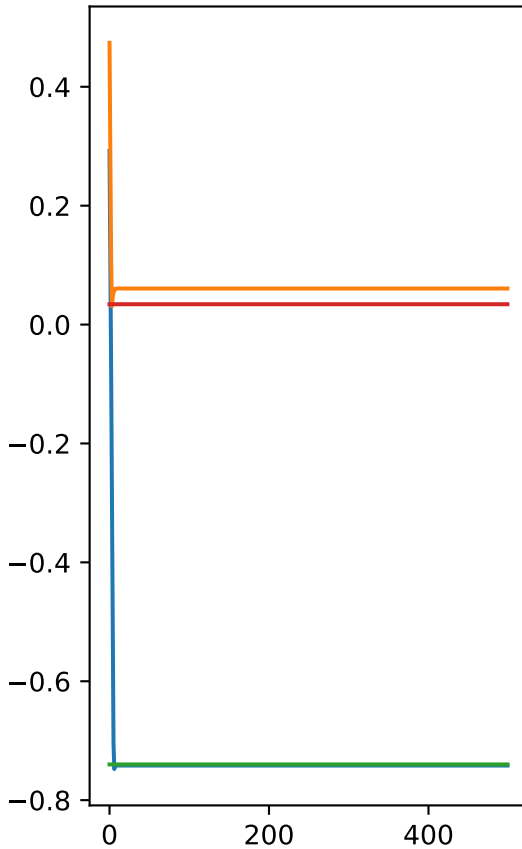
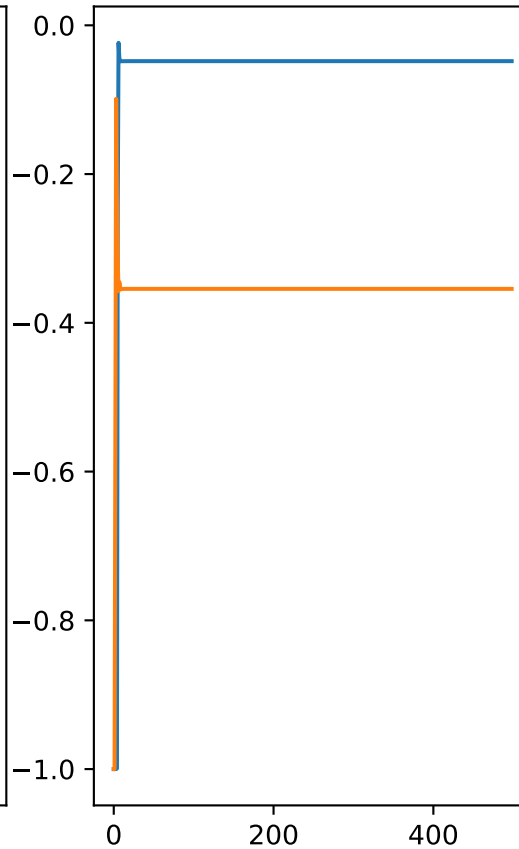


Reward: quartic_root
Speed = 80.2111475802567 [rad/s]

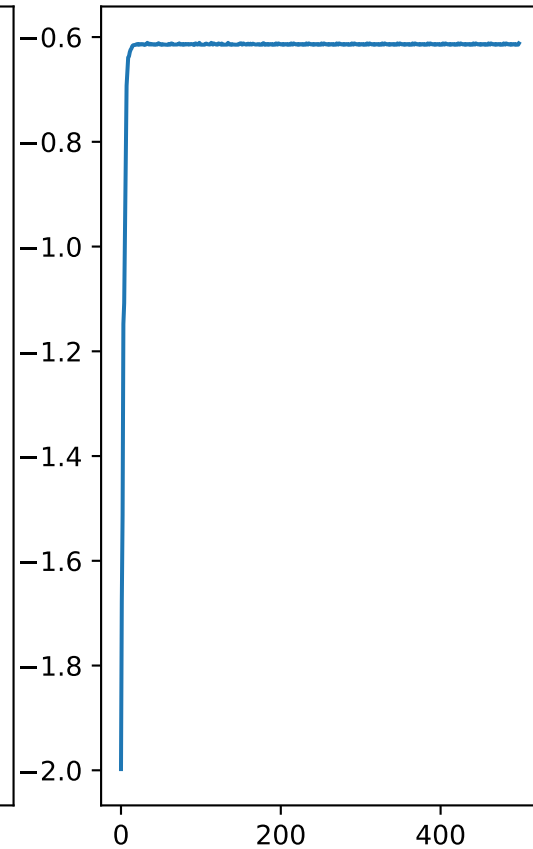
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq