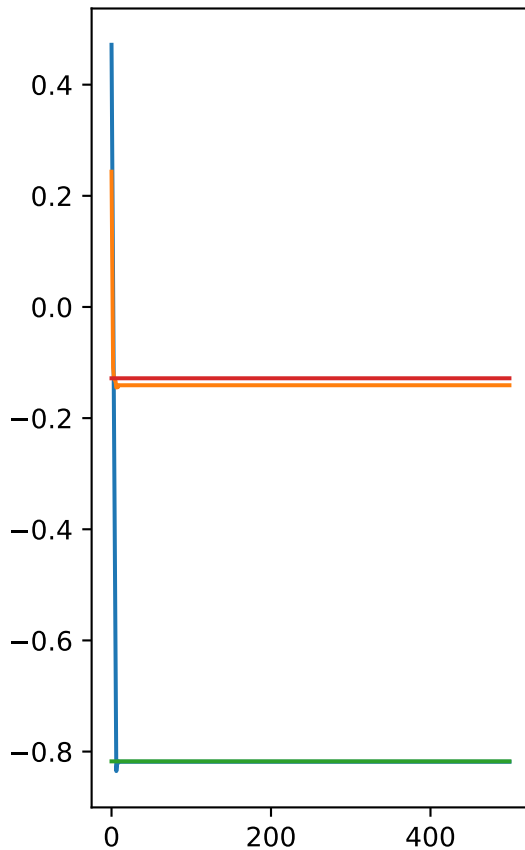
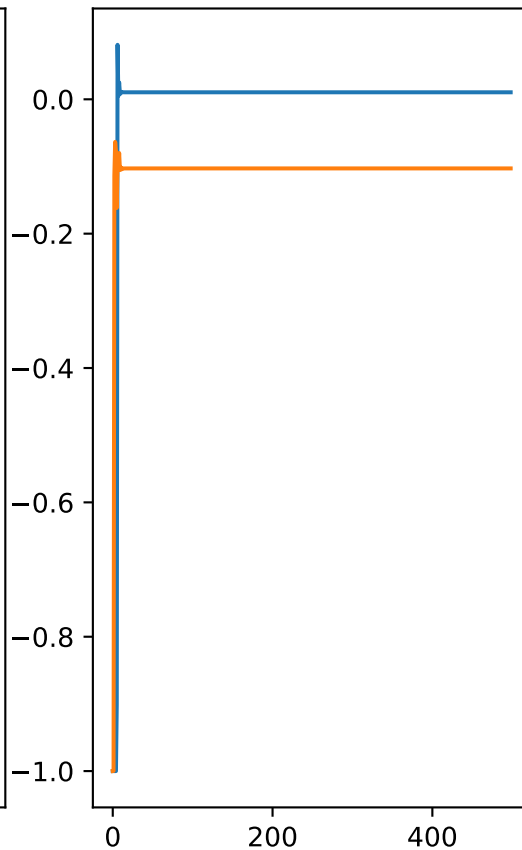


Reward: quartic_root
Speed = 296.4406824631667 [rad/s]

State vs step



Action vs step



Reward vs step

