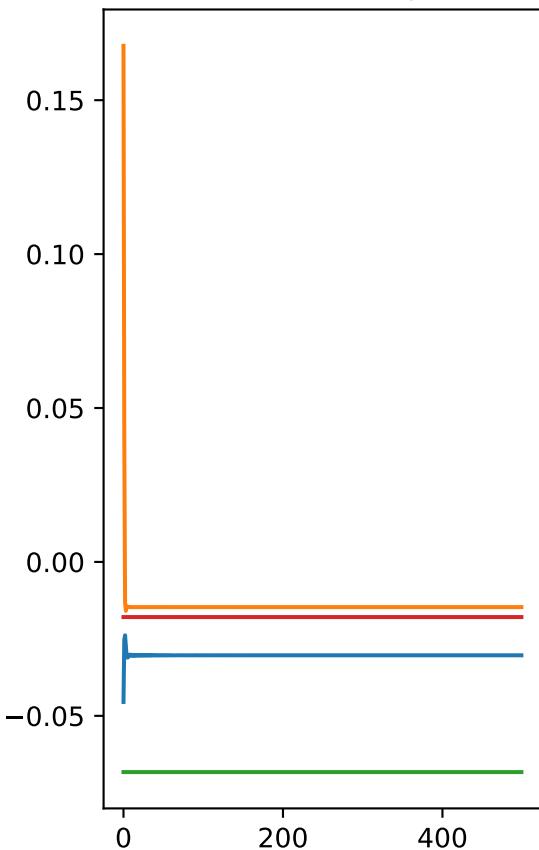
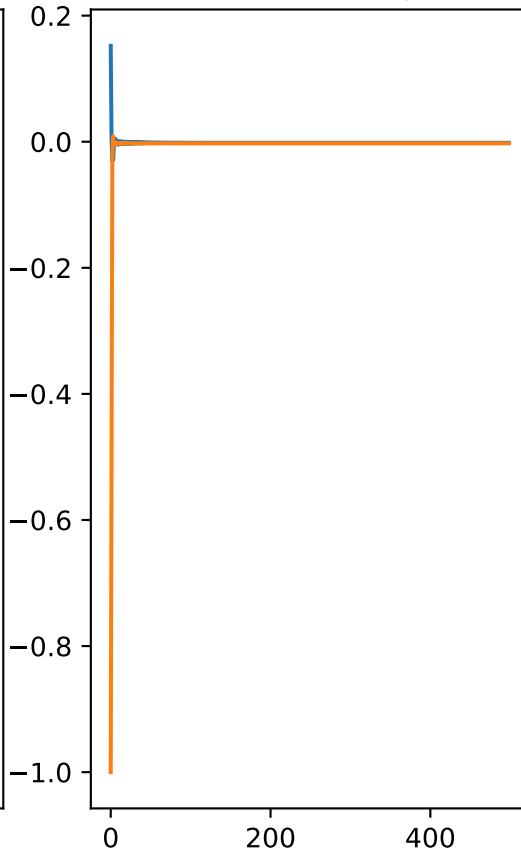


Reward: square\_root  
Speed = 718.6581647023289 [rad/s]

State vs step



Action vs step



Reward vs step

