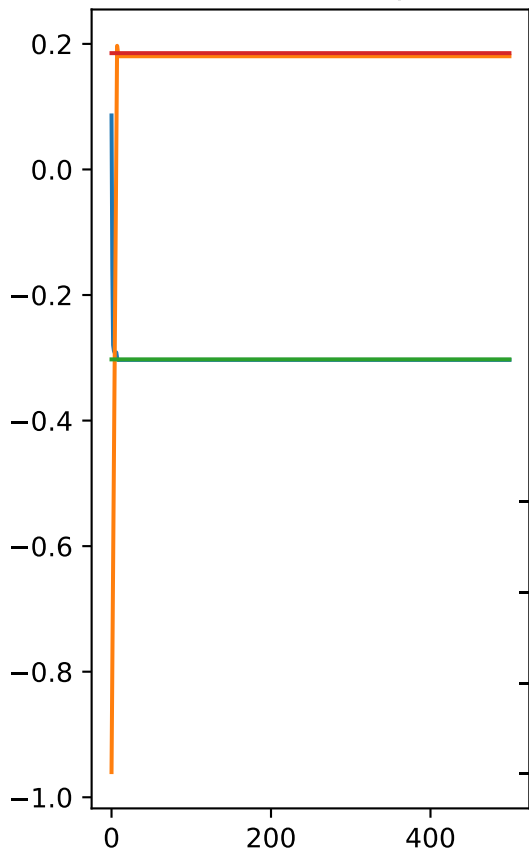
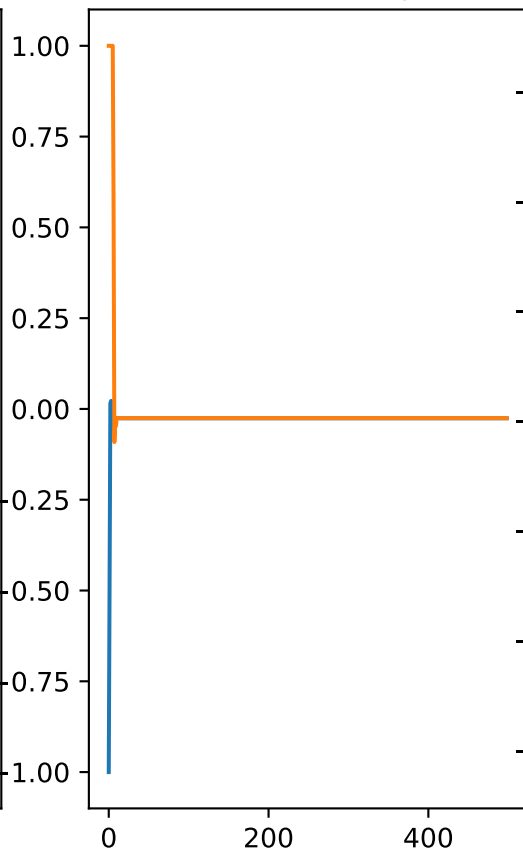


Reward: quartic_root
Speed = 1022.3622424510638 [rad/s]

State vs step



Action vs step



Reward vs step

