Bat Optimization on GPU

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Abstract—The abstract goes here.

A. Pseudo-code

I. Introduction

The bat algorithm was introduced by [1]. It uses the

Many populational optimization algorithms can benefit from

This work attemps to investigate the applicability of GPU parallization on the bat algorithm. Previously some demonstra-

tions of the bat algorithm paralelized on CPU were presented

(reference referece), however, til the day of this publication

It was developed two versions of the algorithm. One that

no implementation of the bat algorithm was found on GPU.

inspiration of microbas to look at their preys.

runs on CPU and the other which uses CPU.

paralization.

Parameters: n, $\alpha \lambda$ Initialize Bats Evaluate fitness bats Selects best

while stop criteria false do

for i=1 to n do

$$f_{i} = f_{min} + (f_{max} - f_{min})\beta, \in \beta[0, 1]$$
$$\vec{v}_{i}^{t+1} = \vec{v}_{i}^{t} + (\vec{x}_{i}^{t} + \vec{x}_{*}^{t})f_{i}$$
$$\vec{x}_{temp} = \vec{x}_{i}^{t} + \vec{v}_{i}^{t+1}$$

if $rand < r_i, rand \in [0, 1]$ then local search

 $\vec{x}_{temp} = \vec{x}_* + \epsilon A_m, \epsilon \in [-1, 1]$ (1)

end if

Single dimension perturbation in x_{temp}

$$\begin{aligned} \textbf{if} a &< A_i^t, a \in [0,1] \\ \vec{x}_i^t &= \vec{x}_{temp} \\ r_i &= exp(\lambda * i) \\ a_i &= a_0 * \alpha^i \end{aligned}$$

end if

Selects best

end for end while

II. BAT DESIGN ON CPU

III. BAT DESIGN ON GPU

In this work the bath algorithm used was the one proposed by [2], since it represents a concrete demonstration of how the bat metha-heuristic.

The CPU version was single threaded.

The random algorightm used was the mersenne twister.

Since the BAT agorithm uses a population of bats, the most intuitive parallization method to apply on it is to use each bat on a GPU core. [?] used a similar method for a GPU implementation for the PSO algorithm.

A. Pseudo-code GPU

Parameters: $n, \alpha \lambda$

Initialize bats assicrously

syncronize threads

Evaluate fitness bats

Selects best

while stop criteria false do

for each thread i

$$f_{i} = f_{min} + (f_{max} - f_{min})\beta, \in \beta[0, 1]$$
$$\vec{v}_{i}^{t+1} = \vec{v}_{i}^{t} + (\vec{x}_{i}^{t} + \vec{x}_{*}^{t})f_{i}$$
$$\vec{x}_{temp} = \vec{x}_{i}^{t} + \vec{v}_{i}^{t+1}$$

if $rand < r_i, rand \in [0, 1]$ then local search

$$\vec{x}_{temp} = \vec{x}_* + \epsilon A_m, \epsilon \in [-1, 1]$$

end if

Single dimension perturbation in x_{temp}

$$\mathbf{if} a < A_i^t, a \in [0, 1]$$
$$\vec{x}_i^t = \vec{x}_{temp}$$
$$r_i = exp(\lambda * i)$$
$$a_i = a_0 * \alpha^i$$

end if

syncronize threads

Selects best

end for

end while

For the GPU version the approach used was the split of each individual in one thread.

The benchmark functions used were the following: ROSENBROOK, SPHERE, SCHWEFEL, ACKLEY, RAS-TRINGIN, GRIEWANK, SHUBER

IV. EXPERIMENT

A. Experiment 1

• Function: Griewank

• Bats: 256

• Iterations: 10000

B. Experiment 2

• Function: Griewank

• **Bats:** 768

• Iterations: 10000

V. RESULTS

A. Device details

The experiments were executed on a machine with the following configuration:

Intel(R) Core(TM) i5-4460 CPU @ 3.20GHz GK208 GeForce GT 720 1024 MB of vram

B. Experiment 1

CPU: 1m4.888sGPU: 0m55.439sSpeedup: 1.16x

C. Experiment 2

CPU: 2m27.902sGPU: 0m21.976s

Speedup: 7x

(2)

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D. Subsection Heading Here

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VI. CONCLUSION

It was observed speedups with big populations. The original BAT was proposed with 40 individuals and the speedups was seen with 250 individuals. The advantages of the algorithm may be tested against a CPU implementation to be fair. With this work it's clear that is possible to speedup the bat methaueristic using GPU but the best results are only achieved by a great population size.

VII. FURTHER WORKS

It may be explored the usage of blocks as representation for the dimensions in which each bat deals.

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