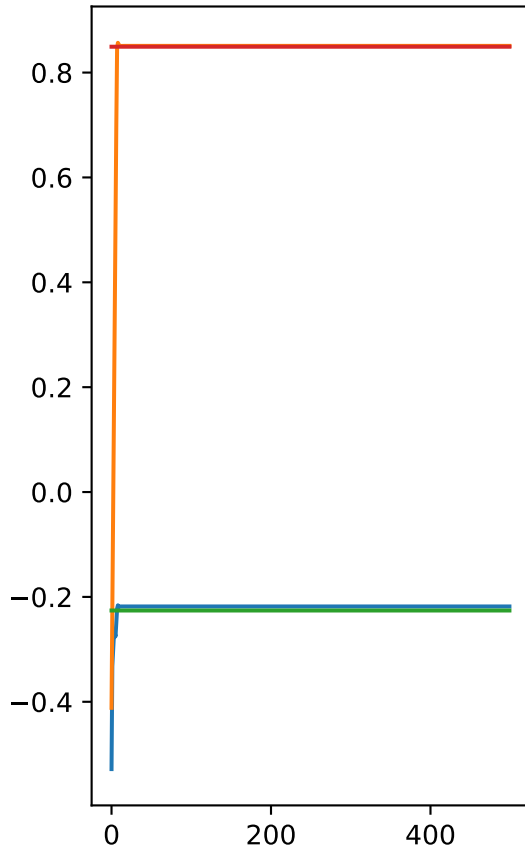
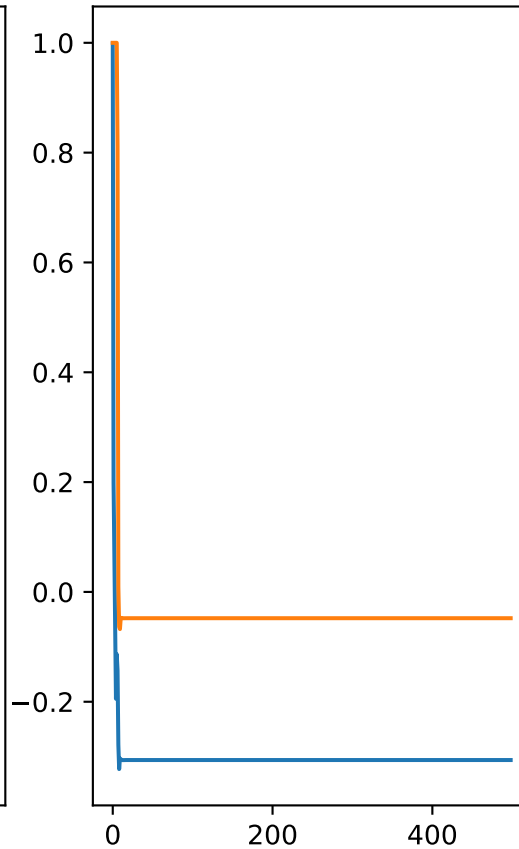


Reward: quartic\_root\_2  
Speed = 715.6296761673397 [rad/s]

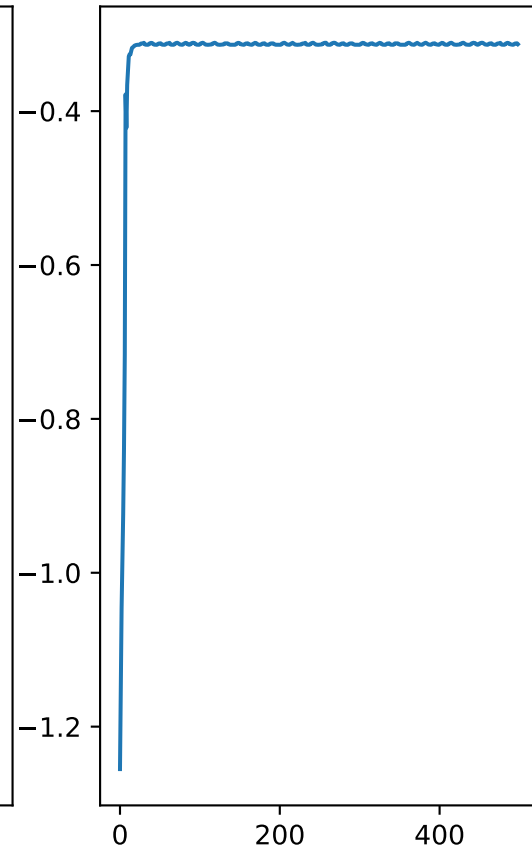
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq