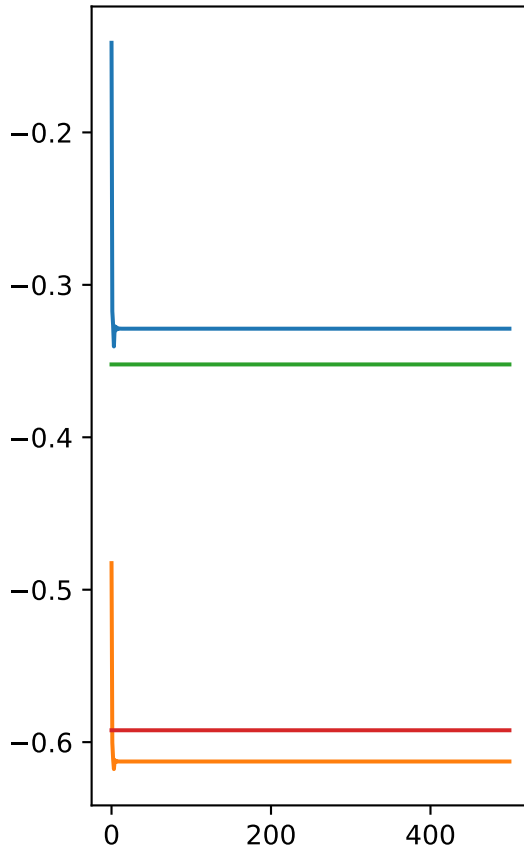


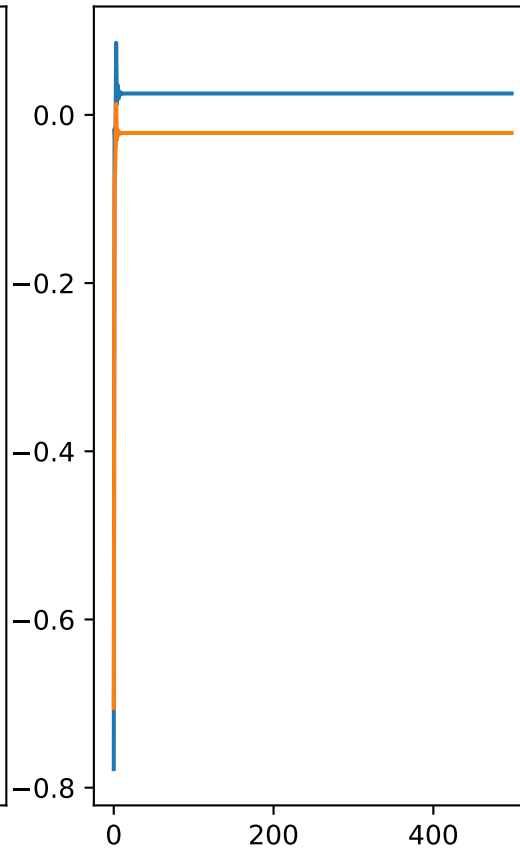
Reward: quartic\_root\_2  
Speed = 32.8987571538594 [rad/s]

State vs step



— Id — Idref  
— Iq — Iqref

Action vs step



— Vd — Vq

Reward vs step

