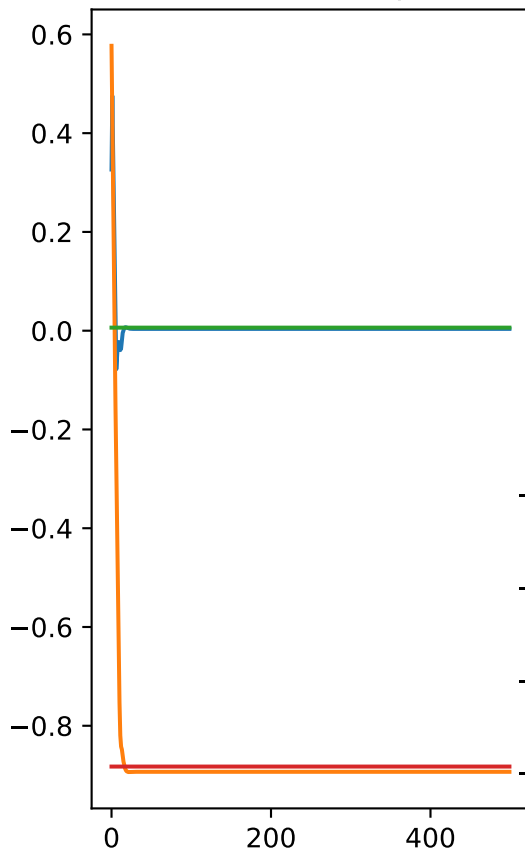
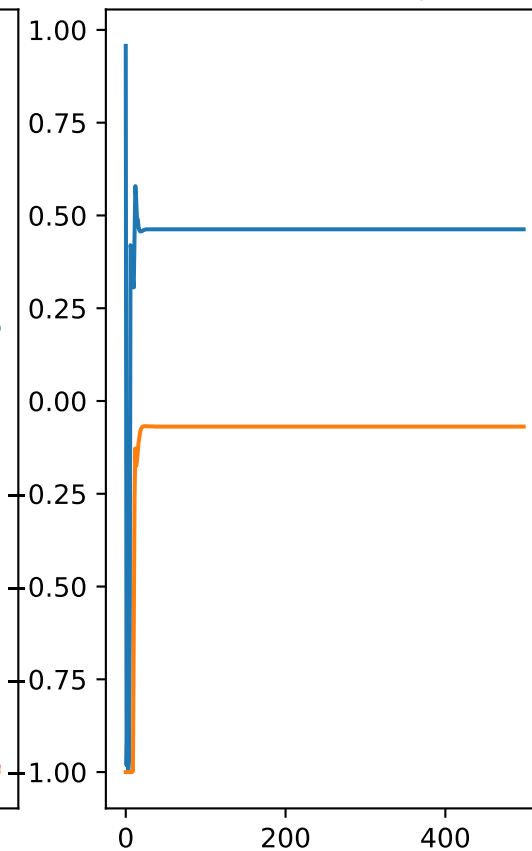


Reward: quadratic
Speed = 787.6726943830794 [rad/s]

State vs step



Action vs step



Reward vs step

