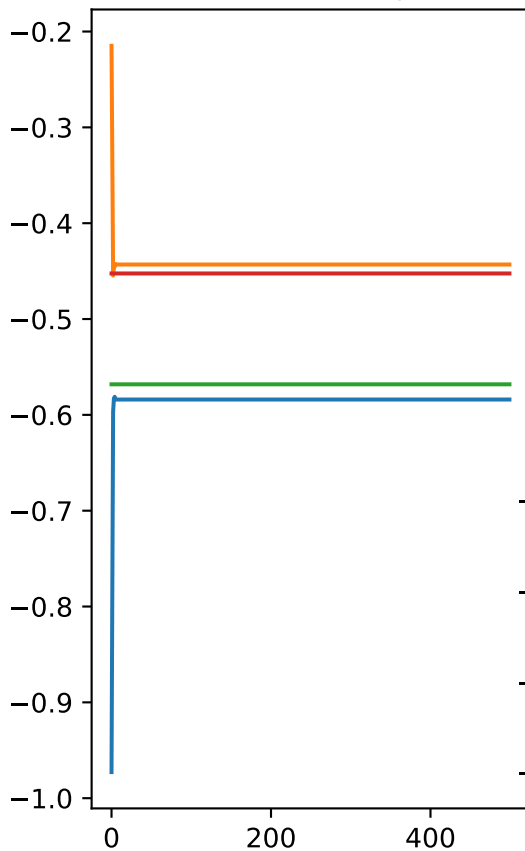
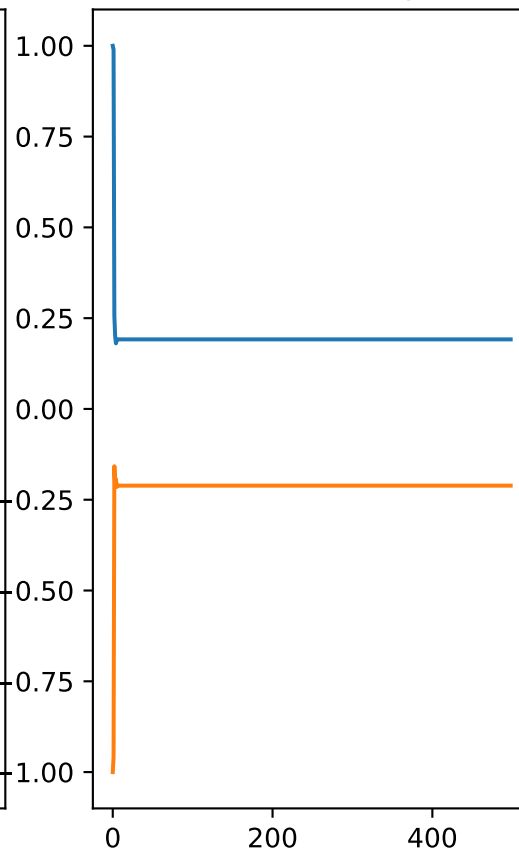


Reward: quartic_root
Speed = 918.4634317045562 [rad/s]

State vs step



Action vs step



Reward vs step

