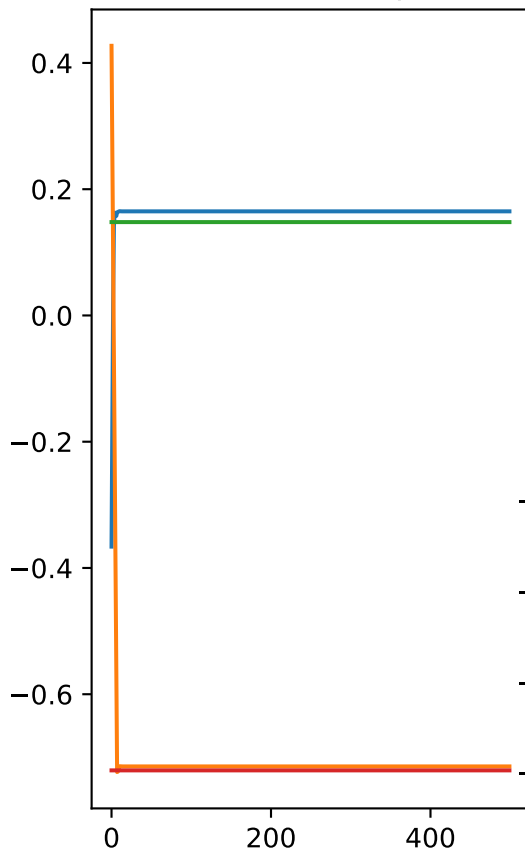
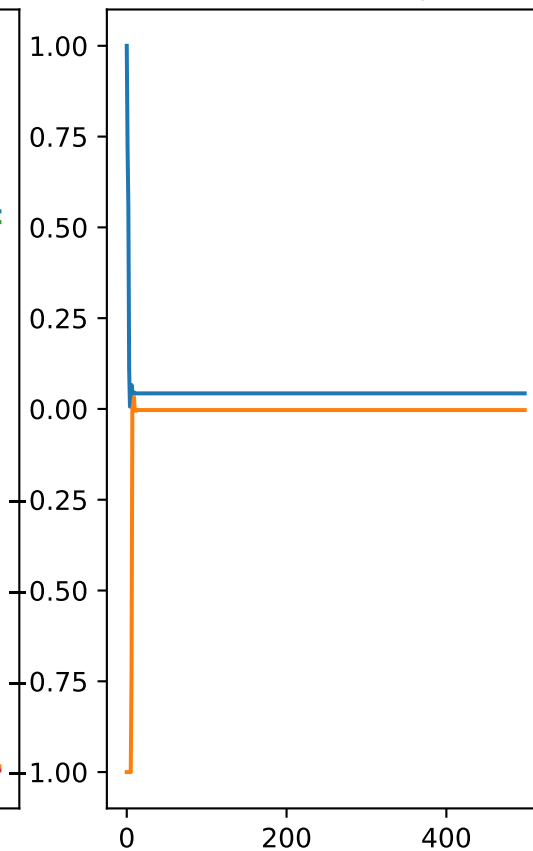


Reward: quartic\_root  
Speed = 489.849687753134 [rad/s]

State vs step



Action vs step



Reward vs step

