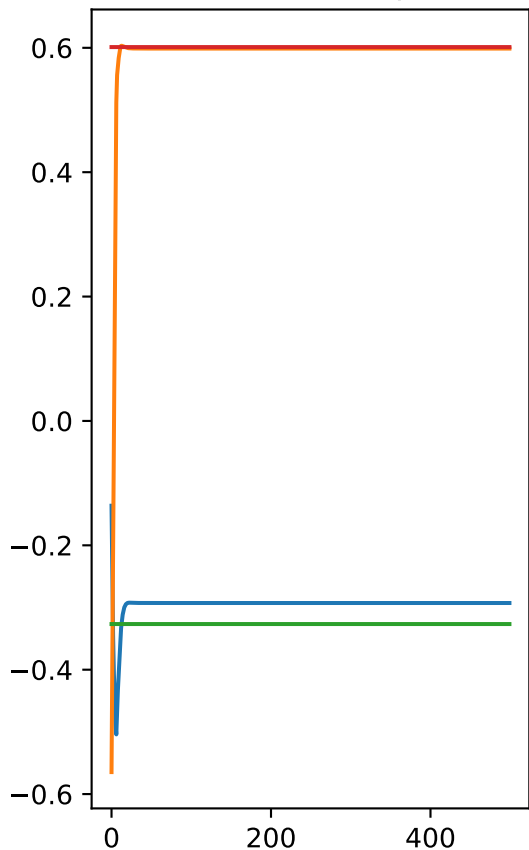
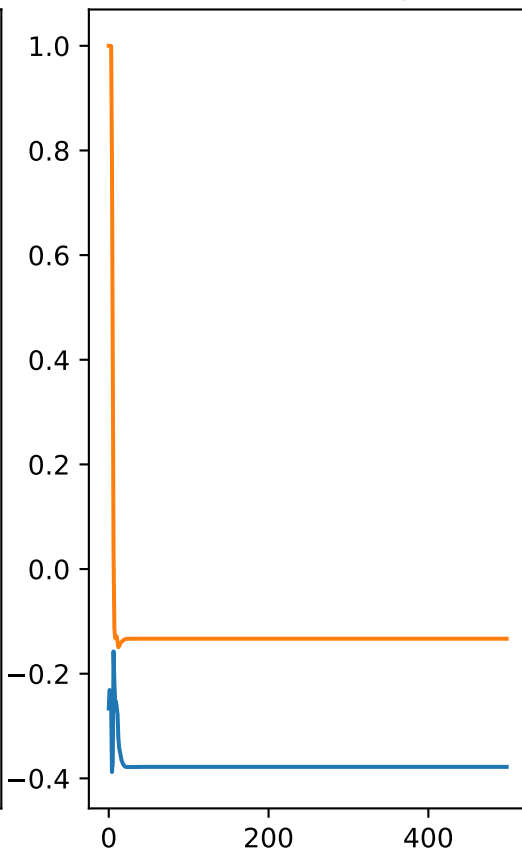


Reward: quadratic
Speed = 95.6300794315156 [rad/s]

State vs step



Action vs step



Reward vs step

