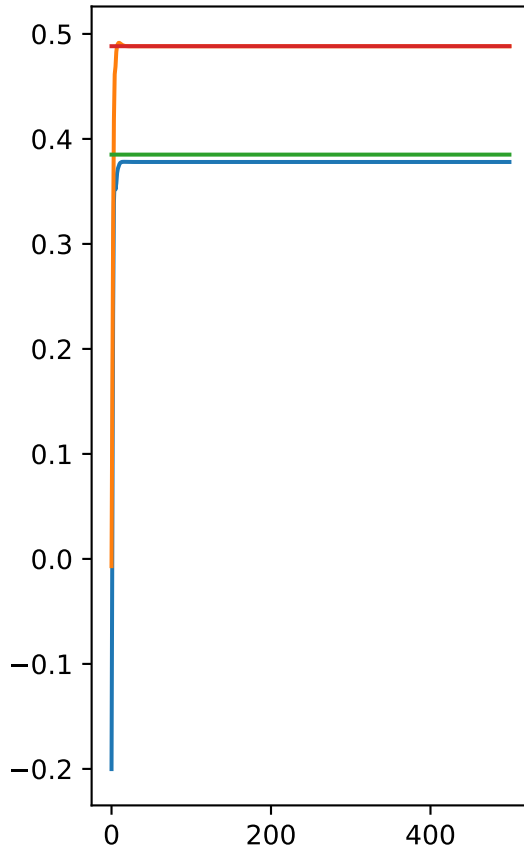
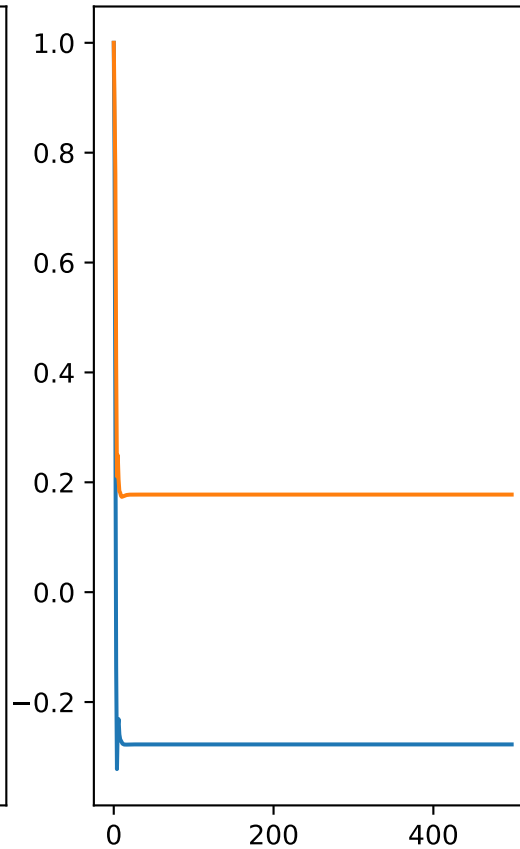


Reward: quadratic_2
Speed = 555.0691504626835 [rad/s]

State vs step



Action vs step



Reward vs step

