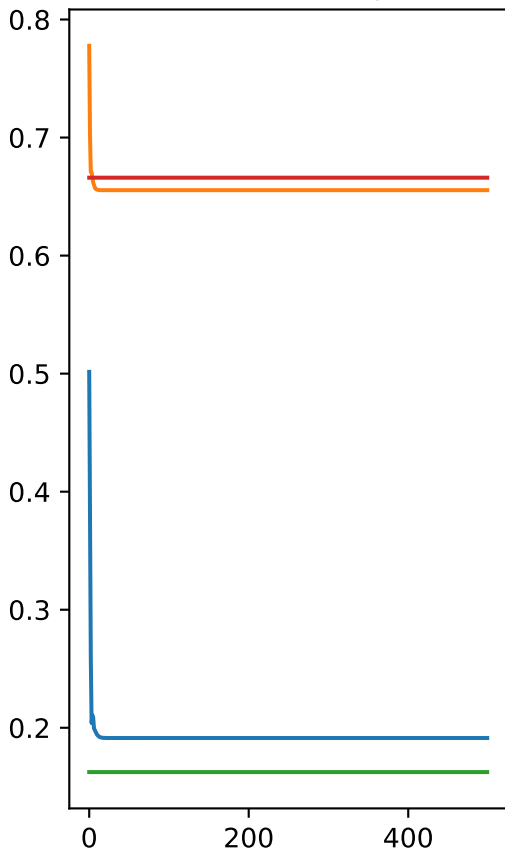
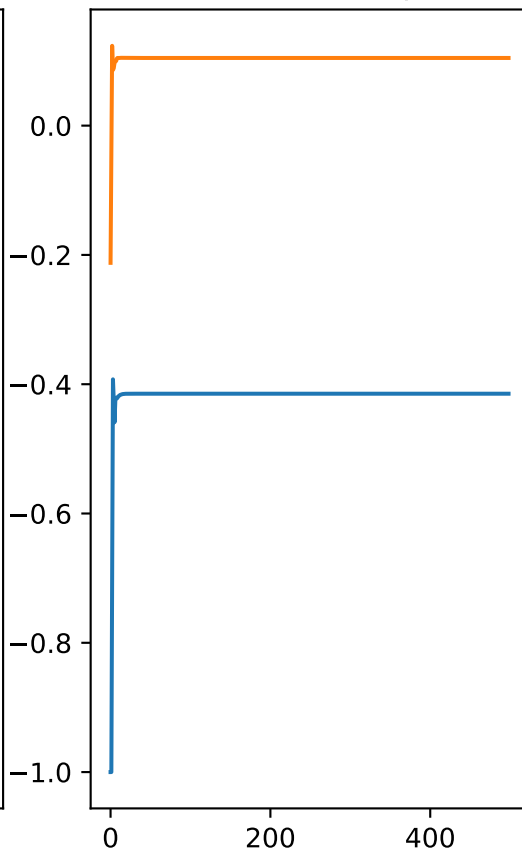


Reward: quadratic\_2  
Speed = 807.7160109316656 [rad/s]

State vs step



Action vs step



Reward vs step

