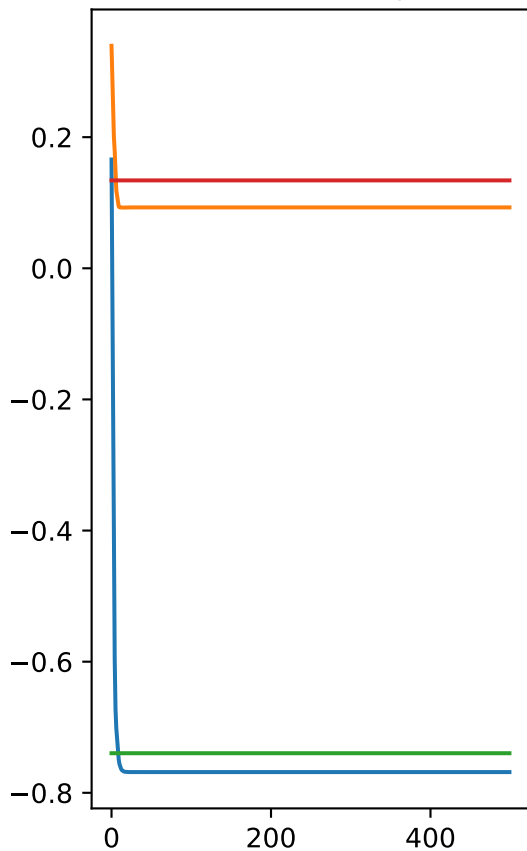
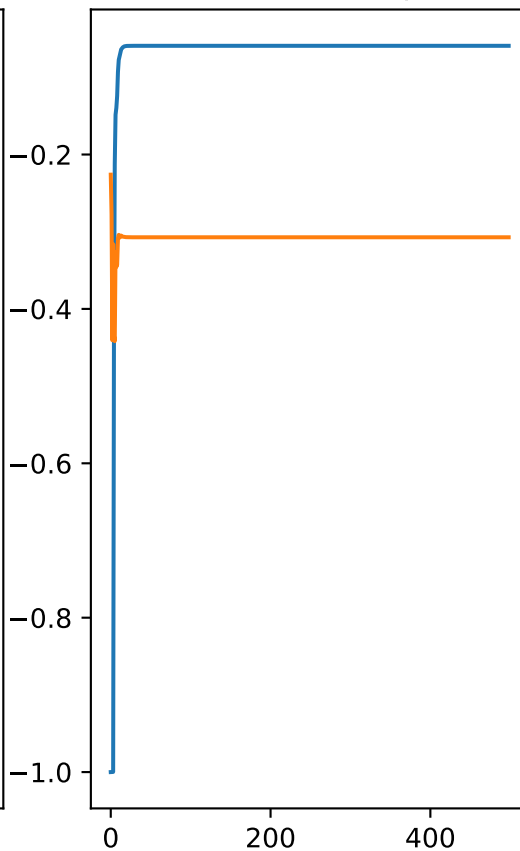


Reward: quadratic_2
Speed = 1109.2712422534644 [rad/s]

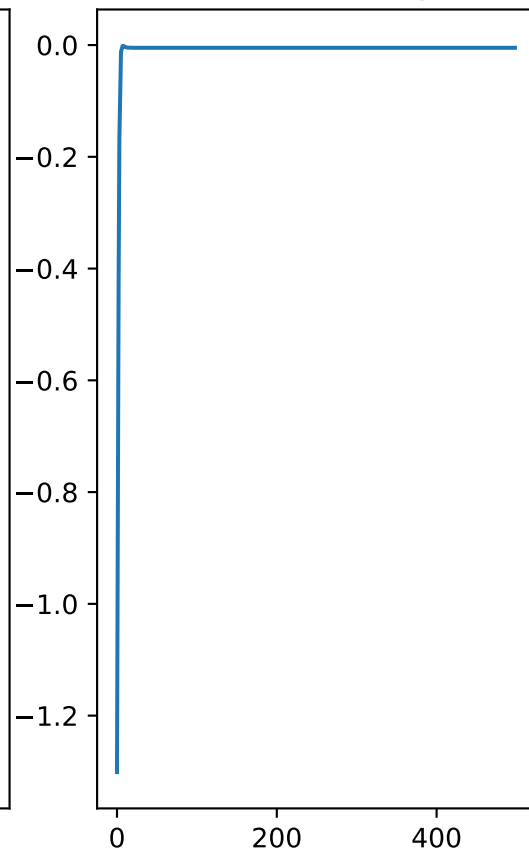
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq