

# A Unified Machine Learning Framework for Optimization Under Uncertainty

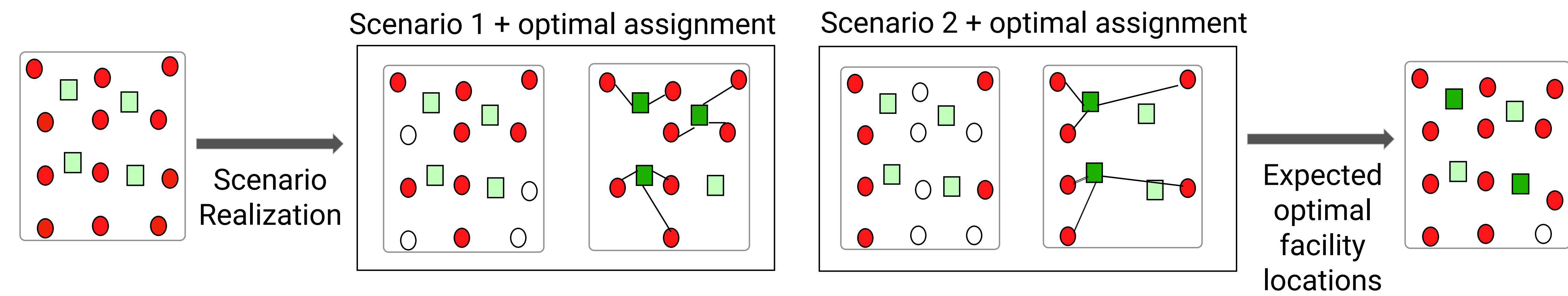
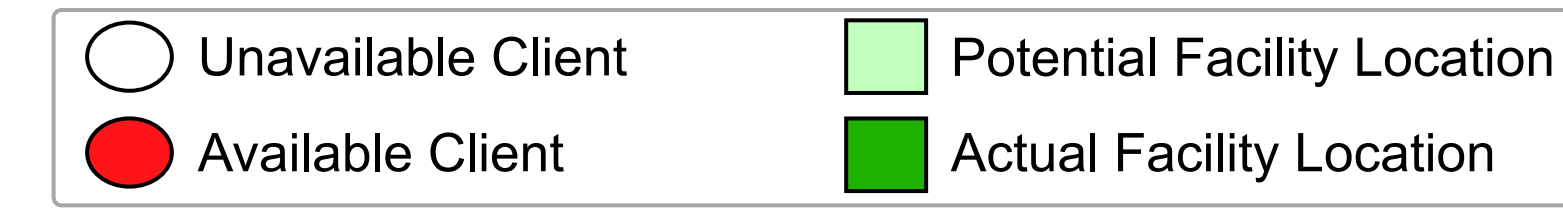
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## Learning for Two-Stage Stochastic Programming (2SP)

Published at NeurIPS 2022. Joint work with Rahul Patel, Elias Khalil, and Merve Bodur

### Stochastic Facility Location Problem

**Objective:** Determine the optimal set of facilities to construct given uncertainty in client requests.

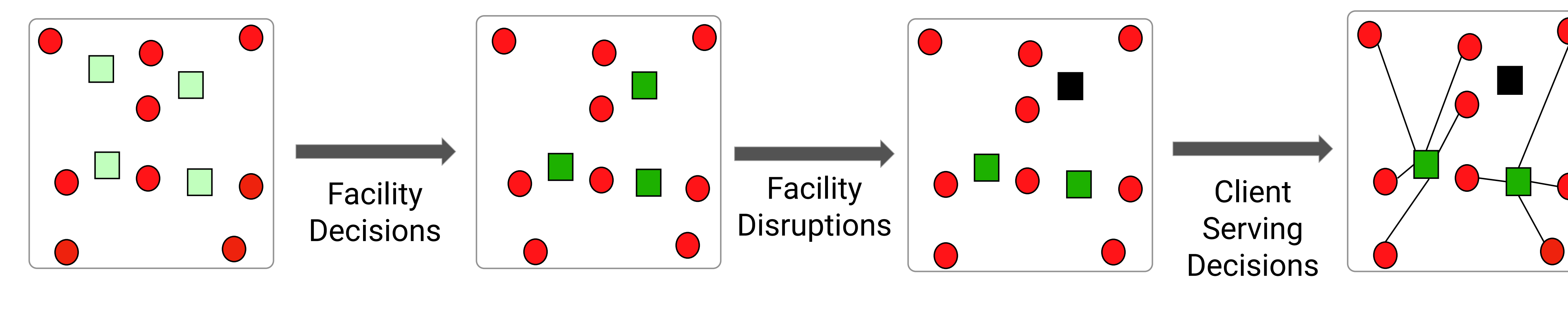


## Learning for Two-Stage Robust Optimization (2RO)

Under review. Joint work with Esther Julien, Jannis Kurtz, and Elias Khalil

### Robust Facility Location Problem

**Objective:** Determine the optimal set of facilities to open under the worst-case facility disruption.



### Overall framework

#### Data Collection

- Sample decisions + uncertainty.
- Solve subproblems with off-the-shelf solvers.



#### Evaluation on new instances

- Solve the surrogate MILP with an off-the-shelf solver.



#### Supervised Learning

- Train an NN using off-the-shelf ML packages.



### Optimization Formulation

**Objective:** Determine optimal first-stage decisions that minimize sum of the first-stage cost and expected second-stage cost.

**Challenge:** Exact optimization becomes exponentially harder with the number of observed scenarios,  $K$ . Integer decision further aggravates intractability.

#### First-Stage Problem

$$\min_{\mathbf{x}} \{ \mathbf{c}^T \mathbf{x} + \sum_{k=1}^K p_k Q(\mathbf{x}, \xi_k) : \mathbf{x} \in \mathcal{X} \}$$

First-stage decisions (blue box), Expected second-stage cost (orange box)

#### Second-Stage Problem

$$Q(\mathbf{x}, \xi) := \min_{\mathbf{y}} \{ F(\mathbf{y}, \xi) : \mathbf{y} \in \mathcal{Y}(\mathbf{x}, \xi) \}$$

Second-stage cost (blue box), Second-stage decisions (green box)

**Objective:** Determine optimal first-stage decisions that minimize the sum of the first-stage cost and worst-case cost.

**Challenge:** Solving the nested optimization problem is intractable and specialized algorithms only exists for a limited classes of problems.

#### First-Stage Problem

$$\min_{\mathbf{x}} \{ \mathbf{c}^T \mathbf{x} + Q(\mathbf{x}) : \mathbf{x} \in \mathcal{X} \}$$

First-stage decisions (blue box), Worst-case cost (orange box)

#### Second-Stage Problem

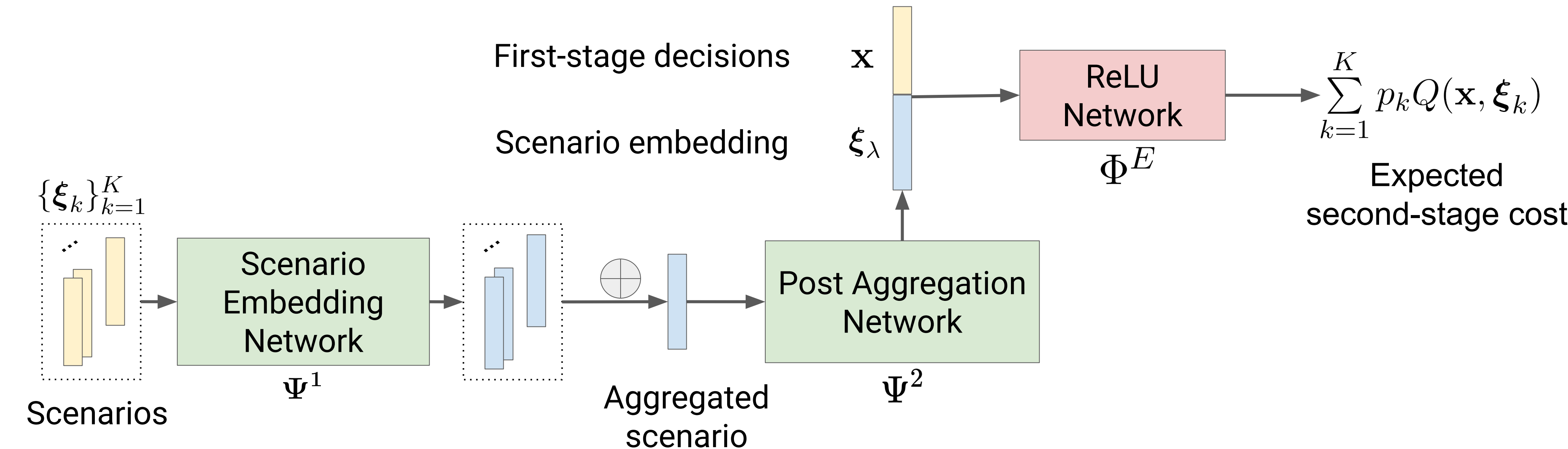
$$Q(\mathbf{x}) := \max_{\xi \in \Xi} \min_{\mathbf{y}} \{ \mathbf{d}(\xi)^T \mathbf{y} : \mathbf{y} \in \mathcal{Y}(\mathbf{x}, \xi) \}$$

Worst-case uncertainty (orange box), Second-stage cost (blue box), Second-stage decisions (green box)

### Machine Learning Methodology

**ML Solution:** Replace the expected stage-cost value function with a neural network approximation.

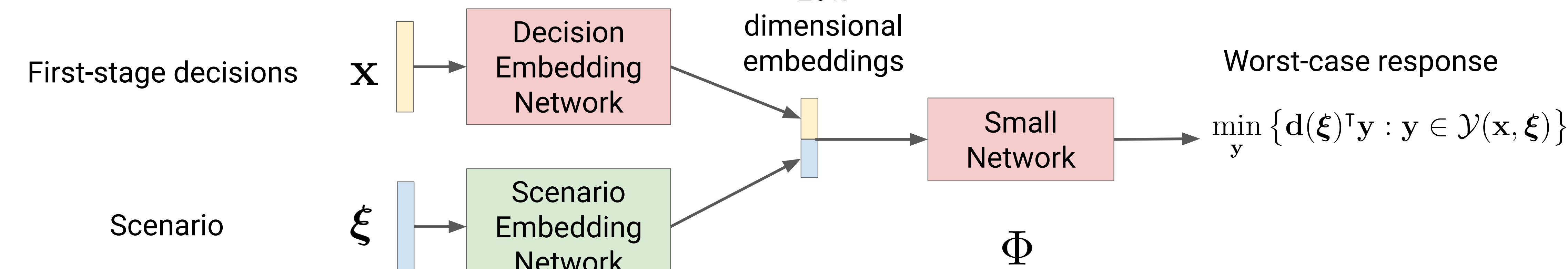
**Neural Network Architecture:**



**Surrogate Optimization Model:**  $\min_{\mathbf{x}} \{ \mathbf{c}^T \mathbf{x} + \text{NN}(\mathbf{x}, \{\xi_k\}_{k=1}^K) : \mathbf{x} \in \mathcal{X} \}$

**ML Solution:** Replace the worst-case response optimization problem with a neural network approximation.

**Neural Network Architecture:**



**Surrogate Optimization Model:**  $\min_{\mathbf{x}, \mathbf{y}, \xi_a} \{ \mathbf{c}^T \mathbf{x} + \mathbf{d}(\xi_a)^T \mathbf{y} : \mathbf{x} \in \mathcal{X}, \mathbf{y} \in \mathcal{Y}(\mathbf{x}, \xi_a), \xi_a \in \arg \max_{\xi \in \Xi} \{ \text{NN}(\mathbf{x}, \xi) \} \}$

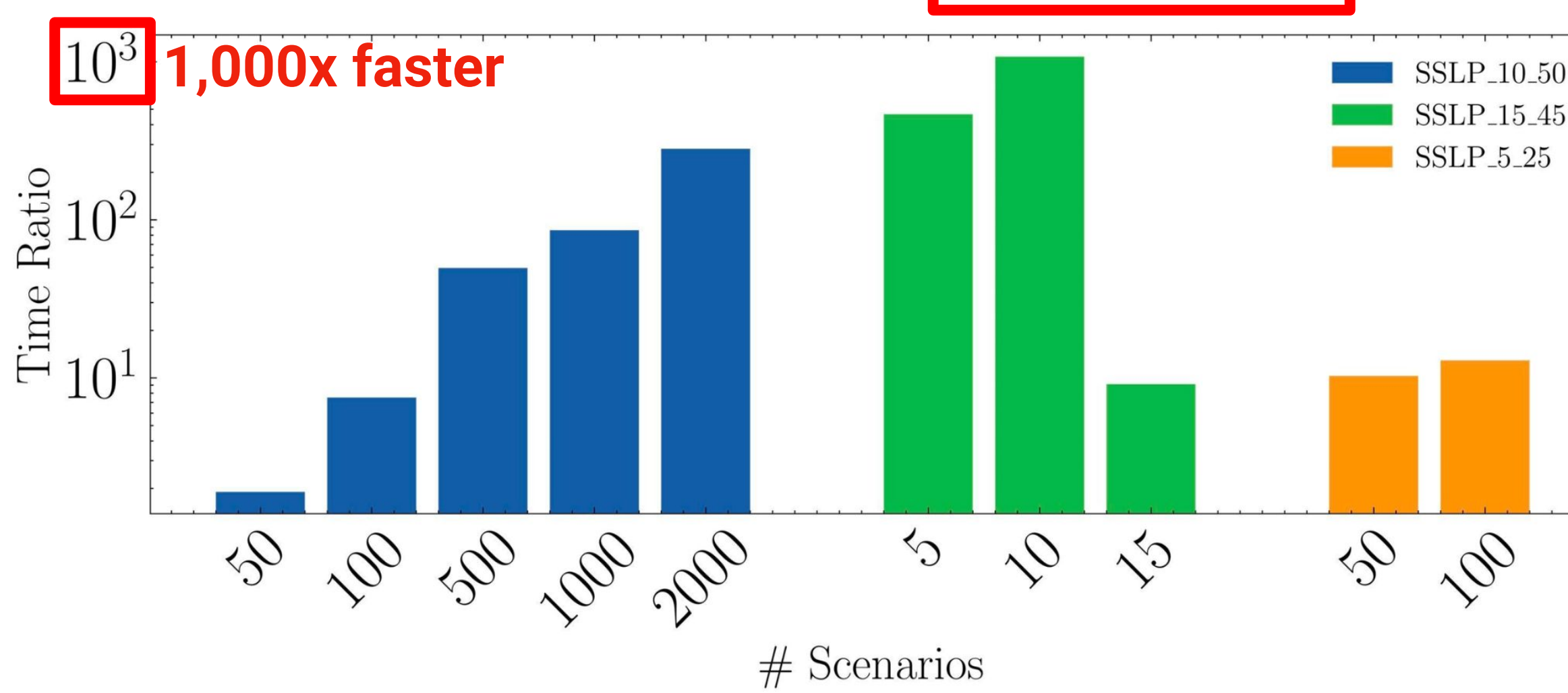
- Optimization problem solved via constraint generation of small networks.
- Worst-case scenarios determined via adversarial problem ( $\max_{\xi \in \Xi} \text{NN}(\hat{\mathbf{x}}, \xi)$ ).

### Experimental Results

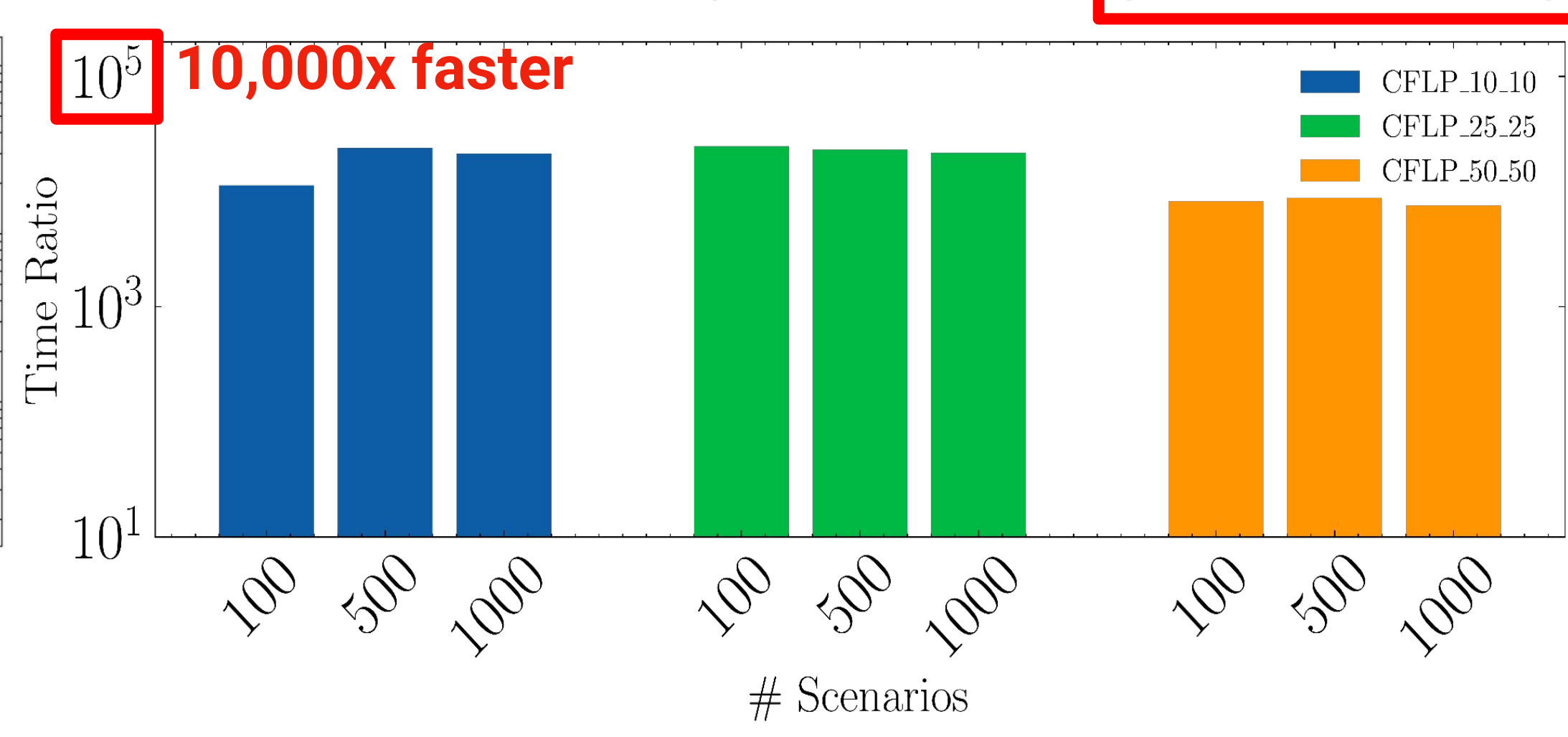
#### Stochastic Programming

Reduction factor in solving time over baseline (Integer L-shaped/EF) (higher is better).

**Stochastic Server Location** (Gap: 0.87%)



**Capacitated Facility Location** (Gap: -2.93%)

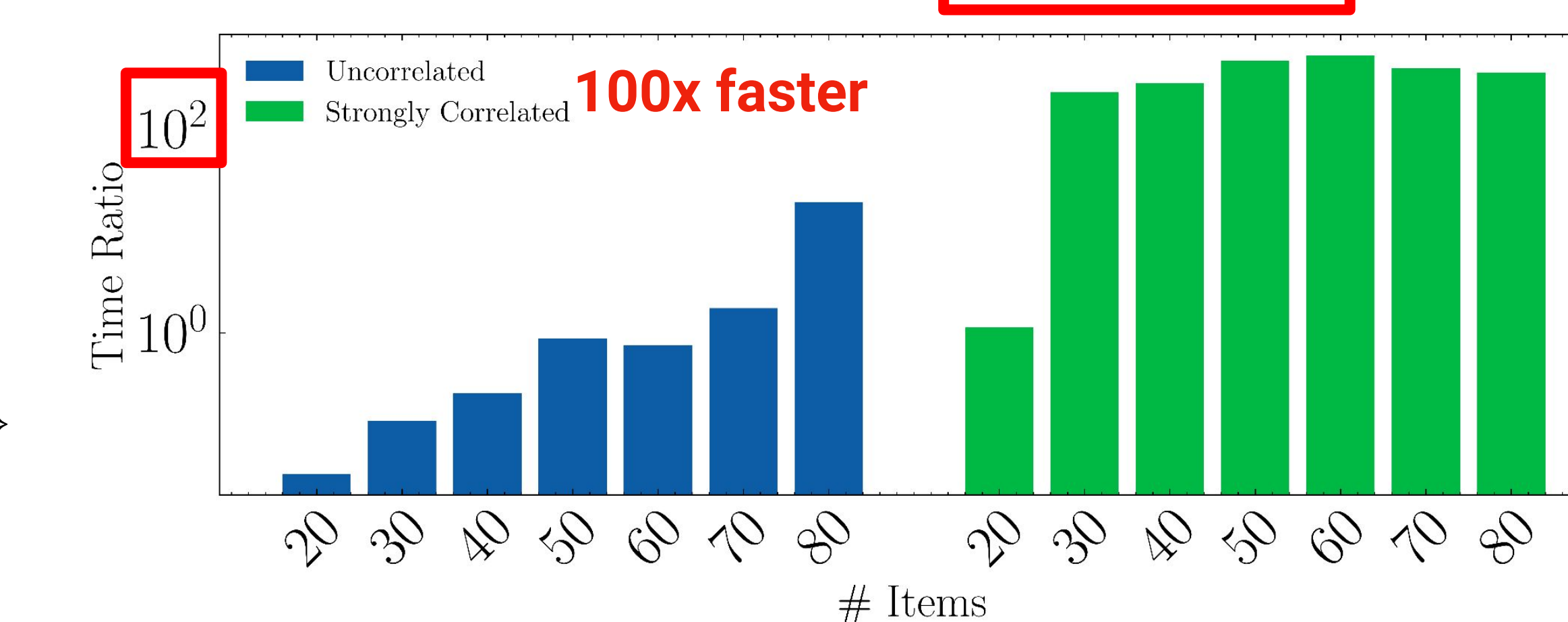


- ML finds OPT on most SSLP instances and best known solutions on most CFLP instances.

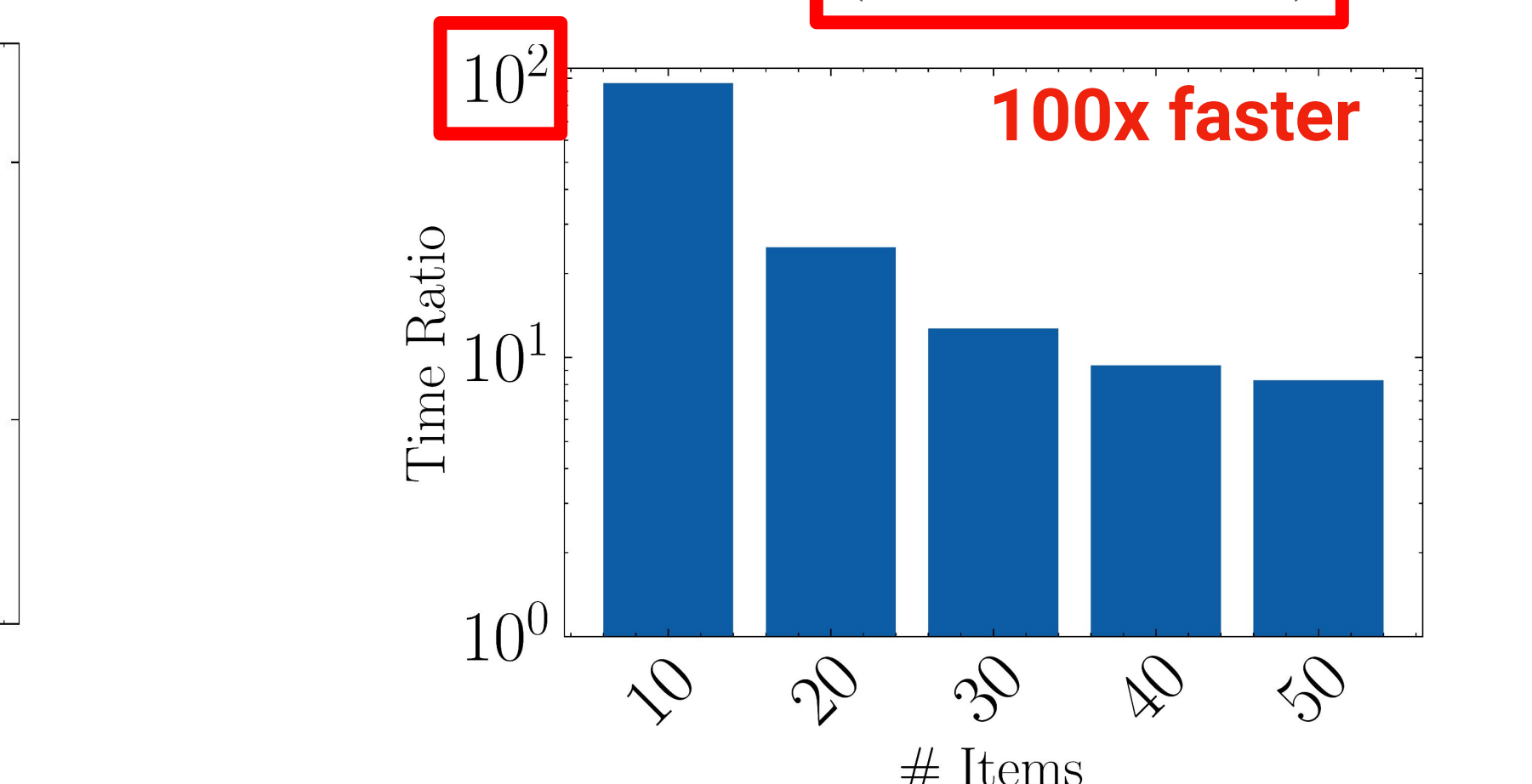
#### Robust Optimization

Reduction factor in solving time over baseline (branch-and-price/k-adaptability) (higher is better).

**Robust Knapsack Problem** (Gap: 1.30%)



**Capital Budgeting** (Gap: 0.33%)



- ML finds best solutions on difficult instances; near OPT on easy instances.

2SP



2RO



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