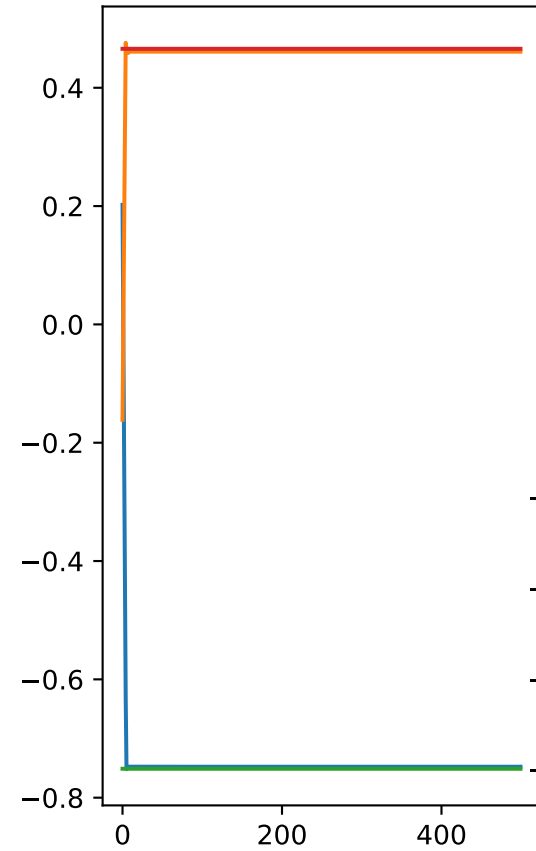
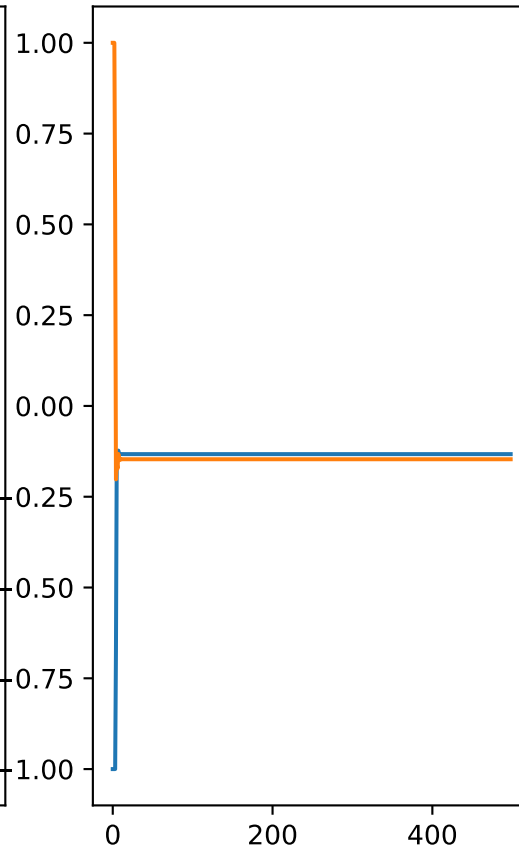


Reward: quartic_root
Speed = 637.7809750976056 [rad/s]

State vs step



Action vs step



Reward vs step

