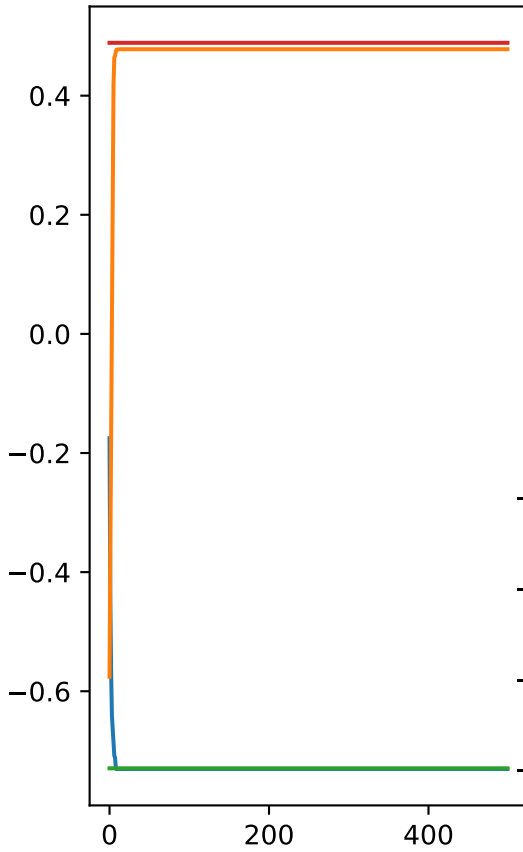
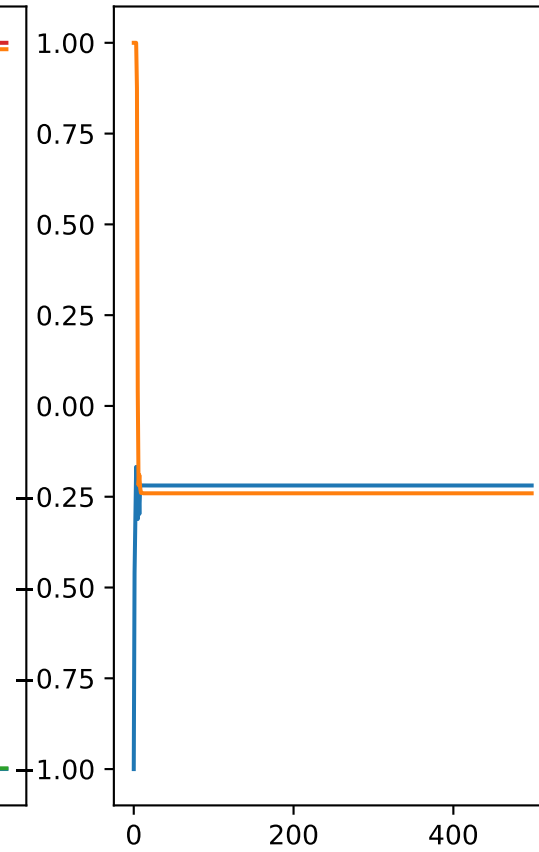


Reward: square\_root\_2  
Speed = 735.1578208478069 [rad/s]

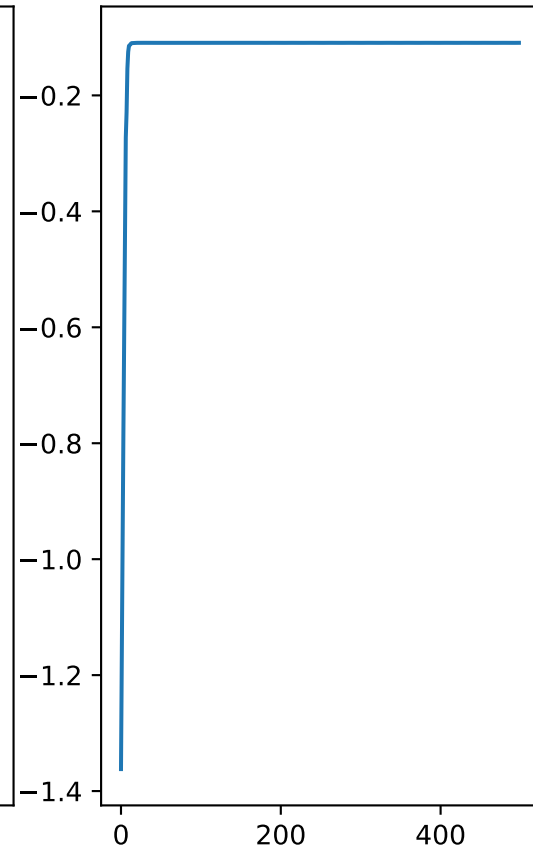
State vs step



Action vs step



Reward vs step



Id Iqref  
Iq Iqref

Vd Vq