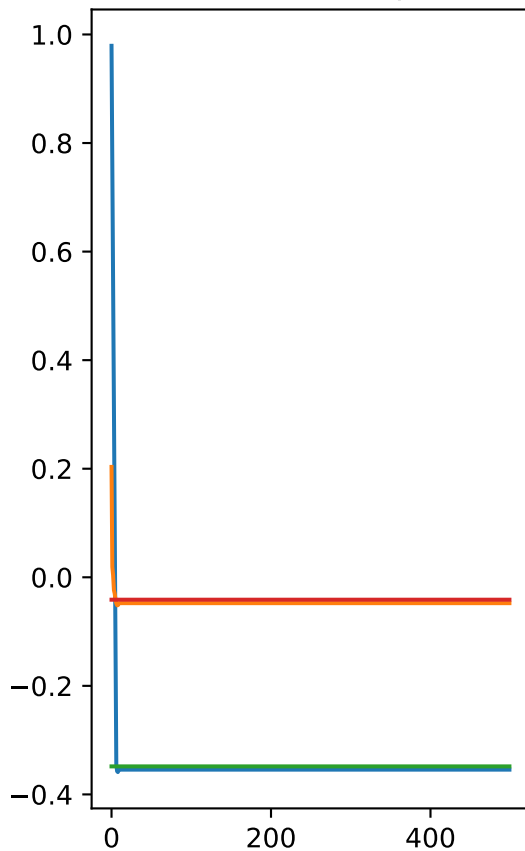
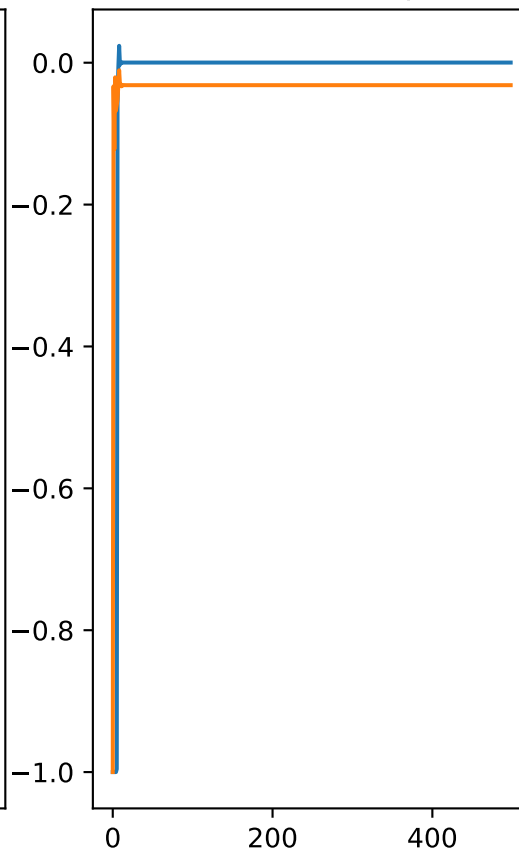


Reward: quartic_root
Speed = 418.2339446059731 [rad/s]

State vs step



Action vs step



Reward vs step

