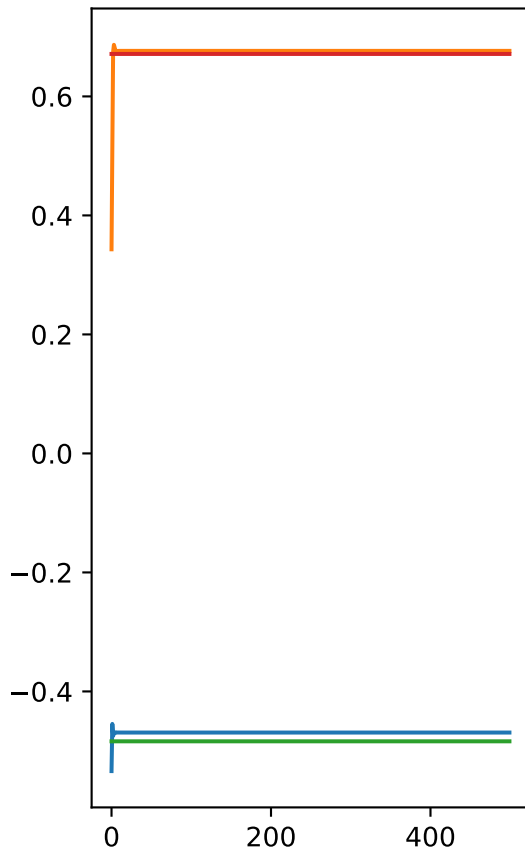
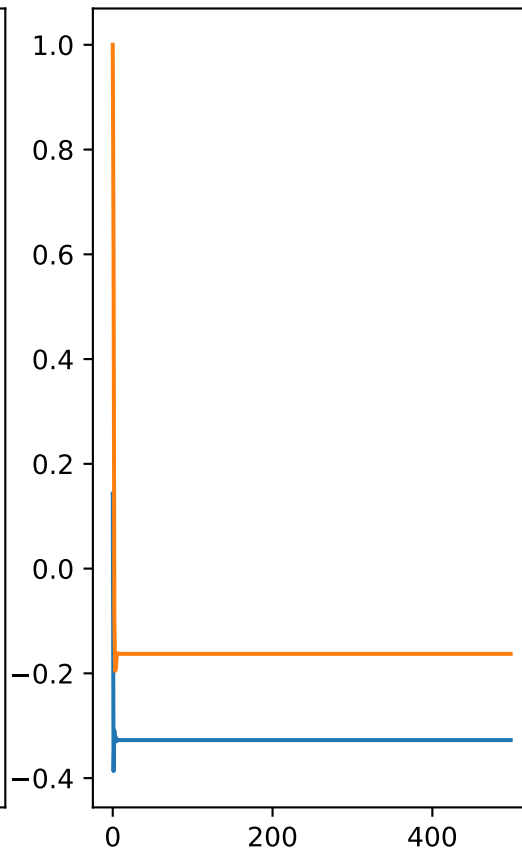


Reward: quartic_root
Speed = 760.9691448433412 [rad/s]

State vs step



Action vs step



Reward vs step

