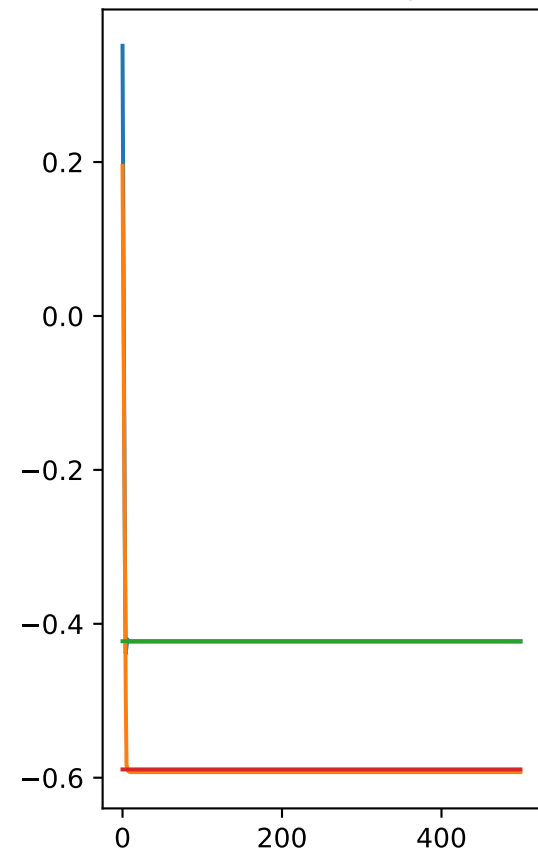
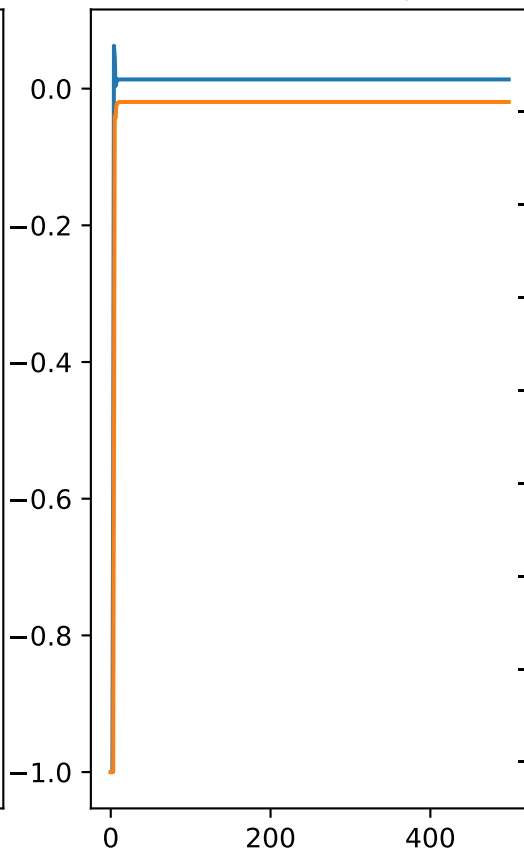


Reward: square_root
Speed = 23.448847056315643 [rad/s]

State vs step



Action vs step



Reward vs step

