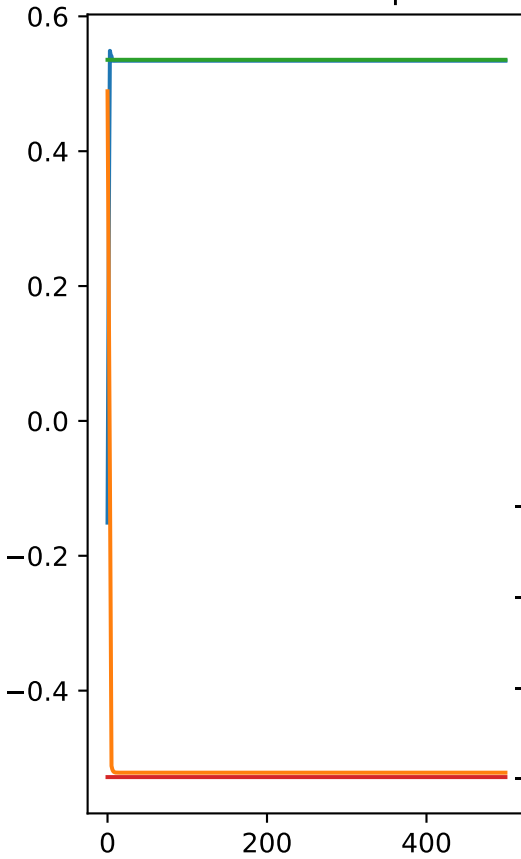
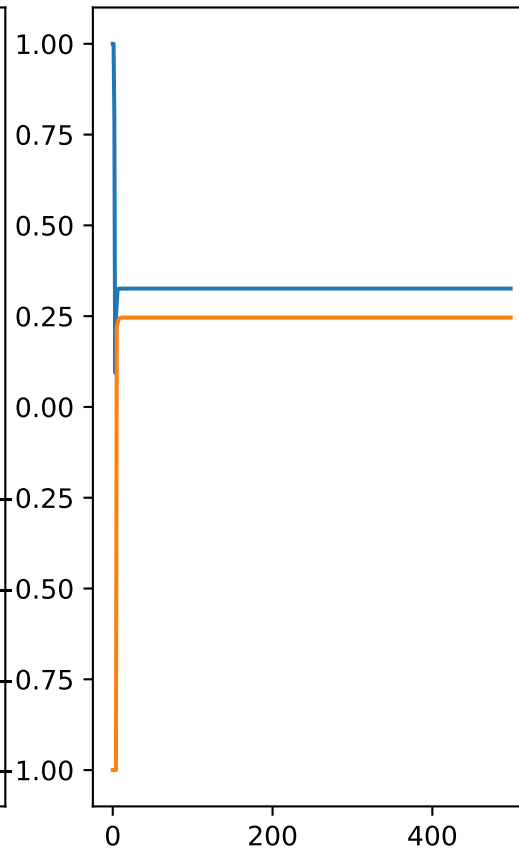


Reward: square_root
Speed = 652.7224573011702 [rad/s]

State vs step



Action vs step



Reward vs step

