

$$\begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{\theta} \\ \dot{u}_1 \\ \dot{u}_2 \end{pmatrix} = \begin{pmatrix} v \cos \delta \cos \theta \\ v \cos \delta \sin \theta \\ \frac{v \sin \delta}{3} \\ u_1 \\ u_2 \end{pmatrix}$$

$$\begin{pmatrix} \dot{x} \\ \dot{y} \\ \dot{\theta} \end{pmatrix} = \begin{pmatrix} \bar{u}_1 \cdot \cos \theta \\ \bar{u}_1 \cdot \sin \theta \\ \bar{u}_2 \end{pmatrix}$$

or preend $\bar{u}_1 = v \cdot \cos \delta$

$$\bar{u}_2 = \frac{v \sin \delta}{3}$$

$$\mu = f(x, \bar{u})$$

$$\mu = \underset{\substack{\uparrow \\ \text{gain}}}{K} \cdot \left(\bar{u} - \begin{pmatrix} v \cos \delta \\ \frac{v \sin \delta}{3} \end{pmatrix} \right)$$

③

