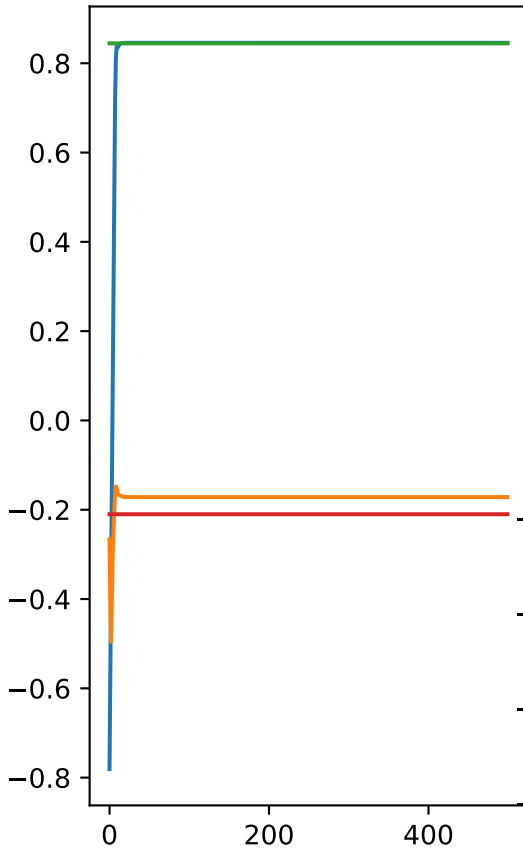
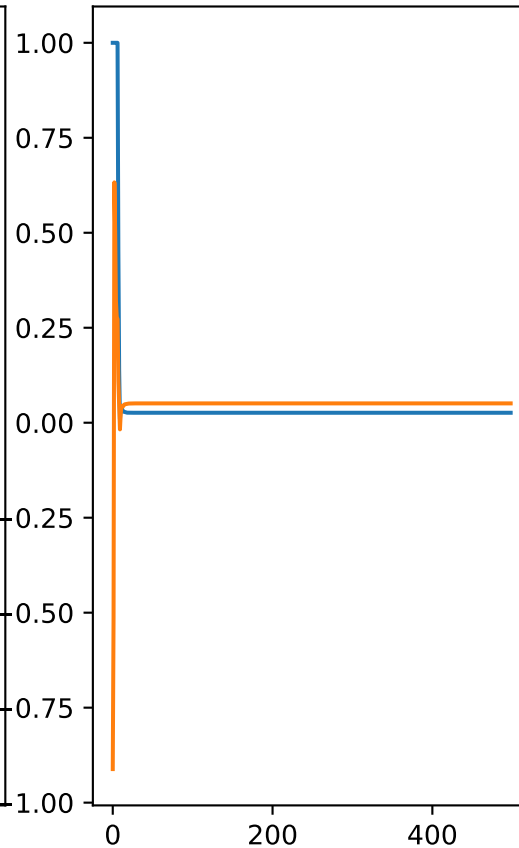


Reward: quadratic_2
Speed = 969.5709078275058 [rad/s]

State vs step



Action vs step



Reward vs step

