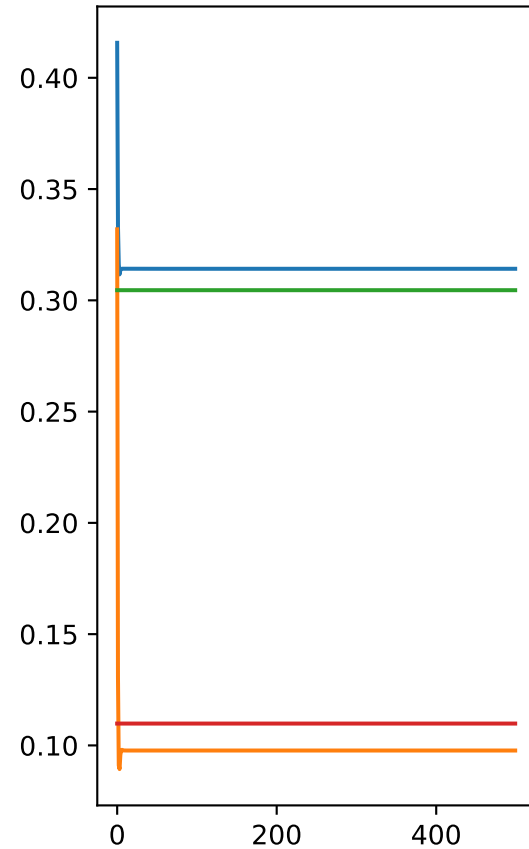
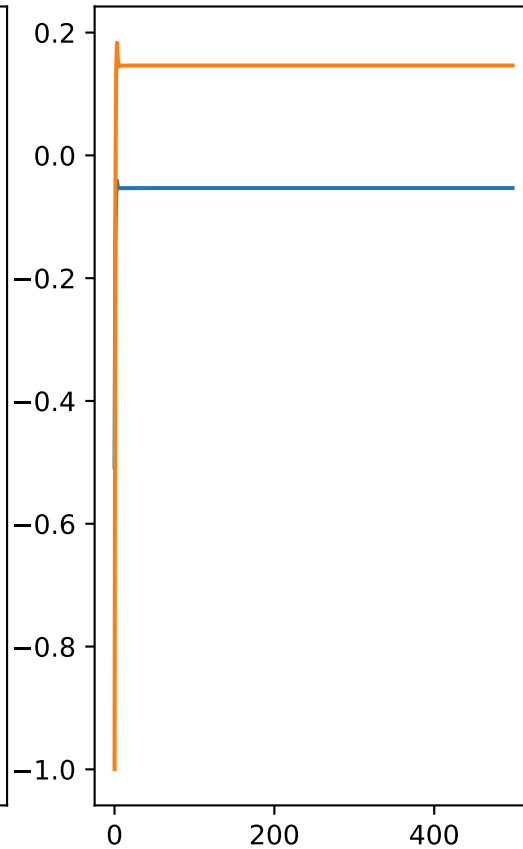


Reward: quartic_root
Speed = 593.2332142794141 [rad/s]

State vs step



Action vs step



Reward vs step

