

Advanced Engineering Mathematics

Mini Project 1



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29/09/2024

$$\frac{d^2x}{dt^2} + \alpha \frac{dx}{dt} = j \quad (1)$$

$$\frac{dj}{dt} = -\beta j - \frac{dx}{dt} + u(t) \quad (2)$$

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1.1

We will first differentiate equation (1).

$$\frac{d^3x}{dt^3} + \alpha \frac{d^2x}{dt^2} = \frac{dj}{dt} \quad (3)$$

Then equate what we got to the equation (2).

$$\frac{d^3x}{dt^3} + \alpha \frac{d^2x}{dt^2} = -\beta j - \frac{dx}{dt} + u(t)$$

We now want to isolate j and substitute what we will get into (1).

$$\begin{aligned} j &= -\frac{1}{\beta} \left(\frac{d^3x}{dt^3} + \alpha \frac{d^2x}{dt^2} + \frac{dx}{dt} - u(t) \right) \\ -\beta \frac{d^2x}{dt^2} - \alpha\beta \frac{dx}{dt} &= \frac{d^3x}{dt^3} + \alpha \frac{d^2x}{dt^2} + \frac{dx}{dt} - u(t) \\ \frac{d^3x}{dt^3} + (\alpha + \beta) \frac{d^2x}{dt^2} + (1 + \alpha\beta) \frac{dx}{dt} &= u(t) \end{aligned} \quad (4)$$

1.2

Based on the equation (4) we will construct the transfer function, assuming that $u(t) = e^{st}$

$$H(s) = \frac{1}{s^3 + (\alpha + \beta)s^2 + (1 + \alpha\beta)s} \quad (5)$$

$$s^3 + (\alpha + \beta)s^2 + (1 + \alpha\beta)s \neq 0.$$

1.3

Now, as we know the actual function $u(t) = \sin(2t)$, we can find general real solution to (4). We will start by finding the particular solution.

$$u(t) = \sin(2t) = \text{Im}(e^{i2t})$$

$$y_{par}(t) = \text{Im}(H(i2)e^{i2t})$$

$$\begin{aligned} H(i2) &= \frac{1}{(2i)^3 + (\alpha + \beta)(2i)^2 + (1 + \beta\alpha)2i} = \frac{1}{-8i - 4(\alpha + \beta) + 2i(1 + \beta\alpha)} = \\ &= \frac{1}{-4(\alpha + \beta) + i(-8 + 2(1 + \beta\alpha))} = \frac{-4(\alpha + \beta) - i(-6 + 2\beta\alpha)}{16(\alpha + \beta)^2 + (-6 + 2\beta\alpha)^2} \\ y_{par}(t) &= \text{Im}\left(\frac{-4(\alpha + \beta) - i(-6 + 2\beta\alpha)}{16(\alpha + \beta)^2 + (-6 + 2\beta\alpha)^2}(\cos(2t) + i\sin(2t))\right) = \\ &= \cos(2t)\left(-\frac{-6 + 2\beta\alpha}{16(\alpha + \beta)^2 + (-6 + 2\beta\alpha)^2}\right) - \sin(2t)\left(\frac{-4(\alpha + \beta)}{16(\alpha + \beta)^2 + (-6 + 2\beta\alpha)^2}\right) \end{aligned}$$

We now need to find general real solution to the homogeneous part.

$$\lambda^3 + (\alpha + \beta)\lambda^2 + \lambda(1 + \alpha\beta) = 0$$

$$\lambda^2 + (\alpha + \beta)\lambda + (1 + \alpha\beta) = 0$$

$$\lambda = \frac{-(\alpha + \beta) \pm \sqrt{\alpha^2 + \beta^2 - 4\beta\alpha - 4}}{2}$$

So we have 3 different λ as the solution to the characteristic polynomial,

$\lambda = 0 / \frac{-(\alpha + \beta) \pm \sqrt{\alpha^2 + \beta^2 - 4\beta\alpha - 4}}{2}$. As we know that alpha and beta are very

small positive numbers, we can state that $\alpha^2 + \beta^2 - 4\beta\alpha - 4 < 0$, therefore,

we have two complex solutions of the form $a + wt$. Thus, a general complex

solution is

$$y_{hom}(t) = c_1 e^{0 \cdot t} + c_2 e^{a+wt} + c_3 e^{a-wt}, \quad c_1, c_2, c_3 \in \mathbb{C}$$

The general complex solution is then

$$y_{hom}(t) = c_1 e^{0 \cdot t} + c_2 \operatorname{Re}(e^{a+wt}) + c_3 \operatorname{Im}(e^{a+wt})$$

$$y_{hom}(t) = c_1 e^{0 \cdot t} + c_2 e^{at} \cos(wt) + c_3 e^{at} \sin(wt) \quad c_1, c_2, c_3 \in \mathbb{R}$$

We can now combine two solutions to get a general real solution to (4).

$$y(t) = y_{hom}(t) + y_{par}(t) = c_1 e^{0 \cdot t} + c_2 e^{at} \cos(wt) + c_3 e^{at} \sin(wt) + A \cos(2t) + B \sin(2t)$$

(6)

Where,

$$A = \frac{6-2\beta\alpha}{16(\alpha+\beta)^2+(-6+2\beta\alpha)^2}$$

$$B = \frac{4(\alpha+\beta)}{16(\alpha+\beta)^2+(-6+2\beta\alpha)^2}$$

$$a = -\frac{\alpha+\beta}{2}$$

$$w = \frac{\sqrt{\alpha^2+\beta^2-4\beta\alpha-4}}{2}$$

1.4

$$v(t) = \frac{dx}{dt}$$

$$\frac{dv(t)}{dt} = j(t) - \alpha v(t)$$

$$\frac{dj}{dt} = -\beta j - v(t) + u(t)$$

Now we can write it in the matrix form with the solution for $x(t)$.

$$\left\{ \begin{array}{l} \begin{bmatrix} \frac{dx}{dt} \\ \frac{dv}{dt} \\ \frac{dj}{dt} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & \alpha & 1 \\ 0 & -1 & -\beta \end{bmatrix} \begin{bmatrix} x \\ v \\ j \end{bmatrix} + u(t) \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ y = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ v \\ j \end{bmatrix} \end{array} \right.$$

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2.1

$$f(t) = z(t) - x(t)$$

Substitute this equation into the given one and simplify.

$$\begin{aligned} & z'''(t) - x'''(t) + (\alpha + \beta)(z''(t) - x''(t)) + \\ & + (1 + \alpha\beta + g_2)(z'(t) - x'(t)) + g_1(z(t) - x(t)) = \\ & = z'''(t) + (\alpha + \beta)z''(t) + (1 + \alpha\beta)z'(t) \\ & - x'''(t) - (\alpha + \beta)x''(t) - (1 + \alpha\beta)x'(t) + g_2(z'(t) - x'(t)) + g_1(z(t) - x(t)) = 0 \end{aligned}$$

It is not hard to see $g_2(z'(t) - x'(t)) + g_1(z(t) - x(t)) = g_1f + g_2f' = u(t)$.

$$x'''(t) + (\alpha + \beta)x''(t) + (1 + \alpha\beta)x'(t) = u(t)$$

We arrived to the same equation (4).

2.2

For this task we will use Theorem 2.47, which implies that if the inhomogeneous system of first-order differential equations is asymptotically stable,

then the homogeneous part is also stable.

So, from Routh-Hurwitz Method we can construct the matrix

$$\begin{bmatrix} \alpha + \beta & g_1 \\ 1 & 1 + \alpha\beta + g_2 \end{bmatrix},$$

All entries and determinant of this matrix must be greater than 0.

$$\det = \alpha + \beta + \alpha^2\beta + \beta^2\alpha + (\alpha + \beta)g_2 - g_1 > 0$$

$$g_2 > -(1 + \alpha\beta)$$

These two conditions can be represented on (g_1, g_2) plane as follows

