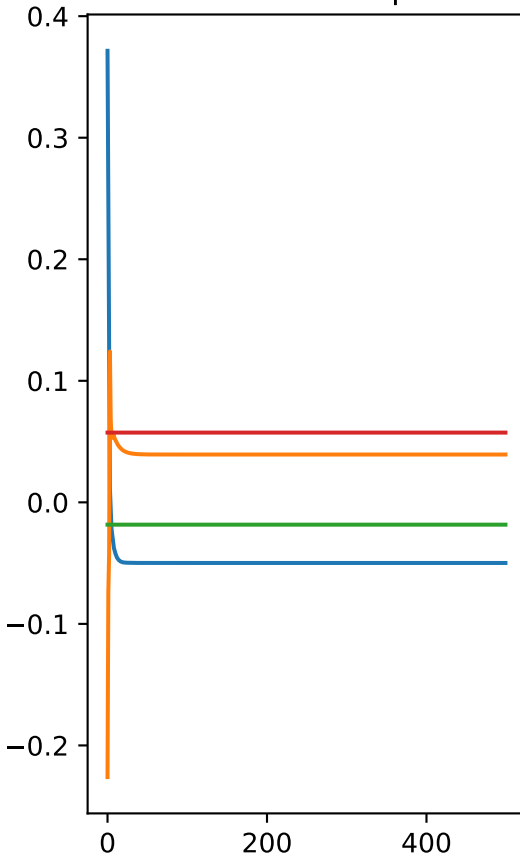
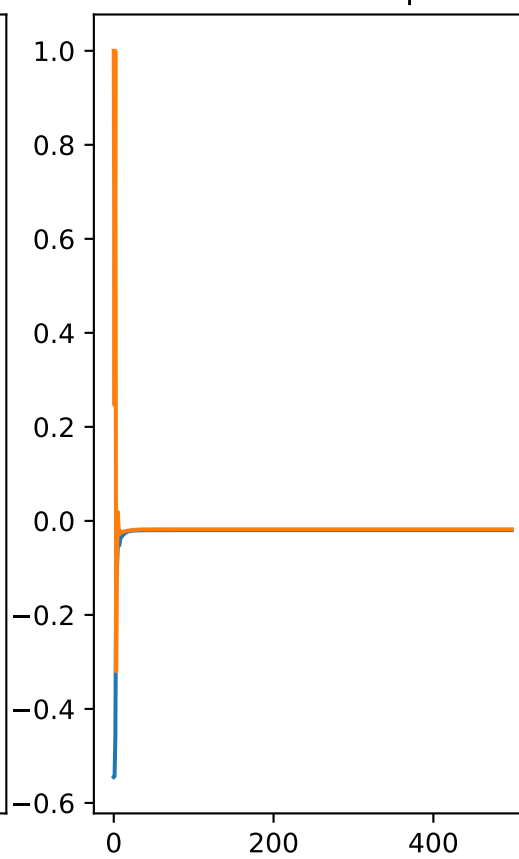


Reward: quadratic_2
Speed = 774.616180954316 [rad/s]

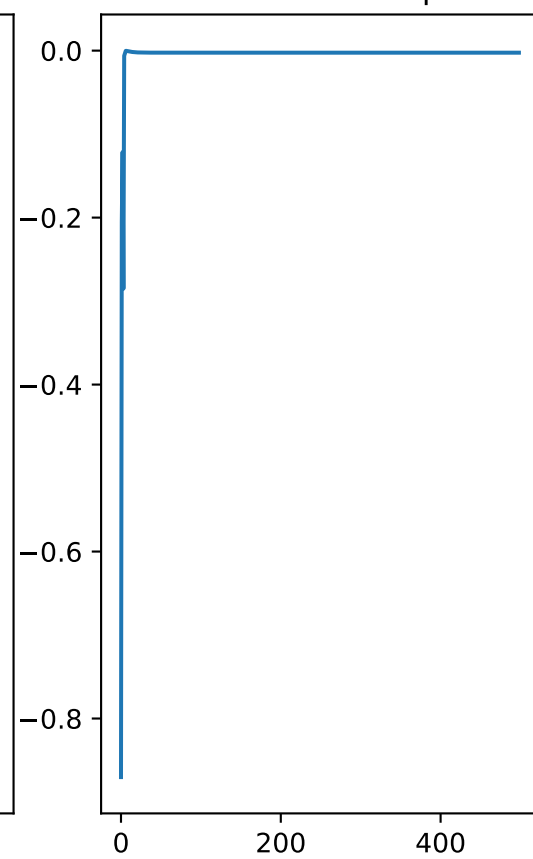
State vs step



Action vs step



Reward vs step



Id Iqref
Iq Iqref

Vd Vq