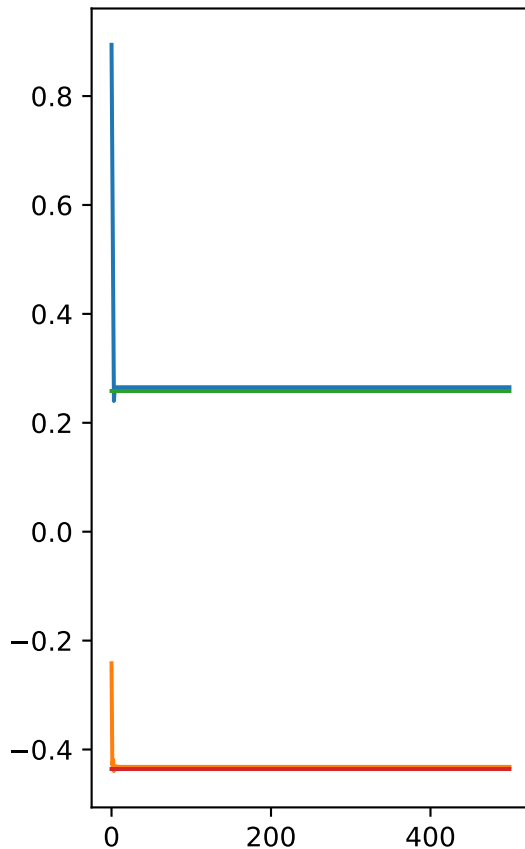
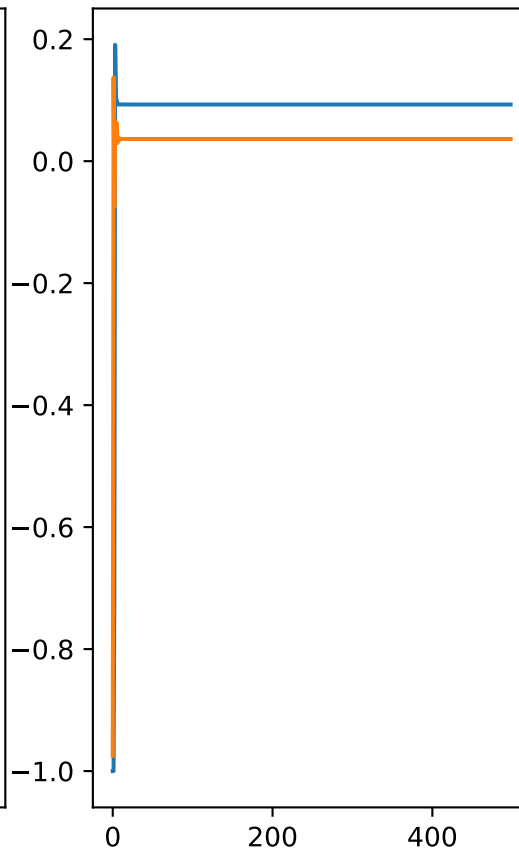


Reward: quartic_root
Speed = 819.3902189190017 [rad/s]

State vs step



Action vs step



Reward vs step

