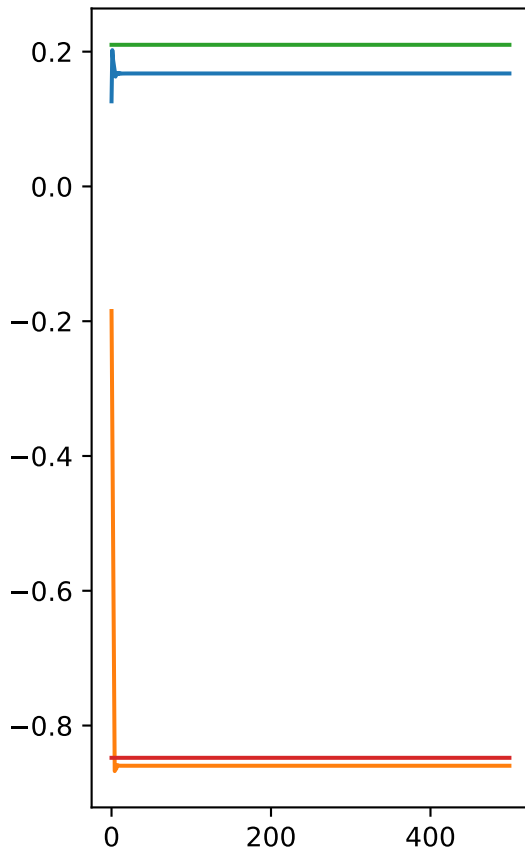
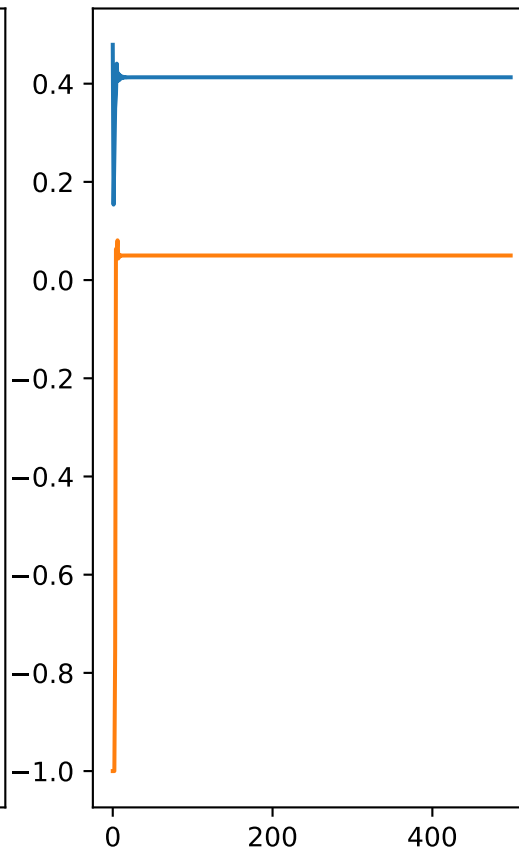


Reward: quartic_root
Speed = 640.331967171522 [rad/s]

State vs step



Action vs step



Reward vs step

