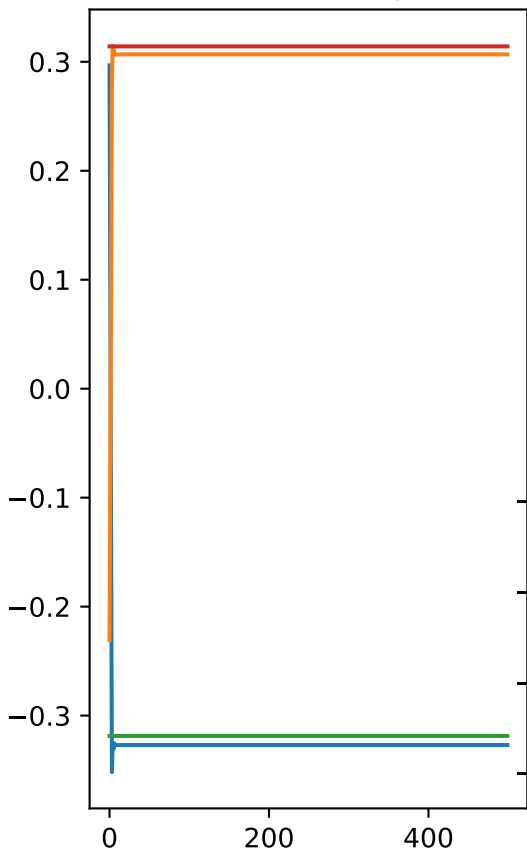
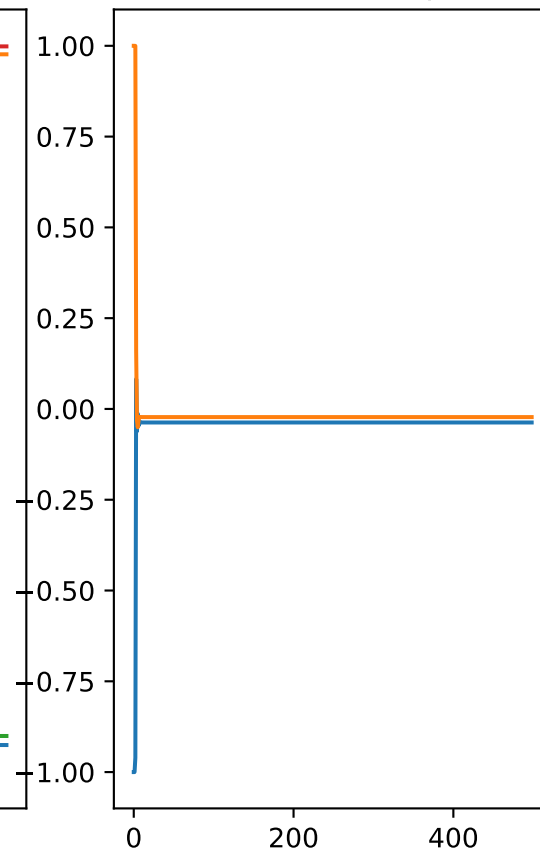


Reward: quartic_root
Speed = 1099.5700121925784 [rad/s]

State vs step



Action vs step



Reward vs step

