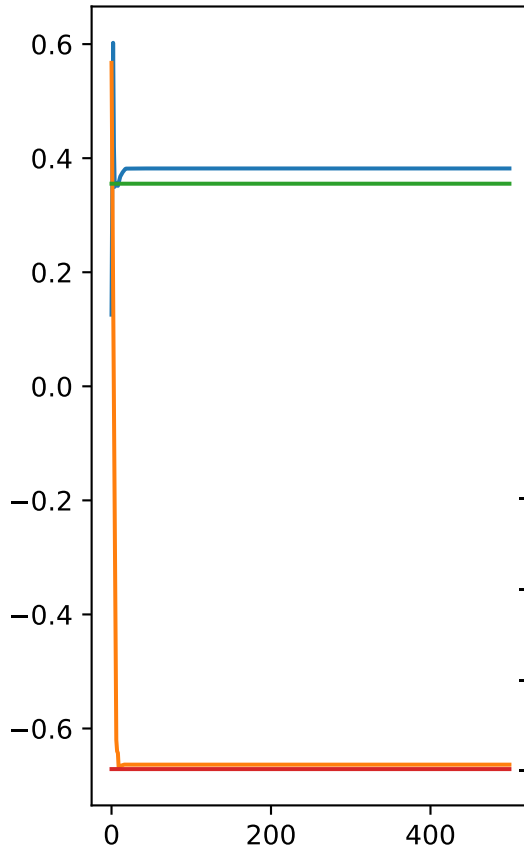
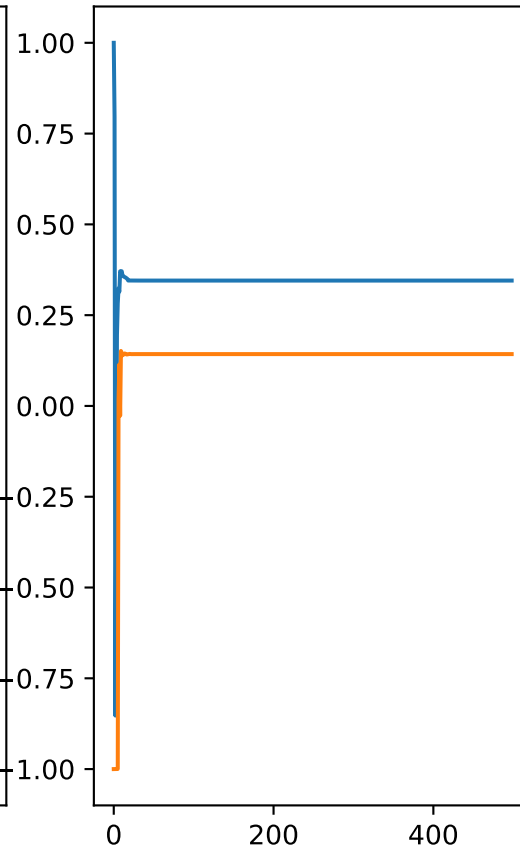


Reward: quadratic_2
Speed = 1103.4027171201226 [rad/s]

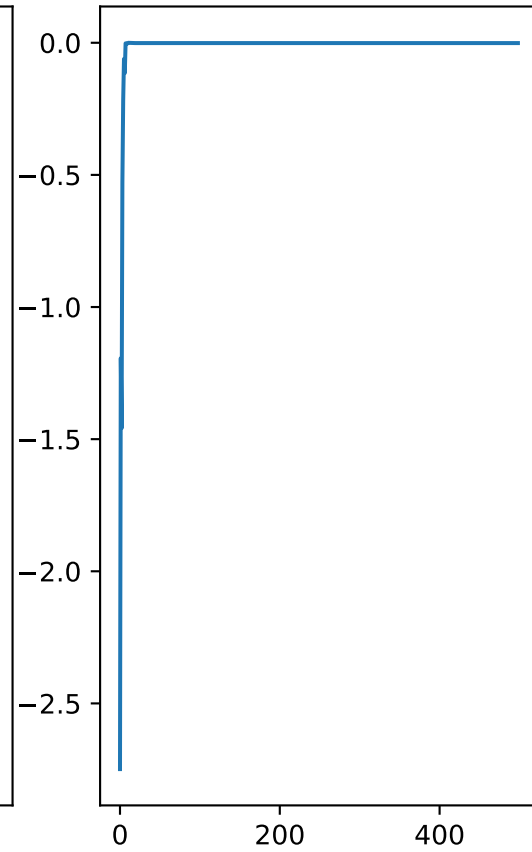
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq