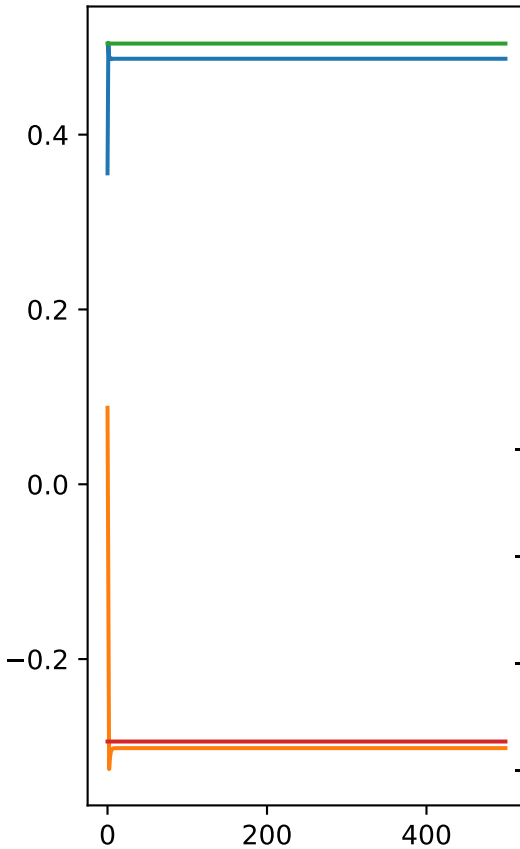
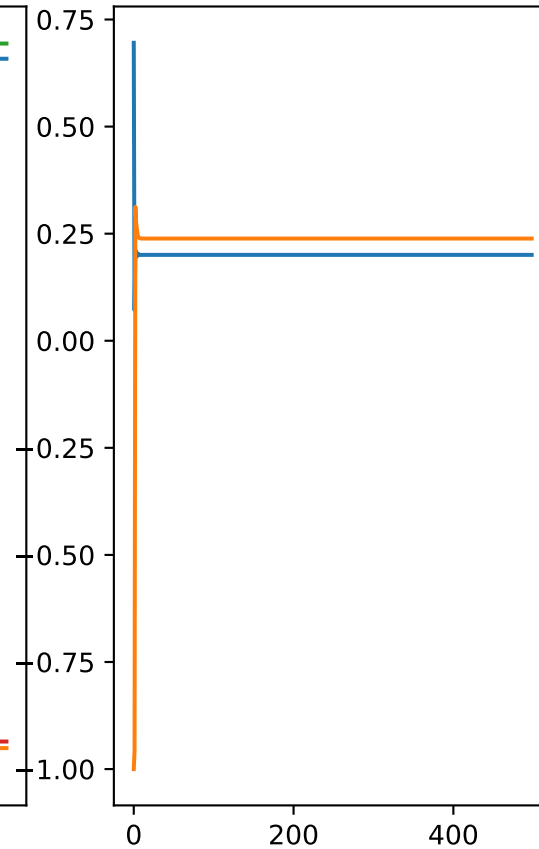


Reward: quartic_root
Speed = 901.2224014458706 [rad/s]

State vs step



Action vs step



Reward vs step

