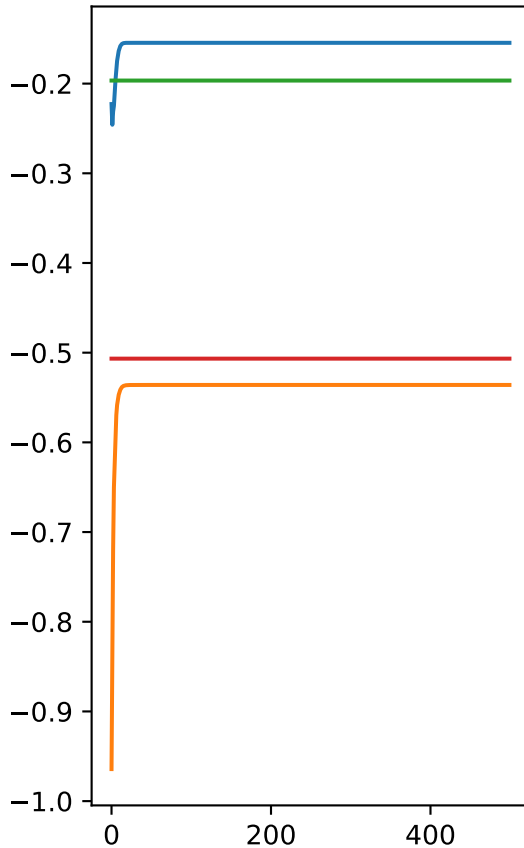
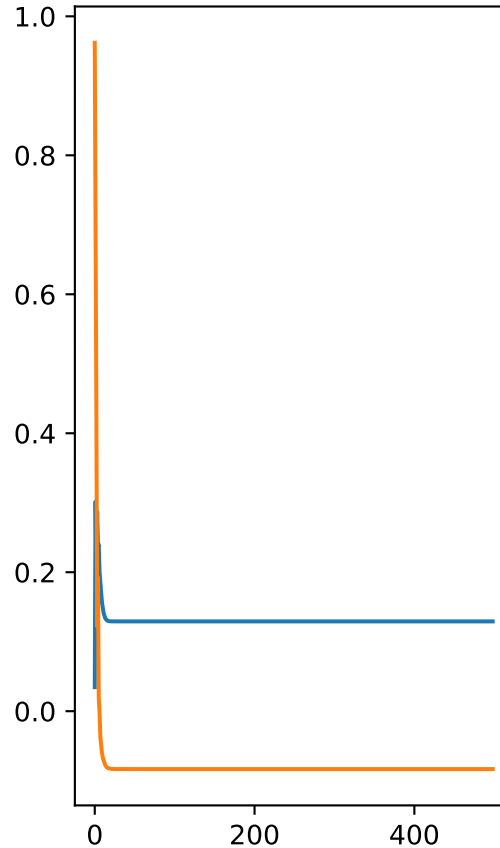


Reward: quadratic  
Speed = 255.96441225375884 [rad/s]

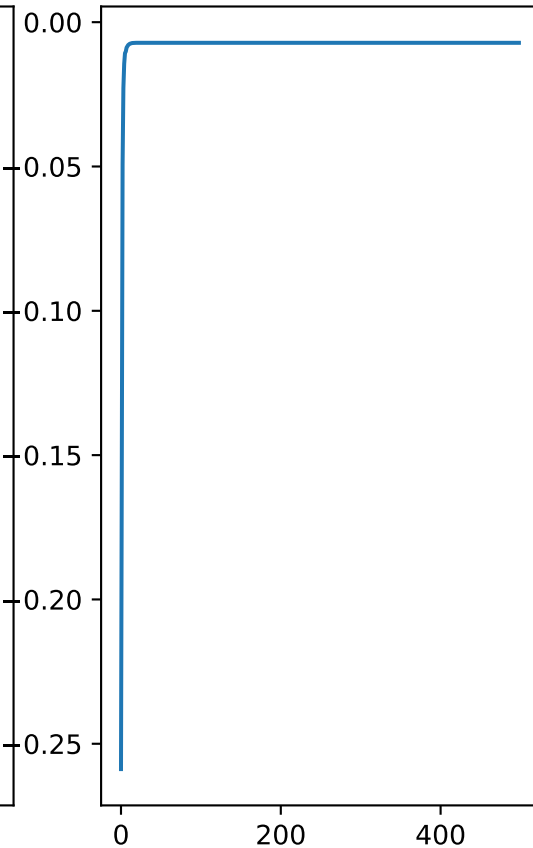
State vs step



Action vs step



Reward vs step



Id Idref  
Iq Iqref

Vd Vq