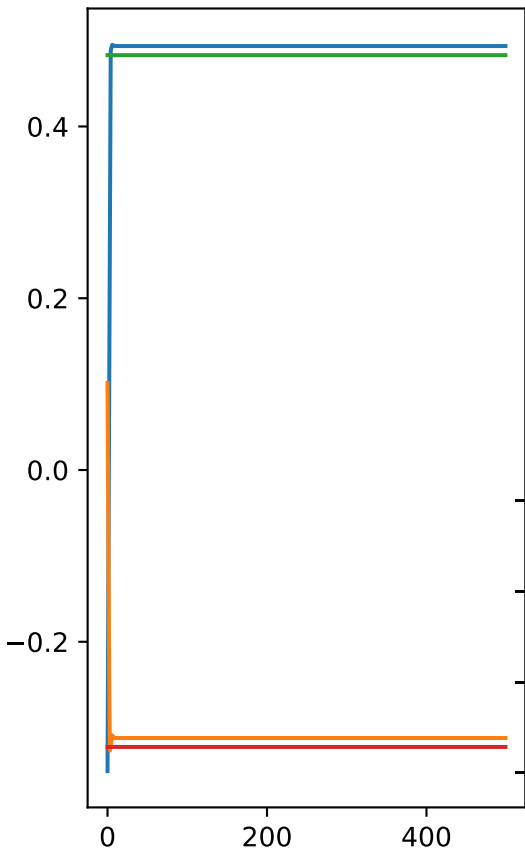
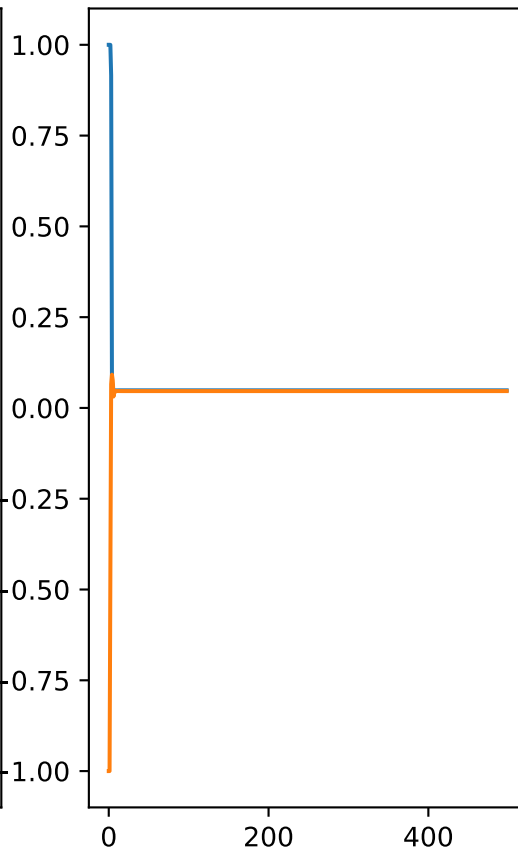


Reward: quartic\_root\_2  
Speed = 120.48636369152581 [rad/s]

State vs step



Action vs step



Reward vs step

