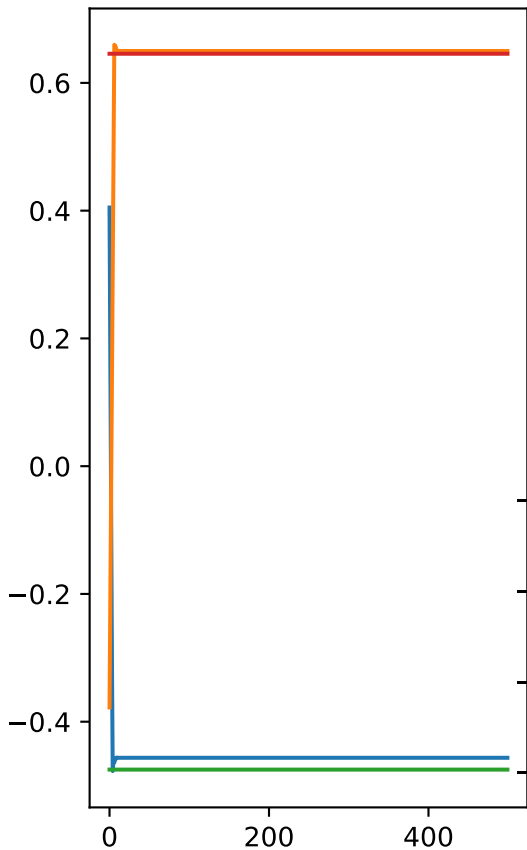
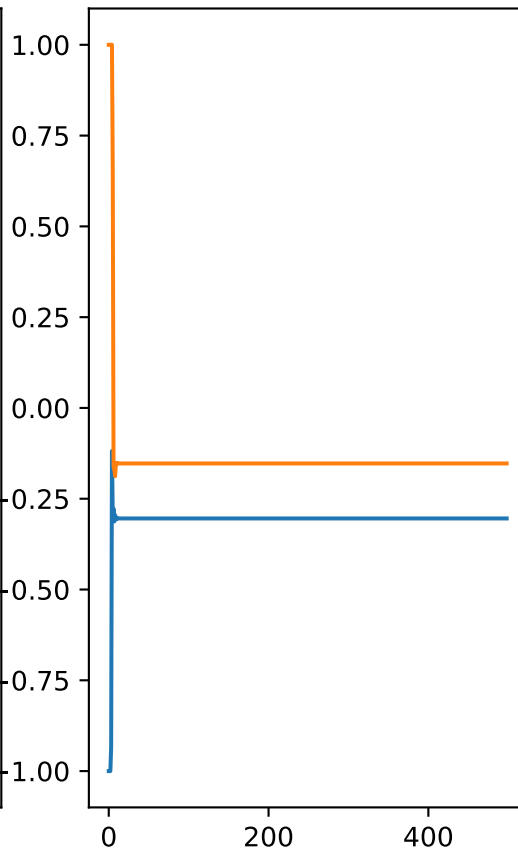


Reward: quartic_root
Speed = 1029.0349839769608 [rad/s]

State vs step



Action vs step



Reward vs step

