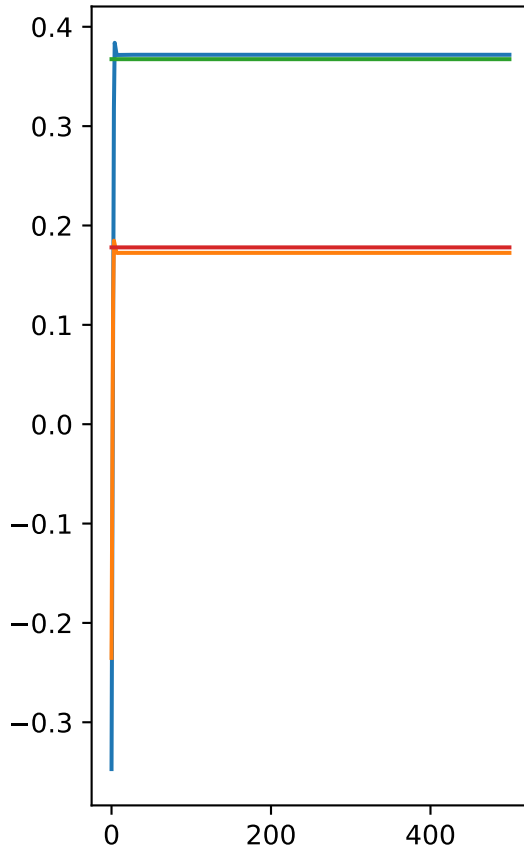
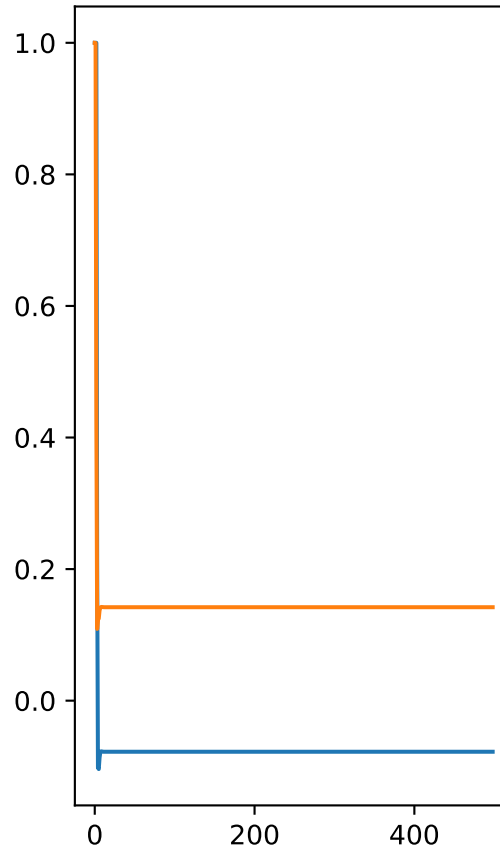


Reward: quartic_root_2
Speed = 729.8171259201404 [rad/s]

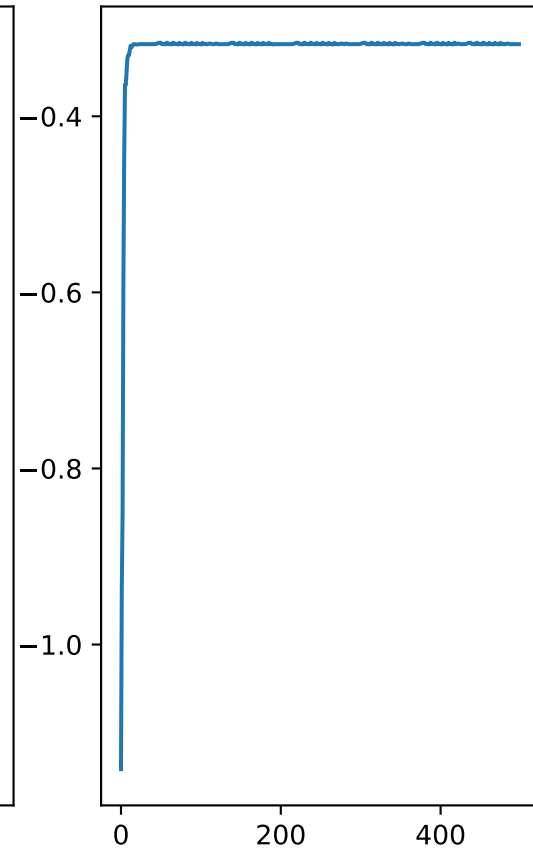
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq