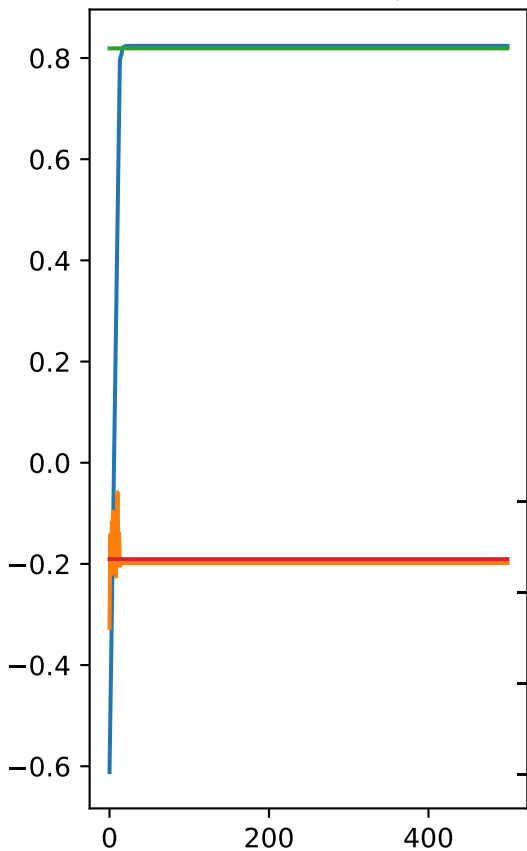
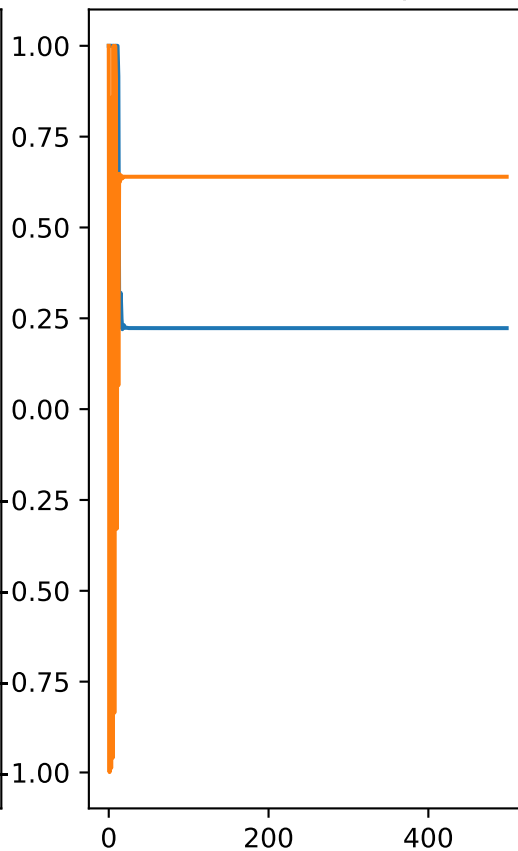


Reward: quartic_root_2
Speed = 354.07006740636854 [rad/s]

State vs step



Action vs step



Reward vs step

