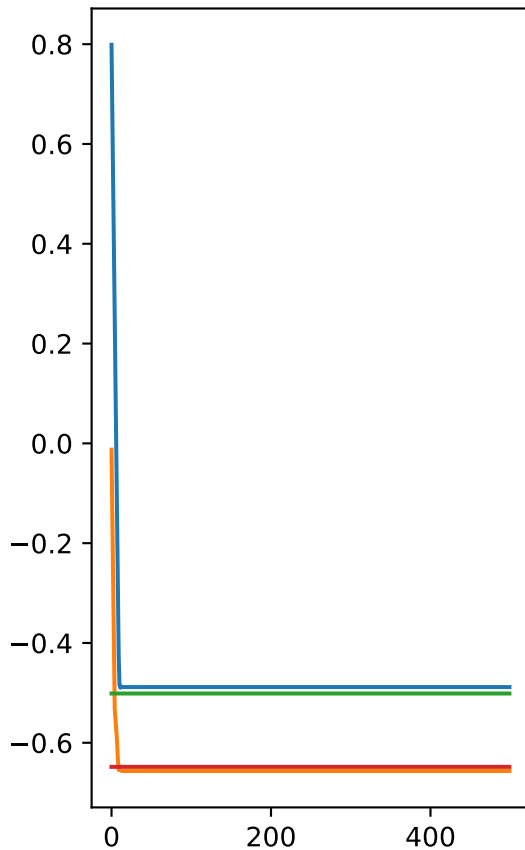
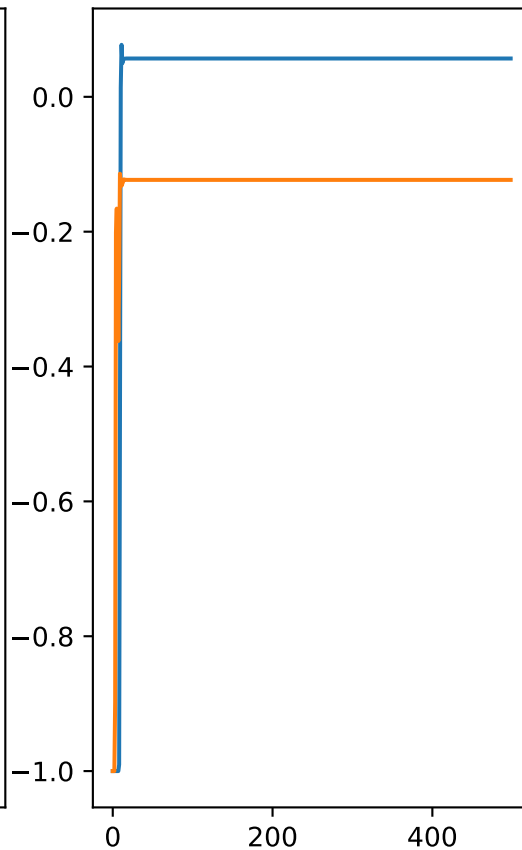


Reward: quartic\_root  
Speed = 935.8176379871917 [rad/s]

State vs step



Action vs step



Reward vs step

