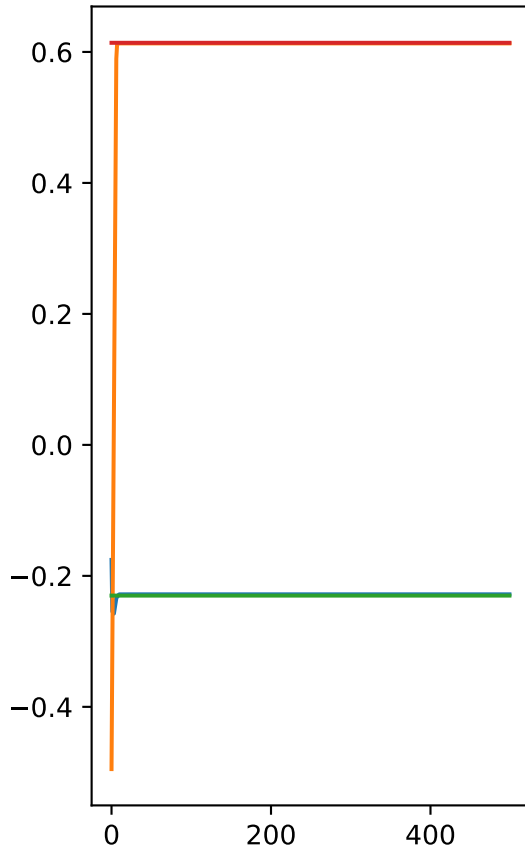
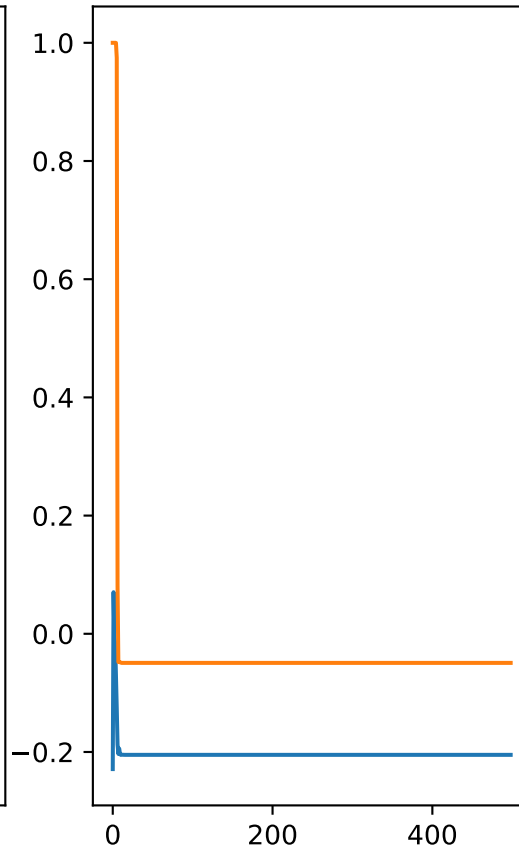


Reward: square_root
Speed = 391.7565973113235 [rad/s]

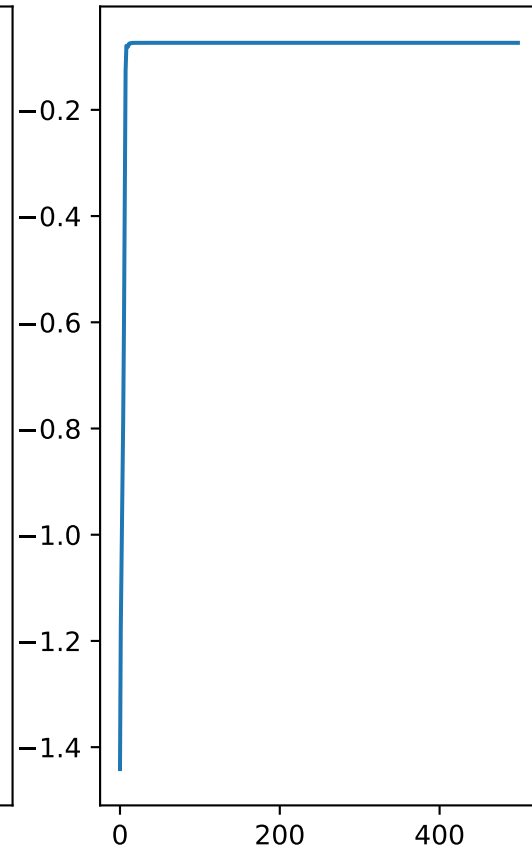
State vs step



Action vs step



Reward vs step



Id Iqref
Iq Iqref

Vd Vq