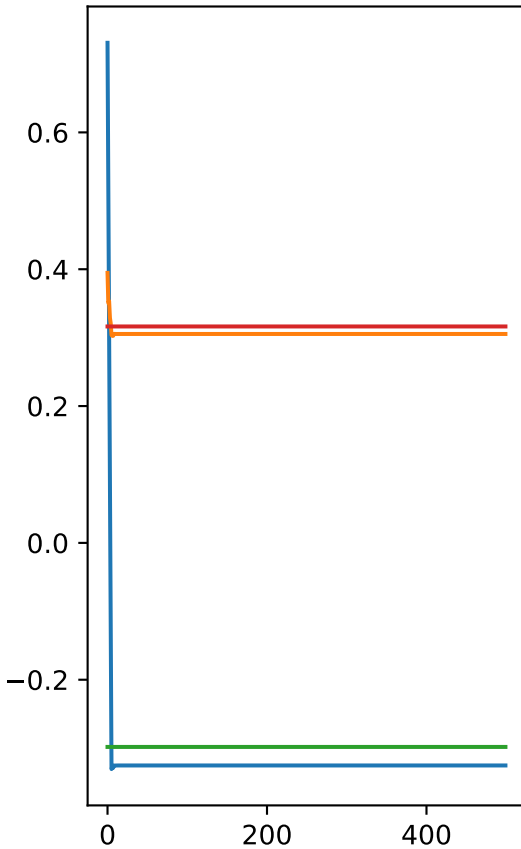
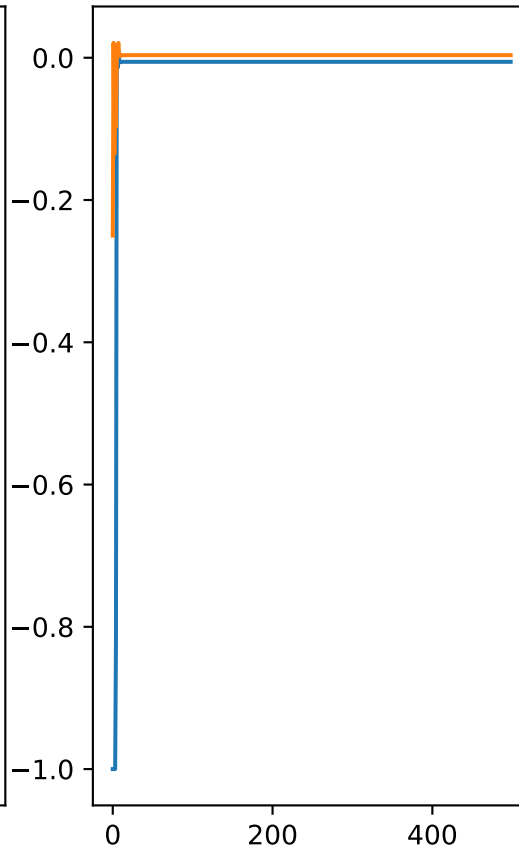


Reward: quartic_root
Speed = 828.1740565633828 [rad/s]

State vs step



Action vs step



Reward vs step

