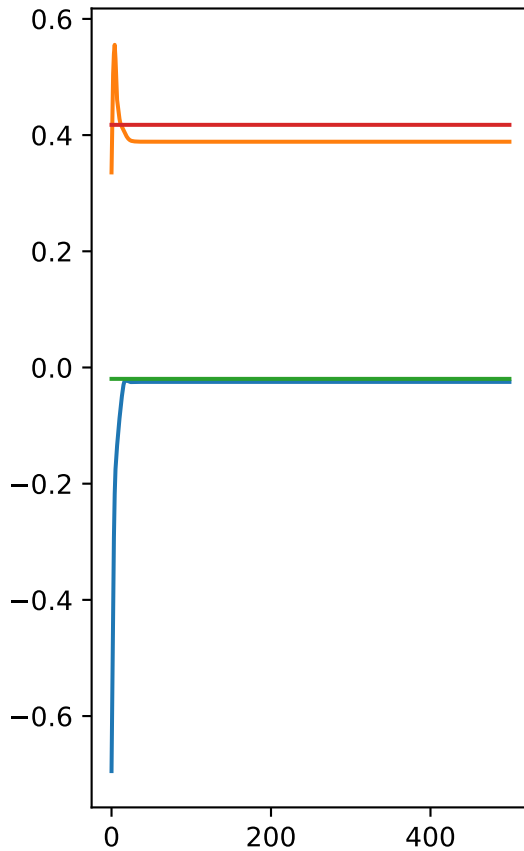
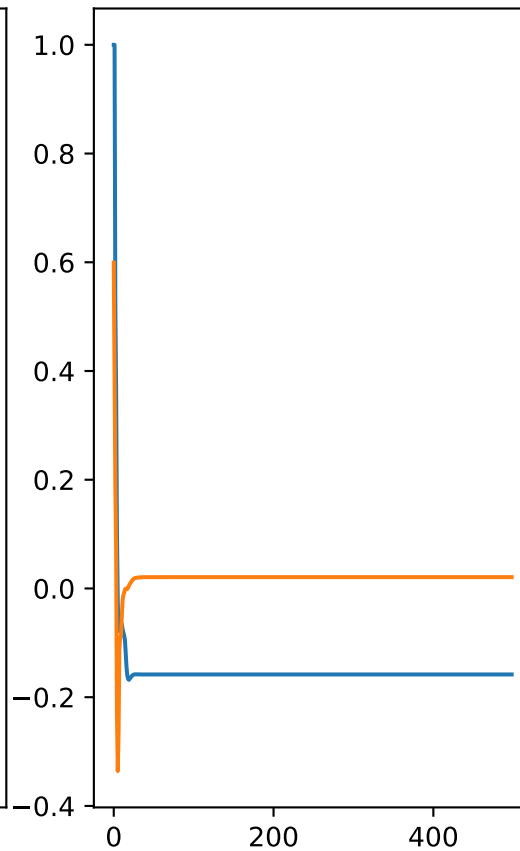


Reward: quadratic_2
Speed = 577.7137553790858 [rad/s]

State vs step



Action vs step



Reward vs step

