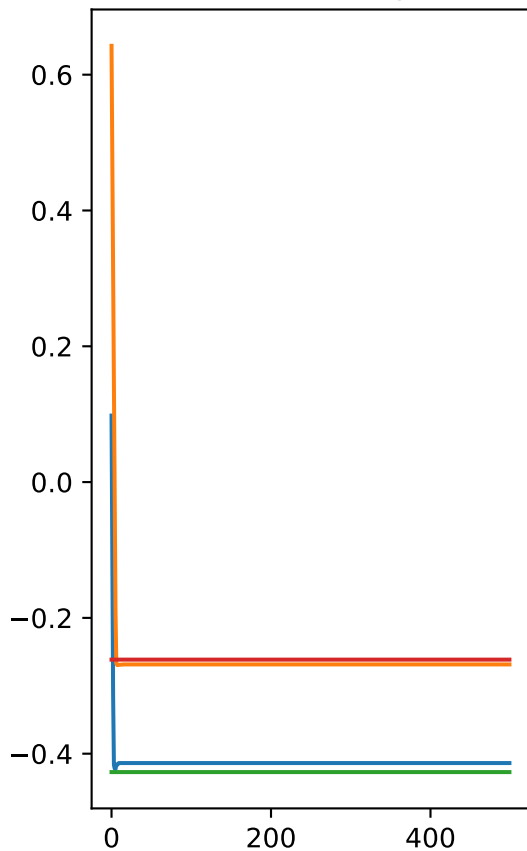
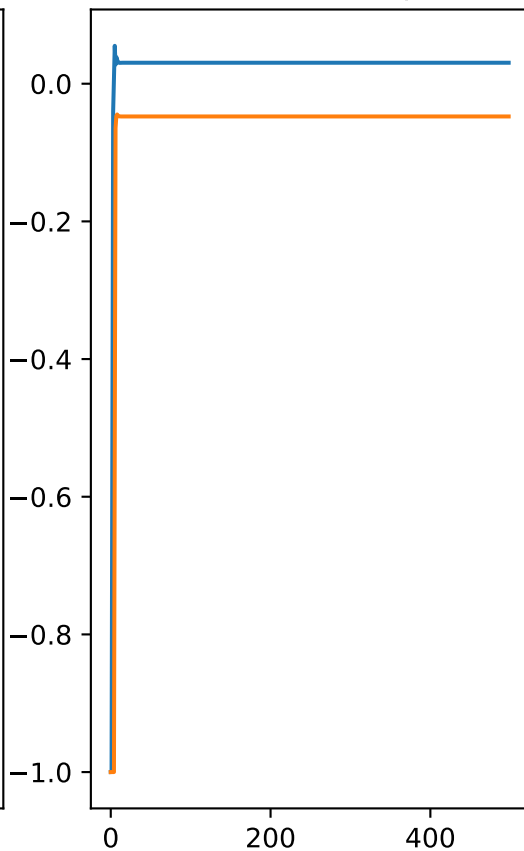


Reward: quartic_root_2
Speed = 385.36031687371207 [rad/s]

State vs step



Action vs step



Reward vs step

