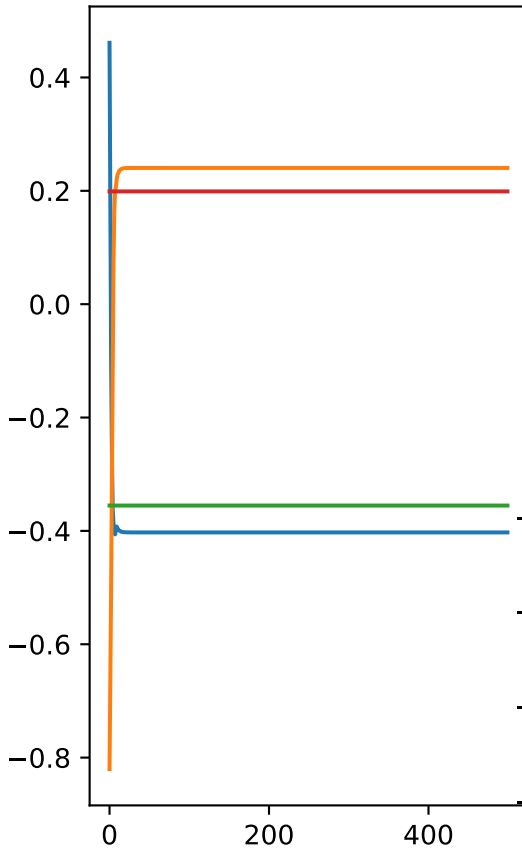
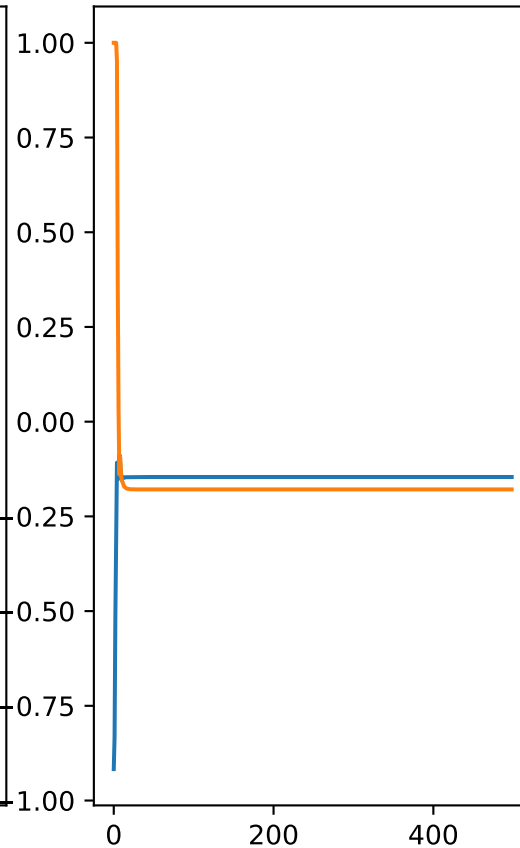


Reward: quadratic
Speed = 442.5624454736865 [rad/s]

State vs step



Action vs step



Reward vs step

