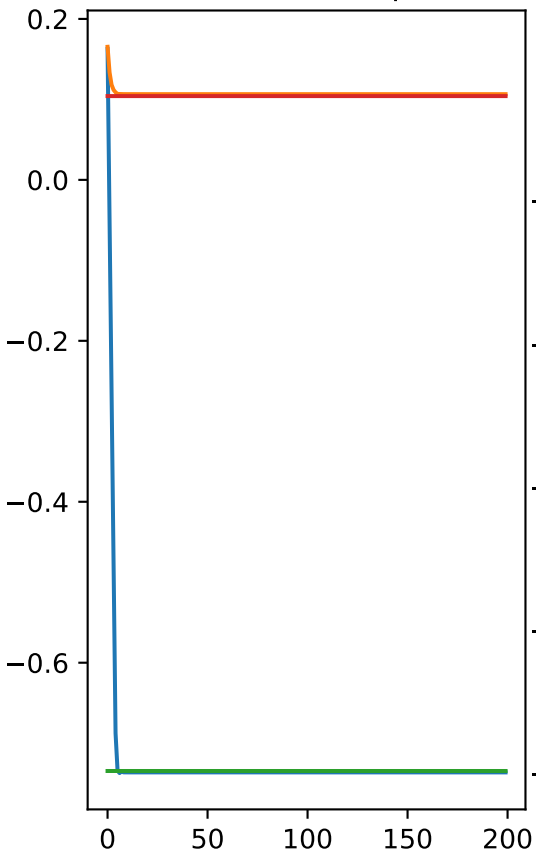
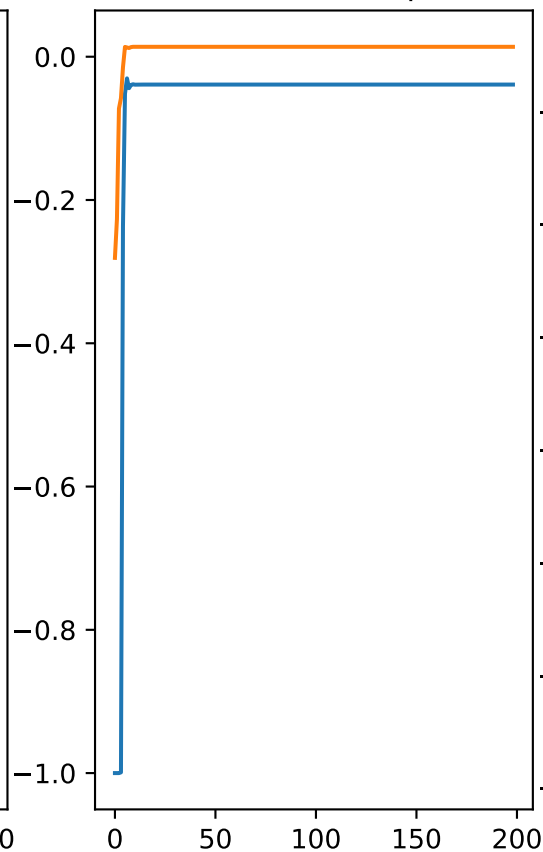


Reward: square_root
Speed = 823.9769562973099 [rad/s]

State vs step



Action vs step



Reward vs step

