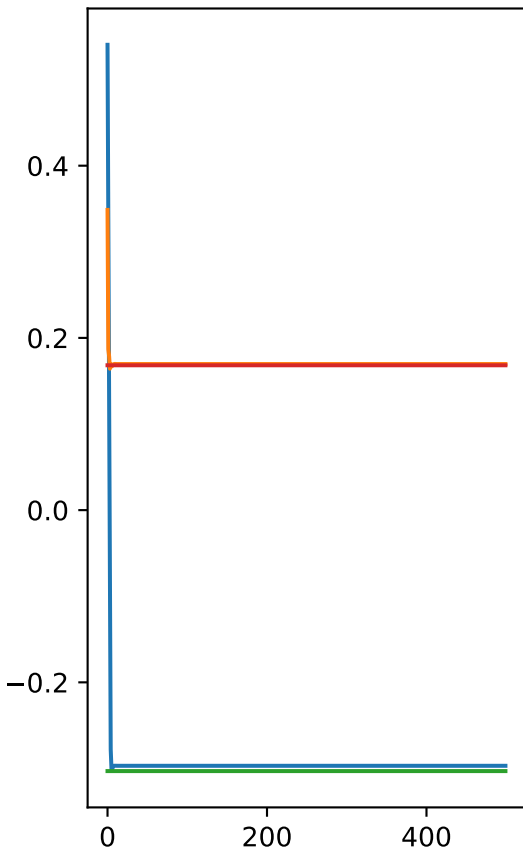
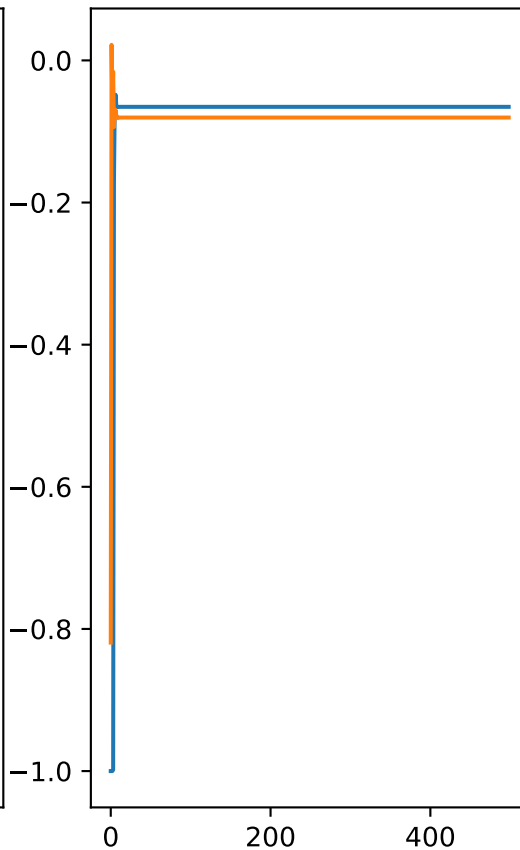


Reward: quartic_root
Speed = 219.97432428556272 [rad/s]

State vs step



Action vs step



Reward vs step

