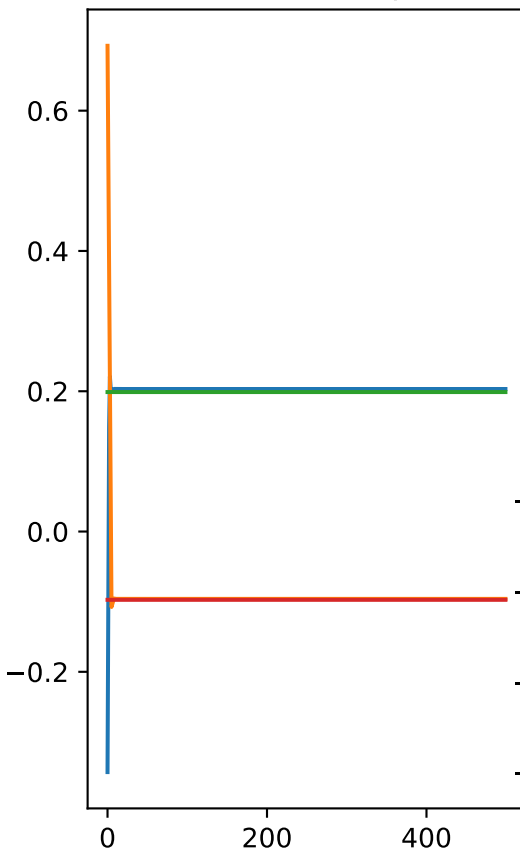
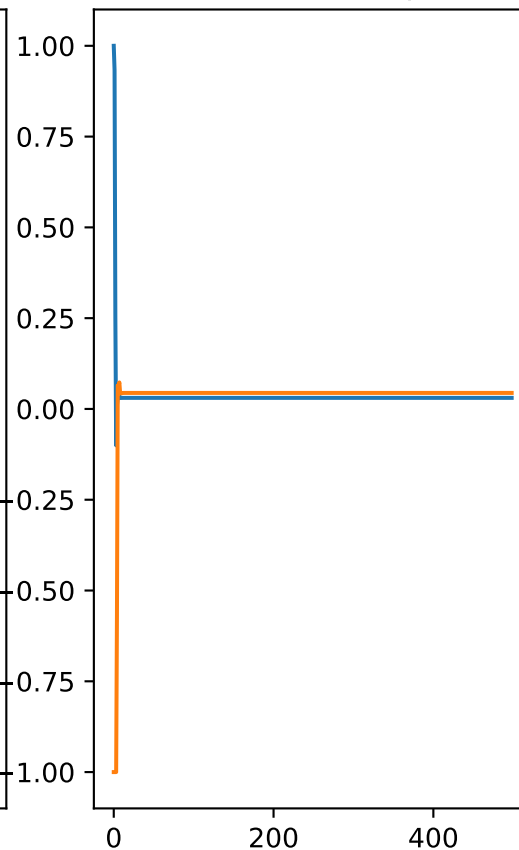


Reward: quartic_root
Speed = 568.9550097056003 [rad/s]

State vs step



Action vs step



Reward vs step

