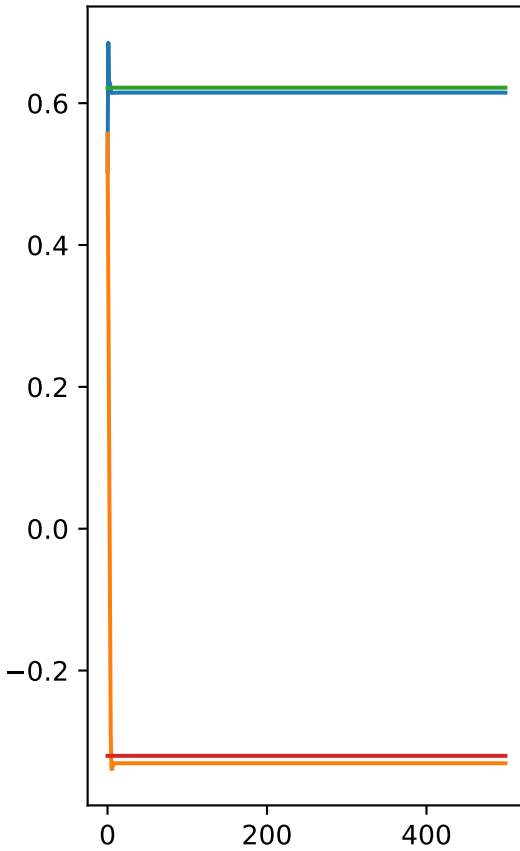
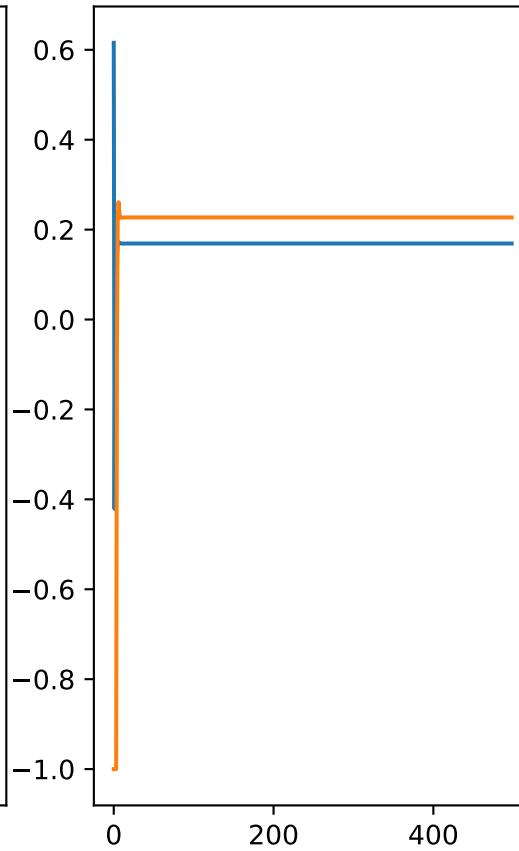


Reward: quartic_root
Speed = 290.8612205796124 [rad/s]

State vs step



Action vs step



Reward vs step

