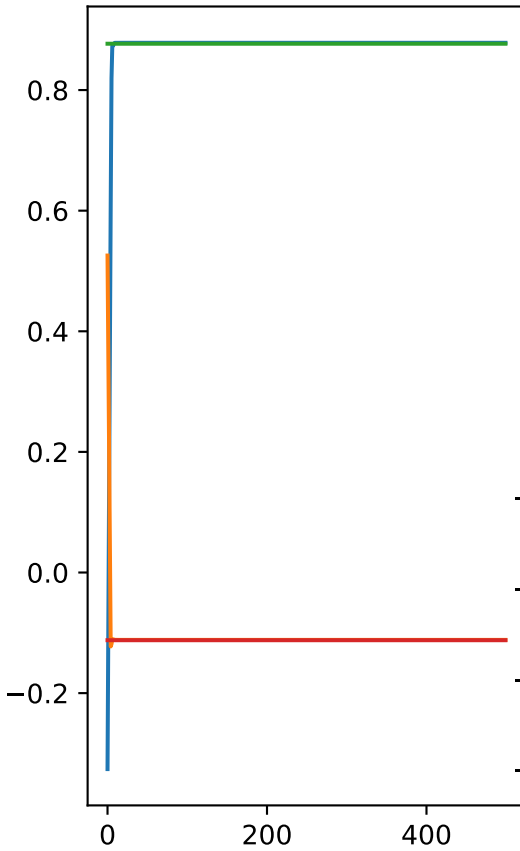
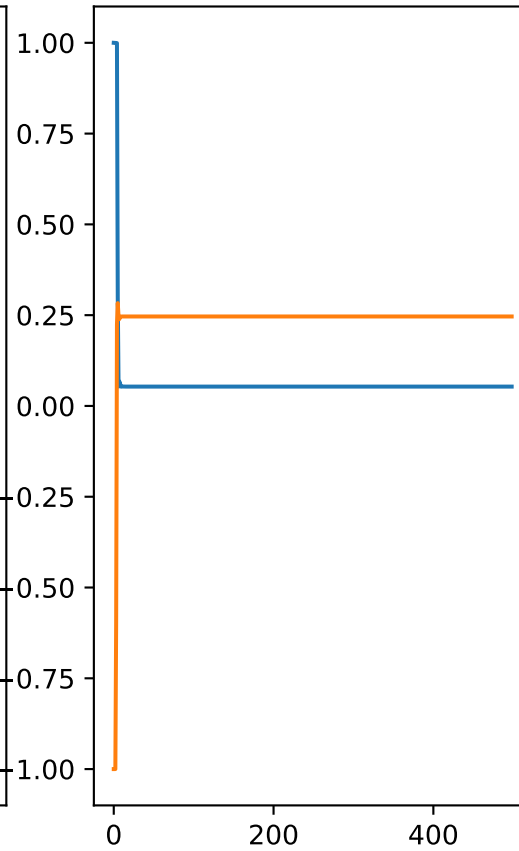


Reward: square\_root  
Speed = 208.5012265724196 [rad/s]

State vs step



Action vs step



Reward vs step

