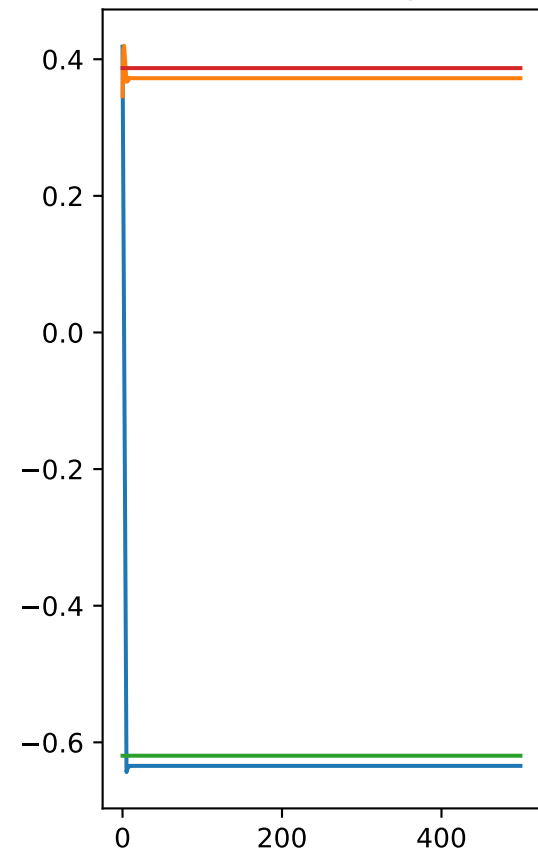
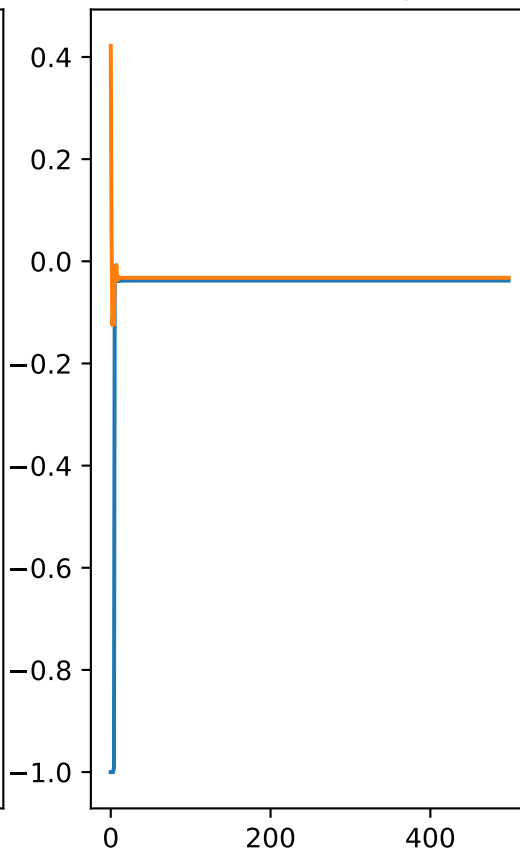


Reward: quartic_root
Speed = 426.72881262732375 [rad/s]

State vs step



Action vs step



Reward vs step

