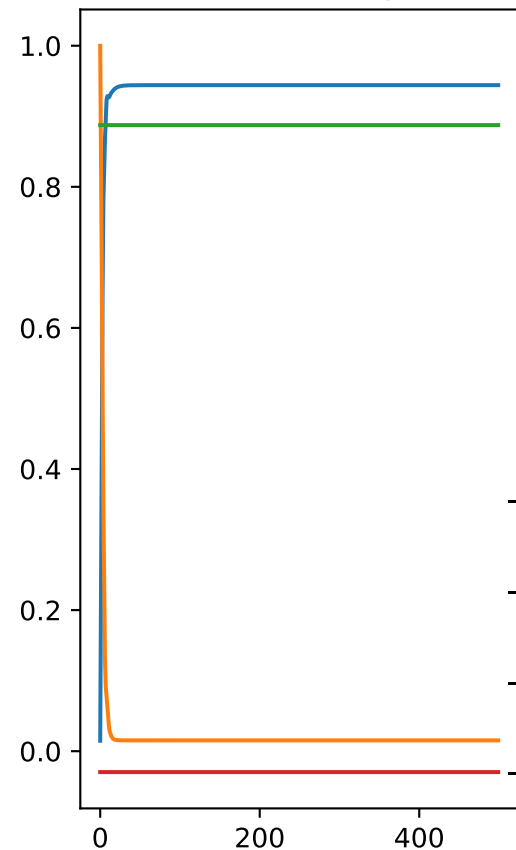
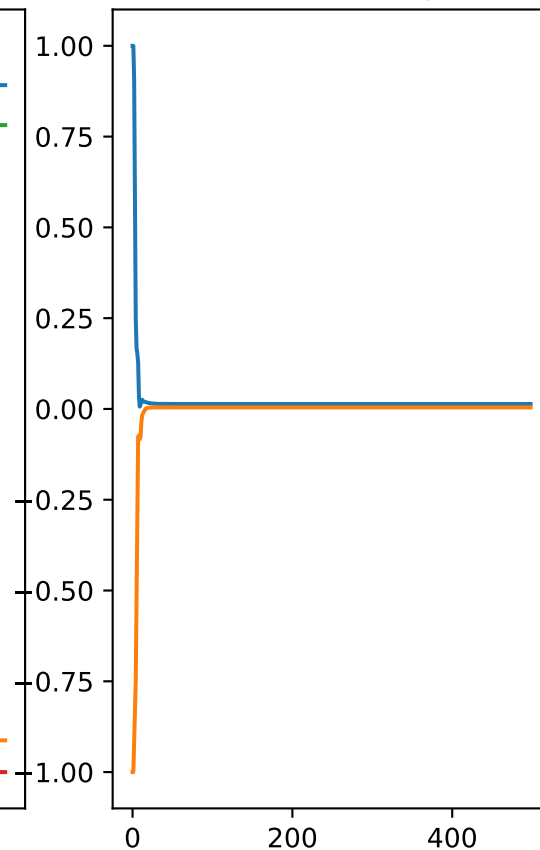


Reward: quadratic\_2  
Speed = 1045.823609745469 [rad/s]

State vs step



Action vs step



Reward vs step

