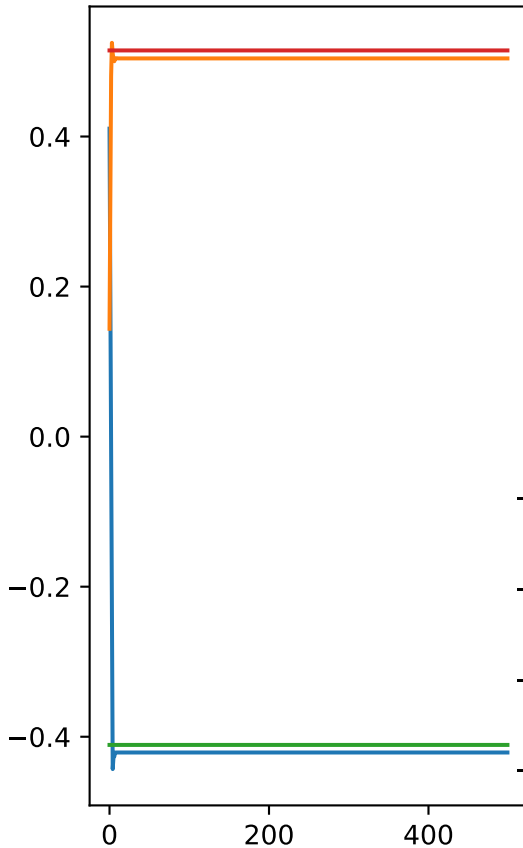
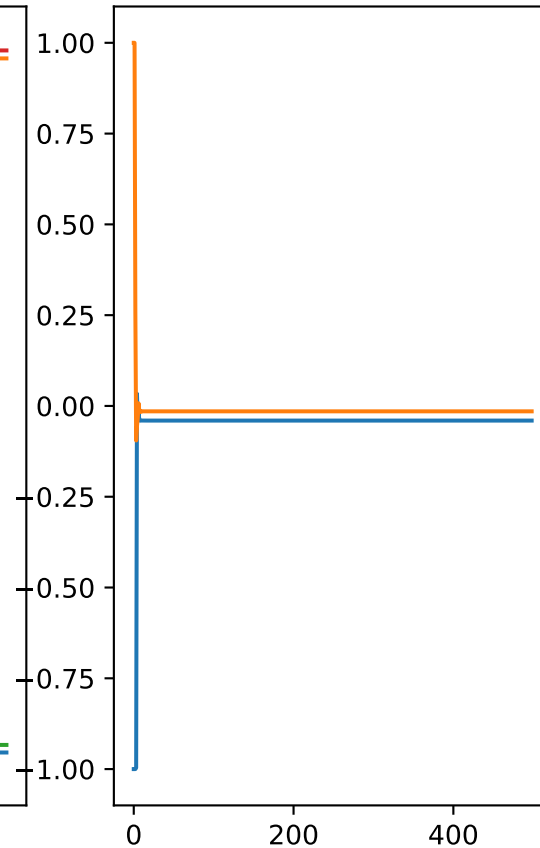


Reward: quartic\_root  
Speed = 620.9923493290972 [rad/s]

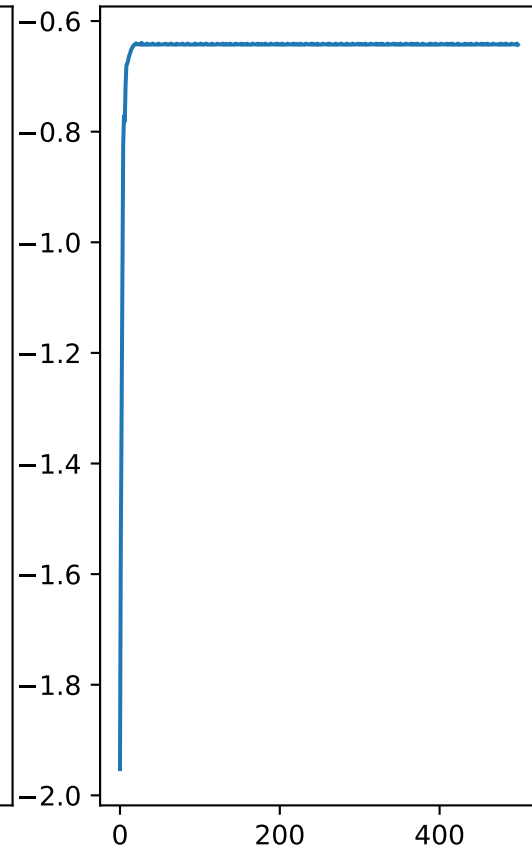
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq