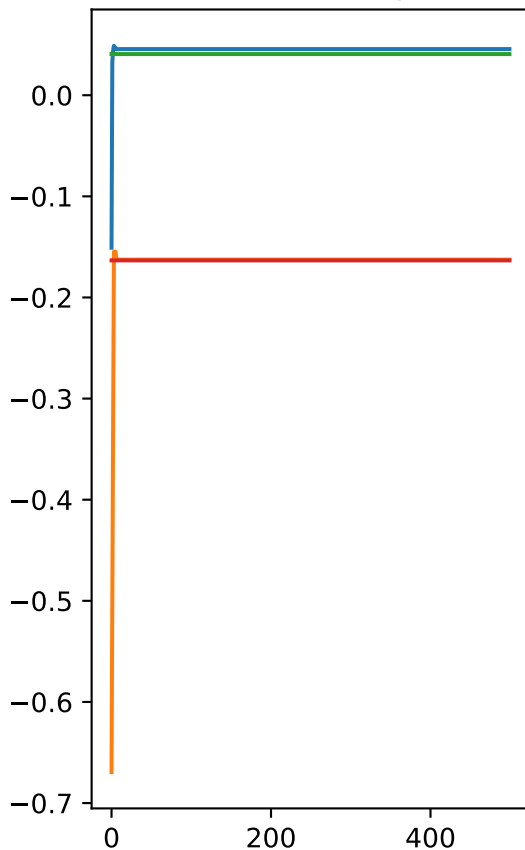
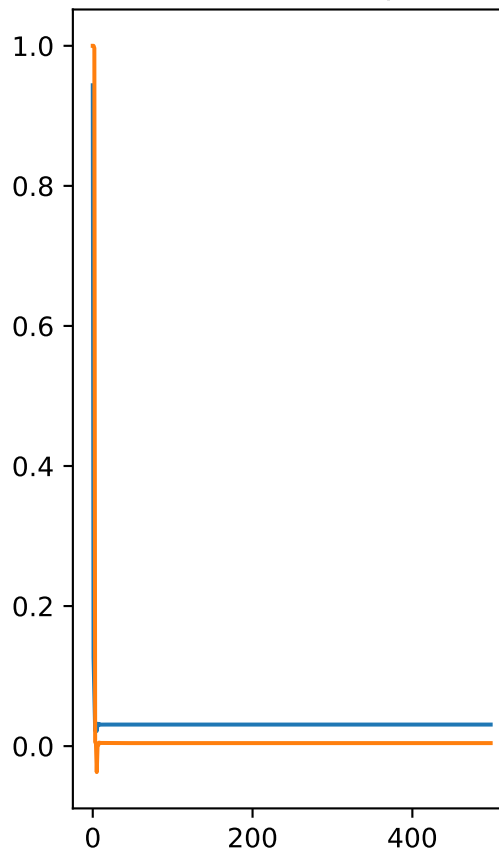


Reward: quartic_root
Speed = 81.02795677163813 [rad/s]

State vs step



Action vs step



Reward vs step

