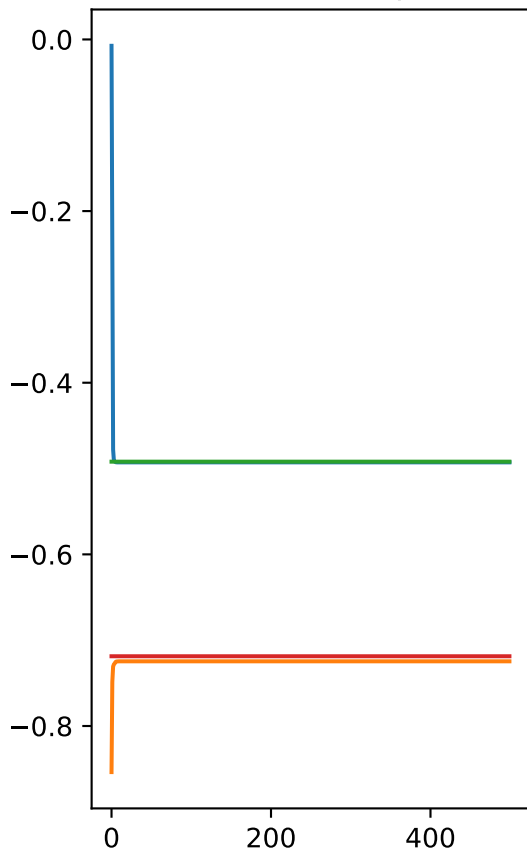
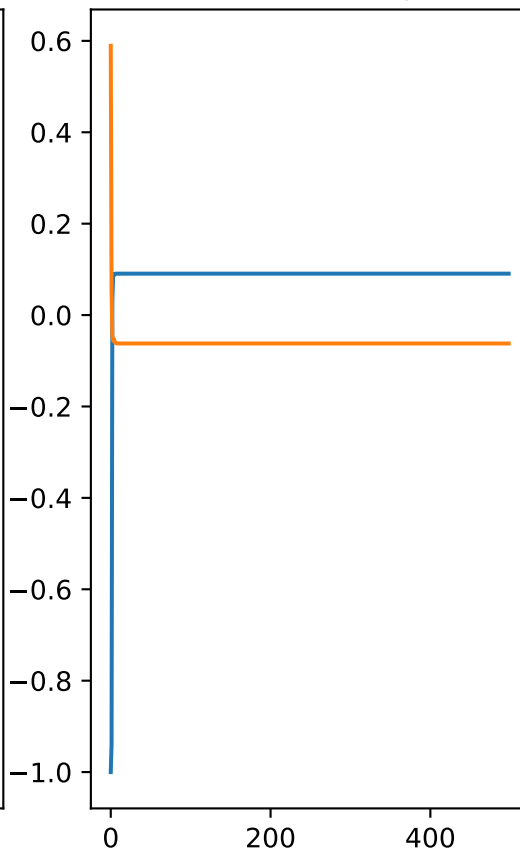


Reward: square_root
Speed = 935.013346693231 [rad/s]

State vs step



Action vs step



Reward vs step

