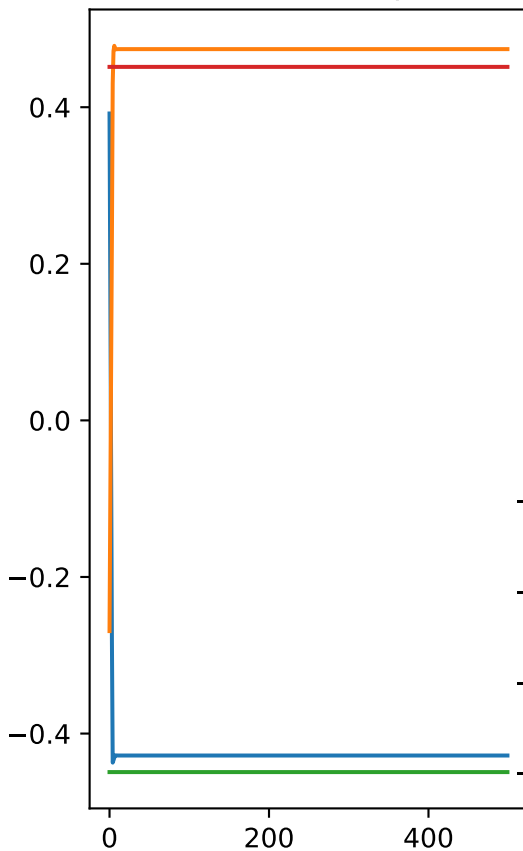
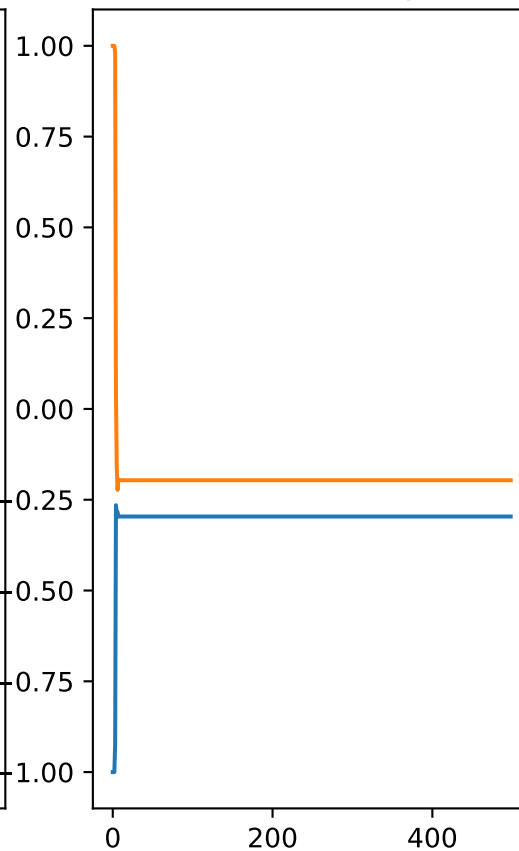


Reward: quartic_root
Speed = 913.3363555858276 [rad/s]

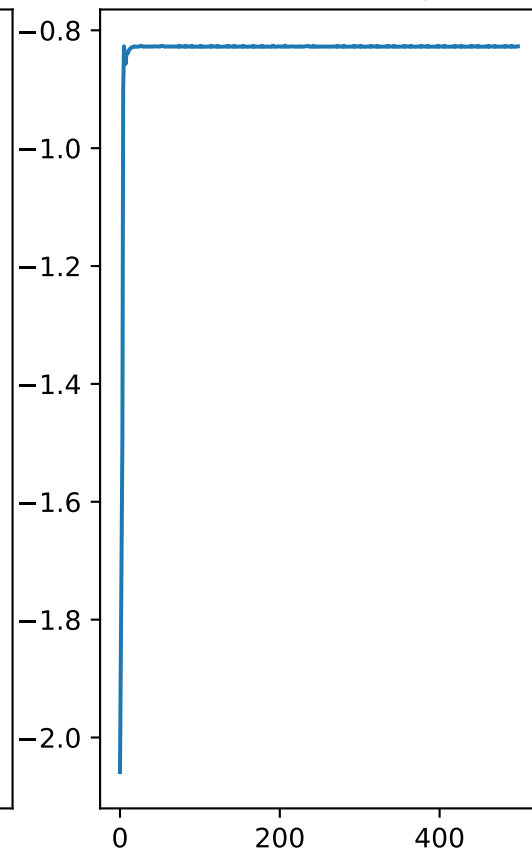
State vs step



Action vs step



Reward vs step



Id Iqref
Iq Iqref

Vd Vq