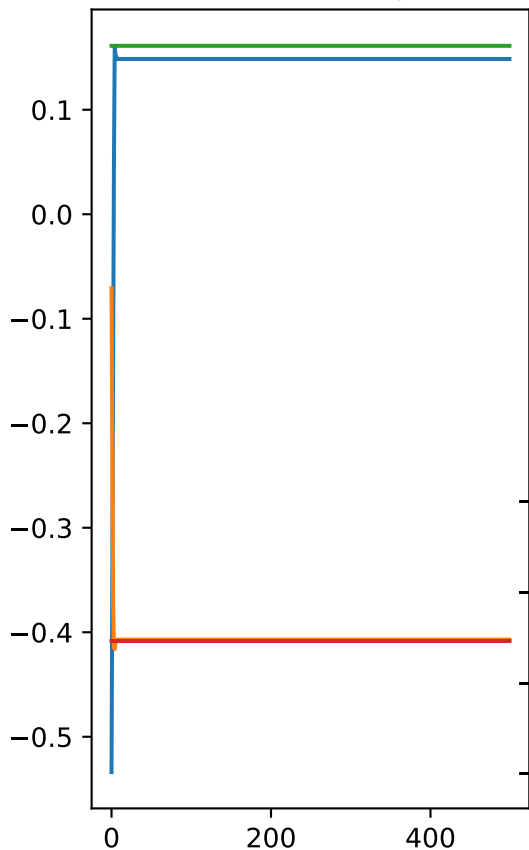
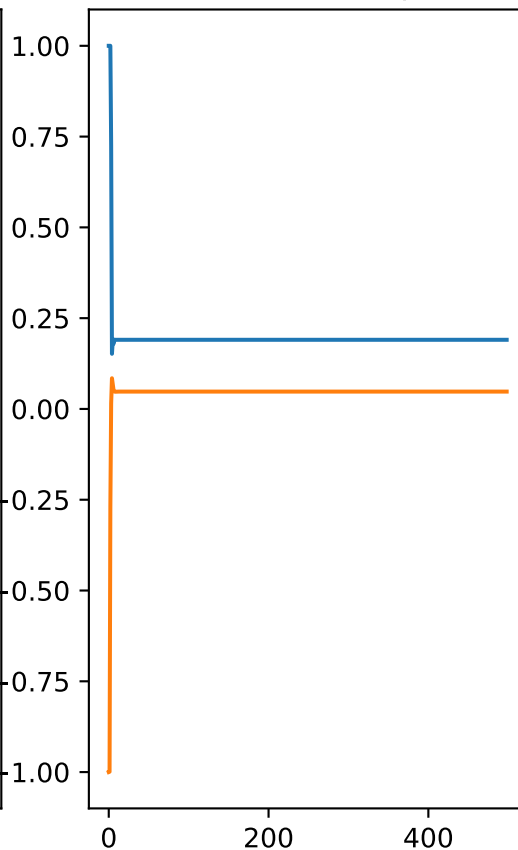


Reward: quartic_root
Speed = 1107.8386779688403 [rad/s]

State vs step



Action vs step



Reward vs step

