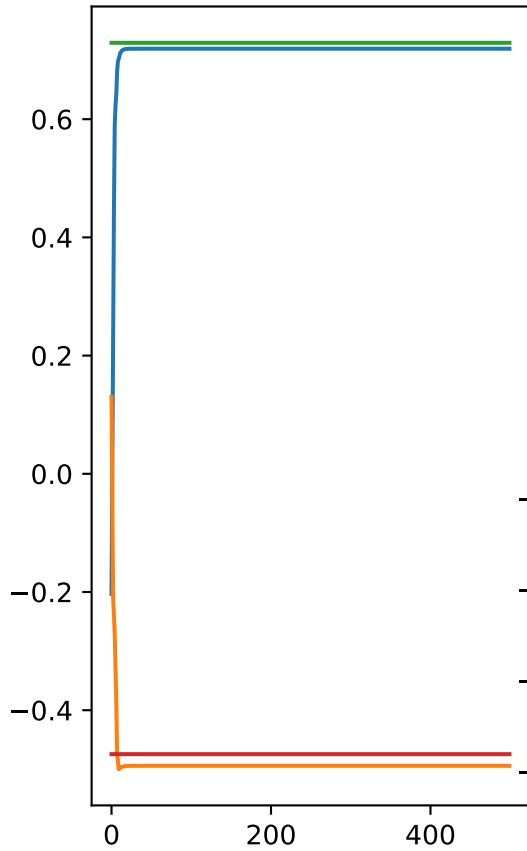


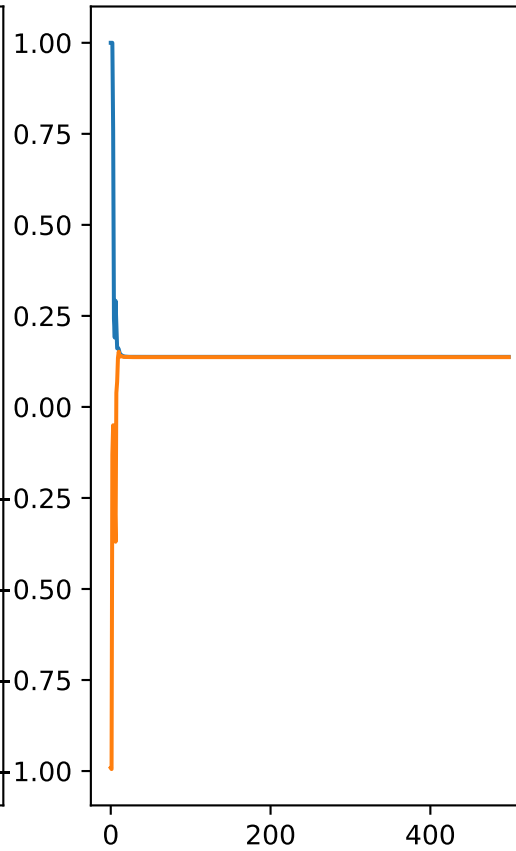
Reward: quadratic_2
Speed = 906.0855999124643 [rad/s]

State vs step



— Id — Idref
— Iq — Iqref

Action vs step



— Vd — Vq

Reward vs step

