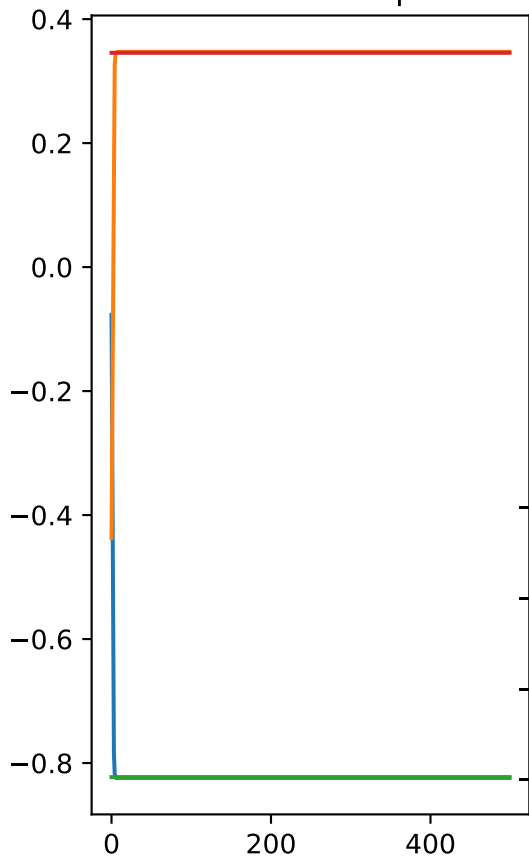
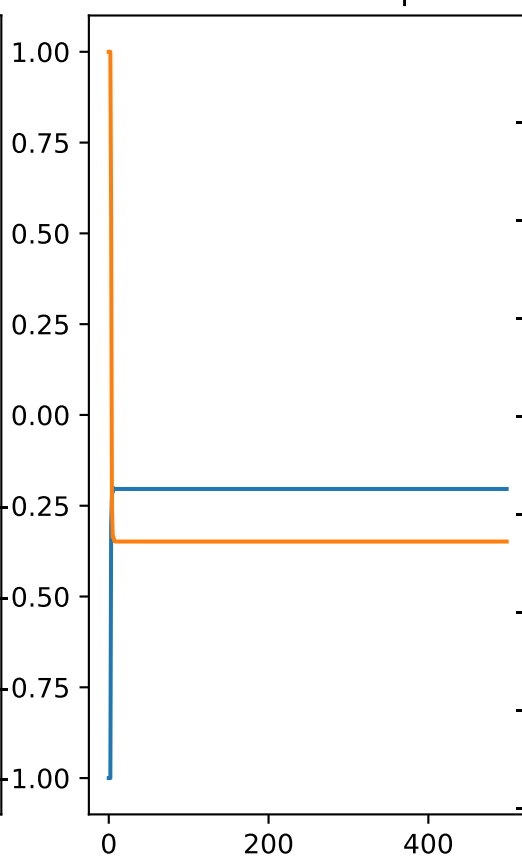


Reward: square\_root  
Speed = 674.5879003452102 [rad/s]

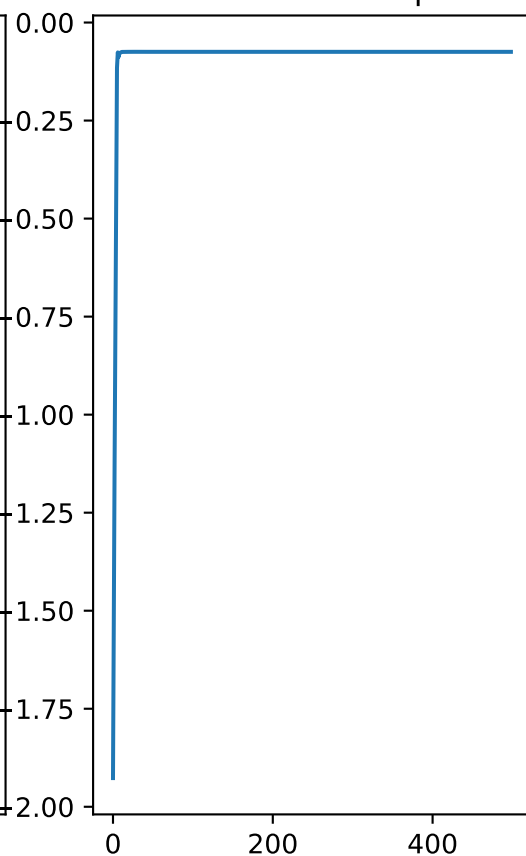
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq