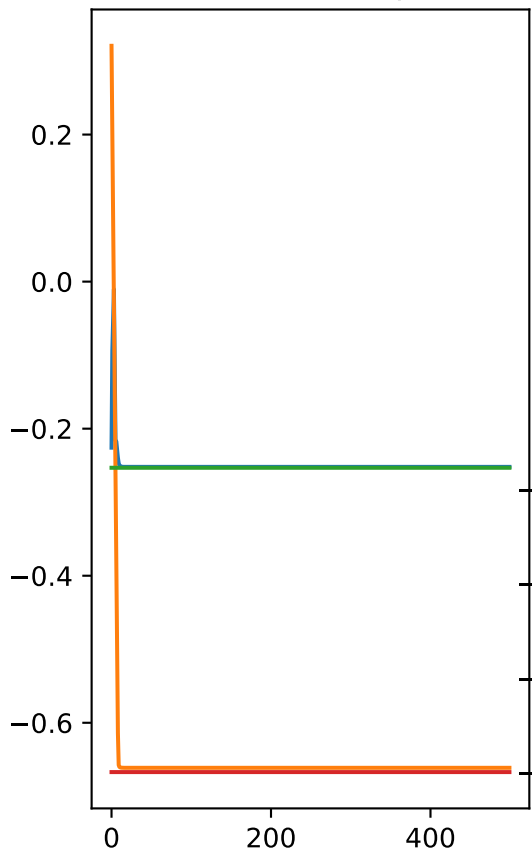
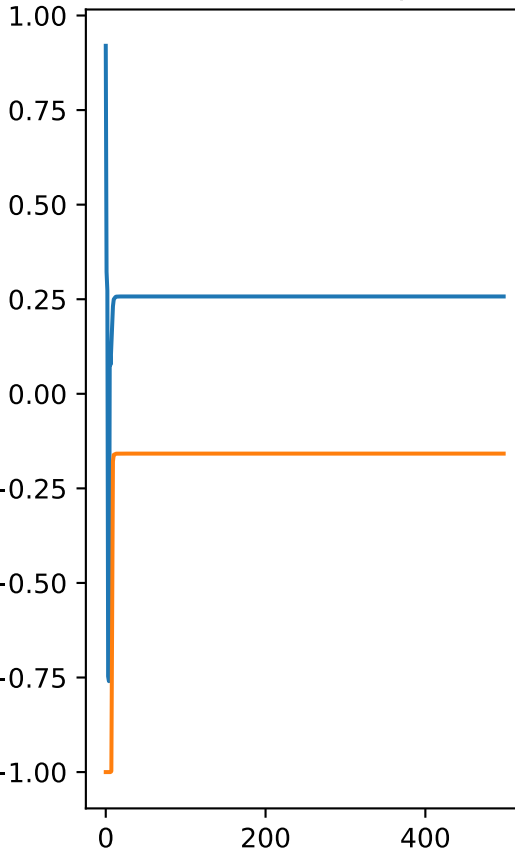


Reward: square_root_2
Speed = 985.3667903654167 [rad/s]

State vs step



Action vs step



Reward vs step

