The effect of starvation on the dynamics of consumer populations

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April 13, 2016

₁ 1 Introduction

The behavioral ecology of most, if not all, organisms is influenced by the energetic state of

3 individuals. An individual's energetic state directly influences how it invests its stores in an

uncertain environment. Such behaviors are generally manifested as trade-offs, which often

5 concern investing in individual maintenance and growth vs. producing offspring [Mangel],

6 among a host of other behavioral duties [REFS]. The timing of these behaviors is often

7 important and is under strong selective pressure, as they tend to have large effects on the

future fitness of the organism [Mangel]. To what extent, and when, organisms invest in

9 these two necessary biological functions – growth and maintenance vs. reproduction – may

be driven by habitat, seasonality, evolutionary history, inter- or intra-specific interactions,

or even resource limitation. The influence of resource limitation on an organism's ability to

maintain its nutritional stores may lead to delays or shifts in reproduction.

Maximizing fitness between growth and maintenance activities vs. reproductive behav-

iors in large part structures the life-history of species, and this can be achieved by a variety of potential mechanisms all of which, to some extent, depend on resource availability: i) 15 Behavioral: The investment of time and energy towards reproductive and parental behaviors depends on resource availability (1). For example, reindeer invest less in calves born after harsh winters (when the mother's energetic state is poor) than in calves born after 18 moderate winters (2), whereas many bird species invest differently in broods during periods of resource scarcity (3, 4), sometimes delaying or foregoing reproduction for an entire season (5). Resource limitation can also alter the behaviors of species in well-mixed environments: freshwater and marine zooplankton have been observed to avoid reproduction under nutritional stress (6), while those that do reproduce evince lower survival rates (7). Similarly, artificially induced stress has been observed to decrease reproductive success in Atlantic cod (8). ii) Physiological: Diverse mammals (47 species in 10 families) exhibit de-25 layed implantation whereby females postpone fetal development (blastocyst implantation), often timing with accumulation of nutritional reserves (9, 10). Furthermore, many mammals (including humans) suffer irregular menstrual cycling and higher rates of spontaneous abortion during periods of nutritional stress (11, 12). iii) Spatio-temporal: Organisms may also separate maintenance/growth from reproduction over space and time. For example, many salmonids, birds, and some mammals return to migratory breeding sites to reproduce 31 after one or multiple seasons in alternative environments spent accumulating body mass and nutritional reserves (13?, 14). The existence of so many independently evolved mechanisms 33 across such a diverse suite of organisms points to the importance and universality of the fundamental tradeoff between spending energy on ones own tissues and spending energy on passing down genetic material.

Organisms employ different strategies to avoid reproduction during times of nutritional

stress, and how this is achieved has received tremendous empirical and theoretical attention,
owing to the importance of these activities in shaping life-history [REF]. What is less well
understood is how resource limitation affect dynamics at the level of the population? Traditional Lotka-Volterra models assume a resource density dependence on population growth
rates, thus implicitly incorporating the requirement of resource availability for reproduction.

However, resource limitation and the subsequent effects of starvation can also be accounted
for explicitly, such that reproductive growth of a population is only allowed to occur if individuals have sufficient energetic reserves. Incorporating energetic dynamics that occur on
an individual level [REF] into a population-based framework (15, 16), though straightforward conceptually, has many challenges that arise mathematically (17), and this has limited
simple theoretical models aiding our understanding of larger-scale dynamics.

Here we explore how reproductive trade-offs, which occur at the level of the individual,
may influence the dynamics of a population. We first establish a simple stage-structured
population model that captures the essential dynamics of energetic reproductive tradeoffs,
and explore the impact of different fluxes on system-level stability. By relating different rate
constants to allometric relationships, we uncover important constraints in the timescales of
different physiological processes that determine dynamics and investigate how organisms of
alternative body sizes and taxonomic affinities are expected to evince contrasting populationlevel dynamics. We then develop a more general dynamic model in order to understand if
there are common attributes of these energetically-constrained systems that have implica-

⁵⁹ 2 Methods

60 2.1 Model description

We first integrate energetics into the dynamics of a consumer-resource system by assuming 61 that the consumer population can be divided into discrete energetic states, the occupation of 62 each being contingent on the consumption of a single resource R. In the simplest case, there 63 are only two energetic states for the consumer population: i) an energetically replete (full) state F, where the consumer reproduces at rate λ , and ii) an energetically deficient (hungry) 65 state H, where reproduction is suppressed, and mortality occurs at rate μ . Consumers transition from state F to state H by starvation at rate σ and in proportion to the lack of 67 food 1-R. Conversely, consumers recover from state H to the full state F at rate ρ and in 68 proportion to the density of resources consumed R. The resource has logistic growth with a linear growth rate a and a carrying capacity of unity. Resources are eliminated by the 70 consumer in either state: by energetically deficient consumers at rate ρ , and by energetically 71 replete consumers at rate b. Accordingly, the system of equations is written

$$\frac{\mathrm{d}}{\mathrm{dt}}F = \lambda F + \rho HR - \sigma(1 - R)F,$$

$$\frac{\mathrm{d}}{\mathrm{dt}}H = \sigma(1 - R)F - \rho RH - \mu H,$$

$$\frac{\mathrm{d}}{\mathrm{dt}}R = aR(1 - R) - R(\rho H + bF).$$
(1)

There are three steady states for the 2-stage consumer-resource system: two trivial steady states at $(R^* = 0, H^* = 0, F^* = 0)$ and $(R^* = 1, H^* = 0, F^* = 0)$, and one non-trivial internal steady state where $(R^* > 0, H^* > 0, F^* > 0)$. The latter steady state is the one of chief 76 ecological interest, where

$$F^* = \frac{a\lambda\mu(\mu+\rho)}{(\lambda\rho+\mu\sigma)(\lambda\rho+\mu m)},$$

$$H^* = \frac{a\lambda^2(\mu+\rho)}{(\lambda\rho+\mu\sigma)(\lambda\rho+\mu m)},$$

$$R^* = \frac{\mu(\sigma-\lambda)}{\lambda\rho+\mu\sigma}.$$
(2)

Because there is only one internal steady state, as long as it is stable the population trajectories will be globally attracted to it for any set of initial conditions greater than zero.

Analysis of the stability of the consumer-resource system is explored with respect to the local stability of the internal steady state, which is the only feasible steady state as long as both the consumer and resource have non-zero, positive, values. In a multidimensional system, linear stability is determined with respect to the Jacobian Matrix **J**, which is a matrix where each element is defined by the partial derivative of each equation with respect to each variable. In the case of the 2-stage consumer model, the Jacobian evaluated at the internal steady state (denoted by |*) is written

$$\mathbf{J}|_{*} = \begin{pmatrix} -\frac{\lambda\rho(\sigma-\lambda)}{\lambda\rho+\mu\sigma} & \frac{\mu\rho(\sigma-\lambda)}{\lambda\rho+\mu\sigma} & \frac{\alpha\lambda(\mu+\rho)}{m\mu+\lambda\rho} \\ \frac{\lambda(\mu+\rho)\sigma}{\lambda\rho+\mu\sigma} & -\frac{\mu(\mu+\rho)\sigma}{\lambda\rho+\mu\sigma} & -\frac{\alpha\lambda(\mu+\rho)}{m\mu+\lambda\rho} \\ -\frac{m\mu(\sigma-\lambda)}{\lambda\rho+\mu\sigma} & -\frac{\mu\rho(\sigma-\lambda)}{\lambda\rho+\mu\sigma} & -\frac{\alpha\mu(\sigma-\lambda)}{\lambda\rho+\mu\sigma} \end{pmatrix}.$$
(3)

If the parameters of the Jacobian matrix at the internal steady state are such that its leading eigenvalue is < 0, then the system is stable to small pulse perturbations, conditioned on the value of the starvation rate σ relative to the value of the consumer reproduction rate λ . As σ nears and becomes lower than a given λ , the resource steady state R^* crosses the origin and exchanges stability to become unstable. As such, a transcritical bifurcation exists at $\lambda = \sigma$, such that the existence of an internal stable fixed point is dependent on the condition that $\sigma > \lambda$. Biologically, this means that the rate of starvation is greater (operating on a smaller timescale) than the rate of consumer reproduction (operating on a relatively longer timescale). As will be shown in Section XX, this general expectation will hold for most classes of organisms, while the exact difference in timescales between reproduction and starvation can be derived using allometric scaling relationships.

Oscillating, or cyclic, dynamics present additional risks to populations. If cycles are large, stochastic effects may result in extinction. In continuous-time systems, cycles arise when a pair of complex conjugate eigenvalues cross the imaginary axis and attain positive real parts. This condition is called a Hopf bifurcation, and is defined by $Det(\mathbf{S}) = 0$, where \mathbf{S} is the Sylvester matrix, which is composed of the coefficients of the characteristic polynomial describing the Jacobian matrix. Although the Hopf condition for the specific 2-stage model cannot be easily written, the analytical solution can be explored using a symbolic computational language such as Mathematica.

$_{105}$ 2.2 Analysis of a generalized model

We may gain additional insight by that we do not know the specific rate functions from our 2-stage consumer resource model presented in Eq. 1. For example, we assume a linear mortality term for hungry foragers μH , though we may wish to assert that our knowledge of consumer mortality involves those that are energetically deficient, but nothing else. In this case, we would assume only that the rate of mortality is governed by the function M(H). Substituting general functions for all rate laws from Eq. 1, we obtain the generalized ODE system

$$\frac{\mathrm{d}}{\mathrm{dt}}F = G(F) + S(R, H) - K(R, F),$$

$$\frac{\mathrm{d}}{\mathrm{dt}}H = K(R, F) - S(R, H) - M(H),$$

$$\frac{\mathrm{d}}{\mathrm{dt}}R = P(R) - L(R, H, F).$$
(4)

tion functions, respectively, M(H) determines consumer mortality, and P(R) and L(R, H, F)114 are functions describing the growth and consumption-loss of resources, respectively. 115 If the system is written in this generalized manner, we cannot solve for the steady state 116 solution (F^*, H^*, R^*) , however we can normalize the system to the unknown steady states. 117 We denote normalized variables and functions in lowercase, such that $f = F/F^*$, $h = H/H^*$, 118 $r = R/R^*$, and for example the normalized mortality function $m(h) = M(H)/M^*$, where M^* 119 is shorthand for $M(H^*)$. Additional rearrangements of terms under equilibrium conditions 120 allows us to define two additional sets of scaling parameters with intuitive biological proper-121 ties: the turnover rates of full foragers, hungry foragers, and the resource $(\alpha_f, \alpha_h, \alpha_r)$, and 122 the proportional branching biomass through different compartments of the model, generally 123 designated by the parameter β . For instance, β_f is the proportion of full consumer growth 124 due to reproduction, whereas $(1 - \beta_f)$ is the proportion of full consumer growth due to re-125 cruitment from the hungry forager class. Similarly, β_h is the proportion of hungry consumer 126 loss due to mortality, whereas $(1 - \beta_h)$ is the proportion of hungry consumer loss due to 127 recruitment into the full consumer class (see SUPP for a detailed derivation). Substituting 128 the normalized variables and functions into Eq. 5, we obtain 129

where G(F) determines consumer growth, S(R, H) and K(R, F) are the recovery and starva-

$$\dot{f} = \alpha_f \left[\beta_f g(f) + (1 - \beta_f) s(r, h) - k(r, f) \right],$$

$$\dot{h} = \alpha_h \left[k(r, f) - (1 - \beta_h) s(r, h) - \beta_h m(h) \right],$$

$$\dot{r} = \alpha_r \left[p(r) - l(r, h, f) \right],$$
(5)

and linearization of this normalized, general ODE system yields the Jacobian matrix

$$\mathbf{J}_{\text{gen}}|_{*} = \begin{pmatrix} \alpha_{f} \left(\beta_{f} \frac{\partial g}{\partial f} - \frac{\partial k}{\partial f} \right) & \alpha_{f} (1 - \beta_{f}) \frac{\partial s}{\partial h} & \alpha_{f} \left((1 - \beta_{f}) \frac{\partial s}{\partial r} - \frac{\partial k}{\partial r} \right) \\ \alpha_{h} \frac{\partial k}{\partial f} & -\alpha_{h} \left(\beta_{h} \frac{\partial m}{\partial h} + (1 - \beta_{h}) \frac{\partial s}{\partial h} \right) & \alpha_{h} \left(\frac{\partial k}{\partial r} - (1 - \beta_{h}) \frac{\partial s}{\partial r} \right) \\ -\alpha_{r} \frac{\partial l}{\partial f} & -\alpha_{r} \frac{\partial l}{\partial h} & \alpha_{r} \left(\frac{\partial p}{\partial r} - \frac{\partial l}{\partial r} \right) \end{pmatrix}. \tag{6}$$

Due to the normalization procedure, the partial derivatives in Eq. 8 have tangible biologi-131 cal meaning. Because, for example, the partial derivative (containing functions and variables 132 normalized to the unknown steady states) $\partial g/\partial f = \partial \log G/\partial \log F$, it scales in such a way 133 that it represents the percent change in consumer growth (governed by G(F)) relative to a percent change in the density of full consumers F, more commonly known as a functional 135 elasticity. For example, if growth is a linear function (e.g. $G(F) = \lambda F$), $\partial g/\partial f = 1$; if growth 136 is a quadratic function (e.g. $G(F) = \lambda F^2$), $\partial g/\partial f = 2$, while more complex functions may 137 depend on the value of the steady state. For example, if consumer growth is modeled as 138 Holling Type II growth, such that $G(F) = c_1 F^2/(c_2 + F^2)$, where c_1 and c_2 are unknown constants, then its elasticity will vary between 0 and 2, depending on the steady state value 140 F^* , which is unknown in the generalized system. 141

Deriving a Jacobian in terms of the normalized ODE system is useful because it allows

us to place strict constraints on the values of the unknown variables (the turnover rates, biomass branching parameters, and the functional elasticities), without assuming detailed 144 knowledge of the functions controlling different rates within the system. In addition, we can now insert a number of assumptions that will align our generalized Jacobian more closely 146 with the original 2-stage consumer resource system. We will assume the following: i) both 147 the consumer and resource suffers linear mortality, ii) resource growth is logistic, iii) recovery 148 and starvation are linear with respect to both full and hungry consumer densities, and iv) 149 consumers and resources have equivalent turnover rates scaled to unity. These assumptions 150 lead to the following simplifications 151

$$i) \frac{\partial m}{\partial h} = 1, \qquad \frac{\partial l}{\partial r} = 1, \qquad \frac{\partial l}{\partial f} = 1 - \frac{\partial l}{\partial h},$$

$$ii) \frac{\partial k}{\partial r} = \left(1 - \frac{1}{R^*}\right)^{-1},$$

$$iii) \frac{\partial s}{\partial r} = \frac{\partial s}{\partial h} = 1, \frac{\partial k}{\partial f} = 1,$$

$$iv) \alpha_f = \alpha_r = 1,$$

$$(7)$$

where R^* ranges from 0 to 1. The remaining free parameters include the timescale of hungry foragers α_h , the branching parameters β_f and β_h , the elasticity of consumer growth with respect to full consumer densities $\partial g/\partial f$, the elasticity of resource growth with respect to resource density $\partial p/\partial r$, the elasticity of resource loss with respect to full consumer density $\partial l/\partial f$, and the elasticity of starvation with respect to resource density $\partial k/\partial r$. See Table XX for a list of the free parameters in the generalized model, as well as the ranges of potential values for each. These substitutions result in the simplified Jacobian matrix

$$\mathbf{J}_{\text{gen}}|_{*} = \begin{pmatrix} \left(\beta_{f} \frac{\partial g}{\partial f} - 1\right) & \left(1 - \beta_{f}\right) & \left(\left(1 - \beta_{f}\right) \frac{\partial s}{\partial r} - 1\right) \\ \alpha_{h} & -\alpha_{h} & -\alpha_{h} \left(1 - \frac{\partial k}{\partial r} - \beta_{h}\right) \\ \frac{\partial l}{\partial h} - 1 & -\frac{\partial l}{\partial h} & \left(\frac{\partial p}{\partial r} - 1\right) \end{pmatrix}. \tag{8}$$

Because the remaining free parameters have known ranges, but not specific values, we 159 wish to assess the correlations of each to system stability. By randomly drawing values from 160 uniform distributions bounded by the known ranges of each free parameter, we obtain an 161 ensemble of potential Jacobian matrices whereupon the stability of each is determined by 162 numerically calculating the real part of the leading eigenvalue. If the real part of the leading 163 eigenvalue is $< 1 \times 10^{-6}$, we assumed the system to be stable. Replicating this procedure on 164 the order of 10⁷ times allowed us to determine the correlation of each free parameter with 165 stability to the extent that variance was negligible. 166

¹⁶⁷ 2.3 Allometric scaling relationships

Nearly all of the rates described in the specific model, and generalized upon in the generalized model, are to some extent governed by the body size of the consumer. The scaling relationship between an organism's metabolic rate B and its body size at reproductive maturity M plays a central role in other scaling relationships. Organismal metabolic rate B is known to scale as $B = B_0 M^{\eta}$, where η is the scaling exponent, generally assumed to be 3/4 for metazoans, etc. Kempes et al. [REF] show how the population-level growth rate also can be related to body size as $\lambda = \lambda_0 M^{\eta-1}$.

Population growth requires that individuals

176 3 Results

$_{77}$ 3.1 2-stage consumer resource model

Analysis of the continuous-time 2-stage consumer resource model shows that the equilibrial 178 states of both populations are highly sensitive to changes in starvation and recovery rates of 179 the consumer. The consumer and resource population densities vary inversely: when the 180 consumer densities are high, resource densities are low, and vice versa. High starvation and low recovery rates result in low consumer densities and high resource densities. If starvation 182 rates are low, resources have a fixed point near zero for any value of the recovery rate. Full 183 and hungry consumer stages tend have fixed points that are tightly correlated, the extent 184 to which is driven by the similarity of consumer growth and mortality rates; if $\lambda = \mu$, then 185 $F^* = H^*$.

A transcritical bifurcation exists at $\lambda = \sigma$, such that the condition $\sigma > \lambda$ is required for 187 biologically reasonable dynamics. The TC bifurcation occurs in this model because we have 188 assumed that all energetically replete individuals reproduce at the same rate, whereas the 189 traditional Lotka-Volterra dynamic assumes that the reproductive rate of the consumer is 190 scaled to resource density, such that the growth function would be $G(F,R) = \lambda RF$. Thus, the Lotka-Volterra dynamic *implicitly* accounts for starvation in reducing the reproductive 192 rate of the consumer. However, our 2-stage model explicitly accounts for starvation as well 193 as recovery, such that individuals who are not starved should adopt a reproductive rate 194 independent of resource density. 195

The existence of the transcritical bifurcation reveals important biological insight. Reproduction requires maintenance and growth of biological tissues, both of which have strong scaling relationships with body size. Recent work by Kempes et al. [REF] derived the

timescale of reproduction in terms of allometric considerations, where $t_{\lambda} \propto M^{1-\eta}$ (REF). Starvation is the loss of energy required for maintenance, and we have shown it to have a timescale $t_{\sigma} \propto \log(M)$. Accordingly, the timescale of reproduction is always larger than the timescale of starvation, such that $\lambda < \sigma$. A third important parameter in our framework is the rate of recovery. The recovery timescale t_{ρ} controls the rate at which individuals move from the hungry class to the full class, and this requires not only tissue maintenance, but growth, such that it is bounded on the short side by t_{σ} . Moreover, [why is recovery timescale bounded on the high side], such that it is bounded on the long side by t_{λ} .

We have used scaling relationships between tissue turnover and growth to strictly constrain 5/6 population-level parameters in our 2-stage consumer resource model (including
the mortality rate t_{μ} , which we have shown is just a xxx of t_{σ}). This exercise accomplishes
two goals: 1) it allows us to constrain the plausible parameter space of the two-stage model,
and 2)

This allows us to derive many aspects of the system in terms of consumer body mass M and the allometric scaling exponent η .

²¹⁴ 3.2 Generalized analysis

Constraining the model with allometric scaling relationships yields important insights regarding the tradeoff between [fitness and energy]

²¹⁷ 4 Discussion

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