

Problem1__2__Jeanne

November 15, 2020

The code and write up below correspond to questions 1 and 2 of the computational assignment. The code is set up such that all functions are defined at the beginning, and ran later in the problem. Notice that I do not use the transition matrix T for problem 1. After implementing it for problem 2 I aimed at rewriting the code for problem 1 to use the (time saving) approach of T, but I ran out of time. After understanding the Transition matrix approach through spending a positive number of hours debugging the transition matrix function, I recognize it is indeed a very convenient way to set the problem up, which I didn't know about.

v1 refers to question 1, v2 refers to question 2.

```
[1]: import numpy as np
      from matplotlib import pyplot as plt
      from scipy.sparse import csr_matrix
      import time
      from scipy import sparse
      import numpy.linalg as lin
```

```
[2]: # Define primitives
      def u_f1(S,y):
          '''Utility function version 1'''
          U = 2*y**0.5
          if y > S:
              U = -100000000
          return U

      def u_f2(S,y):
          '''Utility function version 2'''
          U = 5*y - 0.05*y**2
          if y > S:
              U = -100000000
          return U

      def Bellman_simple(Vp, ik, jk, utilitymatrix):
          '''
          Bellman Function for the non-interpolation case (Problem 1)
          '''
          Value = utilitymatrix[ik, jk] + * Vp[ik-jk]
          return(Value)
```

```

def Bellman_interp(Vp, ik, jk, utilitymatrix, T):
    """
    Bellman : value function for state variable Kgrid[ik] with policy Kgrid[jk]
    ↪ (Problem 2)
    """
    N = len(T)
    beg = N*jk
    fin = N*(jk+1)
    subT = T[ik, beg:fin] # get the index of the new state by subsetting in the
    ↪ transition matrix
    state_new = np.where(subT > 0)[0]
    if len(state_new)==1: # Reach the boundary: extraction > stock --> next
    ↪ stock == 0
        state_new1 = state_new[0]
        weight1 = subT[state_new1]
        Vnext = Vp[state_new1]*weight1
    if len(state_new)>1:
        state_new1 = state_new[0]
        state_new2 = state_new[1]
        weight1 = subT[state_new1]
        weight2 = subT[state_new2]
        Vnext = Vp[state_new1]*weight1 + Vp[state_new2]*weight2
    Value = utilitymatrix[ik, jk] + * Vnext
    return (Value)

# Price functions = derivatives of utility functions wrt extraction (MU)
def p1_f(C1):
    return (1/(C1**0.5))

def p2_f(C2):
    return (5 - 0.1*C2)

```

```

[3]: def T_f(S, A, interp=True):
    """
    This function computes the transition matrix for the interpolation problem
    ↪ (Problem 2)
    It can be easily adapted to the standard case
    """

    # Initialize
    N = len(S)
    Na = len(A)
    T = np.zeros((N, N*Na))

    # For each action indexed k, and each initial state i, compute resulting
    ↪ state j

```

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if interp==True:
    for i in range(N):
        for k in range(Na):
            diff = S[i] - A[k]
            if diff < 0:
                index1_raw = 0
                index1_adj = index1_raw + (N)*k
                T[i, index1_adj] = 1.0
            if diff >= 0:
                dist = abs(S - diff) # How far from the difference is each
→element of S
                index1_raw = np.where(dist == sorted(dist)[0])[0][0] # Find
→the index of the closest
                index2_raw = np.where(dist == sorted(dist)[1])[0][0] # Find
→the index of the second closest
                weight1 = 1 - sorted(dist)[0] / np.sum(sorted(dist)[0:2])
                weight2 = 1 - sorted(dist)[1] / np.sum(sorted(dist)[0:2])
                index1_adj = index1_raw + (N)*k
                index2_adj = index2_raw + (N)*k
                T[i, index1_adj] = weight1
                T[i, index2_adj] = weight2

return(T)

```

```

[4]: def VFI_v1(State_grid, Action_grid, V0, utilitymatrix, maxiter = 1000,
→tol=1e-8, =(1/1.05), howard=True, print_i=True):
    '''
    VFI routine for problem 1
    (should be merged with VFI_v2 for concision but I'm running out of time)
    '''
    N = len(State_grid)
    Na = len(Action_grid)
    ### Initiate vectors & numbers
    iter = 0
    epsi = 1
    IndexAction_new = np.zeros(Na)
    Action = np.zeros(Na)
    Vp = V0
    Vp_new = np.zeros(N)

    while (epsi > tol) & (iter < maxiter):
        for ik in range(N):
            # ik = index of the stock today
            # d = max extraction < current stock
            #d = int(gk[max(ik-1), 0])
            d = 0

            #Value function Tj for each choice g(k)

```

```

Vnext = np.zeros(len(State_grid)-d)

# Compute the value function Tj for each choice of g(k)
for jk in range(d, Na):
    Vnext[jk - d] = Bellman_simple(Vp, ik, jk, utilitymatrix)

# Choose the maximum
Vp_new[ik] = np.max(Vnext)
#IndexAction_new[ik] = d + int(np.where(Vnext==np.max(Vnext))[0][0])
IndexAction_new[ik] = d + int(np.max(np.where(Vnext==np.
↪max(Vnext))[0]))

if howard==True:
    # Reduces the number of iterations by updating the Vnew grid more
↪often
    for c in range(100):
        for ik in range(len(Action_grid)):
            jk = int(IndexAction_new[ik])
            Vp_new[ik] = Bellman_simple(Vp_new, ik, jk, utilitymatrix)

### Check the error
epsi = np.abs(Vp_new - Vp).max()

### Keep track of what is going on
if print_i==True:
    print("iteration is ", iter, " and Error term is ", epsi)

IndexAction = IndexAction_new*1. #Update
Vp = Vp_new*1. #Update

if epsi < tol:
    break

iter=iter+1

#Calculate Values for g(k)
for jk in range(len(Action_grid)):
    Action[jk] = Action_grid[int(IndexAction[jk])]
print("Total number of iterations : ", iter)

# Calculate the N*N optimal transition matrix T_opt that gives the state
↪transition proba under optimal action
return[Vp, IndexAction, Action, iter]

```

```

[5]: def VFI_v2(State_grid, Action_grid, V0, utilitymatrix, T, maxiter = 1000, tol =
→ 1e-8, =(1/1.05), print_i=True):
    '''
    VFI Routine for Problem 2
    '''

    ### Initiate vectors & numbers
    iter = 0
    epsi = 1
    N = len(State_grid)
    Na = len(Action_grid)
    IndexAction_new = np.zeros(Na)
    Vp = np.zeros(N)

    while (epsi > tol) & (iter < maxiter):
        # Copy the old value vector
        Vold = np.copy(Vp)
        # Initiate the matrix
        Vnextall = np.zeros((N, Na))
        # For each Na*N block (each action): computes the pair [old, new] states
        for jk in range(Na):
            beg = N*jk
            fin = N*(jk+1)
            Tnext = T[:,beg:fin]
            vals = T[:,beg:fin].dot(Vp)
            Vnextall[:,jk] = vals
        #  $V = U + \beta V$ 
        Uall = utilitymatrix + * Vnextall
        # Find the maximum total V for each starting i (Vp[i]), and the index
→ of the corresponding action maxArgAction[i]
        maxArgAction = np.zeros(N)
        for i in range(N):
            maxArgAction[i] = np.argmax(Uall[i,:])
            Vp[i] = np.max(Uall[i,:])

        ### Check the error
        epsi = lin.norm(Vp - Vold)

        ### Keep track of what is going on
        if print_i==True:
            print("iteration is ", iter, " and Error term is ", epsi)

        IndexAction_new = np.copy(maxArgAction)

        if epsi < tol:
            break

```

```

        iter=iter+1

    return(Vp, IndexAction_new, iter)

```

0.1 Question 1: Solving the DDP by value function iteration ; discrete state space

```

[6]: ### Parameters
r = 0.05
    = 1/(1+r)
Stot = 1000

N = 501
Na = 501
S1 = np.linspace(0,1000,N)
A1 = np.linspace(0,1000,Na)
V0 = np.zeros(N)

### Compute utility matrix for utility 1 and 2
utilitymatrix1_v1 = np.ones((N, Na))
for i in range(0,N):
    for j in range(0,Na):
        utilitymatrix1_v1[i,j] = u_f1(S1[i], A1[j])

utilitymatrix2_v1 = np.ones((N, Na))
for i in range(0,N):
    for j in range(0,Na):
        utilitymatrix2_v1[i,j] = u_f2(S1[i], A1[j])

```

```

[7]: ##### UTILITY 1
### Solve the model
[Vp1_v1, IndexAction1_v1, Action1_v1, iter1_v1] = VFI_v1(S1, A1, V0,
    ↪utilitymatrix1_v1, howard=True, print_i=False)
print("solving model 1 done")

### Calculate the N*N optimal transition matrix
T_opt1 = np.zeros((N, N))
for ik in range(N):
    ij = np.where(S1 == S1[ik] - Action1_v1[ik])[0][0]
    T_opt1[ik, ij] = 1

##### UTILITY 2
### Solve the model
[Vp2_v1, IndexAction2_v1, Action2_v1, iter2_v1] = VFI_v1(S1, A1, V0,
    ↪utilitymatrix2_v1, howard=True, print_i=False)

```

```

print("solving model 2 done")

### Calculate the N*N optimal transition matrix
T_opt2 = np.zeros((N, N))
for ik in range(N):
    ij = np.where(S1 == S1[ik] - Action2_v1[ik])[0][0]
    T_opt2[ik, ij] = 1

```

```

Total number of iterations : 22
solving model 1 done
Total number of iterations : 14
solving model 2 done

```

```

[8]: ##### Simulate the model for 80 periods
# St = each period's stock
# C = each period's extraction

## Simulate 1
St1_v1 = 1000*np.ones(80)
C1_v1 = np.zeros(80)
for i in range(80-1):
    init_index1 = np.where(S1==St1_v1[i])[0][0]
    C1_v1[i] = Action1_v1[init_index1]
    final_index1 = np.where(T_opt1[init_index1,]==1)[0][0]
    St1_v1[i+1] = S1[final_index1]
p1_v1 = p1_f(C1_v1)

## Simulate 2
St2_v1 = 1000*np.ones(80)
C2_v1 = np.zeros(80)
for i in range(80-1):
    init_index2 = np.where(S1==St2_v1[i])[0][0]
    C2_v1[i] = Action2_v1[init_index2]
    final_index2 = np.where(T_opt2[init_index2,]==1)[0][0]
    St2_v1[i+1] = S1[final_index2]
p2_v1 = p2_f(C2_v1)

```

```

/Applications/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:47:
RuntimeWarning: divide by zero encountered in true_divide

```

```

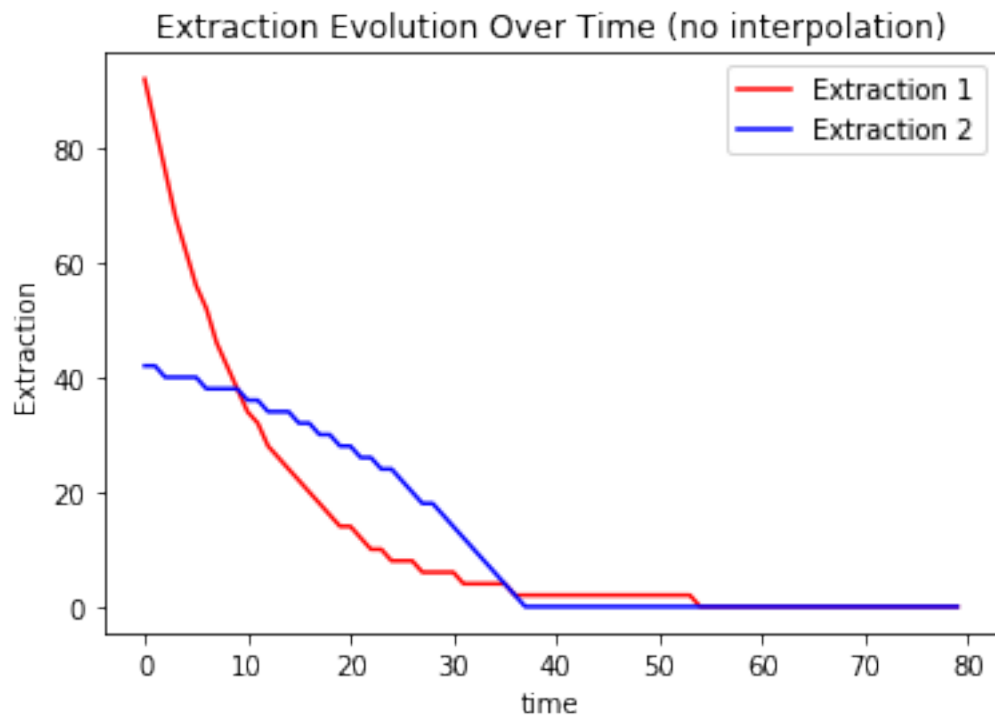
[9]: plt.plot(range(0,80), C1_v1, color="red", label="Extraction 1")
plt.plot(range(0,80), C2_v1, color="blue", label="Extraction 2")
plt.title("Extraction Evolution Over Time (no interpolation)")
plt.xlabel("time")
plt.ylabel("Extraction")
plt.legend()
plt.show()

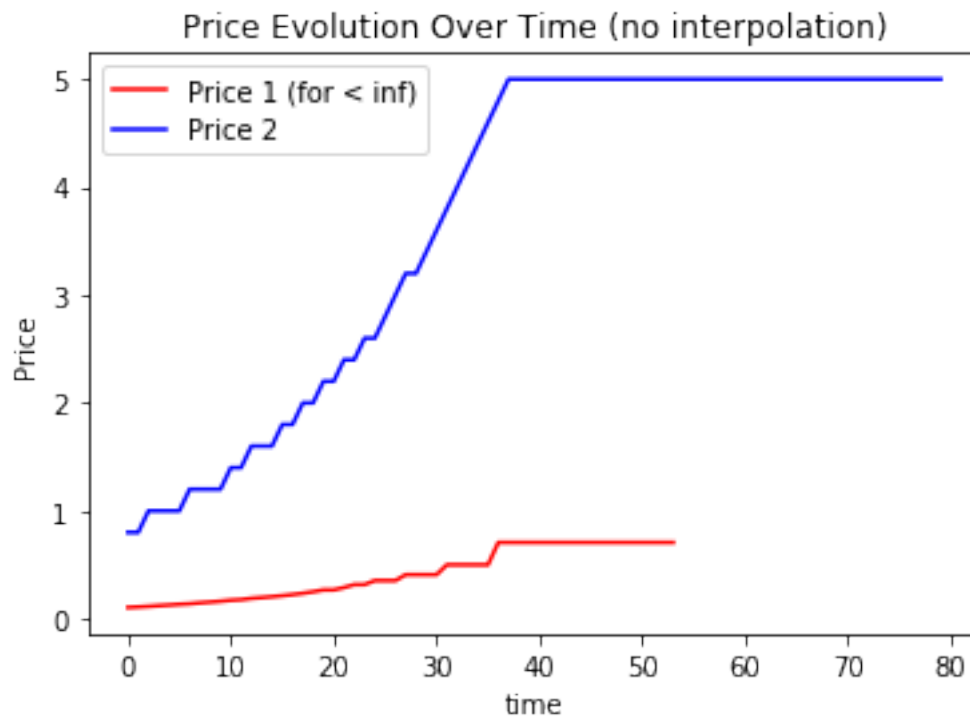
```

```

# For printing purposes
plt.plot(range(0,80), p1_v1, color="red", label="Price 1 (for < inf)")
plt.plot(range(0,80), p2_v1, color="blue", label="Price 2")
plt.title("Price Evolution Over Time (no interpolation)")
plt.xlabel("time")
plt.ylabel("Price")
plt.legend()
plt.show()

```

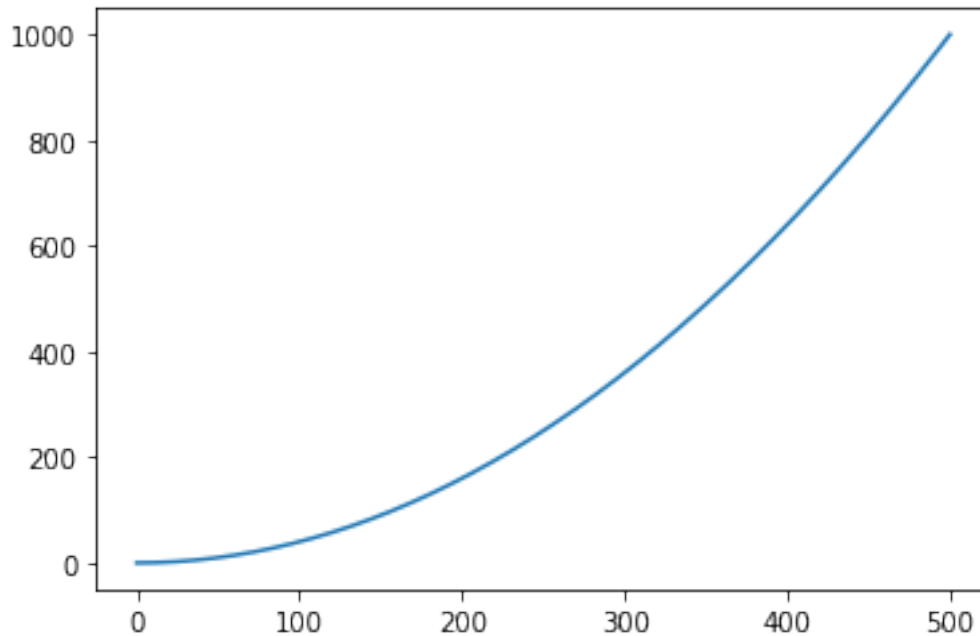




0.2 Question 2: Interpolating Between the States

```
[10]: N2 = 501
      Na2 = 501
      S2 = np.linspace(0,1000,N2)
      A2 = np.linspace(0,(1000**0.5),Na2)**2
      plt.plot(range(501), A2)
```

```
[10]: [<matplotlib.lines.Line2D at 0x7fab364f9a90>]
```



```
[11]: ### Compute utility matrix for utility 1 and 2
utilitymatrix1_v2 = np.ones((N2, Na2))
for i in range(0,N2):
    for j in range(0,Na2):
        utilitymatrix1_v2[i,j] = u_f1(S2[i], A2[j])

utilitymatrix2_v2 = np.ones((N2, Na2))
for i in range(0,N2):
    for j in range(0,Na2):
        utilitymatrix2_v2[i,j] = u_f2(S2[i], A2[j])

[12]: ### Compute the Transition Matrix
T2 = T_f(S2, A2, interp=True)
T2 = csr_matrix(T2)

[13]: ### VFI
V0 = np.zeros(N2)
[Vp1_v2, IndexAction1_v2, iter1_v2] = VFI_v2(S2, A2, V0, utilitymatrix1_v2, T = T2, print_i=True)
print("Utility 1: DONE")

[Vp2_v2, IndexAction2_v2, iter2_v2] = VFI_v2(S2, A2, V0, utilitymatrix2_v2, T = T2, print_i=False)
print("Utility 2: DONE")
```

iteration is 0 and Error term is 999.6306757998175

iteration is 1 and Error term is 382.22358359005364
iteration is 2 and Error term is 271.571086320296
iteration is 3 and Error term is 212.4579473176012
iteration is 4 and Error term is 173.61935439472015
iteration is 5 and Error term is 145.52413508394983
iteration is 6 and Error term is 124.15091213179542
iteration is 7 and Error term is 107.05369166338109
iteration is 8 and Error term is 93.12997699892438
iteration is 9 and Error term is 81.61902093185495
iteration is 10 and Error term is 71.86880582805578
iteration is 11 and Error term is 63.499016900233514
iteration is 12 and Error term is 56.34387846166145
iteration is 13 and Error term is 50.11094282974448
iteration is 14 and Error term is 44.7271788902159
iteration is 15 and Error term is 40.03579837182327
iteration is 16 and Error term is 35.830256185787505
iteration is 17 and Error term is 32.08515277453874
iteration is 18 and Error term is 28.793217288378887
iteration is 19 and Error term is 25.85500434718936
iteration is 20 and Error term is 23.263422138973258
iteration is 21 and Error term is 20.937125947878076
iteration is 22 and Error term is 18.864180362648234
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iteration is 24 and Error term is 15.301786992192639
iteration is 25 and Error term is 13.796044899269988
iteration is 26 and Error term is 12.462800808911043
iteration is 27 and Error term is 11.278960520867294
iteration is 28 and Error term is 10.208583906133356
iteration is 29 and Error term is 9.222334728356675
iteration is 30 and Error term is 8.330500392772214
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iteration is 33 and Error term is 6.132718692188198
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iteration is 45 and Error term is 1.7013876165972117
iteration is 46 and Error term is 1.5302798225278205
iteration is 47 and Error term is 1.377525028198638
iteration is 48 and Error term is 1.2418433820183594

iteration is 49 and Error term is 1.1198974079407147
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iteration is 144 and Error term is 9.264112207212626e-05

iteration is 145 and Error term is 8.384435652972197e-05
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iteration is 148 and Error term is 6.214076891246526e-05
iteration is 149 and Error term is 5.623196484022768e-05
iteration is 150 and Error term is 5.0883776362478124e-05
iteration is 151 and Error term is 4.604329509733521e-05
iteration is 152 and Error term is 4.166254236062395e-05
iteration is 153 and Error term is 3.7698023761286684e-05
iteration is 154 and Error term is 3.4110321235545106e-05
iteration is 155 and Error term is 3.086372000750748e-05
iteration is 156 and Error term is 2.792586752857811e-05
iteration is 157 and Error term is 2.5267461755080753e-05
iteration is 158 and Error term is 2.2861967968253335e-05
iteration is 159 and Error term is 2.068536049624401e-05
iteration is 160 and Error term is 1.8715887791416153e-05
iteration is 161 and Error term is 1.6933859175228303e-05
iteration is 162 and Error term is 1.53214508089017e-05
iteration is 163 and Error term is 1.3862530277247316e-05
iteration is 164 and Error term is 1.2542496378061458e-05
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iteration is 166 and Error term is 1.0267486845718118e-05
iteration is 167 and Error term is 9.289730302979291e-06
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iteration is 175 and Error term is 4.171560404394463e-06
iteration is 176 and Error term is 3.7742809653693257e-06
iteration is 177 and Error term is 3.414835212564135e-06
iteration is 178 and Error term is 3.0896204569114575e-06
iteration is 179 and Error term is 2.795377039643345e-06
iteration is 180 and Error term is 2.529155604656228e-06
iteration is 181 and Error term is 2.288287552685445e-06
iteration is 182 and Error term is 2.070358665214905e-06
iteration is 183 and Error term is 1.8731842053924212e-06
iteration is 184 and Error term is 1.6947877403880837e-06
iteration is 185 and Error term is 1.5333811015854592e-06
iteration is 186 and Error term is 1.387346127270166e-06
iteration is 187 and Error term is 1.2552190419629498e-06
iteration is 188 and Error term is 1.1356752832116564e-06
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iteration is 190 and Error term is 9.296583459057608e-07
iteration is 191 and Error term is 8.411199399401749e-07
iteration is 192 and Error term is 7.610136834763229e-07

iteration is 193 and Error term is 6.885365211773941e-07
iteration is 194 and Error term is 6.229618536460992e-07
iteration is 195 and Error term is 5.636323840452894e-07
iteration is 196 and Error term is 5.099532483308441e-07
iteration is 197 and Error term is 4.6138644844401135e-07
iteration is 198 and Error term is 4.17444958410823e-07
iteration is 199 and Error term is 3.7768842935398683e-07
iteration is 200 and Error term is 3.417181512709929e-07
iteration is 201 and Error term is 3.0917369330924925e-07
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iteration is 207 and Error term is 1.695933627893029e-07
iteration is 208 and Error term is 1.5344157078332136e-07
iteration is 209 and Error term is 1.3882814758306414e-07
iteration is 210 and Error term is 1.2560641144860583e-07
iteration is 211 and Error term is 1.1364391024864586e-07
iteration is 212 and Error term is 1.0282068756664399e-07
iteration is 213 and Error term is 9.302821295002828e-08
iteration is 214 and Error term is 8.416839465686991e-08
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iteration is 216 and Error term is 6.889973610741334e-08
iteration is 217 and Error term is 6.233789682678046e-08
iteration is 218 and Error term is 5.640092645543799e-08
iteration is 219 and Error term is 5.1029487576229526e-08
iteration is 220 and Error term is 4.6169517193644627e-08
iteration is 221 and Error term is 4.177236071458647e-08
iteration is 222 and Error term is 3.7794061767050025e-08
iteration is 223 and Error term is 3.4194701521793885e-08
iteration is 224 and Error term is 3.093802910986831e-08
iteration is 225 and Error term is 2.7991513597837628e-08
iteration is 226 and Error term is 2.5325667322783733e-08
iteration is 227 and Error term is 2.291373747184729e-08
iteration is 228 and Error term is 2.0731451578392997e-08
iteration is 229 and Error term is 1.8757053463294803e-08
iteration is 230 and Error term is 1.697062794247227e-08
iteration is 231 and Error term is 1.5354362073591056e-08
iteration is 232 and Error term is 1.389204826372071e-08
iteration is 233 and Error term is 1.2569027100806917e-08
iteration is 234 and Error term is 1.1371987969748516e-08
iteration is 235 and Error term is 1.0288952116634768e-08
iteration is 236 and Error term is 9.309039605482992e-09
Utility 1: DONE
Utility 2: DONE

```

[14]: ### Find the optimal Transition matrices
T_opt1_v2 = np.zeros((N2, N2))
for ik in range(N2):
    diff = S2[ik] - A2[int(IndexAction1_v2[ik])]
    dist = abs(S2 - diff) # How far from the differenre is each element of S2
    index1 = np.where(dist == sorted(dist)[0])[0][0] # Find the index of the
    →closest
    index2 = np.where(dist == sorted(dist)[1])[0][0] # Find the index of the
    →second closest
    weight1 = sorted(dist)[0] / np.sum(sorted(dist)[0:2])
    weight2 = sorted(dist)[1] / np.sum(sorted(dist)[0:2])
    weight1 + weight2 == 1
    T_opt1_v2[ik, index1] = weight1
    T_opt1_v2[ik, index2] = weight2

T_opt1_v2 = csr_matrix(T_opt1_v2)

T_opt2_v2 = np.zeros((N2, N2))
for ik in range(N2):
    diff = S2[ik] - A2[int(IndexAction2_v2[ik])]
    dist = abs(S2 - diff) # How far from the differenre is each element of S2
    index1 = np.where(dist == sorted(dist)[0])[0][0] # Find the index of the
    →closest
    index2 = np.where(dist == sorted(dist)[1])[0][0] # Find the index of the
    →second closest
    weight1 = sorted(dist)[0] / np.sum(sorted(dist)[0:2])
    weight2 = sorted(dist)[1] / np.sum(sorted(dist)[0:2])
    weight1 + weight2 == 1
    T_opt2_v2[ik, index1] = weight1
    T_opt2_v2[ik, index2] = weight2

T_opt2_v2 = csr_matrix(T_opt2_v2)

```

```

[15]: ### Simulate

St1_v2 = 1000*np.ones(80)
C1_v2 = np.zeros(80)
for i in range(80-1):
    #init_index1 = np.where(S2==St1_v2[i])[0][0]
    init = St1_v2[i]
    # Find closest states
    dist = abs(S2 - init)
    tokeep = sorted(dist)[0:2]
    index1 = np.where(dist == tokeep[0])[0][0]
    index2 = np.where(dist == tokeep[1])[0][0]
    weight1 = 1 - tokeep[0] / np.sum(tokeep[0:2])
    weight2 = 1 - tokeep[1] / np.sum(tokeep[0:2])

```



```

    weight1 + weight2 == 1
    C1_v2[i] = A2[int(IndexAction1_v2[index1]))*weight1 +
    ↪A2[int(IndexAction1_v2[index2]))*weight2
    St1_v2[i+1] = St1_v2[i] - C1_v2[i]
p1_v2 = p1_f(C1_v2)

# Simulate
St2_v2 = 1000*np.ones(80)
C2_v2 = np.zeros(80)
for i in range(80-1):
    #init_index1 = np.where(S2==St1_v2[i])[0][0]
    init = St2_v2[i]
    # Find closest states
    dist = abs(S2 - init)
    tokeep = sorted(dist)[0:2]
    index1 = np.where(dist == tokeep[0])[0][0]
    index2 = np.where(dist == tokeep[1])[0][0]
    weight1 = 1 - tokeep[0] / np.sum(tokeep[0:2])
    weight2 = 1 - tokeep[1] / np.sum(tokeep[0:2])
    weight1 + weight2 == 1
    C2_v2[i] = A2[int(IndexAction2_v2[index1]))*weight1 +
    ↪A2[int(IndexAction2_v2[index2]))*weight2
    St2_v2[i+1] = St2_v2[i] - C2_v2[i]

p2_v2 = p2_f(C2_v2)

```

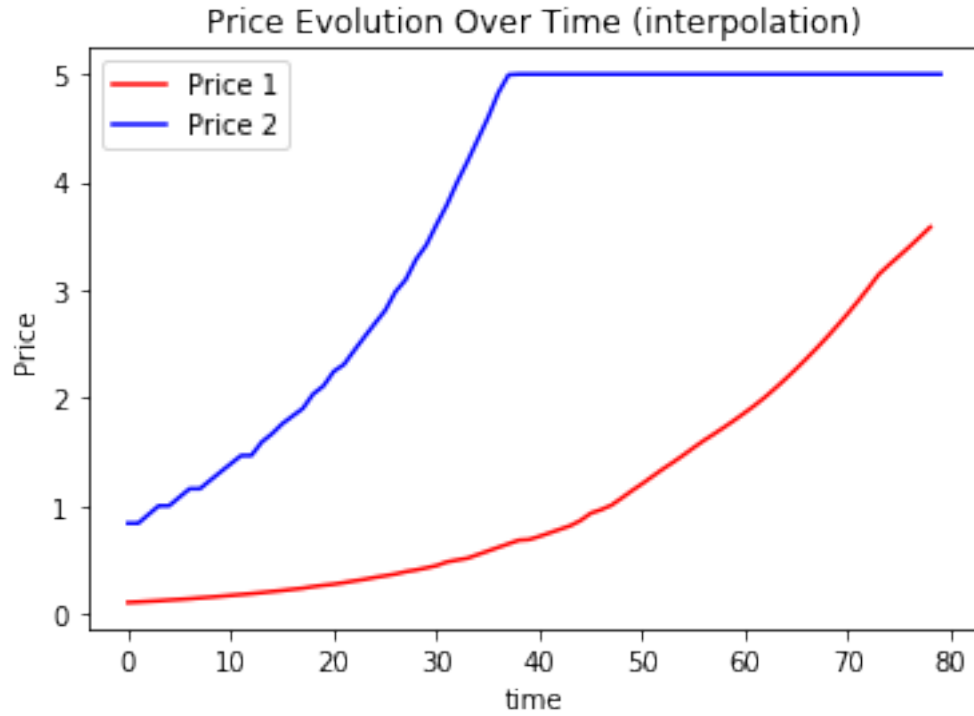
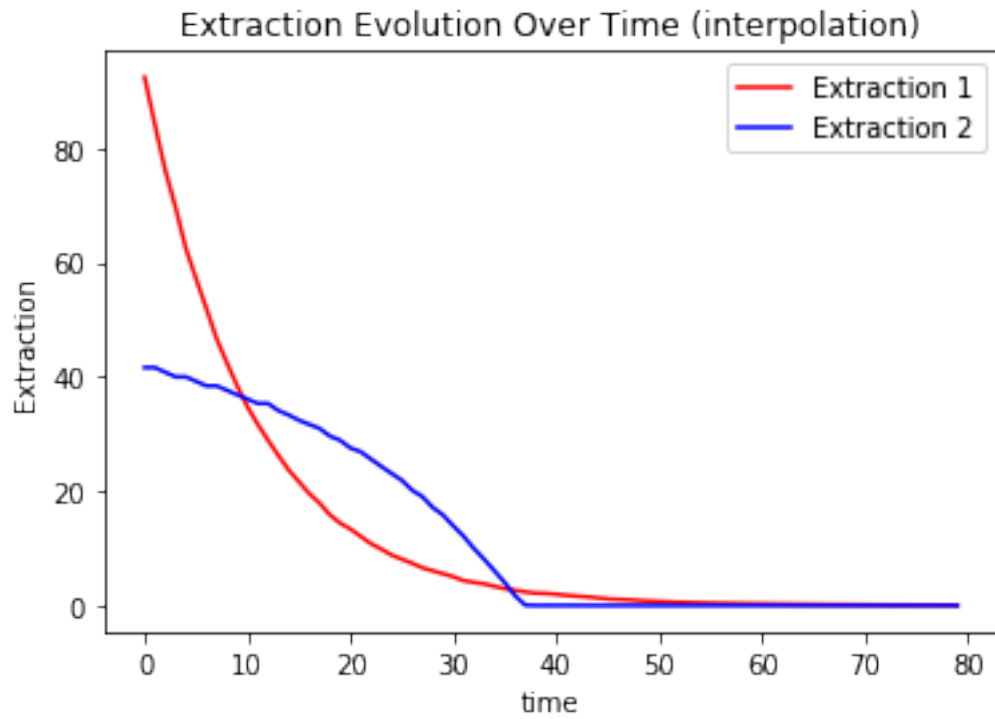
/Applications/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:47:
RuntimeWarning: divide by zero encountered in true_divide

```

[16]: plt.plot(range(0,80), C1_v2, color="red", label="Extraction 1")
plt.plot(range(0,80), C2_v2, color="blue", label="Extraction 2")
plt.title("Extraction Evolution Over Time (interpolation)")
plt.xlabel("time")
plt.ylabel("Extraction")
plt.legend()
plt.show()

# For printing purposes
plt.plot(range(0,80), p1_v2, color="red", label="Price 1")
plt.plot(range(0,80), p2_v2, color="blue", label="Price 2")
plt.title("Price Evolution Over Time (interpolation)")
plt.xlabel("time")
plt.ylabel("Price")
plt.legend()
plt.show()

```



```

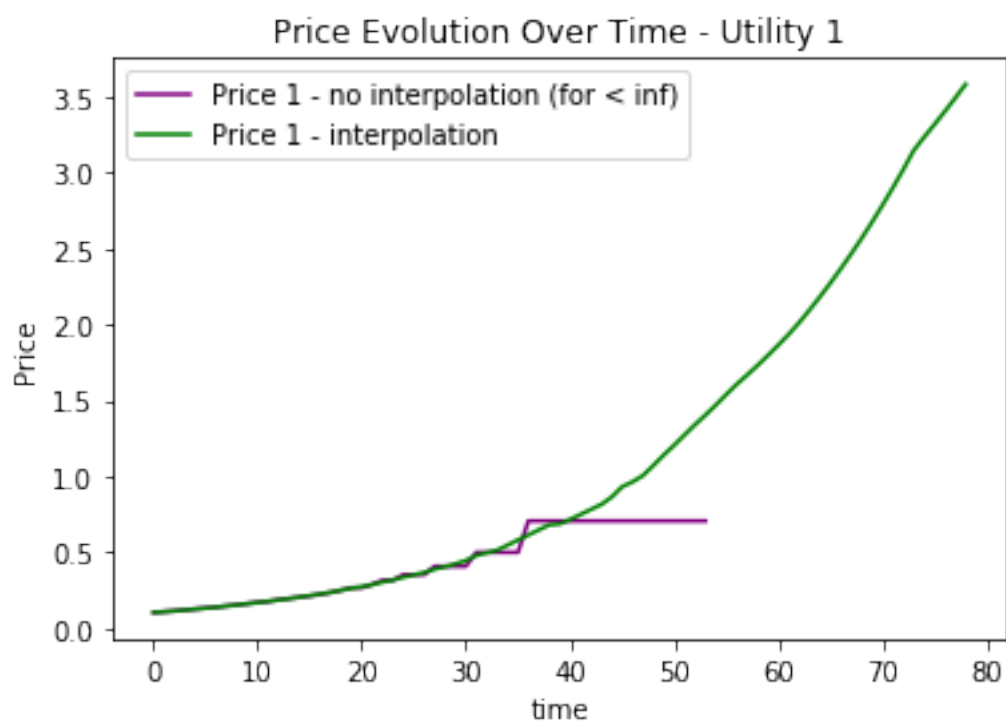
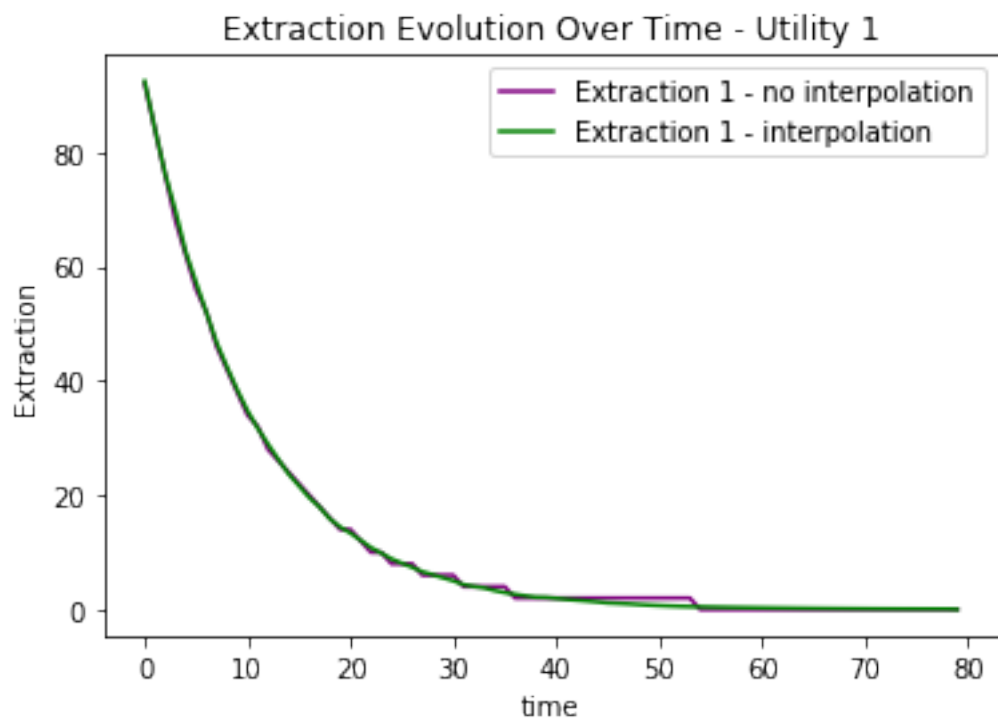
[17]: # For Free: a comparison of the interpolation & non-interpolation outcomes
plt.plot(range(0,80), C1_v1, color="purple", label="Extraction 1 - no_
↳interpolation")
plt.plot(range(0,80), C1_v2, color="green", label="Extraction 1 -_
↳interpolation")
plt.title("Extraction Evolution Over Time - Utility 1")
plt.xlabel("time")
plt.ylabel("Extraction")
plt.legend()
plt.show()

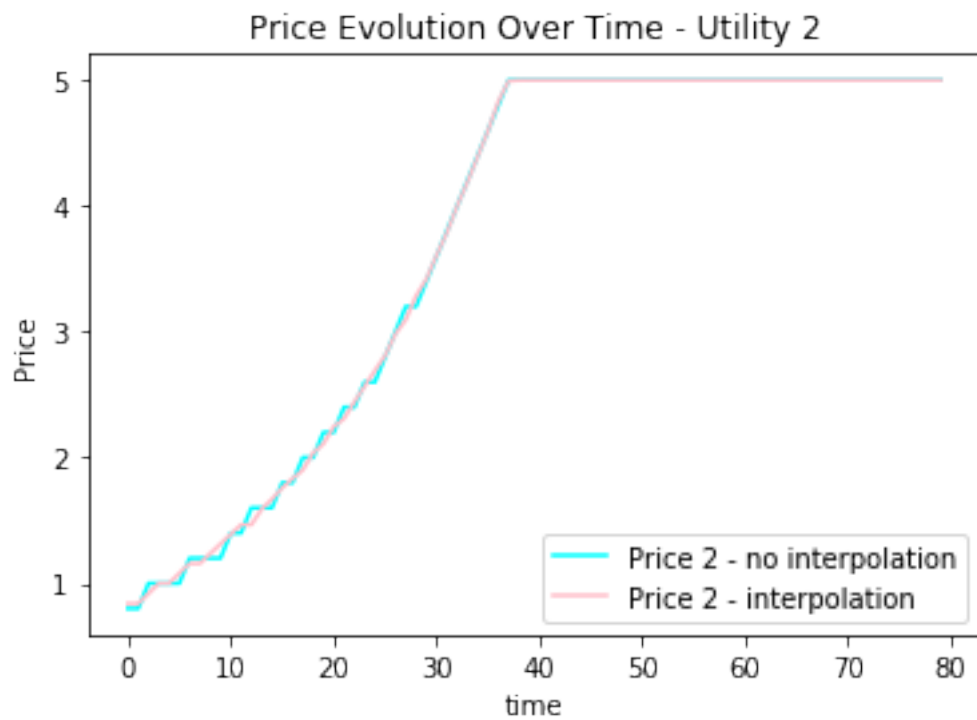
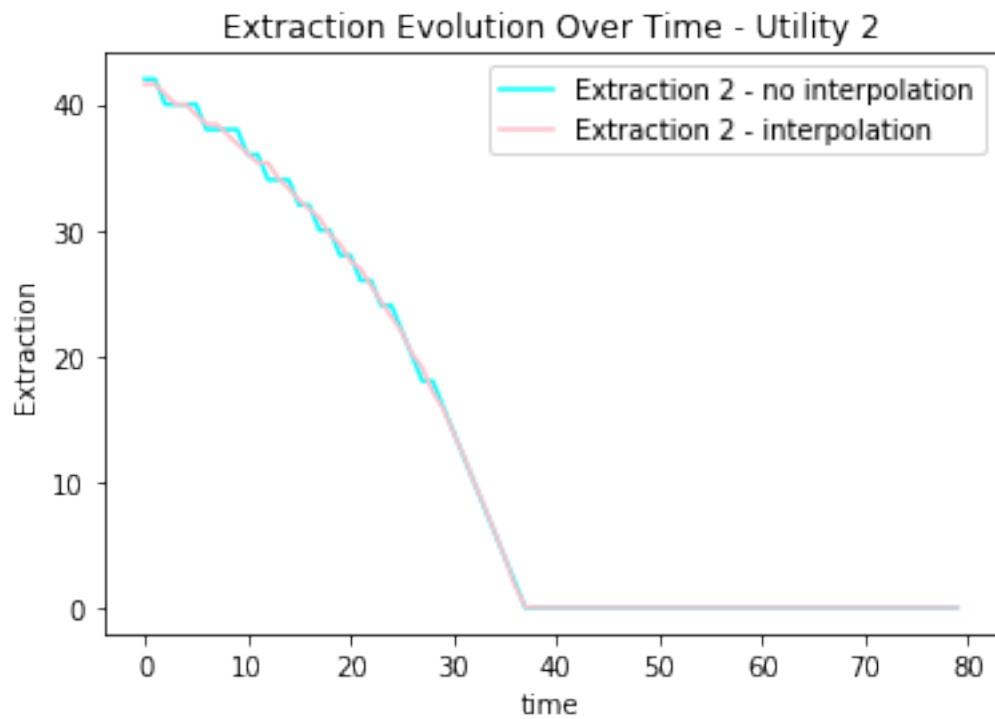
plt.plot(range(0,80), p1_v1, color="purple", label="Price 1 - no interpolation_
↳(for < inf)")
plt.plot(range(0,80), p1_v2, color="green", label="Price 1 - interpolation")
plt.title("Price Evolution Over Time - Utility 1")
plt.xlabel("time")
plt.ylabel("Price")
plt.legend()
plt.show()

plt.plot(range(0,80), C2_v1, color="cyan", label="Extraction 2 - no_
↳interpolation")
plt.plot(range(0,80), C2_v2, color="pink", label="Extraction 2 - interpolation")
plt.title("Extraction Evolution Over Time - Utility 2")
plt.xlabel("time")
plt.ylabel("Extraction")
plt.legend()
plt.show()

plt.plot(range(0,80), p2_v1, color="cyan", label="Price 2 - no interpolation")
plt.plot(range(0,80), p2_v2, color="pink", label="Price 2 - interpolation")
plt.title("Price Evolution Over Time - Utility 2")
plt.xlabel("time")
plt.ylabel("Price")
plt.legend()
plt.show()

```





A couple remarks about the differences between problem 1 and problem 2: - Interestingly, with utility 1, notice that the price goes to ∞ in problem 1, but not in problem 2. The intuition is that with this utility, $u'_1(0) = \infty$, so if the agent is not constrained by the grid, he will make sure to always extract a strictly positive amount every period. When $t \rightarrow \infty$ we should converge to 0 stock, but always strictly positive. The grid interpolation approximates a continuous problem. - For utility 2, we do not observe the same phenomenon because u'_2 is bounded about by 5.