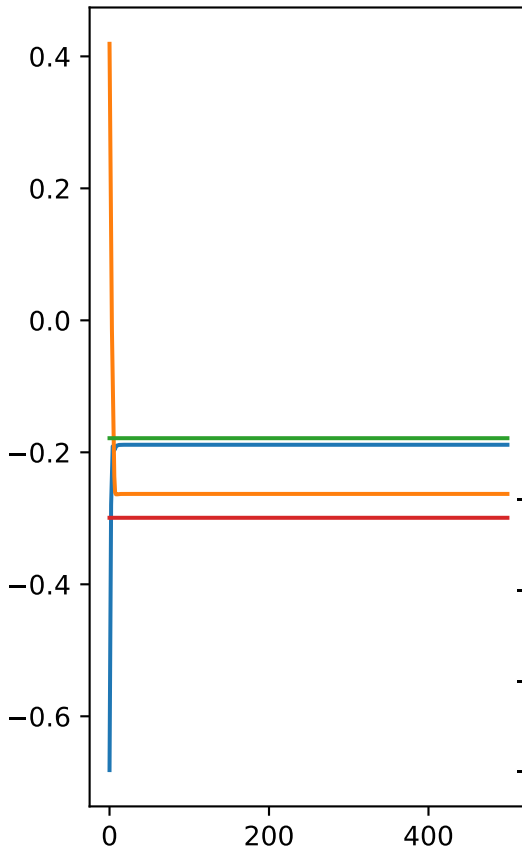
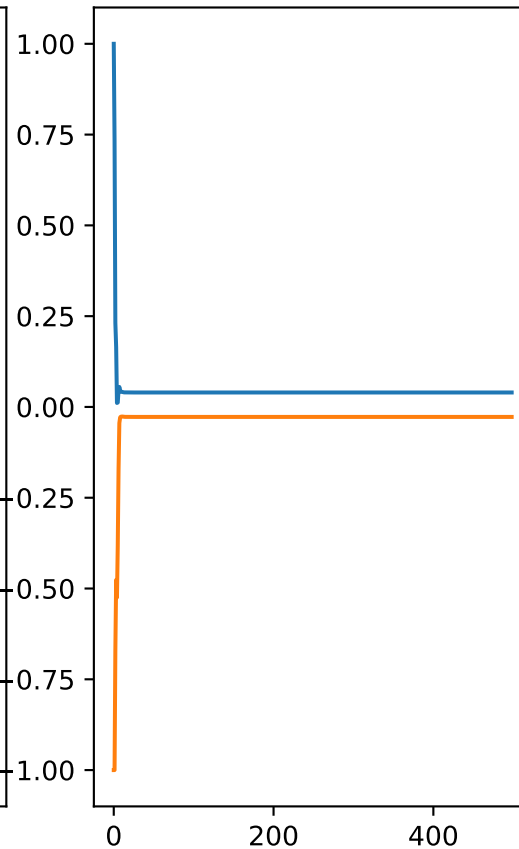


Reward: quadratic_2
Speed = 945.8832633866064 [rad/s]

State vs step



Action vs step



Reward vs step

