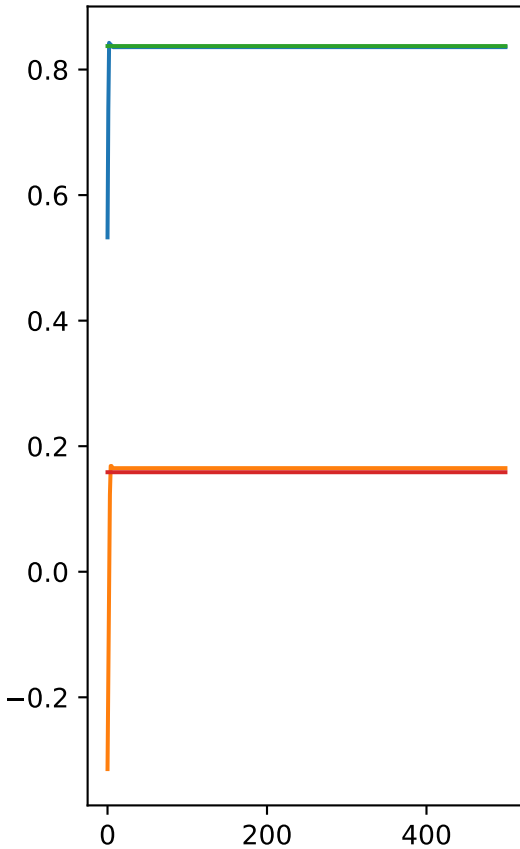
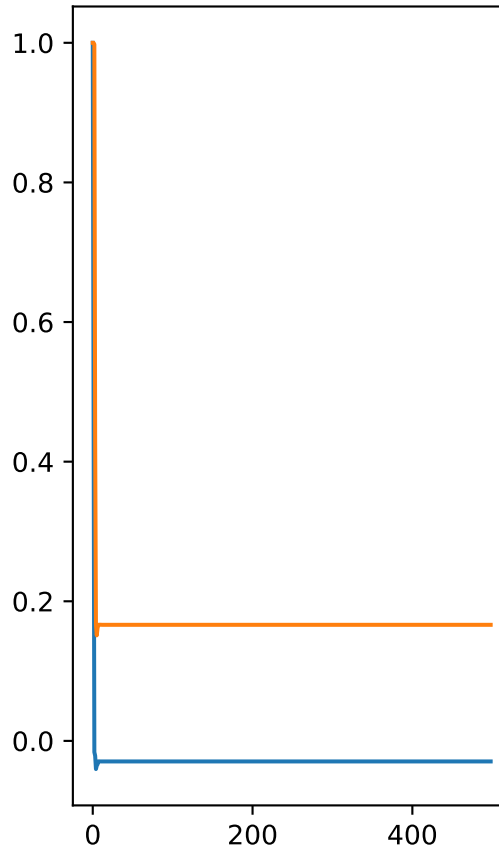


Reward: quartic\_root\_2  
Speed = 518.2120038225848 [rad/s]

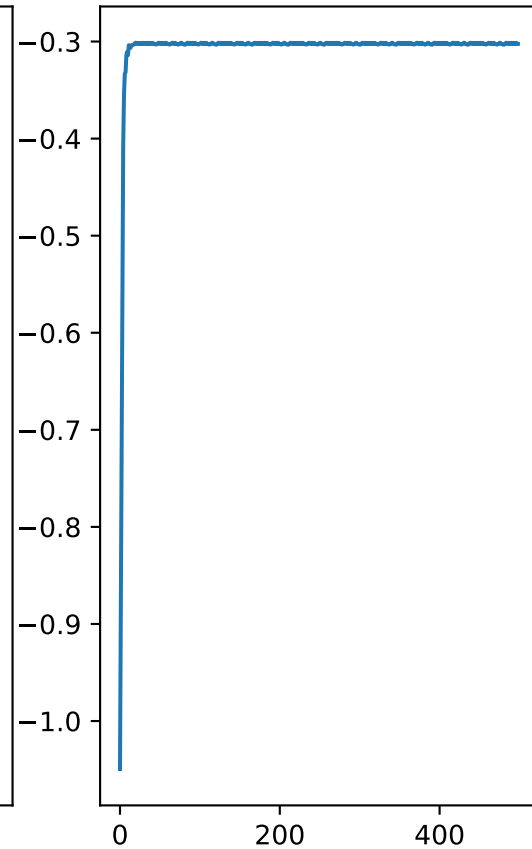
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq