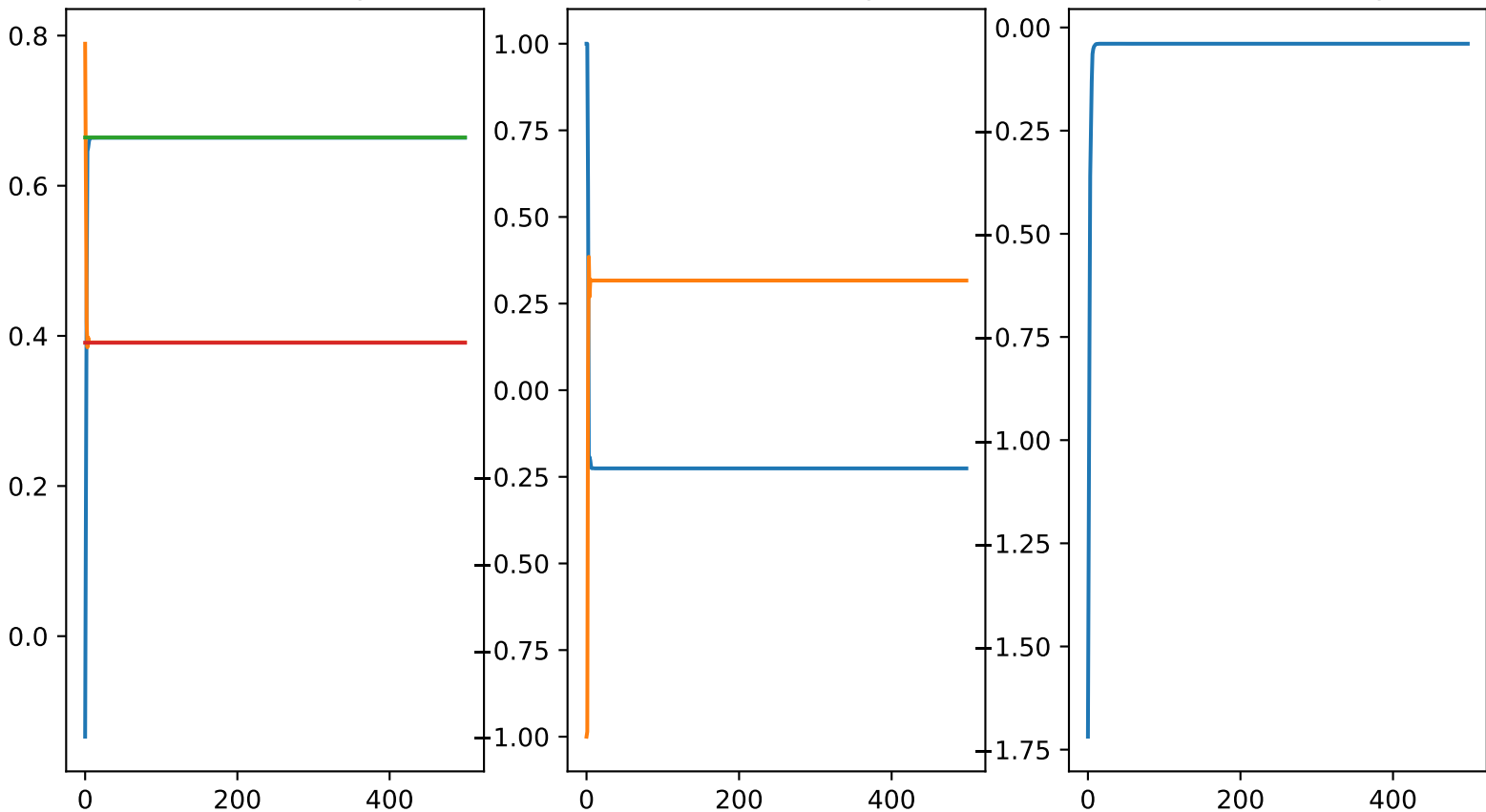


Reward: square_root
Speed = 406.9493362801695 [rad/s]

State vs step

Action vs step

Reward vs step



I_d I_q I_{dref} I_{qref}

V_d V_q