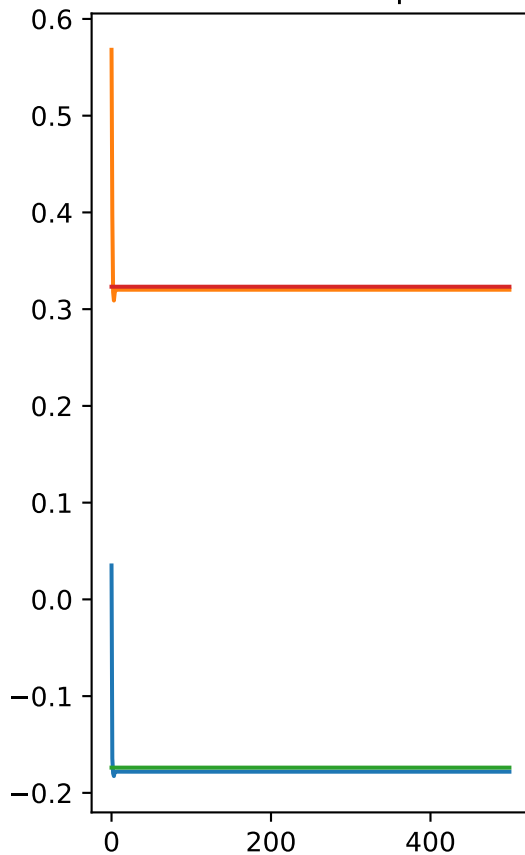
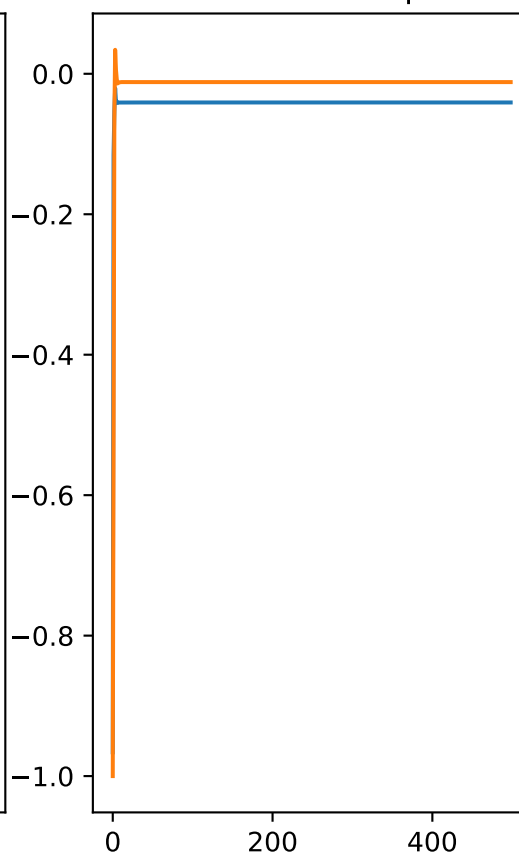


Reward: quartic\_root  
Speed = 578.0153458889697 [rad/s]

State vs step



Action vs step



Reward vs step

