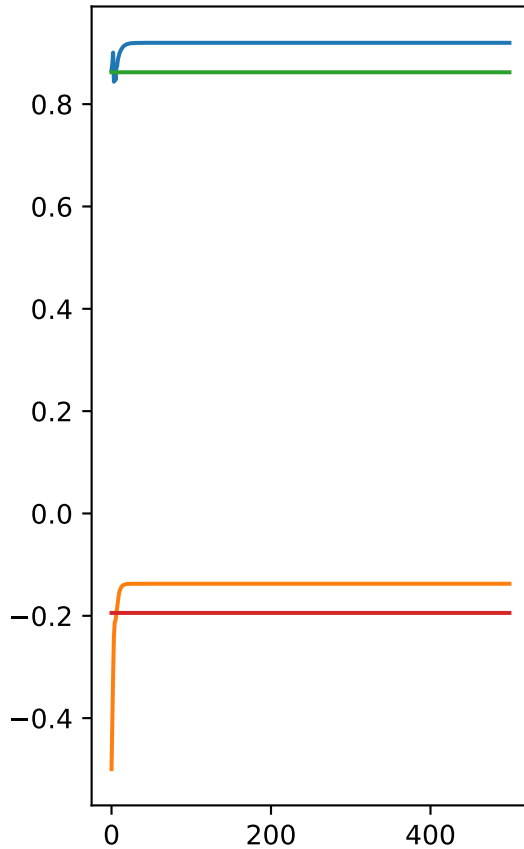
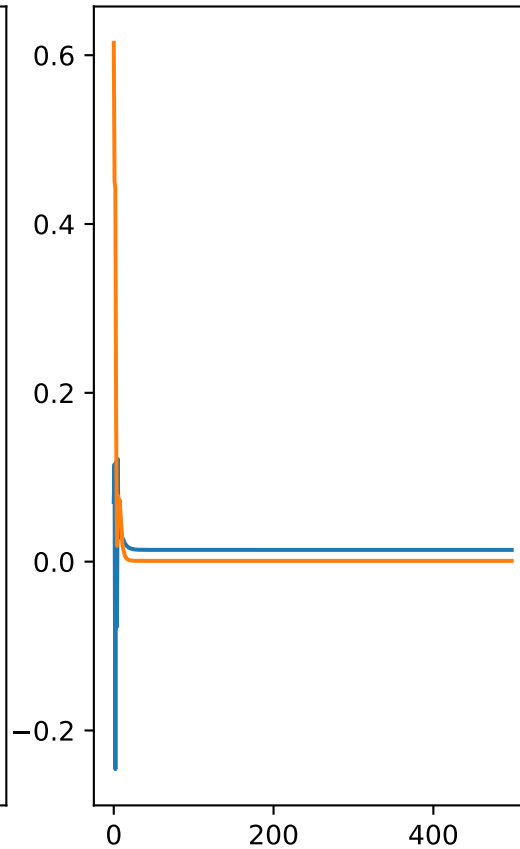


Reward: quadratic\_2  
Speed = 116.1635320533795 [rad/s]

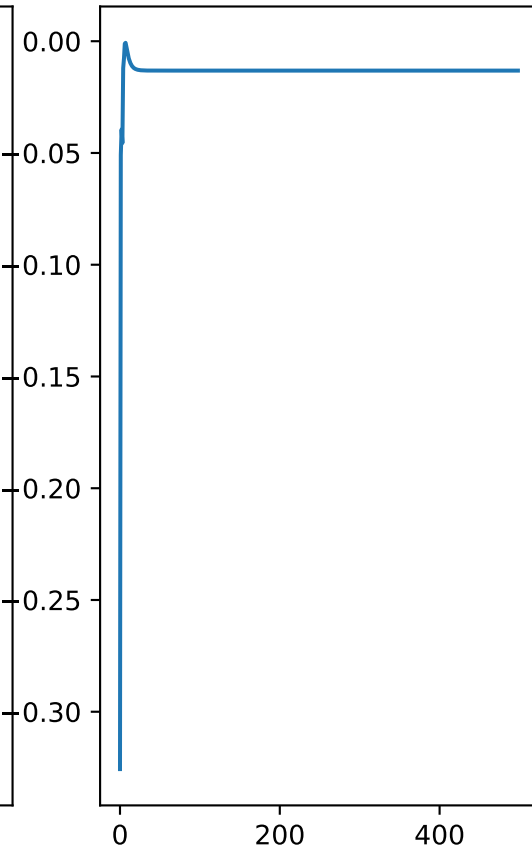
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq