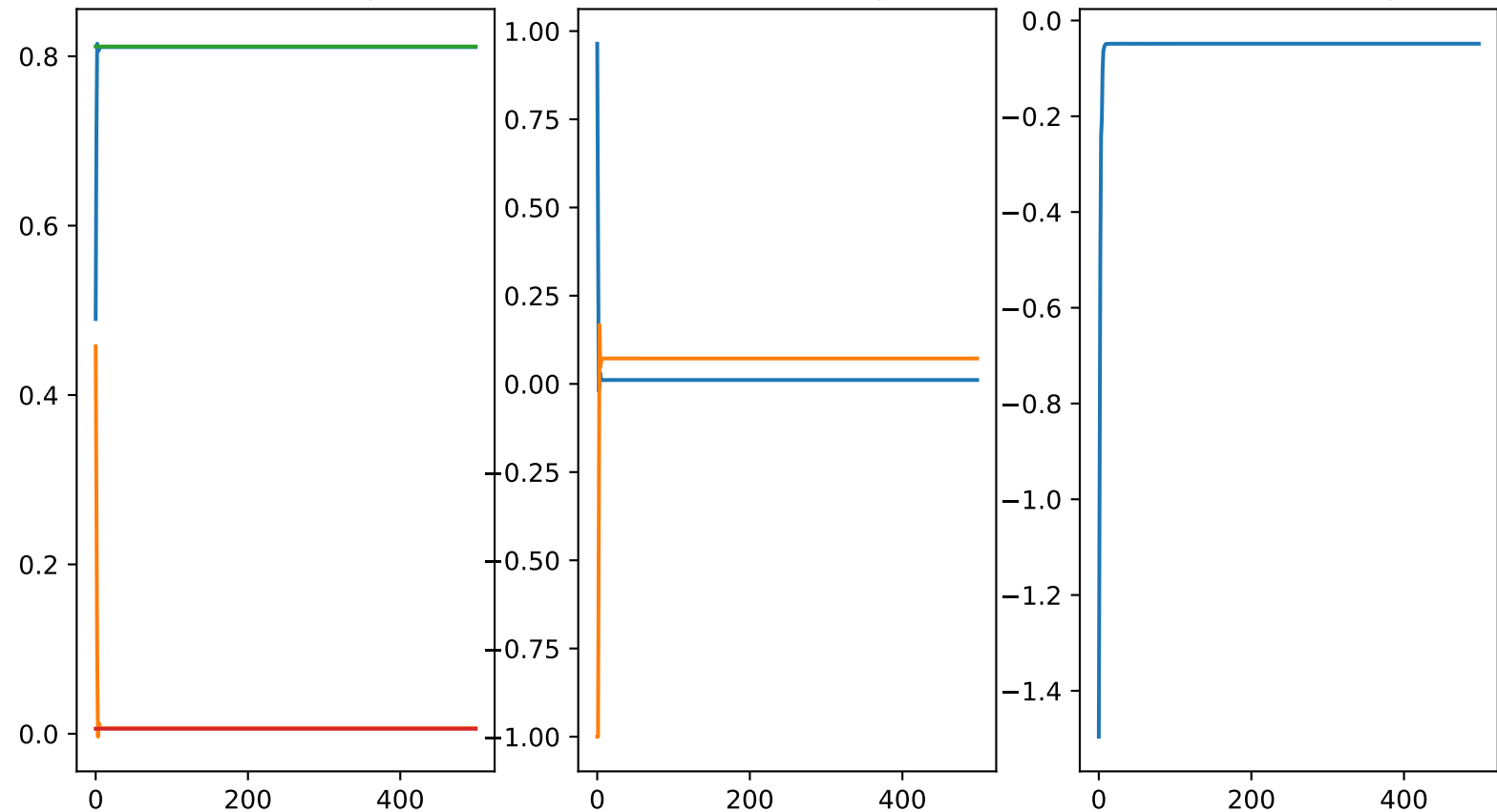


Reward: square\_root  
Speed = 676.6990713651 [rad/s]

State vs step

Action vs step

Reward vs step



$I_d$   $I_{dref}$   
 $I_q$   $I_{qref}$

$V_d$   $V_q$