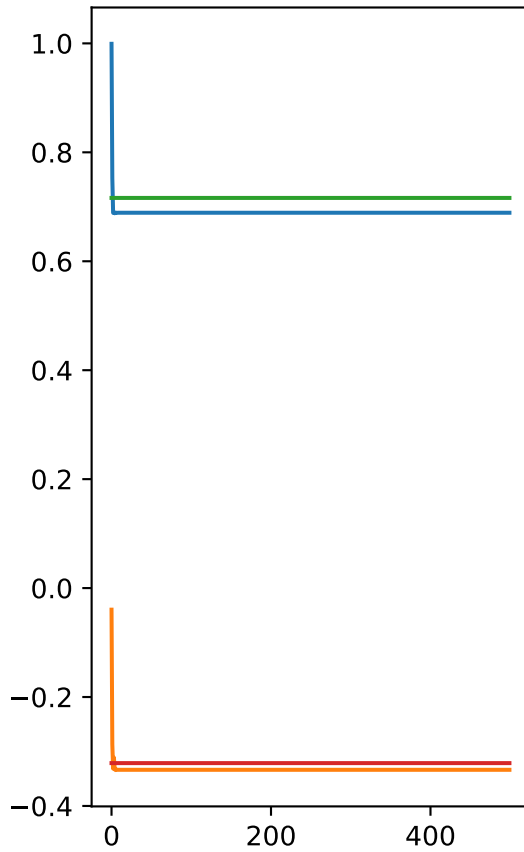
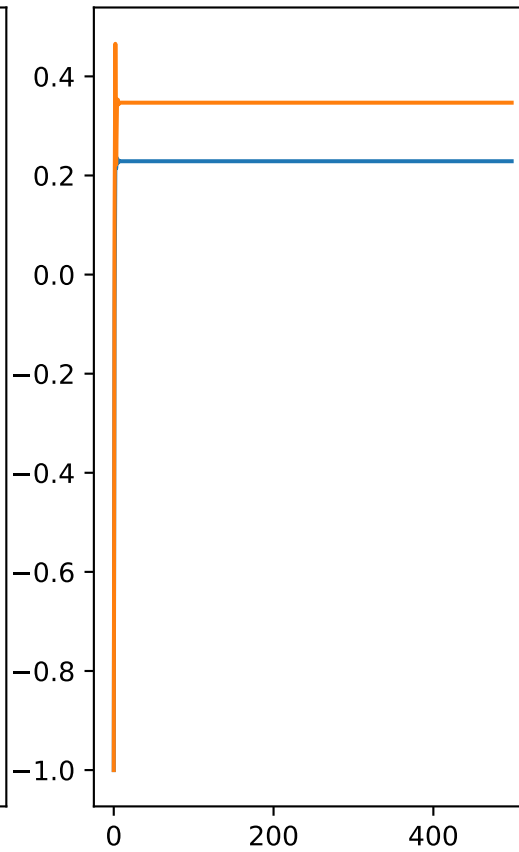


Reward: quartic_root
Speed = 633.92310329776 [rad/s]

State vs step



Action vs step



Reward vs step

