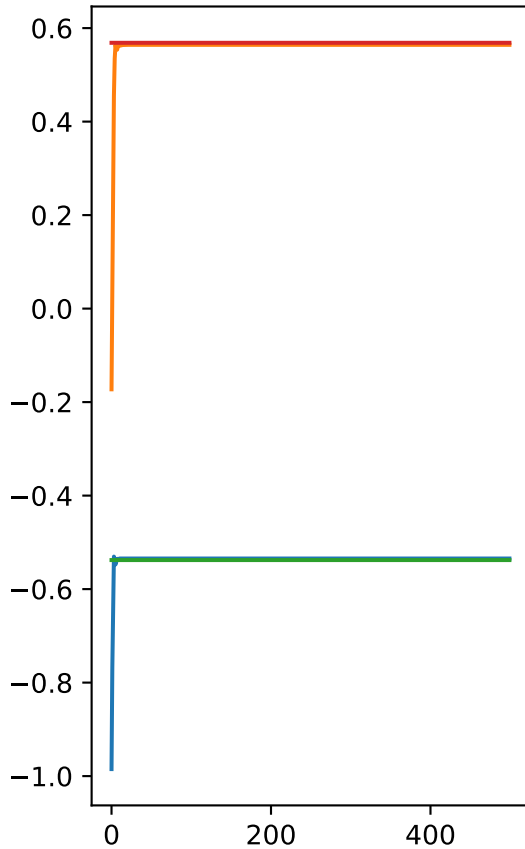
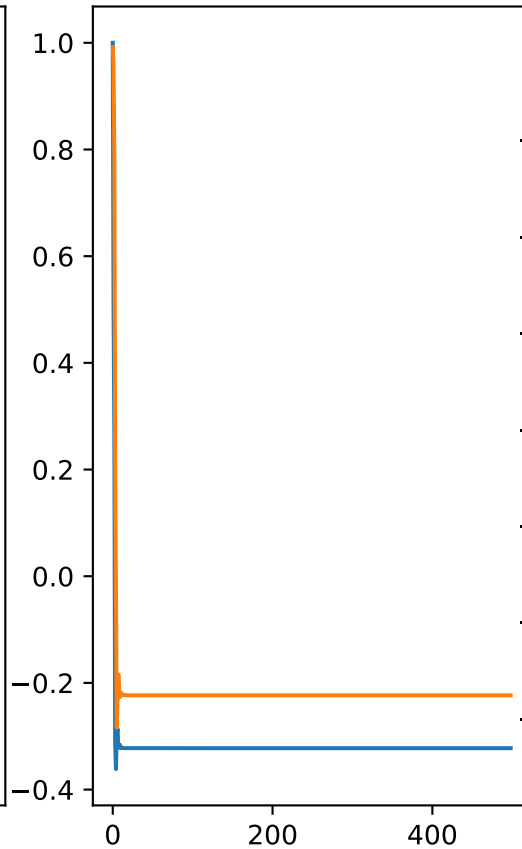


Reward: quadratic_2
Speed = 540.9445429892302 [rad/s]

State vs step



Action vs step



Reward vs step

