

NEURAL MECHANISMS OF HIERARCHICAL PLANNING DURING NAVIGATION

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1 Introduction

Planning, or making multiple decisions in order to achieve a goal, is costful. Efficient planning can be achieved by exploiting hierarchical representations. It has been shown that humans spontaneously chunk abstract spaces into multiple contexts in a hierarchical fashion ¹

However, it is still unknown To test whether humans plan hierarchically, we designed a novel navigation task where the space of states is intrinsically hierarchical.

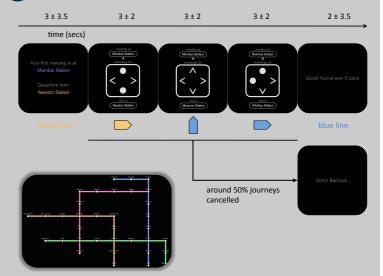
We predicted that context switching would be associated with activation in the Anterior Cingulate Cortex (dACC), a region previously associated with task-switching 2 and tracking the reward value of alternative contexts 3 .

refontal Cortex (mPFC), a region would track distance to goal. Furthermore, we predicted that the previously associated with outcome expectation ³,

Methods

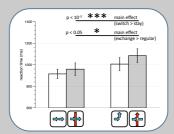
 ${\bf N}$ = 19 participants (age 00±00, 00 males) performed a navigation task within a virtual with which they were familiar, while undergoing . The instruction was to minimise the length of all journeys. Completed journeys were economically rewarded after participation (journeys could be randomly cancelled on every step, with fixed probability). The map was shown during a preliminary training session but not during the scanning session. Possible directions (actions) were North / South / East / West. Regular, exchange and elbow stations allowed us to disentangle between effects due to number of possible directions, direction switch, and line switch

Design



First Result - dACC signals line switch





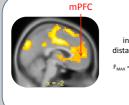
shown interaction. This can be interpreted as the dACC being

A positive beta weight was found in the

RT), for which main effects of switch > stay and exchange > regular are significant, but not the interaction.

for the

Second Result – mPFC tracks distance to goal but not reward



inverse of distance to goal _{MAX} = 4.09 p < 10⁻³



positive feedback



negative feedback $F_{MAX} = 6.00 \text{ p} < 10^{-3}$



positive > negative p < 10⁻³

The same GLM revealed that activity in mPFC (bilateral) inversely correlates with distance to goal.

was consistently activated at the end of (feedback time), independently of the Strikingly, it was consistently (positive or negative).



This results provide evidence that humans exploit hierarchical structures during navigation, dividing the space into multiple contexts. The in pursuit of reward. Additionally, we report evidence for a new role of the vmPFC in tracking distance to goal but not reward outcome.

This is in line with previous proposals of a hierarchical organisation of the prefrontal cortex, where resources in anterior regions are allocated to long-term outcomes, in opposition with posterior short-term outcomes. However in our study, activation in vmPFC depends on the structure of the task rather than outcome.

References

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