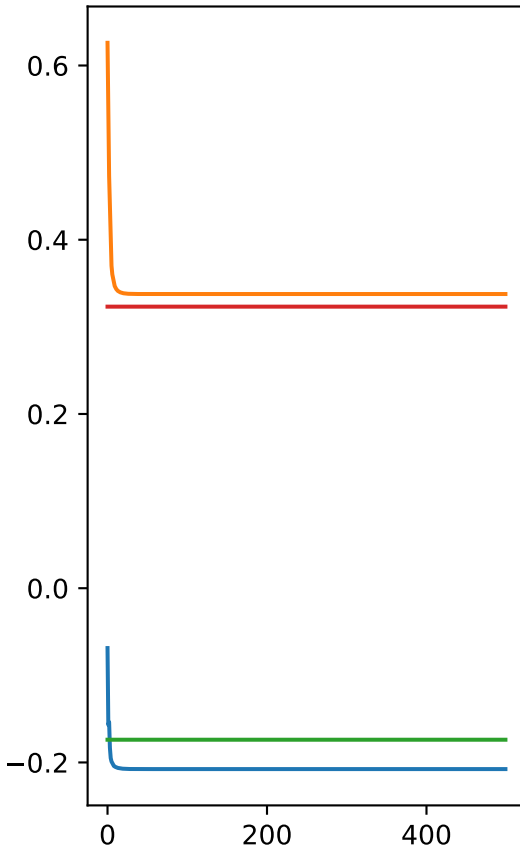
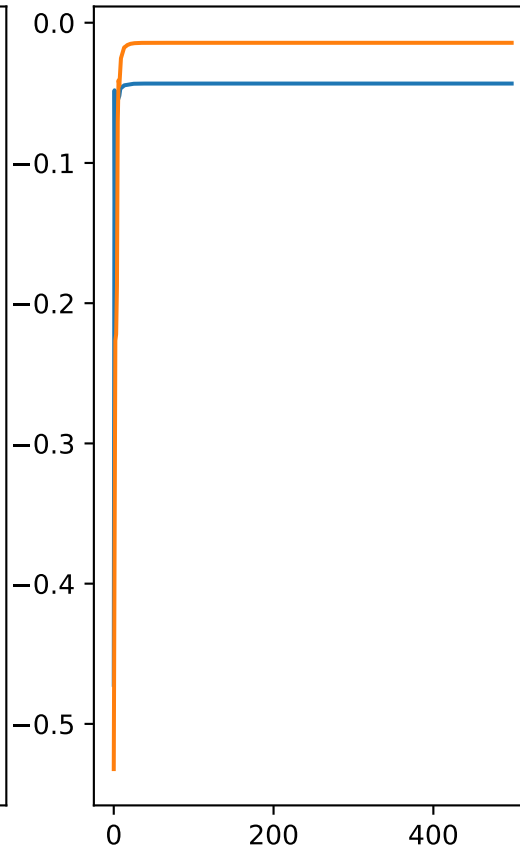


Reward: quadratic_2
Speed = 578.0153458889697 [rad/s]

State vs step



Action vs step



Reward vs step

