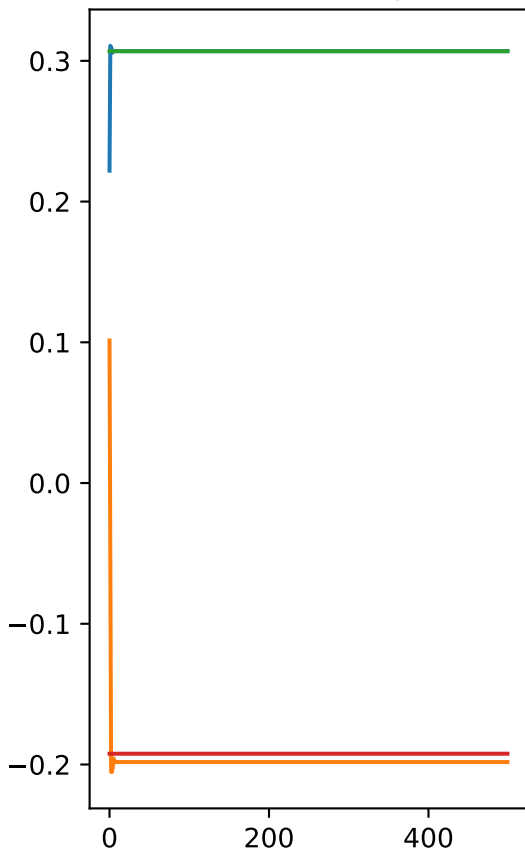
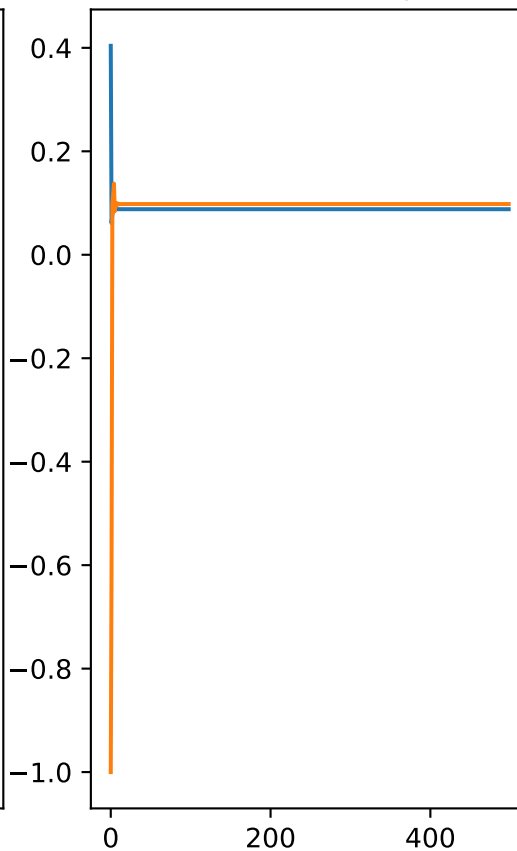


Reward: quartic_root
Speed = 1067.8148122496098 [rad/s]

State vs step



Action vs step



Reward vs step

