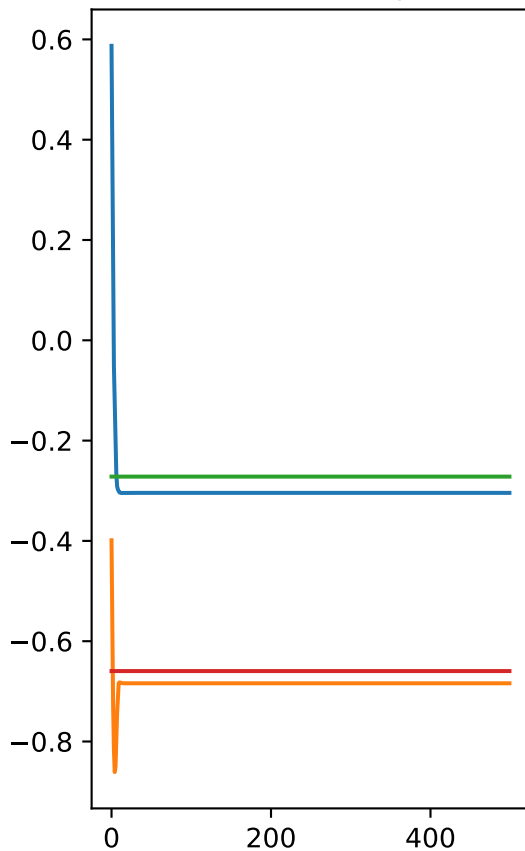
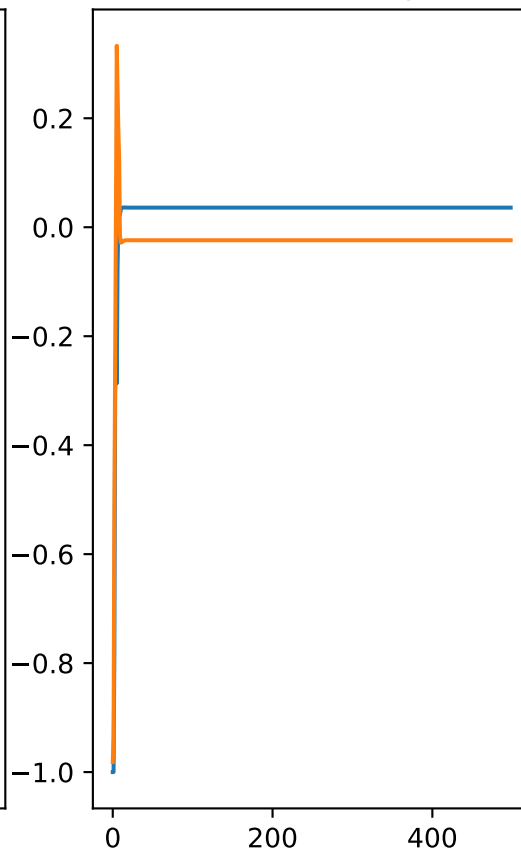


Reward: quadratic_2
Speed = 523.4647270493055 [rad/s]

State vs step



Action vs step



Reward vs step

