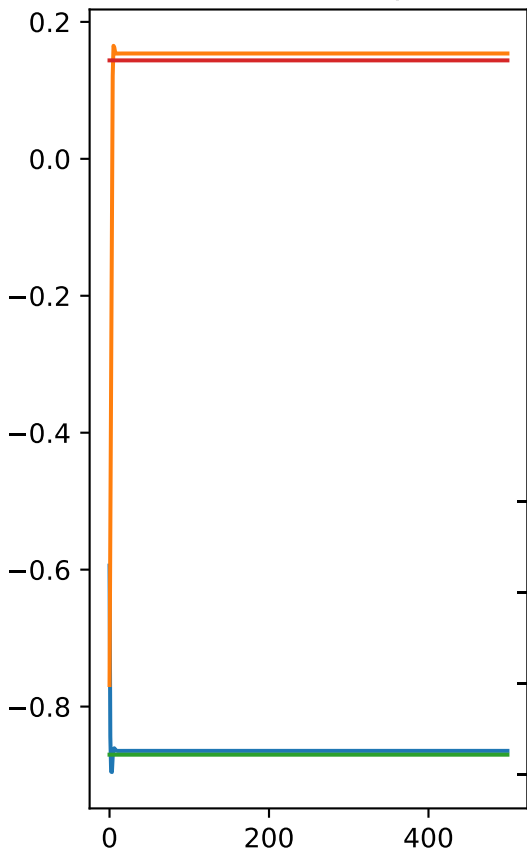
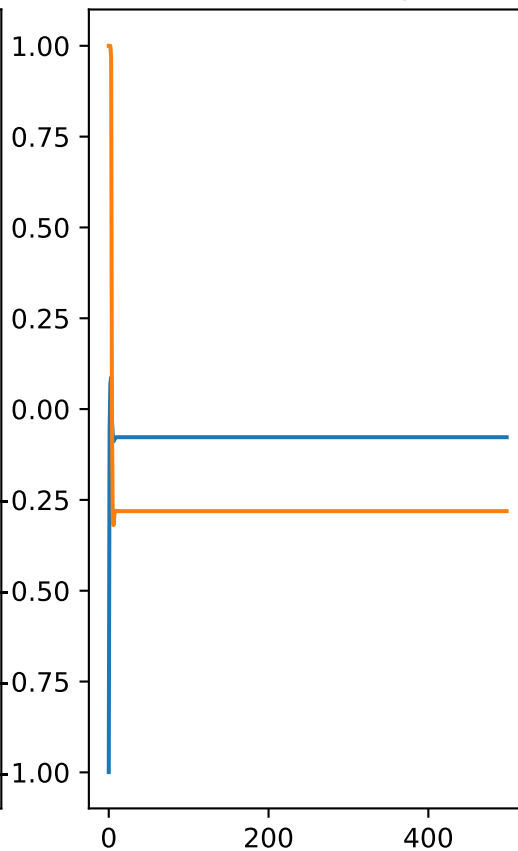


Reward: quartic_root
Speed = 1032.3021832917834 [rad/s]

State vs step



Action vs step



Reward vs step

