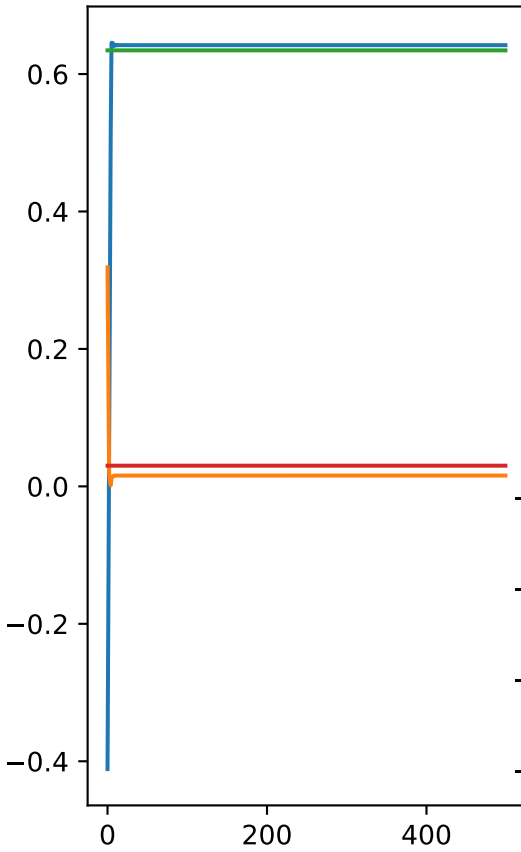
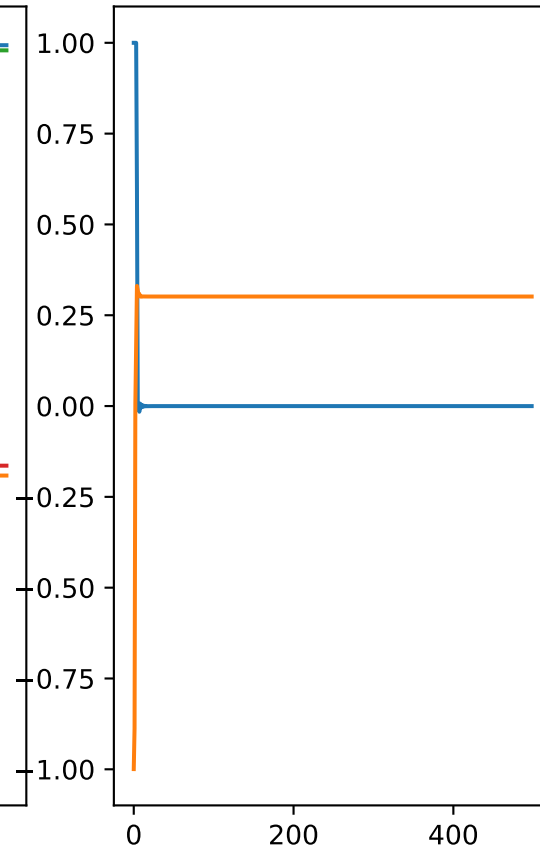


Reward: quartic_root
Speed = 87.86406762595185 [rad/s]

State vs step



Action vs step



Reward vs step

