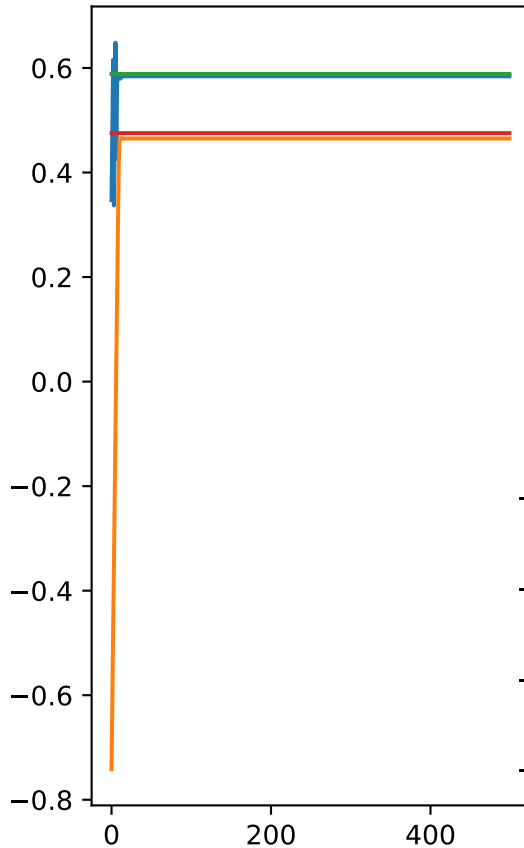
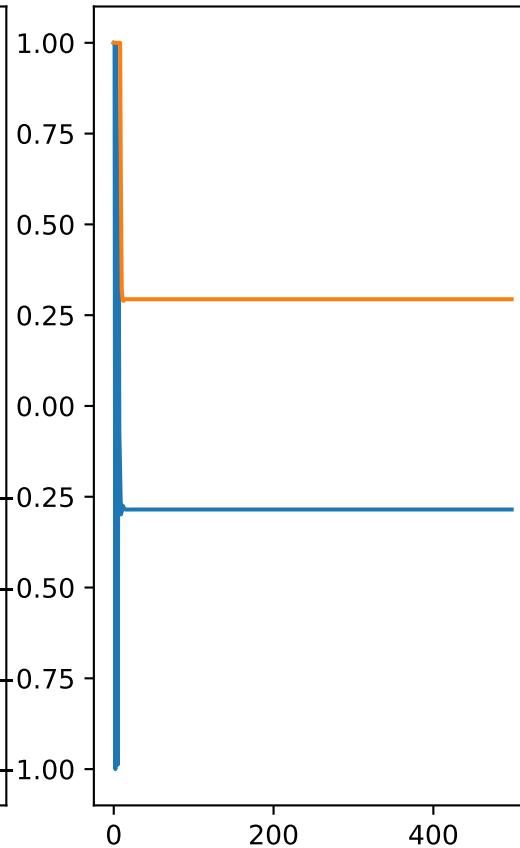


Reward: quartic_root
Speed = 395.5893396895707 [rad/s]

State vs step



Action vs step



Reward vs step

