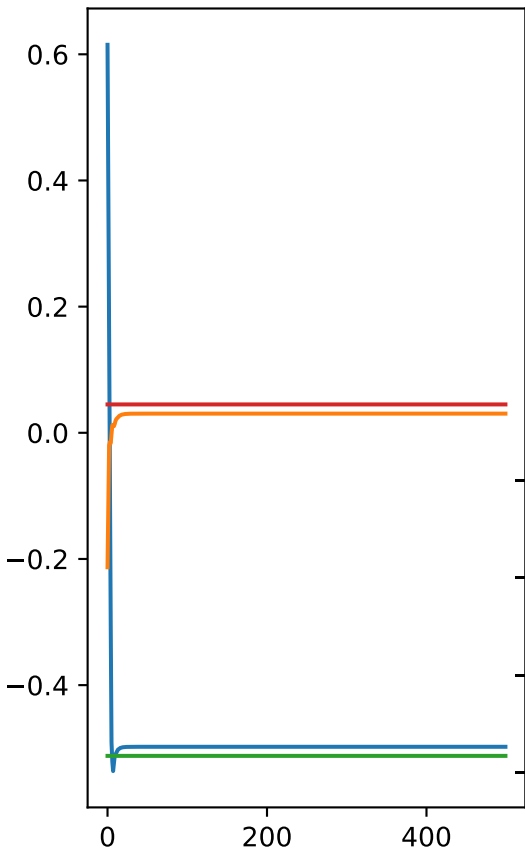
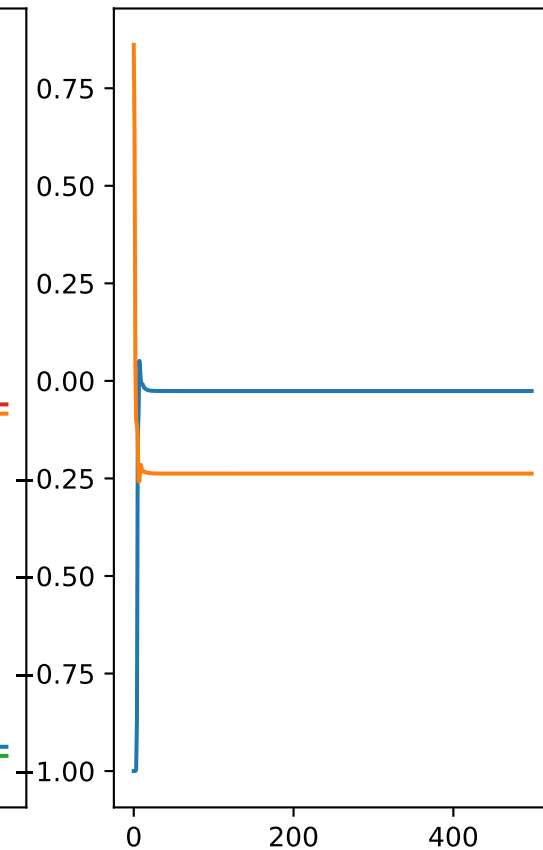


Reward: quadratic_2
Speed = 41.481587513480264 [rad/s]

State vs step



Action vs step



Reward vs step

