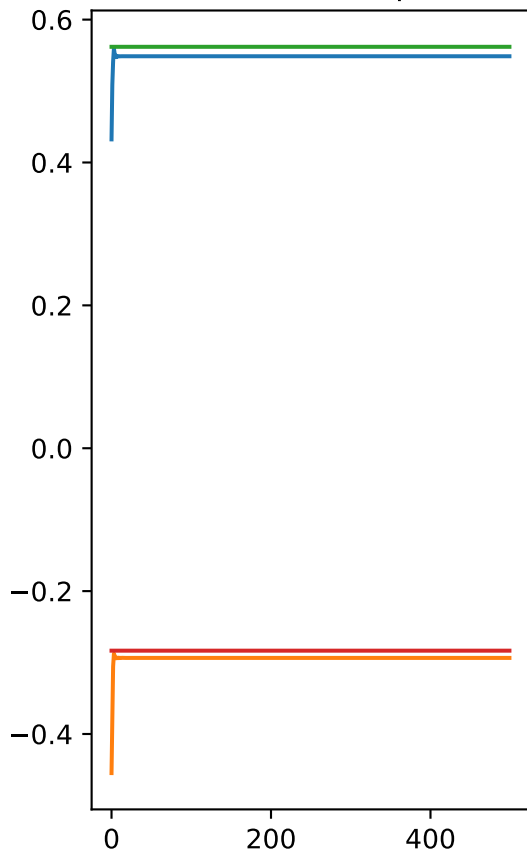
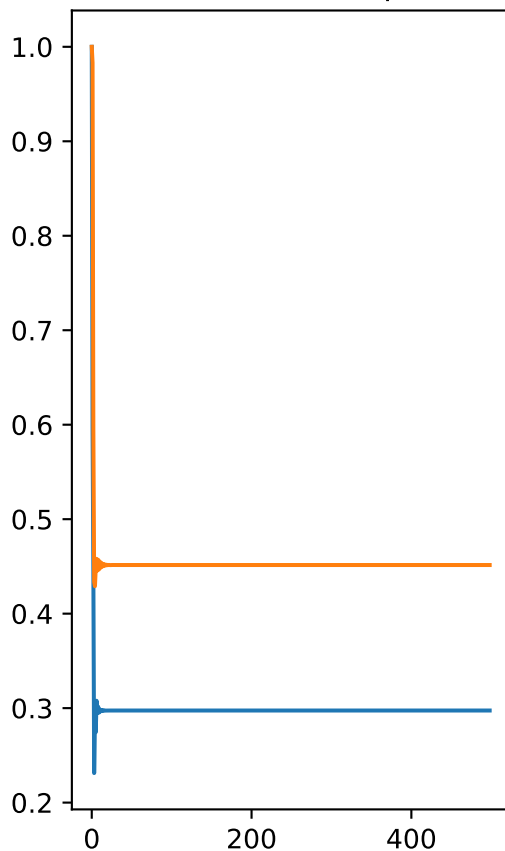


Reward: quartic_root
Speed = 154.70458400746497 [rad/s]

State vs step



Action vs step



Reward vs step

