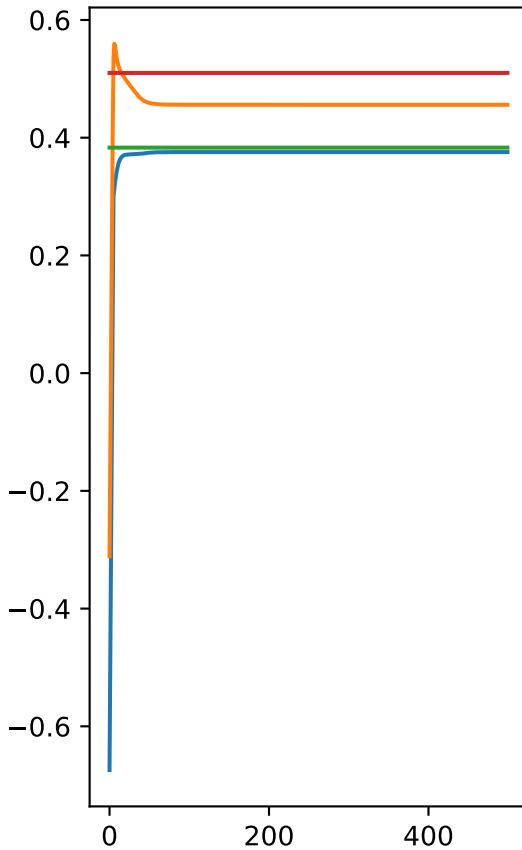
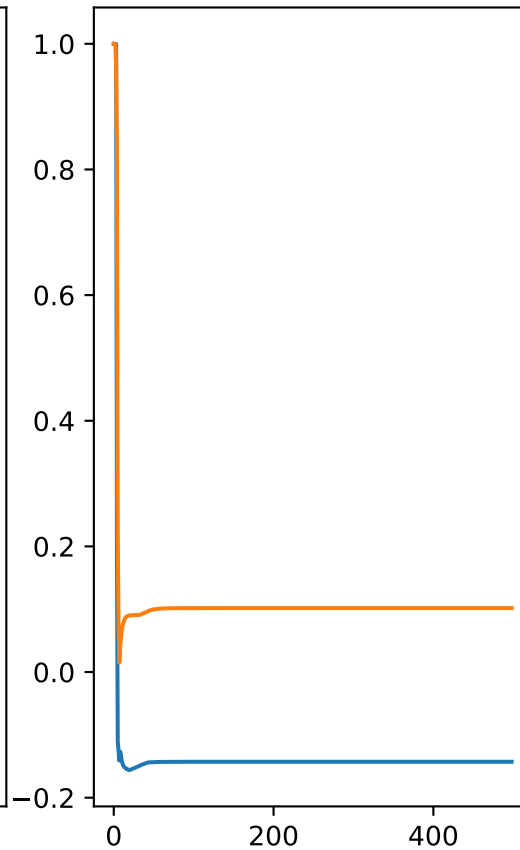


Reward: quadratic
Speed = 620.1503826280903 [rad/s]

State vs step



Action vs step



Reward vs step

