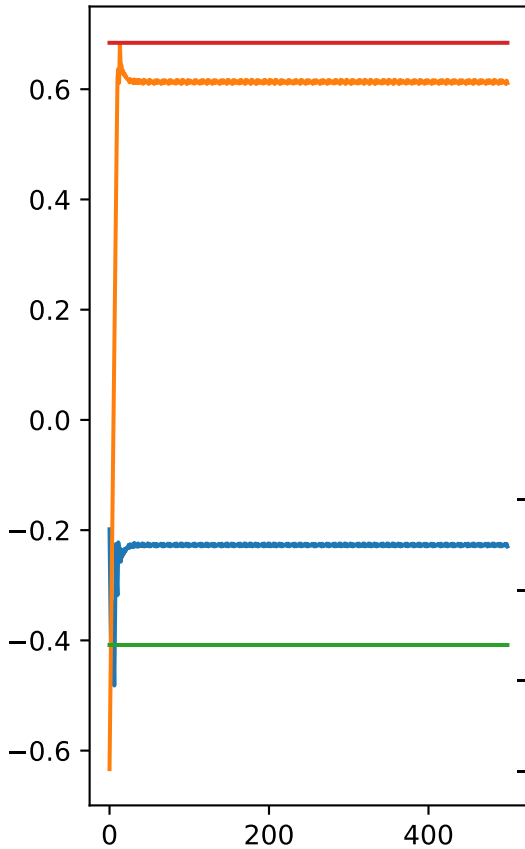
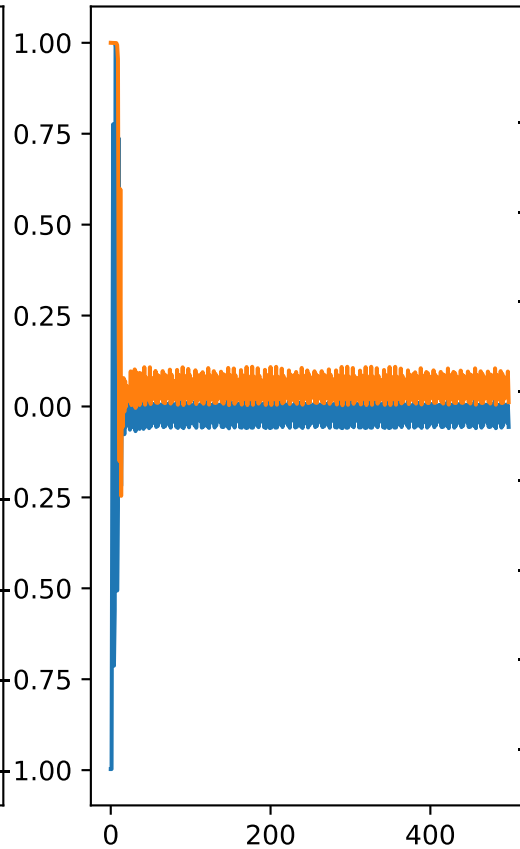


Reward: quadratic
Speed = 973.8936926522737 [rad/s]

State vs step



Action vs step



Reward vs step

