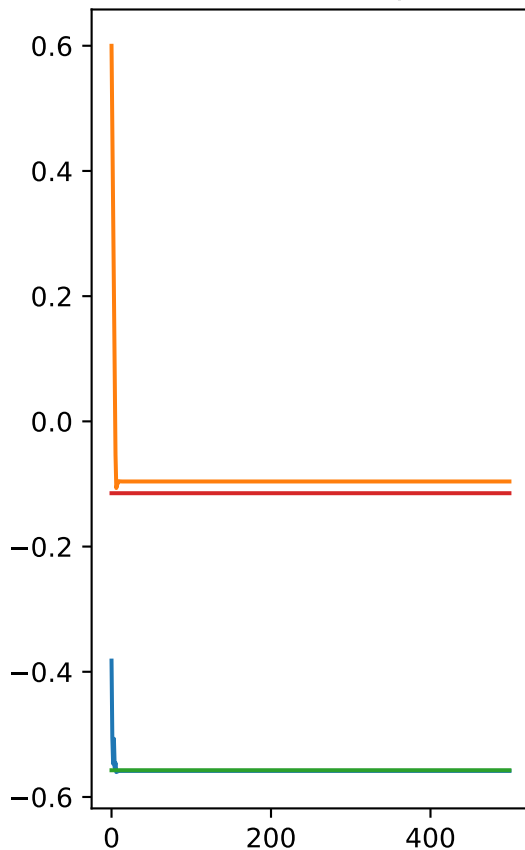
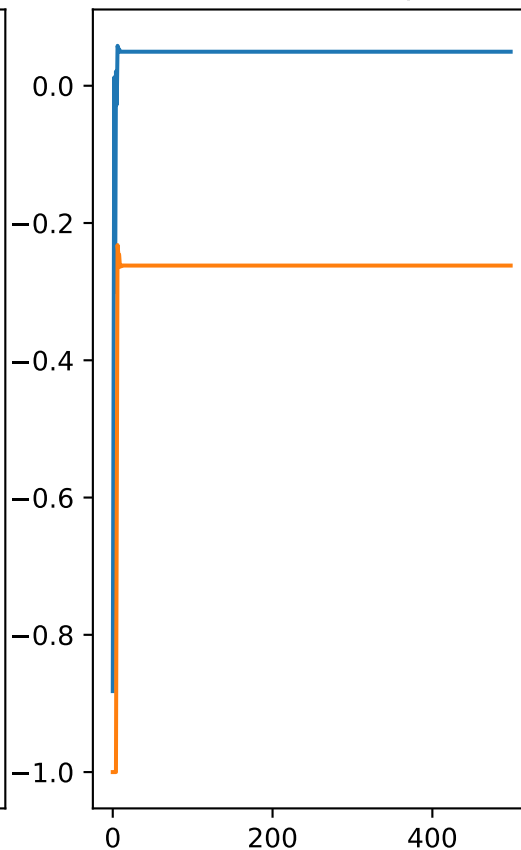


Reward: quartic_root
Speed = 152.9327257178837 [rad/s]

State vs step



Action vs step



Reward vs step

