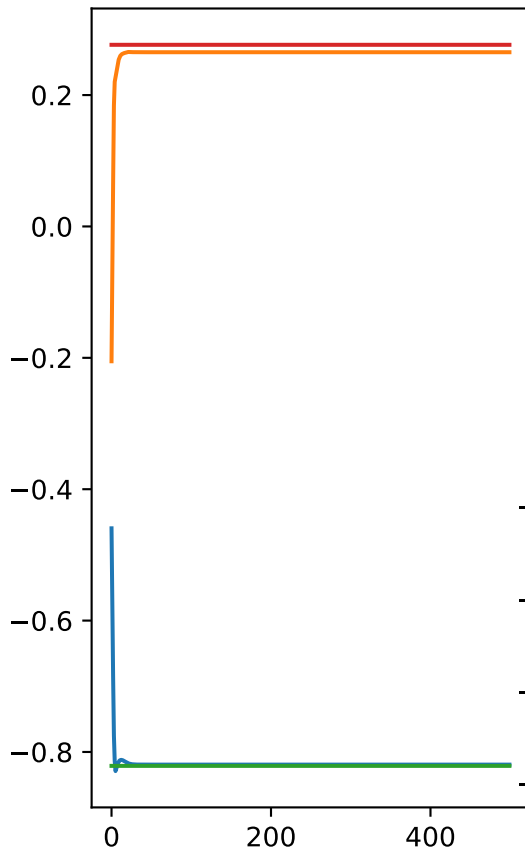
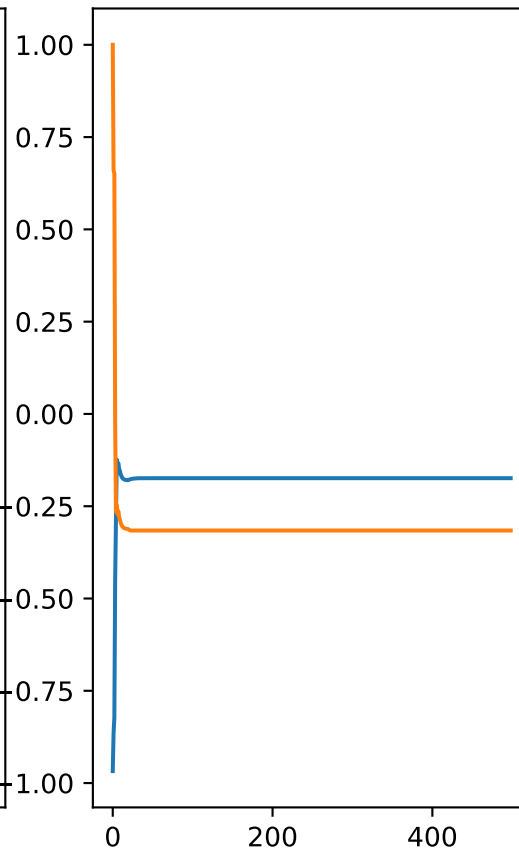


Reward: quadratic
Speed = 473.16154222031645 [rad/s]

State vs step



Action vs step



Reward vs step

