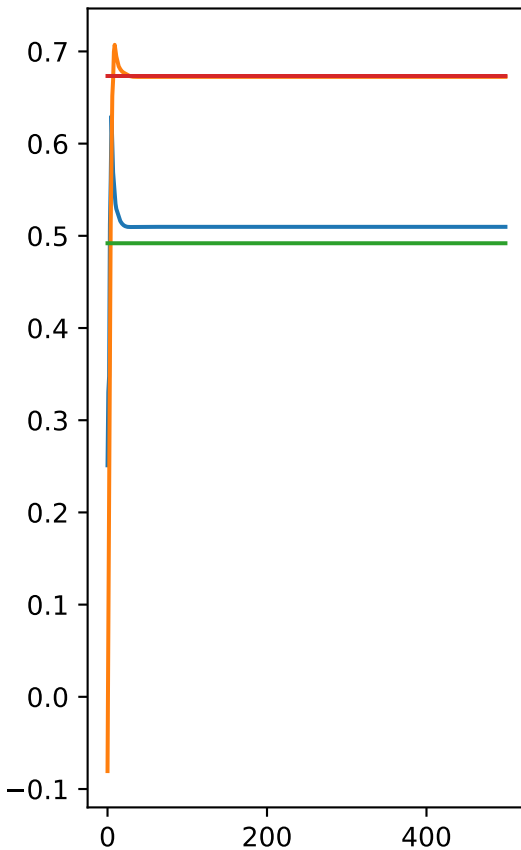
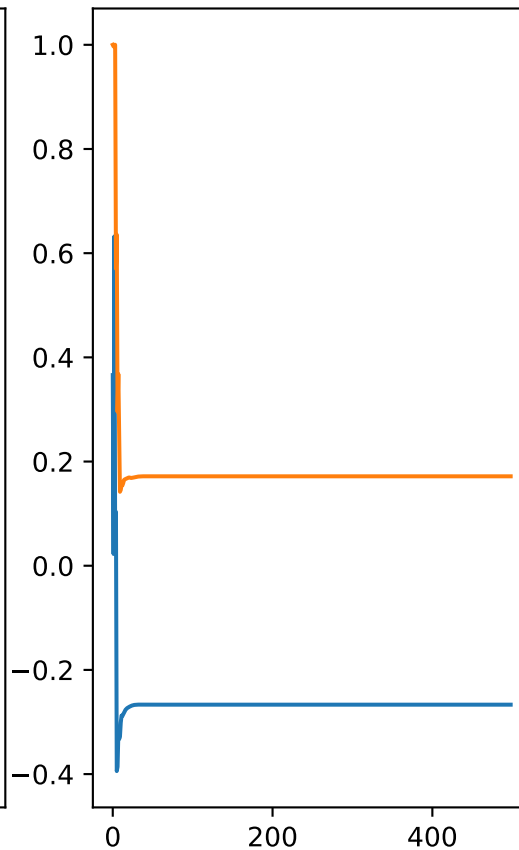


Reward: quadratic_2
Speed = 210.28564021012437 [rad/s]

State vs step



Action vs step



Reward vs step

