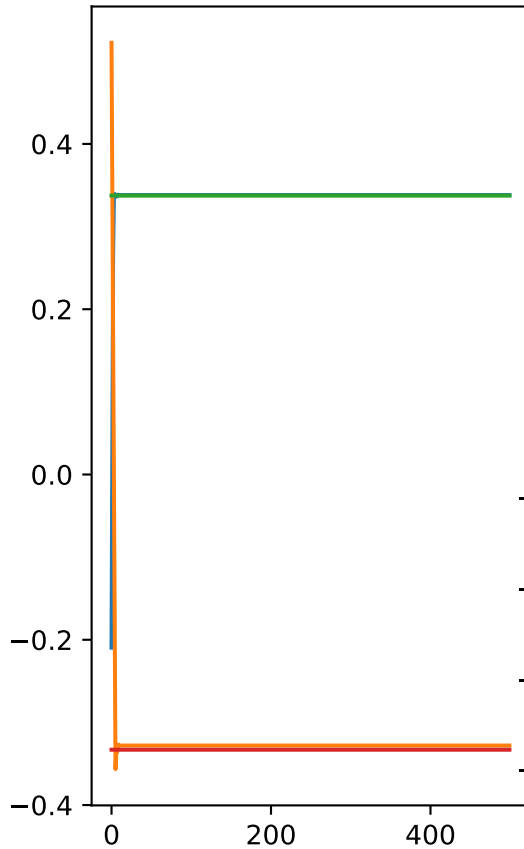
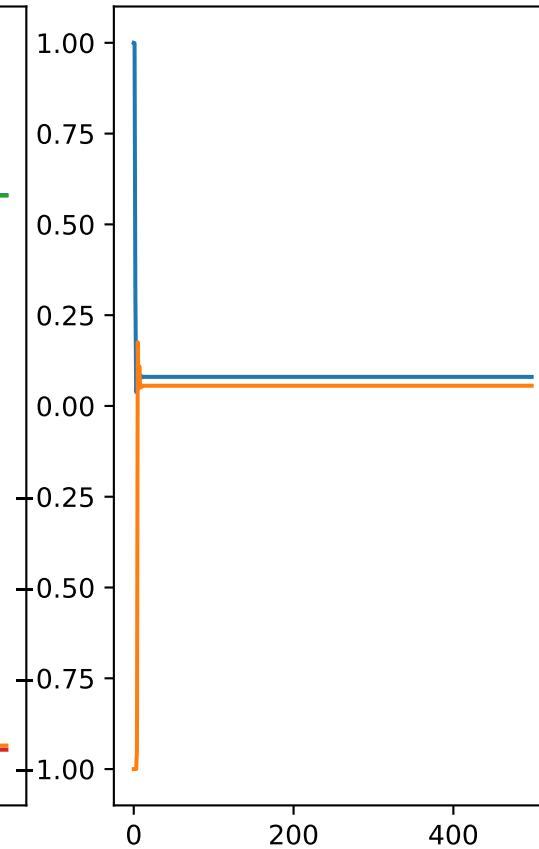


Reward: quartic_root
Speed = 497.7916335979138 [rad/s]

State vs step



Action vs step



Reward vs step

