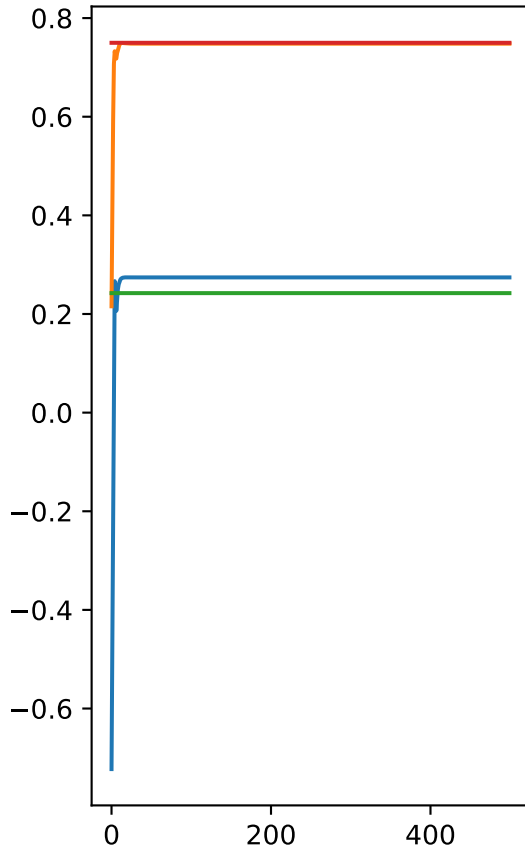
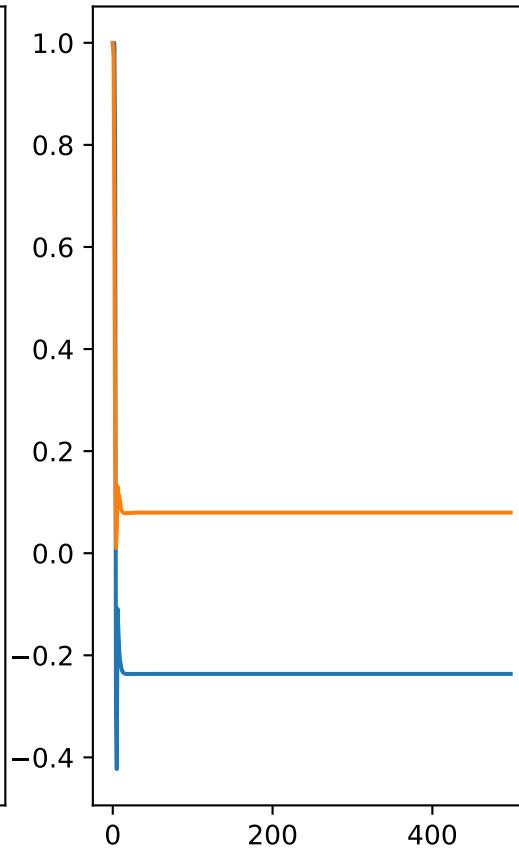


Reward: quadratic_2
Speed = 44.69857947982265 [rad/s]

State vs step



Action vs step



Reward vs step

