

## Series 3, March March 19-20, 2015 (The $K$ -means Algorithm)

### Solution 1 ( $K$ -means Theory):

1. (a) (Convergence of the  $K$ -Means Algorithm) The  $K$ -means algorithm converges since at each iteration it either reduces or keeps the same the value of the objective function  $J$ , where

$$J = \sum_{n=1}^N \sum_{k=1}^K z_{k,n} \|\mathbf{x}_n - \mathbf{u}_k\|_2^2 \quad (\|\mathbf{x}_n - \mathbf{u}_k\|_2^2 = (x_{1,n} - u_{1,k})^2 + \dots + (x_{d,n} - u_{d,k})^2)$$

with the constraint

$$\sum_{k=1}^K z_{k,n} = 1 \quad \text{and} \quad z_{k,n} \in \{0, 1\}.$$

When initializing the algorithm, at step 2 of the  $K$ -means algorithm we set

$$z_{k^*(\mathbf{x}_n),n} = 1 \quad \text{and} \quad z_{k',n} = 0,$$

where

$$k^*(\mathbf{x}_n) = \underset{k}{\operatorname{argmin}} \{ \|\mathbf{x}_n - \mathbf{u}_1\|_2^2, \dots, \|\mathbf{x}_n - \mathbf{u}_k\|_2^2, \dots, \|\mathbf{x}_n - \mathbf{u}_K\|_2^2 \}.$$

This makes the value of  $J$  minimal considering that we have to assign the value 1 to one and only one  $z_{k,n}$ , and 0 to all others.

At step 3, the centroid update term you are familiar with:

$$\mathbf{u}_k = \frac{\sum_{n=1}^N z_{k,n} \mathbf{x}_n}{\sum_{n=1}^N z_{k,n}} \quad \forall k, k = 1, \dots, K \quad (1)$$

means that

$$0 = \sum_{n=1}^N z_{k,n} (\mathbf{x}_n - \mathbf{u}_k) \quad \forall k, k = 1, \dots, K$$

Note that this equals setting the derivative of  $J$  with respect to  $\mathbf{u}_k$  to zero for all  $k, k = 1, \dots, K$ , as a particular derivative is given by:

$$\frac{\partial J}{\partial \mathbf{u}_k} = \frac{\partial \sum_{n=1}^N z_{k,n} \|\mathbf{x}_n - \mathbf{u}_k\|_2^2}{\partial \mathbf{u}_k} = \sum_{n=1}^N z_{k,n} \begin{bmatrix} \frac{\partial (x_{1,n} - u_{1,k})^2}{\partial u_{1,k}} \\ \vdots \\ \frac{\partial (x_{d,n} - u_{d,k})^2}{\partial u_{d,k}} \end{bmatrix} = -2 \sum_{n=1}^N z_{k,n} (\mathbf{x}_n - \mathbf{u}_k)$$

Note that  $\frac{\partial^2 J}{\partial \mathbf{u}_k^2} \geq 0$ , or in other words, the gradient of  $J$  with respect to  $\mathbf{u}_k$  is pointing downwards (or is flat). Thus, the value of  $J$  does not increase after the centroid update. Considering all the above, it follows that repeating steps 2 and 3 in iterations means that the value of  $J$  will converge.

- (b) (The  $K$ -Means Algorithm and Matrix Factorization) At step 2 of each iteration the  $K$ -means algorithm also minimises

$$\sum_{n=1}^N \sum_{k=1}^K \|\mathbf{x}_n - z_{k,n} \mathbf{u}_k\|_2^2 \quad (2)$$

This follows from the constraints that  $\sum_{n=1}^N z_{k,n} = 1$  and either  $z_{k,n} = 0$  or  $z_{k,n} = 1$ , for all  $k, n$ , since they lead to the following equality:

$$\min_{\mathbf{Z}} \sum_{n=1}^N \sum_{k=1}^K \|\mathbf{x}_n - z_{k,n} \mathbf{u}_k\|_2^2 = \sum_{n=1}^N ((K-1) \|\mathbf{x}_n\|_2^2 + \min\{\|\mathbf{x}_n - \mathbf{u}_1\|_2^2, \dots, \|\mathbf{x}_n - \mathbf{u}_K\|_2^2\})$$

Similarly, at step 3, for a given  $\mathbf{Z}$  we minimize (2) since, for all  $k$ , the minimum of (2) with respect to  $\mathbf{u}_k$  is given by

$$\frac{\partial \sum_{n=1}^N \|\mathbf{x}_n - z_{k,n} \mathbf{u}_k\|_2^2}{\partial \mathbf{u}_k} = 0$$

which leads to (1) since  $z_{k,n} = z_{k,n}^2$  for all  $k, n$ . It follows that the  $K$ -means algorithm minimizes the objective function given by

$$J = \|\mathbf{X} - \mathbf{UZ}\|_2^2$$

where  $\mathbf{U} = [\mathbf{u}_1 \cdots \mathbf{u}_K]$ ,  $\mathbf{X} = [\mathbf{x}_1 \cdots \mathbf{x}_N]$ ,  $\mathbf{X} \in \mathbb{R}^{D \times N}$ ,  $\mathbf{U} \in \mathbb{R}^{D \times K}$ , and  $\mathbf{Z} \in \mathbb{R}^{K \times N}$ .