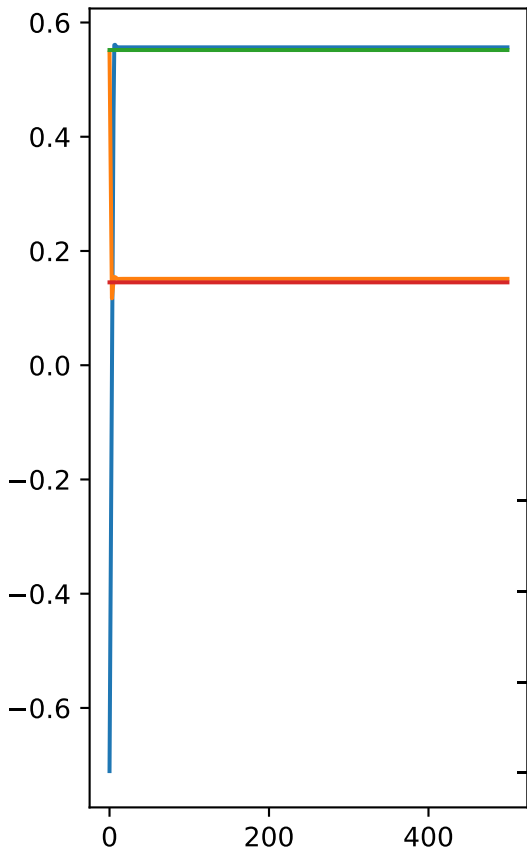
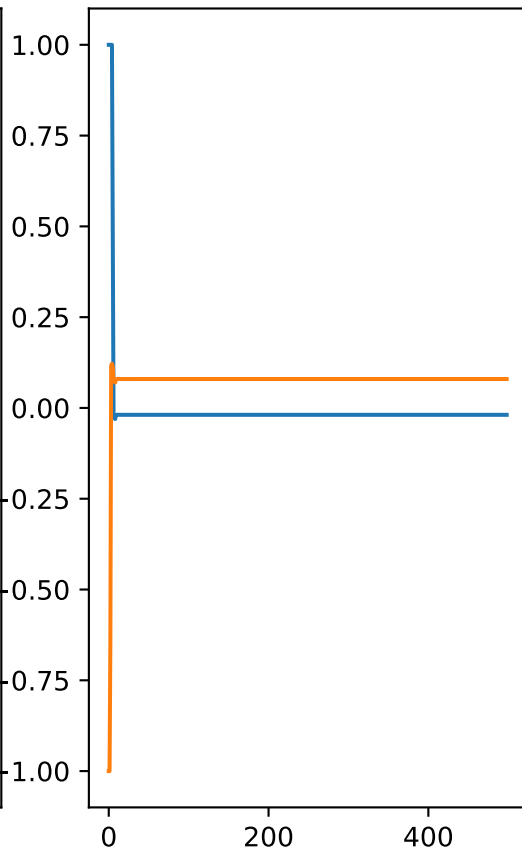


Reward: quartic_root
Speed = 393.40278040488556 [rad/s]

State vs step



Action vs step



Reward vs step

