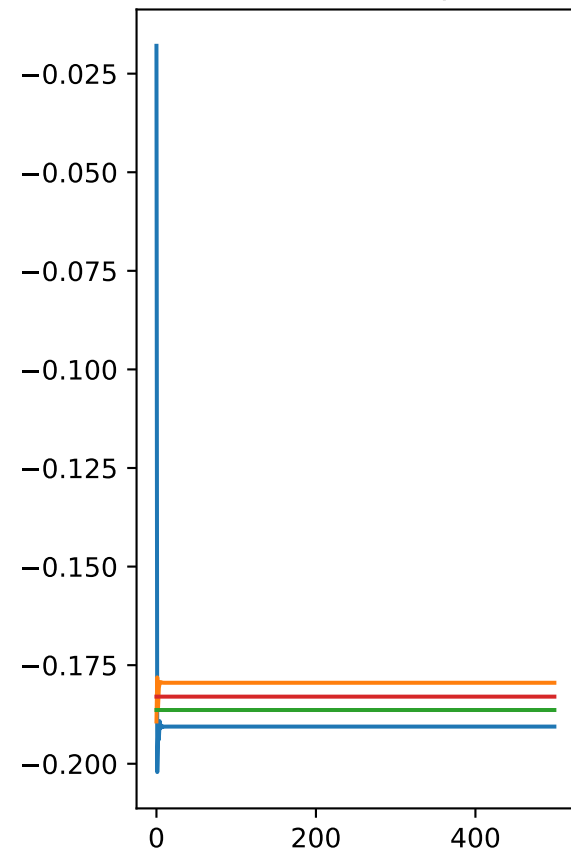
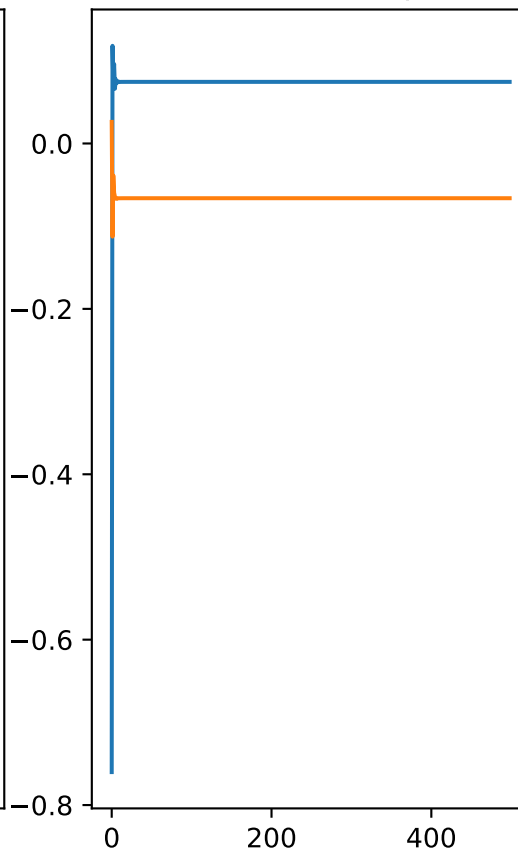


Reward: quartic_root
Speed = 944.752327062569 [rad/s]

State vs step



Action vs step



Reward vs step

