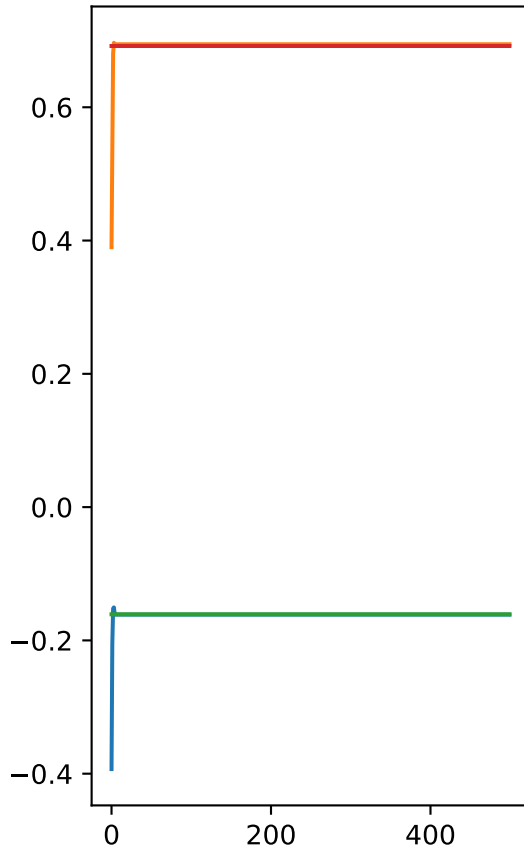
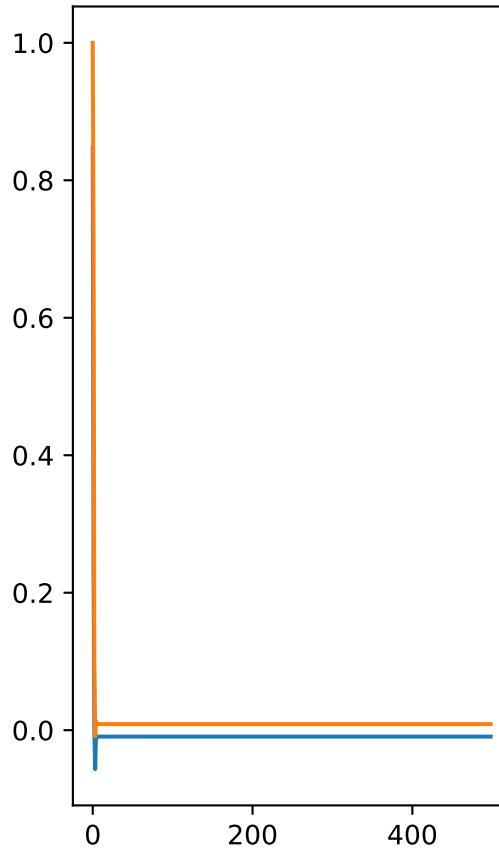


Reward: square_root
Speed = 283.158022965369 [rad/s]

State vs step



Action vs step



Reward vs step

