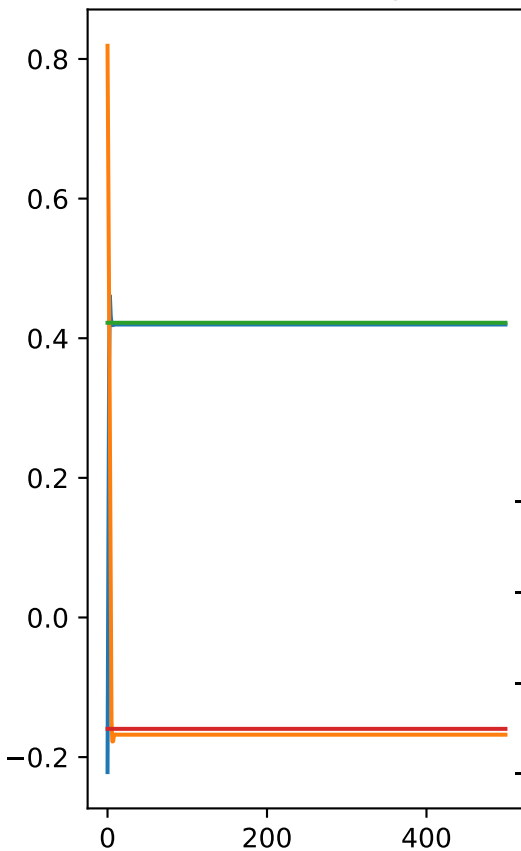
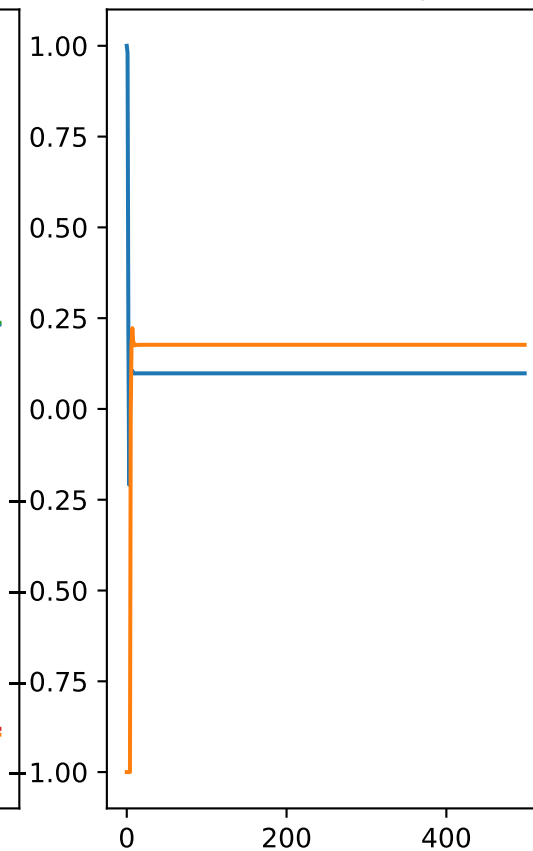


Reward: quartic_root
Speed = 675.480125889414 [rad/s]

State vs step



Action vs step



Reward vs step

