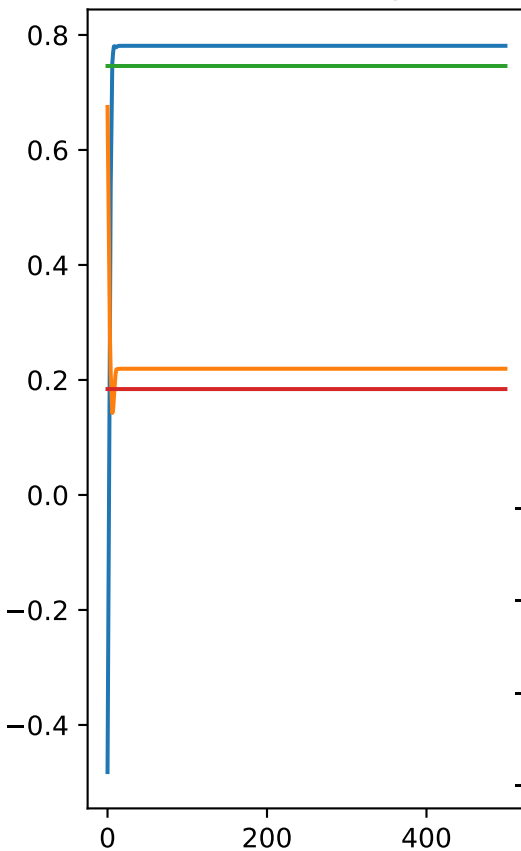
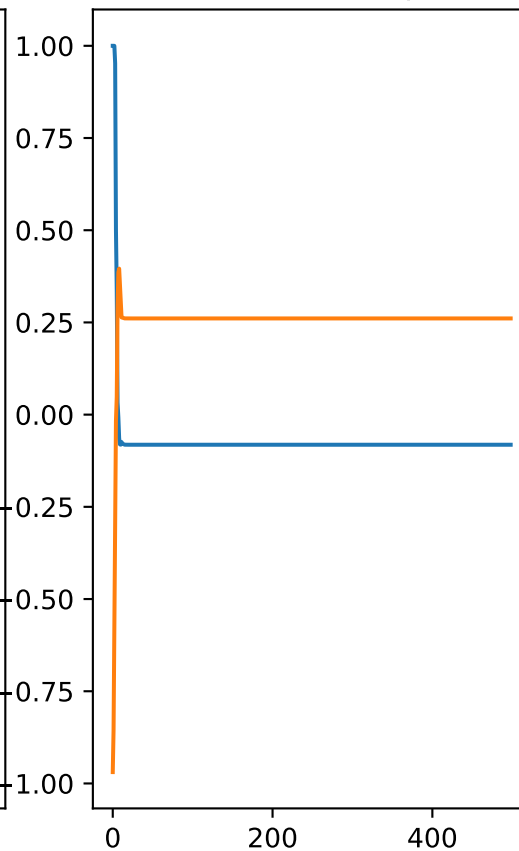


Reward: quadratic_2
Speed = 733.6498308476847 [rad/s]

State vs step



Action vs step



Reward vs step

