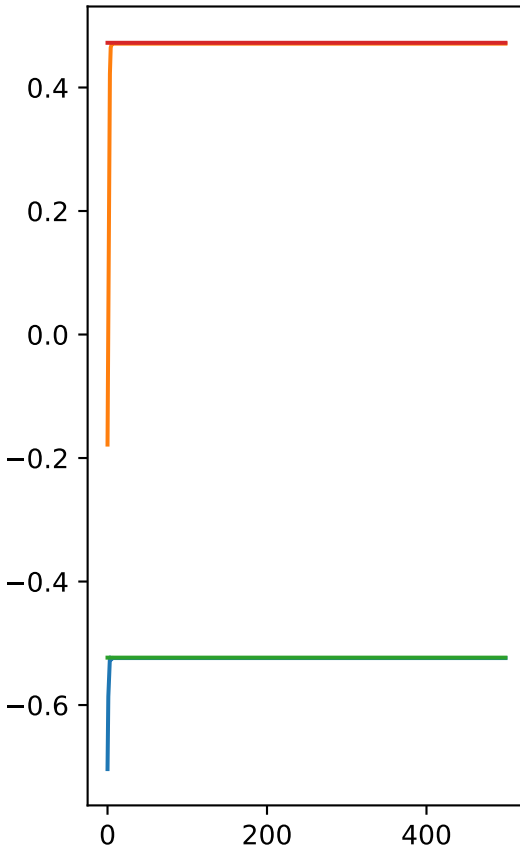
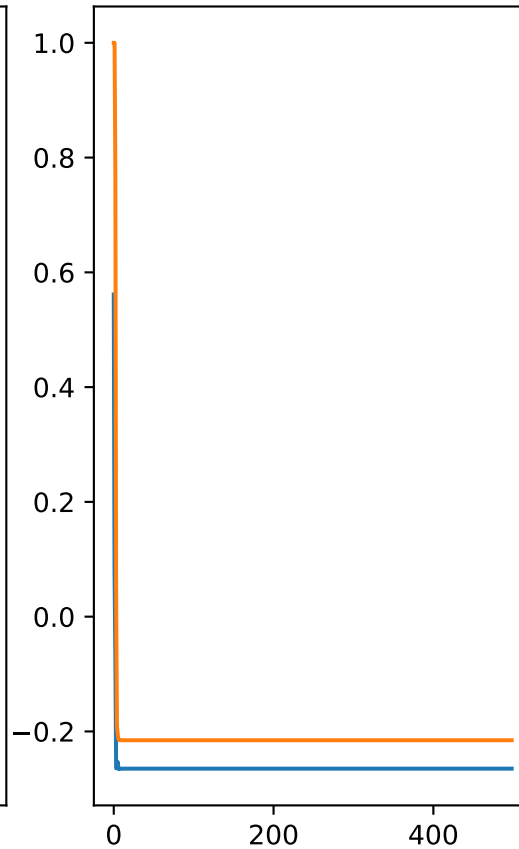


Reward: square_root
Speed = 571.6441948729567 [rad/s]

State vs step



Action vs step



Reward vs step

