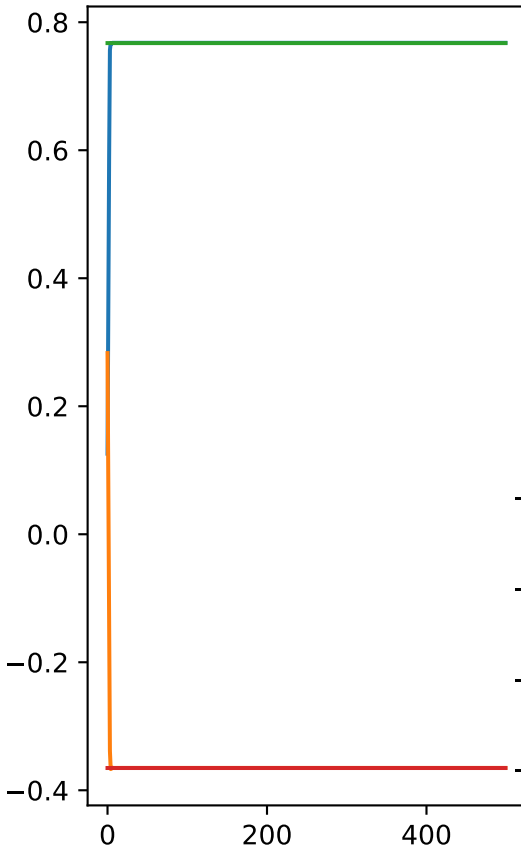
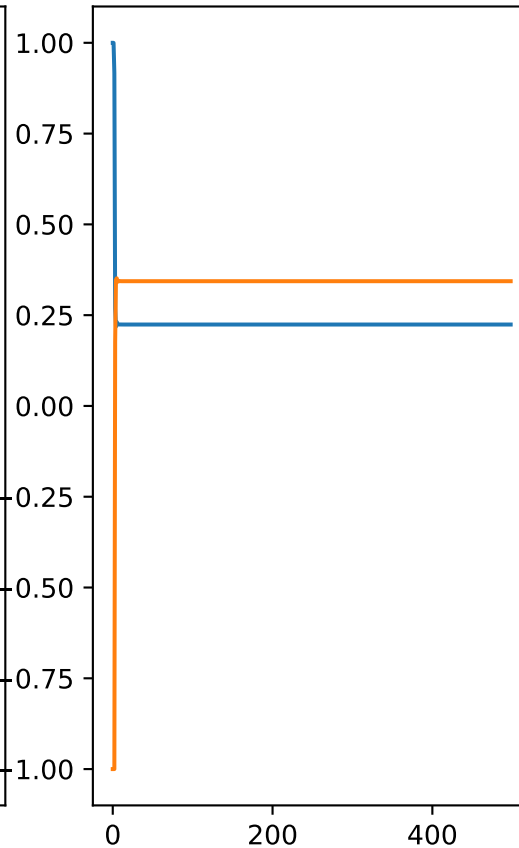


Reward: square\_root  
Speed = 14.76548496628754 [rad/s]

State vs step



Action vs step



Reward vs step

