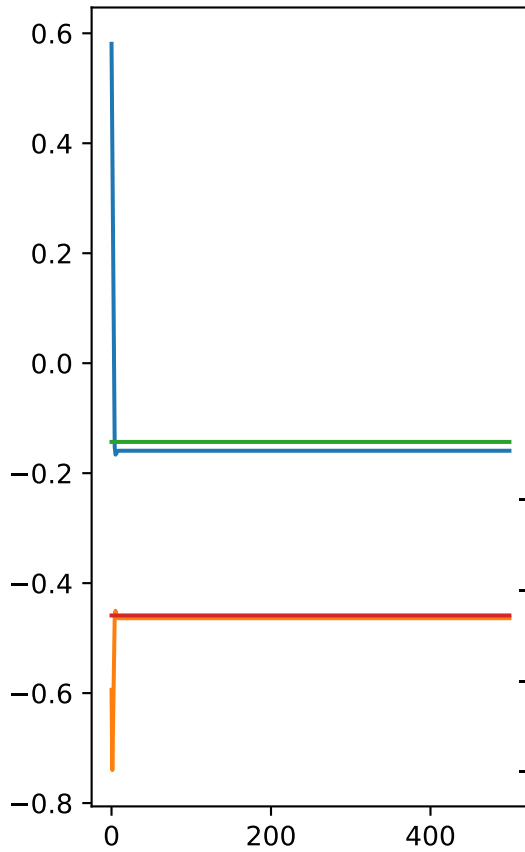
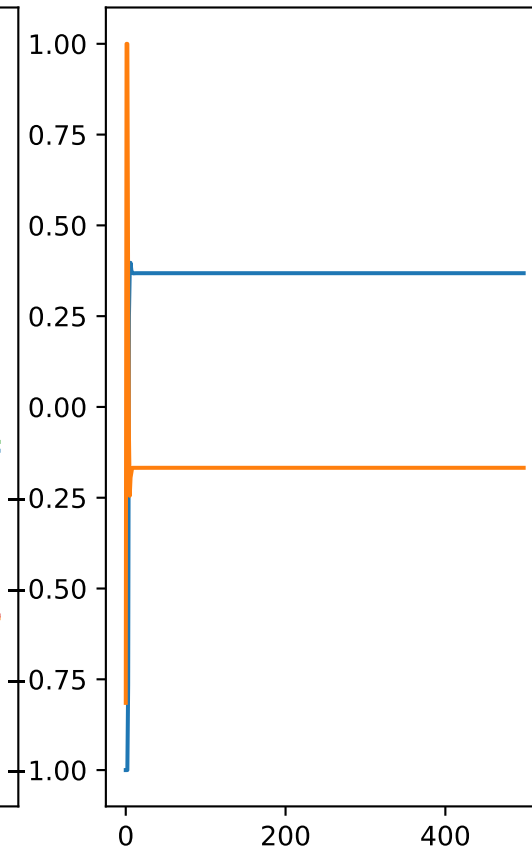


Reward: quartic_root_2
Speed = 165.13467964681377 [rad/s]

State vs step



Action vs step



Reward vs step

