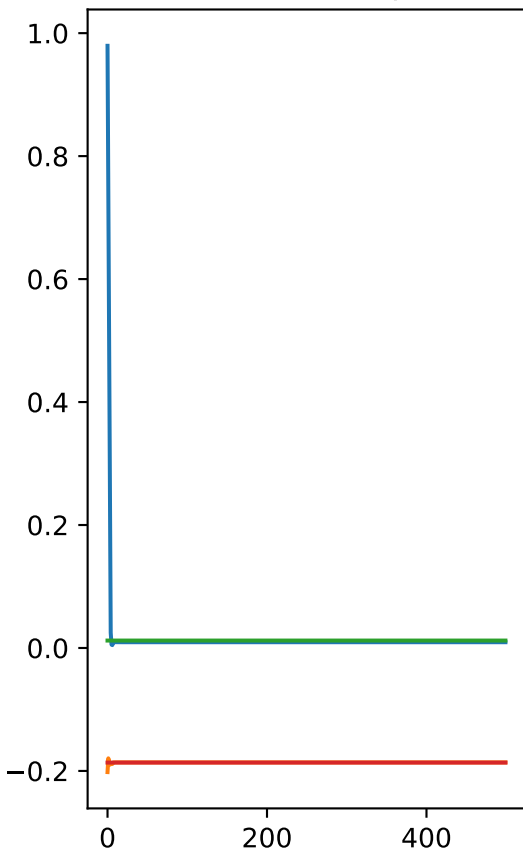
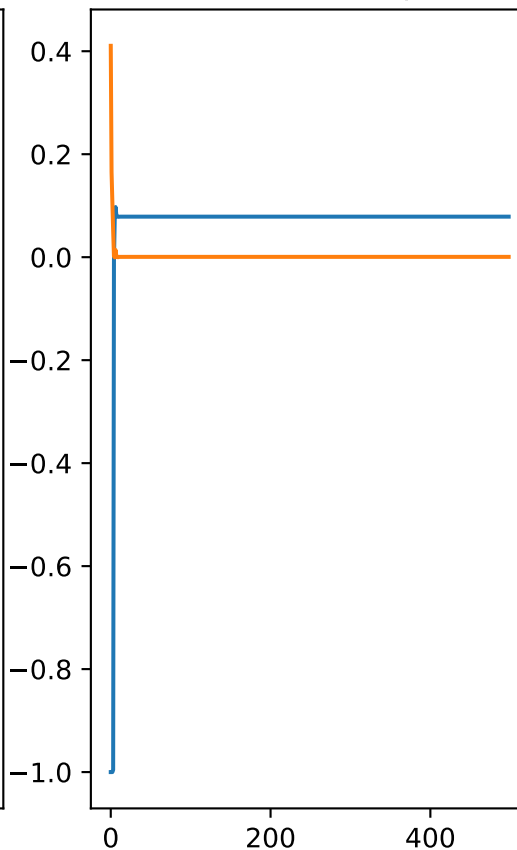


Reward: quartic_root
Speed = 232.99306868052278 [rad/s]

State vs step



Action vs step



Reward vs step

