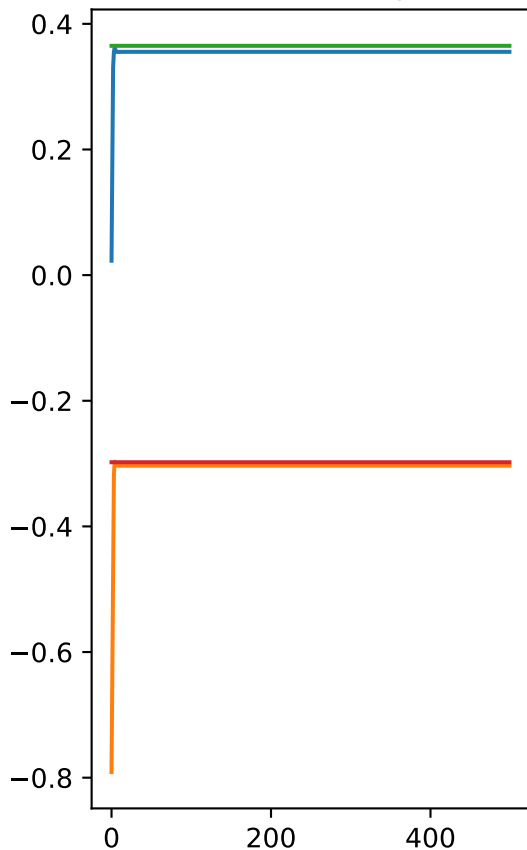
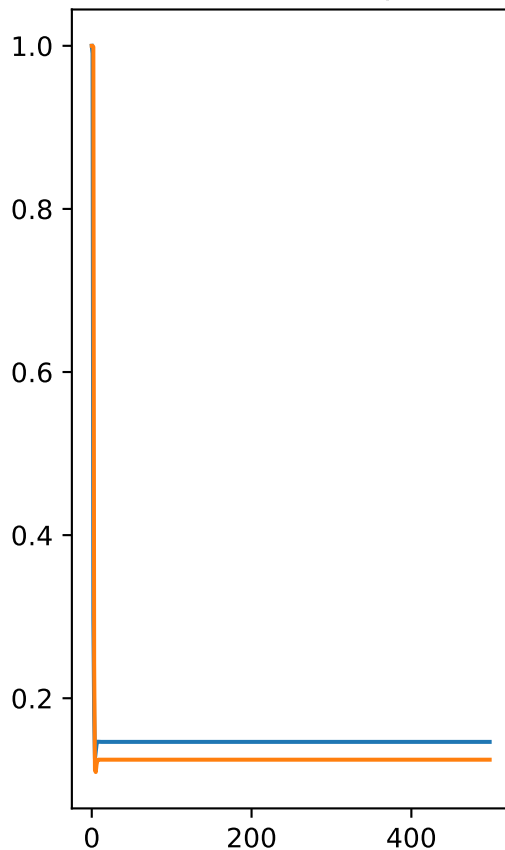


Reward: quartic\_root\_2  
Speed = 509.05111250211894 [rad/s]

State vs step



Action vs step



Reward vs step

