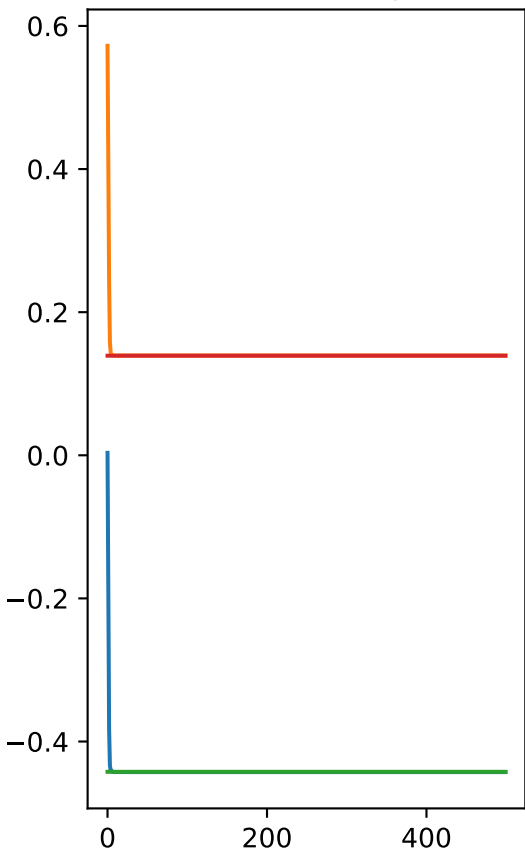
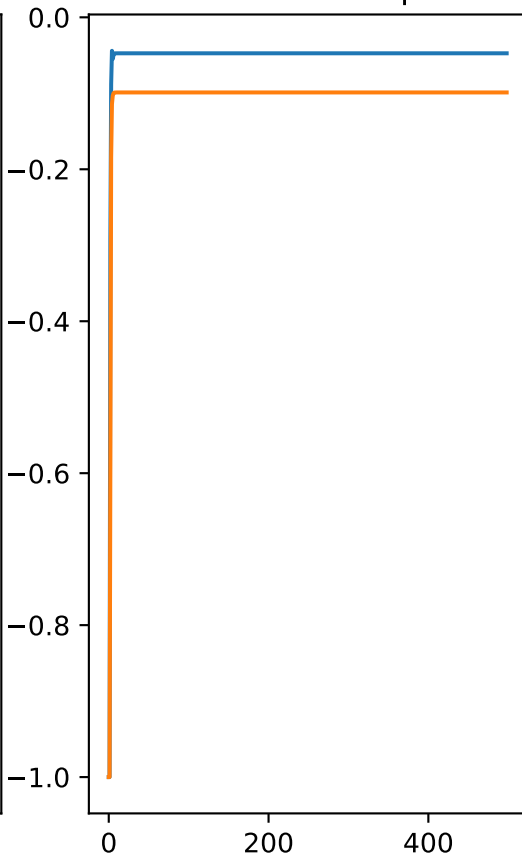


Reward: square\_root  
Speed = 406.15766587306223 [rad/s]

State vs step



Action vs step



Reward vs step

