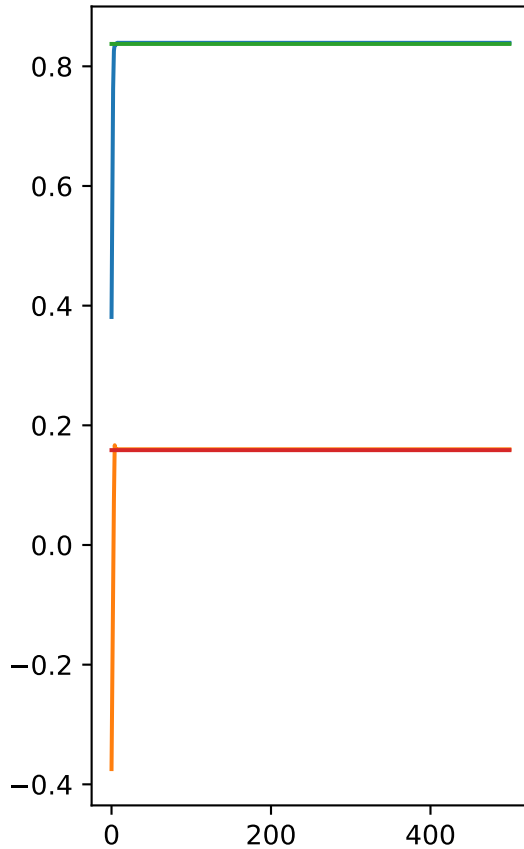
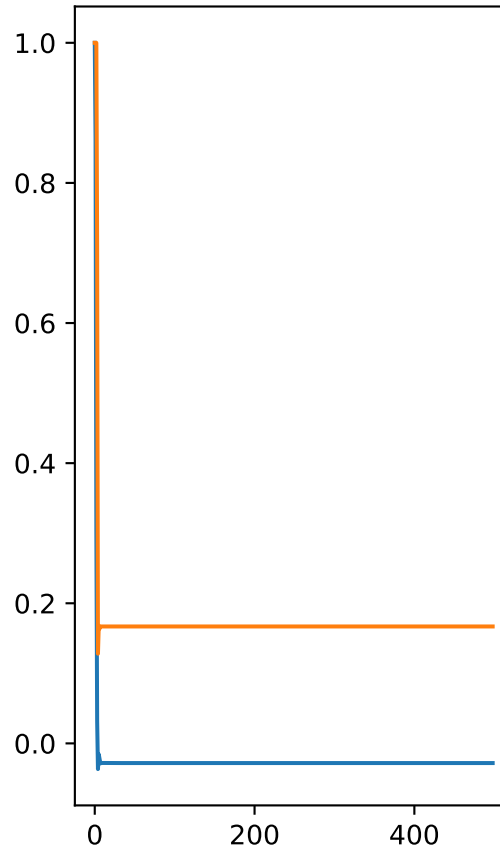


Reward: square_root
Speed = 518.2120038225848 [rad/s]

State vs step



Action vs step



Reward vs step

