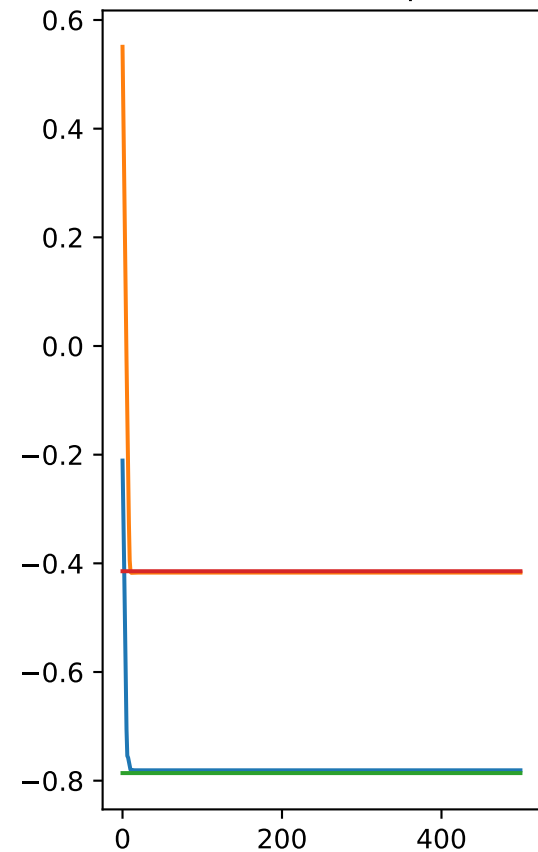
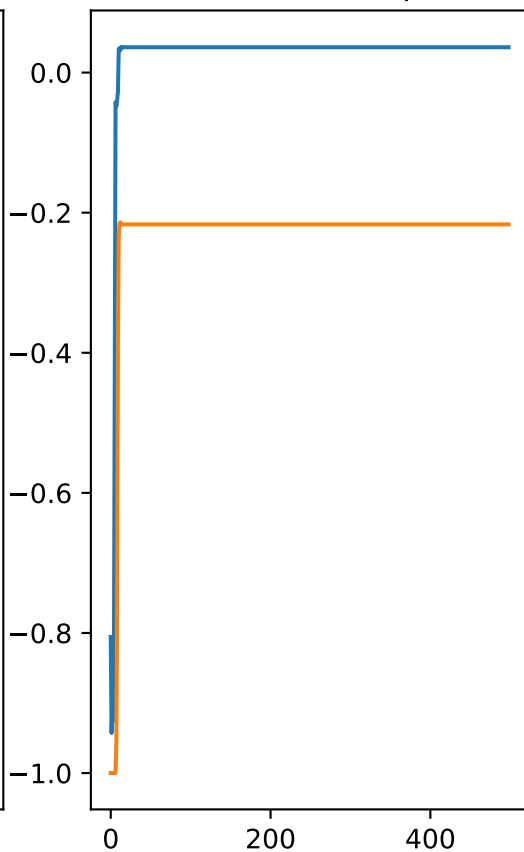


Reward: square_root_2
Speed = 1036.1097962484323 [rad/s]

State vs step



Action vs step



Reward vs step

