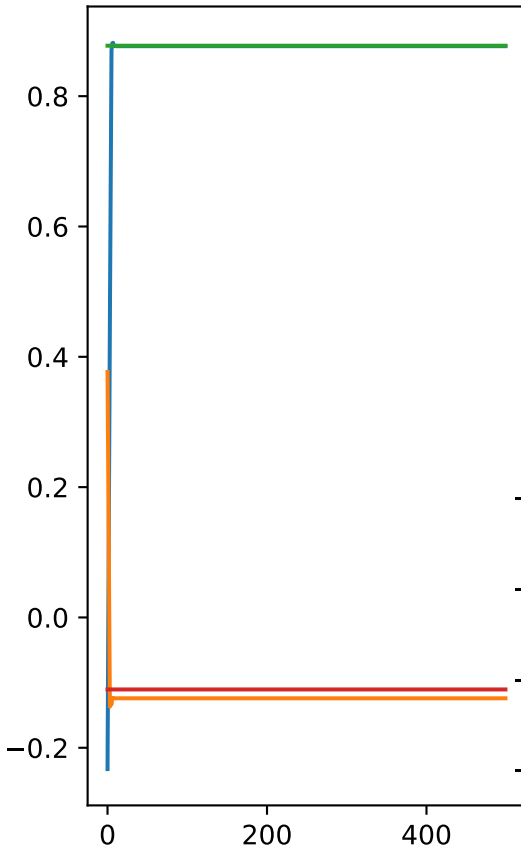
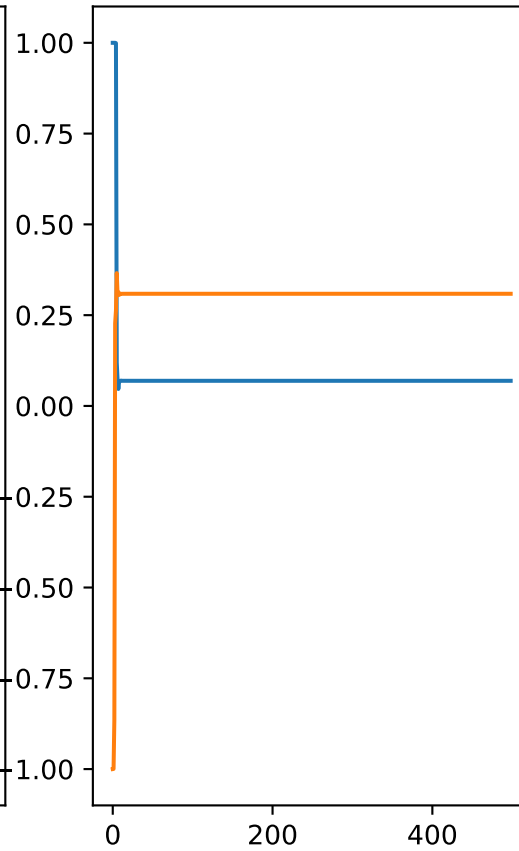


Reward: quartic_root
Speed = 922.9370679603202 [rad/s]

State vs step



Action vs step



Reward vs step

