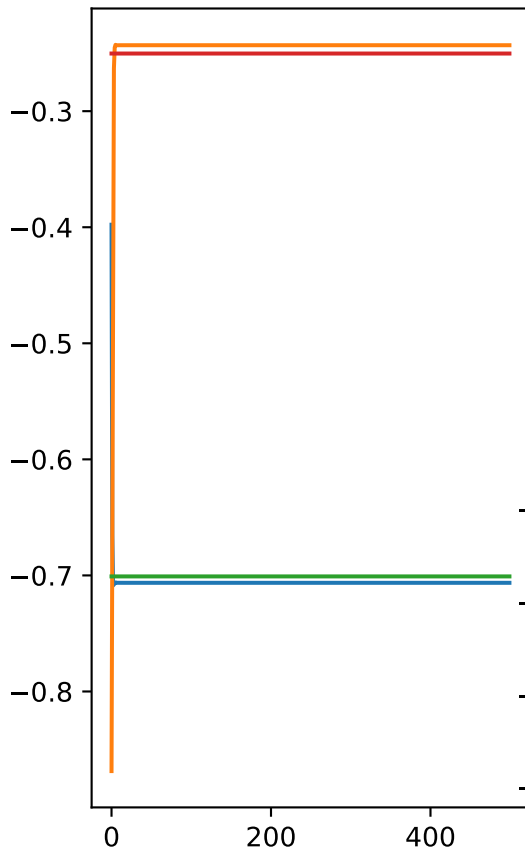
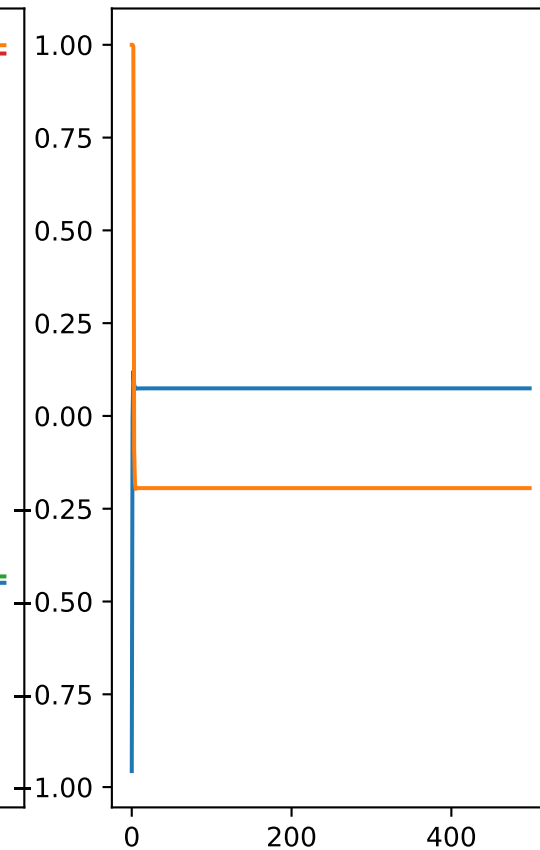


Reward: square_root
Speed = 697.1445335606667 [rad/s]

State vs step



Action vs step



Reward vs step

