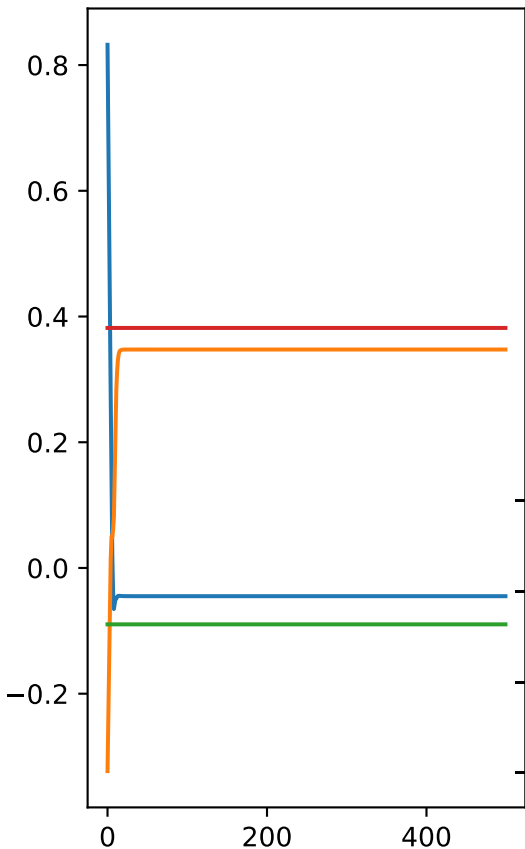
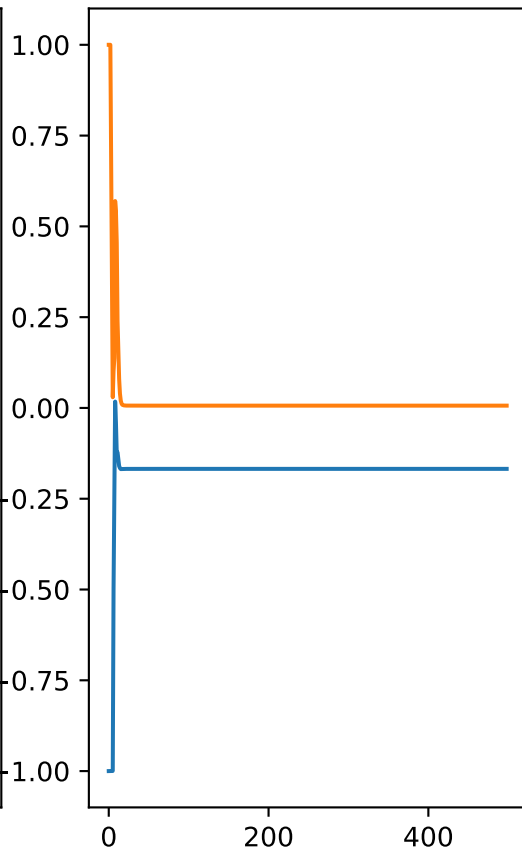


Reward: quadratic\_2  
Speed = 1089.7681895438927 [rad/s]

State vs step



Action vs step



Reward vs step

