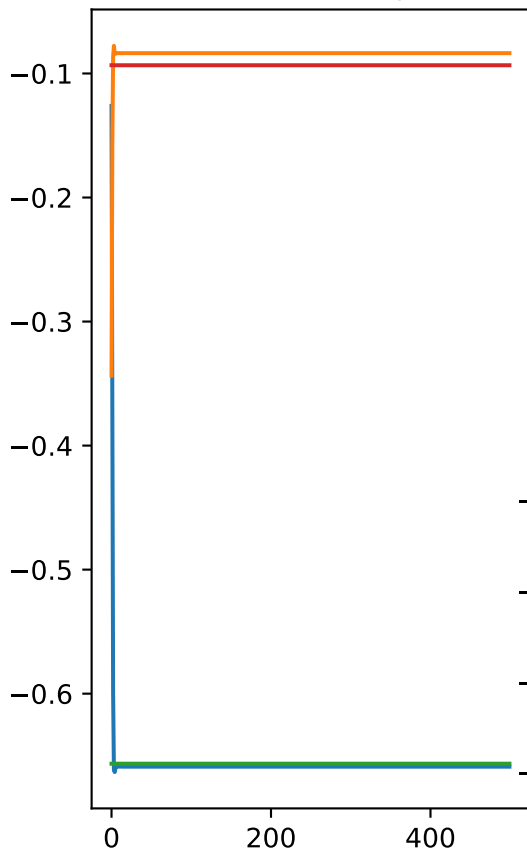
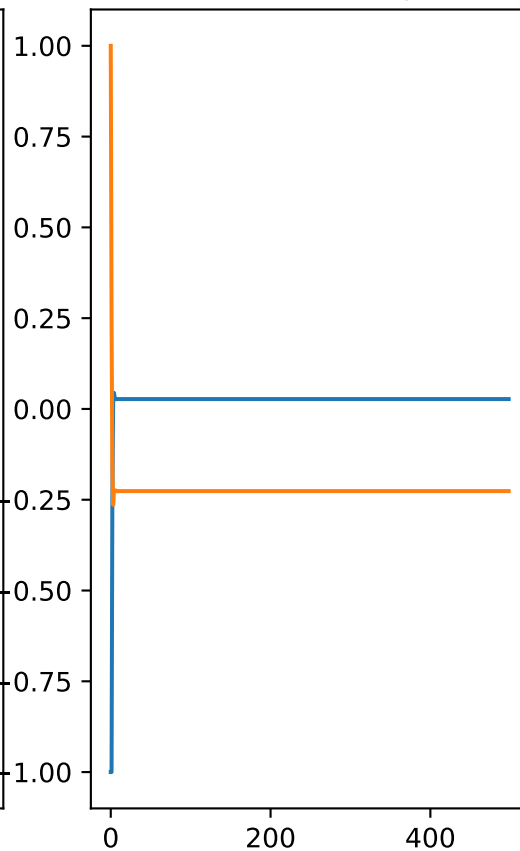


Reward: quartic\_root  
Speed = 425.5852554164329 [rad/s]

State vs step



Action vs step



Reward vs step

