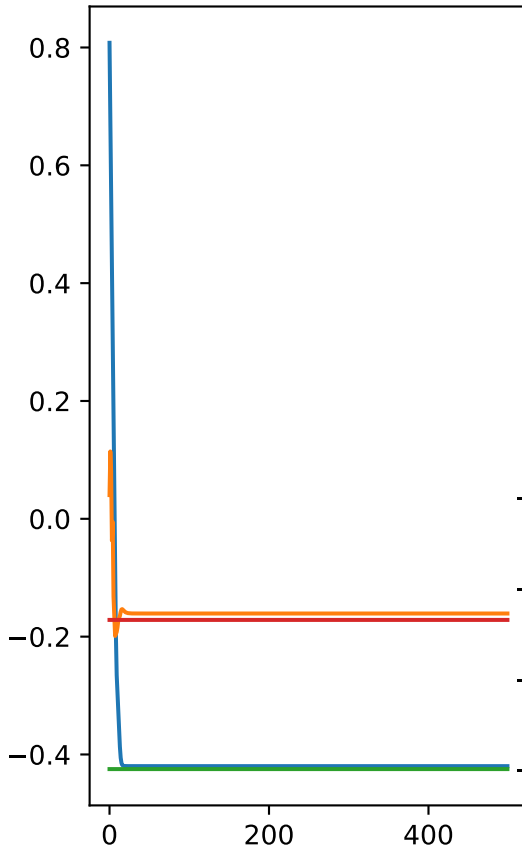
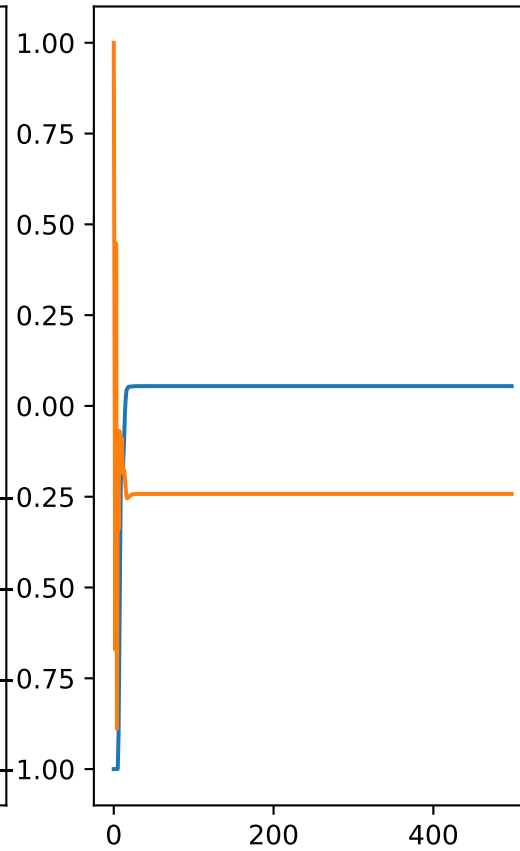


Reward: quadratic_2
Speed = 466.1620807629373 [rad/s]

State vs step



Action vs step



Reward vs step

