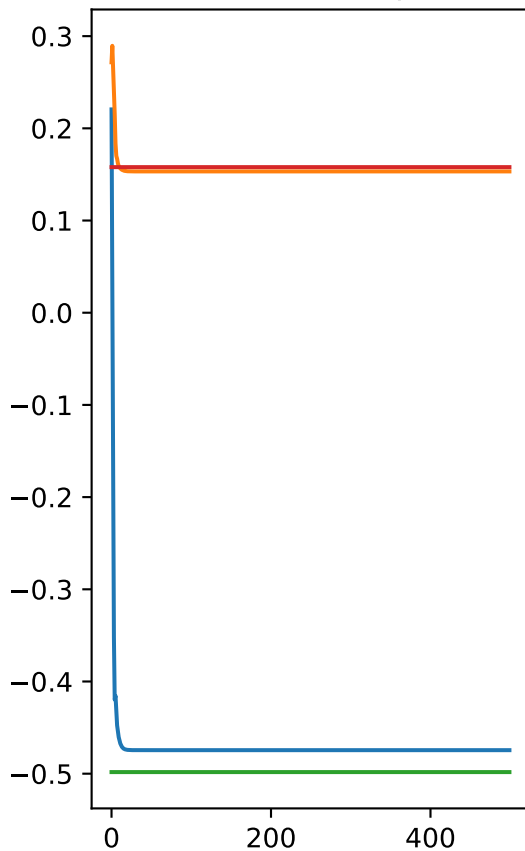
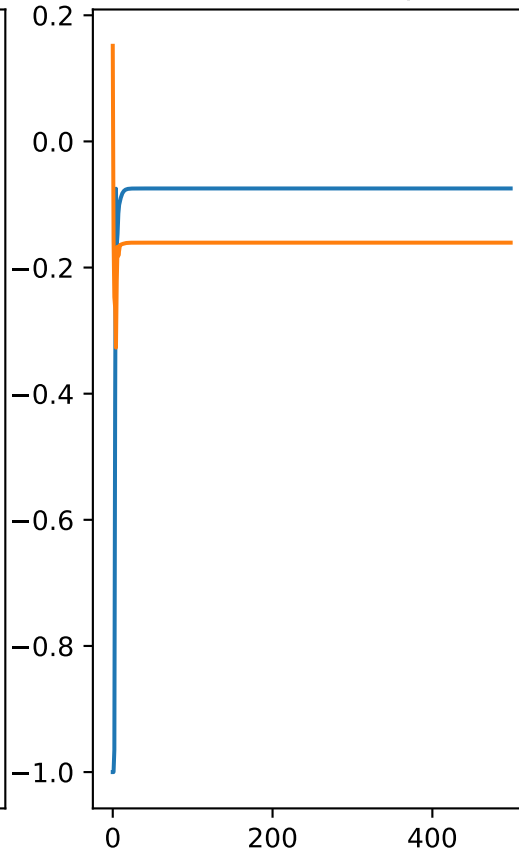


Reward: quadratic\_2  
Speed = 631.8999414295188 [rad/s]

State vs step



Action vs step



Reward vs step

