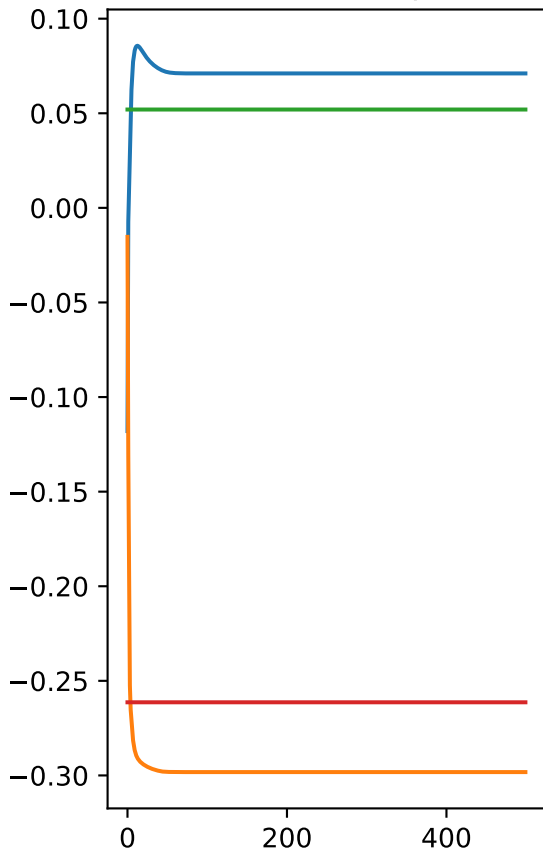
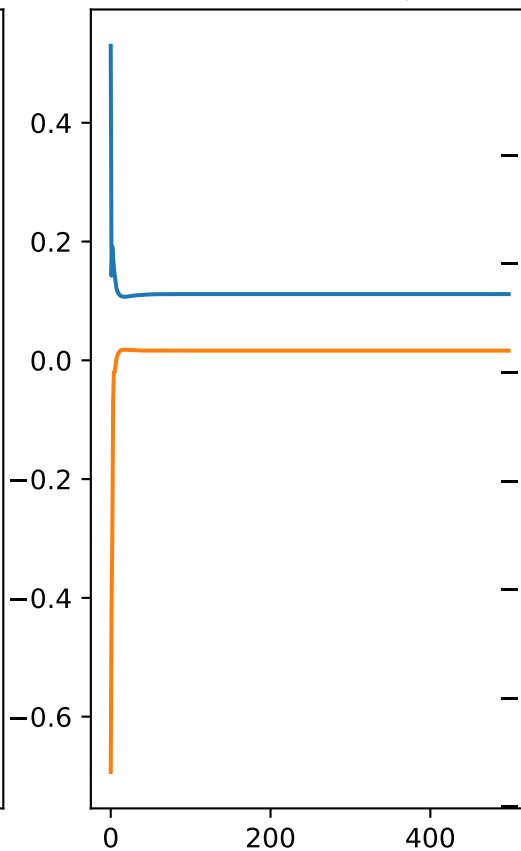


Reward: quadratic
Speed = 260.43802978417136 [rad/s]

State vs step



Action vs step



Reward vs step

