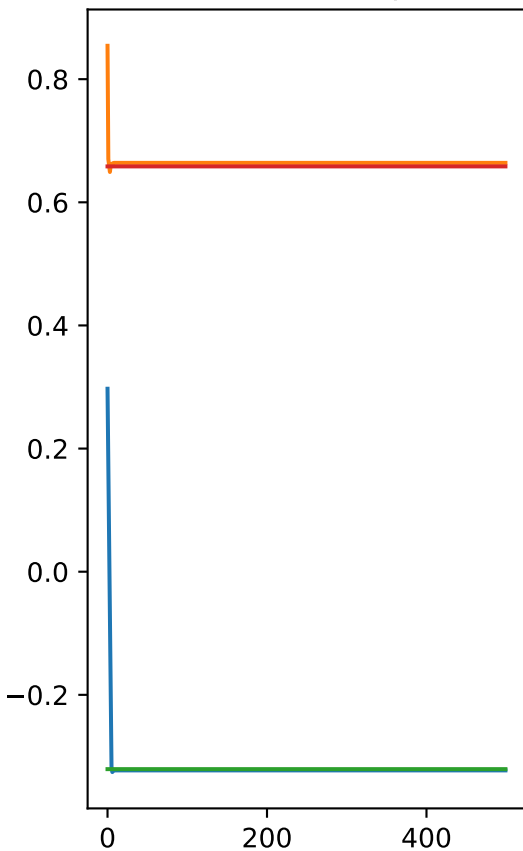
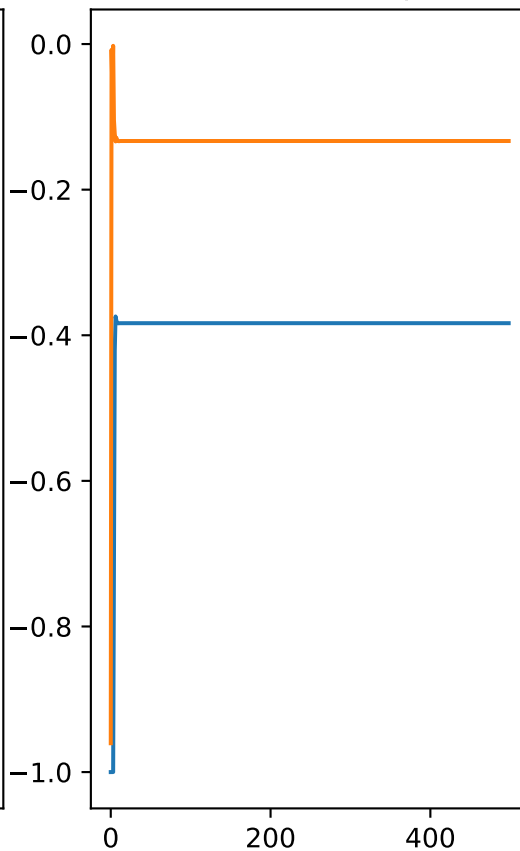


Reward: quartic_root
Speed = 120.92618474555239 [rad/s]

State vs step



Action vs step



Reward vs step

