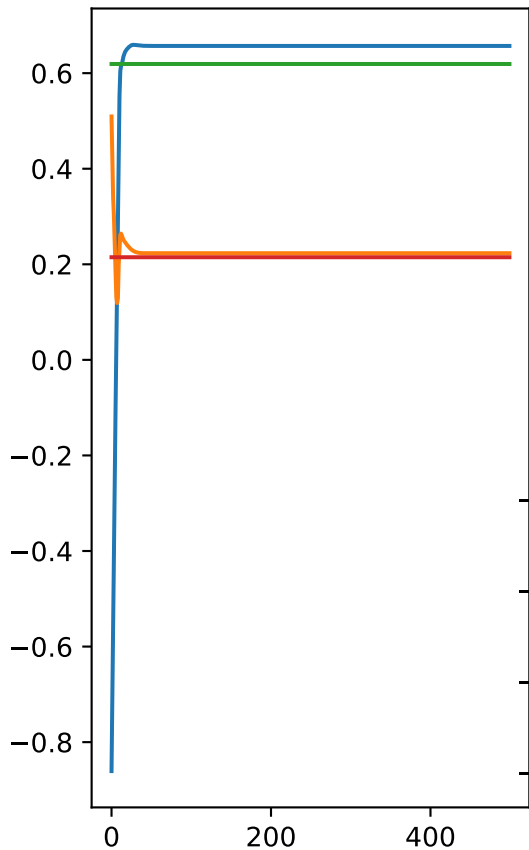
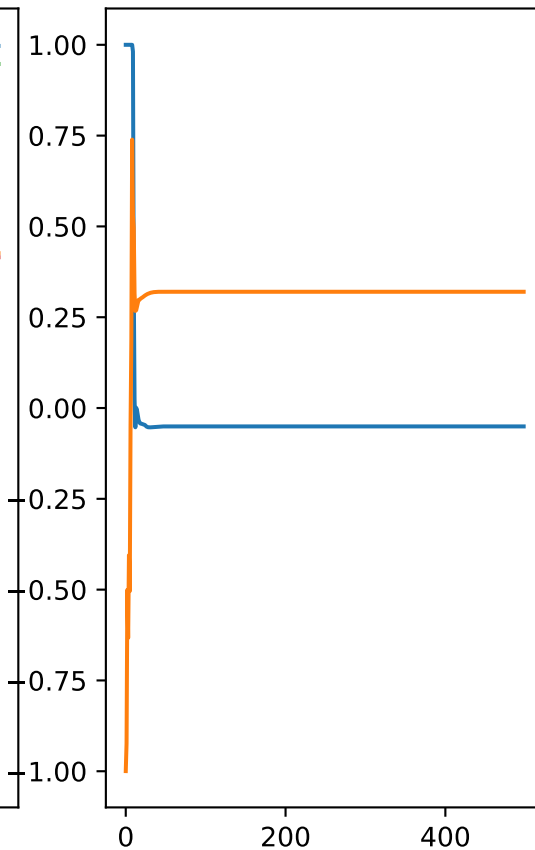


Reward: quadratic
Speed = 369.56439688509835 [rad/s]

State vs step



Action vs step



Reward vs step

