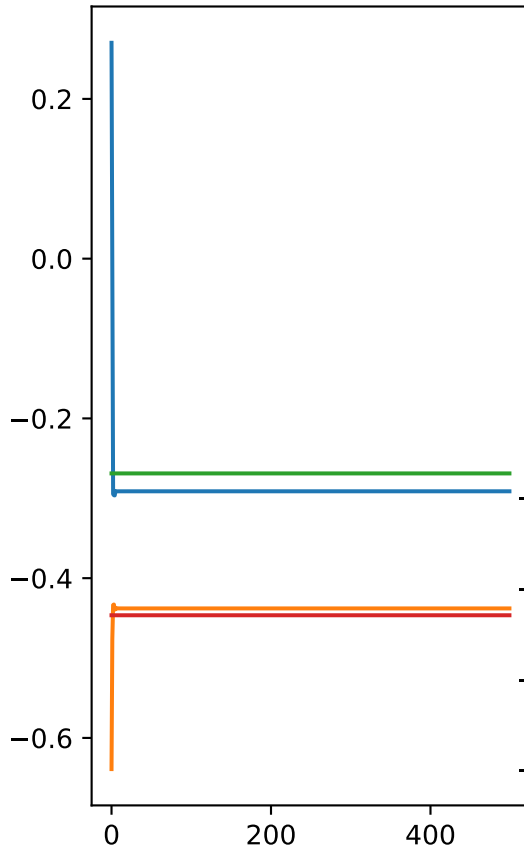
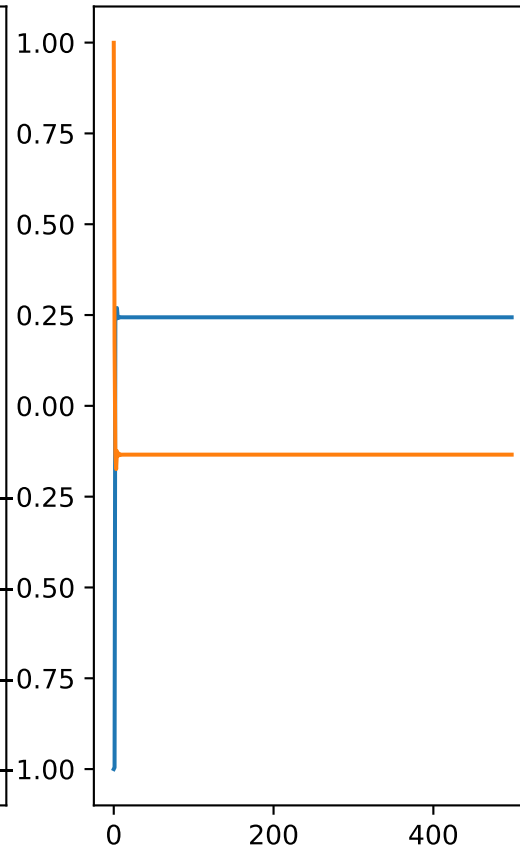


Reward: quartic_root
Speed = 85.7654800422126 [rad/s]

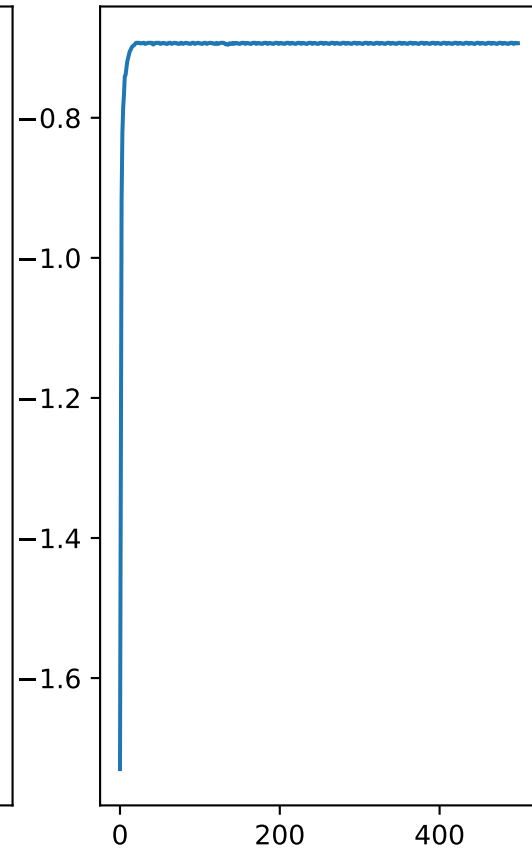
State vs step



Action vs step



Reward vs step



Id Idref
Iq Iqref

Vd Vq