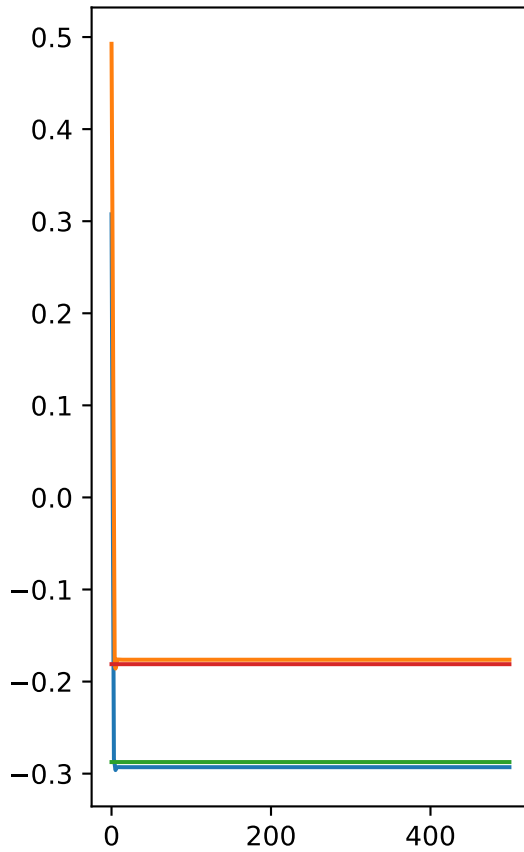
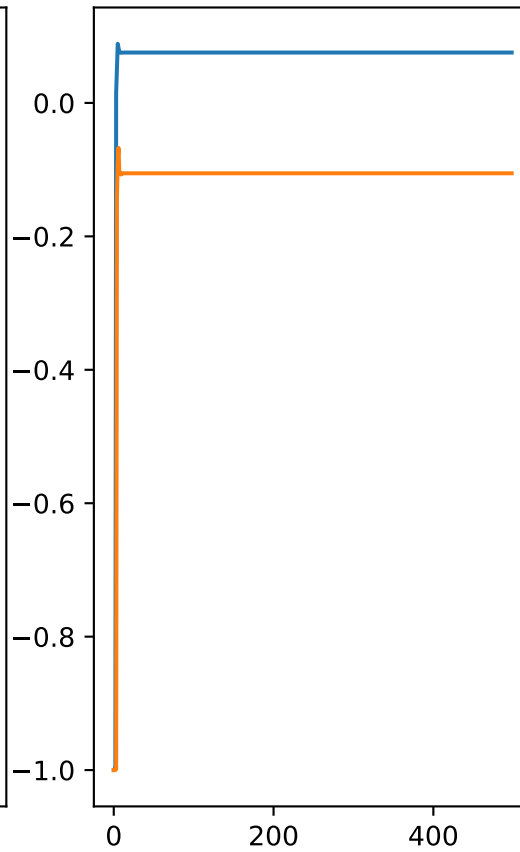


Reward: quartic_root
Speed = 176.93449729143916 [rad/s]

State vs step



Action vs step



Reward vs step

