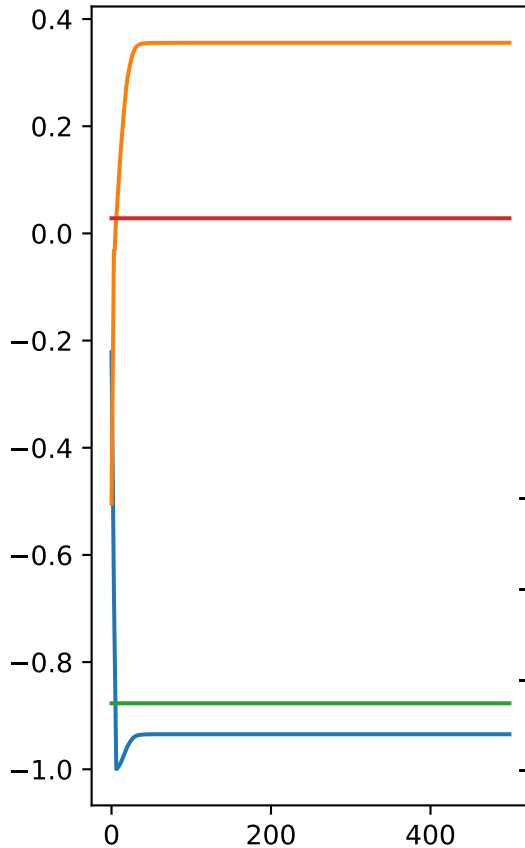
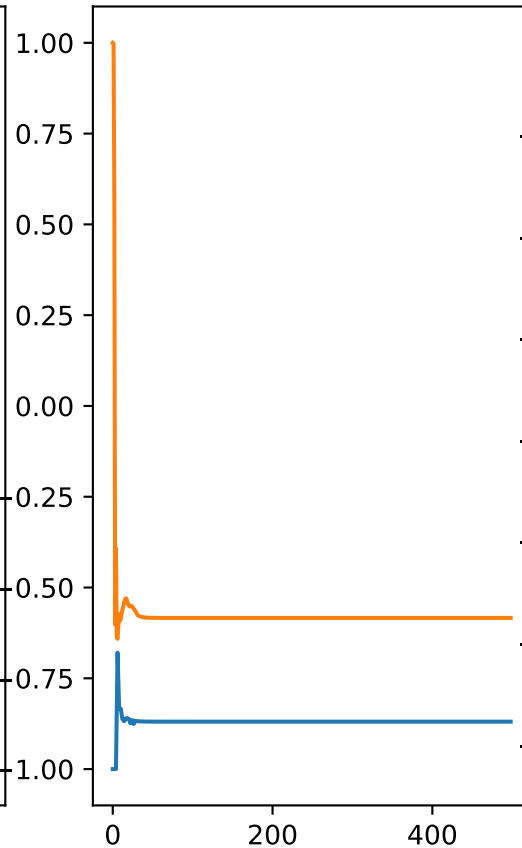


Reward: quadratic_2
Speed = 426.7916549066712 [rad/s]

State vs step



Action vs step



Reward vs step

