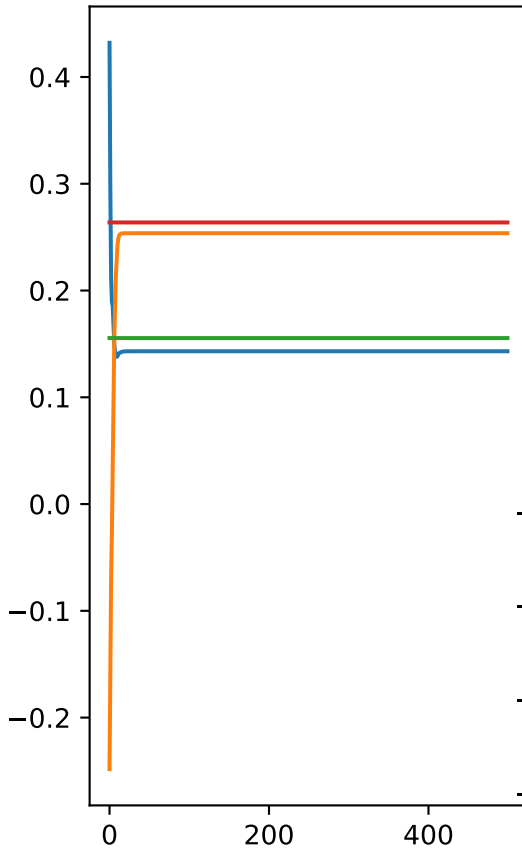
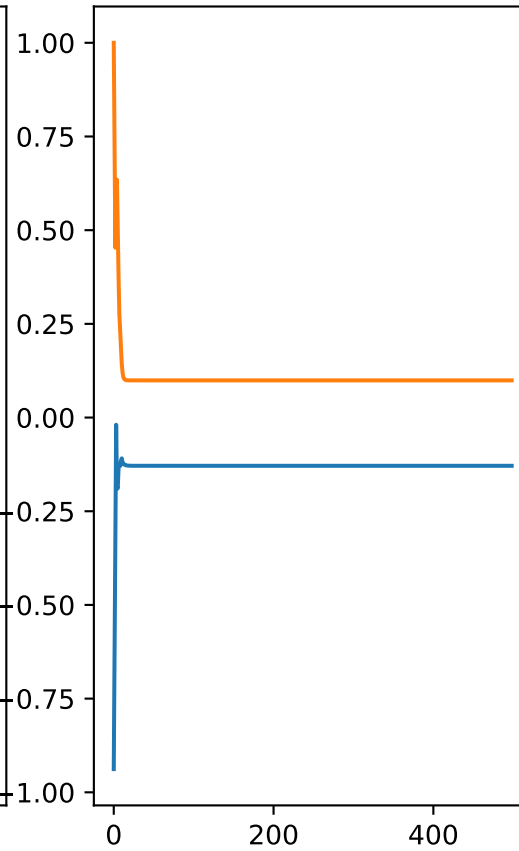


Reward: quadratic_2
Speed = 640.8974727842435 [rad/s]

State vs step



Action vs step



Reward vs step

