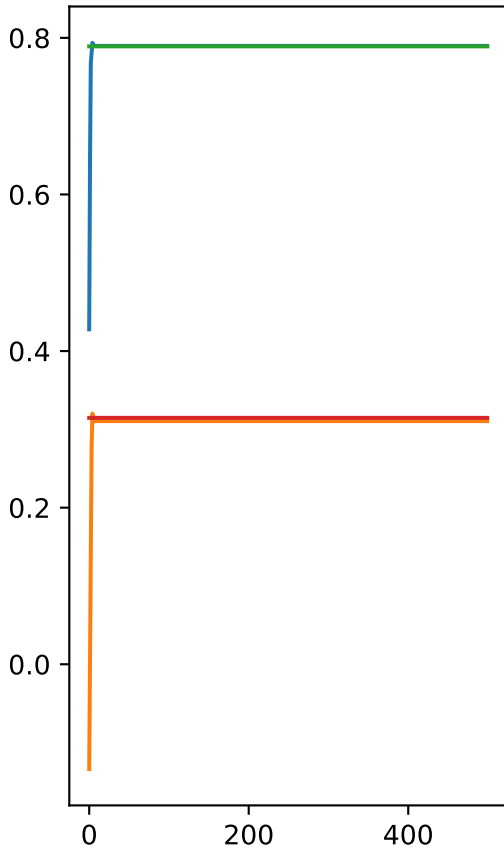
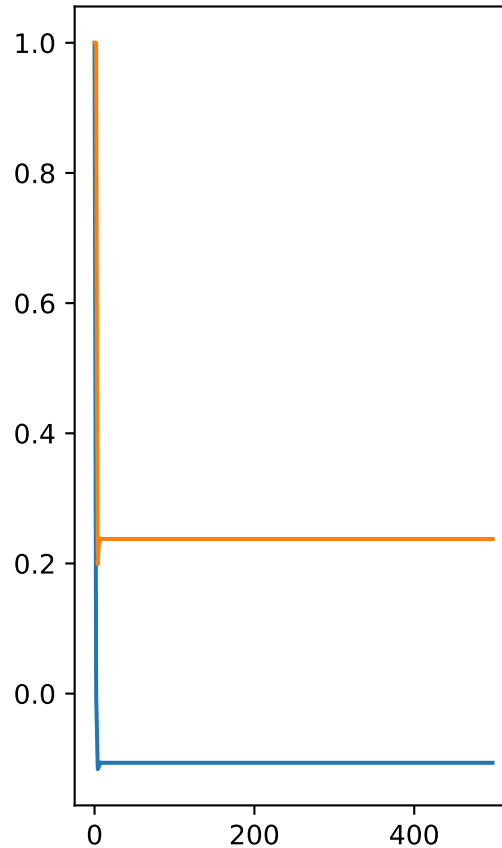


Reward: quartic_root_2
Speed = 669.8755533096127 [rad/s]

State vs step



Action vs step



Reward vs step

