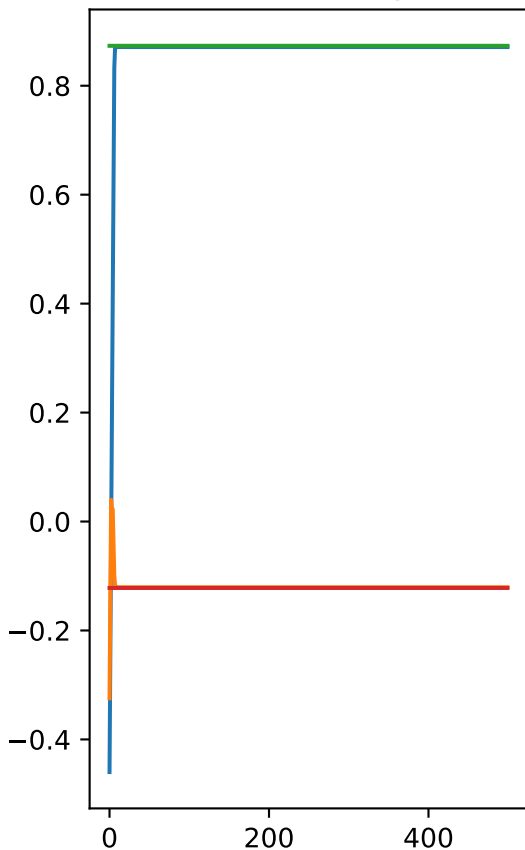
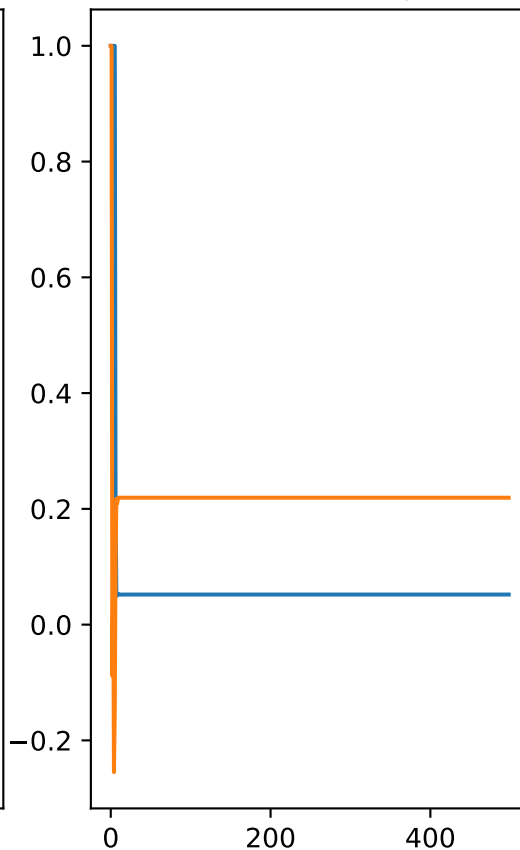


Reward: square_root_2
Speed = 36.203713799140885 [rad/s]

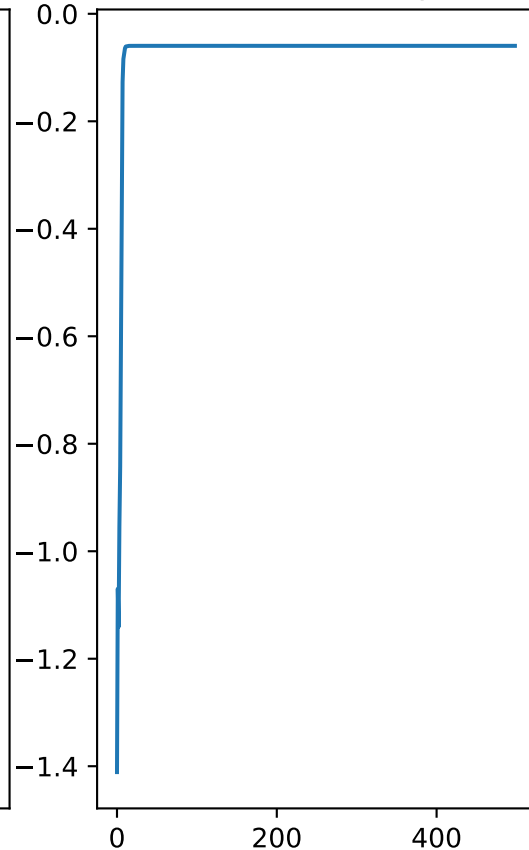
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq