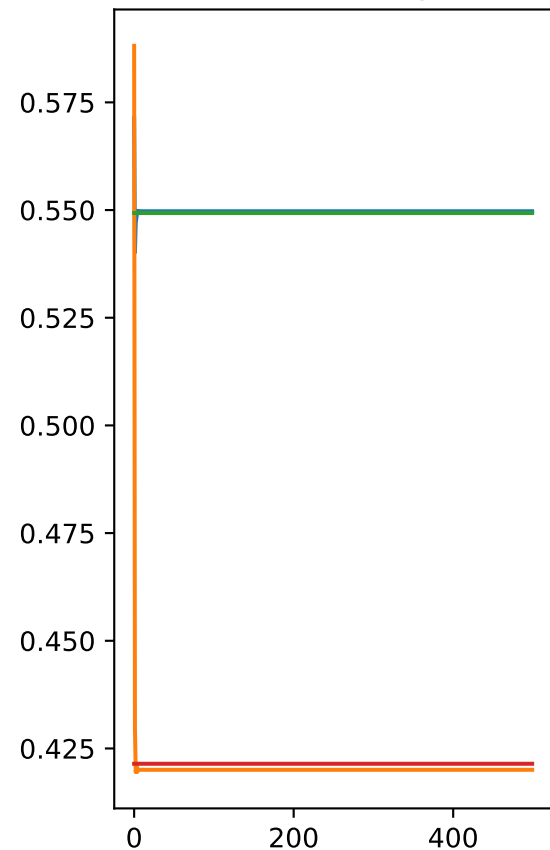
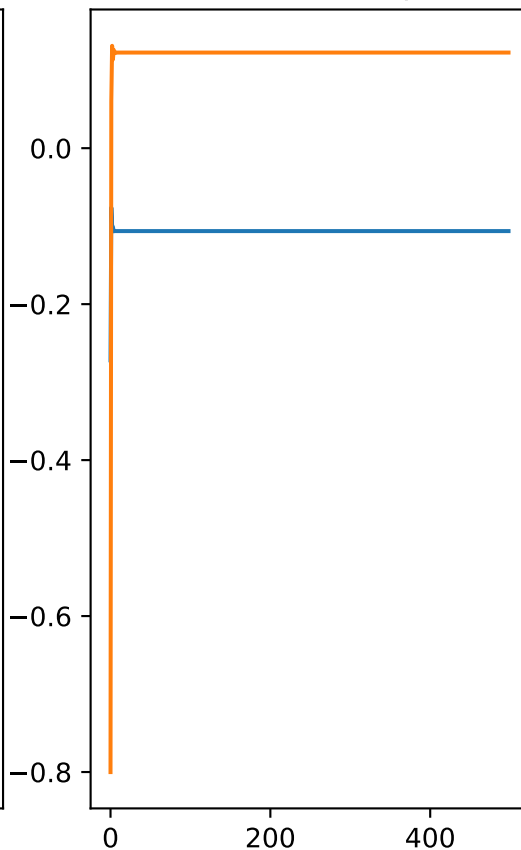


Reward: quartic\_root  
Speed = 907.8951429717675 [rad/s]

State vs step



Action vs step



Reward vs step

