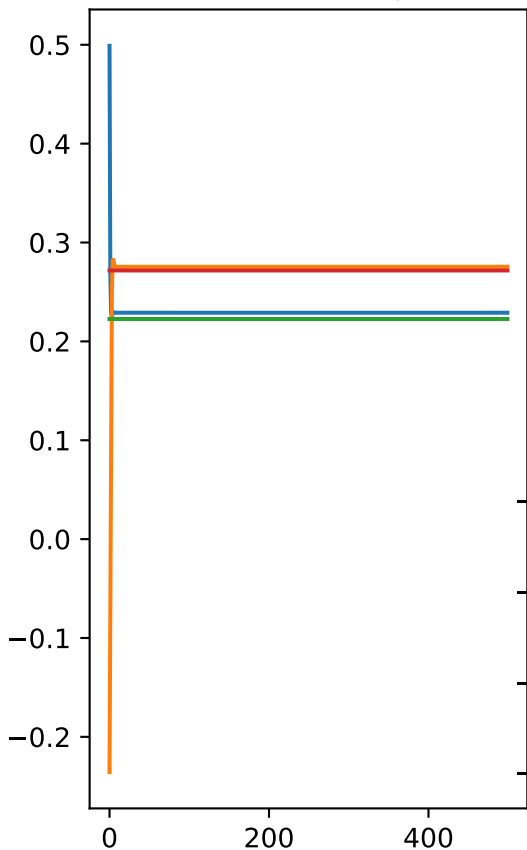
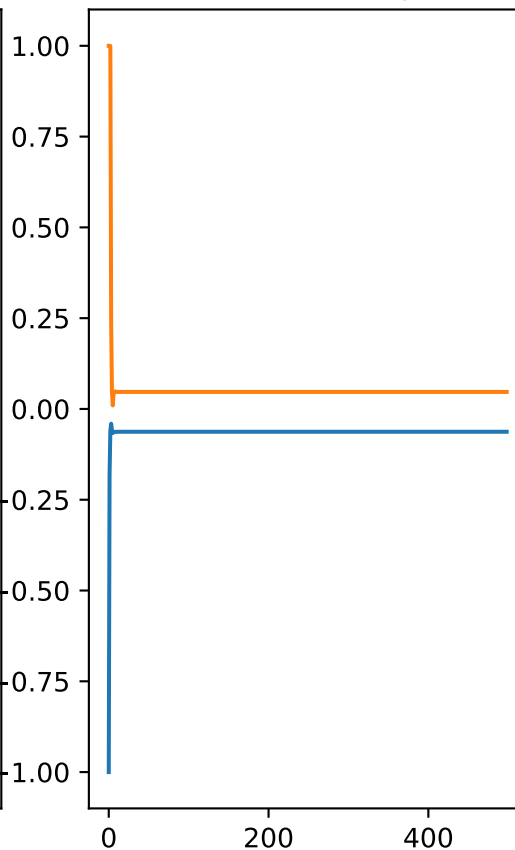


Reward: quartic_root
Speed = 15.368671837727586 [rad/s]

State vs step



Action vs step



Reward vs step

