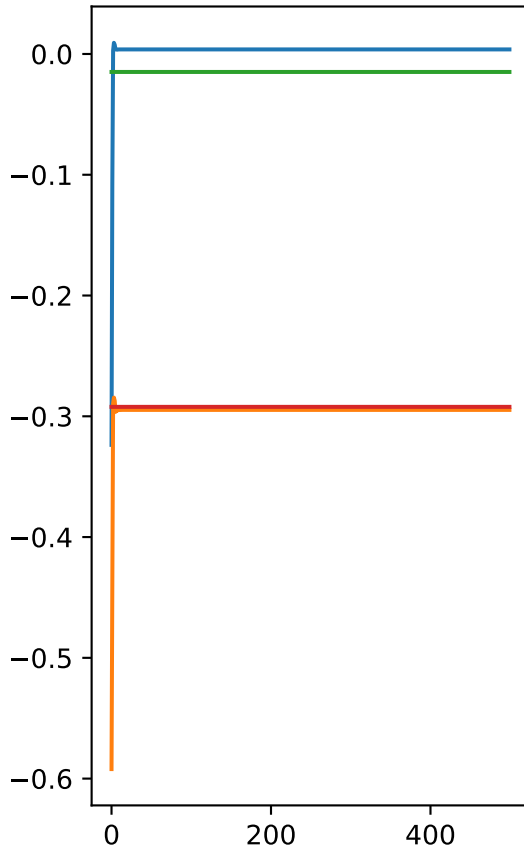
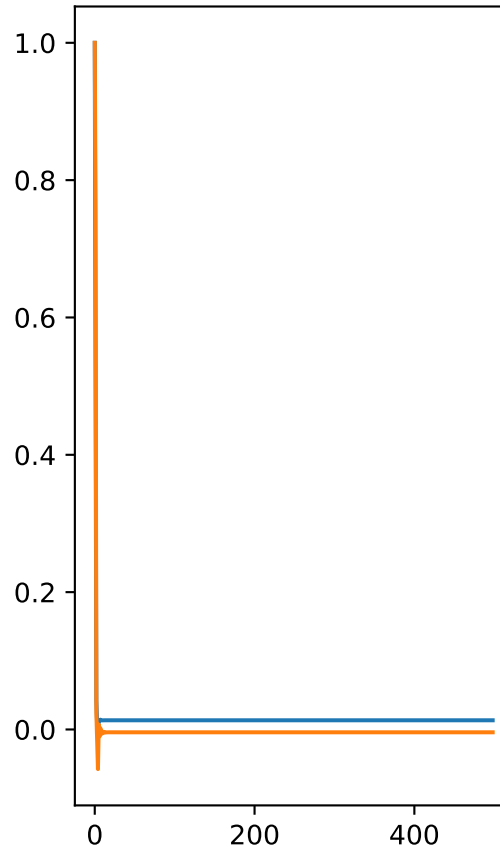


Reward: quartic_root
Speed = 716.7857793636782 [rad/s]

State vs step



Action vs step



Reward vs step

