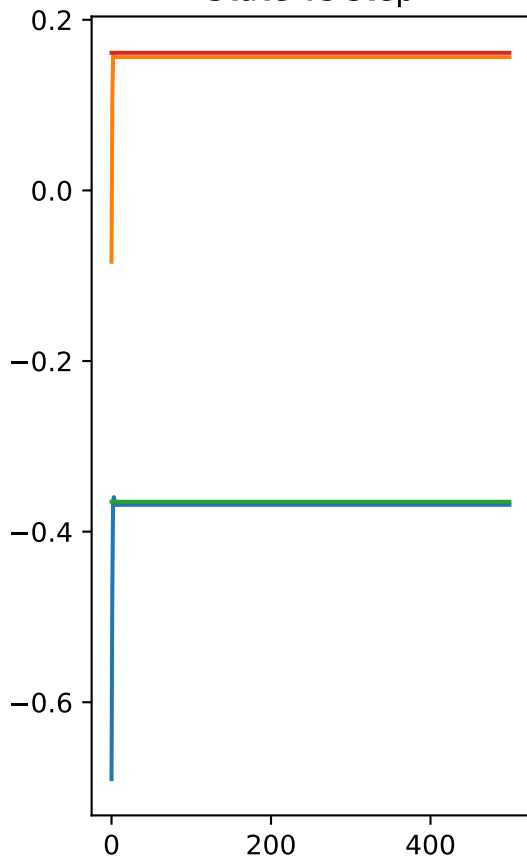
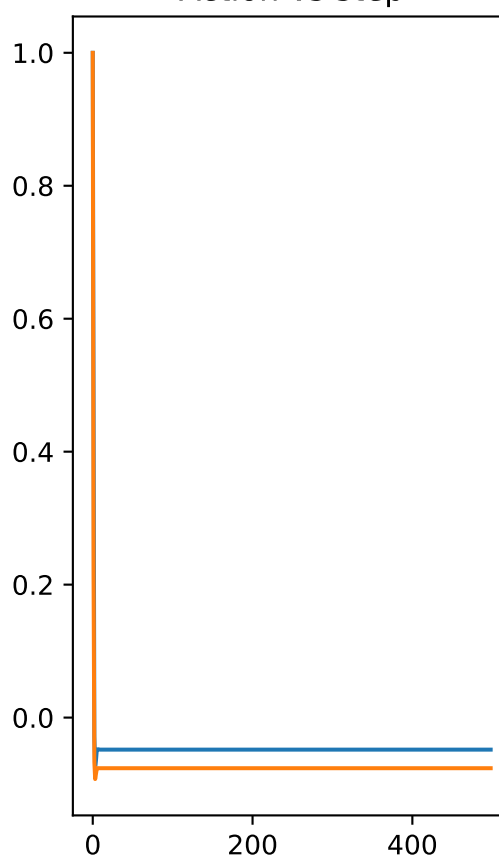


Reward: quartic_root_2
Speed = 487.75110016939476 [rad/s]

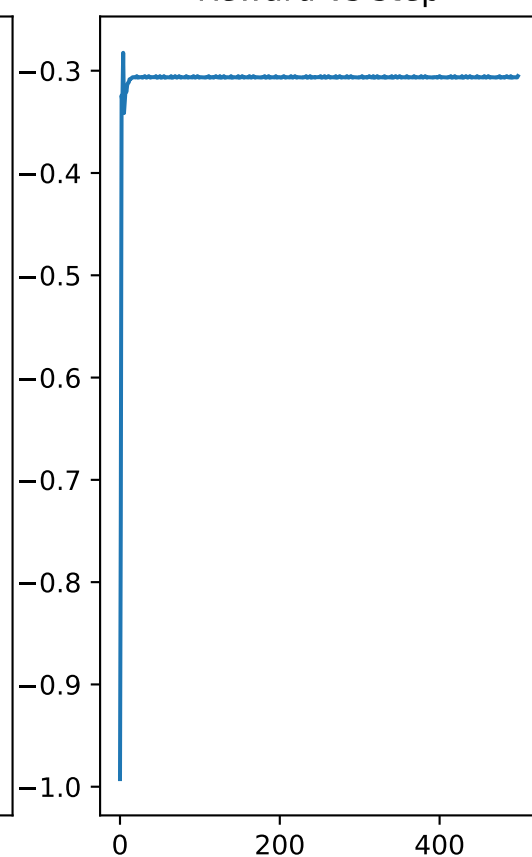
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq