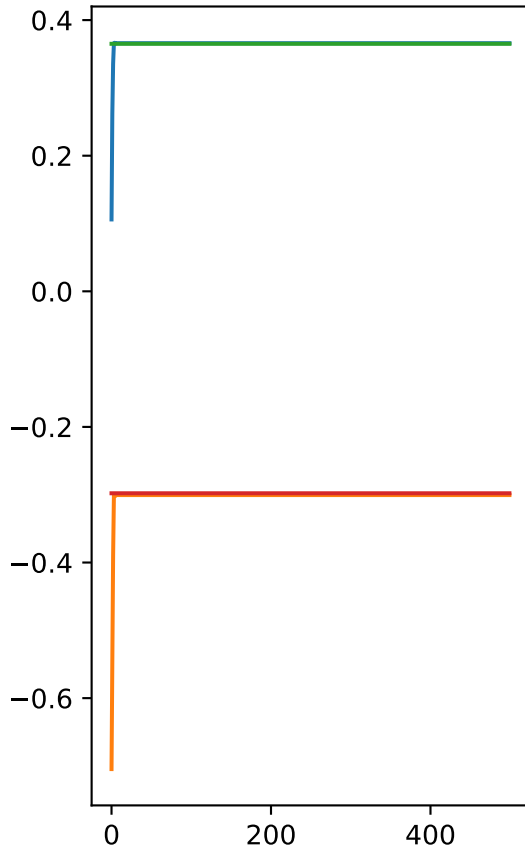
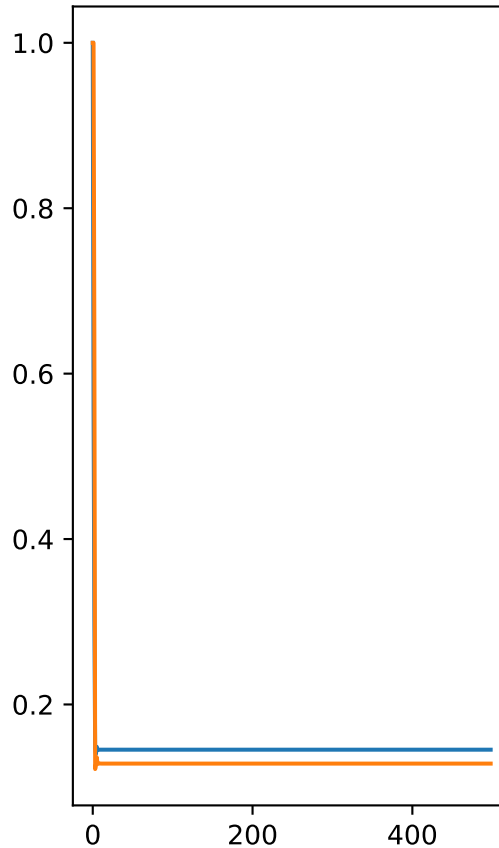


Reward: square_root
Speed = 509.05111250211894 [rad/s]

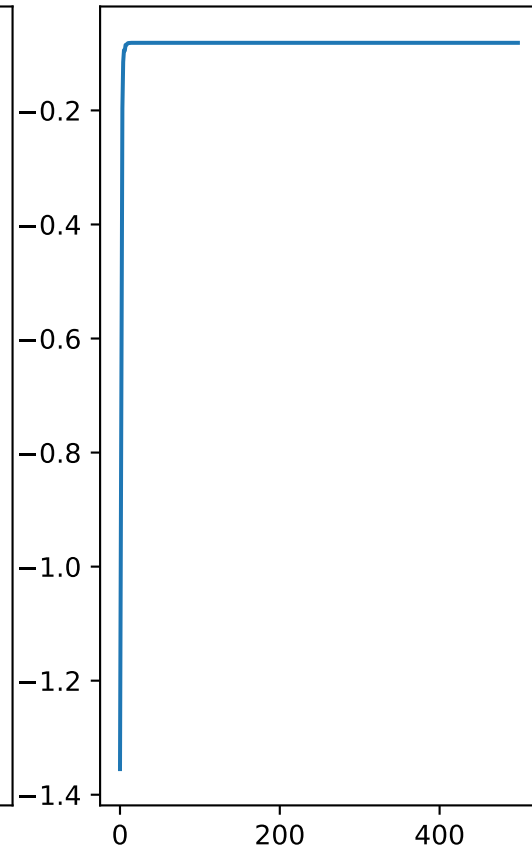
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq