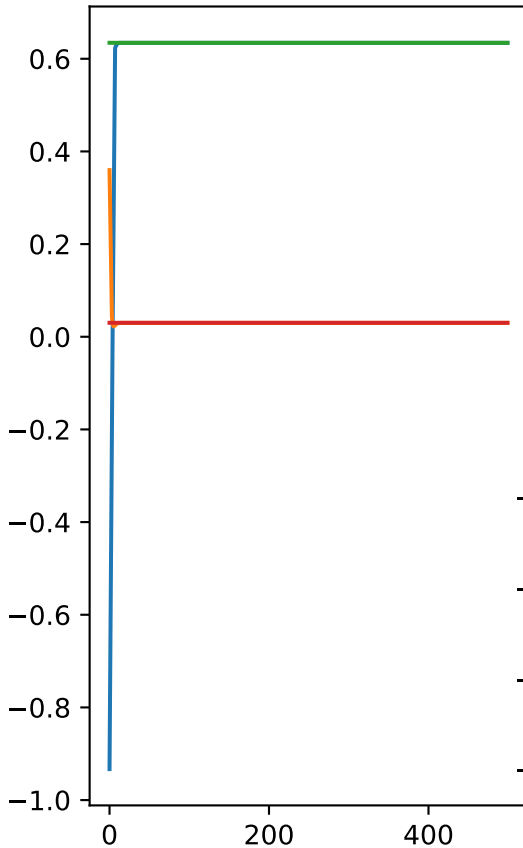
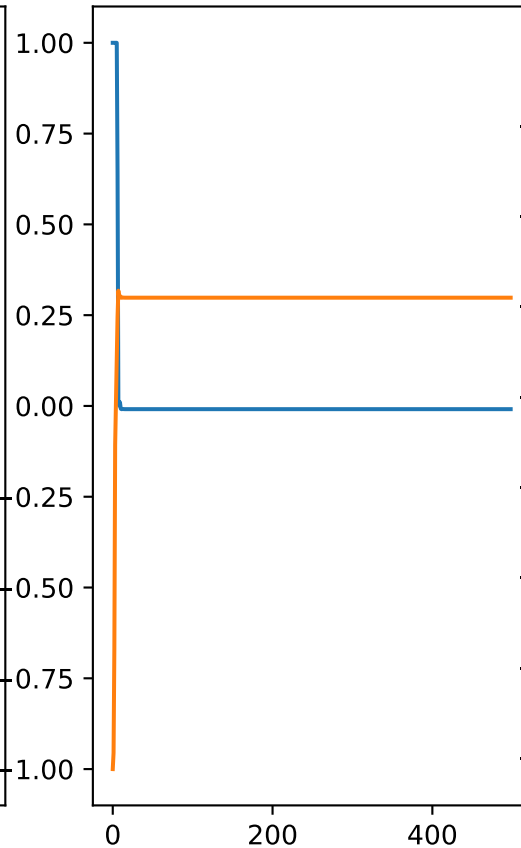


Reward: square\_root  
Speed = 87.86406762595185 [rad/s]

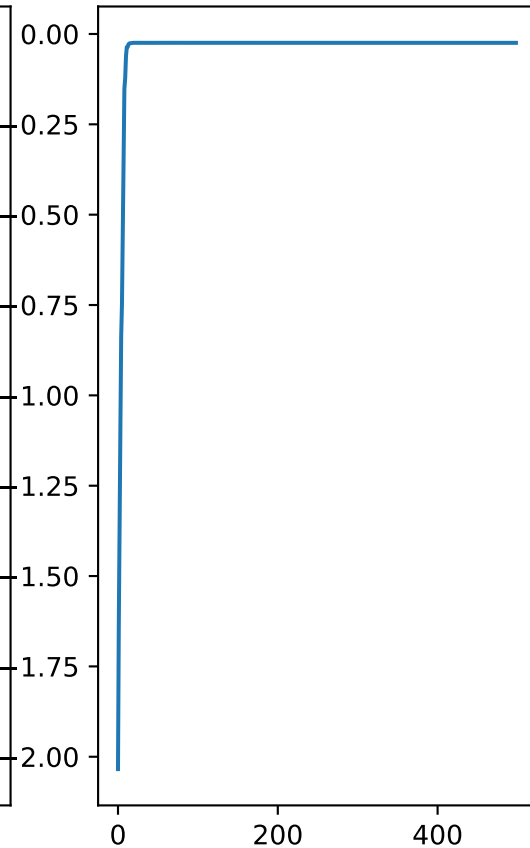
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq