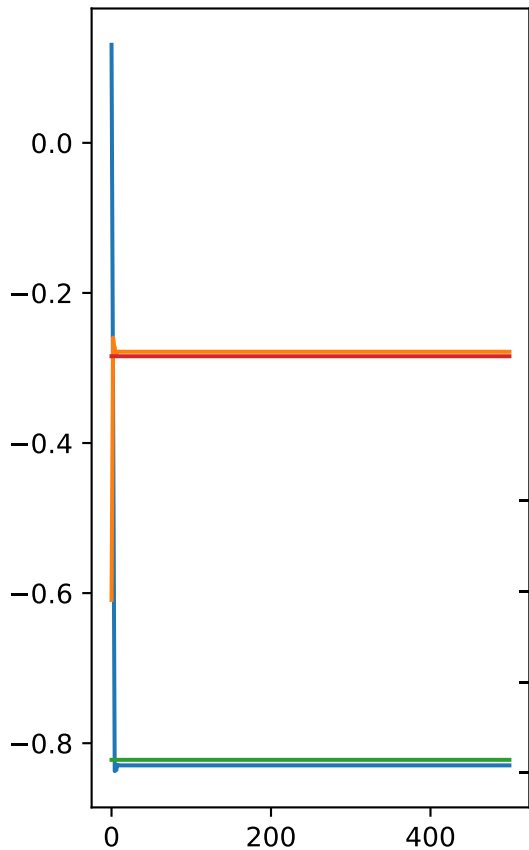
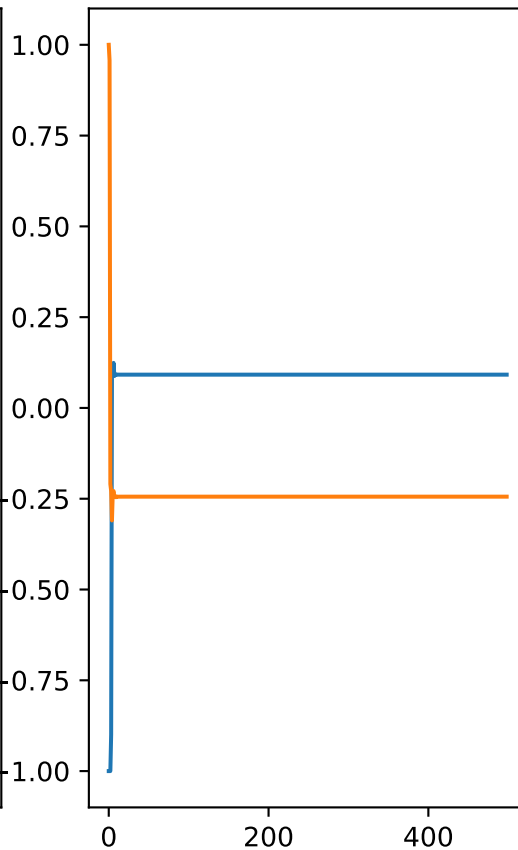


Reward: quartic_root
Speed = 356.18120097555556 [rad/s]

State vs step



Action vs step



Reward vs step

