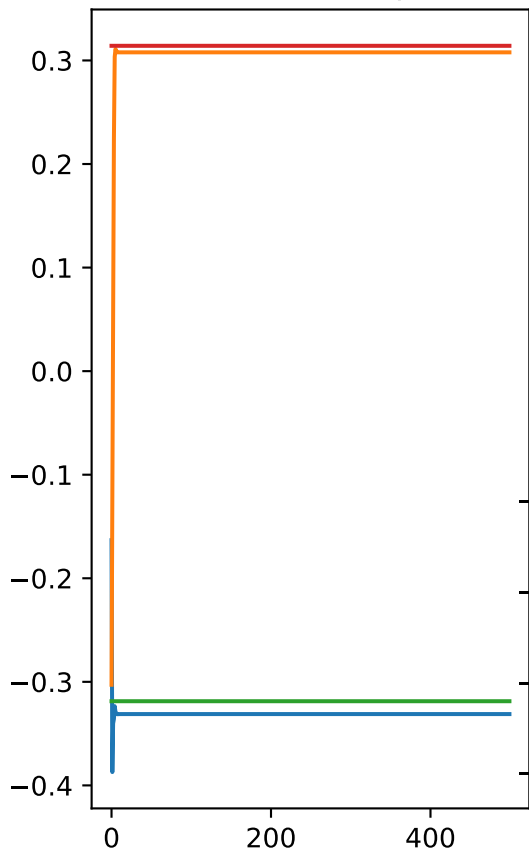
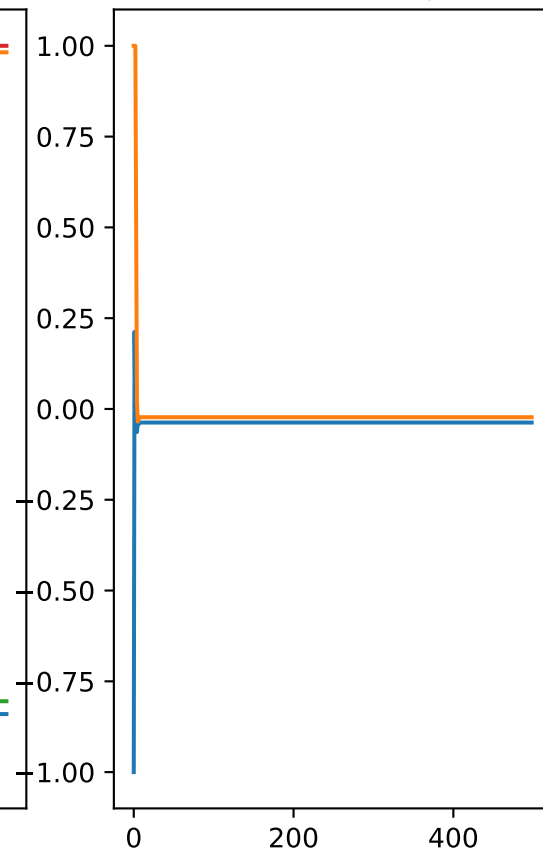


Reward: quartic_root_2
Speed = 1099.5700121925784 [rad/s]

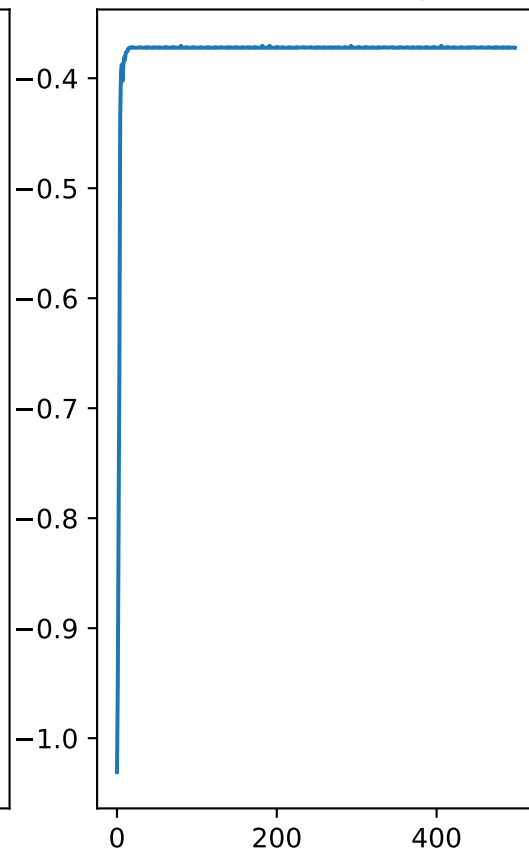
State vs step



Action vs step



Reward vs step



— I_d — I_{dref}
— I_q — I_{qref}

— V_d — V_q