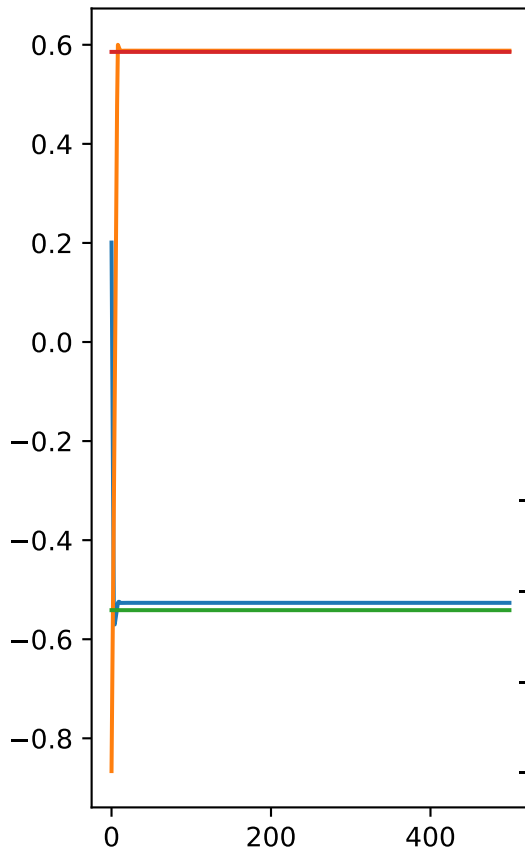
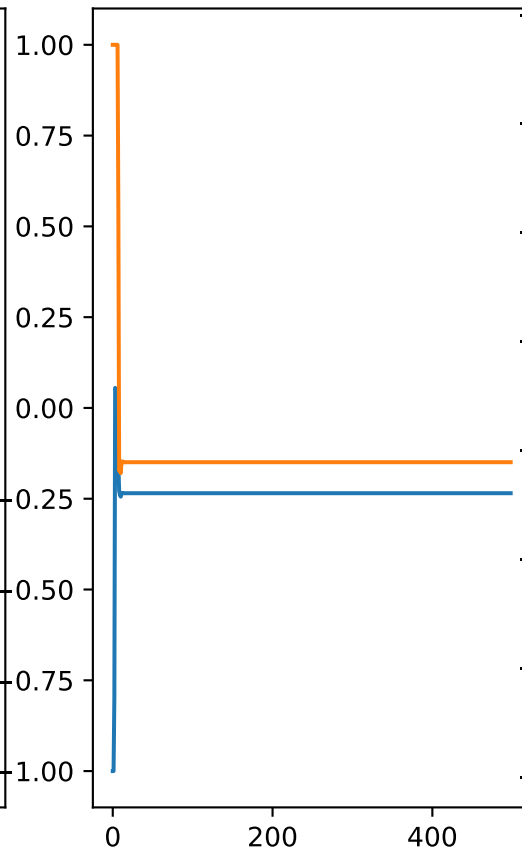


Reward: quartic_root
Speed = 89.37202953804687 [rad/s]

State vs step



Action vs step



Reward vs step

