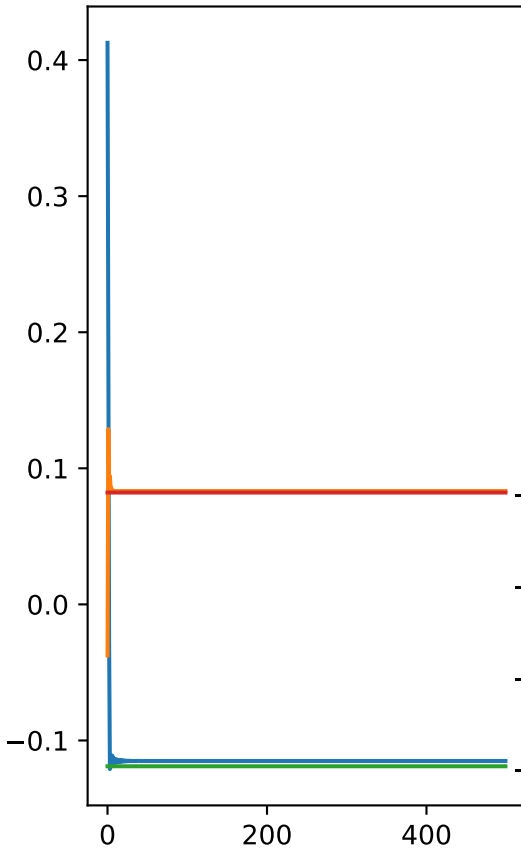
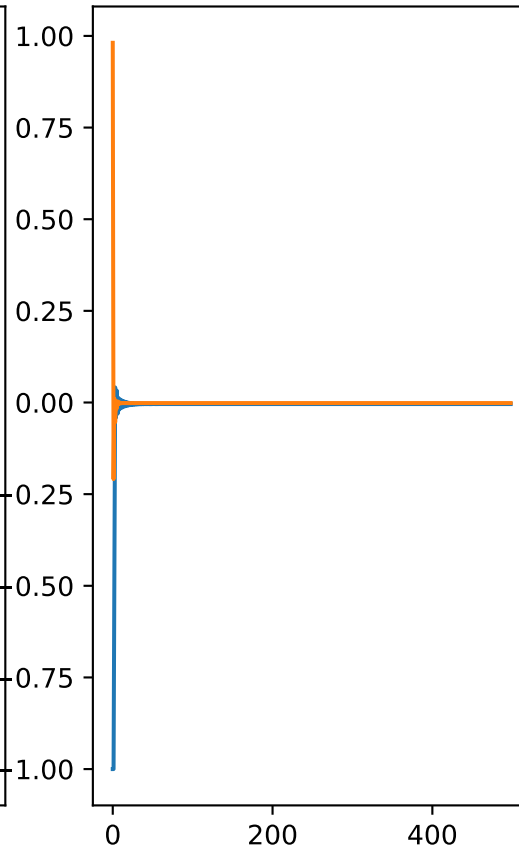


Reward: quartic_root
Speed = 1002.1680744714814 [rad/s]

State vs step



Action vs step



Reward vs step

