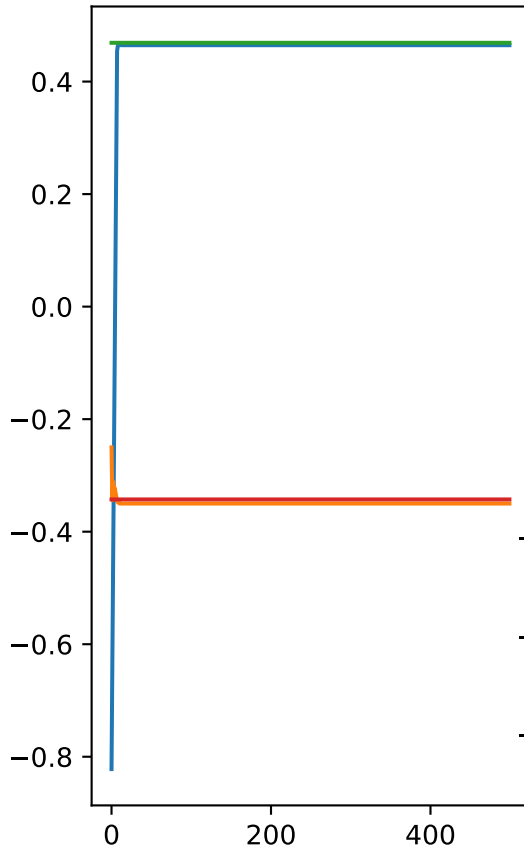
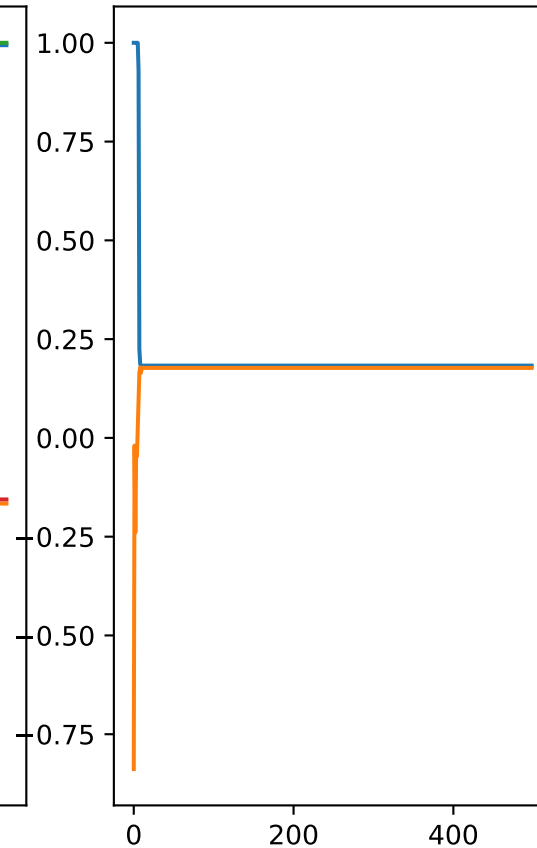


Reward: quartic_root
Speed = 672.4264704821235 [rad/s]

State vs step



Action vs step



Reward vs step

