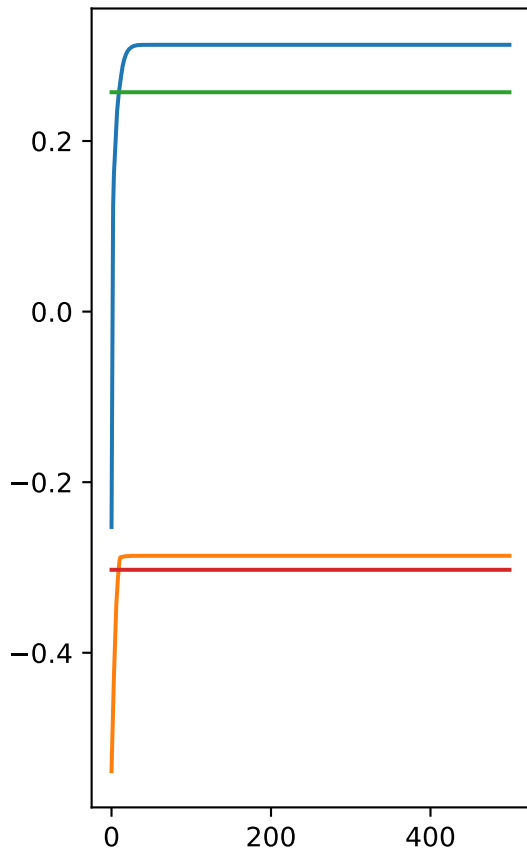


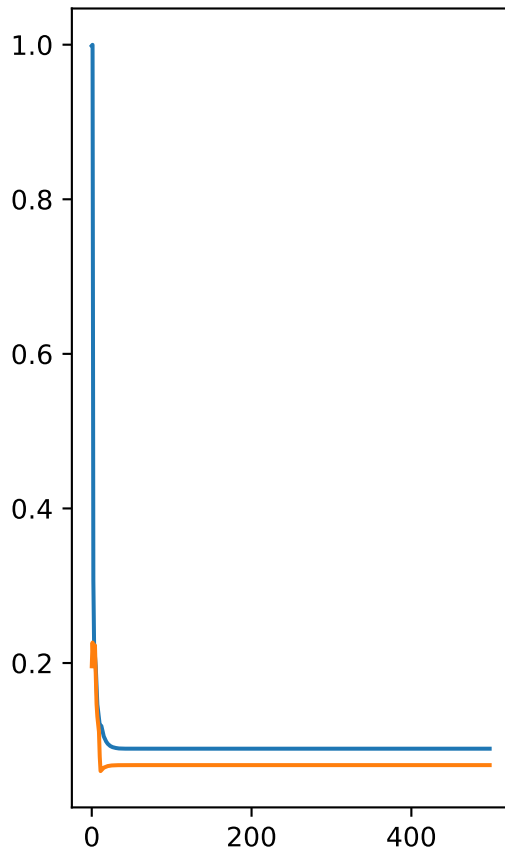
Reward: quadratic\_2  
Speed = 1125.5572795900043 [rad/s]

State vs step



— Id — Idref  
— Iq — Iqref

Action vs step



— Vd — Vq

Reward vs step

