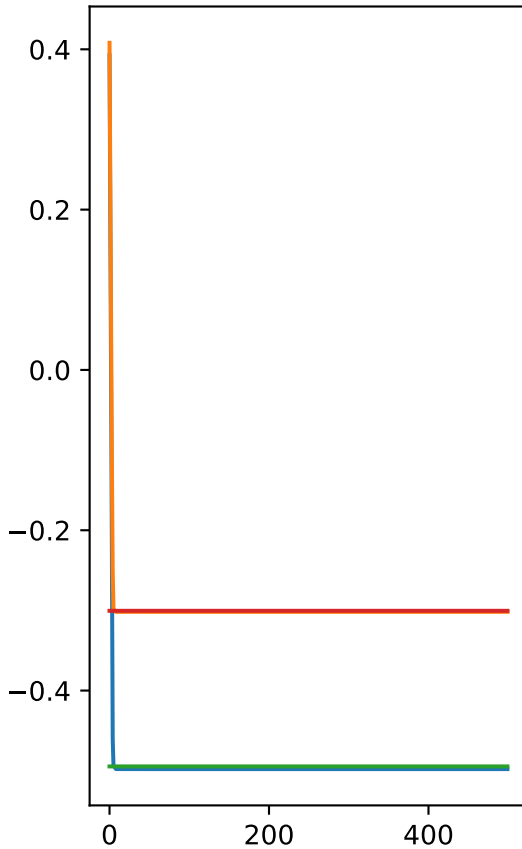
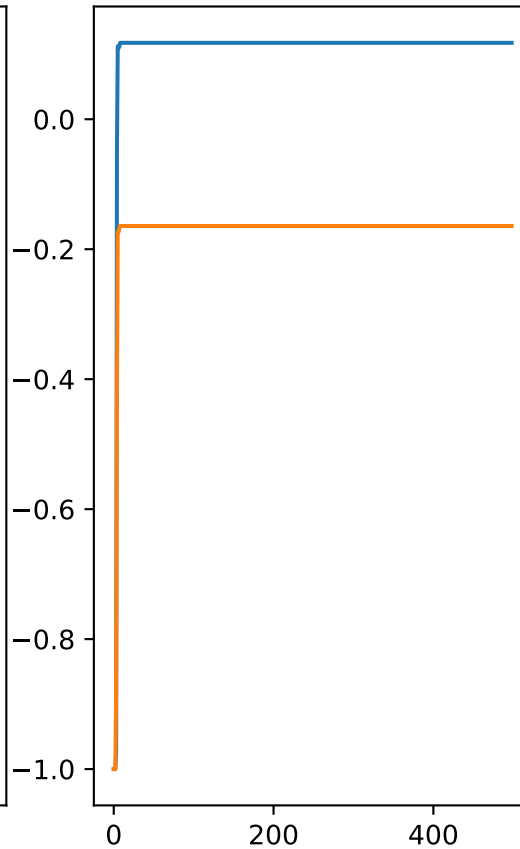


Reward: square_root
Speed = 987.9680412825301 [rad/s]

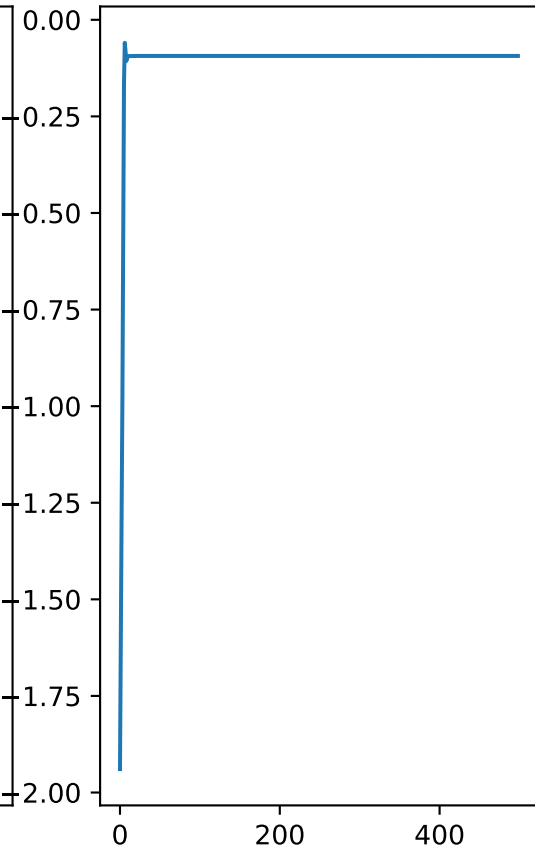
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq