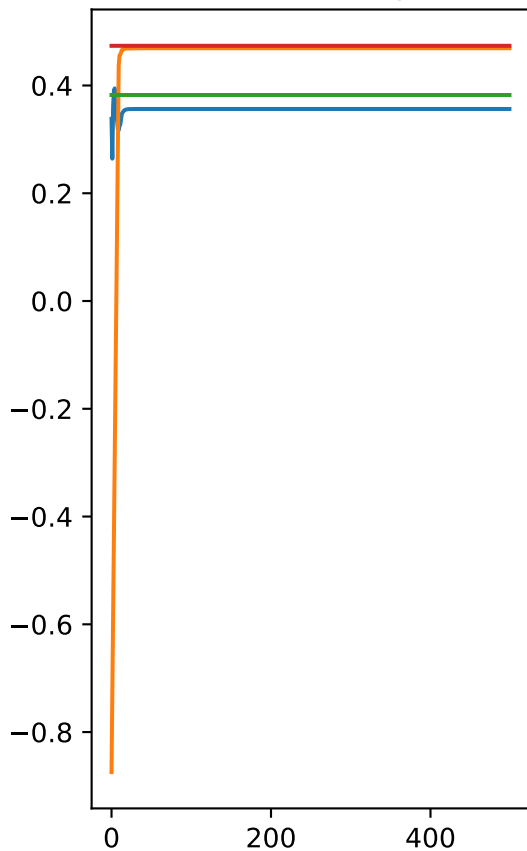
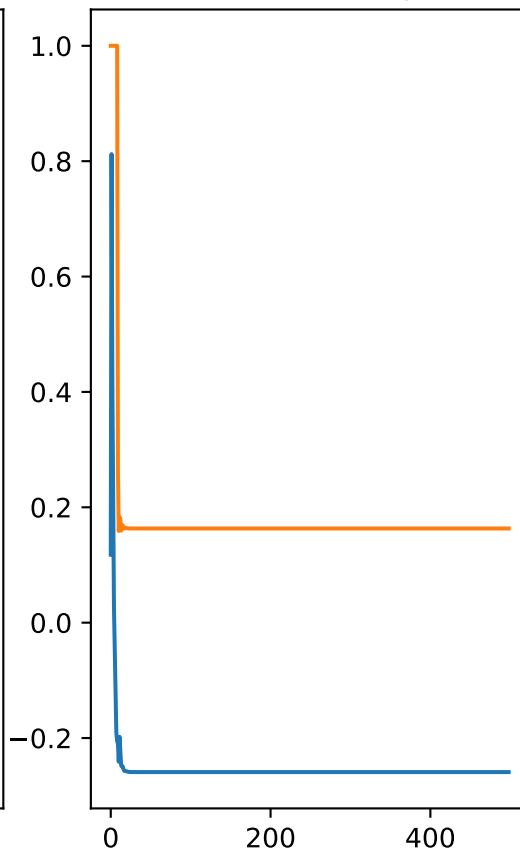


Reward: quadratic\_2  
Speed = 1069.2598850689787 [rad/s]

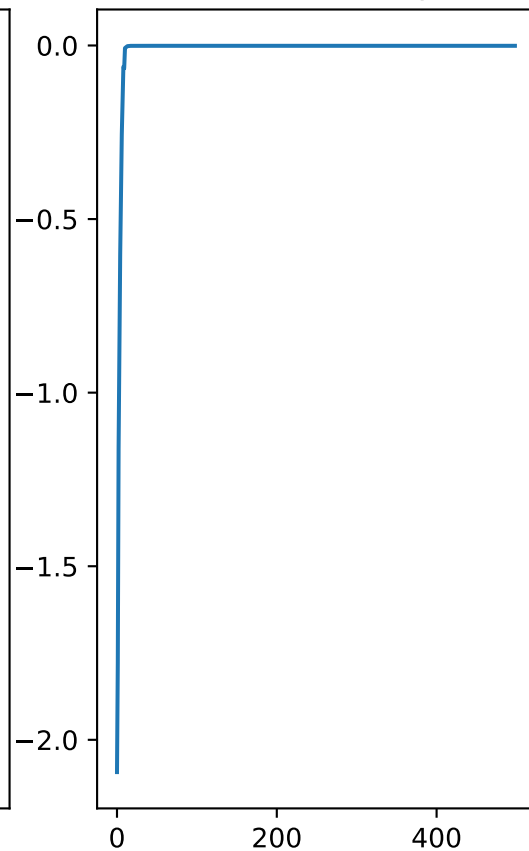
State vs step



Action vs step



Reward vs step



Id Iqref  
Iq Iqref

Vd Vq