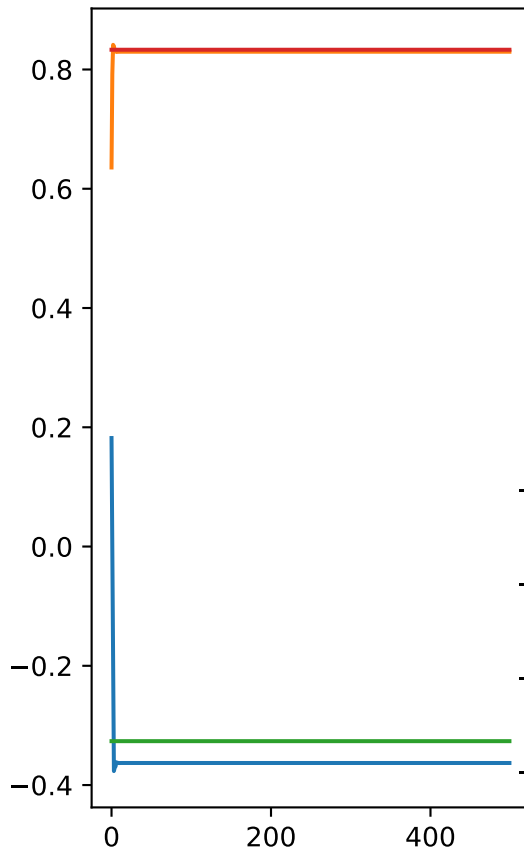
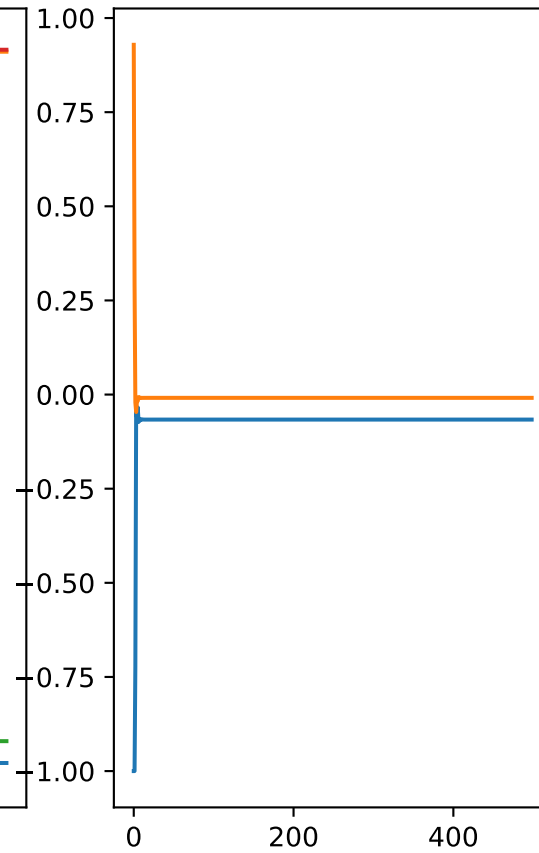


Reward: quartic_root
Speed = 697.7477145804345 [rad/s]

State vs step



Action vs step



Reward vs step

