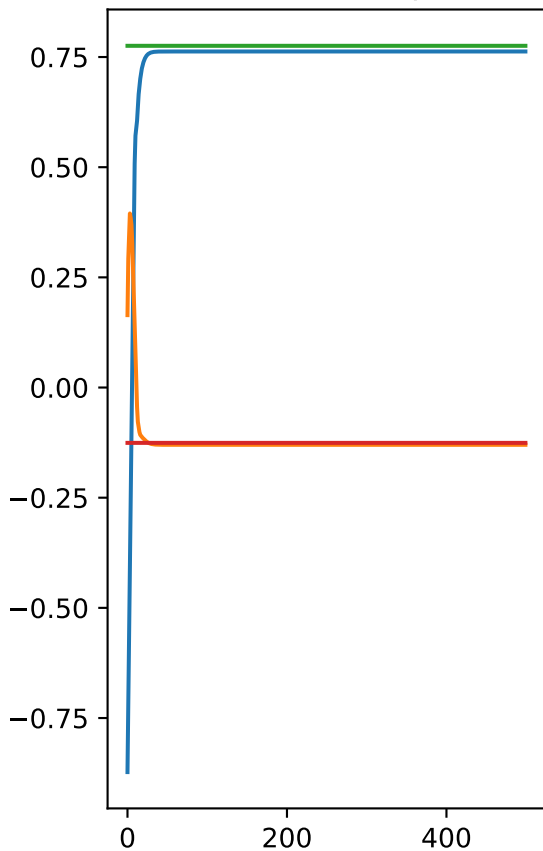
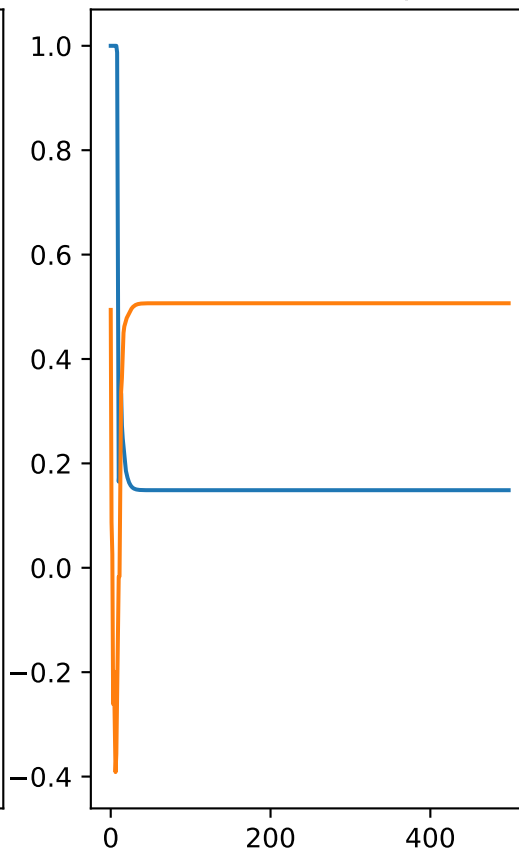


Reward: quadratic
Speed = 65.86034722439055 [rad/s]

State vs step



Action vs step



Reward vs step

