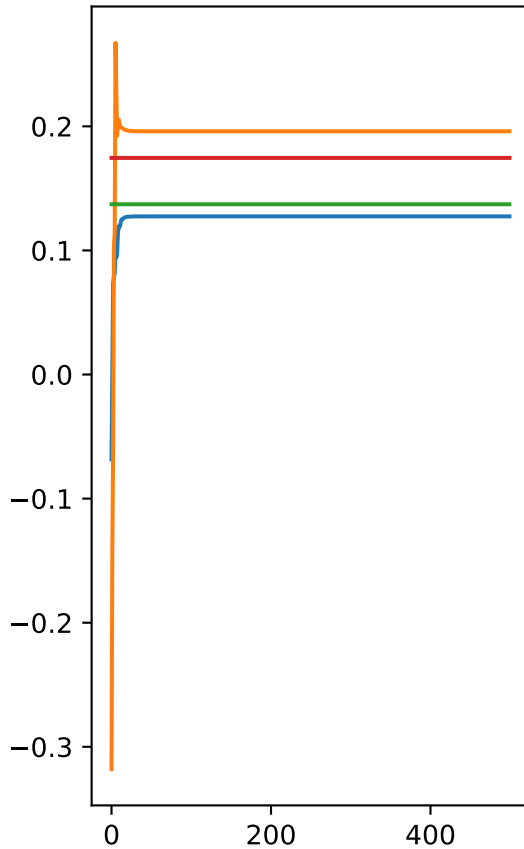
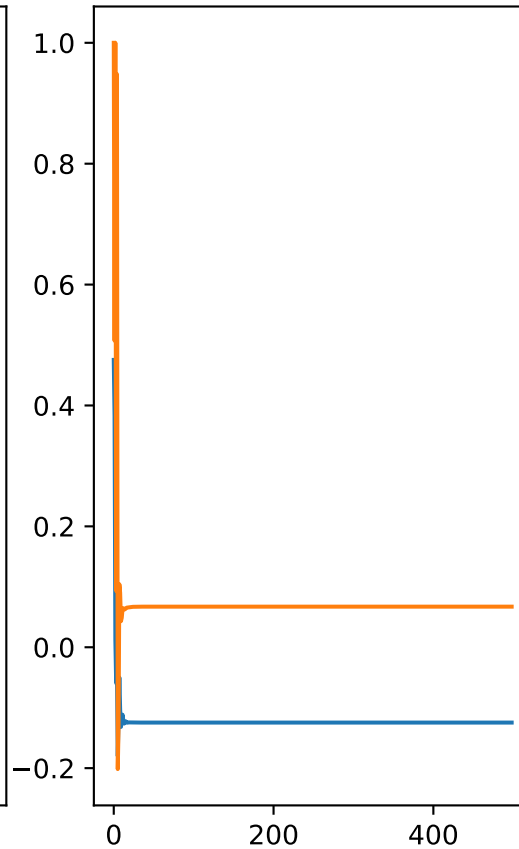


Reward: quadratic_2
Speed = 269.1088224820624 [rad/s]

State vs step



Action vs step



Reward vs step

