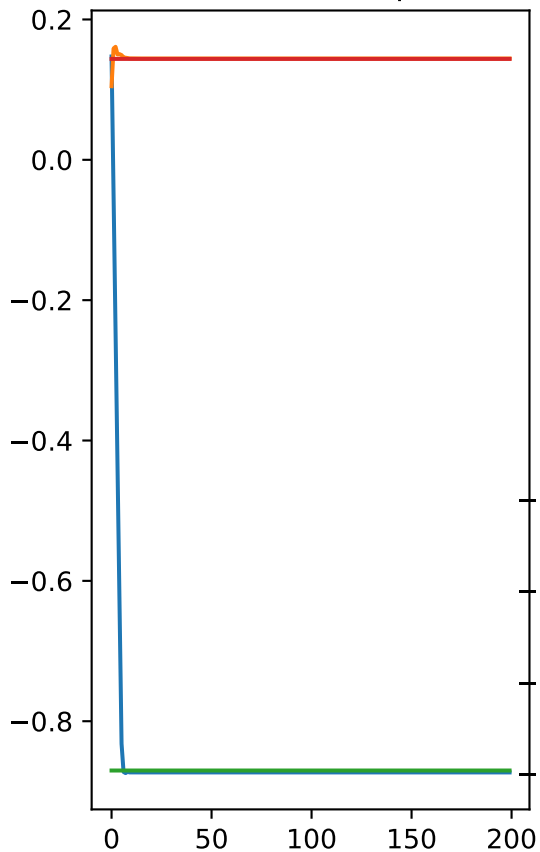
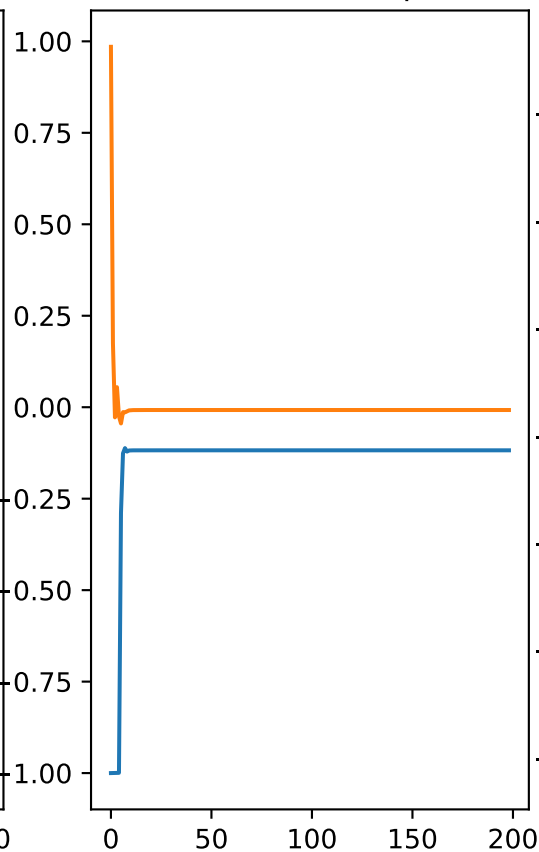


Reward: square_root
Speed = 1032.3021832917834 [rad/s]

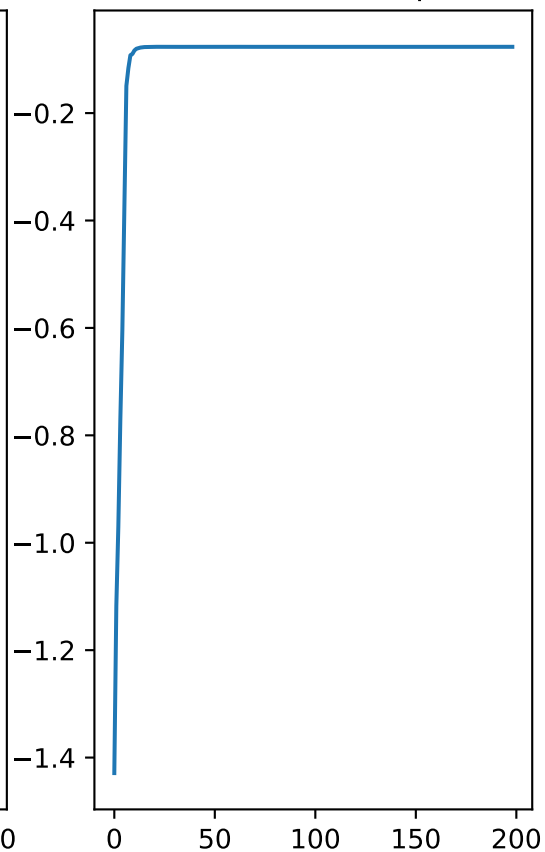
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— Vd — Vq