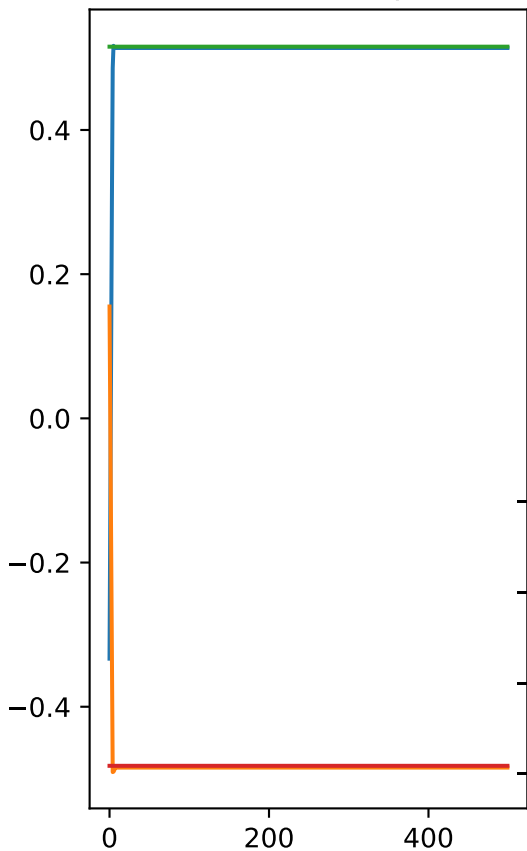
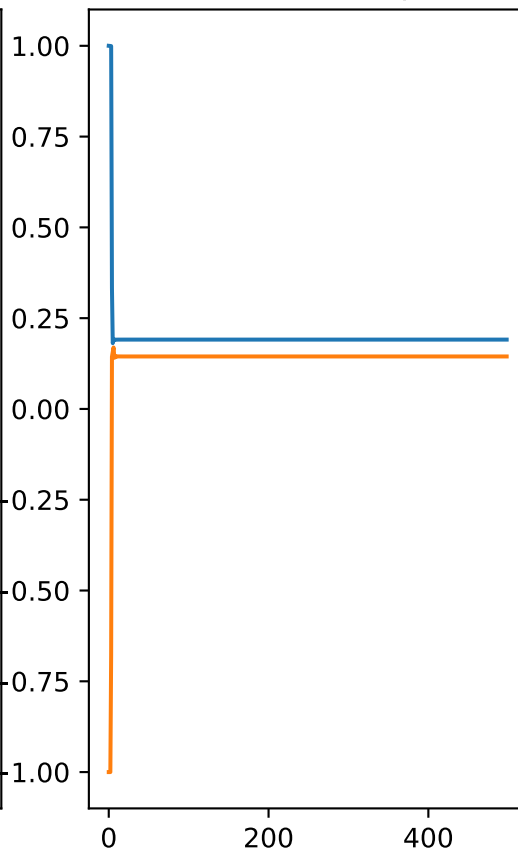


Reward: quartic\_root  
Speed = 158.21060645422986 [rad/s]

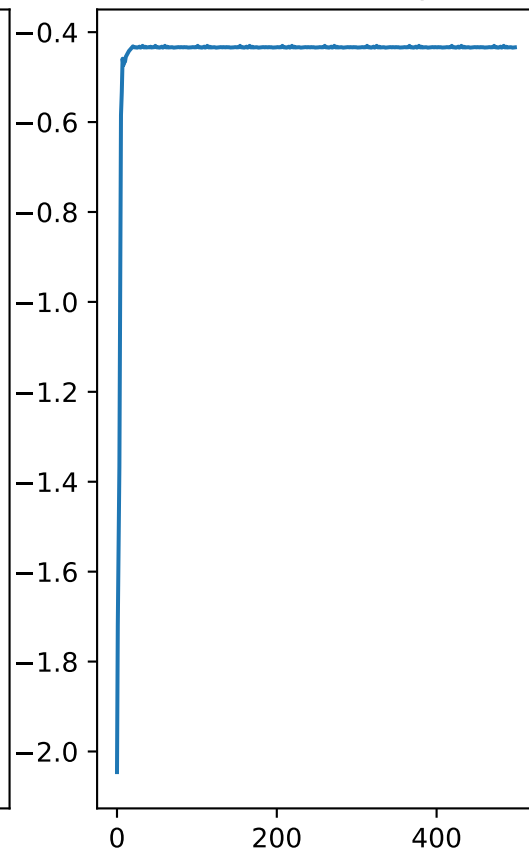
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq