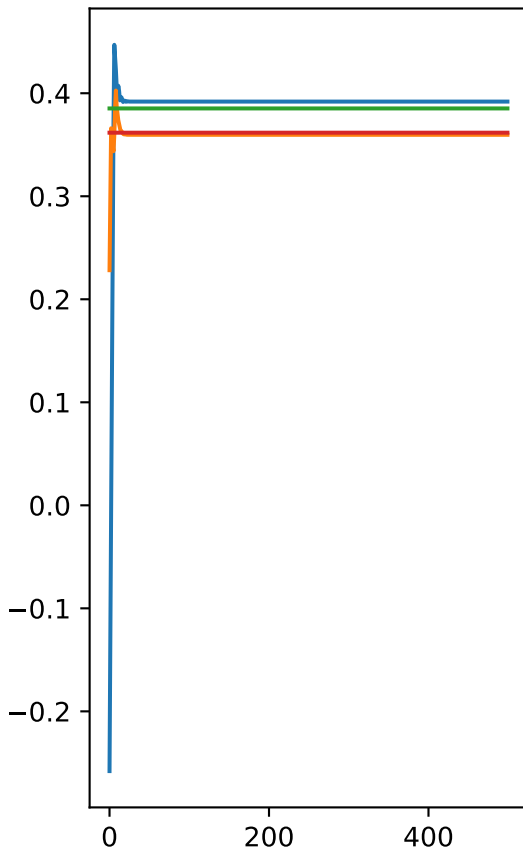
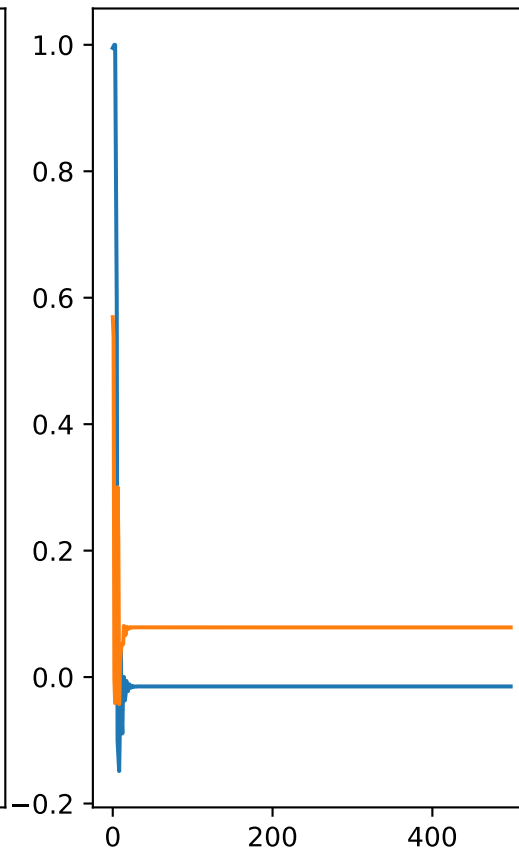


Reward: quadratic_2
Speed = 1114.9260736764625 [rad/s]

State vs step



Action vs step



Reward vs step

