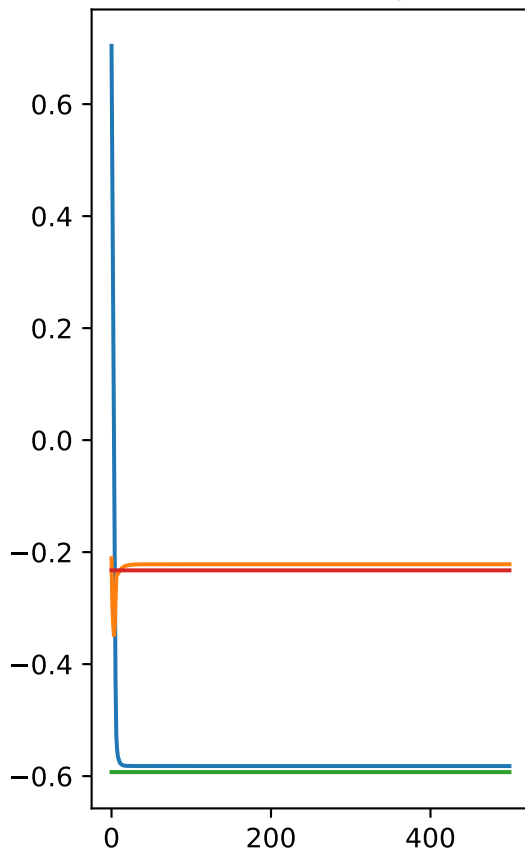
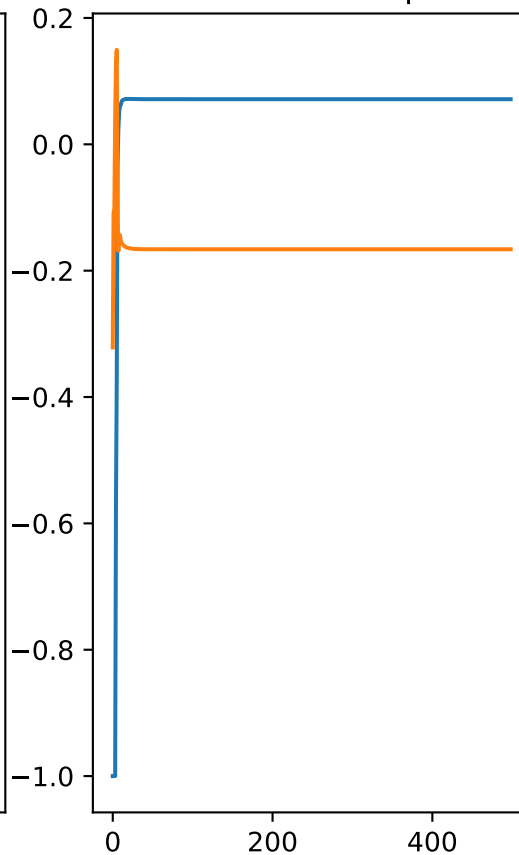


Reward: quadratic\_2  
Speed = 1034.3756789046272 [rad/s]

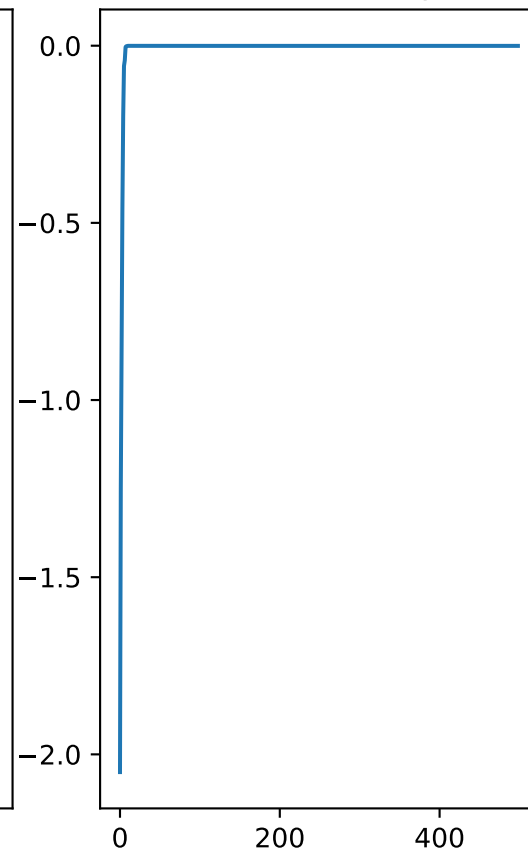
State vs step



Action vs step



Reward vs step



—  $I_d$  —  $I_{dref}$   
—  $I_q$  —  $I_{qref}$

—  $V_d$  —  $V_q$