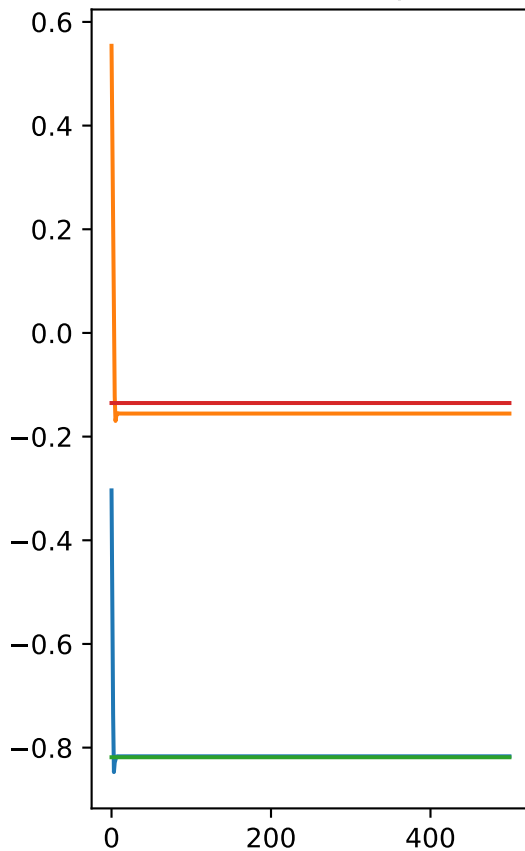
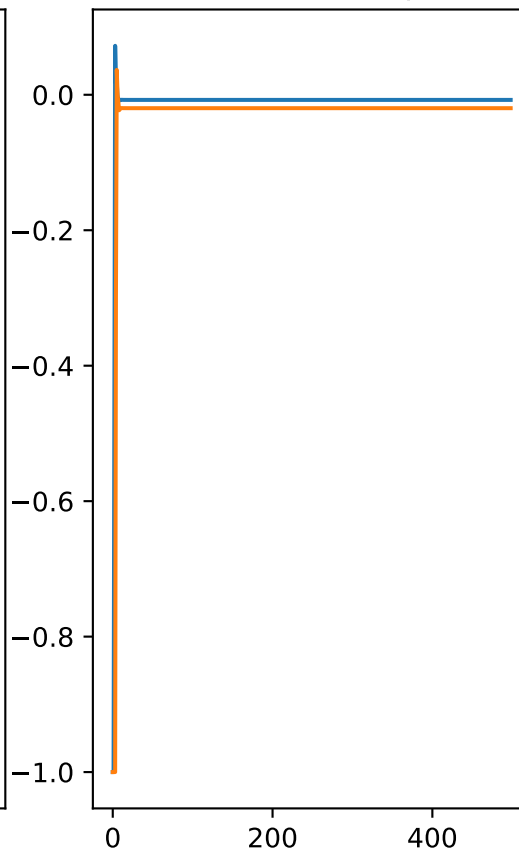


Reward: quartic_root
Speed = 1027.4641516974912 [rad/s]

State vs step



Action vs step



Reward vs step

