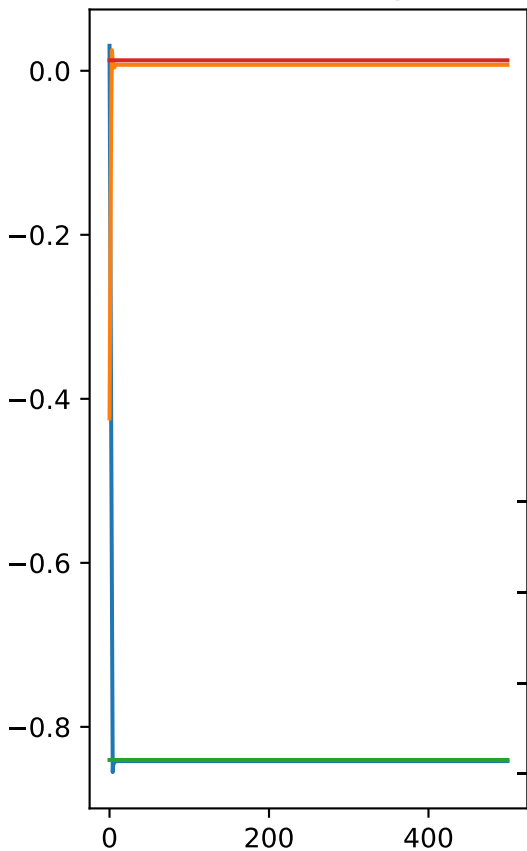
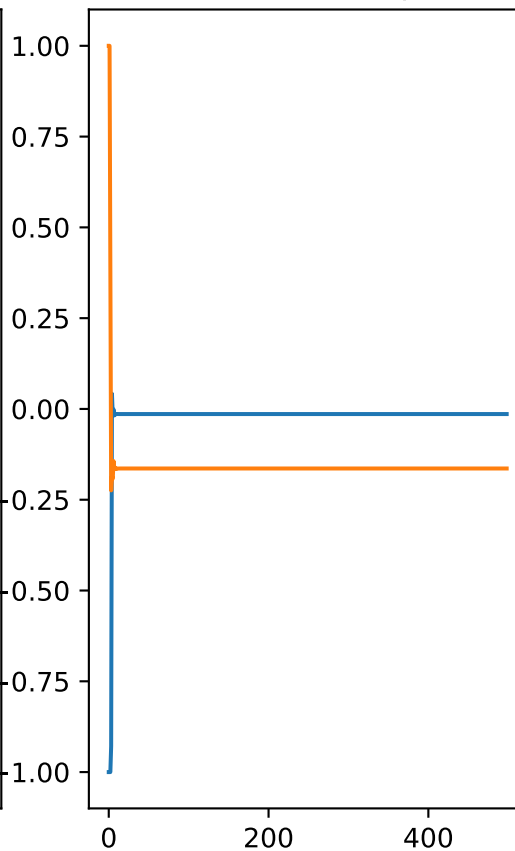


Reward: quartic_root
Speed = 155.62192961059148 [rad/s]

State vs step



Action vs step



Reward vs step

