

INTRO to DATA SCIENCE

LECTURE 11: K-MEANS CLUSTERING

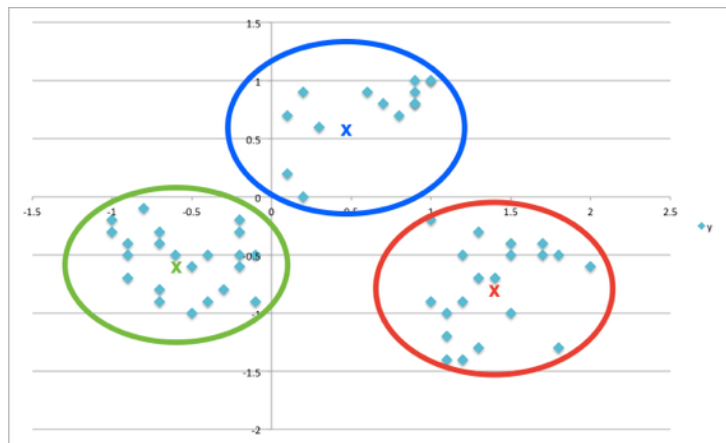
Francesco Mosconi
DAT16 SF // September 2, 2015

INTRO TO DATA SCIENCE, REGRESSION & REGULARIZATION

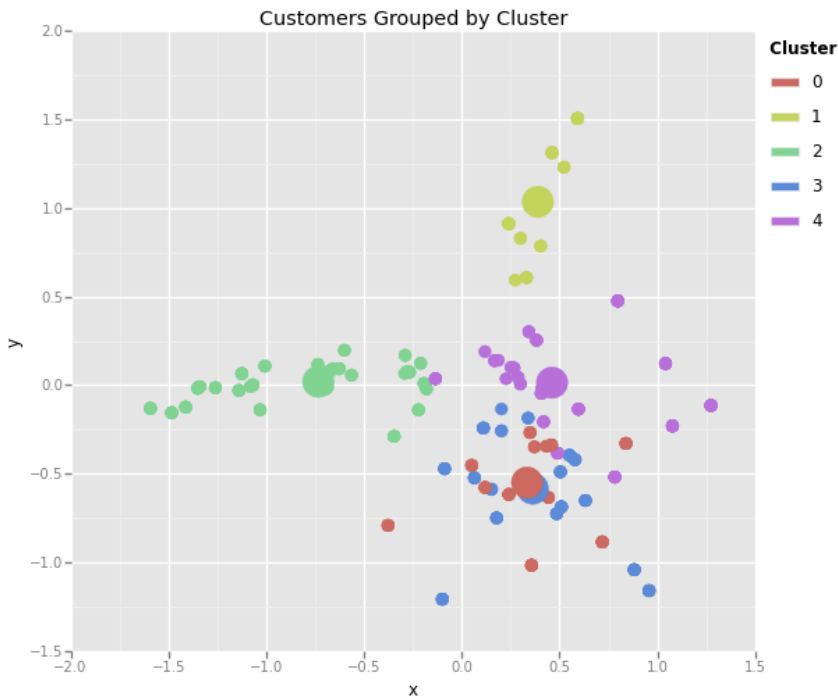
DATA SCIENCE IN THE NEWS

Customer Segmentation in Python

by Greg
August 25, 2015



<http://blog.yhathq.com/posts/customer-segmentation-using-python.html>



LAST TIME:

I. ENSEMBLE TECHNIQUES

II. PROBLEMS IN CLASSIFICATION

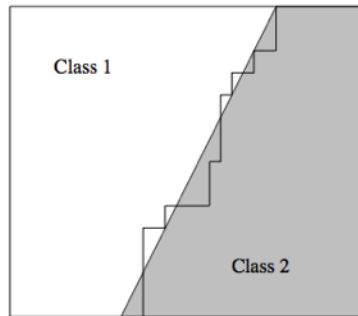
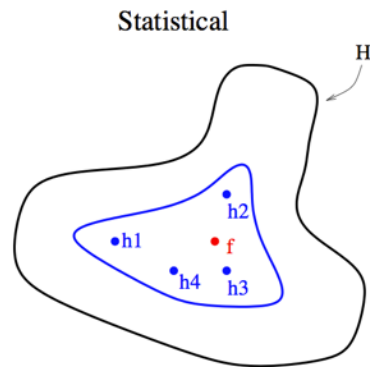
III. BAGGING

IV. BOOSTING

V. RANDOM FORESTS

EXERCISE:

VI. LAB



INTRO TO DATA SCIENCE

QUESTIONS?

WHAT WAS THE MOST INTERESTING THING YOU LEARNT?

WHAT WAS THE HARDEST TO GRASP?

AGENDA

I. CLUSTER ANALYSIS

II. K-MEANS CLUSTERING

III. CLUSTER VALIDATION

EXERCISES:

IV. K-MEANS CLUSTERING IN PYTHON

KEY OBJECTIVES

- **UNDERSTAND HOW CLUSTERING TECHNIQUES FIT IN THE GLOBAL
ML LANDSCAPE**
- **UNDERSTAND K-MEANS CLUSTERING AND BE ABLE TO USE IT IN
PYTHON**

INTRO TO DATA SCIENCE

CLUSTER ANALYSIS

	<i>Continuous</i>	<i>Categorical</i>
<i>Supervised</i>	???	???
<i>Unsupervised</i>	???	???

	<i>Continuous</i>	<i>Categorical</i>
<i>Supervised</i>	<i>regression</i>	<i>classification</i>
<i>Unsupervised</i>	<i>dimension reduction</i>	<i>clustering</i>

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<i>Supervised</i>	<i>regression</i>	<i>classification</i>
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Q: What does categorical mean in this context?

Q: What is a cluster?

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The concept of similarity is central to the definition of a cluster, and therefore to cluster analysis.

In general, greater similarity between points leads to better clustering.

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Clustering provides a layer of abstraction from individual data points.

The goal is to extract and enhance the natural structure of the data (not to impose arbitrary structure!)

Q: How do you solve a clustering problem?

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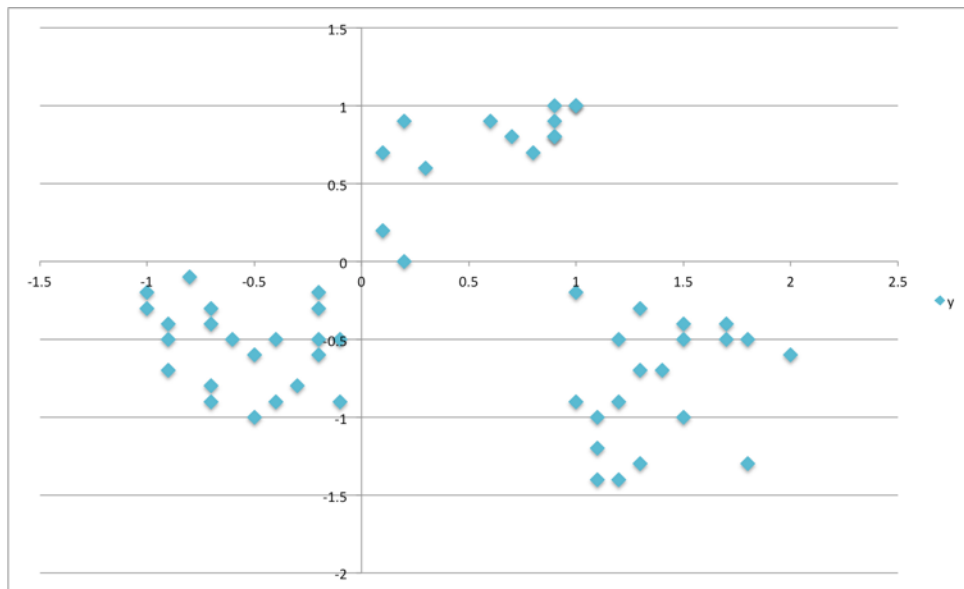
A: Think of a cluster as a “potential class”; then the solution to a clustering problem is to programmatically determine these classes.

Q: How do you solve a clustering problem?

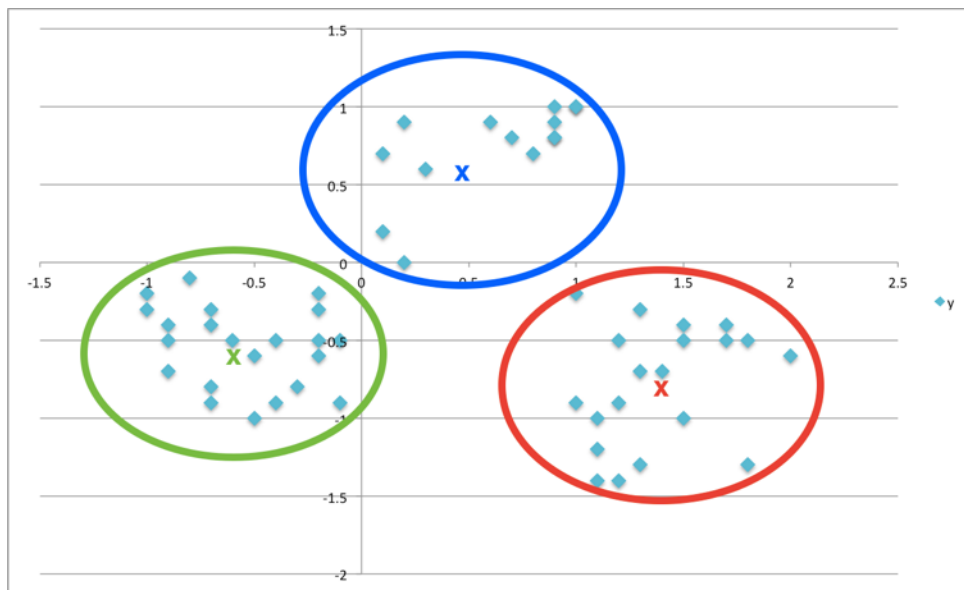
A: Think of a cluster as a “potential class”; then the solution to a clustering problem is to programmatically determine these classes.

The real purpose of clustering is data exploration, so a solution is anything that contributes to your understanding.

Quick check: how many clusters do you see?



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K-MEANS CLUSTERING

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partition – performs complete clustering (each point belongs to exactly one cluster)

Q: How are these partitions determined?

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A: Each point is assigned to the cluster with the nearest centroid.

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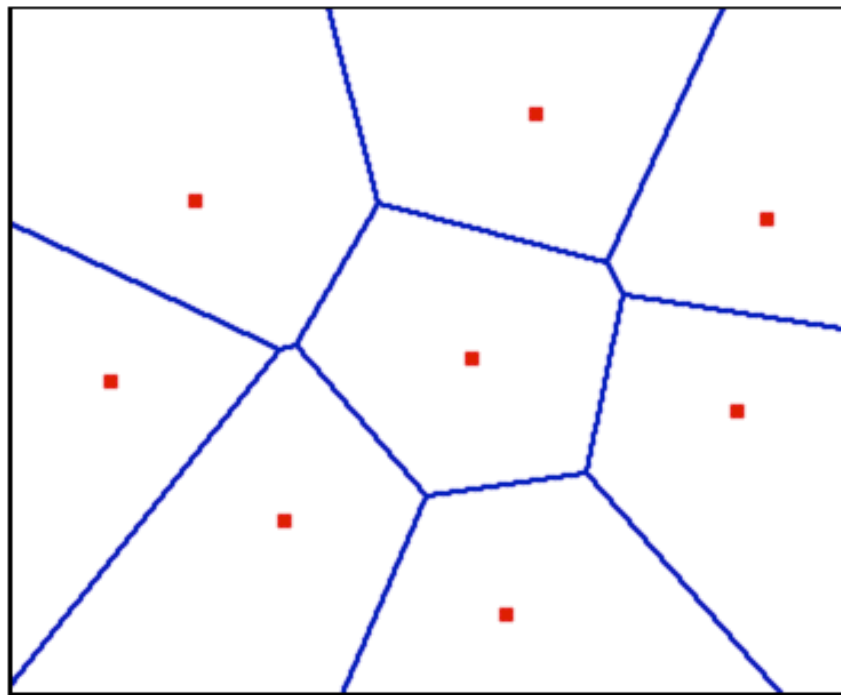
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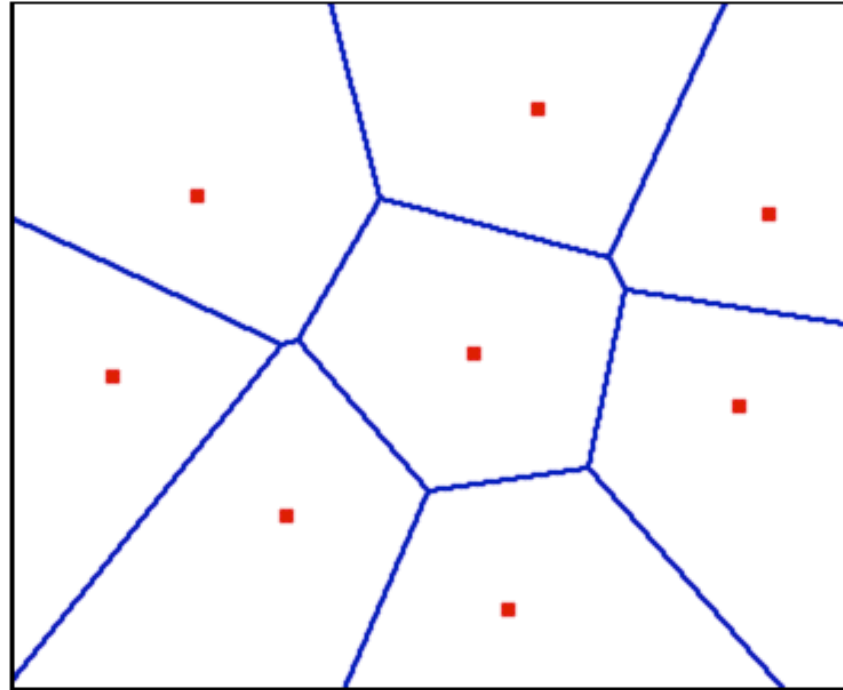
centroid – the mean of the data points in a cluster

-> requires continuous (vector-like) features

-> highlights iterative nature of algorithm

Q: What do these partitions look like?





NOTE

These partitions are sometimes called Voronoi cells, and these maps Voronoi diagrams.

One important point to keep in mind is that partitions are not scale-invariant!

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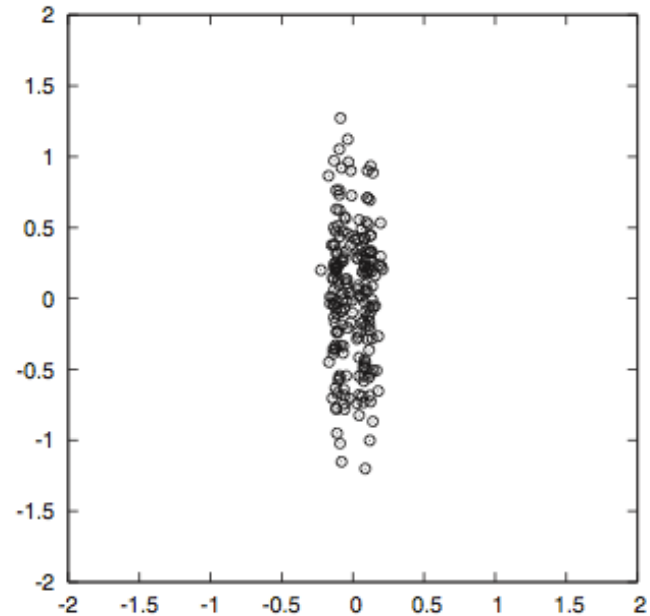
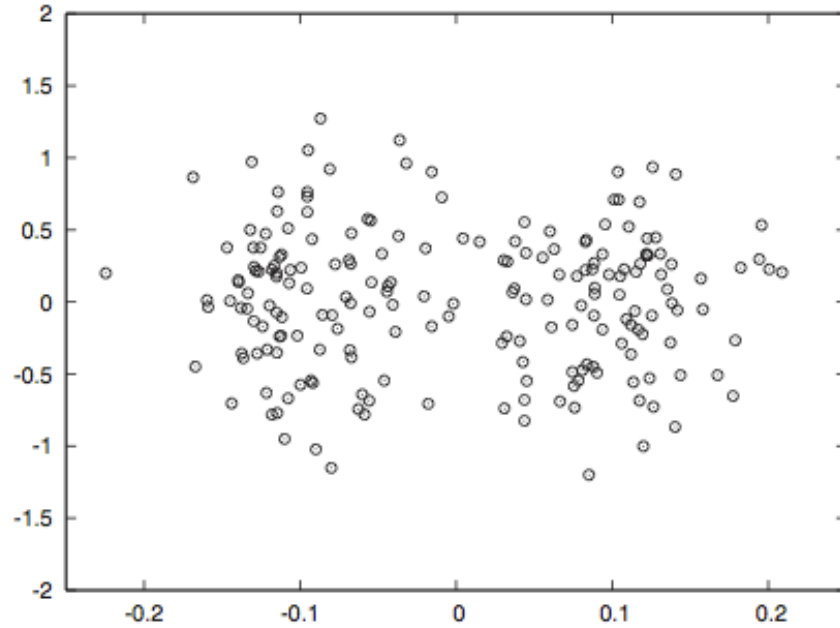
This means that the same data can yield very different clustering results depending on the scale and the units used.

Therefore it's important to think about your data representation before applying a clustering algorithm.

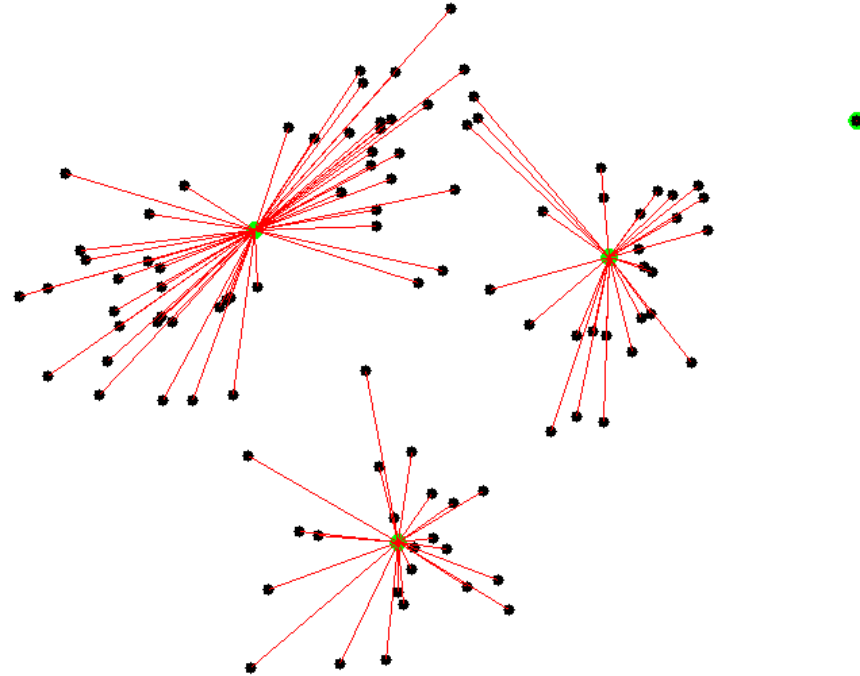
These graphs show two different representations of the same data:

SCALE DEPENDENCE

These graphs show two different representations of the same data:



- 1) *choose k initial centroids (note that k is an input)*
- 2) *for each point:*
 - *find distance to each centroid*
 - *assign point to nearest centroid*
- 3) *recalculate centroid positions*
- 4) *repeat steps 2-3 until stopping criteria met*



<http://shabal.in/visuals/kmeans/2.html>

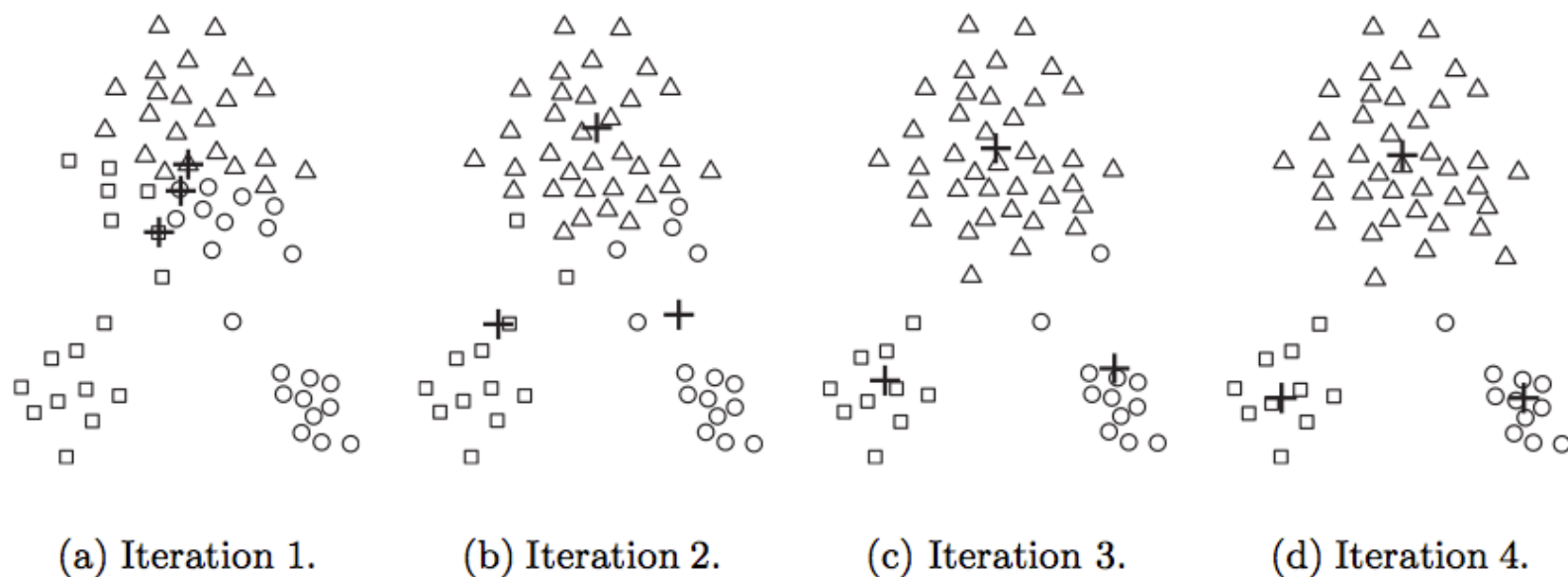


Figure 8.3. Using the K-means algorithm to find three clusters in sample data.

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Difficulties can sometimes be overcome by increasing the value of k and combining subclusters in a post-processing step.

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- perform alternative clustering task, use resulting centroids as initial k-means centroids*
- start with global centroid, choose point at max distance, repeat (but might select outlier)*

Q: How do you determine which centroid is the nearest?

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NOTE

Technically, by defining a similarity measure we are mapping our observations into a metric space.

A similarity measure must satisfy certain general conditions:

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$$d(x, y) \geq 0$$

$$d(x, y) = 0 \iff x = y$$

$$d(x, y) = d(y, x)$$

$$d(x, y) + d(y, z) \geq d(x, z)$$

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NOTE

Another useful property is smoothness.

There are a number of different similarity measures to choose from, and in general the right choice depends on the problem.

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We can express different semantics about our data through the choice of metric.

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$$J(A, B) = \frac{|A \cap B|}{|A \cup B|}$$

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Applying this metric to a problem expresses the sparse nature of the data, and makes a variety of text mining techniques accessible.

The matrix whose entries D_{ij} contain the values $d(x, y)$ for all x and y is called the distance matrix.

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For this reason, it's really the choice of metric that determines the definition of a cluster.

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A: By optimizing an objective function that tells us how “good” the clustering is.

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The iterative part of the algorithm (recomputing centroids and reassigning points to clusters) explicitly tries to minimize this objective function.

Ex: Using the Euclidean distance measure, one typical objective function is the sum of squared errors from each point x to its centroid c_i :

$$SSE = \sum_{i=1}^K \sum_{x \in C_i} d(x, c_i)^2$$

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Given two clusterings, we will prefer the one with the lower SSE since this means the centroids have converged to better locations (a better local optimum).

We iterate until some stopping criteria are met; in general, suitable convergence is achieved in a small number of steps.

STEP 4 – CONVERGENCE

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Stopping criteria can be based on the centroids (eg, if positions change by no more than ε) or on the points (eg, if no more than x% change clusters between iterations).

Recall that, in general, different runs of the algorithm will converge to different local optima (centroid configurations).

quick check:

alone: find 3 business-related problems where you could apply clustering

with the person next to you: discuss which of these are suitable for k-means and why

CLUSTER VALIDATION

In general, k -means will converge to a solution and return a partition of k clusters, even if no natural clusters exist in the data.

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We will look at two validation metrics useful for partitional clustering, cohesion and separation.

Cohesion measures clustering effectiveness within a cluster.

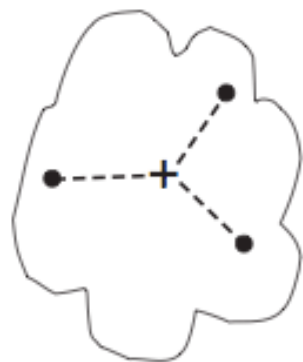
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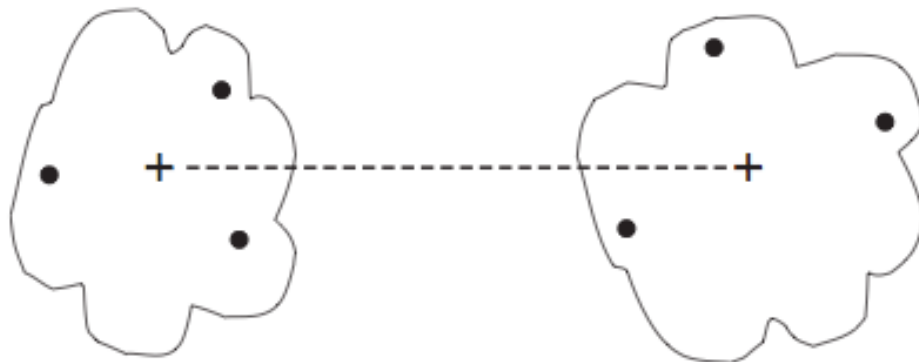
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Separation measures clustering effectiveness between clusters.

$$\hat{S}(C_i, C_j) = d(c_i, c_j)$$



(a) Cohesion.



(b) Separation.

Figure 8.28. Prototype-based view of cluster cohesion and separation.

We can turn these values into overall measures of clustering validity by taking a weighted sum over clusters:

$$\hat{V}_{total} = \sum_1^K w_i \hat{V}(C_i)$$

Here V can be cohesion, separation, or some function of both.

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The weights can all be set to 1 (best for k-means), or proportional to the cluster masses (the number of points they contain).

Cluster validation measures can be used to identify clusters that should be split or merged, or to identify individual points with disproportionate effect on the overall clustering.

One useful measure than combines the ideas of cohesion and separation is the silhouette coefficient. For point x_i , this is given by:

$$SC_i = \frac{b_i - a_i}{\max(a_i, b_i)}$$

such that:

a_i = average in-cluster distance to x_i

b_{ij} = average between-cluster distance to x_i

$b_i = \min_j(b_{ij})$

The silhouette coefficient can take values between -1 and 1.

In general, we want separation to be high and cohesion to be low. This corresponds to a value of SC close to +1.

A negative silhouette coefficient means the cluster radius is larger than the space between clusters, and thus clusters overlap.

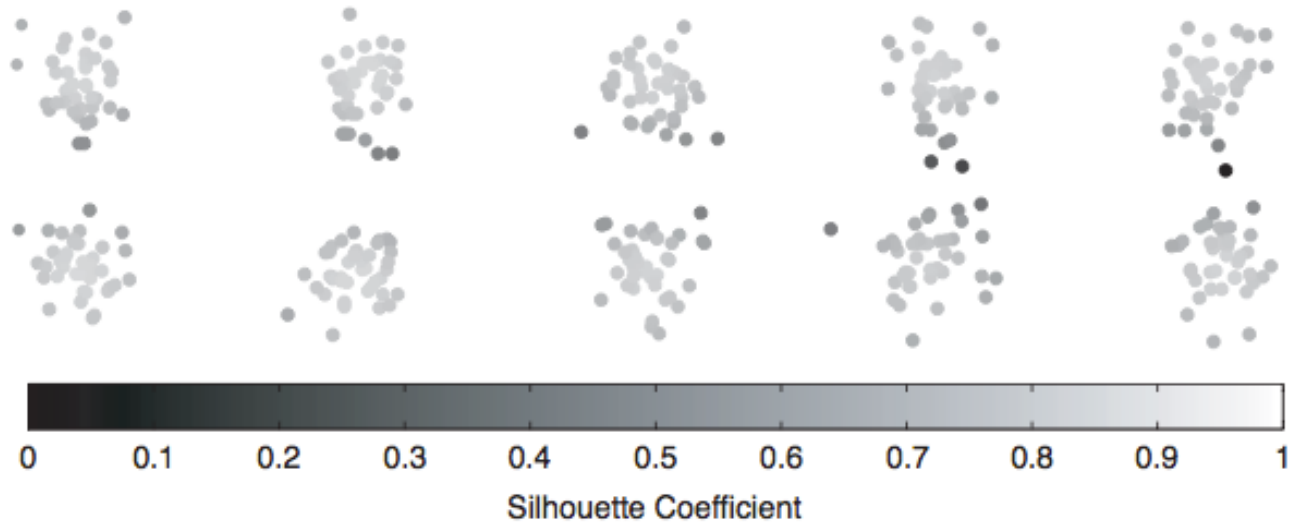


Figure 8.29. Silhouette coefficients for points in ten clusters.

The silhouette coefficient for the cluster C_i is given by the average silhouette coefficient across all points in C_i :

$$SC(C_i) = \frac{1}{m_i} \sum_{x \in C_i} SC_i$$

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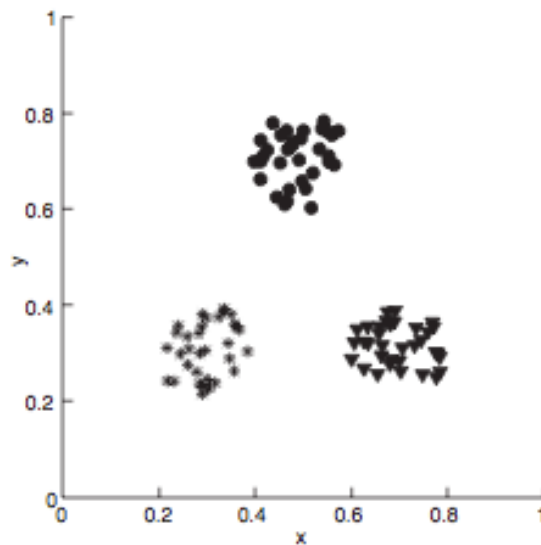
NOTE

This gives a summary measure of the overall clustering quality.

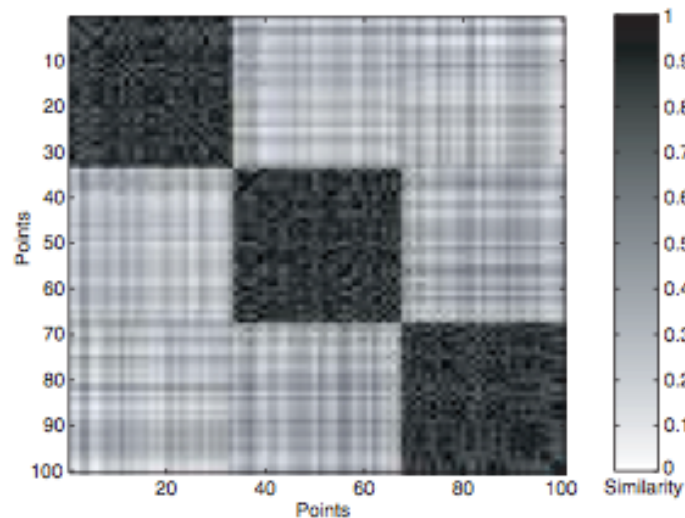
An alternative validation scheme is given by comparing the similarity matrix with an idealized (0/1) similarity matrix that represents the same clustering configuration.

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This can be done either graphically or using correlations.



(a) Well-separated clusters.



(b) Similarity matrix sorted by K-means cluster labels.

One useful application of cluster validation is to determine the best number of clusters for your dataset.

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Q: How would you do this?

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Q: How would you do this?

A: By computing the overall SSE or SC for different values of k .

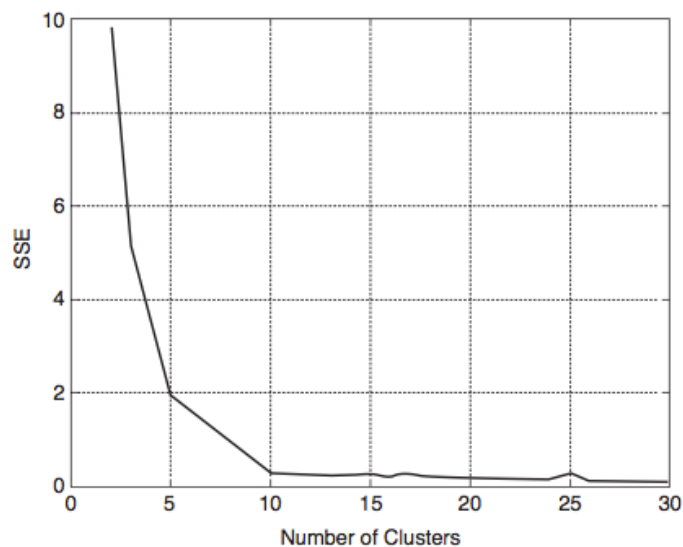


Figure 8.32. SSE versus number of clusters for the data of Figure 8.29.

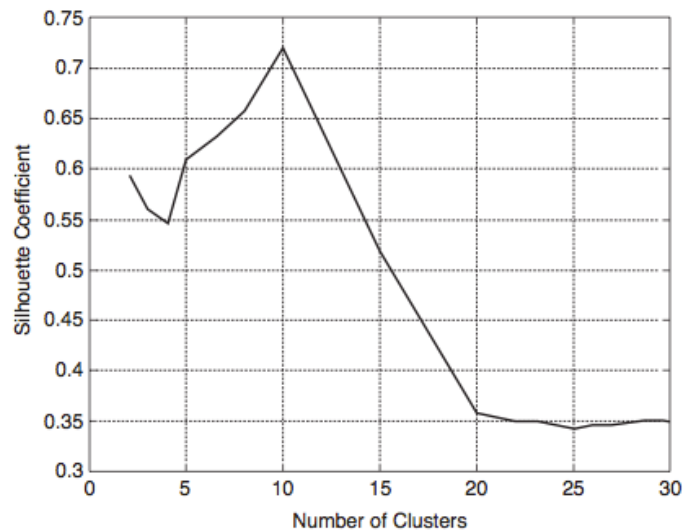


Figure 8.33. Average silhouette coefficient versus number of clusters for the data of Figure 8.29.

Q: How can you determine your level of confidence in these validation metrics?

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A: Statistically; eg, by computing frequency distributions for these metrics (over several runs of the algorithm) and determining statistical significance.

Ultimately, cluster validation and clustering in general are suggestive techniques that rely on human interpretation to be meaningful.

quick check:

*what is the silhouette coefficient?
(in your own words)*

EX: K-MEANS CLUSTERING