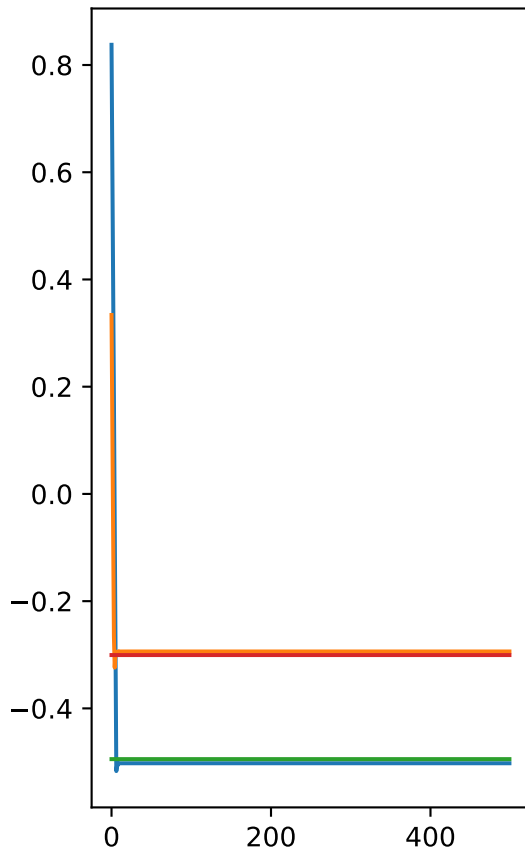
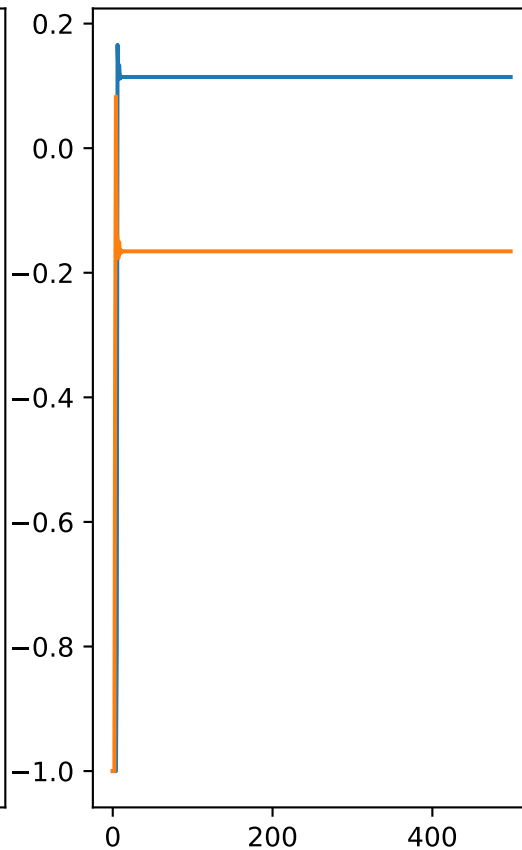


Reward: quartic_root
Speed = 987.9680412825301 [rad/s]

State vs step



Action vs step



Reward vs step

