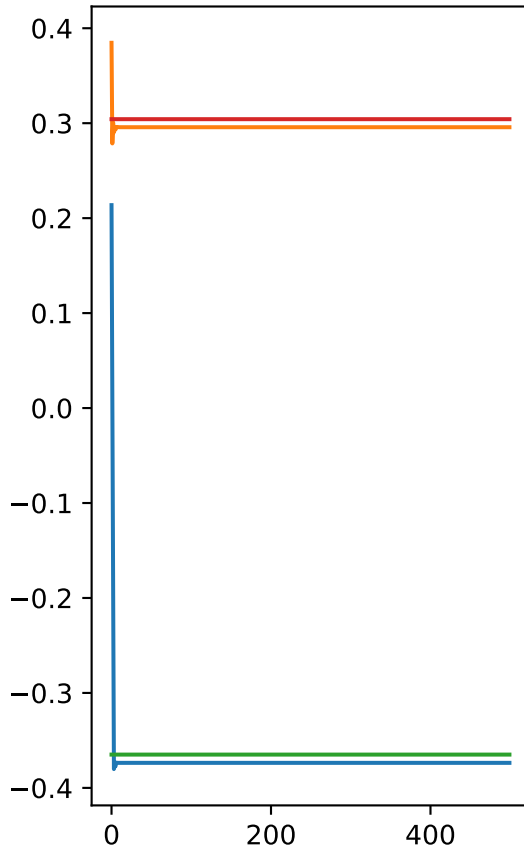
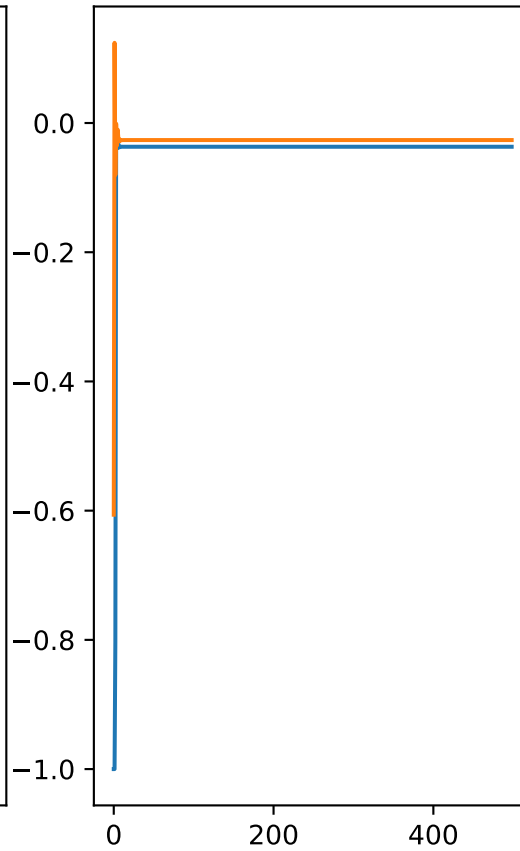


Reward: quartic_root
Speed = 524.6459596672424 [rad/s]

State vs step



Action vs step



Reward vs step

