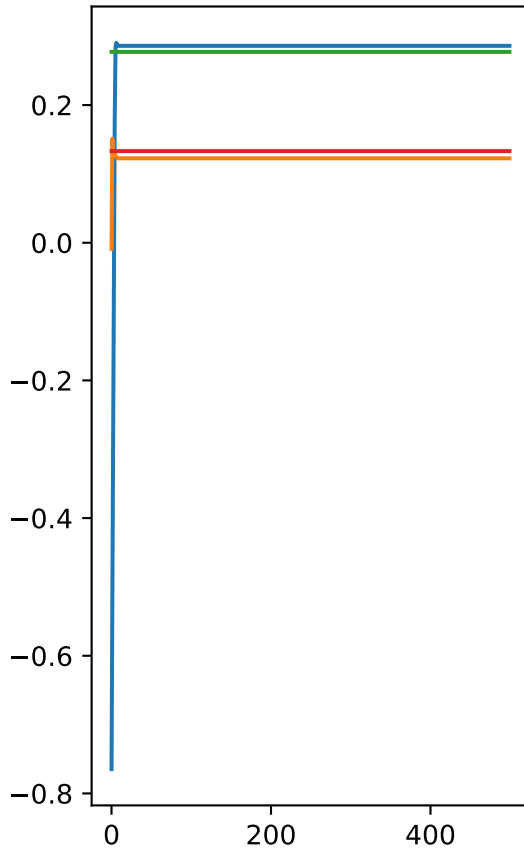
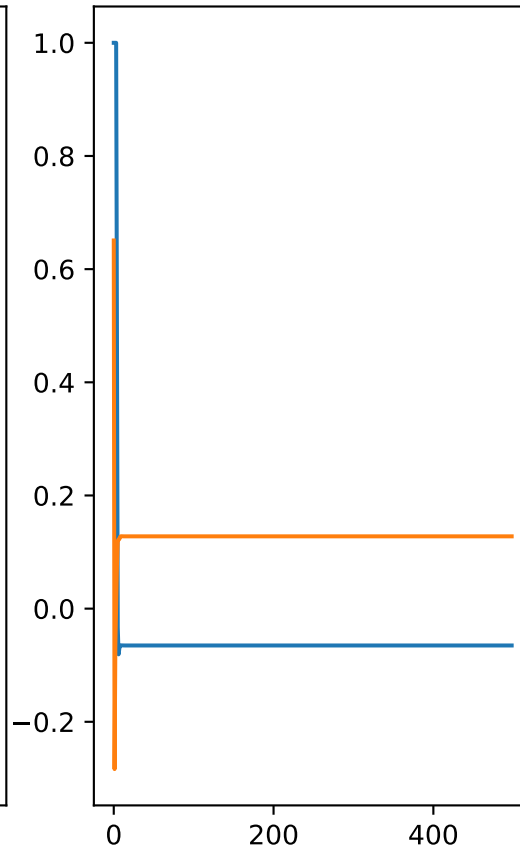


Reward: quartic_root
Speed = 636.2981519697846 [rad/s]

State vs step



Action vs step



Reward vs step

