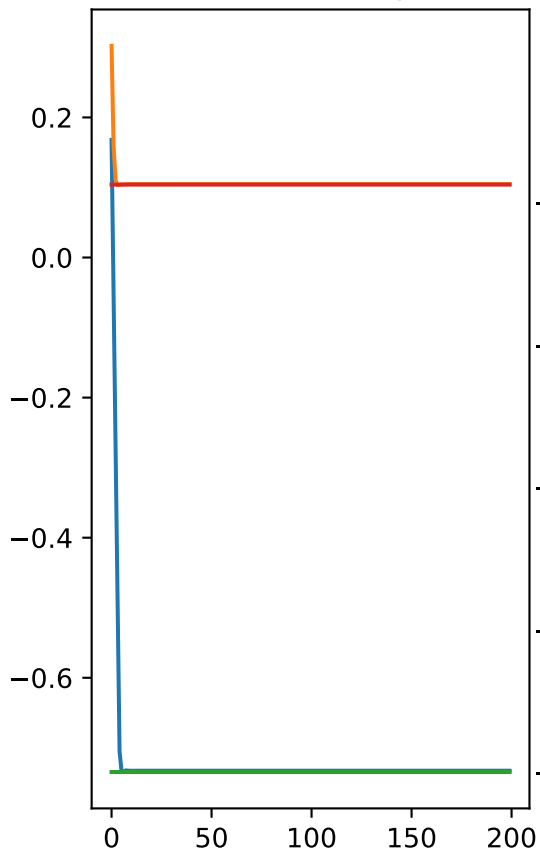
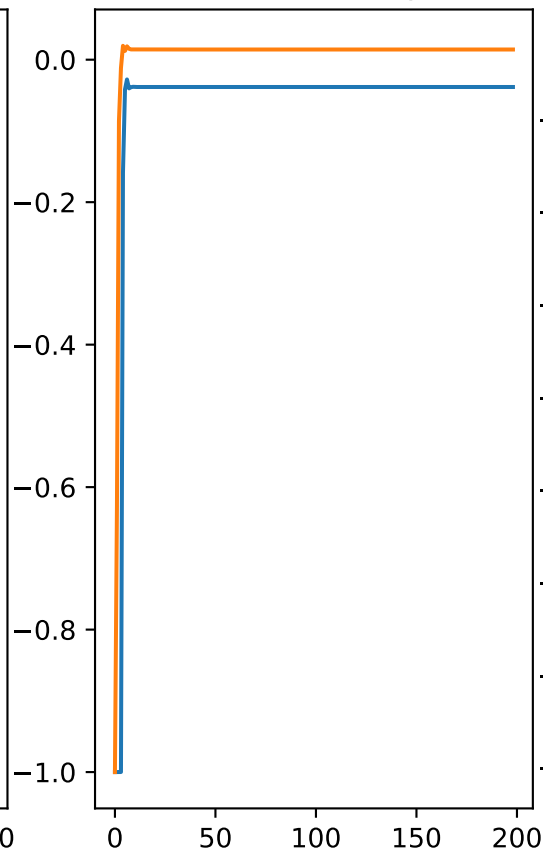


Reward: square\_root  
Speed = 823.9825739027343 [rad/s]

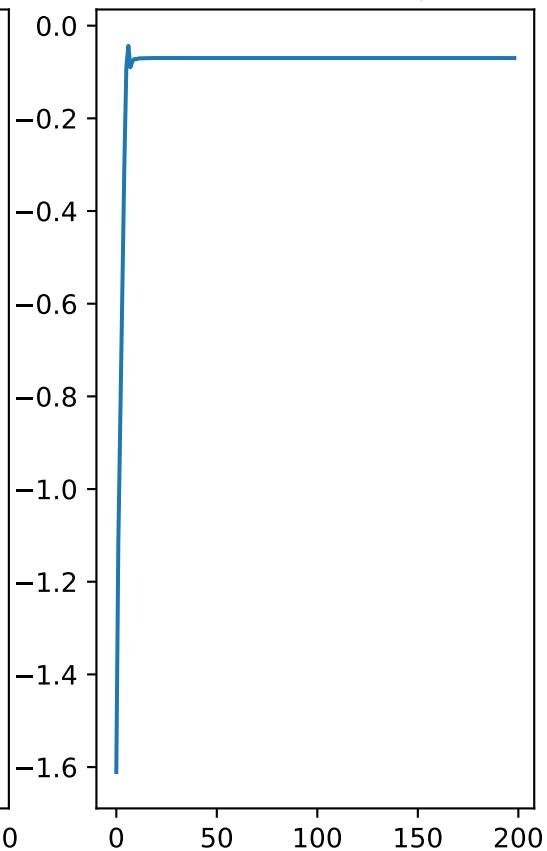
State vs step



Action vs step



Reward vs step



Id Iqref  
Iq Idref

Vd Vq