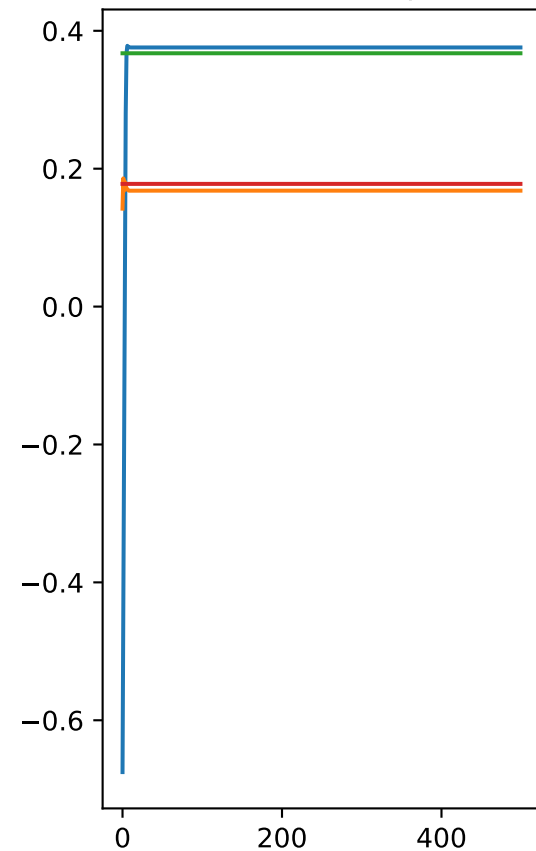
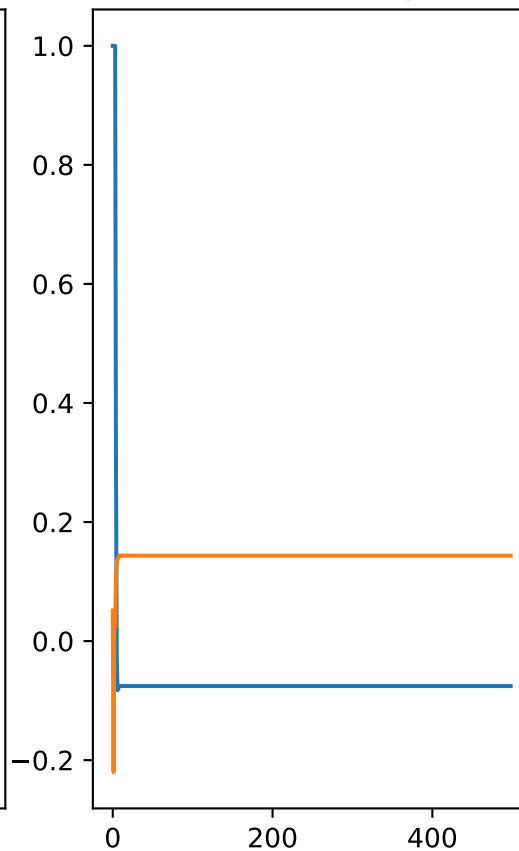


Reward: quartic\_root  
Speed = 729.8171259201404 [rad/s]

State vs step



Action vs step



Reward vs step

