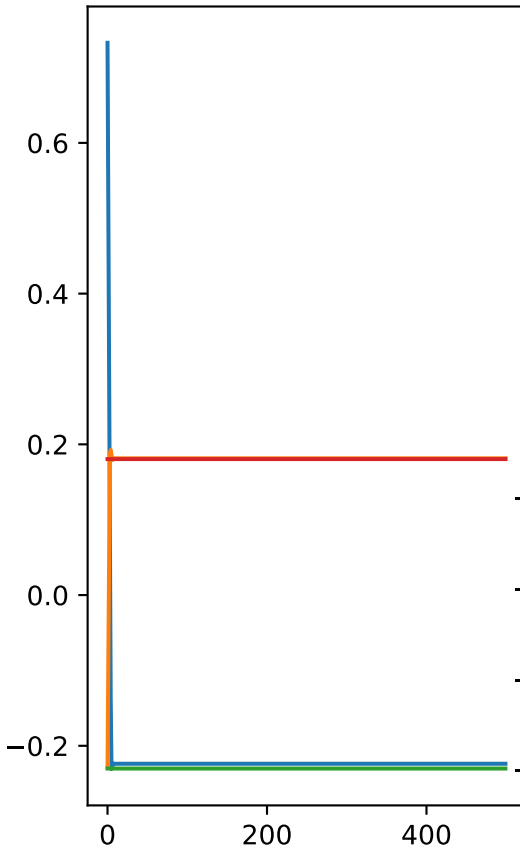
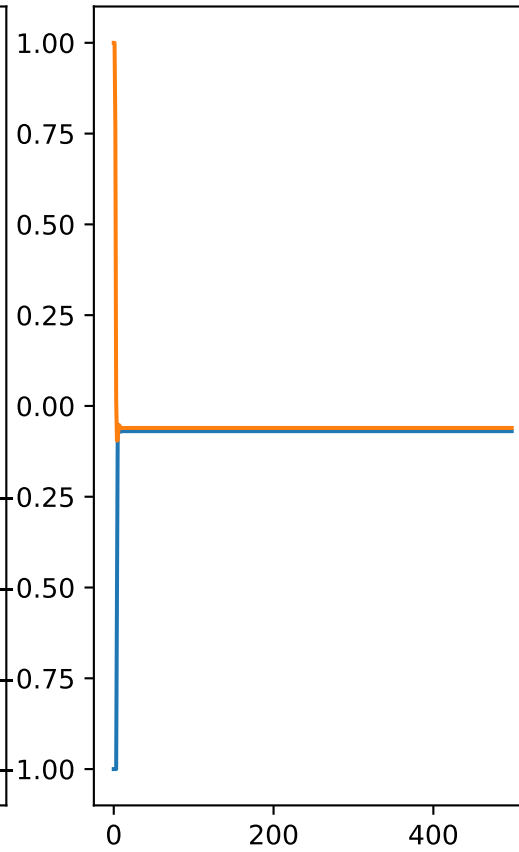


Reward: quartic\_root  
Speed = 283.6355568771446 [rad/s]

State vs step



Action vs step



Reward vs step

