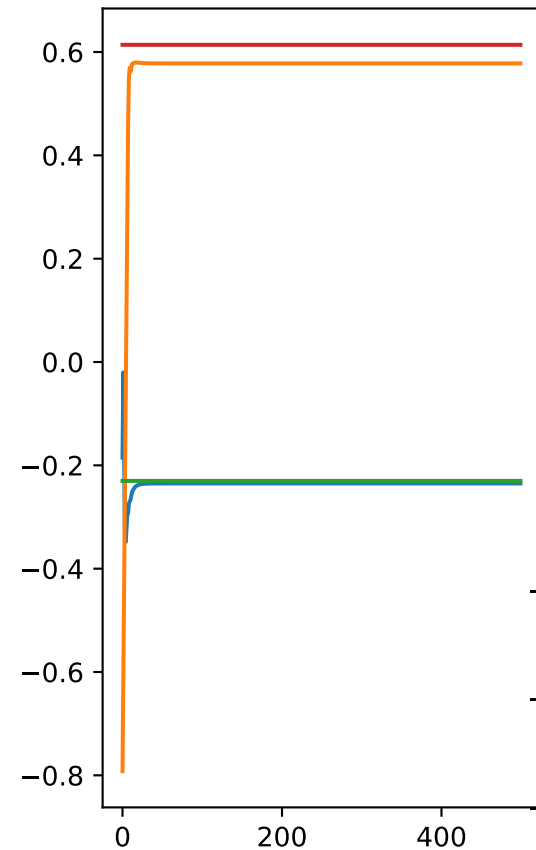
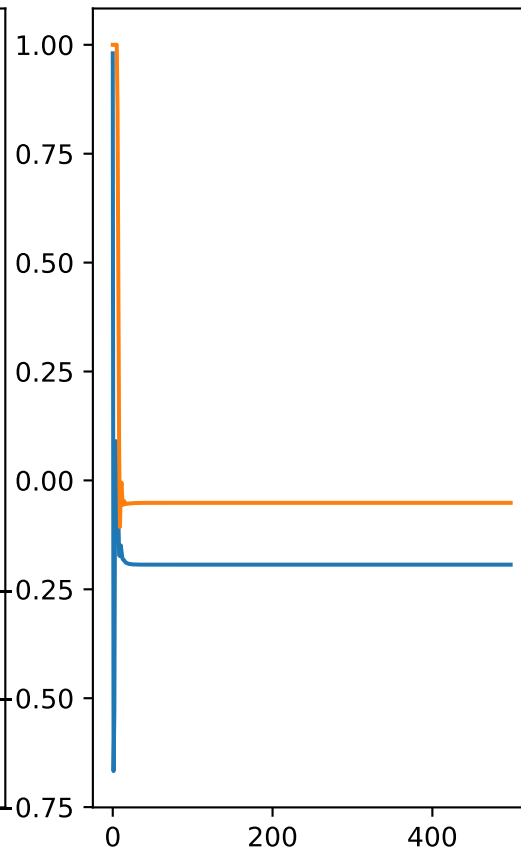


Reward: quadratic  
Speed = 391.7565973113235 [rad/s]

State vs step



Action vs step



Reward vs step

