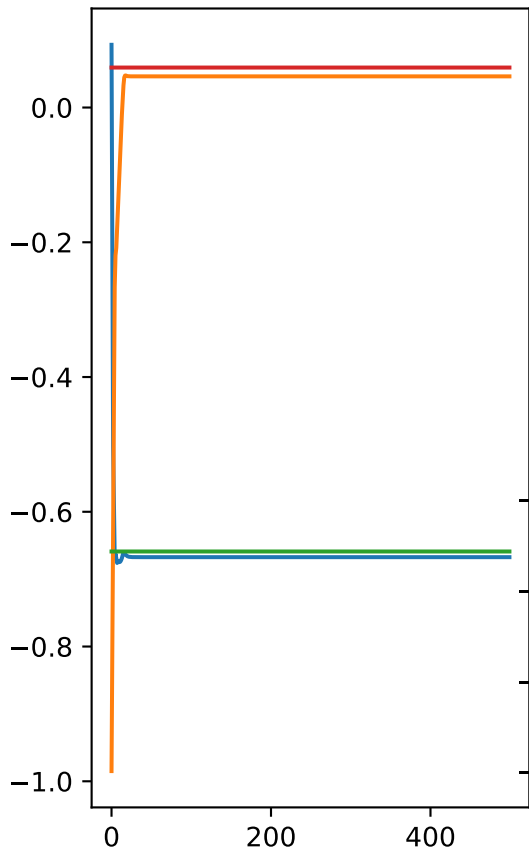
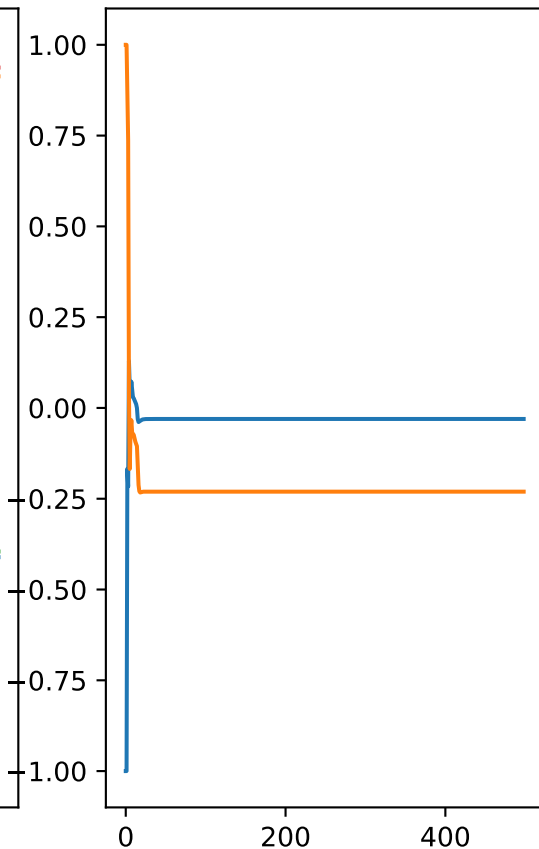


Reward: quadratic_2
Speed = 1128.6234435320398 [rad/s]

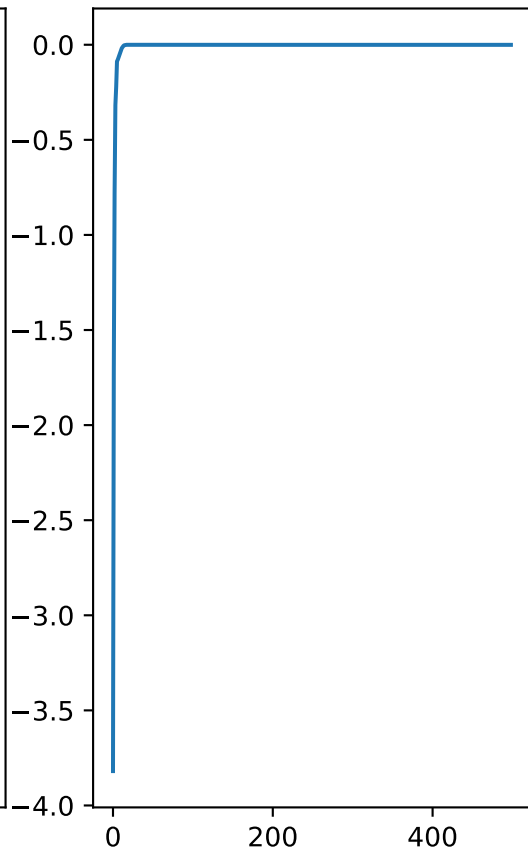
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq