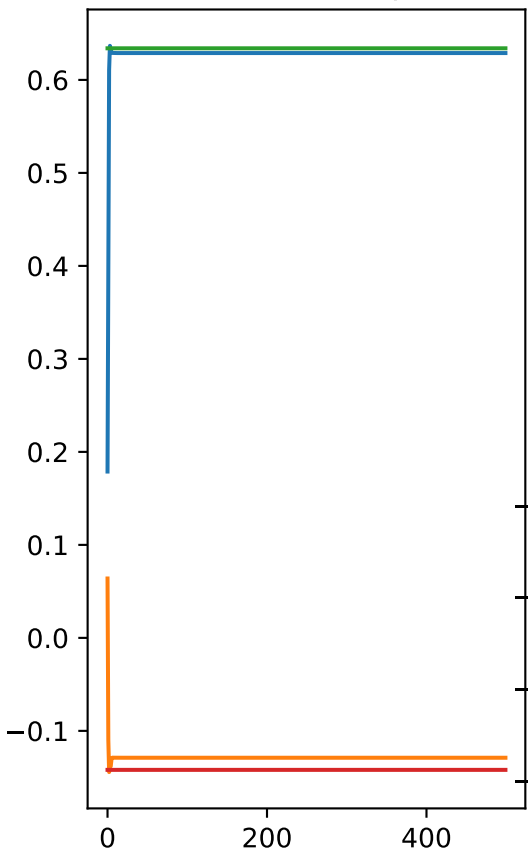
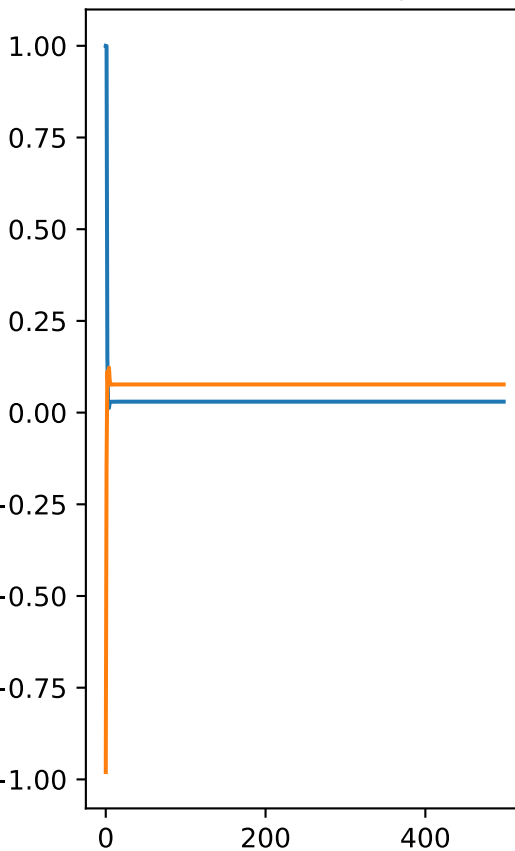


Reward: square\_root  
Speed = 254.26795159164854 [rad/s]

State vs step



Action vs step



Reward vs step

