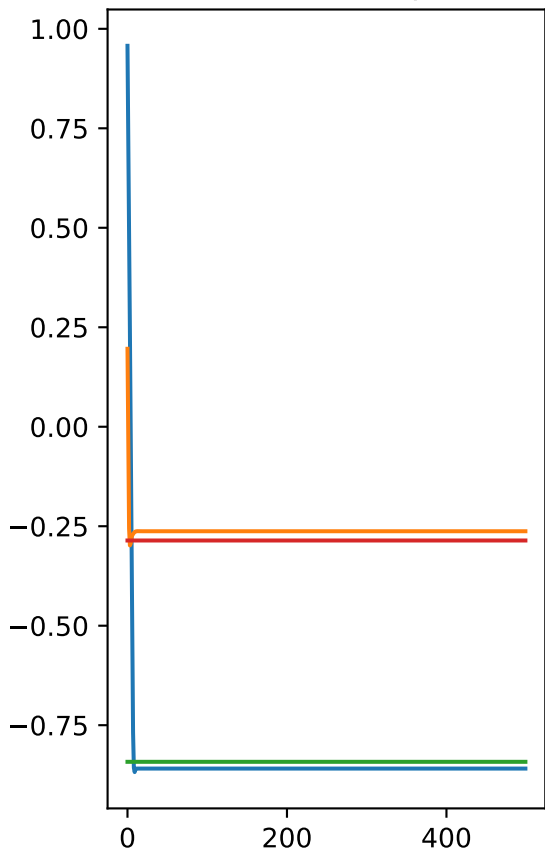
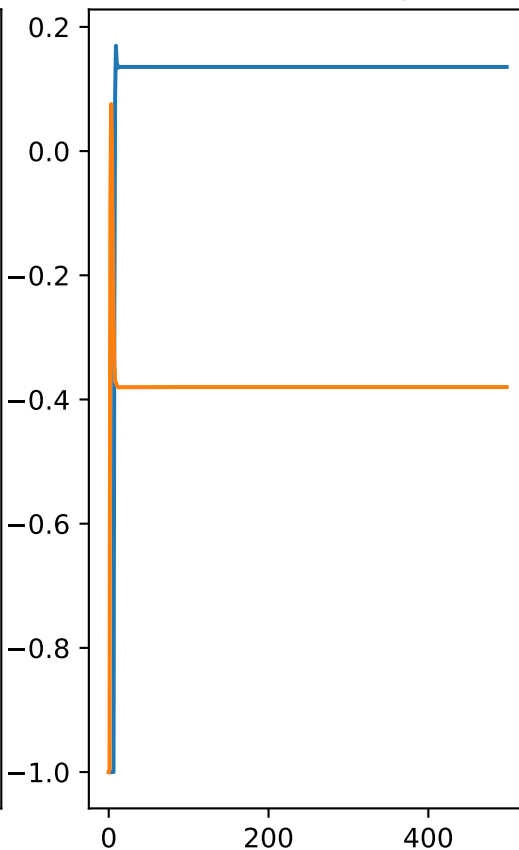


Reward: quartic_root
Speed = 372.5551725623386 [rad/s]

State vs step



Action vs step



Reward vs step

