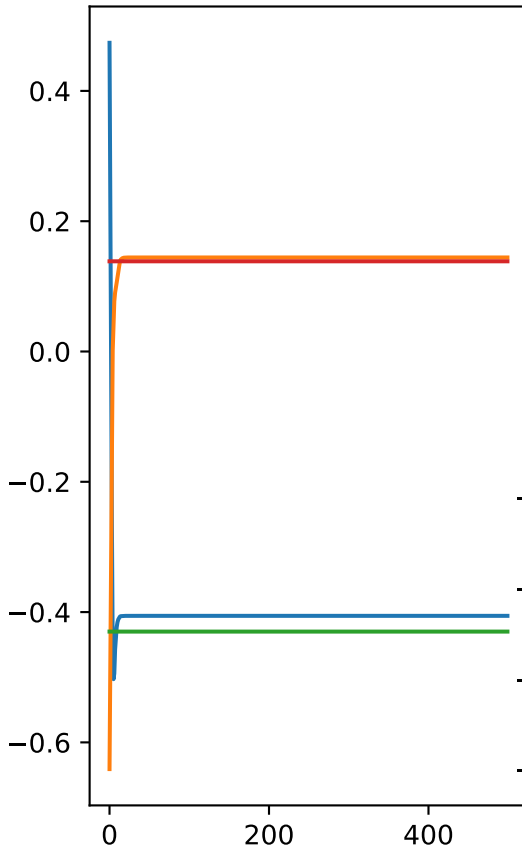
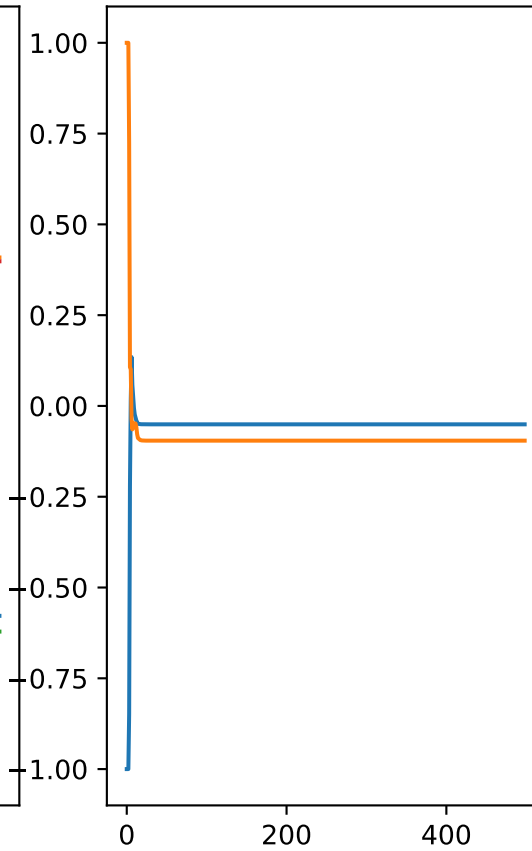


Reward: quadratic\_2  
Speed = 195.784053961992 [rad/s]

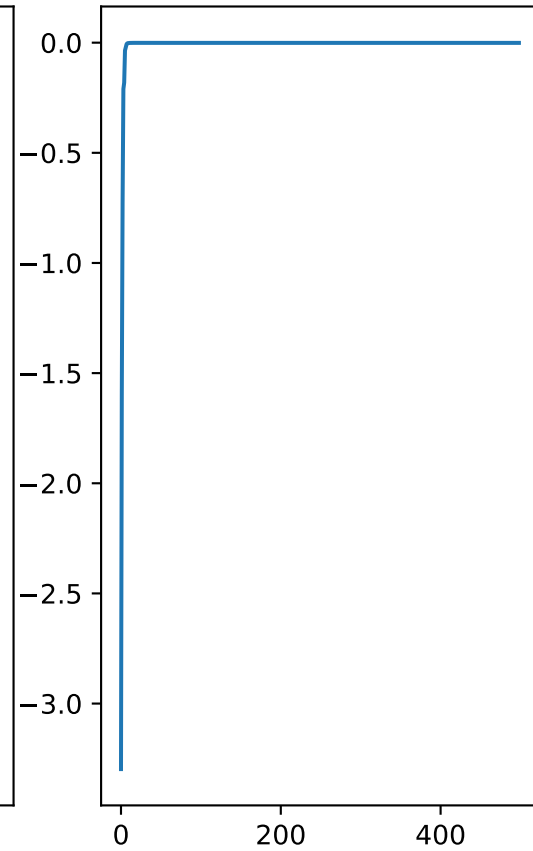
State vs step



Action vs step



Reward vs step



— Id — Idref  
— Iq — Iqref

— Vd — Vq