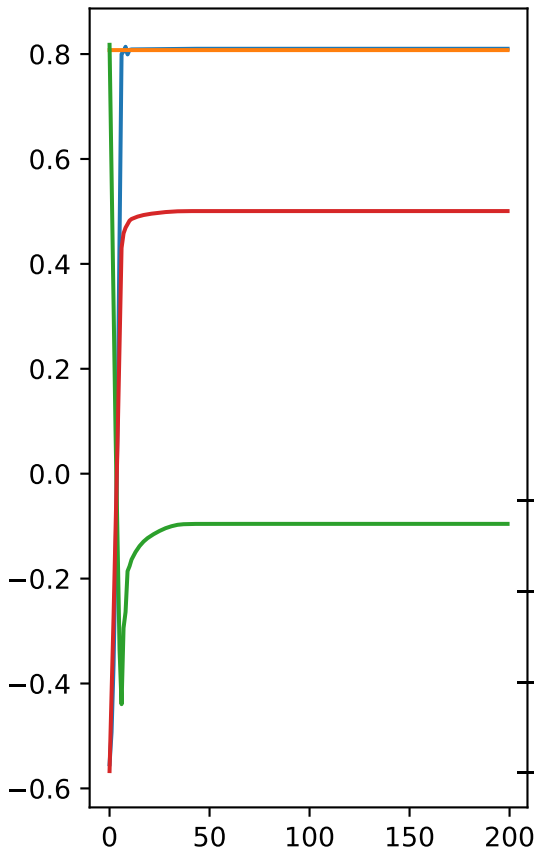
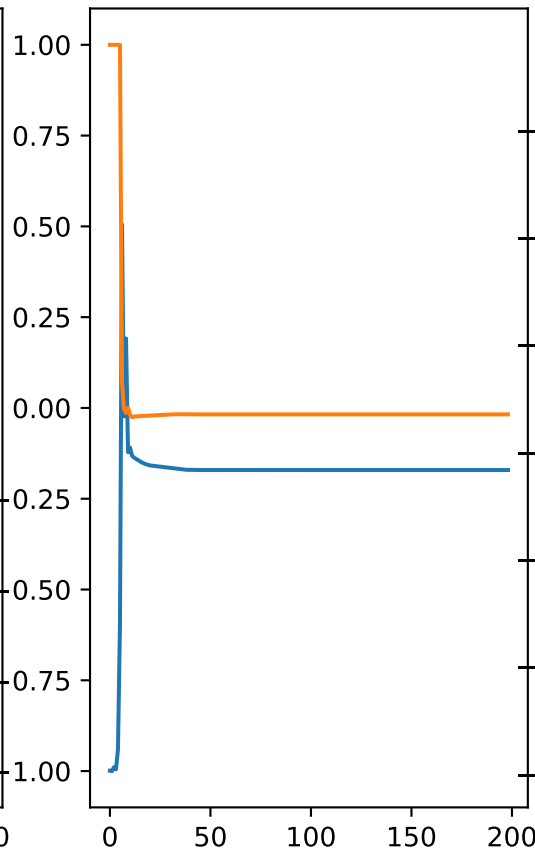


Reward: absolute  
Speed = 352.6730812894322 [rad/s]

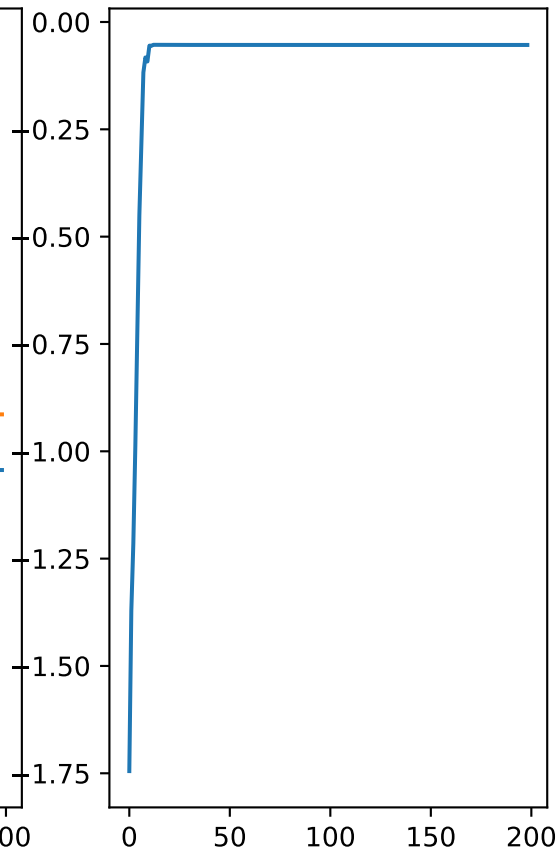
State vs step



Action vs step



Reward vs step



$T_e$   $T_{ref}$   $I_d$   $I_q$

$V_d$   $V_q$