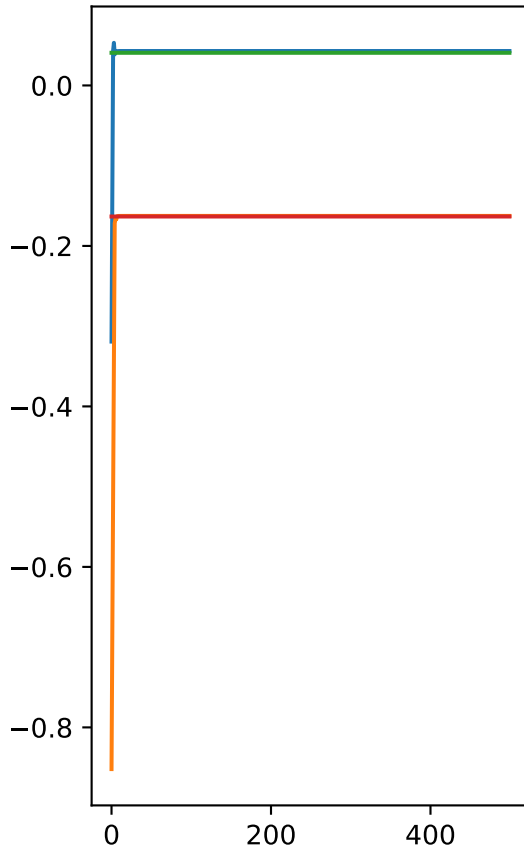
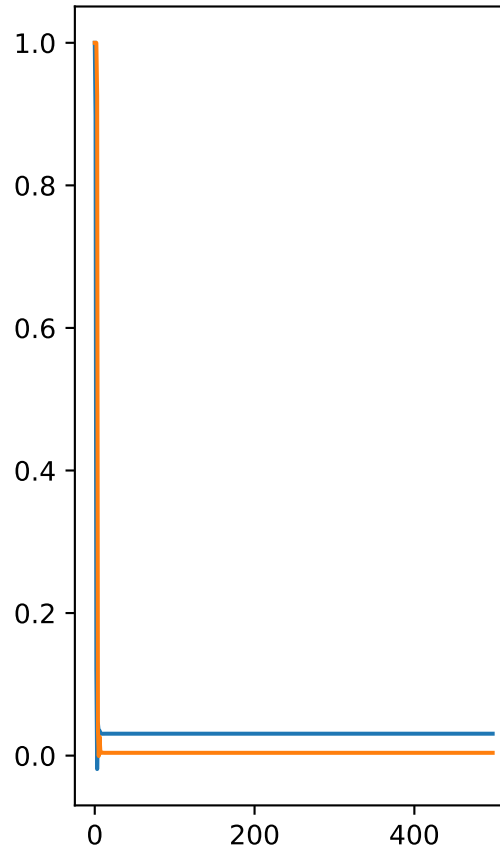


Reward: square\_root\_2  
Speed = 81.02795677163813 [rad/s]

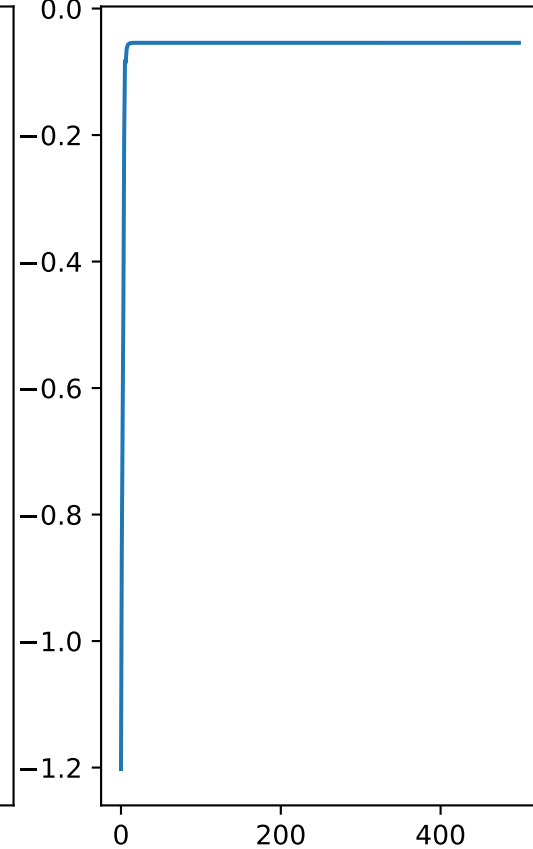
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq