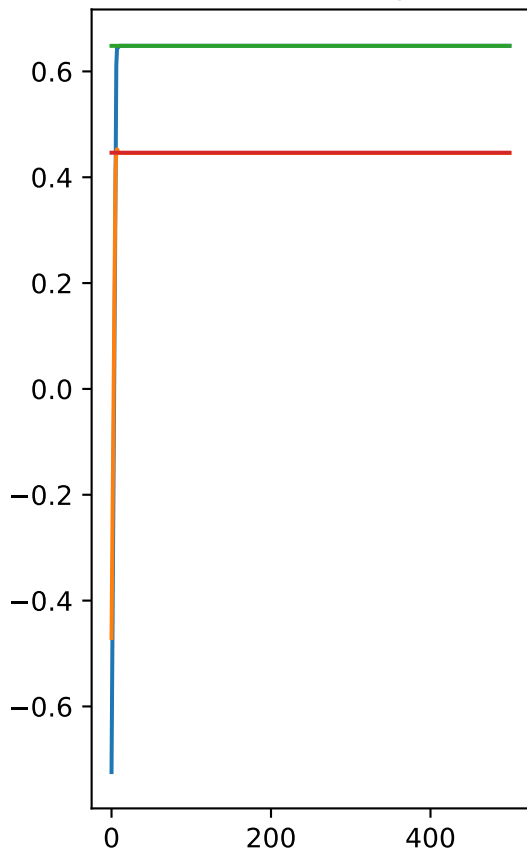
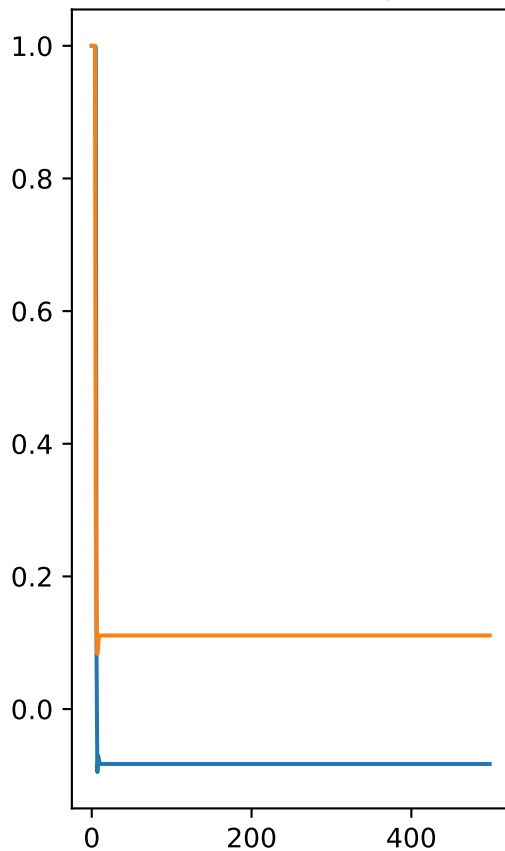


Reward: square_root
Speed = 117.13113649970285 [rad/s]

State vs step



Action vs step



Reward vs step

