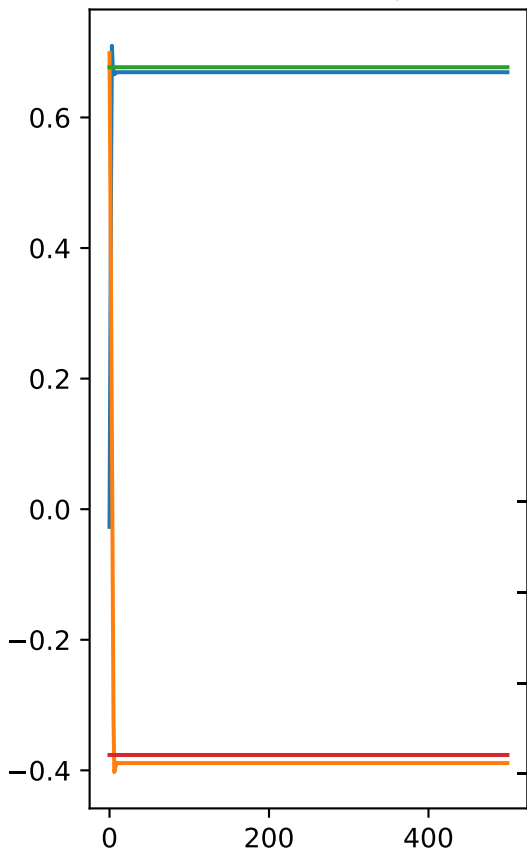
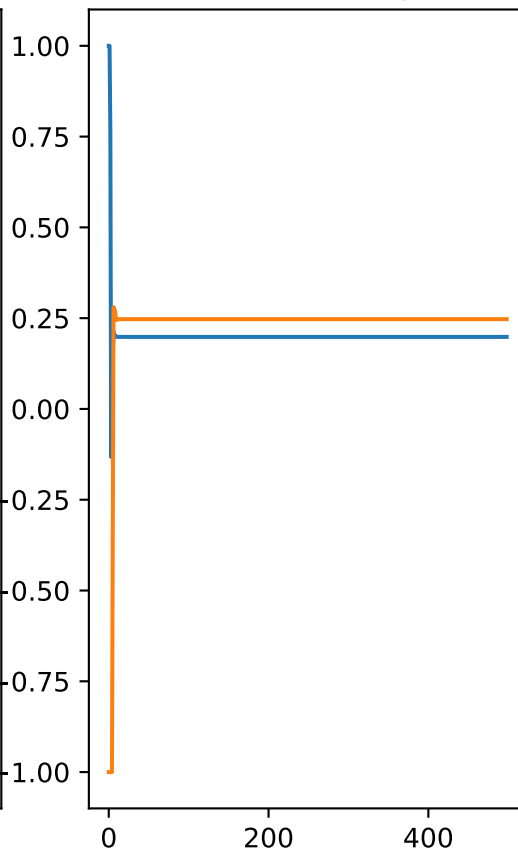


Reward: quartic_root
Speed = 122.15768556936197 [rad/s]

State vs step



Action vs step



Reward vs step

