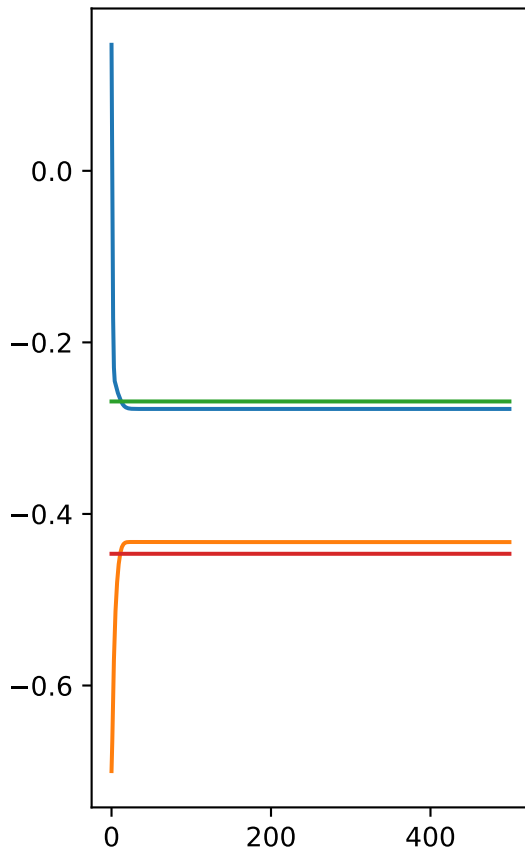
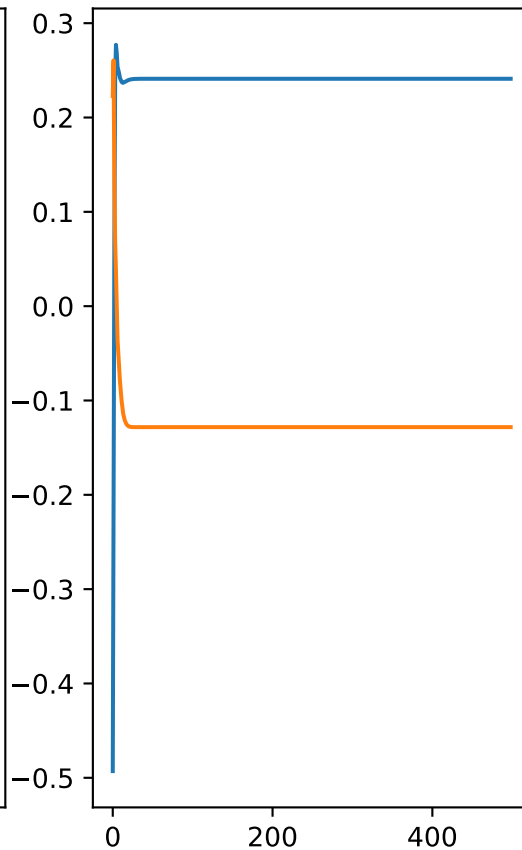


Reward: quadratic\_2  
Speed = 85.7654800422126 [rad/s]

State vs step



Action vs step



Reward vs step

