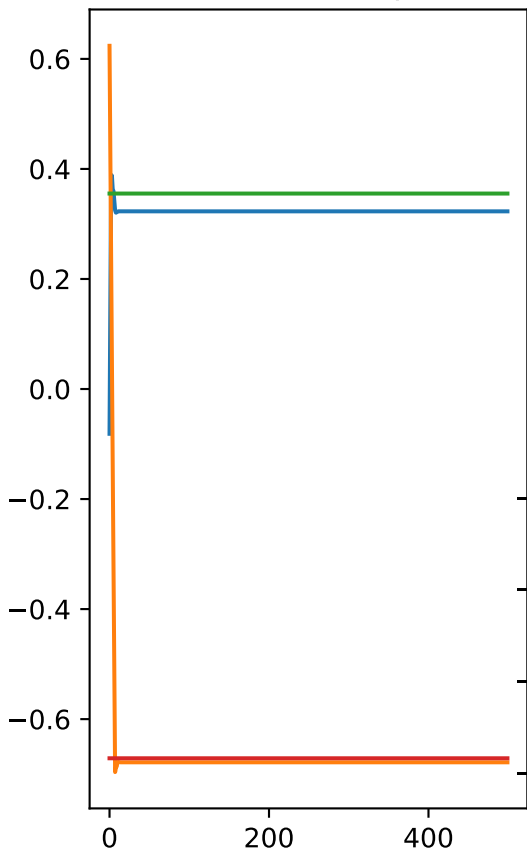
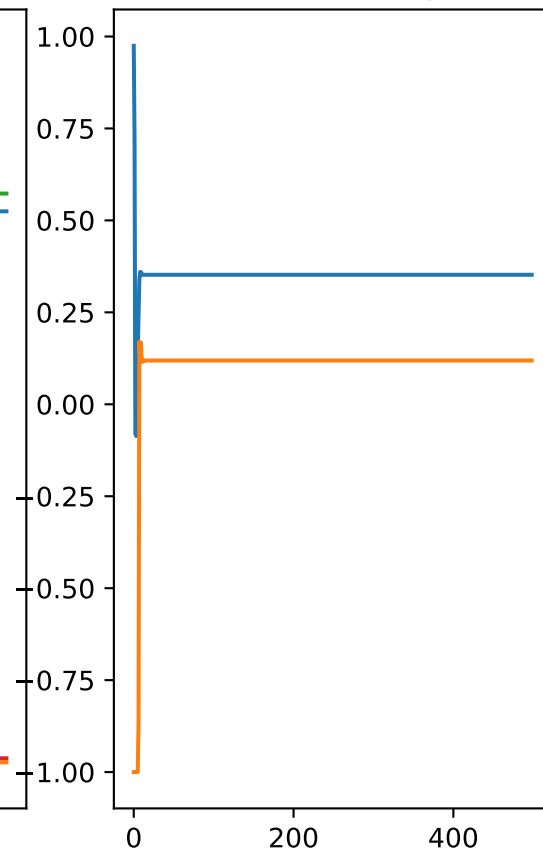


Reward: quartic_root
Speed = 1103.4027171201226 [rad/s]

State vs step



Action vs step



Reward vs step

