## Asymptotic Notation Divide and Conquer Comparison Sorts II

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# Unit Overview Algorithmic Efficiency & Sorting

### **Topics**

- Analysis of Algorithms
- Introduction to Sorting
- Comparison Sorts I
  - Asymptotic Notation
  - Divide and Conquer
  - Comparison Sorts II
  - The Limits of Sorting
  - Comparison Sorts III
  - Non-Comparison Sorts
  - Sorting in the C++ STL

## Review

# Review Analysis of Algorithms [1/2]

### **Efficiency**

- General meaning. Using few resources: time, space, etc.
- Specific meaning. Fast (not using much time).
- For other kinds of efficiency, we qualify: space efficiency, etc.
- Unless we say otherwise, we are talking about the worst case: maximum resource usage—usually for a given input size.

### Our **model of computation** includes:

- Legal operations: what we are allowed to do.
- Basic operations: the operations we count.
- How we measure the size of the input.

Scalable: works well with large problems. (Or, it scales well.)

	Using Big-O	In Words	
Cannot read all of input	O(1)	Constant time	
	<i>O</i> (log <i>n</i> )	Logarithmic time	Faste
	O(n)	Linear time	
	<i>O</i> ( <i>n</i> log <i>n</i> )	Log-linear time	Slow
Probably \( \psi \) not scalable	$O(n^2)$	Quadratic time	
not scalable *	$O(c^n)$ , for some $c > 1$	Exponential time	

### **Rule of Thumb**

For nested "real" loops (we do not count, for example, a loop executed only a fixed number of times) order is  $O(n^t)$ , where t is the number of nested loops.

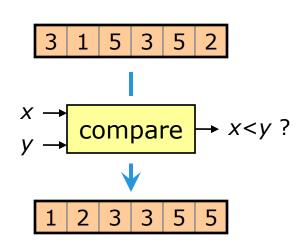
## Review Introduction to Sorting — Basics, Analyzing

**Sort**: Place a list in order.

**Key**: The part of the item we sort by.

**Comparison sort**: Sorting algorithm that only gets information about item by comparing them in pairs.

A general-purpose comparison sort places no restrictions on the size of the list or the values in it.



Analyzing a general-purpose comparison sort:

- (Time) Efficiency
- Requirements on Data
- Space Efficiency <
- Stability <
- Performance on Nearly Sorted Data ← 1. All items close to proper places,

**In-place** = no large additional space required.

**Stable** = never reverses the relative order of equivalent items.

- OR
- 2. few items out of order.

# Review Introduction to Sorting — Overview of Algorithms

### Sorting Algorithms Covered

- Quadratic-Time [O(n²)] Comparison Sorts
  - ✓ Bubble Sort
  - ✓ Insertion Sort
    - Quicksort
- Log-Linear-Time [O(n log n)] Comparison Sorts
  - Merge Sort
  - Heap Sort (mostly later in semester)
  - Introsort
- Special Purpose—Not Comparison Sorts
  - Pigeonhole Sort
  - Radix Sort

## Review

### Comparison Sorts I — Bubble Sort

**Bubble Sort** proceeds in a number of **passes**, each of which "bubbles" a large item to the top by doing compare/swap on pairs of consecutive items.

### 3 4 1 7 5 2 This pair is next (as 6 & 5).

### **Analysis**

- (Time) Efficiency:  $O(n^2)$ . Average case same.  $\odot$
- Requirements on Data: Works for Linked Lists, etc.
- Space Efficiency: In-place. ©
- Stability: It is stable. ©
- Performance on Nearly Sorted Data: ⊕/⊕
  - O(n) for type 1 (all close).  $\odot$
  - $O(n^2)$  for type 2 (few wrong).  $\otimes$

#### Note

Too slow. Do not use in practice.

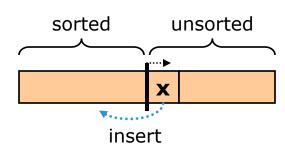
See bubble\_sort.cpp.

Swap?

Yes

# Review Comparison Sorts I — Insertion Sort [1/2]

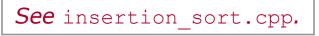
### **Insertion Sort** repeatedly does this:



### **Analysis**

- (Time) Efficiency:  $O(n^2)$ . Average case same.  $\odot$
- Requirements on Data: Works for Linked Lists, etc. ©
- Space Efficiency: In-place. ©
- Stability: It is stable. ©
- Performance on Nearly Sorted Data: O(n) for both kinds. ☺

#### **Notes**



- Too slow for most use cases.
- Fast in special cases: nearly sorted data and small lists.
- Thus, often used as part of other algorithms.

std::move (<utility>) takes one argument, which it casts to an Rvalue. Use it to force move construction/assignment.

```
a = b;  // Does a copy
a = move(b); // Does a move
```

std::move does not move anything!
It casts to an Rvalue, which makes
a non-const argument **movable**.

The second line of code above is often faster. However, when we do it, we are making an implicit promise: we will not use the current value of b again.

There is another std::move, in <algorithm>, taking 3 arguments. It is the move version of std::copy.

## **Asymptotic Notation**

Recall our definition of big-O:

Algorithm A is **order** f(n) [written O(f(n))] if there exist constants k and  $n_0$  such that algorithm A performs no more than  $k \times f(n)$  basic operations when given input of size  $n \ge n_0$ .

The fundamental idea here actually has little to do with algorithms.

Rather, this is a method for talking about *how quickly a function* grows—a mathematical function, that is.

We have applied this idea to the (mathematical) function that tells the maximum number of steps an algorithm takes for input of a given size.

But we could apply it to other things, too.

# Asymptotic Notation Big-O More Generally — Definition

Suppose we have nonnegative real-valued functions f and g on the nonnegative integers. That is, for each nonnegative integer n, f(n) and g(n) are nonnegative real numbers.

We say g(n) is O(f(n)) if there exist constants k and  $n_0$  such that  $g(n) \le k \times f(n)$ , whenever  $n \ge n_0$ . Big-O is an example of **asymptotic notation**: it is about what happens when a number (often n) gets arbitrarily large.

	1	n	n log n	n <sup>2</sup>	5 <i>n</i> <sup>2</sup>	$n^2 \log n$	$n^3$	n <sup>4</sup>
$O(n^2)$	???	???	???	???	???	???	???	???

Our earlier definition of big-O is a special case: let g(n) be the maximum number of basic operations required to execute algorithm A for input of size n.

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# Asymptotic Notation Big-O More Generally — Applications

We can now use big-O for other concepts—for example, space efficiency.

We have defined **in-place** to be the same as O(1) additional space (**additional** = beyond the space required by its input).

So in-place means constant additional space.

Bubble Sort and Insertion Sort use O(1), that is, constant, additional space.

So does Binary Search, if the recursion is eliminated. Otherwise, it uses *logarithmic* additional space for the recursion.

Our next sorting algorithm can use more than this.

## Asymptotic Notation Omega

Another kind of asymptotic notation:  $\Omega$  (Omega).

```
We say g(n) is \Omega(f(n)) if there exist constants k and n_0 such that g(n) \ge k \times f(n), whenever n \ge n_0.
```

The definition of big-*O* has "≤" here.

	1	n	n log n	n <sup>2</sup>	5 <i>n</i> <sup>2</sup>	$n^2 \log n$	$n^3$	n <sup>4</sup>
$O(n^2)$	YES	YES	YES	YES	YES	no	no	no
$\Omega(n^2)$	???	???	???	???	???	???	???	???

If we say an algorithm is  $\Omega(f(n))$ , then we mean that, for input of size n, the algorithm's worst-case number of basic operations is at least  $k \times f(n)$ , for some number k, when n is large enough.

Its best-case number of operations may be smaller.

# Asymptotic Notation Theta

One last kind of asymptotic notation:  $\Theta$  (Theta).

```
We say g(n) is \Theta(f(n)) if g(n) is O(f(n)), and g(n) is \Omega(f(n)).
```

The values of k used above may be different.

For example, a function would be  $\Theta(n^2)$  if it always lies between (say)  $3n^2$  and  $7n^2$ , whenever n is large enough.

	1	n	n log n	n <sup>2</sup>	5 <i>n</i> <sup>2</sup>	$n^2 \log n$	n³	n <sup>4</sup>
$O(n^2)$	YES	YES	YES	YES	YES	no	no	no
$\Omega(n^2)$	no	no	no	YES	YES	YES	YES	YES
Θ( <i>n</i> <sup>2</sup> )	???	???	???	???	???	???	???	???

# Asymptotic Notation Summary

Three ways to say how fast a (mathematical) function grows.

### *g*(*n*) is:

- O(f(n)) if  $g(n) \le k \times f(n)$  ...
- $\Omega(f(n))$  if  $g(n) \ge k \times f(n)$  ...

 $\Theta$  is very useful!  $\Omega$  not as much, but we *will* use it.

•  $\Theta(f(n))$  if both are true—possibly with different values of k.

	1	n	n log n	n <sup>2</sup>	5 <i>n</i> <sup>2</sup>	$n^2 \log n$	$n^3$	n <sup>4</sup>
$O(n^2)$	YES	YES	YES	YES	YES	no	no	no
$\Omega(n^2)$	no	no	no	YES	YES	YES	YES	YES
$\Theta(n^2)$	no	no	no	YES	YES	no	no	no

Useful: Let g(n) be the maximum number of basic operations performed by some algorithm when given input of size n.

Or: let g(n) be the maximum amount of additional space some algorithm uses when given input of size n.

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## Divide and Conquer

### Divide and Conquer Algorithmic Strategies

- An <u>algorithmic strategy</u> is a general method for putting together an algorithm.
- Example: split the input into parts and handle each part with a recursive call. This idea, called **Divide and Conquer**, is used by a number of fast algorithms.
- A similar idea is used by Binary Search, which splits its input into parts, but only makes a recursive call on *one* of the parts. We call this **Decrease and Conquer**.

See CS 411 for more about these and other algorithmic strategies.

### Questions

- How do we analyze the efficiency of algorithms that use Divide and Conquer or Decrease and Conquer?
- Can we use Divide and Conquer to build an improved sorting algorithm? One faster than  $\Theta(n^2)$ ? (We have not seen any, yet.)

# Divide and Conquer The Master Theorem — Background

Say we are analyzing a recursive algorithm.

- Its worst-case number of operations, for input of size n, is T(n).
- We want to know how fast T(n) grows.

Suppose our algorithm uses Divide/Decrease and Conquer:

- The number of recursive calls it makes is <u>a</u>.
- The size of the dataset passed to each recursive call is n/<u>b</u> (or a nearby integer, if n/b is not an integer).
- Whatever other work the algorithm does requires f(n) operations.

This gives us a recurrence relation:

- T(n) = a T(n/b) + f(n).
  - "n/b" can be a nearby integer.

If the algorithm splits its input into parts of size (about) n/b, then b is the number of parts, and those parts must be (nearly) equal-sized.

Given such a recurrence, we can often determine the order of T(n) using the **Master Theorem**.

#### The **Master Theorem**

Suppose T(n) = a T(n/b) + f(n), where  $a \ge 1$ , b > 1, and f(n) is  $\Theta(n^d)$ .

"n/b" can be a nearby integer.

Compare a to  $b^d$ .

- Case 1. If  $a < b^d$ , then T(n) is  $\Theta(n^d)$ .
- Case 2. If  $a = b^d$ , then T(n) is  $\Theta(n^d \log n)$ .
- Case 3. If  $a > b^d$ , then T(n) is  $\Theta(n^k)$ , where  $k = \log_b a$ .

We may also replace each "Θ" above with "O".

Recall:  $\log_b a$  is the power we would need to raise b to, in order to get a. So  $b^k = a$ .

A typical application of the Master Theorem proceed as follows.

We are analyzing an algorithm that takes input of size *n*. It splits its input into nearly equal-sized parts, and it makes recursive calls, each call handling one of the parts.

Find *b*, *a*, *d*.

- b is the number of nearly equal-sized parts.
- a is the number of recursive calls.
- f(n) is the amount of other work done in the body of the algorithm.
- Write f(n) as  $\Theta(n^d)$  or  $O(n^d)$ .

**Other work** means anything the algorithm does other than making recursive calls.

Compare a to  $b^d$ , and apply the appropriate case: 1, 2, or 3.

# Divide and Conquer The Master Theorem — Example: Efficiency of Searching

Sequential Search is  $\Theta(???)$  (use the Rule of Thumb).

Analyze Binary Search using the Master Theorem:

Assume a random-access dataset.

. . .

Divide/Decrease and Conquer are common ways to get algorithms that are  $\Theta(\log n)$  or  $\Theta(n \log n)$ .

We said that the base of the logarithm does not matter. Why?

• Suppose (for example) that an algorithm takes  $5 \log_2 n$  steps.

This is just a number.

It is about 16.6.

- This algorithm is  $\Theta(\log_2 n)$ .
- Is it also  $\Theta(\log_{10}n)$ ? Yes!

•  $5 \log_2 n = 5(\log_2 10 \times \log_{10} n) = (5 \log_2 10) \times \log_{10} n.$ 

**Fact.** If b and c are greater than 1, then  $\Theta(\log_b n)$  and  $\Theta(\log_c n)$  are the same thing—and similarly for  $O(\log_b n)$  and  $O(\log_c n)$ .

So we generally leave off the base and simply say  $\Theta(\log n)$ ,  $O(\log n)$ ,  $\Theta(n \log n)$ , etc.

## **Comparison Sorts II**

# Comparison Sorts II Merge Sort — Introduction

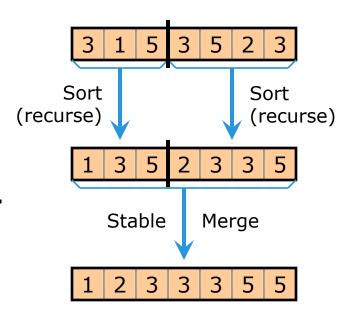
We can use <u>Divide and Conquer</u> to build a better sort.

We are given a list to sort.

Split the list into two parts that are the same size—or nearly so.

Sort each part with a recursive call.

Merge the parts into a single sorted list. Do this without reversing the relative order of equivalent items—that is, in a stable manner: Stable Merge.

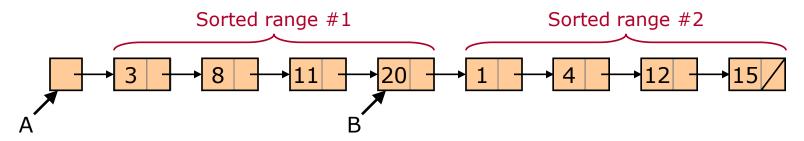


This algorithm is called is **Merge Sort** [John von Neumann, 1945].

# Comparison Sorts II Merge Sort — Merging in a Linked List

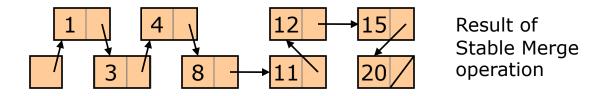
Consider how a Stable Merge would be done.

We can do an efficient Stable Merge of a Linked List in-place.



To merge two sorted ranges within a Linked List:

- Two pointers: A & B. A starts at the head, B at the end of range #1.
- Check whether the item after B's node is less than the item after A's node. If so, remove the item after B's node and re-insert it after A.
  - This uses only pointer operations. We do not move any data items.
- Advance A or B as appropriate and repeat.

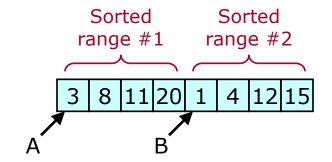


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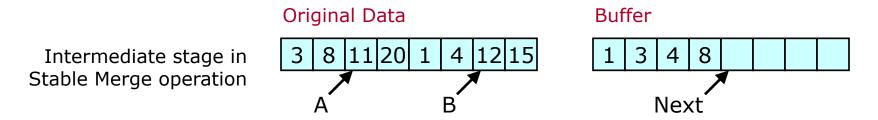
### Comparison Sorts II Merge Sort — General-Purpose Merge

Efficient Stable Merge in an array generally uses a separate buffer.

 This Stable Merge algorithm does not require an array; it works with just about any kind of data.



As before, use two pointers. Check which item comes first, and copy that to the buffer. Advance pointers as appropriate.



At the end, we could copy the buffer back to the original array.

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### Comparison Sorts II Merge Sort — CODE

#### TO DO

- Implement Merge Sort.
  - Make the Stable Merge a separate function. Use the general-purpose Stable Merge algorithm.

See merge sort.cpp.

- Analyze.
  - Coming up.

Note. Our code allocates the buffer every time a Stable Merge is done. It also merges to the buffer and then copies the data back every time. There are ways to handle the Stable Merge more efficiently. However, this simple version of Merge Sort should give us a decent idea of how it works and how fast it is.

## Comparison Sorts II Merge Sort — Analysis [1/3]

We wish to analyze Merge Sort using the Master Theorem. How much "other work" [f(n)] does it do?

In addition to the recursive calls, Merge Sort does:

What???

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## Comparison Sorts II Merge Sort — Analysis [2/3]

Analyze Merge Sort using the Master Theorem

...

## Comparison Sorts II Merge Sort — Analysis [3/3]

```
(Time) Efficiency
???
Requirements on Data
???
Space Efficiency
???
Stability
???
Performance on Nearly Sorted Data
???
```

### Comparison Sorts II Merge Sort — Notes

### Merge Sort has the characteristics we are most interested in:

- It runs in  $\Theta(n \log n)$  time.
- It is stable.
- It works well with different kinds of data—Linked Lists, in particular.
  - Note that it may be written differently for different kinds of data.

### Merge Sort is very practical and is often used.

- Merge Sort is considered to be the fastest known general-purpose comparison sort:
  - When a stable sort is required.
  - When sorting a Linked List.
- Merge Sort is the usual implementation for three of the seven sorting algorithms in the C++ Standard Template Library.

Merge Sort is a good standard to judge sorting algorithms by.