

# Computer Vision using Convolutional NN

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# Computer vision:

Computers gaining high level understanding from images and videos.  
Some Areas:

- Image classification
- Object Recognition
- Object Detection
- Semantic Segmentation
- Instance Segmentation – automatic delineation of
- 3D reconstruction

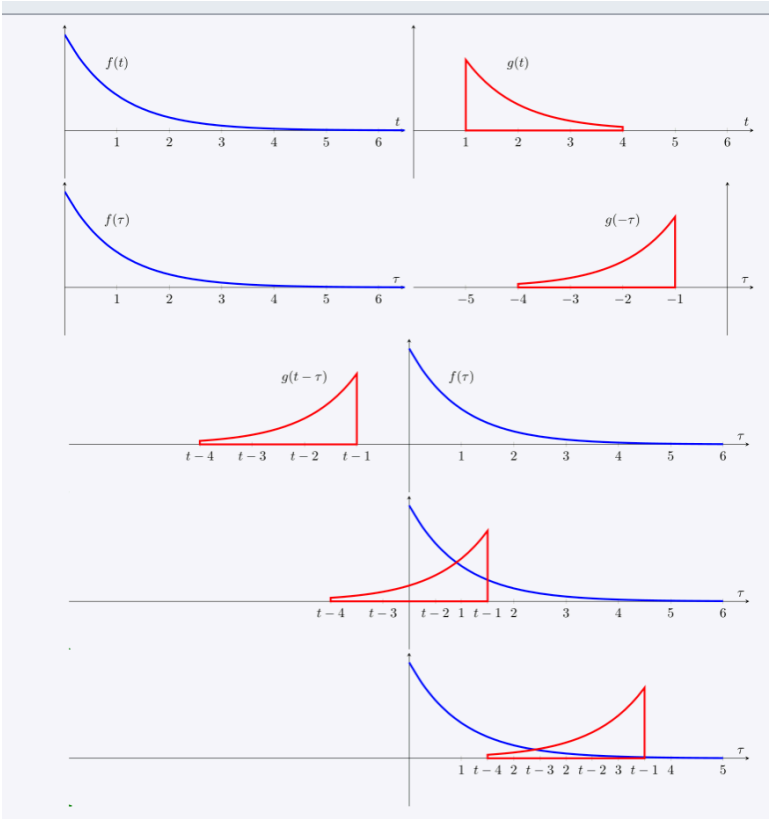
## **Before ANN:**

- SURF, SIFT features + SVMs for object detection
- EigenFaces for Face Recognition
- Kernels for edge detection... Convolutions were used before CNNs!

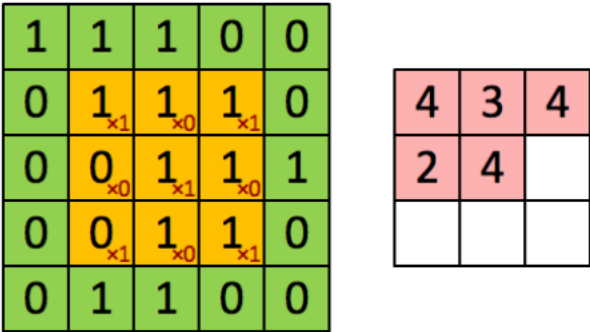
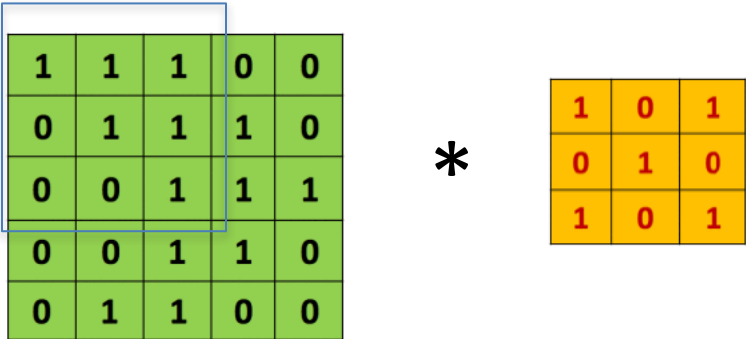
# Image Convolutions:

## Convolution Mathematics

$$(f * g)[n] = \sum_{m=-\infty}^{\infty} f[m]g[n - m]$$





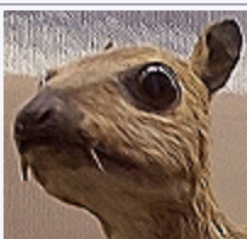
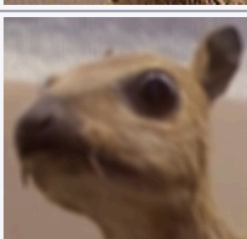
## Convolution images



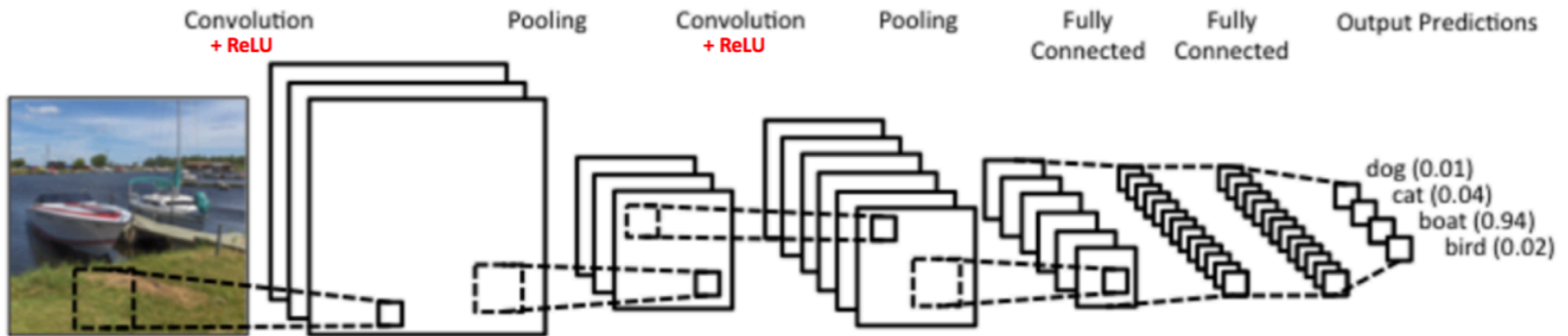
Image

Convolved  
Feature

# Kernels

<b>Edge detection</b>	$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$	
	$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$	
<b>Sharpen</b>	$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$	
<b>Box blur</b> (normalized)	$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$	

# CNN Visualization



## Hyperparameters:

Architecture of the Network:

- Number and type of layers
- Depth: number of kernels for a particular layer
- Type of Activation Functions

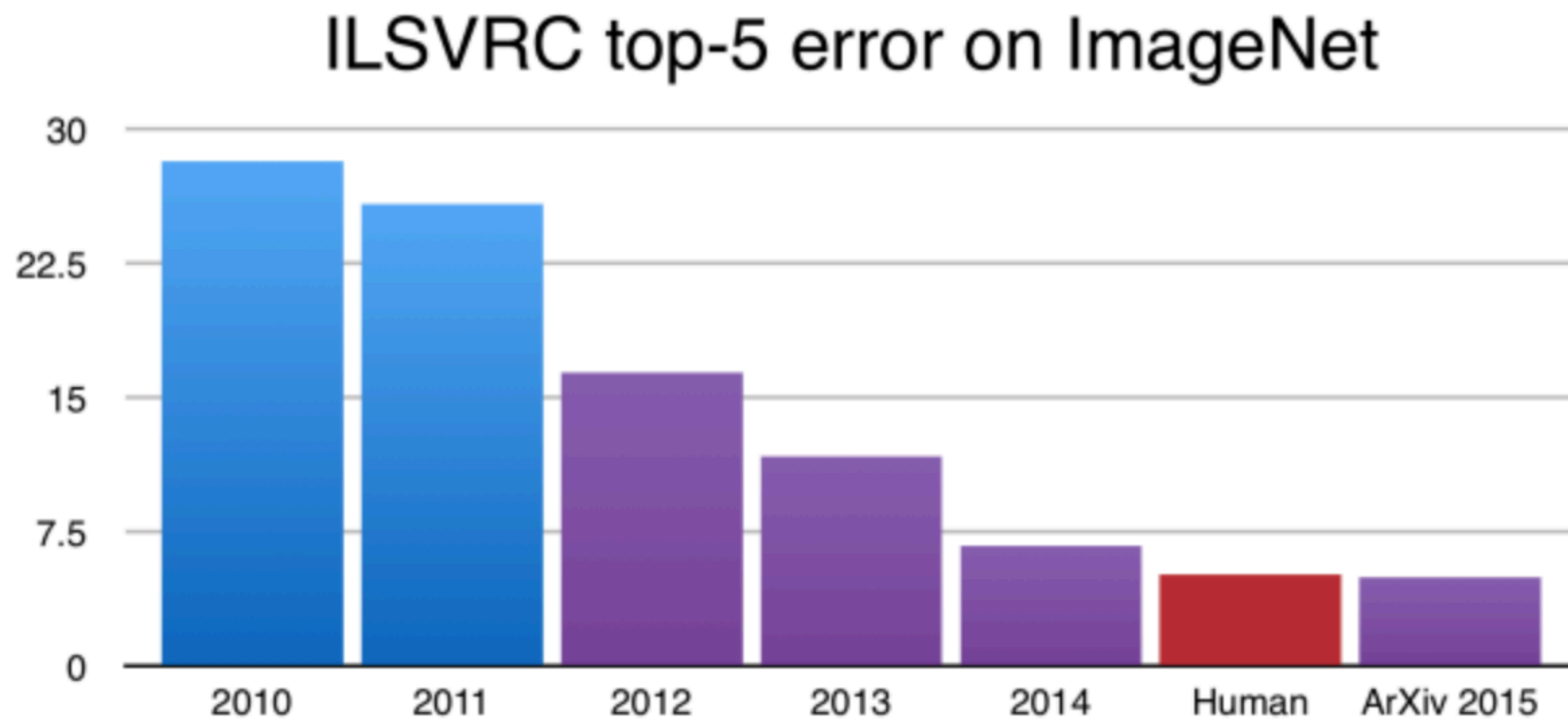
## Optimization:

- Learning Rate
- Parameters depending on the function used.
- Batches

# History of CNNs

- **LeNet 1990s**
- **1990s to 2012:** convolutional neural network were in incubation.
- **AlexNet (2012)** – In 2012, Alex Krizhevsky (and others) released [AlexNet](#) which was a deeper and much wider version of the LeNet and won by a large margin the difficult ImageNet LSVR Challenge in 2012.
- **ZF Net (2013)** – The ILSVRC 2013 winner was a Convolutional Network from Matthew Zeiler and Rob Fergus. It was an improvement on AlexNet by tweaking the architecture hyperparameters.
- **GoogLeNet (2014)** – The ILSVRC 2014 winner was a Convolutional Network from [Szegedy et al.](#) from Google. Its main contribution was the development of an *Inception Module* that dramatically reduced the number of parameters in the network (4M, compared to AlexNet with 60M).
- **VGGNet (2014)** – The runner-up in ILSVRC 2014 was the network that became known as the [VGGNet](#). Its main contribution was in showing that the depth of the network (number of layers) is a critical component for good performance.
- **ResNets (2015)** – [Residual Network](#) developed by Kaiming He (and others) was the winner of ILSVRC 2015.
- **DenseNet (August 2016)** – Recently published by Gao Huang (and others), the [Densely Connected Convolutional Network](#) has each layer directly connected to every other layer in a feed-forward fashion. The DenseNet has been shown to obtain significant improvements over previous state-of-the-art architectures on five highly competitive object recognition benchmark tasks. Check out the Torch implementation [here](#).

# ImageNet model errors



# CNNs for Image Detection and Object Segmentation

Extending the achievements of Alexnet to Instance Segmentation.

- R-CNN
- Fast R-CNN
- Faster R-CNN
- Mask R-CNN



# Ideas for next session

Implementation and challenges:

- Optimizers: which optimizers to use?
- Hyper parameters, how to choose them?
- Model overfitting:
  - Regularization
  - Visualize plots: learning curve, etc.
- Which functions to use for the middle layers?
- Which functions to use in the last layers?