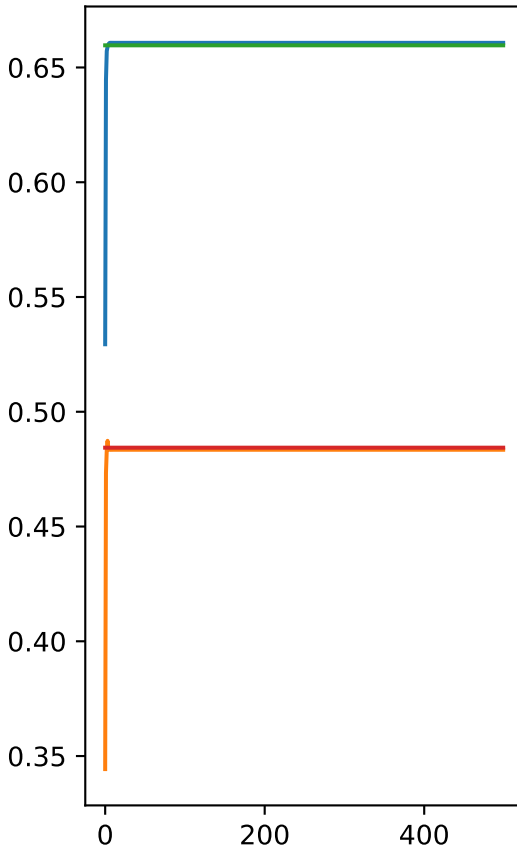
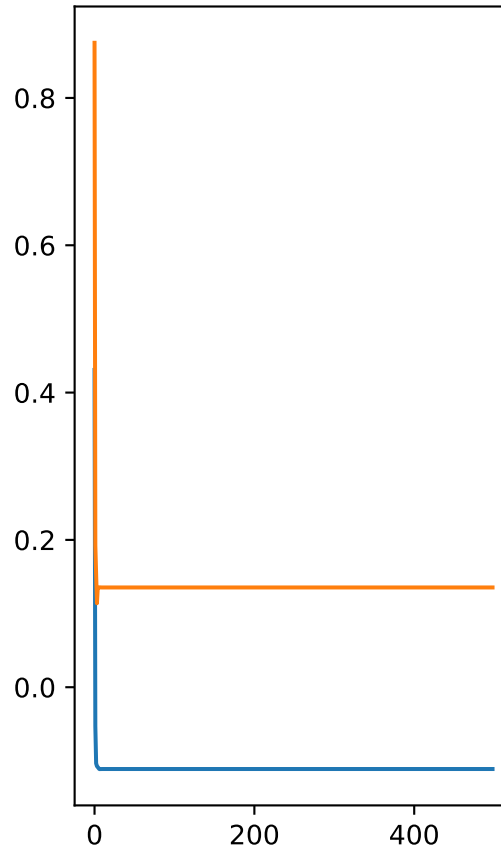


Reward: square_root
Speed = 90.50300331278707 [rad/s]

State vs step



Action vs step



Reward vs step

