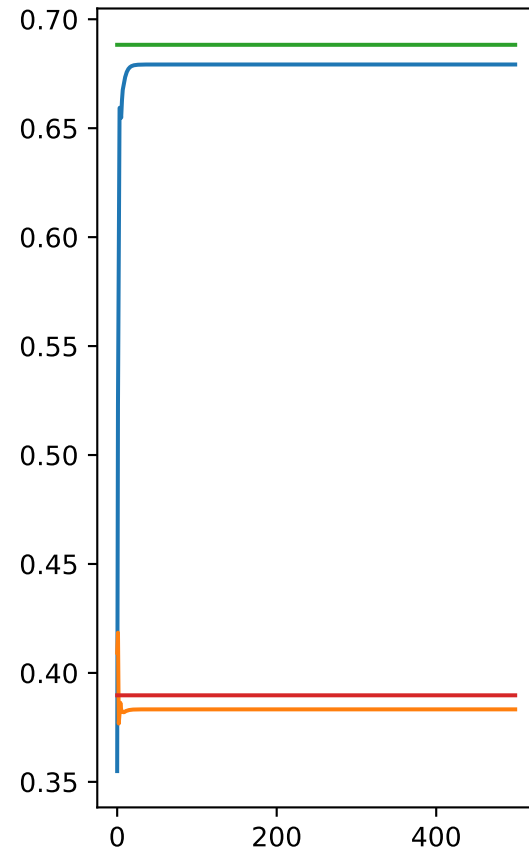
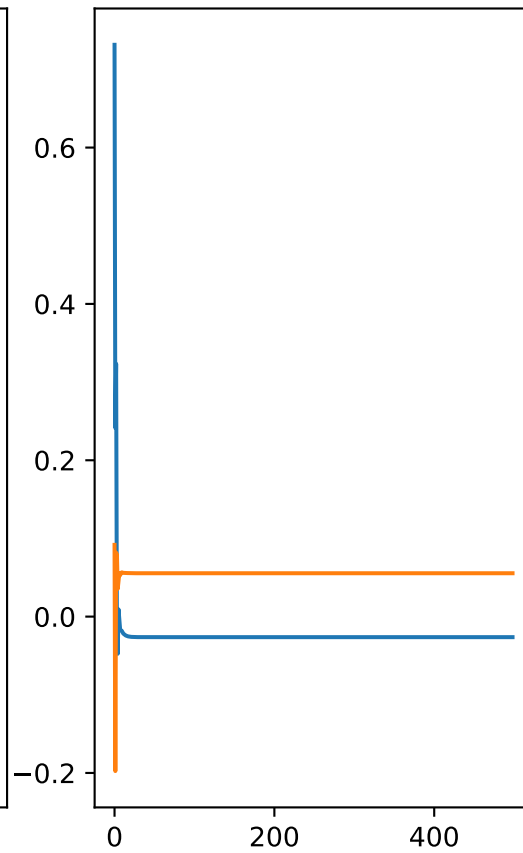


Reward: quadratic_2
Speed = 689.7680933286084 [rad/s]

State vs step



Action vs step



Reward vs step

