

# H52F-05H: Robust Adaptation to Multi-Scale Climate Variability

Toward Better Water Planning and Management in an Uncertain World I

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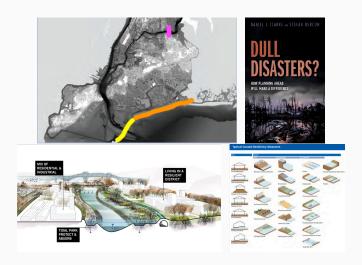
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# **Motivating Example**

What to do after Sandy? [City of New York, 2013]



# Hypotheses

#### Idea 1: Risk Estimates over Finite Future Periods

#### **Typical Approach:**

Cost-Benefit Analysis (CBA), probably with discounting, over a finite planning horizon of M years.

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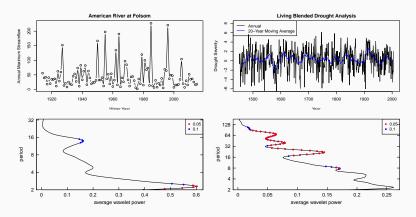
Cost-Benefit Analysis (CBA), probably with discounting, over a finite planning horizon of M years.

Project should be evaluated on climate conditions over this finite planning period:

- For "mega-project",  $M \ge 50$  years
- For small, flexible project,  $M \le 5$  years

# Idea 2: Hydroclimate Systems Vary on Many Scales

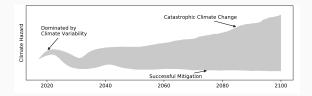
Inter-annual to multi-decadal cyclical variability key (for small M)



**Figure 1:** (a) 500 year reconstruction of summer rainfall over Arizona from LBDA [*Cook et al.*, 2010]. (b) A 100 year record of annual-maximum streamflows for the American River at Folsom. (c),(d): wavelet global (average) spectra.

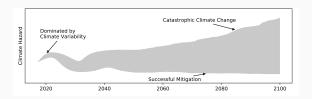
# Idea 3: Physical Drivers of Risk Depend on M

The physical drivers of hazard depend on the projection horizon (M),

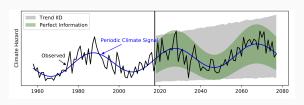


# Idea 3: Physical Drivers of Risk Depend on M

The physical drivers of hazard depend on the projection horizon (M),



but our ability to identify these mechanisms depends on information available (e.g., the length of an *N*-year observational record).



# Stylized Experiments

# **Experiment Setup**

#### Research Objective

How well can one identify & predict cyclical and secular climate signals over a finite planning period (M), given limited information?

Let  $P^*(X > X^*)$ . Note that the insurance premium (or risk factor) is:

$$R = \mathbb{E}[P^*] + \lambda \mathbb{V}[P^*]$$

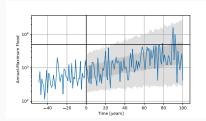
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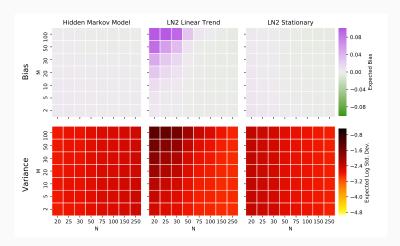
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Systematic, stylized experiments: what happens as we vary M, N, climate structure, estimating model?

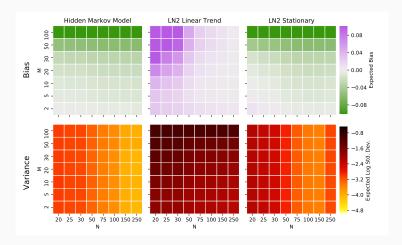
# Stationary Scenario (LFV Only)

With limited data, the uncertainties caused by extrapolating from complex models lead to poor performance.



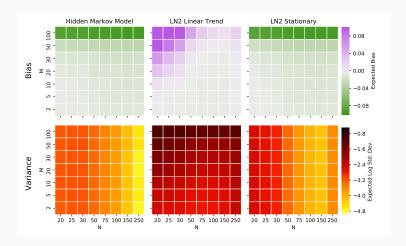
# Nonstationary Scenario I (Secular Change Only)

Long planning periods need trend estimation, but this demands lots of information. For short planning periods, simple models may be better.



# Nonstationary Scenario II (Secular Change + LFV)

As the system becomes more complex, more data is needed to understand it.



# **Discussion**

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- Investment evaluation depends on climate condition over finite planning period
- Physical hydroclimate systems vary on many scales
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#### Implications:

- Ability to identify and predict different climate signals depends on information available (e.g., N)
- Importance of predicting different climate signals depends on extrapolation desired (i.e., planning period)
- In general, low risk tolerance and/or limited information favor investments with short planning periods.

#### References i

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# Thanks for your attention!

Interested in making these ideas more concrete? I'd love to collaborate!

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**Supplemental Discussion** 

# $\textbf{Idealized Experiments} \iff \textbf{Real World}$

The idealized models used here are analogs:

Analysis	Real World
<i>N</i> -year record	Total informational uncertainty of an estimate
Statistical models of increasing complexity and $\#$ parameters	Statistical and dynamical model chains of increasing complexity and # parameters
Linear trends	Secular changes of unknown form
low-frequency climate variability (LFV) from the El Niño-Southern Oscillation (ENSO)	LFV from many sources
LFV and trend additive	LFV and trend interact

**Generating Synthetic Streamflow** 

**Sequences** 

# **Example Sequences and Fits**



Figure A1: Example of sequences generated with M=100 and N=50

# **Equations for Synthetic Streamflow Generation**

First

$$\log Q(t) \sim \mathcal{N}(\mu(t), \sigma(t)).$$
 (A1)

Where  $\sigma(t) = \xi \mu(t)$ , with  $\sigma(t) \geq \sigma_{\min} > 0$ . Then,

$$\mu(t) = \mu_0 + \beta x(t) + \gamma(t - t_0), \tag{A2}$$

and where x(t) is NINO3.4 index from realistic ENSO model [Zebiak and Cane, 1987; Ramesh et al., 2016]

### **Spectrum of LFV Used**

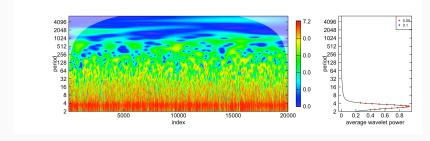


Figure A2: Wavelet spectrum of (sub-set of) ENSO model used to embed synthetic streamflow sequences with low-frequency variability. ENSO data from *Ramesh et al.* [2016].

**Climate Risk Estimation** 

# Stationary LN2 Model

Treat the N historical observations as independent and identically distributed (IID) draws from stationary distribution

where  $\mathcal N$  denotes the normal distribution and  $\mathcal N^+$  denotes a half-normal distribution. Fit in Bayesian framework using stan [Carpenter et al., 2017].

#### Trend LN2 Model

Treat the N historical observations as IID draws from log-normal distribution with linear trend

$$\mu = \mu_0 + \beta_\mu (t - t_0)$$
 $\log Q_{\text{hist}} \sim \mathcal{N}(\mu, \xi \mu)$ 
 $\mu_0 \sim \mathcal{N}(7, 1.5)$ 
 $\beta_\mu \sim \mathcal{N}(0, 0.1)$ 
 $\log \xi \sim \mathcal{N}(0.1, 0.1)$ 

where  $\xi$  is an estimated coefficient of variation. Also fit in stan.

#### **Hidden Markov Model**

Two-state hidden Markov model (HMM) [see *Rabiner and Juang*, 1986] implemented using pomegranate python package [*Schreiber*, 2017]. See package documentation for reference.