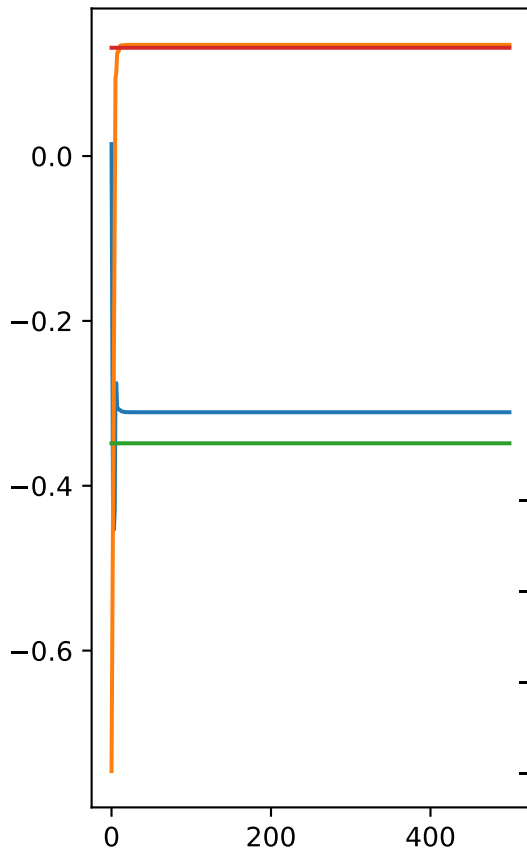
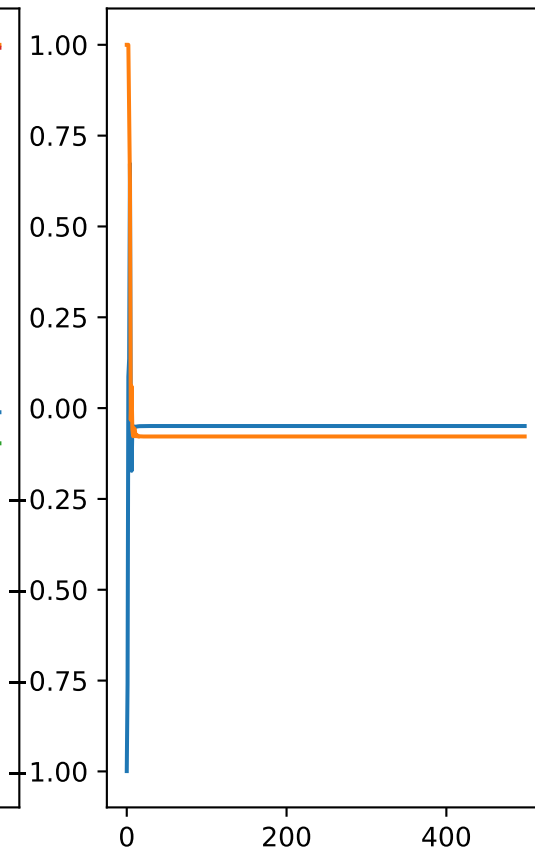


Reward: quadratic_2
Speed = 894.9266386946529 [rad/s]

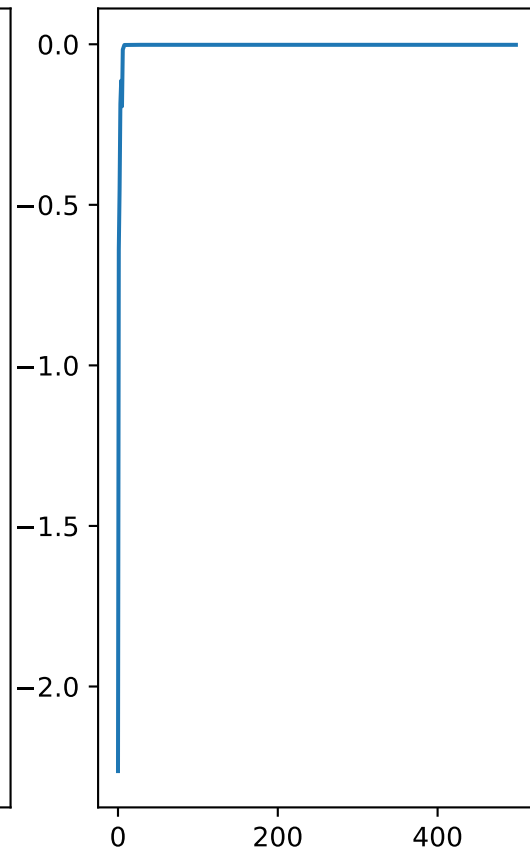
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq