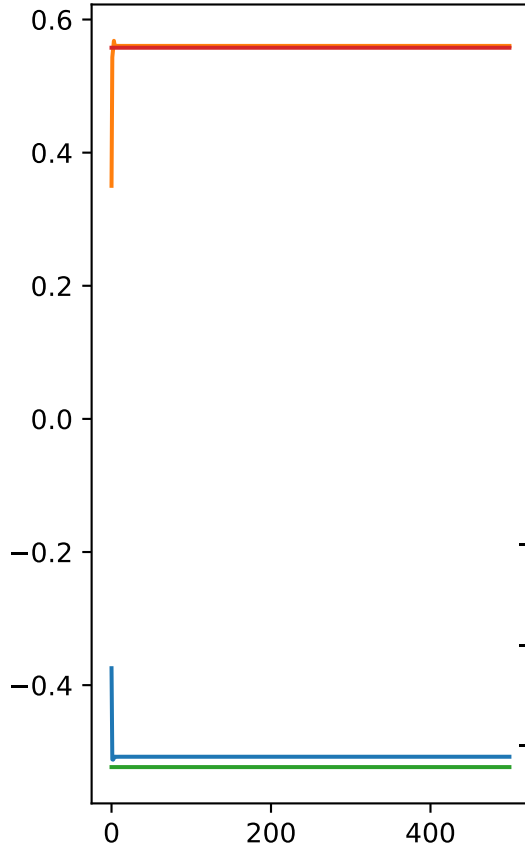
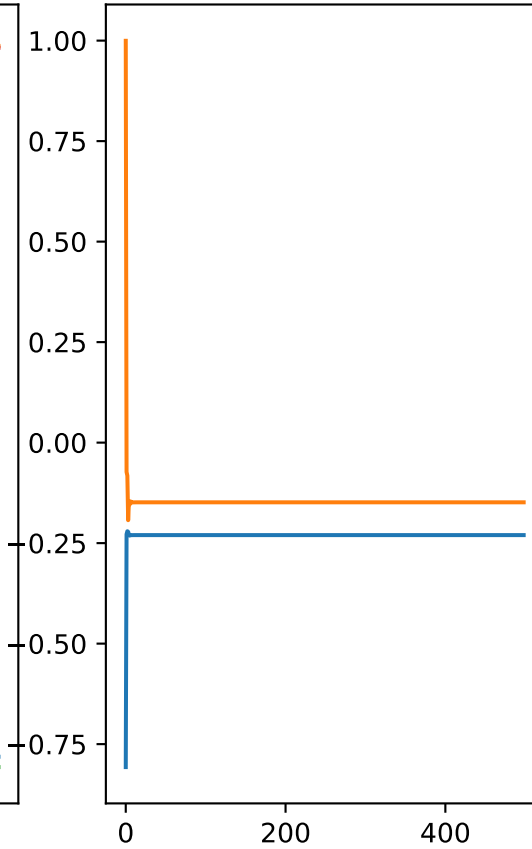


Reward: quartic\_root  
Speed = 770.6075326248799 [rad/s]

State vs step



Action vs step



Reward vs step

