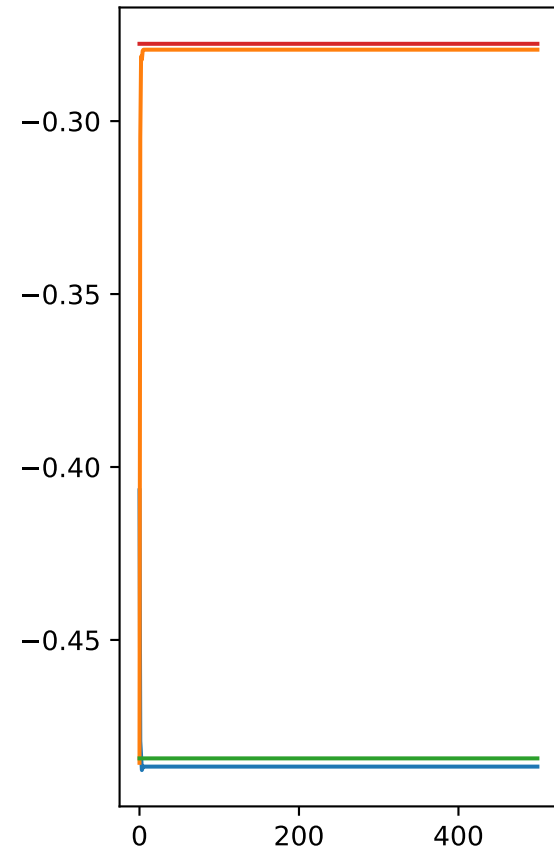
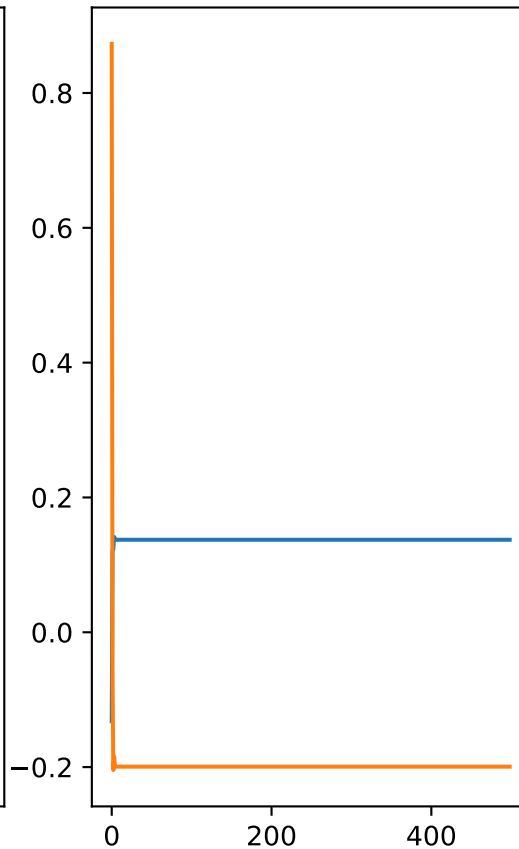


Reward: square_root
Speed = 975.0372873138673 [rad/s]

State vs step



Action vs step



Reward vs step

