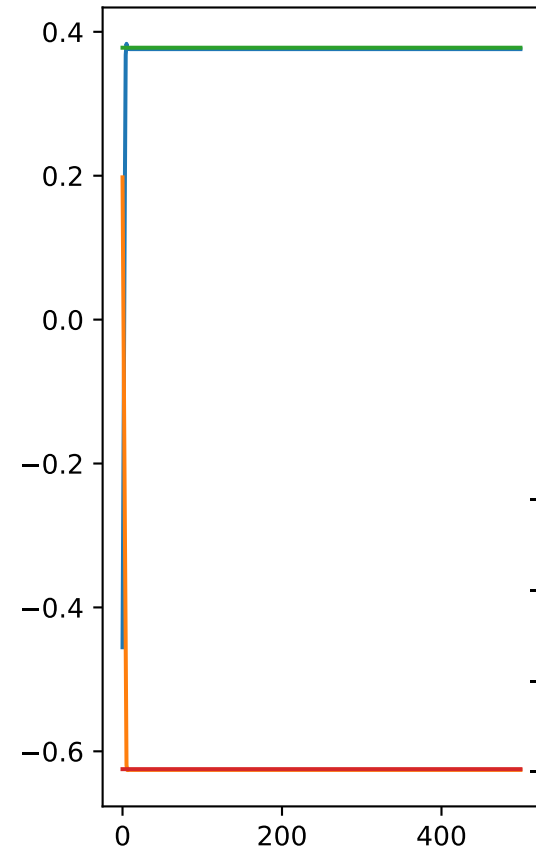
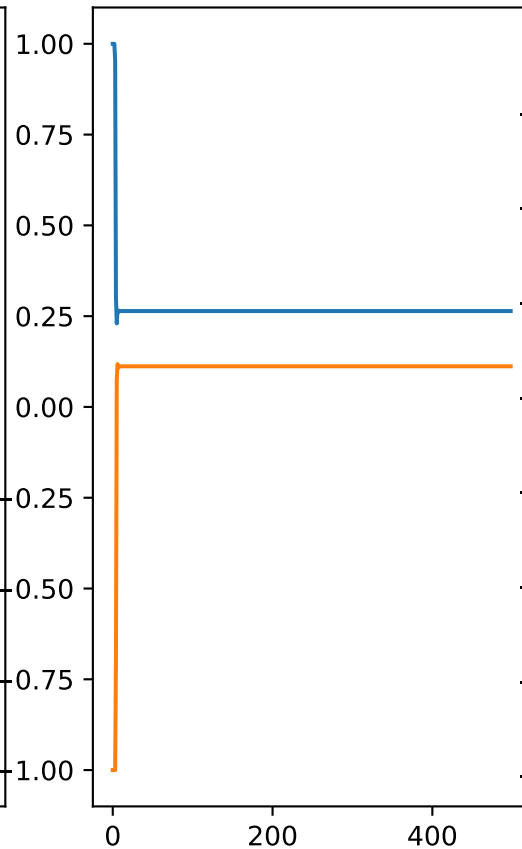


Reward: square_root
Speed = 854.5383027354881 [rad/s]

State vs step



Action vs step



Reward vs step

