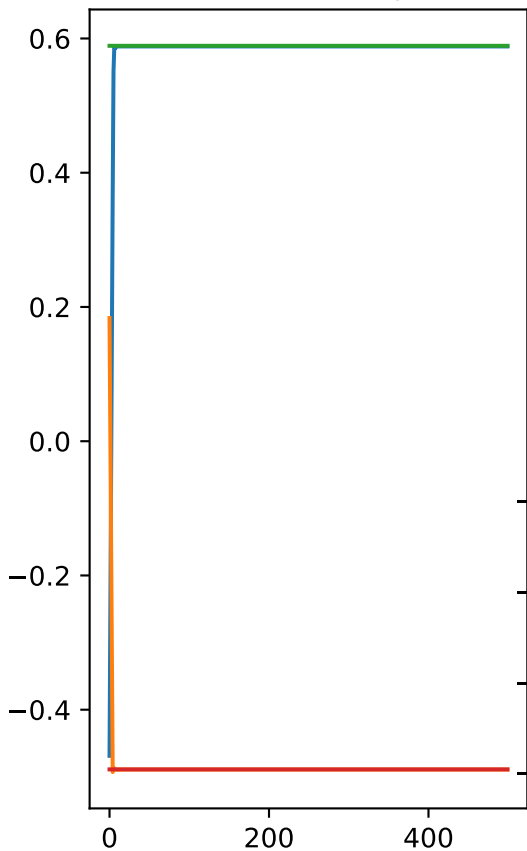
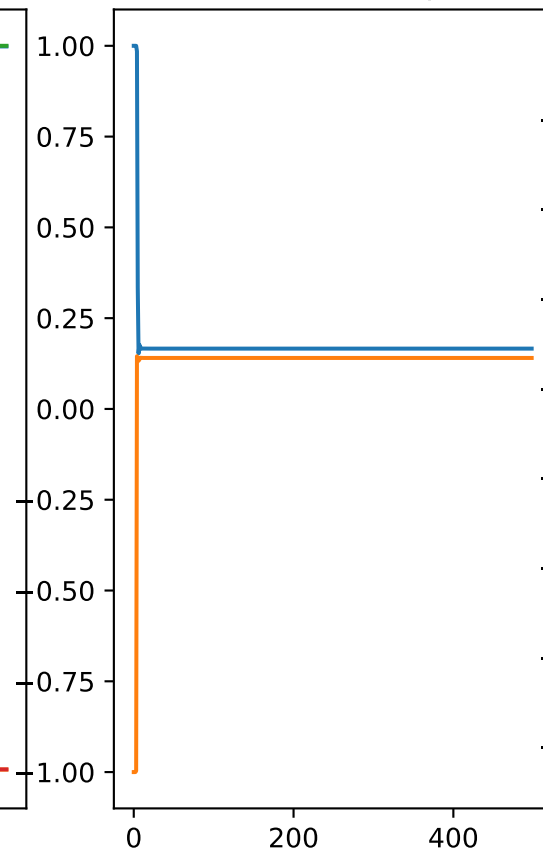


Reward: square\_root  
Speed = 31.15203296721441 [rad/s]

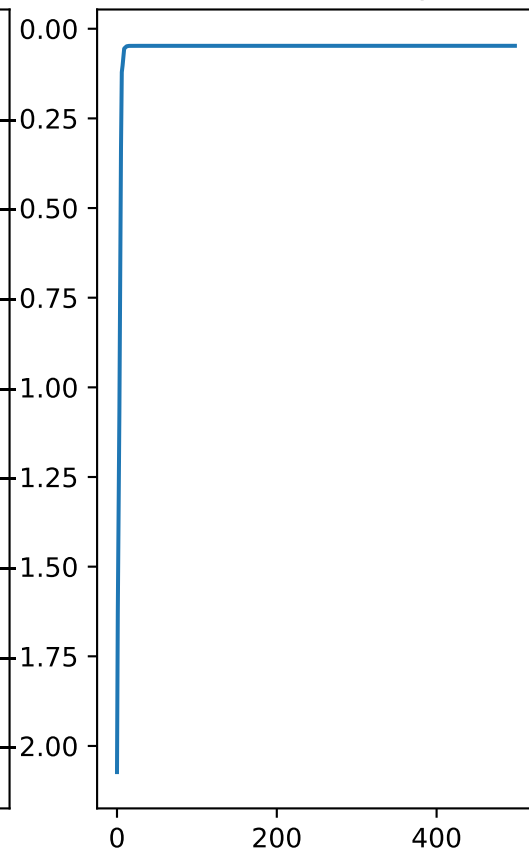
State vs step



Action vs step



Reward vs step



— Id — Idref  
— Iq — Iqref

— Vd — Vq