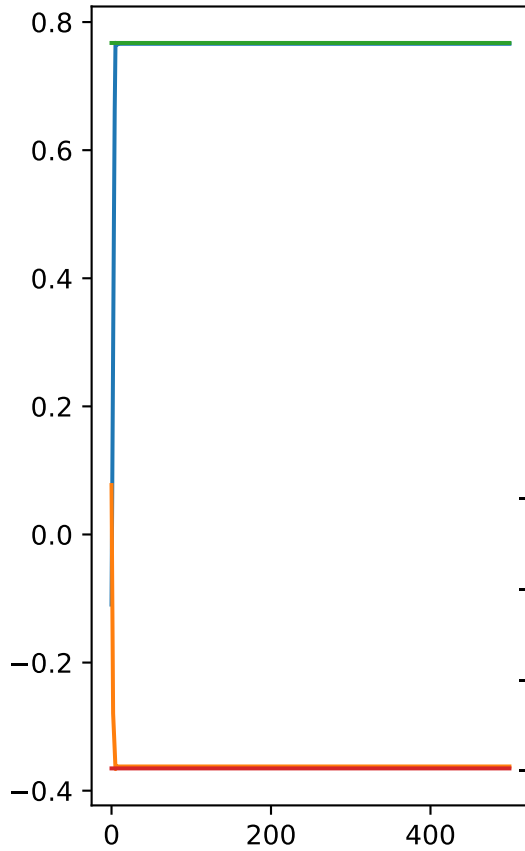
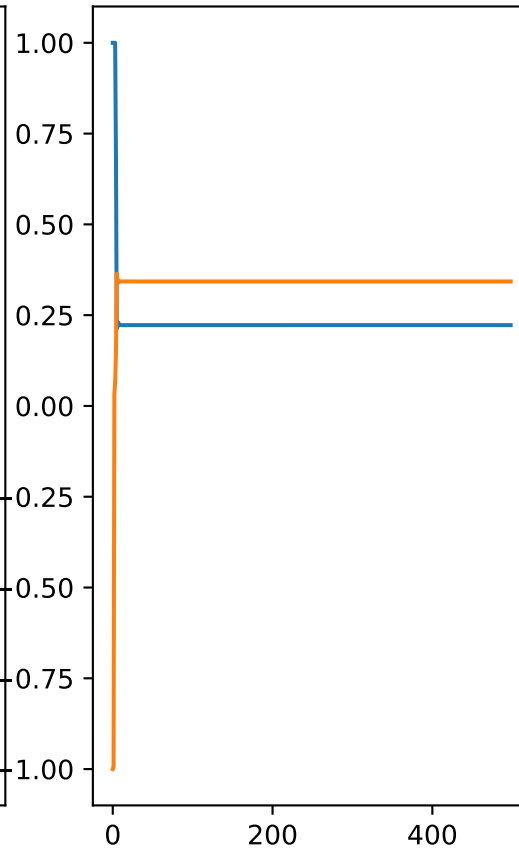


Reward: square_root_2
Speed = 14.76548496628754 [rad/s]

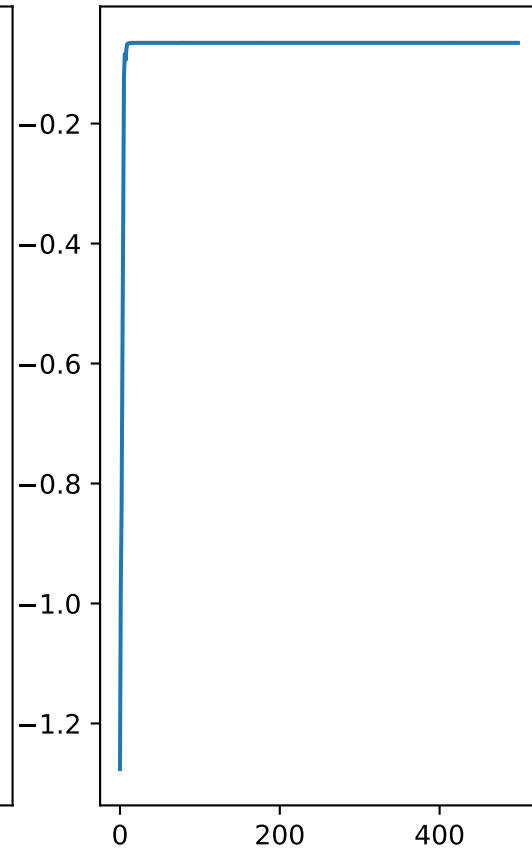
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq