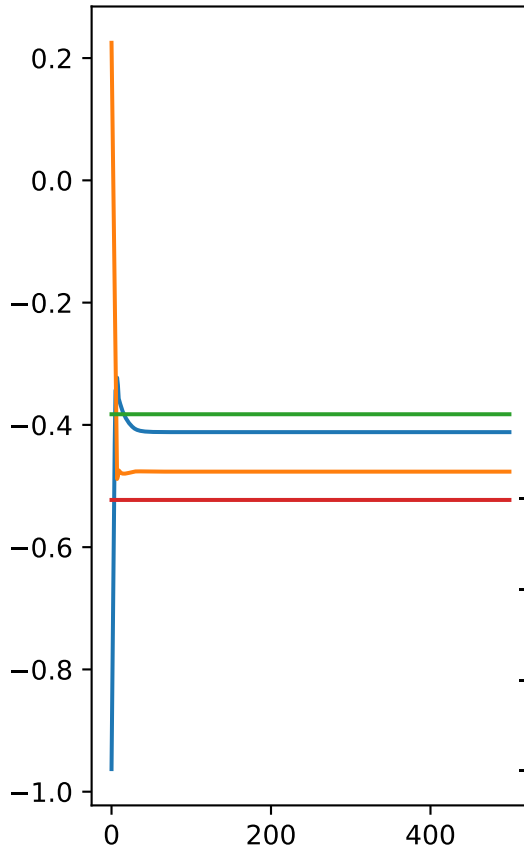
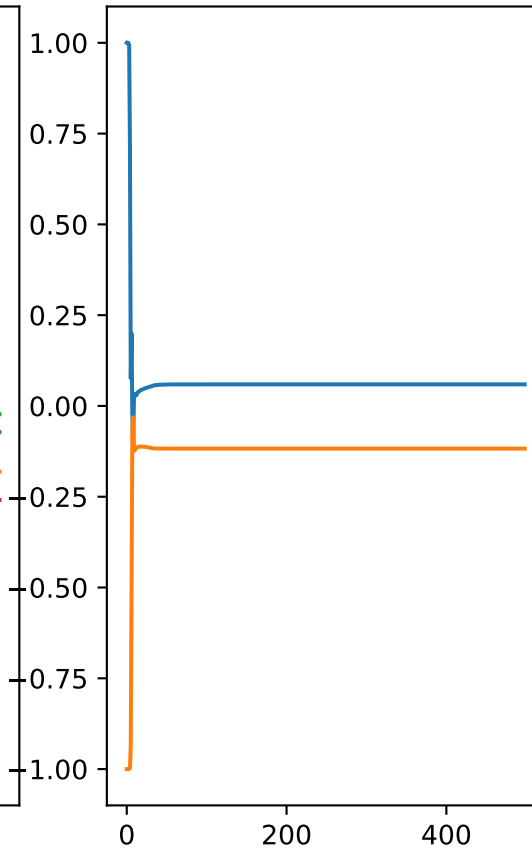


Reward: quadratic_2
Speed = 715.403473922251 [rad/s]

State vs step



Action vs step



Reward vs step

