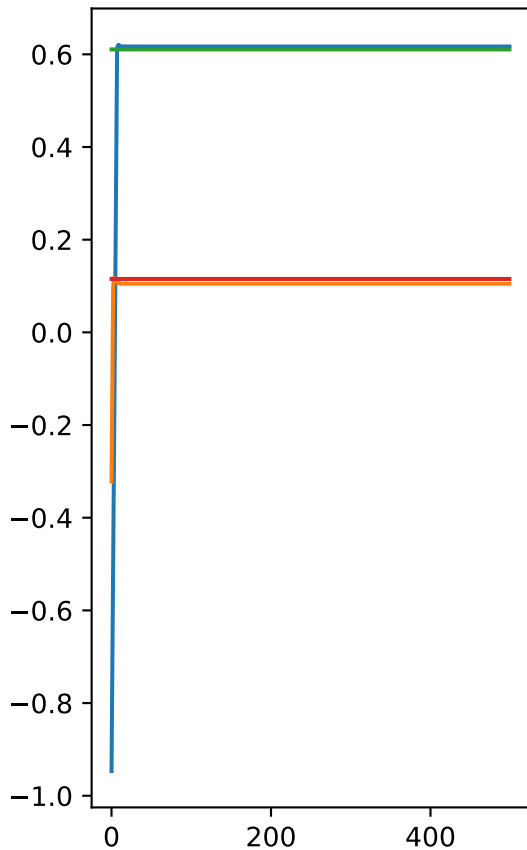
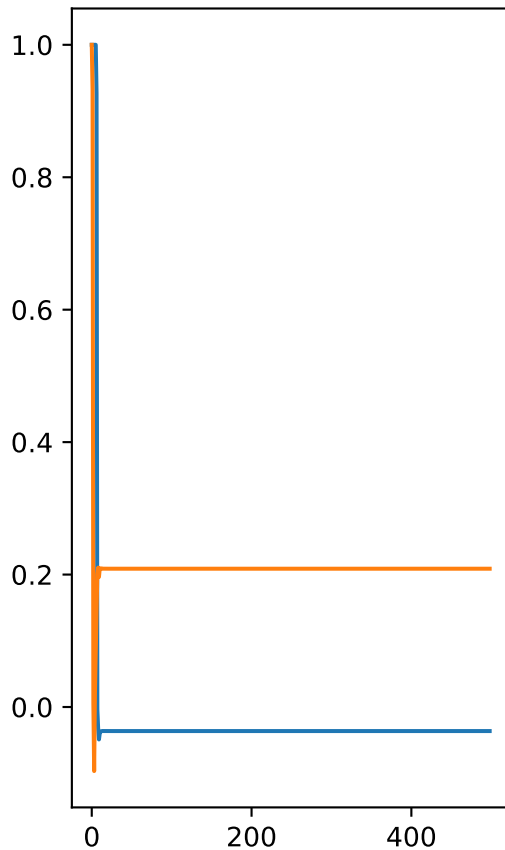


Reward: quartic_root
Speed = 254.12972104750583 [rad/s]

State vs step



Action vs step



Reward vs step

