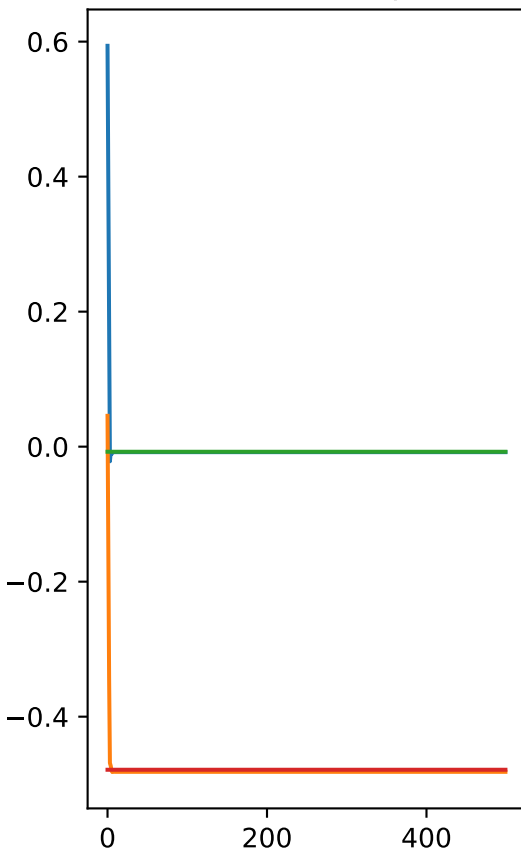
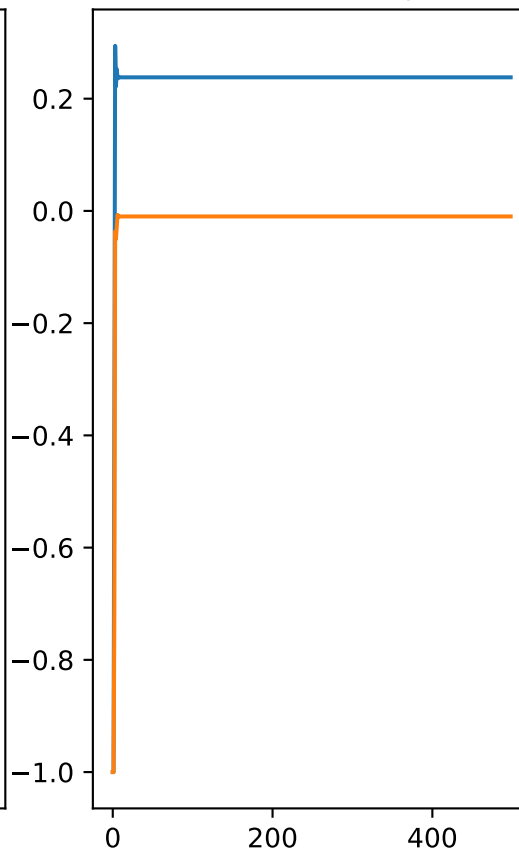


Reward: quartic_root
Speed = 799.5981965863997 [rad/s]

State vs step



Action vs step



Reward vs step

