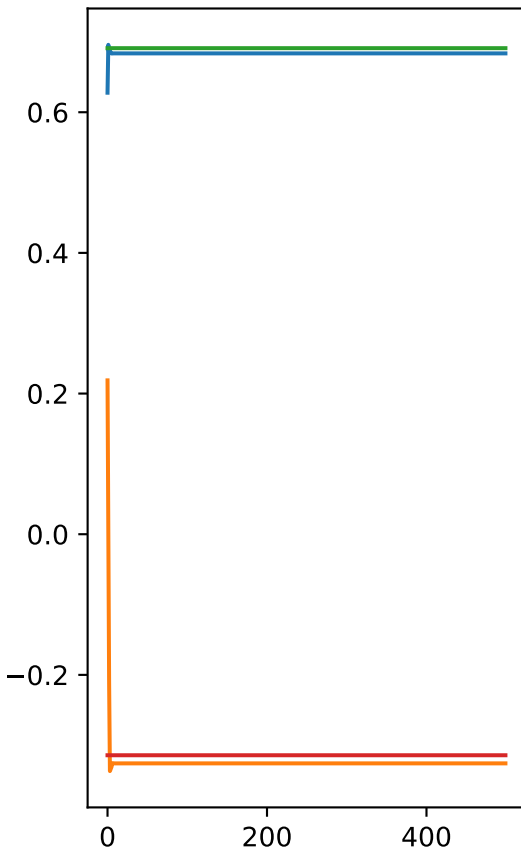
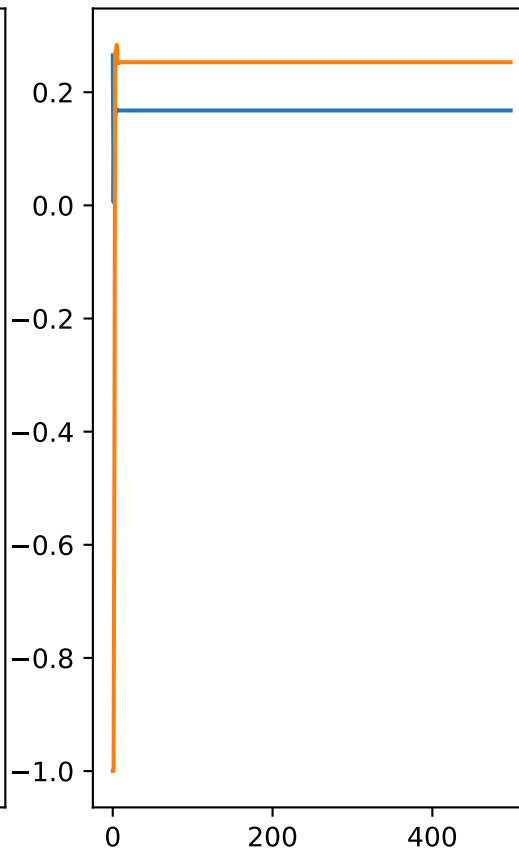


Reward: quartic_root
Speed = 831.3408130932177 [rad/s]

State vs step



Action vs step



Reward vs step

