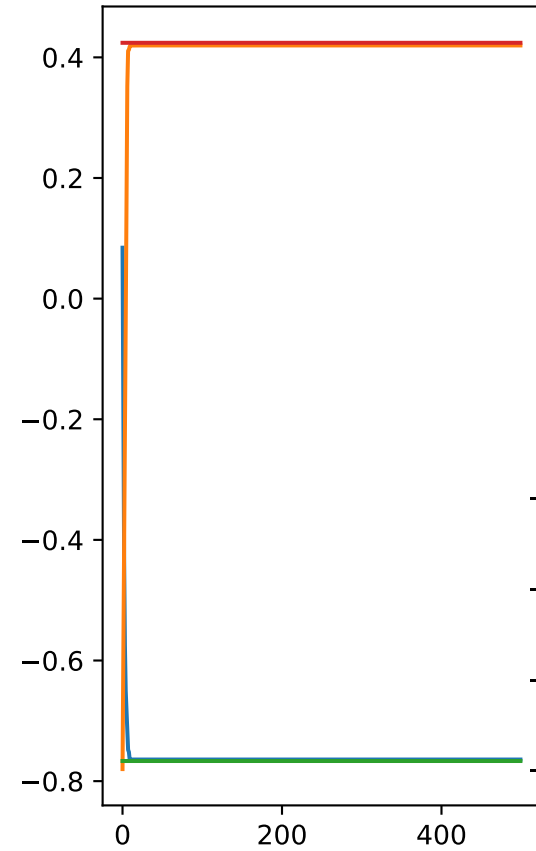
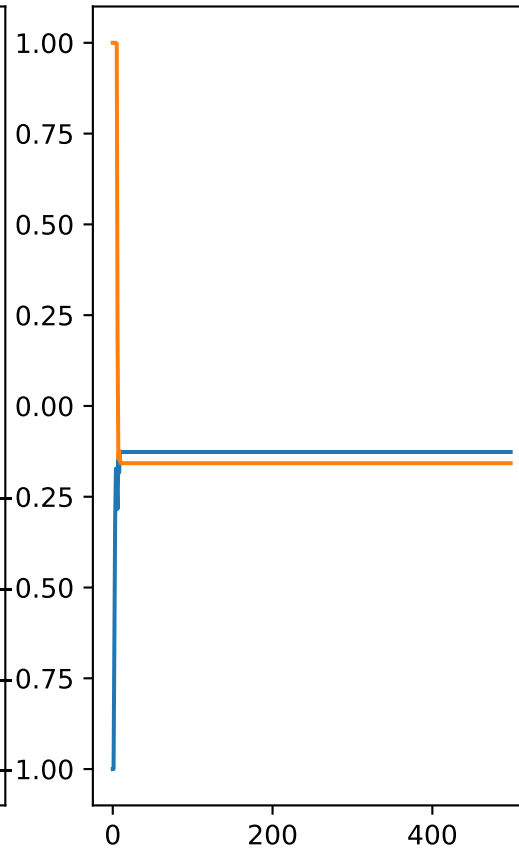


Reward: square_root_2
Speed = 98.67114203997977 [rad/s]

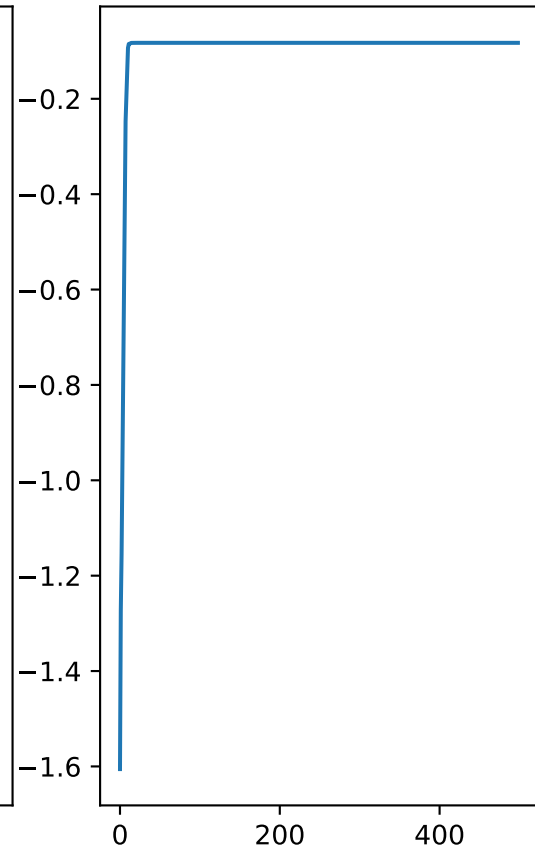
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq