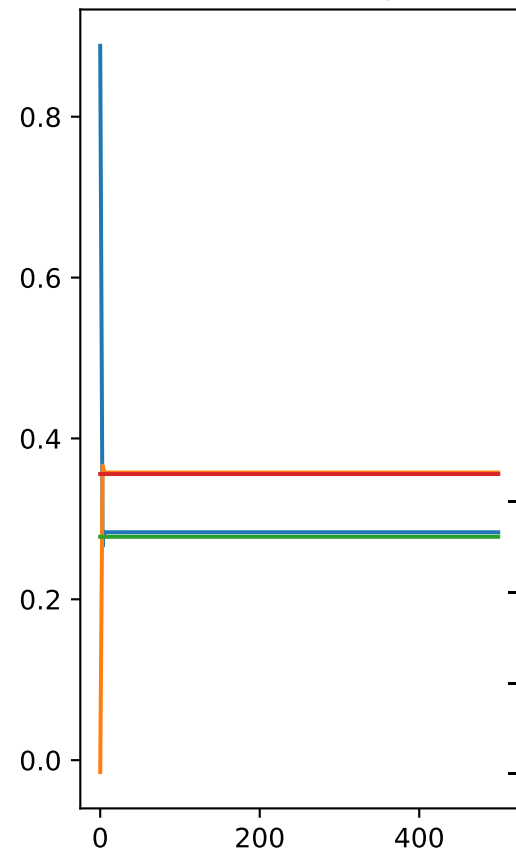
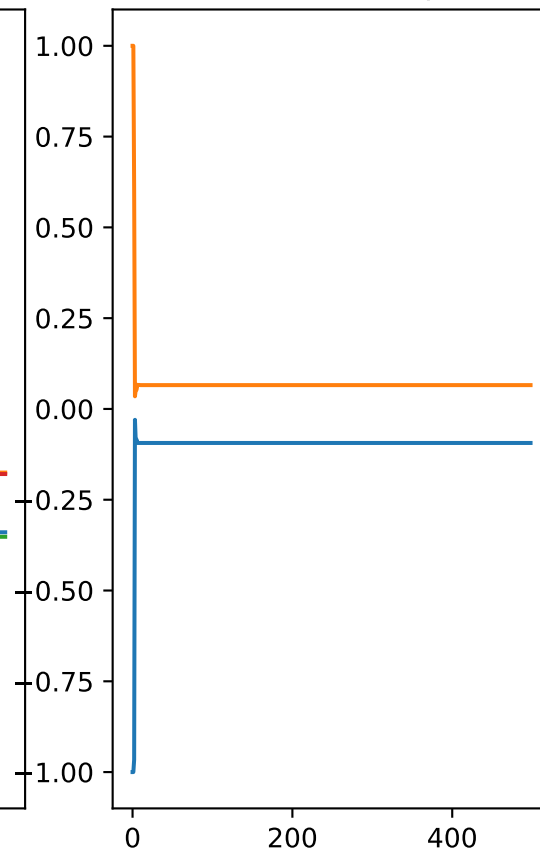


Reward: quartic_root
Speed = 997.5561702208719 [rad/s]

State vs step



Action vs step



Reward vs step

