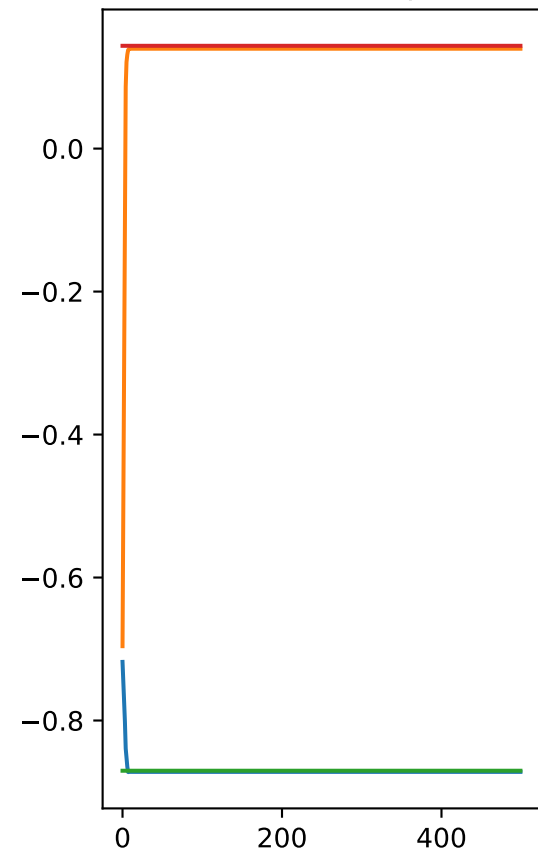
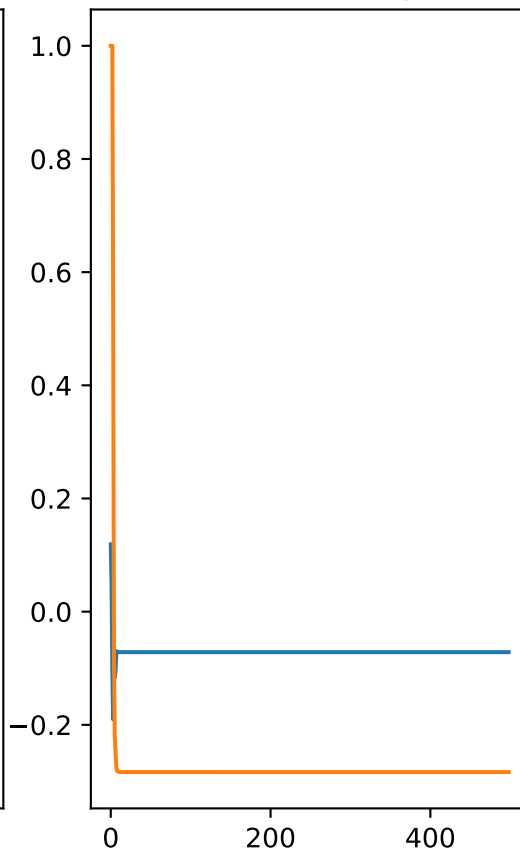


Reward: square_root_2
Speed = 1032.3021832917834 [rad/s]

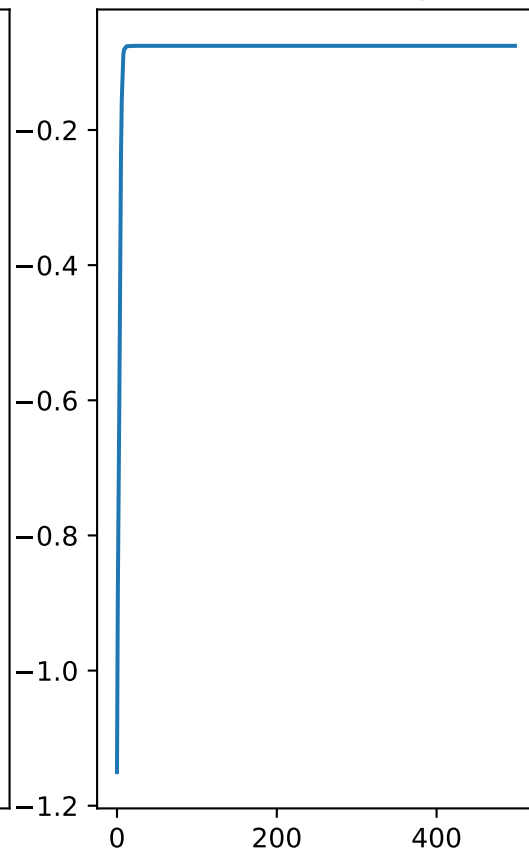
State vs step



Action vs step



Reward vs step



Id Iq Idref Iqref

Vd Vq