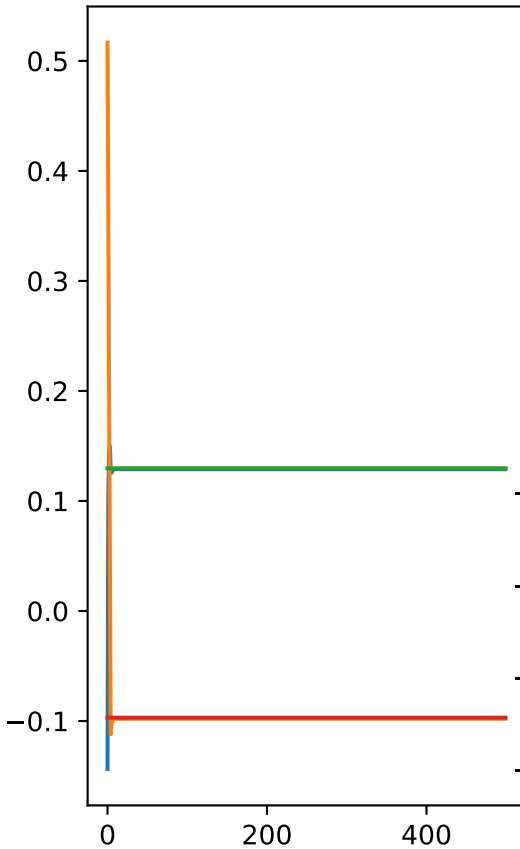
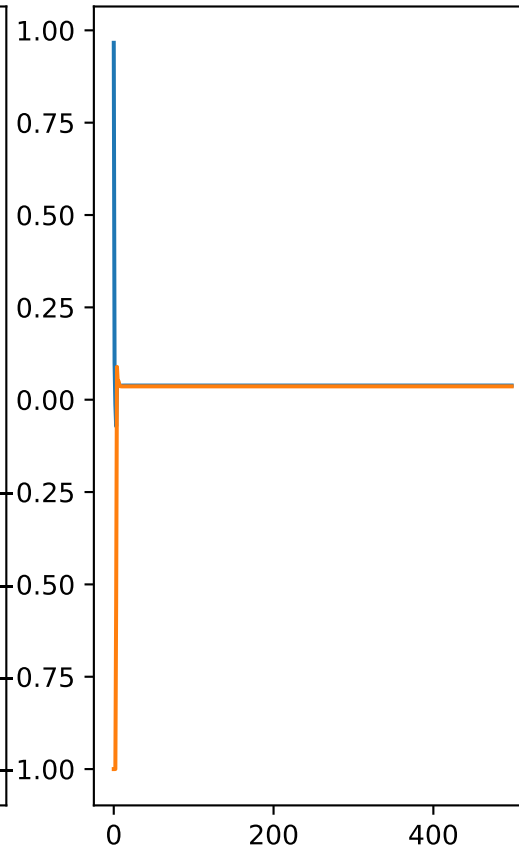


Reward: quartic_root_2
Speed = 631.9753671450169 [rad/s]

State vs step



Action vs step



Reward vs step

