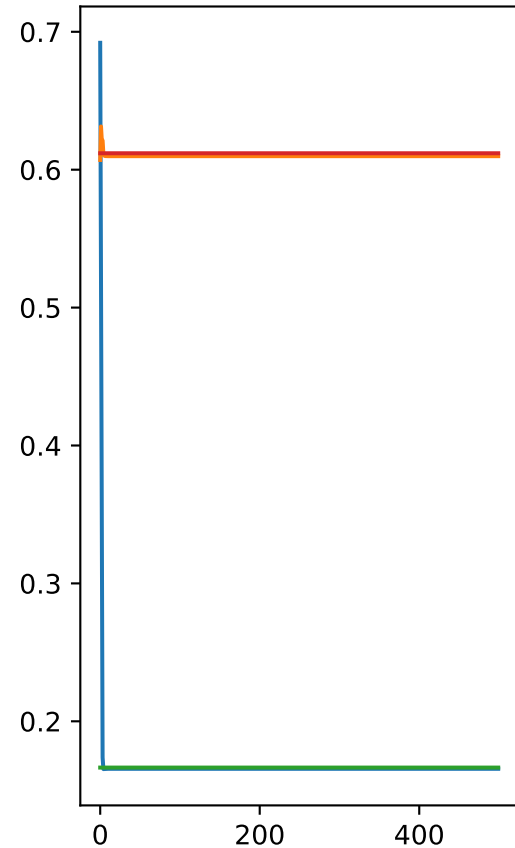
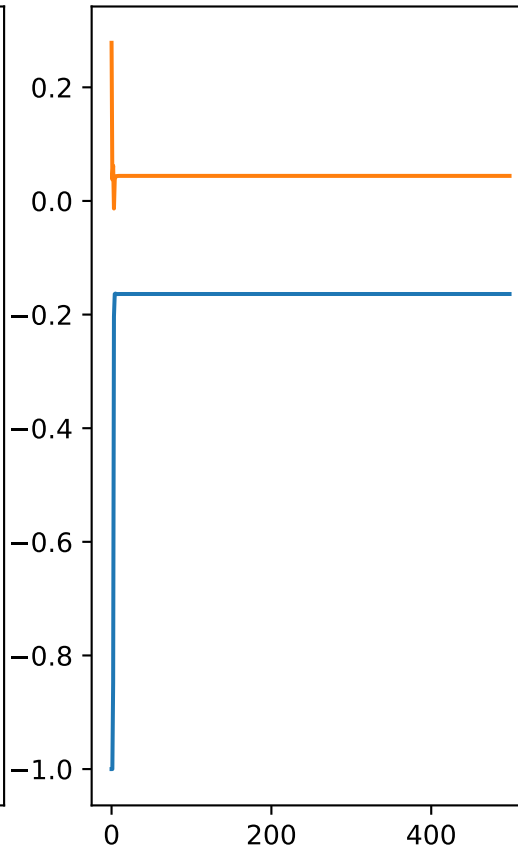


Reward: square\_root\_2  
Speed = 746.291615193317 [rad/s]

State vs step



Action vs step



Reward vs step

