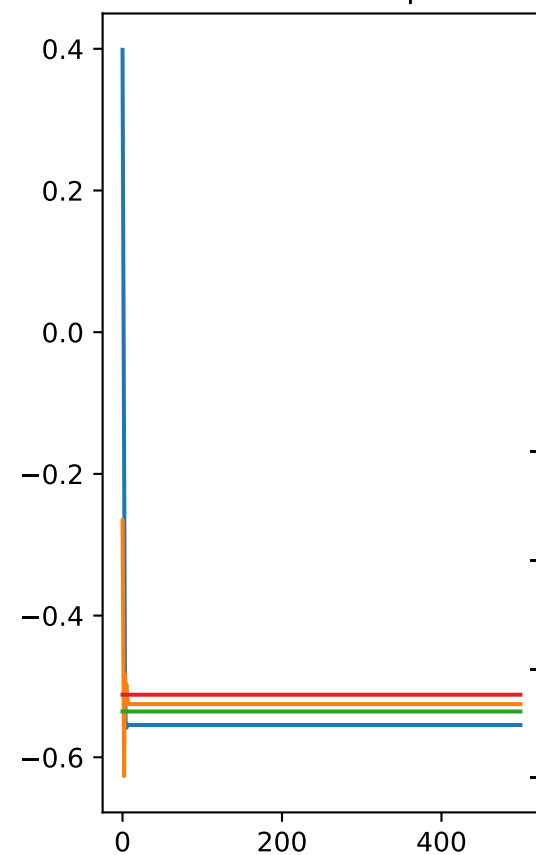
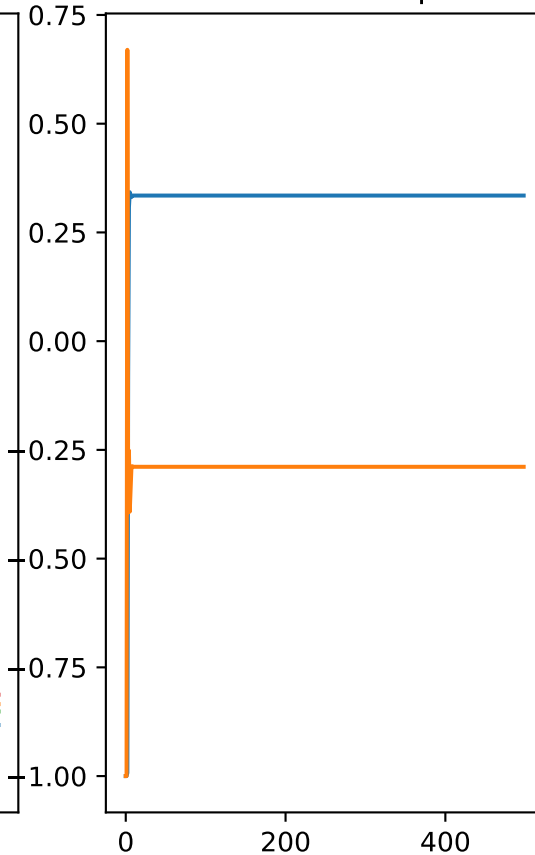


Reward: quartic\_root\_2  
Speed = 747.5734029483506 [rad/s]

State vs step



Action vs step



Reward vs step

