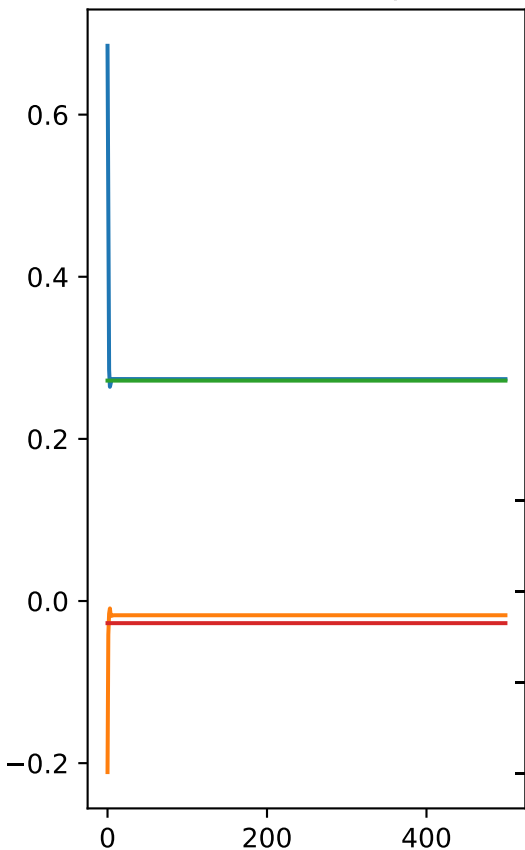
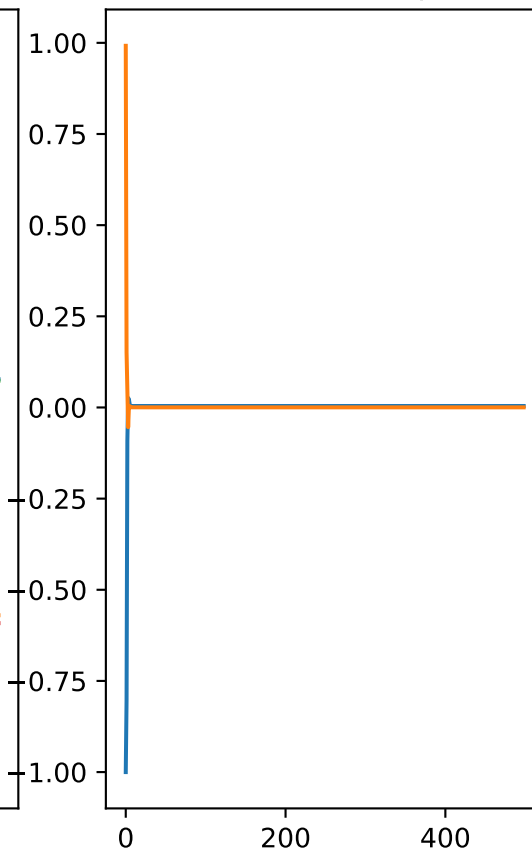


Reward: quartic_root
Speed = 891.8102159094205 [rad/s]

State vs step



Action vs step



Reward vs step

