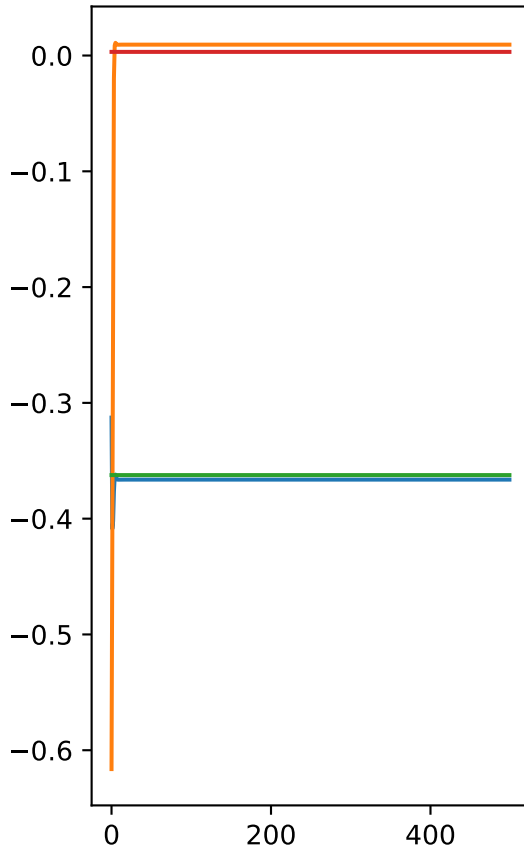
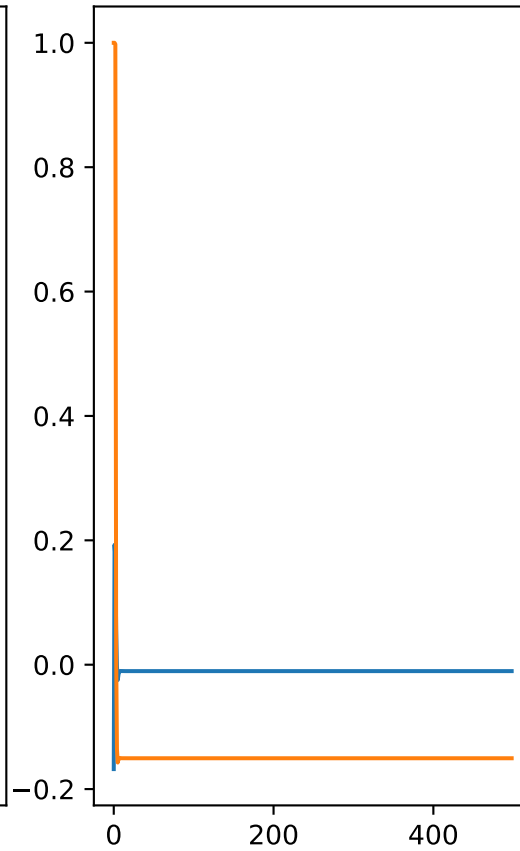


Reward: quartic_root_2
Speed = 857.9060946381102 [rad/s]

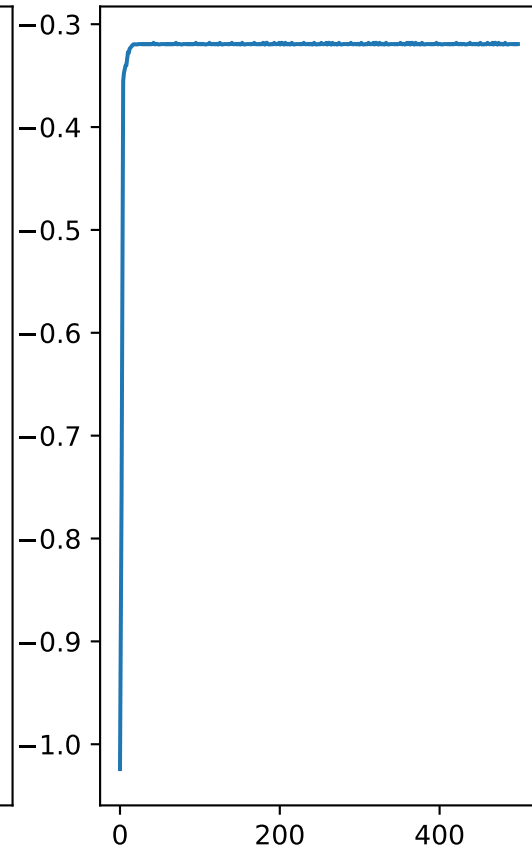
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq