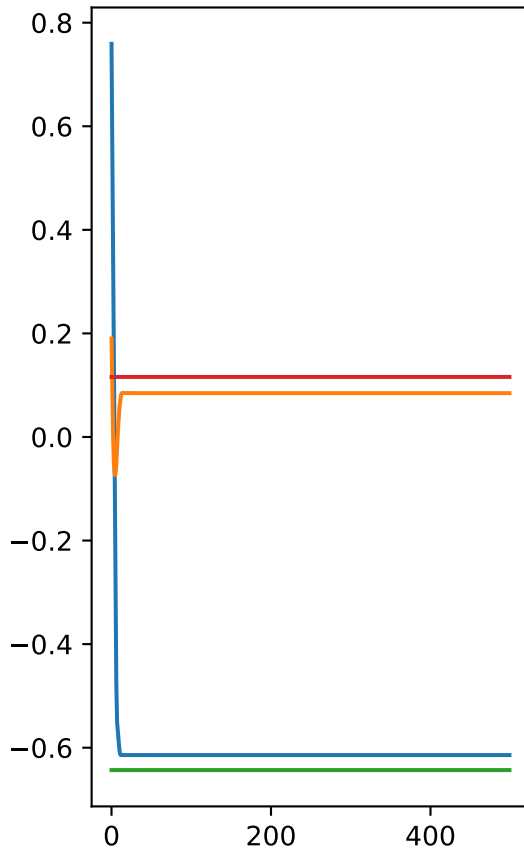
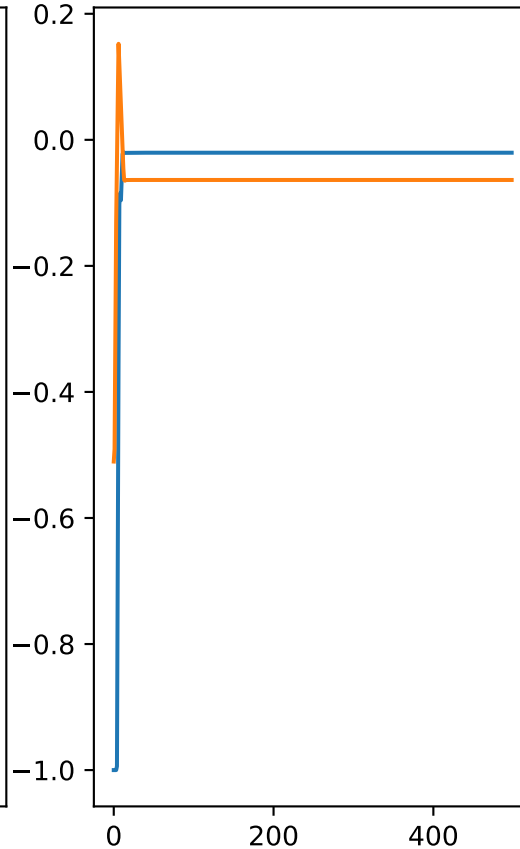


Reward: quadratic  
Speed = 402.8150033920385 [rad/s]

State vs step



Action vs step



Reward vs step

