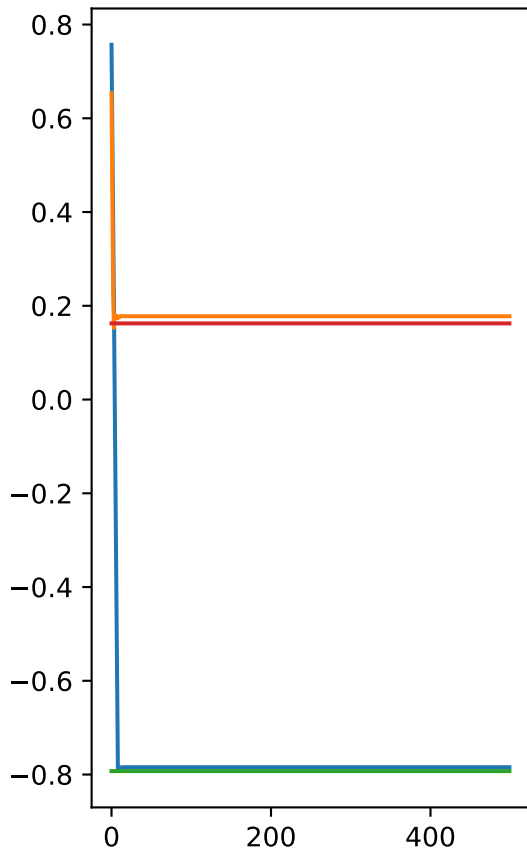
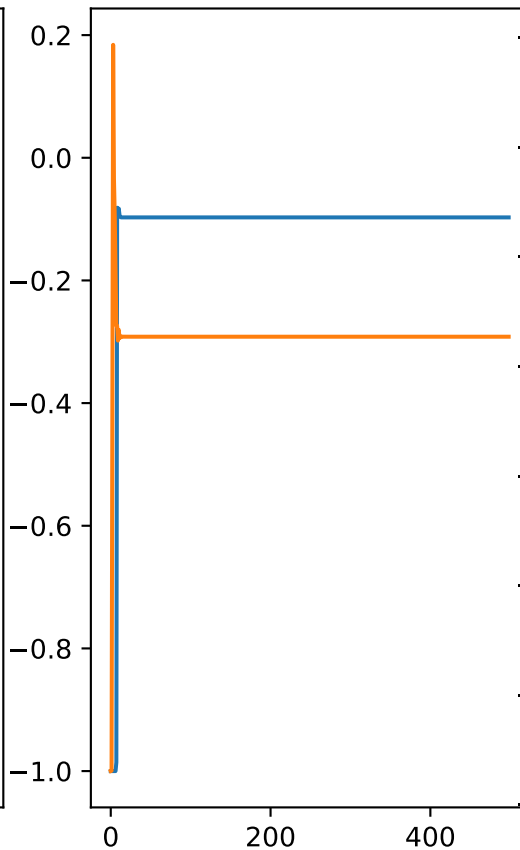


Reward: quartic_root
Speed = 1043.2098502936108 [rad/s]

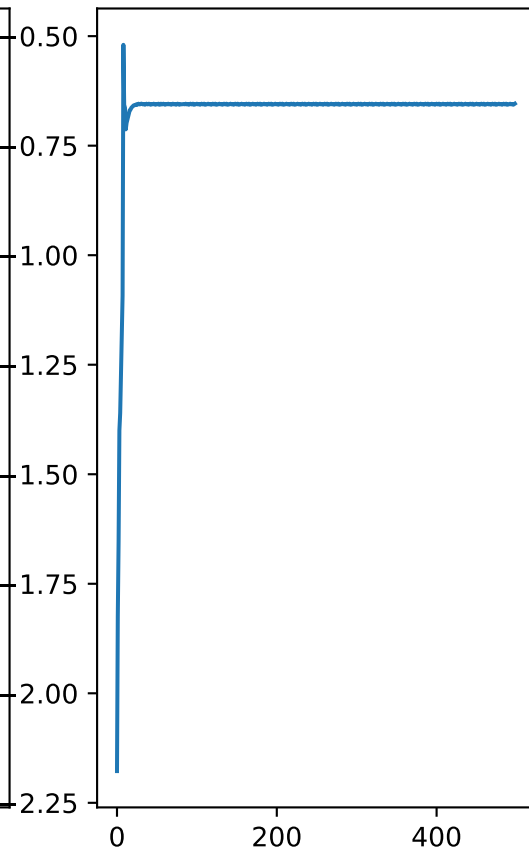
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq