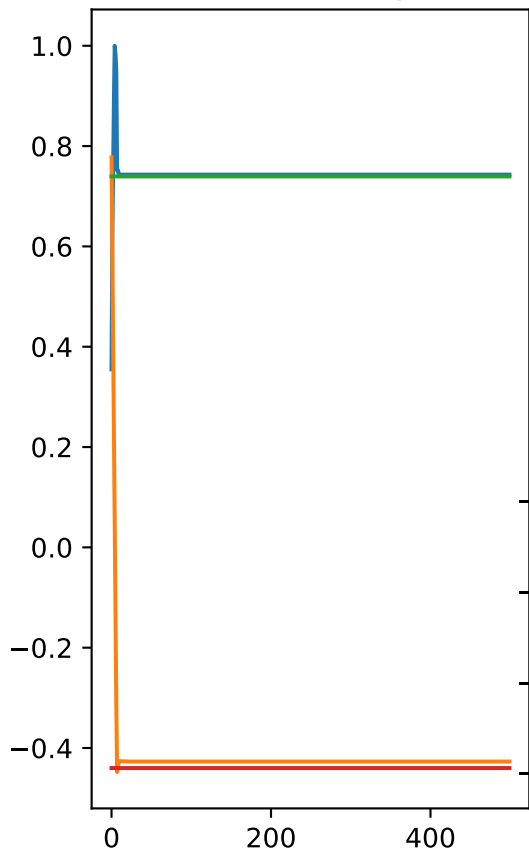
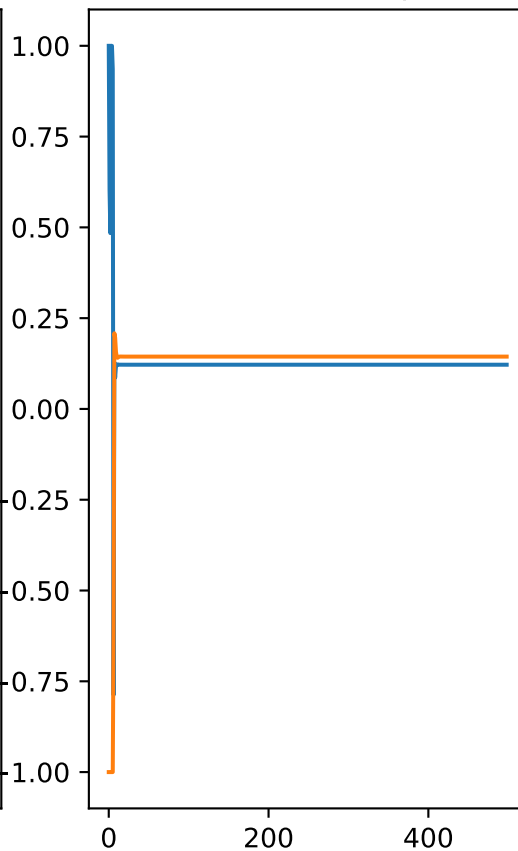


Reward: quartic_root
Speed = 16.838936106421592 [rad/s]

State vs step



Action vs step



Reward vs step

