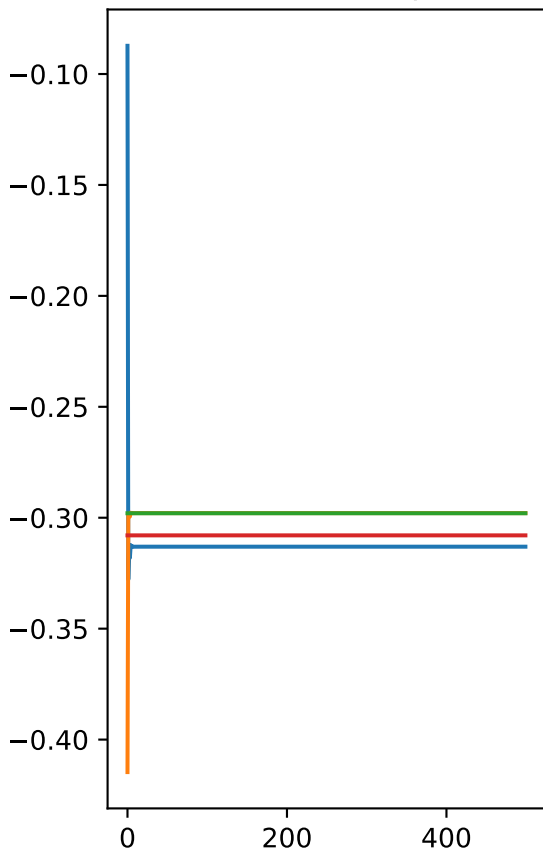
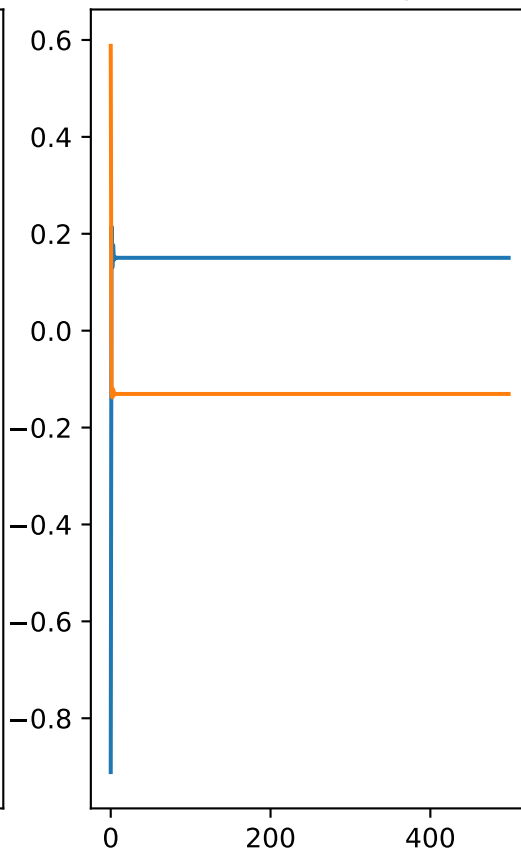


Reward: quartic_root_2
Speed = 441.2555282970545 [rad/s]

State vs step



Action vs step



Reward vs step

