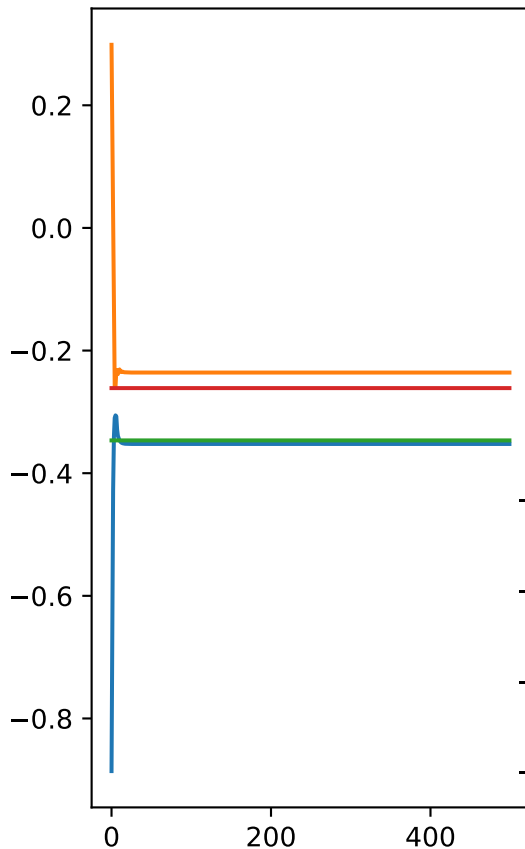
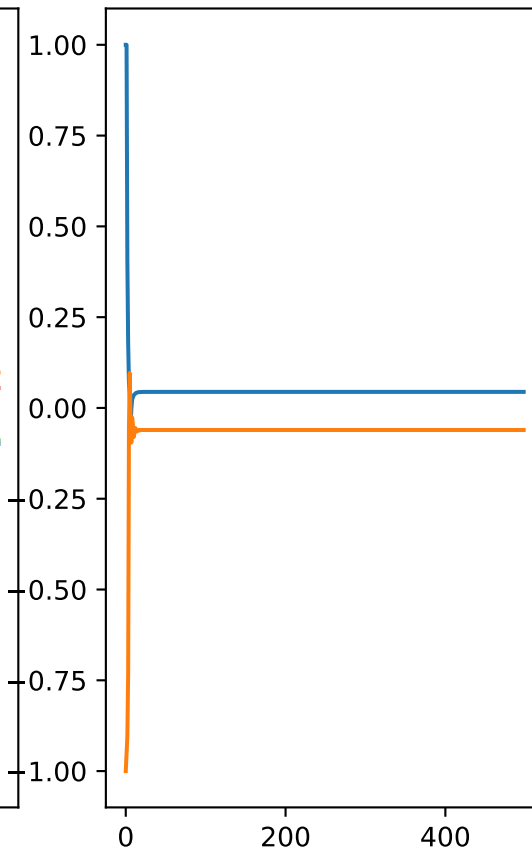


Reward: quadratic\_2  
Speed = 279.9661744646386 [rad/s]

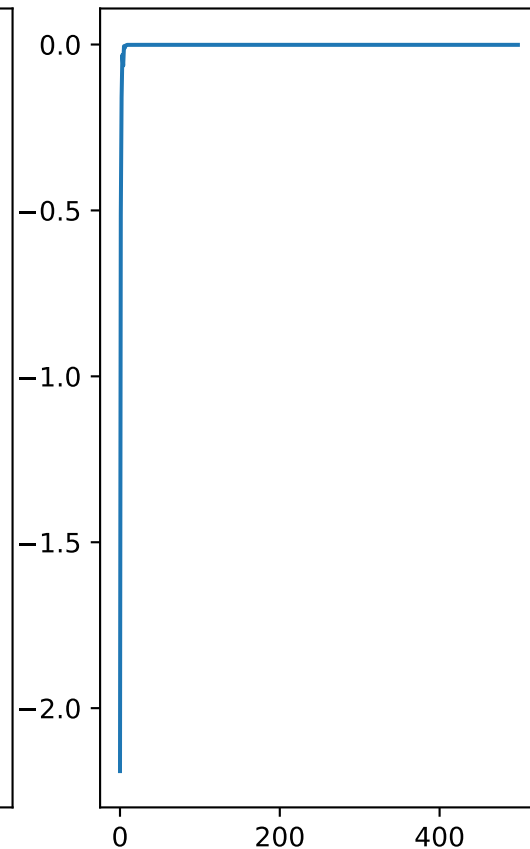
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq