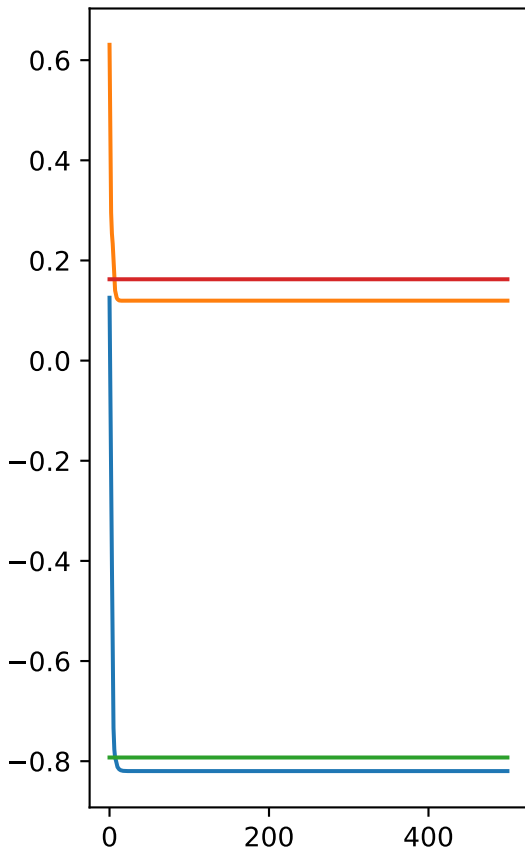
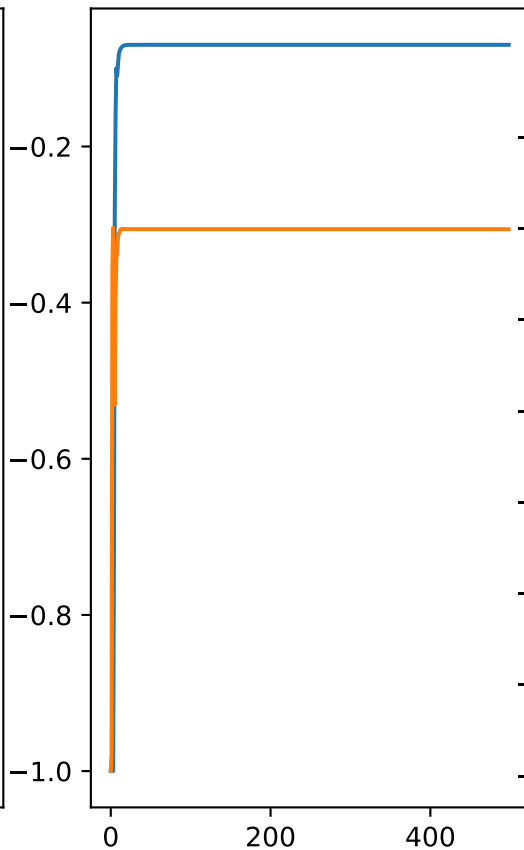


Reward: quadratic\_2  
Speed = 1043.2098502936108 [rad/s]

State vs step



Action vs step



Reward vs step

