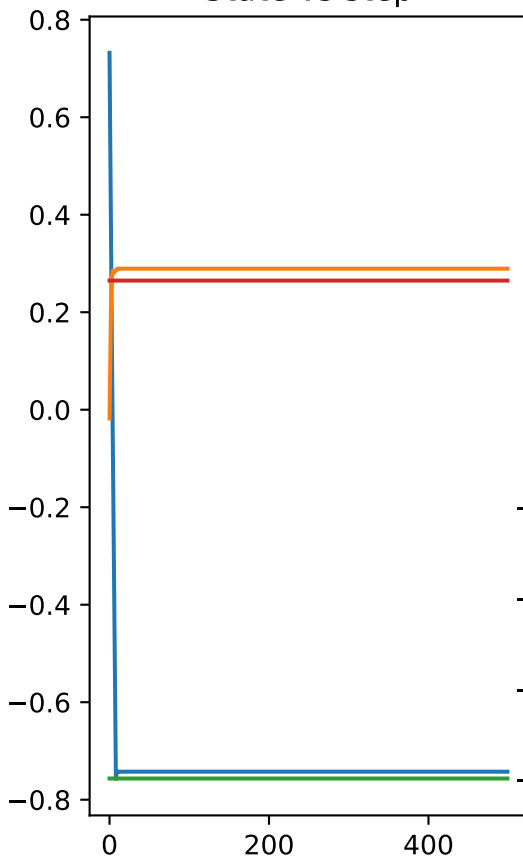
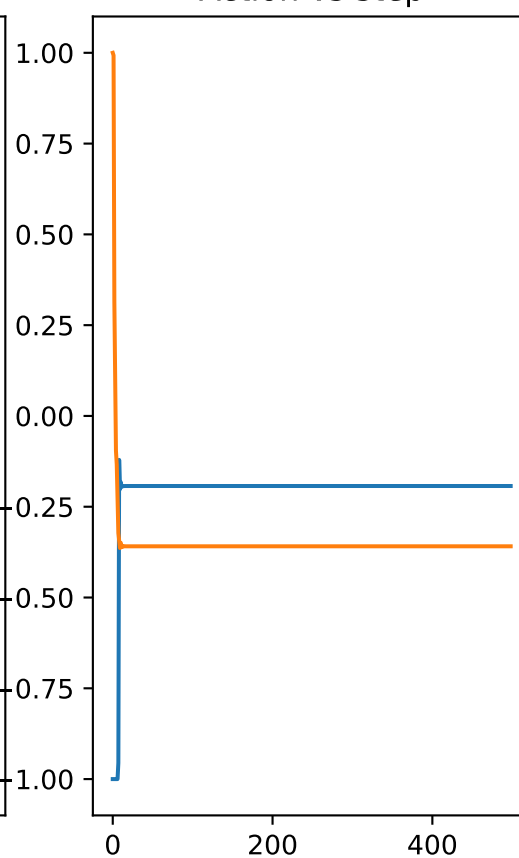


Reward: quartic_root
Speed = 843.6809694782633 [rad/s]

State vs step



Action vs step



Reward vs step

