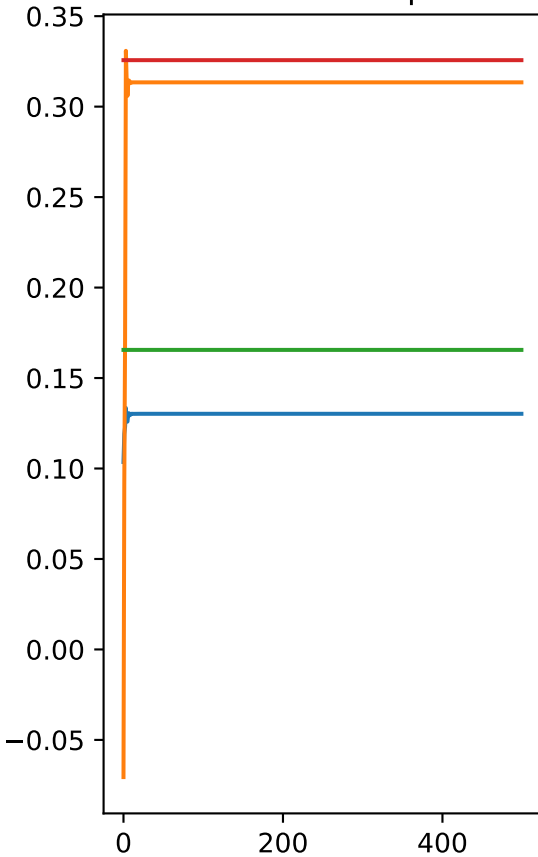
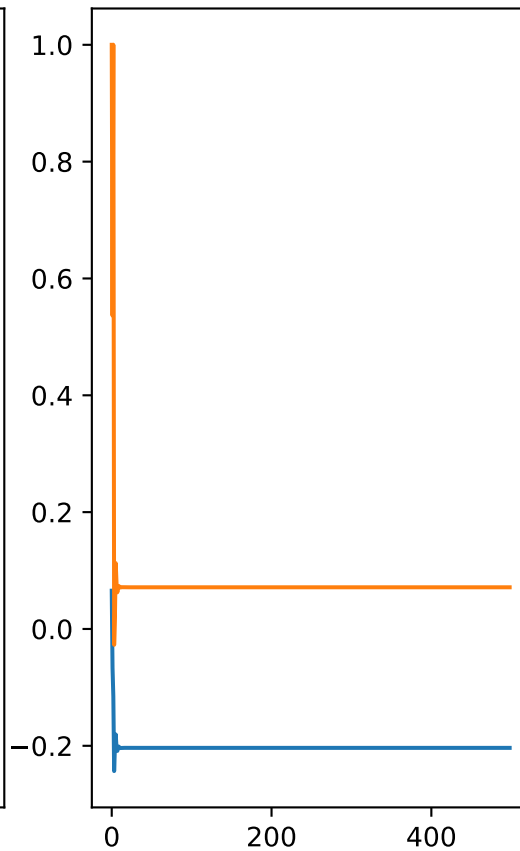


Reward: quadratic_2
Speed = 587.7668347930527 [rad/s]

State vs step



Action vs step



Reward vs step

