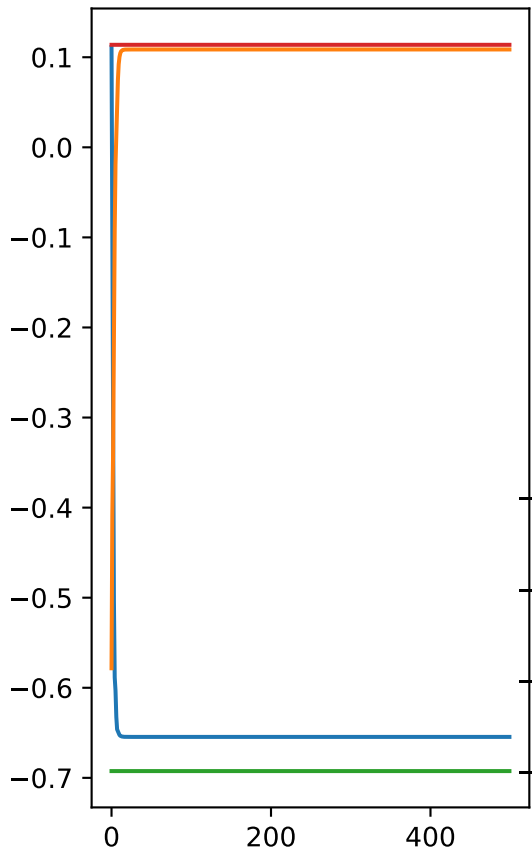
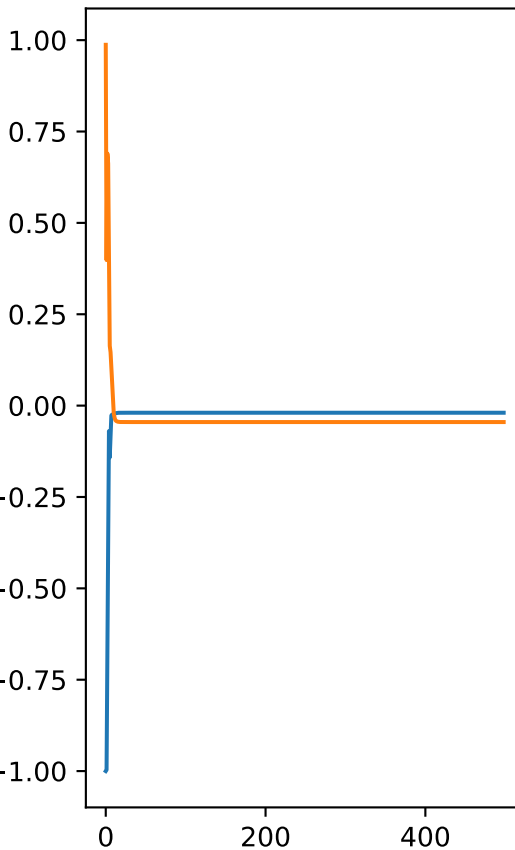


Reward: quadratic
Speed = 219.54706794233533 [rad/s]

State vs step



Action vs step



Reward vs step

