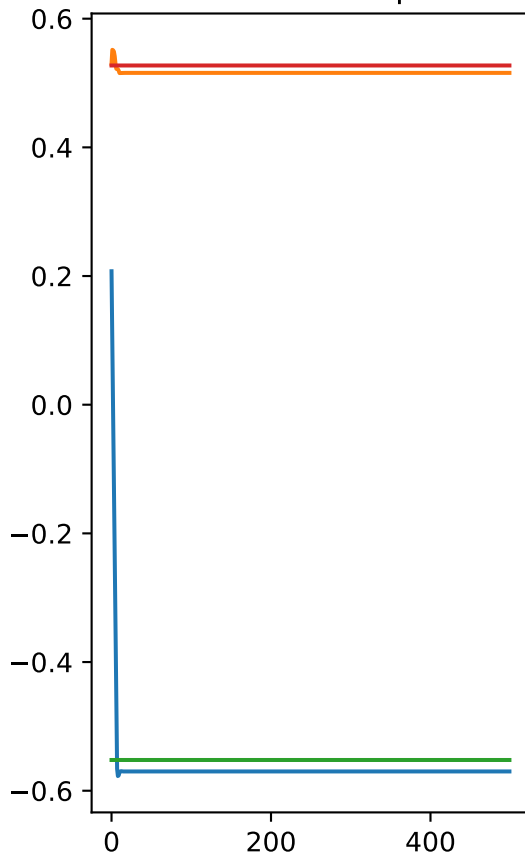
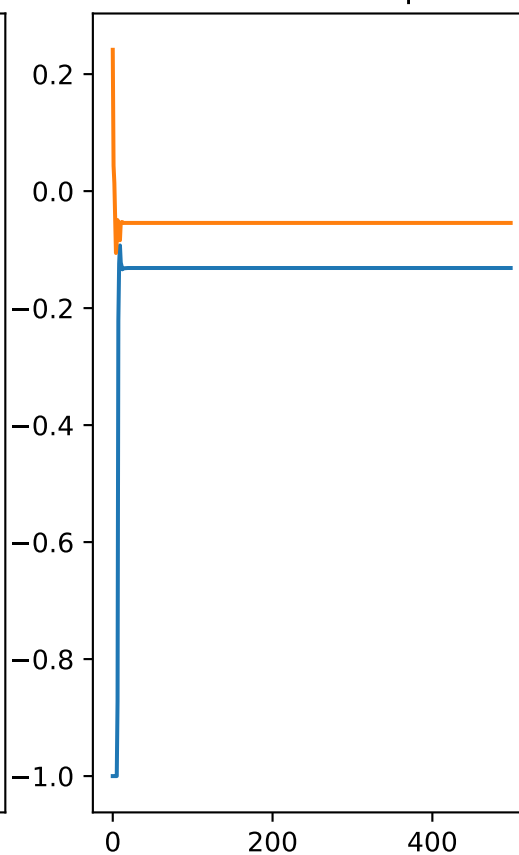


Reward: quartic\_root  
Speed = 83.18937727204913 [rad/s]

State vs step



Action vs step



Reward vs step

