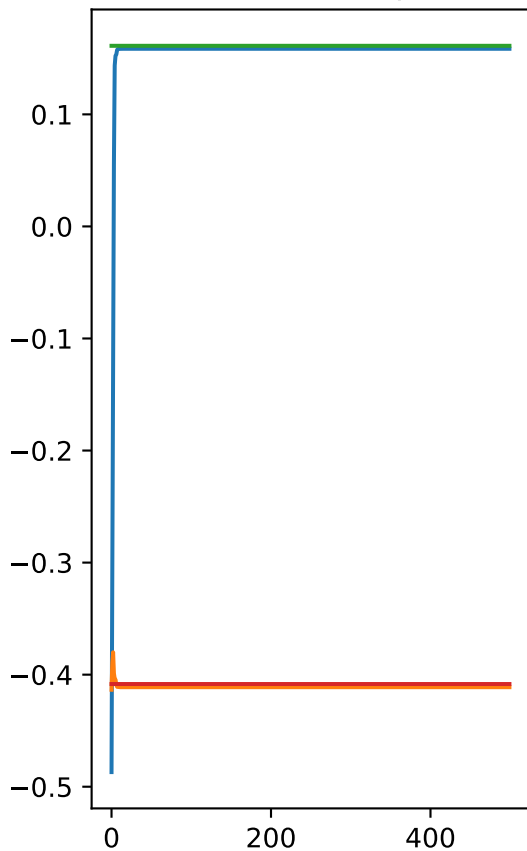


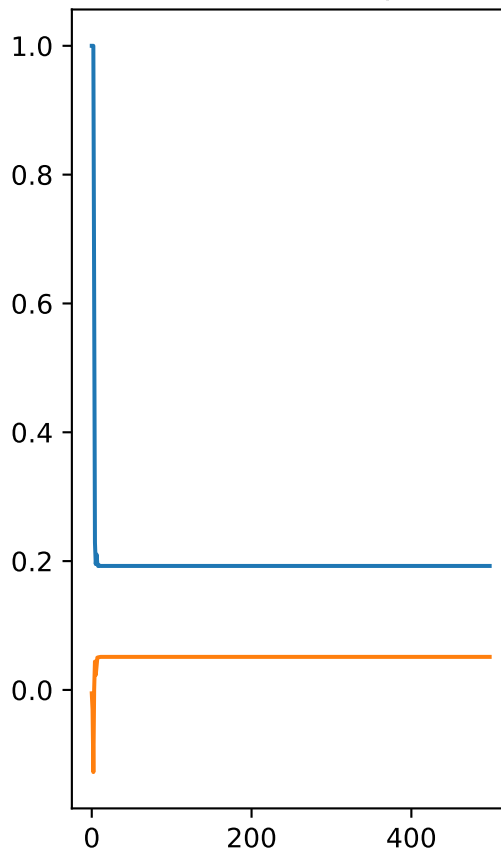
Reward: absolute
Speed = 1107.8386779688403 [rad/s]

State vs step



— I_d — I_{dref}
— I_q — I_{qref}

Action vs step



— V_d — V_q

Reward vs step

