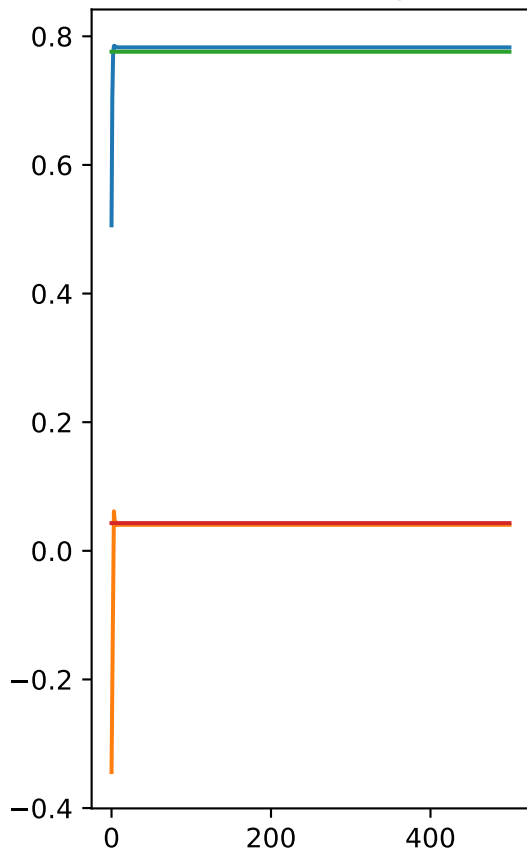
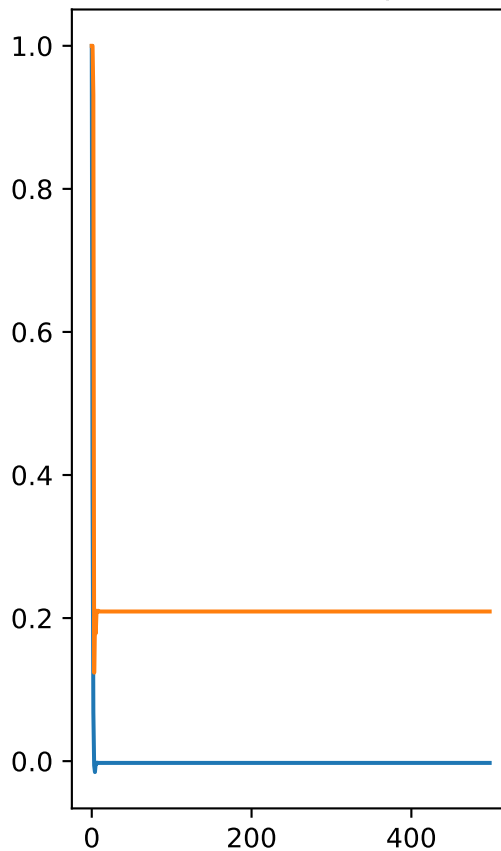


Reward: quartic_root
Speed = 688.863284348254 [rad/s]

State vs step



Action vs step



Reward vs step

