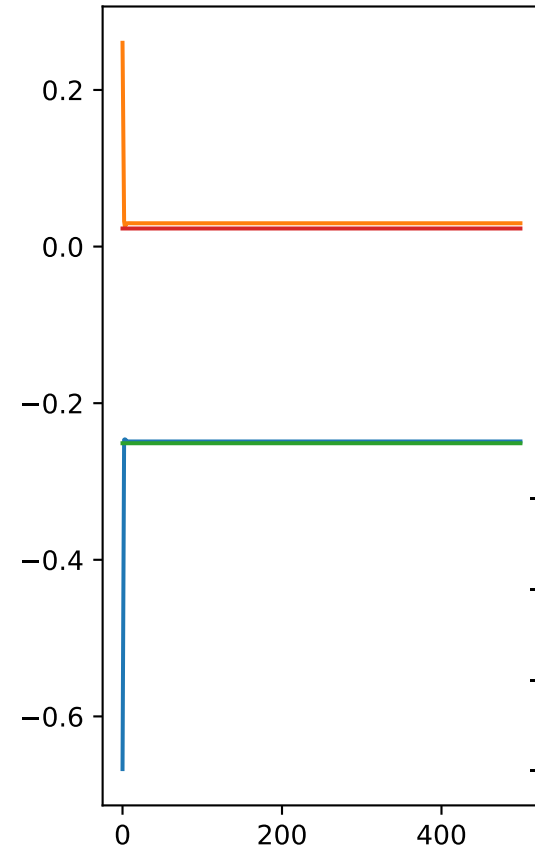
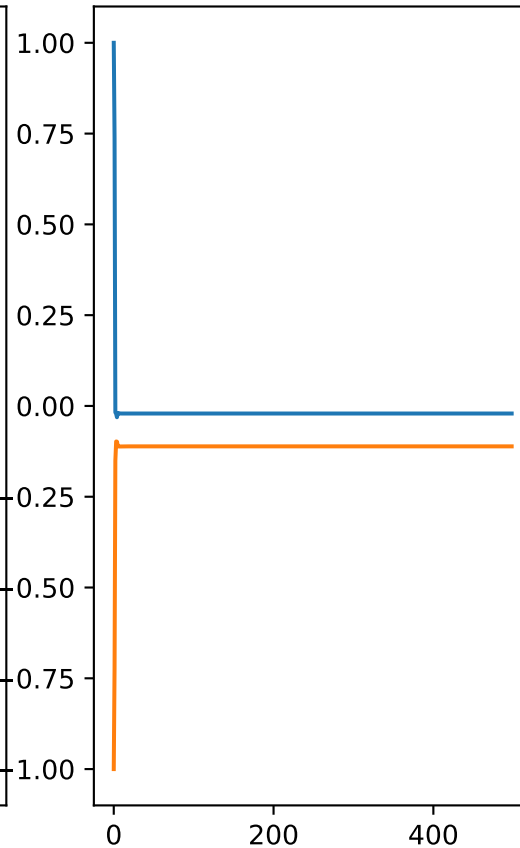


Reward: quartic_root
Speed = 342.0565935021023 [rad/s]

State vs step



Action vs step



Reward vs step

