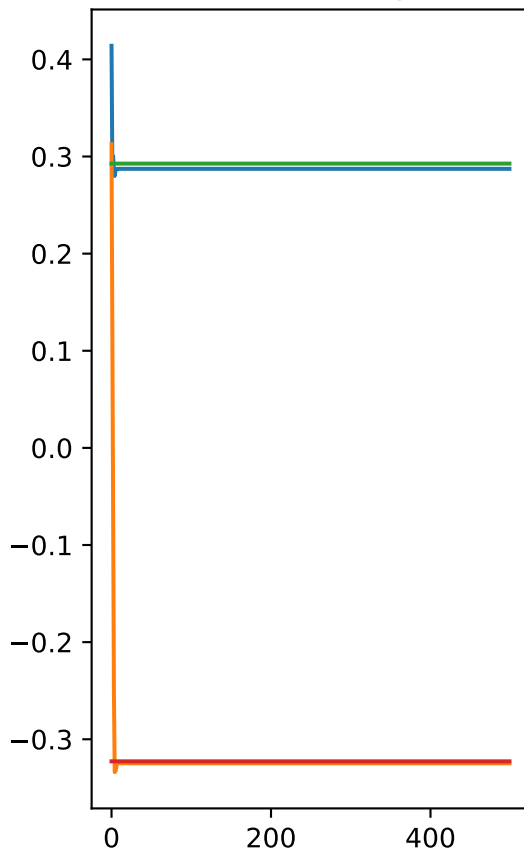
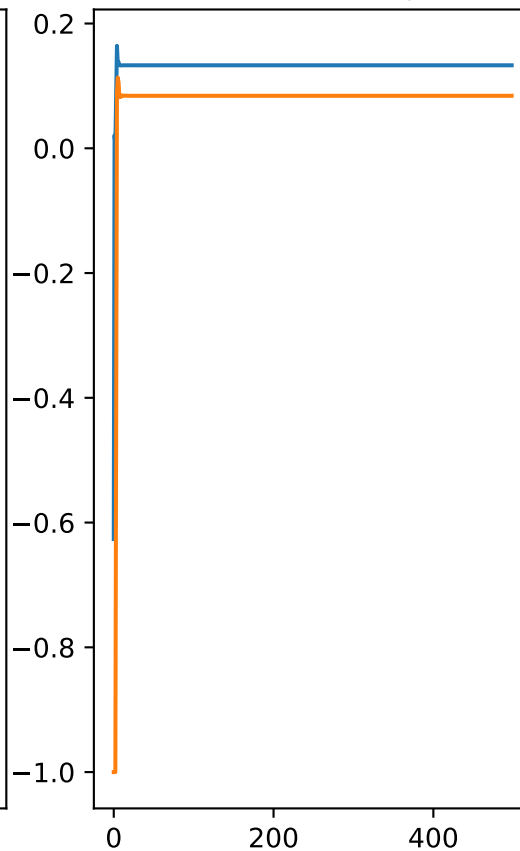


Reward: quartic_root
Speed = 954.7551101826361 [rad/s]

State vs step



Action vs step



Reward vs step

