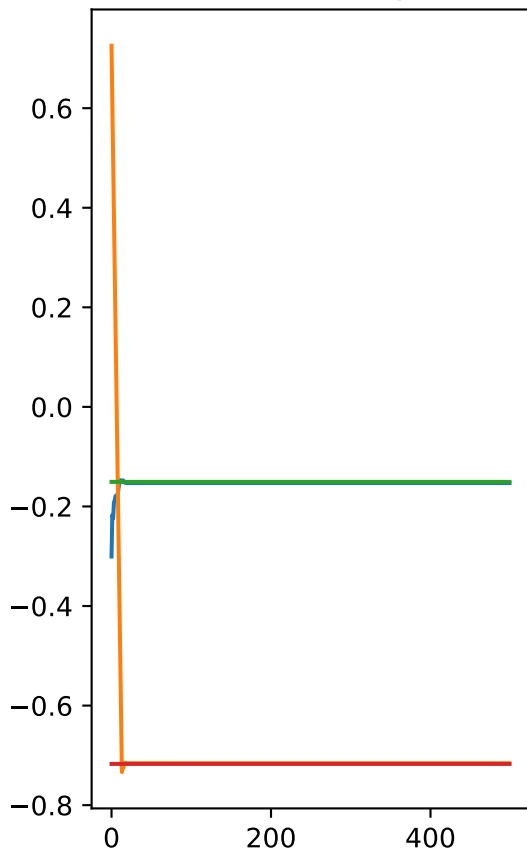
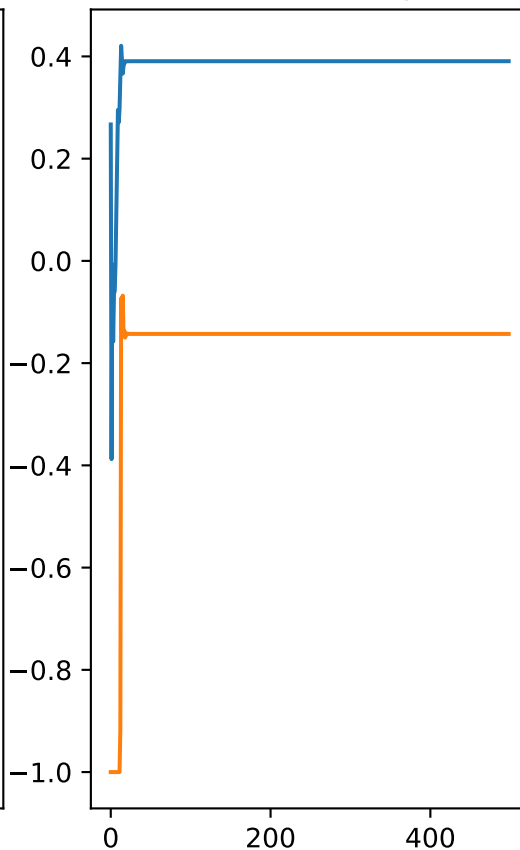


Reward: quartic_root
Speed = 1015.4883906509739 [rad/s]

State vs step



Action vs step



Reward vs step

