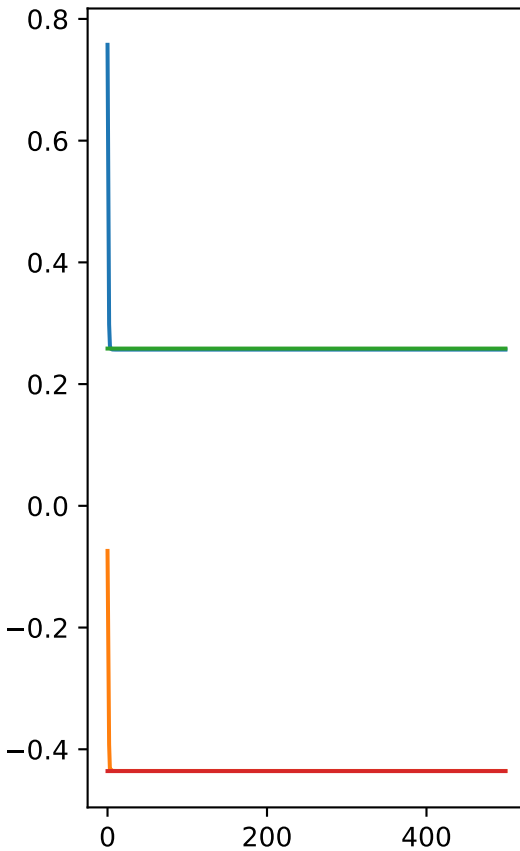
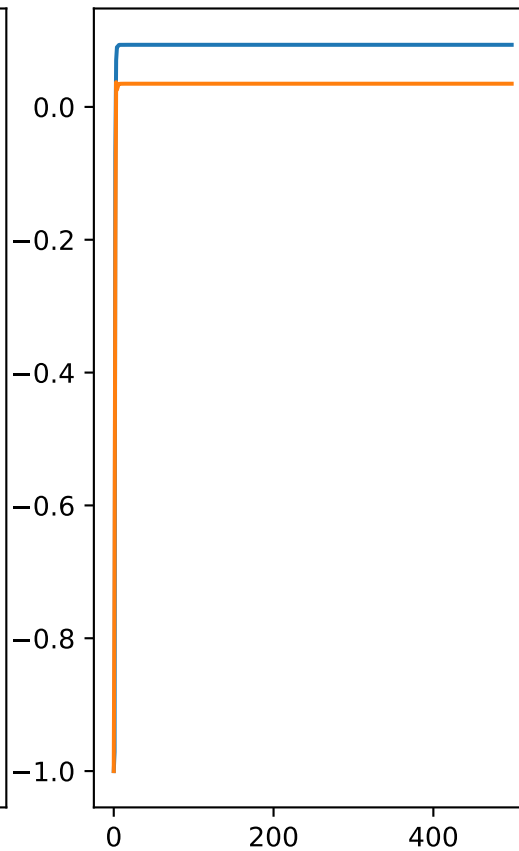


Reward: square\_root  
Speed = 819.3902189190017 [rad/s]

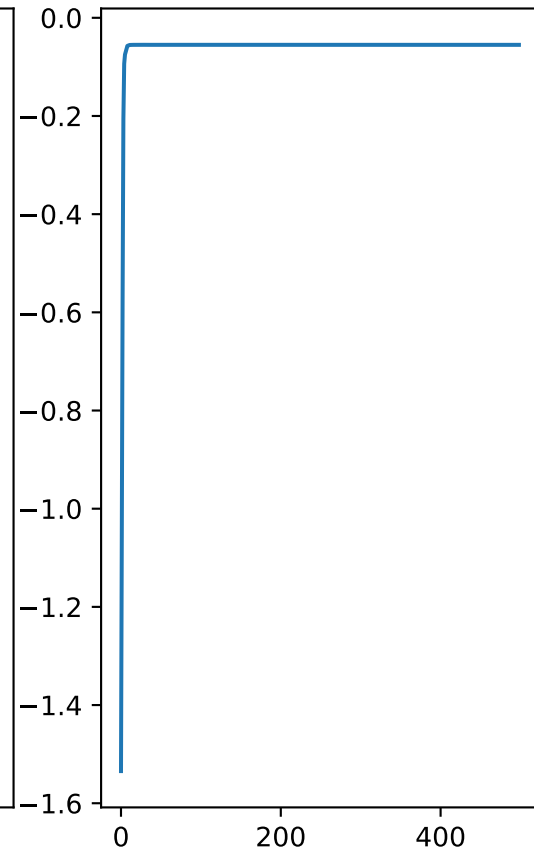
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq