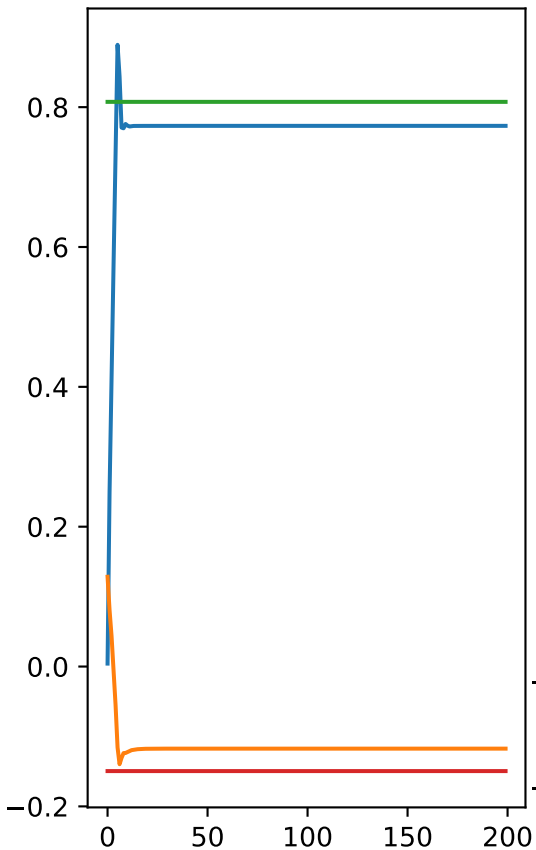
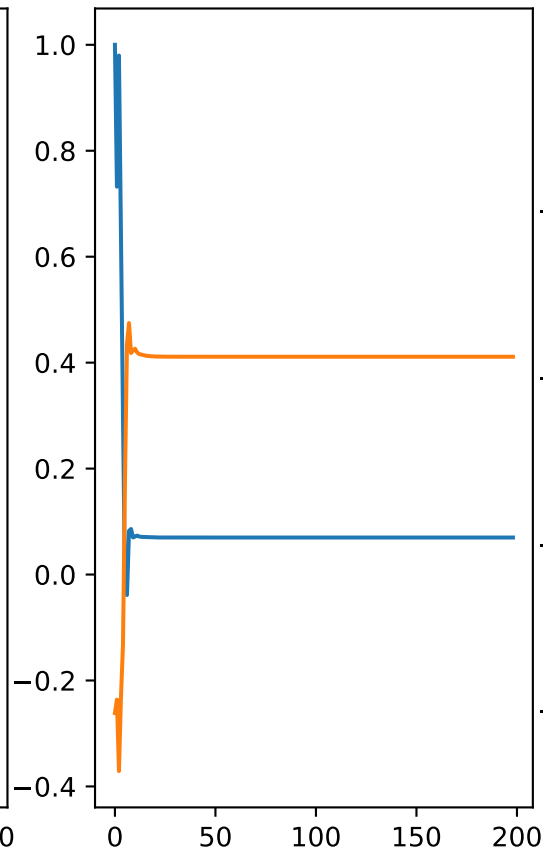


Reward: quadratic
Speed = 478.7709459407828 [rad/s]

State vs step



Action vs step



Reward vs step

