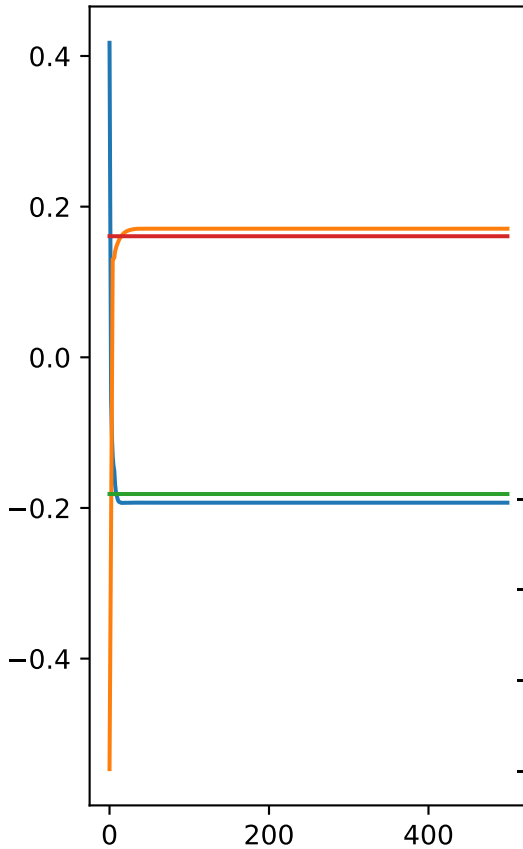
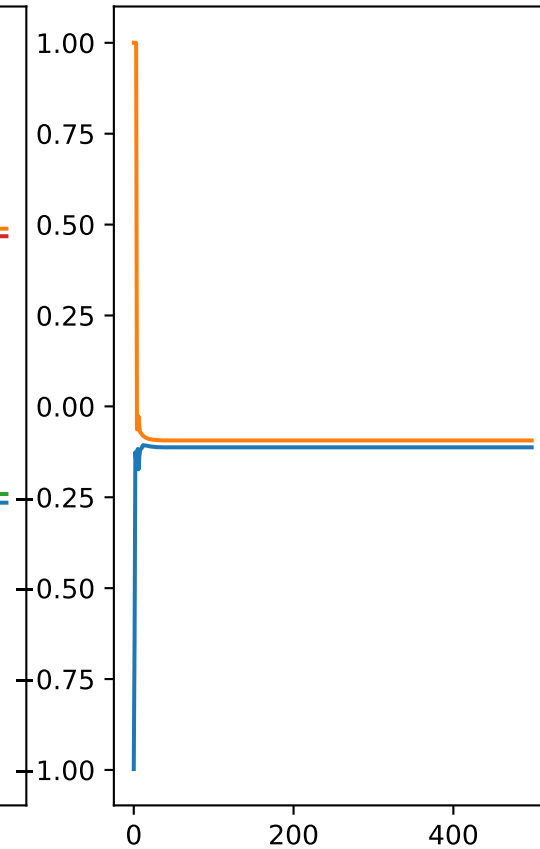


Reward: quadratic\_2  
Speed = 777.3807918371705 [rad/s]

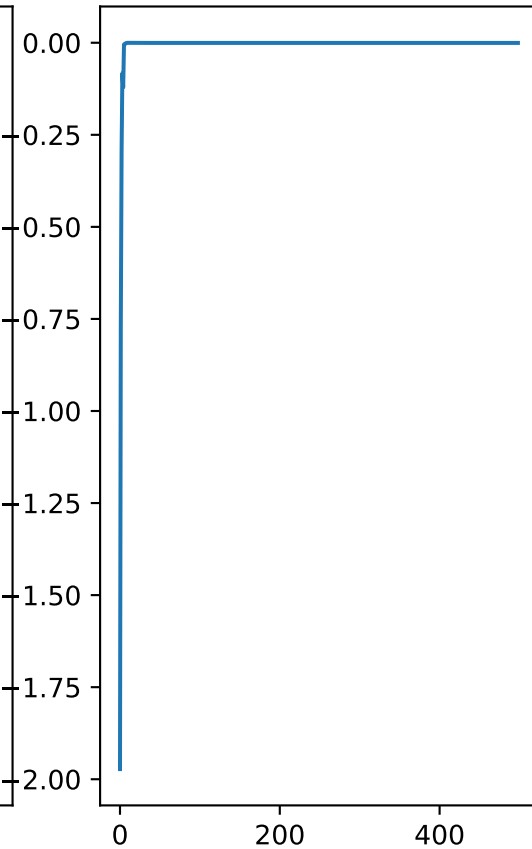
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq