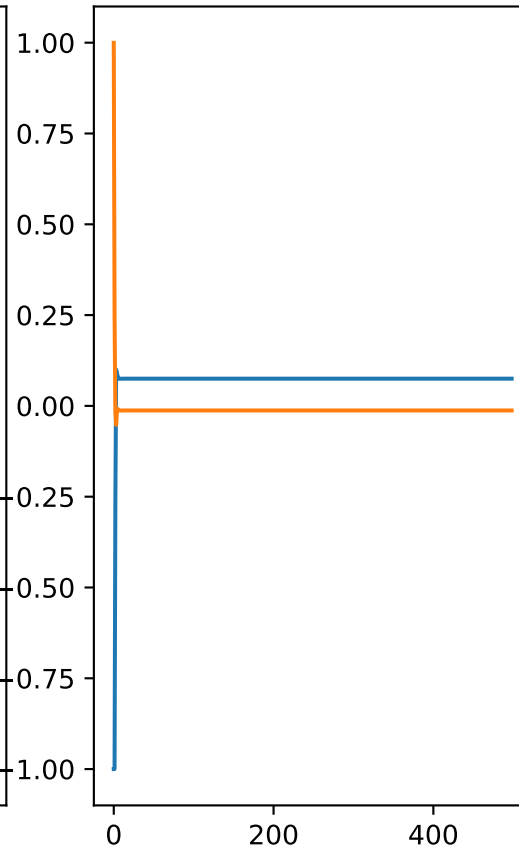


Reward: quartic_root
Speed = 775.3576299689292 [rad/s]

State vs step



Action vs step



Reward vs step

