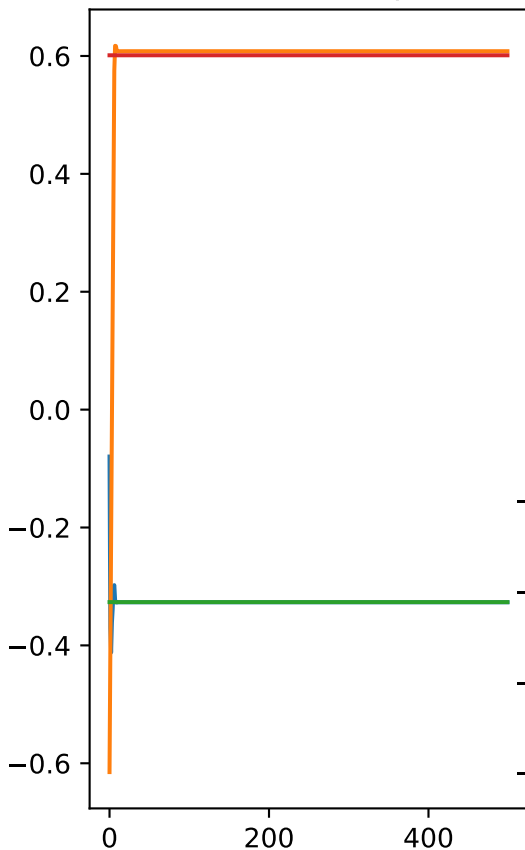
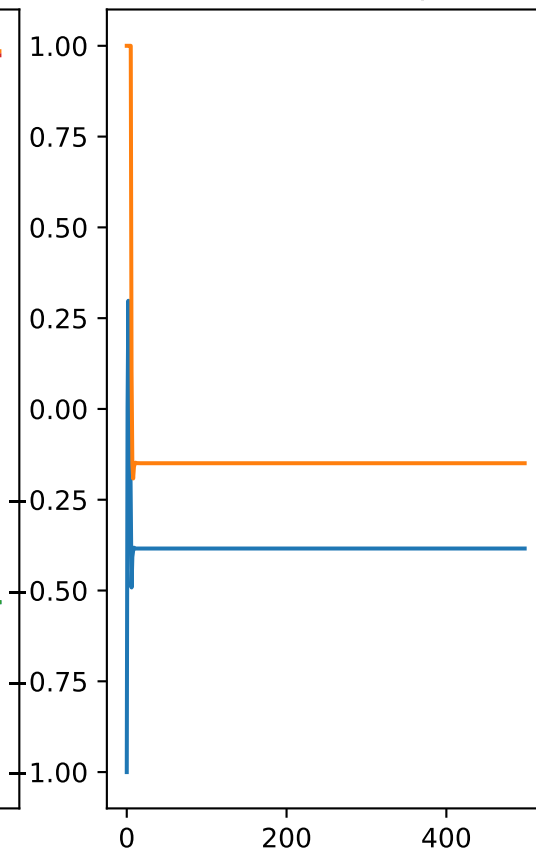


Reward: quartic_root
Speed = 95.6300794315156 [rad/s]

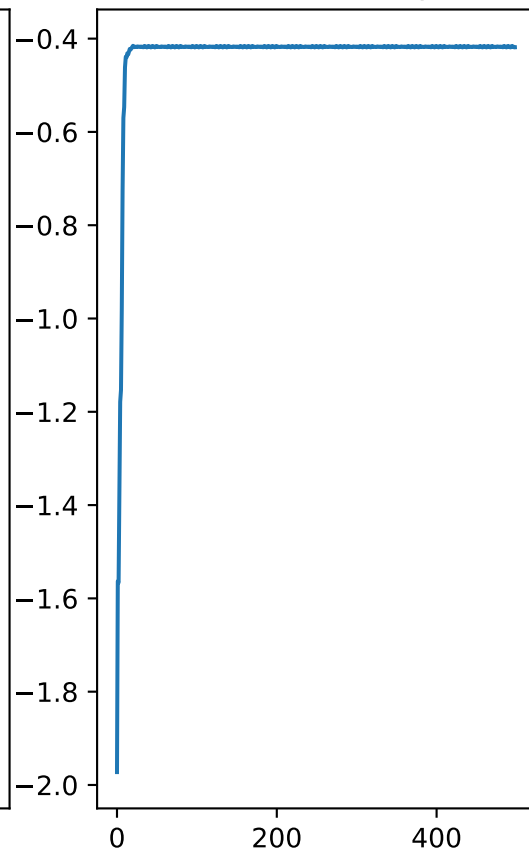
State vs step



Action vs step



Reward vs step



— I_d — I_d^{ref}
— I_q — I_q^{ref}

— V_d — V_q