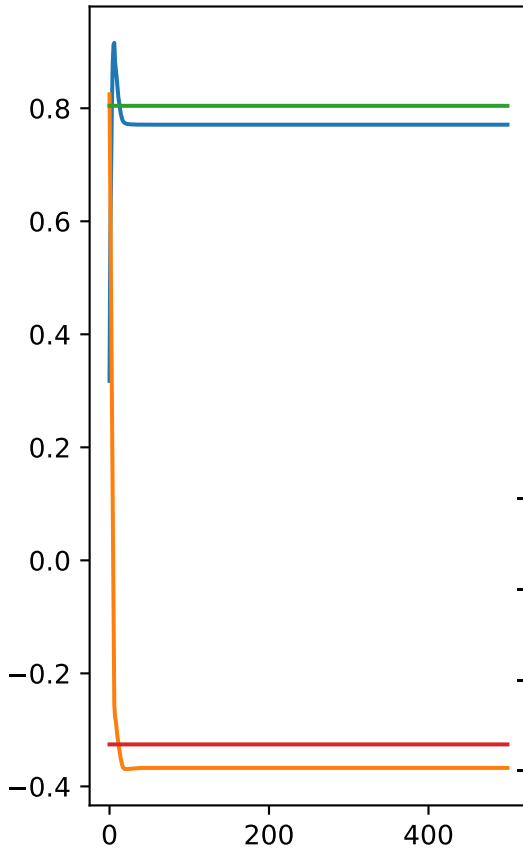
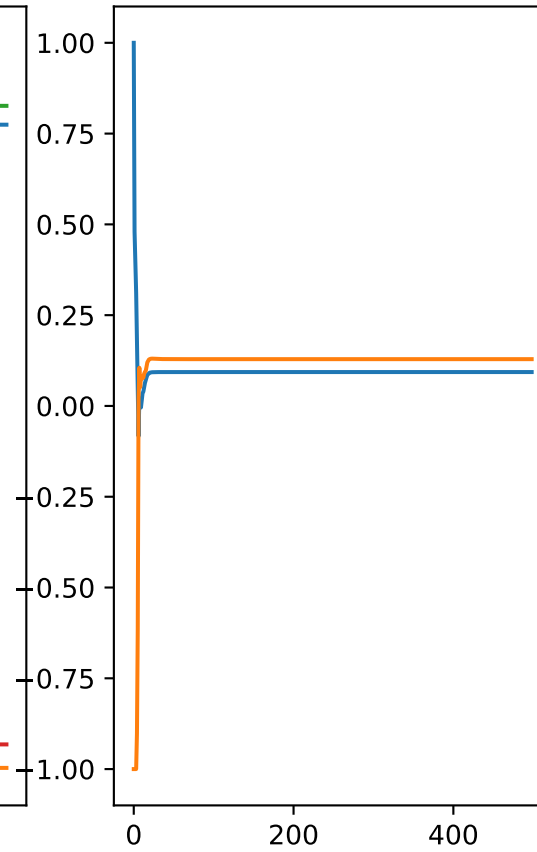


Reward: quadratic
Speed = 1.005309623752476 [rad/s]

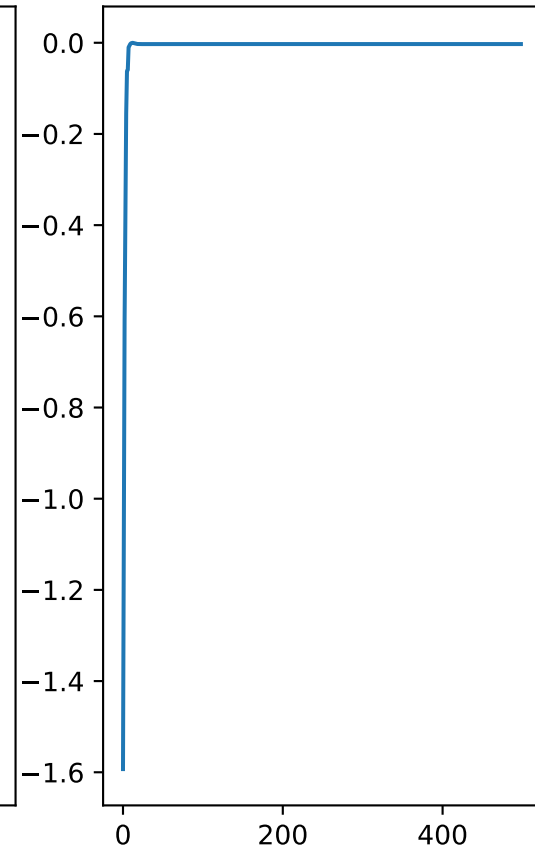
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq