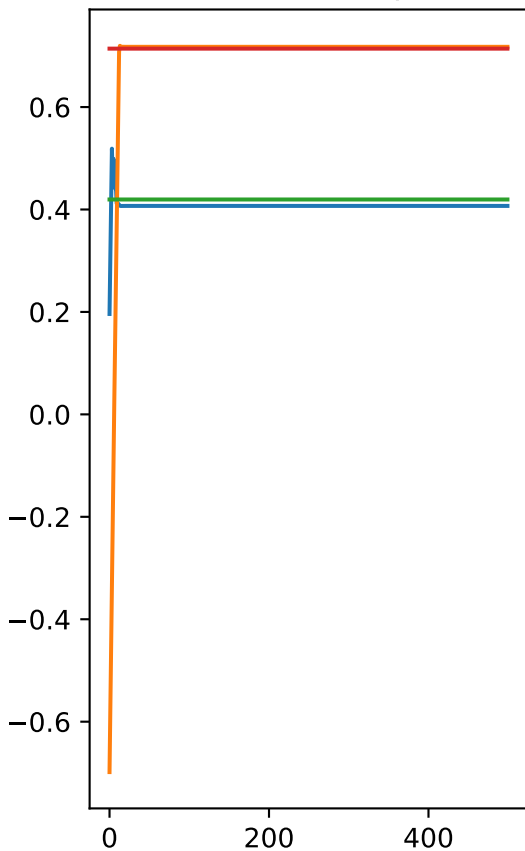
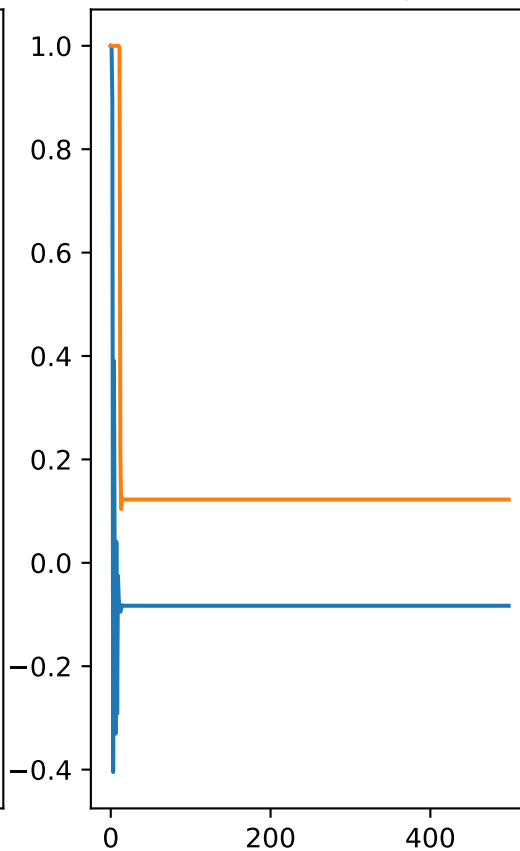


Reward: square_root
Speed = 423.65006524913764 [rad/s]

State vs step



Action vs step



Reward vs step

