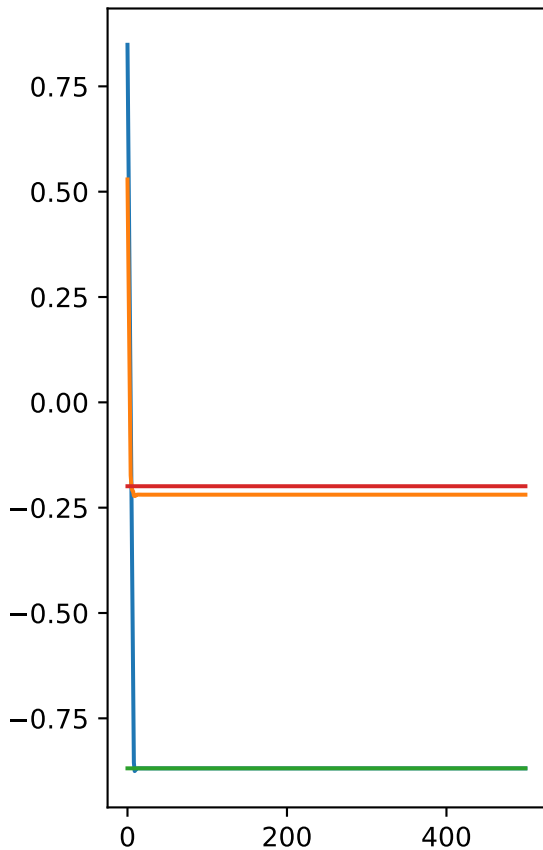
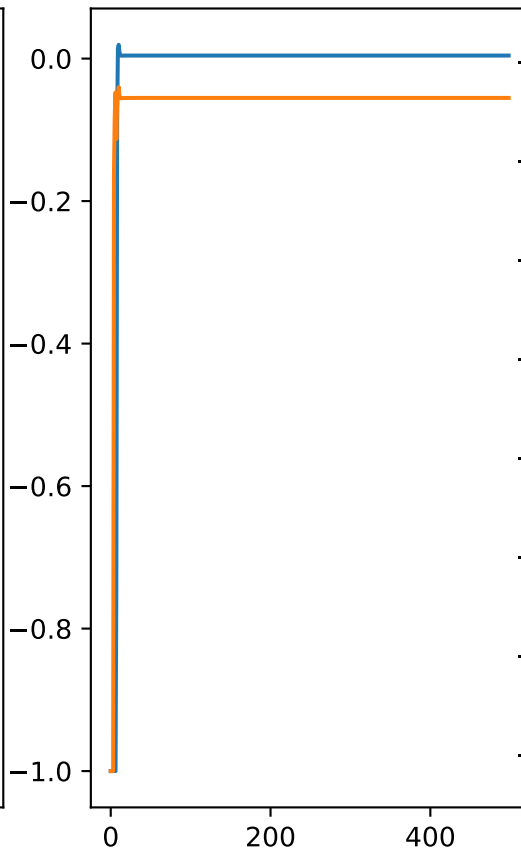


Reward: quartic_root
Speed = 561.4780143364455 [rad/s]

State vs step



Action vs step



Reward vs step

