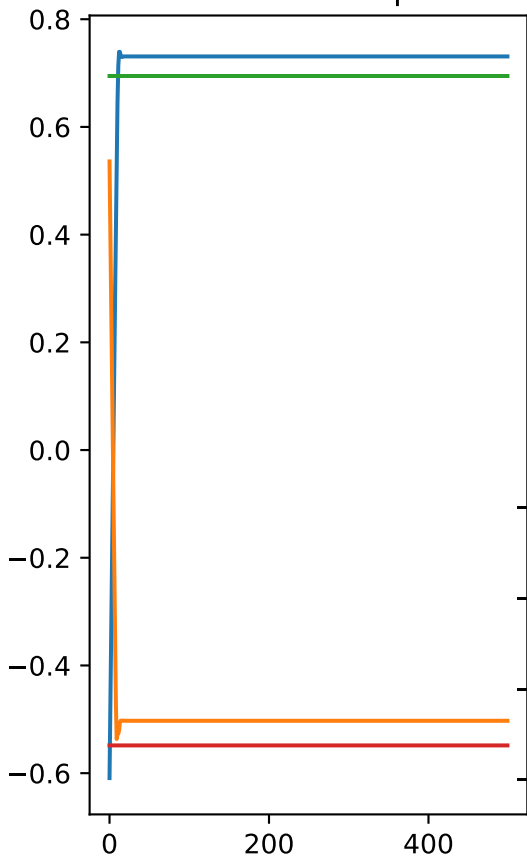
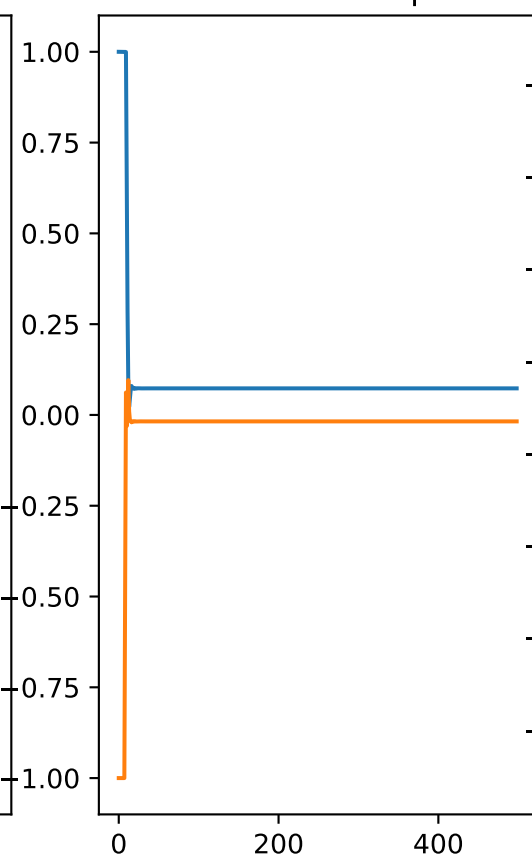


Reward: square_root
Speed = 265.15041427047174 [rad/s]

State vs step



Action vs step



Reward vs step

