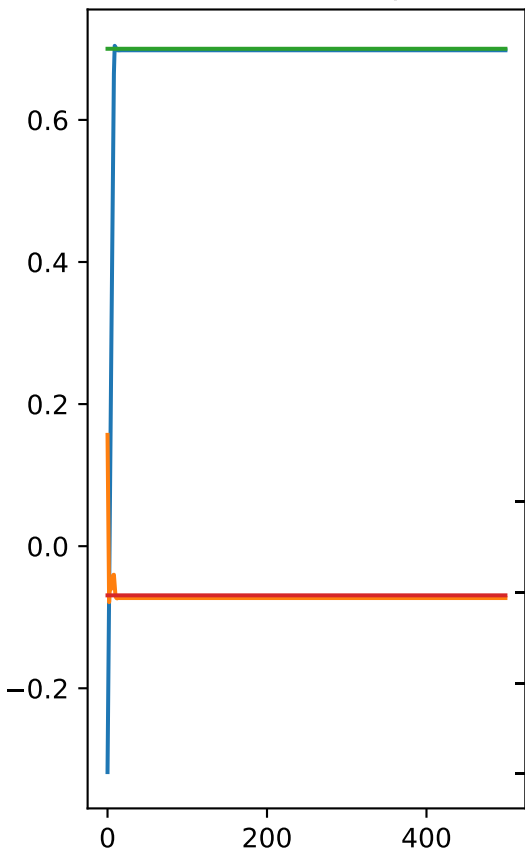
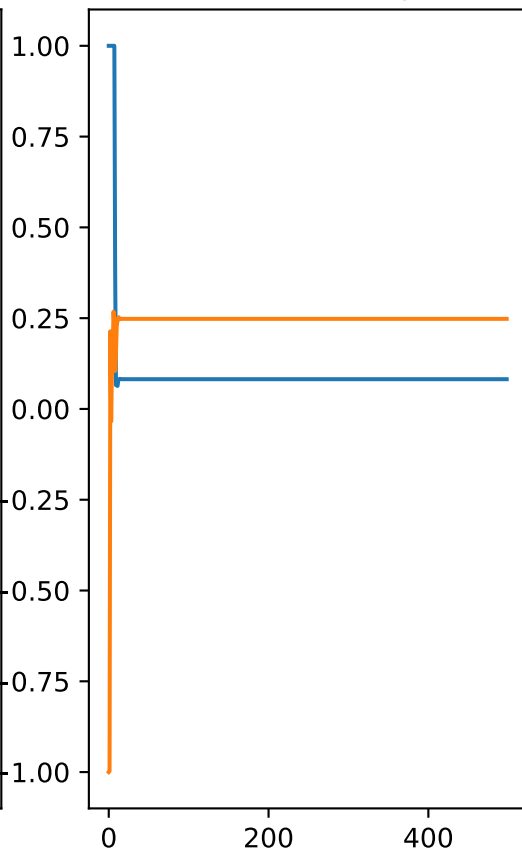


Reward: square_root
Speed = 1111.4955143958987 [rad/s]

State vs step



Action vs step



Reward vs step

