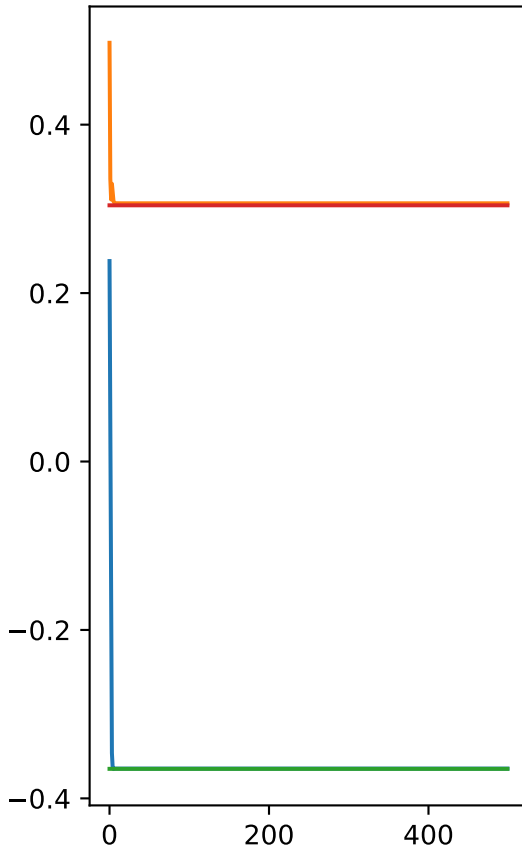
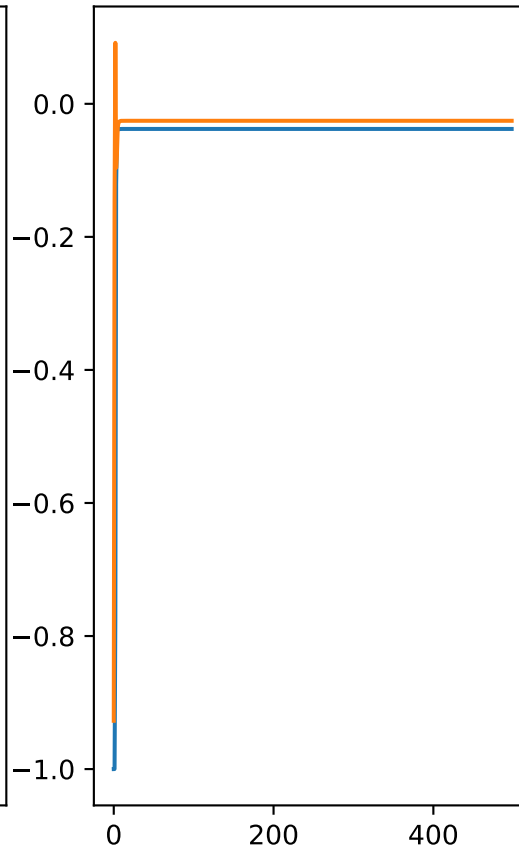


Reward: square\_root\_2  
Speed = 524.6459596672424 [rad/s]

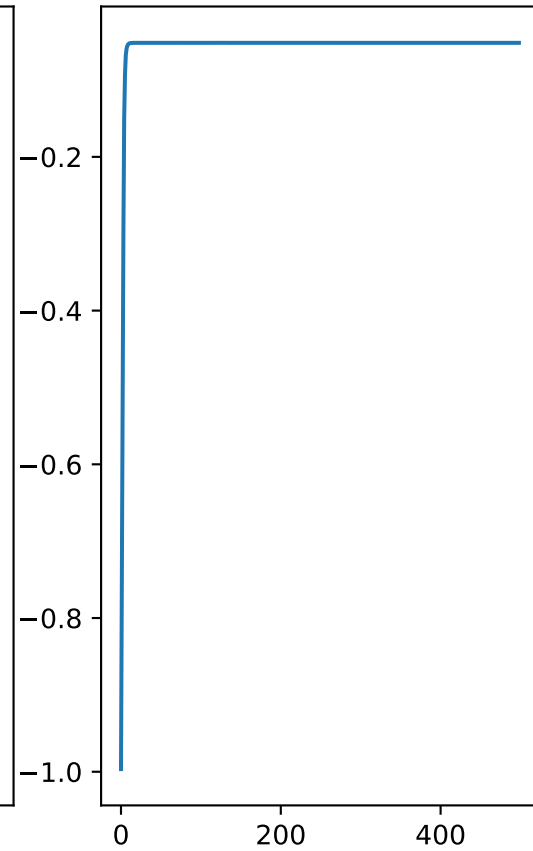
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq