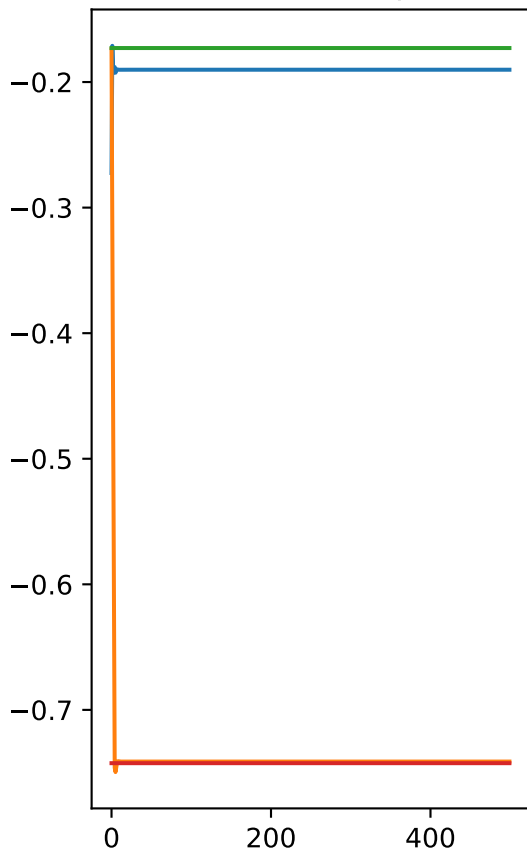
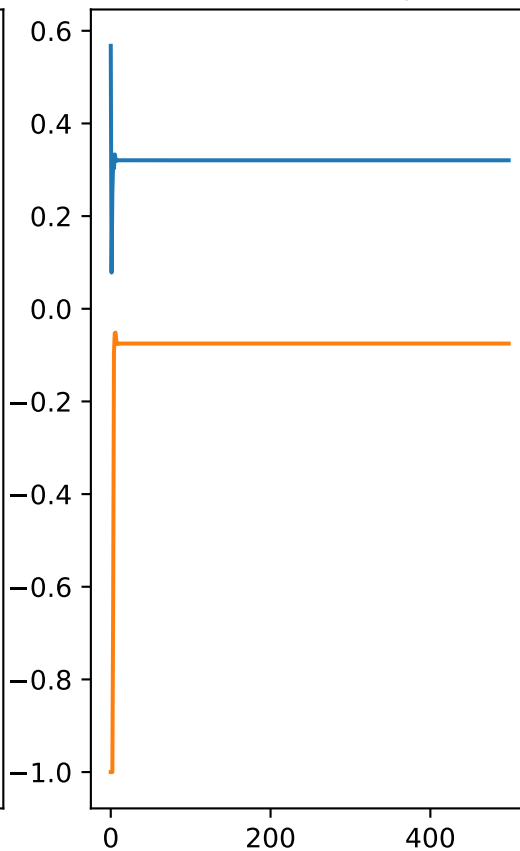


Reward: quartic_root
Speed = 663.3158380048545 [rad/s]

State vs step



Action vs step



Reward vs step

