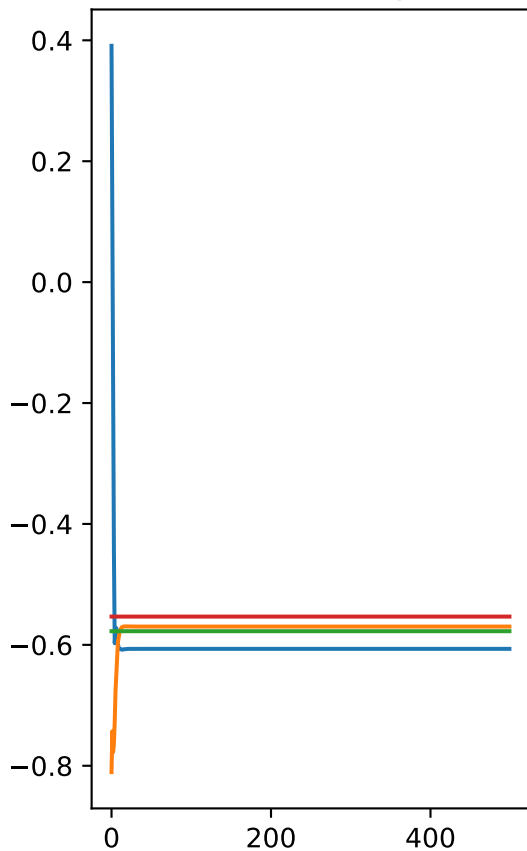
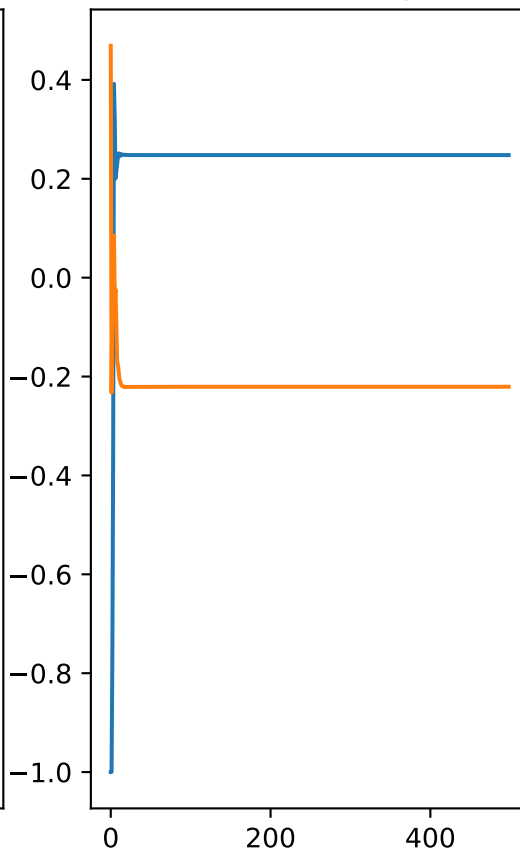


Reward: quadratic
Speed = 285.60847862754036 [rad/s]

State vs step



Action vs step



Reward vs step

