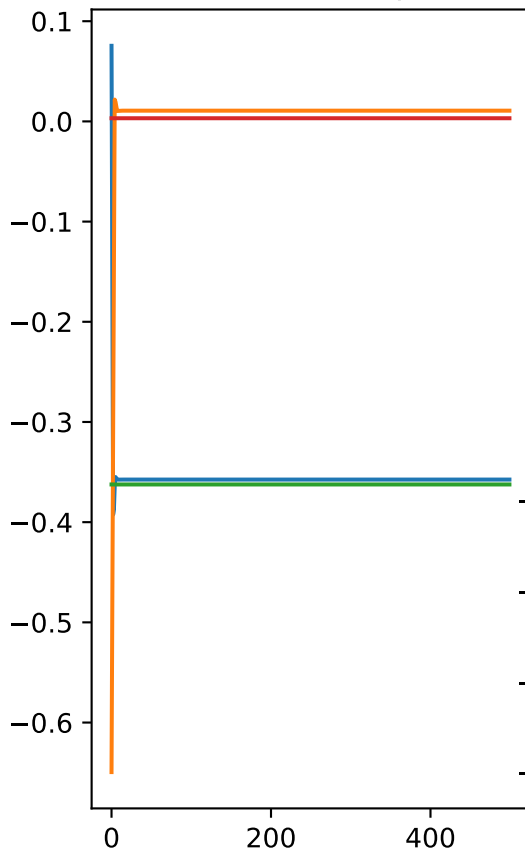
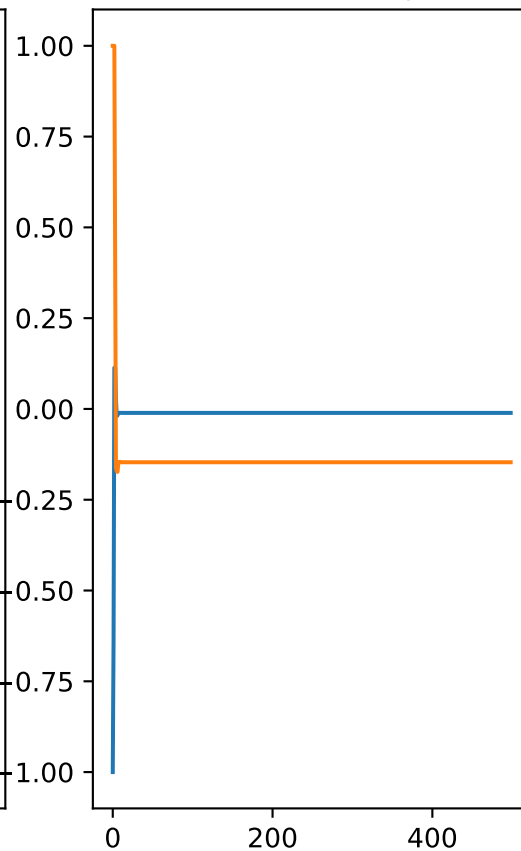


Reward: quartic_root
Speed = 857.9060946381102 [rad/s]

State vs step



Action vs step



Reward vs step

