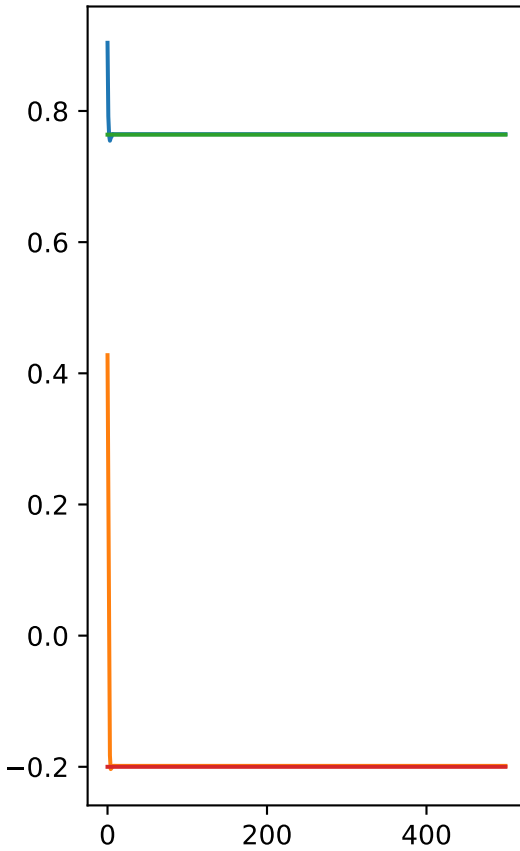
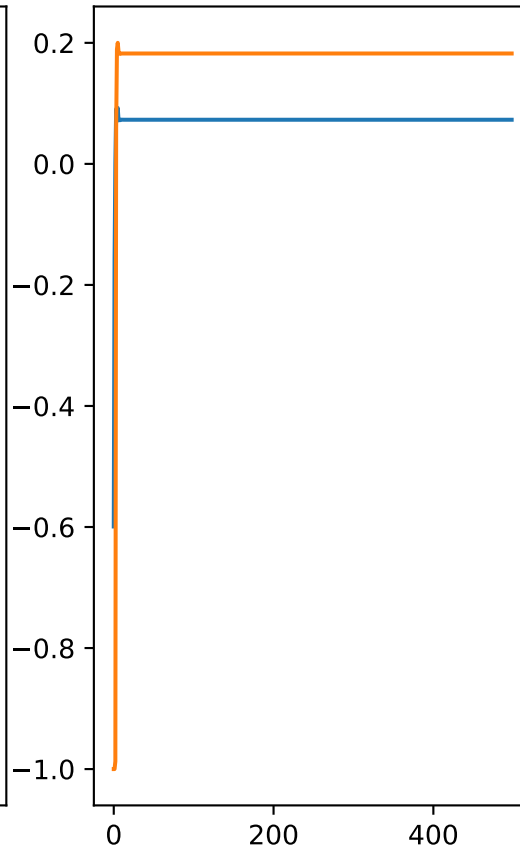


Reward: quartic_root_2
Speed = 370.80847178238287 [rad/s]

State vs step



Action vs step



Reward vs step

