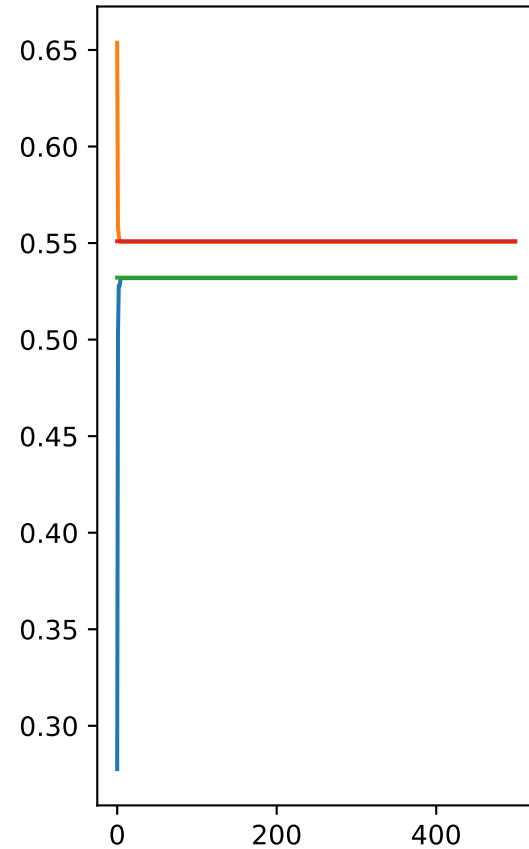
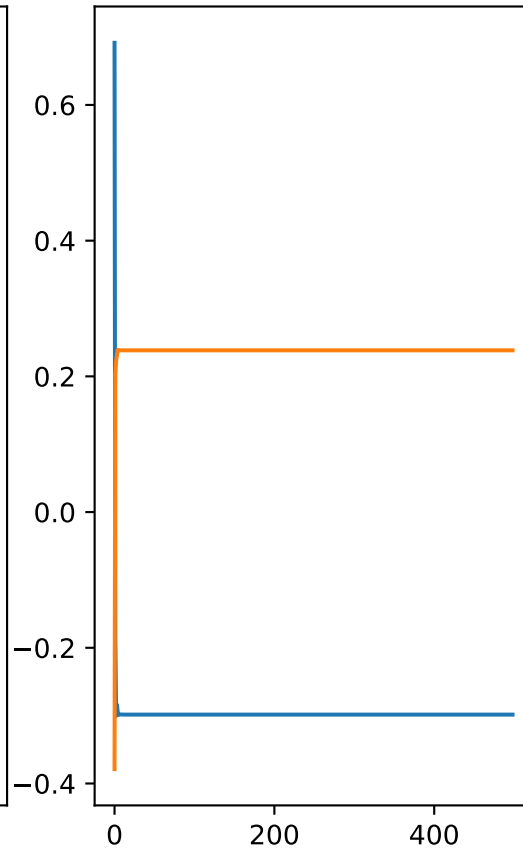


Reward: square_root
Speed = 49.85079438282529 [rad/s]

State vs step



Action vs step



Reward vs step

