

Tests of Causality between two infinite-order autoregressive series

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Abstract

We propose a test for non-causality at various horizons for infinite-order vector autoregressive. We first introduce multiple horizon infinite-order vector autoregressions which can be approximated by a multiple horizon finite-order vector autoregressions. The order is assumed to increase with the sample size. Under some regularity conditions, we study the estimation of parameters obtained from the approximation of the infinite-order autoregression by a finite-order autoregression. The test can be implemented simply through linear regression methods and do not involve the use of artificial simulations. The asymptotic distribution of the new test statistic is derived under the hypothesis of non-causality at various horizons. An asymptotic power of the test will be studied. Bootstrap procedures are also considered. The methods are applied to a VAR model of the US economy.

Keywords: Causality tests; infinite-order vector autoregressive process; causality; consistency; asymptotic power; bootstrap.

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1 Introduction

The concept of causality introduced by Wiener [22] and Granger [13] is now a basic notion for studying dynamic relationships between time series. The literature on this topic is considerable; see, for example, the reviews of Pierce and Haugh [19], Newbold [18], Geweke [10], Lütkepohl [15] and Gouriéroux and Monfort [12, chapter 10]. The original definition of Granger [13], which is used or adapted by most authors on this topic, refers to the predictability of a variable $X(t)$, where t is an integer, from its own past, the one of another variable $Y(t)$ and possibly a vector $Z(t)$ of auxiliary variables, **one period ahead**: more precisely, we say that Y causes X in the sense of Granger if the observation of Y up

to time t ($Y(\tau) : \tau \leq t$) can help one to predict $X(t+1)$ when the corresponding observations on X and Z are available ($X(\tau), Z(\tau) : \tau \leq t$); a more formal definition will be given below.

Recently, however, Lütkepohl [16] and Dufour and Renault [9] have noted that, for multivariate models where a vector of auxiliary variables Z is used in addition to the variables of interest X and Y , it is possible that Y does not cause X in this sense, but can still help to predict X **several periods ahead**; on this issue, see also Sims [21], Renault, Sekkat and Szafarz [20] and Giles [11]. For example, the values $Y(\tau)$ up to time t may help to predict $X(t+2)$, even though they are useless to predict $X(t+1)$. This is due to the fact that Y may help to predict Z one period ahead, which in turn has an effect on X at a subsequent period. It is clear that studying such indirect effects can have a great interest for analyzing the relationships between time series. In particular, one can distinguish in this way properties of “short-run (non-)causality” and “long-run (non-)causality”.

In that case, Dufour, Pelletier and Renault [8] studied the problem of testing non-causality at various horizons as defined in Dufour and Renault [9] for finite-order vector autoregressive (VAR) models. However, it is usually known that a finite-order VAR process is a rough approximation to the true data generation process (DGP) of a given multivariate time series. Different tests were developed to study causality and orthogonality of two infinite-order autoregressive vector series, see Bouhaddioui and Roy [3], Bouhaddioui and Dufour [4] and [5].

In this paper, we develop a test of non-causality at various horizons as defined in Dufour and Renault [9] for infinite-order autoregressive ($\text{VAR}(\infty)$) series. For a given sample size N , the true $\text{VAR}(\infty)$ model is approximated by a finite order $\text{VAR}(p)$ model where the order p is a function of the sample size N that tends, at some rate, to infinity as N increases.

In such models, the non-causality restriction at horizon one takes the form of the relatively simple zero restrictions on the coefficients of the VAR [see Boudjellaba, Dufour and Roy [2] and Dufour and Renault [9]]. However, as cited in Dufour, Pelletier and Renault [8], non-causality restrictions at higher horizons (greater than or equal to 2) are generally nonlinear, taking the form of zero restrictions on multilinear forms in the coefficients of the VAR. When applying standard test statistics such as Wald-type test criteria, such forms can easily lead to asymptotically singular covariance matrices, so that standard asymptotic theory would not apply to such statistics. Further, calculation of the relevant covariance matrices – which involve the derivatives of potentially large numbers of restrictions – can become quite awkward.

Consequently, we propose simple tests for non-causality restrictions at various horizons [as defined in Dufour and Renault [9]] which can be implemented only through linear regression methods and do not involve the use of artificial simulations [e.g., as in Lütkepohl-Burda [17]]. This will be done, in particular, by considering multiple horizon infinite-

order vector autoregressions [called (∞, h) -autoregressions] which can be approximated by a multiple horizon finite-order vector autoregressions [called (p, h) -autoregressions]. The order p obeys to some constraints and is a function of the sample size. Under some regular conditions, the parameters of interest can be estimated by usual linear methods.

In section 2, we describe the model considered and introduce the notion of infinite-order autoregression at horizon h [or (∞, h) -autoregression] which will be the basis of our method. We study the estimation of parameters obtained from the approximation of the (∞, h) -autoregression by a finite (p, h) -autoregression. In section 3, we study the testing of non-causality at various horizons for infinite-order stationary processes. In section 4, we study the asymptotic power of the test under a specific local alternatives. Finally, in section 5, we conduct a small Monte Carlo experiment in order to study the exact level and power of the test for finite samples.

2 Multiple horizons infinite-order autoregressions

Consider a m -dimensional infinite-order autoregressive process of the form

$$\mathbf{X}_t = \boldsymbol{\mu}_t + \sum_{k=1}^{\infty} \boldsymbol{\pi}_k \mathbf{X}_{t-k} + \mathbf{a}_t, \quad t \in \mathbb{Z}, \quad (2.1)$$

where $\mathbf{X}_t = (X_{1t}, X_{2t}, \dots, X_{mt})'$ is a $m \times 1$ random vector, $\boldsymbol{\mu}_t$ is a deterministic trend, $\sum_{k=1}^{\infty} \|\boldsymbol{\pi}_k\| < \infty$ and $\|\cdot\|$ is the Euclidean matrix norm defined by $\|\mathbf{A}\| = \text{tr}(\mathbf{A}'\mathbf{A})$. We suppose that $\mathbb{E}[\mathbf{a}_s \mathbf{a}_t'] = \delta_{ts} \boldsymbol{\Sigma}$, $\forall t, s \in \mathbb{Z}$ with $\delta_{ts} = 1$ if $t = s$ and 0 elsewhere and $\boldsymbol{\Sigma}$ is positive definite matrix. The innovation process $\{\mathbf{a}_t\}$ satisfies the following assumption

Assumption 2.1. The m -dimensional strong white noise $\mathbf{a} = \{\mathbf{a}_t = (a_{1t}, \dots, a_{mt})'\}$ is such that $\mathbb{E}(\mathbf{a}) = 0$, its covariance regular matrix $\boldsymbol{\Sigma}$ and finite fourth moments.

This usual representation, 2.1, is an autoregression at horizon 1. At time $t + h$, where h is an integer, we can write

$$\mathbf{X}_{t+h} = \boldsymbol{\mu}_t^{(h)} + \sum_{k=1}^{\infty} \boldsymbol{\pi}_k^{(h)} \mathbf{X}_{t+h-k} + \sum_{j=0}^{h-1} \boldsymbol{\psi}_j \mathbf{a}_{t+h-j}, \quad t \in \mathbb{Z},$$

where $\boldsymbol{\psi}_0 = \mathbb{I}_m$ is the $(m \times m)$ identity matrix. The appropriate formulas for the coefficients $\boldsymbol{\pi}_k^{(h)}$, $\boldsymbol{\mu}_t^{(h)}$ and $\boldsymbol{\psi}_j$ are given in Dufour and Renault [9] and Dufour, Pelletier and Renault [8]. We can also write that equation in the following way

$$\mathbf{X}_{t+h}' = \boldsymbol{\mu}_t^{(h)'} + \mathbf{X}(t)' \boldsymbol{\pi}^{(h)} + \mathbf{u}_{t+h}', \quad t \in \mathbb{Z}, \quad (2.2)$$

where $\mathbf{X}(t)' = [\mathbf{X}_t', \mathbf{X}_{t-1}', \dots]$, $\boldsymbol{\pi}^{(h)} = [\boldsymbol{\pi}_1^{(h)}, \boldsymbol{\pi}_2^{(h)}, \dots]'$ and $\mathbf{u}_{t+h}' = \sum_{j=0}^{h-1} \boldsymbol{\psi}_j \mathbf{a}_{t+h-j}$. We call 2.2 an "infinite-order autoregression at horizon h ". We suppose that the deterministic part of such autoregression is a linear function of a finite-dimensional parameter

vector, *i.e.*

$$\boldsymbol{\mu}_t^{(h)} = \gamma(h)D_t^{(h)} \quad (2.3)$$

where $\gamma(h)$ is a $m \times n$ coefficient vector and $D_t^{(h)}$ is a $n \times 1$ vector of deterministic regressors. If $\boldsymbol{\mu}_t$ is a constant vector, then $\boldsymbol{\mu}_t^{(h)}$ is also a constant vector which can be denoted by $\boldsymbol{\mu}_t^{(h)} = \mu_h$.

Based on realization $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_T$ of length T , we fit an autoregression model of order p , whose coefficients are denoted by $\boldsymbol{\pi}_{1,p}^{(h)}, \dots, \boldsymbol{\pi}_{p,p}^{(h)}$ and we can write

$$\boldsymbol{\pi}^{(h)}(p) = \left[\boldsymbol{\pi}_{1,p}^{(h)}, \dots, \boldsymbol{\pi}_{p,p}^{(h)} \right]'. \quad (2.4)$$

If we define by

$$\boldsymbol{\Pi}^{(h)}(p) = \begin{bmatrix} \gamma(h)' \\ \boldsymbol{\pi}^{(h)}(p) \end{bmatrix} = \left[\Pi_1^{(h)}(p), \Pi_2^{(h)}(p), \dots, \Pi_p^{(h)}(p) \right]$$

the corresponding least square estimator $\hat{\boldsymbol{\Pi}}^{(h)}(p)$ is given by

$$\hat{\boldsymbol{\Pi}}^{(h)}(p) = \left[\overline{\mathbf{X}}_p(h)' \overline{\mathbf{X}}_p(h) \right]^{-1} \overline{\mathbf{X}}_p(h)' \mathbf{x}_h^{(h)} \quad (2.5)$$

$$\text{where } \mathbf{x}_h^{(k)} = \begin{bmatrix} \mathbf{X}'_{0+h} \\ \mathbf{X}'_{1+h} \\ \vdots \\ \mathbf{X}'_{T-k+h} \end{bmatrix}, \quad \overline{\mathbf{X}}_p(k) = \begin{bmatrix} \mathbf{X}(0,p)' \\ \mathbf{X}(1,p)' \\ \vdots \\ \mathbf{X}(T-k,p)' \end{bmatrix}_{(T-k+1) \times (n+mp)},$$

$$\mathbf{X}(t,p) = \begin{bmatrix} D_t^{(h)'} \\ \mathbf{X}_t(p) \end{bmatrix}_{(n+mp) \times 1}, \quad \mathbf{X}_t(p)' = [\mathbf{X}_t', \mathbf{X}_{t-1}', \dots, \mathbf{X}_{t-p+1}'].$$

In the sequel, we state the following assumptions.

Assumption 2.2. p is a function of T such that

$$p \rightarrow \infty, \quad \frac{p^3}{T} \rightarrow 0 \text{ and } \sqrt{T} \sum_{j=p+1}^{\infty} \|\boldsymbol{\pi}_j\| < \infty \text{ as } T \rightarrow \infty. \quad (2.6)$$

To derive the asymptotic properties of $\hat{\boldsymbol{\pi}}^{(h)}(p)$, we can also express the OLS estimator as

$$\hat{\boldsymbol{\Pi}}^{(h)}(p) = \hat{\boldsymbol{\Gamma}}_{1,p}' \hat{\boldsymbol{\Gamma}}_p^{-1}, \quad (2.7)$$

where $\hat{\boldsymbol{\Gamma}}_{1,p} = (T-p)^{-1} \sum_{t=p+1}^{T-h} \mathbf{X}_t(p) \mathbf{X}_t'$ and $\hat{\boldsymbol{\Gamma}}_p = (T-p)^{-1} \sum_{t=p+1}^{T-h} \mathbf{X}_t(p) \mathbf{X}_t(p)'$.

The consistency rate of $\hat{\boldsymbol{\Pi}}^{(h)}(p)$ is given in the following proposition.

Proposition 2.1. *Let $\{\mathbf{X}_t\}$ be a process given by (2.2) and satisfying the Assumption 2.1. Under the Assumption 2.2, the estimator $\hat{\Pi}^{(h)}(p)$ defined by (2.7) is such that*

$$\|\hat{\Pi}^{(h)}(p) - \Pi^{(h)}(p)\| = O_p\left(\frac{p^{1/2}}{T^{1/2}}\right).$$

Now, if we suppose that the process \mathbf{X}_t is second-order stationary, we define the auto-covariance matrix at lag k by $\Gamma(k) = \mathbb{E}(\mathbf{X}_t \mathbf{X}_{t+k}')$, $k \in \mathbb{Z}$.

3 Tests of causality for an infinite-order stationary h -autoregressions

Let us now consider the following hypothesis

$$\mathcal{H}_0(h) : \mathbf{R}\Pi_i^{(h)} = 0, \quad i = 1, 2, \dots,$$

where \mathbf{R} is a $q \times (n + mp)$ matrix of rank q . In particular, as mentioned in Dufour, Pelletier and Renault [8], if we wish to test the hypothesis that x_{jt} does not cause x_{it} at horizon h , the restriction would take the form

$$\mathcal{H}_{j \rightarrow i}^{(h)} : \pi_{ijk}^{(h)} = 0, \quad k = 1, 2, \dots,$$

where $\pi_k^{(h)} = \left[\pi_{ijk}^{(h)} \right]_{i,j=1,\dots,m}$, $k = 1, 2, \dots$

From the model (2.2) and from the equation (2.7), we have

$$\text{vec}(\hat{\Pi}^{(h)}(p)) = \text{vec} \left\{ \left[(T-p)^{-1} \sum_{t=p+1}^{T-h} \mathbf{X}_t(p) \mathbf{X}_t'(p) \right] \left[(T-p)^{-1} \sum_{t=p+1}^{T-h} \mathbf{X}_t(p) \mathbf{X}_t(p)' \right] \right\}.$$

If we denote by

$$\begin{aligned} \mathbf{W}_{1T} &= \text{vec} \left[(T-p)^{-1} \sum_{t=p+1}^{T-h} \mathbf{u}_{t+h} \mathbf{X}_t'(p) \right] \\ \mathbf{W}_{2T} &= \text{vec} \left[(T-p)^{-1} \sum_{t=p+1}^{T-h} \{ \mathbf{u}_{t+h}(p) - \mathbf{u}_{t+h} \} \mathbf{X}_t'(p) \right], \end{aligned}$$

where $\mathbf{u}_{t+h}(p) = \mathbf{X}_{t+h}' - \mathbf{X}_t'(p) \Pi^{(h)}(p)$, and under the hypothesis \mathcal{H}_0 , we have

$$(\mathbb{I}_p \otimes \mathbf{R}) \text{vec}(\hat{\Pi}^{(h)}(p)) = (\mathbb{I}_p \otimes \mathbf{R}) (\hat{\Gamma}_p^{-1} \otimes \mathbb{I}_m) (\mathbf{W}_{1T} + \mathbf{W}_{2T}),$$

which can be also decomposed as

$$\begin{aligned} (\mathbb{I}_p \otimes \mathbf{R}) \text{vec}(\hat{\Pi}^{(h)}(p)) &= (\mathbb{I}_p \otimes \mathbf{R}) (\Gamma_p^{-1} \otimes \mathbb{I}_m) \mathbf{W}_{1T} + (\mathbb{I}_p \otimes \mathbf{R}) (\Gamma_p^{-1} \otimes \mathbb{I}_m) \mathbf{W}_{2T} \\ &\quad + (\mathbb{I}_p \otimes \mathbf{R}) \{ (\hat{\Gamma}_p^{-1} - \Gamma_p^{-1}) \otimes \mathbb{I}_m \} (\mathbf{W}_{1T} + \mathbf{W}_{2T}) \\ &= \mathbf{A}(p) + \mathbf{B}_1(p) + \mathbf{B}_2(p) \\ &= \mathbf{A}(p) + \mathbf{B}(p). \end{aligned} \tag{3.1}$$

Also, we denote by $\Sigma_u^{(h)}$ the covariance matrix of $\{\mathbf{u}_t^{(h)}\}$ and $\hat{\Sigma}_u^{(h)}$ is its estimator such that

$$\sqrt{T}(\hat{\Sigma}_u^{(h)} - \Sigma_u^{(h)}) \xrightarrow{L} N(0, \Omega_h) \quad (3.2)$$

where \xrightarrow{L} denotes convergence in law and Ω_h is a given matrix. The test statistic is based on the following quadratic form

$$\mathcal{T}(\hat{\mathbf{u}}^{(h)}, \hat{\Sigma}_u^{(h)}) = T\hat{\pi}^{(h)}(p)'(\mathbb{I}_p \otimes \mathbf{R})'\hat{\Delta}_{p,h}^{-1}(\mathbb{I}_p \otimes \mathbf{R})\hat{\pi}^{(h)}(p) \quad (3.3)$$

where $\hat{\pi}^{(h)}(p) = \text{vec}(\hat{\Pi}^{(h)}(p))$ and $\hat{\Delta}_{p,h} = (\mathbb{I}_p \otimes \mathbf{R})(\hat{\Gamma}_p^{-1} \otimes \hat{\Sigma}_u^{(h)})(\mathbb{I}_p \otimes \mathbf{R}')$. Now, we consider the following statistic test which is a standardized version of $\mathcal{T}(\hat{\mathbf{u}}^{(h)}, \hat{\Sigma}_u^{(h)})$ given by

$$\mathcal{Q}_T^{(h)} = \frac{\mathcal{T}(\hat{\mathbf{u}}^{(h)}, \hat{\Sigma}_u^{(h)}) - pq}{\sqrt{2pq}} \quad (3.4)$$

The main result to test the non-causality is stated in the following theorem.

Theorem 3.1. *Let $\{\mathbf{X}_t\}$ be a process given by (2.2) and satisfying the Assumption 2.1. If the order p satisfies the Assumption 2.2 and under any hypothesis of the form $\mathcal{H}_0(h)$, we have*

$$\mathcal{Q}_T^{(h)} \xrightarrow{L} N(0, 1).$$

Proof. Using the decomposition (3.1), we start by defining the pseudo-statistic

$$\mathcal{T}_T^{(h)} = T\mathbf{A}(p)'\Delta_{p,h}^{-1}\mathbf{A}(p)$$

where $\Delta_{p,h} = (\mathbb{I}_p \otimes \mathbf{R})(\Gamma_p^{-1} \otimes \Sigma_u^{(h)})(\mathbb{I}_p \otimes \mathbf{R}')$. Thus, we can write

$$\mathcal{Q}_T^{(h)} = \frac{\mathcal{T}_T^{(h)} - pq}{\sqrt{2pq}} + \frac{T\mathcal{Z}_p^{(h)}}{\sqrt{2pq}}, \quad (3.5)$$

where

$$\mathcal{Z}_p^{(h)} = \mathbf{A}(p)'\{\hat{\Delta}_{p,h}^{-1} - \Delta_{p,h}^{-1}\}\mathbf{A}(p) + 2\mathbf{A}(p)'\hat{\Delta}_{p,h}^{-1}\mathbf{B}(p) + \mathbf{B}(p)'\hat{\Delta}_{p,h}^{-1}\mathbf{B}(p).$$

The asymptotic distribution of $\mathcal{Q}_T^{(h)}$ follows from the next two propositions. The proof is given in the appendix of a technical report available from the author (Bouhaddioui and Dufour [6]).

Proposition 3.1. *Under the assumptions of Theorem 3.1, we have that*

$$\mathcal{Z}_p^{(h)} = o_p\left(\frac{p^{1/2}}{T}\right).$$

Proposition 3.2. *Under the assumptions of Theorem 3.1, we have that*

$$\frac{\mathcal{T}_T^{(h)} - pq}{\sqrt{2pq}} \xrightarrow{L} N(0, 1).$$

□

4 Local asymptotic power

Let consider the series of local alternative hypothesis

$$\mathcal{H}_{\varphi_p(T)}(h) : \mathbf{R}\Pi_i^{(h)} = \varphi_i(T), \quad i = 1, 2, \dots,$$

where $\varphi_p(T) = \text{vec}(\varphi_1(T), \dots, \varphi_p(T)) = T^\kappa \text{vec}(\varphi_1, \dots, \varphi_p) = \varphi_p$ and $\|\varphi_i(T)\| \rightarrow 0$ as $T \rightarrow \infty$. We can give the following theorem which characterizes the local power behavior of the test for the particular class of local alternatives designed by $\mathcal{H}_{\varphi_p(T)}(h)$. The proof is given in the appendix of a technical report available from the author (Bouhaddioui and Dufour [6]).

Theorem 4.1. *Let $\{X_t\}$ be a process given by (2.2) and satisfying the Assumption 2.1. If the order p satisfies the Assumption 2.2 and under the local alternative hypothesis of the form $\mathcal{H}_{\varphi_p(T)}(h)$ with $\varphi_p(T) = T^{-1/2}\varphi_p$, we have*

$$\frac{\mathcal{Q}_T^{(h)} - \mu_{\varphi_p}^{(h)}}{\sigma_p^{(h)}} \xrightarrow{L} N(0, 1)$$

where $\mu_{\varphi_p}^{(h)} = \frac{\varphi_p' \Delta_{p,h}^{-1} \varphi_p}{\sqrt{2pq}}$ and $\sigma_p^{(h)} = \sqrt{1 + \mu_{\varphi_p}^{(h)}}$.

5 Empirical illustration and Simulation

In this section, we present an application of these causality tests at various horizons to macroeconomic time series. The data set considered is the one used Bernanke and Mihov [1] and Dufour, Pelletier and Renault [8] in order to study United States monetary policy. The data set considered consists of monthly observations on nonborrowed reserves (NBR, also denoted ω_1), the federal funds rate (r , ω_2), the GDP deflator (P , ω_3) and real GDP (GDP , ω_4). The monthly data on GDP and GDP deflator were constructed by state space methods from quarterly observations [for more details, see Bernanke and Mihov [1]]. The sample goes from January 1965 to December 1996 for a total of 384 observations. In what follows, all variables were first transformed by a logarithmic transformation.

Before performing the causality tests, we must specify the order of the VAR model. First, in order to get apparently stationary time series, all variables were transformed by taking first differences of their logarithms. In particular, for the federal funds rate, this helped to mitigate the effects of possible break in the series in the years 1979-1981. Once the data is made stationary, we use a nonparametric approach for the estimation and Akaike's information criterion to specify the orders of the long VAR(k) models. Using Akaike's criterion for the unconstrained VAR model, which corresponds to four variables, we observe that it is minimized at $k = 16$.

Vector autoregressions of order p at horizon h were estimated as described in section 2 and

the matrix \hat{V}_{ip}^{NW} , required to obtain covariance matrices, were computed. On looking at the values of the test statistics $\mathcal{Q}_T^{(h)}$ and their corresponding p -values at various horizons it quickly becomes evident that the $N(0, 1)$ asymptotic approximation of the statistic $\mathcal{Q}_T^{(h)}$ is very poor. Now, let consider the GDP as the VAR(16) estimated with our data in first difference but we impose that some coefficients are zero such that the federal funds rate does not cause GDP up to horizon h and then we test the $r \xrightarrow{h} GDP$ hypothesis. The constraints of non-causality from j to i up to horizon h that we impose are

$$\hat{\pi}_{ijl} = 0, \quad 1 \leq l \leq p, \quad (5.1)$$

$$\hat{\pi}_{ikl} = 0, \quad 1 \leq l \leq h, \quad 1 \leq k \leq m. \quad (5.2)$$

Rejection frequencies for this case are given in Table 5.1.

In light of these results we computed the p -values by doing a parametric bootstrap, i.e. doing an asymptotic Monte Carlo test based on a consistent point estimate [see Dufour(2006) [7]]. The procedure to test the hypothesis $\omega_j \xrightarrow{h} \omega_i | I_{(j)}$ is the following:

1. An unrestricted VAR(p) model is fitted for the horizon one, yielding the estimates $\hat{\Pi}^{(1)}$ and $\hat{\Sigma}$ for $\Pi^{(1)}$ and Σ . The autoregressive order was obtained by minimizing the AIC criterion for $p \leq P$, where P was fixed to 24.
2. An unrestricted (p, h) -autoregression is fitted by least squares, yielding the estimate $\hat{\Pi}^{(h)}$ of $\Pi^{(h)}$.
3. The test statistic $\mathcal{Q}_T^{(h)}$ for testing non-causality at the horizon h from ω_j to ω_i is computed. We denoted by $\mathcal{Q}_{T,j \rightarrow i}^{(h)}(0)$ the test statistic based on the actual data.
4. N simulated samples from (2.2) are drawn by Monte Carlo methods, using $\Pi^{(h)} = \hat{\Pi}^{(h)}$ and $\Sigma = \hat{\Sigma}$. We impose the constraints of non-causality $\hat{\pi}_{ijk} = 0, k = 1, \dots, p$. Estimates of the impulse response coefficients are obtained from $\hat{\Pi}^{(1)}$ through the relations described in Eq. (2.4). We denote by $\mathcal{Q}_{T,j \rightarrow i}^{(h)}(n)$ the test statistic for $\mathcal{H}_{j \rightarrow i}^{(h)}$ based on n th simulated sample ($1 \leq n \leq N$).
5. The simulated p -value $\hat{p}[\mathcal{Q}_{T,j \rightarrow i}^{(h)}(0)]$ is obtained, where

$$\hat{p}[x] = \{1 + \sum_{n=1}^N \mathcal{I}[\mathcal{Q}_{T,j \rightarrow i}^{(h)}(n) - x]\} / (n + 1),$$

where $\mathcal{I}[x] = 1$ if $x \geq 0$ and $\mathcal{I}[x] = 0$ if $x < 0$.

6. The null hypothesis $\mathcal{H}_{j \rightarrow i}^{(h)}$ is rejected at level α if $\hat{p}[\mathcal{Q}_{T,j \rightarrow i}^{(h)}(0)] \leq \alpha$.
7. Finally, for each nominal level $\alpha = 1\%, 5\%$ and 10% , we obtained from the 2000 realizations (with $N = 999$), the empirical frequencies of rejection of the null hypothesis of non-correlation. The power analysis was conducted in the similar way using the model VAR $_{\delta}$ for different values of δ .

From looking at the results in Table 5.1, we see that we get a much better size control by using this bootstrap procedure. The rejection frequencies over 1000 replications (with $N = 999$) are very close to the nominal size. Although the coefficients ψ_j 's are functions of π_j 's we do not constrain them in the bootstrap procedure because there is no direct mapping from $\pi_k^{(h)}$ to π_k and ψ_j . This certainly produces a power loss but the procedure remains valid because the ψ_j 's are computed with the $\hat{\pi}_k$, which are consistent estimates of the true π_k both under the null and alternative hypothesis. To illustrate that our procedure has power for detecting departure from the null hypothesis of non-causality at a given horizon we ran the following Monte Carlo experiment. We again took a VAR(16) fitted on our data in first differences and we imposed the constraints (5.1)-(5.2) so that there was no causality from r to GDP up to horizon 12. Next the value of one coefficient previously set to zero was changed to induce causality from r to GDP at horizon 4 and higher: $\pi_3(1, 3) = \theta$. As θ increases from zero to one the strength of the causality from r to GDP is higher. Under this setup, we could compute the power of our simulated test procedure to reject the null hypothesis of non-causality at a given horizon. The power curves are plotted as a function of θ for the various horizons. The level of the tests was controlled through the bootstrap procedure. In this experiment we took again $N = 999$ and we did 1000 simulations. These curves are plotted in Bouhaddioui-Dufour (2009) [6]. As expected, the power curves are flat at around 5% for horizons one to three since the null is true for these horizons. For horizons four and up we get the expected result that power goes up as θ moves from zero to one, and the power curves gets flatter as we increase the horizon.

Now that we have shown that bootstrap procedure does have power we present causality tests at horizon one to 24 for every pair of variables in Tables 5.2 and 5.3. For every horizon we have 12 causality tests and we group them by pairs. When we say that a given variable cause or does not cause another, it should be understood that we mean the growth rate of the variables. The p -values are computed by taking $N = 999$. Table 5.4 summarize the results by presenting the significant results at the 5% and 10% levels.

The first thing to notice is that we have significant causality results at short horizons for some pairs of variables while we have it at longer horizons for other pairs. This is an interesting illustration of the concept of causality at horizon h of Dufour and Renault [9]. The instrument of the central bank, the nonborrowed reserves, cause the federal funds rate at horizon one, the prices at horizons 1, 2, 3 and 9 (10% level). It does not cause the other two variables at any horizon and except the GDP at horizon 12 and 16 (10% level) nothing is causing it. We see that the impact of variations in the nonborrowed reserves is over a very short term. Another variable, the GDP, is also causing the federal funds rates over short horizons (one to five months).

An interesting result is the causality from the federal funds rate to the GDP. Over the first few months the funds rate does not cause GDP, but from horizon 3 (up to 20) we do find

Table 5.1: Rejection using the asymptotic distribution $N(0,1)$ with VAR(16)

Asymptotic						Bootstrap					
h	$\alpha = 5\%$	$\alpha = 10\%$	h	$\alpha = 5\%$	$\alpha = 10\%$	h	$\alpha = 5\%$	$\alpha = 10\%$	h	$\alpha = 5\%$	$\alpha = 10\%$
1	22.2	32.2	7	36.9	52.3	1	5.2	9.6	7	4.3	10.8
2	23.4	38.6	8	39.4	55.6	2	4.8	9.3	8	4.1	9.6
3	27.6	40.5	9	42.8	58.4	3	4.9	10.5	9	4.8	9.1
4	31.2	44.2	10	46.6	61.5	4	5.8	11.0	10	5.6	10.7
5	32.7	46.4	11	49.5	63.4	5	6.0	9.8	11	5.4	10.4
6	34.6	48.8	12	53.7	66.8	6	5.3	10.2	12	4.1	9.1

significant causality. This result can easily be explained by, e.g. the theory of investment. Notice that we have following indirect causality. Nonborrowed reserves do not cause GDP directly over any horizon, but they cause the federal funds rate which in turn causes GDP. Concerning the observation that there are very few causality results for long horizons, this may reflect the fact that, for stationary processes, the coefficients of prediction formulas converge to zero as the forecast horizon increases.

Using the results of Proposition 4.5 in Dufour and Renault [9], we know that for the highest horizon that we have to consider is 33 since we have a VAR(16) with four time series. Causality tests for horizons 25 through 33 were also computed but are not reported. Some p -values smaller or equal to 10% are scattered over horizons 30 to 33 but no discernible pattern emerges.

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Table 5.2: Causality tests and simulated p -values for series in first differences (of logarithm) for horizon 1 to 12.

h	1	2	3	4	5	6	7	8	9	10	11	12
$NBR \rightarrow r$	43.584 (0.035)	39.375 (0.064)	28.332 (0.281)	24.268 (0.325)	18.314 (0.412)	20.895 (0.364)	22.745 (0.401)	19.843 (0.267)	21.226 (0.358)	23.054 (0.285)	20.667 (0.257)	18.445 (0.349)
$r \rightarrow NBR$	27.895 (0.267)	25.853 (0.346)	26.933 (0.389)	21.562 (0.420)	22.572 (0.369)	18.942 (0.572)	22.193 (0.357)	49.773 (0.031)	30.381 (0.139)	47.923 (0.073)	36.859 (0.146)	33.287 (0.201)
$NBR \rightarrow P$	52.368 (0.003)	47.329 (0.042)	45.835 (0.063)	40.376 (0.168)	37.289 (0.368)	48.104 (0.043)	42.864 (0.082)	39.249 (0.235)	40.982 (0.189)	35.849 (0.390)	33.457 (0.471)	29.045 (0.569)
$P \rightarrow NBR$	20.347 (0.690)	23.458 (0.562)	25.926 (0.483)	21.285 (0.439)	24.338 (0.523)	26.371 (0.379)	28.912 (0.428)	31.026 (0.284)	32.902 (0.301)	33.954 (0.358)	36.789 (0.274)	35.496 (0.305)
$NBR \rightarrow GDP$	29.267 (0.091)	27.834 (0.285)	22.863 (0.589)	26.891 (0.459)	23.897 (0.672)	20.915 (0.579)	17.983 (0.459)	15.789 (0.631)	20.951 (0.584)	18.937 (0.479)	23.179 (0.395)	25.951 (0.421)
$GDP \rightarrow NBR$	21.894 (0.734)	24.671 (0.657)	26.740 (0.620)	23.934 (0.572)	27.891 (0.495)	36.956 (0.406)	39.034 (0.329)	41.361 (0.279)	20.941 (0.396)	40.921 (0.258)	37.812 (0.185)	42.846 (0.162)
$r \rightarrow P$	36.189 (0.085)	37.228 (0.082)	32.963 (0.201)	30.951 (0.174)	28.954 (0.273)	24.518 (0.246)	27.913 (0.310)	26.841 (0.356)	31.852 (0.274)	38.752 (0.184)	41.954 (0.243)	31.953 (0.361)
$P \rightarrow r$	25.983 (0.571)	18.653 (0.730)	23.841 (0.562)	19.846 (0.638)	17.439 (0.749)	15.742 (0.809)	14.952 (0.761)	12.762 (0.893)	16.529 (0.751)	17.930 (0.650)	19.203 (0.704)	22.391 (0.659)
$r \rightarrow GDP$	30.781 (0.301)	33.610 (0.192)	36.074 (0.072)	42.358 (0.041)	40.227 (0.053)	45.332 (0.017)	63.228 (0.005)	79.225 (0.003)	92.556 (0.001)	98.265 (0.002)	102.347 (0.001)	109.104 (0.002)
$GDP \rightarrow r$	45.274 (0.028)	48.739 (0.031)	43.996 (0.043)	42.337 (0.032)	39.058 (0.045)	37.072 (0.078)	32.916 (0.169)	29.045 (0.291)	30.517 (0.206)	33.928 (0.265)	30.841 (0.178)	34.968 (0.342)
$P \rightarrow GDP$	25.865 (0.468)	26.285 (0.263)	22.324 (0.361)	17.653 (0.635)	14.327 (0.792)	18.462 (0.671)	20.846 (0.530)	24.739 (0.368)	22.894 (0.429)	27.541 (0.404)	23.218 (0.367)	25.431 (0.470)
$GDP \rightarrow P$	27.834 (0.420)	25.719 (0.321)	30.260 (0.165)	37.984 (0.073)	46.228 (0.032)	38.539 (0.082)	36.226 (0.076)	40.338 (0.041)	33.941 (0.234)	28.946 (0.320)	30.860 (0.286)	26.701 (0.346)

Table 5.3: Causality tests and simulated p -values for series in first differences (of logarithm) for horizon 13 to 24.

h	13	14	15	16	17	18	19	20	21	22	23	24
$NBR \rightarrow r$	22.561 (0.658)	20.981 (0.571)	24.376 (0.682)	19.867 (0.561)	23.196 (0.621)	30.458 (0.439)	36.719 (0.429)	42.951 (0.359)	50.983 (0.286)	37.942 (0.461)	32.901 (0.671)	28.937 (0.727)
$r \rightarrow NBR$	53.289 (0.168)	50.921 (0.184)	46.871 (0.238)	42.571 (0.439)	37.682 (0.561)	39.872 (0.459)	33.718 (0.574)	30.791 (0.621)	38.963 (0.566)	48.931 (0.359)	36.916 (0.466)	30.992 (0.554)
$NBR \rightarrow P$	43.985 (0.451)	45.647 (0.362)	40.368 (0.450)	42.389 (0.423)	50.356 (0.278)	41.882 (0.367)	38.649 (0.562)	58.902 (0.239)	60.035 (0.178)	55.341 (0.190)	48.467 (0.254)	45.392 (0.321)
$P \rightarrow NBR$	39.045 (0.376)	36.891 (0.257)	37.841 (0.351)	30.956 (0.567)	25.874 (0.623)	38.904 (0.284)	44.396 (0.326)	42.951 (0.287)	48.903 (0.241)	52.314 (0.189)	47.825 (0.257)	43.671 (0.348)
$NBR \rightarrow GDP$	33.454 (0.561)	28.904 (0.346)	23.456 (0.589)	25.671 (0.420)	20.903 (0.782)	18.793 (0.803)	28.583 (0.634)	23.674 (0.746)	31.083 (0.639)	33.865 (0.549)	39.865 (0.476)	42.347 (0.386)
$GDP \rightarrow NBR$	47.890 (0.345)	53.763 (0.231)	68.256 (0.074)	64.963 (0.081)	52.930 (0.189)	49.045 (0.278)	43.960 (0.348)	40.819 (0.459)	32.489 (0.672)	28.793 (0.758)	33.478 (0.720)	35.672 (0.546)
$r \rightarrow P$	23.856 (0.673)	38.561 (0.385)	37.428 (0.479)	39.045 (0.376)	28.983 (0.654)	30.163 (0.457)	37.439 (0.402)	46.842 (0.376)	50.263 (0.228)	53.980 (0.268)	59.125 (0.128)	55.471 (0.208)
$P \rightarrow r$	24.561 (0.748)	22.174 (0.704)	28.940 (0.629)	30.984 (0.673)	22.895 (0.707)	32.054 (0.579)	20.981 (0.658)	21.267 (0.745)	24.618 (0.569)	34.901 (0.583)	37.279 (0.607)	38.235 (0.564)
$r \rightarrow GDP$	130.742 (0.001)	110.226 (0.001)	95.786 (0.003)	94.893 (0.002)	78.654 (0.031)	85.849 (0.024)	75.356 (0.042)	68.925 (0.063)	63.952 (0.088)	56.476 (0.138)	52.845 (0.204)	55.671 (0.249)
$GDP \rightarrow r$	40.652 (0.367)	37.658 (0.472)	42.398 (0.320)	31.278 (0.539)	26.874 (0.662)	20.210 (0.827)	18.934 (0.869)	20.313 (0.758)	31.682 (0.528)	39.028 (0.458)	41.204 (0.431)	32.571 (0.548)
$P \rightarrow GDP$	11.274 (0.962)	13.256 (0.943)	17.823 (0.895)	21.034 (0.845)	18.920 (0.873)	23.561 (0.742)	27.351 (0.784)	38.419 (0.534)	49.735 (0.356)	55.301 (0.284)	58.247 (0.236)	67.208 (0.174)
$GDP \rightarrow P$	27.361 (0.562)	36.712 (0.358)	32.901 (0.428)	43.561 (0.385)	58.903 (0.273)	48.752 (0.329)	41.328 (0.374)	61.045 (0.268)	63.451 (0.304)	68.201 (0.224)	58.762 (0.287)	54.612 (0.359)

Table 5.4: Summary of Causality relations at various horizons for series in first difference.

h	1	2	3	4	5	6	7	8	9	10	11	12
$NBR \nrightarrow r$	**	*										
$r \nrightarrow NBR$								**		*		
$NBR \nrightarrow P$	**	**	*			**	*					
$P \nrightarrow NBR$												
$NBR \nrightarrow GDP$	*											
$GDP \nrightarrow NBR$												
$r \nrightarrow P$	*	*										
$P \nrightarrow r$												
$r \nrightarrow GDP$			*	**	*	**	**	**	**	**	**	**
$GDP \nrightarrow r$	**	**	**	**	**	*						
$P \nrightarrow GDP$												
$GDP \nrightarrow P$					*	**	*	*	**			
h	13	14	15	16	17	18	19	20	21	22	23	24
$NBR \nrightarrow r$												
$r \nrightarrow NBR$												
$NBR \nrightarrow P$												
$P \nrightarrow NBR$												
$NBR \nrightarrow GDP$												
$GDP \nrightarrow NBR$			*	*								
$r \nrightarrow P$												
$P \nrightarrow r$												
$r \nrightarrow GDP$	**	**	**	**	**	**	**	*	*			
$GDP \nrightarrow r$												
$P \nrightarrow GDP$												
$GDP \nrightarrow P$												

Note: The symbols * and ** indicate rejection of the non-causality hypothesis at the 10% and 5% levels, respectively.

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