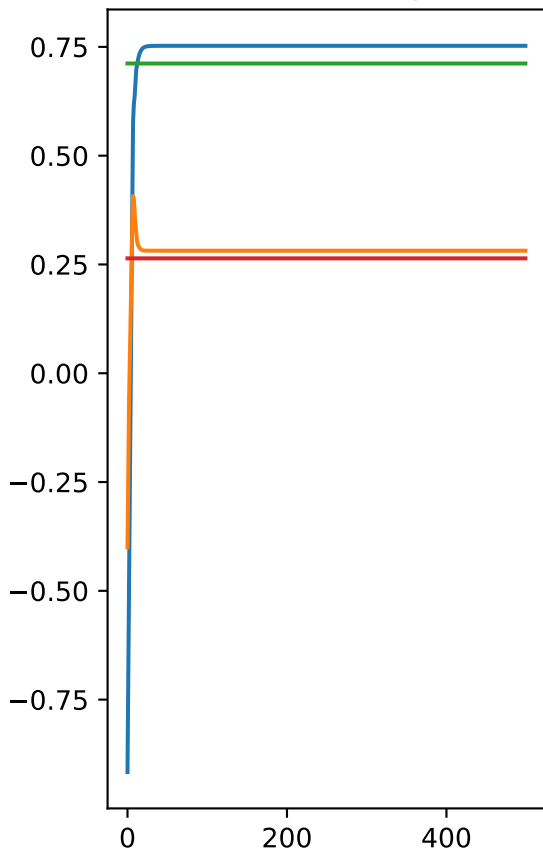
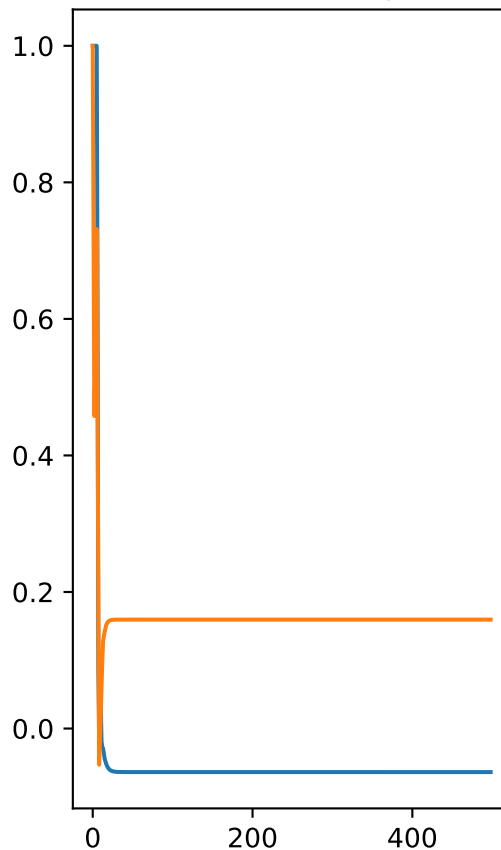


Reward: quadratic
Speed = 504.97958444263253 [rad/s]

State vs step



Action vs step



Reward vs step

