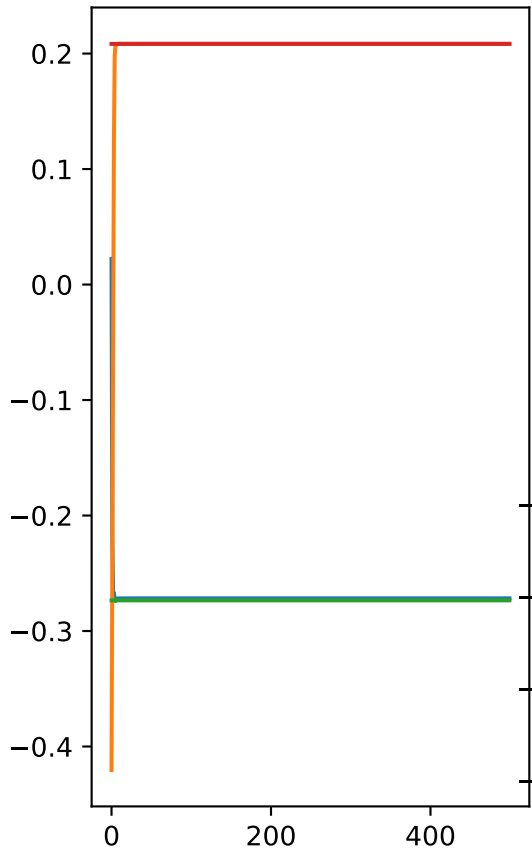
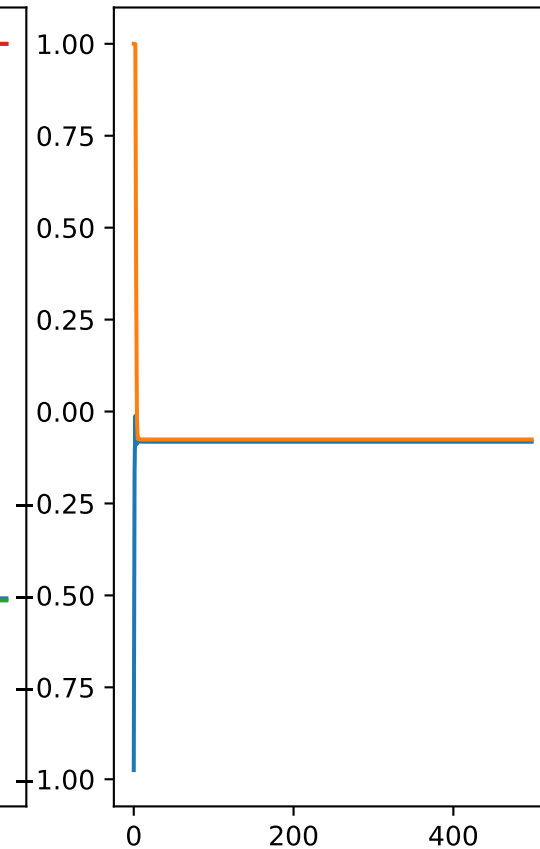


Reward: square_root
Speed = 24.49185615211674 [rad/s]

State vs step



Action vs step



Reward vs step

