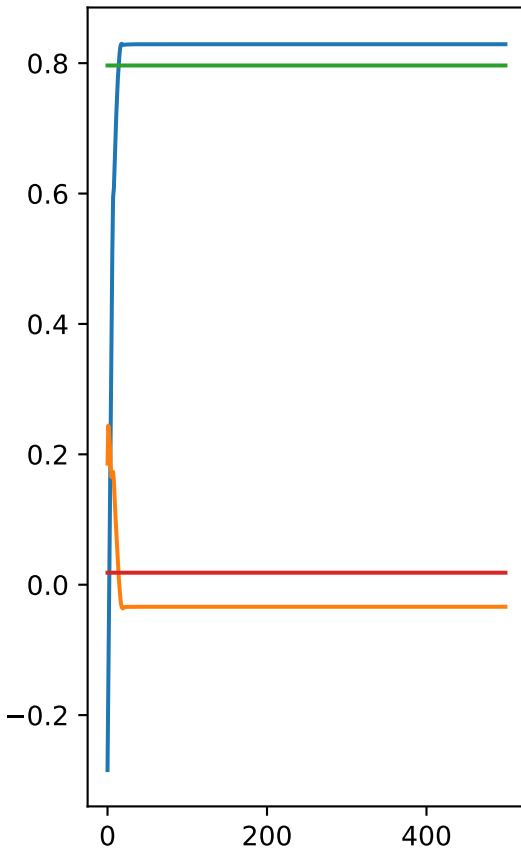
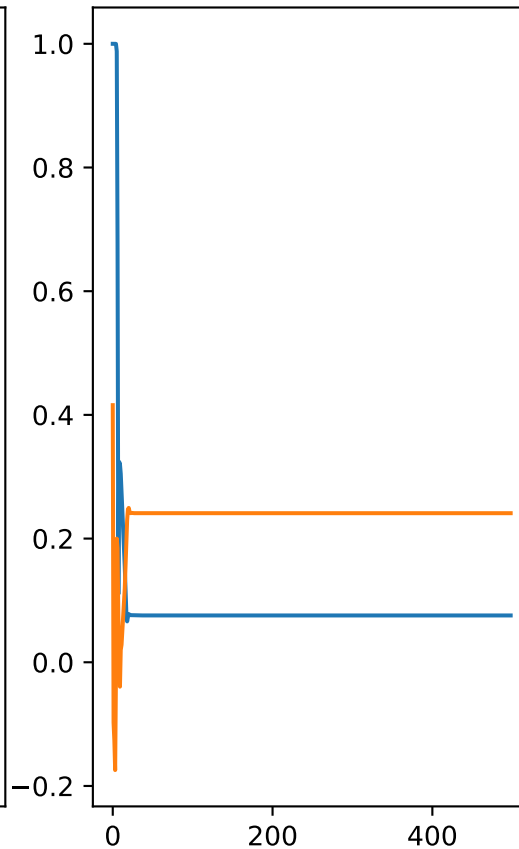


Reward: quadratic  
Speed = 60.19291363989036 [rad/s]

State vs step



Action vs step



Reward vs step

