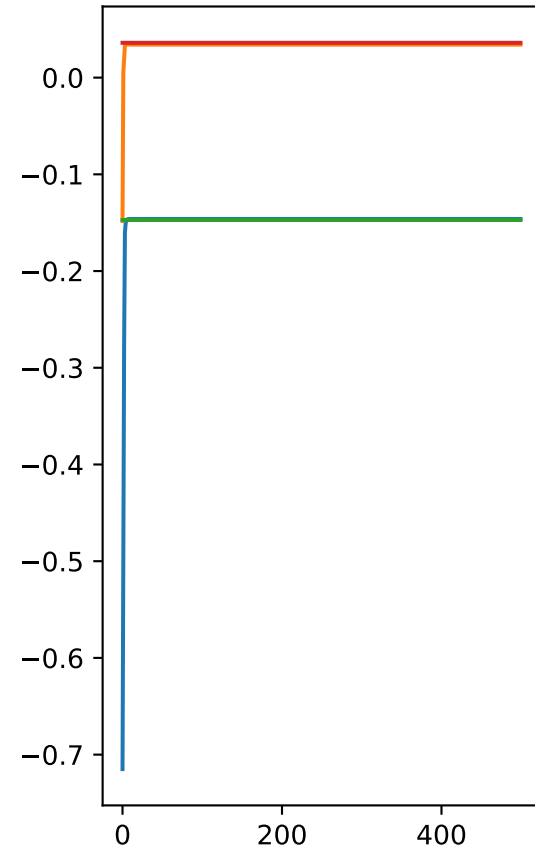
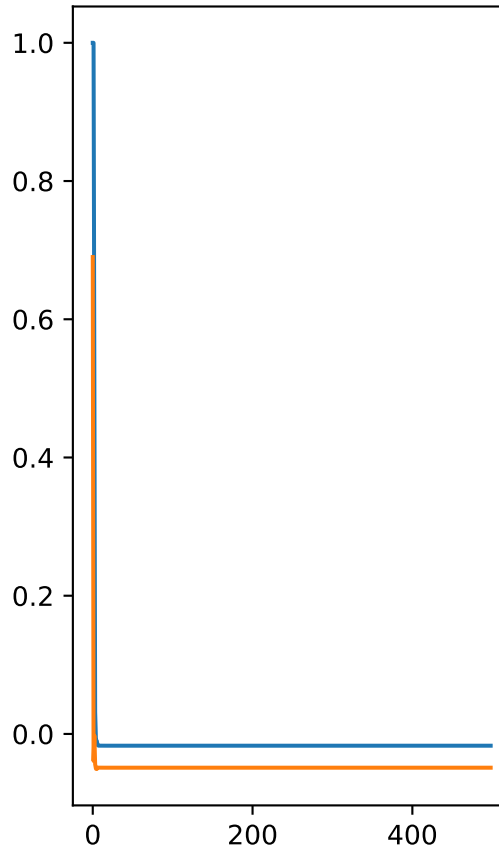


Reward: square_root
Speed = 73.73946483383645 [rad/s]

State vs step



Action vs step



Reward vs step

