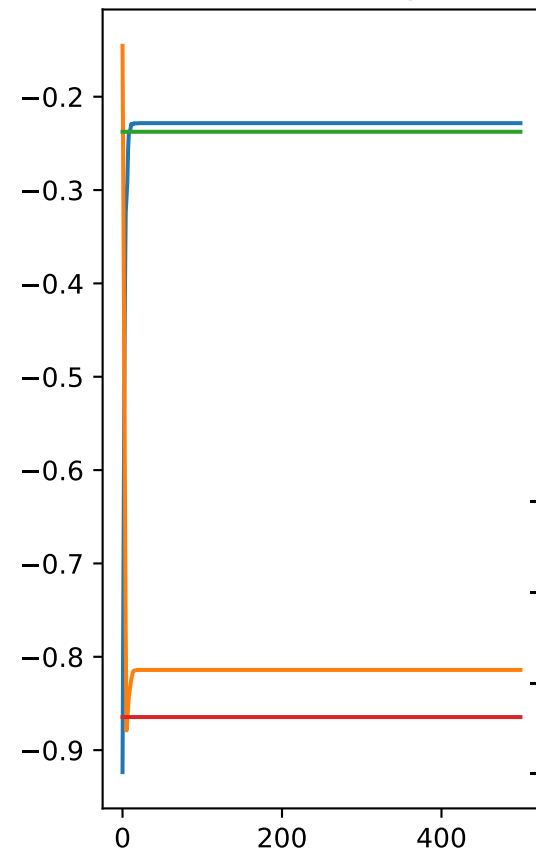
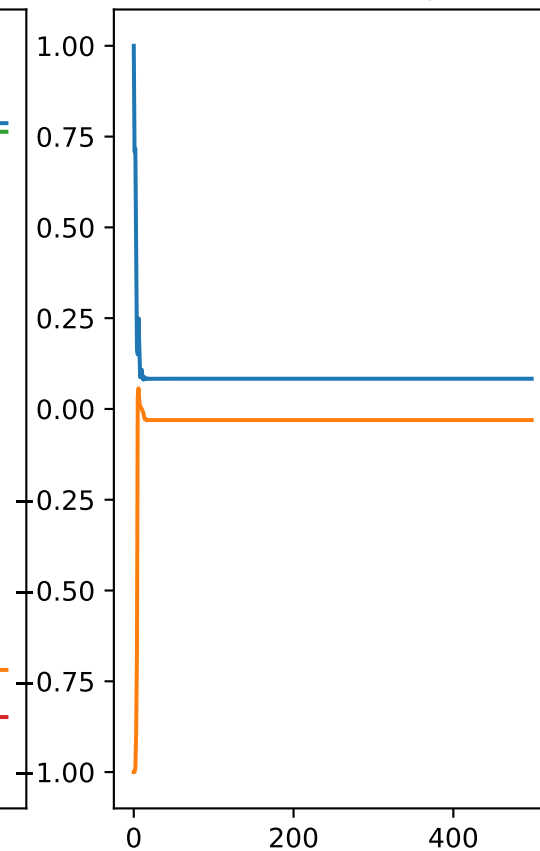


Reward: quadratic_2
Speed = 218.3658165990469 [rad/s]

State vs step



Action vs step



Reward vs step

