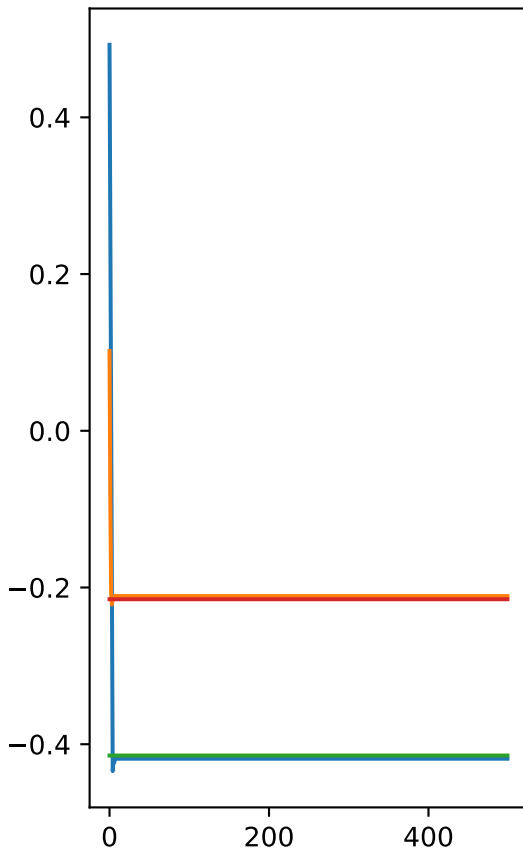
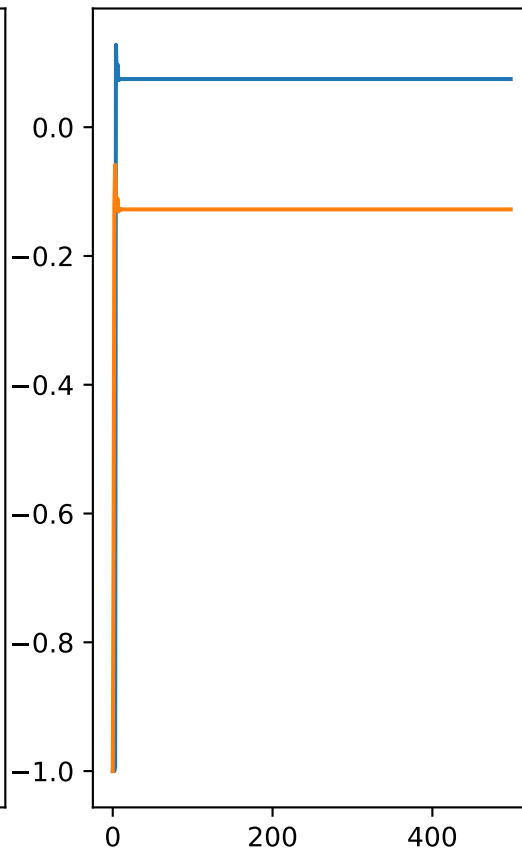


Reward: quartic_root
Speed = 313.116263285185 [rad/s]

State vs step



Action vs step



Reward vs step

