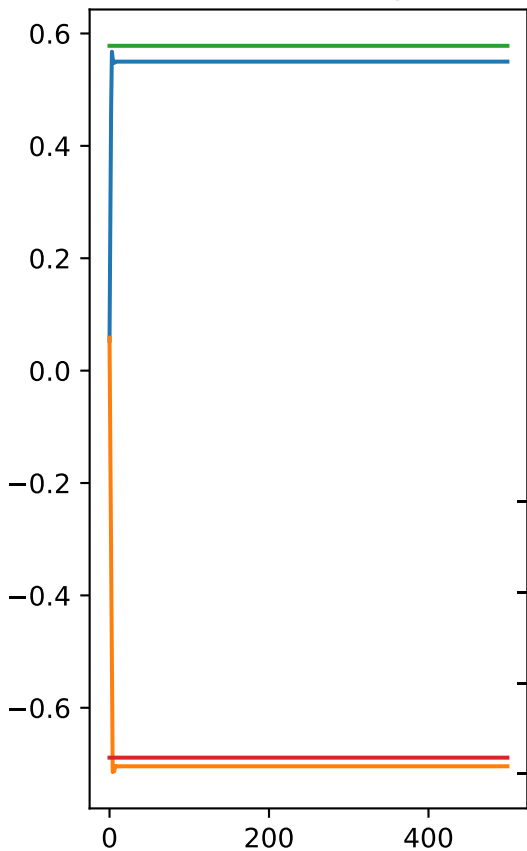
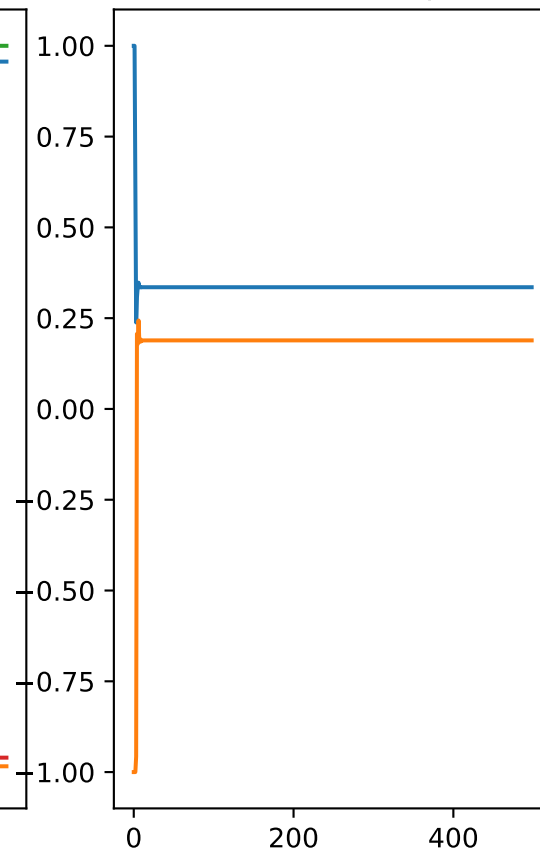


Reward: quartic_root
Speed = 133.24123043435105 [rad/s]

State vs step



Action vs step



Reward vs step

