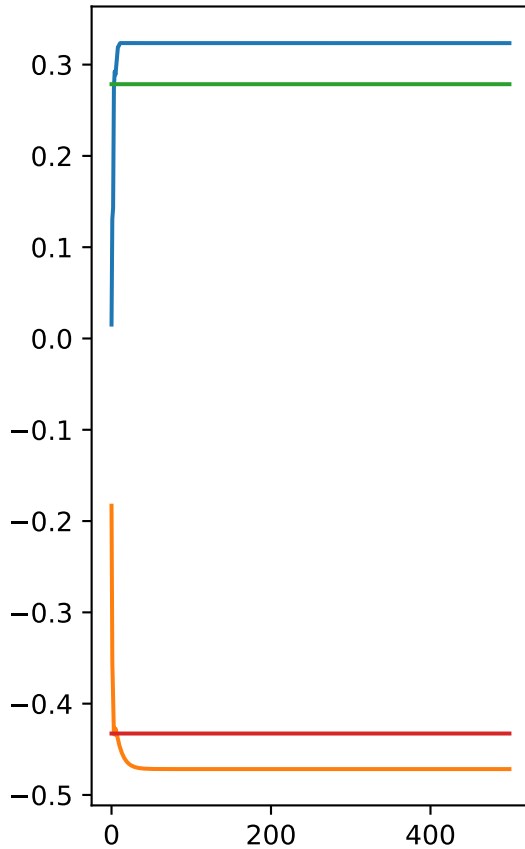
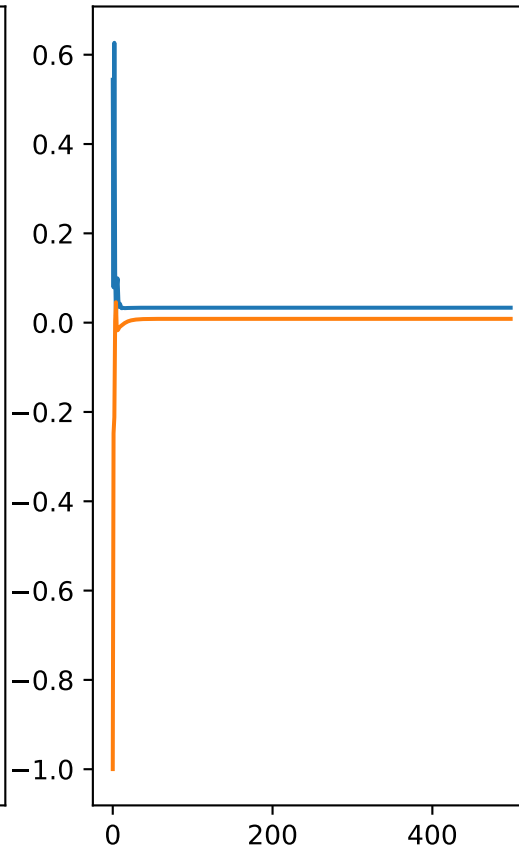


Reward: quadratic
Speed = 33.6401733991077 [rad/s]

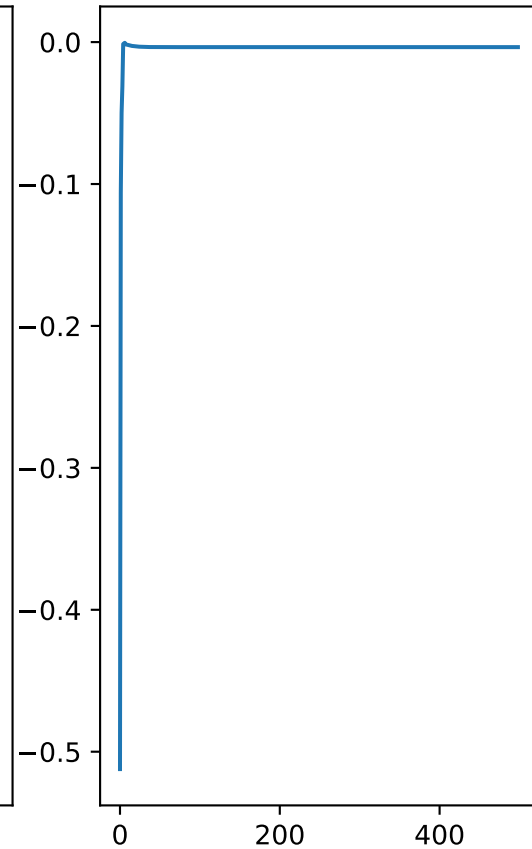
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq