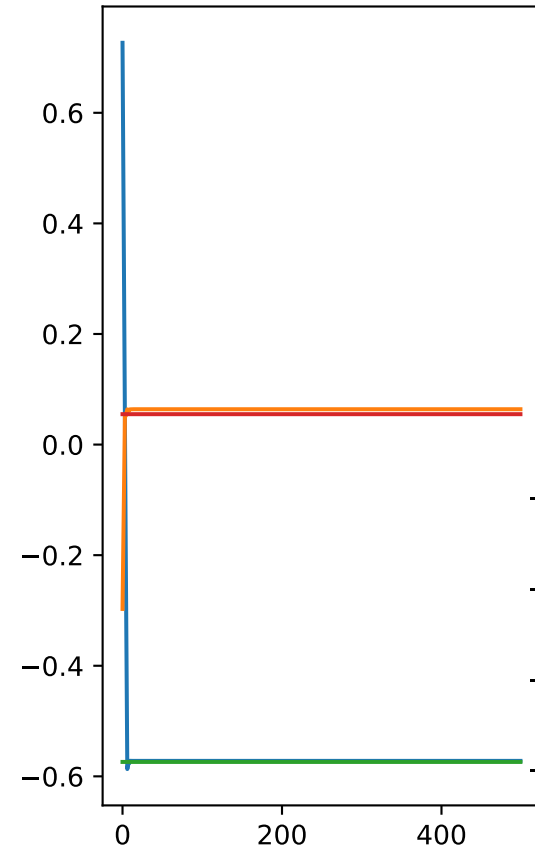
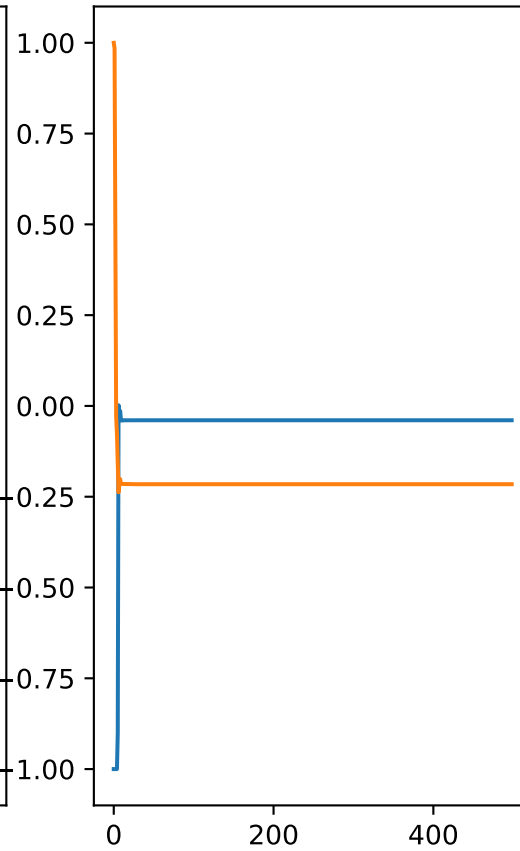


Reward: quartic_root_2
Speed = 678.9986943216268 [rad/s]

State vs step



Action vs step



Reward vs step

