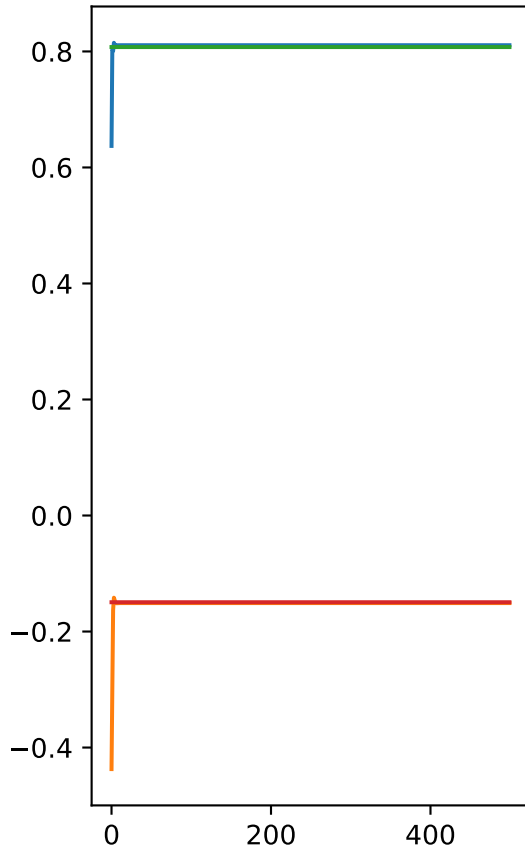
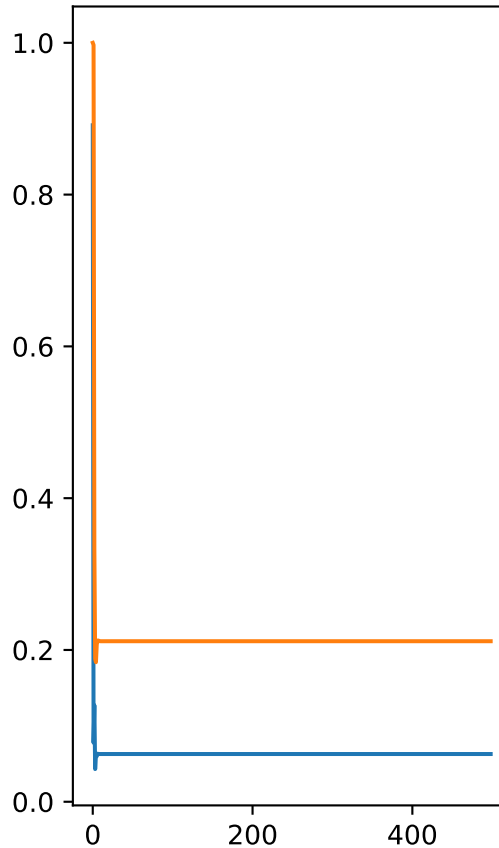


Reward: quartic_root
Speed = 478.7661522508206 [rad/s]

State vs step



Action vs step



Reward vs step

