# Jonathan Wapman

jdwapman@ucdavis.edu | (925) 548-9038 | https://github.com/jdwapman

#### Education

#### University of California, Davis

Master of Science, Electrical Engineering

**Expected June 2020** 

- **GPA:** 4.00/4.00
- Research Focus: Load-Balancing for GPU-Accelerated Graph Algorithms (Advisor: Professor John Owens)
- Coursework: Linear Systems & Signals, Nonlinear Systems, Optimal Control, Reinforcement Learning

Bachelor of Science, Electrical Engineering

**Graduated March 2018** 

- **GPA:** 3.96/4.00
- **Awards:** Outstanding Senior in Electrical Engineering (1 per year), Dean's List: 10 Quarters, Robert Murdoch Mem. Scholarship, Fred Fuchslin Mem. Scholarship, Best Undergraduate Poster UC Davis Industrial Affiliates Conference

## Skills

- Engineering: Control Systems, Digital Design, Embedded Systems, Parallel Computing, Optimization, Robotics
- Languages: C, C++, CUDA, Python, MATLAB, Verilog, Bash, MIPS, VB.NET
- Software: OpenCV, NumPy, SciPy, Numba, Git, Gunrock, Eagle, LabView, Simulink, Linux Command Line

# Experience

## **Owens Research Group**

Davis, CA

Graduate Student Researcher

December 2018 - Present

- Currently researching methods to map GPU graph algorithms and load-balancing methods to a dataflow programming model in collaboration with Nvidia as part of DARPA's Software-Defined Hardware program.
- Implemented the HITS graph ranking algorithm in the Gunrock open-source parallel graph analytics library.

#### **NASA let Propulsion Laboratory**

Pasadena, CA

Guidance & Control Intern

*June 2018 – September 2018* 

• Developed and tested control algorithms and real-time, embedded software drivers to enable automated position control of a planar air-bearing platform used for CubeSat dynamics tests to support future CubeSat missions.

## **Lawrence Livermore National Laboratory**

Livermore, CA

Computational Engineering Intern

March 2018 - June 2018

• Modeled and simulated decentralized multi-agent robotic swarm algorithms for signal detection, information exchange, and motion planning applied to chemical plume identification and localization.

Engineering Intern - National Ignition Facility

*June 2017 – September 2017* 

• Created a sensor and LabView virtual instrument used to measure and track the capacitance of over 4000 highenergy-density capacitors for preventative maintenance. Achieved accuracy within 3% and repeatability within 1%.

#### Yankelevich & Marcu Laboratory

Davis, CA

Research Assistant

January 2017 - March 2018

• Implemented low-cost, automated hardware and software systems to capture, analyze, and visualize fluorescence lifetime imaging data for guided surgery applications using C++ and Python on a Raspberry Pi computer.

# **Projects**

- Adversarial Reinforcement Learning: Currently researching applications of various reinforcement learning algorithms such as SARSA and Q-Learning to multi-agent environments.
- **Computer Vision:** Designed object-detection algorithms to identify ground-level targets from onboard a rocket while in flight. Algorithm executed using C++, OpenCV, and the Yolo neural network on an Nvidia Jetson TX1.
- **CubeSat Constellation Optimization:** Applied optimization and model-predictive control systems to simulate CubeSat constellation separation using atmospheric drag as the leader of a three-person team.