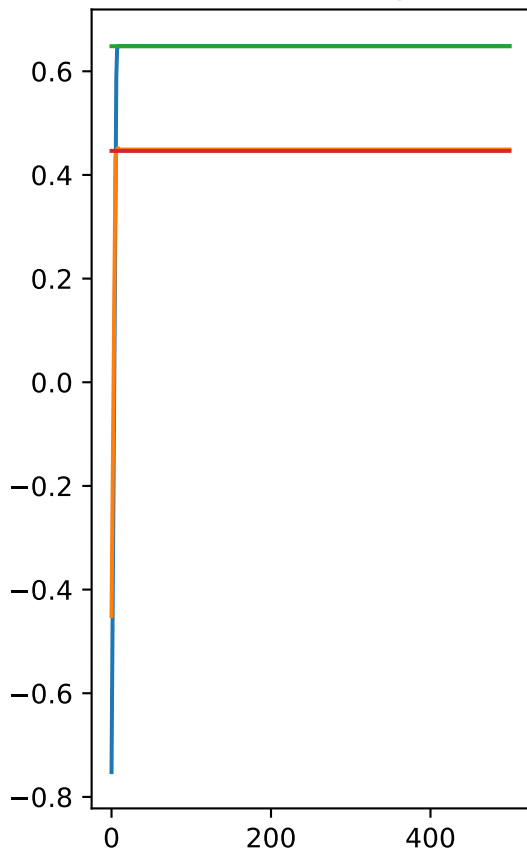
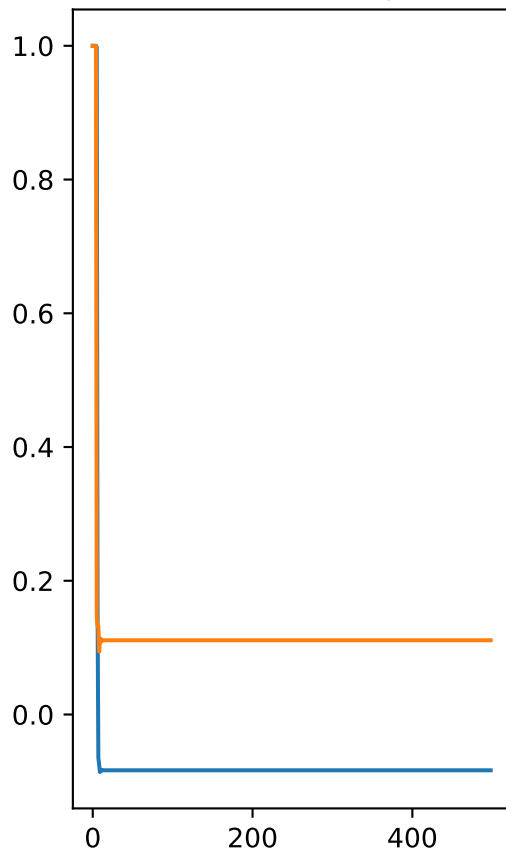


Reward: square\_root\_2  
Speed = 117.13113649970285 [rad/s]

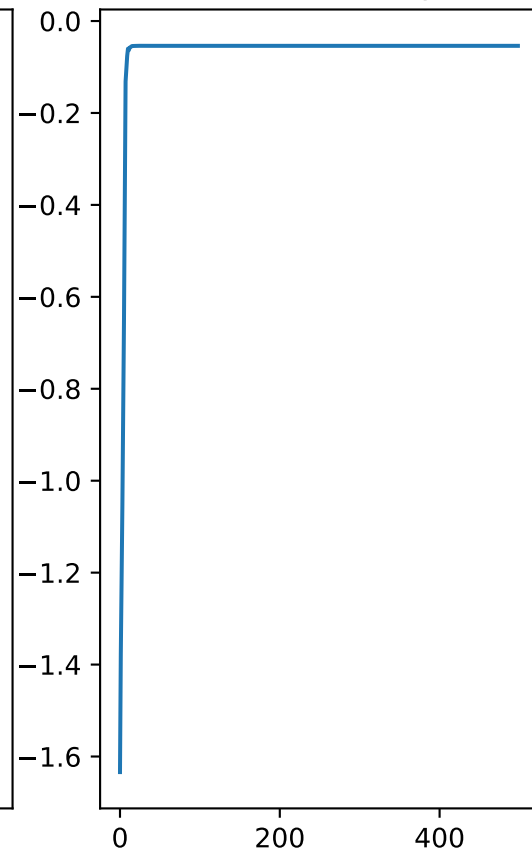
State vs step



Action vs step



Reward vs step



$I_d$   $I_q$   $I_{dref}$   $I_{qref}$

$V_d$   $V_q$