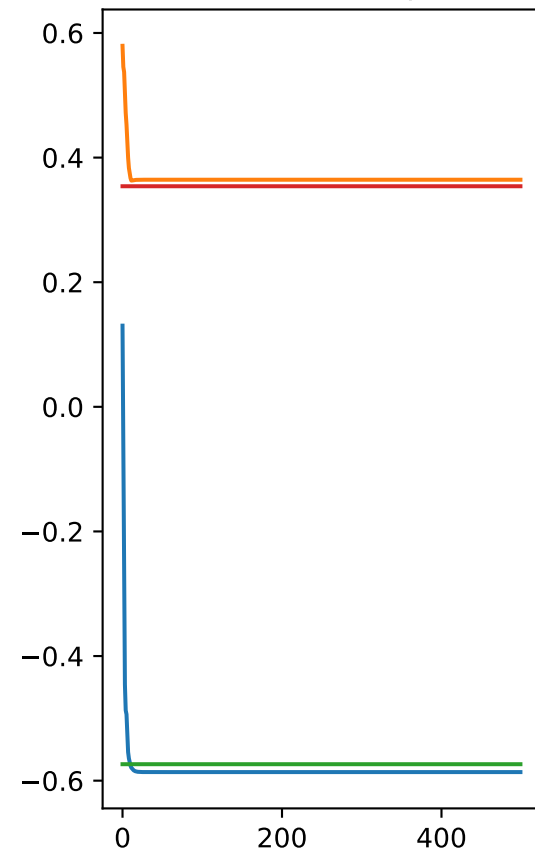
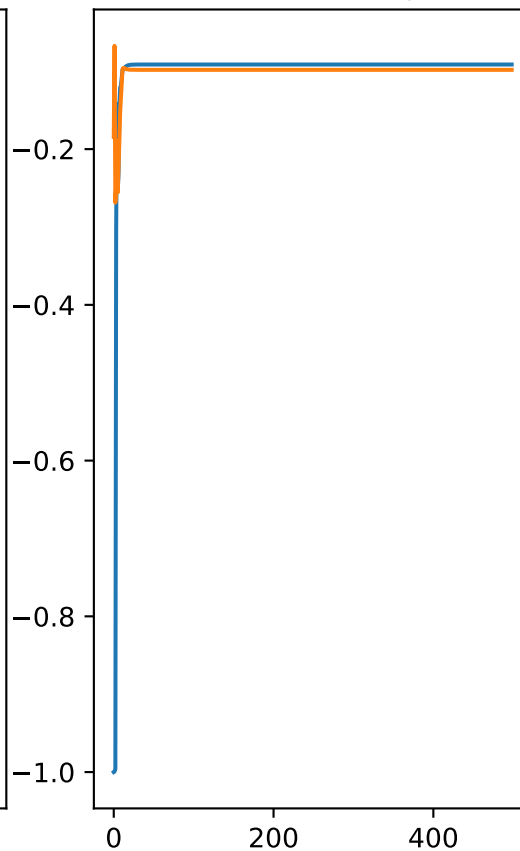


Reward: quadratic_2
Speed = 866.7905248702906 [rad/s]

State vs step



Action vs step



Reward vs step

