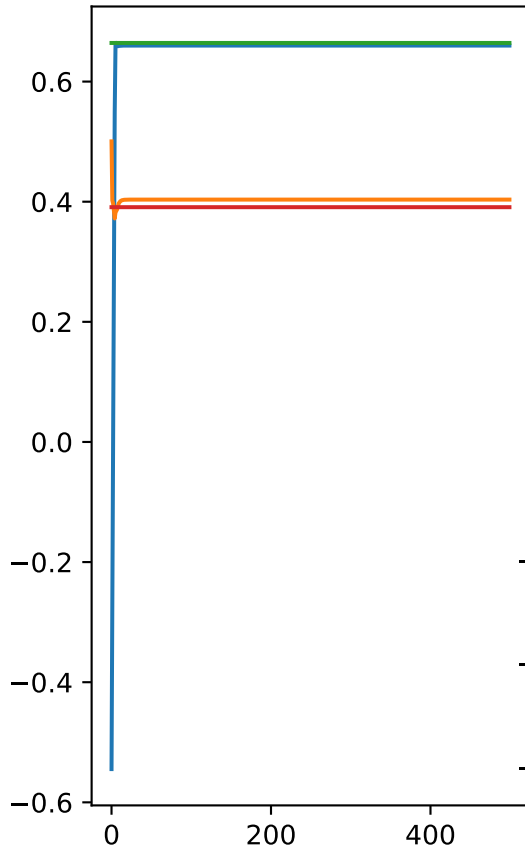
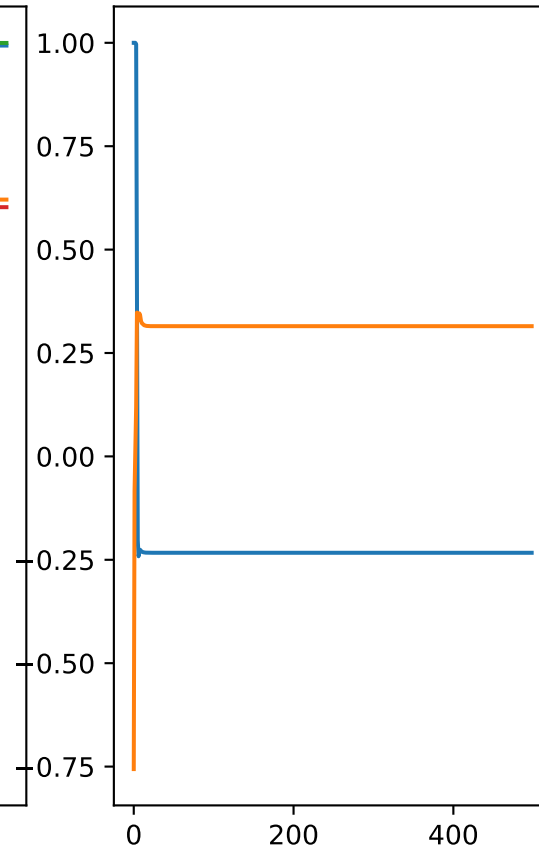


Reward: quartic_root
Speed = 406.9493362801695 [rad/s]

State vs step



Action vs step



Reward vs step

