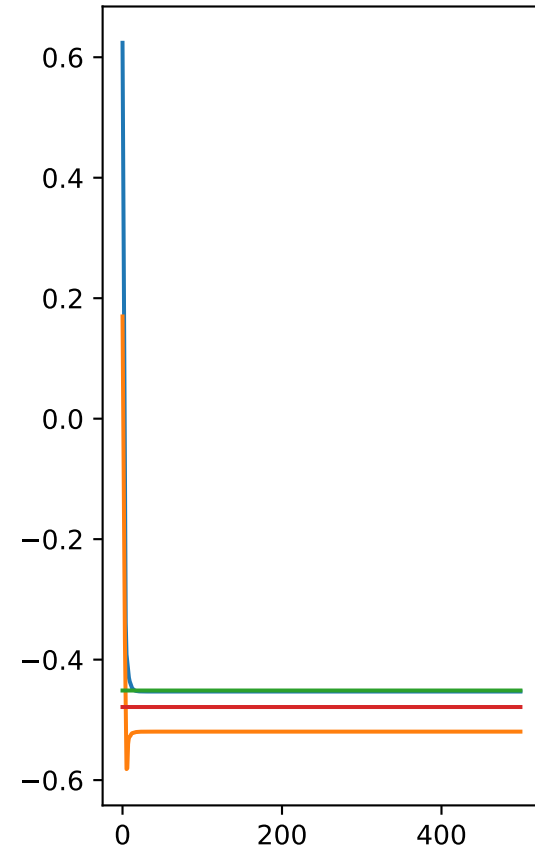
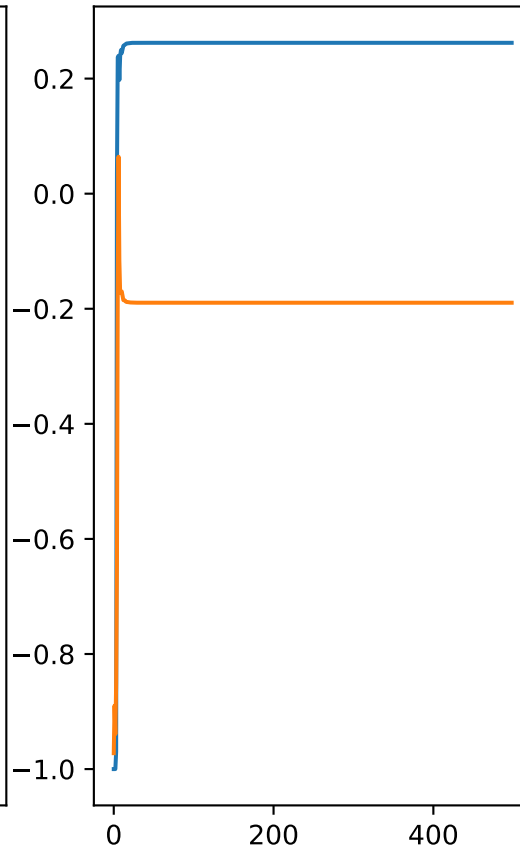


Reward: quadratic  
Speed = 577.2488049034608 [rad/s]

State vs step



Action vs step



Reward vs step

