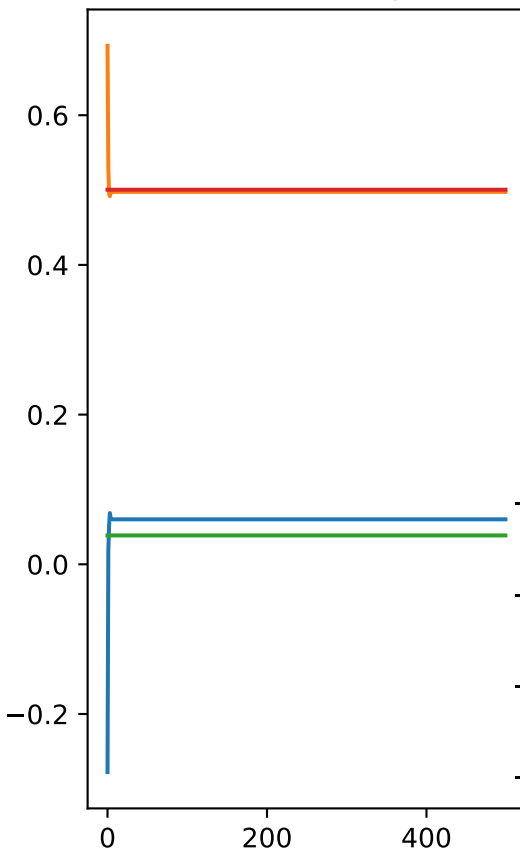
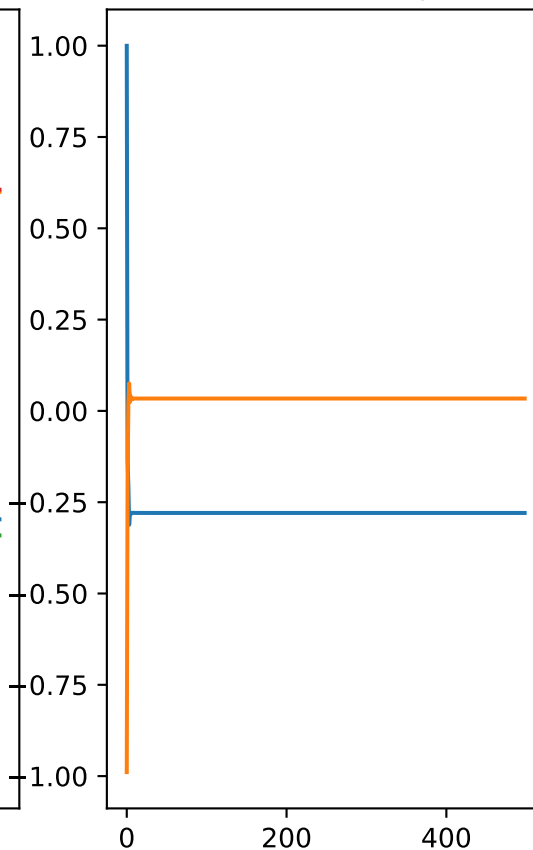


Reward: quartic_root
Speed = 266.595543265895 [rad/s]

State vs step



Action vs step



Reward vs step

