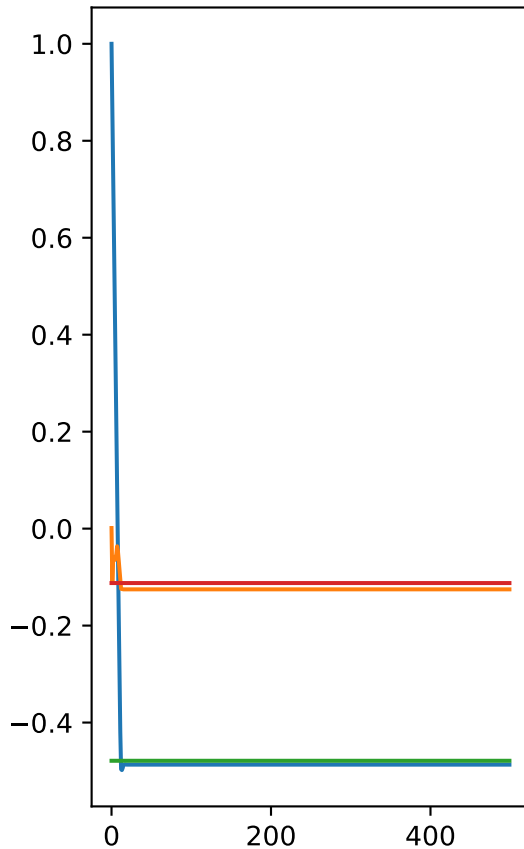
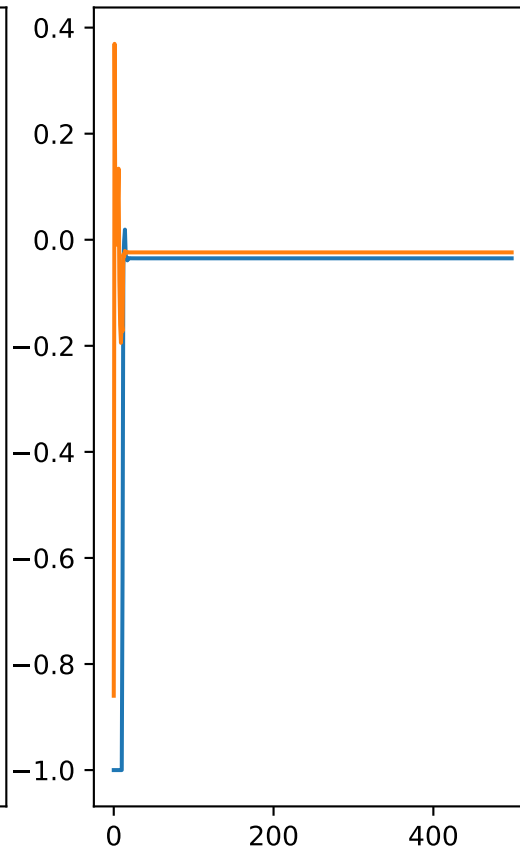


Reward: quartic_root
Speed = 435.21109721252384 [rad/s]

State vs step



Action vs step



Reward vs step

