UPLB Eliens - Pegaraw Notebook

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1 Data Structures

1.1 Disjoint Set Union

```
struct DSU {
        vector<int> parent, size;
        DSU(int n) {
          parent.resize(n);
           size.resize(n);
          for (int i = 0; i < n; i++) make_set(i);</pre>
         void make set(int v) {
          parent[v] = v:
           size[v] = 1;
2
  12
         bool is_same(int a, int b) { return find_set(a)
             == find set(b); }
         int find_set(int v) { return v == parent[v] ? v :
              parent[v] = find_set(parent[v]); }
3
         void union_sets(int a, int b) {
         a = find_set(a);
          b = find set(b);
          if (a != b) {
            if (size[a] < size[b]) swap(a, b);</pre>
             parent[b] = a;
             size[a] += size[b];
  23 };
```

1.2 Minimum Queue

```
1 11 get_minimum(stack<pair<11, 11>> &s1, stack<pair<</pre>
           11, 11>> &s2) {
         if (s1.empty() || s2.empty()) {
           return s1.empty() ? s2.top().second : s1.top().
               second:
           return min(s1.top().second, s2.top().second);
   8 void add_element(ll new_element, stack<pair<ll, ll</pre>
           >> &s1) {
         11 minimum = s1.empty() ? new_element : min(
             new_element, s1.top().second);
  10
         s1.push({new_element, minimum});
  12 11 remove_element(stack<pair<11, 11>> &s1, stack<
            pair<11, 11>> &s2) {
8
         if (s2.empty()) {
           while (!sl.empty()) {
            11 element = s1.top().first;
             s1.pop();
             11 minimum = s2.empty() ? element : min(
                 element, s2.top().second);
  18
             s2.push({element, minimum});
  19
9
         11 removed_element = s2.top().first;
         s2.pop();
10
         return removed_element;
10
```

1.3 Range Add Point Query

```
template<typename T, typename InType = T>
    class SegTreeNode {
    public:
      const T IDN = 0, DEF = 0;
      int i, j;
      T val;
      SegTreeNode<T, InType>* lc, * rc;
      SegTreeNode(int i, int j) : i(i), j(j) {
       if (j - i == 1) {
         lc = rc = nullptr;
          val = DEF;
          return:
        int k = (i + j) / 2;
        lc = new SegTreeNode<T, InType>(i, k);
        rc = new SegTreeNode<T, InType>(k, j);
        val = 0:
      SegTreeNode(const vector<InType>& a, int i, int j
          ) : i(i), j(j) {
        if (i - i == 1) {
         lc = rc = nullptr;
         val = (T) a[i];
          return;
        int k = (i + j) / 2;
        lc = new SegTreeNode<T, InType>(a, i, k);
        rc = new SegTreeNode<T, InType>(a, k, j);
        val = 0;
      void range_add(int 1, int r, T x) {
       if (r <= i || j <= 1) return;</pre>
        if (1 <= i && j <= r) {
         val += x;
          return;
        lc->range_add(1, r, x);
        rc->range_add(1, r, x);
38
39
      T point_query(int k) {
       if (k < i || j <= k) return IDN;</pre>
        if (j - i == 1) return val;
        return val + lc->point_query(k) + rc->
             point_query(k);
44
    template<typename T, typename InType = T>
    class SegTree {
   public:
     SegTreeNode<T, InType> root;
      SegTree(int n) : root(0, n) {}
     SegTree(const vector<InType>& a) : root(a, 0, a.
          size()) {}
      void range_add(int 1, int r, T x) { root.
           range add(1, r, x); }
      T point_query(int k) { return root.point_query(k)
53 };
```

1.4 Range Add Range Query

```
1 template<typename T, typename InType = T>
2 class SegTreeNode {
3 public:
```

```
const T IDN = 0, DEF = 0;
      int i, j;
      T val, to_add = 0;
      SegTreeNode<T, InType>* lc, * rc;
      SegTreeNode(int i, int j) : i(i), j(j) {
        if (j - i == 1) {
          lc = rc = nullptr;
11
          val = DEF;
          return;
13
        int k = (i + j) / 2;
15
        lc = new SegTreeNode<T, InType>(i, k);
         rc = new SegTreeNode<T, InType>(k, j);
17
        val = operation(lc->val, rc->val);
18
19
      SegTreeNode(const vector<InType>& a, int i, int j
           ) : i(i), j(j) {
        if (j - i == 1) {
21
          lc = rc = nullptr;
          val = (T) a[i];
23
          return;
24
         int k = (i + j) / 2;
26
        lc = new SegTreeNode<T, InType>(a, i, k);
27
         rc = new SegTreeNode<T, InType>(a, k, j);
28
        val = operation(lc->val, rc->val);
29
      void propagate() {
31
        if (to_add == 0) return;
32
        val += to_add;
        if (i - i > 1) {
         lc->to_add += to_add;
35
          rc->to_add += to_add;
36
        to\_add = 0;
38
39
      void range_add(int 1, int r, T delta) {
40
        propagate();
41
        if (r <= i || j <= 1) return;</pre>
42
        if (1 <= i && j <= r) {</pre>
43
          to add += delta;
          propagate();
44
45
         } else {
46
          lc->range_add(l, r, delta);
47
          rc->range add(1, r, delta);
48
          val = operation(lc->val, rc->val);
49
51
      T range_query(int 1, int r) {
52
        propagate();
        if (1 <= i && j <= r) return val;</pre>
54
        if (j <= l || r <= i) return IDN;</pre>
         return operation(lc->range_query(l, r), rc->
             range_query(1, r));
56
      T operation(T x, T y) {}
58 };
59 template<typename T, typename InType = T>
60 class SegTree {
61 public:
62
      SegTreeNode<T, InType> root;
63
      SegTree(int n) : root(0, n) {}
64
      SegTree(const vector<InType>& a) : root(a, 0, a.
           size()) {}
      void range_add(int 1, int r, T delta) { root.
           range_add(l, r, delta); }
66
      T range_query(int 1, int r) { return root.
           range_query(1, r); }
67 };
```

```
1.5 Segment Tree
    template<typename T, typename InType = T>
    class SegTreeNode {
    public:
      const T IDN = 0, DEF = 0;
      int i, j;
      T val:
      SegTreeNode<T, InType>* lc, * rc;
      SeqTreeNode(int i, int j) : i(i), j(j) {
        if (i - i == 1) {
          lc = rc = nullptr;
          val = DEF;
          return;
        int k = (i + j) / 2;
        lc = new SegTreeNode<T, InType>(i, k);
        rc = new SegTreeNode<T, InType>(k, j);
        val = op(lc->val, rc->val);
18
19
      SegTreeNode(const vector<InType>& a, int i, int j
           ) : i(i), j(j) {
        if (j - i == 1) {
          lc = rc = nullptr;
          val = (T) a[i];
          return;
        int k = (i + j) / 2;
        lc = new SegTreeNode<T, InType>(a, i, k);
        rc = new SegTreeNode<T, InType>(a, k, j);
        val = op(lc->val, rc->val);
29
30
      void set(int k, T x) {
        if (k < i | | j <= k) return;</pre>
        if (j - i == 1) {
          val = x;
34
          return:
        1c->set(k, x);
        rc \rightarrow set(k, x);
38
        val = op(lc->val, rc->val);
39
      T range_query(int 1, int r) {
        if (1 <= i && j <= r) return val;</pre>
        if (j <= 1 || r <= i) return IDN;</pre>
        return op(lc->range_query(l, r), rc->
             range_query(1, r));
45
      T \circ p(T \times, T y) \{ \}
46
    };
    template<typename T, typename InType = T>
    class SegTree {
49
    public:
50
      SegTreeNode<T, InType> root;
      SegTree(int n) : root(0, n) {}
      SegTree(const vector<InType>& a) : root(a, 0, a.
53
      void set(int k, T x) { root.set(k, x); }
      T range_query(int 1, int r) { return root.
           range_query(1, r); }
 1.6 Sparse Table
```

11 log2_floor(ll i) {

```
return i ? __builtin_clzll(1) - __builtin_clzll(i
3
   vector<vector<ll>> build_sum(ll N, ll K, vector<ll>
      vector<vector<ll>> st(K + 1, vector<ll>(N + 1));
      for (ll i = 0; i < N; i++) st[0][i] = array[i];</pre>
      for (ll i = 1; i <= K; i++)</pre>
        for (11 j = 0; j + (1 << i) <= N; <math>j++)
          st[i][j] = st[i - 1][j] + st[i - 1][j + (1 <<
                (i - 1))];
12
   11 sum_query(11 L, 11 R, 11 K, vector<vector<11>>> &
         st) {
      11 sum = 0;
      for (11 i = K; i >= 0; i--) {
       if ((1 << i) <= R - L + 1) {
          sum += st[i][L];
          L += 1 << i;
      return sum;
    vector<vector<ll>> build_min(ll N, ll K, vector<ll>
      vector<vector<ll>> st(K + 1, vector<ll>(N + 1));
      for (11 i = 0; i < N; i++) st[0][i] = array[i];</pre>
      for (11 i = 1; i <= K; i++)</pre>
26
        for (11 j = 0; j + (1 << i) <= N; <math>j++)
          st[i][j] = min(st[i-1][j], st[i-1][j+(1
                << (i - 1));
28
      return st;
29
    11 min_query(ll L, ll R, vector<vector<ll>>> &st) {
      ll i = log2\_floor(R - L + 1);
      return min(st[i][L], st[i][R - (1 << i) + 1]);</pre>
33 }
```

2 Dynamic Programming

2.1 Divide And Conquer

```
1 11 m, n;
    vector<ll> dp_before(n), dp_cur(n);
    11 C(11 i, 11 j);
    void compute(ll 1, ll r, ll optl, ll optr) {
      if (1 > r) {
        return:
      11 \text{ mid} = (1 + r) >> 1;
      pair<11, 11> best = {LLONG_MAX, -1};
      for (ll k = optl; k <= min(mid, optr); k++) {</pre>
        best = min(best, \{(k ? dp\_before[k - 1] : 0) +
             C(k, mid), k});
      dp_cur[mid] = best.first;
      11 opt = best.second;
      compute(l, mid - 1, optl, opt);
      compute(mid + 1, r, opt, optr);
17
    ll solve() {
      for (11 i = 0; i < n; i++) {
20
        dp\_before[i] = C(0, i);
21
      for (11 i = 1; i < m; i++) {
```

2.2 Edit Distance

```
1  ll edit_distance(string x, string y, ll n, ll m) {
       vector<vector<int>> dp(n + 1, vector<int>(m + 1,
            INF));
      dp[0][0] = 0;
       for (int i = 1; i <= n; i++) {</pre>
        dp[i][0] = i;
      for (int j = 1; j \le m; j++) {
        dp[0][j] = j;
10
      for (int i = 1; i <= n; i++) {</pre>
11
         for (int j = 1; j \le m; j++) {
          dp[i][j] = min({dp[i-1][j] + 1, dp[i][j-1]}
               1] + 1, dp[i - 1][j - 1] + (x[i - 1] !=
               y[j - 1])));
13
14
      return dp[n][m];
16 }
```

2.3 Knapsack

2.4 Knuth Optimization

```
1 11 solve() {
       // read N and input
       vector<vector<ll>> dp(N, vector<ll>(N)), opt(N,
            vector<11>(N));
       auto C = [&](ll i, ll j) {
        // Implement cost function C.
       for (11 i = 0; i < N; i++) {</pre>
9
         opt[i][i] = i;
         ... // Initialize dp[i][i] according to the
              problem
11
       for (11 i = N - 2; i >= 0; i--) {
13
         for (11 j = i + 1; j < N; j++) {
14
           11 \text{ mn} = 11\_\text{MAX}, \text{ cost} = C(i, j);
```

2.5 Longest Common Subsequence

```
11 LCS(string x, string y, 11 n, 11 m) {
      vector < vector < 11 >> dp(n + 1, vector < 11 > (m + 1));
      for (ll i = 0; i <= n; i++) {
        for (11 j = 0; j \le m; j++) {
          if (i == 0 || j == 0) {
            dp[i][j] = 0;
           } else if (x[i - 1] == y[j - 1]) {
            dp[i][j] = dp[i - 1][j - 1] + 1;
            dp[i][j] = max(dp[i - 1][j], dp[i][j - 1]);
      11 \text{ index} = dp[n][m];
      vector<char> lcs(index + 1);
      lcs[index] = ' \setminus 0';
      11 i = n, j = m;
      while (i > 0 \&\& j > 0) {
        if (x[i-1] == y[j-1]) {
           lcs[index - 1] = x[i - 1];
          i--;
           j--;
           index--;
         } else if (dp[i - 1][j] > dp[i][j - 1]) {
        } else {
           j--;
28
2.9
30
      return dp[n][m];
```

2.6 Longest Increasing Subsequence

```
1  ll get_ceil_idx(vector<ll> &a, vector<ll> &T, ll l,
          11 r, 11 x) {
      while (r - 1 > 1) {
        11 m = 1 + (r - 1) / 2;
        if (a[T[m]] >= x) {
         r = m:
        } else {
          1 = m;
 8
 9
10
      return r;
11
   11 LIS(11 n, vector<11> &a) {
13
      11 len = 1;
      vector<11> T(n, 0), R(n, -1);
      T[0] = 0;
```

2.7 Subset Sum

3 Geometry

3.1 Circle Line Intersection

```
double r, a, b, c; // given as input
    double x0 = -a * c / (a * a + b * b);
    double y0 = -b * c / (a * a + b * b);
   if (c * c > r * r * (a * a + b * b) + EPS) {
      puts ("no points");
    } else if (abs (c *c - r * r * (a * a + b * b)) <</pre>
        EPS) {
      puts ("1 point");
      cout << x0 << ' ' << y0 << '\n';
    } else {
      double d = r * r - c * c / (a * a + b * b);
      double mult = sqrt (d / (a * a + b * b));
      double ax, ay, bx, by;
      ax = x0 + b * mult;
     bx = x0 - b * mult;
     ay = y0 - a * mult;
     by = y0 + a * mult;
      puts ("2 points");
      cout << ax << ' ' << ay << '\n' << bx << ' ' <<
          by << '\n';</pre>
19 }
```

3.2 Convex Hull

```
struct pt {
      double x, y;
    11 orientation(pt a, pt b, pt c) {
      double v = a.x * (b.y - c.y) + b.x * (c.y - a.y)
           + c.x * (a.y - b.y);
      if (v < 0) {
        return -1:
      } else if (v > 0) {
        return +1;
      return 0;
12
13
    bool cw(pt a, pt b, pt c, bool include_collinear) {
      11 o = orientation(a, b, c);
      return o < 0 || (include_collinear && o == 0);</pre>
16
17
    bool collinear(pt a, pt b, pt c) {
18
      return orientation(a, b, c) == 0;
19
    void convex_hull(vector<pt>& a, bool
         include_collinear = false) {
      pt p0 = *min_element(a.begin(), a.end(), [](pt a,
        return make_pair(a.y, a.x) < make_pair(b.y, b.x
24
      sort(a.begin(), a.end(), [&p0](const pt& a, const
            pt& b) {
        11 o = orientation(p0, a, b);
26
        if (o == 0) {
          return (p0.x - a.x) * (p0.x - a.x) + (p0.y - a.x)
               a.y) * (p0.y - a.y)
               < (p0.x - b.x) * (p0.x - b.x) + (p0.y -
                    b.y) * (p0.y - b.y);
29
        return o < 0;
31
      });
      if (include collinear) {
        11 i = (11) a.size()-1;
34
        while (i \geq= 0 && collinear(p0, a[i], a.back()))
              i--;
        reverse(a.begin()+i+1, a.end());
      vector<pt> st;
38
      for (ll i = 0; i < (ll) a.size(); i++) {</pre>
39
        while (st.size() > 1 && !cw(st[st.size() - 2],
             st.back(), a[i], include_collinear)) {
40
          st.pop_back();
41
42
        st.push_back(a[i]);
43
      }
44
      a = st;
45 }
```

18

38

40

45

49

54

56

57 58

60

63

66

3.3 Line Sweep

```
return p.y + (q.y - p.y) * (x - p.x) / (q.x - p
         .x);
};
bool intersect1d(double 11, double r1, double 12,
     double r2) {
  if (11 > r1) {
    swap(11, r1);
  if (12 > r2) {
    swap(12, r2);
  return max(11, 12) <= min(r1, r2) + EPS;</pre>
11 vec (const pt& a, const pt& b, const pt& c) {
  double s = (b.x - a.x) * (c.y - a.y) - (b.y - a.y)
      ) \star (c.x - a.x);
  return abs(s) < EPS ? 0 : s > 0 ? +1 : -1;
bool intersect(const seg& a, const seg& b) {
  return intersect1d(a.p.x, a.q.x, b.p.x, b.q.x) &&
          intersect1d(a.p.y, a.q.y, b.p.y, b.q.y) &&
          vec(a.p, a.q, b.p) * vec(a.p, a.q, b.q) <=
                330
          vec(b.p, b.q, a.p) * vec(b.p, b.q, a.q) <=
                0;
bool operator<(const seg& a, const seg& b) {</pre>
    double x = max(min(a.p.x, a.q.x), min(b.p.x, b.
         q.x));
    return a.get_y(x) < b.get_y(x) - EPS;</pre>
struct event {
  double x;
  11 tp, id;
  event() {}
  event (double x, 11 tp, 11 id) : x(x), tp(tp), id(
       id) {}
  bool operator<(const event& e) const {</pre>
    if (abs(x - e.x) > EPS) {
       return x < e.x;
    return tp > e.tp;
};
set<seg> s;
vector<set<seq>::iterator> where;
set<seg>::iterator prev(set<seg>::iterator it) {
  return it == s.begin() ? s.end() : --it;
set<seg>::iterator next(set<seg>::iterator it) {
  return ++it;
pair<11, 11> solve(const vector<seg>& a) {
  11 n = (11) a.size();
  vector<event> e;
  for (11 i = 0; i < n; ++i) {
    e.push_back(event(min(a[i].p.x, a[i].q.x), +1,
    e.push_back(event(max(a[i].p.x, a[i].q.x), -1,
         i));
  sort(e.begin(), e.end());
  s.clear():
  where.resize(a.size());
  for (size_t i = 0; i < e.size(); ++i) {</pre>
    11 id = e[i].id;
    if (e[i].tp == +1) {
```

```
set<seg>::iterator nxt = s.lower_bound(a[id])
               , prv = prev(nxt);
          if (nxt != s.end() && intersect(*nxt, a[id]))
            return make_pair(nxt->id, id);
7.5
          if (prv != s.end() && intersect(*prv, a[id]))
            return make_pair(prv->id, id);
78
          where[id] = s.insert(nxt, a[id]);
79
          set<seg>::iterator nxt = next(where[id]), prv
                = prev(where[id]);
          if (nxt != s.end() && prv != s.end() &&
              intersect(*nxt, *prv)) {
            return make_pair(prv->id, nxt->id);
          s.erase(where[id]);
      return make_pair(-1, -1);
```

3.4 Nearest Points

```
struct pt {
     ll x, y, id;
3 };
    struct cmp_x {
     bool operator()(const pt & a, const pt & b) const
        return a.x < b.x || (a.x == b.x && a.y < b.y);
    };
    struct cmp_y {
      bool operator()(const pt & a, const pt & b) const
        return a.y < b.y;</pre>
1.3
   };
   11 n;
   vector<pt> a;
    double mindist;
    pair<11, 11> best_pair;
    void upd_ans(const pt & a, const pt & b) {
      double dist = sqrt((a.x - b.x) * (a.x - b.x) + (a.x - b.x)
           .y - b.y) * (a.y - b.y);
      if (dist < mindist) {</pre>
       mindist = dist;
        best_pair = {a.id, b.id};
24
    vector<pt> t;
    void rec(ll l, ll r) {
      if (r - 1 \le 3) {
        for (ll i = l; i < r; ++i) {
          for (11 j = i + 1; j < r; ++j) {
            upd_ans(a[i], a[j]);
        sort(a.begin() + 1, a.begin() + r, cmp_y());
        return:
      11 m = (1 + r) >> 1, midx = a[m].x;
      rec(1, m);
      rec(m, r);
```

```
39
      merge(a.begin() + l, a.begin() + m, a.begin() + m
           , a.begin() + r, t.begin(), cmp v());
      copy(t.begin(), t.begin() + r - 1, a.begin() + 1)
41
      11 \text{ tsz} = 0;
      for (11 i = 1; i < r; ++i) {</pre>
42
43
       if (abs(a[i].x - midx) < mindist) {</pre>
          for (11 j = tsz - 1; j >= 0 && a[i].y - t[j].
               y < mindist; --j) {
             upd_ans(a[i], t[j]);
46
47
          t[tsz++] = a[i];
48
49
     }
50 }
51 t.resize(n);
52 sort(a.begin(), a.end(), cmp_x());
53 mindist = 1E20;
54 rec(0, n);
```

4 Graph Theory

4.1 Articulation Point

```
void APUtil(vector<vector<ll>>> &adj, ll u, vector
         bool> &visited.
    vector<ll> &disc, vector<ll> &low, ll &time, ll
         parent, vector<bool> &isAP) {
      11 children = 0;
      visited[u] = true;
      disc[u] = low[u] = ++time;
      for (auto v : adj[u]) {
        if (!visited[v]) {
          children++;
 9
          APUtil(adj, v, visited, disc, low, time, u,
               isAP);
          low[u] = min(low[u], low[v]);
11
          if (parent != -1 \&\& low[v] >= disc[u]) {
            isAP[u] = true;
13
        } else if (v != parent) {
15
          low[u] = min(low[u], disc[v]);
16
17
18
      if (parent == -1 && children > 1) {
19
        isAP[u] = true;
20
21 }
22 void AP (vector<vector<11>> &adj, 11 n) {
23
      vector<11> disc(n), low(n);
24
      vector<bool> visited(n), isAP(n);
      11 time = 0, par = -1;
      for (11 u = 0; u < n; u++) {
27
       if (!visited[u]) {
          APUtil(adj, u, visited, disc, low, time, par,
                isAP);
29
31
      for (11 u = 0; u < n; u++) {
       if (isAP[u]) {
          cout << u << " ";
34
36 }
```

4.2 Bellman Ford

```
void bellman_ford(vector<vector<ll>>> &edges, 11 n,
         11 m, 11 src, vector<11> &dis) {
      for (11 i = 0; i < n; i++) {</pre>
        dis[i] = INF;
      for (11 i = 0; i < n - 1; i++) {
        for (11 j = 0; j < m; j++) {
          11 u = edges[j][0], v = edges[j][1], w =
              edges[j][2];
          if (dis[u] < INF) {</pre>
            dis[v] = min(dis[v], dis[u] + w);
      for (ll i = 0; i < m; i++) {
       11 u = edges[i][0], v = edges[i][1], w = edges[
             i1[2];
        if (dis[u] < INF && dis[u] + w < dis[v]) {</pre>
          cout << "The graph contains a negative cycle.</pre>
               " << '\n';
18
     }
19 }
```

4.3 Bridge

```
void bridge util(vector<vector<ll>> &adj, ll u,
         vector<bool> &visited, vector<ll> &disc,
         vector<11> &low, vector<11> &parent) {
      static 11 time = 0;
      visited[u] = true;
      disc[u] = low[u] = ++time;
      list<ll>::iterator i;
      for (auto v : adj[u]) {
      if (!visited[v]) {
 8
          parent[v] = u;
          bridge_util(adj, v, visited, disc, low,
               parent);
          low[u] = min(low[u], low[v]);
          if (low[v] > disc[u]) {
            cout << u << ' ' << v << '\n';
        } else if (v != parent[u]) {
          low[u] = min(low[u], disc[v]);
18
19 void bridge(vector<vector<ll>> &adj, ll n) {
     vector<bool> visited(n, false);
      vector<1l> disc(n), low(n), parent(n, -1);
      for (11 i = 0; i < n; i++) {
       if (!visited[i]) {
         bridge_util(adj, i, visited, disc, low,
              parent);
25
26
     }
27 }
```

4.4 Dijkstra

```
priority_queue<pair<11, 11>, vector<pair<11, 11</pre>
    >>, greater<pair<11, 11>>> pg;
for (int i = 0; i < n; i++) {
 dis[i] = INF;
dis[0] = 0;
pg.push({0, 0});
while (!pq.empty()) {
 auto p = pq.top();
 pq.pop();
 11 u = p.second;
 if (dis[u] != p.first) {
    continue;
 for (auto x : adj[u]) {
   11 v = x.first, w = x.second;
   if (dis[v] > dis[u] + w) {
     dis[v] = dis[u] + w;
     pq.push({dis[v], v});
```

4.5 Find Cycle

```
1 bool dfs(11 v) {
      color[v] = 1;
      for (ll u : adj[v]) {
       if (color[u] == 0) {
          parent[u] = v;
          if (dfs(u)) {
            return true;
        } else if (color[u] == 1) {
          cycle_end = v;
          cycle_start = u;
          return true;
1.5
      color[v] = 2;
      return false;
18
    void find_cycle() {
      color.assign(n, 0);
      parent.assign(n, -1);
      cycle_start = -1;
      for (11 v = 0; v < n; v++) {
       if (color[v] == 0 && dfs(v)) {
          break:
      if (cycle_start == -1) {
        cout << "Acvclic" << endl;</pre>
       } else {
        vector<ll> cycle;
        cycle.push_back(cycle_start);
32
        for (ll v = cycle_end; v != cycle_start; v =
             parent[v]) {
          cycle.push_back(v);
34
        cycle.push_back(cycle_start);
        reverse(cycle.begin(), cycle.end());
        cout << "Cycle found: ";</pre>
38
        for (ll v : cvcle) {
39
          cout << v << ' ';
```

4.6 Floyd Warshall

```
void floyd_warshall(vector<vector<ll>>> &dis, ll n)
      for (11 i = 0; i < n; i++) {
        for (11 j = 0; j < n; j++) {
          dis[i][j] = (i == j ? 0 : INF);
      for (11 k = 0; k < n; k++) {
         for (11 i = 0; i < n; i++) {
          for (11 j = 0; j < n; j++) {
            if (dis[i][k] < INF && dis[k][j] < INF) {</pre>
11
              dis[i][j] = min(dis[i][j], dis[i][k] +
                   dis[k][j]);
13
          }
14
        }
15
16
      for (11 i = 0; i < n; i++) {
17
        for (11 j = 0; j < n; j++) {
18
          for (11 k = 0; k < n; k++) {
19
            if (dis[k][k] < 0 && dis[i][k] < INF && dis</pre>
                 [k][j] < INF) {
20
              dis[i][j] = -INF;
21
23
24
25 }
```

4.7 Hierholzer

```
void print_circuit(vector<vector<ll>>> &adj) {
      map<11, 11> edge_count;
      for (ll i = 0; i < adj.size(); i++) {</pre>
        edge_count[i] = adj[i].size();
      if (!adj.size()) {
        return;
      stack<ll> curr_path;
      vector<ll> circuit;
11
      curr_path.push(0);
12
13
      11 curr v = 0;
      while (!curr_path.empty()) {
14
        if (edge_count[curr_v]) {
15
           curr_path.push(curr_v);
16
           11 next_v = adj[curr_v].back();
17
           edge_count[curr_v]--;
18
           adj[curr_v].pop_back();
19
          curr_v = next_v;
20
21
         } else {
           circuit.push_back(curr_v);
22
           curr_v = curr_path.top();
23
          curr_path.pop();
25
26
       for (ll i = circuit.size() - 1; i >= 0; i--) {
27
         cout << circuit[i] << ' ';
```

```
29 }
```

4.8 Is Bipartite

```
1 bool is_bipartite(vector<11> &col, vector<vector<11</pre>
         >> &adi, 11 n) {
      queue<pair<11, 11>> q;
      for (ll i = 0; i < n; i++) {
       if (col[i] == -1) {
 5
          q.push({i, 0});
 6
          col[i] = 0;
          while (!q.empty()) {
            pair<11, 11> p = q.front();
            q.pop();
            11 v = p.first, c = p.second;
            for (11 j : adj[v]) {
              if (col[i] == c) {
                return false;
              if (col[j] == -1) {
                col[j] = (c ? 0 : 1);
                q.push({j, col[j]});
      return true;
24 }
```

4.9 Is Cyclic

```
bool is cyclic util(int u, vector<vector<int>> &adj
         , vector<bool> &vis, vector<bool> &rec) {
      vis[u] = true;
      rec[u] = true;
      for(auto v : adj[u]) {
        if (!vis[v] && is_cyclic_util(v, adj, vis, rec)
            ) {
          return true;
        } else if (rec[v]) {
 8
          return true;
9
10
      rec[u] = false;
12
      return false;
13
14 bool is_cyclic(int n, vector<vector<int>> &adj) {
15
      vector<bool> vis(n, false), rec(n, false);
16
      for (int i = 0; i < n; i++) {</pre>
       if (!vis[i] && is_cyclic_util(i, adj, vis, rec)
            ) {
18
          return true;
19
      return false;
22 }
```

4.10 Kahn

```
1  void kahn(vector<vector<11>> &adj) {
2    11 n = adj.size();
```

```
vector<ll> in_degree(n, 0);
      for (11 u = 0; u < n; u++) {
        for (ll v: adj[u]) {
          in_degree[v]++;
8
      queue<11> q;
      for (11 i = 0; i < n; i++) {
        if (in_degree[i] == 0) {
          q.push(i);
      11 cnt = 0;
      vector<11> top_order;
      while (!q.empty()) {
       11 u = q.front();
        q.pop();
        top_order.push_back(u);
        for (l1 v : adj[u]) {
          if (--in_degree[v] == 0) {
            q.push(v);
        cnt++;
28
      if (cnt != n) {
29
        cout << -1 << '\n';
        return;
      for (ll i = 0; i < (ll) top_order.size(); i++) {</pre>
        cout << top_order[i] << ' ';</pre>
34
      cout << '\n';
36
```

4.11 Kosaraju

```
void topo_sort(int u, vector<vector<int>>& adj,
         vector<bool>& vis, stack<int>& stk) {
      vis[u] = true;
      for (int v : adj[u]) {
        if (!vis[v]) {
          topo_sort(v, adj, vis, stk);
      stk.push(u);
9
    vector<vector<int>> transpose(int n, vector<vector<</pre>
         int>>& adj) {
      vector<vector<int>> adj_t(n);
      for (int u = 0; u < n; u++) {
        for (int v : adj[u]) {
          adj_t[v].push_back(u);
18
      return adj_t;
19
    void get_scc(int u, vector<vector<int>>& adj_t,
         vector<bool>& vis, vector<int>& scc) {
      vis[u] = true;
      scc.push_back(u);
      for (int v : adj_t[u]) {
25
        if (!vis[v]) {
26
          get_scc(v, adj_t, vis, scc);
```

```
29 }
    void kosaraju(int n, vector<vector<int>>& adj,
         vector<vector<int>>& sccs) {
      vector<bool> vis(n, false);
      stack<int> stk;
34
      for (int u = 0; u < n; u++) {
35
        if (!vis[u]) {
36
          topo_sort(u, adj, vis, stk);
37
38
39
      vector<vector<int>> adj_t = transpose(n, adj);
40
      for (int u = 0; u < n; u++) {
41
       vis[u] = false;
42
43
      while (!stk.empty()) {
44
       int u = stk.top();
45
        stk.pop();
46
        if (!vis[u]) {
47
          vector<int> scc;
48
          get_scc(u, adj_t, vis, scc);
49
          sccs.push back(scc);
51
52 }
```

4.12 Kruskal Mst

```
struct Edge {
      ll u, v, weight;
      bool operator<(Edge const& other) {</pre>
        return weight < other.weight;</pre>
6 };
    11 n;
    vector<Edge> edges;
    11 \cos t = 0;
10 vector<11> tree_id(n);
    vector<Edge> result;
    for (ll i = 0; i < n; i++) {</pre>
      tree_id[i] = i;
14 }
15 sort(edges.begin(), edges.end());
    for (Edge e : edges) {
17
      if (tree_id[e.u] != tree_id[e.v]) {
18
         cost += e.weight;
19
         result.push_back(e);
20
        11 old_id = tree_id[e.u], new_id = tree_id[e.v
         for (11 i = 0; i < n; i++) {
          if (tree_id[i] == old_id) {
            tree_id[i] = new_id;
2.4
25
26
```

4.13 Lowest Common Ancestor

```
1 struct LCA {
2  vector<11> height, euler, first, segtree;
3  vector<bool> visited;
4  11 n;
5  LCA(vector<vector<11>> &adj, 11 root = 0) {
```

```
n = adj.size();
        height.resize(n);
        first.resize(n);
        euler.reserve(n * 2);
        visited.assign(n, false);
        dfs(adj, root);
        11 m = euler.size();
        seqtree.resize(m * 4);
        build(1, 0, m - 1);
      void dfs(vector<vector<ll>>> &adj, ll node, ll h =
        visited[node] = true;
18
        height[node] = h;
19
         first[node] = euler.size();
20
         euler.push_back(node);
        for (auto to : adj[node]) {
          if (!visited[to]) {
            dfs(adj, to, h + 1);
             euler.push_back(node);
      void build(ll node, ll b, ll e) {
        if (b == e) {
30
          segtree[node] = euler[b];
31
        } else {
          11 \text{ mid} = (b + e) / 2;
          build(node << 1, b, mid);</pre>
34
          build(node << 1 | 1, mid + 1, e);</pre>
          11 1 = segtree[node << 1], r = segtree[node</pre>
                << 1 | 1];
36
          segtree[node] = (height[1] < height[r]) ? 1 :</pre>
37
38
39
      11 query(11 node, 11 b, 11 e, 11 L, 11 R) {
40
        if (b > R | | e < L) {
41
          return -1;
42
43
        if (b >= L && e <= R) {
          return segtree[node];
        11 \text{ mid} = (b + e) >> 1;
         11 left = guery(node << 1, b, mid, L, R);</pre>
         11 right = query(node << 1 | 1, mid + 1, e, L,</pre>
49
        if (left == -1) return right;
50
        if (right == -1) return left;
         return height[left] < height[right] ? left :</pre>
             right;
      11 lca(11 u, 11 v) {
        11 left = first[u], right = first[v];
        if (left > right) {
56
          swap(left, right);
57
58
        return query(1, 0, euler.size() - 1, left,
             right);
59
60 };
```

4.14 Maximum Bipartite Matching

```
1 bool bpm(ll n, ll m, vector<vector<bool>> &bpGraph, ll u, vector<bool> &seen, vector<ll> &matchR)
```

```
for (11 v = 0; v < m; v++) {
       if (bpGraph[u][v] && !seen[v]) {
         seen[v] = true;
         if (matchR[v] < 0 || bpm(n, m, bpGraph,</pre>
             matchR[v], seen, matchR)) {
           matchR[v] = u;
           return true;
     return false;
   11 maxBPM(11 n, 11 m, vector<vector<bool>> &bpGraph
     vector<11> matchR(m, -1);
     11 result = 0;
     for (11 u = 0; u < n; u++) {
       vector<bool> seen(m, false);
       if (bpm(n, m, bpGraph, u, seen, matchR)) {
        result++;
     return result;
4.15 Max Flow
```

```
1 bool bfs(ll n, vector<vector<ll>>> &r_graph, ll s,
         11 t, vector<11> &parent) {
      vector<bool> visited(n, false);
      queue<11> q;
      q.push(s);
      visited[s] = true;
      parent[s] = -1;
      while (!q.empty()) {
        11 u = q.front();
        q.pop();
        for (11 v = 0; v < n; v++) {
          if (!visited[v] && r_graph[u][v] > 0) {
            if (v == t) {
              parent[v] = u;
              return true;
            q.push(v);
            parent[v] = u;
            visited[v] = true;
      return false;
    11 fordFulkerson(ll n, vector<vector<ll>>> graph, ll
          s, 11 t) {
      11 u, v;
      vector<vector<ll>> r_graph;
      for (u = 0; u < n; u++) {
        for (v = 0; v < n; v++) {
29
          r_graph[u][v] = graph[u][v];
      vector<11> parent;
      11 \text{ max flow} = 0;
      while (bfs(n, r_graph, s, t, parent)) {
        11 path flow = INF;
36
        for (v = t; v != s; v = parent[v]) {
          u = parent[v];
38
          path_flow = min(path_flow, r_graph[u][v]);
```

```
39     }
40     for (v = t; v != s; v = parent[v]) {
41         u = parent[v];
42         r_graph[u][v] -= path_flow;
43         r_graph[v][u] += path_flow;
44     }
45     max_flow += path_flow;
46     }
47     return max_flow;
48  }
```

4.16 Prim Mst

```
1 vector<ll> prim_mst(ll n, vector<vector<pair<ll, ll</pre>
         >>> &adj) {
      priority queue<pair<11, 11>, vector<pair<11, 11</pre>
           >>, greater<pair<11, 11>>> pg;
      11 \text{ src} = 0;
      vector<11> key(n, INF), parent(n, -1);
      vector<bool> in_mst(n, false);
      pq.push(make_pair(0, src));
      key[src] = 0;
      while (!pq.empty()) {
       11 u = pq.top().second;
10
        pq.pop();
11
        if (in mst[u]){
12
          continue:
13
14
        in mst[u] = true;
15
        for (auto p : adj[u]) {
16
         11 v = p.first, w = p.second;
17
          if (in_mst[v] == false && w < key[v]) {</pre>
18
           kev[v] = w;
19
             pq.push(make_pair(key[v], v));
20
             parent[v] = u;
21
22
23
        }
24
      return parent;
25
```

4.17 Topological Sort

```
void dfs(ll v) {
      visited[v] = true;
      for (ll u : adj[v]) {
        if (!visited[u]) {
          dfs(u);
8
      ans.push_back(v);
9
10 void topological_sort() {
11
    visited.assign(n, false);
      ans.clear();
13
      for (11 i = 0; i < n; ++i) {
      if (!visited[i]) {
15
         dfs(i);
16
17
      reverse(ans.begin(), ans.end());
19 }
```

5 Miscellaneous

5.1 Gauss

```
1 const double EPS = 1e-9;
    const 11 INF = 2;
    11 gauss(vector <vector <double>> a, vector <double>
         &ans) {
      11 n = (11) a.size(), m = (11) a[0].size() - 1;
      vector<11> where (m, -1);
      for (11 col = 0, row = 0; col < m && row < n; ++</pre>
           col) {
        11 sel = row;
        for (11 i = row; i < n; ++i) {</pre>
          if (abs(a[i][col]) > abs(a[sel][col])) {
13
        if (abs (a[sel][col]) < EPS) {</pre>
         continue;
        for (ll i = col; i <= m; ++i) {</pre>
         swap(a[sel][i], a[row][i]);
18
19
        where[col] = row;
        for (11 i = 0; i < n; ++i) {</pre>
         if (i != row) {
            double c = a[i][col] / a[row][col];
            for (11 j = col; j <= m; ++j) {
             a[i][j] = a[row][j] * c;
28
        ++row;
      ans.assign(m, 0);
      for (11 i = 0; i < m; ++i) {
        if (where[i] != -1) {
33
          ans[i] = a[where[i]][m] / a[where[i]][i];
34
35
36
      for (11 i = 0; i < n; ++i) {</pre>
       double sum = 0;
38
        for (11 j = 0; j < m; ++j) {
39
         sum += ans[j] * a[i][j];
        if (abs (sum - a[i][m]) > EPS) {
42
          return 0:
43
44
45
      for (11 i = 0; i < m; ++i) {
       if (where[i] == -1) {
          return INF:
48
49
50
      return 1:
```

5.2 Ternary Search

```
1 double ternary_search(double 1, double r) {
2 double eps = 1e-9;
3 while (r - 1 > eps) {
4 double m1 = 1 + (r - 1) / 3;
5 double m2 = r - (r - 1) / 3;
```

6 Number Theory

6.1 Extended Euclidean

```
1  ll gcd_extended(ll a, ll b, ll &x, ll &y) {
2    if (b == 0) {
3         x = 1;
4         y = 0;
5         return a;
6    }
7    ll xl, yl, g = gcd_extended(b, a % b, xl, yl);
8    x = yl;
9    y = x1 - (a / b) * yl;
10    return g;
11 }
```

6.2 Find All Solutions

```
1 bool find_any_solution(ll a, ll b, ll c, ll &x0, ll
         &y0, 11 &q) {
      q = qcd_{extended(abs(a), abs(b), x0, y0);
     if (c % g) {
       return false;
     x0 \star = c / q;
     v0 \star = c / q;
     if (a < 0) {
      x0 = -x0;
     if (b < 0) {
       y0 = -y0;
13
14
      return true;
15
   void shift_solution(ll & x, ll & y, ll a, ll b, ll
      cnt) {
     x += cnt * b;
     y -= cnt * a;
    11 find_all_solutions(ll a, ll b, ll c, ll minx, ll
          maxx, 11 miny, 11 maxy) {
      if (!find_any_solution(a, b, c, x, y, g)) {
        return 0;
25
      a /= q;
      b /= q;
      11 \text{ sign}_a = a > 0 ? +1 : -1;
      11 \text{ sign}_b = b > 0 ? +1 : -1;
      shift_solution(x, y, a, b, (minx - x) / b);
      if (x < minx) {</pre>
        shift_solution(x, y, a, b, sign_b);
```

```
9
```

```
if (x > maxx) {
34
        return 0;
36
      11 1x1 = x;
      shift_solution(x, y, a, b, (maxx - x) / b);
      if (x > maxx) {
39
      shift_solution(x, y, a, b, -sign_b);
40
41
     11 \text{ rx1} = x;
      shift_solution(x, y, a, b, -(miny - y) / a);
      if (y < miny) {</pre>
       shift_solution(x, y, a, b, -sign_a);
45
46
     if (y > maxy) {
47
       return 0;
48
49
     11 \ 1x2 = x;
50
      shift_solution(x, y, a, b, -(maxy - y) / a);
      if (y > maxy) {
       shift_solution(x, y, a, b, sign_a);
      11 \text{ rx2} = x;
      if (1x2 > rx2) {
       swap(1x2, rx2);
57
      11 1x = max(1x1, 1x2), rx = min(rx1, rx2);
      if (1x > rx) {
59
60
       return 0;
61
      return (rx - 1x) / abs(b) + 1;
```

6.3 Linear Sieve

6.4 Miller Rabin

```
bool check_composite(u64 n, u64 a, u64 d, 11 s) {
    u64 x = binpower(a, d, n);
    if (x == 1 || x == n - 1) {
        return false;
    }
    for (11 r = 1; r < s; r++) {
        x = (u128) x * x * n;
        if (x == n - 1) {
            return false;
    }
    return true;
}</pre>
```

```
bool miller_rabin(u64 n) {
     if (n < 2) {
       return false;
    11 r = 0:
     u64 d = n - 1;
19
      while ((d & 1) == 0) {
      d >>= 1;
       r++;
      for (11 a : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29,
          31, 37}) {
       if (n == a) {
        return true;
28
       if (check_composite(n, a, d, r)) {
29
        return false;
30
      return true;
```

6.5 Modulo Inverse

6.6 Pollard Rho Brent

```
1  11 mult(11 a, 11 b, 11 mod) {
   return (__int128_t) a * b % mod;
3 }
 4 11 f(11 x, 11 c, 11 mod) {
     return (mult(x, x, mod) + c) % mod;
   11 pollard_rho_brent(ll n, ll x0 = 2, ll c = 1) {
     11 \times = \times 0, q = 1, q = 1, \times s, y, m = 128, 1 = 1;
      while (g == 1) {
       y = x;
       for (11 i = 1; i < 1; i++) {
        x = f(x, c, n);
13
14
       11 k = 0:
        while (k < 1 \&\& g == 1) {
         xs = x:
          for (11 i = 0; i < m && i < 1 - k; i++) {
          x = f(x, c, n);
            q = mult(q, abs(y - x), n);
```

6.7 Range Sieve

```
1 vector<bool> range_sieve(ll 1, ll r) {
     11 n = sqrt(r);
     vector<bool> is_prime(n + 1, true);
     vector<ll> prime;
     is_prime[0] = is_prime[1] = false;
     prime.push_back(2);
      for (11 i = 4; i <= n; i += 2) {
      is_prime[i] = false;
      for (11 i = 3; i <= n; i += 2) {</pre>
      if (is_prime[i]) {
          prime.push_back(i);
          for (11 j = i * i; j <= n; j += i) {
           is_prime[j] = false;
       }
      vector<bool> result(r - 1 + 1, true);
      for (ll i : prime) {
       for (ll j = max(i * i, (l + i - 1) / i * i); j
             <= r; j += i) {
          result[j - 1] = false;
22
24
      if (1 == 1) {
      result[0] = false;
26
      return result;
```

6.8 Segmented Sieve

```
vector<ll> segmented_sieve(ll n) {
   const ll S = 10000;
   ll nsqrt = sqrt(n);
   vector<char> is_prime(nsqrt + 1, true);
   vector<ll> prime;
   is_prime[0] = is_prime[1] = false;
   prime.push_back(2);
   for (ll i = 4; i <= nsqrt; i += 2) {
      is_prime[i] = false;
   }
   for (ll i = 3; i <= nsqrt; i += 2) {
      if (is_prime[i]) {
        prime.push_back(i);
      for (ll j = i * i; j <= nsqrt; j += i) {
        is_prime[j] = false;
      }
}</pre>
```

```
18
19
      vector<ll> result;
20
      vector<char> block(S);
      for (11 k = 0; k * S \le n; k++) {
22
        fill(block.begin(), block.end(), true);
23
        for (ll p : prime) {
24
          for (11 j = max((k * S + p - 1) / p, p) * p -
                k * S; j < S; j += p) {
            block[j] = false;
26
27
28
        if (k == 0) {
29
          block[0] = block[1] = false;
31
        for (11 i = 0; i < S && k * S + i <= n; i++) {
32
          if (block[i]) {
33
            result.push_back(k * S + i);
34
        }
36
      return result;
38
```

6.9 Tonelli Shanks

```
1  11 legendre(ll a, ll p) {
      return bin_pow_mod(a, (p - 1) / 2, p);
 4 ll tonelli_shanks(ll n, ll p) {
      if (legendre(n, p) == p - 1) {
        return -1;
      if (p % 4 == 3) {
        return bin_pow_mod(n, (p + 1) / 4, p);
11
      11 Q = p - 1, S = 0;
      while (Q % 2 == 0) {
       Q /= 2;
14
        S++;
15
      11 z = 2;
      for (; z < p; z++) {
18
        if (legendre(z, p) == p - 1) {
19
20
21
      11 M = S, c = bin_pow_mod(z, Q, p), t =
           bin_pow_mod(n, Q, p), R = bin_pow_mod(n, Q)
           + 1) / 2, p);
23
      while (t % p != 1) {
24
25
        if (t % p == 0) {
          return 0;
26
27
28
        11 i = 1, t2 = t * t % p;
         for (; i < M; i++) {
29
          if (t2 % p == 1) {
30
            break;
          t2 = t2 * t2 % p;
        11 b = bin_pow_mod(c, bin_pow_mod(2, M - i - 1,
              p), p);
        M = i:
36
        c = b * b % p;
        t = t * c % p;
38
        R = R * b % p;
39
```

```
return R;
41 }
```

7 Strings

7.1 Hashing

```
11 compute_hash(string const& s) {
     const 11 p = 31, m = 1e9 + 9;
     11 hash_value = 0, p_pow = 1;
     for (char c : s) {
      hash\_value = (hash\_value + (c - 'a' + 1) *
           p_pow) % m;
6
      p_pow = (p_pow * p) % m;
8
     return hash_value;
9
```

7.2 Knuth Morris Pratt

```
vector<ll> prefix_function(string s) {
      ll n = (ll) s.length();
      vector<ll> pi(n);
      for (ll i = 1; i < n; i++) {
       11 j = pi[i - 1];
        while (j > 0 \&\& s[i] != s[j]) {
          j = pi[j - 1];
 8
 9
        if (s[i] == s[j]) {
          j++;
        pi[i] = j;
13
      return pi;
```

7.3 Rabin Karp

```
vector<11> rabin_karp(string const& s, string const
     const 11 p = 31, m = 1e9 + 9;
     11 S = s.size(), T = t.size();
     vector<ll> p_pow(max(S, T));
     p_pow[0] = 1;
6
     for (ll i = 1; i < (ll) p_pow.size(); i++) {</pre>
       p_pow[i] = (p_pow[i-1] * p) % m;
8
9
     vector<11> h(T + 1, 0);
     for (11 i = 0; i < T; i++) {
       h[i + 1] = (h[i] + (t[i] - 'a' + 1) * p_pow[i])
     11 h_s = 0;
     for (11 i = 0; i < S; i++) {</pre>
       h_s = (h_s + (s[i] - 'a' + 1) * p_pow[i]) % m;
     vector<11> occurences;
     for (11 i = 0; i + S - 1 < T; i++) {
       11 \text{ cur}_h = (h[i + S] + m - h[i]) % m;
       if (cur_h == h_s * p_pow[i] % m) {
         occurences.push_back(i);
```

```
return occurences;
25
```

7.4 Suffix Array

```
vector<ll> sort_cyclic_shifts(string const& s) {
      11 n = s.size();
      const 11 alphabet = 256;
      vector<ll> p(n), c(n), cnt(max(alphabet, n), 0);
      for (11 i = 0; i < n; i++) {
        cnt[s[i]]++;
8
      for (ll i = 1; i < alphabet; i++) {</pre>
        cnt[i] += cnt[i - 1];
      for (ll i = 0; i < n; i++) {</pre>
        p[--cnt[s[i]]] = i;
14
      c[p[0]] = 0;
      11 \text{ classes} = 1;
      for (ll i = 1; i < n; i++) {</pre>
        if (s[p[i]] != s[p[i-1]]) {
          classes++;
        c[p[i]] = classes - 1;
      vector<11> pn(n), cn(n);
      for (11 h = 0; (1 << h) < n; ++h) {
        for (ll i = 0; i < n; i++) {</pre>
          pn[i] = p[i] - (1 << h);
          if (pn[i] < 0) {
            pn[i] += n;
2.9
        fill(cnt.begin(), cnt.begin() + classes, 0);
        for (11 i = 0; i < n; i++) {
          cnt[c[pn[i]]]++;
        for (ll i = 1; i < classes; i++) {</pre>
          cnt[i] += cnt[i - 1];
        for (11 i = n-1; i >= 0; i--) {
          p[--cnt[c[pn[i]]]] = pn[i];
40
        cn[p[0]] = 0;
        classes = 1;
42
        for (ll i = 1; i < n; i++) {
43
          pair<11, 11> cur = {c[p[i]], c[(p[i] + (1 <<
               h)) % n]};
          pair<11, 11> prev = {c[p[i-1]], c[(p[i-1])}
                + (1 << h)) % n]};
          if (cur != prev) {
            ++classes;
          cn[p[i]] = classes - 1;
50
        c.swap(cn);
52
      return p:
53
    vector<ll> build_suff_arr(string s) {
55
      s += (char) 0;
      vector<ll> sorted_shifts = sort_cyclic_shifts(s);
      sorted shifts.erase(sorted shifts.begin());
      return sorted_shifts;
59
```

```
Pegaraw
```

Pegaraw Pegaraw

_		
f(n) = O(g(n))	iff \exists positive c, n_0 such that $0 \le f(n) \le cg(n) \ \forall n \ge n_0$.	$\sum_{i=1}^{n} i = \frac{n(n+1)}{2}, \sum_{i=1}^{n} i^2 = \frac{n(n+1)(2n+1)}{6}, \sum_{i=1}^{n} i^3 = \frac{n^2(n+1)^2}{4}.$
$f(n) = \Omega(g(n))$	iff \exists positive c, n_0 such that $f(n) \ge cg(n) \ge 0 \ \forall n \ge n_0$.	$ \begin{array}{ccc} i=1 & & i=1 \\ In general: & & & \\ n & & & & \\ & & & & \\ & & & & \\ & & & &$
$f(n) = \Theta(g(n))$	iff $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$.	$\sum_{i=1}^{n} i^{m} = \frac{1}{m+1} \left[(n+1)^{m+1} - 1 - \sum_{i=1}^{n} \left((i+1)^{m+1} - i^{m+1} - (m+1)i^{m} \right) \right]$
f(n) = o(g(n))	iff $\lim_{n\to\infty} f(n)/g(n) = 0$.	$\sum_{i=1}^{n-1} i^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k n^{m+1-k}.$
$\lim_{n \to \infty} a_n = a$	iff $\forall \epsilon > 0$, $\exists n_0$ such that $ a_n - a < \epsilon$, $\forall n \ge n_0$.	Geometric series:
$\sup S$	least $b \in \mathbb{R}$ such that $b \geq s$, $\forall s \in S$.	$\sum_{i=0}^{n} c^{i} = \frac{c^{n+1} - 1}{c - 1}, c \neq 1, \sum_{i=0}^{\infty} c^{i} = \frac{1}{1 - c}, \sum_{i=1}^{\infty} c^{i} = \frac{c}{1 - c}, c < 1,$
$\inf S$	greatest $b \in \mathbb{R}$ such that $b \le s$, $\forall s \in S$.	$\sum_{i=0}^{n} ic^{i} = \frac{nc^{n+2} - (n+1)c^{n+1} + c}{(c-1)^{2}}, c \neq 1, \sum_{i=0}^{\infty} ic^{i} = \frac{c}{(1-c)^{2}}, c < 1.$
$ \liminf_{n \to \infty} a_n $	$\lim_{n \to \infty} \inf \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$	Harmonic series: $n 1 \sum_{n=1}^{n} 1 \sum_{n=1}^{n} n(n+1) n(n-1)$
$\limsup_{n \to \infty} a_n$	$\lim_{n \to \infty} \sup \{ a_i \mid i \ge n, i \in \mathbb{N} \}.$	$H_n = \sum_{i=1}^n \frac{1}{i}, \qquad \sum_{i=1}^n iH_i = \frac{n(n+1)}{2}H_n - \frac{n(n-1)}{4}.$
$\binom{n}{k}$	Combinations: Size k subsets of a size n set.	$\sum_{i=1}^{n} H_i = (n+1)H_n - n, \sum_{i=1}^{n} {i \choose m} H_i = {n+1 \choose m+1} \left(H_{n+1} - \frac{1}{m+1} \right).$
$\begin{bmatrix} n \\ k \end{bmatrix}$	Stirling numbers (1st kind): Arrangements of an n element set into k cycles.	$1. \binom{n}{k} = \frac{n!}{(n-k)!k!}, \qquad 2. \sum_{k=0}^{n} \binom{n}{k} = 2^n, \qquad 3. \binom{n}{k} = \binom{n}{n-k},$
$\left\{ egin{array}{c} n \\ k \end{array} \right\}$	Stirling numbers (2nd kind): Partitions of an n element set into k non-empty sets.	$4. \binom{n}{k} = \frac{n}{k} \binom{n-1}{k-1}, \qquad \qquad 5. \binom{n}{k} = \binom{n-1}{k} + \binom{n-1}{k-1}, \\ 6. \binom{n}{m} \binom{m}{k} = \binom{n}{k} \binom{n-k}{m-k}, \qquad \qquad 7. \sum_{k=0}^{n} \binom{r+k}{k} = \binom{r+n+1}{n},$
$\left\langle {n\atop k}\right\rangle$	1st order Eulerian numbers: Permutations $\pi_1\pi_2\pi_n$ on $\{1,2,,n\}$ with k ascents.	8. $\sum_{k=0}^{n} {k \choose m} = {n+1 \choose m+1},$ 9. $\sum_{k=0}^{n} {r \choose k} {s \choose n-k} = {r+s \choose n},$
$\left\langle\!\left\langle {n\atop k}\right\rangle\!\right\rangle$	2nd order Eulerian numbers.	10. $\binom{n}{k} = (-1)^k \binom{k-n-1}{k},$ 11. $\binom{n}{1} = \binom{n}{n} = 1,$
C_n	Catalan Numbers: Binary trees with $n+1$ vertices.	12. $\binom{n}{2} = 2^{n-1} - 1,$ 13. $\binom{n}{k} = k \binom{n-1}{k} + \binom{n-1}{k-1},$
		$16. \begin{bmatrix} n \\ n \end{bmatrix} = 1, \qquad \qquad 17. \begin{bmatrix} n \\ k \end{bmatrix} \ge \begin{Bmatrix} n \\ k \end{Bmatrix},$
		$\begin{bmatrix} n \\ -1 \end{bmatrix} = \begin{bmatrix} n \\ n-1 \end{bmatrix} = \binom{n}{2}, 20. \sum_{k=0}^{n} \begin{bmatrix} n \\ k \end{bmatrix} = n!, 21. \ C_n = \frac{1}{n+1} \binom{2n}{n},$
$22. \left\langle {n \atop 0} \right\rangle = \left\langle {n \atop n-1} \right\rangle$	$\begin{pmatrix} n \\ -1 \end{pmatrix} = 1,$ 23. $\begin{pmatrix} n \\ k \end{pmatrix} = \langle n \rangle$	$\binom{n}{n-1-k}$, 24. $\binom{n}{k} = (k+1)\binom{n-1}{k} + (n-k)\binom{n-1}{k-1}$,
$25. \left\langle {0 \atop k} \right\rangle = \left\{ {1 \atop 0} \right\}$	if $k = 0$, otherwise 26. $\left\langle \frac{1}{2} \right\rangle$	
28. $x^n = \sum_{k=0}^{n} \binom{n}{k}$	$\left. \left\langle \left(\begin{array}{c} n \\ n \end{array} \right), \qquad $ 29. $\left\langle \begin{array}{c} n \\ m \end{array} \right\rangle = \sum_{k=1}^{n} \left\langle \left(\begin{array}{c} n \\ n \end{array} \right) \right\rangle$	$\sum_{k=0}^{n} {n+1 \choose k} (m+1-k)^n (-1)^k, 30. m! {n \choose m} = \sum_{k=0}^{n} {n \choose k} {n \choose n-m},$
$31. \left\langle {n \atop m} \right\rangle = \sum_{k=0}^{n} \cdot$	${n \choose k} {n-k \choose m} (-1)^{n-k-m} k!,$	32. $\left\langle {n \atop 0} \right\rangle = 1,$ 33. $\left\langle {n \atop n} \right\rangle = 0$ for $n \neq 0,$
$34. \left\langle \!\! \left\langle \!\! \begin{array}{c} n \\ k \end{array} \!\! \right\rangle = (k + 1)^n $	$+1$ $\left\langle \left\langle \left$	
$36. \left\{ \begin{array}{c} x \\ x-n \end{array} \right\} = \left\{ \begin{array}{c} x \\ x \end{array} \right\}$	$\sum_{k=0}^{n} \left\langle \!\! \left\langle n \right\rangle \!\! \right\rangle \left(\!\! \left(x + n - 1 - k \right) \!\! \right), $	37. ${n+1 \choose m+1} = \sum_{k} {n \choose k} {k \choose m} = \sum_{k=0}^{n} {k \choose m} (m+1)^{n-k},$

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The Chinese remainder theorem: There exists a number C such that:

 $C \equiv r_1 \mod m_1$

: : :

 $C \equiv r_n \mod m_n$

if m_i and m_j are relatively prime for $i \neq j$. Euler's function: $\phi(x)$ is the number of positive integers less than x relatively prime to x. If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x then

$$\phi(x) = \prod_{i=1}^{n} p_i^{e_i - 1} (p_i - 1).$$

Euler's theorem: If a and b are relatively prime then

$$1 \equiv a^{\phi(b)} \bmod b$$
.

Fermat's theorem:

$$1 \equiv a^{p-1} \bmod p.$$

The Euclidean algorithm: if a > b are integers then

$$gcd(a, b) = gcd(a \mod b, b).$$

If $\prod_{i=1}^{n} p_i^{e_i}$ is the prime factorization of x

$$S(x) = \sum_{d|x} d = \prod_{i=1}^{n} \frac{p_i^{e_i+1} - 1}{p_i - 1}.$$

Perfect Numbers: x is an even perfect number iff $x = 2^{n-1}(2^n - 1)$ and $2^n - 1$ is prime. Wilson's theorem: n is a prime iff

$$(n-1)! \equiv -1 \mod n$$
.

$$\mu(i) = \begin{cases} (n-1)! = -1 \bmod n. \\ \text{M\"obius inversion:} \\ \mu(i) = \begin{cases} 1 & \text{if } i = 1. \\ 0 & \text{if } i \text{ is not square-free.} \\ (-1)^r & \text{if } i \text{ is the product of} \\ r & \text{distinct primes.} \end{cases}$$
 If

 If

$$G(a) = \sum_{d|a} F(d),$$

$$F(a) = \sum_{d \mid a} \mu(d) G\left(\frac{a}{d}\right).$$

Prime numbers:

$$p_n = n \ln n + n \ln \ln n - n + n \frac{\ln \ln n}{\ln n}$$

$$+O\left(\frac{n}{\ln n}\right),$$

$$\pi(n) = \frac{n}{\ln n} + \frac{n}{(\ln n)^2} + \frac{2!n}{(\ln n)^3} + O\left(\frac{n}{(\ln n)^4}\right).$$

efii		

LoopAn edge connecting a vertex to itself.

Directed Each edge has a direction. SimpleGraph with no loops or

multi-edges.

WalkA sequence $v_0e_1v_1\ldots e_\ell v_\ell$. TrailA walk with distinct edges. Pathtrail with distinct

vertices.

ConnectedA graph where there exists a path between any two

vertices.

connected ComponentΑ maximal subgraph.

TreeA connected acyclic graph. Free tree A tree with no root. DAGDirected acyclic graph. EulerianGraph with a trail visiting each edge exactly once.

Hamiltonian Graph with a cycle visiting each vertex exactly once.

CutA set of edges whose removal increases the number of components.

Cut-setA minimal cut. Cut edge A size 1 cut.

k-Connected A graph connected with the removal of any k-1vertices.

k-Tough $\forall S \subseteq V, S \neq \emptyset$ we have $k \cdot c(G - S) \le |S|$.

A graph where all vertices k-Regular have degree k.

k-Factor Α k-regular spanning subgraph.

Matching A set of edges, no two of which are adjacent.

CliqueA set of vertices, all of which are adjacent.

Ind. set A set of vertices, none of which are adjacent.

Vertex cover A set of vertices which cover all edges.

Planar graph A graph which can be embeded in the plane.

Plane graph An embedding of a planar

$$\sum_{v \in V} \deg(v) = 2m.$$

If G is planar then n - m + f = 2, so

$$f \le 2n - 4, \quad m \le 3n - 6.$$

Any planar graph has a vertex with degree ≤ 5 .

Notation:

E(G)Edge set Vertex set V(G)

c(G)Number of components

G[S]Induced subgraph deg(v)Degree of v

Maximum degree $\Delta(G)$ $\delta(G)$ Minimum degree

 $\chi(G)$ Chromatic number $\chi_E(G)$ Edge chromatic number

 G^c Complement graph K_n Complete graph

 K_{n_1,n_2} Complete bipartite graph

Ramsev number

Geometry

Projective coordinates: (x, y, z), not all x, y and z zero.

$$(x, y, z) = (cx, cy, cz) \quad \forall c \neq 0.$$

Cartesian Projective (x, y)(x, y, 1)y = mx + b(m, -1, b)

x = c(1,0,-c)Distance formula, L_p and L_{∞}

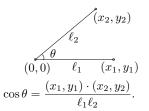
 $\sqrt{(x_1-x_0)^2+(y_1-y_0)^2}$ $[|x_1 - x_0|^p + |y_1 - y_0|^p]^{1/p},$

 $\lim \left[|x_1 - x_0|^p + |y_1 - y_0|^p \right]^{1/p}.$

Area of triangle $(x_0, y_0), (x_1, y_1)$ and (x_2, y_2) :

$$\frac{1}{2} \operatorname{abs} \begin{vmatrix} x_1 - x_0 & y_1 - y_0 \\ x_2 - x_0 & y_2 - y_0 \end{vmatrix}.$$

Angle formed by three points:



Line through two points (x_0, y_0) and (x_1, y_1) :

$$\begin{vmatrix} x & y & 1 \\ x_0 & y_0 & 1 \\ x_1 & y_1 & 1 \end{vmatrix} = 0.$$

Area of circle, volume of sphere:

$$A = \pi r^2, \qquad V = \frac{4}{3}\pi r^3.$$

If I have seen farther than others, it is because I have stood on the shoulders of giants.

- Issac Newton

14 Pegaraw

Taylor's series:

$$f(x) = f(a) + (x - a)f'(a) + \frac{(x - a)^2}{2}f''(a) + \dots = \sum_{i=0}^{\infty} \frac{(x - a)^i}{i!}f^{(i)}(a).$$

Expansions:

Expansions:
$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-cx} = 1 + x + x^2 + x^3 + x^4 + \cdots = \sum_{i=0}^{\infty} c^i x^i,$$

$$\frac{1}{1-x^n} = 1 + x^n + x^{2n} + x^{3n} + \cdots = \sum_{i=0}^{\infty} x^{ni},$$

$$\frac{x}{(1-x)^2} = x + 2x^2 + 3x^3 + 4x^4 + \cdots = \sum_{i=0}^{\infty} i x^i,$$

$$x^k \frac{d^n}{dx^n} \left(\frac{1}{1-x}\right) = x + 2^n x^2 + 3^n x^3 + 4^n x^4 + \cdots = \sum_{i=0}^{\infty} i^n x^i,$$

$$e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\ln(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 - \frac{1}{4}x^4 - \cdots = \sum_{i=0}^{\infty} (-1)^{i+1} \frac{x^i}{i},$$

$$\sin x = x - \frac{1}{3}x^3 + \frac{1}{6}x^5 - \frac{1}{17}x^7 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\cos x = 1 - \frac{1}{2}x^2 + \frac{1}{4}x^4 - \frac{1}{6!}x^6 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$(1+x)^n = 1 + nx + \frac{n(n-1)}{2}x^2 + \cdots = \sum_{i=0}^{\infty} (-1)^i \frac{x^{2i+1}}{(2i+1)!},$$

$$\frac{1}{(1-x)^{n+1}} = 1 + (n+1)x + \binom{n+2}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{i}{i}x^i,$$

$$\frac{1}{x^i} = 1 + x + 2x^2 + 5x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + x + 2x^2 + 6x^3 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{\sqrt{1-4x}} = 1 + (2+n)x + \binom{4+n}{2}x^2 + \cdots = \sum_{i=0}^{\infty} \binom{2i}{i}x^i,$$

$$\frac{1}{1-x} \ln \frac{1}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{1}{2}\left(\ln \frac{1}{1-x}\right)^2 = \frac{1}{2}x^2 + \frac{3}{4}x^3 + \frac{11}{24}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x + \frac{3}{2}x^2 + \frac{1}{16}x^3 + \frac{25}{212}x^4 + \cdots = \sum_{i=0}^{\infty} \frac{H_{i-1}x^i}{i},$$

$$\frac{x}{1-x} = x^2 + x^2 + 2x^3 + 3x^4 + \cdots = \sum_{i=0}^{\infty} F_{i}x^i.$$

Ordinary power series:

$$A(x) = \sum_{i=0}^{\infty} a_i x^i.$$

Exponential power series:

$$A(x) = \sum_{i=0}^{\infty} a_i \frac{x^i}{i!}.$$

Dirichlet power series:

$$A(x) = \sum_{i=1}^{\infty} \frac{a_i}{i^x}.$$

Binomial theorem

$$(x+y)^n = \sum_{k=0}^n \binom{n}{k} x^{n-k} y^k.$$

$$x^{n} - y^{n} = (x - y) \sum_{k=0}^{n-1} x^{n-1-k} y^{k}.$$

For ordinary power se

$$\alpha A(x) + \beta B(x) = \sum_{i=0}^{\infty} (\alpha a_i + \beta b_i) x^i,$$

$$x^k A(x) = \sum_{i=k}^{\infty} a_{i-k} x^i,$$

$$\frac{A(x) - \sum_{i=0}^{k-1} a_i x^i}{x^k} = \sum_{i=0}^{\infty} a_{i+k} x^i,$$

$$A(cx) = \sum_{i=0}^{\infty} c^i a_i x^i,$$

$$A'(x) = \sum_{i=0}^{\infty} (i+1) a_{i+1} x^i,$$

$$xA'(x) = \sum_{i=1}^{\infty} ia_i x^i,$$

$$\int A(x) dx = \sum_{i=1}^{\infty} \frac{a_{i-1}}{i} x^{i},$$

$$\frac{A(x) + A(-x)}{2} = \sum_{i=1}^{\infty} a_{2i} x^{2i},$$

$$\frac{A(x) - A(-x)}{2} = \sum_{i=0}^{\infty} a_{2i+1} x^{2i+1}.$$

Summation: If $b_i = \sum_{i=0}^i a_i$ then

$$B(x) = \frac{1}{1-x}A(x).$$

Convolution:

$$A(x)B(x) = \sum_{i=0}^{\infty} \left(\sum_{j=0}^{i} a_j b_{i-j}\right) x^i.$$

God made the natural numbers; all the rest is the work of man. Leopold Kronecker