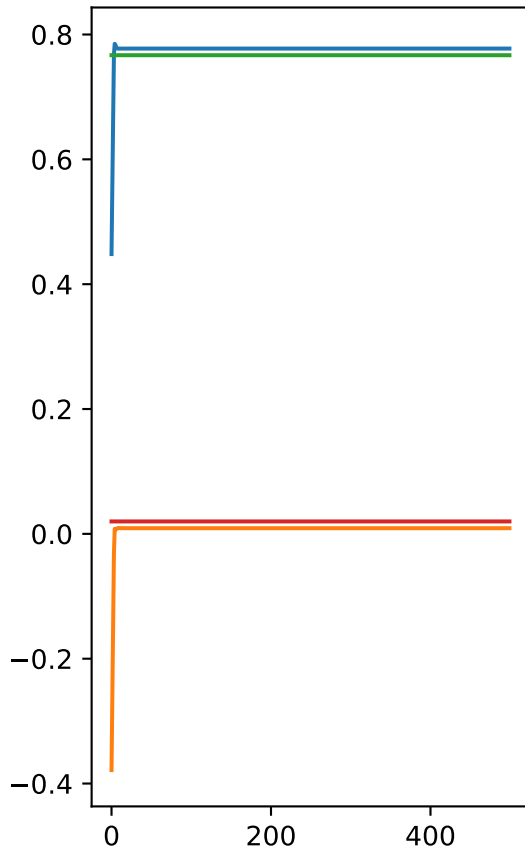
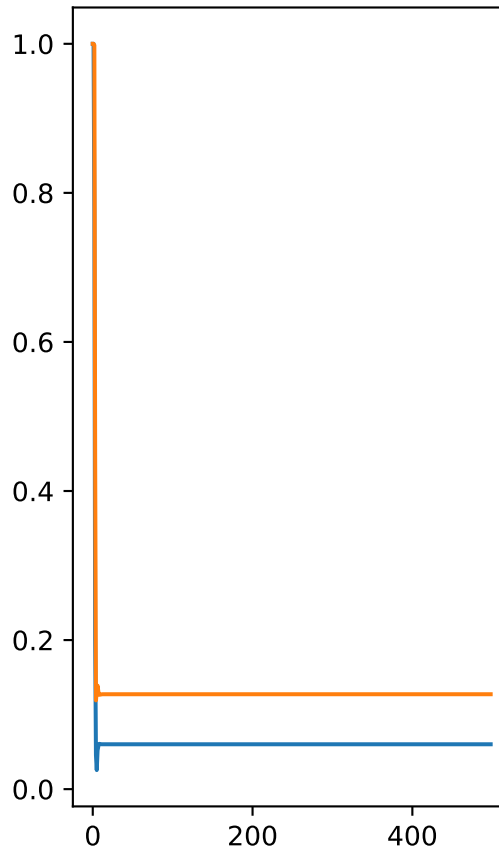


Reward: quartic\_root\_2  
Speed = 983.3813039042218 [rad/s]

State vs step



Action vs step



Reward vs step

