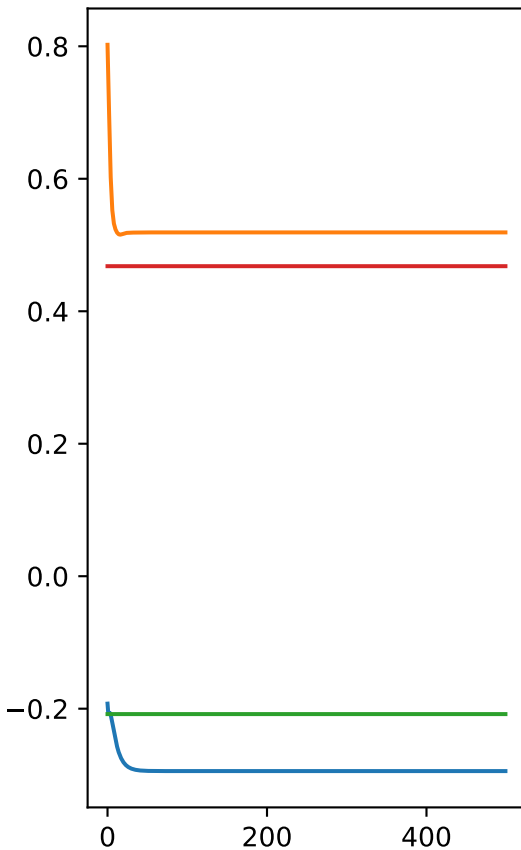
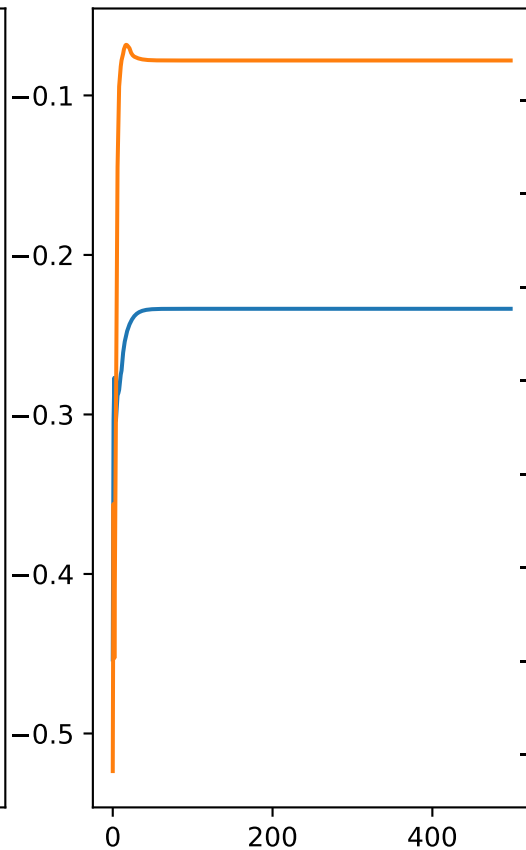


Reward: quadratic  
Speed = 513.223158247999 [rad/s]

State vs step



Action vs step



Reward vs step

