

Dongki Jung

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EDUCATION	University of Maryland, College Park <ul style="list-style-type: none">■ Ph.D. in Computer Science<ul style="list-style-type: none">● Adviser: Prof. Dinesh Manocha	Aug 2024 – Present
	Korea Advanced Institute of Technology (KAIST) <ul style="list-style-type: none">■ M.S. in Electrical Engineering<ul style="list-style-type: none">● Adviser: Prof. Changick Kim	Feb 2019 – Feb 2021
	Korea University <ul style="list-style-type: none">■ B.S. in Electrical Engineering<ul style="list-style-type: none">● Auxiliary Police (mandatory military service)	Mar 2013 – Feb 2019 May 2014 – Feb 2016
EMPLOYMENT	NAVER LABS <ul style="list-style-type: none">■ Spatial AI Team■ Robotics Vision Team■ Research Intern at Computer Vision Team	Mar 2022 – Aug 2024 Apr 2021 – Feb 2022 Sep 2020 – Mar 2021
RESEARCH INTERESTS	3D Reconstruction, SfM, Foundation Model, and Neural Rendering	
PUBLICATIONS	PREPRINTS <ul style="list-style-type: none">[1] Jaehoon Choi, Dongki Jung, Yonghan Lee, Sungmin Eum, Dinesh Manocha, and Heesung Kwon, “UAVTwin: Neural Digital Twins for UAVs using Gaussian Splatting”, <i>Submitted</i>. INTERNATIONAL CONFERENCES <ul style="list-style-type: none">[1] Dongki Jung, Jaehoon Choi, Yonghan Lee, Dinesh Manocha, “MoRe: Monocular Geometry Refinement via Graph Optimization for Cross-View Consistency”, <i>WACV</i>, 2026.[2] Jaehoon Choi, Dongki Jung, Christopher Maxey, Sungmin Eum, Yonghan Lee, Dinesh Manocha, and Heesung Kwon, “UAV4D: Dynamic Neural Rendering of Human-Centric UAV Imagery using Gaussian Splatting”, <i>AAAI</i>, 2026[3] Dongki Jung, Jaehoon Choi, Yonghan Lee, and Dinesh Manocha, “RPG360: Robust 360 Depth Estimation with Perspective Foundation Models and Graph Optimization”, <i>NeurIPS</i>, 2025.[4] Dongki Jung*, Jaehoon Choi*, Yonghan Lee, Dinesh Manocha, “IM360: Textured Mesh Reconstruction for Large-scale Indoor Mapping with 360° Cameras,” <i>ICCV</i>, 2025. (* equal contribution)[5] Dongki Jung, Jaehoon Choi, Yonghan Lee, Somi Jeong, Taejae Lee, Dinesh Manocha, Suyong Yeon, “EDM: Equirectangular Projection-Oriented Dense Kernelized Feature Matching,” <i>CVPR</i>, 2025.[6] Obin Kwon, Dongki Jung, Youngji Kim, Soohyun Ryu, Suyong Yeon, Songhwai Oh, Donghwan Lee, “WayIL: Image-based Indoor Localization with Wayfinding Maps,” <i>ICRA</i>, 2024.[7] Jaehoon Choi, Dongki Jung, Taejae Lee, Sangwook Kim, Youngdong Jung, Dinesh Manocha, Donghwan Lee, “TMO: Textured Mesh Acquisition of Objects with a Mobile Device by using Differentiable Rendering,” <i>CVPR</i>, 2023.[8] Dongki Jung*, Jaehoon Choi*, Yonghan Lee, Deokhwa Kim, Dinesh Manocha, Donghwan Lee, “SelfTune: Metrically Scaled Monocular Depth Estimation through Self-Supervised Learning,” <i>ICRA</i>, 2022. (* equal contribution)[9] Dongki Jung*, Jaehoon Choi*, Yonghan Lee, Deokhwa Kim, Changick Kim, Dinesh Manocha, Donghwan Lee, “DnD: Dense Depth Estimation in Crowded Indoor Dynamic Scenes,” <i>ICCV</i>, 2021. (* equal contribution)[10] Taekyung Kim, Jaehoon Choi, Seokeon Choi, Dongki Jung, Changick Kim, “A Few Depth Points are All You Need for Multi-view Stereo: A Novel Semi-supervised Learning Method for Multi-view Stereo,” <i>ICCV</i>, 2021.[11] Jaehoon Choi, Dongki Jung, Yonghan Lee, Deokhwa Kim, Dinesh Manocha, and Donghwan Lee, “SelfDeco: Self-Supervised Monocular Depth Completion in Challenging Indoor Environments,” <i>ICRA</i>, 2021.	

- [12] **Dongki Jung***, Jaehoon Choi*, Donghwan Lee, Changick Kim, “SAFENet: Self-Supervised Monocular Depth Estimation with Semantic-Aware Feature Extraction,” *NeurIPS*, 2020. (* equal contribution)
- [13] **Dongki Jung**, Seunghan Yang, Jaehoon Choi, and Changick Kim, “Arbitrary Style Transfer Using Graph Instance Normalization,” *ICIP*, 2020.
- [14] Yonghan Lee, Jaehoon Choi, **Dongki Jung**, Jaeseong Yun, Soohyun Ryu, Dinesh Manocha, Suyong Yeon, “Mode-GS: Monocular Depth Guided Anchored 3D Gaussian Splatting for Robust Ground-View Scene Rendering,” *arXiv* 2024.
- [15] Seunghan Yang, Youngeun Kim, **Dongki Jung**, Changick Kim, “Partial Domain Adaptation Using Graph Convolutional Networks,” *arXiv* 2020.

CHALLENGES

INTERNATIONAL CHALLENGES

- [1] **3rd place** in the Track 3: City-Scale Multi-Camera Vehicle Tracking at **AI City Challenge** held in *IEEE Conference on Computer Vision and Pattern Recognition Workshop* 2020

PROJECT EXPERIENCE

- ATM vandalism action recognition Mar 2018 – Jun 2018
 - Research internship at *Korea University*. Funded by *Nautilus HYOSUNG*
 - Aimed at making the ATM vandalism dataset with own annotation and object detection with YOLOv2
- 3D Object Recognition Algorithm for Indoor and Outdoor Scenes May 2019 – Sep 2020
 - Research project at *KAIST*. Funded by *LG Electronics Co., Ltd*
 - Aimed at Developing the 2D object detection and depth estimation for cross-modality of RGB and FIR images.
- Dense mapping (SfM/Neural SDF) for indoor scene reconstruction Dec 2022 – Aug 2024
 - Research project at *NAVER LABS*
 - Developed a fully automated pipeline for textured mesh using omnidirectional camera
 - served for a real estate property tours

PATENTS

- Dongki Jung, Donghwan Lee, Yonghan Lee, Deokhwa Kim, “Method and System for Training Monocular Depth Estimation Models,” Korean Patent No. 10-2023-0064188
- Eight pending patents in South Korea.

TEACHING

- University of Maryland College Park, Teaching Assistant Aug 2024 – Present
 - CMSC351 – Algorithms

AWARDS & SCHOLARSHIPS

- Academic Achievement Award, *Korea University*
 - Semester High Honors in the first Semester of 2016
 - Semester High Honors in the second Semester of 2016
 - Semester High Honors in the first Semester of 2017
 - Semester High Honors in the second Semester of 2017
 - Great Honor in Winter 2018 Graduation
- KU Alumni Scholarships
 - the second Semester of 2016
- YooJung Scholarship Foundation
 - the first and second Semesters of 2017
 - the first and second Semesters of 2018

LANGUAGES

- Korean: Native language
- English: Business Level

SKILLS

Python, C++, ROS, Docker, *LATEX*, MATLAB, PyTorch, TensorFlow,

REFERENCES

■ Dinesh Manocha

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■ Donghwan Lee

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■ **Martin Humenberger**

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