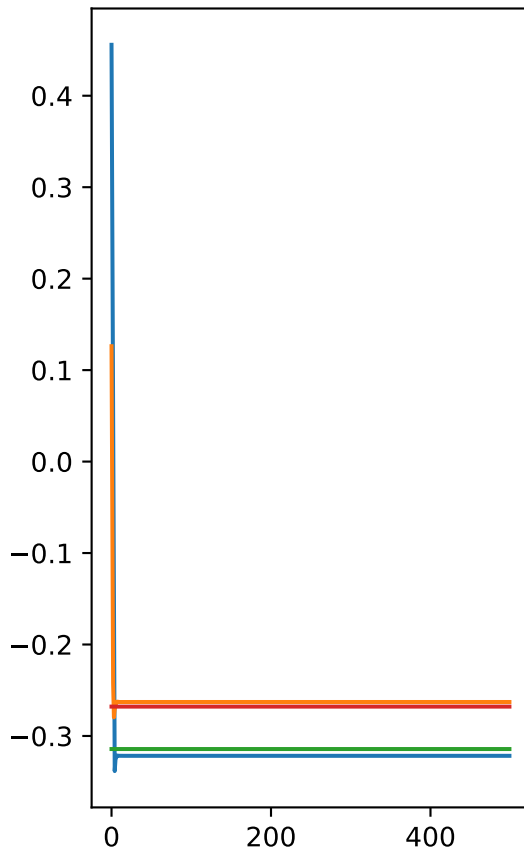
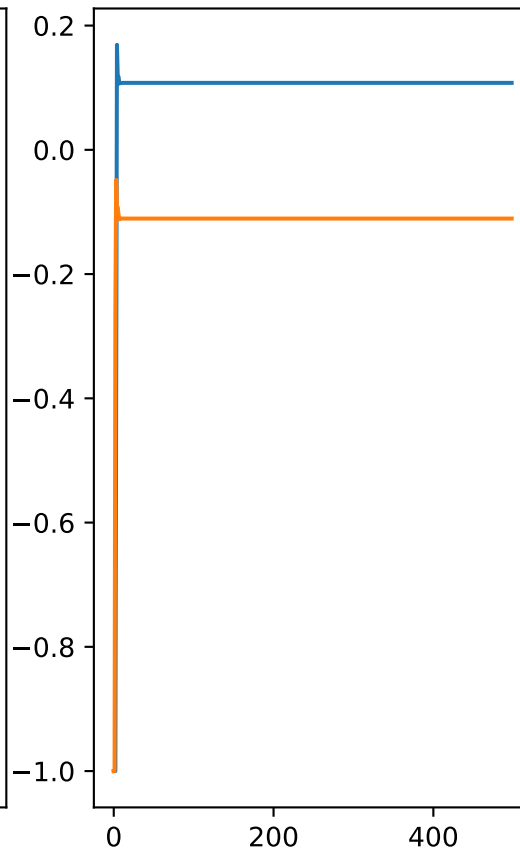


Reward: quartic_root
Speed = 672.7531904136058 [rad/s]

State vs step



Action vs step



Reward vs step

