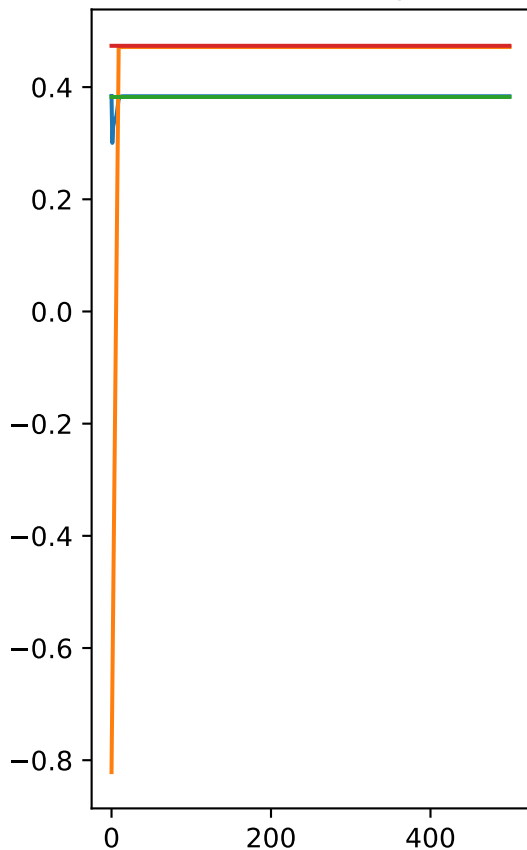
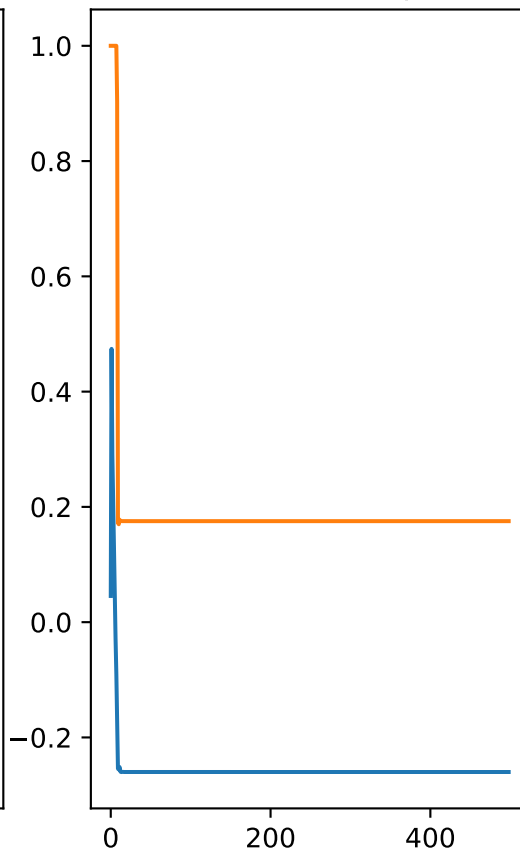


Reward: square_root
Speed = 1069.2598850689787 [rad/s]

State vs step



Action vs step



Reward vs step

