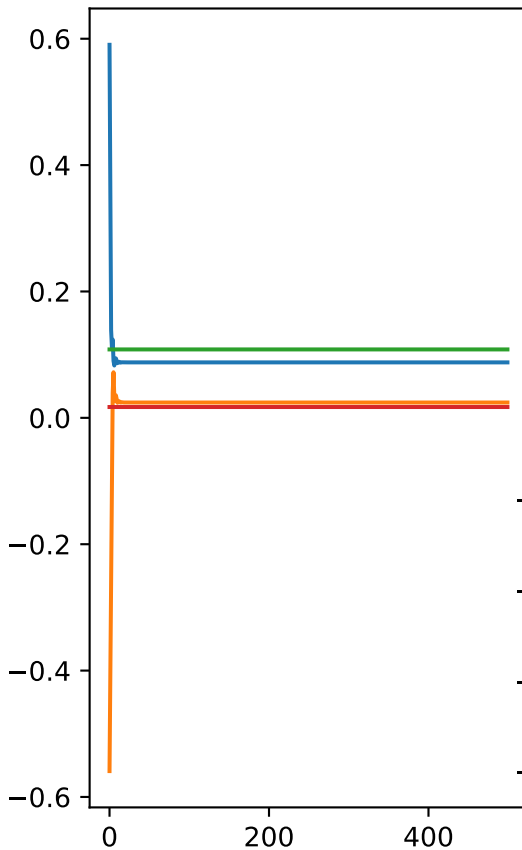
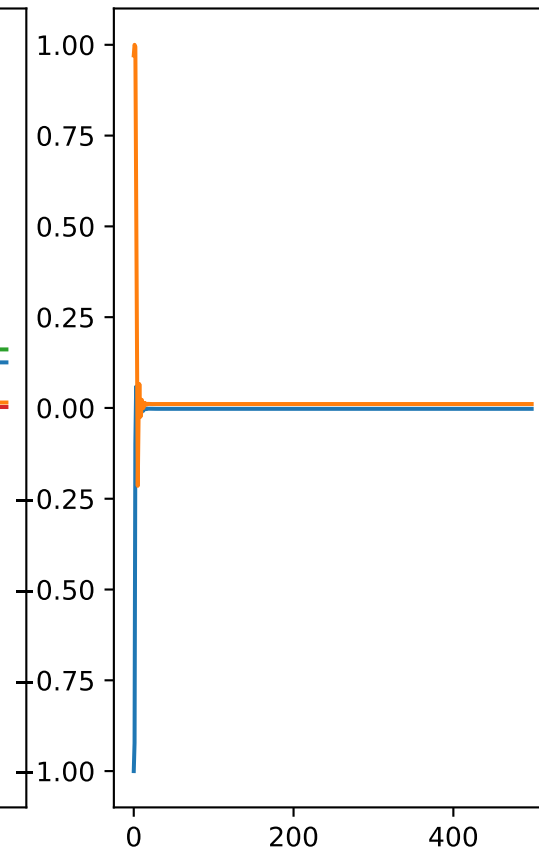


Reward: quadratic
Speed = 436.2666827224688 [rad/s]

State vs step



Action vs step



Reward vs step

