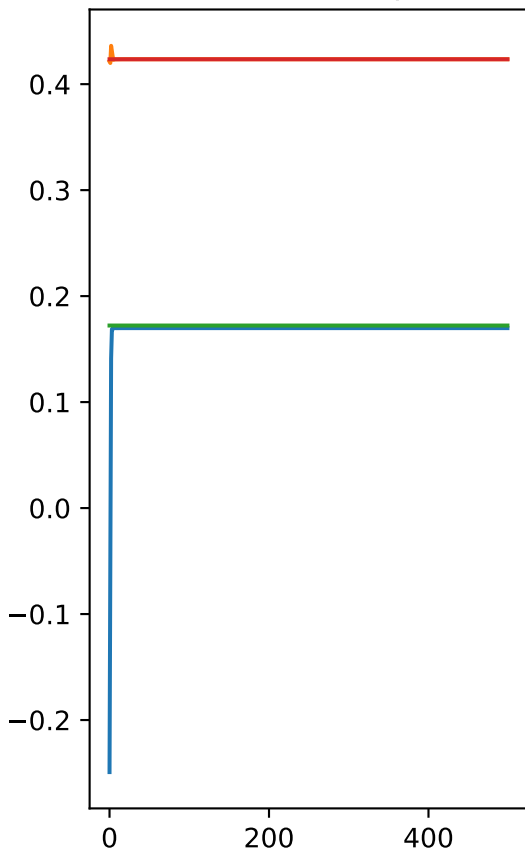
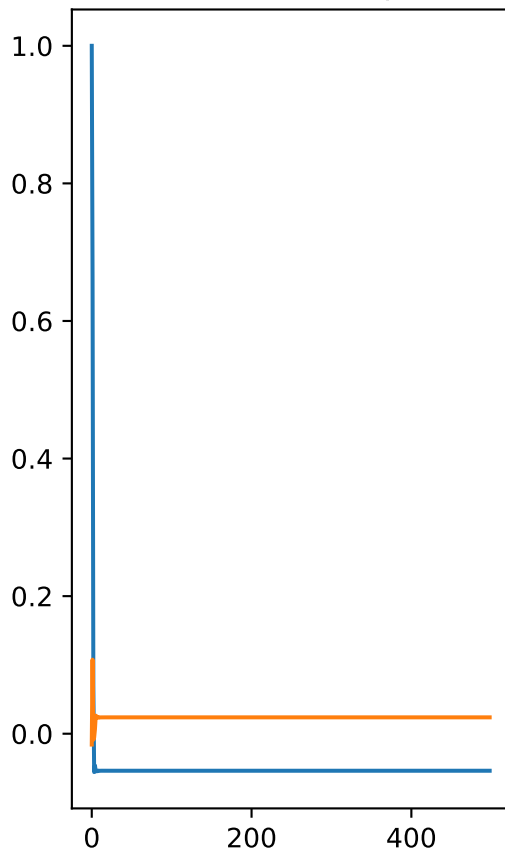


Reward: quartic_root_2
Speed = 351.46881648925523 [rad/s]

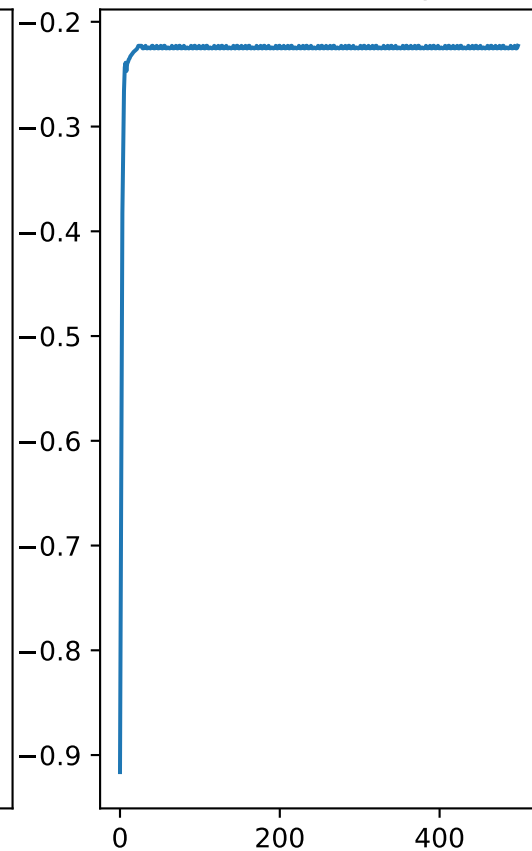
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq