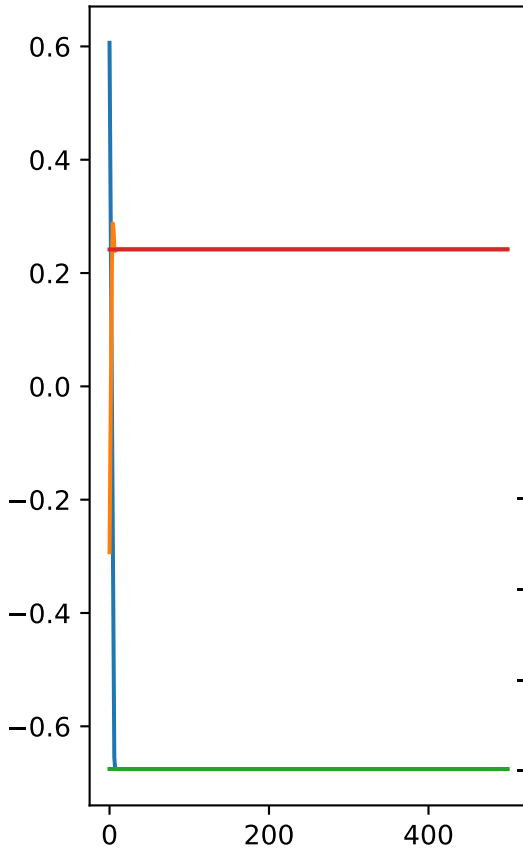
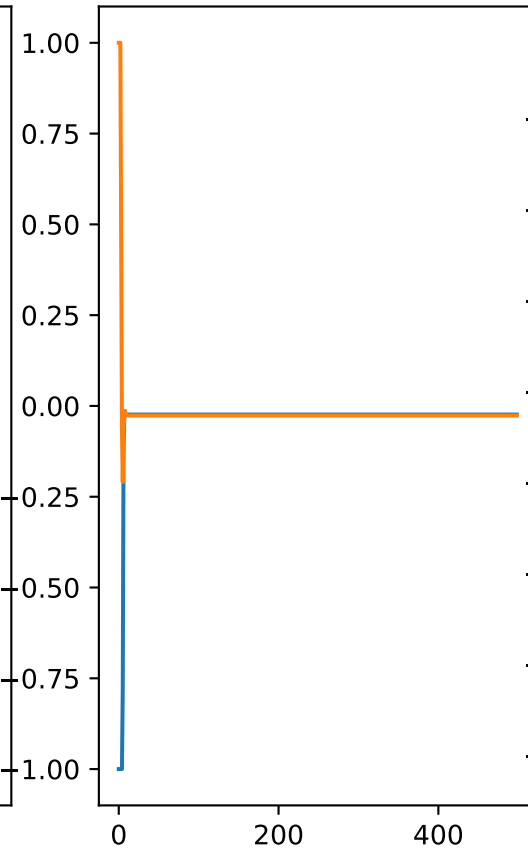


Reward: square\_root  
Speed = 354.7486366909315 [rad/s]

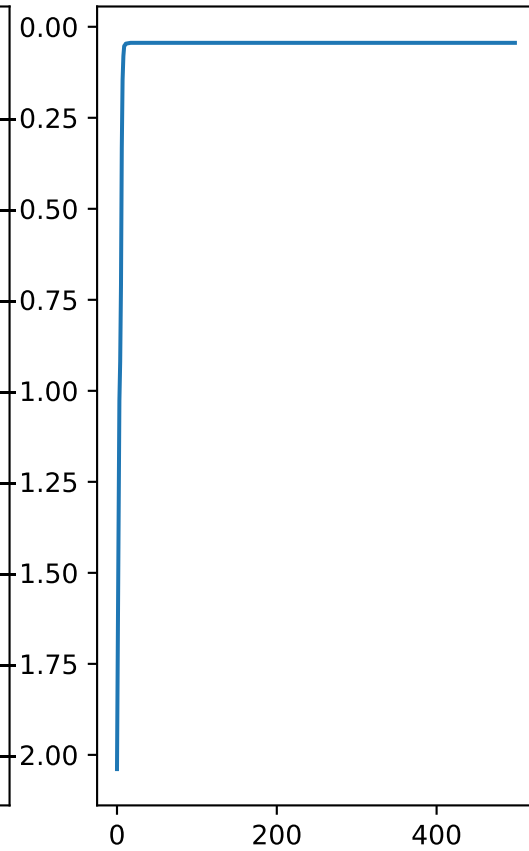
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq