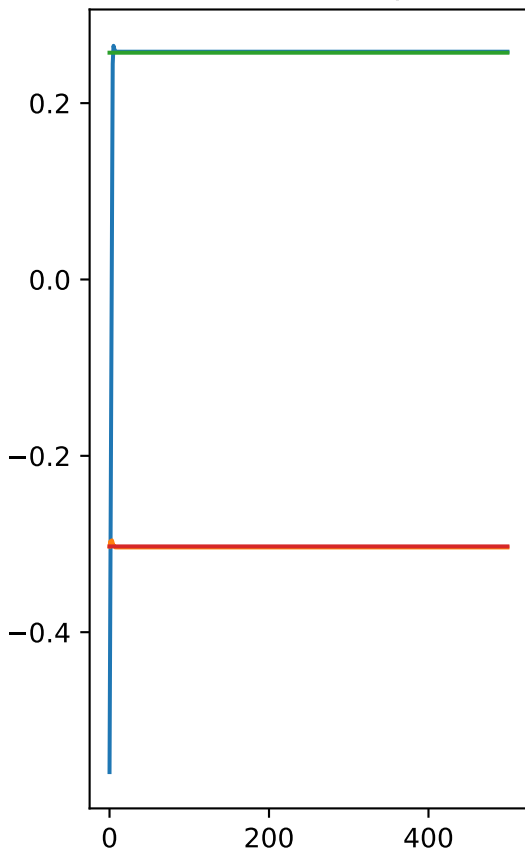
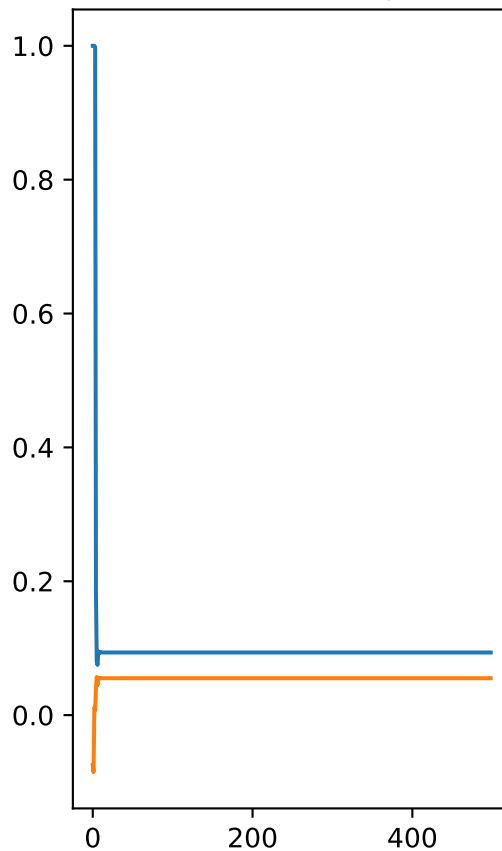


Reward: quartic_root
Speed = 1125.5572795900043 [rad/s]

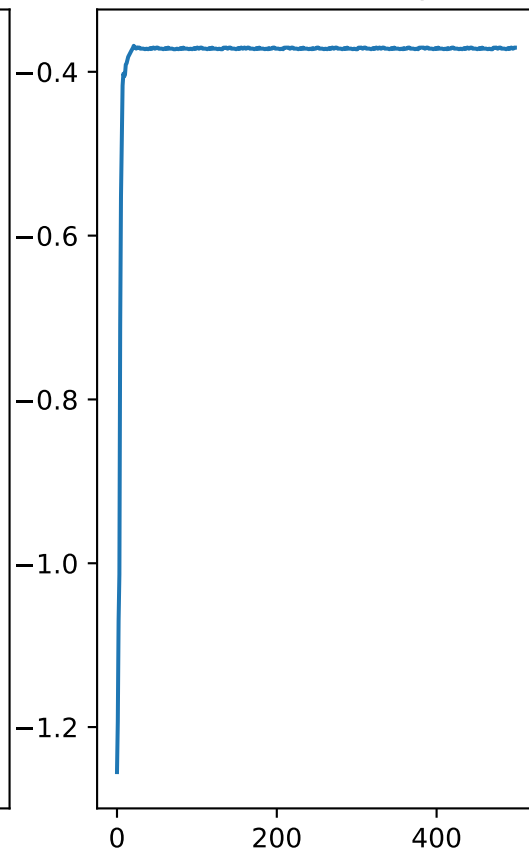
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq