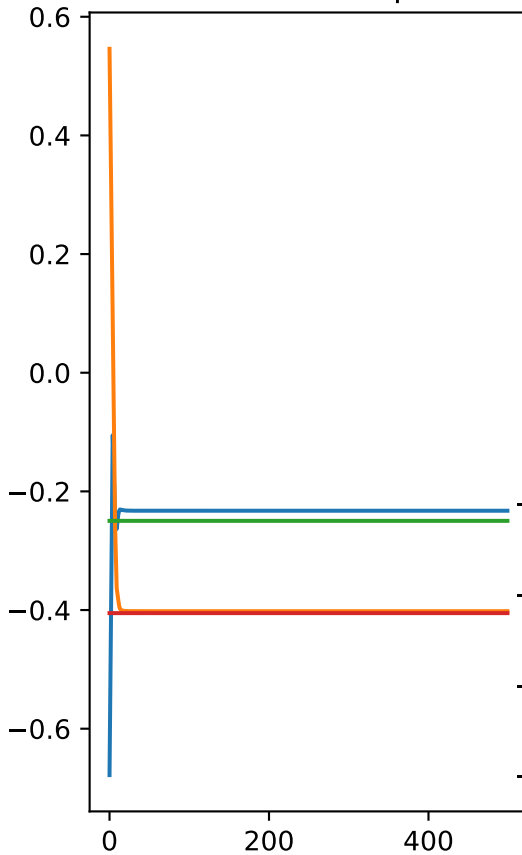
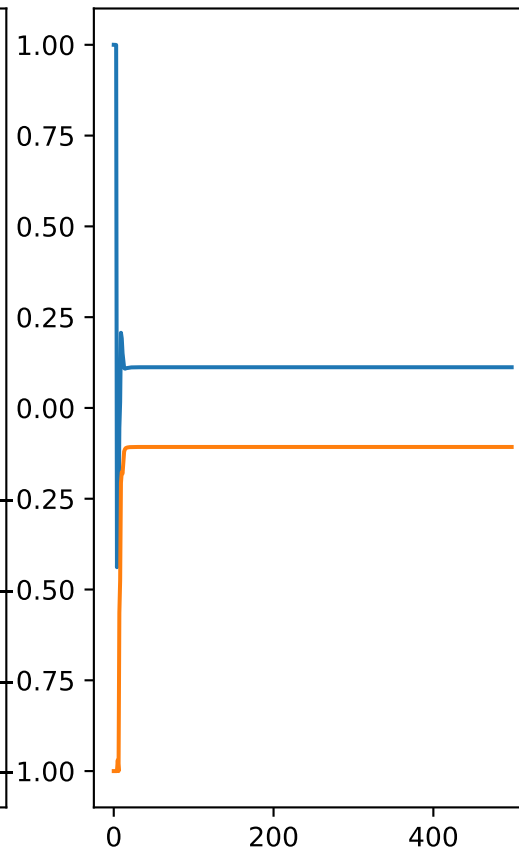


Reward: quadratic
Speed = 906.0479245054181 [rad/s]

State vs step



Action vs step



Reward vs step

