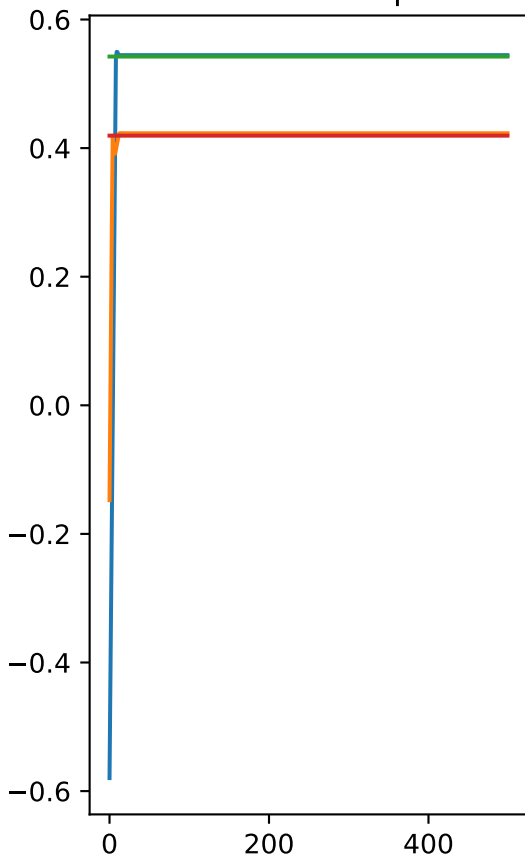
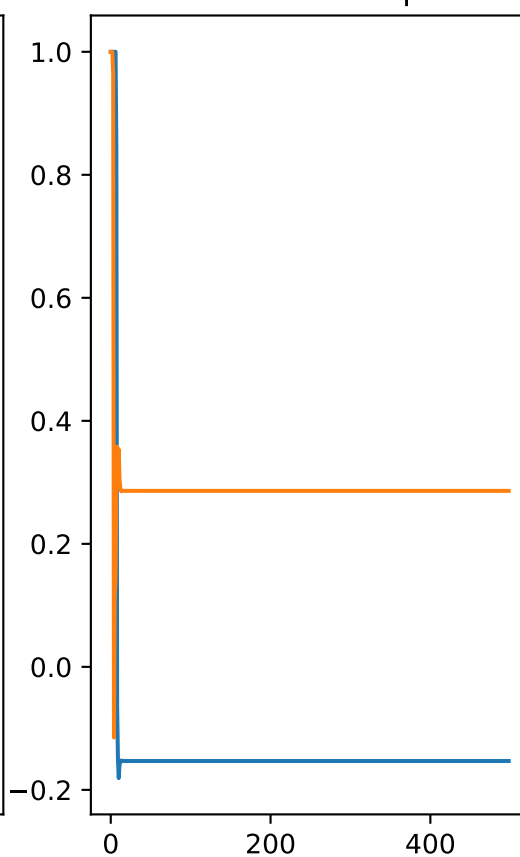


Reward: quartic_root_2
Speed = 1080.0544509482618 [rad/s]

State vs step



Action vs step



Reward vs step

