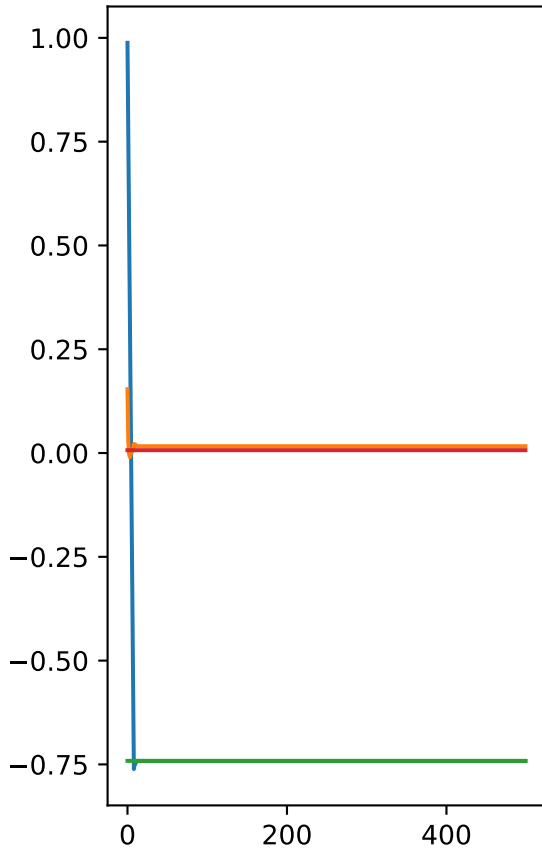
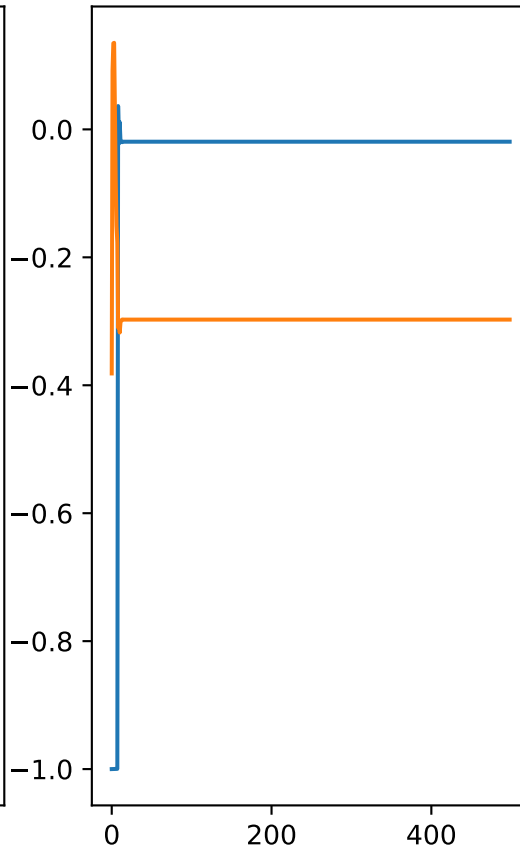


Reward: quartic_root
Speed = 872.3574220430457 [rad/s]

State vs step



Action vs step



Reward vs step

