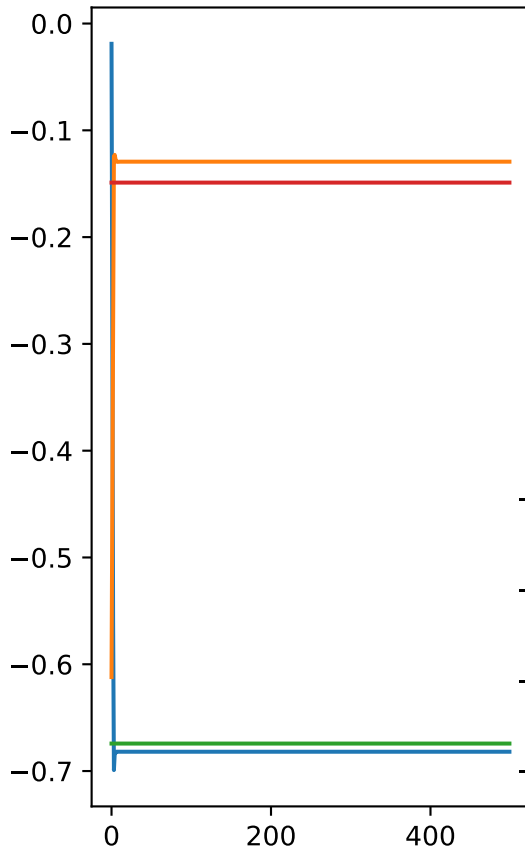
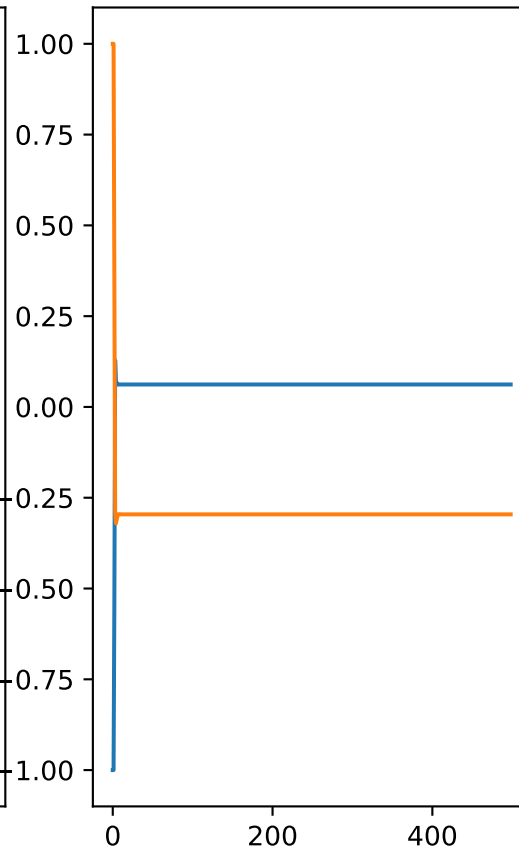


Reward: quartic_root
Speed = 852.6282419897911 [rad/s]

State vs step



Action vs step



Reward vs step

