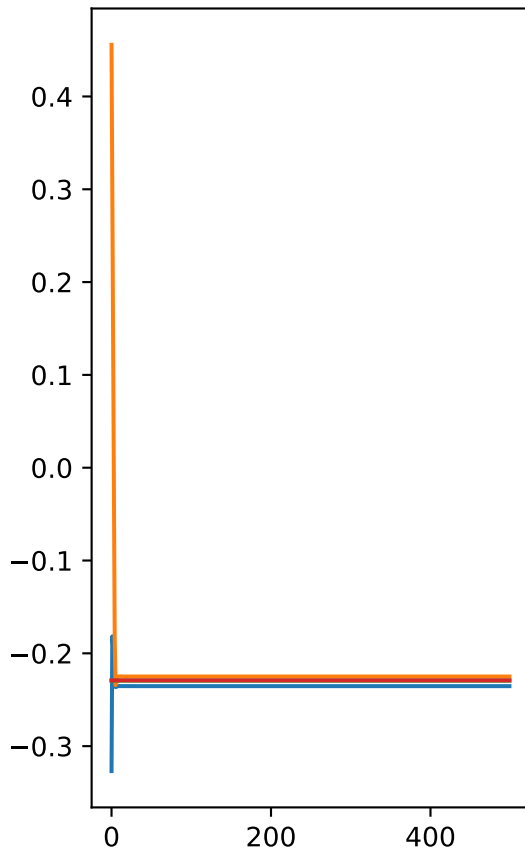
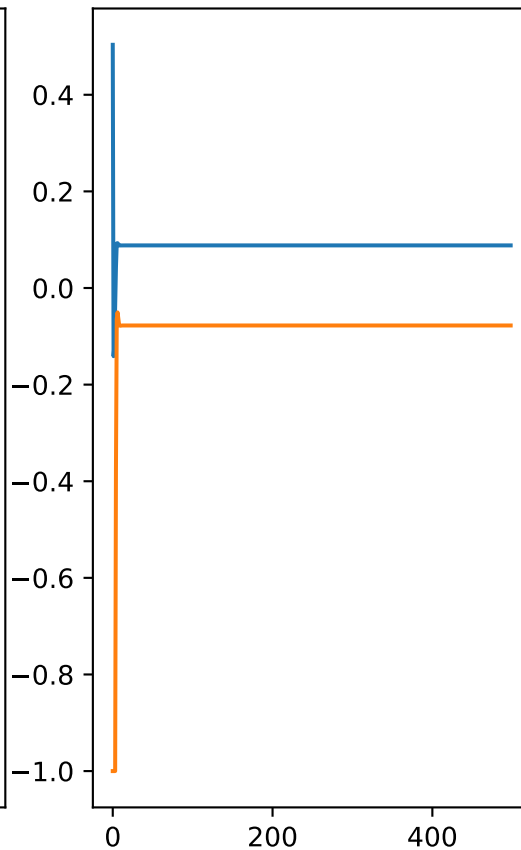


Reward: quartic\_root  
Speed = 897.5907318911136 [rad/s]

State vs step



Action vs step



Reward vs step

