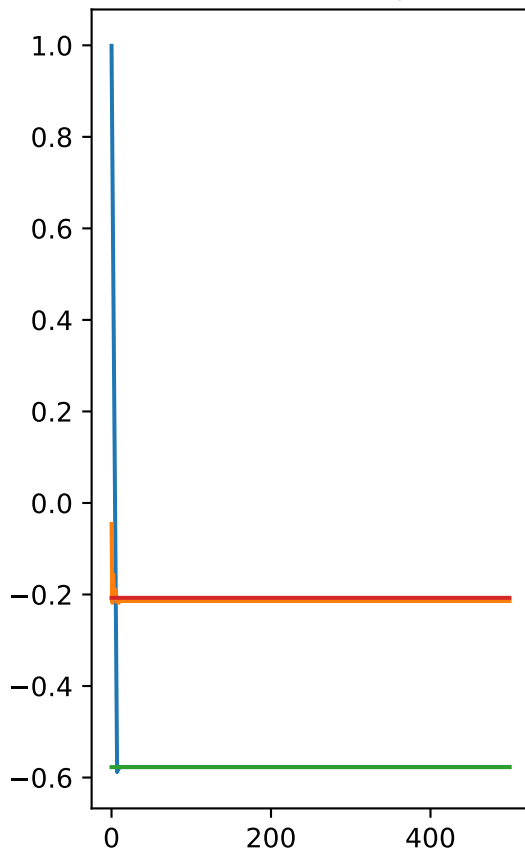
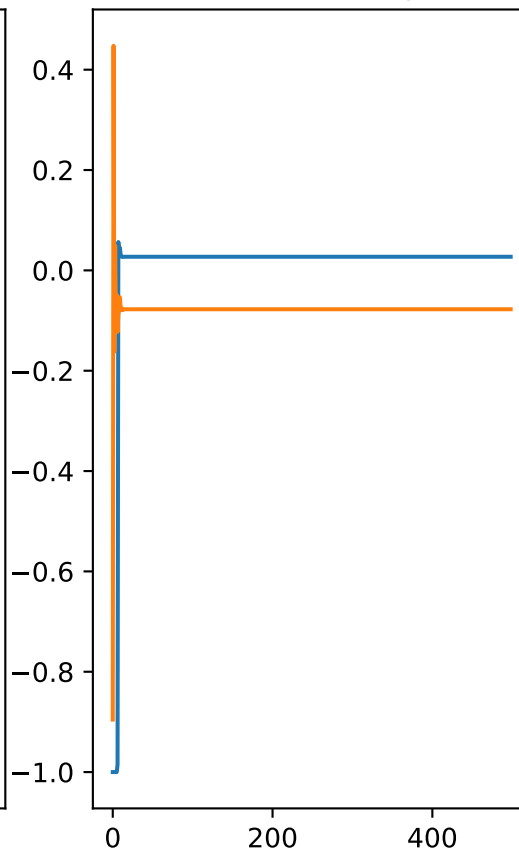


Reward: quartic\_root  
Speed = 260.7396202940552 [rad/s]

State vs step



Action vs step



Reward vs step

