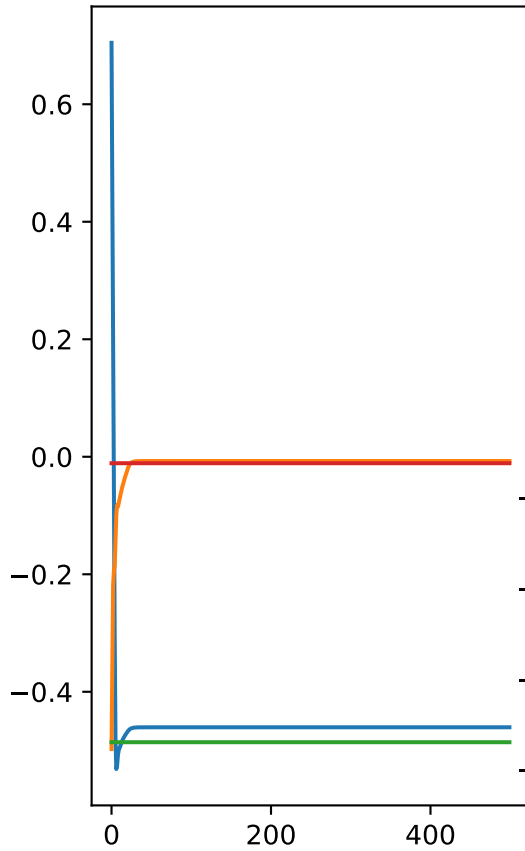
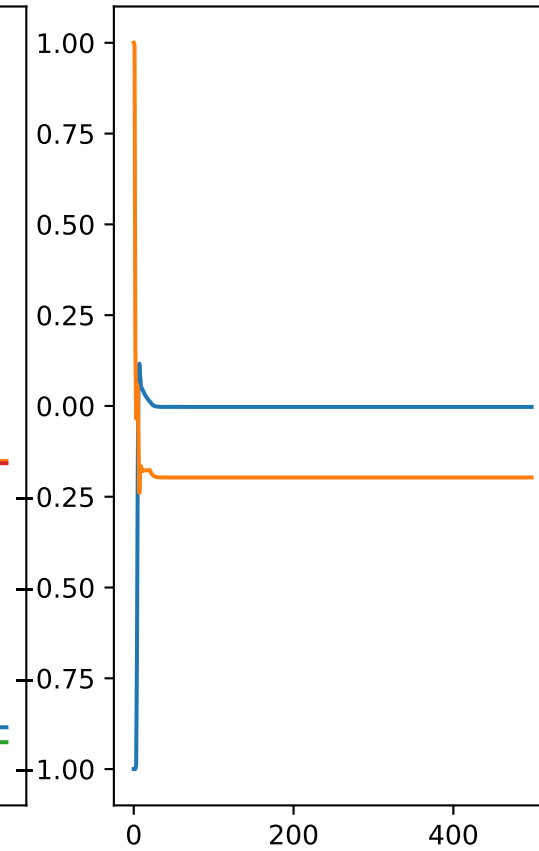


Reward: quadratic_2
Speed = 851.8742844404329 [rad/s]

State vs step



Action vs step



Reward vs step

